

```
import abc

from numpy import array, identity, linalg, matrix, random
import numpy as np
import random as rn

class SampleCreator(object):
    """
    Abstract base class for a simulator of one path each for an ensemble of ra
    ndom variables (eg several Brownian motions W1, W2, etc)
    Attributes:
        size (int): the number of random variables
    """
    # indicate that this is an abstract base class (abc)
    __metaclass__ = abc.ABCMeta

    def __init__(self, size):
        self.size = size

    @abc.abstractmethod
    def create_sample(self, n_samples=1, time_step=1, *args):
        """
        Generate a single path for each random variable (number of random vari
        ables, eg number of Brownian motions, is self.size). One path consists of n_sa
        mples steps
        Args:
            n_samples (int): the number of steps along a single path
            time_step (float): the size of a mini time step
        Returns:
            ndarray: a 2D array (num rows: self.size, num cols: n_samples). Ea
            ch row is one single path for one random variable
        """

class SimpleGaussianSampleCreator(SampleCreator):
    """
    Creates IID samples distributed in Gaussian fashion. Does not use numpy
    because numpy seeding does not play well with multiprocessing
    """

    def create_sample(self, n_samples=1, time_step=1, *args):
        """
        Generate a single path for each random variable (number of random vari
        ables, eg number of Brownian motions, is self.size). One path consists of n_sa
        mples steps
        Args:
            n_samples (int): the number of steps along a single path
            time_step (float): the size of a mini time step. For Brownian moti
            on, time_step is variance of the normal dist
        Returns:
            ndarray: a 2D array (num rows: self.size, num cols: n_samples). Ea
            ch row is one single path for one random variable
        """
```

```

    # each sample has a mean = 0 and variance = time_step
    sigma = time_step ** 0.5
    return array([
        array([rn.gauss(0, sigma) for _ in xrange(n_samples)])
        for _ in xrange(self.size)
    ])

```

```
class IIDSampleCreator(SampleCreator):
```

```
    """
```

Simulator of one path each for an ensemble of independent random variables

Attributes:

size (int): the number of independent random variables (eg the number of independent Brownian motions W1, W2, etc)

distro (method of numpy.random): the distribution from which to take one step and form one random path

```
    """
```

```

    def __init__(self, size, distro=random.normal):
        self.distro = distro
        super(IIDSampleCreator, self).__init__(size)

```

```

    def create_sample(self, n_samples=1, time_step=1, *args):

```

```
        """
```

Generate a single path for each random variable (number of random variables, eg number of Brownian motions, is self.size). One path consists of n_samples steps

Args:

n_samples (int): the number of steps along a single path

time_step (float): the size of a mini time step. For Brownian motion, time_step is variance of the normal dist

Returns:

ndarray: a 2D array (num rows: self.size, num cols: n_samples). Each row is one single path for one random variable

```
        """
```

```

        # each sample has a mean = 0 and variance = time_step
        return array([
            self.distro(scale=time_step*0.5, size=n_samples)
            for _ in xrange(self.size)
        ])

```

```
class CorrelatedSampleCreator(IIDSampleCreator):
```

```
    """
```

Simulator of one path each for an ensemble of correlated random variables (eg correlated Brownian motions). When the variables together take one time step, their steps are correlated by a given correlation matrix

Attributes:

size (int): the number of correlated random variables (eg the number of correlated Brownian motions W1, W2, etc)

distro (method of numpy.random): the distribution from which to take one step and form one random path

_corr_matrix (ndarray): correlation matrix of the steps being taken along correlated paths by the random variables

_ts_transforms (dict): a dict mapping one time_step to a transformation

n matrix C where $C * C.T$ = the covariance matrix corresponding to the size of that time_step
 '''

```
def __init__(self, corr_matrix, scales=None, distro=random.normal):
    self._set_corr_matrix(corr_matrix)
    size = len(corr_matrix) # len(ndarray) returns num of rows
    self._ts_transforms = {}

    super(CorrelatedSampleCreator, self).__init__(size=size,
                                                  distro=distro)

def _set_corr_matrix(self, cm):
    '''
    Set the corr matrix of self to cm after checking conditions
    Args:
        cm (ndarray): a symmetrix positive definite correlation matrix
    Returns:
        Set self._corr_matrix to cm
    '''
    r, c = cm.shape

    if r != c:
        raise ValueError('Correlation matrix %s is not square' % cm)

    for i in xrange(r):
        for j in xrange(i+1):
            if cm.item(i, j) != cm.item(j, i):
                raise ValueError('Correlation matrix %s is not symmetric'
                                % cm)

    if not np.all(linalg.eigvalsh(cm) > 0):
        raise ValueError('Correlation matrix %s is not positive definite'
                        % cm)

    self._corr_matrix = cm

def create_sample(self, n_samples=1, time_step=1, *args):
    '''
    Generate a single path for each random variable (number of random vari
    ables, eg number of Brownian motions, is self.size). One path consists of n_sa
    mples steps
    Args:
        n_samples (int): the number of steps along a single path
        time_step (float): the size of a mini time step. For Brownian moti
    on, time_step is variance of the normal dist
    Returns:
        ndarray: a 2D array (num rows: self.size, num cols: n_samples). Ea
    ch row is one single path for one random variable. The steps are correlated by
    self._corr_matrix
    '''
    # try to see if a transform matrix C is already made for this time_ste
    p
```

```

transform = self._ts_transforms.get(time_step)
# if there is no matrix C yet then create one for this time_step
if transform is None:
    transform = self._create_transform(time_step)
    self._ts_transforms[time_step] = transform

# first create a set of independent paths for the group of variables
# these iid samples must be standard normal before transforming
# here iid is n_samples columns of Z, where Z is a column of std normal
1 iid = super(CorrelatedSampleCreator, self).create_sample(n_samples, time_step=1)
# matrix transform is C, and  $Y = C*Z$  so  $\text{covar}(Y) = C*C.T$ 
# matrix.A returns self as ndarray
return (transform * matrix(iid)).A

def _create_transform(self, time_step):
    """
    From a time_step dt, calculate covar matrix and the transform matrix C
    where  $C * C.T = \text{the target covar matrix}$ 
    Args:
        time_step: variance of each step of the Brownian motion
    Returns:
        matrix: the transformation matrix C
    """
    # first create a diag matrix where the diag is sqrt(dt)
    ts = time_step ** 0.5
    I = matrix(ts*identity(self.size))

    # make the covar matrix based on dt and corr matrix
    covar = I * self._corr_matrix * I

    # if Z is a column of std normal independent variables, then  $Y = C*Z$ 
    # then  $\text{covar}(Y) = C * C.T$ 
    # here we return the transform matrix C
    return matrix(linalg.cholesky(covar))

```

```

import abc
import itertools
import math

class Stock(object):
    """
    Abstract base class for a stock object
    Attributes:
        spot (float): the current spot price
        post_walk_price (float): the price at T after walking one full path
    """

    __metaclass__ = abc.ABCMeta

    def __init__(self, spot):
        self.spot = spot
        self.post_walk_price = spot

    @abc.abstractmethod
    def find_volatilities(self, time_step, vol_steps):
        """
        Return the volatility values over multiple time steps
        This is a generator function that returns a generator of vol
        Args:
            time_step (float): size of a mini time step (dt)
            vol_steps (list): a 1D iterable of the Brownian increments driving
stochastic variance in the Heston model
        Returns:
            generator: a generator to generate vol on the fly, over time steps
        """

    def walk_price(self, risk_free, time_step, price_steps, vol_steps=None):
        """
        Simulate the stock to walk one full path over multiple steps using geo
metric Brownian motion
        Args:
            risk_free (float): the rate in the deterministic term of dS
            time_step (float): size of a mini time step (dt)
            price_steps (list): a 1D iterable of the Brownian increments drivi
ng the diffusion term in dS
            vol_steps (list): a 1D iterable of the Brownian increments driving
stochastic variance in the Heston model. If not provided, default behavior is
to use the price_steps.

        Returns:
            float: the price S(T) after walking one full simulated path.
        """
        vol_steps = price_steps if vol_steps is None else vol_steps
        vols = self.find_volatilities(time_step, vol_steps)

        lprice = math.log(self.post_walk_price)

        # for dW, sigma in itertools.izip(price_steps, vols):

```

```

#     t1 = (risk_free - (0.5 * sigma**2)) * time_step
#     t2 = sigma * dW
#     lprice += (t1 + t2)
# self.post_walk_price = math.exp(lprice)

price = self.post_walk_price
for dW, sigma in itertools.izip(price_steps, vols):
    price += time_step*risk_free*price + sigma*price*dW

self.post_walk_price = price
return self.post_walk_price

```

```
class ConstantVolatilityStock(Stock):
```

```
'''
```

```
A stock with constant volatility
```

```
Attributes:
```

```
    spot (float): the current spot price
```

```
    post_walk_price (float): the price at T after walking one full path
```

```
    vol (float): the constant vol in the diffusion term
```

```
'''
```

```
def __init__(self, spot, vol):
```

```
    super(ConstantVolatilityStock, self).__init__(spot)
```

```
    self.vol = vol
```

```
def find_volatilities(self, time_step, vol_steps):
```

```
'''
```

```
Return the volatility values over multiple time steps
```

```
This is a generator function that returns a Generator of vol
```

```
Args:
```

```
    time_step (float): size of a mini time step
```

```
    vol_steps (list): here the vol is constant so vol_steps contain the
```

```
marks of time steps that vol will undertake
```

```
Returns:
```

```
    generator: returns the stock's volatility n times, where n is the
length of vol_steps
```

```
'''
```

```
return itertools.repeat(self.vol, len(vol_steps))
```

```
class VariableVolatilityStock(Stock):
```

```
'''
```

```
A stock with stochastic volatility based on Heston model
```

```
Attributes:
```

```
    spot (float): the current spot price
```

```
    post_walk_price (float): the price at T after walking one full path
```

```
    _base_vol (float): the starting point of the vol at t = 0. The square
of _base_vol is the starting variance V(0)
```

```
    _kappa (float): the mean reversion speed in Heston SDE for dV(t)
```

```
    _theta (float): the mean reversion level in Heston SDE for dV(t)
```

```
    _gamma (float): the constant diffusion term in Heston SDE for dV(t)
```

```
'''
```

```
def __init__(self, spot, base_vol, kappa, theta, gamma):
    super(VariableVolatilityStock, self).__init__(spot)

    self.vol = base_vol
    self._base_vol = base_vol
    self._kappa = kappa
    self._theta = theta
    self._gamma = gamma

def find_volatilities(self, time_step, vol_steps):
    """
    Return the volatility values over multiple time steps
    This is a generator function that returns a Generator of vol
    Args:
        time_step (float): size of a mini time step
        vol_steps (list): a 1D iterable of the Brownian increments driving
    stochastic variance in the Heston model
    Returns:
        generator: a random walk of the volatility using the full truncati
    on method. Thus, if we are left in a situation where the next step would lead
    us to a negative variance, the step instead goes to zero.
    """
    volatility = max(0, self.vol)
    variance = self._base_vol**2

    for dZ in vol_steps:
        drift = self._kappa * (self._theta - variance) * time_step
        diffusion = self._gamma * volatility * dZ
        variance = variance + drift + diffusion
        volatility = max(0, variance) ** 0.5
        self.vol = volatility
        yield volatility
```

```
import copy
import numpy
```

```
import mlmc.random_numbers as random
```

```
def create_simple_path(stocks,
                       risk_free,
                       T,
                       n_steps,
                       rng_creator=None,
                       chunk_size=100000):
    """
```

Get the post walk price of each of the inputted stocks
 Each stock walks one path to final time T
 The post walk price is returned without changing the stock itself
 This path simulation is vanilla Monte Carlo for Euler Maruyama
 To address memory issues, the simulation is run in chunks.

Args:

stocks (iterable): list of stocks that will walk
risk_free (float): risk free rate driving stock drift
T (float): the final time at end of a walk
n_steps (long): number of steps along one path
rng_creator (callable): a no-arg function that will return an object implementing the SampleCreator interface. Default is a function that returns an IIDSampleCreator that outputs both dW and dZ.
chunk_size (long): a walk of n_steps is done in chunks to address memory issues; chunk_size is the size of one chunk

Returns:

list: the post walk price of each stock

"""

```
stocks = [copy.deepcopy(s) for s in stocks]
rng = rng_creator() if rng_creator else random.SimpleGaussianSampleCreator
(2*len(stocks))
```

```
dt = float(T) / n_steps
```

```
chunks = [chunk_size for _ in xrange(n_steps/chunk_size)]
chunks.append(n_steps % chunk_size)
```

```
for c in chunks:
    if not c:
        continue
```

```
samples = rng.create_sample(n_samples=c, time_step=dt)
interval = rng.size / len(stocks)
```

```
for i, s in enumerate(stocks):
    # samples[i*interval] are the dW
    # samples[i*interval + 1] are the dZ
    s.walk_price(risk_free,
```



```

        dt,
        *samples[i*interval:(i+1)*interval])

```

```

return [s.post_walk_price for s in stocks]

```

```

def create_layer_path(stocks,
                      risk_free,
                      T,
                      n_steps,
                      rng_creator=None,
                      chunk_size=100000,
                      K=2):

```

```

    """

```

Each stock walks one path in the finer level, and one path on the coarser level, to final time T

The post walk price is returned without changing the stock itself
 This path simulation is MultiLevel Monte Carlo for Euler Maruyama
 To address memory issues, the simulation is run in chunks.

Args:

stocks (iterable): list of stocks that will walk
 risk_free (float): risk free rate driving stock drift
 T (float): the final time at end of a walk
 n_steps (long): number of steps along one path
 rng_creator (callable): a no-arg function that will return an object implementing the SampleCreator interface. Default is a function that returns an IIDSampleCreator that outputs both dW and dZ.

chunk_size (long): a walk of n_steps is done in chunks to address memory issues; chunk_size is the size of one chunk

K (int): for level L in MLMC, the interval [0,T] is partitioned into K **L intermediate time steps

Returns:

list: the post walk price of each stock

```

    """

```

```

stocks = [
    (copy.deepcopy(s), copy.deepcopy(s))
    for s in stocks
]

```

```

rng = rng_creator() if rng_creator else random.SimpleGaussianSampleCreator(2*len(stocks))

```

dt is for the coarser level, dt_sub for finer level

```

dt = float(T) / n_steps
dt_sub = dt / K

```

```

chunks = [chunk_size for _ in xrange(n_steps/chunk_size)]
chunks.append(n_steps % chunk_size)

```

```

for c in chunks:

```

```
    if not c:
        continue

    # first, samples := dW and dZ are the finer level
    samples = rng.create_sample(n_samples=c*K,
                                time_step=dt_sub)
    interval = rng.size / len(stocks)

    # s1 walks the coarse level, s2 walks the fine level
    for i, (s1, s2) in enumerate(stocks):
        subs = samples[i*interval:(i+1)*interval] # finer level
        fulls = numpy.array([
            numpy.array([s[i:i+K].sum() for i in xrange(0, c*K, K)])
            for s in subs
        ]) # coarser level

        s1.walk_price(risk_free, dt, *fulls)
        s2.walk_price(risk_free, dt_sub, *subs)

    return [
        (s1.post_walk_price, s2.post_walk_price)
        for s1, s2 in stocks
    ]

def calculate(task):
    return task[0>(*task[1:])

def main():
    import multiprocessing
    from mlmc.stock import ConstantVolatilityStock
    pool = multiprocessing.Pool(4)
    stock = ConstantVolatilityStock(10, 0.1)

    x = pool.map(
        calculate,
        [
            [create_simple_path] + [[stock], 0.01, 1, 100]
            for _ in xrange(100)
        ]
    )

    import pprint
    pprint.pprint(sorted(xx[0] for xx in x))

if __name__ == '__main__':
    main()
```

```
from __future__ import division
```

```
import abc
import collections
import datetime
import functools
import itertools
import math
import numpy as np
import scipy.stats as ss
```

```
from mlmc import path, stock
```

```
class Option(object):
```

```
    __metaclass__ = abc.ABCMeta
```

```
    ''' A general representation of an option. '''
```

```
    def __init__(self, assets, risk_free, expiry, is_call):
```

```
        '''
        assets: list of underlying assets. Will probably be stocks in this fra
mework.
```

```
        risk_free: the risk-free interest rate
```

```
        expiry: days until expiration of the option
```

```
        is_call: boolean. Whether the option is a call option or a put option
        '''
```

```
        self.assets = assets
```

```
        self.risk_free = risk_free
```

```
        self.expiry = expiry
```

```
        self.is_call = is_call
```

```
    @abc.abstractmethod
```

```
    def determine_payoff(self, *args, **kwargs):
```

```
        ''' Figure out the valuation of the option '''
```

```
class EuropeanStockOption(Option):
```

```
    ''' A stock option with a European payout '''
```

```
    def __init__(self, assets, risk_free, expiry, is_call, strike):
```

```
        '''
        assets: list of underlying assets. Will probably be stocks in this fra
mework.
```

```
        risk_free: the risk-free interest rate
```

```
        expiry: days until expiration of the option
```

```
        is_call: boolean. Whether the option is a call option or a put option
```

```
        strike: the strike price of the option
        '''
```

```
        if isinstance(assets, collections.Iterable):
```

```
            assets = assets[:1]
```

```
            if not isinstance(assets[0], stock.Stock):
```

```

        raise TypeError("Requires an underlying stock")
    elif isinstance(assets, stock.Stock):
        assets = [assets]
    else:
        raise TypeError("Requires an underlying stock")

    super(EuropeanStockOption, self).__init__(assets, risk_free, expiry, is_call)
    self.strike = strike

    def determine_payoff(self, final_spot, *args, **kwargs):
        v1, v2 = (final_spot, self.strike) if self.is_call else (self.strike, final_spot)
        return max(v1 - v2, 0)

class EuropeanSwaption(Option):

    ''' An exchange option with a European payout. '''

    def __init__(self, assets, risk_free, expiry, is_call):
        '''
        assets: list of underlying assets. Will probably be stocks in this framework.
        risk_free: the risk-free interest rate
        expiry: days until expiration of the option
        is_call: boolean. Whether the option is a call option or a put option
        '''

        if len(assets) != 2:
            raise ValueError('Requires two underlying assets')

        super(EuropeanSwaption, self).__init__(assets, risk_free, expiry, is_call)

    def determine_payoff(self, s1_final_spot, s2_final_spot, *args, **kwargs):
        v1, v2 = (s1_final_spot, s2_final_spot) if self.is_call else (s2_final_spot, s1_final_spot)
        return max(v1 - v2, 0)

class OptionSolver(object):

    ''' Given an option, will solve for the 'correct' price of the option '''

    __metaclass__ = abc.ABCMeta

    @abc.abstractmethod
    def solve_option_price(self, option, return_stats=False):
        '''
        Actually solve the option price.
        option: an Option object. May need to be a specific type of option
        return_stats: boolean. Return not only the option price, but also asso

```

```
iate statistics
'''
```

```
class AnalyticEuropeanStockOptionSolver(OptionSolver):
```

```
    ''' A Black-Scholes stock option pricer. Only works for European stock options '''
```

```
    def solve_option_price(self, option):
        '''
```

```
        Actually solve the option price.
```

```
        option: an Option object. May need to be a specific type of option
        '''
```

```
        underlying = option.assets[0]
```

```
        spot = underlying.spot
```

```
        vol = underlying.vol
```

```
        risk_free = option.risk_free
```

```
        expiry = option.expiry
```

```
        strike = option.strike
```

```
        log_diff = math.log(spot / strike)
```

```
        vt = 0.5 * vol**2
```

```
        denom = vol * math.sqrt(expiry)
```

```
        d1 = (log_diff + (risk_free + vt)*expiry) / denom
```

```
        d2 = (log_diff + (risk_free - vt)*expiry) / denom
```

```
        discount = math.exp(-risk_free * expiry)
```

```
        if option.is_call:
```

```
            S, d1, K, d2 = spot, d1, -strike, d2
```

```
        else:
```

```
            S, d1, K, d2 = -spot, -d1, strike, -d2
```

```
        return S * ss.norm.cdf(d1) + K * ss.norm.cdf(d2) * discount
```

```
class StatTracker(object):
```

```
    ''' Keeps track of running means and variances '''
```

```
    def __init__(self, discount):
        '''
```

```
        discount: the discount value that we will use to weigh all stats.
        '''
```

```
        self.discount = discount
```

```
        self.count = 0
```

```
        self.total = 0
```

```
        self.sum_of_squares = 0
```

```
        self.initial_val = None
```

```
@property
```

```

def variance(self):
    '''
    The running variance of the samples so far added
    '''
    if self.count in (0, 1):
        return float('inf')

    square_of_sum = self.total**2 / self.count
    variance = (self.sum_of_squares - square_of_sum) / (self.count - 1)
    return (self.discount * variance)

@property
def stdev(self):
    '''
    The running standard deviation of the samples so far added
    '''
    if self.count in (0, 1):
        return float('inf')

    return self.variance ** 0.5

@property
def mean(self):
    '''
    The running arithmetic mean of the samples so far added
    '''
    if self.count == 0:
        return float('nan')

    return self.discount * (self.total + self.initial_val*self.count) / se
lf.count

def add_sample(self, s):
    '''
    Add a sample to our set of samples for use in the
    running statistics
    '''
    if self.initial_val is None:
        self.initial_val = s

    self.count += 1
    diff = s - self.initial_val
    self.total += diff
    self.sum_of_squares += diff**2

def get_interval_length(self, z_score):
    '''
    Determine the size of the confidence interval given a specific z-score
    z_score: float. The number of standard deviations away from the sample
mean
    we expect the population mean to fall into. 1.96 for 95% conf
idence.
    '''

```

```
    if self.count == 0:
        return float('inf')

    return self.stdev * self.count**(-0.5) * z_score
```

```
class NaiveMCOptionSolver(OptionSolver):
```

```
    '''
```

```
Solve an option price using a simple Monte Carlo strategy
of continued Euler-Maruyama paths until the resultant
mean has an associated confidence interval shorter
than the max_interval_length
    '''
```

```
def __init__(self,
              max_interval_length,
              confidence_level=0.95,
              rng_creator=None,
              n_steps=None):
```

```
    '''
```

```
max_interval_length: float. The longest the confidence interval may be
confidence_level: float. The % chance the population mean falls within
                    the calculated confidence interval
rng_creator: fn. No-arg function that returns a SampleCreator object
n_steps: int. Number of steps per Euler-Maruyama path. Defaults to
           option expiry normalized by the max_interval_length
    '''
```

```
self.max_interval_length = max_interval_length
self.confidence_level = confidence_level
self.rng_creator = rng_creator
self.n_steps = n_steps
```

```
@property
```

```
def confidence_level(self):
    ''' The confidence level of the solver '''
    return self._confidence_level
```

```
@confidence_level.setter
```

```
def confidence_level(self, value):
    self._confidence_level = value
    self._z_score = ss.norm.ppf(1 - 0.5*(1-self.confidence_level))
```

```
@property
```

```
def z_score(self):
    ''' The z score associated with the confidence level '''
    return self._z_score
```

```
def _simulate_paths(self, option, n_steps, discount):
    stat_tracker = StatTracker(discount)
    cnt = itertools.count()
```

```
    while next(cnt) < 10 or stat_tracker.get_interval_length(self.z_score)
```

```

> self.max_interval_length:
    result = path.create_simple_path(option.assets,
                                      option.risk_free,
                                      option.expiry,
                                      n_steps,
                                      self.rng_creator)
    payoff = option.determine_payoff(*result)
    stat_tracker.add_sample(payoff)
    return stat_tracker

def solve_option_price(self, option, return_stats=False):
    """
    Actually solve the option price.
    option: an Option object. May need to be a specific type of option
    return_stats: boolean. Return not only the option price, but also asso
ciate statistics
    """
    expiry = option.expiry
    risk_free = option.risk_free
    discount = math.exp(-risk_free * expiry)

    n_steps = self.n_steps or int(math.floor(expiry / self.max_interval_le
ngth))

    tracker = self._simulate_paths(option, n_steps, discount)

    if return_stats:
        return tracker.mean, tracker.stdev, tracker.count, n_steps
    else:
        return tracker.mean

class LayeredMCOptionSolver(OptionSolver):
    """
    Solve option price using a multi-level Monte Carlo (MLMC)
    strategy. There are multiple ways of doing this
    """

    @abc.abstractmethod
    def run_levels(self, option, discount):
        """
        Run the multiple levels of E-M paths

        option: Option. What we're looking to price
        discount: float. Discount factor of money in the future.
        """

    def run_bottom_level(self, option, steps):
        """
        Run the bottom level of E-M paths. Each of the E-M paths
        will have only one step

```



```

    option: Option. What we're looking to price
    steps: int. Totally irrelevant, used only because run_upper_levels
            requires it as part of the signature.
    """
    result = path.create_simple_path(option.assets,
                                     option.risk_free,
                                     option.expiry,
                                     1,
                                     self.rng_creator)
    return option.determine_payoff(*result),

def run_upper_level(self, option, steps):
    """
    Run a non-bottom level of E-M paths. This comes out to
    running two paths, one with K times as many steps as the other

    option: Option. What we're looking to price
    steps: int. the number of steps for the path with fewer steps.
    """
    result = path.create_layer_path(option.assets,
                                    option.risk_free,
                                    option.expiry,
                                    steps,
                                    self.rng_creator,
                                    K=self.level_scaling_factor)

    coarse, fine = zip(*result)
    payoff_coarse = option.determine_payoff(*coarse)
    payoff_fine = option.determine_payoff(*fine)

    return (payoff_fine - payoff_coarse),

def run_level(self, option, L, n, *trackers):
    """
    Run an individual level

    option: Option. What we're looking to price.
    L: int. The level we wish to run.
    n: int. The number of times we wish to run the level.
    *trackers: iterable of StatTrackers. Will be used to keep track of
              price, and possibly also time to run path.
    """
    if L == 0:
        fn = self.run_bottom_level
        steps = 1
    else:
        fn = self.run_upper_level
        steps = self.level_scaling_factor ** (L - 1)
    for _ in xrange(n):
        for s, t in zip(fn(option, steps), trackers):
            t.add_sample(s)

def solve_option_price(self, option, return_stats=False):
    """

```

Actually solve the option price.

option: an Option object. May need to be a specific type of option

return_stats: boolean. Return not only the option price, but also associate statistics

'''

expiry = option.expiry

risk_free = option.risk_free

discount = math.exp(-risk_free * expiry)

trackers = self.run_levels(option, discount)

if return_stats:

means = [t.mean for t in trackers]

variances = [t.variance for t in trackers]

counts = [t.count for t in trackers]

price = sum([t.mean for t in trackers])

return (price, means, variances, counts)

else:

return sum([t.mean for t in trackers])

class SimpleLayeredMCOptionSolver(LayeredMCOptionSolver):

'''

The MLMC strategy should use a simple system for determining whether or not to continue, based on the empirical size of the highest level in comparison to the second-highest level. The number of paths run should simply be initially assumed as the same for all levels

'''

def __init__(self,
max_interval_length,
level_scaling_factor=4,
base_steps=1000,
rng_creator=None,
min_L=3):

'''

max_interval_length: float. Size of the error of the price

level_scaling_factor: int. Ratio of steps in level l+1 to steps in level l

el 1

base_steps: int. Number of paths to initially run per level

rng_creator: no-arg function returning SampleCreator

min_L: int. Starting number of levels to run

'''

self.max_interval_length = max_interval_length

self.level_scaling_factor = max(level_scaling_factor, 2)

self.base_steps = base_steps

self.rng_creator = rng_creator

self.min_L = min_L

def _determine_additional_steps(self, option, trackers):

find_dt = lambda l: option.expiry / (self.level_scaling_factor ** l)

```

    tot = 2 * (self.max_interval_length ** -2) * sum(
        (t.variance/find_dt(L)) ** 0.5
        for L, t in enumerate(trackers)
    )
    ideal_ns = (
        tot * (t.variance * find_dt(L)) ** 0.5
        for L, t in enumerate(trackers)
    )
    return [
        int(math.ceil(max((ideal_n - t.count), 0)))
        for ideal_n, t in zip(ideal_ns, trackers)
    ]

def _is_error_too_high(self, trackers):
    t1, t2 = trackers[-2:]

    empirical = max(abs(t1.mean) / self.level_scaling_factor, abs(t2.mean)
    )
    estimated = ((self.level_scaling_factor - 1) * self.max_interval_length
    h / (2**0.5))
    return estimated < empirical

def run_levels(self, option, discount):
    trackers = [
        (self.base_steps, StatTracker(discount))
        for _ in xrange(self.min_L)
    ]

    while sum(n for n, _ in trackers) > 0:
        for L, (n, t) in enumerate(trackers):
            self.run_level(option, L, n, t)

        addl_steps = self._determine_additional_steps(
            option,
            [x[1] for x in trackers]
        )

        nt = []
        for L, (addl, (n, t)) in enumerate(zip(addl_steps, trackers)):
            self.run_level(option, L, addl, t)
            nt.append((0, t))

        trackers = nt

        if self._is_error_too_high([x[1] for x in trackers]):
            trackers.append((self.base_steps, StatTracker(discount)))

    return [t[1] for t in trackers]

class HeuristicLayeredMCOptionSolver(LayeredMCOptionSolver):
    """

```

The MLMC strategy should use a system for determining whether or not to continue based on the empirically-determined decay factors of the size of the layer means, layer variances and layer costs.

'''

```
def __init__(self,
              target_mse,
              rng_creator=None,
              initial_n_levels=3,
              level_scaling_factor=4,
              initial_n_paths=5000,
              alpha=None,
              beta=None,
              gamma=None):
    '''
    target_mse: float. Target mean standard error
    rng_creator: no-arg function returning SampleCreator
    initial_n_levels: int. Number of levels to run initially. Must be >2
    level_scaling_factor: int. Ratio of steps in level l+1 to steps in lev
el 1
    initial_n_paths: int. Number of paths to run initially on the base lev
el
    alpha: float. decay factor of the means of the level
    beta: float. decay factor of the variances of the level
    gamma: float. growth factor of the cost of the level
    '''
    self.target_mse = target_mse
    self.rng_creator = rng_creator
    self.initial_n_levels = max(initial_n_levels, 3)
    self.level_scaling_factor = max(level_scaling_factor, 2)
    self.initial_n_paths = initial_n_paths

    self._alpha = alpha
    self._beta = beta
    self._gamma = gamma

def cost_determined(fn):
    @functools.wraps(fn)
    def wrapper(self, *args, **kwargs):
        d1 = datetime.datetime.now()
        res = fn(self, *args, **kwargs)
        d2 = datetime.datetime.now()

        delta = d2 - d1
        delta = delta.seconds + delta.microseconds*1e-6
        return delta, res[0]

    return wrapper
```

```
run_bottom_level = cost_determined(LayeredMCOptionSolver.run_bottom_level)
run_upper_level = cost_determined(LayeredMCOptionSolver.run_upper_level)
```

```

def _determine_additional_n_values(self, trackers):
    overall = int(math.ceil(sum(
        (p.variance * c.mean)**0.5
        for _, p, c in trackers
    ) / (self.target_mse**2)))

    return [
        max(0, int(math.ceil(overall * (p.variance * c.mean)**0.5)) - p.co
unt)
        for _, p, c in trackers
    ]

def _find_coefficients(self, payoff_trackers, cost_trackers):
    A = np.array([[i, 1] for i, _ in enumerate(payoff_trackers, 1)])

    if self._alpha:
        alpha = self._alpha
    else:
        x = np.array([[np.log2(p.mean)] for p in payoff_trackers])
        alpha = max(0.5, -np.linalg.lstsq(A, x)[0][0])

    if self._beta:
        beta = self._beta
    else:
        x = np.array([[np.log2(p.variance)] for p in payoff_trackers])
        beta = max(0.5, -np.linalg.lstsq(A, x)[0][0])

    if self._gamma:
        gamma = self._gamma
    else:
        x = np.array([[np.log2(p.mean)] for p in cost_trackers])
        gamma = np.linalg.lstsq(A, x)[0][0]

    return alpha, beta, gamma

def run_levels(self, option, discount):
    n_levels = self.initial_n_levels
    trackers = [
        (self.initial_n_paths, StatTracker(discount), StatTracker(1))
        for _ in xrange(n_levels)
    ]

    while sum(n for n, _, _ in trackers):
        for i, (n, payoff_tracker, cost_tracker) in enumerate(trackers):
            self.run_level(option, i, n, cost_tracker, payoff_tracker)

        addl_n_values = self._determine_additional_n_values(trackers)
        alpha, beta, gamma = self._find_coefficients(*zip(*((p, c) for (_,
p, c) in trackers[1:])))

        trackers = [
            (addl_n, p, c)
            for addl_n, (_, p, c) in

```

```
        itertools.izip(addl_n_values, trackers)
    ]

    if all(n <= 0.01*p.count for n, p, _ in trackers):
        remaining_error = max(
            (t.mean * 2**(alpha*i)) / (2**alpha - 1)
            for i, (_, t, _) in enumerate(trackers[-2:], start=-2)
        )

        if remaining_error > (0.5**0.5) * self.target_mse:
            guess_v = trackers[-1][1].variance / (2^beta)
            guess_c = trackers[-1][2].mean * (2 ** gamma)
            term = (guess_v/guess_c) ** 0.5

            base = sum((t.variance/c.cost)**0.5 for _, t, c in trackers
s)

            base += term
            guess_n = 2 * term * base / (self.target_mse**2)
            trackers.append((guess_n, StatTracker(discount), StatTrack
er(1)))

    return [p for _, p, _ in trackers]
```