Al Lab - Session 5 Model-Free Reinforcement Learning

Riccardo Sartea

University of Verona Department of Computer Science

June 7th 2019



Start Your Working Environment

Start the previously installed (Session 1) conda environment ai-lab

Listing 1: Upgrade and spin up

cd ai-lab git pull conda activate ai-lab jupyter notebook

AI Lab - Session 5 Introduction 2/6

Tutorial

There is no specific tutorial for this session since there is nothing new with respect to what you have already used before

Al Lab - Session 5 Tutorial 3/6

Assignments

- Your assignments for this session are at: session5/session5_mfrl.ipynb. You will be required to implement Q-Learning and SARSA algorithms
- In the following you can find the pseudocodes

AI Lab - Session 5 Model-Free RL 4/6

Q-Learning

```
Input: environment [A, S], problem, episodes, \alpha, \gamma, expl\_func, expl\_param
Output: policy, rewards, lengths
 1: \forall a \in A, \forall s \in S initialize Q(s, a) arbitrarily
 2: rewards, lengths \leftarrow [0, ..., 0]
                                                                   Null vectors of length episodes
 3: for i \leftarrow 0 to episodes do
         Initialize s
 4:
 5:
         repeat
 6:
             a \leftarrow \text{EXPL\_FUNC}(Q, s, expl\_param)
7:
             s', r \leftarrow take action a from state s
                                                                                      Act and observe
             Q(s, a) \leftarrow Q(s, a) + \alpha (R + \gamma \max_{a \in A_s} Q(s', a) - Q(s, a))
 8:
                                                                                                      D TD
 9:
             s \leftarrow s'
         until s is terminal
10:
11:
         Update rewards, lengths
12: \pi \leftarrow [0, ..., 0]
                                                                            \triangleright Null vector of length |S|
13: for each s in S do
                                                                                         14:
         \pi_s \leftarrow \operatorname{argmax} Q(s, a)
                  a \in A_s
15: return \pi, rewards, lengths
```

AI Lab - Session 5 Model-Free RL 5/6

SARSA

```
Input: environment [A, S], problem, episodes, \alpha, \gamma, expl_func, expl_param
Output: policy, rewards, lengths
 1: \forall a \in A, \forall s \in S initialize Q(s, a) arbitrarily
 2: rewards, lengths \leftarrow [0, ..., 0]
                                                                  Null vectors of length episodes
 3: for i \leftarrow 0 to episodes do
 4:
         Initialize s
 5:
        a \leftarrow \text{EXPL\_FUNC}(Q, s, expl\_param)
 6:
        repeat
 7:
             s', r \leftarrow take action a from state s
                                                                                     Act and observe
             a' \leftarrow \text{EXPL\_FUNC}(Q, s', expl\_param)
 8:
             Q(s,a) \leftarrow Q(s,a) + \alpha(R + \gamma Q(s',a') - Q(s,a))
9:
                                                                                                    D □ TD
            s \leftarrow s'
10:
            a' \leftarrow a
11:
12:
        until s is terminal
13:
         Update rewards, lengths
14: \pi \leftarrow [0, ..., 0]
                                                                           \triangleright Null vector of length |S|
15: for each s in S do
                                                                                       \pi_s \leftarrow \operatorname{argmax} Q(s, a)
16:
                  a \in A
17: return \pi, rewards, lengths
```

AI Lab - Session 5 Model-Free RL 6/6