

# Configurations of the operational amplifiers

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This code was developed by Miodrag Bolic for the book PERVASIVE CARDIAC AND RESPIRATORY MONITORING DEVICES.

```
% Changing the path from main_folder to a particular chapter
main_path=fileparts(which('Main_Content.mlx'));
if ~isempty(main_path)
    %addpath(append(main_path, '/Chapter2'))
    cd (append(main_path, '/Chapter3/Amplifier configurations'))
    addpath(append(main_path, '/Service'))
end
SAVE_FLAG=0; % saving the figures in a file
```

## Introduction

This notebook provides an introduction to operational amplifiers and models for a:

1. The model of an operational amplifier
2. Basic amplifier configurations

## Operational amplifier

Operational amplifiers are characterized using several parameters such as:

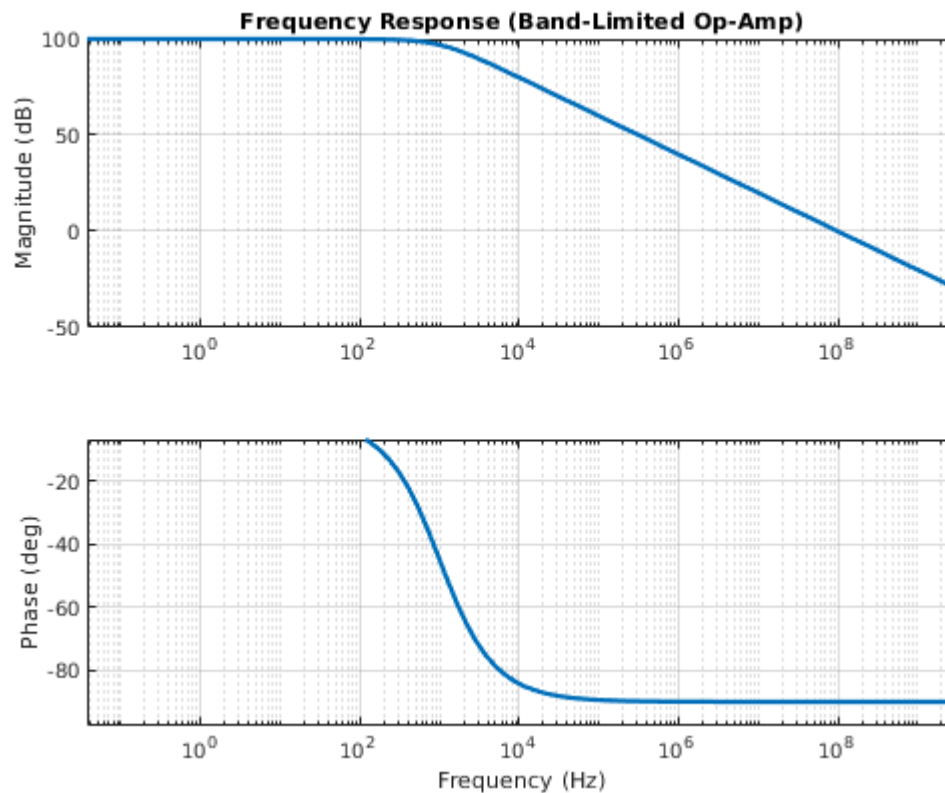
- Open-loop gain where  $V_0 = A(V_1 - V_2)$  and can be order of million
- Input resistance,  $R_{in}$  that should be very high, for example in the order of  $G\Omega$
- Output resistance,  $R_{out}$  that is commonly low in order of  $100 \Omega$
- Minimum and maximum output voltage
- Maximum slew rate which is the maximum positive or negative rate of change of output voltage magnitude. A typical number is, for example,  $2.8 \text{ V}/\mu\text{s}$ .

- Open-loop bandwidth is the frequency at which the gain drops by 3 dB in comparison with the gain at low frequencies.

Operational amplifiers are normally used in negative feedback configuration in which the output is connected to one input. By doing that, the ideal operational amplifier will adjust the output until the difference of the voltages at input is close to zero.

% Please note that we are using the model provided by Mathworks here.

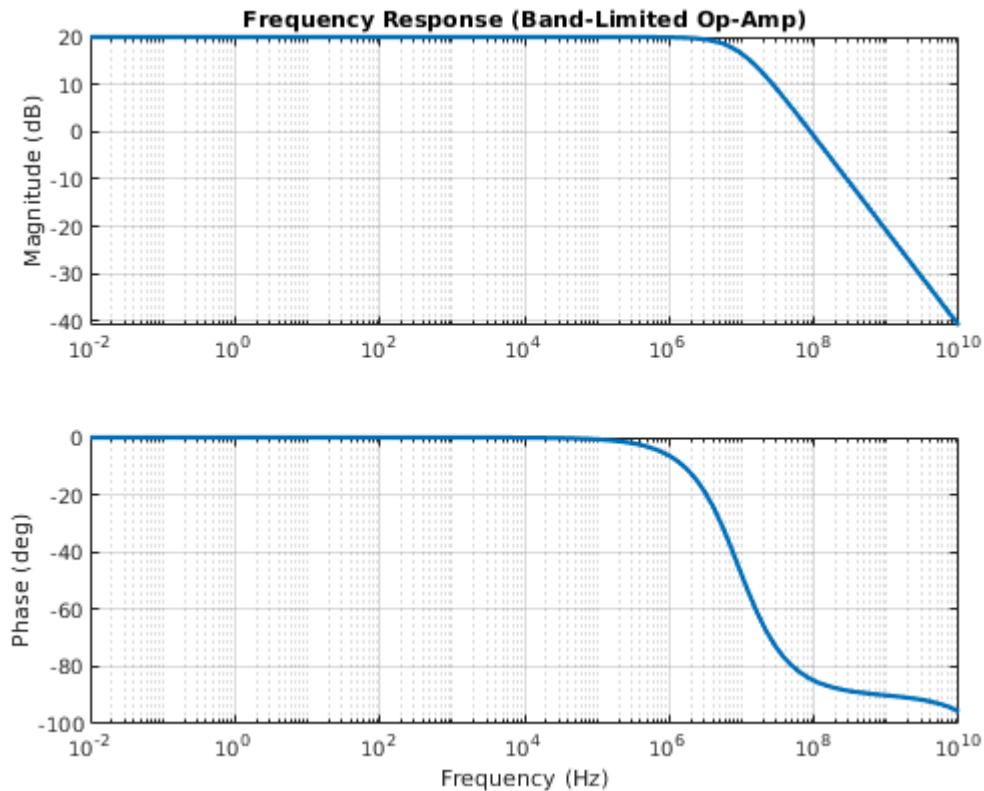
```
% Run linearization
figure
%% Open the model and set circuit parameters
open_system('ssc_opamp_bandlimited')
%% Linearize
[a,b,c,d]=linmod('ssc_opamp_bandlimited');
ssc_opamp_bandlimited_bodeplot
```



```
exportgraphics(gcf,"Fig3.2b.jpg", 'Resolution',600)
%annotation_save('b'),'Fig3.2b.jpg', SAVE_FLAG);
```

```
figure
%% Open the model and set circuit parameters
open_system('ssc_opamp_bandlimited_noninverting')

%% Linearize
[a,b,c,d]=linmod('ssc_opamp_bandlimited_noninverting');
```



## Exersizes

**Excercise 1:** Analyze frequency response of the op-amp model without the feedback circuit. What is the Gain BandWidth Product (GBWP)?

**Excercise 2:** Analyze frequency response of the op-amp model acting as an invertiong amplifier. What is the Gain BandWidth Product (GBWP)?

## Inverting amplifier

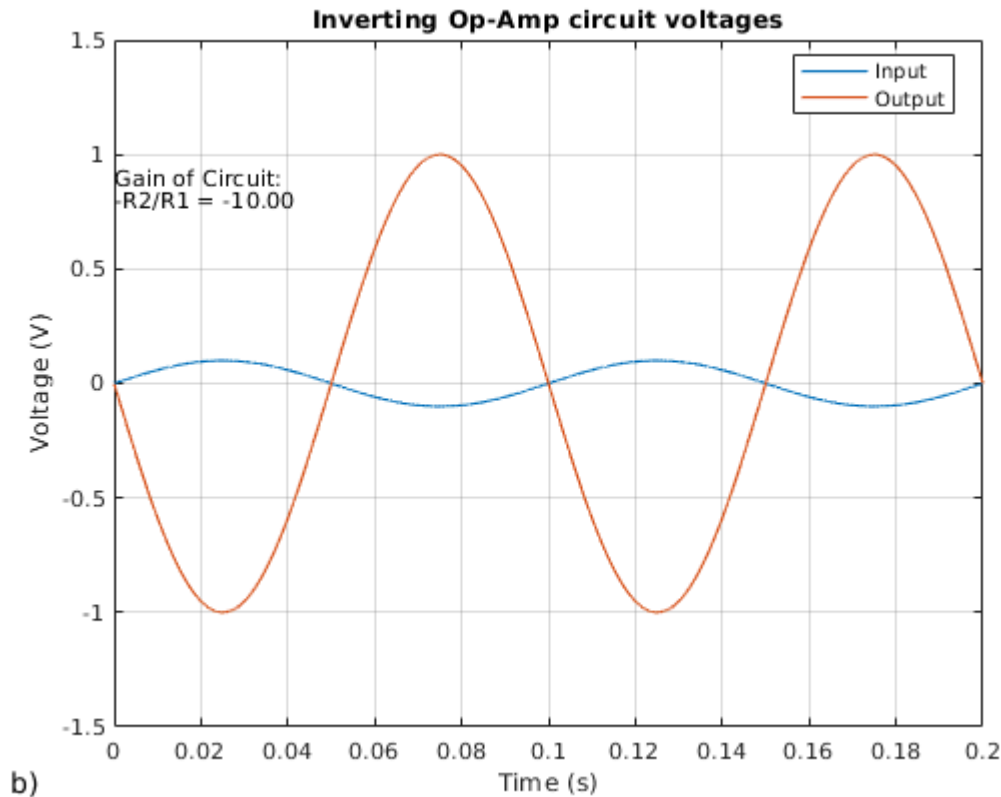
```
model_name = 'inverting';
open_system(model_name);
ScopeData1=sim(model_name);
temp_vin = simlog_ssc_opamp_inverting.AC_Voltage.v.series;
temp_vout = simlog_ssc_opamp_inverting.Sensor_Vout.Voltage_Sensor.V.series;

% Plot results
figure
plot(temp_vin.time,temp_vin.values,'LineWidth',1);
hold on
plot(temp_vout.time,temp_vout.values,'LineWidth',1);
hold off
text(0.1e-3,0.9,'Gain of Circuit:');
text(0.1e-3,0.8,sprintf('%s %2.2f', '-R2/R1 = ',-max(temp_vout.values)/max(temp_vin.values))
```

```

grid on
title('Inverting Op-Amp circuit voltages');
ylabel('Voltage (V)');
xlabel('Time (s)');
ylim([-1.5,1.5])
legend({'Input','Output'},'Location','Best');
annotation_save('b','Fig3.3b.jpg',SAVE_FLAG);

```



## Noninverting amplifier

```

clear_all_but('SAVE_FLAG')
model_name = 'noninverting1';
open_system(model_name);
sim(model_name);
temp_vin = simlog_ssc_opamp_noninverting.Sensor_Vin.Voltage_Sensor.V.series;
temp_vout = simlog_ssc_opamp_noninverting.Sensor_Vout.Voltage_Sensor.V.series;

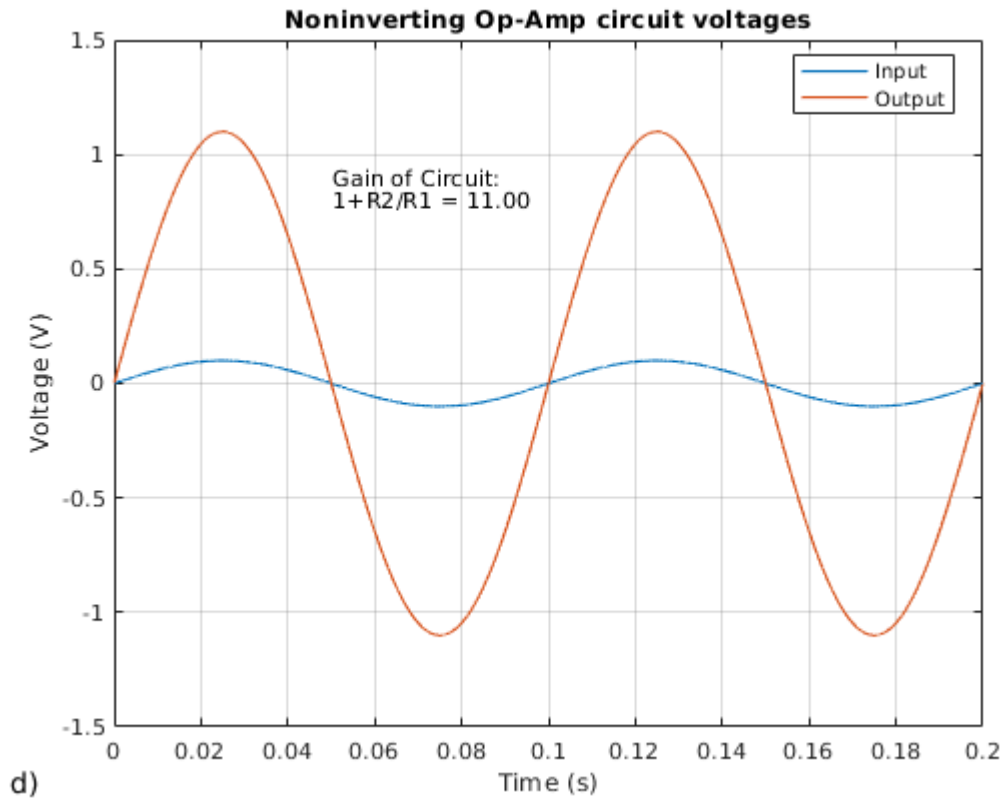
% Plot results
figure
plot(temp_vin.time,temp_vin.values,'LineWidth',1);
hold on
plot(temp_vout.time,temp_vout.values,'LineWidth',1);
hold off
text(0.05,0.9,'Gain of Circuit:');
text(0.05,0.8,sprintf('%s %2.2f','1+R2/R1 =',max(temp_vout.values)/max(temp_vin.values)));
grid on

```

```

title('Noninverting Op-Amp circuit voltages');
ylabel('Voltage (V)');
xlabel('Time (s)');
ylim([-1.5,1.5])
legend({'Input','Output'},'Location','Best');
annonation_save('d'),'Fig3.3d.jpg', SAVE_FLAG);

```



## Differentiator

```

clear_all_but('SAVE_FLAG')
model_name = 'differentiator';
open_system(model_name);
sim(model_name);
% Get simulation results
temp_vin = simout.Data(:,2);
temp_vout = simout.Data(:,1);

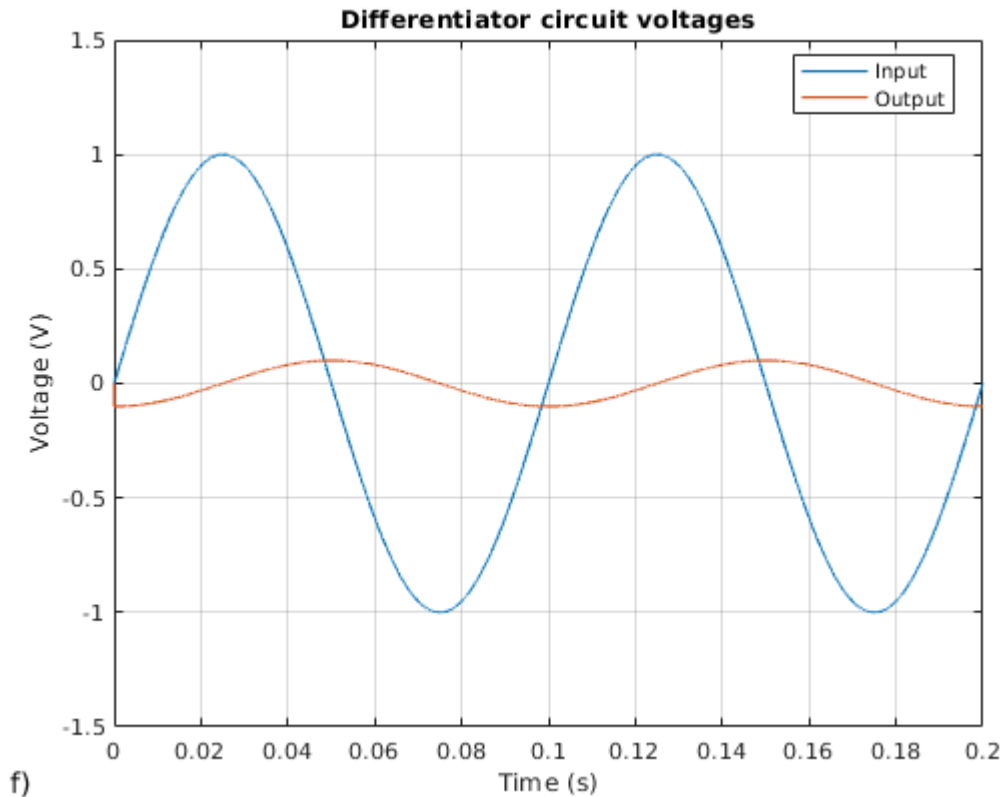
% Plot results
figure
plot(simout.Time,temp_vin,'LineWidth',1);
hold on
plot(simout.Time,temp_vout,'LineWidth',1);
hold off
grid on
title('Differentiator circuit voltages');
ylabel('Voltage (V)');
xlabel('Time (s)');
ylim([-1.5,1.5])

```

```

legend({'Input','Output'},'Location','Best');
annnotation_save('f'),'Fig3.3f.jpg', SAVE_FLAG);

```



## Integrator

This is the integrator from the Problem 4.17 from the book. Please note that the values of the resistance and the capacitance are not set properly and that this should be done in order to solve Problem 4.17.

```

clear all
model_name = 'integrator1';
open_system(model_name);
T=0.0001;

t=0:T:2;
a=sin(2*pi*t*100);
ind=find(a>0);
pulsel=zeros(1, length(a));
pulsel(ind)=-1;
Vin(:,1)=t; %time;
Vin(:,2)=pulsel;

sim(model_name);
% Get simulation results
temp_vin = simout.Data(:,2);
temp_vout = simout.Data(:,1);

% Plot results
figure

```

```

plot(simout.Time,temp_vin,'LineWidth',1);
hold on
plot(simout.Time,temp_vout,'LineWidth',1);
hold off
grid on
title('Differentiator Circuit Voltages');
ylabel('Voltage (V)');
xlabel('Time (s)');
ylim([-1.5,1.5])
xlim([0,0.2])
legend({'Input','Output'},'Location','Best');

```

