

MA20104 Probability & Statistics

Summary of lectures in the first week.

(Instructor: Swanand Khare)

Random Experiment: (R)

An experiment whose outcomes are not deterministic (fixed) is called a random experiment.

There are a lot of real life examples of the random experiments which lead to the development of probability theory.

(Various examples of random experiment are discussed in the class).

Sample space: (S) Set of all possible outcomes of a random experiment.

Event: Any subset of the sample space.

The objective is to be able to assign probabilities to outcomes/events of a random experiment.

Types of sample spaces:

Ω : 1) discrete / denumerable / countable

2) Continuous

3) mixed

Probability assignment:

Case 1 : The case of equally likely outcomes
(relative frequency approach).

- Conduct Define random experiment. (R)
- List all possible outcomes (Ω) and make sure that all outcomes are equally likely.
- Event E is collection of favourable outcomes.

Then $P(E) = \frac{\text{no. of favourable outcomes}}{\text{total no. of outcomes}}$

$$P(E) = \frac{\# E}{\# \Omega}$$

Examples: Tossing a fair coin, Rolling a fair die etc.

Case 2: The case when the outcomes in a sample space may NOT be equally likely.

Let the sample space be finite.

In this case, we can repeat the random experiment (R) 'n' number of times. Then count how many number of times a particular outcome appears. Then the ratio of $\frac{n_f}{n}$ is a very good 'estimate' of the probability of occurrence of that particular outcome.

Simulation exercise: Simulate the scenario of throwing a fair die in a computer. Then for various values of $n = 10, 50, 100, 1000, 10000, \dots$ compute estimates of $P(\{1\}), P(\{3\})$. How does the "quality" of these estimates change with varying n ? We will revisit this example again in greater details in the later part of this course.

In this case, let $\Omega = \{S_1, S_2, \dots, S_k\}$. Then using the procedure described above, we can assign probabilities to the outcomes S_1, S_2, \dots, S_k looking at the estimates. However, intuitively we would follow following rules in this probability assignment.

$$P(\Omega) = P(S_1) + P(S_2) + \dots + P(S_k) = 1.$$

Further, we would expect that $P(\{S_1, S_2\}) = P(\{S_1\}) + P(\{S_2\})$ and for any event $E \subseteq \Omega$,

$$P(E^c) = 1 - P(E).$$

In fact, these expectations can be formalised in a mathematical way to give a rigorous definition of a probability space and probability measure.

Probability Space

Consider a random experiment Ω with sample space Ω . We are interested in building a collection of events, denoted as \mathcal{F} , so that we can assign probabilities to every member of \mathcal{F} . Then obviously we would

expect that \mathcal{F} satisfies some properties observed earlier. The most trivial requirement of \mathcal{F} is that it contains Ω . Further for any event $A \subseteq \Omega$, we expect $A^c \in \mathcal{F}$. Also, for a sequence of events $A_1, A_2, \dots, A_n, \dots$ we expect $\bigcup_{i=1}^{\infty} A_i$ and $\bigcap_{i=1}^{\infty} A_i \in \mathcal{F}$. We formally define such \mathcal{F} now.

Definition: Let R be a random experiment with sample space Ω . A non-empty collection \mathcal{F} of subsets of Ω is called a σ -field of Ω if the following properties hold:

- i) $\Omega \in \mathcal{F}$
- ii) $A \in \mathcal{F} \Rightarrow A^c \in \mathcal{F}$
- iii) $A_n \in \mathcal{F}$ for $n=1, 2, \dots$, then $\bigcup_{n=1}^{\infty} A_n \in \mathcal{F}$
and $\bigcap_{n=1}^{\infty} A_n \in \mathcal{F}$.

Example: Let R be a random experiment with a finite sample space Ω . Then $\mathcal{F} = 2^{\Omega}$, power set of Ω . (Power set is set of all subsets). In a fair coin tossing expt., $\mathcal{F} = \{\emptyset, \{H\}, \{T\}, \{H, T\}\}$.

With the definition of σ -field \mathcal{F} in place, now we can give definition of probability measure (we have termed this probability assignment / probability model for the random experiment) which is also called an axiomatic definition.

Definition: Let R be the random experiment with sample space Ω and associated σ -algebra \mathcal{F} . Then a set function $P: \mathcal{F} \rightarrow \mathbb{R}$ is called probability measure if

i) for $A \in \mathcal{F}$, $0 \leq P(A) \leq 1$.

ii) $P(\Omega) = 1$.

iii) $A_1, A_2, \dots, A_n, \dots \in \mathcal{F}$ is a collection of mutually disjoint events, then

$$P\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} P(A_n)$$

Example: R : Tossing a coin.

$$\Omega = \{H, T\}. \quad \mathcal{F} = \{\emptyset, \{H\}, \{T\}, \{H, T\}\}$$

Note that it is enough to specify $P(H)$ alone here. Then all other probability assignments follow from the postulates (i), (ii), (iii) in the definition.

Example: R: Throwing a die

$$\Omega = \{1, 2, 3, 4, 5, 6\} ; \mathcal{F} = 2^\Omega$$

Note that here also it is enough to assign probabilities $P\{\{1\}\}, P\{\{2\}\}, P\{\{3\}\}, P\{\{4\}\}, P\{\{5\}\}$. Then using the axioms in the definition, one can assign the other probabilities easily.

Example: Uniform probability spaces

We have done this in class, though I did not mention the name. One of the most important problems in probability theory is to pick a point "at random" from a set Ω . Then intuition suggests that for two subsets A & B of Ω with "equal size", the chance of picking a point from A should be same as that from B. If Ω is finite, then one can measure size of a set by its cardinality. Thus sets A & B are of same size if they have same cardinality. The corresponding probability space in this case is then: Ω - sample space, \mathcal{F} : power set of Ω and for any $A \in \mathcal{F}$, $P(A) = \frac{|A|}{|\Omega|}$.

Note that, we have already seen two examples of this scenario: (1) Tossing a fair coin and (2) Rolling a fair die. The condition of fairness plays a key role in making the corresponding probability spaces uniform.

Another interesting case arises here when $\Omega = [0,1]$. Here, measure of "size" of any subset $A = (a,b)$ of Ω can be considered to be its length $b-a$. Two sets are of equal size if they have same length. Now the challenge here is to construct σ -algebra \mathcal{F} . It is shown (see the book Probability & Measure by P. Billingsley) that \mathcal{F} is a Borel-sigma field. (In loose terms, all sets in \mathcal{F} can be constructed by countable union and intersection of open intervals). The probability measure is $P(A) = b-a$ when $A = [a,b]$ with $0 \leq a \leq b \leq 1$. It is to be noted that all the usual sets one would encounter in real life applications are generally present in the collection \mathcal{F} and we can assign the probability to these sets (events).

Some consequences of definition of probability space. ⑨

Thm: If $A \in \mathcal{F}$, then $P(A^c) = 1 - P(A)$

Pf: Note $\Omega = A \cup A^c$ is a representation of Ω as union of disjoint events.

$$1 = P(\Omega) = P(A \cup A^c) = P(A) + P(A^c)$$

$$\Rightarrow P(A^c) = 1 - P(A).$$

Thm: $P(A_1 \cup A_2) = P(A_1) + P(A_2) - P(A_1 \cap A_2)$

Pf: $A_1 \cup A_2 = A_1 \cup (A_2 \cap A_1^c)$... disjoint union.

$$\Rightarrow P(A_1 \cup A_2) = P(A_1) + P(A_2 \cap A_1^c) \quad -(1)$$

Further, $A_2 = (A_1 \cap A_2) \cup (A_2 \cap A_1^c)$... disjoint union.

$$\Rightarrow P(A_2) = P(A_1 \cap A_2) + P(A_2 \cap A_1^c) \quad -(2)$$

From (1) & (2)

$$P(A_1 \cup A_2) = P(A_1) + P(A_2) - P(A_1 \cap A_2)$$

Remark: To better understand, draw Venn diagrams.

Remark: Generalize above theorem to the case of union of events A_1, A_2, \dots, A_n .

Remark: From the above theorem, it is clear that

$$P(A_1 \cup A_2) \leq P(A_1) + P(A_2)$$

Law of total probability.

A collection $\{B_1, B_2, \dots, B_k\}$ is said to be a partition of the sample space Ω if (i) $B_i \subseteq \Omega, i=1, 2, \dots, k$ (ii) B_i 's are mutually disjoint and (iii) $\Omega = \bigcup_{i=1}^k B_i$.

Then for any event $A \subseteq \Omega$, we can write

$$A = \bigcup_{i=1}^k (A \cap B_i) \quad \text{which is a disjoint union}$$

of events. Thus
$$\boxed{P(A) = \sum_{i=1}^k P(A \cap B_i)}$$
.

Special Type of chains of events.

Thm: Let $A_1, A_2, \dots, A_n, \dots$ be an increasing sequence of events of Ω , that is,

$$A_1 \subseteq A_2 \subseteq \dots \subseteq A_n \subseteq \dots \subseteq A \subseteq \Omega.$$

Then $\lim_{n \rightarrow \infty} P(A_n) = P(A)$.

Proof: Define $B_1 = A_1, B_2 = A_2 \cap A_1^c, \dots$

In general, $B_k = A_k \cap A_{k-1}^c$ for $k=2, 3, \dots$

Then $A = \bigcup_{i=1}^{\infty} B_i$; where B_i are mutually disjoint. (Check this with Venn diagram).

Then. $P(A) = \sum_{i=1}^{\infty} P(B_i) = \lim_{n \rightarrow \infty} \sum_{i=1}^n P(B_i)$

... from definition of limit
of series

$$= \lim_{n \rightarrow \infty} P(B_1 \cup B_2 \cup \dots \cup B_n)$$

... B_i 's are mutually
disjoint

$P(A) = \lim_{n \rightarrow \infty} P(A_n)$

... See Venn diagram.

Theorem: Let $A_1, A_2, \dots, A_n, \dots$ be a decreasing sequence of events of Ω , that is,

$$A_1 \supseteq A_2 \supseteq \dots \supseteq A_n \supseteq \dots \supseteq A$$

Then $\lim_{n \rightarrow \infty} P(A_n) = P(A).$

Proof: $A_1 \supseteq A_2 \supseteq \dots \supseteq A_n \supseteq \dots \supseteq A$

$$\Rightarrow A_1^c \subseteq A_2^c \subseteq \dots \subseteq A_n^c \subseteq \dots \subseteq A^c$$

$$\Rightarrow \lim_{n \rightarrow \infty} P(A_n^c) = P(A^c) \quad \text{— by previous theorem}$$

$$\Rightarrow \lim_{n \rightarrow \infty} [1 - P(A_n)] = 1 - P(A)$$

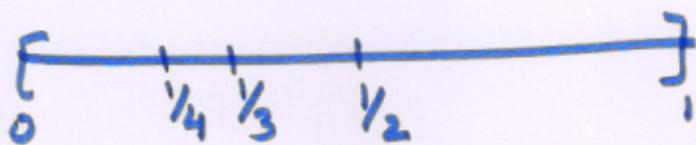
$$\Rightarrow \boxed{\lim_{n \rightarrow \infty} P(A_n) = P(A)}$$

Example: Consider the uniform probability space

with $\Omega = [0,1]$. Remember, here \mathcal{F} is a Borel-sigma algebra which contains subsets of $[0,1]$ which can be constructed from countable unions and intersections of intervals. We illustrate the use of previous theorem to compute certain probabilities.

Let $A_n = [0, \frac{1}{n}]$ for $n \in \mathbb{N}$.

Then clearly, $A_1 \supseteq A_2 \supseteq \dots \supseteq A_n \supseteq \dots \supseteq A = \{0\}$



$$P(A_n) = \frac{1}{n} - 0 = \frac{1}{n}$$

According to the previous theorem,

$$P(\{0\}) = P(A) = \lim_{n \rightarrow \infty} P(A_n) = \lim_{n \rightarrow \infty} \frac{1}{n}$$

Thus P(\{0\}) = 0

We can similarly deduce that for any $\{x\}$ with $x \in [0,1]$, $P(\{x\}) = 0$. Then using, the third postulate in the probability space definition, we conclude

$P(Q \cap [0,1]) = 0$ where $Q \cap [0,1]$ is the set of all rational numbers in $[0,1]$.