## I. Linear Algebra

# I.6. The Spectral Decomposition

Lecture based on

https://github.com/gwthomas/math4ml (Garrett Thomas, 2018)

https://mml-book.github.io/ (Deisenroth et al., 2020, Mathematics for Machine Learning)

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A matrix  $\mathbf{Q} \in \mathbb{R}^{n \times n}$  is said to be **orthogonal** if its columns are pairwise orthonormal.

This definition implies that

$$\mathbf{Q}^{\mathsf{T}}\mathbf{Q} = \mathbf{Q}\mathbf{Q}^{\mathsf{T}} = \mathbf{I}$$

or equivalently,  $\mathbf{Q}^{\top} = \mathbf{Q}^{-1}$ .

A nice thing about orthogonal matrices is that they preserve inner products:

$$(\mathbf{Q}\mathbf{x})^{\mathsf{T}}(\mathbf{Q}\mathbf{y}) = \mathbf{x}^{\mathsf{T}}\mathbf{Q}^{\mathsf{T}}\mathbf{Q}\mathbf{y} = \mathbf{x}^{\mathsf{T}}\mathbf{I}\mathbf{y} = \mathbf{x}^{\mathsf{T}}\mathbf{y}$$

A direct result of this fact is that they also preserve 2-norms:

$$\|\mathbf{Q}\mathbf{x}\|_2 = \sqrt{(\mathbf{Q}\mathbf{x})^{\mathsf{T}}(\mathbf{Q}\mathbf{x})} = \sqrt{\mathbf{x}^{\mathsf{T}}\mathbf{x}} = \|\mathbf{x}\|_2$$

Therefore multiplication by an orthogonal matrix can be considered as a transformation that preserves length, but may rotate or reflect the vector about the origin.

The **trace** of a square matrix is the sum of its diagonal entries:

$$\operatorname{tr}(\mathbf{A}) = \sum_{i=1}^{n} A_{ii}$$

The trace has several nice algebraic properties:

$$\mathbf{0}\operatorname{tr}(\mathbf{A} + \mathbf{B}) = \operatorname{tr}(\mathbf{A}) + \operatorname{tr}(\mathbf{B})$$

$$\mathbf{0}\operatorname{tr}(\alpha\mathbf{A}) = \alpha\operatorname{tr}(\mathbf{A})$$

$$\mathbf{m}\operatorname{tr}(\mathbf{A}^{\top})=\operatorname{tr}(\mathbf{A})$$

$$\mathbf{v}$$
 tr(ABCD) = tr(BCDA) = tr(CDAB) = tr(DABC)

The first three properties follow readily from the definition.

The last is known as invariance under cyclic permutations.

Note that the matrices cannot be reordered arbitrarily, for example  $tr(\mathbf{ABCD}) \neq tr(\mathbf{BACD})$  in general.

Also, there is nothing special about the product of four matrices – analogous rules hold for more or fewer matrices.

Interestingly, the trace of a matrix is equal to the sum of its eigenvalues (repeated according to multiplicity):

$$\operatorname{tr}(\mathbf{A}) = \sum_{i} \lambda_{i}(\mathbf{A})$$

A matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$  is said to be **symmetric** if it is equal to its own transpose  $(\mathbf{A} = \mathbf{A}^{\mathsf{T}})$ , meaning that  $A_{ij} = A_{ji}$  for all (i, j).

This definition seems harmless enough but turns out to have some strong implications.

We summarize the most important of these as

### Theorem (Spectral Theorem)

If  $\mathbf{A} \in \mathbb{R}^{N \times N}$  is symmetric, then there exists an orthonormal basis for  $\mathbb{R}^N$  consisting of eigenvectors of  $\mathbf{A}$ .

The practical application of this theorem is a particular factorization of symmetric matrices, referred to as the **eigendecomposition** or **spectral decomposition**.

Denote the orthonormal basis of eigenvectors  $\mathbf{q}_1,\ldots,\mathbf{q}_n$  and their eigenvalues  $\lambda_1,\ldots,\lambda_n$ .

Let  ${f Q}$  be an orthogonal matrix with  ${f q}_1,\ldots,{f q}_n$  as its columns, and  ${f \Lambda}={
m diag}(\lambda_1,\ldots,\lambda_n).$ 

Since by definition  $\mathbf{A}\mathbf{q}_i = \lambda_i \mathbf{q}_i$  for every i, the following relationship holds:

$$\mathbf{A}\mathbf{Q}=\mathbf{Q}\boldsymbol{\Lambda}$$

Right-multiplying by  $\mathbf{Q}^{\!\top}\!,$  we arrive at the decomposition

$$\mathbf{A} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{\mathsf{T}}$$

Let  $\mathbf{A} \in \mathbb{R}^{N \times N}$  be a symmetric matrix.

The expression  $\mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x}$  is called a **quadratic form**.

The Rayleigh quotient

$$R_{\mathbf{A}}(\mathbf{x}) = \frac{\mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x}}{\mathbf{x}^{\mathsf{T}} \mathbf{x}}$$

The Rayleigh quotient has a couple of important properties which the reader can (and should!) easily verify from the definition:

**1** Scale invariance: for any vector  $\mathbf{x} \neq \mathbf{0}$  and any scalar  $\alpha \neq 0$ ,  $R_{\mathbf{A}}(\mathbf{x}) = R_{\mathbf{A}}(\alpha \mathbf{x})$ .

 $\mathbf{m}$  If  $\mathbf{x}$  is an eigenvector of  $\mathbf{A}$  with eigenvalue  $\lambda$ , then  $R_{\mathbf{A}}(\mathbf{x}) = \lambda$ .

The Rayleigh quotient is bounded by the largest and smallest eigenvalues of  ${\bf A}.$ 

### **Proposition**

For any  $\mathbf{x}$  such that  $\|\mathbf{x}\|_2 = 1$ ,

$$\lambda_{\min}(\mathbf{A}) \leq \mathbf{x}^{\mathsf{T}} \mathbf{A} \mathbf{x} \leq \lambda_{\max}(\mathbf{A})$$

with equality if and only if x is a corresponding eigenvector.

#### Proof.

We show only the  $\max$  case because the argument for the  $\min$  case is entirely analogous. Since  $\mathbf{A}$  is symmetric, we can decompose it as  $\mathbf{A} = \mathbf{Q} \mathbf{\Lambda} \mathbf{Q}^{\mathsf{T}}$ . Then use the change of variable  $\mathbf{y} = \mathbf{Q}^{\mathsf{T}} \mathbf{x}$ , noting that the relationship between  $\mathbf{x}$  and  $\mathbf{y}$  is one-to-one and that  $\|\mathbf{y}\|_2 = 1$  since  $\mathbf{Q}$  is orthogonal. Hence

$$\max_{\|\mathbf{x}\|_2 = 1} \mathbf{x}^{\top} \mathbf{A} \mathbf{x} = \max_{\|\mathbf{y}\|_2 = 1} \mathbf{y}^{\top} \mathbf{\Lambda} \mathbf{y} = \max_{y_1^2 + \dots + y_n^2 = 1} \sum_{i=1}^n \lambda_i y_i^2$$

Written this way, it is clear that  $\mathbf{y}$  maximizes this expression exactly if and only if it satisfies  $\sum_{i \in I} y_i^2 = 1$  where  $I = \{i : \lambda_i = \max_{j=1,\dots,n} \lambda_j = \lambda_{\max}(\mathbf{A})\}$  and  $y_j = 0$  for  $j \notin I$ . That is, I contains the index or indices of the largest eigenvalue. In this case, the maximal value of the expression is

$$\sum_{i=1}^{n} \lambda_i y_i^2 = \sum_{i \in I} \lambda_i y_i^2 = \lambda_{\max}(\mathbf{A}) \sum_{i \in I} y_i^2 = \lambda_{\max}(\mathbf{A})$$

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#### ... continued.

Then writing  $q_1, \ldots, q_n$  for the columns of Q, we have

$$\mathbf{x} = \mathbf{Q}\mathbf{Q}^{\mathsf{T}}\mathbf{x} = \mathbf{Q}\mathbf{y} = \sum_{i=1}^{n} y_i \mathbf{q}_i = \sum_{i \in I} y_i \mathbf{q}_i$$

where we have used the matrix-vector product identity.

Recall that  $\mathbf{q}_1, \dots, \mathbf{q}_n$  are eigenvectors of  $\mathbf{A}$  and form an orthonormal basis for  $\mathbb{R}^n$ .

Therefore by construction, the set  $\{\mathbf{q}_i: i \in I\}$  forms an orthonormal basis for the eigenspace of  $\lambda_{\max}(\mathbf{A})$ .

Hence  $\mathbf{x}$ , which is a linear combination of these, lies in that eigenspace and thus is an eigenvector of  $\mathbf{A}$  corresponding to  $\lambda_{\max}(\mathbf{A})$ .

We have shown that  $\max_{\|\mathbf{x}\|_2=1} \mathbf{x}^T \mathbf{A} \mathbf{x} = \lambda_{\max}(\mathbf{A})$ , from which we have the general inequality  $\mathbf{x}^T \mathbf{A} \mathbf{x} \leq \lambda_{\max}(\mathbf{A})$  for all unit-length  $\mathbf{x}$ .

By the scale invariance of the Rayleigh quotient, we immediately have as a corollary (since  $\mathbf{x}^{\mathsf{T}}\mathbf{A}\mathbf{x}=R_{\mathbf{A}}(\mathbf{x})$  for unit  $\mathbf{x}$ )

#### Theorem (Min-max theorem)

For all  $\mathbf{x} \neq \mathbf{0}$ ,

$$\lambda_{\min}(\mathbf{A}) \le R_{\mathbf{A}}(\mathbf{x}) \le \lambda_{\max}(\mathbf{A})$$

with equality if and only if  $\mathbf{x}$  is a corresponding eigenvector.