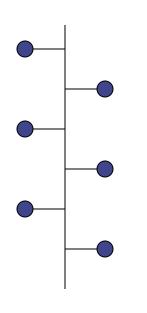
Rechnernetze und Verteilte Systeme

Introduction to Communication Networks and Distributed Systems



Unit 8: Algorithms for distributed systems



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Algorithms for distributed systems

- Overview
 - Transactions and Distributed coordination
 Very valuable additional set of slides:

www.ics.uci.edu/~cs223/handouts/2-3pc.ppt

Replication

Transactions

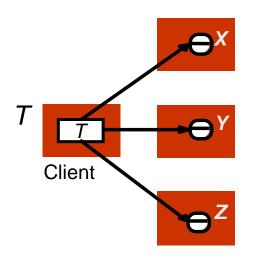
- A special case of atomic actions, originally from databases
- Sequence of operations that transforms a current consistent state to a new consistent state
 - Without ever exposing an inconsistent state
- Example
 - Move \$10 from my savings account to my checking account
 - Basically, subtract \$10 from savings account, add \$10 to checking account.

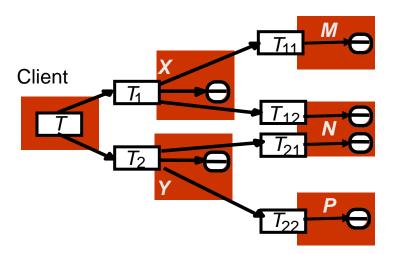
Be aware: Both might run on different computers!

But never "lose" my \$10 - and never give me an extra \$10!
Even if some computers will crash!

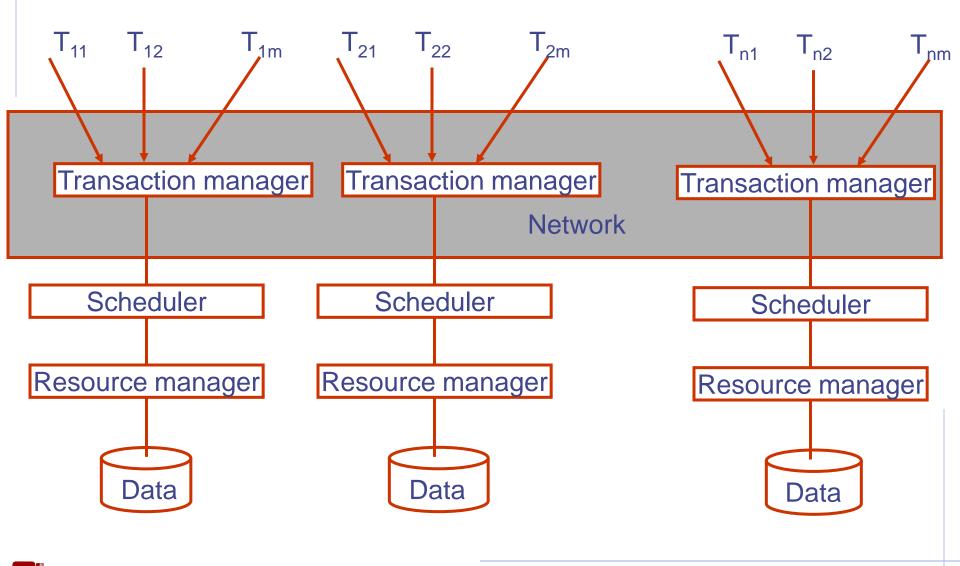
Basics

- Distributed transactions access objects located on spatially distributed servers (nodes)
 - Atomicity: Transaction is either committed by all nodes or aborted by all nodes
 - ⇒Coordination by one or by a group servers (nodes) necessary
- Transaction types
 - Plain transaction: current transaction finished, before starting a new one
 - Nested transaction: top level transaction can start further transactions



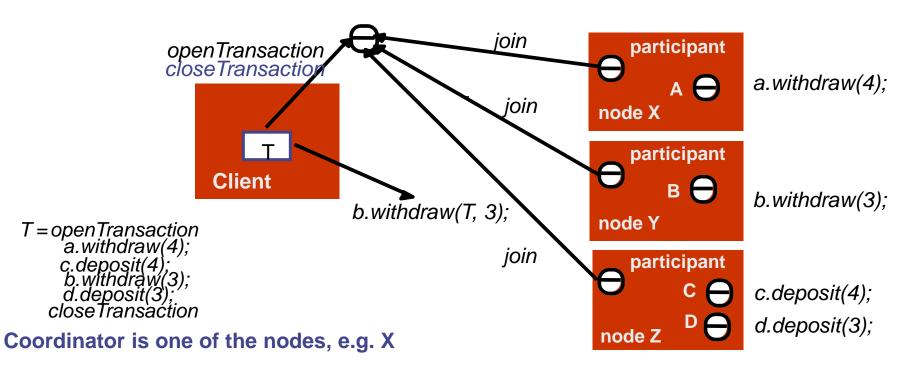


Transaction systems architecture



Coordinating distributed transactions

- Client starts a distributed transaction by openTransaction request
 - Manager opens the transaction, assigns a unique ID
 - Manager coordinates the transaction processing ⇒ responsible for commit/abort of the transaction
 - participant = server (node) with required objects (also called *cohort*)



Coordinator (2)

- During the execution of a distributed transaction
 - Coordinator creates a list with references to all participants
 - Participants acknowledge the coordinator
 - New participants can be inserted with functions such as join (Trans-ID, reference to a new participant)
 - Coordinator must be informed about new participants
- Coordinator calls closeTransaction

What Problems Could Arise?

- Other processes could write the variables
- Other processes could read the variables
- Failures could interrupt the process
- How can we avoid these problems?

Running Transactions

- Multiple transactions must not interfere
- You can run them one at a time
 - Or run them concurrently...
 - But avoiding all interference
- Serializability avoids interference
 - A property of a proposed schedule of transactions
 - A serializable schedule produces the same results as some serial execution of those transactions
 - Even though the actions may be have been performed in a different order

Indivisible actions, atomic action...

- If several users access a common resource with a sequence of actions at the same time, race conditions occur and the system can become inconsistent.
- Indivisible action
 - some actions are indivisible (e.g. actions on semaphores)
 - these can be used to group a sequence of actions into an indivisible action
- Atomic action (or transaction) with following characteristics
 - Indivisible, i.e. performed in one step;
 - Either successful or "has never happened",
 - ⇒data is not corrupted by only partially executed action sequences
 - Can consist of "normal" actions or embedded atomic actions.

Commit and Abort

- A commit is an unconditional guarantee that a transaction will be completed
- An abort is an unconditional guarantee that a transaction will be completely backed out
 - Requires returning system to its pre-transaction state
 - Typically done
 - either by logging/rolling back the changes or
 - by delaying updates until commit point is reached
- In both cases, regardless of multiple failures
- All transactions eventually either commit or abort

Distributed Commitment Mechanisms

- Mechanisms to guarantee atomicity of actions in a distributed system
- Important mechanisms for building distributed transactions
- Works with mechanisms to permit backing out of transactions

Distributed coordination

- Guaranteed correctness for distributed transactions is a complex issues, as node and networks failures can occur at any time
- Demands on commit protocol
 - All nodes meet the same decision.
 - One node is not allowed to change the decision once the decision was acknowledged
 - Decision to commit the transaction is allowed if and only if all nodes can commit
- Simplest implementation: 1 Phase commit (1PC):
 - Coordinator requests all participants to commit
 - Useless in real world
- Two phase commit protocol:
 - Phase 1: ask all participants about the status
 - Phase 2: decide on commit/abort, send the decision, request acknowledgments

Two Phase commit protocol (2PC)

2PC protocol with four layers

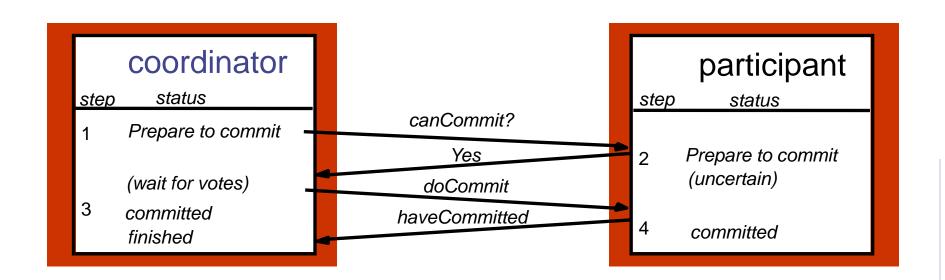
- vote request
- Vote
- Decision
- Acknowledge

Operations

- canCommit?(trans)-> Yes / No: Coordinator asks if the participant can commit the local transaction, participants vote
- doCommit(trans): Coordinator -> participant: commit transaction
- doAbort(trans): see doCommit(), now with abort
- haveCommitted(trans, participant): Participant -> coordinator:
 Transaction committed
- getDecision(trans) -> Yes / No: Participant -> coordinator, participants wants to know the decision on a certain transaction after the participant voted but did not receive an answer ⇒ Time out to recognize server failures

2PC procedure

- Coordinator asks all participants canCommit(), get the replies
- Coordinator evaluates the votes (also its own vote)
 - All votes Yes, then doCommit() for all nodes
 - One No vote, then call doAbort() to roll-back the transaction
- All participant wait for the command, acknowledge the execution
- If committed, ⇒ haveCommitted message sent to the coordinator



Characteristics of Two-Phase Commit

- Conditions to agree:
 - Access locked for other transactions
 - Possibility for atomic activation/roll back assured!
 (writing the state to permanent storage!!!)
- timeouts handle lost/delayed messages

Details: Abort by Write-Ahead Logs

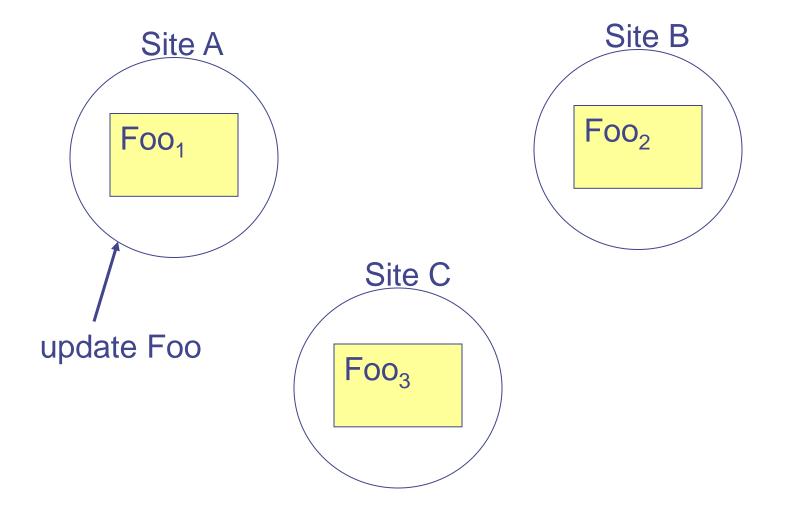
- An operation-based abort mechanism
 - Record operations and undo them, if necessary
- For each operation performed, record enough information to completely undo it
 - Either old state or other information
- Undo log

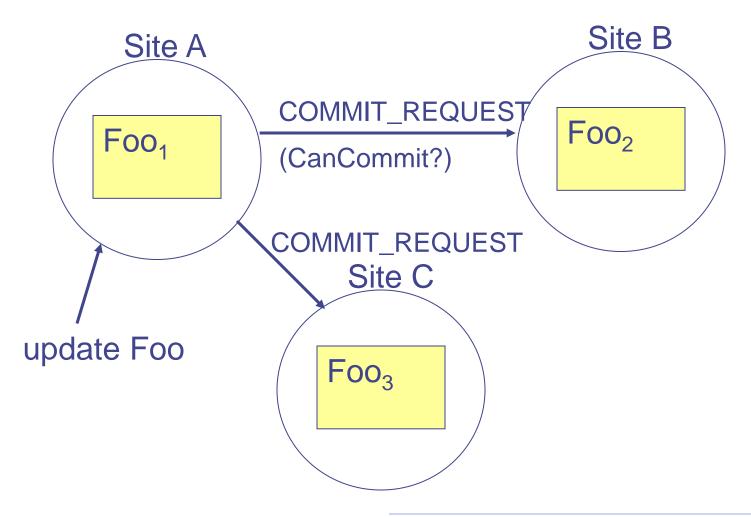
- Write-ahead Log Protocol
 - Write the undo log to stable storage
 - Make the update
 - If transaction commits, undo log can be deleted/garbage collected
 - If transaction aborts, use undo log to roll back operation
 - And then delete/garbage collect the log

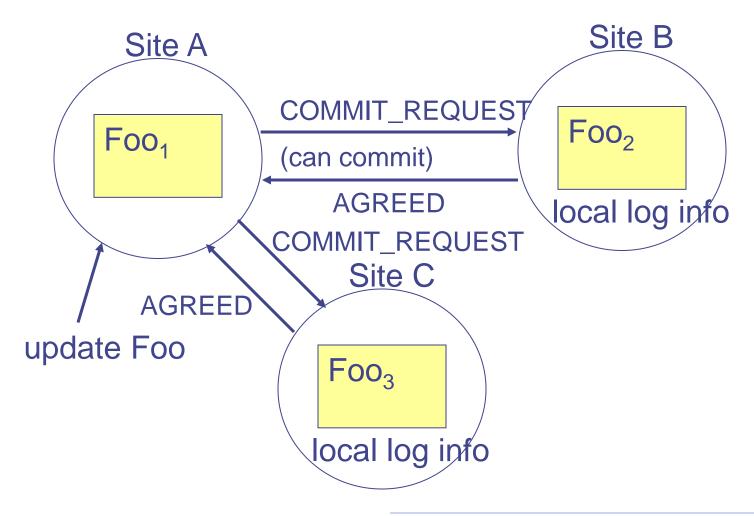
Details: Abort by Shadow Pages

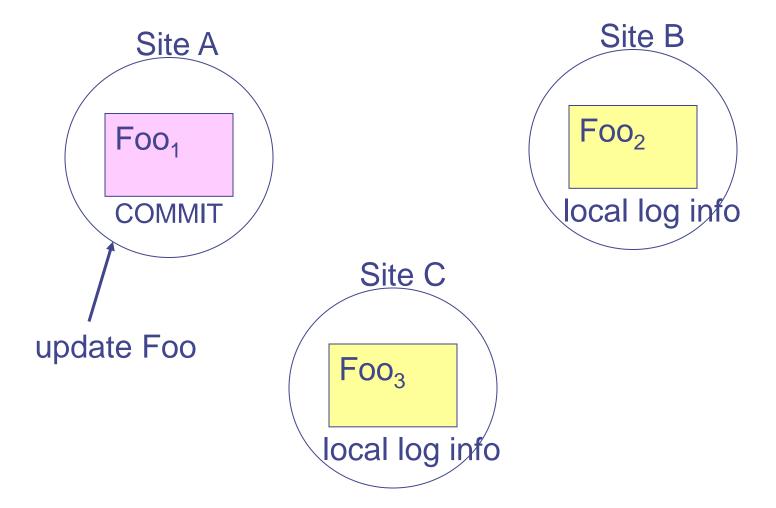
- State-based approach
- Save a checkpoint of the state before performing transaction operations
- If transaction aborts, restore old state
- Can be expensive if state is large
- Shadow paging limits the cost

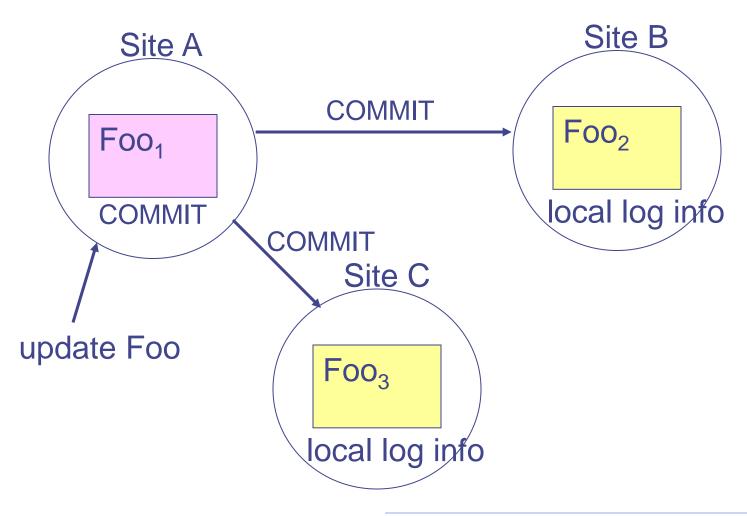
- Before writing a data item in a transaction
 - 1. Make a complete copy of its page
 - 2. Allow transaction to use the copy (transparently)
 - 3. On commit, switch shadow page for new page
 - 4. On abort, restore shadow page

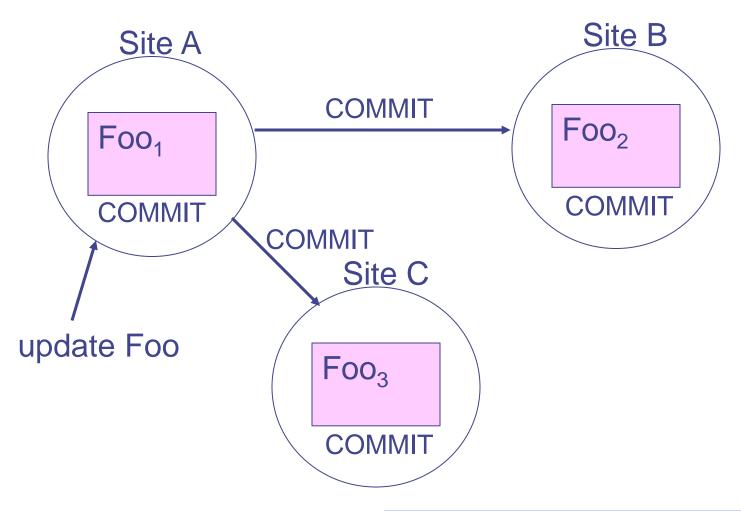


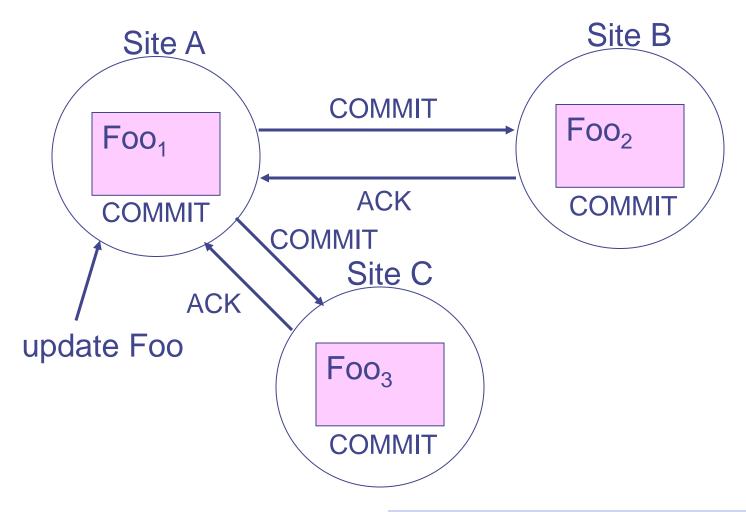


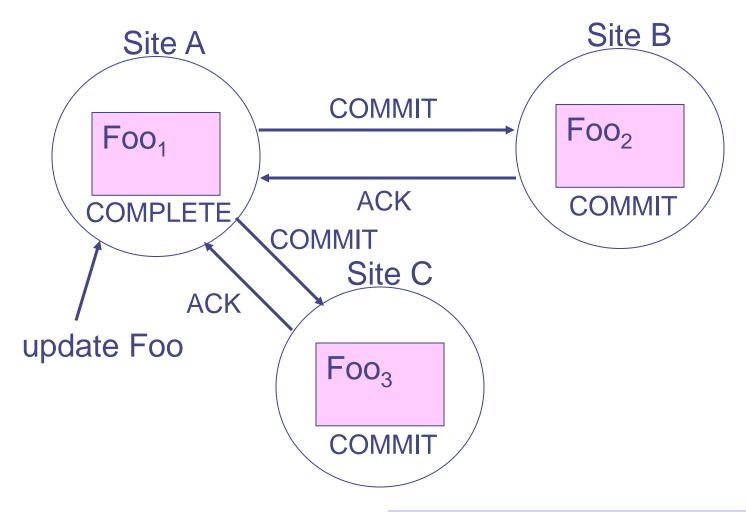












Two-Phase Commit Failure Recovery

- Coordinator fails before writing COMMIT record to log
 - On recovery, broadcast ABORT
- Coordinator fails between COMMIT and COMPLETE
 - On recovery, broadcast COMMIT
- Coordinator fails after writing COMPLETE
 - Transaction succeeded, do nothing
- Cohort crashes in Phase 1
 - Coordinator aborts transaction
- Cohort crashes in Phase 2
 - On recovery, check with coordinator whether to commit or abort

Three-Phase-Commit- Protocol (3PC)

- 2PC problem: some nodes may remain in state uncertain for long time, if the coordinator fails and no
 - → getDecision() requests are replied
- 3PC: non-blocking improvement of 2PC
- Prerequisites
 - Failure of K<N nodes at most, where K is a user-set parameter
- Idea
 - Blocking in 2PC results from a situation, where not all failed nodes are in state "uncertain" and can not decide "abort", because some nodes maybe already decided to commit
 - 3PC avoids this situation by introducing a new layer, so a node can not decide to commit as long as a non failed node is in state "uncertain"
- Price
 - Management overhead much higher than in case of 2PC:
 - 6N messages and 3(N1) logging processes necessary

3PC procedure

Phase 1: analogously to 2PC

- The coordinator collects all votes and makes a decision
- No: Abort and information to all participants that voted yes
- Yes: all nodes answer Yes \Rightarrow additional layer \Rightarrow Application 3PC

Phase 2:

 Coordinator changes mode to preCommit and guarantees that the transaction will not be terminated

(If the coordinator fails, a transaction roll back is still possible!)

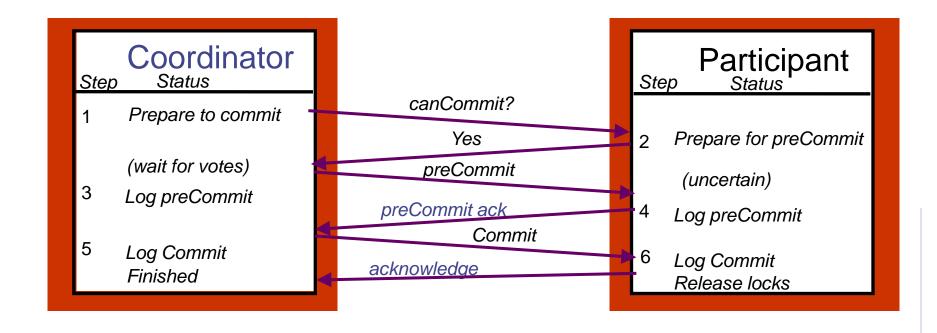
- Coordinator logs the new state and sends preCommit to all participants
- Participants log the new state and acknowledge the preCommit request

Phase 3:

 Coordinator collects all answers: if all messages arrived, a commit is executed and doCommit is sent to all participants ⇒ Participants write the data in the database and confirm transaction

3PC procedure (2)

- Coordinator failure recognized by applying time-out
 - All active participants elect a new coordinator
 - commit protocol starts, so the new coordinator can proceed the commit handling



3PC commit protocol

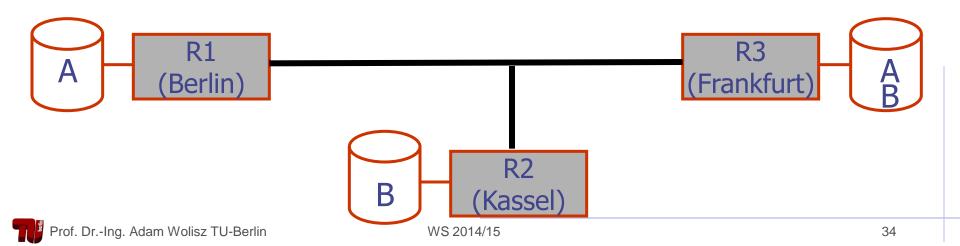
- New coordinator collects status information from all participants and proceeds according to the following rules
 - R1: If one node is in state finished or aborted, decide abort
 - R2: If one node is in state commit, decide commit
 - R3: If all nodes are in state uncertain, decide abort
 - R4: If some nodes in state preCommit, but no node in state commit, send preCommit to all nodes
- Wait for all acknowledgments and decide commit
- Ignore all participants that do not transmit their status

3PC example

- All participants vote Yes
- Coordinator sends preCommit messages. Node failure occurs during the process, so only a part of the nodes receives the messages
- Now, some nodes are in state preCommit, all other nodes are in state uncertain
- Assume, nodes in state preCommit crash too
 - Remaining nodes start the commit protocol
 - The (elected) new coordinator collect the state information of all nodes that are still operational (all uncertain) and decide according rule R3 abort
 - Failed nodes start after reboot the commit protocol and receive the decision abort
 - Although they already received preCommit, nodes decide abort

Replication

- Replication goals
 - Increased availability
 - Copy data to k nodes ⇒ Data available even if k-1 nodes crash
 - Performance increase
 - Parallel execution of read access for the same data
 - Reduction of necessary communication by supporting data locality
- Example: Replicated account information



Demands and approaches

- Management of replicated data increases the storage demands and the communication load during write access
- Increased implementation effort to hide the existence of replicated data for the user
 - Automatic, transparent update of all replicated data after modification of an object
 - Ensuring data consistency considering all replicated data sets
- Three well-known approaches for update and synchronization of replicated databases
 - Write-All: Synchronous updates of all replicated nodes
 - Primary-Copy: Immediate update of a master copy, modifications submitted with certain delay
 - Voting: Each replicated set receives one or more votes. For each read or write access, a certain quorum for read or write access must be collected before the operation is performed

Write-All approach

- Write-All-Read-Any or Read-Once-Write-All (ROWA) strategy
 - Synchronous modification of all replicated date before the transaction is committed
 - Each replicated data is updated at any time and can be used for read access (in parallel to the other sets)
 - Selection of data set for reading based on criteria such as minimal network load or least node utilization
 - Singular node failures easy to compensate
- Advantages of ROWA strategy
 - All read accesses of the primary data set (R2) can be performed on replicated data without any delay
 - Data access for all data despite failures of individual nodes

ROWA disadvantages

Locking protocols have to be changed

- All replicated data sets on all involved nodes have to be locked before a write access can occur
- All nodes must participate on the commit protocol

Crucial disadvantage

- Availability decreased compared to non-replicated databases
- If a single node crashes, then the entire database fails, because all nodes with replicated data sets have to be considered
- Relaxed demand: Write-All-Available-Read-Any
 - The modified data sets are updated on the available nodes only
 - In case of crashed nodes, the updates are logged and recovered after reboot
 - Problems in case of network separations: node crashed or messages lost?

Primary-Copy

Goal

- Efficient processing of updates
- One selected data set is determined as primary (master) copy and it is updated immediately
- Other replicated data sets are updated asynchronously from the primary node as soon as possible

Efficiency

- Update messages are transferred as bundle to the target node
- Primary copies stored on different nodes to avoid bottle necks and hot spots
- Disadvantage: Deferred modification of replicated sets
- Implementation
 - Write locks requested for all copies (same as ROWA), but only the primary copy is updated immediately
 - Primary copy node updates as soon as possible all other objects and releases the locks after finishing all operations

Alternatives

- Write locks requested only for the primary copy ⇒ reduced number of locking conflicts
- Handling for read requests on old, possibly inconsistent data necessary
 - Read on primary copy: All read transactions refer the primary copy
 fault tolerance, but no locality and parallelism
 - Read access to local copies, lock requests for primary copy node: Solely locks increase the load of the primary copy, the reading occurs on other nodes
 - Check during locking, if the object has to be updated and if so then update with highest priority
 - Reduced load for primary copy node
 - Local reads: inconsistent data possible, but in special cases might be tolerable
- Failure of primary copy node
 - No transactions possible
 - Election of new primary copy node with suitable algorithms

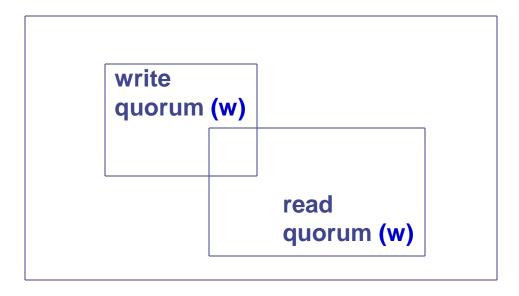
Voting

- Before a read or write access to an object, a sufficient number of votes has to be collected
- Majority votes
 - Write: Transaction hast to lock the majority of the needed objects (lock = vote)
 - Read: Majority of replicated data sets is locked for reading and one specific object is referenced
 - Guaranteed, that the referenced object will not be modified by another transaction concurrently
 - At least one replicated data set is updated
 - Assigned counter reflects the update status (version) of each replicated data set
- Advantage: Objects usable in case of crash of several nodes
- Disadvantage: Each access requires several messages to guarantee the vote majority

Weighted Voting (Quorum Consensus)

- We assign a certain weight to each replicated data set (number of votes)
- For read and write access a certain, pre-defined number of votes (read quorum or write quorum) is necessary and need to be collected
- If v votes are available, the following rules apply for read quorum r and write quorum w
 - w>v/2: guarantees that no object will be modified simultaneously in two transactions
 - r+w>v prevents, that an object will be read and modified simultaneously.
 Furthermore, it is guaranteed that at least one object from the last write quorum is involved
- We use the weights to determine the costs for write / read access as well as the availability
 - The smaller r and w, the faster read and write access
 - Increased availability, because some node may crash
 - Preferred reading with increased write complexity and vice versa

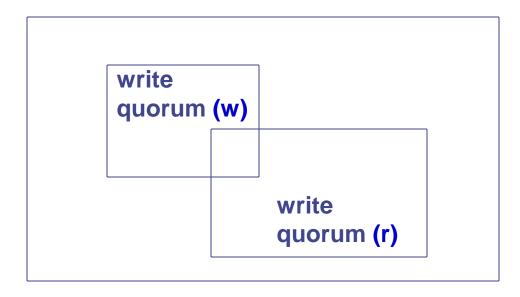
Quorum Consensus Replica Control



Set of all replicas of an item (v)

- Read/write conflict: r + w > v
- An intersection between any read and any write quorum

Quorum Consensus Replica Control



Set of all replicas of an item (v)

- Read/write conflict: w > n/2
- An intersection between any two write quorums

Example Quorum

- Object A replicated on four nodes R1 to R4
- Vote distribution <2,1,1,1>, i.e. R1 with 2 votes
- In case of r = 3 and w = 3, then at least two nodes must be involved in the transaction
 - Preferring R1 means that a faster access to data from R1 is provided
 - Access also after node failure provided. In case that R1 is still alive, then also two nodes can fail without affecting the overall system
- Read access preferred versus write access, in case of following parameters: r=2 and w=4
 - Read access locally on R1
 - For write access at least 3 nodes are necessary
 - Overall failure (no modification possible), if R1 fails

Pros and Cons

- Voting approach can emulate suitable parameter selection assumed – all other approaches
 - Majority approach: each replicated data set gets the same weight (1 vote)
 - ROWA: same as majority, each data set with one vote. In addition r=1 and w=v=number of replicated data sets
 - Primary copy: primary copy gets one vote, all other replicated data sets have no votes and r=w=1
 - ⇒Read access has to be requested from the primary copy
- Disadvantage
 - Complex definition of suitable parameters

Snapshot replication

- Replication over WANs leads to high overhead
- Slower networks increase the demands on replication mechanisms
- Lower requirements regarding update speed open space for additional techniques such as snapshots
- Definition
 - Certain database view is provided
 - Query result is exported as an DB image and provided as an object with a specific name
 - Snapshot access with the used query language, only read access allowed

Example

CREATE SNAPSHOT underflow AS

SELECT CustomerNR, AccountNR, AccountBal

FROM Account WHERE AccountBal <0

REFRESH EVERY DAY

Snapshot properties

In example

- Snapshot corresponds to a copy of all accounts with negative balance
- Snapshot refreshed in given intervals, here every day

Advantages

- Coupling to DB query languages allows the summary of any information, also aggregated information, dependencies, ...
- Lower load to the primary copy node, as all accesses are performed locally and without communication
- Consistency problems avoided, as only read operations allowed

Disadvantages

 Lower quality than in case of "real" replication ⇒ Data older than the real data, but in guaranteed interval

Examples

- Lists of spare parts in shops
- Book catalogues
- Phone and e-mail directories