

1 Homework 3

1.1 Problem 1

$$G(s) = \frac{\frac{K}{s(s+2)}}{1 + \frac{K}{s(s+2)}} = \frac{K}{s^2 + 2s + K}, \quad K > 0. \text{ 二阶系统.}$$

$$\omega_n = \sqrt{K}, \quad \zeta = \frac{1}{\sqrt{K}}. \text{ 欠阻尼} \implies K > 1.$$

$$M_p = e^{-\frac{\pi\zeta}{\sqrt{1-\zeta^2}}} = e^{-\frac{\pi}{\sqrt{K-1}}} < 10\%.$$

$$\implies \sqrt{K-1} < \frac{\pi}{\ln 10} \implies K < 1 + \left(\frac{\pi}{\ln 10}\right)^2.$$

$$\therefore 1 < K < 1 + \left(\frac{\pi}{\ln 10}\right)^2.$$

1.2 Problem 2

$$t_r \approx \frac{1.8}{\omega_n} \leq 0.6 \implies \omega_n \geq 3.$$

$$M_p = e^{-\frac{\pi\zeta}{\sqrt{1-\zeta^2}}} \leq 17\% \implies \zeta \geq -\frac{\ln 0.17}{\sqrt{(\ln 0.17)^2 + \pi^2}} \approx 0.49.$$

$$t_s \approx \frac{4.4}{\sigma} \leq 8.8 \implies \sigma \geq 0.5.$$

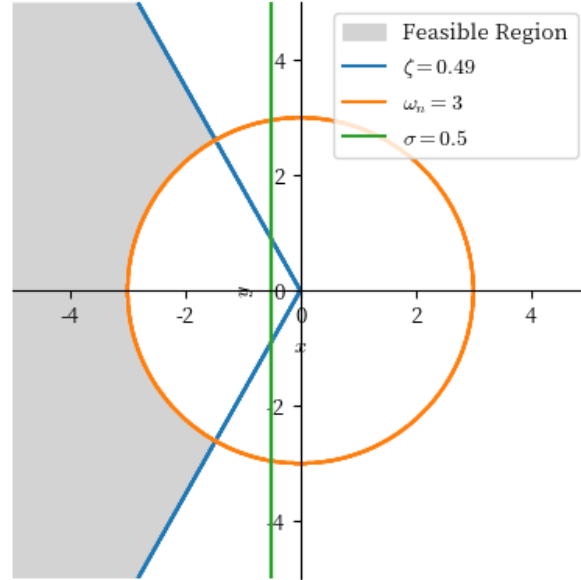


图 1: Range of poles

1.3 Problem 3

$$1. \quad J_m s \Omega_m(s) + \left(b + \frac{K_t K_e}{R_a}\right) \Omega_m(s) = \frac{K_t}{R_a} V_a(s).$$

$$\implies \frac{\Omega_m(s)}{V_a(s)} = \frac{K_t}{R_a J_m s + R_a b + K_t K_e} = \frac{0.2}{s + 0.104}.$$

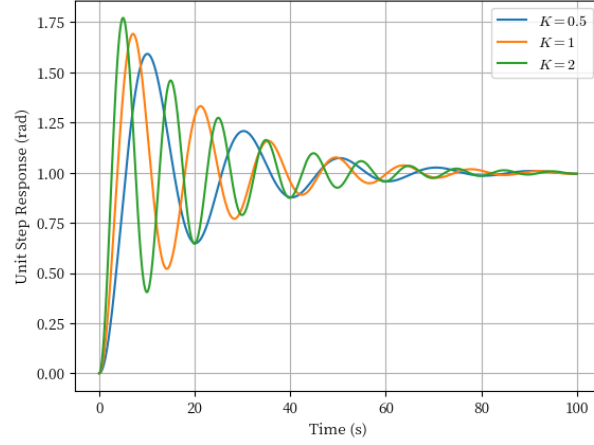
$$2. \quad V_a(s) = \frac{10}{s}, \quad \Omega_m(s) = \frac{2}{s(s+0.104)} = \frac{250}{13} \left(\frac{1}{s} - \frac{1}{s+0.104} \right).$$

$$\xrightarrow{\mathcal{L}^{-1}} \omega(t) = \frac{250}{13} (1 - e^{-0.104t}) 1(t) \text{ rad/s.}$$

$$\therefore \omega(+\infty) = \frac{250}{13} \text{ rad/s.}$$

$$3. \quad J_m s^2 \Theta_m(s) + \left(b + \frac{K_t K_e}{R_a}\right) s \Theta_m(s) = \frac{K_t}{R_a} V_a(s).$$

$$\implies \frac{\Theta_m(s)}{V_a(s)} = \frac{K_t}{R_a J_m s^2 + R_a b + K_t K_e s} = \frac{0.2}{s^2 + 0.104s}.$$

图 2: Range of K

$$4. \frac{\Theta_m(s)}{K(\Theta_r(s) - \Theta_m(s))} = \frac{0.2}{s^2 + 0.104s}.$$

$$\Rightarrow \frac{\Theta_m(s)}{\Theta_r(s)} = \frac{0.2K}{s^2 + 0.104s + 0.2K}.$$

$$5. \text{二阶系统, } \omega_n = \sqrt{0.2K}, \zeta = \frac{0.052}{\sqrt{0.2K}}.$$

$$M_p = e^{\frac{-\pi\zeta}{\sqrt{1-\zeta^2}}} < 20\% \Rightarrow \zeta > -\frac{\ln 0.2}{\sqrt{(\ln 0.2)^2 + \pi^2}} \approx 0.456.$$

$$\Rightarrow K < 0.065, \text{ i.e. } K \text{ 的最大值为 } 0.065.$$

$$6. t_r \approx \frac{2.16\zeta + 0.60}{\omega_n} < 4 \text{ s} \Rightarrow K > 0.334.$$

7. 单位阶跃响应:

	$K = 0.5$	$K = 1$	$K = 2$
RiseTime	3.688	2.503	1.72
SettlingTime	72.715	72.24	75.113
SettlingMin	0.649	0.521	0.404
SettlingMax	1.592	1.692	1.772
Overshoot	59.231	69.227	77.169
Undershoot	0.0	0.0	0.0
Peak	1.592	1.692	1.772
PeakTime	10.072	7.073	4.984
SteadyStateValue	1.0	1.0	1.0

$K > 0.334$, 超调量 $M_p > 20\%$, 上升时间 $t_r < 4 \text{ s}$. 与前两小问的计算结果一致.

1.4 Problem 4

劳斯阵列:

$$\begin{bmatrix} 1 & 10 & 5 & 0 & 0 & 0 \\ 5 & 10 & K & 0 & 0 & 0 \\ 8 & \frac{25-K}{5} & 0 & 0 & 0 & 0 \\ \frac{K+55}{8} & K & 0 & 0 & 0 & 0 \\ \frac{-K^2-350K+1375}{5(K+55)} & 0 & 0 & 0 & 0 & 0 \\ K & 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

系统稳定 $\iff K > 0 \wedge K + 55 > 0 \wedge -K^2 - 350K + 1375 > 0$.

$\iff 0 < K < 80\sqrt{5} - 175$.

K 不满足取值范围:

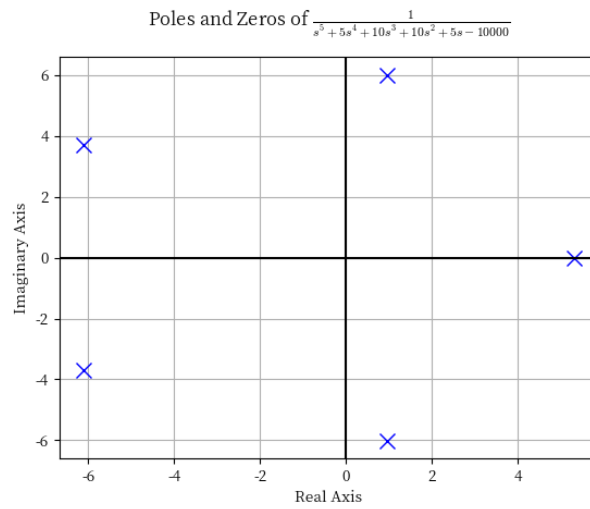


图 3: $K = -10000$

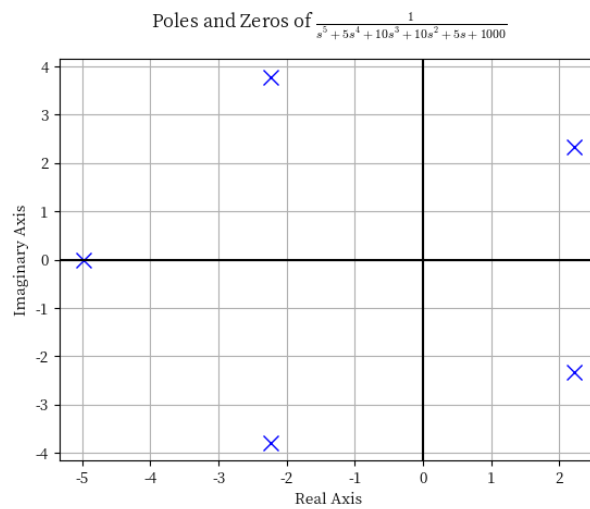
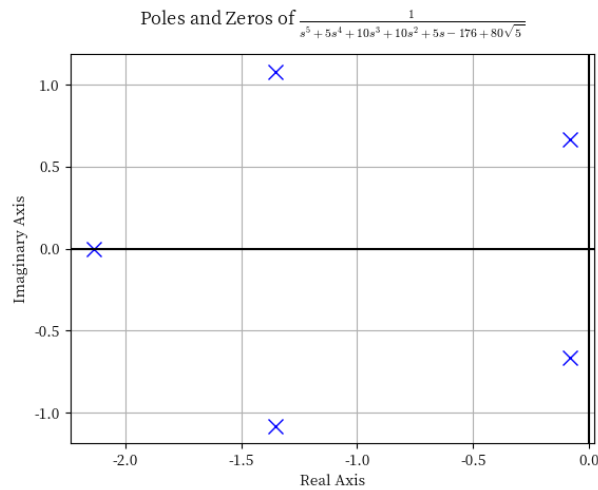
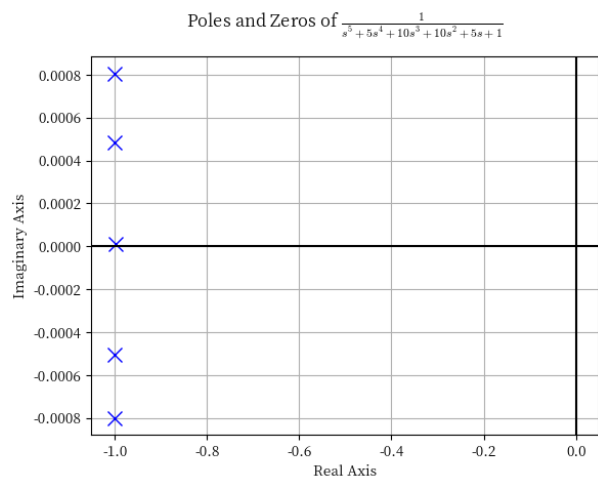


图 4: $K = 1000$

K 满足取值范围:

图 5: $K = 80\sqrt{5} - 176$ 图 6: $K = 1$

1.5 Problem 5

$$G(s) = \frac{KK_o(s+z)}{(s+p)(s^2-a^2)+KK_o(s+z)}.$$

劳斯阵列:

$$\begin{bmatrix} 1 & KK_o - a^2 & 0 & 0 \\ p & KK_o z - a^2 p & 0 & 0 \\ \frac{KK_o(p-z)}{p} & 0 & 0 & 0 \\ KK_o z - a^2 p & 0 & 0 & 0 \end{bmatrix}.$$

系统稳定 $\iff p > 0 \wedge KK_o(p-z) > 0 \wedge KK_o z - a^2 p > 0.$

1.6 Problem 6

$$G_o(s) = G_c(s)G_p(s) = \frac{10(s+2)}{s^2(s+5)}, \text{ 2 型系统.}$$

加速度误差常数 $K_a = \lim_{s \rightarrow 0} s^2 G_o(s) = 4.$

1.7 Problem 7

$$G_o(s) = \frac{K}{s(4s+1)}, 1 \text{ 型系统.}$$

$$\text{速度误差常数 } K_v = \lim_{s \rightarrow 0} sG_o(s) = K = 1.$$

1.8 Problem 8

$$G(s) = \frac{3K}{4(s+1)}.$$

$$E(s) = (1 - G(s))R(s) = \frac{4s+4-3K}{4s(s+1)}.$$

$$e_{ss} = \lim_{s \rightarrow 0} sE(s) = 1 - \frac{3K}{4} = 0.$$

$$\implies K = \frac{4}{3}.$$

1.9 Problem 9

$$1. G_o(s) = \frac{K_1 K_2 / Is}{s(1 + K_1 K_2 K_3 / Is)} = \frac{K_1 K_2}{s(25s + K_1 K_2 K_3)}, 1 \text{ 型系统.}$$

$$e_{ss} = \frac{1}{\lim_{s \rightarrow 0} sG_o(s)} = K_3 < 0.01.$$

$$2. G(s) = \frac{G_o(s)}{1 + G_o(s)} = \frac{\frac{K_1 K_2}{25}}{s^2 + \frac{K_1 K_2 K_3}{25}s + \frac{K_1 K_2}{25}}.$$

$$\text{二阶系统, } \omega_n = \frac{\sqrt{K_1 K_2}}{5}, \zeta = \frac{\sqrt{K_1 K_2 K_3}}{10}.$$

$$M_p = e^{-\frac{\pi\zeta}{\sqrt{1-\zeta^2}}} < 10\% \implies \zeta > -\frac{\ln 0.1}{\sqrt{(\ln 0.1)^2 + \pi^2}} \approx 0.591.$$

$$K_1 K_2 = \frac{100\zeta^2}{K_3^2} > \frac{100 \times 0.591^2}{0.01^2} \approx 349464.$$