MATH 237 - Calculus 3

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Directional Derivative Recall

$$\frac{\partial f}{\partial x} = \lim_{h \to 0} \frac{f(a+h,b) - f(a,b)}{h}$$

rate of change of f in the direction x = a.

Choose a direction $\hat{\boldsymbol{u}} = (u_1, u_2)$

 $(x,y) = (a,b) + s(u_1,u_2)$ similar equation for tangent line

when
$$s = 0 \implies (x, y) = (a, b)$$

Consider distance

$$||\boldsymbol{x} - \boldsymbol{a}|| = ||s(u_1, u_2)|| = |s|||(u_1, u_2)||$$

If we choose ||u|| = 1, then |s| is the distance along this from some (x, y) to (a, b). So, ||u|| = 1 is a convention. If $||u|| \neq 1$, normalize it

$$u = \frac{1}{||u||}u$$

Rate of change of u is

$$\frac{\partial f}{\partial \boldsymbol{u}}(a,b) = \lim_{s \to 0} \frac{f(a+su_1,b+su_2) - f(a,b)}{s}$$

Other ways to write

$$\frac{\partial f}{\partial \boldsymbol{u}}(a,b) = D_{\boldsymbol{u}}f(\boldsymbol{a}) = \frac{d}{ds}f(\boldsymbol{a} + s\boldsymbol{u})\Big|_{s=0}$$

sub for $x = a + su_1, y = b + su_2$ then $f(x, y) = f(a + su_1, b + su_2) = f(a + su)$

2 Quiz

./figures/angle

2.1 Definition (Directional Derivative)

The directional derivative of f(x, y) at a point (a, b) in the direction of a unit vector $\mathbf{u} = (u_1, u_2)$ defined by

$$D_{\mathbf{u}}f(a,b) = \frac{d}{ds}f(a+su_1,b+su_2)\Big|_{s=0}$$

provided the derivative exists.

2.2 Theorem

If f(x,y) is differentiable at (a,b) and $\mathbf{u}=(u_1,u_2)$ is a unit vector, then

$$D_{\mathbf{u}}f(a,b) = \nabla f(a,b) \cdot \mathbf{u}$$

Remark 1. Be careful to check the condition of Theorem before applying it. If f is not differentiable at (a, b), then we must apply the definition of the directional derivative.

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Remark 2. If we choose $\mathbf{u} = \mathbf{i} = (1,0)$ or $\mathbf{u} = \mathbf{j} = (0,1)$, then the directional derivative is equal to the partial derivatives f_x or f_y respectively.

2.3 Theorem

If f(x,y) is differentiable at (a,b), and $\nabla f(a,b) \neq (0,0)$, then the largest value of $D_{\mathbf{u}}f(a,b)$ is $||\nabla f(a,b)||$, and occurs when \mathbf{u} is in the direction of $\nabla f(a,b)$.

2.4 Theorem

If $f(x,y) \in C^1$ in a neighborhood of (a,b) and $\nabla f(a,b) \neq (0,0)$, then $\nabla f(a,b)$ is orthogonal to the level curve f(x,y) = k through (a,b).

2.5 Theorem

If $f(x,y,z) \in C^1$ in a neighborhood of (a,b,c) and $\nabla f(a,b,c) \neq (0,0,0)$, then $\nabla f(a,b,c)$ is orthogonal to the level curve f(x,y,z) = k through (a,b,c).

2.6 Definition (2nd degree Taylor polynomial)

The second degree Taylor polynomial $P_{2,(a,b)}$ of f(x,y) at (a,b) is given by

$$P_{2,(a,b)}(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b) + \frac{1}{2} [f_{xx}(a,b)(x-a)^2 + 2f_{xy}(a,b)(x-a)(y-b) + f_{yy}(a,b)(y-b)^2]$$

2.7 Theorem

If f''(x) exists on [a, x], then there exists a number c between a and x such that

$$f(x) = f(a) + f'(a)(x - a) + R_{1,a}(x)$$

where

$$R_{1,a}(x) = \frac{1}{2}f''(c)(x-a)^2$$

2.8 Theorem (Taylor's Theorem

If $f(x,y) \in C^2$ in some neighborhood N(a,b) of (a,b), then for all $(x,y) \in N(a,b)$ there exists a point (c,d) on the line segment joining (a,b) and (x,y) such that

$$f(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b) + R_{1,(a,b)}(x,y)$$

where

$$R_{1,(a,b)}(x,y) = \frac{1}{2} [f_{xx}(c,d)(x-a)^2 + 2f_{xy}(c,d)(x-a)(y-b) + f_{yy}(c,d)(y-b)^2]$$

Remark 3. Like the one variable case, Taylor's Theorem for f(x,y) is an existence theorem. That is, it only tells us that the point (c,d) exists, but not how to find it.

Remark 4. The most important thing about the error term $R_{1,(a,b)(x,y)}$ is not its explicit form, but rather its dependence on the magnitude of the displacement ||(x,y)(a,b)||. We state the result as a Corollary.

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2.9 Corollary

If $f(x,y) \in C^2$ in some closed neighborhood N(a,b) of (a,b), then there exists a positive constant M such that

$$R_{1,(a,b)}(x,y) \le M||(x,y) - (a,b)||^2$$

for all $(x, y) \in N(a, b)$.

2.10 Taylor's Theorem of order k

If $f(x,y) \in C^{k+1}$ at each point on the line segment joining (a,b) and (x,y), then there exists a point (c,d) on the line segment between (a,b) and (x,y) such that

$$f(x,y) = P_{k,(a,b)}(x,y) + R_{k,(a,b)}(x,y)$$

where

$$R_{k,(a,b)}(x,y) = \frac{1}{(k+1)!} |(x-a)D_1 + (y-b)D_2|^{k+1} f(c,d)$$

2.11 Corollary

If $f(x,y) \in C^k$ in some neighborhood of (a,b) then

$$\lim_{(x,y)\to(a,b)} \frac{|f(x,y) - P_{k,(a,b)}(x,y)|}{||(x,y) - (a,b)||^k} = 0$$

2.12 Corollary

If $f(x,y) \in C^{k+1}$ in some closed neighborhood N(a,b) of (a,b), then there exists a constant M>0 such that

$$|f(x,y) - P_{k,(a,b)}(x,y)| \le M||(x,y) - (a,b)||^{k+1}$$

for all $(x,y) \in N(a,b)$.

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3.1 Definition (Local Maximum and Minimum)

A point (a, b) is a local maximum point for f(x, y) if

$$f(x,y) \le f(a,b)$$

for all (x, y) in some neighborhood of (a, b).

A point (a, b) is a local minimum point for f(x, y) if

$$f(x,y) \ge f(a,b)$$

for all (x, y) in some neighborhood of (a, b).

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3.2 Theorem

Let f(x,y) have continuous partials. If (a,b) is a local maximum or minimum point of f, then

$$\nabla f(a,b) = 0$$

or at least one of f_x , f_y does not exist at (a, b).

Proof. Let (a,b) be a local maximum or minimum point of f. Fix x=a, consider f(a,y)=z (cross section), it has a local maximum/minimum point at $y=b \implies \frac{\partial f}{\partial y}(a,b)=0$ (or DNE) when y=b.

Similarly,
$$\frac{\partial f}{\partial x}(a,b) = 0$$
 (or DNE).

3.3 Definition (Critical Point)

A point (a,b) in the domain of f(x,y) is called a *critical point* of f if $\frac{\partial f}{\partial x}(a,b)=0$ or $\frac{\partial f}{\partial x}(a,b)$ does not exist, and $\frac{\partial f}{\partial y}(a,b)=0$ or $\frac{\partial f}{\partial y}(a,b)$ does not exist.

3.4 Examples

Consider $f(x,y) = \sqrt{x^2 + y^2}$ which is a cone (upper half). (0,0) is a local minimum point.

$$f(x,y) = \sqrt{x^2 + y^2} > 0 = f(0,0)$$

However, $f_x(0,0)$ and $f_y(0,0)$ does not exist.

Consider $g(x,y) = x^2 - y^2$ which is a hyperbolic paraboloid (saddle surface)

$$g_x = 2x$$
$$g_y = 2y$$

So, (0,0) is the only critical point of g, but

$$g(x,0) > g(0,0)$$

 $h(0,y) < h(0,0)$

for all $x, y \in \mathbb{R}$, so (0,0) is neither a local maximum or minimum point. We classify it as a *saddle point*.

To summarize, all critical points are either local maxima, minima or saddle points.

3.5 Example (Finding Critical Points)

Find all critical points of $f(x, y) = xy(1 - x^2 - y^2)$.

$$f_x = y(1 - x^2 - y^2) + xy(-2x) \tag{1}$$

$$=y[(1-x^2-y^2)+x(-2x)]$$
(2)

$$=y(1-x^2-y^2-2x^2) (3)$$

$$=y(1-y^2-3x^2) (4)$$

(5)

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Similarly, we get

$$f_y = x(1 - 3y^2 - x^2) = 0 ag{6}$$

Note that (1) and (6) are both non-linear systems. (6) yields roots y=0 and $y=\pm\sqrt{1-3x^2}$ for roots, split into two cases.

Case 1 y = 0

Substituting into (6) we get $x(1-x^2)=0$, giving x=-1,0,1. Thus, the corresponding critical points are: (-1,0),(0,0),(1,0).

Case 2 $y = \pm \sqrt{1 - 3x^2}$

Substituting into (6) we get $x(8x^2-2)$, giving $x=0,\frac{1}{2},-\frac{1}{2}$. To find the corresponding y values, plug the x values into $y=\pm\sqrt{1-3x^2}$. Thus, the corresponding critical points are: $(0,0),\underbrace{(\frac{1}{2},\frac{1}{2}),(-\frac{1}{2},\frac{1}{2})}_{+\text{ sqrt}},\underbrace{(\frac{1}{2},-\frac{1}{2}),(-\frac{1}{2},-\frac{1}{2})}_{-\text{ sqrt}}$.

We need an analogy to the 2nd derivative test for y = f(x).

 $f'' > 0 \rightarrow \text{local minimum}, f'' < 0 \rightarrow \text{local maximum}$

Consider the Taylor Series for f(x,y) about (a,b) such that $\nabla f(a,b) = (0,0)$

$$f(x,y) - f(a,b) \approx \frac{1}{2} \left[f_{xx}(a,b)(x-a)^2 + 2f_{xy}(a,b)(y-b) + f_{yy}(a,b)(y-b)^2 \right] + \underbrace{\cdots}_{\text{HOT}}$$
(7)

If x is close to a and y is close to b, then the higher order terms can be neglected. So,

$$f(x,y) - f(a,b) \approx \frac{1}{2} \left[f_{xx}(a,b)(x-a)^2 + 2f_{xy}(a,b)(y-b) + f_{yy}(a,b)(y-b)^2 \right]$$
 (8)

3.6 Theorem (Second Partials Derivatives Test)

Suppose $f(x,y) \in C^2$ in some neighborhood of (a,b) and that

$$\nabla f(a,b) = 0$$

- (1) If f(x,y) f(a,b) > 0 (positive definite) for all (x,y) near (a,b), $(x,y) \neq (0,0) \neq (a,b)$ then (a,b) is a local minimum point of f.
- (2) If f(x,y) f(a,b) < 0 (negative definite) for all (x,y) near (a,b), $(x,y) \neq (0,0) \neq (a,b)$ then (a,b) is a local maximum point of f.
- (3) If f(x,y) f(a,b) < 0 for some (x,y) near (a,b) and f(x,y) f(a,b) > 0 for some other (x,y) near (a,b), then (a,b) is a saddle point (indefinite) of f.