

## △ Antithetic variables

Goal : reduce the variance (compared with simple MC)

SMC : ① generate  $u$  from  $\text{Unif}(0,1)$

② Inverse transform

Steps : ① Generate  $\frac{m}{2}$  replicates (Suppose we need  $m$  replicates)

$$\left\{ \begin{array}{l} Y_j = g(F_x^{-1}(u_1^{(j)}), \dots, F_x^{-1}(u_n^{(j)})) \\ Y_j' = g(F_x^{-1}(1-u_1^{(j)}), \dots, F_x^{-1}(u_n^{(j)})) \end{array} \right.$$

② Calculate  $\hat{\theta} = \frac{1}{m} \sum_{j=1}^{\frac{m}{2}} (Y_j + Y_j')$  sample average

$$\begin{aligned} \text{eg: } \Phi(x) &= \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt \\ &= E\left\{ x e^{-\frac{x^2 u^2}{2}} \right\} \text{ where } u \sim \text{Unif}(0,1) \end{aligned}$$

## △ Control variates

$$\theta = E\{g(x)\}$$

If there is a function  $f$  with  $\mu = E\{f(x)\}$  known

and  $f(x)$  is correlated with  $g(x)$  then define

$\hat{\theta}_c = g(x) + c(f(x) - \mu)$  is called an estimator

with control variates

Remarks : ①  $\mu$  known

② correlated

③  $\hat{\theta}_c$  is unbiased

How to choose  $c$  to reduce the variance :

$$\text{Var}(\hat{\theta}_c) = \text{Var}(g(x)) + 2c \cdot \text{Cov}(g(x), f(x)) + c^2 \text{Var}(f(x))$$

is a quadratic function of  $c$

$$C^* = - \frac{\text{Cov}(g(x), f(x))}{\text{Var}(f(x))}$$

$$\text{Var}(\hat{\theta}_{C^*}) = \text{Var}(g(x)) - \frac{\{\text{Cov}(g(x), f(x))\}^2}{\text{Var}(f(x))}$$

Percentage of variance reduction

$$\begin{aligned} & \frac{\text{Var}(g(x)) - \text{Var}(\hat{\theta}_{C^*})}{\text{Var}(g(x))} \times 100\% \\ &= \frac{\{\text{Cov}(g(x), f(x))\}^2}{\text{Var}(g(x)) \cdot \text{Var}(f(x))} \times 100\% = \{\text{Corr}(f(x), g(x))\}^2 \times 100\% \end{aligned}$$

Remark: ①  $f(x)$  is called the control variate

②  $\hat{\theta}_C$  is good when  $f(x)$  and  $g(x)$  are strongly correlated

③ In practice, we need to estimate  $C$ ,

estimate  $\text{Cov}(f(x), g(x))$  and  $\text{Var}(f(x))$

$$\text{eg. 5.7. } \theta = E e^u = \int_0^1 e^x dx \quad g(u) = e^u$$

control variate  $f(u) = u \sim \text{Unif}(0,1)$

$$C^* = - \frac{\text{Cov}(e^u, u)}{\text{Var}(u)} = -1.69$$

$$\hat{\theta}_{C^*} = e^u - 1.69(u - \frac{1}{2})$$

$$\text{eg. 5.8. } \theta = E g(x) = \int_0^1 \frac{e^{-x}}{1+x^2} dx$$

$g(x) = \frac{e^{-x}}{1+x^2}$      $f(x)$  { close to  $g(x)$  in shape  
easy to obtain  $E\{f(x)\}$ }

$$\text{choose } f(x) = \frac{e^{-\frac{x}{2}}}{1+x^2} \quad \frac{g}{f} = \frac{e^{-x}}{e^{-\frac{x}{2}}} \quad (\because X \sim \text{Unif}(0,1))$$

$$\mu = \int_0^1 \frac{e^{-\frac{x}{2}}}{1+x^2} dx = \frac{\pi}{4} e^{-\frac{1}{2}} \quad \therefore \frac{g}{f} \text{ is not const.}$$

△ Antithetic variable as control variates

Control variate : linear combination of two unbiased estimators

Suppose two unbiased estimators  $\hat{\theta}_1$  and  $\hat{\theta}_2$

$\hat{\theta}_c = c \cdot \hat{\theta}_1 + (1-c) \hat{\theta}_2 \quad (0 \leq c \leq 1)$  is unbiased for  $\theta$

$$\text{eg. } \hat{\theta}_c = g(x) + c(f(x) - \mu)$$

$$= (1-c)g(x) + c(g(x) + f(x) - \mu)$$

$$\underbrace{\phantom{0}}_{\sim} \quad \underbrace{\phantom{0}}_{\sim} \quad \text{both unbiased}$$

$$\theta = E[g(x)] = E(g(x) + f(x) - \mu)$$

$$\text{Var}(\hat{\theta}_c) = c^2 \text{Var}(\hat{\theta}_1) + 2c(1-c)\text{Cov}(\hat{\theta}_1, \hat{\theta}_2) + (1-c)^2 \text{Var}(\hat{\theta}_2)$$

Assume  $\hat{\theta}_1$  and  $\hat{\theta}_2$  are identically dist. with  $\text{corr}(\hat{\theta}_1, \hat{\theta}_2) \triangleq r$

$$\text{then } \text{Var}(\hat{\theta}_c) = [(2-2r)c^2 - (2-2r)c + 1] \text{Var}(\hat{\theta}_1)$$

$$c^* = \frac{1}{2} \Rightarrow \hat{\theta}_c = \frac{1}{2}(\hat{\theta}_1 + \hat{\theta}_2)$$

△ Extension to multiple control variates

$$\text{If } E\hat{\theta}_i = \theta \quad i=1, \dots, k$$

$$\text{constants } C = (c_1, \dots, c_k) \quad \sum c_i = 1, \quad c_i \geq 0$$

then  $\sum_{i=1}^k c_i \hat{\theta}_i$  is unbiased

$$\text{Correspondingly. } \hat{\theta}_c = g(x) + \sum_{i=1}^k c_i^* (f_i(x) - \mu_i), \text{ where } \mu_i = E[f_i(x)]$$

△ Duality between control variate to LR (linear regression)

Simple LR: Observe  $(x_1, Y_1), \dots, (x_n, Y_n)$

$$Y = \beta_0 + \beta_1 X + \varepsilon$$

Assumptions: Linear

$$E(\varepsilon | X) = 0$$

$$\text{Cov}(\vec{\varepsilon} | X) = \sigma^2 I \text{ with } \sigma \text{ unknown const.}$$

$$LS: \min_{\beta_0, \beta_1} \sum_{i=1}^n (\bar{Y}_i - \beta_0 - \beta_1 X_i)^2$$

$$\begin{cases} \hat{\beta}_0 = \bar{Y} - \hat{\beta}_1 \bar{X} \\ \hat{\beta}_1 = \frac{\sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})}{\sum_{i=1}^n (X_i - \bar{X})^2} = \frac{\text{Cov}(X, Y)}{\text{Var}(X)} \end{cases}$$

Observe .  $(f(x_1), g(x_1))$ , ...,  $(f(x_n), g(x_n))$

$$g(x) = \beta_0 + \beta_1 f(x) + \varepsilon$$

$$\begin{cases} \hat{\beta}_0 = \bar{g(x)} - \hat{\beta}_1 \bar{f(x)} \\ \hat{\beta}_1 = \frac{\text{Cov}(f(x), g(x))}{\text{Var}(f(x))} = -\hat{c}^* \end{cases}$$

Remark : ① Predicted value at  $\mu = \bar{E}\{f(x)\}$

$$\begin{aligned} \hat{\beta}_0 + \hat{\beta}_1 \cdot \mu &= \bar{g(x)} - \hat{\beta}_1 \bar{f(x)} + \hat{\beta}_1 \mu \\ &= \bar{g(x)} - \hat{c}^* (\bar{f(x)} - \mu) = \hat{\theta} \hat{c}^* \end{aligned}$$

② Variance of control variate estimator

$$\begin{aligned} &\text{Var}(\bar{g(x)}) + \hat{c}^* (\bar{f(x)} - \mu) \\ &= \frac{1}{n} \text{Var}(g(x)) + \hat{c}^* (f(x) - \mu) \\ &= \frac{1}{n} \text{Var}(g(x) - \hat{\beta}_1 f(x) - \hat{\beta}_0) = \frac{1}{n} \text{Var}(\text{residual}) = \frac{1}{n} \hat{\sigma}_\varepsilon^2 \end{aligned}$$

③ Proportion of the variance reduction

$$\text{Corr}(g(x), f(x))^2 = R^2$$

means the proportion of the variance of  $g(x)$  explained by  $f(x)$

Extension to multiple LR and multiple control variate

$$Y = \beta_0 + \sum_{j=1}^p \beta_j X_j + \varepsilon$$

$$\text{eg. } g(x) = \frac{e^{-x}}{1+x^2}, f(x) = \frac{e^{-\frac{x}{2}}}{1+x^2} \quad \text{see in the code}$$

## △ Importance Sampling

$$\mathbb{D} = \int_a^b g(x) dx = E[g(x)]$$

$\frac{1}{b-a} \int_a^b g(x) dx$ : Average value of  $g(x)$  over  $[a,b]$

$$E[g(x)]. X \sim \text{Unif}(a,b)$$

SMC: ① Generate from  $\text{Unif}(a,b)$

$$\text{② Calculate } \frac{b-a}{m} \sum_{i=1}^m g(x_i)$$

Drawback: what if  $g(x)$  not be uniform over  $[a,b]$

Solution: choose a non-uniform weighted function

Def: Let  $X \sim f$ , such that  $f(x) > 0$  on the support of  $g$

$$\text{Set } Y = \frac{g(x)}{f(x)} \text{ then } \int g(x) dx = \int \frac{g(x)}{f(x)} f(x) dx = E_f(Y)$$

IS steps: ① Generate  $X_1, \dots, X_m$  from  $f$

$$\text{② Calculate } \frac{1}{m} \sum_{i=1}^m Y_i = \frac{1}{m} \sum_{i=1}^m \frac{g(X_i)}{f(X_i)} \xrightarrow{\text{SLN}} \int g(x) dx$$

We call  $f$  the importance function or envelope

$$\text{Var}\left(\frac{1}{m} \sum Y_i\right) = \frac{1}{m} \text{Var}(Y) \text{ where } Y = \frac{g(x)}{f(x)}$$

$\text{Var}(Y)$  small  $\Leftrightarrow$  ①  $\frac{g(x)}{f(x)}$  close to const.

②  $f$  should be easy to stimulate.