



# MORE ON ASSEMBLY PROGRAMMING

EL-GY 6483 Real Time Embedded Systems



# A SIMPLE C PROGRAM

```
int total;
```

```
int i;
```

```
total = 0;
```

```
for (i = 10; i > 0; i--) {
```

```
total += i;
```

```
}
```

# ARM EQUIVALENT

MOV R0, #0 ; R0 accumulates total

MOV R1, #10 ; R1 counts from 10 to 1

again ADD R0, R0, R1

SUBS R1, R1, #1

BNE again *BNE will do a branch (jump) only if the "equal" condition is not currently active.*

halt B halt ; infinite loop to stop

# MEMORY INSTRUCTIONS

*ADD Through Memory Address*

addInts MOV R4, #0

addLoop LDR R2, [R0]

ADD R4, R4, R2

ADD R0, R0, #4

SUBS R1, R1, #1

BNE addLoop

# MORE ADDRESSING MODES

addInts MOV R4, #0

addLoop SUBS R1, R1, #1  $R_1 = R_1 - 1$

LDR R2, [R0, R1, LSL #2]  $R_0 \quad R_0 + R_1 * 4$

ADD R4, R4, R2

BNE addLoop

# WHAT DOES THE ASSEMBLER DO?

Translate

MOV R3, R9

into

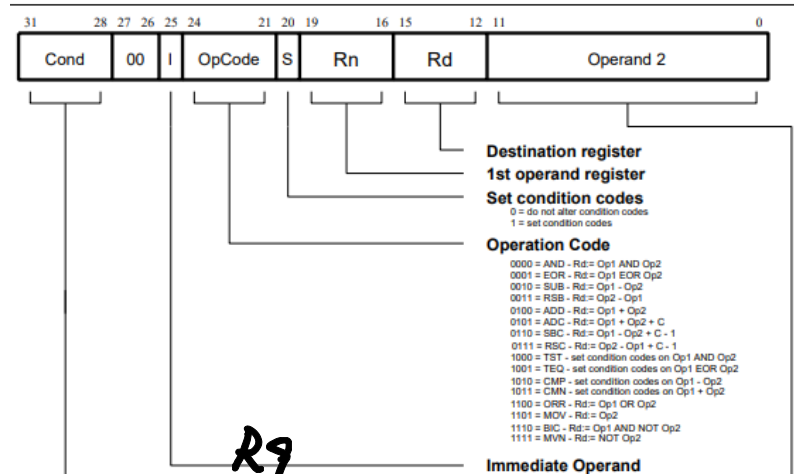
1110 0001 1010 0000 0011 0000 0000 1001

*MOV R3*  
*MOV R9*  
*?*

*NO*

*R3*

*R9*



3	3	2	2	2	2	2	2	2	2	2	2	1	1	1	1	1	1	1	1	1	1	0	9	8	7	6	5	4	3	2	1	0	Instruction Type
1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0	9	8	7	6	5	4	3	2	1	0		
Condition				0	0	I	OPCODE				S	Rn				Rs				OPERAND-2								Data processing					

1101	LE	Signed less than or equal	Z set or N is no
1110	AL	Always	any
1111	NV	Never (do not use!)	none

# HELLO WORLD FOR ARM ASSEMBLY

```
global _start
```

```
_start:
```

```
MOV R7, #4
```

} exit code

```
MOV R0, #1
```

```
MOV R2, #12
```

⇒ 12 characters

```
LDR R1, =string
```

```
SWI 0
```

How SWI works

Depends on R7, R0, R2

```
MOV R7, #1
```

⇒ exit code

```
SWI 0
```

```
.data
```

```
string:
```

```
.ascii "Hello World\n"
```

# CALLING ARM ASSEMBLY FROM C

```
#include <stdio.h>

extern void strcpy(char *d, const char *s);

int main()
{
    const char *srcstr = "First string - source ";
    char dststr[] = "Second string - destination ";

    /* dststr is an array since we're going to change it */

    printf("Before copying:\n");
    printf(" %s\n %s\n",srcstr,dststr);
    strcpy(dststr,srcstr); // in strcpy.s
    printf("After copying:\n");
    printf(" %s\n %s\n",srcstr,dststr);

    return (0);
}
```



# CALLING ARM ASSEMBLY FROM C

PRESERVE8

AREA SCopy, CODE, READONLY

EXPORT strcpy = *.global*

strcpy ; R0 points to destination string.  
; R1 points to source string.

} *Define function name*

LDRB R2, [R1],#1 ; Load byte and update address. {  $R_1 \rightarrow R_2$   
 $R_1 + 1$

STRB R2, [R0],#1 ; Store byte and update address. {  $R_2 \rightarrow R_0$   
 $R_0 + 1$

CMP R2, #0 ; Check for null terminator.

BNE strcpy ; Keep going if not.

BX lr ; Return.

END

# INLINE ASSEMBLY EXAMPLES

Calling assembly inline: *put assembly code in C program.*

*/\* NOP example \*/*

`__asm("mov r0,r0");`

*C variable*  
`/* Rotating bits example */`

`asm("mov %[result], %[value], ror #1" : [result] "=r" (y) : [value] "r" (x));` *next slide*

Each *asm* statement is divided by colons into up to four parts:

1. The assembler instructions, defined in a single string literal:

"mov %[result], %[value], ror #1"

2. An optional list of output operands, separated by commas. Each entry consists of a symbolic name enclosed in square brackets, followed by a constraint string, followed by a C expression enclosed in parentheses. Our example uses just one entry:

[result] "=r" (y)

3. A comma separated list of input operands, which uses the same syntax as the list of output operands. Again, this is optional and our example uses one operand only:

[value] "r" (x)

# Variable Constraints

Constraint	Used for	Range
a	Simple upper registers	r16 to r23
b	Base pointer registers pairs	y,z
d	Upper register	r16 to r31
e	Pointer register pairs	x,y,z
G	Floating point constant	0.0
I	6-bit positive integer constant	0 to 63
J	6-bit negative integer constant	-63 to 0
K	Integer constant	2
L	Integer constant	0
l	Lower registers	r0 to r15
M	8-bit integer constant	0 to 255
n	16-bit integer constant?	
N	Integer constant	-1
O	Integer constant	8, 16, 24
P	Integer constant	1
q	Stack pointer register	SPH:SPL
r	Any register	r0 to r31
t	Temporary register	r0
v	32-bit integer constant?	
w	Special upper register pairs	r24, r26, r28, r30
x	Pointer register pair X	x (r27:r26)
y	Pointer register pair Y	y (r29:r28)
z	Pointer register pair Z	z (r31:r30)

Modifier	Specifies
=	Write-only operand, usually used for all output operands.
+	Read-write operand (not supported by inline assembler)
&	Register should be used for output only

```
asm volatile("swap %0" : "=r" (value) : "0" (value));
```

# INLINE ASSEMBLY EXAMPLE

```
int foo(int x, int y)
{
    __asm
    {
        SUBS x,x,y
        BEQ end
    }
    return 1;
end:
    return 0;
}
```

# ARM CALLING CONVENTION

Register	Role
r0-r3	arguments passed, r0 holds result
r4-r10	local variables, callee-save
r11	<u>frame pointer</u>
r12	intra-procedure-call scratch register
r13	stack pointer
r14	link register
r15	program counter

Only 4 registers.  
if 10 parameters  
stack pop off first

Additional parameters and return values may be passed via stack.