

HW3

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1 DPV Problem 4.11

Algorithm

- Step 1 Initialize an adjacent matrix for each element in the graph
- Step 2 for each node n in the graph, run a Dijkstra Shortest Path to each node k in store distance to list at (n, k) (Initialize default distance to ∞)
- Step 3 Initialize a temp variable min_dist to ∞
- Step 4 Loop through each element in the matrix above the diagonal, and sum with its corresponded symmetric value of the matrix diagonal, and update min_dist if the sum is smaller than current min_dist
- Step 5 Return no if the min_dist is ∞ , else min_dist is the required target value

Runtime

- Step 1 initialize size will be $O(v^2)$, where v is the number of element in the graph
 - Step 2 Dijkstra Algorithm will take $O(v^2)$, as describe in lecture, and we will need to loop through each node with the algorithm, so we have $O(v^3)$
 - Step 3 $O(1)$
 - Step 4 Loop will be $O(v^2)$
 - Step 5 $O(1)$
- Conclusion The largest component of the time complexity is $O(v^3)$, so the overall time complexity of the algorithm is $O(v^3)$

2 DPV Problem 4.13

a) Algorithm

Step 1 For all edge e , disconnect all path that has length larger than L , the limitation of the car capacity

Step 2 Start from node s , do an DFS, and stop if node t is reached, and return true

Step 3 Return false if DFS is finish and node t is not found in when search

Runtime

Step 1 $O(|E|)$ for iterating through the graph and disconnect them

Step 2 $O(|E| + |V|)$ for DFS

Step 3 $O(1)$

Conclusion Overall time complexity is $O(|E| + |V|)$, a linear solution

b) Algorithm

Step 1 Start from point s , do an Dijkstra from node s , initialize distance as -1 .

Change the update algorithm: Each time we decrease the distance from node u to v , we keep the $fuel(v) = \max(fuel(u), len(u, v))$.

Step 2 node t 's distance will be the minimum L .

Runtime

Step 1 $O((|E| + |V|) \times \log(|V|))$ for Dijkstra Algorithm, using set implementation for findMinimum.

Step 2 $O(1)$ for return value

Conclusion Overall time complexity is $O((|E| + |V|) \times \log(|V|))$

3 DPV Problem 4.20

Algorithm

Step 1 Do Dijkstra from node s and t , save for later usage.

Step 2 Set result as the distance shortest distance from s to t ; Node $a = s, b = t$ as the final result

Step 3 For each edge e' from available edges, add the edge(u, v) to the graph. Calculate distance from $total_distance = dist(s, u) + len(edge) + dist(v, t)$, while $dist(v, t)$ is the same as $dist(t, v)$ as the it is an undirected graph. If the total_distance is smaller than result, let $result = total_distance$, and node $a = u, b = v$

Step 4 After the iteration, check node a, b . If $a == s, b == t$ then there is no better solution, otherwise the path should be set between node a, b

Runtime

Step 1 Dijkstra's time complexity is $O((|V| + |E|) * \log(|V|))$, using Set implementation

Step 2 $O(1)$ for initialize value

Step 3 $O(|E'|)$ for the for loop

Step 4 $O(1)$ for return value

Conclusion The overall time complexity is $O((|V| + |E|) * \log(|V|))$

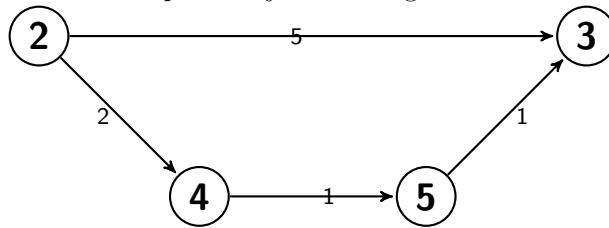
4 DPV Problem 5.5

a) The minimum spanning tree will not change.

Prove by Contradiction

- Assume we have $mst2$, after $+1$ for all edge, and $mst1$ for the original graph; and $mst2$ is different from $mst1$.
- Define $cost()$ as the sum of the total weighted edge of the graph.
- We have $cost(mst1) + (|v| - 1) > cost(mst2)$
- However, based on equation above, we also have: $cost(mst1) > cost(mst2) - (|v| - 1)$. This means that before the $+1$ for all edge, $mst2$ is a better solution for the graph than $mst1$, which is **fishy**
- the tree will not change.

b) The shortest path subject to change. Here is an example



5 DPV Problem 5.6

Prove by Contradiction

1. Assume there are two different $\text{mst}(\text{mst1}, \text{mst2})$ for the distinct tree
2. Since mst1 is different from mst2 , we know there must be at least one edge different between mst1 and mst2
3. Define $\text{cost}()$ collect the sum of the mst
4. since each edge in the graph distinct, we have $\text{cost}(\text{mst1}) \neq \text{cost}(\text{mst2})$
5. Then it must be that mst1 is either better or worse than mst2 , which makes one of them not qualify for being an mst . This conclusion is **fishy**
6. There is only one mst for undirected weighted graph which all edges are unique