

# Practical-1: Pen and paper exercises

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November 7, 2016

## Exercise 1

We start by the loss function which is given by  $\mathcal{L} = 0.5(y_{out} - y_{gt})^2$ . Using this we compute the derivatives of the loss function with respect to the weights starting from

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial W_{out}} &= \frac{\partial}{\partial W_{out}} (0.5(y_{out} - y_{gt})^2) \\ &= 2 \times 0.5(y_{out} - y_{gt}) \frac{\partial}{\partial W_{out}} (y_{out} - y_{gt}) \\ &= (y_{out} - y_{gt}) \frac{\partial}{\partial W_{out}} y_{out} \\ &= (y_{out} - y_{gt}) \frac{\partial}{\partial W_{out}} (f_3(W_{out} f_2(w_2 f_1(w_1 x_{in})))) , \text{ by the chain rule} \\ &= (y_{out} - y_{gt}) \frac{\partial f_3(s_{out})}{\partial W_{out}} z_2.\end{aligned}$$

Similarly,

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial W_2} &= (y_{out} - y_{gt}) \frac{\partial \mathcal{L}}{\partial W_2} (f_3(W_{out} f_2(w_2 f_1(w_1 x_{in})))) , \text{ by the chain rule} \\ &= (y_{out} - y_{gt}) \frac{\partial f_3(s_{out})}{\partial W_{out}} \frac{\partial \mathcal{L}}{\partial W_2} (f_2(w_2 f_1(w_1 x_{in}))) \\ &= (y_{out} - y_{gt}) \frac{\partial f_3(s_{out})}{\partial W_{out}} \frac{\partial f_2(s_2)}{\partial W_2} z_1.\end{aligned}$$

And similarly,

$$\begin{aligned}\frac{\partial \mathcal{L}}{\partial W_1} &= (y_{out} - y_{gt}) \frac{\partial \mathcal{L}}{\partial W_1} (f_3(W_{out} f_2(w_2 f_1(w_1 x_{in})))) , \text{ by the chain rule} \\ &= (y_{out} - y_{gt}) \frac{\partial f_3(s_{out})}{\partial W_{out}} \frac{\partial f_2(s_2)}{\partial W_2} \frac{\partial \mathcal{L}}{\partial W_1} (f_1(w_1 x_{in})) \\ &= (y_{out} - y_{gt}) \frac{\partial f_3(s_{out})}{\partial W_{out}} \frac{\partial f_2(s_2)}{\partial W_2} \frac{\partial f_1(s)}{\partial W_1}.\end{aligned}$$

## Prelude

We start by  $\Delta W_N = \frac{\partial \mathcal{L}}{\partial W_N}$ ,

$$\begin{aligned}\Delta W_N &= \frac{\partial \mathcal{L}}{\partial W_N} = \delta_N \\ \Delta W_{N-1} &= \delta_N w_{N-1} \frac{\partial \mathcal{L}}{\partial W_{N-1}} \\ \Delta W_{N-2} &= \delta_{N-1} w_{N-2} \frac{\partial \mathcal{L}}{\partial W_{N-2}} \\ &\vdots \\ \Delta W_0 &= \delta_1 w_0 \frac{\partial \mathcal{L}}{\partial W_0}\end{aligned}$$

We can write the general form for the weight updates  $\Delta W_{i \rightarrow j} = \delta_j z_i$ .

## Exercise-2

Iteration #1 for the first sample [0.75, 0.8]:

- $s_i = [0.458, 0.869, 0.704]$
- $z_i = [0.458, 0.869, 0.704]$
- $s_{out} = 0.098589999999999997$
- $z_{out} = 0.098589999999999997$ , using ReLU as activation function in the output unit.
- $\mathcal{L} = 0.40626999405000003$
- $\delta_{out} = (z_{out} - x[0]) \frac{\partial \mathcal{L}}{\partial s_{out}} = -0.098589999999999997$
- $\delta_i = \delta_{out} \frac{\partial \mathcal{L}}{\partial s_i} = [-0.90141, -0.90141, -0.90141]$
- $w = [0.10256916, 0.18666506, 0.21691853]$
- $W = [[0.7352115, 0.8352115, 0.1352115], [0.1542256, 0.5742256, 1.0242256]]$

Using the following script in python we proceed:

```
_x = x[0] # sample
_y = y[0] # target
s_i = np.dot(_x, W) # forward propagation
z_i = relu(s_i) # relu at s_i
s_out = np.dot(z_i, w) # forward propagation
```

```

z_out = relu(s_out) # relu at s_out
L = error(z_out, _y) # error
delta_out = (z_out - _y) * d_relu(s_out) # error signal at s_out
delta_i = delta_out * d_relu(s_i) # error signal at s_i
Delta_w = - theta * delta_out * z_i # derivative at weights w
Delta_W = - theta * delta_i * _x.reshape((2,1)) # derivative at weights W
w = w + Delta_w # new w
W = W + Delta_W # new W

```

Here we present the results for all iterations and all samples:

```

-Iteration: 0
---- sample: 0
  _x: [ 0.75  0.8 ]
  _y: 1
  s_i: [ 0.458  0.869  0.704]
  z_i: [ 0.458  0.869  0.704]
  s_out: 0.09859
  z_out: 0.09859
  L: 0.40626999405
  delta_out: -0.90141
  delta_i: [-0.90141 -0.90141 -0.90141]
  Delta_w: [ 0.08256916  0.15666506  0.12691853]
  Delta_W: [[ 0.1352115  0.1352115  0.1352115]
[ 0.1442256  0.1442256  0.1442256]]
  w: [ 0.10256916  0.18666506  0.21691853]
  W: [[ 0.7352115  0.8352115  0.1352115]
[ 0.1542256  0.5742256  1.0242256]]

-Iteration: 1
---- sample: 0
  _x: [ 0.75  0.8 ]
  _y: 1
  s_i: [ 0.68697511  0.09797511  0.91497249]
  z_i: [ 0.68697511  0.09797511  0.91497249]
  s_out: 0.338770985555
  z_out: 0.338770985555
  L: 0.218611904772
  delta_out: -0.661229014445
  delta_i: [-0.66122901 -0.66122901 -0.66122901]
  Delta_w: [ 0.09084957  0.1452026  0.12100127]
  Delta_W: [[ 0.09918435  0.09918435  0.09918435]
[ 0.10579664  0.10579664  0.10579664]]
  w: [ 0.19139386  0.33768451  0.18478376]
  W: [[ 0.82947987  0.92947987  0.40369876]
[ 0.27986348  0.69986348  0.96403  ]]

-Iteration: 2
---- sample: 0
  _x: [ 0.75  0.8 ]
  _y: 1
  s_i: [ 0.85468168  1.26568168  1.06573624]
  z_i: [ 0.85468168  1.26568168  1.06573624]
  s_out: 0.689419606272
  z_out: 0.689419606272
  L: 0.0482300904842
  delta_out: -0.310580393728
  delta_i: [-0.31058039 -0.31058039 -0.31058039]
  Delta_w: [ 0.05308947  0.07861918  0.06619936]
  Delta_W: [[ 0.04658706  0.04658706  0.04658706]
[ 0.04969286  0.04969286  0.04969286]]
  w: [ 0.24073021  0.41988187  0.15732563]
  W: [[ 0.86662429  0.96662429  0.60480604]
[ 0.34926007  0.76926007  0.85853287]]

-Iteration: 0
---- sample: 1
  _x: [ 0.2  0.05]
  _y: 1
  s_i: [ 0.15475358  0.19575358  0.07825358]
  z_i: [ 0.15475358  0.19575358  0.07825358]
  s_out: 0.0693879488373
  z_out: 0.0693879488373
  L: 0.433019394885
  delta_out: -0.930612051163
  delta_i: [-0.93061205 -0.93061205 -0.93061205]
  Delta_w: [ 0.02880311  0.03643413  0.01456474]
  Delta_W: [[ 0.03722448  0.03722448  0.03722448]
[ 0.00930612  0.00930612  0.00930612]]
  w: [ 0.13137227  0.22309919  0.23148327]
  W: [[ 0.77243598  0.87243598  0.17243598]
[ 0.16353172  0.58353172  1.03353172]]

-Iteration: 1
---- sample: 1
  _x: [ 0.2  0.05]
  _y: 1
  s_i: [ 0.17988915  0.22088915  0.12894125]
  z_i: [ 0.17988915  0.22088915  0.12894125]
  s_out: 0.132846770649
  z_out: 0.132846770649
  L: 0.375977361587
  delta_out: -0.867153229351
  delta_i: [-0.86715323 -0.86715323 -0.86715323]
  Delta_w: [ 0.03119829  0.03830895  0.02236236]
  Delta_W: [[ 0.03468613  0.03468613  0.03468613]
[ 0.00867153  0.00867153  0.00867153]]
  w: [ 0.22259215  0.37599345  0.20714613]
  W: [[ 0.864166  0.964166  0.43838488]
[ 0.28853501  0.70853501  0.97270154]]

-Iteration: 2
---- sample: 1
  _x: [ 0.2  0.05]
  _y: 1
  s_i: [ 0.19078786  0.23178786  0.16388785]
  z_i: [ 0.19078786  0.23178786  0.16388785]
  s_out: 0.169035682078
  z_out: 0.169035682078
  L: 0.34525084883
  delta_out: -0.830964317922
  delta_i: [-0.83096432 -0.83096432 -0.83096432]
  Delta_w: [ 0.03107758  0.03852149  0.02723699]
  Delta_W: [[ 0.03323857  0.03323857  0.03323857]
[ 0.00830964  0.00830964  0.00830964]]
  w: [ 0.27243779  0.45840336  0.18456262]
  W: [[ 0.89986286  0.99986286  0.63804461]
[ 0.35756971  0.77756971  0.86684251]]

-Iteration: 0
---- sample: 2
  _x: [-0.75  0.8 ]
  _y: -1
  s_i: [-0.44850161 -0.18750161  0.69749839]
  z_i: [-0.44850161 -0.18750161  0.69749839]
  s_out: 0.161459210144
  z_out: 0.161459210144
  L: 0.674493748414
  delta_out: 1.16145921014
  delta_i: [ 0. 0. 1.16145921]
  Delta_w: [ 0. 0. -0.16202319]
  Delta_W: [[ 0. 0. 0.17421888]
[-0. -0. -0.18583347]]
  w: [ 0.13137227  0.22309919  0.06946009]
  W: [[ 0.77243598  0.87243598  0.34665486]
[ 0.16353172  0.58353172  0.84769825]]

-Iteration: 1
---- sample: 2
  _x: [-0.75  0.8 ]
  _y: -1
  s_i: [-0.41729649 -0.15629649  0.44937257]
  z_i: [-0.41729649 -0.15629649  0.44937257]
  s_out: 0.0930857863762
  z_out: 0.0930857863762
  L: 0.597418268189
  delta_out: 1.09308578638
  delta_i: [ 0. 0. 1.09308579]
  Delta_w: [ 0. 0. -0.09824055]
  Delta_W: [[ 0. 0. 0.16396287]
[-0. -0. -0.17489373]]
  w: [ 0.22259215  0.37599345  0.10890557]
  W: [[ 0.864166  0.964166  0.60234775]
[ 0.28853501  0.70853501  0.79780781]]

-Iteration: 2
---- sample: 2
  _x: [-0.75  0.8 ]
  _y: -1
  s_i: [-0.38884138 -0.12784138  0.21494055]
  z_i: [-0.38884138 -0.12784138  0.21494055]
  s_out: 0.0396699918483
  z_out: 0.0396699918483
  L: 0.540456845595
  delta_out: 1.03966999185
  delta_i: [ 0. 0. 1.03966999]
  Delta_w: [ 0. 0. -0.04469345]
  Delta_W: [[ 0. 0. 0.1559505]
[-0. -0. -0.1663472]]
  w: [ 0.27243779  0.45840336  0.13986918]
  W: [[ 0.89986286  0.99986286  0.79399511]
[ 0.35756971  0.77756971  0.70049531]]

-Iteration: 0
---- sample: 3
  _x: [ 0.2 -0.05]
  _y: -1
  s_i: [ 0.14631061  0.14531061  0.02694606]
  z_i: [ 0.14631061  0.14531061  0.02694606]
  s_out: 0.053511510936
  z_out: 0.053511510936
  L: 0.564943251837
  delta_out: 1.05351151094
  delta_i: [ 1.05351151  1.05351151  1.05351151]
  Delta_w: [-0.03082798 -0.03061728 -0.0056776 ]
  Delta_W: [[-0.04214046 -0.04214046 -0.04214046]
[ 0.01053512  0.01053512  0.01053512]]
  w: [ 0.10054428  0.19248191  0.06378249]
  W: [[ 0.73029552  0.83029552  0.3045144 ]
[ 0.17406684  0.59406684  0.85823336]]

-Iteration: 1
---- sample: 3
  _x: [ 0.2 -0.05]
  _y: -1
  s_i: [ 0.15840645  0.15740645  0.08057916]
  z_i: [ 0.15840645  0.15740645  0.08057916]
  s_out: 0.103219346565
  z_out: 0.103219346565
  L: 0.608546463317
  delta_out: 1.10321934656
  delta_i: [ 1.10321935  1.10321935  1.10321935]
  Delta_w: [-0.03495141 -0.03473077 -0.0177793 ]
  Delta_W: [[-0.04412877 -0.04412877 -0.04412877]
[ 0.01103219  0.01103219  0.01103219]]
  w: [ 0.18764074  0.34126269  0.09112628]
  W: [[ 0.82003723  0.92003723  0.55821898]
[ 0.2995672  0.7195672  0.80884  ]]

-Iteration: 2
---- sample: 3
  _x: [ 0.2 -0.05]
  _y: -1
  s_i: [ 0.16209409  0.16109409  0.12377426]
  z_i: [ 0.16209409  0.16109409  0.12377426]
  s_out: 0.135318828438
  z_out: 0.135318828438
  L: 0.644474421103
  delta_out: 1.13531882844
  delta_i: [ 1.13531883  1.13531883  1.13531883]
  Delta_w: [-0.03680569 -0.03657863 -0.02810465]
  Delta_W: [[-0.04541275 -0.04541275 -0.04541275]
[ 0.01135319  0.01135319  0.01135319]]
  w: [ 0.2356321  0.42182473  0.11176453]
  W: [[ 0.85445011  0.95445011  0.74858236]
[ 0.3689229  0.7889229  0.7118485  ]]

```

### Exercise-3

i)

Since  $\max(0, p_j - p_{y_i} + \text{margin})$  is minimized when  $p_j - p_{y_i} = -\text{margin}$  which results  $p_j = p_{y_i} - \text{margin}$ , the loss function is trying to maximize the difference of the probability output for the class  $p_{y_i}$  with regards to every other class  $j$  by the value of  $\text{margin}$ . In simple words,  $\mathcal{L}_{\text{hinge}}$  is trying to maximize the difference between probability outputs of different classes.

ii)

$$\frac{\partial \mathcal{L}_{\text{hinge}}}{\partial o_j} = \frac{\partial}{\partial o_j} (\max(0, p_j - p_{y_i} + \text{margin}))$$

For  $p_{y_i} > \text{margin}$ ,  $\frac{\partial \mathcal{L}_{\text{hinge}}}{\partial o_j} = 0$ , while for  $p_{y_i} = \text{margin}$ ,  $p_{y_i} > \text{margin}$ ,  $\frac{\partial \mathcal{L}_{\text{hinge}}}{\partial o_j} = \emptyset$ . We assume  $p_{y_i} < \text{margin}$ ,

$$\begin{aligned} \frac{\partial \mathcal{L}_{\text{hinge}}}{\partial o_j} &= \frac{\partial}{\partial o_j} (p_j - p_{y_i} + \text{margin}) \\ &= \frac{\partial}{\partial o_j} p_j \\ &= \frac{\partial}{\partial o_j} \left( \frac{\exp(o_j)}{\sum_k \exp(o_k)} \right) \\ &= \frac{\partial}{\partial o_j} \left( \frac{\exp(o_j)}{\exp(o_j) + \sum_{k \neq j} \exp(o_k)} \right) \\ &= (\exp(o_j))' \left( \exp(o_j) + \sum_{k \neq j} \exp(o_k) \right) - \exp(o_j) \left( \exp(o_j) + \sum_{k \neq j} \exp(o_k) \right)' \\ &= \exp(o_j) \left( \exp(o_j) + \sum_{k \neq j} \exp(o_k) \right) - \exp(2o_j) \\ &= \exp(2o_j) + \exp(o_j) \sum_{k \neq j} \exp(o_k) - \exp(2o_j) \\ &= \exp(o_j) \sum_{k \neq j} \exp(o_k), \end{aligned}$$

which is the derivative of the loss function  $\mathcal{L}_{\text{hinge}}$  with respect to  $o_j$ .

### Exercise-4