

Chapter 5 Monte Carlo Integration and Variance Reduction

△ MC Integration

eg. given function $g(x)$.
 integral $\int_a^b g(x) dx$
 $-\infty \leq a < b \leq +\infty$
 this is our target

eg. consider a r.v. $X \sim f$
 $E\{g(x)\} = \int_{-\infty}^{+\infty} g(x)f(x) dx$
 this is our tool

Define an operator $E_n\{g(x)\} = \frac{1}{n} \sum_{i=1}^n g(x_i)$

as the empirical average, other notations like $\bar{g}(x)$, $\bar{g}_n(x)$

In theory, $E_n\{g(x)\}$ is a "good" estimator of $E\{g(x)\}$

"good":

- ① unbiased $E(E_n\{g(x)\}) = E\{g(x)\}$
- ② consistent $E_n\{g(x)\} \xrightarrow{a.s.} E\{g(x)\}$ as $n \rightarrow +\infty$
(SLLN)
- ③ asymptotic normality (CLT)
 $\sqrt{n}(E_n\{g(x)\} - E\{g(x)\}) \xrightarrow{d} N(0, \sigma^2)$

eg. Let $\theta = \int_0^1 g(x) dx = \int_{-\infty}^{+\infty} g(x)f(x) dx$

where $f(x) = \mathbb{1}_{[0,1]}(x) = 1 (0 \leq x \leq 1)$

$\hat{\theta} = \frac{1}{m} \sum_{i=1}^m g(x_i)$ where $\{x_i\}$'s are generated from $Unif(0,1)$

eg. $\theta = \int_a^b g(x) dx$

① change variables $y = \frac{x-a}{b-a} \in (0,1)$

$$\theta = \int_0^1 g(y(b-a)+a)(b-a) dy$$

② Generate from $U_{\text{Unif}}(a, b)$

$$f(x) = \mathbb{1}_{[a,b]}(x) \cdot \frac{1}{b-a}$$

$$\theta = \int_{-\infty}^{+\infty} g(x) f(x) dx \cdot (b-a)$$

Steps of simple MC estimator

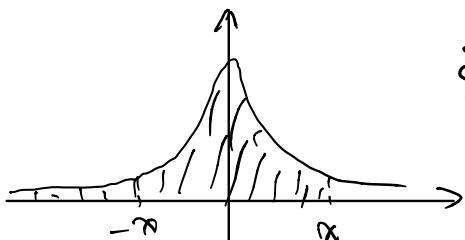
① Generate x_1, \dots, x_m from $U_{\text{Unif}}(a, b)$

② Compute $\bar{g}(x) = \frac{1}{m} \sum_{i=1}^m g(x_i)$

③ Calculate $\hat{\theta} = (b-a) \bar{g}_{m+1}(x)$

e.g. (MC integration over an unbounded interval)

$$\Phi(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-t^2/2} dt \quad (\text{c.d.f. of } N(0, 1))$$



$$\Phi(+\infty) = 1 \quad \& \quad \Phi(x) + \Phi(-x) = 1$$

$$\Phi(x) = \begin{cases} \frac{1}{2} + \frac{1}{\sqrt{2\pi}} \int_0^x e^{-t^2/2} dt & x \geq 0 \\ 1 - \Phi(-x) & x < 0 \end{cases}$$

$$\text{Let } \theta = \int_0^x e^{-t^2/2} dt, x \geq 0$$

Direct method : $U_{\text{Unif}}(0, x)$

when x changes, the generating procedures change

Indirect method : change of variables

$$t = xy, \text{ then } y = \frac{t}{x} \sim (0, 1)$$

$$\theta = \int_0^1 x \cdot \exp\left\{-\frac{(xy)^2}{2}\right\} dy, \text{ where } x \text{ fixed}$$

$$\theta = E_T \left(x \cdot \exp\left\{-\frac{(xT)^2}{2}\right\} \right), \text{ where } T \sim U_{\text{Unif}}(0, 1)$$

Steps: ① Generating u_1, \dots, u_m from $\text{Unif}(0, 1)$
 ② $\hat{\theta} = \overline{g_m(u)} = \frac{1}{m} \sum_{i=1}^m \alpha \cdot \exp\left\{-\frac{(x u_i)^2}{2}\right\}$

Hit-or-miss: Assume we can generate from $N(0, 1)$

$$\Phi(x) = P(Z \leq x) \quad Z \sim N(0, 1)$$

$$= E\{1_{(Z \leq x)}\}$$

$$\hat{\Phi}(x) = E_m\{1_{(Z \leq x)}\} = \frac{1}{m} \sum_{i=1}^m 1_{(Z_i \leq x)}$$

Steps: ① Generating $Z_1, \dots, Z_m \sim N(0, 1)$

② Evaluating each indicator $1_{(Z_i \leq x)}, i=1, \dots, m$

$$\hat{\Phi}(x) = \frac{1}{m} \sum_{i=1}^m 1_{(Z_i \leq x)}$$

△ Uncertainty quantification of $\hat{\theta}$

$$\hat{\theta} = \frac{1}{m} \sum_{i=1}^m g(x_i) \quad \rightarrow E \hat{\theta} = \theta$$

Assume unbiasedness first, then compare the variance

$$\begin{aligned} \text{Var } \hat{\theta} &= \frac{1}{m^2} \sum_{i=1}^m \text{Var}(g(x_i)) = \frac{1}{m} \text{Var}(g(x)) \\ &= \frac{1}{m} \sigma^2, \text{ where } \sigma^2 = \text{Var}(g(x)) \end{aligned}$$

In practice, σ^2 is unknown and is needed to be estimated

$$\text{"plug-in" estimator. } \sigma^2 = \text{Var}(g(x)) = E[g(x) - E\{g(x)\}]^2$$

$$\text{replace } E \text{ by } E_m : \hat{\sigma}^2 = E_m[g(x) - E_m\{g(x)\}]^2$$

$$E\{g(x)\} = \frac{1}{m} \sum_{i=1}^m g(x_i) = \overline{g_m(x)}$$

$$\hat{\sigma}^2 = \frac{1}{m} \sum_{i=1}^m \left\{ g(x_i) - \overline{g_m(x)} \right\}^2$$

$$\text{Then, } \widehat{\text{Var}}(\hat{\theta}) = \frac{1}{m} \hat{\sigma}^2 = \frac{1}{m^2} \sum_{i=1}^m \left\{ g(x_i) - \overline{g_m(x)} \right\}^2$$

standard error \rightarrow

$$\text{s.e.}(\hat{\theta}) = \sqrt{\widehat{\text{Var}}(\hat{\theta})} = \frac{1}{m} \left[\sum_{i=1}^m \left\{ g(x_i) - \overline{g_m(x)} \right\}^2 \right]^{\frac{1}{2}}$$

because in statistics, m is always very large
so we don't care about the biasedness.

$$\text{CLT: } \frac{\hat{\theta} - \theta}{\text{s.e.}(\hat{\theta})} \xrightarrow{d} N(0, 1) \quad m \rightarrow +\infty$$

△ Variance and Efficiency

Efficiency : two estimators $\hat{\theta}_1$ and $\hat{\theta}_2$ are unbiased,
if $\text{Var}(\hat{\theta}_1) < \text{Var}(\hat{\theta}_2)$, then we say $\hat{\theta}_1$ is
more efficient than $\hat{\theta}_2$.

$$\text{Quantity } \frac{\text{Var}(\hat{\theta}_2) - \text{Var}(\hat{\theta}_1)}{\text{Var}(\hat{\theta}_2)} \times 100\%$$

is the percentage of improvement of $\hat{\theta}_1$ over $\hat{\theta}_2$

$$① \quad \theta = \int_a^b g(x) dx = E_x g(x), \quad X \sim \text{Unif}(a, b)$$

$$\hat{\theta} = (b-a) \frac{1}{m} \sum_{i=1}^m g(x_i)$$

$$\text{Var}(\hat{\theta}) = \frac{(b-a)^2}{m} \text{Var}(g(x))$$

$$② \quad F(x) = \int_{-\infty}^x f(t) dt = E(1\{X \leq x\}), \quad X \sim f$$

$$\hat{F}(x) = \frac{1}{m} \sum_{i=1}^m 1\{X_i \leq x\}$$

$$\text{Var}(\hat{F}(x)) = \frac{1}{m} F(x)(1-F(x))$$

△ Variance Reduction

- { Antithetic variable
- Control Variate
- Importance Sampling
- Stratified Sampling

△ General Set-up

n -variate fun. $g(\mathbf{x}) = g(x_1, \dots, x_n)$

Given generated samples

$$\mathbf{X}^{(j)} = (x_1^{(j)}, \dots, x_n^{(j)})^T, j=1, \dots, m$$

$$\text{Goal: } \theta = E\{g(\mathbf{x})\}$$

$$\text{Tool: } \hat{\theta} = E_m\{g(\mathbf{x})\} = \frac{1}{m} \sum_{j=1}^m g(\mathbf{X}^{(j)})$$

△ Antithetic variable

e.g. Two r.v. u_1 and u_2

$$\text{Var}\left(\frac{u_1+u_2}{2}\right) = \frac{1}{4} (\text{Var}(u_1) + \text{Var}(u_2) + 2\text{Cov}(u_1, u_2))$$

If u_1 and u_2 ind.

$$\text{Var}\left(\frac{u_1+u_2}{2}\right) = \frac{1}{4} (\text{Var}(u_1) + \text{Var}(u_2))$$

To reduce the variance. $\text{Cov}(u_1, u_2)$ should be negative

Facts. ① u and $1-u$ are nega. corr.

② If $u \sim \text{Unif}(0,1)$ then $1-u \sim \text{Unif}(0,1)$

$$\text{Define } Y_j = g(\mathbf{X}^{(j)}) = g(x_1^{(j)}, \dots, x_n^{(j)})$$

$$= g(F_x^{-1}(u_1^{(j)}), \dots, F_x^{-1}(u_n^{(j)}))$$

$$Y'_j = g(F_x^{-1}(1-u_1^{(j)}), \dots, F_x^{-1}(1-u_n^{(j)}))$$

Question: Y_j and Y'_j have the same distribution,

When are Y_j and Y'_j negatively correlated?

Def: $(x_1, \dots, x_n) \leq (y_1, \dots, y_n) \Leftrightarrow x_j \leq y_j, \forall j$

$g(\mathbf{x})$ increasing $\Leftrightarrow g(x_1, \dots, x_n) \leq g(y_1, \dots, y_n)$ for $x \leq y$

Prop. 5.1. $X = (X_1, \dots, X_n)$ are iid. f, g increasing func.
then $E\{f(x)g(x)\} \geq \{Ef(x)\} \cdot \{Eg(x)\}$

Pf. Induction

$n=1$ suppose X and Y are iid.

$$\{f(x)-f(Y)\} \{g(x)-g(Y)\} \geq 0$$

$$\Rightarrow E[\{f(x)-f(Y)\} \{g(x)-g(Y)\}] \geq 0$$

$$\Rightarrow E\{f(x)g(x)\} + E\{f(Y)g(Y)\} \geq$$

$$E\{f(Y)g(x)\} + E\{f(x)g(Y)\}$$

$$\Rightarrow 2E\{f(x)g(x)\} \geq E\{f(Y)\} E\{g(x)\} + E\{f(x)\} E\{g(Y)\}$$

$$\Rightarrow 2E\{f(x)g(x)\} \geq E\{f(X)\} E\{g(X)\} + E\{f(X)\} E\{g(X)\}$$

$$= 2E\{f(X)\} E\{g(X)\}$$

If $n-1$ case is true, we need to show n case is true

Conditioning on $X_n = x_n$

$$E\{f(x)g(x) \mid X_n = x_n\} = E\{f(x_1, \dots, x_{n-1}, x_n)g(x_1, \dots, x_{n-1}, x_n)\}$$

$$\geq E\{f(x_1, \dots, x_n)\} E\{g(x_1, \dots, x_n)\}$$

$$= E\{f(x) \mid X_n = x_n\} \cdot E\{g(x) \mid X_n = x_n\}$$

Taking expectation w.r.t. X_n

$$\text{we have } E\{f(x)g(x)\} \geq \{Ef(x)\}\{Eg(x)\}$$

Corollary 5.1. If $g(x)$ is a monotone fun.

$$\text{then } Y = g(F_X^{-1}(u_1), \dots, F_X^{-1}(u_n))$$

$$Y' = g(F_x^{-1}(1-u_1), \dots, F_x^{-1}(1-u_n))$$

are negh. corr.

Pf: Assume g increasing

then Y and $-Y'$ are both increasing in U

$$-E\{Y \cdot Y'\} \geq - (EY) \cdot (EY')$$

$$\text{Cov}(Y, Y') = E(Y \cdot Y') - (EY) \cdot (EY') \leq 0$$