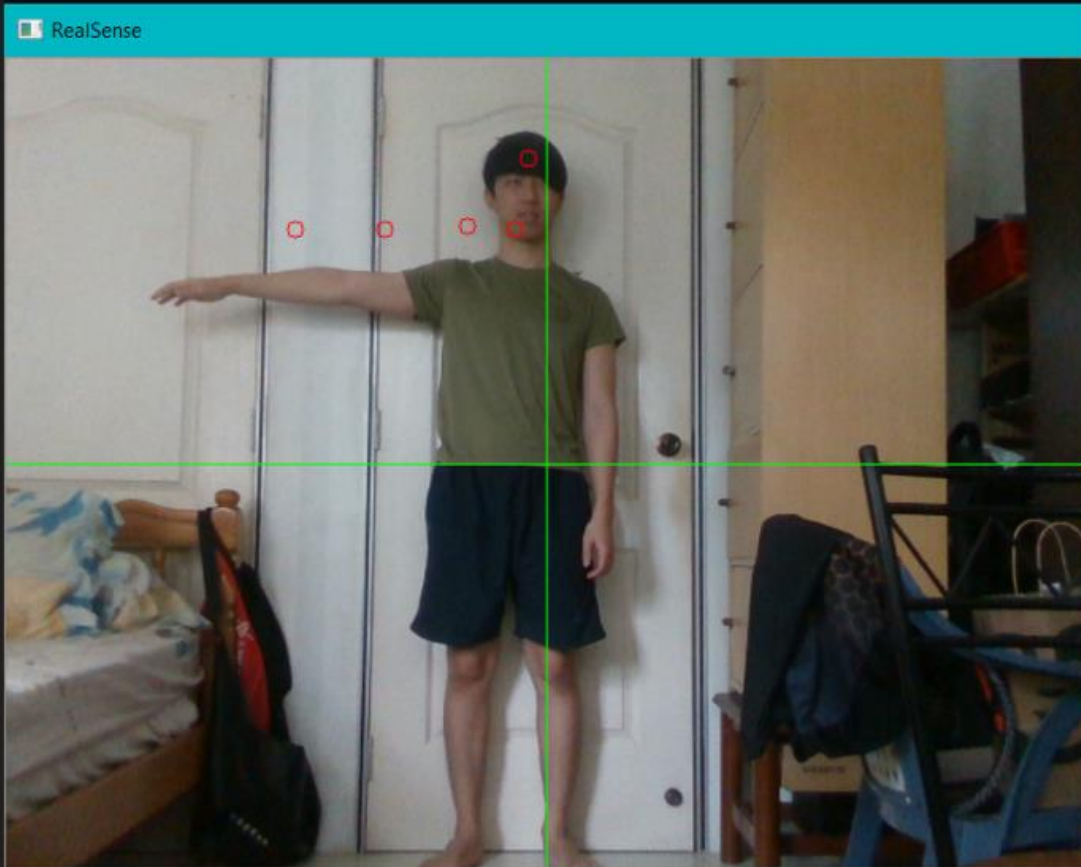- Changing the *keypoint_scale* to 0 gives values>640 and 480
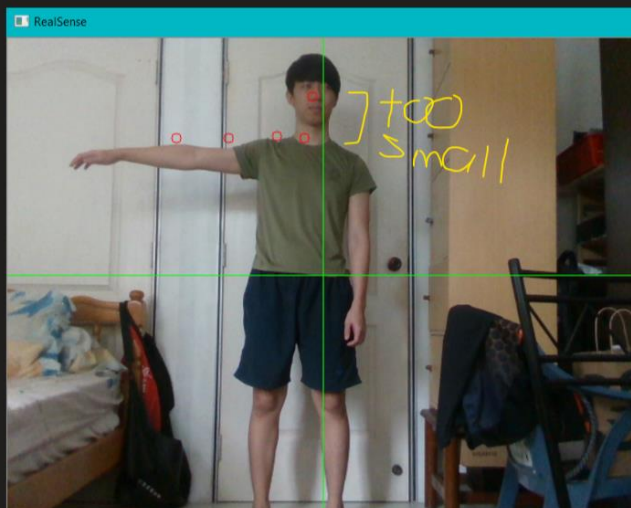- Now testing with *keypoint_scale* 1 and *net_resolution* 640x480

"part_candidates":[{
    "0":[309.238,59.2782,0.931129,178.258,206.256,0.0825484]
    "1":[301.24,101.24,0.868038,178.253,229.252,0.314031,468
    "2":[273.261,99.2404,0.800037,455.253,221.244,0.0858809,
    "3":[224.248,101.284,0.784882,131.249,205.256,0.169264,1
    "4":[171.273,101.264,0.826189,171.226,206.243,0.196233],
    "5":[331.276,106.252,0.823927,467.256,224.257,0.0503118,
    "6":[337.246,151.249,0.748236,130.26,204.292,0.0726609,4
    "7":[339.194,198.264,0.807639,171.229,206.263,0.0781549,
    "8":[298.244,194.254,0.606876,472.256,285.261,0.111468,1
    "9":[277.243,193.255,0.588246,185.247,288.245,0.154211,4
    "10":[276.235,267.275,0.842157,195.236,307.254,0.0523308
    "11":[275.249,345.252,0.782005,459.217,363.258,0.0585597
    "12":[316.258,195.224,0.605486,189.25,288.254,0.144799,4
    "13":[314.253,268.213,0.818096,163.227,308.23,0.108269,4
    "14":[309.273,341.263,0.751291,458.214,364.242,0.0683623
    "15":[302.272,52.2773,0.883725,177.232,204.267,0.0805041
    "16":[315.293,53.2461,0.913151,179.244,203.273,0.0824666
    "17":[290.261,59.2864,0.894166,179.228,208.251,0.0910799
    "18":[322.221,60.2609,0.461964,178.254,209.259,0.0800609
    "19":[313.243,356.227,0.353391],
    "20":[318.266,354.263,0.403402],
    "21":[307.243,347.247,0.619315,458.231,364.242,0.0639719],
    "22":[268.265,356.26,0.388956],
    "23":[262.259,355.2,0.430585],
    "24":[477.259,327.251,0.0524771,277.268,349.234,0.655957,459.229,364.251,0.0622215]}]}

4) Getting depth information from multiple points [14/9/20]

1. testing by using the frame 110 on top.
so i first draw circles based on the coordinates of 0,1,2,3,4.
Then i run the script to stand at the same spot.
Result:

RealSense

] too small (handwritten)

5RR 164 69 111 0 R9R623 1R5R 6 423 679 0 RR651541

^ If tried to align joint 0 to my actual body.

Whaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaaat?????
Isit cause the camera to low?

Due to midterms next after recess week, focus would be placed on other mods first. Then if i got time then do this.
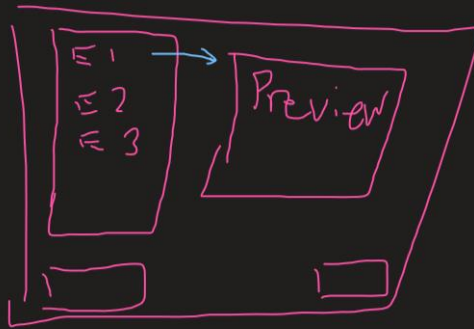THIS IS TAKING SO MUCH TIME URGH

6.1

Monday, 14 September 2020   4:28 PM

<u>Slide making</u>
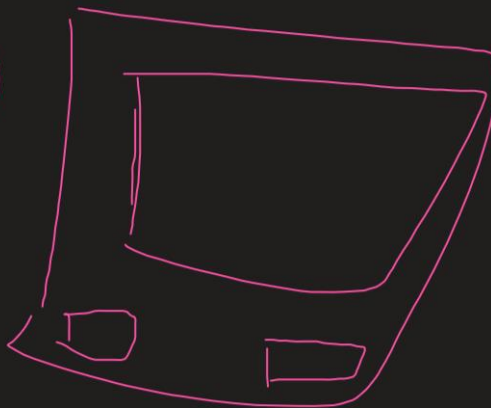- Made a engineering sample of the GUI
- Need integrate both camera and sensor into some kind of visual feedback

②

E 1 → Preview
E 2
E 3

③

- Page to follow after selection in (2).
- The bot right would be a label to show how much to turn.