

Linear Algebra

Lecture 13



Composition of linear transformation

Let $T: V \rightarrow W$ and $U: W \rightarrow Z$ be linear transformations and $B_1 = \{v_1, \dots, v_n\}$, $B_2 = \{w_1, \dots, w_m\}$ and $B_3 = \{z_1, \dots, z_p\}$ are ordered bases for V , W and Z respectively.

$$\text{Let } A = [U]$$

$$B = [T]$$

Composition of these linear $f \circ g$.

$$UT : V \rightarrow Z$$

$$v_i \mapsto UT(v_i)$$

$$UT(v_j) = U(T(v_j))$$

$$= U\left(\sum_{k=1}^m B_{kj} w_k\right)$$

$$= \sum_{k=1}^m B_{kj} U(w_k)$$

$$= \sum_{k=1}^m B_{kj} \left(\sum_{i=1}^p A_{ik} z_i \right)$$

$$= \sum_{i=r}^p \left(\sum_{k=r}^m A_{ik} B_{kj} \right) z_i$$

$$(UT)(z_j) = \sum_{i=r}^p C_{ij} z_i$$

where $C_{ij} = \underbrace{\sum_{k=1}^m A_{ik} B_{kj}}$

is the matrix representing
linear transformation UT .

Matrix multiplication: For $A \in F^{m \times n}$
 $B \in F^{n \times p}$

$$C = AB$$

where $C_{ij} = \sum_{k=1}^m A_{ik} B_{kj}$ $i=1, \dots, m$
 $j=1, \dots, p$

Invertibility :

Definition. Let V and W be vector spaces over a field F and let $T: V \rightarrow W$ be a linear map. A function $U: W \rightarrow V$ is said to be an inverse of T if

$$TU = I_w \quad \text{and} \quad UT = I_v$$

If T has an inverse, then T is said to be invertible and inverse of T is denoted as T^{-1} .

Lemma: If T and U are invertible functions, then

$$i) (T+U)^{-1} = U^{-1} T^{-1}$$

$$2) \quad (\tau^{-1})^{-1} = \tau$$

$$\begin{aligned}
 (TU) U^{-1} T^{-1} &= T (U U^{-1}) T^{-1} \\
 &= T I T^{-1} \\
 &= T T^{-1} \\
 &= I
 \end{aligned}$$

$(TU)^+$
 $= U^{-1} T^{-1}$

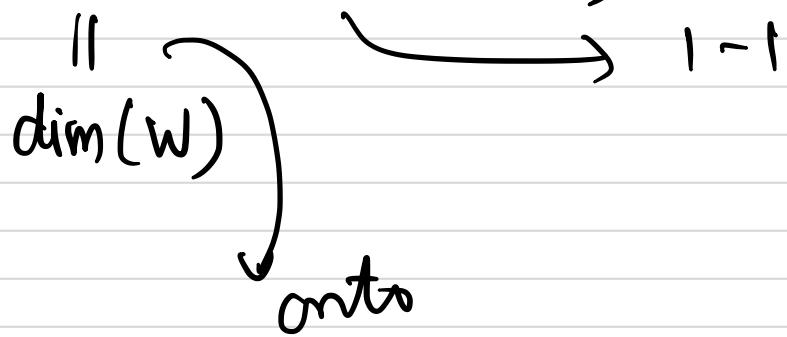
$$U^{-1}T^{-1}(TU) = I$$

$$T: V \rightarrow W$$

T is invertible if and only if T is 1-1 and onto.

$$\text{Rank}(T) + \text{nullity}(T) = \dim(V)$$

$$\Rightarrow \text{Rank}(T) = \dim(V)$$



Lemma:

Let V & W be vector spaces over \mathbb{F} and $T: V \rightarrow W$ be a linear invertible transformation. Then $T^{-1}: W \rightarrow V$ is also linear.

Pf: Let $y_1, y_2 \in W$ and $c \in \mathbb{F}$.

Since T is 1-1 and onto, \exists unique x_1 & x_2 such that

$$x_1 = T^{-1}(y_1), \quad x_2 = T^{-1}(y_2)$$

$$T^{-1}(cy_1 + y_2) = T^{-1}(cT(x_1) + T(x_2))$$

$$= T^{-1} (\overbrace{T(cx_1 + x_2)}^{\text{linearity}})$$

$$= cx_1 + x_2$$

$$= c T^{-1}(y_1) + T^{-1}(y_2)$$

$\Rightarrow T^{-1}$ is a linear function. \blacksquare

Theorem: Let T be invertible linear transformation from V to W . Then V is finite dimensional if and only if W is finite dimensional. Moreover $\dim(V) = \dim(W)$.

Matrix representation of T^{-1}

Let V and W be finite dimensional vector spaces over \mathbb{F} with ordered basis $B_1 = \{v_1, \dots, v_n\}$ and $B_2 = \{w_1, \dots, w_m\}$

Let $T: V \rightarrow W$ be linear. Then T is invertible iff $m=n$.

Let $T^{-1} \in L(W, V)$ and let B be a matrix representation of T^{-1} .

$$T^j(\omega_j) = \sum_{i=1}^n B_{ij} v_i \quad \text{for } j=1, 2, \dots, n$$

Let T have the matrix representation A with respect to the listed ordered basis.

$$TT^{-1} = AB$$

||

identity

linear

transformation from

$U \rightarrow W$

$$\overset{-1}{TT} = BA$$

||

identity

linear

transformation from

$V \rightarrow V$

$$= I_n$$

This inspires the definition of inverse of a square matrix.

Isomorphism:

Let V and W be vector spaces over \mathbb{F} . We say V is isomorphic to W if there exists a linear transformation $T: V \rightarrow W$ which is invertible. Such a linear transformation is called as isomorphism.

Examples of isomorphic vector spaces.

Ex: Let $V = \mathbb{R}^{n+1}$ and $W = P_n(\mathbb{R})$

Ex: Let V & W be finite dimensional vector spaces over \mathbb{F} .

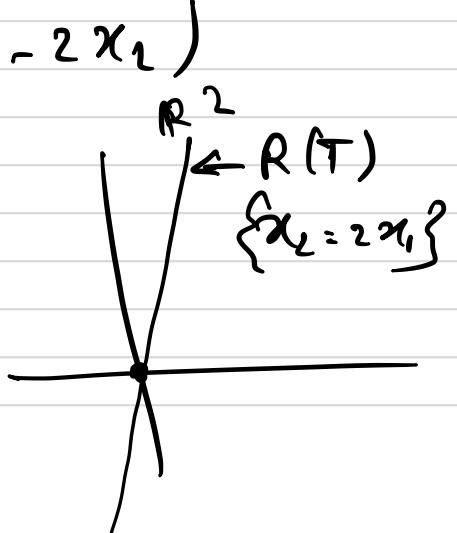
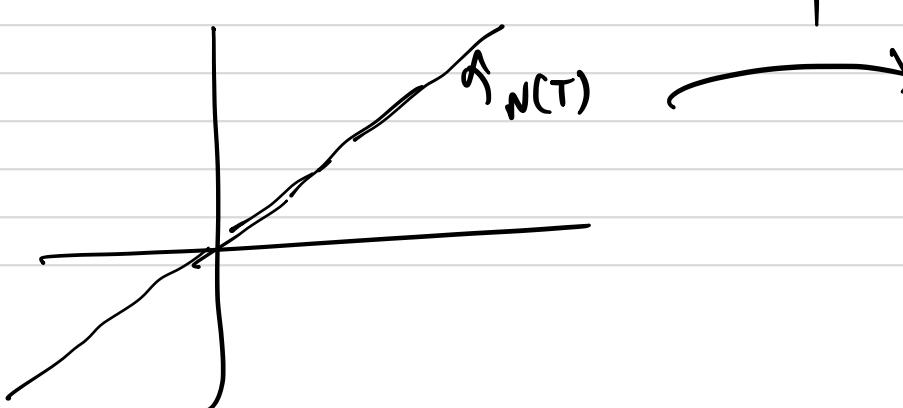
$L(V, W)$ and $\mathbb{R}^{m \times n}$ and $\mathbb{R}^{n \times m}$
where $m = \dim(W)$
 $n = \dim(V)$

Ex: Let V and W be finite dimensional vector spaces. Let T be a linear transformation from $V \rightarrow W$.

$$V/N(T) \cong R(T) \quad \left. \begin{array}{l} \text{rank-nullity} \\ \text{theorem.} \end{array} \right\}$$

Example: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\mathbb{R}^2 \quad T(x_1, x_2) = (x_1 - x_2, 2x_1 - 2x_2)$$



Let $T: V \rightarrow Z$ be a linear transformation which is onto.

Define that map

$$\bar{T} : V/N(T) \rightarrow Z$$

$$\text{by } \bar{T}(\underbrace{v + N(T)}_{\substack{\uparrow \\ \text{is any coset of } N(T)}) = T(v)$$

\uparrow
is any coset of $N(T)$

(a) Prove that \bar{T} is well defined.

Prove that for $v_1 + N(T) = v_2 + N(T)$

$$T(v_1 + N(T)) = \bar{T}(v_1 + N(T))$$

$$T(v_1) = T(v_2)$$

(b) \bar{T} is linear

$$\bar{T} \left[c(v_1 + N(T)) + (v_2 + N(T)) \right]$$

$$= \bar{T} [cv_1 + v_2 + N(T)]$$

$$= T(cv_1 + v_2) = cT(v_1) + cT(v_2)$$

$$= c\bar{T}(v_1 + N(T)) + \bar{T}(v_2 + N(T))$$

(C) Is \bar{T} an isomorphism??

$$\bar{T}(v_1 + N(T)) = \bar{T}(v_2 + N(T))$$

$$\Rightarrow \bar{T}((v_1 - v_2) + N(T)) = 0$$

$$\Rightarrow v_1 - v_2 \in N(T)$$

Take any element $z \in Z$.

Since T is onto, $\exists v \in V$ such

that $T(v) = z$

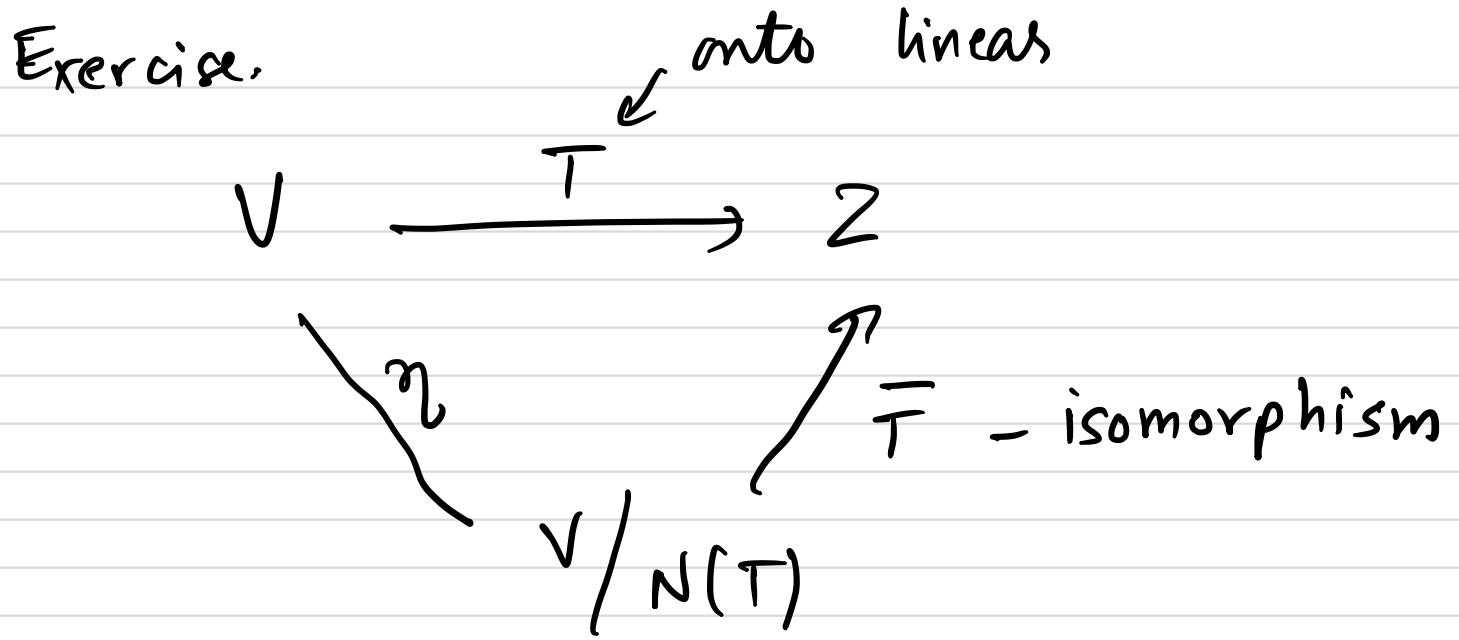
$$\bar{T}(v + N(T))$$

↑
 $V/N(T)$

onto

$$V \xrightarrow{T} Z \quad T = \bar{T}_n$$

$n \searrow \nearrow \bar{T}$
 $V/N(T)$



Define $\eta : V \rightarrow V/N(T)$

as $\eta(v) = v + N(T) \quad \forall v \in V$.

Prove: $T = \bar{T}\eta$ (The diagram commutes)

Step 1: Show η is onto.

$$R(\eta) = V/N(T)$$

Step: Composition $\bar{T}\eta$ is well-defined.

take $v \in V$

$$\begin{aligned}
 \bar{T}\eta(v) &= \bar{T}(\eta(v)) = \bar{T}(v + N(T)) \\
 &= T(v)
 \end{aligned}$$