Topology Basis And Continuous Functions

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1   Basis For Topology

Definition. **(Topology Basis)** Let $(X, \mathcal{T})$ be a topological space. A **basis** for topology $\mathcal{T}$ is a collection of subsets $\mathcal{B}$ such that for any open set $U \in \mathcal{T}$,

$$U = \bigcup_{\alpha \in I} B_\alpha, B_\alpha \in \mathcal{B}$$

In other words, any open set could be denoted as the union of a collection of subsets in $\mathcal{B}$

EXAMPLE. Let $X = \mathbb{R}$ and $\mathcal{T}$ be the conventional topology on $\mathbb{R}$. Let $\mathcal{B}$ consists of all open interval with rational endpoint, which is:

$$\mathcal{B} = \{(a, b) \mid a, b \in \mathbb{Q}, a < b\}$$

Then for any $U \underset{open}{\subset} \mathbb{R}$, and any $x \in U$, there is an interval I with: $x \in I_x \subset U$ and therefore: $U = \bigcup_{x \in U} I_x$.

Note that we say $\mathcal{B}$ is a basis for some specific topology if $\mathcal{B}$ satisfies the above definition. Under such condition, we already pointed out what topology this basis is corresponding to. The next question is: what kind of collection of subsets could be a basis for some topology on X?(If we didn't specify the topology yet)

Suppose there is a collection of subsets of X, say $\mathcal{B}$. If B is a basis for some topology $\mathcal{T}$, then every open set in $\mathcal{T}$ could be denoted as union of elements in $\mathcal{B}$. Note that $X \in \mathcal{T}$ therefore $X = \bigcup_{\alpha \in I} B_\alpha$.

Moreover, consider $U, V \in \mathcal{T}$, and denote them as union of basis elements of $\mathcal{B}$:

$$U = \bigcup_{\alpha \in I} U_\alpha, U_\alpha \in \mathcal{B}$$

$$V = \bigcup_{\beta \in J} V_\beta, V_\beta \in \mathcal{B}$$

Then $U \cap V$ is supposed to be denoted as union of basis elements in $\mathcal{B}$. However, notice that:

$$U \cap V = \bigcup_{\alpha \in I} \bigcup_{\beta \in J} (U_\alpha \cap V_\beta)$$

Therefore, we only need that $U_\alpha \cap V_\beta$ could be denoted as union of basis elements in $\mathcal{B}$.So far, we have got a sufficient condition that makes $\mathcal{B}$ be a basis of some topology on X:

Theorem 1. *Let X be a set and $\mathcal{B}$ be a collection of subsets in X. If $\mathcal{B}$ satifies the following two requirements, then $\mathcal{B}$ is a basis for some topology:*
(i) For any $x \in X$, there is some $B \in \mathcal{B}$ such that $x \in B \subset X$
(ii) For any $B_1, B_2 \in mathcalB$ with $U \cap V \neq \varnothing$, and any $x \in B_1 \cap B_2$, there is some $B_3 \in \mathcal{B}$ such that $x \in B_3 \subset B_1 \cap B_2$

Proof. Define $\mathcal{T} = \{\bigcup_{\alpha \in I} B_\alpha \mid B_\alpha \in \mathcal{B}\}$, then it's easy to verify that $\mathcal{T}$ is a topology on X and $\mathcal{B}$ is a basis of $\mathcal{T}$.

Definition. If $\mathcal{B}$ satisfies these two conditions in theorem 1, then we define **the topology generated by $\mathcal{B}$** as follows: A subset U of X is said to be open in X if for each $x \in U$, there is a basis element $B \in \mathcal{B}$ such that $x \in B \subset U$.

REMARK. The topology generated by $\mathcal{B}$ is apparently equivalent to the topology mentioned in the proof of theorem 1. And now we know the topology generated by $\mathcal{B}$ is actually those sets which can be denoted as union of elements in $\mathcal{B}$.

The word "basis" might be confusing. We know the open set of $\mathcal{B}$-generated topology equals to the union of some subsets in $\mathcal{B}$ but this expression is not unique. However, in other subjects, for example, linear algebra , a basis means element could be uniquely expressed as linear combination of basis elements.

However, there is one thing follows the same for the basis concepts in linear albegra and topology, that is there might be multiple basis for the same topology,or linear space.But the following theorem, gives a sufficient condition for equivalent topology.

Theorem 2. *We say two basis are **equalvalent** if they generates the same topology. If two basis $\mathcal{B}_1$, $\mathcal{B}_2$ satisfies the following two conditions, then they are equivalent.*
(i) For any $B_1 \in \mathcal{B}_1$, any $x \in B_1$, there is some $B_2 \in \mathcal{B}_2$ such that $x \in B_2 \subset B_1$
(ii) For any $B_2 \in \mathcal{B}_2$, any $x \in B_2$, there is some $B_1 \in \mathcal{B}_1$ such that $x \in B_1 \subset B_2$

Proof. Trivial. The condition specifies that every element in $\mathcal{B}_1$ could be expressed as union of elements in $\mathcal{B}_2$ and vice versa.

Definition. (**subbasis**) A **subbasis** $\mathcal{S}$ for a topology on X is a collection of subsets of X whose union equals to X. The **topology generated by the subbasis $\mathcal{S}$** is defined to be the collection $\mathcal{T}$ of all unions of finite intersection of elements of $\mathcal{S}$

2 Continuous Function

2.1 Continuous Function

Definition. Let X and Y be topological spaces. A function $f : X \to Y$ is said to be **continuous** if for each open set V of Y, the set $f^{-1}(V)$ is an open set of X

It is easy to see that the continuity of a function f depends not only on the function itself, but also the specified topology of its domain and range. To emphasize this fact, we may say f is continuous **relative** to specific topologies on X and Y.

EXAMPLE. In analysis, a real-value function of real variable is said to be continuous if it's continuous at every point of its domain. And a function $f : \mathbb{R} \to \mathbb{R}$ is continous at x_0 is define as follows:

$\forall \epsilon > 0$, there is some δ such that $\mid f(x) - f(x_0) \mid$ if $\mid x - x_0 \mid < \delta$.

Then a continous real variable function is continous from $\mathbb{R}$ to $\mathbb{R}$.

We have seen many other theorems about continuity in mathmatical analysis, for exmaple, a continuous function would map a limit point to a limit point, which is $\lim\limits_{n\to\infty} f(a_n) = f(\lim\limits_{n\to\infty} a_n)$. Some of these theorems are generalized for more general space, the following theorem describes this.

Theorem 3. *Let X and Y be topological spaces; let $f : X \to Y$. Then the following conditions are equivalent:*

(1) f is continuous

(2) Let $\mathcal{B}$ be a basis for Y, then $f^{-1}(B_\beta)$ is open in X

(3) For every subset A of X, one has $f(\bar{A}) \subset \overline{f(A)}$

(4) For every subset B of Y, one has $\overline{f^{-1}(B)} \subset f^{-1}(\bar{B})$

(5) For every closed set B of Y, $f^{-1}(B)$ is closed in X.

Proof. $(\mathbf{1}) \Rightarrow (\mathbf{2})$: Every $B_\beta \in \mathcal{B}$ is an open set in Y, therefore $f^{-1}(B_\beta)$ is open in X.

$(\mathbf{1}) \Rightarrow (\mathbf{3})$: Let x is a limit point of A, it's sufficient to show that $f(x)$ is a limit point of $f(A)$ if $f(x) \notin f(A)$ (There are other situations where $x \in A$ or $f(x) \in f(A)$, but it's simple). We prove as proceed: For any open set U of Y that contains $f(x)$, consider $f^{-1}(U)$, note that $x \in f^{-1}(U)$ as $f(x) \in U$. And by definition of continuous function we have $f^{-1}(U)$ is an open set of X that contains x. Therefore $f^{-1}(U) \cap A \neq \varnothing$ and $U \cap f(A) \neq \varnothing$. By definition, $f(x)$ is a limit point of $f(A)$.

$(\mathbf{2}) \Rightarrow (\mathbf{1})$ We will show that f is continous if it satisfies condition in (2). For any open set U in Y, we can denote U as union of the basis elements, such that: $U = \bigcup\limits_{\beta \in I} B_\beta$, and by theorem about inverse image of union, we have:

$$f^{-1}(\bigcup_{\beta \in I} B_\beta) = \bigcup_{\beta \in I} f^{-1}(B_\beta)$$

, which is open in X. The proof is done.

$(\mathbf{3}) \Rightarrow (\mathbf{4})$ By the definition of inverse image, it's sufficient to show that $f(\overline{f^{-1}(B)}) \subset \bar{B}$. By (3), we have:
$$f(\overline{f^{-1}(B)}) \subset \overline{f(f^{-1}(B))} \subset \bar{B}$$
The last subsets holds as $f(f^{-1}(B) \subset B$.

$(\mathbf{4}) \Rightarrow (\mathbf{5})$ If F is closed in Y, then $\bar{F} = F$. Then we have: $\overline{f^{-1}(F)} \subset f^{-1}(\bar{F}) = f^{-1}(F)$ by (3). It's obvious that $f^{-1}(F) \subset \overline{f^{-1}(F)}$ and hence $f^{-1}(F) = \overline{f^{-1}(F)}$, which shows $f^{-1}(F)$ is closed in X

$(\mathbf{5}) \Rightarrow (\mathbf{1})$ For any open set $U \in Y$, consider $f^{-1}(U)$. Let $V = Y \setminus U$, then V is closed and $f^{-1}(U) = f^{-1}(Y \setminus V) = X \setminus f^{-1}(V)$. Notice that $f^{-1}(V)$ is closed, therefore $f^{-1}(U)$ is open and f is a continous function.

2.2 Limit and Hausdorff Space

We mention before the proof of theorem 3, that in $\mathbb{R} - \mathbb{R}$ function we have $\lim_{n \to \infty} f(a_n) = f(\lim_{n \to \infty} a_n)$ if f is continous. We may generalize this theorem if we define the **limit** of a sequence of point in topological space.

Definition. Let X be a topological space, $\{x_n\} \subset X$ is a sequence of point in X, we say x is the **limit** of $\{x_n\}$, denoted by $\lim_{n \to \infty} x_n = x$(this denotion might be invalid), if :

$$U \underset{open}{\subset} X, x \in X \Rightarrow \exists N \in \mathbb{N}, st. \forall n > N, x_n \in U$$

The open set U of X that contains x is called a **neighborhood** of x

REMARK. The limit of $\{x_n\}$ might not be unique in a general topological space.

Consider $X = \{0, 1\}, \mathcal{T} = \{\varnothing, X, \{0\}\}$. And consider a point sequence :$\{x_n = 0\}, \forall n \in \mathbb{N}$. Then both 0 and 1 ar e limit of this sequence by definition.

As explained above, $\lim_{n \to \infty} x_n = x$ is an invalid denotion if there are two limits. However, we may put a constraints on the space to make there exists only one limit(if there is any) for a sequence.

Definition. (**Hausdorff space**) Let X be a topological space. X is said to be a **Hausdorff space** if for any $x_1, x_2 \in X$ and $x_1 \neq x_2$, there exists two open sets $U_1, U_2 \subset X$ such that $x_1 \in U_1, x_2 \in U_2$ and $U_1 \cap U_2 = \varnothing$

Theorem 4. *Let X be a Hausdorff space, then any sequence $\{x_n\}$ has unique limit (if there is any)*

Proof. If there are two limits of $\{x_n\}$, say a and b. Then by definition of Hausdorff space, there are two open sets U_a, U_b contains a and b respectively but $U_a \cap U_b = \varnothing$. According to the definition of limit, there exists N_1, N_2 such that $x_n \in U_a, \forall n > N_1$; $x_n \in U_b, \forall n > N_2$. Let $N = \max(N_1, N_2)$, then $x_n \in U_a \cap U_b, n > N$, a contradiction.

There are multiple other interesting facts about Hausdorff space. Recall that we mentioned a fact in last section: a single point might not be closed in a general topological space. A typical example is as follows:

$$X = \{a, b, c\}, \mathcal{T} = \{\{a, b\}, \{b\}, \{b, c\}, \varnothing, X\}$$

In this topological space, $\{b\}$ is not closed. And further more, the sequence $\{x_n\}$ where $x_n = b, \forall n \in \mathbb{N}$ has two limits a and c.

We have proved in Hausdorff space, sequence has only one limit. Further more, a single point is closed in Hausdorff space.

Theorem 5. *Let X be a Hausdorff space, then every finite set of X is closed.*

Proof. It suffices to show that any single point is closed. Let $\{x_0\}$ be a one-point set. For any $x \in X, x \neq x_0$, there is some open set U_x contains x but does not intersect x_0, therefore x is not a limit point of x_0. We have this fact for arbitraty $x \neq x_0$. So the closure of $\{x_0\}$ is $\{x_0\}$ itself. Therefore $\{x_0\}$ is closed .

The condition that finite point sets be closed is called **T$_1$ axiom**. And T_1 axiom is **weaker** than Hausdorff condition, which means: a topological space that satisfies T_1 axiom may not be a Hausdorff space. We will explain the reason in later chapters.

Theorem 6. *Let X be a space satisfying the T_1 axiom; let A be a subset of X. Then the point x is a limit point of A if and only if every neighborhood of x contains infinitely many points of A.*

Proof. ($\Leftarrow$) : If any neighborhood of x contains infinitely many points of A, the neighborhood must contain some points other than x iteself, so that x is a limit point of A.
($\Rightarrow$) : Conversely, suppose that x is a limit point of A, and suppose there is some open set U containing x but intersects only finitely many points with A. Consider $A \setminus \{x\} \cap U$, denoted by V, then V also has finitely many points.

By T_1 axiom, V is closed in X and $X \setminus V$ is open. Notice that $U \cap (X \setminus V)$ is an open set that contains x. However, this open set intersects an empty set with A, which contradicts the assumption that x is a limit point of A.

Now let's back to the topic of continous function. The following theorem is a generalized property of its $\mathbb{R}$ version

Theorem 7. *Let X and Y be Hausdorff spaces. And f a continous function from X to Y. Let $\{x_n\}$ be a sequence in X and converged to x, then sequence$\{f(x_n)\}$ has a limit, and $\lim\limits_{n \to \infty} f(x_n) = f(\lim\limits_{n \to \infty} x_n)$*

Proof. Let $\lim\limits_{n \to \infty} x_n = x$, then we only need to show that any open set of Y that contains $f(x)$ must contain all elements after of $\{f(x_n)\}$ after some N.

Let $V \underset{open}{\subset} Y$ and $f(x) \in V$, then $x \in f^{-1}(V)$ and $f^{-1}(V) \underset{open}{\subset} X$. Therefore, according to the definition of limit, $\exists N \in \mathbb{N}, \forall n > N, x_n \in f^{-1}(V)$. Therefore, $\forall n > N, f(x_n) \in V$ and the proof is done.

2.3   Homeomorphisms

Definition. (**Homeomorphism**) Let X and Y be topological spaces; let $f : X \to Y$ be a bijection. If both f and f^{-1} are continuous, then f is called **homeomorphism**

The condition that $f^{-1} : Y \to X$ is continuous says that for each open set of X, $(f^{-1})^{-1}(U)$ is open in Y. Notice that $(f^{-1})^{-1}(U) = f(U)$. So the condition actually says that $f(U)$ is open if and only if U is open.

The homeomorphism says that not only every element of X corresponds to some element of Y, there is also a corresponsence between the collection of open sets of X and Y. This is quite similar to the concept of *Isomorphism* which preserves the algebraic structure. *Homeomorphism* is a bijection that preserves the *topological structure*

Let $f : X \to Y$ be an injective continuous function, where X and Y are topological spaces. Let $f(X)$ is subspace topology. Then $f' : X \to f(X)$ is a bijection . If f' happens to be a homeomorphism, then f is called an *imbedding*

Munkres's book provides a very classical example where a function is bijective and continuous without being homeomorphism, which shows that the continuity of f^{-1} is necessary.