

$$u_t + u u_x = \nu u_{xx}$$

$$(i) \quad \begin{cases} u(x, 0) = \sin \pi x, & 0 < x < 1 \\ u(0, t) = u(1, t) = 0, & t > 0 \end{cases}$$

(H-9)

(lab  $\nu=1$ )

$$\text{Also, } u(x, 0) = 4x(1-x) \quad 0 \leq x < 1$$

$$(ii) \quad \begin{cases} u(0, t) = u(1, t) = 0, & t > 0 \end{cases}$$

(H-1)

(lab)

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### ADI Scheme

$$\frac{\partial u}{\partial t} = \nu \nabla^2 u, \quad \text{in } \mathbb{R}.$$

$$u(x, y, 0) = f(x, y) \rightarrow \text{I.C.}$$

$u(x, y, t)$  is prescribed at the boundary

$$t_n \rightarrow t_{n+1}$$

$$u_{ij}^n \rightarrow u_{ij}^{n+1}$$

#### Two Step Method

Step-I:  $t_n \rightarrow t_{n+1/2}$ ,  $x$ -derivatives implicitly (or  $y$ -derivatives) and

$y$ -derivatives ( $x$ -derivatives) explicit

$$\frac{u_{ij}^{n+1/2} - u_{ij}^n}{\delta t} = \nu \left[ \frac{u_{i+1,j}^{n+1/2} - 2u_{ij}^{n+1/2} + u_{i-1,j}^{n+1/2}}{\delta x^2} + \frac{u_{i,j+1}^n - 2u_{ij}^n + u_{i,j-1}^n}{\delta y^2} \right]$$

At a fixed  $j$  ( $= 1, 2, \dots, M-1$ )

Solve for  $i=1, 2, \dots, N-1$ , leading to a tri-diag. system

Step II:  $t_{n+1/2} \rightarrow t_{n+1}$   $y$ -derivatives ( $x$ -derivatives)

implicit &  $x$ -derivatives ( $y$ -deriv) explicit

$$\frac{u_{ij}^{n+1} - u_{ij}^{n+1/2}}{\delta t} = \frac{\nu}{2} \left[ \frac{u_{i+1,j}^{n+1/2} - 2u_{ij}^{n+1/2} + u_{i-1,j}^{n+1/2}}{\delta x^2} + \frac{u_{i,j+1}^{n+1} - 2u_{ij}^{n+1} + u_{i,j-1}^{n+1}}{\delta y^2} \right]$$

At a fixed  $i$  ( $= 1, 2, \dots, N-1$ )

Solve for  $j=1, 2, \dots, M-1$ ,  $\rightarrow$  tri-diagonal system



H.T Expand by Taylor Series show that ADI scheme is  $O(\delta t^2, \delta x^2, \delta y^2)$  and Von-Neumann analysis reveals that the ADI scheme is unconditionally stable.

H.T (Q)  $u_t = \nabla^2 u, 0 \leq x, y \leq 1, t > 0.$   
 $u(x, y, 0) = \sin \pi x \cdot \sin \pi y$   
 $u = 0$  on the boundary

Derive the ensuing tridiagonal system at each step.

(Q)  $u_t = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}, u(x, y, z, t).$

$\nabla^2 Q = 0$  Laplace Equation  
 $\frac{\partial Q}{\partial t} + \nabla^2 Q = 0, 0 \rightarrow 0$   
 $t=0 \quad t=T$

Laplace or Poisson Equation

$\nabla^2 Q = 0 \rightarrow$  Laplace Eq.  
 $\nabla^2 Q = f(x, y) \rightarrow$  Poisson Eq.  
 $b^2 - ac < 0$

$\frac{\partial^2 u}{\partial x^2} - \frac{\partial^2 u}{\partial y^2} = 0, b^2 - ac > 0 \rightarrow$  hyperbolic

Elliptic PDE  $\nabla^2 Q = 0 = f(x, y).$

all conditions on  $Q$  is prescribed on the boundary for this it also refers as boundary value problem.  
 $\nabla^2 Q = f(x, y), x, y \in \mathbb{R}.$

$Q$  is prescribed on the boundary  $\partial \mathbb{R}$  of  $\mathbb{R}$   
 $\mathbb{R}: 0 < x < a, 0 < y < b$   
 $\partial \mathbb{R}: x=a, a', y=a, b$

$\frac{\partial^2 Q}{\partial x^2} + \frac{\partial^2 Q}{\partial y^2} = f(x, y).$

$x_i = i \delta x, i=0, 1, \dots, N$

$y_j = j \delta y, j=0, 1, \dots, M.$

$Q(x_i, y_j) = Q_{ij}, i=1, 2, \dots, N-1$   
 $j=1, 2, \dots, M-1$

Discretize the equation through central difference scheme.

$\frac{Q_{i+1,j} - 2Q_{i,j} + Q_{i-1,j}}{\delta x^2} + \frac{Q_{i,j+1} - 2Q_{i,j} + Q_{i,j-1}}{\delta y^2} = f_{ij}$

$i=1, 2, \dots, N-1, j=1, 2, \dots, M-1$

which are  $(N-1) \times (M-1)$  equations involving  $(N-1) \times (M-1)$  variables  $Q_{ij}$ .

$\begin{matrix} Q_{0,j}, Q_{N,j} & j=0, 1, \dots, M \\ Q_{i,0}, Q_{i,M} & i=0, 1, \dots, N \end{matrix} \rightarrow \text{known}$

Eq. (\*) forms a closed system

(Q)  $\nabla^2 u = -10(x^2 + y^2 + 10), 0 < x < 3, 0 < y < 3.$

$u = 0$  on the boundary  $x=0, 3$   
 $y=0, 3$

$\delta x = \delta y = 1$   
 $u_{ij}, 2 \times 2 = 4 \text{ points}$

$(u_{i+1,j} - 2u_{i,j} + u_{i-1,j}) + (u_{i,j+1} - 2u_{i,j} + u_{i,j-1}) = -10(x_i^2 + y_j^2 + 10)$

$i=1, 2, j=1, 2 \rightarrow$  (H.T)

$$i, j = 1, 2$$

$$\delta x, \delta y \sim 0.01, M = \frac{3}{0.01} = 300$$

(299 x 299) equation

Gauss-Seidel method to solve the system of equations

$$\nabla^2 u = f(x, y)$$

$$u_{i,j}^{(k+1)} = \frac{1}{4} \left( u_{i+1,j}^{(k)} + u_{i-1,j}^{(k)} + u_{i,j+1}^{(k)} + u_{i,j-1}^{(k)} \right) + \frac{\delta x^2}{4} f_{i,j}$$

= f<sub>ij</sub>

At the (k+1)<sup>th</sup> iteration, k ≥ 0,

$u_{i,j}^{(0)} \rightarrow \text{known}$

$u_{i,j}$  is the unknown at the j<sup>th</sup> equation

Other variables are treated as known.

$$u_{i,j}^{(k+1)} = u_{i+1,j}^{(k)} + u_{i-1,j}^{(k)} + \beta^2 (u_{i,j+1}^{(k)} + u_{i,j-1}^{(k)}) - 2(1+\beta^2) u_{i,j}^{(k)} - \frac{f_{i,j}}{2}$$

$$\beta = \frac{\delta x}{\delta y}$$

$$i = 1, 2, \dots, N-1$$

$$j = 1, 2, \dots, M-1 \text{ for } k \geq 0$$

Start the iteration with  $u_{i,j}^{(0)}, \forall i, j$

$$-2u_{i,j} \left( \frac{1}{\delta x^2} + \frac{1}{\delta y^2} \right) = f_{i,j} - u_{i+1,j}^{(k)} - u_{i-1,j}^{(k)} - u_{i,j+1}^{(k)} - u_{i,j-1}^{(k)}$$

$$-2u_{i,j} \left( \frac{\beta^2 + 1}{\delta x^2} \right) = -\frac{f_{i,j} \delta x^2}{2(1+\beta^2)} + \frac{\delta x^2}{2(1+\beta^2)} (u_{i+1,j}^{(k)} + u_{i-1,j}^{(k)} + \beta^2 (u_{i,j+1}^{(k)} + u_{i,j-1}^{(k)}))$$

$$u_{i,j} = \frac{u_{i+1,j}^{(k)} + u_{i-1,j}^{(k)} + \beta^2 (u_{i,j+1}^{(k)} + u_{i,j-1}^{(k)}) - f_{i,j} \delta x^2}{2(1+\beta^2)}$$

$$i = 1, 2, \dots$$

To start the iteration,

given  $u_{i,j}^{(0)}$  at all grid points.

This procedure is repeated till

$$\max_{i,j} |u_{i,j}^{(k+1)} - u_{i,j}^{(k)}| < \epsilon$$

$\epsilon = 0.5 \times 10^{-5}$  convergence criteria.

$$|a_{ii}| \geq \sum_{j \neq i} |a_{ij}|, \forall i \rightarrow \text{diagonally dominant}$$

which is the sufficient condition for convergence.

G.S-iteration converges at a slow rate.

$$u_{i,j}^{(k+1)} = \omega u_{i,j}^{(k+1)} + (1-\omega) u_{i,j}^{(k)}$$

Successive over relaxation.

$$u_{i,j}^{(k+1)} = \bar{u}_{i,j}^{(k+1)} + \omega (u_{i,j}^{(k+1)} - \bar{u}_{i,j}^{(k+1)})$$

$$\omega > 1$$

$\bar{u}_{i,j}^{(k+1)}$  is the modified value at (k+1)<sup>th</sup> iteration

$\omega$  is the relaxation parameter  $1 \leq \omega \leq 2$

$\omega = 1$  is the Gauss-Seidel iteration.

$$u_{i,j}^{(k+1)} = \omega u_{i,j}^{(k+1)} + (1-\omega) u_{i,j}^{(k)}$$

$$0 < \omega < 1 \rightarrow \text{interpolated value}$$

→ successive-under-relaxation



Lab:  $\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} = \alpha \frac{\partial^2 T}{\partial x^2}$ ,  $0 < x < 1$ ,  $t > 0$ .  
 $u = 0.1$ ,  $\alpha = 0.01$

$T(0, t) = 0$ ,  $T(1, t) = 100$ ,  $t > 0$

$T(x, 0) = 100x$

HT:  $\frac{\partial T}{\partial t} + T \frac{\partial T}{\partial x} = \gamma \frac{\partial^2 T}{\partial x^2}$ ,  $0 < x < 1$ ,  $t > 0$ .

$T(x, 0) = f(x)$ ,  $T(0, t) = T(1, t) = 0$

Discretize by the Crank-Nicolson scheme and use Newton's linearization technique to generate determine the ensuing tri-diagonal system which needs to be solved

Hint:  $T_n \rightarrow T_{n+1}$ ,  $(T_i^{(n+1)})^{(k+1)} = (T_i^{(n)})^{(k)} + \Delta T_i$   
 $\delta x = 0.25$ ,  $T = 1$

Q:  $\nabla^2 u - 2 \frac{\partial u}{\partial x} = -2$ , in  $R$ ,  $u = 0$  on  $\partial R$

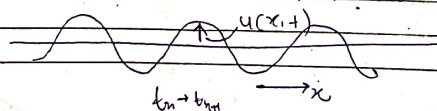
HT:  $R: 0 < x < 1$ ,  $0 < y < 1$ ,  $h = 1/3$

Q:  $-\nabla^2 u + 0.1u = 1$ ,  $0 < x < 1$   
 $u = 0$ , on  $x = 0$ ,  $y = 0$ .

HT & (Lab):  $\frac{\partial u}{\partial n} = 0$ , on  $x = 1$ ,  $y = 1$ ,  $n$  - unit normal.  
 $\delta x = \delta y = 0.5$

# Hyperbolic PDE:

$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$ ,  $u(x, 0) = f(x)$ ,  $\frac{\partial u}{\partial t}(x, 0) = g(x)$   
 $u(0, t)$  &  $u(b, t)$  are given



$u_j^{n+1} - 2u_j^n + u_j^{n-1} = c^2 \left( \frac{u_{j+1}^n - 2u_j^n + u_{j-1}^n}{\delta x^2} \right)$

Explicit Scheme

$u_j^{n+1} = \nu^2 \left( u_{j+1}^n + u_{j-1}^n \right) + 2(1 - \nu^2) u_j^n - u_j^{n-1}$   
 $j = 1, 2, \dots, N-1$

$n = 0$ ,  $\frac{\partial u}{\partial t} \Big|_j = g_j$ ,  $\frac{u_j^1 - u_j^0}{\delta t} = g_j$ ,  $u_j^1 = u_j^0 - 2\delta t g_j$

$u_j^1 = \nu^2 (u_{j+1}^0 + u_{j-1}^0) + 2(1 - \nu^2) u_j^0 - \{u_j^0 - 2\delta t g_j\}$

$u_j^1 = \frac{\nu^2}{2} [(f_{j+1} + f_{j-1}) + (1 - \nu^2) f_j] + \delta t g_j$

$\nu < 1$ , stable

Lab:  $T_{n+1}$

$C = 1$ ,  $\delta x = 1/5$ ,  $\nu = 0.5$

$u(0, t) = u(1, t) = 0$

$u(x, 0) = \sin \pi x$ ,  $\frac{\partial u}{\partial t}(x, 0) = 0$ ,  $0 \leq x \leq 1$

Find for  $n = 1, 2, 3$ . Lap for  $\delta t$  scheme

$\frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = 0$ ,  $\left( \frac{\partial}{\partial t} - c \frac{\partial}{\partial x} \right) \left( \frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} \right) = 0$

$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = z$ ,  $\frac{\partial z}{\partial t} - c \frac{\partial z}{\partial x} = 0$  Hyperbolic PDE

$\frac{\partial u}{\partial t} + c \frac{\partial u}{\partial x} = 0 \rightarrow 1^{st}$  order hyperbolic PDE

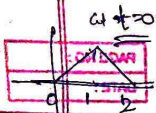
wave eq

$u(x, 0) = \begin{cases} x, & 0 < x < 1 \\ 2-x, & 1 < x \leq 2 \\ 0 & \text{otherwise} \end{cases}$

Gas dynamics

Euler eqs for inviscid flow

transport governed by convection. no diffusion



$$\frac{dx}{c} = \frac{dt}{1} = \frac{du}{0}$$

$$u = C_1, x - ct = C_2$$

$$f(C_1, C_2) \Rightarrow$$

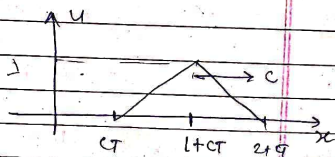
So,  $u = f(x-ct)$ ,  $f$  is any arbitrary function.

$$u(x,0) = f(x) = \begin{cases} x, & 0 \leq x \leq 1 \\ 2-x, & 1 \leq x \leq 2 \\ 0, & \text{otherwise.} \end{cases}$$

$$f(x-ct) = \begin{cases} x-ct, & 0 \leq x-ct \leq 1 \\ 2-x+ct, & 1 \leq x-ct \leq 2 \\ 0, & \text{otherwise.} \end{cases}$$

$$u(x,t) = f(x-ct)$$

velocity = c



$$\frac{\partial u}{\partial t} - c \frac{\partial u}{\partial x} = 0$$

$$\Rightarrow u = g(x+ct)$$

$$u(x,t) = g(x+ct)$$

$$u(x,t) = g(x+ct)$$

$$= u(x+ct, 0)$$

§  $u_t + cu_x = 0$ .  $C$  is either  $C(x,t)$  or a constant.

$u(x,0) = u_0(x)$ ,  $\rightarrow$  I.C.; B.C. over  $x$  is prescribed

FTCS  $t_n \rightarrow t_{n+1}, n > 0$

$$\frac{u_j^{n+1} - u_j^n}{\delta t} + C \frac{u_{j+1}^n - u_{j-1}^n}{2\delta x} = 0$$

$$u_j^{n+1} = u_j^n - \frac{r}{2} (u_{j+1}^n - u_{j-1}^n)$$

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Stability:  $u_j^n \rightarrow A^n e^{i\theta j}$ ,  $q = \frac{A^{n+1}}{A^n}$

$$q = 1 - i\gamma \sin \theta$$

$$|q| \leq 1$$

$C$  for stability

$$|q|^2 = 1 + \gamma^2 \sin^2 \theta > 1$$

$\hookrightarrow$  unconditionally unstable

FTBS (Euler's scheme)

$$(i) \frac{u_j^{n+1} - u_j^n}{\delta t} + C \frac{(u_j^n - u_{j-1}^n)}{\delta x} = 0$$

$$u_j^{n+1} = (1-\gamma) u_j^n + \gamma u_{j-1}^n$$

$$q = \frac{A^{n+1}}{A^n} = 1 - \gamma + \gamma (\cos \theta - i \sin \theta)$$

$$|q|^2 = 1 - 2\gamma(1-\gamma)(1-\cos \theta)$$

stable  $0 < \gamma \leq 1$ , for stability

$$\gamma = \frac{C \delta t}{\delta x} > 0, \text{ if } C > 0$$

(ii) if  $C < 0$ , FTFS

$\hookrightarrow$  not stable

(12)

Show that  $u_t + cu_x = 0$ , stable for

(a) FTBS when  $C > 0$

(b) FTBS when  $C < 0$

Find the value of  $\gamma$ .  
check for consistency.