

Budhananda - Stat

Regression - Midsem

Time series - Endsem

Endsem exam (RF + TS)

Prediction



with less error



Absolute distance (L_1 norm) ^{Assumption}

or

Squared distance (L_2 norm)



Dataanalysis (Given)



model Building



Prediction

Simple linear Regression

$$Y = \beta_0 + \beta_1 X$$

↓
Dependent

↓
Independent

of $Y; \beta_0, \beta_1$

+ ϵ

$\epsilon \sim N(0, \sigma^2)$

σ^2 unknown

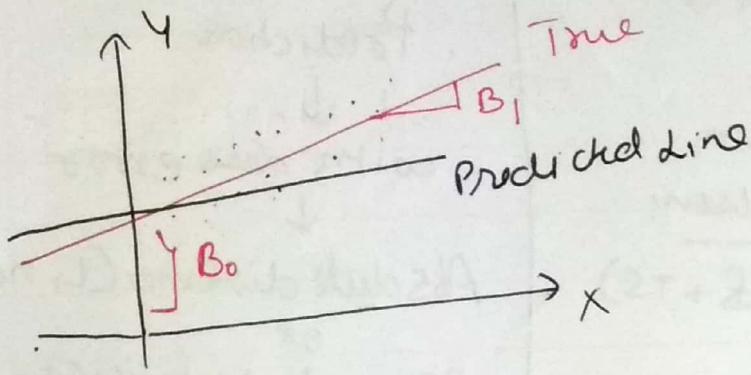
and non-random / Non-stochastic
{ value of the variable is final & no
noise/error associated with x
, whatever you know is final }

Linear - means - linear in parameters
model not in variable

Eg * $Y = \beta_0 + \beta_1 x$ is a linear

$Y^* = \beta_0^* + \beta_1^* x + \beta_2^* x^2$ is also a linear model

$$Y^* = C_1 x^{n^2} \begin{pmatrix} \beta_0^* \\ \beta_1^* \\ \vdots \\ \beta_n^* \end{pmatrix}$$



True $y = B_0 + \beta_1 x + \epsilon$
 Estimate $\hat{y} = \hat{B}_0 + \hat{\beta}_1 x_{\text{new}}$

Error : (Squared error)

or L_2 (Norm)

$\underline{y} = (y_1, y_2, \dots, y_n)^T$ then the length of \underline{y} is

$$\|\underline{y}\|_2^2 = \sum_{i=1}^n y_i^2 = \underline{y} \cdot \underline{y} = \underline{y}^T \underline{y}$$

$$\underline{z} = \begin{pmatrix} z_1 \\ \vdots \\ z_n \end{pmatrix} \quad \underline{\tilde{y}} = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

$$\begin{aligned} \|\underline{y}\|_2 &= \sqrt{\sum_{i=1}^n y_i^2} \\ \|\underline{\tilde{y}}\|_1 &\leq \sum_{i=1}^n |y_i| \end{aligned}$$

then

$$\|\underline{z} - \underline{y}\|_2^2 = \sum_{i=1}^n (y_i - z_i)^2 = (\underline{y} - \underline{z})^T (\underline{y} - \underline{z}) = (\underline{y} - \underline{z}) \cdot (\underline{y} - \underline{z})$$

We want to mimimize

~~$$S = \sum_{i=1}^n [y_i - (B_0 + B_1 x_i)]^2$$~~

$$S = \sum_{i=1}^n [y_i - (B_0 + \beta_1 x_i)]^2$$

Then the estimate we get for B_0 & B_1 are known as least square estimates of B_0, B_1 .

$$\hat{B}_{0,LS}, \hat{B}_{1,LS}$$

Given data = $\{(y_1, x_1), (y_2, x_2), \dots, (y_n, x_n)\}$

$$\begin{aligned} \frac{\partial S}{\partial B_0} &= 0 \\ \frac{\partial S}{\partial B_1} &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{normal equations}$$

Solve the normal equations for $\hat{B}_{0,LS}$ & $\hat{B}_{1,LS}$

$$\hat{B}_{0,LS} = \bar{Y} - \hat{B}_{1,LS} \bar{X}$$

$$\hat{B}_{1,LS} = \frac{\sum y_i x_i - n \bar{x} \bar{y}}{\sum x_i^2 - n (\bar{x})^2}$$

\therefore we can predict

$$\hat{Y}_{new} = \hat{B}_{0,LS}$$

We can estimate the error

$$S^2 = \sum_{i=0}^n (\hat{y}_i - y_i)^2$$

Testing we can't do as both \hat{B}_0 , \hat{B}_1 are random variable

Ans

Results from linear Algebra

Data $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$

$$y^i = B_0 + B_1 x_i^i + \epsilon^i \quad \forall i = 1, 2, \dots, n$$

$$\begin{aligned} \tilde{Y} &= \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} & X &= \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_n \end{pmatrix} & \beta &= \begin{pmatrix} B_0 \\ B_1 \end{pmatrix} \end{aligned}$$

$$\tilde{\epsilon} = \begin{pmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_n \end{pmatrix} \quad \textcircled{1} \quad \epsilon_i \text{ iid } N(\mu, \sigma^2)$$

As mean would automatically get adjusted in the constant

\textcircled{2} B_0, B_1, σ^2 are unknown

\textcircled{3} x_i^i 's are non random

$$\tilde{Y} = X \tilde{\beta} + \tilde{\epsilon}$$

$$\begin{matrix} Y \\ n \times 1 \end{matrix} \in \mathbb{R}^n$$

$$\begin{matrix} X \\ n \times 2 \end{matrix}, \quad \begin{matrix} \beta \in \mathbb{R}^2 \\ \epsilon \in \mathbb{R}^n \end{matrix}$$

Definition Vector Space

A vector space V over \mathbb{R} ,

denoted by $(V, +, \cdot, \mathbb{R})$ has

the following property $\forall \alpha, \beta \in \mathbb{R}$

$$\text{f } x, y, z \in V$$

①

$$\text{Closure (a) } + : V \times V \longrightarrow V$$

$$\text{per } (b) (x+y) + z = x + (y+z)$$

(c) $\exists 0 \in V$ such that

Identity

$$0 + x = x + 0 = x \quad \forall x \in V$$

Inverse (d) $\exists -x \forall x \in V$ such that

$$-x + x = x + (-x) = 0$$

commutative

$$(e) \quad x+y = y+x \quad \forall x, y \in V$$

$$\textcircled{2} \quad \cdot : \mathbb{R} \times V \rightarrow V$$

$$\textcircled{3} \quad \alpha \cdot (\beta \cdot z) = (\alpha \cdot \beta) \cdot z$$

$$\textcircled{4} \quad 1 \cdot z = z$$

$$\textcircled{5} \quad (\alpha + \beta) \cdot n = \alpha \cdot n + \beta \cdot n$$

$$\textcircled{6} \quad \alpha \cdot (z + y) = \alpha z + \alpha y$$

Example

\textcircled{1} \mathbb{R}^n is a vector space

\textcircled{2} C^n

\textcircled{3} $P_n = \{ \text{all polynomials with degree } \leq n \}$ is also a vector space

$$P_n(0) = a_0 + a_1 x + \dots + a_n x^n$$

$$= (a_0, \dots, a_n) \begin{pmatrix} 1 \\ x \\ x^2 \\ \vdots \\ x^n \end{pmatrix}$$

Subspace:

Let $(V, +, \cdot, \mathbb{R})$ is a vector space & $S \subseteq V$ such that $(S, +, \cdot, \mathbb{R})$ is also a vector space then S is known as the subspace of V .

A subset which is a vector space under the same operation

Example

Q If \mathbb{R}^2 is a vector space with usual vector addition
2 scalar multiplication

then

- ① x axis is a subspace
- ② y axis is subspace
- ③ Any line passing through origin

Q In \mathbb{R}^3 ,

- (a) $(0, 0, 0)$
- (b) All the lines passing through $(0, 0, 0)$
- (c) All planes passing through $(0, 0, 0)$
are subspaces

Q If P_7 is the vector space

$S = P_8 \quad 8 \leq 7$ is a subspace

$P_n \rightarrow n+1$ dimensional vector space

Independent Vectors: A set of vectors

v_1, v_2, \dots, v_n are said to be (linearly) independent

if

$$\sum_{i=1}^n c_i v_i = 0 \Leftrightarrow c_1 = c_2 = \dots = c_n = 0$$

$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \text{ by } \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow c_1 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

Span : Let $\{v_1, v_2, \dots, v_k\}$ be a collection of K vectors in \mathbb{R}^n , the span of this collection is defined to be all possible linear combinations of $\{v_1, v_2, \dots, v_k\}$

$$Sp \{v_1, v_2, \dots, v_k\}$$

$$= \left\{ \sum_{i=1}^k c_i v_i \mid c_i \in \mathbb{R}, v_i \in \mathbb{R}^n \right\}$$

$$\text{Ex } \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sim v_1 \quad \begin{pmatrix} 0 \\ 1 \end{pmatrix} \sim v_2$$

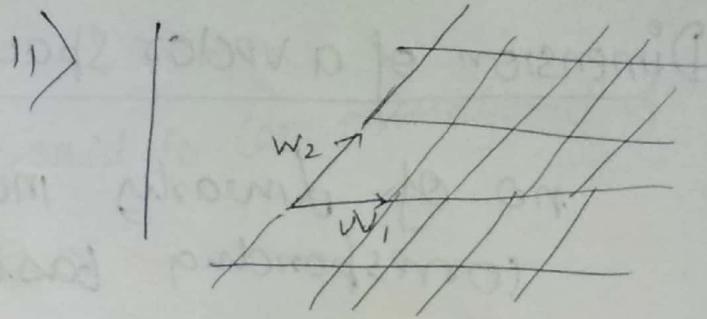
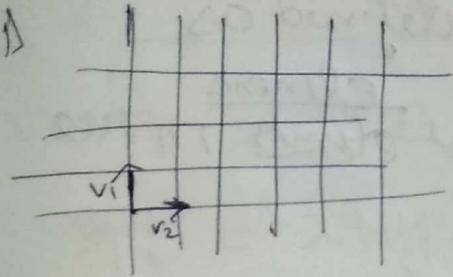
$$Sp \{x, y\} = \left\{ c_1 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 0 \\ 1 \end{pmatrix} \mid c_1, c_2 \in \mathbb{R} \right\}$$

$$= \mathbb{R}^2$$

$$2) w_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \sim v_1 \quad w_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \sim v_2$$

$$Sp \{w_1, w_2\} = \mathbb{R}^2$$

then what is the diff b/w w_1 & w_2



$$R^2 \quad \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$R^2 \quad \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

Same space can be represented by 2 diff
vect

Basis : A basis of vector space ($S \subseteq V$) is a
a subspace ($S \subseteq V$) defined as a set of linearly independent
vectors such that the span of the set
is the vector space V or the subspace
($S \subseteq V$) respectively

earlier 2 example of basis of R^2

\Rightarrow Basis may not be unique

$\left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right\}$ is a basis of R^2

$\left\{ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix} \right\}$ is a basis of R^2

$\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$ cannot generate R^2 but it
generates x-axis which
is a subspace of R^2

Dimension of a vector space is defined as

no of linearly independent ~~elements~~ in the corresponding basis

$V = \{B\}$ then $|B|$ is the dimension
of V if B is the basis

$$\dim(V) = |B|$$

when B is basis of V

$$A = V \{ (n, y, 0), n \in \mathbb{R}, y \in \mathbb{R} \}$$

$$A = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\} \text{ in } \mathbb{R}^3, \text{ i.e. } A \subset \mathbb{R}^3$$

$$\text{among } A \subset \mathbb{R}^3, \dim(A) = 2$$

* If $v_1, v_2, \dots, v_k \in \mathbb{R}^n$ then

i) $k > n$ then the collection is always linearly dependent

$$\left\{ \underbrace{\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}}_{\mathbb{R}^3}, \underbrace{\begin{pmatrix} 1 \\ 0 \\ c \end{pmatrix}}_k \right\}$$

Orthogonal Vectors

Vectors $\underline{x}, \underline{y} \in V$ are said to be orthogonal if

$$\underline{x} \cdot \underline{y} = \underline{x}^T \underline{y} = \underline{y}^T \underline{x} = 0$$

Notation: $\underline{x} \perp \underline{y}$

(*) 0 is orthogonal to any vector by itself

Orthogonal basis

If the vectors of the basis set B are orthogonal to each other then the Basis is known as orthogonal basis.

* helps in making calculation & analysis easier.

Orthogonal Complement

If S is a subset of V then the orthogonal complement of S is defined by

$$S^\perp = \{ \underline{v} \mid \underline{v}^T \underline{u} = 0 \quad \forall \underline{u} \in S \}$$

$$S^\perp \cap S = \underline{0} \neq \emptyset$$

Ex. $\mathbb{R}^3 = V$

$$S = SP \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}$$
$$S^\perp = SP \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\dim(S) + \dim(S^\perp) = \dim(V)$$

- * These dimensions will give us the degrees of freedom in statistical analysis

Projection Matrix : If S is a subspace of a vector space then the projection matrix P_S for $S \subseteq V$ satisfies the following condition

- ① If $v \in S$, $P_S v = v$
- ② If $v \in V$, $P_S v \in S$

$$V = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \in \mathbb{R}^3 = V, S = \{(n, 0) \mid n \in \mathbb{R}\}$$

$$P_S = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, P_S V = \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix}$$

$$V_1 = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} \in S, P_S V_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$$

- * If P_S is a projection matrix for $S \subseteq V$ and $(I_n - P_S)$ is the projection matrix for $S^\perp \subseteq V$ then P_S and $I_n - P_S$ are orthogonal projection matrices of S & S^\perp respectively.

$$(I_n - P_S) \underline{v} = \underline{v}_2 \quad v_1, v_2 \text{ are orthogonal mtrs}$$

$$P_S = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad I_3 - P_S = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$P_S \underline{v} = \begin{pmatrix} 1 \\ \frac{1}{2} \\ 0 \end{pmatrix}, (I_3 - P_S) \underline{v} = \begin{pmatrix} 0 \\ 0 \\ \frac{1}{2} \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ \frac{1}{2} \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ \frac{1}{2} \end{pmatrix} = 0$$

$$(P_S \underline{x})^T (I_3 - P_S) \underline{v}$$

$$= \underline{v}^T (P_S^T I_3 - P_S^T P_S) \underline{v}$$

$$= \underline{v}^T (P_S - P_S P_S) \underline{v} \quad - P_S^T = P_S$$

$$= \underline{v}^T O_{3 \times 3} \underline{v} = 0 \quad P_S^2 = P_S$$

Admiration

(A)

Proposition Projection matrix is an idempotent matrix

Let P_S be the projection of $S \subseteq V$

Only when $\Rightarrow \boxed{\forall \underline{v} \in W} - P_S \underline{v} = P_S (P_S \underline{v})$

$\Rightarrow P_S = P_S^2$

In: Projecor matrix has eigen values 1 & 0 only

Pf

Let 1 be an eigen value of P_S with nonzero eigen vector \tilde{v} then

$$\textcircled{1} \quad P_S \tilde{v} = \lambda \tilde{v} \quad \oplus$$

$$P_S \tilde{v} = P_S^2 \tilde{v} = P_S(P_S \tilde{v}) = P_S(\lambda \tilde{v}) = \lambda P_S \tilde{v} = \lambda^2 \tilde{v} \quad \textcircled{2}$$

$$\textcircled{1} - \textcircled{2}$$

$$\Rightarrow \tilde{v} = \lambda(1-\lambda)\tilde{v}$$

\tilde{v} is a non zero vector

$$\Rightarrow 0 = \lambda(1-\lambda) \Rightarrow \lambda = 1 \text{ or } 0$$

In If $\{v_1, v_2, \dots, v_k\}$ is an orthonormal basis
 $(\text{norm} = 1 \text{ & orthogonal to each other})$

$$P_S = \sum_{i=1}^k v_i v_i^T$$

is an orthogonal projection matrix for S^\perp

Proj now

Column space: The column space of $A = [a_1, a_2 \dots a_p]$

$$\begin{aligned} C(A) &= Sp\{a_1, a_2, \dots, a_p\} \\ &= \left\{ \sum_{i=1}^p x_i a_i \mid x \in \mathbb{R}^p \right\} \\ &= \left\{ Ax \mid x \in \mathbb{R}^n \right\} \end{aligned}$$

Row space of A is $R(A) = C(A^\top)$

Proof:

- ① $C(A+B) = C(A) + C(B)$
- ② $C(AB) \subseteq C(A)$
- ③ $\dim(C(A)) = \text{Rank}(A)$
- ④ $C(AA^\top) = C(A) \Rightarrow \text{Rank}(AA^\top) = \text{Rank}(A)$

⑤ If A has n columns then
 $\dim(C(A)^\perp) = n - \text{Rank}(A)$

Proof ⑤

Part 1 $C(AA^\top) \subseteq C(A)$ by ④

Part 2 Let $\underline{L} \in C(C(AA^\top))^\perp$

$$\Leftrightarrow \underline{L}^\top AA^\top = \underline{O}^\top \quad ①$$

$$\underline{L}^\top AA^\top \underline{L} = \underline{O}^\top \underline{L}$$

But

$$\text{d} \quad (\underline{A^T L})^T (\underline{A^T L}) = 0$$

$$\Rightarrow A^T L = 0$$

$$\Rightarrow A^T A = 0^T \quad \text{②}$$

$$\Leftrightarrow \mathcal{L} \in C(C(A))^T$$

$$C(C(A^T))^{\perp} \subseteq C(C(A))^{\perp}$$

For any matrix A the projection \mathcal{L} on $C(A)$ is $(AA^T)^{-1}A^T$ and the orthogonal projection matrix is $A(A^T A)^{-1}A^T$

① Positive definite matrix

An $n \times n$ is said to be a p.d. matrix

$$\text{if } \forall \underline{x} \quad \underline{x}^T A \underline{x} \geq 0 \quad \text{and} \quad \underline{x} \neq \underline{0}$$

② Positive semi-definite matrix

$$\text{if } \underline{x}^T A \underline{x} \geq 0 \quad \text{and} \quad \underline{x} \neq \underline{0}$$

$$\begin{aligned} \Leftrightarrow |A| > 0 &\quad \Leftrightarrow \text{pd. } \cancel{\text{diag}} \text{ matrix} \\ |A| \geq 0 &\quad \Leftrightarrow \text{p.s.d. matrix} \end{aligned}$$

Generalized inverse of a matrix A usually denoted by

G or A^- with prop that

$$AGA = A$$

$$A A^T A = A$$

- ① Need not be unique
- ② True for non square matrix also

Multivariate Analysis

Def 1 $\underline{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = (x_1, x_2, \dots, x_n)^T$

$$E(\underline{x}) = \begin{pmatrix} E(x_1) \\ E(x_2) \\ \vdots \\ E(x_n) \end{pmatrix} = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix} = \underline{u} = (u_1, u_2, \dots, u_n)^T$$

if $E(x_i) < \infty \quad i = 1, 2, \dots, n$

Def 2: Dispersion matrix of \underline{x} / variance & covariance of \underline{x}

$$D(\underline{x}) = ((\text{cov}(x_i, x_j)))_{ij}$$

$$= ((E(x_i x_j) - E(x_i) E(x_j)))_{ij}$$

$$= ((E(x_i x_j) - u_i u_j))_{ij}$$

Representation

$$\sum_{n \times m} \text{ or } \sum_{\infty}$$

→ dimension

Diagonal elements are the variances of the corresponding random variables, [but $i=j$ Note - you can't see its variance]

Not all elements are normal covariance

Properties

$$\textcircled{1} \quad \text{cov}(\tilde{u}_p, \tilde{v}_q) = ((\text{cov}(u_i, v_j)))_{ij}$$

dim : $p \times q$

$$= E \left(\underbrace{\tilde{u}_p \tilde{v}_q^T}_{\text{matrix}} \right) - \tilde{u}_p \tilde{v}^T$$

Column Row

$$= \text{cov}(\tilde{u}_p, \tilde{v}_q)$$

$$\textcircled{2} \quad E(\tilde{x} + \tilde{b}) = E(\tilde{x}) + \tilde{b}$$

where \tilde{b} is constant vector

$$\textcircled{3} \quad D(\tilde{x} + \tilde{b}) = D(\tilde{x}) \text{ where } \tilde{b} \text{ is constant vector}$$

$$\textcircled{1} \quad \text{cov}(\underline{x} + \underline{b}, \underline{y} + \underline{c}) = \text{cov}(\underline{x}, \underline{y}) \quad \text{where} \\ \underline{b}, \underline{c} \text{ are constant vector}$$

Product Rule

$$\textcircled{2} \quad E(\underline{l}^T \underline{x}) = \underline{\underline{l}}^T \underline{\underline{x}} \quad \text{where } \underline{l} \text{ is constant vector}$$

dot product

$$\textcircled{3} \quad D(\underline{l}^T \underline{x}) = \underline{l}^T \Sigma \underline{l} = \text{var}(\underline{l}^T \underline{x})$$

$$\textcircled{4} \quad E(A\underline{x}) = A\underline{\underline{x}}$$

↓
matix × vector = vector

$$\textcircled{5} \quad D(A\underline{x}) = A \Sigma A^T$$

$$\textcircled{6} \quad \text{cov}(U_p, V_q) = \Gamma = E(U_p \cdot V_q^T) - \cancel{E(U_p^T)} U_p \cancel{V_q^T}$$

then $\text{cov}(A\underline{U}, B\underline{V}) = A\Gamma B^T$

$$\Rightarrow \text{cov}(A\underline{x}, B\underline{x}) = A \Sigma B^T$$

Proof (B)

ECAZ)

$$= E[\underbrace{a_1 a_2 \dots a_n}_{\sim}] \begin{pmatrix} n_1 \\ n_1 \\ \vdots \\ n_n \end{pmatrix}$$

$$= E\left(\sum_{i=1}^n a_i a_i^\top\right) = \sum_{i=1}^n a_i a_i^\top = A \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{pmatrix} = A \tilde{u}$$

In: Show mat $D(\tilde{x})$ is positive semi definite matrix

$$D(\tilde{x}) = \Sigma$$

but $\ell \neq 0$ and we need to

prove mat $\tilde{\ell}^T \Sigma \tilde{\ell} \geq 0$

$$\Leftrightarrow \text{var}(\tilde{\ell}^T \tilde{x}) \geq 0$$

because variance of a random variable is non negative

In let $E(\tilde{x}) = \tilde{u}$ $D(\tilde{x}) = \Sigma$

$$P((\tilde{x} - \tilde{u}) \in G(\Sigma)) = 1$$

random

deterministic
linear combination

$$\left(\sum_n Y_n = \tilde{x} - \tilde{u} \right) \Rightarrow \tilde{x} = \tilde{u} + \sum Y_n$$

To prove that, it is enough to show that
any element in $C(C(\varepsilon))^\perp$ is
orthogonal to $(\underline{x} - \underline{y})$.

Let $\underline{l} \in C(C(\varepsilon))^\perp$

(from lecture notes) $\leftarrow l^T \underline{\zeta} = 0^T$

$$l^T \underline{\zeta} l = 0^T l = 0$$

$$\Rightarrow \text{Var}(l^T \underline{x}) = 0$$

$$\Rightarrow \text{Var}(l^T (\underline{x} - \underline{y})) = 0 \quad \textcircled{1}$$

& we know $E(l^T (\underline{x} - \underline{y})) = 0 \quad \textcircled{2}$

$$\Rightarrow P(l^T (\underline{x} - \underline{y}) = 0) = 1$$

$\Rightarrow \underline{l}$ is orthogonal to $(\underline{x} - \underline{y})$

Th: Let \mathbf{x} be a random vector with n components such that

$$\mathbb{E}(\mathbf{x}) = \mathbf{u}, \quad D(\mathbf{x}) = \Sigma \text{ and}$$

$$\text{rank } (\Sigma) = r \leq n -$$

If we assume that $\Sigma = \mathbf{B}\mathbf{B}^T$

such where \mathbf{B} is a $(n \times r)$ matrix

& \mathbf{C} is a left inverse of \mathbf{B}

$$\text{is } (\mathbf{C}_{(r \times n)} \mathbf{B}_{(n \times r)}) = I_r \text{ then defining}$$

$$\cdot \mathbf{y} = \mathbf{C}(\mathbf{x} - \mathbf{u}) \text{ we get}$$

$$\textcircled{1} \quad \mathbb{E}(\mathbf{y}) = 0$$

$$\textcircled{2} \quad D(\mathbf{y}) = I_r$$

$$\textcircled{3} \quad \mathbf{x} = \mathbf{u} + \mathbf{B}\mathbf{y} \text{ with prob 1}$$

C

$$\Sigma_{\text{encl}} = \Sigma^T$$

$$\Sigma = P D P^T$$

where P is an orthogonal matrix

$$D = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix}, \quad \lambda_i \geq 0$$

$$\Sigma_{ij} = \lambda_j P_{ji}$$

$$\Sigma^{1/2} = P D^{1/2} P^T$$

Multivariate Normal: A random vector X_n is said to follow multivariate normal if it has pdf

$$f(x) = \frac{e^{-\frac{1}{2} (x-\mu)^T \Sigma^{-1} (x-\mu)}}{\sqrt{(2\pi)^n |\Sigma|}}$$

$$E(X) = \mu \quad D(X) = \Sigma_{\text{encl}}$$

$$\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

Consider $\underline{x} \in \mathbb{R}^2$

$$E(\underline{x}) = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \quad D(\underline{x}) = \begin{bmatrix} \sigma_1^2 & \rho \sigma_1 \sigma_2 \\ \rho \sigma_1 \sigma_2 & \sigma_2^2 \end{bmatrix} = \Sigma_{2 \times 2}$$

$$f\left(\begin{pmatrix} n_1 \\ n_2 \end{pmatrix}\right) = \exp \left\{ -\frac{1}{2} (\underline{n} - \underline{u})^T \Sigma^{-1} (\underline{n} - \underline{u}) \right\}$$
$$\frac{(2\pi)^2 \sqrt{|\Sigma|}}{(2\pi)^2 \sqrt{\sigma_1^2 \sigma_2^2}}$$

$$= e^{-\frac{1}{2(1-\rho^2)} \left[\left(\frac{n_1 - u_1}{\sigma_1} \right)^2 + \left(\frac{n_2 - u_2}{\sigma_2} \right)^2 - 2\rho \frac{(n_1 - u_1)(n_2 - u_2)}{\sigma_1 \sigma_2} \right]} \frac{1}{2\pi \sigma_1 \sigma_2 \sqrt{1-\rho^2}}$$

Let \underline{x} be random vector in \mathbb{R}^n

$A \cong$ matrix $n \times n$

$$E(\underline{x}) = \underline{u} \quad \& \quad D(\underline{x}) = \Sigma$$

$$E(\underline{x}^T A \underline{x}) = \text{tr}(A \Sigma) + \underline{u}^T A \underline{u}$$

$$E(\underline{x}^T A \underline{x}) \Rightarrow E[\text{tr}(A \Sigma)]$$

As this
is scalar

$$\text{so } \underline{x}^T A \underline{x} = \text{tr}[A \Sigma]$$

$$= E \left[\underbrace{\text{tr}(\theta)}_{\substack{\text{Scalar} \\ \text{multiplier}}} \underbrace{xx^T}_{\substack{\text{random pars}}} \right]$$

$$x^T A x \rightarrow \text{Quadratic form}$$

$$\sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j$$

$$= +\theta [A E(x x^T)]$$

$$E(x) = \sum -E(x_i) \frac{u u^T}{n}$$

$$= +\theta [A (\varepsilon + U U^T)]$$

$$= \text{tr}(A \varepsilon) + \text{tr}(A \underbrace{U U^T}_{\text{as done}}) \quad \begin{matrix} \text{Extractor} \\ \text{in } \text{tr}(A x x^T) \end{matrix}$$

$$= \text{tr}(A \varepsilon) + \text{tr}(U^T A \underbrace{U}_{\text{--- ①}})$$

$$= \text{tr}(A \varepsilon) + (\underbrace{U^T A U}_{\text{--- ①}})$$

when $x_1, x_2, \dots, x_n \sim i.i.d N(0, I_n)$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \sim N(\theta, I_n)$$

$$\begin{aligned} E \left(\sum_i x_i^2 \right) &= E(x^T I_n x) \\ &\stackrel{\text{sumation}}{=} \text{tr}(I_n I_n) + \underbrace{Q^T I_n Q}_{\text{done ②}} \\ &= n + 0 \end{aligned}$$

$$\sum_{i=1}^n E(x_i^2) = n$$

$x_i \sim N(u, 1)$

$\Rightarrow \epsilon \sim I_n$

$$E(\epsilon x_i^2)$$

$$A = I_n$$

$$U = U \begin{pmatrix} 1 \\ & 1 \\ & & 1 \end{pmatrix}$$

$$= \text{tr}(A\epsilon) + U^T A U$$

$$= \text{tr}(I_n I_n) + U \begin{pmatrix} 1 \\ & 1 \\ & & 1 \end{pmatrix} I_n U$$

$$= n + u^2 n = (1 + u^2)n$$

$\frac{1}{n} \sum x_i \sim N(u, 1)$ f m debeden

$$\text{then } E(\epsilon x_i^2) = n + U^T I_n U$$

$$= n + \sum_{i=1}^n u_i^2$$

$\frac{1}{n} \sum x_i^2 \sim \chi_n^2$ then $\sum_{i=1}^n x_i^2 \sim \chi_n^2$

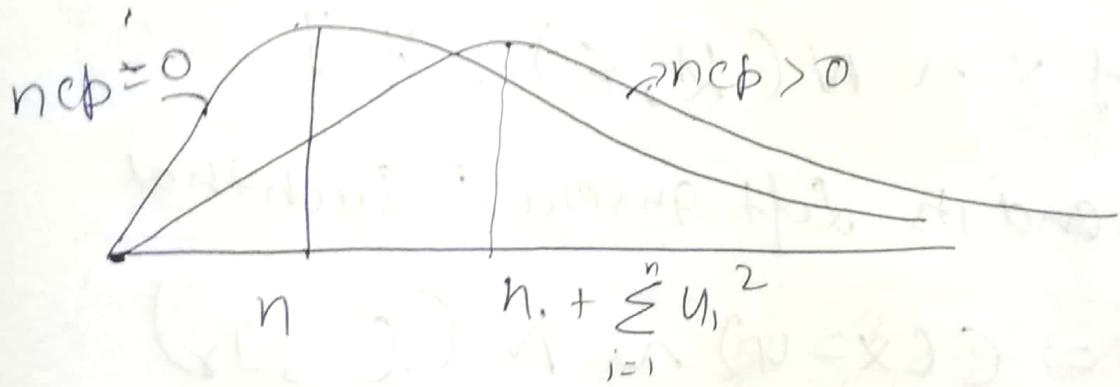
$x_i \sim N(u_i, 1)$ then

and $x_i \sim N(u_i, 1)$ then $\sum_{i=1}^n x_i^2 \sim \chi_{df=n}^2$
 $\sum_{i=1}^n u_i^2 \sim \chi_{df=n}^2$

non centrality parameter $\Delta = ncb$

$$n \leq n + \sum_{j=1}^n u_j^+ u_j$$

$$E\left(\chi^2_{df=n, ncp=0}\right) \leq E\left(\chi^2_{df=n, ncp=\sum_{j=1}^n u_j^+ u_j}\right)$$



④ If $\tilde{X} \sim N(\mu, \Sigma_n)$ then

$$\tilde{X}^\top A \tilde{X} \sim \chi^2_{df = \text{rank}(A)} \\ ncp = \tilde{U}^\top A \tilde{U}$$

if A is an idempotent matrix

- (Eq 2)

Result

① If $\underline{x} \sim N(\underline{u}, \Sigma)$

$$\underline{A}\underline{x} \sim N(A\underline{u}, A\Sigma A^T) \quad \text{with} \quad \begin{aligned} \text{Var}(A\underline{x}) &= A\Sigma A^T \\ E(A\underline{x}) &= A\underline{u} \end{aligned}$$

② If $\underline{x} \sim N(\underline{u}, \Sigma)$, $\underline{y} \in$

\mathbb{B} and its left inverse \mathbb{C} such that

$$\underline{y} = \mathbb{C}(\underline{x} - \underline{u}) \sim N(\underline{\varrho}, \mathbb{I}_n)$$

$$\underline{x} = \underline{u} + \mathbb{B}\underline{y} \quad \text{with probability } 1$$

③ If A_1, A_2 symmetric & idempotent matrix such that $\mathbb{Q} = A_1 - A_2$ is p.s.d then

$\underline{x}^T \mathbb{Q} \underline{x}$ & $\underline{x}^T A_2 \underline{x}$ are independent

$$A_1 = \mathbb{Q} + A_2, \quad |\mathbb{Q}| \geq 0$$

for normally distributed \underline{x}

④ If $A = A^T$ and $CA = 0$ mtrank
(symmetric)

then $x^T A x$ & Cx are independent

rank
result

$x \sim N(0, 1) \rightarrow$ independent

$y \sim X_n^2$

$\frac{x}{\sqrt{n}} \sim t_n$

$\bar{x} \neq S^2 = \sum (x_i - \bar{x})^2$

are always independent

26/7/19

x_1, x_2, \dots, x_n iid $N(\mu, \sigma^2)$

Naive prediction: $\hat{x} = \frac{1}{n} \sum_{i=1}^n x_i$

Square error = $\frac{1}{n} \sum_{i=1}^n (x_i - \hat{x})^2$ ↗
why
→ (don't worry about this just a scaling factor?)

we are interested for the independence of \hat{x} & $S^2 = \sum_{i=1}^n (x_i - \hat{x})^2$

$$\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i = \left(\frac{1}{n} - \frac{1}{n} \right) \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

$$\hat{\ell} = \frac{1}{n} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}^T \tilde{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \Rightarrow \tilde{x} = \hat{\ell}^T \tilde{x}$$

$$\hat{\ell} = \frac{1}{n} \tilde{1} \quad \hat{\ell}^T \tilde{1}$$

$$S^2 = \sum_{i=1}^n (x_i - \bar{x})^2 \Leftrightarrow \tilde{x}^T A \tilde{x} \quad ??$$

$$P = \left(I_n - \frac{1}{n} \tilde{1} \tilde{1}^T \right)$$

$$\begin{aligned}
\tilde{x}^T P \tilde{x} &= \tilde{x}^T \left(I_n - \frac{1}{n} \tilde{1} \tilde{1}^T \right) \tilde{x} \\
&= \tilde{x}^T I_n \tilde{x} - \frac{1}{n} (\tilde{x}^T \tilde{1})(\tilde{1}^T \tilde{x}) \\
&= \sum_{i=1}^n x_i^2 - \frac{1}{n} \left(\sum_{i=1}^n x_i \right) \left(\sum_{i=1}^n x_i \right) \quad \boxed{n \bar{x} = \sum_{i=1}^n x_i} \\
&= \sum_{i=1}^n x_i^2 - \frac{1}{n} n \bar{x} \cdot n \bar{x} = \sum_{i=1}^n (x_i^2) - n \bar{x}^2 \\
&= \sum_{i=1}^n (x_i - \bar{x})^2 = S^2
\end{aligned}$$

$$\textcircled{1} \quad \ell^T P = 0^T \quad \textcircled{2} \quad P^T = P \quad \textcircled{3} \quad P^2 = P \xrightarrow{\text{as } n \rightarrow \infty} N(\mu, I_n)$$

$$X^T A X \sim \chi_{df, ncp}^2$$

$$\textcircled{1} \quad \frac{1}{n} \underline{1}^T \left(I_n - \frac{1}{n} \underline{1} \underline{1}^T \right) \\ - \frac{1}{n} \underline{1}^T \left(\underline{1}^T - \underline{1}^T \right) = 0^T$$

\downarrow
if A is ~~symmetric~~

$$\textcircled{2} \quad P^T = \left(I_n - \frac{1}{n} \underline{1} \underline{1}^T \right)^+ \\ = \left(I_n - \frac{1}{n} (\underline{1}^T \underline{1})^T \right) = P$$

$$\textcircled{3} \quad P^2 = P$$

$$X \sim N(\mu, \Sigma)$$

$$\sim \sim N(\mu, \rho \Sigma P^T) - \text{from result } \textcircled{1} \text{ in eqn}$$

\downarrow

from $\textcircled{1} \quad \textcircled{2} \quad \textcircled{3}$

$$\textcircled{1} \quad \text{As } \ell^T P = 0^T \quad \& \quad P^T = P$$

$$\ell^T X = \overbrace{X}^{\text{and independently distributed}} \quad \& \quad X^T P X = S^2$$

$$\textcircled{2} \quad \bar{x} = \underline{\ell}^T \underline{x} \sim N(\underline{\ell}^T \underline{u}, \sigma^2 \underline{\ell}^T \underline{J}_n \underline{\ell})$$

$A \in \mathbb{R}^T \quad A = \underline{\ell}$

$$\begin{bmatrix} \underline{u} = \underline{u} - \underline{1} \\ \underline{\ell} = \frac{1}{n} \underline{1} \end{bmatrix}$$

$$\equiv N(\underline{u}, \frac{\sigma^2}{n})$$

$$\begin{aligned} & \frac{1}{n} \underline{1}^T \underline{1} \underline{1} \\ &= \left(\frac{1}{n} \right)^2 \underline{1}^T \underline{1} \\ &= \frac{1}{n} \end{aligned}$$

$$\textcircled{3} \quad S^2 = \sum_{i=1}^n (x_i - \bar{x})^2$$

$$= \underline{x}^T P \underline{x}$$

$$\therefore \frac{S^2}{\sigma^2} = \frac{\underline{x}^T P \underline{x}}{\sigma^2}$$

$$= \underline{y}^T P \underline{y}$$

$$\frac{S^2}{\sigma^2} \sim \chi^2_{df} = \text{rank}(P)$$

neb $\epsilon U^* \underline{1}^T \underline{1} \underline{1}^T P \underline{1}$

Now

$$\underline{x} \sim N(\underline{u}, \sigma^2 \underline{J}_n)$$

$$x_i \sim N(u_i, \sigma^2)$$

to get Result
acc to eq 2
we need scale down
as varia us $\sigma^2 J_n$ in
eq 2

$$\begin{aligned} y_i &= \frac{x_i}{\sigma} \\ \underline{y} &\sim \left(\frac{\underline{u}}{\sigma} \right) \underline{1}^T, \underline{J}_n \\ \therefore \underline{y} &\sim N\left(\frac{\underline{u}}{\sigma} \underline{1}^T, \underline{J}_n\right) \end{aligned}$$

$$\text{rank}(P) = m-1 \rightarrow \text{Now}$$

$$(U^T)^2 \underline{1}^T P \underline{1}$$

$$= \underline{1}^T \left(I_n - \frac{1}{n} \underline{1} \underline{1}^T \right) \underline{1}$$

$$= \underline{1}^T \underline{1} - \frac{1}{n} (\underline{1}^T \underline{1}) \cdot (\underline{1}^T \underline{1})$$

$$= \frac{n}{n} - \frac{1}{n} n n = 0$$

$$\frac{s^2}{\sigma^2} \stackrel{\text{df}=n-1}{\sim} \chi^2_{n-1} \Rightarrow s^2 \sim \sigma^2 \chi^2_{n-1}$$

~~ncp = 0~~

$$⑨ t = \frac{\sqrt{n}(\bar{x} - u)}{\sqrt{s^2/n}} = \frac{(\bar{x} - u)}{\frac{s^2}{\sigma^2(n-1)}}$$

$$\bar{x} \sim N(u, \frac{\sigma^2}{n}) \Rightarrow \frac{(\bar{x} - u)}{\frac{s^2}{\sigma^2(n-1)}} \sim N(0, 1)$$

$\frac{s^2}{\sigma^2} \sim \chi^2_{n-1}$ ncp = 0 and they are independent
indepnt fr t_{n-1} , ncp = 0

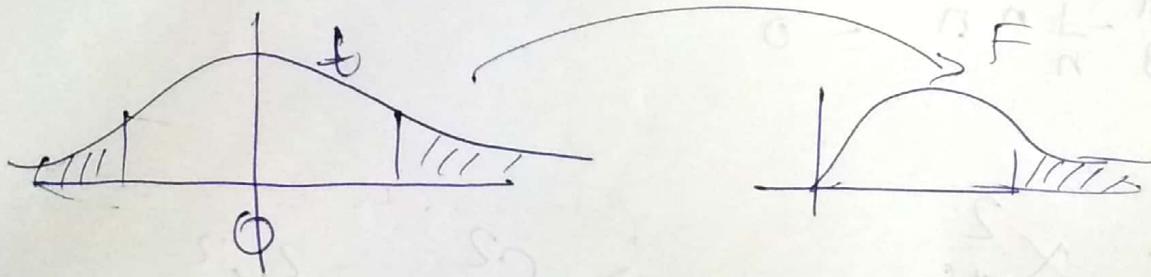
* is used to do testing about u when σ is unknown

$$x \sim X_n^2$$

$$y \sim X_m^2 \quad \text{independent}$$

$$\hat{\epsilon}^2 = \frac{(N(0,1))^2}{X_{n-1/n-1}^2} = \frac{X_1^2/1}{(X_{n-1/n-1}^2)^T}$$

$$= F_{1, n-1}$$



both tautest

Th $x \sim N(\mu, I_n)$ & $x^T A_i x = \sum_{i=1}^k x^T A_i x$

when $A_i^T = A_i$ & $A^T A$ non

$$x^T A_i x \sim \chi^2_{df = \text{rank}(A_i)}$$

$$n \in \mathbb{R} = \sum A_i x$$

f Each A_i are independent

$$Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

↓ ↗
Random Known
Random ↗
non random ↗
(all unknown)

$$\epsilon_i \sim N(0, \sigma^2)$$

Gauss markov model : Unknown parameters
 $\beta_0, \beta_1, \sigma^2$

We can get a numerical value from data or estimates
 $\hat{\beta}_0, \hat{\beta}_1, \sigma^2$, but to do testing we need their
 distribution

Eg Hypothesis: $H_0: \beta_0 = 0$
 $H_1: \beta_0 \neq 0$

Simple linear regression

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i \quad i=1 \dots n$$

D = $\{(y_i, x_i)\}, i=1 \dots n\}$ known data set

unknown: B_0, B_1, σ^2 where
 $\epsilon_i \sim N(0, \sigma^2)$

If ϵ_i follows $N(0, \sigma^2)$ then it is known as Gauss
markov model

$$\tilde{Y} = \begin{pmatrix} Y_1 \\ \vdots \\ Y_n \end{pmatrix}, \tilde{\epsilon} = \begin{pmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{pmatrix}, \tilde{B} = \begin{pmatrix} B_0 \\ B_1 \end{pmatrix}, X = \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix}$$

$$\tilde{Y} = X\tilde{B} + \tilde{\epsilon}$$

$$\tilde{\epsilon} \sim N(0, \sigma^2 I_n)$$

$$\boxed{\tilde{Y} \sim N(X\tilde{B}, \sigma^2 I_n)}$$

* Y_i is independent but not identically distributed

Estimation of B_0, B_1, σ^2

- ① Least square method
- ② Maximum likelihood method

Estimated Value of
 B_0, B_1 same
in Both case
but not σ^2

Least square method

LS condition is to minimize

$$\begin{aligned}
 S(\beta_0, \beta_1) &= \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2 \\
 &= \| \underline{y} - \underline{x} \underline{\beta} \|_2^2 \\
 &= (\underline{y} - \underline{x} \underline{\beta})^\top (\underline{y} - \underline{x} \underline{\beta})
 \end{aligned}$$

$$\begin{pmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{pmatrix} = \underset{(\beta_0, \beta_1)}{\arg \min} S(\beta_0, \beta_1)$$

$$\frac{\partial f^T A}{\partial \underline{\beta}} = A^T$$

$$\frac{\partial f^T A \underline{\beta}}{\partial \underline{\beta}} = b^T (A + A^T)$$

$$\begin{aligned}
 &= (\underline{y}^T - \underline{\beta}^T \underline{x}^T) (\underline{y} - \underline{x} \underline{\beta}) \\
 &= \underline{y}^T \underline{y} - \underline{y}^T \underline{x} \underline{\beta} - \underline{\beta}^T \underline{x}^T \underline{y} - \underline{\beta}^T \underline{x}^T \underline{x} \underline{\beta}
 \end{aligned}$$

$$\frac{\partial S}{\partial \underline{\beta}} = 0 \Rightarrow \underline{x}^T \underline{y} = \underline{x}^T \underline{x} \hat{\underline{\beta}} \quad | \text{ normal equation}$$

$$\boxed{\hat{\underline{\beta}} = (\underline{x}^T \underline{x})^{-1} \underline{x}^T \underline{y}}$$

④ $(\underline{x}^T \underline{x})$ will not be invertible if all x_i values are same or (2 columns of \underline{x} are linear combinations of each other)

Since one column is $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$ the other must be

scalar multiple of other $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow$ all x_i are same

After solving ① ~~②~~ ③ we get

$$\hat{B}_0 = \bar{y} - \hat{B}_1 \bar{x}$$

$$\hat{B}_1 = \frac{\sum_{i=1}^n b_i y_i - n \bar{x} \bar{y}}{\sum_{i=1}^n b_i^2 - n \bar{x}^2} = \frac{s_{xy}}{s_{xx}}$$

Refine $s_{xy} = \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})$

$$= \sum_{i=1}^n (x_i - \bar{x})y_i - \bar{y} \sum_{i=1}^n (x_i - \bar{x})$$
$$= \sum_{i=1}^n x_i^o y_i = \sum_{i=1}^n x_i^o (y_i - \bar{y})$$

w

Production

$$\hat{y}_i = \hat{B}_0 + \hat{B}_1 x_i \quad \forall i = 1, \dots, n$$

$$\hat{y} = x \hat{B}$$

$$\hat{y} = x(x^T x)^{-1} x^T y = P_x y$$

$$y = P_x y$$

* \hat{y} is the orthogonal of y on the column space of x in $\mathcal{C}(x)$

The error vector in this LS production

$$\text{is } \hat{\epsilon} = y - P_x y \\ = (I_n - P_x)y$$

\Rightarrow ① $\hat{\epsilon}$ is orthogonal to \hat{y}

② Although ϵ cov matrix In^2

ϵ does not have independent component

$$y \sim N(x_B, \sigma^2 I_n)$$

$$\tilde{e} = (I - P_X) y \sim N(\tilde{e}, \sigma^2 (I_n - P_X))$$

$$\hat{y} = P_X y \sim N(x_B, \sigma^2 P_X^T P_X)$$

$$\sim N(x_B, \sigma^2 P_X)$$

$$= P_X^T P_X = P_X$$

$$P_X = X(X^T X)^{-1} X^T \times (X^T X)^{-1} X^T$$

$$\longleftrightarrow$$

$$= X(X^T X)^{-1} X^T = P_X$$

$$\tilde{e} = (I - P_X) y \quad y \sim N(x_B, \sigma^2 I_n)$$

$$\tilde{e} \sim N((I - P_X)x_B, \sigma^2 (I - P_X)^T I_n (I - P_X))$$

$$= N((x - x_B) B)$$

$$P_{\text{ex}} = \alpha$$

SLR

$$S = (\tilde{y} - \tilde{x}\tilde{\beta})^T (\tilde{y} - \tilde{x}\tilde{\beta}) \\ = \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2$$

$$\hat{\tilde{\beta}} = \arg \min \tilde{S}(\tilde{\beta})$$

$$\boxed{\hat{\tilde{\beta}} = (x^T x)^{-1} x^T y}$$

Normal equation
 $x^T y = x^T x \tilde{\beta}$

$$\hat{y} = \hat{x}\hat{\beta} = x(x^T x)^{-1} x^T y = P_x y$$

$$\hat{\epsilon} \sim N(\hat{\beta}, \sigma^2 P_x)$$

$$\hat{\epsilon} = u - \hat{y} = (I_n - P_x)u$$

$$\hat{\epsilon} \sim N(\hat{\epsilon}, (I_n - P_x)\sigma^2)$$

* $(x^T x)$ is invertible

$$y \sim N(\tilde{x}\tilde{\beta}, \sigma^2 I_n)$$

$$u \sim N(0, \Sigma)$$

$$z \sim N(Au, A\Sigma A^T)$$

$$\hat{\beta} \sim N(\beta, (x^T x)^{-1} \sigma^2)$$

$$\hat{\beta} \sim N(\beta, (x^T x)^{-1} \sigma^2)$$

Format from normal equation unknown

$$\hat{B}_1 = \frac{S_{xy}}{S_{xx}}$$

$$\hat{B}_0 = \bar{y} - \hat{B}_1 \bar{x}$$
4N

$$\hat{B}_1 = \frac{S_{xy}}{S_{xx}} = \frac{\sum_{i=1}^n (y_i - \bar{y})(x_i - \bar{x})}{S_{xx}}$$

$$= \sum_{i=1}^n \frac{y_i (x_i - \bar{x})}{S_{xx}}$$

$$\text{Let } \frac{(x_i - \bar{x})}{S_{xx}} = \alpha_i$$

$$\text{when } \alpha_i = \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{pmatrix}$$

$$= \sum_{i=1}^n y_i \alpha_i$$

$\hat{B}_1 = \underline{x}^T y \rightarrow$ linear estimator so
 B_1 has demar as α_i to B_1

as we $y \sim N(\underline{x}B, \sigma^2 I_n)$

$$\hat{B}_1 \sim N(\underline{\alpha}^T \underline{x} B, \sigma^2 \underline{\alpha}^T I_n \underline{\alpha})$$

$\cancel{\sum_{i=1}^n \alpha_i = 0}$

$\rightarrow \cancel{\alpha^T \sum_{i=1}^n x_i - n \bar{x} = 0}$

$$\Rightarrow \sum_{i=1}^n \alpha_i^* = 0$$

$$\Rightarrow \underline{1}^T \underline{\alpha}^* = \underline{\alpha}^T \underline{1} = 0$$

$$= \underline{\alpha}^T \underline{x}$$

$$= \sum_{i=1}^n \alpha_i^* x_i^*$$

$$= \sum_{i=1}^n \frac{(x_i^* - \bar{x}) x_i^*}{S_{xx}} = 1$$

$$\cdot \hat{B}_1 \sim N(\underline{\alpha}^T \underline{x} B_1, \sigma^2 \underline{\alpha}^T \underline{I} \underline{n} \underline{\alpha})$$

$$\sim N((\underline{\alpha}^T \underline{I})^0, \underline{\alpha}^T \underline{X}, \sigma^2 \underline{\alpha}^T \underline{\alpha})$$

$$\sim N(B_1, \sigma^2 \frac{S_{xx}}{S_{nn}^2})$$

$$\underline{\alpha}^T \underline{\alpha} = \sum \frac{(x_r - \bar{x})^2}{S_{nn}^2}$$

$\Rightarrow \hat{B}_1$ is an unbiased linear estimator of B_1

$$B_0 = \bar{y} - \hat{B}_1 \bar{x} = \underline{\alpha}^T \underline{y} = \sum_{i=1}^n c_i^* y_i$$

$\Rightarrow \hat{B}_0$ is an unbiased, linear estimator of B_0
(H.W.)

hw

Ⓐ $\hat{\beta}_0$ & $\hat{\beta}_1$ may be dependent
 Find the $\text{cov}(\hat{\beta}_0, \hat{\beta}_1)$ now
 which means $\text{cov}(1, 2) \text{ or } (2, 1)$ elements
 $\sigma^2(X^T X)^{-1}$

Error $\tilde{\epsilon} = (\tilde{y} - \tilde{g}) \sim N(0, (I_n - P_X)\sigma^2)$

$$P_X = X(X^T X)^{-1} X^T$$

$$\tilde{\epsilon} = (\tilde{y} - \tilde{g}) \perp (I - P_X)\tilde{y}$$

Prove

$$\textcircled{1} \quad P_X^T = P_X \quad (\text{just prove at earlier})$$

$$\textcircled{2} \quad P_X^2 = P_X$$

Sum and cross terms

P_X has rank 2

$I - P_X$ has rank $(n-2)$

$$\sum_{i=1}^n \tilde{\epsilon}^2 = \tilde{\epsilon}^T \tilde{\epsilon} = [(\tilde{y} - P_X \tilde{y})]^T [(\tilde{y} - P_X \tilde{y})] = \tilde{y}^T (I - P_X) \tilde{y}$$

$$\frac{ESS}{\sigma^2} = \frac{\mathbf{y}^T (\mathbf{I}_{n-p_x}) \mathbf{y}}{\sigma^2}$$

$$\sim \chi^2_{df} = \text{rank}((\mathbf{I}_{n-p_x}) \mathbf{J}_n)$$

$$ncp = \frac{(\mathbf{x}^T \mathbf{B})^T (\mathbf{J}_{n-p_x}) (\mathbf{x}^T \mathbf{B})}{\sigma^2}$$

If A is an independent matrix from

$$\mathbf{Z} \sim N(0, \mathbf{A}\mathbf{E}\mathbf{A}^T), \mathbf{U}^T \mathbf{A} \mathbf{U} = \frac{\chi^2_{df}}{\sigma^2}$$

$$\sim \frac{\mathbf{Z}^T \mathbf{A} \mathbf{Z}}{\sigma^2} \sim \frac{\chi^2_{df}}{\sigma^2}, \mathbf{U}^T \mathbf{A} \mathbf{U} = \frac{\chi^2_{df}}{\sigma^2}$$

$$df = \frac{n-2}{(s-n)} = \frac{(223)}{5-2} = 50$$

$$ncp = \frac{(\mathbf{B}^T \mathbf{x}^T (\mathbf{J}_{n-p_x}) \mathbf{x}^T \mathbf{B})}{\sigma^2}$$

$$= \frac{\mathbf{B}^T (\mathbf{x}^T \mathbf{x} - (\mathbf{x}^T \mathbf{x})^T (\mathbf{x}^T \mathbf{x})) \mathbf{B}}{\sigma^2}$$

$$ncp = \frac{\mathbf{B}^T \mathbf{B}}{\sigma^2}$$

$$\frac{ESS}{\sigma^2} \sim \chi_{n-2, 0}^2$$

$$ESS \sim \sigma^2 \chi_{n-2, MCP=0}^2$$

$$\hat{B}_1 \sim N(B_1, \frac{\sigma^2}{S_{nn}})$$

$$\hat{B}_0 \sim N(B_0, (\frac{1}{n} + \frac{\bar{x}^2}{S_{nn}}) \sigma^2) \text{ if } n > 1$$

$$ESS \sim \sigma^2 \chi_{n-2, MCP=0}^2$$

$$\hat{\sigma}^2 = \frac{ESS}{n-2} = \frac{\sum (y - \hat{y}_i)^2}{n-2}$$

A $\hat{\sigma}^2$ is an unbiased estimator of σ^2

$$E(\hat{\sigma}^2) = E\left(\frac{ESS}{n-2}\right) = \sigma^2 \frac{(n-2)}{(n-2)} = \sigma^2$$

① \hat{Q} and \hat{G} are orthogonal to each other and distributionally they are independent

$$\hat{G} \sim N(XB, \sigma^2 P_X)$$

$$\hat{Q} \sim N(CQ, \sigma^2 (I_n - P_X))$$

if mean vector is 0/w 2 Normal dist
distribution is zero they will be
independent (completely - not only linear)

independent

$$\text{cov}(\hat{x}, \hat{y})$$

use $\text{cov}(AX, BX) = A \Sigma B^T$

$$\hat{y} = P_X Y$$

$$\hat{x} = (I - P_X) Y$$

$$Y \sim N(XB, \sigma^2 I_n)$$

$$\text{cov}(AY, BY)$$

$$= (A I B^T)^2$$

$$\Rightarrow \text{cov}(\hat{y}, \hat{x}) = P_X I_n (I_n - B^T) \sigma^2$$

$$= P_X I_n (I_n - P_X) \sigma^2$$

$$= (P_X - P_X^2) \sigma^2$$

$$= (P_X - P_X) \sigma^2 = 0 \text{ matrix}$$

}
independent

$$(P_X Y)^T (I - P_X^T Y) = Y^T P_X (I - P_X^T Y) Y$$

(orthogonal - $P_X^T Y = 0$)

\Rightarrow orthogonal

we have Data $\{(x_i, y_i) \mid i=1, \dots, n\}$

From there we get \hat{B}_0, \hat{B}_1 & LS estimate

so the prediction line $\hat{y} = \hat{B}_0 + \hat{B}_1 x$

Now for a new value no underlying same model, we can predict the value
value of y_0 as follows

$$\hat{y}_0 = \hat{B}_0 + \hat{B}_1 x_0$$

Although $y_0 \sim N(\hat{B}_0 + \hat{B}_1 x_0, \sigma^2)$

But we only know x_0, B_0, B_1 and
only estimated

$$\hat{y}_0 = \hat{B}_0 + \hat{B}_1 x_0$$

$$= \bar{y} + \hat{B}_1 x + \hat{B}_1 x_0$$

$$\text{as } \hat{B}_0 = \bar{y} - \hat{B}_1 x$$

$$\boxed{\begin{aligned}\hat{B}_1 &= \alpha^T y \\ \bar{y} &= \frac{1}{n} \sum y_i\end{aligned}}$$

$$\begin{aligned}E(\hat{y}_0) &= (\bar{B}_0 + \hat{B}_1 \bar{x}) + \hat{B}_1 (x_0 - \bar{x}) \\ &= \bar{B}_0 + \hat{B}_1 x_0\end{aligned}$$

↓

\hat{y}_0 is an unbiased estimator of y_0

$$\text{Var}(\hat{y}_0) = \text{Var}(\bar{y}) + (x_0 - \bar{x})^2 \text{Var} \hat{B}_1$$

$$+ 2 \cdot \text{cov}(\bar{y}, \hat{B}_1) (x_0 - \bar{x})$$

$$\downarrow \text{above}$$

$$= \frac{\sigma^2}{n} + (x_0 - \bar{x}) \frac{\sigma^2}{S_{nn}} + 0$$

$$\hat{y}_0 \sim N(C(\bar{B}_0 + \hat{B}_1 x_0), \sigma^2 \left(\frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{nn}} \right))$$

$$E(\bar{y}) = E\left(\frac{1}{n} \sum y_i\right) = \frac{1}{n} (B_0 + B_1 \bar{x})$$

Hypothesis problem

$$H_0: \beta_0 = b_0$$

$$H_1: \beta_0 \neq b_0$$

$$\hat{\beta}_0 \sim N\left(\beta_0, \sigma^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}\right)\right)$$

Testing mean

$$\frac{\hat{\beta}_0 - \beta_0}{\sqrt{\sigma^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}\right)}} \sim N(0, 1)$$

Under H_0

$$\frac{\hat{\beta}_0 - b_0}{\sigma \sqrt{\left(\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}\right)}} \sim N(0, 1)$$

But when who put me in mind
estimated σ we get a
the estimator

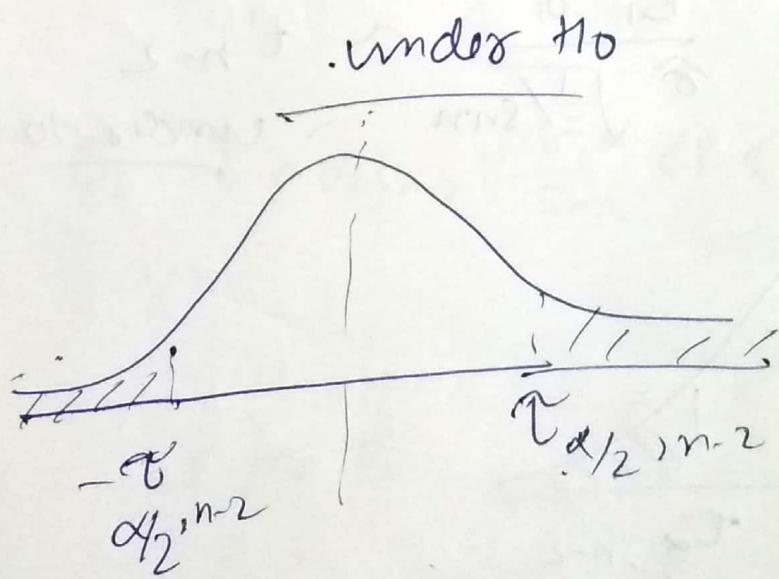
Look it is really beautiful

$$S^2 = \frac{1}{n} \sum_{i=1}^n (\hat{y}_i - y_i)^2 \rightarrow \text{you are getting sum of squares}$$

$$= \frac{\sum (y_i - \bar{y})^2}{S_{yy}} \rightarrow \text{here you are getting error without even semicolon}$$

Estimated average error

$$T = \frac{\hat{B}_0 - b_0}{\hat{\sigma} \sqrt{\frac{1}{n} + \frac{x}{S_{yy}}}} \sim t_{n-2}$$



$$H_0: B_0 = b_0$$

$|T_{obs}| > T_{\alpha/2, n-2}$, we reject H_0
in favor of H_1 at level α
asym. CI for B_0 ??

$$B_1 = 0 \text{ or } n_1$$

H₀: $B_1 = b_1$

$$H_1: B_1 \neq b_1$$

$$\frac{\hat{B}_1 - B_1}{\sqrt{\frac{\sigma^2}{S_{nn}}}} \sim N(0, 1)$$

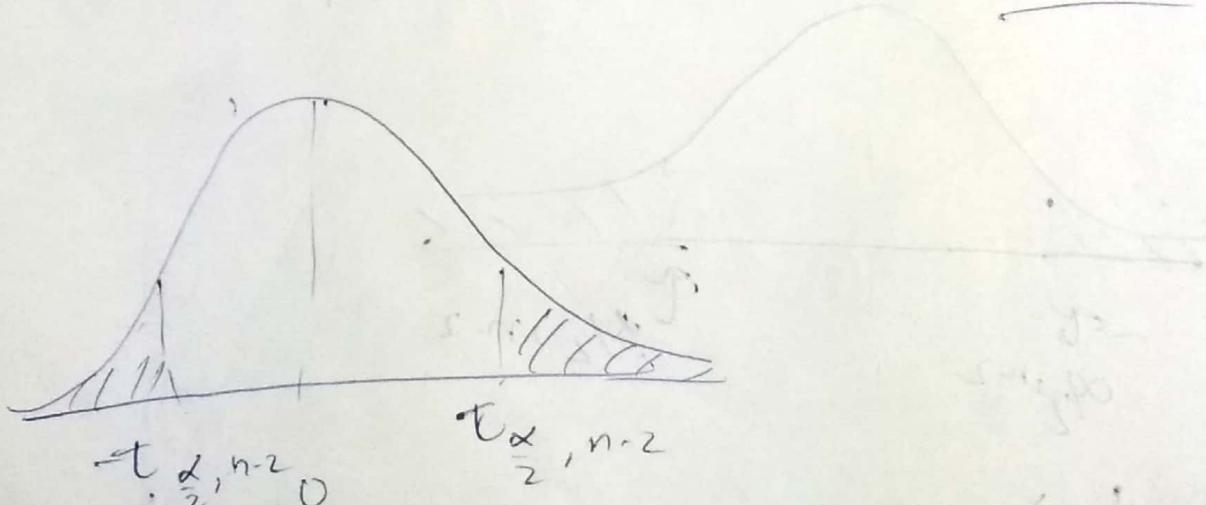
x variable does
not have any impact

g

Under H₀, $\frac{\hat{B}_1 - b_1}{\sqrt{\frac{\sigma^2}{S_{nn}}}} \sim N(0, 1)$

But σ^2 is unknown and $\hat{\sigma}^2 = \frac{ESS}{n-2}$

Hence $T = \frac{\hat{B}_1 - b_1}{\hat{\sigma} \sqrt{\frac{1}{S_{nn}}}} \sim t_{n-2}$ under H₀



If $|T_{ob}| > t_{\alpha/2, n-2}$ then we reject H₀ in favour of H₁.

95% CI for β_1

$$T = \frac{\hat{\beta}_1 - \beta_1}{\sqrt{\hat{\sigma}^2 / s_{nn}}} \sim t_{n-2}$$

$$P(-t_{0.025, n-2} < T < t_{0.025, n-2}) = 0.95$$

$$P(-t_{0.025, n-2} < \frac{\hat{\beta}_1 - \beta_1}{\sqrt{\hat{\sigma}^2 / s_{nn}}} < t_{0.025, n-2}) = 0.95$$

$$P(\hat{\beta}_1 - t_{0.025, n-2} \sqrt{\frac{\hat{\sigma}^2}{s_{nn}}} < \beta_1 < \hat{\beta}_1 + t_{0.025} \sqrt{\frac{\hat{\sigma}^2}{s_{nn}}}) = 0.95$$

95% LI for β_0

$$P(\hat{\beta}_0 - t_{0.025, n-2} \sqrt{\hat{\sigma}^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{s_{nn}} \right)} < \beta_0 < \hat{\beta}_0 + t_{0.025, n-2} \sqrt{\hat{\sigma}^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{s_{nn}} \right)}) = 0.95$$

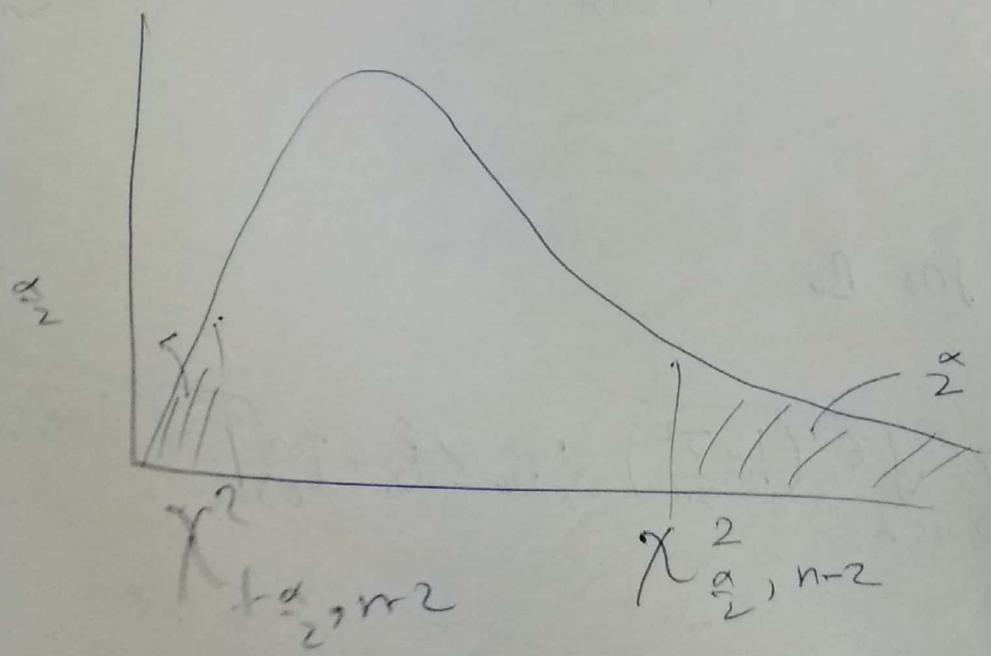
Q.S. v. C.F. for σ^2

$$\hat{\sigma}_e^2 = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n-2} = \frac{ESS}{n-2}, \quad \frac{ESS}{\sigma^2} \sim \chi^2_{n-2}$$

$$P\left(\chi^2_{1-\frac{\alpha}{2}, n-2} < \frac{ESS}{\sigma^2} < \chi^2_{\frac{\alpha}{2}, n-2}\right) = 1-\alpha$$

$\alpha = 0.05$

$$P\left(\frac{ESS}{\chi^2_{\frac{\alpha}{2}, n-2}} < \sigma^2 < \frac{ESS}{\chi^2_{1-\frac{\alpha}{2}, n-2}}\right) = 1-\alpha$$



Prediction Interval of y_0 for

some no. under same model from
where the data are coming

why do we calculate \hat{y}_0 at some place

→ y_0 is not a parameter, but it is
a random variable

$$\text{True } y_0 \sim N(B_0 + B_1 n_0, \sigma^2)$$

$$\hat{y}_0 \sim N(B_0 + B_1 n_0, \frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{mn}}) \sigma^2$$

So also y_0 & \hat{y}_0 are independent

$$T = \frac{y_0 - \hat{y}_0}{\sqrt{\sigma^2_{y_0}}} \sim N(0, 1)$$

$$\Rightarrow \frac{y_0 - \hat{y}_0}{\sqrt{\sigma^2_{y_0}}} \sim t_{n-2} \quad \sigma^2 \text{ is replaced by } \hat{\sigma}^2$$

$$P(-T_{\alpha/2, n-2} < \frac{y_0 - \hat{y}_0}{\sqrt{\hat{\sigma}^2_{y_0}}} < T_{\alpha/2, n-2}) = 1-\alpha$$

PP.

Prediction Interval

$$P(\hat{y}_0 - T_{\alpha/2, n-2} \sqrt{\hat{\sigma}^2 y_0} < y_0 < \hat{y}_0 + T_{\alpha/2, n-2} \sqrt{\hat{\sigma}^2 y_0}) = 1-\alpha$$

least square estimate of in SLR

maximum likelihood estimate

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i, \epsilon_i \sim N(0, \sigma^2)$$

$\Rightarrow y_i \sim N(\beta_0 + \beta_1 x_i, \sigma^2)$ are independent
disturbed

$$(\hat{\beta}_0, \hat{\beta}_1, \hat{\sigma}^2) = \underset{\beta_0, \beta_1, \sigma^2}{\operatorname{argmax}} \prod_{i=1}^n \frac{e^{-\frac{1}{2} \left(\frac{y_i - \beta_0 - \beta_1 x_i}{\sigma} \right)^2}}{\sqrt{2\pi} \sigma}$$

U
as gradient

$$= \underset{\beta_0, \beta_1, \sigma^2}{\operatorname{argmax}} \frac{e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2}}{(\sqrt{2\pi} \sigma)^n}$$

now taking log + diff to max gives min
 $\Rightarrow \sum (y_i - \beta_0 - \beta_1 x_i)$

$$\begin{cases} \hat{\beta}_0_{LS} = \hat{\beta}_0_{MLE} \\ \text{&} \hat{\beta}_1_{LS} = \hat{\beta}_1_{MLE} \end{cases}$$

$$\left. \begin{array}{l} \hat{\sigma}_{LS}^2 = \frac{ESS}{n-2} \\ \hat{\sigma}_{MLE}^2 = \frac{ESS}{n} \end{array} \right\} \begin{array}{l} \text{unbiased} \\ \text{biased} \end{array}$$

Now earlier x_i was non stochastic if y_i was stochastic as ϵ_i was stochastic

Now (x, y) is a paired random variable with bivariate normal distribution

$$N(\mu_x, \mu_y, \sigma_x^2, \sigma_y^2, \rho)$$

Given data $D_i = \{(x_i, y_i)\}, i=1, \dots, n$

The Regression model

$$E(Y|X=x) \quad \text{or} \quad E(X|Y=y)$$

$$f(x, y) = \frac{1}{2\pi\sigma_x\sigma_y\sqrt{1-\rho^2}} \left\{ \left(\frac{x - \mu_x}{\sigma_x} \right)^2 + \left(\frac{y - \mu_y}{\sigma_y} \right)^2 - 2\rho \left(\frac{x - \mu_x}{\sigma_x} \right) \left(\frac{y - \mu_y}{\sigma_y} \right) \right\}$$

$$= \left[\left(\frac{y - \mu_y}{\sigma_y} \right) - \rho \left(\frac{x - \mu_x}{\sigma_x} \right) \right]^2 + (1 - \rho^2) \left(\frac{x - \mu_x}{\sigma_x} \right)^2$$

$$f(y) = e^{-\frac{1}{2(1-\rho^2)} \left[\left(\frac{y - u_y}{\sigma_y} \right)^2 + \frac{\rho^2 (n - u_n)^2}{\sigma_n^2} \right]} \cdot \frac{e^{-\frac{(n - u_n)^2}{2\sigma_n^2}}}{\sqrt{2\pi} \sqrt{1-\rho^2} \sigma_y}$$

$$E(Y|n) = u_y + \rho \frac{\sigma_y}{\sigma_n} (n - u_n), \quad \text{Var}(Y|n) = (1-\rho^2) \sigma_y^2$$

$$E(X|Y) = u_n + \rho \frac{\sigma_n}{\sigma_y} (Y - u_y), \quad \text{Var}(X|Y) = (1-\rho^2) \sigma_n^2$$

$$\text{Var}(X|Y) = (1-\rho^2) \sigma_n^2 \leq \sigma_n^2$$

$$\text{Var}(Y|X) = (1-\rho) \sigma_y^2 \leq \sigma_y^2$$

* conditional variances less or equal as compared
 \uparrow
 $\rho = 0$

to uncondition variance

$$E(Y|X=n) = \sigma$$

$$\beta_0 = \bar{y} - \rho \frac{\sigma_y}{\sigma_x} \bar{x}$$

To check regression

$$H_0: \beta_1 = 0 \Leftrightarrow (\rho = 0) \text{ as } \sigma_n, \sigma_y \text{ are } 0$$

$$H_1: \beta_1 \neq 0 \Rightarrow (\rho \neq 0)$$

$H_0: \rho = 0$ vs $\rho \neq 0$ in Bivariate normal

$$\hat{\rho} = \hat{\gamma} = \frac{\sum (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum (x_i - \bar{x})^2 \sum (y_i - \bar{y})^2}}$$

Under $H_0: \rho = 0$

$$T = \frac{n \sqrt{n-2}}{\sqrt{1-\rho^2}} \sim t_{n-2}, ncp=0$$

But life is much more complicated when

$$H_0: \rho_0 = 0 \quad \text{vs} \quad H_1: \rho \neq \rho_0$$

$$\text{Defn: } Z = \frac{1}{2} \log \left(\frac{1+\sigma}{1-\sigma} \right) = \operatorname{tanh}^{-1}(\sigma)$$

$$U_2 = \frac{1}{2} \log \left(\frac{1+P_0}{1-P_0} \right) = \operatorname{tanh}^{-1}(P_0)$$

$$\sigma_z^2 = (n-3)^{-1}$$

$$\frac{Z - U_2}{\sigma_z} \sim N(0, 1) \text{ when } n \rightarrow \infty$$

Variance stabilization formula

$$T_n \xrightarrow{b} 0 \quad \text{as } n \rightarrow \infty, P \neq 1$$

$$\sqrt{n}(T_n - U) \xrightarrow{d} N(0, \sigma^2)$$

$$\text{then } \sqrt{n}(g(T_n) - g(U)) \xrightarrow{d} N(0, \sigma^2(g'(U))^2)$$

P value

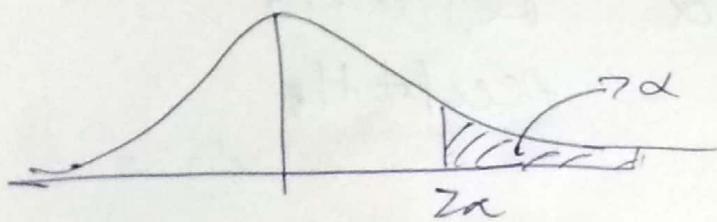
$$H_0: U = U_0 \quad \text{vs } U > U_0$$

test at level $\alpha = 0.1, 0.05, 0.01$

$$Z = \left(\frac{\bar{X} - \mu_0}{\sigma} \right) \sqrt{n}$$

σ known

$$Z \sim N(0, 1) \text{ under } H_0$$



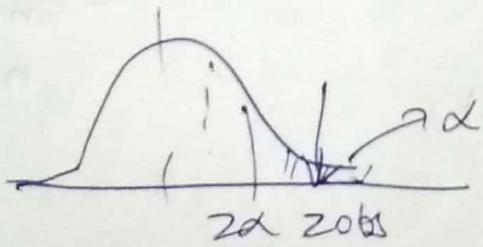
④ We reject H_0 in favour of H_1 if

$$Z_{\text{obs}} > z_\alpha$$

{ we need to know
z α value according to
 α

if α changes z α
so conclusion
of test may change

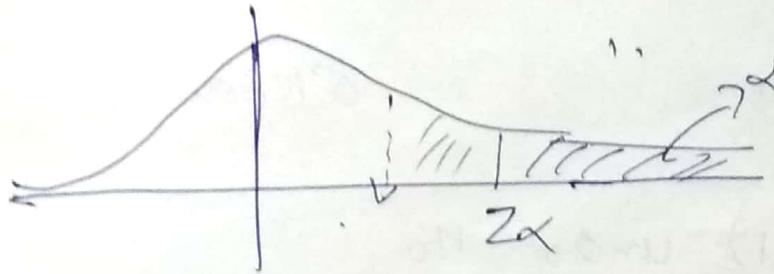
Subh δ



Calculate $P_{H_0}(Z > Z_0)$ because it's an upper tail test

check $P_{H_0}(Z > Z_{\text{obs}}) < \alpha$ to Reject H_0

Pvalue < α to Reject



$P < \alpha$ Rejection
 $P > \alpha$ Acceptance

Multiple linear regression

$$Y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}_{n \times 1}, \quad X = \begin{pmatrix} 1 & x_{11} & x_{21} & \cdots & x_{n1} \\ 1 & x_{12} & x_{22} & & \\ \vdots & \vdots & \vdots & & \\ 1 & x_{1m} & x_{2m} & \ddots & x_{nm} \end{pmatrix}_{n \times (m+1)}$$

$$\hat{\beta} = \begin{pmatrix} \beta_0 \\ \vdots \\ \beta_k \end{pmatrix}_{(k+1) \times 1}$$

$$\epsilon = \begin{pmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{pmatrix}_{n \times 1}$$

$$Y = X\hat{\beta} + \epsilon \quad \epsilon \sim N(0, \sigma^2 I_n)$$

LS condition, $S^2 = (\hat{Y} - X\hat{\beta})^T (\hat{Y} - X\hat{\beta})$

$$S^2(\hat{\beta})$$

$$\hat{\beta} = \arg \min C S^2(\beta)$$

$$\beta \in \mathbb{R}^{k+1}$$

$$\hat{\beta} = (X^T X^{-1}) X^T Y + \text{Assume } |X^T X| \neq 0$$

$$\hat{\beta} \sim N(\beta, (X^T X)^{-1} \sigma^2)$$

No: $\beta_1 = \beta_2 \dots \beta_k = 0$

H_0 : No is not true

$$y_i \stackrel{iid}{\sim} N(\beta_0, \sigma^2)$$

$$\beta = \begin{pmatrix} \beta_0 \\ \vdots \\ \beta_k \end{pmatrix}$$

whether we should build model or not

If we replace the prediction by \hat{y}

$$\sum_{i=1}^n (y_i - \bar{y})^2 = \text{total sum of squares} = SST$$

$$\sum_{i=1}^n (\hat{y}_i - \bar{y})^2 = \text{Error sum of squares}$$

$$= \hat{y}^T (I_n - P_x) \hat{y}$$

$$SST = \underline{y}^T \left(I_n - \frac{1}{n} \underline{1} \underline{1}^T \right) \underline{y}$$

$$SS_{\text{Model}} = \sum_{i=1}^n (\hat{y}_i - \bar{y}) = \underline{\hat{y}}^T \left(R - \frac{1}{n} \underline{1} \underline{1}^T \right) \underline{y}$$

$$\begin{aligned} SST &= SS_{\text{Error}} + SS_{\text{Model}} \\ &= ESS + SS_{\text{Model}} \end{aligned}$$

$$\begin{aligned} SST &= \underline{y}^T \left(I_n - \frac{1}{n} \underline{1} \underline{1}^T \right) \underline{y} \\ &= \underline{y}^T \left(I_n - P_X + P_X - \frac{1}{n} \underline{1} \underline{1}^T \right) \underline{y} \\ &= \underline{y}^T (I_n - P_X) \underline{y} + \underline{y}^T (P_X - \frac{1}{n} \underline{1} \underline{1}^T) \underline{y} \\ &= SSE + SS_{\text{Model}} \end{aligned}$$

$$SST \sim \sigma^2 \chi_{n-1}^2$$

$$SSE_{\text{Model}} \sim \sigma^2 \chi_{n-(R+1)}^2, \quad n_{cb}=0 \xrightarrow{\text{Rank of } P_X} \text{Rank of } (P_X)$$

$$SS_{\text{Model}} \sim \sigma^2 \chi_R^2, \quad n_{cb}=1$$

NCP for SS Model

$$NCP_{POS} \quad \frac{1}{\sigma^2} \mathbf{y}^T (\mathbf{P}_X - \frac{1}{n} \mathbf{1} \mathbf{1}^T) \mathbf{y}$$

$$\begin{aligned} & \mathbf{y} \sim N(\mathbf{x}\beta, \sigma^2 \mathbf{I}_n) \Rightarrow \frac{1}{\sigma^2} \mathbf{y} \sim N(\mathbf{x}\beta, \mathbf{I}_n) \\ & \Rightarrow \frac{1}{\sigma^2} \mathbf{y}^T (\mathbf{P}_X - \frac{1}{n} \mathbf{1} \mathbf{1}^T) \mathbf{y} \\ & = \frac{1}{\sigma^2} \mathbf{\beta}^T \mathbf{x}^T (\mathbf{P}_X - \frac{1}{n} \mathbf{1} \mathbf{1}^T) \mathbf{x} \end{aligned}$$

Divide by σ^2

$$PN = \frac{1}{\sigma^2} \mathbf{\beta}^T \mathbf{x}^T (\mathbf{R} - \frac{1}{n} \mathbf{1} \mathbf{1}^T) \mathbf{x} \beta$$

$$\mathbf{\beta} = \begin{pmatrix} \beta_0 \\ \beta_R \end{pmatrix} \quad \mathbf{x} = \begin{pmatrix} 1 : \mathbf{x}_R \end{pmatrix}$$

$$\Rightarrow \frac{1}{\sigma^2} \mathbf{\beta}^T (\mathbf{x}^T \mathbf{P}_X \mathbf{x} - \frac{1}{n} \mathbf{x}^T \mathbf{1} \mathbf{1}^T \mathbf{x}) \beta$$

$$= \frac{1}{\sigma^2} \mathbf{\beta}^T (\mathbf{x}^T \mathbf{x} - \frac{1}{n} \mathbf{x}^T \mathbf{1} \mathbf{1}^T \mathbf{x}) \beta$$

$$= \frac{1}{\sigma^2} \mathbf{\beta}^T \left(\begin{pmatrix} n & \mathbf{1}^T \mathbf{x}_R \\ \mathbf{x}_R^T \mathbf{1} & \mathbf{x}_R^T \mathbf{x}_R \end{pmatrix} - \frac{1}{n} \begin{pmatrix} \mathbf{1}^T \\ \mathbf{x}_R^T \end{pmatrix} \begin{pmatrix} \mathbf{1} & \mathbf{1}^T \end{pmatrix} \begin{pmatrix} 1 & \mathbf{x}_R \end{pmatrix} \right) \beta$$

$$= \frac{1}{\sigma^2} \mathbf{\beta}^T \begin{pmatrix} n & \mathbf{1}^T \mathbf{x}_R \\ \mathbf{x}_R^T \mathbf{1} & \mathbf{x}_R^T \mathbf{x}_R \end{pmatrix} \begin{pmatrix} n & \mathbf{1}^T \mathbf{x}_R \\ \mathbf{x}_R^T \mathbf{1} & \mathbf{x}_R^T \mathbf{x}_R \end{pmatrix}^{-1} \begin{pmatrix} n & \mathbf{1}^T \mathbf{x}_R \\ \mathbf{x}_R^T \mathbf{1} & \mathbf{x}_R^T \mathbf{x}_R \end{pmatrix} \beta$$

$$\frac{1}{\sigma^2} \mathbf{B} \begin{pmatrix} n & \mathbf{1}^T \mathbf{x}_R \\ \mathbf{x}_R^T \mathbf{1} & \mathbf{x}_R^T \mathbf{x}_R \end{pmatrix} - \begin{pmatrix} n & \mathbf{1}^T \mathbf{x}_R \\ \mathbf{x}_R^T \mathbf{1} & \frac{1}{n} \mathbf{x}_R^T \mathbf{1} \mathbf{1}^T \mathbf{x}_R \end{pmatrix} \mathbf{B}$$

$$= \frac{1}{\sigma^2} \mathbf{B}^T \begin{bmatrix} 0 & \mathbf{Q}^T \\ 0 & \mathbf{x}_R^T \mathbf{x}_R - \frac{1}{n} \mathbf{x}_R^T \mathbf{1} \mathbf{1}^T \mathbf{x}_R \end{bmatrix} \mathbf{B}$$

$$= \frac{1}{\sigma^2} \begin{pmatrix} \mathbf{B}_0 \\ \mathbf{B}_R \end{pmatrix}^T \begin{bmatrix} 0 & \mathbf{Q}^T \\ \mathbf{Q} & \mathbf{x}_R^T \mathbf{x}_R - \frac{1}{n} \mathbf{x}_R^T \mathbf{1} \mathbf{1}^T \mathbf{x}_R \end{bmatrix} \begin{pmatrix} \mathbf{B}_0 \\ \mathbf{B}_R \end{pmatrix}$$

$$= \frac{1}{\sigma^2} \mathbf{B}_R^T \left(\mathbf{x}_R^T \mathbf{x}_R - \frac{1}{n} \mathbf{x}_R^T \mathbf{1} \mathbf{1}^T \mathbf{x}_R \right) \mathbf{B}_R$$

then $\boxed{\mathbf{n} \cdot \mathbf{c} \cdot \mathbf{p} = 1 = 0}$ iff $\mathbf{B}_R = 0$

which is nothing But

$$\boxed{\mathbf{B}_1 = \mathbf{B}_2 = \dots = \mathbf{B}_R = 0}$$

which was to be proved

Now

Express $\mathbf{x}_R^T \mathbf{x}_R - \frac{1}{n} \mathbf{x}_R^T \mathbf{1} \mathbf{1}^T \mathbf{x}_R$ in the form of centered regression variable

$$SST \sim \sigma^2 X_{n-1}^2, ncp=1$$

$$SSE \sim \sigma^2 X_{n-k-1}^2, ncp=0$$

$$SS_{\text{model}} \sim \sigma^2 X_k^2, ncp=1$$

Total No : $B_1 = B_2 = \dots = B_k = 0$
vs H_1 : H_0 is not true

$$\frac{SS_{\text{model}}}{\sigma^2} \sim \chi_k^2, ncp = \frac{1}{\sigma^2}$$

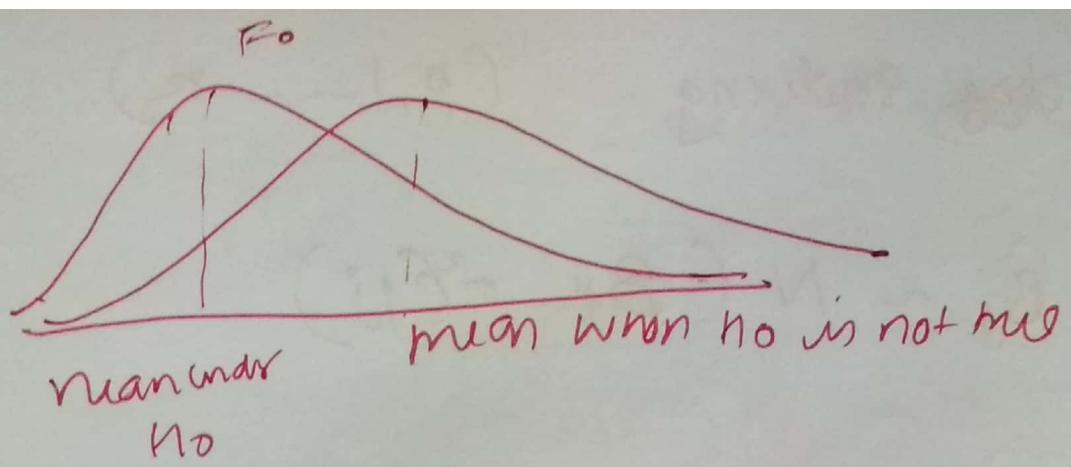
Under H_0

$$\frac{SS_{\text{model}}}{\sigma^2} \sim \chi_n^2, ncp=0$$

$$\hat{\sigma}^2 = \frac{SSE_{\text{error}}}{n-k-1}$$

$$F \approx \frac{SS_{\text{model}}/k}{\frac{SSE_{\text{error}}/(n-k-1)}{}} \sim F_{k, n-k-1}$$

under H_0



So we reject H_0 in favor of H_1 if

$$F_{\text{observe}} > F_{\alpha}, k, n-k-1$$

★ Analysis of variance (ANOVA) for Regression model

$$\hat{\beta} \sim N(\beta, (X^T X)^{-1} \sigma^2)$$

$$H_0 : \beta_j = \beta_j^0 \quad \text{vs} \quad H_1 : \beta_j \neq \beta_j^0 \quad j = 0, \dots, k$$

$$\beta$$

$$\beta = \begin{pmatrix} \beta_0 \\ \vdots \\ \beta_k \end{pmatrix}$$

$$C_{k+1, k} = (X^T X)^{-1}$$

~~(R+1)~~

$$(k+1 \times k+1) \quad (R+1 \rightarrow k+1)$$

By in diag. matrix $(C_0, 1 \dots k)$

$$\Rightarrow \hat{B}_j \sim N(B_j^*, \sigma^2 C_{jj})$$

$$\Rightarrow \frac{\hat{B}_j - B_j}{\sqrt{\sigma^2 C_{jj}}} \sim N(0, 1)$$

$$\Rightarrow T = \frac{\hat{B}_j - b_j}{\hat{\sigma} \sqrt{C_{jj}}} \sim t_{n-k-1}$$

und nro

$$\hat{\sigma}^2 = \frac{\text{SS Error}}{n-R-1}$$

we Reject no in favor of $H_1: Y$

$$|F_{ob}| > T_{\alpha/2, n-k-1}$$

$$F = T^2 \geq F_{\alpha, 1, n-k-1}$$

↓
How? Next page

$$T = \frac{Z}{U/m} \quad Z \sim N(0, 1) \quad Y \sim X^2_m \quad \text{quadratic}$$

$$Z^2 \sim \chi_1^2 \\ Y \sim \chi_m^2$$

$$T^2 = \frac{Z^2}{U/m} = \frac{Z^2 \chi_1^2}{Y/m} \sim F$$

Test for

$$H_0 : \beta_j - \theta \beta_i = 0$$

$$\text{vs } H_1 : \beta_j - \theta \beta_i \neq 0$$

$$\hat{\beta}_j - \theta \hat{\beta}_i \sim ?$$

$$H \quad Z \sim N(\mu, \Sigma)$$

$$e^T Z \sim N(e^T \mu, e^T \Sigma e)$$

$$\hat{\beta} \sim N(\beta, \sigma^2 C)$$

$$\lambda^T = (0 \dots 1 \dots -\theta \dots 0)$$

$$\lambda^T \hat{\beta} \sim N(B_i^0 - \theta B_i, \sigma^2 \left(C_{jj} + \theta^2 C_{ii} \right) - \frac{2C_{ij}}{J})$$

$$(10^{-1}) \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

Now to get
ans

$$(a+f) - 2c =$$

$$\hat{\beta} \sim N(\beta, (X^T X)^{-1} \sigma^2)$$

If $(X^T X)^{-1} \neq 0$ then any linear parametric function of β is in the form

$\lambda^T \beta$ is estimable

i.e we have linear combination of Y e.g

$$Q^T Y \text{ such that } E(Q^T Y) = P^T \hat{\beta}$$

linear parametric function (LPF)

A LPF of β is a linear combination of β i.e.

$$\hat{\beta}^T \mathbf{L}$$

Linear Unbiased Estimator If (LUE)

$E(\hat{\beta}^T \mathbf{L}) = \beta^T \mathbf{L}$ then $\hat{\beta}^T \mathbf{L}$ is said to LUE of $\beta^T \mathbf{L}$

if it holds for all $\mathbf{L} \in \mathbb{R}^{k+1}$

Linear Zero Estimator (LZE)

If $E(\hat{\beta}^T \mathbf{L}) = 0 \quad \forall \mathbf{L} \in \mathbb{R}^{k+1}$ then $\hat{\beta}^T \mathbf{L}$ is known as a linear zero estimator

① Show that $\hat{\beta}^T \mathbf{Y}$ is an LUE of $\beta^T \mathbf{B}$

$$i) \quad \mathbf{x}^T \mathbf{L} = \hat{\beta}^T \mathbf{L}$$

$\hat{\beta}^T \mathbf{Y}$ is an LUE of $\beta^T \mathbf{B}$

$$ii) \quad E(\hat{\beta}^T \mathbf{Y}) = \beta^T \mathbf{B} \quad \forall \mathbf{B} \in \mathbb{R}^{k+1}$$

We know, $\mathbf{y} \sim N(\mathbf{XB}, \sigma^2 \mathbf{I}_m)$

$$\mathbf{L}^T \mathbf{X} \mathbf{B} = \beta^T \mathbf{B} \quad \forall \mathbf{B} \in \mathbb{R}^{k+1}$$

$$\Rightarrow \mathbf{L}^T \mathbf{X} = \beta^T$$

$$\mathbf{x}^T \mathbf{L} = \hat{\beta}^T$$

$\textcircled{2} \quad \underline{\lambda^T y}$ is a LZF iff $\underline{x^T \lambda} = 0$

from def^h

$$E(\underline{\lambda^T y}) = 0 \quad \forall \underline{\beta} \in R^{k+1}$$

$$\Leftrightarrow \underline{\lambda^T x \beta} = 0$$

$$\Leftrightarrow \underline{\lambda^T x} = \underline{0^T}$$

$$\Leftrightarrow \underline{x^T \lambda} = 0$$

$$\Rightarrow \underline{\lambda} \in (CQ)^+$$

$$\underline{\lambda} \in C(I_{n-p_x})$$

$\Rightarrow \exists m \in R^n$ such that

$$\underline{\lambda} = (I - P_x)_m$$

$$\underline{\lambda^T x} = \underline{m^T (I - P_x)x} = \underline{0^T}$$

\Rightarrow Every LZF can be written

$$\text{as } \boxed{\underline{m^T (I - P_x)y}}$$

$$E(\underline{m^T (I - P_x)y}) = \underline{m^T (x \beta - P_x x \beta)}$$

$$= \underline{m^T (x - x) \beta} = 0$$

A linear parametric function of $\beta^T B$ is said to be estimable if there exist $\lambda^T Y$ such that

$$E(\lambda^T Y) = \beta^T B + \beta \in \mathbb{R}^{k+1}$$

③ An 'if' condition for $\beta^T B$ to be estimable is ~~is~~

$$\beta \in C(X^T)$$

Now

$$E(\beta^T B) = \beta^T B$$

$$Q^T X \beta = \beta^T B$$

$$X^T l = b$$

β is a linear combination of X^T
 $\beta \in C(X^T)$

Best linear unbiased estimator (BLUE)

An unbiased estimator of $\beta^T B$ is said to be BLUE of $\beta^T Y$ if it has minimum variance among all linear Unbiased estimators of $\beta^T B$

$$U = \{ \hat{\beta}^T Y \mid E(\hat{\beta}^T Y) = \beta^T \beta = \beta \in R^{K+1} \}$$

$$\text{Var}(\hat{\beta}_0^T Y) \leq V(\hat{\beta}^T Y) \quad \forall \hat{\beta}, \hat{\beta}_0 \in U$$

Th: A linear function of $\hat{\beta}$ is BLUE of its estimation iff it is uncorrelated with all linear zero function/Estimators (LZE)

$$E(\hat{\beta}^T Y) = \beta^T \beta$$

$$\text{if } \text{cov}(\hat{\beta}^T Y, Z^T Y) = 0$$

where $Z^T Y$ is LZF

Ex 1: If $\hat{\beta}^T Y$ is LUE of $\beta^T \beta$ then
corresponding BLUE is $\hat{\beta}^T P_X Y$

$$\hat{\beta}^T Y = \hat{\beta}^T I Y = \hat{\beta}^T [P_X + (I - P_X)] Y$$

$$\hat{\beta} = \hat{\beta}^T P_X Y + \underbrace{\hat{\beta}^T (I_n - P_X) Y}_{\text{LZF from earlier result}}$$

$$\therefore E \hat{\beta}^T (I_n - P_X) Y = 0 \iff \leftarrow$$

$$(ii) E(\ell^T Y) = \ell^T B = E(\ell^T B X Y) = \ell^T B X B$$

from
earlier
result
 $A^{-1} \ell^T X = \ell^T B$

some

$\ell^T Y$ is a m
LVE of
 $\ell^T B$

$$E(\ell^T Y) = \ell^T B$$

~~$E(\ell^T Y) = \ell^T B$~~

$$E(\ell^T B) =$$

$$E(B^T B) =$$

this is an LVE & $\ell^T F$

such $\ell^T B X Y$ & $\ell^T (J_n - B X) Y$ are
uncorrelated $\Rightarrow \ell^T B X Y$ is m BLUE

Exs every estimable LPF has unique
BLUE

lets assume $\exists \ell_1^T Y$ and $\ell_2^T Y$ which is
BLUE of $\ell^T B$

$$\ell_1^T y = \ell_2^T y + (\ell_1 - \ell_2)^T y$$

$$E(\ell_1^T y) = E(\ell_2^T y) + E(\ell_1 - \ell_2)^T y$$

$$\Rightarrow E(\ell_1 - \ell_2)^T y = 0$$

$\Rightarrow (\ell_1 - \ell_2)^T y$ is LZF

$$\Rightarrow V(\ell_1^T y) = V(\ell_2^T y) + V(\ell_1 - \ell_2)^T y + 0$$

Case 1 if $V(\ell_1 - \ell_2)^T y > 0$

then $V(\ell_1^T y) > V(\ell_2^T y)$ contradiction

Case 2 $V(\ell_1 - \ell_2)^T y = 0$

with $E(\ell_1 - \ell_2)^T y = 0$

$$P((\ell_1 - \ell_2)^T y = 0) = 1$$

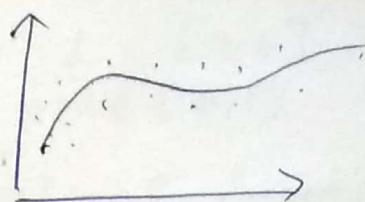
$$P(\ell_1^T y = \ell_2^T y) = 1$$

∴ linearly depend ℓ_1, ℓ_2

$$\ell_1 = k\ell_2$$

Polynomial Regression

Ⓐ Polynomial Regression is linear regression



$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i}^2 + \beta_3 x_{2i}^3 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma^2)$$

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \beta_3 x_{1i} x_{2i} + \beta_4 x_{1i}^2 + \beta_5 x_{2i}^2 + \epsilon_i \quad \epsilon_i \sim N(0, \sigma^2)$$

$$= g(x_{1i}, x_{2i}) + \epsilon_i$$

* f & g both are linear in parameters

for model 1 $\mathbf{X} = \begin{pmatrix} 1 & x_{1i} & x_{1i}^2 & x_{1i}^3 \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_n & x_n^2 & x_n^3 \end{pmatrix}$

$$Y = \mathbf{X} \mathbf{B} + \epsilon \quad \epsilon \sim N(0, \sigma^2 I_n)$$

Note

- ① If all x_i are equal then $(\mathbf{X}^T \mathbf{X})$ is not invertible
- ② If $\sum_{i=1}^n |x_i| < \epsilon$, small numbers, with higher degree of x_i 's will become numerically zero
- ③ We can't fit at most $(n-1)$ degree polynomial
 \Leftrightarrow Interpolation problem
It will lead to overfitting

$$Y = \begin{pmatrix} 1 & x_1 & \dots & x_1^{n-1} \\ 1 & x_2 & \dots & x_2^{n-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & \dots & x_n^{n-1} \end{pmatrix} \begin{pmatrix} B_0 \\ B_1 \\ \vdots \\ B_n \end{pmatrix}$$

Now when all x_i are different from

$$0 \neq |A|$$

④ If we fit $(n-1)$ degree polynomial estimation of σ^2 will not be possible

⑤ In a polynomial regression, hierarchy may not be maintained.

\Rightarrow maybe B_4 is significant but B_2 or B_3 may be insignificant

$$y = B_0 + B_1 x + B_3 x^3$$

$$(6) y_i = g(n_{1i}, n_{2i}) + \epsilon_i \quad (\text{Model 2})$$

Can be used as response surface model in
design of experiment

$$Y = X\beta + \epsilon$$

$$\hat{\beta} = \underbrace{(X^T X)^{-1}}_{(k+1)} \underbrace{X^T Y}_{(k+1) \times (k+1)}$$

Orthogonal Polynomial Regression

$$x \cdot y = \underbrace{x^T y}_{\sum x_i y_i = 0} = 0 \quad x, y \in \mathbb{R}^n$$

$$\langle f(t), g(t) \rangle = 0$$

$$\begin{array}{l} t \in [a, b] \\ \omega + \in [0, 1] \end{array}$$

then also we say $f \perp g$ as orthogonal function

$$\int_a^b f(t)g(t)dt = 0 \quad , \quad \int_0^1 \sin(2\pi t) \cos(2\pi t) dt = 0$$

$$y_i = \sum_{j=0}^K \alpha_j P_j(x_i) \quad i = 1, 2, \dots, n$$

$$P_0(y_i) = 1 \quad \forall i$$

$$P_p(n,) = \text{orthogonal polyn. of } n,$$

$$\sum_{j=1}^K P_j(x_i) P_k(x_i) = 0 \quad \forall j \neq k$$