

Problems of Analysis of Nonlinear Control Systems

Part I: Describing Function method

7.3 Calculate the describing functions $N(X)$ of nonlinearities as shown in Fig. 7.E.2, and sketch the plots of $N(X)$ and $-1/N(X)$.

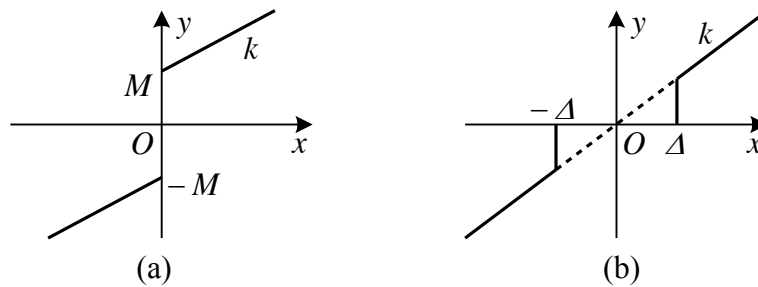


Fig. 7.E.2 Nonlinearity in Problem 7.3

7.5 Given a nonlinear system as shown in Fig. 7.E.3, where $K > 0$. Solve the following problems with describing function method:

- (1) To discuss the motion of the system when $K = 5$;
- (2) To analyze the frequency and amplitude of the sustained oscillation in the output $c(t)$ when $K = 5$.

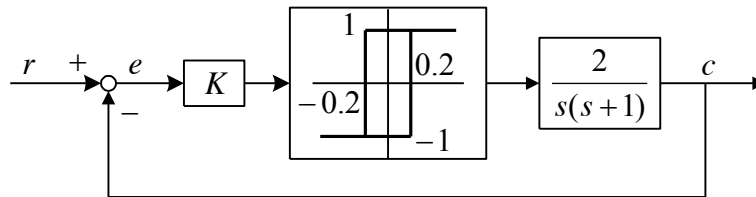


Fig. 7.E.3 The system of Problem 7.5

7.6 Given a system as shown in Fig. 7.E.4, where $K > 0$, $k = 1$. Solve the following problems with the describing function method:

- (1) To discuss the motion of the system when $K = 5$;
- (2) To analyze the frequency and amplitude of the sustained oscillation in the output $c(t)$ when $K = 5$.
- (3) Determine the stability boundary of gain K .

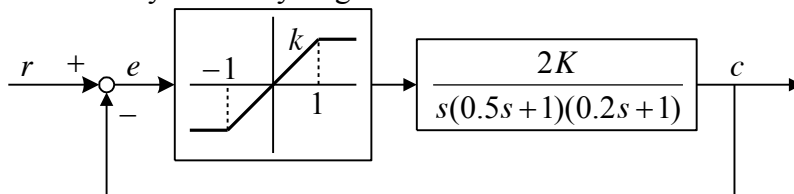
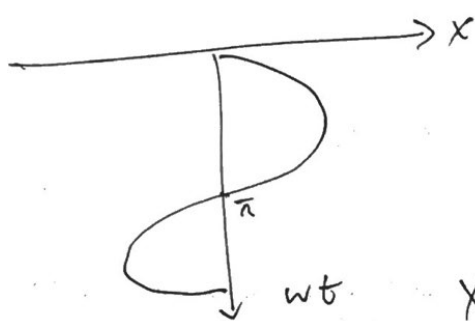
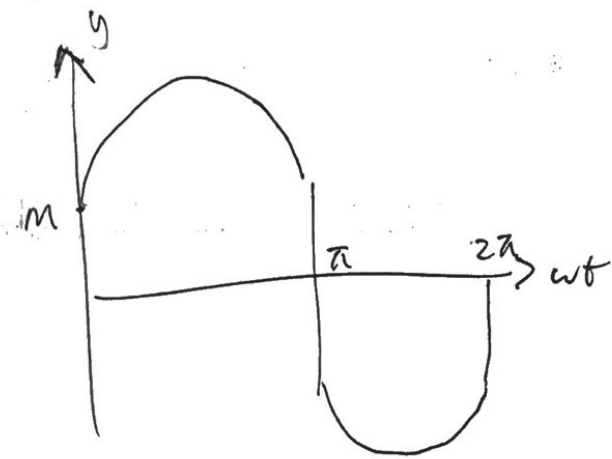
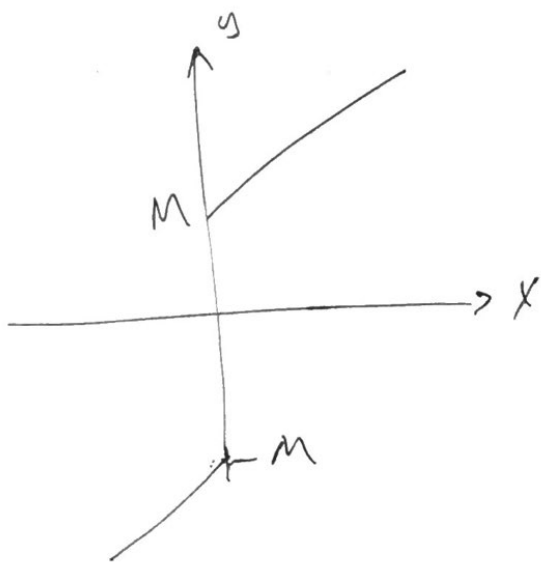


Fig. 7.E.4 The system of Problem 7.6

Q7.3 (a)



$$y = \begin{cases} M + kX & x \geq 0 \\ -M - kX & x < 0 \end{cases}$$

$$X(t) = X \sin wt$$

$$y(t) = M + kX \sin wt$$

Odd function

$$B_1 = \frac{1}{\pi} \int_0^{2\pi} y(t) \sin wt \, dt$$

$$= \frac{4}{\pi} \int_0^{\pi/2} (M + kX \sin wt) \sin wt \, dt$$

$$= \frac{4}{\pi} (M + kX) \left[-\cos wt \right]_0^{\pi/2}$$

$$= \frac{4}{\pi} \int_0^{\pi/2} (M \sin wt + kX \sin^2 wt) \, dt$$

$$= \frac{4}{\pi} \left\{ \left[-M \cos wt \right]_0^{\pi/2} + kX \left[\frac{1}{2} wt - \frac{1}{4} \sin 2wt \right]_0^{\pi/2} \right\}$$

$$= \frac{4}{\pi} \left[-M \cos wt \right]_0^{\pi/2} + \frac{2kX}{\pi} \left[wt - \sin wt \cos wt \right]_0^{\pi/2}$$

$$B_1 = \frac{4}{\pi} M + \frac{\cancel{2kX}}{\cancel{\pi}} \left(\frac{\pi}{2} \right)$$

$$= \frac{4M}{\pi} + kX$$

$$N = \frac{B_1}{X} = \frac{4M}{\pi X} + k //$$

$N(x)$ only has real parts

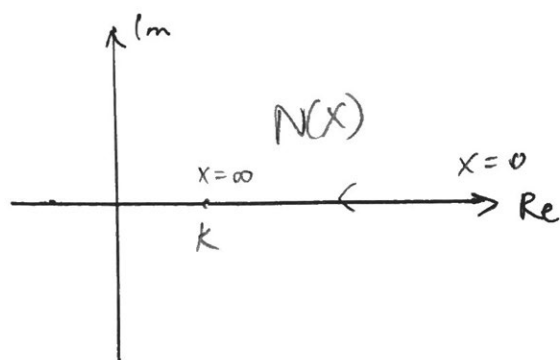
$$N(x) = \frac{4M}{\pi X} + k$$

$$\lim_{X \rightarrow 0} N(x) = \infty$$

$$\lim_{X \rightarrow \infty} N(x) = k$$

$$N(x) = k$$

$$\cancel{N(x)}_{x=}$$

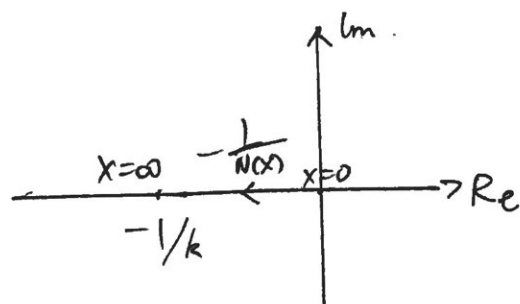


$$-\frac{1}{N(x)} = -\frac{\pi X}{4M + k\pi X}$$

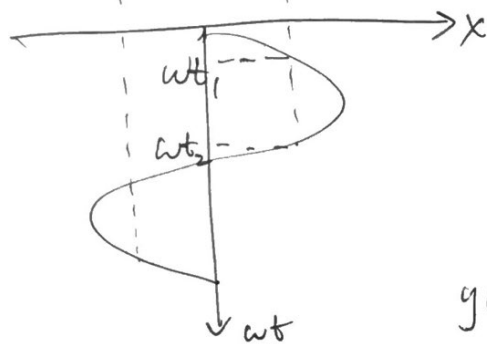
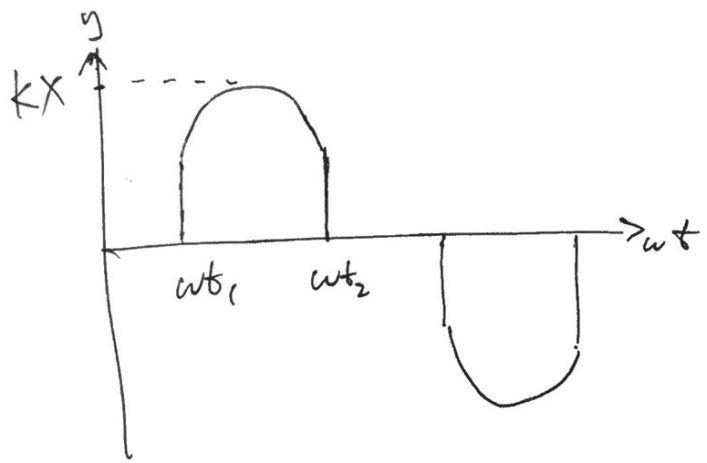
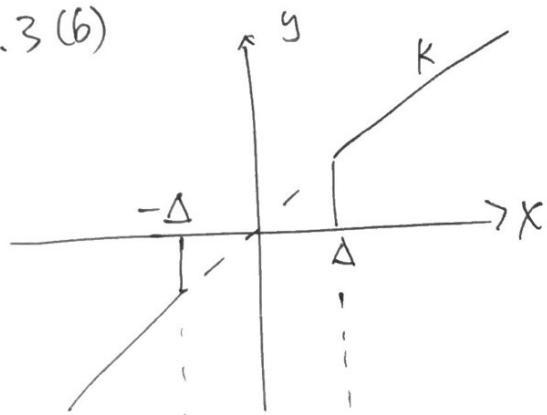
$$\lim_{X \rightarrow 0} -\frac{1}{N(x)} = 0$$

$$\lim_{X \rightarrow \infty} -\frac{1}{N(x)} = -\frac{1}{k}$$

$$= -\frac{1}{k}$$



Q7.3 (b)



$$y = \begin{cases} kx & x \geq \Delta \\ 0 & -\Delta \leq x < \Delta \\ kx & x < -\Delta \end{cases}$$

$$y(t) = \begin{cases} k X \sin \omega t & \\ 0 & \\ k X \sin \omega t & \end{cases}$$

$$x(t) = X \sin \omega t$$

$$\Delta = X \sin \omega t_1$$

$$\omega t_1 = \sin^{-1} \frac{\Delta}{X}$$

Odd function

$$B_1 = \frac{1}{\pi} \int_0^{2\pi} y(t) \sin \omega t \, d\omega t$$

$$= \frac{4}{\pi} \int_{\omega t_1}^{\frac{\pi}{2}} k X \sin \omega t \sin \omega t \, d\omega t$$

$$= \frac{4kX}{\pi} \int_{\omega t_1}^{\frac{\pi}{2}} \left[\frac{1}{2} \omega t - \frac{1}{4} \sin 2\omega t \right]_{\omega t_1}^{\frac{\pi}{2}}$$

$$= \frac{2kX}{\pi} \left[\omega t - \sin \omega t \cos \omega t \right]_{\omega t_1}^{\frac{\pi}{2}}$$

$$= \frac{2kX}{\pi} \left(\frac{\pi}{2} - \omega t_1 + \sin \omega t_1 \cos \omega t_1 \right)$$

$$= \frac{2kX}{\pi} \left(\frac{\pi}{2} - \sin^{-1} \frac{\Delta}{X} + \sin \left(\sin^{-1} \frac{\Delta}{X} \right) \cos \left(\sin^{-1} \frac{\Delta}{X} \right) \right)$$

$$= kX + \frac{2kX}{\pi} \left(-\sin^{-1} \frac{\Delta}{X} + \frac{\Delta}{X} \sqrt{1 - \left(\frac{\Delta}{X} \right)^2} \right)$$

$$N = \frac{B_1}{X} = k + \frac{2k}{\pi} \left(-\sin^{-1} \frac{\Delta}{X} + \frac{\Delta}{X} \sqrt{1 - \left(\frac{\Delta}{X} \right)^2} \right)$$

Q 7.3 (b)

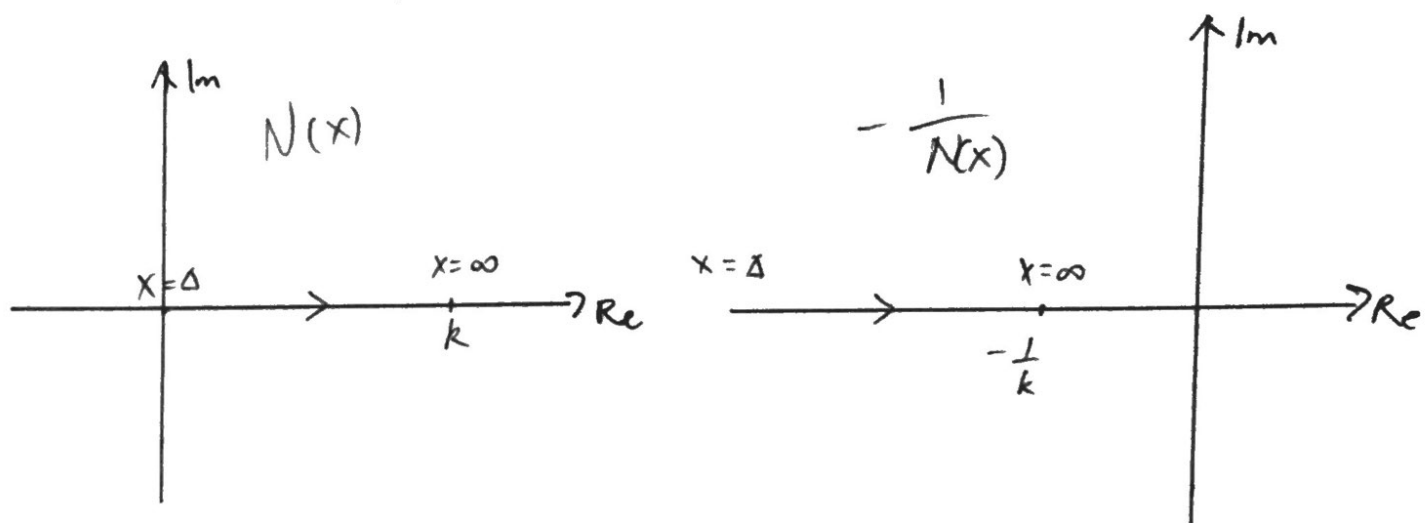
$$N(x) = k + \frac{2k}{\pi} \left(-\sin^{-1} \frac{\Delta}{x} + \frac{\Delta}{x} \sqrt{1 - \left(\frac{\Delta}{x}\right)^2} \right)$$

$$\lim_{x \rightarrow \Delta} N(x) = k + \frac{2k}{\pi} \left(-\frac{\pi}{2} \right) = 0$$

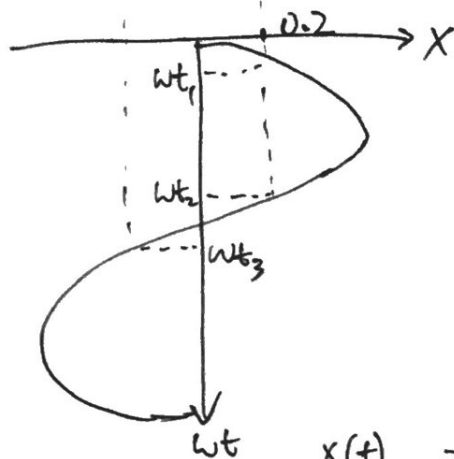
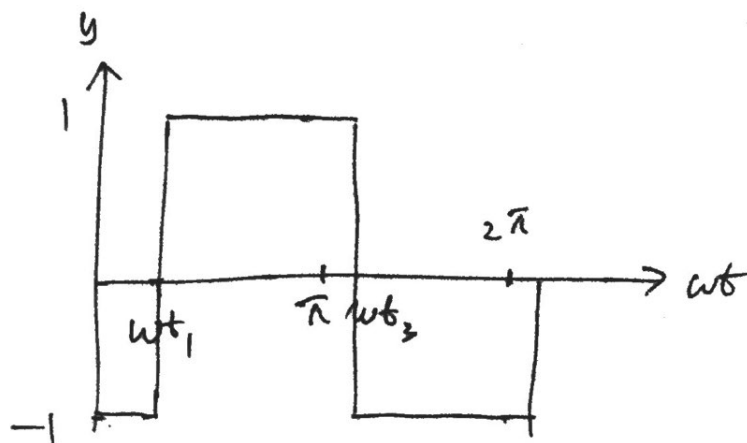
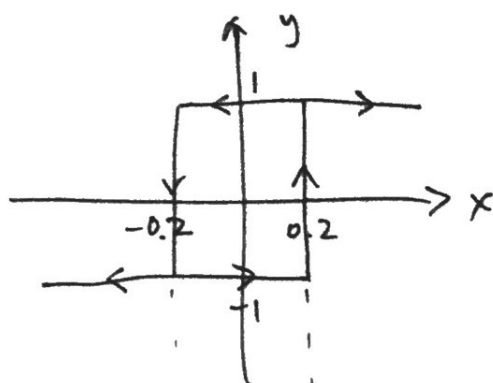
$$\lim_{x \rightarrow \infty} N(x) = k + \frac{2k}{\pi} (0) = k$$

$$\lim_{x \rightarrow \Delta} -\frac{1}{N(x)} = -\infty$$

$$\lim_{x \rightarrow \infty} -\frac{1}{N(x)} = -\frac{1}{k}$$



Q7.5



$$y = \begin{cases} 1 & x \geq 0.2 \\ -1 & x < 0.2 \end{cases} \quad \dot{x} > 0$$

$$y = \begin{cases} 1 & x \geq -0.2 \\ -1 & x < -0.2 \end{cases} \quad \dot{x} < 0$$

$$x(t) = X \sin wt$$

$$wt_1 = \sin^{-1} \frac{0.2}{X}$$

$$A_1 = \frac{1}{\pi} \int_0^{2\pi} y(t) \cos(wt) dt$$

$$= \frac{2}{\pi} \int_0^{\pi} y(t) \cos(wt) dt$$

$$= \frac{2}{\pi} \int_{wt_1}^{\pi} \cos(wt) dt - \frac{2}{\pi} \int_0^{wt_1} \cos(wt) dt$$

$$= \frac{2}{\pi} \left[\sin wt \right]_{wt_1}^{\pi} - \frac{2}{\pi} \left[\sin wt \right]_0^{wt_1}$$

$$= \frac{4}{\pi} \left(-\sin \sin^{-1} \frac{0.2}{X} \right)$$

$$= -\frac{4}{\pi} \frac{0.2}{X}$$

$$= -\frac{0.8}{X\pi}$$

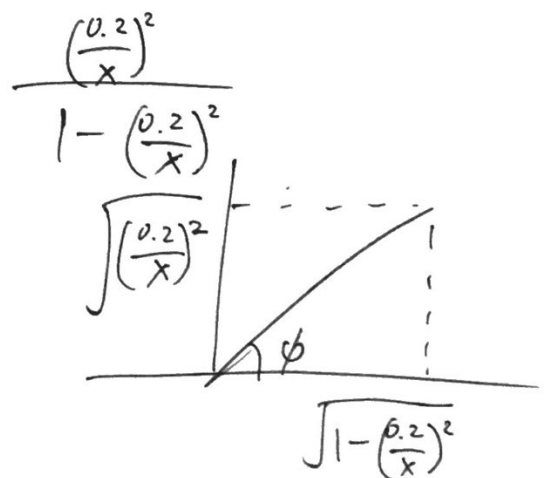
$$\begin{aligned}
 B_1 &= \frac{1}{\pi} \int_0^{2\pi} y(t) \sin(\omega t) dt \\
 &= \frac{2}{\pi} \int_{\omega t_1}^{\pi} \sin(\omega t) dt - \frac{2}{\pi} \int_0^{\omega t_1} \sin(\omega t) dt \\
 &= \frac{2}{\pi} \left[-\cos \omega t \right]_{\omega t_1}^{\pi} + \frac{2}{\pi} \left[\cos \omega t \right]_0^{\omega t_1} \\
 &= \frac{2}{\pi} (1 + \cos \omega t_1) + \frac{2}{\pi} (\cos \omega t_1 - 1) \\
 &= \frac{2}{\pi} \left[1 + \cos \left(\sin^{-1} \frac{0.2}{x} \right) \right] \\
 &= \frac{4}{\pi} \cos \left(\sin^{-1} \frac{0.2}{x} \right) \\
 &= \frac{4}{\pi} \sqrt{1 - \left(\frac{0.2}{x} \right)^2}
 \end{aligned}$$

$$N(x) = B_1 + A_1 j$$

$$\begin{aligned}
 |N(x)| &= \sqrt{B_1^2 + A_1^2} \\
 &= \sqrt{\left(\frac{4}{\pi} \right)^2 \left(1 - \left(\frac{0.2}{x} \right)^2 \right) + \left(\frac{4}{\pi} \right)^2 \left(\frac{0.2}{x} \right)^2} \\
 &= \frac{4}{\pi}
 \end{aligned}$$

$$\begin{aligned}
 \phi &= \tan^{-1} \frac{A_1}{B_1} \\
 &= \tan^{-1} \frac{-\frac{4}{\pi} \frac{0.2}{x}}{\frac{4}{\pi} \sqrt{1 - \left(\frac{0.2}{x} \right)^2}} \\
 &= -\sin^{-1} \frac{0.2}{x}
 \end{aligned}$$

$$N(x) = \frac{4}{\pi x} e^{-j \sin^{-1} \frac{0.2}{x}} \quad // \quad x > 0.2$$



$$Q7.5(1) \quad N(x) G_p(j\omega) = \frac{4}{\pi X} e^{-j\left(\sin^{-1} \frac{0.2}{X}\right)} \frac{2K}{(j\omega)(j\omega+1)}$$

$$|N(x) G_p(j\omega)| = 1 \quad \angle N(x) G_p(j\omega) = -\pi$$

$$|N(x) G_p(j\omega)| = \frac{8K}{\pi X} \left| \frac{1}{-\omega^2 + j\omega} \right|$$

$$1 = \frac{8K}{\pi X} \frac{1}{\omega \sqrt{1+\omega^2}}$$

$$K = \frac{\pi X}{8} \omega \sqrt{1+\omega^2}$$

$$\angle N(x) G_p(j\omega) = -\sin^{-1} \frac{0.2}{X} - \frac{\pi}{2} - \tan^{-1} \omega$$

$$-\pi = -\sin^{-1} \frac{0.2}{X} - \frac{\pi}{2} - \frac{\pi}{2} + \tan^{-1} \frac{1}{\omega}$$

$$\sin^{-1} \frac{0.2}{X} = \tan^{-1} \frac{1}{\omega}$$

$$\sqrt{1+\omega^2} = 5X$$

$$X = \frac{\sqrt{1+\omega^2}}{5}$$

$$Q7.5(2) \quad K = \frac{\pi}{8} \frac{\sqrt{1+\omega^2}}{5} \omega \sqrt{1+\omega^2}$$

$$K=5 \quad 5 = \frac{\pi \omega (1+\omega^2)}{40}$$

$$\frac{200}{\pi} = \omega (1+\omega^2)$$

$$0 = \omega^3 + \omega - \frac{200}{\pi}$$

$$\omega = 3.909 //$$

$$X = \frac{\sqrt{1+\omega^2}}{5}$$

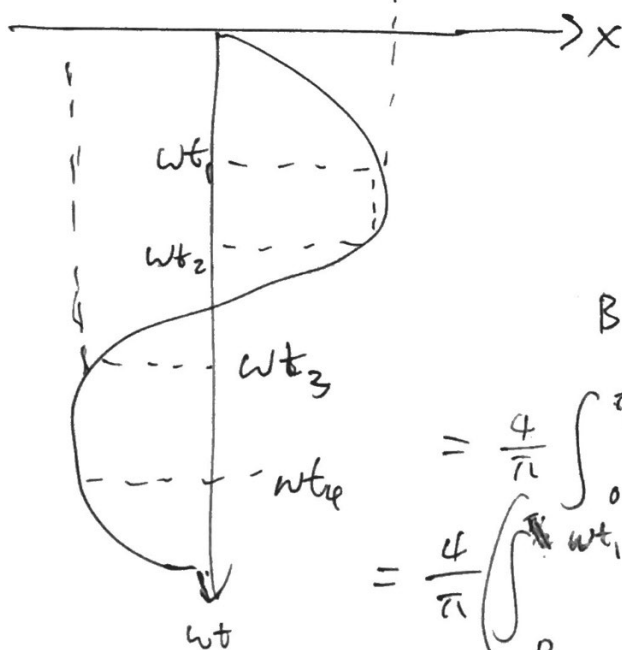
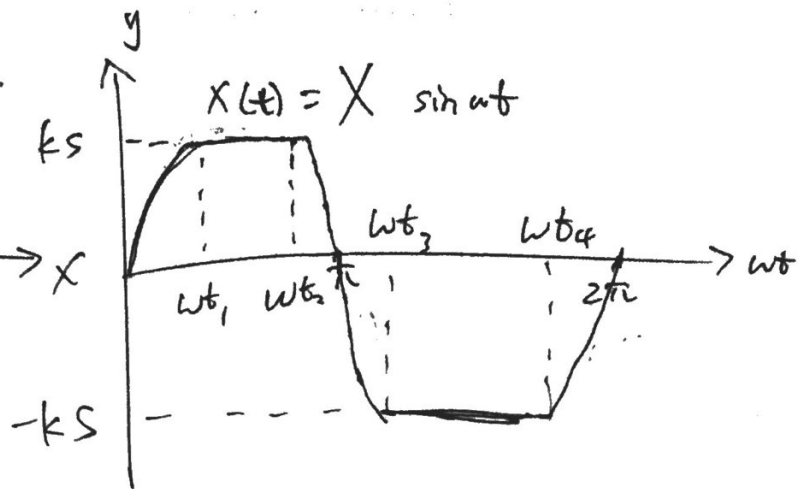
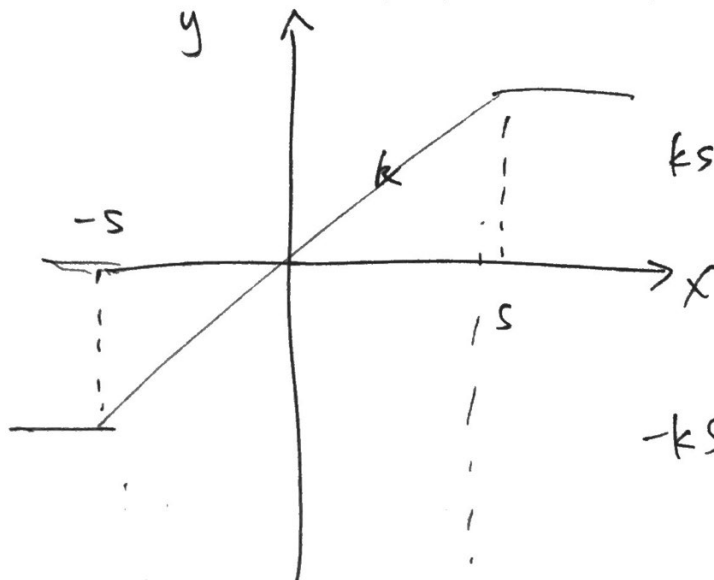
$$= 0.807 //$$

$$C = \frac{X}{K} = 0.16 //$$

sustained
oscillation //

Q7.6

$$y = \begin{cases} kx & x > s \\ kx & -s \leq x \leq s \\ -kx & -s > x \end{cases}$$



$$x(t) = X \sin \omega t$$

$$X \sin \omega t_1 = s$$

$$\omega t_1 = \sin^{-1} \frac{s}{X}$$

$$B_1 = \frac{1}{\pi} \int_0^{2\pi} y(t) \sin(\omega t) d(\omega t)$$

$$= \frac{4}{\pi} \int_0^{\pi/2} y(t) \sin \omega t d\omega t$$

$$= \frac{4}{\pi} \left(\int_0^{\omega t_1} (kX \sin^2 \omega t) d\omega t + \int_{\omega t_1}^{\pi/2} (ks \sin \omega t) d\omega t \right)$$

$$= \frac{4k}{\pi} \left\{ \left[X \left(\frac{1}{2} \omega t - \frac{1}{4} \sin 2\omega t \right) \right]_0^{\omega t_1} - \left[s \cos \omega t \right]_{\omega t_1}^{\pi/2} \right\}$$

$$= \frac{4k}{\pi} \left\{ \frac{X \omega t_1}{2} - \frac{X}{4} \sin 2\omega t_1 + s \cos \omega t_1 \right\}$$

$$= \frac{k}{\pi} (2X \omega t_1 - X \sin 2\omega t_1 + 4s \cos \omega t_1)$$

$$= \frac{k}{\pi} \left(2X \sin^{-1} \frac{s}{X} - X \sin 2 \sin^{-1} \frac{s}{X} + 4s \cos \sin^{-1} \frac{s}{X} \right)$$

$$= \frac{k}{\pi} (2X \omega t_1 - 2X \sin \omega t_1 \cos \omega t_1 + 4s \cos \omega t_1)$$

$$= \frac{2k}{\pi} (X \omega t_1 - X \sin \omega t_1 \cos \omega t_1 + 2s \cos \omega t_1)$$

$$= \frac{2k}{\pi} \left(X \sin^{-1} \frac{s}{X} - X \frac{s}{X} \cos \sin^{-1} \frac{s}{X} + 2s \cos \sin^{-1} \frac{s}{X} \right)$$

$$= \frac{2kX}{\pi} \left(\sin^{-1} \frac{s}{X} + \frac{s}{X} \sqrt{1 - \left(\frac{s}{X}\right)^2} \right)$$

$$N = \frac{B_1}{X} = \frac{2k}{\pi} \left(\sin^{-1} \frac{s}{X} + \frac{s}{X} \sqrt{1 - \left(\frac{s}{X}\right)^2} \right)$$

$$N(X) = \frac{2}{\pi} \left(\sin^{-1} \frac{1}{X} + \frac{1}{X} \sqrt{1 - \left(\frac{1}{X}\right)^2} \right) //$$

Q 7.6 (1)

$$N(X) G_p(j\omega) = \frac{4K}{\pi} \left(\sin^{-1} \frac{1}{X} + \frac{1}{X} \sqrt{1 - \left(\frac{1}{X}\right)^2} \right) \frac{1}{(j\omega)(0.5j\omega + 1)(0.2j\omega + 1)}$$

$$|N(X) G_p(j\omega)| = \frac{4K}{\pi} \left(\sin^{-1} \frac{1}{X} + \frac{1}{X} \sqrt{1 - \left(\frac{1}{X}\right)^2} \right) \frac{1}{\omega \sqrt{1 + 0.25\omega^2} \sqrt{1 + 0.04\omega^2}}$$

~~Hz~~

$$\angle N(X) G_p(j\omega) = -\frac{\pi}{2} - \tan^{-1} 0.5\omega - \tan^{-1} 0.2\omega$$

$$\frac{\pi}{2} = \tan^{-1} 0.5\omega + \tan^{-1} 0.2\omega$$

$$\omega = 3.16 //$$

Q 7.6 (2)

$$K = 5$$

$$1 = \frac{20}{\pi} \left(\sin^{-1} \frac{1}{X} + \frac{1}{X} \sqrt{1 - \left(\frac{1}{X}\right)^2} \right) (0.1429)$$

$$\frac{\pi}{20 \times 0.1429} = \sin^{-1} \frac{1}{X} + \frac{1}{X} \sqrt{1 - \left(\frac{1}{X}\right)^2}$$

$$X = 1.71 //$$

$$C = 1.71 //$$

Q 7.6 (3)

$$\lim_{x \rightarrow 1} \sin^{-1} \frac{1}{x} + \frac{1}{x} \sqrt{1 - \left(\frac{1}{x}\right)^2} =$$

$$\begin{aligned} \lim_{x \rightarrow 1} N(x) &= \frac{2}{\pi} \left(\sin^{-1} \frac{1}{x} + \frac{1}{x} \sqrt{1 - \left(\frac{1}{x}\right)^2} \right) \\ &= \frac{2}{\pi} \cdot \frac{\pi}{2} \\ &= 1 \end{aligned}$$

$$\lim_{x \rightarrow 1} -\frac{1}{N(x)} = -1$$

$$\sin^{-1} \frac{1}{x} + \frac{1}{x} \sqrt{1 - \left(\frac{1}{x}\right)^2} = \frac{5.496}{k}$$

$$\frac{5.496}{k} < \frac{\pi}{2}$$

$$k > 3.50$$