STAT 331 - Applied Linear Models

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1 Introduction to Regression Models

LECTURE 1 | 2020-09-08

DEFINITION 1.1: Response variable

A **response** (**dependent**) **variable** is the primary variable of interest, denoted by a capital roman letter *Y*.

DEFINITION 1.2: Explanatory Variable

An **explanatory** (**independent**, **predictor**) **variable** are variables that impact the response, denoted by x_i for i = 1, ..., p.

DEFINITION 1.3: Regression Model

A **regression model** deals with modelling the functional relationship between a response variable and one or more explanatory variables.

EXAMPLE 1.4: Alligators in Florida

Let Y be the length in metres of an alligator and $x_1 := \{0,1\}$ (male or female). The mass in an alligators stomach consists of fish (x_2) , invertebrates (x_3) , reptiles (x_4) , birds (x_5) , and other (x_6,\ldots,x_p) . We imagine we can explain Y in terms of (x_1,\ldots,x_p) using some function such that $Y=f(x_1,\ldots,x_p)$.

In this course, we will be looking at linear models.

DEFINITION 1.5: Linear model

A general linear model is defined as $Y=\beta_0+\beta_1x_1+\cdots+\beta_px_p+\varepsilon$ where Y is the response variable, (x_1,\ldots,x_p) are the p explanatory variables, $(\beta_0,\beta_1,\ldots,\beta_p)$ are the model parameters, and ε is the random error. We assume that (x_1,\ldots,x_p) are fixed constants, β_0 is the intercept of Y, (β_1,\ldots,β_p) all quantify effect on x_i on Y, and $\varepsilon\sim\mathcal{N}(0,\sigma^2)$.

REMARK 1.6

In general, the model will not perfectly explain the data.

"All models are wrong, but some are useful."

$$Y \sim \mathcal{N}(\beta_0 + \beta_1 x_1 + \dots + \beta_p x_p, \sigma^2) \text{ since } \mathbb{E}[Y] = \beta_0 + \beta_1 x_1 + \dots + \beta_p x_p \text{ and } \mathbb{V}(Y) = \mathbb{V}(\varepsilon) = \sigma^2.$$

2 Simple Linear Regression

LECTURE 2 | 2020-09-09

DEFINITION 2.1: Simple linear regression

A **simple linear regression** is a linear model that uses only one explanatory variable; that is, $Y = \beta_0 + \beta_1 x + \varepsilon$. The **data** in a simple linear regression consists of pairs (x_i, y_i) where i = 1, ..., n.

REMARK 2.2

Before fitting any model, we might want to make a scatter plot to visualize if there is a linear relationship between x and y, or calculate the *correlation*.

DEFINITION 2.3: Correlation

The **correlation** of random variables X and Y is $\rho_{XY} = \frac{\mathsf{Cov}(X,Y)}{\mathsf{Sd}(X)\mathsf{Sd}(Y)}$.

DEFINITION 2.4: Sample correlation

The **sample correlation** of all pairs (x_i, y_i) is

$$\begin{split} r &= \frac{\frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x}) (y_i - \bar{y})}{\sqrt{\frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})^2} \sqrt{\frac{1}{n-1} \sum_{i=1}^{n} (y_i - \bar{y})}} \\ &= \frac{\sum_{i=1}^{n} (x_i - \bar{x}) (y_i - \bar{y})}{\sqrt{\sum_{i=1}^{n} (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^{n} (y_i - \bar{y})^2}} \\ &= \frac{S_{xy}}{\sqrt{S_{xx} S_{yy}}} \end{split}$$

REMARK 2.5

The sample correlation measures the strength and direction of the linear relationship between X and Y. Note that $-1 \leqslant r \leqslant 1$. If $|r| \approx 1$, then there is a strong linear relationship, and if $|r| \approx 0$ then there is a lack of linear relationship. Also, if r > 0, then there is a positive relationship, and if r < 0 then there is a negative relationship. It does not tell us how to predict Y from X. To do so, we need to estimate β_0 and β_1 .

DEFINITION 2.6: Simple linear regression model

For data (x_i,y_i) for $i=1,\ldots,n$, the **simple linear regression model** is $Y_i=\beta_0+\beta_1x_i+\varepsilon_i$ with the assumption that $\varepsilon_i\stackrel{\mathrm{iid}}{\sim}\mathcal{N}(0,\sigma^2)$. Therefore, $Y_i\sim\mathcal{N}(\mu_i=\beta_0+\beta_1x_i,\sigma^2)$.

DEFINITION 2.7: Least squares

The method of estimating β_0 and β_1 by minimizing $S(\beta_0,\beta_1)=\sum_{i=1}^n(y_i-(\beta_0+\beta_1x_i))^2$ is referred to as the **method of the least squares**.

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REMARK 2.8

The least squares is equivalent to maximum likelihood estimate when $\varepsilon_i \overset{\text{iid}}{\sim} \mathcal{N}(0, \sigma^2)$.

THEOREM 2.9: Least Square Estimates (LSEs) for SLR

Minimizing $S(\beta_0, \beta_1)$, gives the least square estimates

$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x} \quad \text{and} \quad \hat{\beta}_1 = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2} = \frac{S_{xy}}{S_{xx}}$$

Proof of: 2.9

$$\begin{split} \frac{\partial S}{\partial \beta_0} &= 2 \sum_{i=1}^n \left[y_i - (\beta_0 + \beta_1 x_i) \right] (-1) \text{ and } \frac{\partial S}{\partial \beta_1} = 2 \sum_{i=1}^n \left[y_i - (\beta_0 + \beta_1 x_i) \right] (-x_i). \\ \text{Now,} \\ \frac{dS}{d\beta_0} &:= 0 \iff \sum_{i=1}^n y_i - n\beta_0 - \beta_1 \sum_{i=1}^n x_i = 0 \iff \beta_0 = \bar{y} - \beta_1 \bar{x} \\ \frac{dS}{d\beta_1} &:= 0 \iff \sum_{i=1}^n \left[y_i - \bar{y} + \beta_1 \bar{x} - \beta_1 x_i \right] x_i = 0 \\ \iff \sum_{i=1}^n x_i (y_i - \bar{y}) - \beta_1 \sum_{i=1}^n x_i (x_i - \bar{x}) = 0 \\ \iff \beta_1 &= \frac{\sum_{i=1}^n x_i (y_i - \bar{y})}{\sum_{i=1}^n x_i (x_i - \bar{x})} = \frac{\sum_{i=1}^n (x_i - \bar{x}) (y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2} = \frac{S_{xy}}{S_{xx}} \end{split}$$

REMARK 2.10

We use a hat on the β 's to show that they are estimates.

DEFINITION 2.11: Fitted value, Residual

The expression $\hat{\mu}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$ is called the **fitted value** that corresponds to the i^{th} observation with x_i as the explanatory variable. The difference between y_i and $\hat{\mu}_i$, and $e_i = y_i - \hat{\mu}_i$ is referred to as the **residual**. It is the vertical distance between the observation y_i and the estimated line $\hat{\mu}_i$ evaluated at x_i .

LECTURE 3 | 2020-09-14

For $Y_i \sim \mathcal{N}(\beta_0 + \beta_1 x_i, \sigma^2)$, the equation of fitted line is given by $y = \hat{\beta}_0 + \hat{\beta}_1 x$. Our interpretation of the parameters is as follows.

- $\hat{\beta}_0$ is the estimate of the expected response when x=0 (but not always meaningful if outside range of x_i 's in data)
- $\hat{\beta}_1$ is the estimate of expected change in response for unit increase in x
- σ^2 is the "variability around the line" where $\sigma^2 = \mathbb{V}(\varepsilon_i) = \mathbb{V}(Y_i)$

Q: How should we estimate σ^2 ?

$$\varepsilon_i = Y_i - (\beta_0 + \beta_1 x_i) \quad \text{ and } \quad e_i = y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i)$$

Our intuition tells us to use variability in the residuals to estimate σ^2 , so we use

$$\hat{\sigma}^2 = \frac{\sum_{i=1}^n (e_i - \bar{e})^2}{n-2} = \frac{\sum_{i=1}^n e_i^2}{n-2}$$

where the first term looks like sample variance of e_i 's. The second equality follows since $\bar{e} = \bar{y} - (\hat{\beta}_0 + \hat{\beta}_1 \bar{x}) = 0$ by definition of our β_0 estimate.

DEFINITION 2.12: Residual sum of squares

 $\mathrm{SS}(\mathrm{Res}) = \sum_{i=1}^n (y_i - \hat{\mu}_i)^2 = \sum_{i=1}^n e_i^2$, is known as the **residual (error) sum of squares**.

REMARK 2.13

The n-2 will be looked at in more detail later, but for now it suffices to say that the degrees of freedom is n-2 or equivalently, n- number of parameters estimated. It allows $\hat{\sigma}^2$ to be an unbiased estimator for the true value of σ^2 ; that is, $\mathbb{E}[\hat{\sigma}^2] = \sigma^2$ whenever $\hat{\sigma}^2$ is viewed as a random variable.

THEOREM 2.14: Linear Combination of Independent Normal Random Variables

If $Y_i \sim \mathcal{N}(\mu_i, \sigma^2)$, i = 1, ..., n independently, then

$$\sum_{i=1}^n a_i Y_i \sim N \bigg(\sum_{i=1}^n a_i \mu_i, \sum_{i=1}^n a_i^2 \sigma_i^2 \bigg)$$

Proof of: 2.14

The proof is completed in STAT 330 with moment generating functions.

Viewing $\hat{\beta}_1$ as a random variable:

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (x_i - \bar{x})(Y_i - \bar{Y})}{\sum_{i=1}^n (x_i - \bar{x})^2} = \frac{\sum_{i=1}^n (x_i - \bar{x})Y_i - \bar{Y}\sum_{i=1}^n (x_i - \bar{x})}{\sum_{i=1}^n (x_i - \bar{x})x_i - \bar{x}\sum_{i=1}^n (x_i - \bar{x})} = \frac{\sum_{i=1}^n (x_i - \bar{x})Y_i}{\sum_{i=1}^n (x_i - \bar{x})x_i} = \sum_{i=1}^n a_i Y_i$$

where $a_i = \frac{x_i - \bar{x}}{\sum_{i=1}^n x_i (x_i - \bar{x})}$. Therefore,

$$\mathbb{E}[\hat{\beta}_1] = \sum_{i=1}^n a_i \mathbb{E}[Y_i] = \frac{\sum_{i=1}^n (x_i - \bar{x})(\beta_0 + \beta_1 x_i)}{\sum_{i=1}^n x_i (x_i - \bar{x})} = \frac{\beta_0 \sum_{i=1}^n (x_i - \bar{x}) + \beta_1 \sum_{i=1}^n x_i (x_i - \bar{x})}{\sum_{i=1}^n x_i (x_i - \bar{x})} = \beta_1$$

Now, we calculate the variance of $\hat{\beta}_1$:

$$\mathbb{V}(\hat{\beta}_1) = \sum_{i=1}^n a_i^2 \mathbb{V}(Y_i) = \sigma^2 \frac{\sum_{i=1}^n (x_i - \bar{x})^2}{\left[\sum_{i=1}^n x_i (x_i - \bar{x})\right]^2} = \sigma^2 \frac{\sum_{i=1}^n (x_i - \bar{x})^2}{\left[\sum_{i=1}^n (x_i - \bar{x})^2\right]^2} = \frac{\sigma^2}{S_{xx}}$$

Using our calculations from $\hat{\beta}_1$, and viewing $\hat{\beta}_0$ as a random variable:

$$\mathbb{E}[\hat{\beta}_0] = \mathbb{E}[\bar{Y}] - \bar{x}\mathbb{E}[\hat{\beta}_1] = \mathbb{E}\left[\frac{\sum_{i=1}^n Y_i}{n}\right] - \bar{x}\beta_1 = \frac{\sum_{i=1}^n (\beta_0 + \beta_1 x_i)}{n} - \beta_1 \bar{x} = \beta_0 + \beta_1 \bar{x} - \beta_1 \bar{x} = \beta_0$$

Now, we calculate the variance of $\hat{\beta}_0$:

$$\mathbb{V}(\hat{\beta}_1) = \mathbb{V}(\bar{Y} - \beta_1 \bar{x}) = \mathbb{V}(\bar{Y}) + (-\bar{x}^2)\mathbb{V}(\beta_1) = \mathbb{V}\left(\frac{\sum_{i=1}^n Y_i}{n}\right) + \bar{x}^2\left(\frac{\sigma^2}{S_{xx}}\right) = \frac{n\sigma^2}{n^2} + \frac{\sigma^2 x^2}{S_{xx}}$$

Also, since $\hat{\beta}_1$ and $\hat{\beta}_0$ are linear combination of Normal random variables, they follow a Normal distribution. Therefore, we get the following theorem.

THEOREM 2.15: Distribution of LSEs

The distribution of the least square estimates are given by

$$\hat{\beta}_1 \sim N\left(\beta_1, \frac{\sigma^2}{S_{xx}}\right) \quad \text{ and } \quad \hat{\beta}_0 \sim N\left(\beta_0, \sigma^2\left(\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}\right)\right)$$

Since $\mathbb{E}[\hat{\beta}_1] = \beta_1$, we say $\hat{\beta}_1$ is an unbiased estimator of β_1 . This implies that as $n \to \infty$, the average of the estimates $\hat{\beta}_1$; that is, $\mathbb{E}[\hat{\beta}_1]$ coincides with the true value of β_1 . A similar argument can be made for β_0 .

Then,
$$\frac{\hat{eta}_1 - eta_1}{\sigma/\sqrt{S_{xx}}} \sim \mathcal{N}(0,1)$$
, but σ is unknown, so need to use $\hat{\sigma}$ to get $\frac{\hat{eta}_1 - eta_1}{\hat{\sigma}/\sqrt{S_{xx}}} \sim t(n-2)$.

DEFINITION 2.16: Standard deviation and standard error of $\hat{\beta}_1$

The **standard deviation** of $\hat{\beta}_1$ is defined as $Sd(\hat{\beta}_1) = \sigma/\sqrt{S_{xx}}$. The **estimated** standard deviation of $\hat{\beta}_1$ is also referred to as the **standard error** of the estimate $\hat{\beta}_1$, and we write $Se(\hat{\beta}_1) = \hat{\sigma}/\sqrt{S_{xx}}$.

DEFINITION 2.17: Student *t* **distribution**

Suppose $Z \sim \mathcal{N}(0,1)$ and $U \sim \chi^2(\nu)$, with Z and U independent. Then, $T = Z/\sqrt{U/\nu}$ has a **Student** t distribution with ν degrees of freedom.

THEOREM 2.18

For a simple linear regression model,

$$\frac{\hat{\sigma}^2(n-2)}{\sigma^2} = \frac{SS(Res)}{\sigma^2} \sim \chi^2(n-2)$$

Proof of: 2.18

Too hard for sure.

Using the theorem stated, we justify the fact that replacing σ with $\hat{\sigma}$ gives us a t(n-2) distribution.

$$\frac{\hat{\beta}_1 - \beta_1}{\hat{\sigma}/\sqrt{S_{xx}}} = \frac{\frac{\beta_1 - \beta_1}{\sigma/\sqrt{S_{xx}}}}{\sqrt{\frac{\hat{\sigma}^2(n-2)}{\sigma^2} \left(\frac{1}{n-2}\right)}} = \frac{Z}{\sqrt{U/\nu}} = T \sim t(n-2)$$

where $\frac{\hat{\sigma}^2(n-2)}{\sigma^2}=U$, $\nu=n-2$, and $Z=\frac{\hat{\beta}_1-\beta_1}{\hat{\sigma}/\sqrt{S_{xx}}}$. A $(1-\alpha)$ confidence interval for β_1 is

$$\hat{\beta}_1 \pm c \operatorname{Se}(\hat{\beta}_1)$$

where c is the $1-\frac{\alpha}{2}$ quantile of t(n-2); that is, $P(|T|\leqslant c)=1-\alpha$ or $P(T\leqslant c)=1-\frac{\alpha}{2}$ where $T\sim t(n-2)$.

<u>Hypothesis test</u>: H_0 : $\beta=0$ versus H_A : $\beta_1\neq 0$. If H_0 is true, then $\hat{\beta}_1/\text{Se}(\hat{\beta}_1)\sim t(n-2)$, so calculate the **t statistic** $t=\hat{\beta}_1/\text{Se}(\hat{\beta}_1)$, and reject H_0 at level α if |t|>c where c is $1-\frac{\alpha}{2}$ quantile of t(n-2). Therefore, p-value $=P(|T|\geqslant |t|)=2P(T\geqslant |t|)$.

LECTURE 4 | 2020-09-16

Suppose we want to predict the response y for a new value of x, say $x=x_0$. Then, SLR model says $Y_0 \sim \mathcal{N}(\beta_0+\beta_1x_0,\sigma^2)$ where Y_0 is a random variable for response when $x=x_0$; that is, $\hat{Y}_0=\hat{\beta}_0+\hat{\beta}_1x_0$. The fitted model predicts the value of y to be $\hat{y}_0=\hat{\beta}_0+\hat{\beta}_1x_0$.

Also, $\mathbb{E}[\hat{Y}_0] = \mathbb{E}[\hat{\beta}_0] + x_0 \mathbb{E}[\hat{\beta}_1] = \beta_0 + \beta_1 x_0 = \mathbb{E}[Y_0]$, since $\hat{\beta}_i$ for i = 0, 1 are unbiased. Therefore, we can say that \hat{Y}_0 is an unbiased estimate of the random variable for the mean of Y_0 . For the variance of \hat{Y}_0 we write

$$\begin{split} \hat{Y}_0 &= \hat{\beta}_0 + \hat{\beta}_1 x_0 = \bar{Y} - \hat{\beta}_1 \bar{x} + \hat{\beta}_1 x_0 \\ &= \bar{Y} + \hat{\beta}_1 (x_0 - \bar{x}) \\ &= \sum_{i=1}^n \left[\frac{Y_i}{n} + (x_0 - \bar{x}) \left(\frac{(x_i - \bar{x})(Y_i - \bar{Y})}{S_{xx}} \right) \right] \\ &= \sum_{i=1}^n \left[\frac{Y_i}{n} + (x_0 - \bar{x}) \left(\frac{(x_i - \bar{x})Y_i}{S_{xx}} \right) \right] \\ &= \sum_{i=1}^n \left[\frac{1}{n} + \frac{(x_0 - \bar{x})(x_i - \bar{x})}{S_{xx}} \right] Y_i \\ &= \sum_{i=1}^n a_i Y_i \end{split}$$

where $a_i = \frac{1}{n} + \frac{(x_0 - \bar{x})(x_i - \bar{x})}{S_{xx}}.$ Therefore,

$$\begin{split} \mathbb{V}(Y_0) &= \sum_{i=1}^n \left[\frac{1}{n} + \frac{(x_0 - \bar{x})(x_i - \bar{x})}{S_{xx}} \right]^2 \\ &= \sum_{i=1}^n \left[\frac{1}{n^2} + \frac{2(x_0 - \bar{x})(x_i - \bar{x})}{nS_{xx}} + \frac{(x_0 - \bar{x})^2(x_i - \bar{x})^2}{(S_{xx})^2} \right] \\ &= \sum_{i=1}^n \left[\frac{1}{n^2} \right] + \frac{2(x_0 - \bar{x})}{nS_{xx}} \sum_{i=1}^n (x_i - \bar{x}) + \frac{(x_0 - \bar{x})^2}{(S_{xx})^2} \sum_{i=1}^n (x_i - \bar{x})^2 \\ &= \frac{1}{n} + \frac{2(x_0 - \bar{x})}{S_{xx}} (0) + \frac{(x_0 - \bar{x})^2}{(S_{xx})^2} (S_{xx}) \\ &= \frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{xx}} \end{split}$$

We proved the following theorem.

THEOREM 2.19: Distribution of Prediction

The distribution of the prediction random variable is given by

$$\hat{Y}_0 \sim N \left(\beta_0 + \beta_1 x_0, \sigma^2 \left(\frac{1}{n} + \frac{\left(x_0 - \bar{x}\right)^2}{S_{xx}}\right)\right)$$

DEFINITION 2.20: Prediction error

The random variable for **prediction error** is defined as $Y_0 - \hat{Y}_0$ where Y_0 and \hat{Y}_0 are independent and \hat{Y}_0 is a function of Y_1, \dots, Y_n .

$$\begin{split} \mathbb{E}[Y_0-\hat{Y}_0] &= \mathbb{E}[Y_0] - \mathbb{E}[\hat{Y}_0] = 0 \\ \mathbb{V}(Y_0-\hat{Y}_0) &= \mathbb{V}(Y_0) + (-1)^2 \mathbb{V}(\hat{Y}_0) = \sigma^2 + \sigma^2 \left(\frac{1}{n} + \frac{\left(x_0 - \bar{x}\right)^2}{S_{xx}}\right) \end{split}$$

We proved the following theorem.

THEOREM 2.21: Distribution of Prediction Error

The distribution of the prediction error is given by

$$Y_0 - \hat{Y}_0 \sim N\left(0, \sigma^2\left(1 + \frac{1}{n} + \frac{\left(x_0 - \bar{x}\right)^2}{S_{xx}}\right)\right)$$

Since σ is unknown, we use $\hat{\sigma}$ and get the following:

$$\frac{Y_0 - \hat{Y}_0}{\hat{\sigma} \sqrt{1 + \frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{xx}}}} \sim t(n - 2)$$

Intuition for prediction error composed of 2 terms:

- $\mathbb{V}(Y_0)$: random error of new observation
- $\mathbb{V}(\hat{Y}_0)$ (predictor): estimating β_0 and β_1

Those are 2 sources of uncertainty.

REMARK 2.22

Be careful that the prediction may not make sense if x_0 is outside the range of the x_i 's in the data.

A $(1-\alpha)$ prediction interval for the mean response $y_0=\beta_0+\beta_1x_0$ at x_0 is

$$\hat{y}_0 \pm c\,\hat{\sigma}\sqrt{1 + \frac{1}{n} + \frac{(x_0 - \bar{x})^2}{S_{xx}}}$$

where c is the $1 - \frac{\alpha}{2}$ quantile of t(n-2).

EXAMPLE 2.23: Orange production 2018 in FL

We are given the following information.

- *x*: acres
- y: # boxes of oranges (thousands)
- (x_i, y_i) recorded for each of 25 FL counties
- r = 0.964
- $\bar{x} = 16133$
- $\bar{y} = 1798$
- $\begin{array}{l} \bullet \ \, S_{xx} = 1.245 \times 10^{10} \\ \bullet \ \, S_{xy} = 1.453 \times 10^9 \\ \end{array}$

Now, $\hat{\beta}_1 = S_{xy}/S_{xx} = 0.1167$ has a positive slope, therefore x and y are positively correlated. The expected number of boxes produced is estimated to be about 117 higher per an additional acre.

Computing $\bar{\beta}_0 = \bar{y} - \bar{\beta}_1 \bar{x} = -85.3$, we see that it is not meaningful to interpret, since it is the expected production if there were 0 acres (outside the range of x_i) as no county has x = 0.

Now suppose $SS(Res) = 1.31 \times 10^7$ the residuals are the differences between y_i and the fitted regression

e.
$$\hat{\sigma}^2 = \frac{\sum_{i=1}^n e_i^2}{n-2} = \frac{1.31 \times 10^7}{25-2} = 5.7 \times 10^5$$

$$\bullet \ \operatorname{Se}(\hat{\beta}_1) = \frac{\hat{\sigma}}{\sqrt{S_{xx}}} = 0.00676$$

- To test H_0 : $\beta_1 = 0$, calculate $t = (\hat{\beta}_1 0)/\text{Se}(\hat{\beta}_1) = 0.1167/0.00676 \approx 17.3$, then elect the 0.975 quantile (for demonstration purposes) of t(23) which is 2.07.
- Note that 17.3 is very unlikely to see in t(23).

Since $17.3 \gg 2.07$, we reject H_0 at $\alpha = 0.05$ level, and conclude there's a significant linear relationship between acres and oranges produced.

The 95% confidence interval for β_1 is given by $0.1167 \pm 2.07(0.00676)$, which does not contain 0.

$$p\text{-value} = P(|t_{23}| \geqslant 17.3) = 2P(t_{23} \geqslant 17.3) \approx 1.2 \times 10^{-14}$$

Predict the # of boxes in thousands produced if we had 10000 acres to grow oranges.

$$\hat{\beta}_0 + \hat{\beta}_1 x_0 = -85.3 + (0.1167)(10000) \approx 1082$$

The 95% prediction interval is given by

$$1082 \pm 2.07\sqrt{5.69 \times 10^5} \sqrt{1 + \frac{1}{25} + \frac{(6133)^2}{1.245 \times 10^{10}}} = [-512.0407, 2675.595]$$

REMARK 2.24

We are **not** trying to establish causation.

The example done in R is included in the next page.

```
# Read data from florange.csv and input it into the dat vector.
dat <- read.csv("florange.csv")</pre>
# Done to make the predict function work well.
x <- dat$acres
y <- dat$boxes
# Output the first 6 rows in dat.
head(dat)
##
        county boxes acres
## 1
       Brevard
                   51
                        696
## 2 Charlotte
                  821 13447
## 3
       Collier 2088 29351
## 4
        DeSoto 7688 66365
## 5
        Glades
                 368 5396
## 6
        Hardee 5306 43126
# Draw a scatterplot with x-axis as `acres` and y-axis as `boxes`.
plot(x,y)
                                                                                  0
                                                                           0
                                                                                     0
     2000 4000 6000
                                                            0
                                                                                0
                                            0
                            0
                     0
                           0
                     10000
                                          30000
             0
                                20000
                                                     40000
                                                                50000
                                                                           60000
                                                 Х
# Compute some common variables with common functions.
r <- cor(x,y)
xbar <- mean(x)
ybar <- mean(y)</pre>
cat("r:", r, "xbar:", xbar, "ybar:", ybar)
## r: 0.9635098 xbar: 16132.64 ybar: 1797.56
Therefore, r = 0.9635098, \bar{x} = 16132.64, and \bar{y} = 1797.56.
# Compute some common variables manually.
Sxx \leftarrow sum((x - xbar)^2)
Sxy \leftarrow sum((x - xbar) * (y - ybar))
cat("Sxx: ", Sxx, "Sxy: ", Sxy)
```

Sxx: 12450023404 Sxy: 1453128337

```
Therefore, S_{xx} = 12450023404 = 1.245 \times 10^{10} and S_{xy} = 1453128337 = 1.453 \times 10^{9}.
# R's lm function fits linear models
lm.1 \leftarrow lm(y~x)
summary(lm.1)
##
## Call:
## lm(formula = y \sim x)
## Residuals:
                    1Q
                          Median
##
         Min
                                         3Q
                                   106.46 1677.32
## -2470.81
                 -6.17
                           71.72
##
## Coefficients:
                   Estimate Std. Error t value Pr(>|t|)
##
## (Intercept) -85.391989 186.178031 -0.459
## x
                   0.116717
                               0.006761 17.263 1.16e-14 ***
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 754.4 on 23 degrees of freedom
## Multiple R-squared: 0.9284, Adjusted R-squared: 0.9252
## F-statistic: 298 on 1 and 23 DF, p-value: 1.164e-14
From the summary, we can see that \hat{\beta}_0 = -85.391989, \hat{\beta}_1 = 0.116717, Se(\hat{\beta}_1) = 0.006761, t = 17.263,
p-value = 1.64 \times 10^{-14}, and \hat{\sigma} = 754.4.
# Sum Squared Fitted Values
sum(lm.1$fitted.values^2)
## [1] 250385207
# Sum Squared Residuals
sum(lm.1$residuals^2)
## [1] 13089860
Therefore, SS(Res) = \sum_{i=1}^{n} e_i^2 = 13089860 = 1.31 \times 10^7.
# Manual calculation of sigma^2 estimate
sum(lm.1$residuals^2) / 23
## [1] 569124.3
Therefore, \hat{\sigma}^2 = 69124.3 = 5.7 \times 10^5.
# Manual calculation of sigma estimate
sqrt(sum(lm.1$residuals^2) / 23)
## [1] 754.4033
Therefore, \hat{\sigma} = 754.4.
# t distribution values
qt(0.975,23)
## [1] 2.068658
Therefore, c = 2.07.
```

```
# 95% confidence interval
confint(lm.1)

## 2.5 % 97.5 %

## (Intercept) -470.5305905 299.7466119

## x 0.1027305 0.1307034

# 95% prediction interval with predicted boxes if we had 10000 acres
predict(lm.1, data.frame(x=10000), interval="prediction")

## fit lwr upr
## 1 1081.777 -512.0407 2675.595
```

Q: Is σ the same for all values of y?

A: It appears to not in the sense that the variance appears to be higher with respect to higher acres. Sigma will be smaller when there's less acres. Later, this will be testing equal variance or homoscedastic assumption. Later, when we talk about variable transformations we can consider taking the logarithm.

Q: Are the error terms plausibly independent? In other words, does knowing one e_i (residual) help predict e_j (another residual) for a different county?

A: There's diagnostics for checking this. However, intuitively there could be some common factors at play when two counties are geographically close.

3 Multiple Linear Regression

LECTURE 5 | 2020-09-21

DEFINITION 3.1: Multiple linear regression

A multiple linear regression (MLR) model is defined as

$$Y = \beta_0 + \beta_1 x_1 + \dots + \beta_p x_p + \varepsilon$$

which links a response variable y to several independent explanatory variables x_1, x_2, \dots, x_n .

EXAMPLE 3.2: Rocket MLR

- x_1 : nozzle area (large or small, 0 or 1)
- x_2 : mixture in propellant, ratio oxidized fuel
- *Y*: thrust

Want to develop linear relationship between response y and x_1, x_2 ; that is, we want to develop a linear relationship between thrust and both nozzle area and mixture in propellant.

In multiple linear regression, there are n observations, where each consists of p response variables (y_i) , and p explanatory variables $(x_{i1}, x_{i2}, \dots, x_{ip})$. Then,

$$Y_i \sim N(\underbrace{\beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \dots + \beta_p x_{ip}}_{\mathbb{E}[Y_i] = \mu_i}, \sigma^2)$$

or $Y_i=\mu_i+\varepsilon_i$ where $\varepsilon_i\stackrel{\mathrm{iid}}{\sim}\mathcal{N}(0,\sigma^2).$ We can write in vector/matrix form

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix}_{n \times 1} = \begin{bmatrix} \beta_0 + \beta_1 x_{11} + \dots + \beta_p x_{1p} \\ \beta_0 + \beta_1 x_{21} + \dots + \beta_p x_{2p} \\ \vdots \\ \beta_0 + \beta_1 x_{n1} + \dots + \beta_p x_{np} \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1}$$

Which we can more commonly write as $Y = X\beta + \varepsilon$ where

$$\boldsymbol{Y} = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix}_{n \times 1} \boldsymbol{X} = \begin{bmatrix} 1 & x_{11} & x_{12} & \cdots & x_{1(p-1)} & x_{1p} \\ 1 & x_{21} & x_{22} & \cdots & x_{2(p-1)} & x_{2p} \\ \vdots & & \ddots & & \vdots \\ 1 & x_{(n-1)1} & x_{(n-1)2} & \cdots & x_{(n-1)(p-1)} & x_{(n-1)p} \\ 1 & x_{n1} & x_{n2} & \cdots & x_{n(p-1)} & x_{np} \end{bmatrix}_{n \times (p+1)} \boldsymbol{\beta} = \begin{bmatrix} \beta_0 \\ \vdots \\ \beta_p \end{bmatrix}_{(p+1) \times 1} \boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} 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\varepsilon_1 \\ \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_1 \\ \vdots \\ \varepsilon_n \end{bmatrix}_{n \times 1} \boldsymbol{\xi} =$$

DEFINITION 3.3: Random vector

We call $\mathbf{Y} = (Y_1, Y_2, \dots, Y_n)^{\top}$ a random vector.

DEFINITION 3.4: Mean vector

The **mean vector** of \boldsymbol{Y} is defined as $\mathbb{E}[\boldsymbol{Y}] = (\mathbb{E}[Y_1], \mathbb{E}[Y_2], \dots, \mathbb{E}[Y_n])^{\top}$.

DEFINITION 3.5: Covariance matrix

The **covariance matrix** (or **variance-covariance matrix**) of **Y** is defined as

$$\mathbb{V}(\boldsymbol{Y}) = \begin{bmatrix} \mathbb{V}(Y_1) & \operatorname{Cov}(Y_1,Y_2) & \cdots & \operatorname{Cov}(Y_1,Y_{n-1}) & \operatorname{Cov}(Y_1,Y_n) \\ \operatorname{Cov}(Y_2,Y_1) & \mathbb{V}(Y_2) & \cdots & \operatorname{Cov}(Y_2,Y_{n-1}) & \operatorname{Cov}(Y_2,Y_n) \\ \vdots & \vdots & \ddots & \vdots & & \vdots \\ \operatorname{Cov}(Y_{n-1},Y_1) & \operatorname{Cov}(Y_{n-1},Y_2) & \cdots & \mathbb{V}(Y_{n-1}) & \operatorname{Cov}(Y_{n-1},Y_n) \\ \operatorname{Cov}(Y_n,Y_1) & \operatorname{Cov}(Y_n,Y_2) & \cdots & \operatorname{Cov}(Y_n,Y_{n-1}) & \mathbb{V}(Y_n) \end{bmatrix}_{n \times r}$$

PROPOSITION 3.6: Properties of Covariance Matrix

Let Y be a random vector and $a \in \mathbb{R}^n$, then the covariance matrix has the following properties.

- (1) Symmetric since $Cov(Y_i, Y_i) = Cov(Y_i, Y_i)$; that is $\mathbb{V}(\mathbf{Y})^{\top} = \mathbb{V}(\mathbf{Y})$.
- (2) Positive semi-definite since $\mathbf{a}^{\top} \mathbb{V}(\mathbf{Y}) \mathbf{a} \geqslant 0$ for all $\mathbf{a} \in \mathbb{R}^n$.
- (3) $\mathbb{V}(Y) = \mathbb{E}[(Y \mathbb{E}[Y])(Y \mathbb{E}[Y])^{\top}]$

Proof of: 3.6

Trivial.

PROPOSITION 3.7: Properties of Random Vector

Let a be a $1 \times n$ matrix (row vector) of constants and A be an $n \times n$ matrix of constants, then the random vector has the following properties.

(1)
$$\mathbb{E}[aY] = a\mathbb{E}[Y]$$

(2)
$$\mathbb{E}[A\mathbf{Y}] = A\mathbb{E}[\mathbf{Y}]$$

(3)
$$\mathbb{V}(\boldsymbol{a}\boldsymbol{Y}) = \boldsymbol{a}\mathbb{V}(\boldsymbol{Y})\boldsymbol{a}^{\top}$$

(4)
$$\mathbb{V}(A\mathbf{Y}) = A\mathbb{V}(\mathbf{Y})A^{\top}$$

Proof of: 3.7

We prove property (4) only.

$$\begin{split} \mathbb{V}(A\boldsymbol{Y}) &= \mathbb{E}[(A\boldsymbol{Y} - \mathbb{E}[A\boldsymbol{Y}]) (A\boldsymbol{Y} - \mathbb{E}[A\boldsymbol{Y}])^{\top}] \\ &= \mathbb{E}[(A\boldsymbol{Y} - A\mathbb{E}[\boldsymbol{Y}]) (A\boldsymbol{Y} - A\mathbb{E}[\boldsymbol{Y}])^{\top}] \\ &= \mathbb{E}[A (\boldsymbol{Y} - \mathbb{E}[\boldsymbol{Y}]) (A (\boldsymbol{Y} - \mathbb{E}[\boldsymbol{Y}]))^{\top}] \\ &= \mathbb{E}[A (\boldsymbol{Y} - \mathbb{E}[\boldsymbol{Y}]) (\boldsymbol{Y} - \mathbb{E}[\boldsymbol{Y}])^{\top} A^{\top}] \\ &= A\mathbb{E}[(\boldsymbol{Y} - \mathbb{E}[\boldsymbol{Y}]) (\boldsymbol{Y} - \mathbb{E}[\boldsymbol{Y}])^{\top}] A^{\top} \\ &= A\mathbb{V}(\boldsymbol{Y}) A^{\top} \end{split}$$

EXAMPLE 3.8: Calculations with MLR Varaibles

Let
$$\mathbf{Y} = (Y_1, Y_2, Y_3)^{\top}$$
. Suppose $\mathbb{E}[\mathbf{Y}] = (3, 1, 2)^{\top}$. Let $\mathbb{V}(Y) = \begin{bmatrix} 4 & 1/2 & -2 \\ 1/2 & 1 & 0 \\ -2 & 0 & 3 \end{bmatrix}$ and $\mathbf{a} = (1, -1, 2)$ and $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$. Note that \mathbf{a} is a 1×3 row vector. Compute the following.

and
$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$
. Note that \boldsymbol{a} is a 1×3 row vector. Compute the following.

(i)
$$\mathbb{E}[aY]$$

(ii)
$$V(aY)$$

(iii) $\mathbb{E}[AY]$

(iv)
$$\mathbb{V}(A\mathbf{Y})$$

Solution. We do the first two and leave the rest as an exercise.

(i)
$$\mathbb{E}[aY] = a\mathbb{E}[Y] = \begin{bmatrix} 1 & -1 & 2 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} = 1(3) - 1(1) + 2(2) = 6.$$

(ii)

$$\begin{split} \mathbb{V}(\boldsymbol{a}\boldsymbol{Y}) &= \boldsymbol{a}\mathbb{V}(\boldsymbol{Y})\boldsymbol{a}^{\top} \\ &= \begin{bmatrix} 1 & -1 & 2 \end{bmatrix} \begin{bmatrix} 4 & 1/2 & -2 \\ 1/2 & 1 & 0 \\ -2 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \\ &= \begin{bmatrix} 1 & -1 & 2 \end{bmatrix} \begin{bmatrix} 4(1) + (1/2)(-1) - 2(2) \\ (1/2)(1) + 1(-1) + 0(2) \\ -2(1) + 0(-1) + 3(2) \end{bmatrix} \\ &= \begin{bmatrix} 1 & -1 & 2 \end{bmatrix} \begin{bmatrix} -1/2 \\ -1/2 \\ 4 \end{bmatrix} \\ &= 1(-1/2) - 1(-1/2) + 2(4) \\ &= 8 \end{split}$$

DEFINITION 3.9: Multivariate normal distribution

Let $Y = (Y_1, \dots, Y_n)^{\top}$ be a random vector. We say that $Y \sim \text{MVN}(\mu, \sigma)$; that is, Y follows a **multivariate** normal distribution (MVN) when

$$f(\boldsymbol{y};\boldsymbol{\mu},\boldsymbol{\varSigma}) = \frac{1}{(2\pi)^{n/2}|\boldsymbol{\varSigma}|^{1/2}} \exp\left\{-\frac{1}{2}(\boldsymbol{y}-\boldsymbol{\mu})^{\top}\boldsymbol{\varSigma}^{-1}(\boldsymbol{y}-\boldsymbol{\mu})\right\}$$

where μ is defined as the **mean vector**, and Σ is defined as the **covariance matrix**. Note that Σ^{-1} is the inverse of the covariance matrix and $|\Sigma|$ is the determinant of Σ .

THEOREM 3.10: Properties of Multivariate Normal Distribution

Let $\boldsymbol{Y} = (Y_1, Y_2, \dots, Y_n)^{\top} \sim MVN(\boldsymbol{\mu}, \boldsymbol{\Sigma})$. (1) Any subset of Y_1, Y_2, \dots, Y_n also has a multivariate normal distribution and in particular

$$Y_i \sim \mathcal{N}(\mu_i, \Sigma_{ii})$$
 $i = 1, 2, \dots, n$

(2) Let $\mathbf{a} = (a_1, a_2, \dots, a_n)$ be a non-zero row vector $(1 \times n)$ of constants, then

$$aY \sim \mathcal{N}(a\mu, a\Sigma a^{\top})$$

(3) Let A be an $n \times n$ matrix of rank n, then

$$AY \sim MVN(A\mu, A\Sigma A^{\top})$$

- (4) The conditional distribution of any subset of (Y_1, Y_2, \dots, Y_n) given any other coordinates that are not in the subset is a multivariate normal distribution.
- (5) Y_i and Y_j are independent random variables if and only if $\Sigma_{ij} = \text{Cov}(Y_i, Y_j) = 0$.

LECTURE 6 | 2020-09-23

Recall that last lecture, for multiple linear regression, we have $Y = XB + \varepsilon$ with the assumption that $\varepsilon \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \sigma^2)$. Therefore, for a random vector ε , we have

$$\boldsymbol{\varepsilon} \sim \text{MVN} \left(\begin{bmatrix} \boldsymbol{0} \\ \boldsymbol{0} \\ \vdots \\ \boldsymbol{0} \\ \boldsymbol{0} \end{bmatrix}, \begin{bmatrix} \boldsymbol{\sigma}^2 & \boldsymbol{0} & \cdots & \boldsymbol{0} & \boldsymbol{0} \\ \boldsymbol{0} & \boldsymbol{\sigma}^2 & \cdots & \boldsymbol{0} & \boldsymbol{0} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \boldsymbol{0} & \boldsymbol{0} & \cdots & \boldsymbol{\sigma}^2 & \boldsymbol{0} \\ \boldsymbol{0} & \boldsymbol{0} & \cdots & \boldsymbol{0} & \boldsymbol{\sigma}^2 \end{bmatrix} \right) = \text{MVN}(\boldsymbol{0}_{n\times 1}, \boldsymbol{\sigma}^2 \boldsymbol{I}_{n\times n})$$

since $Cov(\varepsilon_1, \varepsilon_2) = 0$ due to independence.

Thus, $\boldsymbol{Y} \sim \text{MVN}(X\boldsymbol{B}, \sigma^2 I)$.

DEFINITION 3.11: Least squares for MLR

We define the least squares for a multiple linear regression model as

$$S(\beta_0,\beta_1,\ldots,\beta_p) = \sum_{i=1}^n (y_i - (\underline{\beta_0 + \beta_1 x_{i1} + \cdots + \beta_p x_{ip}}))^2$$

THEOREM 3.12: Least Square Estimates (LSEs) for MLR

Minimizing $S(\beta_0, \beta_1, \dots, \beta_p)$, gives the least squares estimate $\hat{\beta} = (X^T X)^{-1} X^T y$.

Proof of: 3.12

The first partial is $\frac{\partial S}{\partial \beta_0} = \sum_{i=1}^n 2(y_i - \mu_u)(-1)$, and all other partials for $j=1,\dots,p$ are

$$\frac{\partial S}{\partial \beta_j} = \sum_{i=1}^n 2(y_i - \mu_i)(-x_{ij})$$

Set $\frac{\partial S}{\partial \beta_0}=0$ and $\frac{\partial S}{\partial \beta_j}=0$ for $j=1,\ldots,p$ to get

$$\begin{cases} \sum_{i=1}^n (y_i - \mu_i) = 0 \iff \mathbf{1}^\top (\boldsymbol{y} - \boldsymbol{\mu}) = 0 \\ \sum_{i=1}^n (y_i - \mu_i) x_{ij} = 0 \iff \boldsymbol{x}_j^\top (\boldsymbol{y} - \boldsymbol{\mu}) = 0 \quad j = 1, \dots, p \end{cases}$$

since we recall that

$$X = \begin{bmatrix} 1 & x_{11} & \cdots & x_{1(p-1)} & x_{1p} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & x_{n1} & \cdots & x_{n(n-1)} & x_{np} \end{bmatrix} = \begin{bmatrix} \mathbf{1} & \mathbf{x}_1 & \cdots & \mathbf{x}_{p-1} & \mathbf{x}_p \end{bmatrix}$$

Therefore,

$$X^{\top}(\boldsymbol{y} - X\boldsymbol{\beta}) = 0 \iff X^{\top}\boldsymbol{y} - X^{\top}X\boldsymbol{\beta} = 0 \iff X^{\top}X\boldsymbol{\beta} = X^{\top}\boldsymbol{y} \iff \boldsymbol{\beta} = (X^{\top}X)^{-1}X^{\top}\boldsymbol{y}$$

assuming $X^{\top}X$ is invertible; that is, $\operatorname{rank}(X^{\top}X) = p+1$. So, the LS solution for $\boldsymbol{\beta}$ is given by $\hat{\boldsymbol{\beta}} = (X^{\top}X)^{-1}X^{\top}\boldsymbol{y}$.

DEFINITION 3.13: Residuals for MLR

The residuals for a multiple linear regression model is defined as

$$e_i = y_i - (\underline{\hat{\beta}_0 + \hat{\beta}_1 x_{i1} + \cdots \hat{\beta}_p x_{ip}})$$
 fitted value μ_i

or equivalently, $\hat{\mu} = X\hat{B}$ and $e = y - \hat{\mu}$.

The estimate σ^2 based on e_i 's is

$$\hat{\sigma}^2 = \frac{\text{SS}(\text{Res})}{n - (p + 1)} = \frac{\sum_{i=1}^n e_i^2}{n - p - 1} = \frac{e^\top e}{n - p - 1}$$

since d.f. is n - (number of estimated parameters). When viewed as a random variable,

$$\frac{(n-p-1)\hat{\sigma}^2}{\sigma^2} \sim \chi^2(n-p-1)$$

Inference for $\hat{\pmb{\beta}} = (\hat{\beta}_0, \dots, \hat{\beta}_p)^\top = (X^\top X)^{-1} X^\top \pmb{Y}.$

Note that $\hat{\beta}$ is a matrix of constants and Y is a random vector, and $Y \sim \text{MVN}(X\beta, \sigma^2 I)$, so

$$\begin{split} \mathbb{E}[\hat{\boldsymbol{\beta}}] &= \mathbb{E}[(X^{\top}X)^{-1}X^{\top}\boldsymbol{Y}] \\ &= (X^{\top}X)^{-1}X^{\top}\mathbb{E}[\boldsymbol{Y}] \\ &= (X^{\top}X)^{-1}(X^{\top}X)\boldsymbol{\beta} \\ &= \boldsymbol{\beta} \end{split}$$

That is, $\mathbb{E}[\hat{\beta}_0], \dots, \mathbb{E}[\hat{\beta}_p] = \beta_p$ all unbiased.

$$\begin{split} \mathbb{V}((X^\top X)^{-1}X^\top \boldsymbol{Y}) &= (X^\top X)^{-1}X^\top \mathbb{V}(\boldsymbol{Y}) \left[(X^\top X)^{-1}X^\top \right]^\top \\ &= (X^\top X)^{-1}X^\top \sigma^2 I(X^\top)^\top \left[(X^\top X)^{-1} \right]^\top \\ &= \sigma^2 (X^\top X)^{-1} (X^\top X) (X^\top X)^{-1} \end{split} \qquad X^\top X \text{ symmetric}$$

Since $\hat{\beta}$ is a linear transformation of Y we have $\hat{\beta} \sim \text{MVN}(\beta, \sigma^2 \underbrace{(X^\top X)^{-1}}_V)$. We proved the following theorem.

THEOREM 3.14: Distribution of $\hat{\beta}_i$

The distribution of a given $\hat{\beta}_i$ is

$$\hat{\beta}_j \sim \mathcal{N}(\beta_j, \sigma^2 V_{jj}) \qquad j = 0, 1, \dots, p$$

$$Z = \frac{\hat{\beta}_j - \beta_j}{\sigma \sqrt{V_{ij}}} \sim \mathcal{N}(0,1) \quad \text{ and } \quad T = \frac{\hat{\beta}_j - \beta_j}{\hat{\sigma} \sqrt{V_{ij}}} \sim t(n-p-1) \qquad j = 0,1,\dots,p$$

DEFINITION 3.15: Standard error for \hat{eta}_j

We define the **standard error** of $\hat{\beta}_j$ as

$$\mathrm{Se}(\hat{\beta}_j) = \hat{\sigma} \sqrt{V_{jj}} \qquad j = 0, 1, \dots, p$$

So, a $(1 - \alpha)$ confidence interval for β_i is

$$\hat{\beta}_i \pm c \mathsf{Se}(\hat{\beta}_i)$$

where c is $(1 - (\alpha/2))$ quantile of t(n - p - 1).

To test H_0 : $\beta_j = 0$ vs H_A : $\beta_j \neq 0$, calculate t-statistic $t = \frac{\beta_j}{\mathsf{Se}(\hat{\beta}_i)}$ reject at level α if |t| > c and p-value is $2P(T \geqslant |t|)$ where $T \sim t(n-p-1)$.

Interpretation of $\hat{\beta}$: fitted linear regression model says $\widehat{\mathbb{E}[Y]}$ (estimate of the expected response) is

$$\hat{\beta}_0 + \hat{\beta}_1 x_1 + \dots + \hat{\beta}_p x_p$$

- $\hat{\beta}_0$ is the estimate of expected response when all explanatory variables are equal to 0.
- $\hat{\beta}_i$ is the estimated change in expected response for a unit increase in x_i when holding all other explanatory variables constant.

$$\hat{\beta}_0+\hat{\beta}_1(x_1+1)+\cdots+\hat{\beta}_px_p-(\hat{\beta}_0+\hat{\beta}_1x_1+\cdots+\hat{\beta}_px_p)=\hat{\beta}_1$$

REMARK 3.16

When it's written V_{jj} , that means the $j+1^{th}$ column and $j+1^{th}$ row since we start from index 0 for these matrices. Some unfortunate events may have happened on the quiz to me due to this.

EXAMPLE 3.17: Rocket MLR

Let $n=12,\,\hat{\pmb{\beta}}=(473.6,16.7,-1.09)^{\top}=(\hat{\beta}_0,\hat{\beta}_1,\hat{\beta}_2)^{\top}.$ • x_1 : nozzle area (1=L,0=S)

- x_2 : propellant ratio
- Y: thrust

$$\hat{\sigma} = \sqrt{\frac{\sum_{i=1}^{12} e_i^2}{12 - 1 - 2}} = \sqrt{\frac{e^\top e}{9}} = 2.655$$

Interpretation of β :

- $\hat{\beta}_1$ estimated change in expected thrust is 16.7 when changing small to large nozzle while holding other variables (propellant ratio) constant.
- $\hat{\beta}_2$ estimated thrust to decrease by 1.09 on average for a unit increase in propellant ratio while holding other variables (nozzle area) constant.

Given $Se(\hat{\beta}_2) = 0.94$, we compute the t-statistic for H_0 : $\beta_2 = 0$ vs H_A : $\beta_2 \neq 0$ which is t = -1.09/0.94 = 0.94

$$p\text{-value} = 2P(T \geqslant 1.16) = 0.275$$
 from R where $T \sim t(9)$

Do not reject H_0 (e.g. $\alpha = 0.05$), therefore propellant ratio does not significantly influence thrust.

Lecture 7 2020-09-28

Recall that $Y = X\beta + \varepsilon \sim \text{MVN}(X\beta, \sigma^2 I)$, and

- Estimates: $\hat{\boldsymbol{\beta}} = (X^{\top}X)^{-1}X^{\top}\boldsymbol{Y}$
- Fitted values: $\hat{\boldsymbol{u}} = X\hat{\boldsymbol{\beta}}$
- Residuals: $e = y \hat{\mu}$

- Constants: $X = \begin{bmatrix} \mathbf{1} & \mathbf{x}_1 & \cdots & \mathbf{x}_p \end{bmatrix}_{n \times (p+1)}$
- Values of responses: $\mathbf{y} = (y_1, y_2, \dots, y_n)^{\top} \in \mathbb{R}^n$

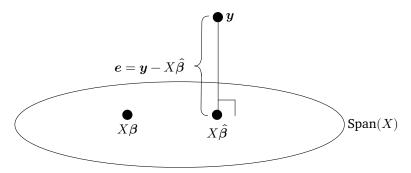
Author's Note: Geometric interpretation of data is omitted in these notes because I'm simply too lazy.

The span of X is $\mathrm{Span}(X)=\{b_0\mathbf{1}+b_1\boldsymbol{x}_1+\cdots+b_p\boldsymbol{x}_p:b_0,\ldots,b_p\in\mathbb{R}\}\subset\mathbb{R}^n$ which is all linear combinations of columns of X which is a subspace of \mathbb{R}^n , and by assumption we know $\mathrm{rank}(X)=p+1$.

We can say Span(X) represents all possible vector values Xb where $\mathbf{b} = (b_0, b_1, \dots, b_p)^{\mathsf{T}}$.

Generally, $y \notin \text{Span}(X)$, so since the linear model is an approximation, ε variability not explained by model.

Intuitively, it makes sense to choose an estimate $\hat{\beta}$ so that $X\hat{\beta}$ is as close to y as possible.



Therefore, e must be orthogonal to Span $(X) \iff e$ is orthogonal to all columns of X.

$$\mathbf{1}^{\top}(\boldsymbol{y} - \hat{\boldsymbol{\mu}}) = 0$$
$$\boldsymbol{x}_{1}^{\top}(\boldsymbol{y} - \hat{\boldsymbol{\mu}}) = 0$$
$$\vdots$$
$$\boldsymbol{x}_{p}^{\top}(\boldsymbol{y} - \hat{\boldsymbol{\mu}}) = 0$$

which is the same as LS estimates. We also know $\hat{\mu} = X\hat{\beta}$ and $e = y - \hat{\mu}$.

DEFINITION 3.18: Hat matrix

The **hat matrix** is defined as $H = X(X^{T}X)^{-1}X^{T}$.

PROPOSITION 3.19: Properties of Hat Matrix

Let H be a hat matrix, then H has the following properties.

- (1) H is symmetric; that is, $H = H^{\top}$.
- (2) H is idempotent; that is, $H^2 = HH = H$.
- (3) I-H is symmetric idempotent; that is, $(I-H)^2 = (I-H)(I-H) = I-H$.

Proof of: 3.19

We prove all three because it's easy.

- (1) $H^{\top} = [X(X^{\top}X)^{-1}X^{\top}]^{\top} = X(X^{\top}X)^{-1}X^{\top} = H.$
- (2) $HH = X(X^{T}X)^{-1}(X^{T}X)(X^{T}X)^{-1}X^{T} = H$.
- (3) (I-H)(I-H) = I(I-H) H(I-H) = II IH HI + HH = I 2H + HH = I 2H + H = I H.

Let's view $\hat{\mu}$ and e as random vectors

$$\hat{\boldsymbol{\mu}} = X\hat{\boldsymbol{\beta}} = X(X^{\top}X)^{-1}X^{\top}\boldsymbol{Y} = H\boldsymbol{Y}$$

$$\begin{split} \boldsymbol{e} &= \boldsymbol{Y} - \hat{\boldsymbol{\mu}} = I\boldsymbol{Y} - H\boldsymbol{Y} = (I - H)\boldsymbol{Y} \\ \mathbb{E}[\hat{\boldsymbol{\mu}}] &= \mathbb{E}[H\boldsymbol{Y}] = H\mathbb{E}[\boldsymbol{Y}] = X(X^{\top}X)^{-1}X^{\top}\underbrace{X\boldsymbol{\beta}}_{\mathbb{E}[\boldsymbol{Y}]} = X\boldsymbol{\beta} \\ \mathbb{V}(\hat{\boldsymbol{\mu}}) &= \mathbb{V}(H\boldsymbol{Y}) = H\mathbb{V}(\boldsymbol{Y})H^{\top} = H\sigma^{2}IH^{\top} = \sigma^{2}(HH^{\top}) = \sigma^{2}H \\ \mathbb{E}[\boldsymbol{e}] &= \mathbb{E}[(I - H)\boldsymbol{Y}] = \mathbb{E}[\boldsymbol{Y}] - \mathbb{E}[H\boldsymbol{Y}] = X\boldsymbol{\beta} - X\boldsymbol{\beta} = 0 \\ \mathbb{V}(\boldsymbol{e}) &= (I - H)\mathbb{V}(\boldsymbol{Y})(I - H)^{\top} = \sigma^{2}(I - H)(I - H)^{\top} = \sigma^{2}(I - H) \end{split}$$

So since $\hat{\mu}$ and e are linear transformations of Y we have proved the following theorem.

THEOREM 3.20: Distribution of $\hat{\mu}$ and e

 $\hat{\mu}$ and \hat{e} have the following distribution.

$$\hat{\pmb{\mu}} \sim \mathit{MVN}(X\pmb{\beta}, \sigma^2 H)$$

$$\hat{e} \sim MVN(0, \sigma^2(I-H))$$

Suppose we want to predict response for x_0 where the first 1 represents the intercept in the row vector.

$$\boldsymbol{x}_0 = \begin{bmatrix} 1 & x_{01} & x_{02} & \cdots & x_{0p} \end{bmatrix}_{1 \times (p+1)}$$

Let Y_0 random variable representing the response associated with x_0 . In multiple linear regression,

$$Y_0 \sim \mathcal{N}(\beta_0 + \beta_1 x_{01} + \dots + \beta_p x_{0p}, \sigma^2)$$

So we predict the value

$$\hat{y}_0 = \hat{\beta}_0 + \hat{\beta}_1 x_{01} + \dots + \hat{\beta}_p x_{0p} = x_0 \hat{\beta}$$

which represents the estimated mean response given $x_{01}, x_{02}, \dots, x_{0p}$. Corresponding distribution has

$$\mathbb{E}[\hat{Y}_0] = \boldsymbol{x}_0 \mathbb{E}[\hat{\boldsymbol{\beta}}] = \boldsymbol{x}_0 \boldsymbol{\beta} = \mathbb{E}[Y_0]$$

$$\mathbb{V}(\hat{Y}_0) = \boldsymbol{x}_0 \mathbb{V}(\hat{\boldsymbol{\beta}}) \boldsymbol{x}_0^\top = \boldsymbol{x}_0 \sigma^2 (\boldsymbol{X}^\top \boldsymbol{X})^{-1} \boldsymbol{x}_0^\top$$

We have proved the following theorem.

THEOREM 3.21: Distribution of Predictor

The distribution of \hat{Y}_0 which is a function of Y_1, \dots, Y_n is

$$\hat{Y}_0 \sim \mathcal{N}(\boldsymbol{x}_0\boldsymbol{\beta}, \sigma^2\boldsymbol{x}_0(X^\top X)^{-1}\boldsymbol{x}_0^\top)$$

$$\begin{split} \frac{\hat{Y}_0 - \boldsymbol{x}_0 \boldsymbol{\beta}}{\sigma \sqrt{\boldsymbol{x}_0 (X^\top X)^{-1} \boldsymbol{x}_0^\top}} &\sim \mathcal{N}(0, 1) \\ \frac{\hat{Y}_0 - \boldsymbol{x}_0 \boldsymbol{\beta}}{\hat{\sigma} \sqrt{\boldsymbol{x}_0 (X^\top X)^{-1} \boldsymbol{x}_0^\top}} &\sim t (n - (p + 1)) = t (n - p - 1) \end{split}$$

A $(1-\alpha)$ confidence interval for the mean response $y_0={m x}_0\hat{m \beta}$ given ${m x}_0$ is

$$\hat{y}_0 \pm c \hat{\sigma} \sqrt{\boldsymbol{x}_0 (X^\top X)^{-1} \boldsymbol{x}_0^\top}$$

where c is the $1 - \alpha/2$ quantile of t(n - p - 1).

Prediction error: $Y_0 - \hat{Y}_0$ which are independent since Y_0 is a random variable with variance σ^2 and \hat{Y}_0 is a function of Y_1,\dots,Y_n . Therefore,

$$\begin{split} \mathbb{E}[Y_0 - \hat{Y}_0] &= \boldsymbol{x}_0 \boldsymbol{\beta} - \boldsymbol{x}_0 \boldsymbol{\beta} = 0 \\ \mathbb{V}(Y_0 - \hat{Y}_0) &= \mathbb{V}(Y_0) + (-1)^2 \mathbb{V}(\hat{Y}_0) = \sigma^2 + \sigma^2 (\boldsymbol{x}_0 (\boldsymbol{X}^\top \boldsymbol{X})^{-1} \boldsymbol{x}_0^\top) \end{split}$$

We have proved the following theorem.

THEOREM 3.22: Distribution of Prediction Error

The distribution of the prediction error is

$$Y_0 - \hat{Y}_0 \sim N(0, \sigma^2(1 + \pmb{x}_0(X^\top X)^{-1} \pmb{x}_0^\top)).$$

A $(1-\alpha)$ prediction interval for the mean response $y_0=\pmb{x}_0\hat{\pmb{\beta}}$ given \pmb{x}_0 is

$$\hat{y}_0 \pm c \hat{\sigma} \sqrt{1 + \boldsymbol{x}_0 (X^\top X)^{-1} \boldsymbol{x}_0^\top}$$

where c is the $1 - \alpha/2$ quantile of t(n - p - 1).

REMARK 3.23

Our intuition tells us that the prediction interval is wider than the confidence interval for mean. In other words, estimating an average is "easier" than an individual response.

LECTURE 8 | 2020-09-30

The example done in R is included in the next page.

```
## NASA rocket data example

## From: R.S. Jankovsky, T.D. Smith, A.J. Pavli (1999). "High-Area-Ratio Rocket

## Nozzle at High Combustion Chamber Pressure-Experimental and Analytical

## Validation".

# setwd(...) first if your CSV file is somewhere else

rocket <- read.csv(file="rocket.csv")

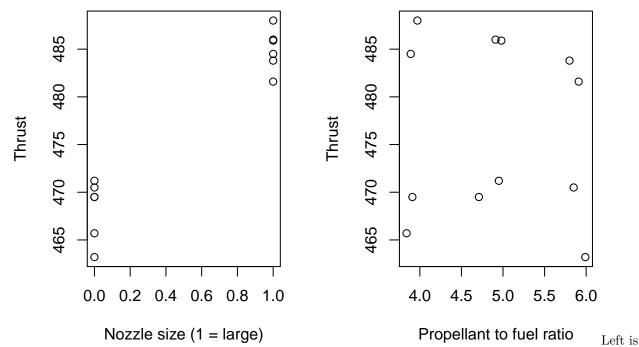
# output all data in rocket vector

rocket</pre>
```

```
##
      thrust nozzle propratio
## 1
       488.0
                    1
                            3.97
## 2
       481.6
                            5.91
                    1
## 3
       485.9
                            4.98
                    1
## 4
       486.0
                    1
                            4.91
## 5
       484.5
                    1
                            3.89
## 6
                            5.80
       483.8
                    1
## 7
       463.2
                    0
                            5.99
## 8
       471.2
                    0
                            4.95
## 9
       469.5
                    0
                            3.91
## 10
       470.5
                    0
                            5.85
                            4.71
## 11
       469.5
                    0
## 12
       465.7
                            3.84
```

Y (thrust) is the response variable, and there are two explanatory variables x_1, x_2 (nozzle, propratio) where nozzle is coded as 1 if it's large.

```
# Scatter plots where mfrow is used to put multiple
# plots on one image
par(mfrow = c(1,2))
plot(rocket$nozzle, rocket$thrust, ylab="Thrust", xlab="Nozzle size (1 = large)")
plot(rocket$propratio, rocket$thrust, ylab="Thrust", xlab="Propellant to fuel ratio")
```



nozzle size vs thrust. Right is propellant relationship vs thrust.

```
# Fit MLR using lm
m1 <- lm(thrust ~ nozzle + propratio, data = rocket)</pre>
summary(m1)
##
## Call:
## lm(formula = thrust ~ nozzle + propratio, data = rocket)
## Residuals:
                 10 Median
##
       Min
                                   3Q
                                          Max
## -3.8459 -1.7555 0.5934 1.2906 3.3008
## Coefficients:
                Estimate Std. Error t value Pr(>|t|)
##
## (Intercept) 473.6039
                              4.7158 100.430 4.88e-15 ***
## nozzle
                 16.7383
                              1.5329 10.919 1.71e-06 ***
## propratio
                 -1.0948
                              0.9414 - 1.163
                                                  0.275
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 2.655 on 9 degrees of freedom
## Multiple R-squared: 0.9303, Adjusted R-squared: 0.9148
## F-statistic: 60.05 on 2 and 9 DF, p-value: 6.238e-06
On the left it's Y (response variable) and on the right it's x_1, x_2 (explanatory variables). From summary, we
get the estimate vector \hat{\beta} = (473.6039, 16.7383, -1.0948)^{\top}.
# Manual beta estimates where rep is used to make the columns of 1s
X <- cbind(rep(1, 12), rocket$nozzle, rocket$propratio) # X matrix</pre>
y <- matrix(rocket$thrust, ncol = 1) # response vector
beta_hat <- solve(t(X) %*% X) %*% t(X) %*% y
beta_hat
##
               [,1]
## [1,] 473.603924
## [2,] 16.738319
## [3,] -1.094822
solve is used for the inverse. ** is used for matrix-matrix multiplication, and t(X) is used for transposing
# Manual sigma estimate
mu_hat <- X %*% beta_hat # fitted values</pre>
e <- y - mu_hat # residuals
sigma_hat \leftarrow sqrt((t(e) \%*\% e) / 9) # Note n-p-1 = 12-2-1 = 9
sigma_hat
##
           [,1]
## [1,] 2.6545
sigma_hat <- sqrt( sum(e^2) / 9) # equivalent</pre>
sigma_hat
## [1] 2.6545
   • \hat{\boldsymbol{\mu}} = X\hat{\boldsymbol{\beta}}
```

```
• e = y - \hat{\mu}
  • \hat{\sigma} = \sqrt{\left(\sum_{i=1}^{n} e_i^2\right)/9} = 2.6545, or
   • \hat{\sigma} = \sqrt{(e^{\top}e)/9} = 2.6545
# Covariance matrix of beta_hat
vcov(m1)
##
                 (Intercept)
                                  nozzle propratio
## (Intercept)
                   22.238325 -1.02316688 -4.32080608
                   -1.023167 2.34987593 -0.03102117
## nozzle
## propratio
                   -4.320806 -0.03102117 0.88631920
sqrt(diag(vcov(m1))) # SEs of individual betas
## (Intercept)
                       nozzle
                                 propratio
##
    4.7157528 1.5329305 0.9414453
# Manual
se_beta <- sigma_hat * sqrt(diag(solve(t(X) %*% X)))</pre>
se_beta
## [1] 4.7157528 1.5329305 0.9414453
   • Se(\hat{\beta}) = \hat{\sigma}\sqrt{(X^{\top}X)^{-1}} = (4.71, 1.53, 0.94)^{\top}
# Estimate the mean response for units with small nozzle and propellant ratio 5.5
# include a 95% CI
predict(object = m1, newdata = data.frame(nozzle = 0, propratio = 5.5),
         interval = "confidence", level = 0.95)
           fit
                     lwr
                                upr
## 1 467.5824 464.7929 470.3719
Therefore, \hat{y}_0 = 467.58. The 95% confidence interval for the mean response given x_0 is [464.7929, 470.3719].
# Manual calculation
x0 \leftarrow matrix(c(1, 0, 5.5), nrow = 1)
y0_hat <- x0 %*% beta_hat
y0_hat
##
## [1,] 467.5824
# mu0 is also known as \hat{Y} 0
se_mu0 <- sigma_hat * sqrt(x0 %*% solve(t(X) %*% X) %*% t(x0))
se_mu0
##
              [,1]
## [1,] 1.233132
crit val \leftarrow qt(0.975,9)
ci_lo <- y0_hat - crit_val*se_mu0
ci_hi <- y0_hat + crit_val*se_mu0
c(y0_hat, ci_lo, ci_hi)
## [1] 467.5824 464.7929 470.3719
   • x_0 = \begin{bmatrix} 1 & 0 & 5.5 \end{bmatrix}
```

```
• \hat{y}_0 = x_0 \hat{\beta} = 467.5824
```

•
$$Se(\hat{Y}_0) = \hat{\sigma} \sqrt{x_0 (X^\top X)^{-1} x_0^\top} = 1.233132$$

Therefore, $\hat{y}_0 = 467.58$. The 95% confidence interval for the mean response given x_0 is [464.7929, 470.3719].

```
## fit lwr upr
## 1 467.5824 460.9612 474.2036
```

[,1]

##

Therefore, $y_0 = 467.5824$. The 95% prediction interval for the response (y_0) given \mathbf{x}_0 is [460.9612474.2036].

```
# Manual calculation for an individual
x0 <- matrix(c(1, 0, 5.5), nrow = 1)
y0_hat <- x0 %*% beta_hat
se_y0 <- sigma_hat * sqrt(1+ x0 %*% solve(t(X) %*% X) %*% t(x0))
se_y0</pre>
```

```
## [1,] 2.926941

crit_val <- qt(0.975,9)
pi_lo <- y0_hat - crit_val*se_y0
pi_hi <- y0_hat + crit_val*se_y0
c(y0_hat, pi_lo, pi_hi)</pre>
```

[1] 467.5824 460.9612 474.2036

```
• Se(Y_0 - \hat{Y}_0) = \hat{\sigma}\sqrt{1 + x_0(X^\top X)^{-1}x_0^\top} = 2.926941
```

Handling categorical variables: when there are explanatory variables with values that fall into one of several categories.

- e.g. nozzle large/small, if just binary, code as 1 and 0
- ordered small, medium, large or not red, blue, green

Approach: can convert to indicator variables or treat as numerical if it makes sense to do so.

Example: Coffee Quality Institute (2018)

Extract a few variables:

	Acidity	Method
1	8.7	Washed-wet
2	8.3	Washed-wet
3	8.2	Natural-dry
4	8.4	Semi-washed/pulped

Flavour (response)

How to set up X? For example,

$$x_{i2} = \begin{cases} 0 & \text{dry} \\ 1 & \text{semi} \\ 2 & \text{wet} \end{cases}$$

Not generally appropriate unless we think a response is linear according to this scheme.

More flexible approach: indicator/dummy variables

$$x_{i2} = \begin{cases} 1 & \text{semi} \\ 0 & \text{otherwise} \end{cases}, \quad x_{i3} = \begin{cases} 1 & \text{wet} \\ 0 & \text{otherwise} \end{cases}$$

Therefore,

$$X = \begin{bmatrix} 1 & 8.7 & 0 & 1 \\ 1 & 8.3 & 0 & 1 \\ 1 & 8.2 & 0 & 0 \\ 1 & 8.4 & 1 & 0 \end{bmatrix}$$

Why not $x_{i4} = \begin{cases} 1 & \text{dry} \\ 0 & \text{otherwise} \end{cases}$? If we did that, we would have

$$X = \begin{bmatrix} 1 & 8.7 & 0 & 1 & 0 \\ 1 & 8.3 & 0 & 1 & 0 \\ 1 & 8.2 & 0 & 0 & 1 \\ 1 & 8.4 & 1 & 0 & 0 \end{bmatrix}$$

This has linearly dependent columns since $x_4 = 1 - x_2 - x_3$. There is no new information and X would not have full rank.

Model:
$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \beta_3 x_{i3} + \varepsilon_i$$
.

Interpretation:

- Mean flavour if acidity = x_{01} and method dry is $\beta_0 + \beta_1 x_{01}$.
- Mean flavour if acidity = x_{01} and method wet is $\beta_0 + \beta_1 x_{01} + \beta_3$.
- Mean flavour if acidity = x_{01} and method semi is $\beta_0 + \beta_1 x_{01} + \beta_2$.

- β_2 is the difference between semi and dry in expected response (holding acidity constant)
- β_3 is the difference between wet and dry in expected response (holding acidity constant)
- $\beta_2 \beta_3$ is the difference between semi and wet (holding other variables constant)

 $\hat{\boldsymbol{\beta}} \sim \text{MVN}(\boldsymbol{\beta}, \sigma^2 V) \text{ where } V = (X^{\top} X)^{-1}.$

- We know $\hat{\beta}_j \sim \mathcal{N}(\beta_j, \sigma^2 V_{jj})$ with $\mathsf{Se}(\hat{\beta}_j) = \hat{\sigma} \sqrt{V_{jj}}$ where $j = 0, \dots, p$.
- What about $\beta_2 \beta_3$?

$$\mathbb{V}(\hat{\beta}_2-\hat{\beta}_3)=\mathbb{V}(\hat{\beta}_2)-\mathbb{V}(\hat{\beta}_3)-2\mathsf{Cov}(\hat{\beta}_2,\hat{\beta}_3)=\sigma^2V_{22}+\sigma^2V_{33}-2\sigma^2V_{23}$$

Therefore,

$$\mathsf{Se}(\hat{\beta}_2 - \hat{\beta}_3) = \hat{\sigma} \sqrt{V_{22} + V_{33} - 2V_{23}}$$

Now, we can construct a CI for $\beta_2 - \beta_3$.

In general, for an explanatory variable with k categories. We need k-1 indicator variables.

LECTURE 9 | 2020-10-05

Analysis of variance (ANOVA): how well does our regression model fit our response variable? Variability in response can be measured by "total sum of squares:"

$$\mathrm{SS}(\mathrm{Total}) = \sum_{i=1}^n (y_i - \bar{y})^2$$

as seen in A1, it's closely related to sample variance of y_1, \dots, y_n , which is SS(Total)/(n-1).

ANOVA decomposes SS(Total) = SS(Reg) + SS(Res) where SS(Reg) is the regression sum of squares and SS(Res) is the residual sum of squares.

The regression sum of squares is variation explained by the model and the residual sum of squares is the variation not explained by the regression model.

Using the fact that

$$y_i - \bar{y} = y_i - \hat{\mu}_i + \hat{\mu}_i - \bar{y}$$

When regression fits data well, the observations y_i tend to be much closer to $\hat{\mu}_i$. Note that \bar{y} is line a regression line with $\beta_1 = 0$.

Mathematically,

$$\underbrace{\sum_{i=1}^n (y_i - \bar{y})^2}_{\text{SS(Total)}} = \underbrace{\sum_{i=1}^n (\hat{\mu}_i - \bar{y})^2}_{\text{SS(Reg)}} + \underbrace{\sum_{i=1}^n (y_i - \hat{\mu}_i)^2}_{\text{SS(Res)}}$$

since we showed that $\sum_{i=1}^n (\hat{\mu}_i - \bar{y}) \underbrace{(y_i - \hat{\mu}_i)}_{e_i} = 0$ in A1 for SLR. It's also true for multiple linear regression

since

$$\sum_{i=1}^n (\hat{\mu}_i - \bar{y}) e_i = \sum_{i=1}^n (e_i \hat{\mu}_i) - \bar{y} \sum_{i=1}^n e_i = \hat{\boldsymbol{\mu}}^\top \boldsymbol{e} - \bar{y} \mathbf{1}^\top \boldsymbol{e} = 0$$

Recall: $\mathbf{1}^{\top}e=0$ is one of LS equations, and $\hat{\boldsymbol{\mu}}=X\hat{\boldsymbol{\beta}}$ is in $\mathrm{Span}(X)$, so e is orthogonal to $\mathrm{Span}(X)$, so $\hat{\boldsymbol{\mu}}^{\top}e=0$.

F is used to test the overall significance of regression (later).

We call the **coefficient of determination** $R^2 = SS(Reg)/SS(Total) = 1 - SS(Res)/SS(Total)$. Clearly, $0 \le R^2 \le 1$. It is the proportion of variation (in our response variable) that is explained by the regression model.

Table 1: ANOVA Table

Source	d.f.	SS	Mean Square	F
Regression Residual	$p \\ n-p-1$	$\begin{array}{c} SS(Reg) \\ SS(Res) \end{array}$	$\frac{\mathrm{SS}(\mathrm{Reg})/p}{\mathrm{SS}(\mathrm{Res})/(n\!-\!p\!-\!1)} = \hat{\sigma}^2$	MS(Reg)/MS(Res)
Total	n-1	SS(Total)		

Larger \mathbb{R}^2 means the fitted values are closer to the observations y_i , which means the residuals are small; that is, smaller SS(Res). Note that (A1) in SLR, R^2 is equivalent to the square of the sample correlation between x and y based on $(x_1, y_1), \dots, (x_n, y_n)$.

Table 2: Rocket ANOVA Table

Source	d.f.	SS	Mean Square	F
Regression Residual	2 9	846.2 63.42	$423.1 \\ 7.05$	60
Total	11	909.62		

Response thrust $R^2 = 846.2/909.62 \approx 0.93$. R^2 interpretation: regression model with nozzle size and propellant ratio explains 93% of variation in thrust (response).

Lecture 10 2020-10-07

Hypothesis testing based on F distribution

So far we've tested H_0 : $\beta_i = 0$ vs H_A : $\beta_i \neq 0$ involving individual parameters, using t distribution.

Now consider hypothesis test of the form H_0 : $A\beta = 0$ where A is a matrix of constraints specifying linear combinations of parameters.

EXAMPLE 3.24: Coffee Continued

The full model is:

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \beta_3 x_{i3} + \varepsilon_i$$

- Y_i is the flavour
- x_{i1} is acidity
- x_{i2} is 1 if semi, and 0 otherwise.
- x_{i3} is 1 if wet, and 0 otherwise.

Example 1.

- H_0 : $\beta_1=\beta_2=\beta_3=0$ versus

- H_A: at least one of β₁, β₂, β₃ not 0.
 If H₀ is true, the model reduces to Y_i = β₀ + ε_i.
 This tests overall significance of regression (whether any of predictors impact response)
- $A=\begin{bmatrix}0&1&0&0\\0&0&1&0\\0&0&0&1\end{bmatrix}$. Note that row i considers the constraint of $\beta_i=0$ for i=1,2,3 in this example.

Example 2.

- H_0 : $\beta_2 = \beta_3 = 0$
- If H_0 is true, $Y_i = \beta_0 + \beta_1 x_{i1} + \varepsilon_i$
- Q: Is reduced model with only acidity plausible?

•
$$A = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$
. Note that $A\beta = \mathbf{0}_{1 \times 2}$

Example 3.

- H_0 : $\beta_2 \beta_3 = 0$ H_A : $\beta_2 \neq \beta_3$ $Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 (x_{i2} + x_{i3}) + \varepsilon_i$ where $(x_{i2} + x_{i3})$ is 1 if semi/wet and 0 if dry.
- Do the wet and semi methods have the same impact on the response (holding acidity constant)?
- $A = \begin{bmatrix} 0 & 0 & 1 & -1 \end{bmatrix}$

In general, with ℓ constraints. A is an $\ell \times (p+1)$ matrix with rank ℓ . Recall that

$$\mathrm{Span}(X) = \{\beta_0 \mathbf{1} + \beta_1 \boldsymbol{x}_1 + \dots + \beta_p \boldsymbol{x}_p\}$$

Let

$$Span(X)_A = \{\beta_0 \mathbf{1} + \beta_1 \mathbf{x}_1 + \dots + \beta_p \mathbf{x}_p : A\boldsymbol{\beta} = 0\}$$

which is a subspace of Span(X) since any vector in Span(X)_A is also in Span(X). We call Span(X)_A the Span(X) with constraint A on β .

Let $\hat{\mu}_A$ denote the fitted values from fitting the reduced model. The residual if we hit the model with $A\beta = 0$ is $\boldsymbol{e}_A = \boldsymbol{y} - \hat{\boldsymbol{\mu}}_A$.

If H_0 : $A\beta = 0$ is true, then $\hat{\mu}$ and $\hat{\mu}_A$ should be close; that is, the model makes similar predictions whether we set $A\beta = 0$ or not when fitting the model.

So to assess whether H_0 is plausible, look at $\|\hat{\boldsymbol{\mu}} - \hat{\boldsymbol{\mu}}_A\|$ where $\|\cdot\|$ is Euclidean or L_2 norm. That is,

$$\|\hat{\boldsymbol{\mu}} - \hat{\boldsymbol{\mu}}_A\| = \sqrt{(\hat{\boldsymbol{\mu}} - \hat{\boldsymbol{\mu}}_A)^\top (\hat{\boldsymbol{\mu}} - \hat{\boldsymbol{\mu}}_A)}$$

If it's "large" or "small" (close to 0) where large gives evidence against H_0 and small gives evidence for H_0 .

By Pythagoras,

$$\|\boldsymbol{y} - \hat{\boldsymbol{\mu}}_A\|^2 = \|\boldsymbol{y} - \hat{\boldsymbol{\mu}}\|^2 + \|\hat{\boldsymbol{\mu}} - \hat{\boldsymbol{\mu}}_A\|^2 \quad \text{ or } \quad \|\boldsymbol{e}_A\|^2 = \|\boldsymbol{e}\|^2 + \|\hat{\boldsymbol{\mu}} - \hat{\boldsymbol{\mu}}_A\|^2$$

or equivalently $e_A^\top e_A = e^\top e + \|\hat{\mu} - \hat{\mu}_A\|^2$ where $e_A^\top e_A$ is the sum of squares residual in the reduced model and $e^\top e$ is the sum of squares residual in the full model.

We define $e_A^{\top} e_A = SS(Res)_A$ and $e^{\top} e = SS(Res)$.

Thus, $\|\hat{\boldsymbol{\mu}} - \hat{\boldsymbol{\mu}}_A\|^2 = \mathrm{SS}(\mathrm{Res})_A - \mathrm{SS}(\mathrm{Res}) \geqslant 0$ additional sum of squares explained by full model vs reduced one with constraints A.

Practical implications:

- SS(Res) cannot decrease when constraints applied.
- Equivalently, full model always has small (or equal) SS(Res) for a fixed SS(Tot) and thus higher R^2 compared to a reduced model.

Define test statistic:

$$F = \frac{(\mathsf{SS}(\mathsf{Res})_A - \mathsf{SS}(\mathsf{Res}))/\ell}{\mathsf{SS}(\mathsf{Res})/(n-p-1)} = \frac{(\mathsf{SS}(\mathsf{Res})_A - \mathsf{SS}(\mathsf{Res}))/\ell}{\hat{\sigma}^2}$$

DEFINITION 3.25: F distribtion

If $U \sim \chi^2(a)$ and $V \sim \chi^2(b)$ are independent. We say F follows an F **distribution** if

$$F = \frac{U/a}{V/b}$$

and write $F \sim F(a, b)$.

Here, we have these facts when H_0 is true

$$\begin{split} V &= \frac{\hat{\sigma}^2(n-p-1)}{\sigma^2} \sim \chi^2(n-p-1) \\ U &= \frac{\|\hat{\pmb{\mu}} - \hat{\pmb{\mu}}_A\|^2}{\sigma^2} \sim \chi^2(\ell) \end{split}$$

where U and V are independent. Therefore,

$$F = \frac{\frac{\|\hat{\boldsymbol{\mu}} - \hat{\boldsymbol{\mu}}_A\|^2}{\sigma^2} \left(\frac{1}{\ell}\right)}{\frac{\hat{\sigma}^2(n-p-1)}{\sigma^2} \left(\frac{1}{n-p-1}\right)} \sim F(\ell, n-p-1)$$

when H_0 is true. Reject H_0 : $A\beta = \mathbf{0}$ at level α if F is greater than $(1 - \alpha)$ quantile of $F(\ell, n - p - 1)$ and p-value is $P(Y \geqslant F)$ where $Y \sim F(\ell, n - p - 1)$.

Relation to T distribution: Say $Y \sim t(a)$

$$Y = \frac{Z}{\sqrt{U/a}}$$

where $Z \sim \mathcal{N}(0,1)$ and $U \sim \chi^2(a)$ are independent. Squaring everything,

$$Y^2 = \frac{Z^2}{U/a}$$

and we know $Z^2 \sim \chi^2(1)$. Therefore, $Y^2 \sim F(1,a)$ (we divide by 1 in the numerator).

Thus, if our hypothesis test has one constraint, then F test is equal to t test of same hypothesis; for example, H_0 : $\beta_1 = 0$ versus H_A : $\beta_1 \neq 0$.

LECTURE 11 | 2020-10-19

Recall the general linear hypothesis: H_0 : $A\beta = 0$ vs H_A : $A\beta \neq 0$ where A gives ℓ constraints.

$$F \text{ statistic} = \frac{(\text{SS}(\text{Res})_A - \text{SS}(\text{Res}))/\ell}{\text{SS}(\text{Res})/(n-p-1)} = \frac{(\text{SS}(\text{Res})_A - \text{SS}(\text{Res}))/\ell}{\hat{\sigma}^2}$$

compare to $F(\ell, n-p-1)$.

Special case: overall test of significance

"Are any predictors related to response?"

- H_0 : $\beta_1 = \beta_2 = \dots = \beta_p = 0$
- H_A : $\beta_i \neq 0$ for at least one j

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & \cdots & 0 & 0 \\ 0 & 0 & 1 & 0 & \cdots & 0 & 0 \\ \vdots & & & \ddots & & & \\ 0 & 0 & 0 & 0 & \cdots & 1 & 0 \\ 0 & 0 & 0 & 0 & \cdots & 0 & 1 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_{p-1} \\ \beta_n \end{bmatrix}$$

If H_0 is true: $Y_i = \beta_0 + \varepsilon_i$ where $Y_i \sim \mathcal{N}(\beta_0, \sigma^2)$.

Fit reduced model; that is, in this case estimate β_0 using the least squares, minimize $\sum_{i=1}^n (y_i - \beta_0)^2$, which can be shown $\hat{\beta}_0 = \bar{y}$. So,

$$\mathrm{SS}(\mathrm{Res})_A = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - \hat{\mu}_i)^2 = \sum_{i=1}^n (y_i - \bar{y})^2 = \mathrm{SS}(\mathrm{Total})$$

Then,

$$F = \frac{(\mathsf{SS}(\mathsf{Total}) - \mathsf{SS}(\mathsf{Res}))/p}{\mathsf{SS}(\mathsf{Res})/(n-p-1)} = \frac{\mathsf{SS}(\mathsf{Reg})/p}{\mathsf{SS}(\mathsf{Res})/(n-p-1)} = \frac{\mathsf{MS}(\mathsf{Reg})}{\mathsf{MS}(\mathsf{Res})} \leftarrow F \text{ statistic on ANOVA table}$$

LECTURE 12 | 2020-10-21

Multicollinearity: occurs when some explanatory variables have a **strong linear** relationship amongst themselves. For example, this might occur exactly

$$\boldsymbol{x}_3 = \alpha_0 \boldsymbol{1} + \alpha_1 \boldsymbol{x}_1 + \alpha_2 \boldsymbol{x}_2$$

in which case the columns of X would be **linearly dependent** and $X^{\top}X$ does not have an inverse. Practically, there is no new info including x_3 when x_1, x_2 are in the model. **Approximately**,

$$\boldsymbol{x}_3 \approx \alpha_0 \boldsymbol{1} + \alpha_1 \boldsymbol{x}_1 + \alpha_2 \boldsymbol{x}_2$$

in which case the columns of X are close to being linearly dependent which cases $\mathbb{V}(\hat{\beta}_j)$ to be **inflated**, in turn leads to inaccurate confidence intervals and conclusions of hypothesis tests for the regression parameters, in practice. $\mathsf{Se}(\hat{\beta}_j)$ when fitting models can change drastically when adding/removing variables from the model.

EXAMPLE 3.26: Hockey (NHL)

In the NHL we have Goals + Assists = Points. Suppose we want to predict a forward's salary. Define

- $x_1 = \text{Goals}$
- $x_2 = Assists$
- $x_3 = Points$

 $x_3 = x_1 + x_2$, therefore we have exact multicollinearity.

EXAMPLE 3.27: Burmese Pythons in Florida (2017)

- y =fat content
- $x_1 = \text{mass}$
- $x_2 = \text{overall length}$
- $x_3 = \text{snout-to-vent length}$

It turns out that x_2 and x_3 are highly correlated. Including all variables in regression lead to inflated $Se(\hat{\beta}_2)$ and $Se(\hat{\beta}_3)$.

3.1 Detection of Multicollinearity

If two predictors are related

- Scatter plot matrix [all possible pairs of scatter plots b/w y, x_1, x_2, \dots, x_p]
- Correlation matrix (all pairwise correlations)

DEFINITION 3.28: Variance inflation factor

For multicollinearity between more than two predictors, we can define the **variance inflation factor** (VIF).

$$\mathrm{VIF}_j = \frac{\mathbb{V}(\hat{\beta}_j)}{\mathbb{V}(\hat{\beta}_j^*)}$$

for $j=1,\ldots,p$, where $\hat{\beta}_j$ is the estimate of β_j with all predictors in the model, and $\hat{\beta}_j^*$ estimate of β_j based on regression with x_j only.

THEOREM 3.29

$$VIF_j \geqslant 1$$

Fit multiple linear regression model of x_i in terms of other predictors; that is,

$$x_{ij} = \alpha_0 + \alpha_1 x_{i1} + \dots + \alpha_{j-1} x_{i(j-1)} + \alpha_{j+1} x_{i(j+1)} + \dots + \alpha_p x_{ip} + \varepsilon_{ij}$$

and compute R^2 for this model, call it R_i^2 .

Intuition: if R_j^2 is close to 1, x_j is strongly related linearly to other predictors. It can be shown that

$$\mathrm{VIF}_j = \frac{1}{1-R_j^2}$$

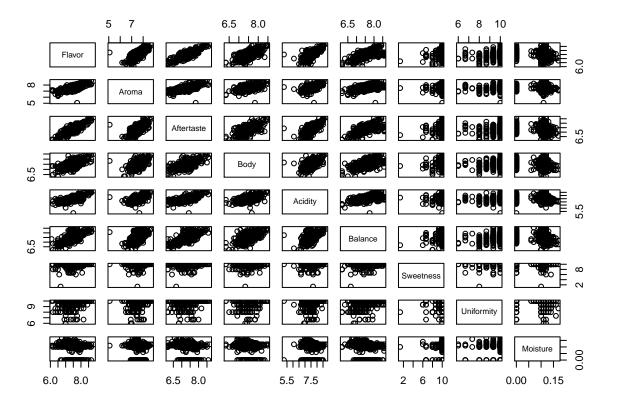
If ${\rm VIF}_j \geq 10$, then there is solid evidence of multicollinearity; that is, $R_j^2 > 0.9$.

Procedure:

• remove predictors with largest VIF, if it exceeds 10. Repeat until no more multicollinearity.

```
## Coffee example (Coffee Quality Institute, 2018) continued
coffee <- read.csv("coffee_arabica.csv")</pre>
# cor(coffee) # doesn't work as there's a categorical variable
cor(coffee[,-1]) # e.g., remove first column
##
                   Aroma
                            Flavor Aftertaste
                                                    Body
                                                             Acidity
                                                                        Balance
## Aroma
             1.00000000 0.7339782 0.6892744 0.56699932 0.60115765 0.6156508
## Flavor
              0.73397820 1.0000000 0.8582783 0.67694834 0.73845546 0.7324530
## Aftertaste 0.68927440 0.8582783 1.0000000 0.67407704 0.69408861 0.7657979
## Body
             0.56699932 0.6769483 0.6740770 1.00000000 0.60795391 0.6924568
## Acidity 0.60115765 0.7384555 0.6940886 0.60795391 1.00000000 0.6417994
## Balance 0.61565084 0.7324530 0.7657979 0.69245676 0.64179938 1.0000000
## Sweetness 0.06955938 0.1345364 0.1185760 0.03977892 0.06906093 0.1016718
## Uniformity 0.14785498 0.2132347 0.2143116 0.07195778 0.14876428 0.2180726
## Moisture -0.11567549 -0.1327342 -0.1745366 -0.21009097 -0.10391684 -0.2161964
##
             Sweetness Uniformity
                                     Moisture
## Aroma
             0.06955938 0.14785498 -0.11567549
## Flavor
             0.13453644 0.21323472 -0.13273418
## Aftertaste 0.11857600 0.21431157 -0.17453658
## Body
             0.03977892 0.07195778 -0.21009097
## Acidity
             0.06906093 0.14876428 -0.10391684
## Balance
             0.10167183 0.21807265 -0.21619640
## Sweetness 1.00000000 0.34756414 0.08049300
## Uniformity 0.34756414 1.00000000 0.02105693
## Moisture 0.08049300 0.02105693 1.00000000
# pairs without response: pairs(coffee[,-1])
# pairs with response, this is what we want
pairs(~ Flavor + Aroma + Aftertaste + Body +
```

Acidity + Balance + Sweetness + Uniformity + Moisture, data=coffee)



Model:

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \beta_3 x_{i3} + \beta_4 x_{i4} + \beta_5 x_{i5} + \beta_6 x_{i6} + \beta_7 x_{i7} + \beta_8 x_{i8} + \beta_9 x_{i9} + \beta_{10} x_{i(10)} + \varepsilon_i$$

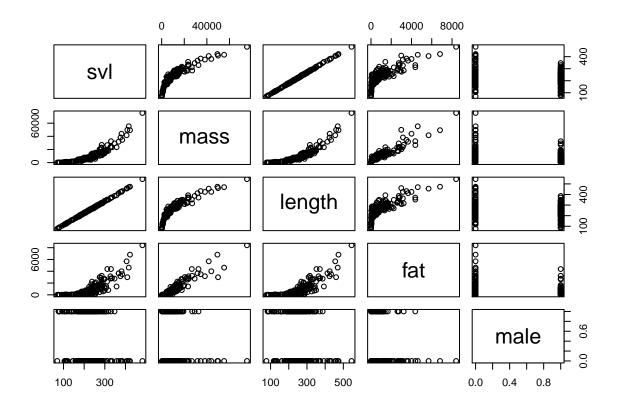
where

- y = flavour
- $x_1 = 1$ if wet, 0 otherwise
- $x_2 = 1$ if semi, 0 otherwise
- $x_3 = \text{Aroma}$
- $x_4 = Aftertaste$
- $x_5 = \text{Body}$
- $x_6 = Acidity$
- $x_7 = Balance$
- $x_8 = \text{Sweetness}$
- $x_9 = \text{Uniformity}$

• $x_{10} = Moisture$ # Full MLR with our own coded indicators mfull <- lm(Flavor~ wet + semi + Aroma + Aftertaste + Body + Acidity + Balance + Sweetness + Uniformity + Moisture, dat=coffee) summary(mfull) ## ## Call: ## lm(formula = Flavor ~ wet + semi + Aroma + Aftertaste + Body + ## Acidity + Balance + Sweetness + Uniformity + Moisture, data = coffee) ## ## Residuals: Min 1Q Median 3Q ## -0.68587 -0.08465 0.00079 0.08910 0.63633 ## Coefficients: Estimate Std. Error t value Pr(>|t|) ## (Intercept) -0.728757 0.168516 -4.325 1.67e-05 *** ## wet -0.033061 0.011024 -2.999 0.00277 ** ## semi ## Aroma 0.468759 ## Aftertaste 0.023912 19.603 < 2e-16 *** ## Body 0.096140 0.024334 3.951 8.28e-05 *** ## Acidity 0.216751 0.021194 10.227 < 2e-16 *** 0.046806 0.022558 2.075 0.03823 * ## Balance ## Sweetness 0.025507 0.010150 2.513 0.01211 * ## Uniformity 0.016297 0.009803 1.663 0.09669 . ## Moisture 0.169012 0.102480 1.649 0.09938 . ## ---## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1 ## Residual standard error: 0.148 on 1108 degrees of freedom ## Multiple R-squared: 0.8091, Adjusted R-squared: 0.8073 ## F-statistic: 469.5 on 10 and 1108 DF, p-value: < 2.2e-16# Full MLR alternative, using factor command mfull_alternative <- lm(Flavor~ factor(Processing.Method) + Aroma + Aftertaste + Body + Acidity + Balance + Sweetness + Uniformity + Moisture, dat=coffee) Suppose we want to check the VIF for j = 1; that is, x_1 . Now, we fit: $x_{i1} = \alpha_0 + \alpha_2 x_{i2} + \alpha_3 x_{i3} + \alpha_4 x_{i4} + \alpha_5 x_{i5} + \alpha_6 x_{i6} + \alpha_7 x_{i7} + \alpha_8 x_{i8} + \alpha_9 x_{i9} + \alpha_{10} x_{i(10)} + \varepsilon_i$ wet_reg <- lm(wet ~ semi + Aroma + Aftertaste + Body + Acidity + Balance + Sweetness + Uniformity + Moisture,dat=coffee) summary(wet_reg) ## ## Call: ## lm(formula = wet ~ semi + Aroma + Aftertaste + Body + Acidity + Balance + Sweetness + Uniformity + Moisture, data = coffee) ## ## Residuals: ## Min 1Q Median 3Q Max ## -1.0015 -0.0283 0.1770 0.2522 0.7704

```
##
## Coefficients:
##
               Estimate Std. Error t value Pr(>|t|)
## (Intercept) 0.81748 0.45838
                                     1.783 0.074794
## semi
               -0.75675
                          0.05551 -13.632 < 2e-16 ***
                                     1.742 0.081774 .
## Aroma
                0.09690 0.05562
                            0.06502 -2.026 0.043054 *
## Aftertaste -0.13169
               -0.21885
                            0.06596 -3.318 0.000936 ***
## Body
## Acidity
               0.18696
                            0.05746
                                      3.254 0.001173 **
## Balance
               -0.10804
                            0.06136 -1.761 0.078563 .
## Sweetness
              0.08373
                            0.02753
                                     3.041 0.002413 **
## Uniformity 0.03547
                                      1.329 0.184053
                            0.02668
## Moisture
                0.59486
                            0.27858
                                     2.135 0.032956 *
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.4031 on 1109 degrees of freedom
## Multiple R-squared: 0.1911, Adjusted R-squared: 0.1845
## F-statistic: 29.11 on 9 and 1109 DF, p-value: < 2.2e-16
r2_wet <- summary(wet_reg)$r.squared
r2_wet
## [1] 0.191077
R_i: In our case, R_1 = 0.191077.
VIF_wet <- 1 / (1 - r2_wet)</pre>
VIF_wet
## [1] 1.236212
VIF j: VIF<sub>1</sub> = 1.236212. Interpretation: in a regression with all the variables compared to a regression with
just this one, the estimated variance has increased by a factor of 1.24, which is not a very large inflation. The
variable wet is not very linearly correlated or dependent on the other predictors that we have in the model.
Aroma_reg <- lm(Aroma ~ wet + semi + Aftertaste +
      Body + Acidity + Balance + Sweetness + Uniformity + Moisture, dat=coffee)
r2_Aroma <- summary(Aroma_reg)$r.squared
r2_Aroma
## [1] 0.5204716
VIF_Aroma <- 1 / (1 - r2_Aroma)</pre>
VIF_Aroma
## [1] 2.085382
R_3 = 0.5204716, VIF<sub>3</sub> = 2.085382.
Aftertaste_reg <- lm(Aftertaste ~ wet + semi + Aroma +
       Body + Acidity + Balance + Sweetness + Uniformity + Moisture, dat=coffee)
r2_Aftertaste <- summary(Aftertaste_reg)$r.squared
r2_Aftertaste
## [1] 0.7101012
VIF_Aftertaste <- 1 / (1 - r2_Aftertaste)</pre>
VIF Aftertaste
```

```
## [1] 3.449479
library(car)
## Loading required package: carData
vif(mfull) # VIF function in the "car" library
##
          wet.
                    semi
                              Aroma Aftertaste
                                                      Body
                                                              Acidity
                                                                         Balance
                                                  2.317728
                                                                        3.002813
##
     1.236212
                1.178004
                           2.085382
                                      3.449479
                                                             2.232210
   Sweetness Uniformity
                           Moisture
     1.159602
                1.209901
                           1.086101
No serious signs of inflation, all VIFs are less than 10.
## Python in FL everglades example (2017)
## Sex, length, total mass, fat mass, and specimen condition data for
## 248 Burmese pythons (Python bivittatus) collected in the Florida Everglades
python <- read.csv("FLpython.csv")</pre>
head(python)
    sex svl mass length
## 1 F 70.0 186
                     77.5 6.000
## 2
      M 76.0 310
                     83.8 11.000
## 3
       M 77.0 260
                     86.1 6.000
## 4
      M 78.0 262
                     87.1 8.000
                     91.1 4.000
       M 81.0 306
## 5
      M 93.5 605 104.6 18.959
python$male <- ifelse(python$sex == 'M', 1, 0) # 1 = M, 0 =F
cor(python[,-1])
##
                                    length
                                                             male
                 svl
                           mass
                                                   fat
           1.0000000 0.8843022 0.9994935 0.8098652 -0.1602418
## svl
           0.8843022 \quad 1.0000000 \quad 0.8858256 \quad 0.9419114 \quad -0.2190993
## mass
## length 0.9994935 0.8858256 1.0000000 0.8114658 -0.1593512
## fat
           0.8098652 0.9419114 0.8114658 1.0000000 -0.2933111
        -0.1602418 -0.2190993 -0.1593512 -0.2933111 1.0000000
pairs(python[,-1])
```



```
mpf <- lm(fat ~ male + svl + mass + length, data = python)
summary(mpf)</pre>
```

```
##
## Call:
## lm(formula = fat ~ male + svl + mass + length, data = python)
##
## Residuals:
                      Median
                                           Max
       Min
                 1Q
                                   3Q
                              110.00 1527.27
## -2445.77 -137.41
                       -5.29
##
## Coefficients:
                Estimate Std. Error t value Pr(>|t|)
## (Intercept) 2.021e+02 1.331e+02
                                      1.518
                                              0.130
              -1.971e+02 4.732e+01 -4.165 4.32e-05 ***
## svl
              -3.370e+00 1.125e+01 -0.300
                                              0.765
## mass
               1.178e-01 5.302e-03 22.210
                                           < 2e-16 ***
               1.594e+00 1.010e+01
                                              0.875
## length
                                     0.158
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 360.9 on 243 degrees of freedom
## Multiple R-squared: 0.897, Adjusted R-squared: 0.8953
## F-statistic: 529 on 4 and 243 DF, p-value: < 2.2e-16
```

```
vif(mpf)
##
          male
                        svl
                                   mass
                                             length
##
      1.058699 994.546545
                               4.813078 1007.484200
mpf_l <- lm(length ~ male + svl + mass, data=python)</pre>
1/(1-summary(mpf_l)$r.squared)
## [1] 1007.484
Misleading conclusion: svl and length are both irrelevant (this is not the case). Also, the standard errors are
very large.
# remove "length" based on VIF
mpf2 <- lm(fat ~ male + mass + svl, data = python)</pre>
summary(mpf2)
##
## lm(formula = fat ~ male + mass + svl, data = python)
##
## Residuals:
##
        Min
                  1Q
                        Median
                                     3Q
                                             Max
## -2444.44 -137.38
                         -6.66
                                 109.22 1530.81
##
## Coefficients:
                 Estimate Std. Error t value Pr(>|t|)
##
## (Intercept) 204.09840 132.30121
                                        1.543
                                                0.1242
                            47.16396 -4.171 4.22e-05 ***
## male
               -196.71705
## mass
                  0.11788
                              0.00524 22.495 < 2e-16 ***
                              0.76433 -2.091
## svl
                 -1.59841
                                                0.0375 *
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
## Residual standard error: 360.2 on 244 degrees of freedom
## Multiple R-squared: 0.897, Adjusted R-squared: 0.8957
## F-statistic: 708.2 on 3 and 244 DF, p-value: < 2.2e-16
vif(mpf2)
       male
                mass
                           svl
## 1.056139 4.720065 4.611903
```

Svl now has a significant t-statistic.

LECTURE 13 | 2020-10-26

Model selection: Given p explanatory variables, find the subset $k \leq p$ of explanatory variables ("reduced model") that gives us the "best" model:

- · goodness of fit
- · interpretability
- predictive performance

Some related concepts:

1. *F* tests compare between 2 specific models where test adequacy of a "reduced" model (subset, "nested") relative to full model.

Quiz 4: $\beta_1 = \beta_2$ in part d-f

- 2. Multicollinearity: can affect interpretability of $\hat{\beta}_j$ usual interpretation "holding other variables constant" doesn't really work when x_j is strongly correlated with other predictors.
- 3. R^2 is the proportion of variability in the response explained by the regression model. It always increases when adding variables.
- 4. $\hat{\sigma}^2$ is estimated residual variable, used for prediction, want $\hat{\sigma}^2$ small to give good predictive performance Two key ingredients:
 - Metric (or criterion) for comparing different models with potentially different number of predictors
 - selection/search strategy (which models should we fit and test?)

Examples of metrics for model selection:

DEFINITION 3.30: Adjusted R^2

$$R_{\mathrm{adj}}^2 = 1 - \frac{\mathrm{SS}(\mathrm{Res})/(n-k-1)}{\mathrm{SS}(\mathrm{Total})/(n-1)} = 1 - \frac{\hat{\sigma}^2}{s^2}$$

for model with k predictors.

Compared to

$$R^2 = 1 - \frac{\mathrm{SS}(\mathrm{Res})}{\mathrm{SS}(\mathrm{Total})} = 1 - \frac{\hat{\sigma}^2(n-k-1)}{s^2(n-1)}$$

- SS(Res)/(n-k-1) estimated $\hat{\sigma}^2$ for model with k predictors
- SS(Total)/(n-1) is the sample variance of responses y_i .

$$\begin{split} R_{\rm adj}^2 &= 1 - \frac{n-1}{n-k-1}(1-R^2) = 1 - \left(1 + \frac{k}{n-k-1}\right)(1-R^2) \\ &= 1 - \left[1(1-R^2) + \left(\frac{k}{n-k-1}\right)(1-R^2)\right] \\ &= 1 - \left[1 - R^2 + \left(\frac{k}{n-k-1}\right)(1-R^2)\right] \\ &= 1 - 1 + R^2 - \frac{k}{n-k-1}(1-R^2) \\ &= R^2 - (1-R^2)\frac{k}{n-k-1} \end{split}$$

Intuition: R_{adi}^2 accounts for number variables in model, penalizes inclusion of unimportant predictors; that is, SS(Res) has little decrease when adding such variables. Meanwhile, \mathbb{R}^2 always increases with more predictors, but R_{adi}^2 can decrease if SS(Res) change is small.

While R_{adi}^2 loses its usual interpretation of R^2 , but can be used as a measure of "goodness of fit" and model selection criterion (e.g. pick subset of predictors that gives the highest $R_{\rm adj}^2$).

EXAMPLE 3.31

Given

- n = 25
- SS(Total) = 20
- p = 6

Suppose we're considering on a subset of k = 4 predictors, and find:

	Reduced	Full		
	k = 4	p=6		
SS(Total)	20	20		
SS(Res)	10	9.8		
R^2	10/20 = 0.5	9.8/20 = 0.49		
$R_{ m adj}^2 \ \hat{\sigma}^2$	$1 - \frac{10/(25 - 4 - 1)}{20/(25 - 1)} = 0.4$	$1 - \frac{9.8/(25-6-1)}{20/(25-1)} \approx 0.347$		
$\hat{\sigma}^2$	10/(25-4-1)=0.5	$9.8/(25-6-1) \approx 0.544$		

- n-k-1 d.f. Res in reduced
- n-p-1 d.f. Res in full

Remarks:

- R²_{adj} < R², but as n → ∞, R²_{adj} → R².
 Model with higher R²_{adj} has lower σ̂², thus is a reasonable metric for model selection.

Akaike Information Criterion (AIC)

Let n be sample size, q is the number of parameters [in multiple linear regression: k predictors + 1 (intercept) $+ 1 (\sigma^2)$

$$\mathrm{AIC} = 2q - 2\ln[L(\hat{\theta})]$$

where $L(\hat{\theta})$ is the likelihood function evaluated at $\hat{\theta}$ (parameter estimates). Note that LS estimates of β are equivalent to maximum likelihood estimates under the usual normal assumptions on ε . Also, 2q is the penalty for including more predictors. With more parameters, $L(\hat{\theta})$ increases, offset by penalty 2q.

If we want to measure just the difference, we can do

$$\mathrm{AIC} = n \ln \left\lceil \frac{\mathrm{SS}(\mathrm{Res})}{n} \right\rceil + 2(p+1)$$

Therefore, model with lower AIC is preferred; that is, differences in AIC matter not the value itself.

Bayesian Information Criterion (BIC)

Similar to AIC, but more strongly penalizes inclusion of more variables.

$$BIC = q \ln(n) - 2 \ln[L(\hat{\theta})]$$

where $q \ln(n)$ depends on sample size.

If we want to measure just the difference, we can do

$$\mathrm{BIC} = n \ln \left[\frac{\mathrm{SS}(\mathrm{Res})}{n} \right] + (p+1) \ln(n)$$

Recap:

- R^2 , AIC, BIC are all based on comparing the fitted models. In other words, they look at the explanatory power of the model.
- They all have penalties to try to prevent "overfitting." That is, having too many variables might end up modelling spurious relationships that are actually noise.

Mean Square Prediction Error (MSPE)

Consider predictive performance of model on *new* data; that is, data *not* used in fitting of models. "Is model generalizable to new data?" Overfitted models tend to have high prediction error.

For example, via cross-validation schemes. We've given 4 examples of metrics/criteria for comparing models. Imagine we have p predictors:

- $\binom{p}{1}$ 1 predictors
- $\binom{p}{2}$ 2 predictors
- •
- $\binom{p}{n}$ p predictors

$$\sum_{j=0}^{p} \binom{p}{j} = 2^{p}$$

Occam's Razor: "The simplest explanation is usually the best one."—William Ockham

LECTURE 14 | 2020-10-28

Model Selection

- ullet Criteria: $R_{
 m adj}^2$, AIC, BIC, MSPE, etc. explicitly penalizes unnecessarily complex models.
- Search strategies (use with chosen criterion)
- (i) Brute force: fit all possible regressions. With p predictors, we have $\sum_{j=0}^{p} {p \choose j} = 2^p$ possible models to fit.
 - Finds optimal model that may be computationally intensive (or infeasible) if p is large.

<u>Idea</u>: Find a "good" (useful) model in reasonable computational time (not necessarily optimal). Many strategies focus on adding/removing variables one at a time.

- (ii) Forward selection: add one variable at a time to model.
 - Start with a model that only has an intercept (β_0) .
 - Fit p simple linear regression models

$$oldsymbol{y} = eta_0 oldsymbol{1} + eta_1 oldsymbol{x}_j + oldsymbol{arepsilon} \quad j = 1, \dots, p$$

- Pick the best of p models (with 1 predictor) according to chosen criterion, and add that variable x_i to model.
- Fit (p-1) models containing x_i and one other variable.
 - If none of (p-1) models improves criterion, stop.
 - Pick the best of (p-1) models according to criterion, so now we have 2 variables in the model.

Continue adding 1 variable at a time in this way until we can no more variables improve the criterion. The final model is one with the best criterion after we *stop*; that is, no further improvement is possible.

Note: Much faster than brute force as the maximum number of models to fit is:

$$p + (p-1) + \dots + 2 + 1 = \sum_{i=1}^{p} i = \frac{p(p+1)}{2}$$

which is $\mathcal{O}(p^2)$ compared to $\mathcal{O}(2^p)$ for all possible regressions.

- (iii) Backward direction: remove one variable at a time to model.
 - Start with model that has *p* predictors.
 - Fit p models that result from removing one variable from the regression; that is, each one has (p-1) variables.
 - Pick the best of p models according to criterion.
 - Eliminate that variable x_i from model.
 - Fit (p-1) models that remove x_i and one other variable from model.
 - Pick best of (p-1) models (2 variables removed).

Continue removing 1 variable at a time in this way until we can no more variables improve the criterion. Same computational complexity as forward selection.

- (iv) Forward-backwards (allows individual variables to be both added/removed)
 - · Start as in forward selection
 - If we have *k* variables in model:
 - Backwards: fit k models with (k-1) variables. If any of these improve criterion, remove the variable.
 - Forwards: fit (p-k) models with (k+1) variables. If any of these improve criterion, add that variable.
 - These are the basic "stepwise" selection models to get a "good" (useful) model.
 - Many other have sophisticated procedures available. For example, stochastic search, lasso.
 - We've assumed that n > p because otherwise $(X^{\top}X)$ is not invertible. More specialized methods needed if number of predictors is larger than sample size.

```
## Coffee example (Coffee Quality Institute, 2018) continued
coffee <- read.csv("coffee_arabica.csv")</pre>
mfull <- lm(Flavor~ factor(Processing.Method) + Aroma + Aftertaste +
    Body + Acidity + Balance + Sweetness + Uniformity + Moisture, dat=coffee)
summary(mfull)$adj.r.squared
AIC(mfull)
BIC(mfull)
library(leaps)
all_regs <- regsubsets(Flavor ~ ., data = coffee, nvmax = 10, nbest = 2~10,
                       really.big = TRUE)
all_regs_summ <- summary(all_regs)</pre>
# all_regs_summ$which
# all_reqs_summ$adjr2
# all_reqs_summ$bic
# Organize results according to number of variables in model
p <- 10
k \leftarrow c(rep(1, choose(p,1)),
           rep(2, choose(p,2)),
           rep(3, choose(p,3)),
           rep(4, choose(p,4)),
           rep(5, choose(p,5)),
           rep(6, choose(p,6)),
           rep(7, choose(p,7)),
           rep(8, choose(p,8)),
           rep(9, choose(p,9)),
           rep(10, choose(p,10)))
boxplot(all_regs_summ$adjr2 ~ k, xlab = "Number of predictors", ylab =
          expression(R[adj]^2), ylim = c(0,1))
abline(h = c(0,1), lty = 2, col = "red")
boxplot(all_regs_summ$bic ~ k, xlab = "Number of predictors", ylab = "BIC")
max(all_regs_summ$adjr2)
bestR2adj <- which.max(all_regs_summ$adjr2)</pre>
min(all regs summ$bic)
bestBIC <- which.min(all_regs_summ$bic)</pre>
# Find out which predictors in those models
all_regs_summ$which[bestR2adj,]
all_regs_summ$which[bestBIC,]
coffee$wet <- ifelse(coffee$Processing.Method == 'Washed / Wet', 1,</pre>
                      0) # 1 = wet, 0 otherwise
coffee$semi <- ifelse(coffee$Processing.Method == 'Semi-washed / Semi-pulped',</pre>
                       1, 0) # 1 = semi/dry, 0 otherwise
coffee$Processing.Method <- NULL</pre>
m_bestr2adj <- lm(Flavor~ wet + Aroma + Aftertaste +</pre>
            Body + Acidity + Balance + Sweetness + Uniformity + Moisture,
            dat=coffee)
```

```
summary(m_bestr2adj)
AIC(m_bestr2adj)
BIC(m_bestr2adj)
m_bestBIC <- lm(Flavor~ wet + Aroma + Aftertaste +</pre>
                  Body + Acidity + Sweetness , dat=coffee)
summary(m_bestBIC)
AIC(m bestBIC)
BIC(m bestBIC)
# Let's also try stepwise methods
library(MASS)
# Full model and empty model with just intercept
full <- lm(Flavor ~ ., data = coffee)</pre>
empty <- lm(Flavor ~ 1, data = coffee)</pre>
# default stepAIC uses AIC criterion
stepAIC(object = empty, scope = list(upper = full, lower = empty), direction
        = "forward")
# Let's get stepAIC to use BIC by specifying the penalty k = log(n)
stepAIC(object = empty, scope = list(upper = full, lower = empty), direction
        = "forward", k = log(nrow(coffee)))
m_f <- stepAIC(object = empty, scope = list(upper = full, lower = empty),</pre>
               direction = "forward", trace = 0, k = log(nrow(coffee)))
summary(m_f)
# Backward
stepAIC(object = full, scope = list(upper = full, lower = empty),
        direction = "backward", k = log(nrow(coffee)))
m_b <- stepAIC(object = full, scope = list(upper = full, lower = empty),</pre>
               direction = "backward", trace = 0, k = log(nrow(coffee)))
summary(m_b)
# Forward-backward
stepAIC(object = empty, scope = list(upper = full, lower = empty),
        direction = "both", k = log(nrow(coffee)))
m_h <- stepAIC(object = empty, scope = list(upper = full, lower = empty),</pre>
               direction = "both", trace = 0, k = log(nrow(coffee)))
summary(m_h)
# 10 variables is still a fairly small problem: in this example
# all 3 approaches identify the same BIC-based model as the exhaustive search.
```

LECTURE 15 | 2020-11-02

Checking model assumptions

Recall: $Y = X\beta + \varepsilon$ where $\varepsilon \sim \text{MVN}(0, \sigma^2 I_n)$. Practically, this means

$$\varepsilon \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \sigma^2)$$

- Independence among all error terms
- · Normally distributed
- Since $\mathbb{E}[Y_i] = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip}$ is implied by $\mathbb{E}[\varepsilon_i] = 0$ for any x_{i1}, \dots, x_{ip} , the linear model is appropriate; that is, it correctly explains response on average.
- Constant error variance σ^2

We could assess these assumptions via ε_i 's, but we can't observe ε_i directly. Rather, we do have an approximation via residuals e_i from the fitted model.

Recall, $e \sim \text{MVN}(0, (I - H)\sigma^2)$. So e and ε are related:

$$e = Y - X\hat{\beta} = (I - H)Y = (I - H)(X\beta + \varepsilon) = (X\beta - HX\beta) + (I - H)\varepsilon = (I - H)\varepsilon$$

Note: we can't "solve" ε since (I-H) is not invertible since it is not full rank: recall H and (I-H) are idempotent, so

$$\operatorname{tr}(H) = p + 1 = \operatorname{rank} X$$

$$\operatorname{tr}(I-H) = n - (p+1) < n$$

Similarly, this does not imply $Y = \varepsilon$. So, $e_i = \varepsilon_i - \sum_{j=1}^n h_{ij}\varepsilon_j$ which means e_i is a good approximation to ε when entries of h_{ij} of H are small (which is "usually" the case, especially when n is large).

$$e_i \sim \mathcal{N}(0, \sigma^2(1-h_{ii})) \iff \frac{e_i - 0}{\sigma \sqrt{1-h_{ii}}} \sim \mathcal{N}(0, 1)$$

If we plug in $\hat{\sigma}$, that defines the studentized residuals.

$$d_i \equiv \frac{e_i}{\hat{\sigma}\sqrt{1 - h_{ii}}}$$

Common practice is to use e for the following residual plots/diagnostics, (using d_i is also possible) to check model assumptions:

Plot e versus $\hat{\mu}$ which was shown in A2 were mutually independent since they are multivariate normal with covariance 0.

Typical "good" scatter plot will have a random scatter around y = 0 (no visible patterns).

Problematic scatter plot is when variance of e_i is not constant (cone) increases with fitted values.

In general, plot of e and $\hat{\mu}$ can show deviations from independence, constant variance if those assumptions are violated.

Plot e versus x_j for each $j=1,\ldots,p$ in model when not many predictors. This can help detect non-linearity between x_j and y, not as practical when p is large.

Typical "good" scatter plot will have a random scatter around y = 0 (no visible patterns).

If the observation numbers were collected in some order (time, space, etc.), also plot e_i versus indices i to check for any patterns (again, look for random scatter)

Histogram of e: is it bell shaped and symmetric to assess Normal assumption, but the histogram can't easily detect overly fat/thing tails.

QQ plot of e more formally assess Normality: scatter plot of ordered quantiles from 2 distributions. In our case: empirical quantiles from residuals (data) versus theoretical quantiles from assumed Normal distribution. If quantiles roughly match, the points will roughly fall on the 45° line through origin.

If these sets of residuals plots show violations, then that could affect the validity of confidence intervals, hypothesis tests, etc.

```
### Residual plots/diagnostics demo
## Florida oranges revisited
dat <- read.csv("florange.csv")</pre>
plot(dat$acres,dat$boxes)
lm.1 <- lm(dat$boxes~dat$acres)</pre>
summary(lm.1)
# Residual plot: vs fitted values
plot(lm.1$fitted.values, lm.1$residuals, xlab = "Fitted Values", ylab = "Residuals")
# Residual plot: vs predictor (just one in this case)
plot(dat$acres, lm.1$residuals, xlab = "Acres", ylab = "Residuals")
# Residual plot: vs i (just to demo plot; no time/space ordering here)
plot(1:nrow(dat), lm.1$residuals, xlab = "Index", ylab = "Residuals")
# Histogram of residuals
hist(lm.1$residuals)
# QQ plot of residuals
qqnorm(lm.1$residuals)
qqline(lm.1$residuals, col="blue", lwd = 2)
## Rocket data revisited
rocket <- read.csv(file="rocket.csv")</pre>
mr <- lm(thrust ~ nozzle + propratio, data = rocket)</pre>
summary(mr)
# Residual plot: vs fitted values
plot(mr$fitted.values, mr$residuals, xlab = "Fitted Values",
    ylab = "Residuals")
# Residual plot: vs predictors
plot(rocket$nozzle, mr$residuals, xlab = "Nozzle (1 = large)",
     ylab = "Residuals")
plot(rocket$propratio, mr$residuals, xlab = "Propellant to fuel ratio",
     ylab = "Residuals")
# Histogram of residuals
hist(mr$residuals)
# QQ plot of residuals
qqnorm(mr$residuals)
qqline(mr$residuals, col="blue", lwd = 2)
```

LECTURE 16 | 2020-11-04

Addressing problems with regression model assumptions

If residual plots reveal problems with assumptions (although plots don't fully check linearity, independence), we might be able to address via <u>transformations</u>, adding variables to model, using different error distribution on ε .

(1) Variance-stabilizing transformations on responses y_i , can help constant variance identified on e vs $\hat{\mu}$ plot.

<u>Idea</u>: apply function $g(\cdot)$ and fit regression on transformed $g(y_i)$; that is

$$g(Y_i) = \beta_0 + \beta_1 x_{i1} + \dots + \beta_p x_{ip} + \varepsilon_i$$

Note this can drastically change SS(Res) and $\hat{\sigma}$, so cannot directly use those among different choices $g(\cdot)$.

<u>Rationale</u>: variance of response might be a function of mean $\mu_i = \mathbb{E}[Y_i]$; could be expressed

$$\mathbb{V}(Y_i) = \mathbb{V}(\varepsilon_i) = h(\mu_i)\sigma^2$$

for some $h(\cdot) > 0$. In which case, we want

$$\mathbb{V}(q(Y_i)) \approx \sigma^2$$

1st order Taylor expansion

$$\begin{split} g(Y_i) &\approx g(\mu_i) + (Y_i - \mu_i) g'(\mu_i) \\ \mathbb{V}(g(Y_i)) &\approx [g'(\mu_i)]^2 \mathbb{V}(Y_i) \end{split}$$

Thus, for $\mathbb{V}(g(Y_i))$ to be constant, we need

$$[g'(\mu_i)]^2 \propto \frac{1}{h(\mu_i)}$$

Examples:

(i) $h(\mu_i)=\mu_i$; that is, $\mathbb{V}(Y_i)=\sigma^2\mu_i\propto\mu_i$. Variance in responses proportional to mean response. We need

$$g'(\mu_i) \propto \frac{1}{\sqrt{h(\mu_i)}} = \frac{1}{\sqrt{\mu_i}}$$

and so $g(\mu_i)=\sqrt{\mu_i}$ works, and we apply $g(y_i)=\sqrt{y_i}$ to obtain approximately constant variance

(ii) $h(\mu_i) = \mu_i^2$; that is, $\mathbb{V}(Y_i) = \sigma^2 \mu_i^2 \propto \mu_i^2$ or $\mathsf{Sd}(Y_i) \propto \mu_i$. We need

$$g'(\mu_i) \propto \frac{1}{\mu_i}$$

and so $g(\mu_i) = \ln(\mu_i)$ works, and we apply $g(y_i) = \ln(y_i)$ to stabilize variance.

(iii) Class of power transformations (Box-Cox)

$$g(y_i) = \begin{cases} \frac{y_i^{\lambda} - 1}{\lambda} & \lambda \neq 0 \\ \ln(y_i) & \lambda = 0 \end{cases}$$

$$g'(\mu_i) = \begin{cases} \mu_i^{\lambda-1} & \lambda \neq 0 \\ \frac{1}{\mu_i} & \lambda = 0 \end{cases} \iff h(\mu_i) \propto \frac{1}{[g'(\mu_i)]^2} = \mu_i^C \quad C \in \mathbf{R}$$

Box-Cox transformation can help address non-constant variance of the form

$$\mu_i^C \sigma^2 = \mathbb{V}(Y_i)$$

Special cases include:

- $\lambda = \frac{1}{2}$ is $\sqrt{\cdot}$
- $\lambda = 0$ is $\ln(\cdot)$
- $\lambda = 1$ is identity
- $\lambda = -1$ is reciprocal

can automatically try a sequence of λ and find the choice that gives the best value of likelihood

Note that interpreting $\hat{\beta}_j$ can be less intuitive as a result of transformation, since now increasing x_j by 1 unit corresponds to an estimated change of $\hat{\beta}_j$ in $g(y_i)$. For $g(y_i) = \ln(y_i)$, $\hat{\beta}_j$ represents estimate of expected change in $\ln(y_i)$ which corresponds to $e^{\hat{\beta}_j}$ being the expected multiplicative change applied to the (original) response. But for an arbitrary λ , the transformation might be less interpretable.

- (2) Transforming and/or adding explanatory variables.
 - If y (or g(y)) has a clear non-linear relationship with some x_j , we can consider transforming x_j (e.g. $\ln(\cdot)$, $\sqrt{\cdot}$, etc.)
 - Could add polynomial terms (e.g. $x^2, x^3, ...$). For example,

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \varepsilon_i$$

suppose we think adding x_1^2 is appropriate, then we define $x_{i3} = x_{i1}^2$ and fit

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \beta_3 x_{i3} + \varepsilon_i$$

which is still linear in β and note that x_1 and x_1^2 are linearly independent.

• Add <u>interaction</u> terms: if we think the effect of x_i on response depends on the value of x_j , e.g. suppose we think x_1 and x_2 interact, then we might fit

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \beta_3 x_{i3} + \varepsilon_i$$

where $x_{i3} = x_{i1} + x_{i2}$, so that

$$Y_i = \beta_0 + (\beta_1 + \beta_2 x_{i2}) x_{i1} + \beta_2 x_{i2} + \varepsilon_i$$

Note: in general, there's $\binom{p}{2}$ possible interactions, consider whether interactions are conceptually plausible.

- (3) QQ-plot of residuals not normal (even after any appropriate transformations)
 - Consider using different distribution for error term ε (e.g. t, Cauchy, Laplace, etc.)

LECTURE 17 | 2020-11-09

Effects of individual observations

(or a few obs) can have an outsized impact on the fitted MLR model

(1) We say an observation $(y_i, x_{i1}, \dots, x_{ip})$ is an outlier if it is substantially different from other observations. This can occur if its response and/or some of its explanatory variables have values that are unusual or extreme compared to the others. Outliers can occur for different reasons. For example, an extraordinary subject, data entry errors. Generally, we don't recommend removing outliers unless we have a strong reason to believe that observation is an error. But it can be useful to investigate what effect it has on our fitted model and quality of fit to the rest of data.

(2) How to detect and characterize outliers: Studentized residual

$$d_i = \frac{e_i}{\hat{\sigma}\sqrt{1 - h_{ii}}}$$

are standardized to have approximately variance 1 where

$$e_i \sim \mathcal{N}(0, \sigma^2(1 - h_{ii}))$$

So, if $|d_i|$ is large, observation i could be considered an outlier in the sense of having an extreme value of response y_i (e.g. $|d_i| > 3$)

(3) Recall that h_{ii} is the i^{th} diagonal element of hat matrix H. We call h_{ii} the **leverage** of observation i.

$$\hat{\boldsymbol{\mu}} = X\hat{\boldsymbol{\beta}} = H\boldsymbol{Y}$$

so

$$\hat{\mu}_i = \begin{bmatrix} h_{i1} & h_{i2} & \cdots & h_{in} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \sum_{j=1}^n h_{ij} y_j = h_{ii} y_i + \sum_{j \neq i} h_{ij} y_j$$

so h_{ii} captures contribution of Y_i in determining its corresponding fitted value. If the leverage is large relative to h_{ij} 's then $\hat{\mu}_i$ is mostly determined by Y_i . In A3, you will show the leverage is between $\frac{1}{n}$ and 1; that is,

$$\frac{1}{n} \le h_{ii} \le 1$$

If $h_{ii}\approx 1$, then $\mathbb{V}(e_i)=\sigma^2(1-h_{ii})\approx 0$, which in turn implies $y_i\approx \hat{\mu}_i$; that is, residuals with observations with high leverage tend to be small.

Rule of thumb: an observation with leverage higher than twice the average leverage is considered high.

$$h_{ii} > 2\bar{h}$$

where
$$\bar{h} = \frac{1}{n} \sum_{i=1}^{n} h_{ii}$$
.

$$tr(H) = rank X = p + 1$$

Recall that $H = X(X^{T}X)^{-1}X^{T}$ only involves predictors. Thus, leverage is useful to help identify outliers n the sense of having explanatory variables with extreme or unusual values. In simple linear regression,

$$h_{ii} = \frac{1}{n} + \frac{(x_i - \bar{x})^2}{S_{xx}}$$

Which means if x_i is far from \bar{x} , that point will have high leverage. This generalizes to multiple linear regression: an observation with high leverage is an outlier with extreme values in one or more explanatory variables. However, leverage does not tell us directly whether that observation is also an outlier in response, in fact, $y_i \approx \hat{\mu}_i$ for such observations with high leverage.

(4) An observation i is quite influential if its presence in fitting regression considerably changes estimates compared to when observation i is not used to fit a model.

Start with fitting $Y = X\beta + \varepsilon$ using all observations and call estimates $\hat{\beta}$ as usual in the least squares.

Let $\hat{\beta}^{(i)}$ denote the least squares estimates based on fitting a model with the i^{th} observation removed.

<u>Idea</u>: If $\hat{\beta}^{(i)}$ is quite different from $\hat{\beta}$, then observation i is highly influential. Measure this via **Cook's distance** between $\hat{\beta}$ and $\hat{\beta}^{(i)}$:

$$D_i = \frac{(\hat{\beta}^{(i)} - \hat{\beta})^\top X^\top X (\hat{\beta}^{(i)} - \hat{\beta})}{\hat{\sigma}^2(p+1)}$$

To see this intuition, let $\hat{\mu}^{(i)} = X \hat{\beta}^{(i)}$ fitted values based on removing i^{th} observation and estimating β . Then,

$$D_i = \frac{(X\hat{\pmb{\beta}}^{(i)} - X\hat{\pmb{\beta}})^\top (X\hat{\pmb{\beta}}^{(i)} - X\hat{\pmb{\beta}})}{\hat{\sigma}^2(p+1)} = \frac{(\hat{\pmb{\mu}}^{(i)} - \hat{\pmb{\mu}})^\top (\hat{\pmb{\mu}}^{(i)} - \hat{\pmb{\mu}})}{\hat{\sigma}^2(p+1)} = \frac{\|\hat{\pmb{\mu}}^{(i)} - \hat{\pmb{\mu}}\|^2}{\hat{\sigma}^2(p+1)}$$

 D_i measures the Euclidean distance between fitted values of two regressions that give $\hat{\mu}^{(i)}$ and $\hat{\mu}$, up to a scaling factor. Further, it can be shown

$$D_i = d_i^2 \left(\frac{h_{ii}}{1 - h_{ii}}\right) \left(\frac{1}{p+1}\right)$$

where we can see that both d_i and h_{ii} are key quantities to calculate D_i and observation i that are most influential will have larges of $|d_i|$ and h_{ii} .

- High $|d_i| \rightarrow$ outlier in response
- High $h_{ii} \rightarrow$ outlier in explanatory variable

So high influential observations tend to be outliers in the sense of having extreme values in *both* response and one/more predictors. Check if some D_i 's are much larger than others, as they would be the most influential observations.

LECTURE 18 | 2020-11-11

Influential observations, continued

For the ith observation, the values of its predictors are

$$\begin{aligned} \boldsymbol{v}_i &= \begin{bmatrix} 1 & x_{i1} & x_{i2} & \cdots & x_{ip} \end{bmatrix}^\top \\ & X &= \begin{bmatrix} \boldsymbol{v}_1^\top \\ \boldsymbol{v}_2^\top \\ \vdots \\ \boldsymbol{v}_n^\top \end{bmatrix} \\ & X^\top X &= \begin{bmatrix} \boldsymbol{v}_1 & \cdots & \boldsymbol{v}_n \end{bmatrix} \begin{bmatrix} \boldsymbol{v}_1^\top \\ \vdots \\ \boldsymbol{v}_n^\top \end{bmatrix} = \sum_{i=1}^n \boldsymbol{v}_j \boldsymbol{v}_j^\top \end{aligned}$$

Recall $H = X(X^{\top}X)^{-1}X^{\top}$ so

$$h_{ii} = \boldsymbol{v}_i^\top (X^\top X)^{-1} \boldsymbol{v}_i^\top$$

Let $X^{(i)}$ be X with i^{th} observation deleted, $y^{(i)}$ be y with i^{th} response deleted. Then,

$$(X^{(i)})^\top X^{(i)} = \sum_{j \neq i} \boldsymbol{v}_j \boldsymbol{v}_j^\top \implies X^\top X = (X^{(i)})^\top X^{(i)} + \boldsymbol{v}_i \boldsymbol{v}_i^\top$$

Similarly,

$$X^{\top}\boldsymbol{y} = \sum_{j=1}^{n} \boldsymbol{v}_{j} y_{j} \implies (X^{(i)})^{\top} \boldsymbol{y}^{(i)} = \sum_{j \neq i} \boldsymbol{v}_{j} y_{j} \implies X^{\top} \boldsymbol{y} = (X^{(i)})^{\top} \boldsymbol{y}^{(i)} + \boldsymbol{v}_{i} y_{i}$$

Let A be an $n \times n$ invertible matrix

$$(A - aa^{\top})^{-1} = A^{-1} + \frac{A^{-1}aa^{\top}A^{-1}}{1 - a^{\top}A^{-1}a}$$

Fit the least squares using $X^{(i)}$ and $\boldsymbol{u}^{(i)}$ to obtain

$$\begin{split} \hat{\boldsymbol{\beta}}^{(i)} &= [(\boldsymbol{X}^{(i)})^{\intercal} \boldsymbol{X}^{(i)}]^{-1} (\boldsymbol{X}^{(i)})^{\intercal} \boldsymbol{y}^{(i)} \\ &= (\boldsymbol{X}^{\intercal} \boldsymbol{X} - \boldsymbol{v}_i \boldsymbol{v}_i^{\intercal})^{-1} (\boldsymbol{X}^{\intercal} \boldsymbol{y} - \boldsymbol{v}_i \boldsymbol{y}_i) \\ &= \left[(\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} + \frac{(\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \boldsymbol{v}_i^{\intercal} (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1}}{1 - \boldsymbol{v}_i^{\intercal} (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i} \right] (\boldsymbol{X}^{\intercal} \boldsymbol{y} - \boldsymbol{v}_i \boldsymbol{y}_i) \\ &= (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{X}^{\intercal} \boldsymbol{y} - (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \boldsymbol{y}_i + \frac{(\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \boldsymbol{v}_i^{\intercal} (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{X}^{\intercal} \boldsymbol{y} - (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \boldsymbol{v}_i^{\intercal} (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \boldsymbol{v}_i^{\intercal} (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \boldsymbol{y}_i \\ &= \hat{\boldsymbol{\beta}} - (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \left[\boldsymbol{y}_i - \frac{\boldsymbol{v}_i^{\intercal} \hat{\boldsymbol{\beta}} - \boldsymbol{h}_{ii} \boldsymbol{y}_i}{1 - \boldsymbol{h}_{ii}} \right] \\ &= \hat{\boldsymbol{\beta}} - (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \left[\frac{\boldsymbol{y}_i - \boldsymbol{v}_i^{\intercal} \hat{\boldsymbol{\beta}}}{1 - \boldsymbol{h}_{ii}} \right] \\ &= \hat{\boldsymbol{\beta}} - (\boldsymbol{X}^{\intercal} \boldsymbol{X})^{-1} \boldsymbol{v}_i \left[\frac{\boldsymbol{e}_i}{1 - \boldsymbol{h}_{ii}} \right] \end{split}$$

Therefore,

$$\hat{\boldsymbol{\beta}}^{(i)} - \hat{\boldsymbol{\beta}} = \frac{-e_i}{1 - h_{ii}} (\boldsymbol{X}^\top \boldsymbol{X})^{-1} \boldsymbol{v}_i$$

In fact, we can get $\hat{\beta}^{(i)}$ from the regression with all n observations; that is, we don't need to fit a separate model.

$$\begin{split} D_i &= \frac{(\hat{\boldsymbol{\beta}}^{(i)} - \hat{\boldsymbol{\beta}})^\top X^\top X (\hat{\boldsymbol{\beta}}^{(i)} - \hat{\boldsymbol{\beta}})}{\hat{\sigma}^2(p+1)} \\ &= \frac{\left(\frac{-e_i}{1-h_{ii}}\right) \boldsymbol{v}_i^\top (X^\top X)^{-1} X^\top X \left(\frac{-e_i}{1-h_{ii}}\right) (X^\top X)^{-1} \boldsymbol{v}_i}{\hat{\sigma}^2(p+1)} \\ &= \frac{e_i^2}{\hat{\sigma}^2(1-h_{ii})(1-h_{ii})} \left(\frac{h_{ii}}{p+1}\right) \\ &= d_i^2 \left(\frac{h_{ii}}{1-h_{ii}}\right) \left(\frac{1}{p+1}\right) \end{split}$$

as claimed, so we can calculate Cook's distance in terms of $|d_i|$ and h_{ii} . Therefore, the most influential observation on estimates of β are those with high $|d_i|$ and h_{ii} .

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Prediction error and cross-validation

Sometimes a key application of a fitted model is to do <u>prediction</u> on new data (and is more important than interpretability).

Previously, we saw model selection criteria that are computed on fitted models (AIC, BIC, Adjusted R^2) which assess how well the model explains the explanatory power of a model on the *data used to fit the model* (or *train*).

While these criteria incorporate penalty terms to try to prevent overfitting, they don't directly assess how well a model would perform in predicting the response on new data given predictors.

We mentioned metrics such as MSPE as measures of predictive accuracy.

To assess accuracy in prediction, we need metrics for measuring prediction error, e.g. evaluated over m observations.

• Mean-squared error (MSE): If we have m observations,

$$MSE = \frac{1}{m} \sum_{i=1}^{m} (y_i - \hat{y}_i)^2$$

where y_i is the actual value, \hat{y}_i is the predicted value (or equivalently, if we apply MSE on the fitted data, this would be the fitted value, $\hat{\mu}_i$; if calculated on training data). Measured on the scale of σ^2 .

Note: MSE is equivalently called MSPE if applied on new data.

• Root-mean-squared error (RMSE): Square root of MSE. Measured on the scale of σ .

$$RSME = \sqrt{MSE}$$

• Mean absolute error (MAE):

$$\text{MAE} = \frac{1}{m} \sum_{i=1}^{m} |y_i - \hat{y}_i|$$

Ideally, we have lots of data, conceptualize having three parts. We have access to train and validation. Test

Train (y_1, y_2, \dots, y_n)	Validation $(y_{n+1}, \dots, y_{n+v})$	$\mathrm{Test}\;(y_{n+v+1},\ldots,y_{n+v+t})$
 n observations Fit models, as many as we want. 	 v observations Estimate prediction error for each fitted model. 	 t observations Used at the very end for final assessment of our selected model.

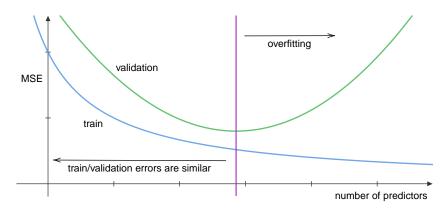
data is from the future, we won't have access to this until the data is released (say the actual stock prices were released); that is, assume we don't get to see this.

For example, using MSE as a metric, based on a fitted model we can compute

MSE Train	MSE Validation	MSE Test		
$\frac{1}{n}\sum_{i=1}^n(y_i-\hat{y}_i)^2$	$\frac{1}{m}\sum_{i=n+1}^{n+v}(y_i-\hat{y_i})^2$	$\frac{1}{t}\sum_{i=n+v+1}^{n+v+t}(y_i-\hat{y}_i)^2$		

- Observe "MSE Train" is equal to $\frac{SS(Res)}{n}$ and our usual estimate of $\hat{\sigma}^2$ is a scaled version of this quantity to compensate for the number of predictors. Specifically, $\hat{\sigma}^2 = \frac{SS(Res)}{n-p-1}$ so it's unbiased.
- Consider "MSE Validation" as an estimate of MSPE on new data.
- "MSE Test" is the actual test of prediction, we call this the actual MSPE.

Idea: We hope that "MSE Validation" \approx "MSE Test" since neither sets were used to fit the model.



So, if we're using MSE/RMSE as a metric (as related to $\hat{\sigma}^2/\hat{\sigma}$) and the MSE/RMSE is significantly larger on validation compared to train, then we probably overfitted the model; that is, we can't expect the model to generalize well to new data.

How to use framework in practice:

• Simplest: randomly divide available data between train/validation, say 80%/20% split. Weakness:

- 1. Don't use all data for training.
- 2. Only get one estimate of prediction error.
- Better: Use cross-validation scheme (CV). How to do CV with K folds:

y	x_1	x_2	 x_p	Folds
				1
				2
		:		÷
				K

- Divide available data for train and validation into K roughly equally sized sets (folds), usually randomly.
- For CV k, use data in fold k as validation, and train on the rest of data.
- Thus, to estimate the prediction error for a given model, we fit it K times, each time treating the data in folds, $1, 2, \ldots, K$ as validation. Therefore, we get K estimates of prediction error for that particular model.
- For example, using RMSE, we get

$$\overline{\text{RSME}} = \text{RMSE}_1, \text{RMSE}_2, \dots, \text{RSME}_K$$

and can take the average

$$\frac{1}{k} \sum_{k=1}^{K} \text{RSME}_{k}$$

as an estimate for RMSPE on new data (test set).

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