# Skeletonization of 2D Binary Images

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Created: June 7, 2001

#### 1 Introduction

This document describes a simple algorithm for creating skeletons of binary blobs in 2D images. The blob pixels are 1-valued and the background pixels are 0-valued. The goals of the algorithm are to preserve the number of connected components in the image and to preserve the number of holes in the image.

Various definitions for pixels are important in the construction. The *interior* of a blob is defined using 4-connectedness. A 1-pixel at (x, y) is an *interior pixel* if its four neighbors at (x+1, y), (x-1, y), (x, y+1), and (x, y-1) are 1-pixels. The *boundary* of a blob is defined using 8-connectedness. A pixel is a *boundary* pixel if it is not an interior pixel and at least one of its eight neighbors is a 0-pixel.

As a whole, a blob can be viewed as an abstract undirected graph whose vertices are the 1-pixels and whose edges are defined by 8-connected adjacency. That is, if  $(x_0, y_0)$  and  $(x_1, y_1)$  are distinct 1-pixels with  $|x_1 - x_0| \le 1$  and  $|y_1 - y_0| \le 1$ , then  $\langle (x_0, y_0), (x_1, y_1) \rangle$  is an edge in the graph. A graph is connected if any two of its vertices are connected by some path through the graph. A vertex of a connected graph is an articulation point if its removal from the graph causes the graph to become disconnected. For the purposes of skeletonization, whether or not a 1-pixel is removed is based on the local behavior of the graph at that pixel. Of particular importance is a 1-pixel that is called a local articulation point. This is a pixel such that if it is removed from the graph, the  $3 \times 3$  neighborhood of that pixel becomes disconnected. Observe that an articulation point is necessarily a local articulation point, but the converse is not true as the following diagram illustrates.

	x-2	x - 1	$\boldsymbol{x}$	x + 1	x+2
y-2	0	1	1	1	0
y-1	0	1	0	1	0
y	0	0	1	0	0
y + 1	0 0 0	0	0	0	0

The pixel (x, y) is a local articulation point. If it were to be removed from the graph, its  $3 \times 3$  neighborhood becomes disconnected into two single-point components, the pixel at (x-1, y-1) and the pixel at (x+1, y-1). However, the full graph in the diagram is connected. The removal of (x, y) does not disconnect the full graph since (x-1, y-1) is connected to (x+1, y-1) via the pixel (x, y-2).

#### 2 Characterization of Local Articulation Points

The definition might lead one to apply a standard connected component labeler to the subgraph in the  $3 \times 3$  neighborhood of (x, y) once (x, y) is removed. However, given the size of the graph, a faster method involves using a look-up table. The binary values of the eight neighbors of (x, y) can be encoded in an 8-bit index for the table. Of course, the table has 256 elements. The bit assignments are  $b_i$  for  $0 \le i \le 7$  are shown below:

 $\begin{array}{c|ccc} b_0 & b_1 & b_2 \\ \hline b_7 & * & b_3 \\ \hline b_6 & b_5 & b_4 \\ \end{array}$ 

The lookup table has a value of 1 if and only if the pixel is a local articulation point. The table is

0	0	0	0	0	1	0	0	0	1	0	0	0	1	0	0
0	1	1	1	1	1	1	1	0	1	0	0	0	1	0	0
0	1	1	1	1	1	1	1	0	1	0	0	0	1	0	0
0	1	1	1	1	1	1	1	0	1	0	0	0	1	0	0
0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
0	1	1	1	1	1	1	1	0	1	0	0	0	1	0	0
0	1	1	1	1	1	1	1	0	1	0	0	0	1	0	0
0	0	0	0	1	1	0	0	1	1	0	0	1	1	0	0
1	1	1	1	1	1	1	1	1	1	0	0	1	1	0	0
0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0
0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0
0	0	0	0	1	1	0	0	1	1	0	0	1	1	0	0
1	1	1	1	1	1	1	1	1	1	0	0	1	1	0	0
0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0
0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0

where the upper left corner corresponds to index 0 and the indices increase from left to right, then top to bottom. For example, notice that the first 1 encountered in the first row of the table is at index 5. This corresponds to the pixel (x, y) shown earlier as an example of a local articulation point. The bits  $b_0$  and  $b_2$  are set to 1 since the corresponding pixels at (x - 1, y - 1) and (x + 1, y - 1) are 1, all other bits being zero. The byte index 00000101 is the decimal number 5.

### 3 Large Scale Thinning

The candidate pixels for being removed are obviously the boundary pixels. But there is more to the story. A 1-pixel-thick horizontal straight line is already a skeleton of itself (according to anyone's definition for skeleton). By definition, all pixels on that line are boundary pixels, but none of them are removed to obtain the skeleton. Somewhat more complicated is the example of a 2-pixel-thick horizontal straight line. Some decision must be made about which pixels should be removed. An obvious choice is to remove the top row of pixels, but it is not clear that a greedy approach is always the best one.

The approach I take is to apply a *large scale thinning* in an iterative manner that determines which pixels are interior ones before making the decision on which boundary pixels to remove. Thus, the method is only partly greedy. After interior pixels are tagged as such, boundary pixels are removed one by one, using a top—to—bottom row scan, as long as they are (1) adjacent in the 8—connected sense to an interior pixel and (2) not a local articulation point. Multiple passes are made using this algorithm until (1) no more interior pixels exist or (2) interior pixels exist yet no more boundary pixels can be removed. The diagram below shows the original binary image (on the left) with background pixels marked as periods for readability. The middle image shows the interior pixels marked with 2, the boundary pixels with value 1. The right image shows the image after boundary pixels are removed in a greedy manner (scan left to right, then top to bottom).

11111111	11111111	111
1111111111	111122221	11112222
111111	122221	2222
1111111	112221	222
11111	12221	222
11111	12221	
11111	12221	
1111		
1111	1221	
111111	112221	
111111111111	11222222111	222222
1111111111111111	12222222222111	2222222222
1111111111111111111	12222222211222211	222222222222
111111111111111111	12222222111111211	2222222212.1
11111111111111	1222212221111	2222.22211
11111.1111	12221.1221	222122
1111.11111	1221.12221	221.1222
1111.11111	1221.12221	221222
1111.11111	1221.12221	22222
1111111111	122212221	222.222
111111111	12222221	222222
1111111111	11222221	1.222222
11111111	11111111	11

The next diagram illustrates a repeat of the process. The left image is the the right image from the previous diagram with all the 2's replaced by 1's.

111	111	111
11111111	11111111	111111
1111	1121	112
111	121	
	121	2
	121	2
	121	22
	11	1
	121	22
111111	112221	222
111111111111	11222222111	222222111
1111111111111	122222211111	2222221111
11111111111.1	1222122111.1	222.2211.1
1111.11111	1221.12111	22211
111111	122111	2211
111.1111	111.1121	11.1.2
111111	111221	11122
11111	11121	12
111.111	121.121	22
111111	122121	22.2
1.111111	1.111111	1.111
11	11	11

## Another pass.

111	111	111
111111	111111	111111
111	111	111
	1	1
	121	
	112221111	
	1212211111	
	121.1111.1	
11111	11111	11
1111	1211	211
11.1.1	11.1.1	11.1.1
11111	11111	11111
11	11	11
11	11	11
11.1	11.1	11.1
1.111	1.111	1.111
11	11	11

#### Another pass.

111	111	111
111111	111111	111111
	111	
	1	
	1	
	1	
1		1
	11111111	
1111.1	111.1	1111.1
1111	11	11
111	111	111
11.1.1	11.1.1	11.1.1
11111	11111	11111
11	11	11
11	11	11
11.1	11.1	11.1
1.111		
11	11	11

The final result after all pixels are relabed to 1 is shown below.

111
111111
111
1
1111111
111.1
11
111
11.1.1
11111
11
11
11.1
1.111
11
±±

The stopping criterion in this example is that there are no more interior pixels. The other stopping criterion that was mentioned earlier is that there are interior pixels, but no boundary pixels can be removed. The only way this is possible is if every boundary pixel is a local articulation point. This is a situation where the small scale information is effectively noise that affects the larger scale aspects of the blob. The following example illustrates how pathological the problems can be. The interior pixels are marked by 4, the boundary pixels are marked by 1, and the background pixels are marked by 0.

Effectively this examples shows lots of single-pixel-sized "holes" surrounded by the 1-pixels. You can imagine taking this type of configuration and scattering it throughout an image to create a very large image with lots of interior pixels, but the image cannot be trimmed. Potentially the worst case is a checkerboard image where (x,y) pixels are 1 for x+y even and 0 for x+y odd except for an arbitrary set of odd-sum components that are set to 1.

If the number of single–pixel–sized holes is expected to be small, a preprocess of the image can be made to fill them with 1–pixel values, effectively a dilation except that the "outermost" 1–pixels are not expanded.

# 4 Smaller Scale Thinning

In the large image example shown earlier, the large scale thinning was applied until the thinned binary blob had no more interior pixels. If skeleton thickness is not an issue, you can stop here and accept this set as the skeleton. On the other hand, many applications desire a 1-pixel thick skeleton that can be segmented into disjoint polylines. The interiorless thinned blob must be reduced even further.

The simplest way to do this is to repeat the large scale thinning algorithm, but by marking all those pixels with exactly three adjacent neighbors in the 4-connected sense (only north, south, east, and west neighbors are counted). Call these points 3-interior points. After marking such pixels, a pass is made to remove boundary pixels that are adjacent to the marked pixels. Essentially the thinned blob is not thick enough to have a true interior point (a 4-interior point), but it is almost thick enough because it has the 3-interior points. As in the large scale thinning, multiple passes are made using this algorithm until (1) no more 3-interior pixels exist or (2) 3-interior pixels exist yet no more boundary pixels can be removed. If condition (2) is the one that stops the process, it is safe to remove any remaining 3-interior pixels (using a greedy removal) because, by definition, they cannot be local articulation points.

Continuing with the previous example, the diagram below shows the image resulting from the large scale thinning (image on the left). The middle image shows the marked pixels. The right image shows the image after boundary pixels are removed in a greedy manner (scan left to right, then top to bottom).

111	131	.3
111111	133111	.33111
111	111	111
	1	1
		1
		1
1111111	1111111	1111111
1111.1	111.1	1111.1
	1	
111	311	311
11.1.1	11.1.1	11.1.1
11111	11131	11131
	11	
	11	
	11.1	
1.111		
	11	=

The next pass yields 3–interior points, but no boundary pixels can be removed. Stopping condition (2) is met and the remaining 3–interior pixels are removed in a greedy manner. The right image below is the result of that removal.

.1	.1	.1
.11111	.11111	.11111
111	111	111
1	1	1
	1	1
1		
1		1
1111111	$\dots\dots1111\dots11111\dots$	1111111
	$\dots\dots1\dots1\dots1\dots\dots11\dots1$	
$\dots\dots1\dots1\dots1\dots\dots11$	$\dots\dots1\dots1\dots1\dots\dots11$	$\dots\dots1\dots1\dots1\dots\dots11$
111	311	11
11.1.1	11.1.1	11.1.1
11111	11131	111.1
	11	
	11	
	$\dots 11.1\dots\dots\dots$	
	1.111	
11	11	11

Although in this example, all 3-interior pixels were removed, the following shows a simple situation where neither 3-interior pixel is a local articulation point *until* the other one is removed. The removal must check for local articulation. The original image is on the left with the 3-interior pixels marked. The middle image is the left image with the first 3-interior pixel removed. The other 3-interior pixel becomes a local articulation point, so it cannot be removed. The right image is the final result of the removal.

0	1	0	0	1	0		0	1	0
0	3	1	 0	0	1	$\rightarrow$	0	0	1
						$\rightarrow$			
0	1	0	0	1	0		0	1	0

### 5 Smallest Scale Thinning

The final thinned blob after the two thinning operations may still not be 1-pixel thick (if possible). In the event that no more 4-interior or 3-interior pixels exist, there may be what I call 2-interior pixels. These pixels have one neighbor in the north/south direction and one neighbor in the east/west direction. Such a pixel forms an "L" with the two neighbors.

An algorithm identical to the 3-interior processing may be applied for the 2-interior case. The 2-interior pixels are marked. Boundary pixels that are adjacent to 2-interior pixels are removed as long as they are not local articulation points. Multiple passes are made until (1) no more 2-interior pixels exist or (2) 2-interior pixels exist yet no more boundary pixels can be removed.

Continuing with the previous example, the diagram below shows the image resulting from the large scale thinning (image on the left). The middle image shows the marked pixels. The right image shows the image after boundary pixels are removed in a greedy manner (scan left to right, then top to bottom).

.11111	.1	.11112
1		1
		1
		1
111111	211112	211112
1111111	1112111	1112111
111.1	$\dots\dots1\dots1\dots1\dots\dots11.1$	1111
1111	11	1112
11	11	11
11.1.1	11.1.1	11.1.1
11111	121.1	121.1
11	11	11
11	11	11
11.1	21.1	11.1
1.111		
11	21	21

The next pass yields 2–interior points, but no boundary pixels can be removed. Stopping condition (2) is met and the remaining 2–interior pixels are removed in a greedy manner. The right image below is the result of that removal.

	.11112	
	211	
1	1	1
	1	
	1	
1	1	1
		1
		1
111111	211112	21111
$\dots\dots1111\dots11111\dots$	1112111	1112111
$\dots\dots1\dots1\dots1\dots\dots11\dots$	$\dots\dots1\dots1\dots1\dots\dots11\dots$	1111
$\dots\dots1\dots1\dots1\dots\dots11$	$\dots\dots1\dots1\dots1\dots11$	1111
$\dots\dots\dots1\dots1\dots\dots\dots\dots$		11
$\ldots \ldots 11.1.1.1\ldots\ldots\ldots$	11.1.1	11.1.1
11111	121.1	121.1
11	11	11
$\dots \dots 1 \dots 1 \dots \dots \dots \dots$	11	11
11.1	21.1	21.1
	11 1	11 1
	11	

The diagram below shows the original image and the final 1–pixel thick skeleton.