

$y'' + A(x)y' + B(x)y = C(x), \quad y(0) = y_0, \quad y(a) = y_a$
 $A(x) \neq 0$, at $x = x_k$; $y_k'' + A_k y_k' + B_k y_k = C_k$
 $A_k y_k' = C_k - y_k'' - B_k y_k$
 $p_k(x_k) = y_k'$, $p_{k-1}'(x_k) = y_k' \rightarrow \textcircled{\text{II}}$
 $\hookrightarrow k=0, 1, 2, \dots, n \quad \textcircled{\text{I}} \quad k=1, 2, \dots, n$

$M_k, y_k \rightarrow$ unknowns

$2n$ relations, M_0, M_1, \dots, M_n & $y_1, \dots, y_{n-1} \Rightarrow 2n$ unknowns.

System of equations $\textcircled{\text{I}}$ & $\textcircled{\text{II}}$ are coupled set of $2n$ linear equations involving $2n$ unknowns M_0, M_1, \dots, M_n & y_1, y_2, \dots, y_{n-1} .

$p_k'(x_k) = y_k'$

$$\left(1 - \frac{h}{3} A_k\right) M_k - \frac{h}{6} A_k M_{k+1} = C_k - B_k y_k - \frac{A_k}{h} (y_{k+1} - y_k)$$

$k=0, 1, \dots, n-1. \quad \textcircled{\text{I}}$

$p_{k-1}'(x_k) = y_k'$; $\frac{h}{6} A_k M_{k-1} + \left(1 + \frac{h}{3} A_k\right) M_k = C_k - B_k y_k$

$-\frac{A_k}{h} (y_k - y_{k-1}) - \textcircled{\text{II}}$

$k=1, 2, \dots, n$

(Q) Solve the BVP: $y'' + 2y' + y = 30x$, $y(0) = 0 = y(1)$, $h=0.5$.

$y_1 = ?$

~~$M_0 = 0$~~

$y_0 = 0, y_2 = 0$

$\rightarrow \left(1 - \frac{h}{3} \cdot 2\right) M_0 - \frac{h}{6} \cdot 2 M_1 = 30(0) - y_0 - \frac{2}{h} (y_1 - y_0)$

$\frac{2 M_0}{6} + \left(1 + \frac{2h}{3}\right) M_1 = 30(0.5) - y_1 - \frac{2}{h} (y_1 - y_0)$

~~$\left(1 + \frac{2h}{3}\right) M_1 = \dots$~~

Spline →

①

Higher order of accuracy.

②

 f_k' is also determined.

< Higher order compact difference scheme

 $y \sim p_k(x)$ in $[x_k, x_{k+1}]$

↳ Hermit interpolation polynomial

Non-Linear BVP

$$F(x, y, y', y'') = 0$$

$$\frac{dy}{dx} = f(x, y, y'), \quad 0 \leq x \leq a$$

$$y_0 = y(0), \quad y(a) = y_a$$

where F is any arbitrary function

$$y'' + 2y y' = 4 + x^2, \quad y(1) = 2, \quad y(2) = 4$$

$$\frac{y_{i+1} - y_i + y_{i-1} + 2y_i}{h^2} = 4 + x_i^2 \quad (i=1, 2, \dots, n-1) \quad (2)$$

which are $(n+1)$ algebraic equations involving $(n+1)$ unknowns, y_1, \dots, y_n

System of eqns. are non-linear, cannot be expressed in matrix form.

Non-linear algebraic eqns

Newton-Raphson method for root finding of a nonlinear eqn. $f(x) = 0$, f is any function of x and if α is the root, then $f(\alpha) = 0, \alpha = ?$ We determine the root iteratively. At any iteration level k , let $x^{(k)}$ is the approx. value of α . The root and let Δx is the error, i.e., $\alpha = x^{(k)} + \Delta x$. $f(\alpha) = 0, \quad f(x^{(k)} + \Delta x) = 0, \quad \Delta x$ is unknown expand by Taylor series

$$0 = f(x^{(k)}) + \Delta x f'(x^{(k)}) + \frac{(\Delta x)^2}{2!} f''(x^{(k)}) + \dots$$

which is an infinite degree polynomial in Δx .Retaining only upto linear order in Δx , we get

$$f(x^{(k)}) + \Delta x f'(x^{(k)}) \approx 0, \quad \Delta x = -\frac{f(x^{(k)})}{f'(x^{(k)})}$$

and the successive approx. for $f'(x^{(k)})$

$$x^{(k+1)} = x^{(k)} - \frac{f(x^{(k)})}{f'(x^{(k)})}, \quad k \geq 0$$

we repeat the process

$$\text{till } |x^{(k+1)} - x^{(k)}| < \epsilon \Rightarrow |\Delta x| < \epsilon$$

Iteration (1) starts with an initial given $x^{(0)}$ for the root; at each iteration, the approx. for the root is modified.

$$\{x_k | k=0, 1, \dots, n\}, \quad x_k \rightarrow \alpha, \text{ as } k \rightarrow \infty$$

$$x_k \rightarrow \alpha, \text{ as } k \rightarrow \infty$$

$$\Rightarrow |x_k - \alpha| < \epsilon, \quad \forall k > K$$

 $K > 0$ a finite integer

$$\alpha = \lim_{k \rightarrow \infty} x_k, \quad \epsilon \in \mathbb{R} \text{ is an arbitrary small quantity}$$

$$|x_k - x_{k+1}| < \epsilon, \quad \forall k > K \quad (\text{stop})$$

Non-linear BVP:- Newton's linearization technique.

$$F(x, y, y', y'') = 0, \quad 0 \leq x \leq a, \quad y_0 \text{ \& } y_a \text{ are given}$$

$$x_i = i \Delta x, \quad \text{are grid points}$$

Discretize the ODE to get $y(x)$

$$f_i(y_{i-1}, y_i, y_{i+1}) = 0, \quad i=1, 2, \dots, n-1$$

where f_i are known (algebraic) function of y_{i-1}, y_i & y_{i+1}

We solve the system of non linear algebraic eqns. iteratively by using the Newton's

linearization technique is, at the $(k+1)^{th}$ iteration $y_i^{(k+1)} = y_i^{(k)} + \Delta y_i$, $i=0, \dots, n$ \rightarrow (a)
 Δy_i is the error at the k^{th} iteration.

$\Delta y_0 = \Delta y_n = 0$ at the two boundary pts.

Substitute (a) in the discretized eqn (b) to get

$$f_i(y_{i-1}^{(k)} + \Delta y_{i-1}, y_i^{(k)} + \Delta y_i, y_{i+1}^{(k)} + \Delta y_{i+1}) = 0 \quad i=0, 1, \dots, n-1 \quad (b)$$

Δy_i for $i=1, 2, \dots, n-1$ are unknowns.

Expand (b) by Taylor series,

$$f_i(y_{i-1}^{(k)}, y_i^{(k)}, y_{i+1}^{(k)}) + \frac{\partial f_i}{\partial y_{i-1}} \Delta y_{i-1} + \frac{\partial f_i}{\partial y_i} \Delta y_i + \frac{\partial f_i}{\partial y_{i+1}} \Delta y_{i+1} + O(\Delta y_{i-1}^2 + \Delta y_i^2 + \Delta y_{i+1}^2) = 0$$

$i=1, 2, \dots, n-1$

which are $(n-1)$ eqns involving $\Delta y_1, \Delta y_2, \dots, \Delta y_{n-1}$, i.e. $(n-1)$ unknowns.

Retaining only upto linear orders in Δy_i s, we get a reduced set of linear algebraic eqns

$$\frac{\partial f_i}{\partial y_{i-1}} \Delta y_{i-1} + \frac{\partial f_i}{\partial y_i} \Delta y_i + \frac{\partial f_i}{\partial y_{i+1}} \Delta y_{i+1} = -f_i(y_{i-1}^{(k)}, y_i^{(k)}, y_{i+1}^{(k)})$$

$i=1, 2, \dots, n-1$

which forms $(n-1)$ linear tri-diag. system for $\Delta y_1, \Delta y_2, \dots, \Delta y_{n-1}$, which can be cast as $AX=d$, $AT=[\Delta y_1, \Delta y_2, \dots, \Delta y_{n-1}]$

Substitute

$$\Delta y_0 = \Delta y_n = 0$$

The solution Δy_i is determined by solving $AX=d$, we get the next approximation for y_i as

$$y_i^{(k+1)} = y_i^{(k)} + \Delta y_i$$

\hookrightarrow modified soln, $\epsilon > 0 \rightarrow$ pre-specified accuracy.

Repeat the process, $\max_{1 \leq i \leq n-1} |\Delta y_i| < \epsilon$

Steps \rightarrow (1) Discretize the nonlinear ODE

(2) Solve the ensuing nonlinear algebraic eqn iteratively.

(3) at each iteration, $y_i^{(k+1)} = y_i^{(k)} + \Delta y_i$

(4) Solve the tri-diag. system $AX=d$ to get Δy_i s.

(5) Repeat till $\max_{1 \leq i \leq n-1} |\Delta y_i| < \epsilon$

(6) $y'' + 2yy' = 4 + 4x^2$, $y(1)=2$, $y(2)=4$, $h=0.25$.

$\Delta y_0 = -2y_0 + y_1 = 0$, $2y_1(y_{i+1} - y_{i-1}) = 4 + 4x_i^2$

To start the method, we need to guess $y_i^{(0)}$, $1 \leq i \leq n$

$y_0 = 2$, $y_2 = 4$, $y_1^{(0)} = 3$, $y_3^{(0)} = 3.5$

$$\frac{1}{h^2} (y_{i-1}^{(k)} - 2y_i^{(k)} + y_{i+1}^{(k)} + \Delta y_{i-1} - 2\Delta y_i + \Delta y_{i+1}) + \frac{1}{h} (y_i^{(k)} + \Delta y_i)(y_{i+1}^{(k)} + \Delta y_{i+1} - y_{i-1}^{(k)} - \Delta y_{i-1}) = 4 + 4x_i^2$$

$$a_i \Delta y_{i-1} + b_i \Delta y_i + c_i \Delta y_{i+1} = d_i$$

Non-linear BVP

Newton's linearization technique: Iterative Method

Max $|\Delta y_i| = X < 10^{-5} = \epsilon \rightarrow \text{converged.}$

$y_i^{(0)}$ & i needs to be provided.
 $\{y_i^{(k)} | k \geq 0\} \lim_{k \rightarrow \infty} y_i^{(k)} \rightarrow y_i \Rightarrow |\Delta y_i| < \epsilon$
 $\epsilon = 0.5 \times 10^{-5}$

k	Δy_i
1	—
2	—
3	—

↑ decrease

$$L[y] = 0 \Rightarrow F_i(y_{i-1}, y_i, y_{i+1}) = 0, i = 1, 2, \dots, n-1$$

$$\Delta y_{i-1} \frac{\partial F_i}{\partial y_{i-1}} + \Delta y_i \frac{\partial F_i}{\partial y_i} + \Delta y_{i+1} \frac{\partial F_i}{\partial y_{i+1}} = d_i$$

$$\Delta y_0 = \Delta y_n = 0, k \geq 0, i = 1, 2, \dots, n-1$$

$$a_i \Delta y_{i-1} + b_i \Delta y_i + c_i \Delta y_{i+1} = d_i \Rightarrow AX = d$$

$$X = \begin{bmatrix} \Delta y_1 \\ \Delta y_2 \\ \Delta y_3 \\ \vdots \\ \Delta y_n \end{bmatrix}, y_i^{(k+1)} = y_i^{(k)} + \Delta y_i, i = 1, 2, \dots, n-1$$

Repeat till Max $|\Delta y_i| < \epsilon$
 $1 \leq i \leq n-1$

Ex1 $y'' - (y')^2 - y^2 + y + 1 = 0, y(0) = 0.5, y(\pi) = -0.5$
 Discretize by central diff. sol

$$\frac{1}{h^2} (y_{i+1} - 2y_i + y_{i-1}) - \frac{1}{4h^2} (y_{i+1} - y_{i-1})^2 - y_i^2 + y_i + 1 = 0, i = 1, 2, \dots, n-1$$

At $(k+1)^{\text{th}}$ iteration, $y_i^{(k+1)} = y_i^{(k)} + \Delta y_i, k \geq 0, i = 1, \dots$

Substitute in (8)

$$\frac{1}{h^2} [y_{i+1}^{(k)} + \Delta y_{i+1} - 2y_i^{(k)} - 2\Delta y_i + y_{i-1}^{(k)} + \Delta y_{i-1}] - \frac{1}{4h^2} [y_{i+1}^{(k)} + \Delta y_{i+1} - y_{i-1}^{(k)} - \Delta y_{i-1}]^2 - (y_i^{(k)} + \Delta y_i)^2 + y_i^{(k)} + \Delta y_i + 1 = 0$$

$$\frac{1}{h^2} (y_{i+1}^{(k)} - y_{i-1}^{(k)})^2 + \frac{2}{h^2} (y_{i+1}^{(k)} - \Delta y_{i+1} - y_{i-1}^{(k)} + \Delta y_{i-1}) (y_{i+1}^{(k)} - y_{i-1}^{(k)}) + (y_i^{(k)})^2 + 2\Delta y_i y_i^{(k)} = 0$$

$$a_i \Delta y_{i-1} + b_i \Delta y_i + c_i \Delta y_{i+1} = d_i, i = 1, 2, 3, \dots, n-1$$

$$a_i = \frac{1}{h^2} + \frac{1}{2h^2} (y_{i+1}^{(k)} - y_{i-1}^{(k)}), b_i = \frac{-2}{h^2} - 2y_i^{(k)} + 1$$

$$c_i = \frac{1}{h^2} + \frac{1}{2h^2} (y_{i+1}^{(k)} - y_{i-1}^{(k)}), d_i = -1 - \frac{1}{h^2} [y_{i+1}^{(k)} - 2y_i^{(k)} + y_{i-1}^{(k)}] + \frac{1}{4h^2} [y_{i+1}^{(k)} - y_{i-1}^{(k)}]^2 + (y_i^{(k)})^2 - y_i^{(k)}$$

$$\Delta y_0 = \Delta y_n = 0, i = 1, 2, \dots, n-1$$

$AX = d, \rightarrow \text{solve to get } \Delta y_i$

$y_i^{(0)}$ needs to be specified $\forall i$

$y^{(0)}(x) = f(x)$, should satisfy the boundary condition

$$y^{(0)}(x) = \frac{x - \pi}{-\pi} (0.5) + \frac{x}{\pi} (0.5) (-1)$$

$$y^{(0)}(x) = \frac{-x}{\pi} + 0.5$$

Lab 10

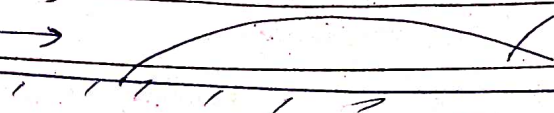
Q $3yy'' + (y')^2 = 0, y(0) = 0, y(1) = 1 \rightarrow \text{unique}$

Discretize

$$3y_i (y_{i+1} - 2y_i + y_{i-1}) + \frac{(y_{i+1} - y_{i-1})^2}{h} = 0, h = 1/3$$

At the $(k+1)^{\text{th}}$ iteration, $y_i^{(k+1)} = y_i^{(k)} + \Delta y_i$
 Substituting in (8)

or fluid movement



11.7

$$f''' + ff'' + 1 - (f')^2 = 0$$

$$f(0) = f'(0) = 0$$

$$f'(1) = 1$$

Get the reduced block-tridiagonal system which needs to be solved at every iteration.

$$X_i = \begin{pmatrix} f_i \\ F_i \end{pmatrix}$$

$$F = f'$$

$$F'' + fF' + 1 - F^2 = 0$$