

Computeranimation

Appendix A – Meshes





Surface Representations

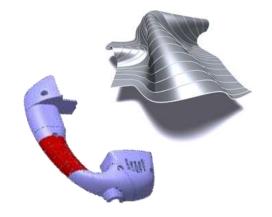
Why do we need surfaces at all

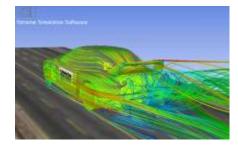
- Design (CAD)
- Rendering
- Simulation
- Documentation Preservation
- Quality Control
- Custom Fitting











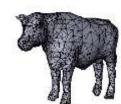


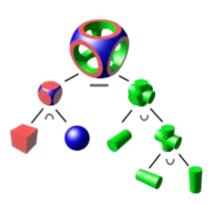


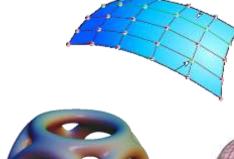
Surface Representations

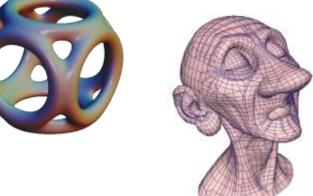
Description of Objects' Surfaces

- Polygonal Meshes
- Parametric Surfaces
- Implicit Surfaces
- Constructive Solid Geometry
- Subdivision Surfaces









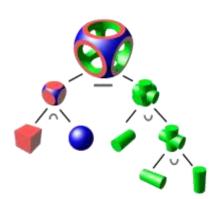


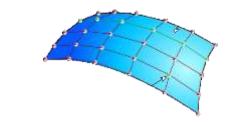


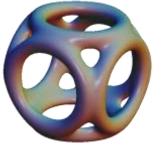
Surface Representations

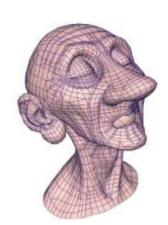
Description of Objects' Surfaces

- Polygonal Meshes ← in this course
- Parametric Surfaces
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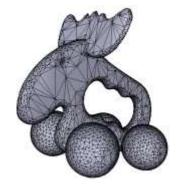


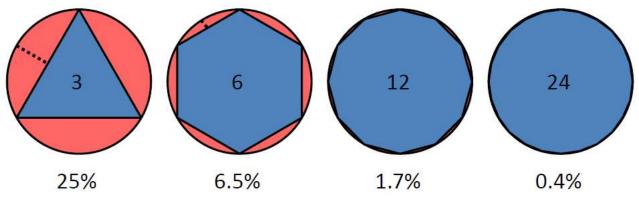




Piecewise Linear Approximation

- Error **O**(h²)







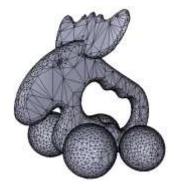


Polygonal Meshes are Good!

- Approximation O(h²)
- Arbitrary Topology
- Piecewise smooth Surfaces
- Adaptive Refinement
- Efficient Rendering



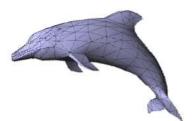








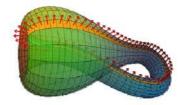
Mesh Zoo



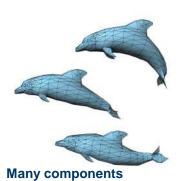
Single component closed, triangular, orientable manifold

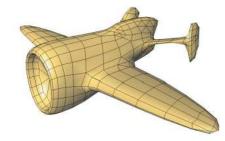


With boundaries

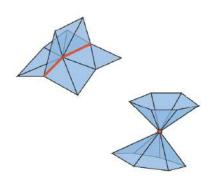


Non-orientable





Triangles and Quads



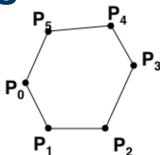
Non-manifold





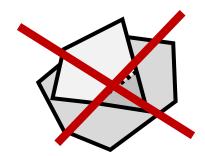
Polygon

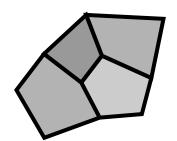
Ordered set of vertices



Polygon mesh

Collection of Polygons satisfying certain restrictions









Most Often Used Polygonal Meshes in Computer Graphics

- Triangle meshes
- Quad meshes

Topology vs. Geometry

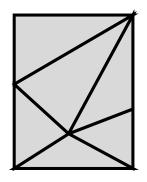
- **Geometry**: The shape of an object: Basically the vertex position
- **Topology**: connectivity / neighbourhood relation

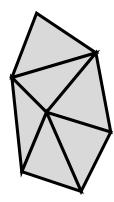




Topologically Equivalent

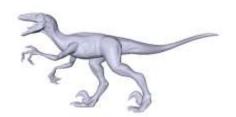
Mesh only differs in vertex Positions

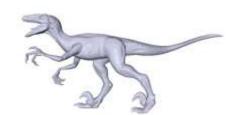




Geometrically (almost) equivalent

- Same shape, different connectivity of mesh-elements



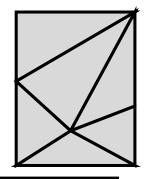


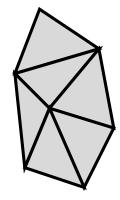




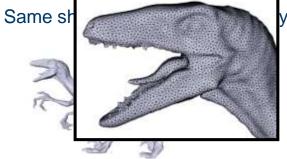
Topologically Equivalent

Mesh only differs in vertex Positions

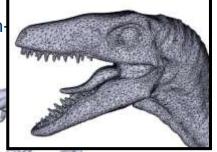




Geometrica







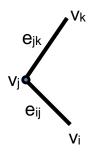


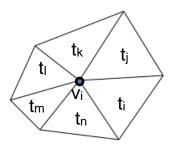


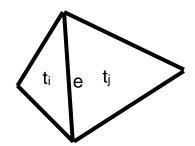
Triangle Meshes

Definition: A triangulation of a set of points consists of:

- Vertices v_i , $\{v_i, i=1,...,N\} \subseteq \Re^3$
- Edges $\subseteq \{v_i v_j, 1 \le i, j \le N\}$
- Triangles $\subseteq \{\Delta(v_i v_i v_k), 1 \le i, j, k \le N\}$
- The triangulation can also have attributes (normals, texture-coordinates, etc...)
- Edges sharing a vertex called adjacent
- Triangles sharing a vertex or an edge are called adjacent







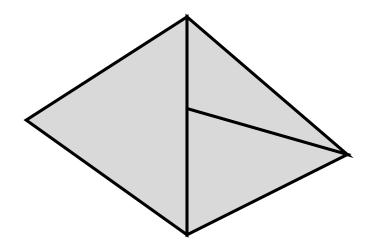


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Triangle Meshes

Is this a valid Triangle Mesh?

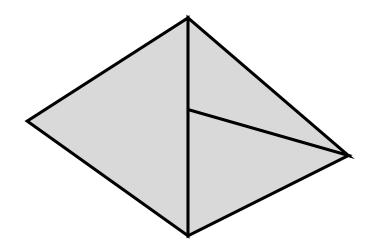


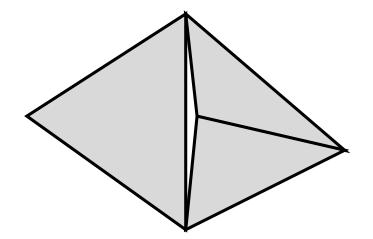




Triangle Meshes

Is this a valid Triangle Mesh?









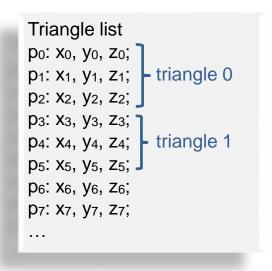
How to represent Triangulations

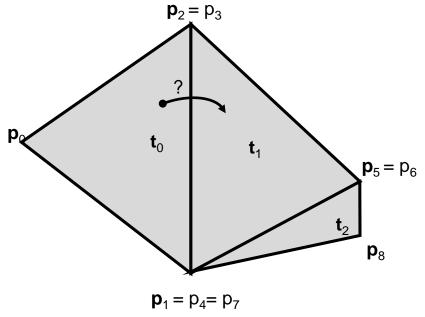
- Considerations: Rendering, Memory usage, complexity of queries
- There is no perfect data structure just a trade off
- Triangle list
- Shared Vertex Structure
- There are many more...





Triangle List









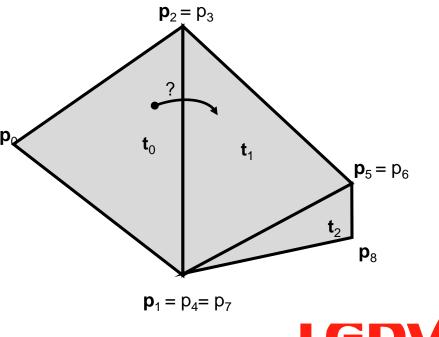
Triangle List

Pros:

- Trivial
- Easy Triangle Removal
- Easy to render

Cons:

- No neighbourhood info (hard to traverse)
- Duplicate Points (waste of storage)



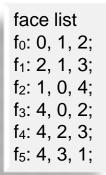
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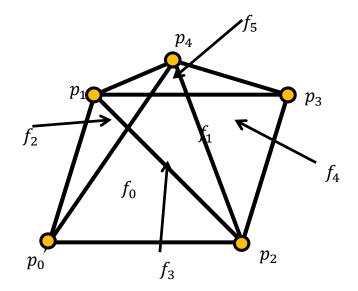


Shared Vertex Data Structure

- Also called "indexed face set"
- Consists of two lists

vertex list po: Xo, yo, Zo; p1: X1, Y1, Z1; p2: X2, Y2, Z2; p3: X3, Y3, Z3; p4: X4, Y4, Z4;









Shared Vertex Data Structure

- Remark: geometric queries are difficult
- Extend face list by reference to neighbour faces

vertex list

Po: Xo, yo, Zo;

P1: X1, Y1, Z1;

p₂: x₂, y₂, z₂;

p₃: x₃, y₃, z₃;

P4: X4, Y4, Z4;

Extended face list

f₀: 0, 1, 2; 1, 3, 2

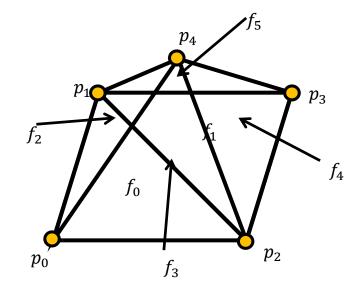
 f_1 : 2, 1, 3; 5, 4, 3

f₂: 1, 0, 4; ...

f₃: 4, 0, 2; ...

f₄: 4, 2, 3; ...

f₅: 4, 3, 1; ...







Shared Vertex Data Structure

Pros:

- Easy
- Gold standard for mesh file formats (obj, off)
- Neighbourhood queries cheap (extended version)
- Low storage cost (each vertex stored once)
- Works for Tri/Quad/Poly/Mixed meshes

Cons:

- Neighbourhood queries expensive (non-extended version)
- High Storage cost (extended version)

