Probabilistic Robotics
PRR06, Fall 2017
Book Assignment 4.6.4
Assigned: Tuesday September 12;
Due: Thursday September 14, 13:00 in the afternoon

September 11, 2017

Implement Exercise 4.6.1 using particle filters instead of histograms, and plot and discuss the results.

Hand-In

When you have completed the assignment, upload your solution to Blackboard, togehter with your solution of Assignment 4.6.1. This should be a PDF, with your Matlab scripts as pseudo-code (for example with the matlab-prettifier package). If you have only partially solved the assignment, upload your partial solution.