

ode

Only One Independent Variable  
 $x \in [a, b]$   
 $t \in \mathbb{R}$

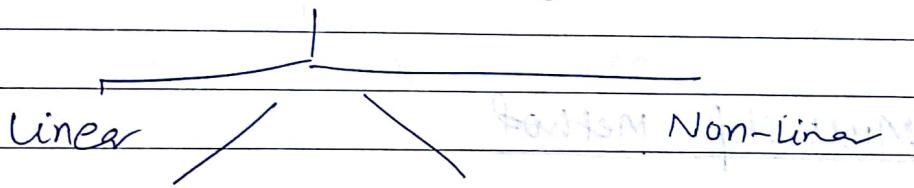
Evolutionary differentials i.e. wrt 't'.

general form:

$$f(t, y, y', \dots, y^{n-1}, y^n) = 0.$$

$t$ - independent.

If linear in terms of differentials  $\Rightarrow$



$$I \vee P \qquad BVP$$

$$f(t, y, y', \dots, y^n) \longrightarrow y = \sum_{i=1}^n c_i y^i + \text{I.C.}$$

$\therefore$  eq<sup>n</sup> solved in an interval.  
 given initial cond<sup>n</sup>.

T I - Dirichlet } BVP

T II - Neumann

T III - Robin

— linear  $a_0 y(t) + b_0$

③ card of existence & soft 8002

Date / /

Saathi

## Vectorization of IVP

soln of IVP:

- ① Picard's method of successive approximation.
- ② Taylor series method.
- ③ Euler (forward) method.
- ④ Backward Euler method.
- ⑤ Modified
- ⑥ A class of Runge-Kutta method

Single step methods // Approximate method

Numerical

Non-numerical

Multistep Method

Date: / /

Picard's

Method of Successive Approximation

(Saath)

$$\frac{dy}{dt} = f(t, y) \quad t \in [t_0, b]$$
$$y(t_0) = y_0$$

$$\int_{t_0}^b \frac{dy}{dt} = \int_{t_0}^b f(t, y) dt$$

$$y - y_0 = \int_{t_0}^b f(t, y) dt$$

$$y(t) = y_0 + \int_{t_0}^b f(t, y) dt$$

$$y_{n+1}(t) = y_0 + \int_{t_0}^b f(t, y_n) dt$$

$y_1(t)$ : Approxn to  $y$  at 1st level.

$$y_1(t) = y_0 + \int_{t_0}^b f(t, y_0) dt$$

now its known  
hence Integrable

$$y_{n+1}(t) = y_0 + \int_{t_0}^b f(t, y_n) dt$$

difference of Approxn general

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$$\{y_{n+1}\}^{\infty} \rightarrow y(t)$$

what's the cond<sup>n</sup> that converges to  $y(t)$ .

we have selected  
 $t \in [0, b]$

take some pt from this interval.  
 & see if they are close enough

~~II Taylor Series Method.~~

$$\frac{dy}{dt} = f(t, y) \xrightarrow{\text{---①}} y(t)$$

$$\text{if } t = y(t_0) = y_0 + h = (t_0 + h)$$

$$y(t) = y_0 + t y'(t_0) + \frac{t^2}{2} y''(t_0) \dots$$

$$\begin{array}{l} t_0 + h \\ \hline t = h \end{array}$$

Value of derivatives from eqn ①

②

Tau

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8/8

IVP

$$y' = x^2 + y^2 \quad y(0) = 1$$

construct

$$j_1, j_2, j_3$$

$$y_{n+1} = y_0 + \int_0^n (x^2 + y_n^2) dx$$

$n=0$

$$j_1 = 1 + \int_0^x (x^2 + 1) dx$$

$$j_1 = \frac{x^3}{3} + x + 1$$

$n=1$

$$j_2 = j_1 + \int_0^x \left[ (x^2) + \left( 1 + x + \frac{x^3}{3} \right)^2 \right] dx$$

so on so forth.

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Numerical soln

$$\frac{dy}{dt} = f(t, y) \quad t \in [t_0, b]$$

at  $y(t_0) = y_0$

step sizes.

S-I: Discretisation of domain:  
dividing the interval onto non-overlapping

$$t_0 - \rightarrow$$

$$a = t_0 < t_1 < t_2 \dots < t_n = b$$

data set  $S: \{t_0, t_1, \dots, t_n\}$  Nodal pts

$t_0, t_n$  - Boundary pts

$t_0, \dots, t_{n-1}$  - Interval  
Nodal Pts

~~We do not have the value at each pt,  
just at nodal pts.~~

\* Btw, further refining helps. \*

$$t_i - t_{i-1} = h \quad \forall i$$

✓

~~It's then equally partitioned  
into different sub domains  
have diff. partition.~~

When ever I replace differentials by finite differences  $\rightarrow$  system of linear algebraic eqn.

$$y^{t_{i+1}} = y^{(t_i+n)} = y(t_i) + h y'(t_i) + \frac{h^2}{2} y''(t_i) \dots$$

$$y^{t_{i+1}} - y^{(t_i)} = h y'(t_i) + \frac{h^2}{2} y''(t_i) \dots$$

$$\cancel{y^{t_{i+1}} - y^{(t_i)}} \sim y'(t_{i+1}) \equiv y'(t_i) + O(h)$$

### I Forward Euler Method

$$y_{i+1} = y_i + h f_i$$

$$\left. \begin{array}{l} y_1 = y_0 + h f_0 \\ y_N = y_{N-1} + h f_{N-1} \end{array} \right\} \text{System of eqn.}$$

$$\left. \begin{array}{l} y_1 = y_0 + h f_0 \\ y_N = y_{N-1} + h f_{N-1} \end{array} \right\} \text{(i) Explicit Method.}$$

- (ii) Single step method.
- (iii)  $O(h)$  1st order approx.

$h$ : step size.

### II Backward Euler method.

$$\begin{aligned} t_{i+1} &= y(t_{i-h}) \\ &= y(t_i) - h y'(t_i) + \frac{h^2}{2} y''(t_i) - \dots \\ &\quad - \frac{h^3}{13} y'''(t_i). \end{aligned}$$

$$\frac{y(t_{i-1}) - y(t_i)}{h} = -y'(t_i) + O(h)$$

$$y_i - y_{i-1} = h \underline{f_i} - O(h)$$

$$y_i - y_{i-1} = h f_i \quad i=1, 2, \dots, N$$

$$y_i = y_{i-1} + h f_i$$

Backward difference  
Method.

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Implicit Method.

S.S.M.

O(h)

(a)  
(b)  
(c)

$$\frac{dy}{dt} \Big|_{t_i} \approx \frac{y_{i+1} - y_{i-1}}{2h} \quad \delta \text{ Central}$$

$$\frac{y_{i+1} - y_i}{h}$$

$$\frac{y_i - y_{i-1}}{h}$$

$$y_{i+1} = y_0 + h y'_i(i) + \frac{h^2}{2} y''_i(i) + \frac{h^3}{24} y'''_i(i)$$

$$y_{i-1} = y_i - h y'_i(i) + \frac{h^2}{2} y''_i(i) \dots$$

$$\boxed{\delta = y'_i(i) + O(h^2)}$$

10.1.11

$$\frac{dy}{dt} = f(t, y)$$

$$y(t_0) = y_0$$

$$\text{Mid point method} \quad y_{i+1} - y_{i-1} + O(h^2)$$

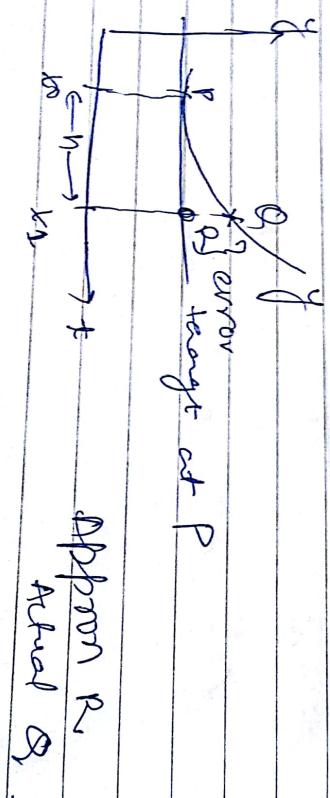
$$\left. \frac{dy}{dt} \right|_{t_i} = \frac{y_{i+1} - y_{i-1}}{2h}$$

### Numerical Method:

(i) EEM :  $y_{i+1} = y_i + h f_i$

(ii) BEM :  $y_{i+1} = y_i + h f_i + \frac{h^2}{2} f''(t_i)$

(iii) MidPoint :  $y_{i+1} = y_{i-1} + 2h f_i$



$$y_1 = y_0 + h f_0$$

$$y(t_1) = y(t_0) + h \cdot f(t_0, y_0)$$

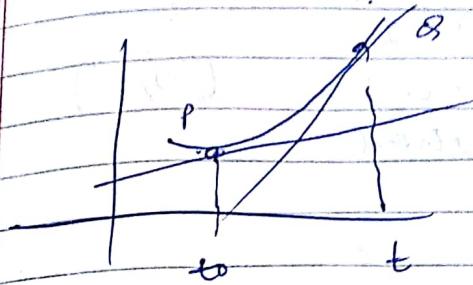
$$= y(t_0) + h \cdot y'(t_0)$$

$$R = y_2 - y_1$$

Backward M.

$$y_1 = y_0 + h f_1 \quad \dots$$

$O(n)$   
1st order  
Aitken's method



$$y_1 = y_0 + h f(t_0, y_0)$$

$$y_1 = y_0 + h y'(t_0)$$

modification

$$y_1 = y_0 + h \frac{1}{2} (f_0 + f_1)$$

$$y_1 = y_0 + \frac{h}{2} [f(t_0, y_0) + f(t_1, y_1)]$$

Set up an iterative mechanism:

$$y_1 = y_0 + \frac{h}{2} [f(t_0, y_0) + f(t_1, y_1^{(0)})]$$

$$y_1^{(s+1)} \leftarrow y_1^{(s)} \quad | \quad s = 0, 1, 2, \dots$$

error tolerance

$$(y_1^{(1)}) = (y_0 + \frac{h}{2} [f(t_0, y_0) + f_1(t_1, y_1^{(0)})])$$

$$(y_1^{(0)}) = y_0 + h f_0$$

$$y_{j+1} = y_j + \frac{h}{2} [f(t_j, y_j) + f_{j+1}]$$

modification

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$$y_1(2) = y_0 + \frac{h}{2} (f(t_0, y_0) + f_1(t_1, y_1(1)))$$

$O(h^2)$

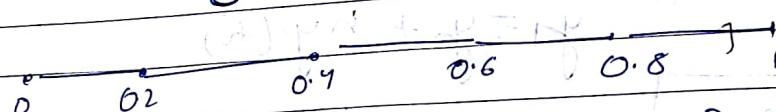
~~$\frac{dy}{dx} = 2x + y, \quad y(0) = 1$~~ 

$[0, 1]$

Using forward Euler method.

~~$\frac{dy}{dx} - y = 2x$~~

~~$e^{xy} (A) \frac{dy}{dx} + y = 2x$~~



~~$y_1 = y_0 + h f_0$~~ 

$f = 2x + y$

$$y_1 = 1 + 0.2(0) \quad (0, 0)$$

$$0.2(1) = 1.2 = y_1$$

$$y_1 = 1$$

$$y_2 = 1 + 0.2(2)(0.2) + 1$$

~~$y_2 = 1.6 \rightarrow 1.4 \times 0.2$~~

~~F2 1.28~~

$$y_2 = 1.2 + (0.2)(2(0.2) + 1.2)$$

$$1.2 + (0.2)(1.6)$$

$$1.2 + 0.32$$

$$y_2 = 1.52$$

$$y_2 = \frac{0.4 + 0.2(2(0.4) + 1.52)}{0.8}$$

$$0.2(1.32)$$

$$0.264$$

$$y_2 = 0.664$$

$$y_2 = 1.784.$$

~~decreasing step size -  $\uparrow$  accuracy~~

$$y_1 = 1 + 0.2(2(0) + 1) = 1.1$$

$$y_2 = 1.1 + 0.1\left(\frac{2(0.1) + 1.1}{1.3}\right).$$

$$y_2 = 1.23$$

- (1)  $h = 0.1$
- (2)  $h = 0.005$
- (3)  $y = e^{ax}$

### Program

$$Q: y' + \frac{1}{2}y = 0 \quad y(0) = 1. \quad [0, 20] \quad h =$$

$$\frac{dy}{y} = -\frac{dx}{2}$$

Intg

$$y = e^{-x/2}$$

$$(i) \underline{h = 1}$$

$$(ii) \underline{h = 4}$$

$$(iii) \underline{h = 4.2}$$

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Saathiy

$$y' = -2 + y^2 \quad y(0) = 1$$

$$\text{Step} \quad h = 0.2 \quad [0, 0.4]$$

$$y_1 = y_0 + h \cdot f_1 \quad 0 \quad 0.2 \quad 0.4$$

$$\therefore y_1 = 1 + h(-2 + y_0^2)$$

$$y_1 = 1 + 0.2(-2 + 1^2)$$

$$0.08 y_1^2 + y_1 - 1 = 0$$

$$(y_1 = \frac{-1 \pm \sqrt{1+0.32}}{0.16})$$

$$\sqrt{0.32} \rightarrow y_1 = \frac{-1 \pm \sqrt{1.32}}{0.16}$$

not  
physically possible.

Date

Date

11/11/17

In FEN: we consider One slope.  
 $f_j = y_j'$  -  $O(h)$ .

In modified EM:

~~slopes used~~

$O(h^2)$

\* explicit method with 2 slopes:

$$k_1 = h f(t_j, y_j)$$

$$k_2 = h f(t_j + h, y_j + k_1)$$

$$y_{j+1} \approx y_{j+k_1}$$

approximate

$$y_{j+1} = y_j + \frac{k_1}{2} + \frac{k_2}{2}$$

$$y_{j+1} = y_j + w_1 k_1 + w_2 k_2$$

$w_i$  = weight of  $k_i$  in the method.

Runge-Kutta method of order 4:

$$y_{j+1} = y_j + (w_1 k_1 + w_2 k_2 + w_3 k_3 + w_4 k_4)$$

$$(w_1, w_2) + A$$
$$(1 + (0) \cdot 0) + 0$$

$$(0, 0) + 0$$

$$(0, 0) + 0$$

Date: / / 9th Order Range Kutta method

$$y_{j+1} = y_j + \frac{1}{6} (K_1 + 2K_2 + 2K_3 + K_4)$$

$$K_1 = h \cdot f(t_j, y_j)$$

$$K_2 = h \cdot f\left(t_j + \frac{h}{2}, y_j + \frac{K_1}{2}\right)$$

$$K_3 = h \cdot f\left(t_j + \frac{h}{2}, y_j + \frac{K_2}{2}\right)$$

$$K_4 = h \cdot f(t_j + h, y_j + K_3)$$

#.  $y' = 2ny$   $y(0) = 1$   $y(0.2)$   
 $y(0.4)$

$$h = 0.2$$

explicit 2 slope method

$$y_{j+1} = y_j + \frac{1}{2} (R_1 + K_2)$$

$$R_1 = h \cdot f(t_j, y_j)$$

$$R_2 = h \cdot f(t_j + h, y_j + R_1)$$

$$y_1 = y_0 + \frac{1}{2}$$

$$R_1 = h \cdot f(t_0, y_0)$$

$$R_1 = 0.2 \cdot \left( \alpha_2(0) + \frac{y_0}{1} \right)$$

$$R_2 = 0.2 \left( \frac{(0.2)}{0.2}, \frac{0.2}{0.4} \right)$$

$$R_2 = 0.2 \left( 3(0.2) \right) 0.16$$

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$$y(0.2) = 1 + \frac{1}{2} (0.2 + 0.32)$$

$$\frac{0.52}{2} = 0.26$$

$$y(0.2) = 1.26$$

$$y(0.4) = y(0.2) + \frac{1}{2} (R_1 + R_2)$$

$$R_1 = h f(0.2, 1.26)$$

$$R_1 = 0.2 \left( 2(y(0.2) + 1.26) \right) \\ 1.66$$

$$R_1 = \underline{0.332}$$

$$b. = 0.2 (0.4 \cdot 1.592)$$

## Order of a method :

$$y' = f$$

$$y(t_{j+1}) = y(t_j) + h y'(t_j) + \frac{h^2}{2} y''(t_j) + \dots$$

Local truncation error:

Order = local  $\rightarrow$  for any  
for any  
One step  
method

$O(n^a)$

- this is a measure of accuracy, it gives an indication of how rapidly the accuracy can be improved with refinement of grid spacing  $h$ .



### 1st Order

$$\text{Error} = E_1$$

Step size  $= h \Rightarrow$  refine  $h \rightarrow h/2$

$$h \rightarrow E_1$$

$$h/2 \rightarrow E_1/2 \text{ error}$$

$$h : E_2$$

$$\frac{h}{2} : \frac{E_2}{4}$$

$$\theta: y' = 2t + y \quad y(0) = 1 \quad h = 0.2 \quad y(0.2)$$

$$y_{j+1} = y_j + \frac{1}{6} (R_1 + 2R_2 + 2R_3 + R_4)$$

$$R_1 = h \left( f(t_j, y_j) \right) \quad R_2 = h \left( f(t_j + h/2, y_j + \frac{R_1}{2}) \right)$$

$$R_3 = h \left( f(t_j + h/2, y_j + \frac{R_2}{2}) \right)$$

$$R_4 = h \left( f(t_j + h, y_j + R_3) \right)$$

$$y_1 = 1 + \cancel{R_1} \quad \cancel{R_2} \quad \cancel{R_3}$$

$$R_1 = 0.2 \left( 2(0.0) + 1 \right)$$

$$R_1 = 0.2 \left( 2(0.1) + 0.1 \right)$$

$$R_2 = 0.2 \left( 2(0.1) + 0.2 \right) = 0.26$$

$$R_2 = 0.06 + 0.2 = 0.26$$

$$R_3 = 0.2 \left( 2(0.1) + 0.26 \right)$$

$$R_3 = 0.26 \quad 1 + 0.13$$

$$R_4 = 0.2 \left( 2(0.2) + 0.26 \right)$$

$$R_4 = 1 + 0.26$$

$$y_2 = 0.2 \left( 0.4 + 1.266 \right)$$

$$y_2 = 0.2 \left( 1.666 \right)$$

$$y = 0.2332$$

$$y_1 = 1 + \frac{1}{6} (0.2 + 2(0.26) + 2(0.226) + 0.333)$$

$$y_1 = 1 + \frac{0.52}{0.72} + 0.450 + 0.33$$

$$y_1 = 1 + \frac{1.5052}{0.72} \quad 25086$$

$$6 \overline{)15052} \quad \downarrow$$

$$\begin{array}{r} 12 \\ 30 \\ 30 \quad 52 \\ \hline 48 \end{array}$$

$$y_1 = 1.2642$$

$$y' - y = Qt \quad \left| \frac{1}{D-1} \right. \quad \boxed{y = Ae^t}$$

$$(3 + (0.01)^6) = 0.31$$

$$(10 + 10\text{g}) \text{ g}$$

Page 10 of 10

$$(\text{left} + \text{right}) \cdot \text{sum}$$

Page 10 of 10

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*Georgie G. Castleberry*

2

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program: ① FEM

② BEM

③ modified EM

Matlab

$$\text{for } y' = -t^2 \sin(t+y)$$

$$y(0) = 0$$

$$[0, 1], n=0, 1$$

$$+ \frac{1}{2} \left( \sin(1) + \sin(0) \right)$$

## Problems Picard's

Q3) Combine first few terms of iteration with initial value problem:  $y_0(x) = 0$  using Picard's method to solve  $y' = xy + 2x - x^3$  with  $y(0) = 0$  & show they converge to form  $y(x) = x^2 + x^4/4 + x^6/6$ .

(a) Picard's iteration formulae

$$y_n(x) = y_0(x) + \int_0^x f(n, y_{n-1}(n)) dn$$

$$f(n, y) = xy + 2x - x^3 \quad n_0 = 0 \quad y_0 = 0.$$

first iteration putting ( $n=1$ )

$$y_1(x) = y_0 + \int_0^x (x_0 y_0 + 2x_0 - x_0^3) dn$$

$$= \int_0^x (2n - n^3) dn$$

$$y_1(x) = x^2 - \frac{x^4}{4}$$

$n=2$

$$y_2(x) = y_0(x) + \int_0^x (x_1 y_1 + 2x - x^3) dn$$

$$y_2(x) = 0 + \int_0^x \left( x \left( x^2 - \frac{x^4}{4} \right) + 2x - x^3 \right) dn$$

$$= \frac{x^3}{3} - \frac{x^5}{20}$$

Date / /

$$y_3(x) = y_0 + \int_{0}^x (n, y_2(n)) dn$$

$$y_3(x) = \int_{0}^x (2n^3 - n^7 + 2n - 3x) dn$$

$$= 2x^3 - x^7 + 2x - 3x^2$$

$$= \int_{0}^x \left( 2n - \frac{x^7}{24} \right) dn$$

$$y_3(n) = n^2 - n^8$$

From these values we can conclude  
that the solution  $y = n^2$ .

$$y' - ny = 2n - n^2$$

~~$$\frac{dy - ny}{dn} + (0)^{-1} = (nc)^{-1}$$~~
~~$$dy - ny = -n^2.$$~~

$$e^{\int dy - \int e^{1/2}} = (nc)^{-1}$$

~~$$\frac{dy e^{-n^{1/2}}}{dn} = (2n - n^3) e^{-n^{1/2}}.$$~~

~~$$e^{-n^{1/2}} y = (n^2 - n^4) e^{-n}$$~~

$$e^{-n^{1/2}} y = \int (2n - n^3) e^{-n^{1/2}} dn.$$

- Q) Use Taylor series to find a numerical solution at  $x = 0.5$  of ODE  $y'' = ny$  given that  $y(0) = 1$  &  $y'(0) = 2$  (use  $n = 0.5$ )

$$y(x_0 + h) = y(x_0) + hy'(x_0) + \frac{h^2}{2} y''(x_0) + \frac{h^3}{6} y'''(x_0) + \frac{h^4}{24} y''''(x_0) \dots$$

Truncate upto 4th order's (just like that)

$$y(x_0 + h) = y(x_0) + hy'(x_0) + \frac{h^2}{2} y''(x_0) + \frac{h^3}{6} y'''(x_0) + \frac{h^4}{24} y''''(x_0)$$

given  $y(0) = 1$  &  $y'(0) = 2$

$$y(x_0) = 1 \quad y''(0) = n_0 y_0 = 1 \times 0 = 0.$$

$$y'''(x_0) = xy'(0) + y(0)$$

$$y'''(0) = 1$$

$$y''''(0) = ny'''(0) + y'(0) + y(0)$$

$$y''''(0) = 2.$$

Date \_\_\_\_\_

Saachi

$$y(x_{0+h}) = 1 + 0.5 \times 1 + \frac{(0.5)^2}{2} \times (2) + \frac{(0.5)^3}{3!} \times (2)$$

$$+ \frac{(0.5)^4}{4!} \times (2)$$

$y(0.5) = 1.526$

(3) Solve the ODE  $y' = 2y + 3e^x$   
 with  $y(0) = 0$  using Taylor series  
 method of order (2) to approximate  
 $y$  for  $x = 0.1, 0.2$

$$y(x_0+h) = y(x_0) + hy'(x_0) + \frac{h^2}{2!} y''(x_0)$$

truncated

$$y(x_0) = 0$$

$$y'(x_0) = 3 = 2(0) + 3e^0$$

$$y'' = \cancel{2y_0 + 3e^0} \cdot 2y_0 + 3e^{2x_0} = 9.$$

$$y(0.1) = 0 + (0.1)(3) + \frac{(0.1)^2}{2} 9$$

$$y(0.1) = 0.3 + \frac{0.01}{2} = 0.045 + 0.3$$

$$= \underline{\underline{0.345}}.$$

$$y(0.2) = (0.2)(3) + \frac{(0.2)^2}{2} 9.$$

$$(0.02)9 = 0.18 + 0.6$$

$$= \underline{\underline{0.78}}$$

Q) Solve  $y' = x - y^2$  for  $y(0) = 1$  by Euler's method for  $n=0.2$ .

$$y_{n+1} = y_n + h f(x_n, y_n)$$

here  $f(x, y) = x - y^2$

$$y = y_1(0.2) = y_0 + (0.2) f(x_0, y_0)$$

$$= 1 + 0.2 (0 - 1)$$

$$= 0.8$$

$$y_2(0.4) = y_1(0.2) + 0.2 ((0.2) - (0.8)^2)$$

$$= 0.8 + 0.2 (0.2 - 0.64)$$

$$- (0.44) 0.2$$

$$= 0.8 - 0.088$$

$$y_2(0.4) = \underline{-0.088} \quad 0.712 \quad \underline{\frac{0.88}{712}}$$

$$y_3(0.6) = y_2(0.4) + 0.2 ((0.4) - (0.712)^2)$$

$$y_3(0.6) = \underline{0.712} \quad 0.6906 \quad \underline{(1.0)} \quad \underline{(0.712)^2}$$

Date

③ Given  $y' = y - x$  where  $y(0) = 2$ .

Find  $y(0.1)$  &  $y(0.2)$  Euler method.  
 $h = 0.1$

SOL.

$$y_{n+1} = y_n + h f(x_n, y_n)$$

$$y_1 = y_0 + 0.1 (f(0, y_0))$$

$$\therefore 2 + 0.1 (2 - 0)$$

$$y_1 = 2.2$$

$$y(0.2) = \frac{y(0.1) + 0.1 (2.2 - 0.1)}{0.1 (2.1)}$$

$$y(0.2) = 2.2 + 0.21$$

$$= 2.41$$

④ Given

$$det = x + u^2 \quad u(0) = 1$$

Saathii

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Any general single step method

for IVP

$$\frac{dy}{dt} = f(t, y)$$

such that  $y(t_0) = y_0 \quad t \in [t_0, b]$

$$y_{j+1} = y_j + h \phi(t_j, y_j, h) \quad \phi \rightarrow \text{increment}$$

$$y_{j+1} = y_j + h f_j \quad \text{euler method}$$

Local Truncation Error

↳ denoted by  $T_{j+1}$

$$(1) T_{j+1} = y(t_{j+1}) - (y_j + h f_j)$$

$$T_{j+1} = y(t_{j+1}) - y_{j+1}$$

$\downarrow$  numerical soln.

exact soln.

$$T_{j+1} = y(t_{j+1}) - [y_j + h f_j]$$

$$= (y_j + h y'(t_j)) - y_{j+1}$$

$O(LTE)$

$$T_{j+1} = y(t_{j+1}) - (y_j + h y'(t_j))$$

$$= [y(t_j) + h y'(t_j) + \frac{h^2}{2} y''(t_j) \dots] - [y_j + h y'(t_j)]$$

$$O(LTE) = O(h^2)$$

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Order of Numerical Method

(Single step method)

as

$O(h^p)$

$$\left| \frac{1}{h} \cdot O(LTE) \right| = O(h^p)$$

$$FEM = O(h) = BEM$$

$$Mod. EM = O(h^2)$$

$$O(LTE) / 4^{th} \text{ Order R.K} = O(h^5)$$

$$y_{j+1} = y_j + h f \quad \text{--- FEM}$$

$$T_{j+1} = y(t_{j+1}) - \{y_j + h y_j\}$$

$$= \frac{h^2}{2!} y''(\xi) \quad t_j < \xi < t_{j+1}$$

$$max |y''(t)| = M$$

( $t_0, t_1$ )

$$T \leq \frac{h^2}{2} M$$

FEM

BEM

2 ways to increase accuracy

- h refinement,

- p refinement.

Backward - less than exact.

## class of Runge-Kutta methods

R-K methods use weighted avg. of slopes on the given interval  $(x_j, x_{j+1})$  instead of simple

general R-K Method with  $v$ -slope

$y_{j+1} = y_j + h \{ \text{weights avg. of slopes of given interval} \}$

$$\left\{ y_{j+1} = y_j + [w_1 k_1 + w_2 k_2 + \dots + w_v k_v] \right)$$

since I have defined:  $R_j = hf(x_j, y_j)$

where

$w_i$  - weights to be determined

## Runge-Kutta Method

$$y_{j+1} = y_j + w_1 + w_2 h$$

$$R_1 = h \left( f(x_j, y_j) \right)$$

$$R_2 = h \left( f(x_j + c_2 h, y_j + R_1) \right)$$

need to find :  $w_1, w_2, c_2, q_2$

\* Make  $y_{j+1}$  close to  $y(x_{j+1})$  upto 2nd Order

$$y(t_{j+1}) - y_{j+1}$$

$$= y(t_{j+1}) - \{ y_j + w_1 h \cdot f(x_j, y_j) \}$$

$$+ w_2 h \left[ f(x_j + c_2 h, y_j + q_2 R_2) \right]$$

$$y(x_{j+1}) = y(x_j) + y'(x_j) h + \frac{h^2}{2} y''(x_j)$$

$$\frac{h^3}{3} y'''(x_j)$$

$$y' = f(x, y)$$

$$y'' = \frac{\partial f}{\partial x} = f_{xx} + f_y y'$$

Date

Book

- ① Numerical methods using MATLAB  
JOKERI Mathew Pearson Publicn
- ② Numerical Methods for scientific & engineering computer:  
M. K. Jain Iyengar.

Implicit

methods with  $v$  slopes.

compact form:

$$y_{j+1} = y_j + \sum_{j=1}^v w_j k_j$$

where,

$$k_j = h f(x_j + g_j h, y_j + \sum_{m=1}^v a_{jm} k_m)$$

where

$$g_j = \sum_{i=1}^v a_{ji}, \quad j=1, 2, \dots, v$$

and  $a_{ji} \quad i \leq j <$ where  $w_i$  are arbitrary parameters :no. of unknown parameters are:  
 $\pi(v+1)$

Sauthi

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y''

$$y_{j+1} = y_j + w_1 k_1$$

$$k_1 = h f(x_j + c_1 k_1, y_j + a_{11} k_1)$$

$$T_{j+1} = y(x_{j+1}) - y_{j+1} \quad y' = f$$

comparison of  $h$  &  $h^2$  terms:

$$w_1 = 1, \quad w_1 c_1 = \frac{1}{2} \quad w_1 a_{11} = \frac{1}{2}$$

$$c_1 = \frac{1}{2}, \quad a_{11} = \frac{1}{2}$$

$$y_j = y_j + k_1, \quad k_1 = h f\left(x_j + \frac{h}{2}, y_j + \frac{1}{2} k_1\right)$$

Higher Order IVP

$$y'' + 2y' + 3y = e^{2x}$$

[0, 1]

$$\begin{aligned} y(0) &= r_1 \\ y'(0) &= r_2 \end{aligned}$$

$$f(x, y, y', y'') = 0.$$

$$y'' + 3y' + 2y = 0$$

$$\text{put } y^* = u$$

$$y' = u' = v$$

$$y'' = v' = -3v - 2u$$

$$u' = v$$

$$v' = -3u - 2u$$

$$x = \begin{bmatrix} u \\ v \end{bmatrix}' = F = \begin{bmatrix} f_1 \\ f_2 \end{bmatrix}$$

$$u' = g_1(x, u, v) \Rightarrow v' = f_1$$

$$v' = g_2(x, u, v) \Rightarrow -3u - 2u$$

$$u' = v$$

$$v' = -3v - 2u$$

} given 2nd order  
into 2 1st order  
eqn

$$\underline{\omega}' = F(x, \underline{\omega})$$

$$y' = f(n, y)$$

$$n: [a, b]$$

$$\text{PEM: } y_{j+1} = y_j + h f_j()$$

$$v_{j+1} = v_j + h g_{1j}$$

$$v_{j+1} = v_j + h g_{2j}$$

Taylor Series Method :

$$y_{j+1} = y_j + h y'_j + \frac{h^2}{2} y''_j + \dots + \frac{h^p}{p!} v_j^p$$
$$j = 0, 1, 2, \dots$$

where  $v_j^{(R)} = \begin{cases} u_j & j \\ u_{2j} & \\ \vdots & \\ u_{nj} & \end{cases}^R$

## Newton Raphson Method

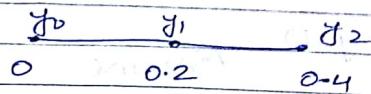
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$$R^{n+1} = R^n - \frac{F(R^n)}{F'(R^n)}$$

(Saath)

ex:  $y' = -2xy^2$  -  $y(0) = 1$   $[0, 0.4]$   
 $h = 0.2$

Using the I.R.K  
with one slope



$$y_{j+1} = y_j + k_j$$

$$k_j = h f\left(x_j + \frac{h}{2}, y_j + \frac{k_j}{2}\right)$$

$$j=0,$$

$$j=0.$$

$$y_1 = y_0 + k_1 = 1 + k_1$$

$$k_1 = 0.2 \left[ -2x_0 y_0^2 \right]$$

$$= 0.2 \left[ -2 \times \left( x_0 + 0.2 \right) \left( 1 + \frac{k_1}{2} \right)^2 \right]$$

$k_1$  - can be calculated.

$$F(k_1) = 0$$

$$R^{n+1} = R^n - \frac{F(R^n)}{F'(R^n)}$$

$$R(R_1) = R_1 + 0.2 \left[ 2x_j + 0.2 \right] \left[ \frac{y_1 + k_1}{2} \right]^2$$

$$F(R_1) = 1 + \left( 0.2 \right) \left( y_j + \frac{R_1}{2} \right) \left( 2x_j + 0.2 \right)$$

Solve

$$R_1(n+1) = R_1(n) - \frac{F(K_1 n)}{F'(R_1 n)}$$

 $n=0, 1, 2, \dots$ 

j=0 Assume:

$$K_1^{(n)} = n f(x_j, y_j)$$

$$K_1(0) = 0$$

$$K_1(1) = -0.0384615$$

$$K_1(2) = -0.03847567$$

$$\begin{aligned} y(0.2) &= y(0) + K_1 \\ &= 1 + (-0.03847567) \\ &= 0.96152 \end{aligned}$$

S1ly;

$$y(0.4) = y(0.2) + K_1$$

$$K_1 = 0.2 \left[ -2 \lambda \left( \pi_1 + \frac{R}{2} \right) \left( y_1 + \frac{R_1}{2} \right)^2 \right]$$

$$y(0.4) = 0.86179013$$

Soln

$$y_{j+1} = y_j + \left( \frac{h(1+k)}{2} \right)$$

$$R_1 = h f(x_j + \frac{3}{4}h), \quad y_j + \frac{R_1}{4} + \frac{3+2\sqrt{3}}{12} R_2$$

Quartic

$$y_{j+2} = h f(x_j + \frac{6}{4}h) - y_j + \frac{3+2\sqrt{3}}{12} (R_1 + R_2)$$

solve:

$$y' = \frac{-2\sqrt{3}}{h^2} y'' - y(\frac{3+2\sqrt{3}}{4})$$

$[0, 0.4]$

Using implicit RK with 2 slopes.

**Example:**

$$u''' + 2u'' + u' - u = \cos(t), \quad 0 \leq t \leq 1$$

$$u(0) = 0, \quad u'(0) = 1, \quad u''(0) = 2$$

2nd order taylor series method

$$\text{soln: } v = v_1, \quad v' = v_1' = v_2, \quad v'' = v_1'' = v_2' = v_3$$

$$v' = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}' = \begin{cases} v_2 \\ v_3 \\ \cos(t) + v_1 - v_2 - 2v_3 \end{cases}$$

Saath

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day

$$u''(0) = \begin{bmatrix} 2 \\ -4 \\ 7 \end{bmatrix}$$

$$v(1) = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} + 1 \cdot \begin{bmatrix} 1 \\ 2 \\ -4 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 2 \\ -4 \\ 7 \end{bmatrix}$$

$$v(1) = \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} \rightarrow \begin{bmatrix} v_1(1) \\ v_2(1) \\ v_3(1) \end{bmatrix} = \begin{bmatrix} u(1) \\ v'(1) \\ u''(1) \end{bmatrix}$$

~~$$u'' + 2u' + u = \cos(x)$$~~

Q:

$$\begin{aligned} u' &= -3u + 2v \\ v' &= 3u - 4v \end{aligned}$$

$$u(0) = 0$$

$$v(0) = 0.5$$

$$h = 0.2$$

$$u' = f(\pi, u, v)$$

$$[0, 0.4]$$

$$v' = g(\pi, u, v)$$

4th Order R.K

$$u_{j+1} = u_j + \frac{1}{4} (R_1 + 2R_2 + 2R_3 + R_4)$$

$$v_{j+1} = v_j + \frac{1}{4} (L_1 + 2L_2 + 2L_3 + L_4)$$

each

$R_i$  have 3 arguments.  $n_i v_i u_i$

Date \_\_\_\_\_

(Saathi)

$$R_1 = h \cdot f(x_j, u_j, v_j)$$

$$L_1 = h \cdot g(x_j, u_j, v_j)$$

$$R_2 = h \cdot f\left(x_j + \frac{h}{2}, u_j + \frac{R_1}{2}, v_j + \frac{L_1}{2}\right)$$

$$L_2 = h \cdot g\left(x_j + \frac{h}{2}, v_j + \frac{K_1}{2} - v_j + \frac{L_1}{2}\right)$$

$$R_3 = h \cdot f\left(x_j + \frac{h}{2}, v_j + \frac{R_2}{2}, v_j + \frac{L_2}{2}\right)$$

$$R_1 = 0.2, \quad L_1 = -0.4$$

$$R_2 = 0.06, \quad L_2 = -0.18$$

$$R_3 = 0.646, \quad L_3 = -0.33$$

$$K_4 = -0.0116, \quad L_4 = -0.0644$$

$$u(0.2) = 0 + \frac{1}{6} (R_1 + 2R_2 + 2R_3 + K_4) = 0.1601$$

My

$$\begin{aligned} v(0.2) &= 0.5 + \frac{1}{6} (L_1 + 2L_2 + 2L_3 + L_4) \\ &= 0.2593 \end{aligned}$$

~~Given:  $y = f(x, y)$~~        $y(x_0) = y_0$   
 ~~$y'(x_0) = ?$~~

linearized equation of  $y' = f(x, y)$   
 called the tot or  
 derived as  
 $y' = f(x, y)$

expand  $f(x, y)$  around  
 $(\bar{x}, \bar{y})$  in T-series.

$$y' = f(\bar{x}, \bar{y}) + (x - \bar{x}) \frac{\partial f}{\partial x} \Big|_{\bar{x}, \bar{y}}$$

$$+ (y - \bar{y}) \frac{\partial f}{\partial y} \Big|_{\bar{x}, \bar{y}}$$

Call       $\lambda = \frac{\partial f}{\partial y} \Big|_{(\bar{x}, \bar{y})}$

$$c = f(\bar{x}, \bar{y}) + (x - \bar{x}) f_x \Big|_{\bar{x}, \bar{y}} - \bar{y} \frac{\partial f}{\partial y} \Big|_{\bar{x}, \bar{y}}$$

$$\bar{y} = \lambda y + c. \quad \checkmark$$

Saathi

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Date \_\_\_\_\_

choose

$$w = y + \frac{c}{\lambda}$$

$$y' = w - \frac{1}{\lambda} f(x) \Big|_P$$

$$v' = \lambda u + \frac{1}{\lambda} f(x) \Big|_{(\bar{x}, \bar{y})}$$

$$\text{or } v' = \lambda u + m.$$

$$\text{take } w = u + \frac{c}{\lambda} \frac{m}{\lambda}$$

$$\therefore \text{Thus } v' = \lambda w \text{ where } w(\text{no. A})$$

$$w(x) \rightarrow Ae^{\lambda x}$$

$$y'' = f(x, y, y') \quad (\bar{x}, \bar{y}, \bar{y}')$$

$$w'' + bw' + cw = 0.$$

$$\boxed{b = -fy/p, \quad c = -fy/p}$$

\* Numerical soln that we have derived:

- (i) Consistency of the method.
- (ii) Stability of num. method.
- (iii) Convergence of num. method

$$(i) \& (ii) \Rightarrow (iii)$$



numerical  
for a consistent method : the  
truncation error  $\rightarrow 0$  as  $n \rightarrow \infty$

$\rightarrow$  The method should be of order 1.  $\leftarrow$

order of local truncation error.

$u(t_j)$   $\rightarrow$  exact solution of D.E at  $t=t_j$

$u_j$   $\rightarrow$  exact solution of the difference.  
(rounding errors.)

$\bar{u}_j$   $\rightarrow$  numerical solution of difference eqn.

Replacement of derivative by differences  
 $\hookrightarrow$  not exact replacement but  
after truncation.

$$|u(t_j) - \bar{u}_j| \rightarrow 0$$

I want exact sol<sup>n</sup> to be as close to  
numerical sol<sup>n</sup> as possible.

$$|u(t_j) - u_j + u_j - \bar{u}_j|$$

$$\leq |L.T.E| + |u_j - \bar{u}_j|$$

L.T.E

Rounding error

Date / /

convergent :

A numerical method is said to converge if, as more grid points are taken (step size decreased), the numerical result moves closer to the exact solution, in the absence of rounding errors.

$$\text{i.e. } u_j(t) \xrightarrow{u \rightarrow 0} u(t_j) \text{ as } h \rightarrow 0$$

stability:

A numerical method is said to be stable if the effect of any simple fixed round off error is bounded, independent of no. of mesh points.

Stability of Single Step Method

$$u' = \lambda u$$

$$u(t_0) = u_0$$

Initial value

matured  $\rightarrow$  real / complex.

$$\text{exact soln: } u(t_j+1) = e^{\lambda h} \cdot u(t_j)$$

$$u(t) = u_0 \cdot e^{\lambda(t-t_0)}$$

$u' = \lambda u$   
at  $u(t_0) = u_0$ .

$$t = t_j + 1, \quad t = t_j$$

$e^{\lambda h} = \infty$  series  
of we approximate

$$e^{\lambda h} = 1 + \lambda h$$

— (1st Order Approx)

$$u(t_{j+1}) = (1 + \lambda h) u(t_j)$$

$$u(t_{j+1}) = u(t_j) + \lambda h u(t_j)$$

$$u(t_{j+1}) = u(t_j) + h f(t_j, u_j)$$

$$e^{\lambda h} = 1 + \lambda h + (\lambda h)^2$$

$E(\lambda h)$  as an approximation to  $e^{\lambda h}$ .

$$u_{j+1} = E(\lambda h) u_j$$

Numerical Method

Define Error  $e_j = u(t_j) - u_j$

difference b/w  
exact &  
numerical  
solution

$$e_{j+1} = u(t_{j+1}) - u_{j+1}$$

$$= e^{\lambda h} u(t_j) - E(\lambda h) u_j$$

(or)

$$e_{j+1} = e^{\lambda h} u(t_j) - E(\lambda h) [u(t_j) - e_j]$$

$$e_{j+1} = [e^{\lambda h} - E(\lambda h)] u(t_j) + \underline{E(\lambda h) e_j}$$

L.T.E

propagation error.

so propagation error must be controlled.

else, unstable sol<sup>n</sup>, since  $E$  keep on increasing away from pt.

$$E_{j+2} = (E^2(\lambda h) - e^{2\lambda h}) u(j) + E^2(\lambda h) e_j$$

$\hat{t}_j \rightarrow$  point where error started to come

now how the error propagates is what we are trying to understand.

so, the Single Step Method : when applied to test eqn  $u' = \lambda u$   $u(t_0) = u_0$

(1) Absolutely stable if  $|E(\lambda h)| \leq 1 \quad \lambda < 0$

(2) Relatively stable if  $|E(\lambda h)| < e^{\lambda h} \quad \lambda > 0$

(3) Periodically stable if  $|E(\lambda h)| = 1$

$\lambda \rightarrow$  pure imaginary

(4) Asymptotically stable if  $u_j \rightarrow 0$  as  $j \rightarrow \infty$

31/01/18

Date \_\_\_\_\_ / \_\_\_\_\_ / \_\_\_\_\_

(•)

PQM.

$$u_{j+1} = u_j + h f_j$$

Test Eqn

$$u' > \lambda u = f$$

$$u_{j+1} = u_j \underbrace{(1 + \lambda h)}_{E(\lambda h)} - (1 + \lambda h)^2 = 0$$

for stability -  $|E(\lambda h)| < 1$

$$|1 + \lambda h| < 1$$

$$-1 < 1 + \lambda h < 1$$

$$-2 < \lambda h < 0$$

$$-2 < \bar{h} < 0$$

Explicit Method

Conditionally stable.

$$\boxed{0 < h < 2}$$

$$1 > h$$

Date / /

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$$y_{j+1} = (I - \lambda h)^{-1} y_j$$

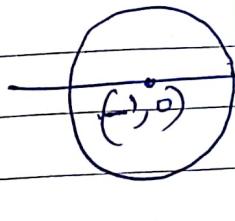
$$\left| \frac{1}{(I - \lambda h)} \right| < 1$$

$\lambda$  is complex:

$$|z| = \sqrt{(a^2 + b^2) + (ka)^2} = \sqrt{a^2 + b^2 + k^2 a^2}$$

$$(x+1)^2 + b^2 \leq 1 \Rightarrow |z| \leq \sqrt{1 + k^2 a^2} = \sqrt{1 + k^2}$$

$$(\lambda < 0) \Rightarrow |z|$$



BEM

date \_\_\_\_\_  
Name \_\_\_\_\_  
Date \_\_\_\_\_/\_\_\_\_\_  
A = \_\_\_\_\_  
B = \_\_\_\_\_  
C = \_\_\_\_\_

usually explicit methods are  
stable as implementable.  
where unconditionally unstable

### Unconditionally stable methods

### Stability of 1st order R-K Method

$$\lambda < 0 \quad E(\lambda h) = \sqrt{1 + \lambda h + (\lambda h)^2} < 1$$

$$-2 < (1 + \lambda h)^2 + 1 < 2$$

$$\lambda h \in (-2, 0)$$

modified euler method.

$y_i$

$$\lambda = \lambda_R + i\lambda_I$$

$$\Gamma = \frac{A}{B} e^{i(\beta - \alpha)}$$

$$A = \sqrt{\left(1 + \frac{\lambda x h}{2}\right)^2 + \left(\frac{\lambda z^2 h^2}{4}\right)}$$

$$B = \int \left(1 - \frac{\lambda x h}{2}\right)^2 + \frac{\lambda^2 h^2}{4}$$

$$\frac{\Delta x}{B} < 1$$

$$\lim_{h \rightarrow \infty} \nabla^2 f_0 \leftarrow f'$$

Utn Order Rk.

$$\underline{\text{Mt. Imp}}$$

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Multi step Method.

三

### Multi step Method

1

+ APPENDIX

B = Step Metric

$$u_{j+1} = a_1 u_j + a_2 u_{j-1} + \dots + a_r u_{j-r+1} + b_1 u'_j + b_2 u'_{j-1} + \dots + b_r u'_{j-r+1}$$

$$y' = f(x, y)$$

$$y(t_0) = y_0$$

$$v_j = \sum_{i=1}^k a_i u_{j-i+1} + b_i v_{j-i+1} = 0$$

If  $b_0 = 0$  — then explicit multistep method

under MSM. [redacted] prediction

If  $b_0 \neq 0$ , — implicit linear MSLM — collector

$$P(E) \cup_{j=k+1}^r - h^{\sigma}(E) \cup'_{j=k+1} = 0.$$

$E f_i = f_{i+1}$



Date

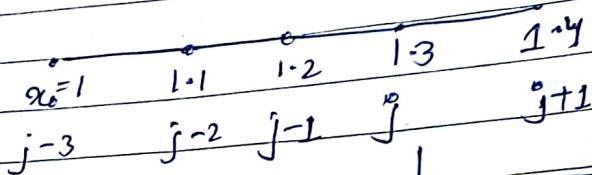
$$y' = x^2(1+y)$$

$$y(1) = 2 \\ y(1.2) = 1.548 \\ y(1.1) = (1 \cdot 2 \cdot 3 \cdot 3) \\ y(1.3) = 1.979.$$

find  $(1.4)$  using AB (AM)  
PC set. (4th order).

$$h = 0.1$$

$$f = (x^2(1+y)) \quad f_i = f(x_i, y_i)$$



$x_{-3} = 1$	$y_{-3}$	$f_{-3}$
$x_{-2} = 1.1$	$y_{-2}$	$2.702$
$x_{-1} = 1.2$	$y_{-1}$	$3.669$
$x_0 = 1.3$	$y_0$	$5.035$
$x_1 = 1.4$	$y_1$	$5.$

$$y_{1P} = 2.57245$$

Predictor

formulae

$$\underline{f(x_1, y_{1P}) - f_1 = 7.002}$$

Date

$y_1^{C_1}$ , 2.5742

E = 7.005432

$y_1^{C_2}$ , 2.5751

E =

$$\boxed{|y_1^{Cn+1} - y_1^{Cn}| < \epsilon \text{ (tolerance)}}$$

Used only once.

(P) C - c - c.  
↓  
f ←  $\frac{dy}{dx}$  Keypup

Milne & Milne Simpson  
P-C Methods

Solve  $\frac{dy}{dx} = f(x, y)$   $y(x_0) = y_0$ .

Find  $y(x_0 + 4h) = y_4$ ?

Consider newton forward interpol for  $f(x, y)$

$$y_4 = y_0 + \frac{4}{3} h [2f_1 - f_2 + 2f_3]$$

$$\boxed{f_{j+1} = y_{j+3} + \frac{4}{3} h [2f_{j-2} - f_{j-1} + 2f_j]}$$

C<sup>o</sup> derived using simpson's  $\frac{1}{3}$  rule

$$y_4 = y_2 + \frac{h^4}{x_2} f(x_1, y_2).$$

$$y_4 = y_2 + \frac{h}{3} \left\{ f_2 + 4f_3 + f_4 \right\}$$

$$y_{j+1} = y_{j-1} + \frac{h}{3} \left[ f_{j-1} + 4f_j + f_{j+1} \right]$$

en: solve  $y' = n - y^2$   $y(0) = 0$   $n=0.2$

Date \_\_\_\_\_

Saathi

Q. Given "R<sub>0</sub>" & "R<sub>1</sub>". Find R<sub>(0,1)</sub> by series method. Using Taylor's formula.

$$y_1 - R = f(x, y_2) \\ y_2 = -(x_2 + f) = g(x_1, y_2)$$

$$y'' + xy' + R = 0 \quad \text{--- (1)}$$

Let's ① write x = n times.

$$y_{n+2} + ny_{n+1} + y_n + 0$$

$$y_{n+2} = -x y_{n+1} - (n+1) y_n$$

$$y_{n+1}(x) = (-1)^n y_n$$

$$(i) y(0) = 1 \quad (ii) y'(0) = -1 \quad (iii) y''(0) = 0$$

$$y_3 = -2 y_1(0) = 0.$$

$$y_4 = -(-3)(-1) \cdot 3.$$

$$\text{Ans: } y(x) = 1 - 3x^2$$

$$\text{Ans: } y(x) = 1 - 3x^2$$

$$y(x) = y(0) + \frac{g'(0)}{2}x^2 + \frac{g''(0)}{12}x^4 + \dots \quad (3)$$

$$y(x) = 1 - \frac{x^2}{2} + \frac{x^4}{8} - \frac{15x^6}{64} \dots \quad (4)$$

$$y' = -x + \frac{x^3}{2} - \frac{1}{8}x^5 + \dots \quad (5)$$

$$y(0) = 0.995 \quad y'(0) = 0.0995$$

$$\begin{aligned} y(0.1) &= 0.9802 \\ y(0.2) &= 0.956 \\ y(0.3) &= 0.92868 \end{aligned}$$

Milne Predictor Corrector

$$z(0.4) = z(0) + \frac{4}{3}h [2g_1 - g_2 + 2g_3]$$

$$= 0.3692$$

$$g(0.4), \quad g(0) + \frac{4}{3}h [2f_1 - f_2 + 2f_3]$$

$$= 0.9237$$

$$g = -(mz + f) \quad f = z$$

$$g(0.4) = -0.7754$$

$$f(0.4) = -0.3692$$

$$z(0.4) = g(0.2) + \frac{h}{3} [f_2 + 4f_3 + f_4] \\ = 0.9232$$

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$$\tau_{j+1} = \rho c_e - h(\varepsilon) = 0.$$

Satisfy

No solution exists for  $\tau_j$  because(1)  $\tau_j$  decreases after  $\tau_j = 0$ 

$$f(\tau_j) = C(\tau_j) + h(\tau_j) > 0$$

$$f(\tau_j) = C(\tau_j) + h(\tau_j) < 0$$

Hence  $\tau_j$  must be above  $\tau_j = 0$ 

$$(x_1) = (x_2) + \alpha + \beta$$

$$P_f = P_f(x_1) + K(x_1)$$

$$P_f = P_f(x_2) + K(x_2)$$

Hence  $P_f$  is strictly increasing

$$(x_1) = (x_2) + \alpha + \beta$$

$$(P_f(x_1) + K(x_1)) > (P_f(x_2) + K(x_2))$$

Hence  $P_f$  is strictly increasing

problem

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Given IVP :  $y(0) = 1$

$y' = \frac{1}{4} y(1 - \frac{t}{20})$  method of  
Adams-Baschforth method

Using Adams-Baschforth  
order  $\underline{\underline{2}}$ . Approximate  $y(1)$   
 $h = 0.2$

Step:

$$y_{i+1} = y_i + h \left[ \frac{3}{4} f(x_i) - \frac{f(x_{i-1})}{2} \right] \quad (2)$$

$$f(x_i, y_i) = \frac{1}{4} \left( 1 - \frac{t}{20} \right)$$

Interpolating value can be computed using  
any single step method

$$y_1 = y_0 + h f(x_0, y_0) \quad (\text{euler})$$

$$= 1.048$$

$$y_2 = y_1 + \frac{h}{2} \left[ 3f_1 - f_0 \right]$$

$$= 1.048 + \frac{0.2}{2} \left[ 3(0.248) - 0.235 \right]$$

$$\approx 1.099$$

$$y_3 = y_2 + \frac{h}{2} [3f_2 - f_1]$$

$$= 1.099 + \frac{0.2}{2} [3(0.26) - 0.248]$$

$$\approx 1.152$$

$$y_{i+1} = y_3 + \frac{h}{2} [3f_3 - f_2] \\ = 1.207$$

$$y_5 = 1.264$$

Sanath

- (2) Use the Adams-Basforth method of order 3 to obtain an approximate value of the IVP  $y' = 2t - y$ ,  $y(0) = 1$

$$y' = 2t - y \quad y(0) = 1$$

with  $N=5$ , at  $t=1$  compare with exact value

$$y(t) = e^{-t} + 2t - 2$$

$\Rightarrow$  Adams-Basforth of order 3 given by

$$y_{i+1} = y_i + \frac{h}{12} [23f(t_i, y_i) - 16f(t_{i-1}, y_{i-1}) + 5f(t_{i-2}, y_{i-2})]$$

for  $i=2, 3, 4$ . Initial conditions

$$\text{here } f(t, y) = 2t - y \quad y_0 = -1 \quad t_0 = 0.$$

$$h = \frac{1-0}{5} = 0.2$$

from exact soln.

$$y_1 = -0.7813$$

$$y_2 = y_1 + \frac{0.2}{12} (23f_1 - 16f_0 + 5f_0)$$

$$y_3 = -0.5297 + \frac{0.2}{12} [23(1.33) - 16 \times 1.181 + 5 \times 1]$$

$$y_0 = \underline{0.367}$$

exact

$$\begin{array}{r} 0.6 \\ 0.8 \\ 1.0 \end{array} \begin{array}{l} -0.2512 \\ \cancel{0.4493} \cancel{\times 0.0493} \\ 0.3679 \end{array}$$

③

Use the Adams Bashforth of order 4 to approximate soln of IVP.

$$y' = 2 + \int_{y-2t}^y t + 3 \quad y(0) = 1$$

on the interval  $[0, 1.5]$  with  $\underline{h=0.25}$

$$y = 1 + 4t + t^2$$

4.

Sol: Adam's Bashforth of order 4 method is  
shown in...

From exact solution:

$$y_1 = 2.016$$

$$y_2 = 3.062$$

$$y_3 = 4.14$$

$$y_4 = 4.014 + \frac{0.25}{24} \left[ 55x(4.375) - 53(4.245) + 3.7(4.125) \right]$$

$$\begin{aligned} &= 5.252 \\ \text{exact } y_4 &= 5.250 \end{aligned}$$

1.25	3.5	-9x4
6.3906	7.5625	

- (A). Solve following IVP using Adams-Basforth-Moulton predictor-corrector method of Order 4.

$$y' = e^{-t} - y \quad y(0) = 2$$

on  $[0, 1.2]$   $h = 0.2$  compare with exact

then

$$y(t) = e^{-t}(t+1)$$

(Explicit)

$$P: y_{i+1}^P = y_i + \frac{h}{24} \left[ 55f_i - 53f_{i-1} + 37f_{i-2} - 9f_{i-3} \right]$$

$$C: y_{i+1}^C = y_i + \frac{h}{24} \left[ 9f_{i+1} + 19f_i - 5f_{i-1} + f_{i-2} \right]$$

Implicit

 $t = 3, 4, 5$ .

time values from exact

$$\text{start} \quad y_1 = 0.9384$$

$$\text{given} \quad y_2 = 0.8781.$$

$$y_3 = -59 f_2 + 37 f_1 - 9 f_0$$

$$y^p = y_3 + \frac{0.2}{24} \int_{y_3}^{y_4} f_3$$

$$y_4^p = 0.8085 + 1.9 f_1 \dots$$

$$y_4^c = y_3 + \frac{0.2}{24} \int_{y_3}^{y_4} g - f(y_4, y_4^p)$$

$$= 0.8088.$$

$$y_5^p = 0.7356$$

$$y_5^c = y_4 + \frac{0.2}{24} \int_{y_4}^{y_5} g - f(y_5, y_5^p)$$

$$= 0.7358.$$

### ⑤ Use milne - Simpson predictor - corrector

method

$$y(0) = 1 \quad h = 0.5$$

$$\frac{dy}{dx} = y_{\text{exact}} - (y_{\text{pred}} - y_{\text{corr}})$$

$$f(x, y) = y \sin x \quad y_0 = 0 \quad y_1 = 1 \quad h = 0.5$$

$$y_i^{(p)} = y_{i-3} + \frac{4h}{3} [f_{i-2} + 2f_{i-1} + 2f_i]$$

$$y_{i+1}^c = y_{i-1} + \frac{h}{3} [f_{i-2} + 2f_{i-1} + 2f_i + f_i^{(p)}]$$

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$$Q1. \frac{dy}{dx} = 2x+y \quad \left\{ \begin{array}{l} y(0) = 1 \\ h = 0.2 \end{array} \right.$$

forward euler:

$$\frac{dy}{dx} = f = 2x+y$$

$$\text{hori: } y_1 = 1 + (0.2) \cdot 1 = 1.2$$

$$\checkmark y_2 = 1.2 + 0.2 (0.4 + 1.2) = 1.2 + 0.2 (1.6) = 1.2 + 0.32 = 1.52 .$$

$y_{3+}$  : soon.

$$Q2. \quad y' = 2x+y \quad y(0) = 1 \quad h = 0.2 .$$

Implicit - 2 step method:

$$\text{hori: } y_{j+1} = y_j + \frac{1}{2} (k_1 + k_2) \quad \left\{ \begin{array}{l} k_1 = h \cdot f(t_j, y_j) \\ k_2 = h \cdot f(t_{j+1}, y_{j+1}) \end{array} \right.$$

$$y_1 = y_0 + \frac{1}{2} (k_1 + k_2)$$

$$k_1 = h \cdot f(0, 1) = 0.2 (1) = 0.2$$

$$k_2 = 0.2 f(0.2, 0.2 + 1) = 0.2 f(0.2, 1.2) = 0.2 (2(0.2) + 1.2) = 0.2 (1.6) = 0.32$$

$$y_1 = 1 + \frac{1}{2} (0.2 + 0.32) = 1.26 .$$

✓

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Solving  $e^x = q \Rightarrow x = \ln q$

as  $x \rightarrow 0$

then we write (2) in powers of  $(q-1)$

$$\begin{aligned}\log(e^x) &= \log(e^{x-1+1}) \\ &= \left[ e^{-1} + -\frac{1}{2}(e^{-1})^2 + \dots \right]\end{aligned}$$

and  $e^{x-1} = [\log(e)]^{x-1}$

$$= [e^{-1}]^{x-1} + O[e^{-1}]^{x-2}$$

in (2) we set

$$\begin{aligned}P(x) - \log(\{e\}^x \sigma(x)) &= c^{x-1} \{e^{-1}\}^{x-1} \\ &\quad + \underline{\alpha(-1)}^{x-2}\end{aligned}$$

$$\Rightarrow P(x) - \log(e) \sigma(x) = 0$$

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Sachin

1.

Arithm's - Backward methods  
 $\sigma(\epsilon) = \frac{\epsilon}{\epsilon-1} (i-1)$

$\epsilon^{\text{th}}$  degree

Find the explicit

$$\epsilon(2) = \epsilon(\epsilon-1) + \epsilon^2 - \epsilon$$

$\epsilon=2$

$$\sigma(\epsilon) = \frac{\epsilon(\epsilon)}{\log(\epsilon)} = \frac{(\epsilon-1)^2 + \epsilon - 1}{(\epsilon-1)^2 + 1}$$

$$= 1 + \frac{1}{2}(\epsilon-1) + (\epsilon-1) + \frac{1}{2}(\epsilon-1)^2 \quad (5)$$

$$= 1 + \frac{3}{2}(\epsilon-1) + O((\epsilon-1)^2) \quad (\text{poj}) = (3)\epsilon^2$$

$$P(\epsilon) = \epsilon^2 - \epsilon^0$$

$$\sigma(\epsilon) = \frac{3}{2}\epsilon - 1$$

The AB explicit Method:

$$P(E) u_{j-k+1} - h \sigma(E) (u'_{j-k+1}) = 0$$

$$(E^2 - E) u_{j-1} - h \left( \frac{3}{2}E - \frac{1}{2}I \right) u'_{j-1} = 0$$

$$(u'_{j+1} - u'_j) - h \left[ \frac{3}{2}u'_j - u'_{j-1} \right] = 0$$

*classmate*

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Adams - Motson method :

$$\rho(\epsilon) = \epsilon^{k-1} (\epsilon - 1)$$
$$\sigma(\epsilon) = K^k \quad \text{step.}$$

$$K=2 \quad \therefore \quad \sigma(\epsilon) = 1 + \frac{3}{2} (\epsilon - 1) + \frac{5}{12} (\epsilon - 1)^2$$

$$U_{j+1} = U_j + \frac{h}{12} [5f_{j+1} + 8f_j - f_{j-1}] \quad P=3$$

- Order calcn on multistep diff from single step method.

Nystrom method (Milne's)

$$\rho(\epsilon) = \epsilon^{k-2} (\epsilon^2 - 1)$$

explicit method.  $\sigma(\epsilon) = (k-1)^{th}$

$$\sigma(\epsilon) = (k-1)$$

impl.  $\sigma(\epsilon) = K^k$

Milne's Simpson.

K=3,

$$U_{j+1} = U_{j-1} + \frac{h}{3} [-7U_j + 2U_{j-1} + U_{j-2}]$$

One Milne Simpson method:

$$\text{Milne Simpson} \quad u_j = \frac{h}{3} [u_{j+1}' + 4u_j' + u_{j-1}'] \quad 1$$

$$h=2 \quad u_{j+1} = u_j + \frac{h}{3} \quad 2$$

$$h=3 \quad \boxed{\{ p=1 \}} \quad 3$$

### Numerical differentiation formulae

given  $\nabla(\epsilon) = \epsilon^k$  deg.  $k$

fixed  $\rho(\epsilon)$  of ~~deg.~~  $k$

$$\rho(\epsilon) = \epsilon^2 + 2(\epsilon - 1) + (\epsilon - 1)^2 \quad k=2$$

$$\rho(\epsilon). \nabla(\epsilon) = \rho(\epsilon) \quad \text{from above condition}$$

$$= (\epsilon - 1) + \frac{3}{2}(\epsilon - 1)^2 + O(\epsilon - 1)^3$$

$$\rho(\epsilon) = \frac{3}{2}\epsilon^2 - 2\epsilon + \frac{1}{2}$$

$$\rho(E) U_{j-k+1} - h \nabla(E) U_{j-k+1}' = 0$$

$$\int_2^3 [E^2 - 2E + 1] U_{j-k+1}' = h E^2 U_{j-k+1}'$$

$$h U_{j+1}' = \frac{3}{2} U_{j+1} - 2U_j + \frac{1}{2} U_{j-1}$$

zarith

linear  
multistep methods

LMSM

Saatihi

	$a_0$	$a_1$	$a_2$	$a_3$	$a_4$
1	1	-1			
2	$\frac{3}{2}$	-2	$\frac{1}{2}$		
3	$\frac{1}{6}$	-3	$\frac{5}{2}$	$-\frac{1}{3}$	
4	$\frac{25}{12}$	-5	3	$-\frac{1}{3}$	$\frac{1}{4}$

Exercise

$$\text{given } \sigma(\epsilon) = (25\epsilon^2 - 16\epsilon + 5)$$

find  $s(\epsilon)$  — explicit

$$P(a) = \log \epsilon \cdot \sigma(\epsilon)$$

$$v_{j+1} = v_j + \frac{h}{12} (23v'_1 - 16v'_{j-1} + 5v'_{j-2}) \cdot P=3.$$

$$P(\epsilon) > (\epsilon-1)^{\epsilon-1} \quad -1 \leq \lambda \leq 1$$

$s(\epsilon)$  — implicit

when  $\lambda = 0$

$$\lambda = -1$$