

Python For Data Science Cheat Sheet

SciPy - Linear Algebra

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SciPy

The **SciPy** library is one of the core packages for scientific computing that provides mathematical algorithms and convenience functions built on the NumPy extension of Python.



Interacting With NumPy

Also see NumPy

```
>>> import numpy as np
>>> a = np.array([1,2,3])
>>> b = np.array([(1+5j,2j,3j), (4j,5j,6j)])
>>> c = np.array([(1.5,2,3), (4,5,6)], [(3,2,1), (4,5,6)])
```

Index Tricks

<pre>>>> np.mgrid[0:5,0:5] >>> np.ogrid[0:2,0:2] >>> np.r_[3,[0]*5,-1:10j] >>> np.c_[b,c]</pre>	Create a dense meshgrid Create an open meshgrid Stack arrays vertically (row-wise) Create stacked column-wise arrays
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Shape Manipulation

<pre>>>> np.transpose(b) >>> b.flatten() >>> np.hstack((b,c)) >>> np.vstack((a,b)) >>> np.hsplit(c,2) >>> np.vsplit(d,2)</pre>	Permute array dimensions Flatten the array Stack arrays horizontally (column-wise) Stack arrays vertically (row-wise) Split the array horizontally at the 2nd index Split the array vertically at the 2nd index
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Polynomials

<pre>>>> from numpy import polyld >>> p = polyld([3,4,5])</pre>	Create a polynomial object
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Vectorizing Functions

<pre>>>> def myfunc(a): if a < 0: return a*2 else: return a/2 >>> np.vectorize(myfunc)</pre>	Vectorize functions
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Type Handling

<pre>>>> np.real(b) >>> np.imag(b) >>> np.real_if_close(c,tol=1000) >>> np.cast['f'](np.pi)</pre>	Return the real part of the array elements Return the imaginary part of the array elements Return a real array if complex parts close to 0 Cast object to a data type
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Other Useful Functions

<pre>>>> np.angle(b,deg=True) >>> g = np.linspace(0,np.pi,num=5) >>> g[3:] += np.pi >>> np.unwrap(g) >>> np.logspace(0,10,3) >>> np.select([c<4],[c*2]) >>> misc.factorial(a) >>> misc.comb(10,3,exact=True) >>> misc.central_diff_weights(3) >>> misc.derivative(myfunc,1,0)</pre>	Return the angle of the complex argument Create an array of evenly spaced values (number of samples) Unwrap Create an array of evenly spaced values (log scale) Return values from a list of arrays depending on conditions Factorial Combine N things taken at k time Weights for Np-point central derivative Find the n-th derivative of a function at a point
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Linear Algebra

You'll use the `linalg` and `sparse` modules. Note that `scipy.linalg` contains and expands on `numpy.linalg`.

```
>>> from scipy import linalg, sparse
```

Creating Matrices

```
>>> A = np.matrix(np.random.random((2,2)))
>>> B = np.asmatrix(b)
>>> C = np.mat(np.random.random((10,5)))
>>> D = np.mat([[3,4], [5,6]])
```

Basic Matrix Routines

Inverse

<pre>>>> A.I >>> linalg.inv(A)</pre>	Inverse Inverse
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Transposition

<pre>>>> A.T >>> A.H</pre>	Tranpose matrix Conjugate transposition
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Trace

<pre>>>> np.trace(A)</pre>	Trace
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Norm

<pre>>>> linalg.norm(A) >>> linalg.norm(A,1) >>> linalg.norm(A,np.inf)</pre>	Frobenius norm L1 norm (max column sum) L inf norm (max row sum)
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Rank

<pre>>>> np.linalg.matrix_rank(C)</pre>	Matrix rank
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Determinant

<pre>>>> linalg.det(A)</pre>	Determinant
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Solving linear problems

<pre>>>> linalg.solve(A,b) >>> E = np.mat(a).T >>> linalg.lstsq(F,E)</pre>	Solver for dense matrices Solver for dense matrices Least-squares solution to linear matrix equation
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Generalized inverse

<pre>>>> linalg.pinv(C) >>> linalg.pinv2(C)</pre>	Compute the pseudo-inverse of a matrix (least-squares solver) Compute the pseudo-inverse of a matrix (SVD)
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Creating Sparse Matrices

<pre>>>> F = np.eye(3, k=1) >>> G = np.mat(np.identity(2)) >>> C[C > 0.5] = 0 >>> H = sparse.csr_matrix(C) >>> I = sparse.csc_matrix(D) >>> J = sparse.dok_matrix(A) >>> E.todense() >>> sparse.isspmatrix_csc(A)</pre>	Create a 2X2 identity matrix Create a 2x2 identity matrix Compressed Sparse Row matrix Compressed Sparse Column matrix Dictionary Of Keys matrix Sparse matrix to full matrix Identify sparse matrix
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Sparse Matrix Routines

Inverse

<pre>>>> sparse.linalg.inv(I)</pre>	Inverse
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Norm

<pre>>>> sparse.linalg.norm(I)</pre>	Norm
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Solving linear problems

<pre>>>> sparse.linalg.spsolve(H,I)</pre>	Solver for sparse matrices
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Sparse Matrix Functions

<pre>>>> sparse.linalg.expm(I)</pre>	Sparse matrix exponential
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Asking For Help

```
>>> help(scipy.linalg.diagsvd)
>>> np.info(np.matrix)
```

Also see NumPy

Matrix Functions

Addition

<pre>>>> np.add(A,D)</pre>	Addition
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Subtraction

<pre>>>> np.subtract(A,D)</pre>	Subtraction
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Division

<pre>>>> np.divide(A,D)</pre>	Division
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Multiplication

<pre>>>> A @ D >>> np.multiply(D,A) >>> np.dot(A,D) >>> np.vdot(A,D) >>> np.inner(A,D) >>> np.outer(A,D) >>> np.tensordot(A,D) >>> np.kron(A,D)</pre>	Multiplication operator (Python 3) Multiplication Dot product Vector dot product Inner product Outer product Tensor dot product Kronecker product
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Exponential Functions

<pre>>>> linalg.expm(A) >>> linalg.expm2(A) >>> linalg.expm3(D)</pre>	Matrix exponential Matrix exponential (Taylor Series) Matrix exponential (eigenvalue decomposition)
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Logarithm Function

<pre>>>> linalg.logm(A)</pre>	Matrix logarithm
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Trigonometric Functions

<pre>>>> linalg.sinm(D) >>> linalg.cosm(D) >>> linalg.tanm(A)</pre>	Matrix sine Matrix cosine Matrix tangent
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Hyperbolic Trigonometric Functions

<pre>>>> linalg.sinhm(D) >>> linalg.coshm(D) >>> linalg.tanhm(A)</pre>	Hypperbolic matrix sine Hyperbolic matrix cosine Hyperbolic matrix tangent
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Matrix Sign Function

<pre>>>> np.signm(A)</pre>	Matrix sign function
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Matrix Square Root

<pre>>>> linalg.sqrtm(A)</pre>	Matrix square root
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Arbitrary Functions

<pre>>>> linalg.funm(A, lambda x: x*x)</pre>	Evaluate matrix function
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Decompositions

Eigenvalues and Eigenvectors

<pre>>>> la, v = linalg.eig(A) >>> l1, l2 = la >>> v[:,0] >>> v[:,1] >>> linalg.eigvals(A)</pre>	Solve ordinary or generalized eigenvalue problem for square matrix Unpack eigenvalues First eigenvector Second eigenvector Unpack eigenvalues
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Singular Value Decomposition

<pre>>>> U,S,Vh = linalg.svd(B) >>> M,N = B.shape >>> Sig = linalg.diagsvd(s,M,N)</pre>	Singular Value Decomposition (SVD) Construct sigma matrix in SVD
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LU Decomposition

<pre>>>> P,L,U = linalg.lu(C)</pre>	LU Decomposition
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Sparse Matrix Decompositions

<pre>>>> la, v = sparse.linalg.eigs(F,1) >>> sparse.linalg.svds(H, 2)</pre>	Eigenvalues and eigenvectors SVD
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