Colours #Creamos un color HSL(float) con dev y lo transformamos en RGB devCol = rd.ColorHSL(dev*0.3,1,0.5) devCol = devCol.ToArgbColor() import Rhino. Geometry as rg import Rhino. Display as rdis #Sustituimos el punto 3 por su nuevo valor import random as rd pts[3] = newPt3import math as m lines = [] ptList = [] #Creamos una marca en cada panel fuera de tolerancia colList = [] if dev>T: rd.seed(s) 10 = rg.Line(pts[0],pts[2])I1 = rg.Line(pts[1],pts[3])for i in range(50): lines.extend([I0,I1]) for j in range(50): #Creamos la polilinea de cada panel y calculamos su area z = rd.gauss(me,dev)pol = rg.PolylineCurve((pts[0],pts[1],pts[2],pts[3],pts[0])) ptList.append(rg.Point3d(i,j,z)) col = rdis.ColorHSL(z*0.2,1,0.5)areaObj = rg.AreaMassProperties.Compute(pol) colList.append(col.ToArgbColor()) area = areaObi.Area a = ptListw = lines## Planarize ## divSrf import Rhino.Geometry as rg import Rhino. Display as rd import Rhino.Geometry as rg from Grasshopper import DataTree as Tree #Creamos un plano con tres puntos cualesquiera from Grasshopper.Kernel.Data import GH_Path as Path plane = rg.Plane(pts[0],pts[1],pts[2]) ptList = [] polList = [] #Proyectamos el punto 3 sobre el plano calculado newPt3 = plane.ClosestPoint(pts[3]) #Initializing an empty data tree ptTree = Tree[object]() #Calculamos el desplazamiento de cada punto dev = pts[3].DistanceTo(newPt3) for i in range(uDiv+1):

```
ptListTemp = []
                                                                                ptList = []
 for j in range(vDiv+1):
                                                                                def koch(ptA, ptB, r0, r1, r2, rM):
    ptTemp = srf.Evaluate(i/uDiv,j/vDiv,2)[1]
                                                                                  #points = []
    ptListTemp.append(ptTemp)
                                                                                  pt0 = ((ptB-ptA)*r0)+ptA
 ptList.append(ptListTemp)
                                                                                  pt1 = ((ptB-ptA)*r1)+ptA
counter = 0
                                                                                  #Calculating vector perpendicular to ptB-ptA
                                                                                  cross = rs.VectorCrossProduct((ptB-ptA),(0,0,1))
for i in range(uDiv):
 for j in range(vDiv):
                                                                                  cross = rs.VectorUnitize(cross)
                                                                                  dist = rs.VectorLength((ptB-ptA))
                                                                                  h = m.sqrt(((dist/3)**2.0)-((dist/6)**2.0))
    pt0 = ptList[i][i]
    pt1 = ptList[i+1][i]
                                                                                  pt1 += cross*(h*rM)
    pt2 = ptList[i][j+1]
    pt3 = ptList[i+1][j+1]
                                                                                  pt2 = ((ptB-ptA)*r2)+ptA
    # Adding points to datatree
                                                                                  #points.extend((pt0,pt1,pt2))
    # The commented lines produce the flipped tree.
                                                                                  return [ptA,pt0,pt1,pt2,ptB]
    #ptTree.Add(pt0,Path(0))
    #ptTree.Add(pt1,Path(1))
                                                                                def recursive (ptA, ptB, gens, list):
    #ptTree.Add(pt2,Path(2))
                                                                                  if gens>0:
    #ptTree.Add(pt3,Path(3))
                                                                                     newPts = koch (ptA,ptB,rat0,rat1,rat2,ratM)
    ptTree.AddRange([pt0,pt1,pt3,pt2],Path(counter))
                                                                                     curve = rs.AddPolyline(newPts)
    counter += 1
                                                                                     if gens == 1:
    polList.append(rg.Polyline([pt0,pt1,pt3,pt2]))
                                                                                       list.append(curve)
panel = polList
                                                                                     recursive(newPts[0],newPts[1],gens-1,list)
                                                                                     recursive(newPts[1],newPts[2],gens-1,list)
                                                                                     recursive(newPts[2],newPts[3],gens-1,list)
recursive(newPts[3],newPts[4],gens-1,list)
## Koch curve
                                                                                     gens-=1
                                                                                     return list
import rhinoscriptsyntax as rs
import math as m
                                                                                crv = recursive(PtA,PtB,G,ptList)
```

```
lines.extend([I0,I1])
                                                                                   #Creamos la polilinea de cada panel y calculamos su area
## DivSrf + Panels
                                                                                   pol = rg.PolylineCurve((pts[0],pts[1],pts[2],pts[3],pts[0]))
import Rhino. Geometry as rq
from Grasshopper import DataTree as Tree
                                                                                   areaObj = rg.AreaMassProperties.Compute(pol)
from Grasshopper.Kernel.Data import GH Path as Path
                                                                                   area = areaObj.Area
                                                                                   w = lines
def planarize(pts,T):
                                                                                   data.extend([pol,area])
                                                                                   return data
  Creates a planar quad panel from a serie of 4 points projecting one of
  those over a plane defined by the other 3 points.
                                                                                panels = []
                                                                                ptList = []
  Returns a list where [0] is a polyline
                                                                                polList = []
  and [1] is the panel area (Float).
                                                                                #Initializing an empty data tree
                                                                                ptTree = Tree[object]()
  data = []
                                                                                for i in range(uDiv+1):
  #Creamos un plano con tres puntos cualesquiera
                                                                                   ptListTemp = []
  plane = rg.Plane(pts[0],pts[1],pts[2])
                                                                                   for j in range(vDiv+1):
  #Proyectamos el punto 3 sobre el plano calculado
  newPt3 = plane.ClosestPoint(pts[3])
                                                                                     ptTemp = srf.Evaluate(i/uDiv,j/vDiv,2)[1]
                                                                                     ptListTemp.append(ptTemp)
  #Calculamos el desplazamiento de cada punto
  dev = pts[3].DistanceTo(newPt3)
                                                                                   ptList.append(ptListTemp)
  #Sustituimos el punto 3 por su nuevo valor
                                                                                # Contador necesario para crear una rama de datos por cada panel
  pts[3] = newPt3
                                                                                counter = 0
  lines = []
                                                                                for i in range(uDiv):
  #Creamos una marca en cada panel fuera de tolerancia
                                                                                   for j in range(vDiv):
  if dev>T:
                                                                                     pt0 = ptList[i][i]
    10 = \text{rg.Line}(\text{pts}[0], \text{pts}[2])
                                                                                     pt1 = ptList[i+1][j]
    I1 = rg.Line(pts[1],pts[3])
                                                                                     pt2 = ptList[i][j+1]
```

```
pt3 = ptList[i+1][j+1]
                                                                              crvCentroid = rs.CurveAreaCentroid(c)[0]
                                                                              #print crvCentroid
    # Adding points to datatree
    # The commented lines produce the flipped tree.
                                                                              # Comprobando casos
    #ptTree.Add(pt0,Path(0))
                                                                              if abs(target-crvArea)>tolerance:
    #ptTree.Add(pt1,Path(1))
                                                                                 if target > crvArea:
    #ptTree.Add(pt2,Path(2))
                                                                                   print "caso 0"
    #ptTree.Add(pt3,Path(3))
                                                                                   print "Targe-Area= %f" %abs(target-crvArea)
                                                                                   print "Tolerance= %f" %tolerance
                                                                                   print "///////""
    ptTree.AddRange([pt0,pt1,pt3,pt2],Path(counter))
    counter += 1
                                                                                   crvNew = rs.ScaleObject(c,crvCentroid,[1+step,1+step,0])
    polList.append(rg.Polyline([pt0,pt1,pt3,pt2,pt0]))
                                                                                   c = scaling(crvNew)
# Loop para iterar en el arbol de datos creado en el loop anterior
                                                                                 elif target < crvArea:
for i in range(ptTree.BranchCount):
                                                                                   print "caso_1"
  panels.append(planarize(ptTree.Branch(Path(i)),tol))
                                                                                   print "Targe-Area= %f" %(target-crvArea)
                                                                                   print "Tolerance= %f" %tolerance
                                                                                   print "////////""
                                                                                   crvNew = rs.ScaleObject(c,crvCentroid,[1-step,1-step,1-step])
## Salida de datos
                                                                                   c = scaling(crvNew)
panel = polList
# Salida de datos de nuestra lista
                                                                              #print "out"
fpanel = [p[0] for p in panels]
                                                                              return c
area = [p[1] for p in panels]
a = scaling(crv)
                                                                            print a
## Recursive_scaling
import rhinoscriptsyntax as rs
import Rhino. Geometry as rg
import math as m
def scaling(c):
  crvArea = rs.CurveArea(c)[0]
```

RW_polygons

```
import Rhino.Geometry as rg
import rhinoscriptsyntax as rs
import random as rd
def addPolygon(p,n):
  #inicializamos pts para diferenciarla de pts global
  pts = []
  for i in range(n):
     pts.append(rs.Polar(p,i*step,r))
  ptM = (pts[0]+pts[1])/2
  dist = rs.Distance(ptM,p)
  pts.append(pts[0]) # Appends the first point again to close the curve
  pol = rg.PolylineCurve(pts)
  return [pol,dist]
rd.seed(s)
pts = []
pol = []
step = 360.0/n
# Creates a loop to build points with polar coordinates
# at 2Pi/n increments.
angleList = [((step)*i)+step/2 for i in range(n)]
pts.append(pt)
pol.append(addPolygon(pt,n)[0])
ptNew = pt
for i in range(it):
  rdAngle = rd.choice(angleList)
  polygon = addPolygon(ptNew,n)
```

```
pol.append(polygon[0])
    #print pol

ptNew = rs.Polar(ptNew,rdAngle,polygon[1]*2)
    pts.append(ptNew)

print pol
pol = rg.Brep.CreatePlanarBreps(pol)
```