

# Machine Learning from Data

Lecture 19: Spring 2021

# Today's Lecture

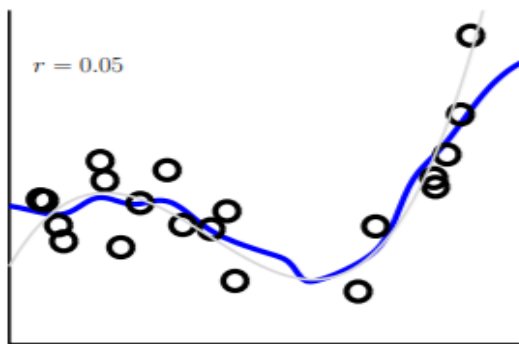
- Unsupervised Learning ✓
- K-means clustering ←
- Probability Density Estimation
- Gaussian Mixture Models

# RECAP: Radial Basis Functions

## Nonparametric RBF

$$g(\mathbf{x}) = \sum_{n=1}^N \left( \frac{\alpha_n(\mathbf{x})}{\sum_{m=1}^N \alpha_m(\mathbf{x})} \right) \cdot y_n$$

$$\alpha_n(\mathbf{x}) = \phi \left( \frac{\|\mathbf{x} - \mathbf{x}_n\|}{r} \right) \quad (\text{bump on } \mathbf{x})$$



No Training

## Parametric $k$ -RBF-Network

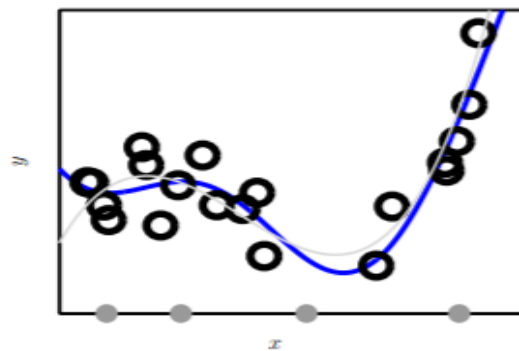
$$h(\mathbf{x}) = w_0 + \sum_{j=1}^k w_j \cdot \phi \left( \frac{\|\mathbf{x} - \boldsymbol{\mu}_j\|}{r} \right)$$

$$= \mathbf{w}^T \boldsymbol{\Phi}(\mathbf{x})$$

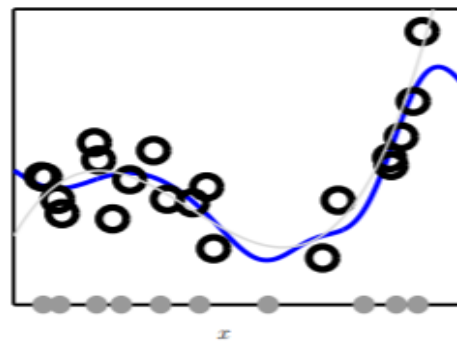
(bump on  $\boldsymbol{\mu}_j$ )

linear model given  $\boldsymbol{\mu}_j$

choose  $\boldsymbol{\mu}_j$  as centers of  $k$ -clusters of data

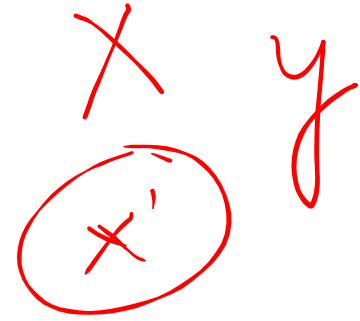


$k = 4, r = \frac{1}{k}$



$k = 10$ , regularized

# Unsupervised Learning



- Preprocessor to organize the data for supervised learning:

Organize data for faster nearest neighbor search

Determine centers for RBF bumps.

- Important to be able to organize the data to identify patterns. ✓

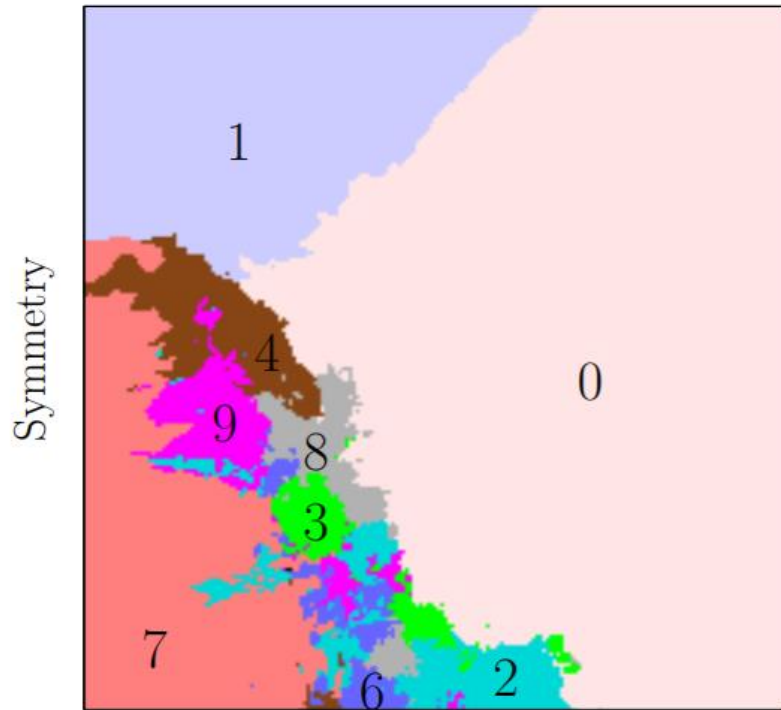
Learn the patterns in data, e.g. the patterns in a language before getting into a supervised setting.

amazon.com organizes books into categories

# Clustering Digits

21-NN rule, 10 Classes

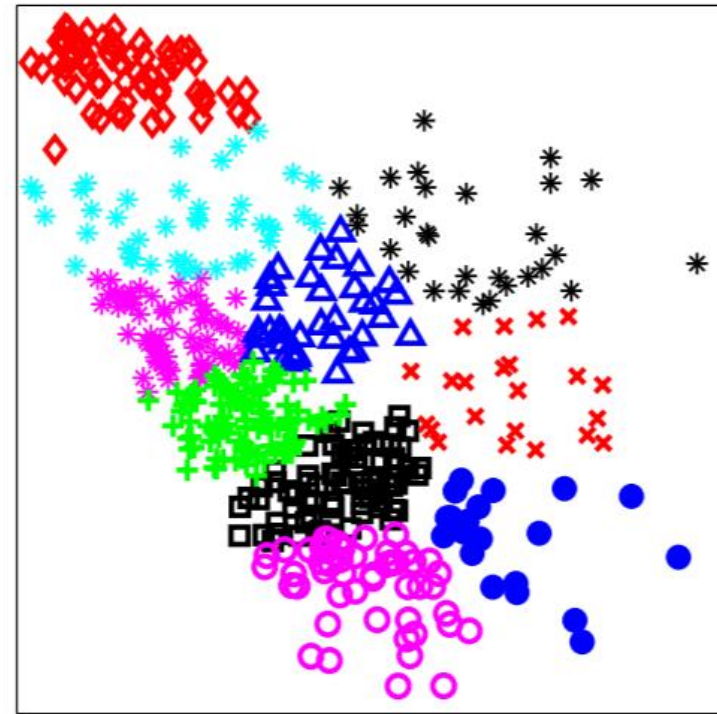
*labels*



Average Intensity



10 Clustering of Data



# Clustering [Unsupervised]

→ Assume we are given  $k$ -subsets.

→  $S_1, S_2, \dots, S_k$

- i) Disjoint (Non overlapping)
- ii) Complete (covers entire dataset)

$$S_i \cap S_j = \emptyset \quad i \neq j$$

$$\bigcup_{i=1}^k S_i = D$$

Trivial

$$\underline{\underline{D}} = [x_1, x_2, \dots, x_N]$$

↓ OUTPUT

Cluster data into  
some subsets

↓  
We need to know  
how many?

What makes clustering good?

- 1) Tightly bound — within cluster ✓
- 2) Well separated — between clusters.

$$s_1, s_2, \dots, s_k \Rightarrow \mu_j$$

$$E_j = \sum_{x_i \in s_j} \|x_i - \mu_j\|^2 \longrightarrow \text{Spread of cluster.}$$

$$E = \sum_{j=1}^k E_j \longrightarrow E \approx \text{small K-means clustering error.}$$

Minimize

$$E = \sum_{n=1}^N \left\| \underline{x}_n - \underset{\uparrow}{\mu(x_n)} \right\|^2$$

Output  $\rightarrow$   $\left. \begin{matrix} S_1 & S_2 & \dots & S_k \\ \mu_1 & \mu_2 & & \mu_k \end{matrix} \right\} \text{NP-hard}$

Alternating Algorithm / Lloyd's  $\rightarrow$  greedily.

- ✓ i)  $\mu_1, \mu_2, \dots, \mu_k$  (given)   
 ✓ ii)  $S_1, S_2, \dots, S_k$  (given)



$$E_j = \sum_{x \in S_j} \|x - \mu_j\|^2$$

$$\mu_j^* = \frac{\sum_{x \in S_j} x}{|S_j|}$$



# Lloyd's Algorithm

- 1) Find the centers  $\mu_1, \mu_2, \dots, \mu_k$ . How?  
→ Randomly selected. (first step)  
OR → Mean vector in  $S_j$
  - 2) Assign data to centers greedily.  
 $\arg \min \|x_n - \mu_j\|^2$
- Repeat until converge.

# Convergence

Change  $\rightarrow$  Error  $\rightarrow$  Improving.  
 $\downarrow$   
decreasing

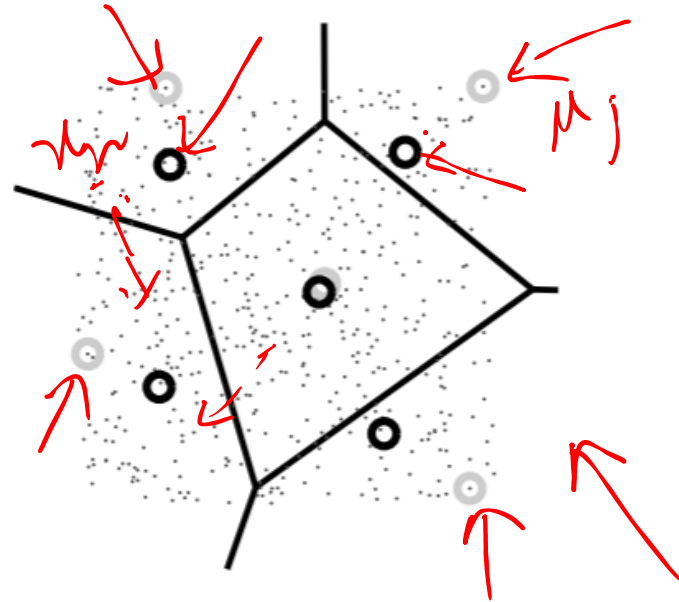
$\rightarrow$  local minima.

## Lloyd's Algorithm for $k$ -Means Clustering

Digits

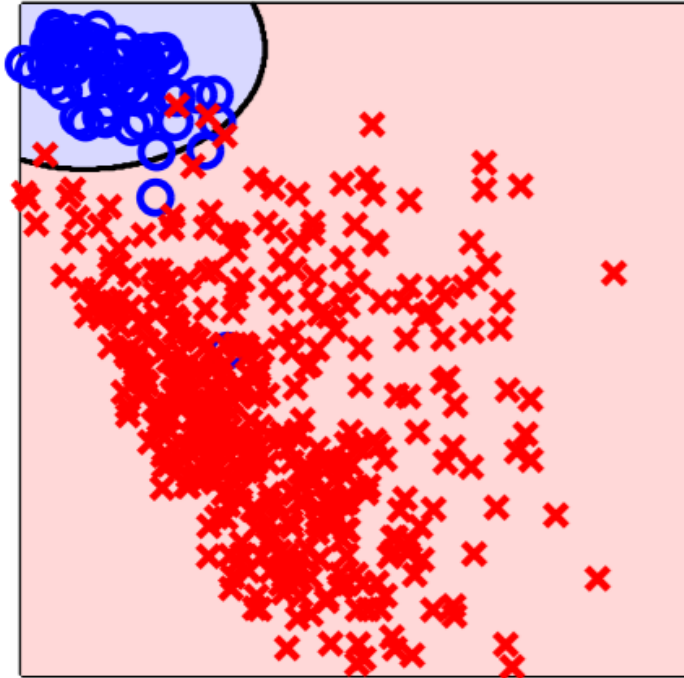
$$E_{\text{in}}(S_1, \dots, S_k; \mu_1, \dots, \mu_k) = \sum_{n=1}^N \| \mathbf{x}_n - \mu(\mathbf{x}_n) \|^2$$

- 1: **Initialize** Pick well separated centers  $\mu_j$ .
- 2: **Update**  $S_j$  to be all points closest  $\mu_j$ .  
 $S_j \leftarrow \{ \mathbf{x}_n : \| \mathbf{x}_n - \mu_j \| \leq \| \mathbf{x}_n - \mu_\ell \| \text{ for } \ell = 1, \dots, k \}.$
- 3: **Update**  $\mu_j$  to the centroid of  $S_j$ .  
$$\mu_j \leftarrow \frac{1}{|S_j|} \sum_{\mathbf{x}_n \in S_j} \mathbf{x}_n$$
- 4: Repeat steps 2 and 3 until  $E_{\text{in}}$  stops decreasing.

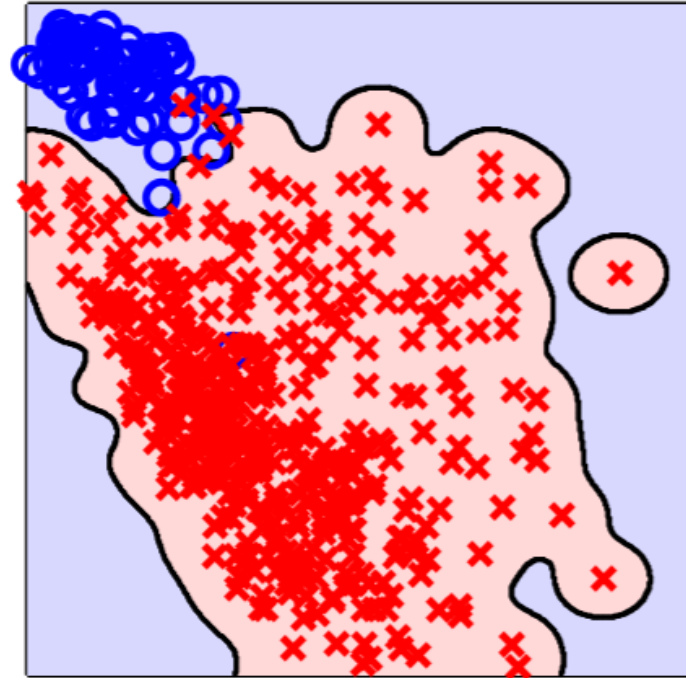


## Application to $k$ -RBF-Network

10-center RBF-network



300-center RBF-network



Overfitting  
↓  
Regularization

Choosing  $k$  - knowledge of problem (10 digits) or CV.

1 VS  
NOT 1



## Probability Density Estimation

$$\underline{\underline{P(\mathbf{x})}}$$

Data  $\rightarrow P(x)$   
Test  $\rightarrow$

$\rightarrow P(\mathbf{x})$  measures how likely it is to generate inputs *similar* to  $\mathbf{x}$ .

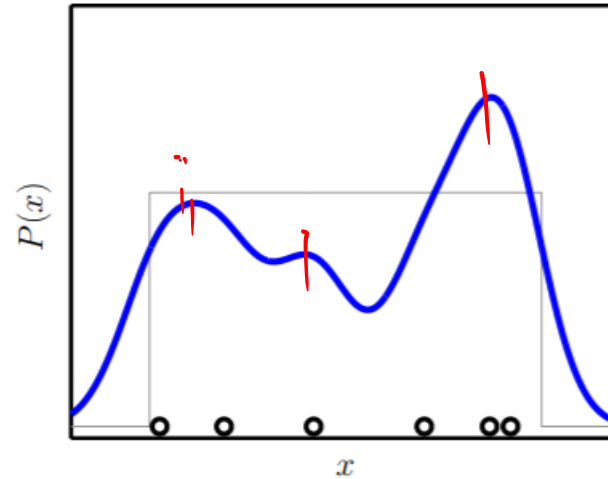
Similarity

Estimating  $P(\mathbf{x})$  results in a 'softer/finer' representation than clustering

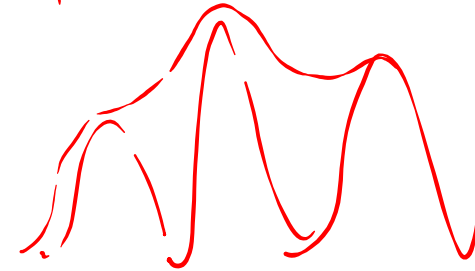
Clusters are regions of high probability.

## Parzen Windows – RBF density estimation

Basic idea: put a bump of ‘size’ (volume)  $\frac{1}{N}$  on each data point.



Normalized  
prob. density



$$\phi(z) = \frac{1}{(2\pi)^{d/2}} e^{-\frac{1}{2}z^2}$$

$$\hat{P}(\mathbf{x}) = \frac{1}{Nr^d} \sum_{i=1}^N \phi\left(\frac{\|\mathbf{x} - \mathbf{x}_i\|}{r}\right)$$

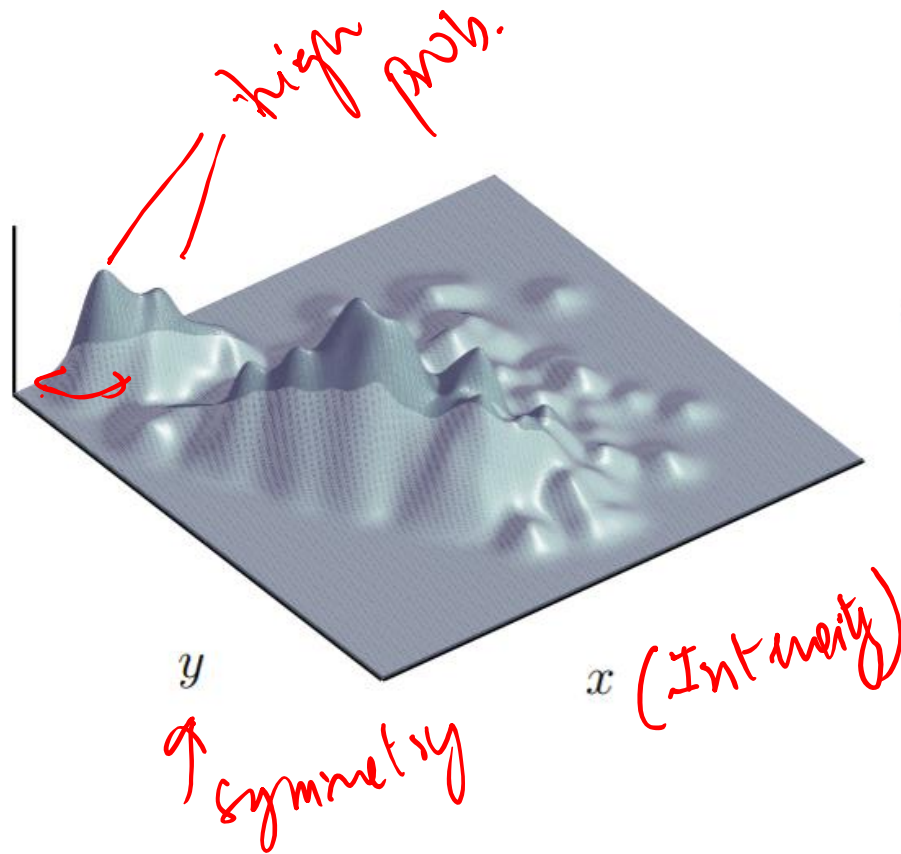
scale

$\frac{1}{N}$

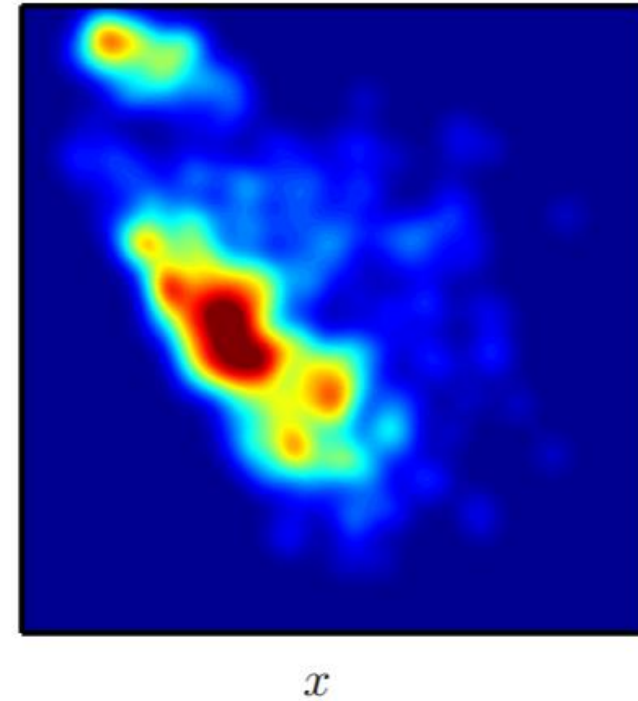
## Digits Data

Non-parametric  
RBF

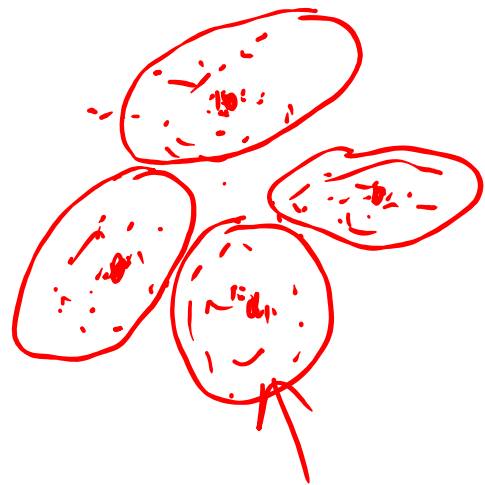
RBF Density Estimate



Density Contours



# Gaussian Mixture Model (GMM)



$$k=4$$

$$\mu_1, \mu_2, \mu_3, \mu_4$$

Shape: Covariance Matrix

$$\Sigma_1, \Sigma_2, \Sigma_3, \Sigma_4$$

Bump weights

$$w_1, w_2, w_3, w_4$$

gaussian density.

GMM

$$\hat{P}(x) = \sum_{k=1}^K w_k N(x, \mu_k, \Sigma_k)$$



$$N(x, \mu, \Sigma)$$

mean

covariance matrix

$$x_1, x_2, \dots, x_n$$

$$N(x, \mu, \Sigma) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}}$$

$$e^{-1/2 (x-\mu)^T \Sigma^{-1} (x-\mu)}$$

$$\frac{1}{n} \sum x_i = E[x] = \mu$$

$$\frac{1}{n} \sum x_i x_i^T \Rightarrow E[xx^T] = \mu\mu^T + \Sigma$$

$$\hat{P}(x) = \sum_{k=1}^K \omega_k \mathcal{N}(x, \mu_k, \Sigma_k), \quad \omega_k \geq 0$$

$\sum_{k=1}^K \omega_k = 1$

$(\omega_j, \mu_k, \Sigma_j)$   
 $\downarrow$   $\downarrow$   $\downarrow$   
 weights    centers    shapes.

Pick in such a way  $\rightarrow$  max. the prob. to generate the data  $x_1, x_2, \dots, x_L$

Maximum Likelihood.

## Expectation Maximization

1) we know which  $x_n$  belongs to which bump  
→  $\mu_j \times \sum_j x_j \times w_j$

2) if we know  $\{w_j, \mu_j, \sum_j\}$  → which  $x_n$  belongs to  $j$

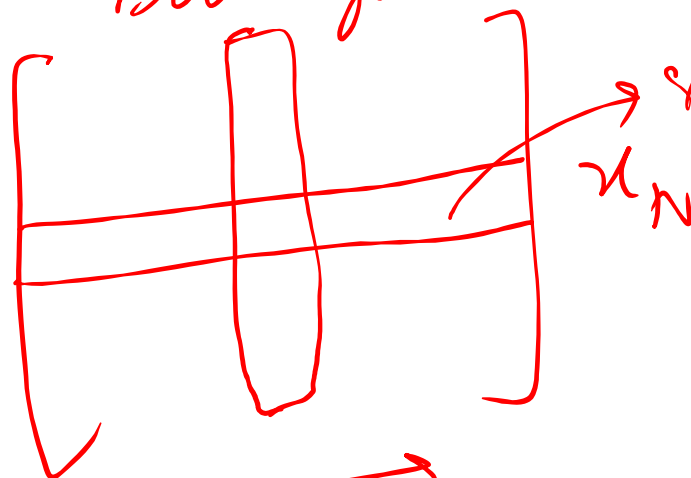
Algo

1) Initialization:

membership  
variable  $v_{nj}$

$v_{nj}$  = The fraction of data point  $x_n$  that belongs to cluster  $j$

$$n = 1 \dots N$$



$\sum_n v_{nj} = 1$

$$v_{nj} \geq 0$$

$$\sum_j v_{nj} = 1$$

Assume we know

$$\{v_{nj}\}$$

$$\left. \begin{aligned} N_j &= \sum_{n=1}^N v_{nj} \\ N &= \sum_j N_j \end{aligned} \right\}$$

Volume  $\omega_j = \frac{N_j}{N}$

$$\mu_j = \frac{\sum_{n=1}^N w_{nj} x_n}{N_j}$$

$$\Sigma_j = \frac{1}{N_j} \sum_{n=1}^N w_{nj} x_n x_n^T - \mu_j \mu_j^T$$

② Update  $w_{nj} = \frac{P[x_n \text{ came from bump } j]}{\sum_j P[x_n \text{ came from bump } j]}$

$$= \frac{\omega_j N(x_n | \mu_j, \Sigma_j)}{\sum_j \omega_j N(x_n | \mu_j, \Sigma_j)}$$

③ Repeat  
Until convergence



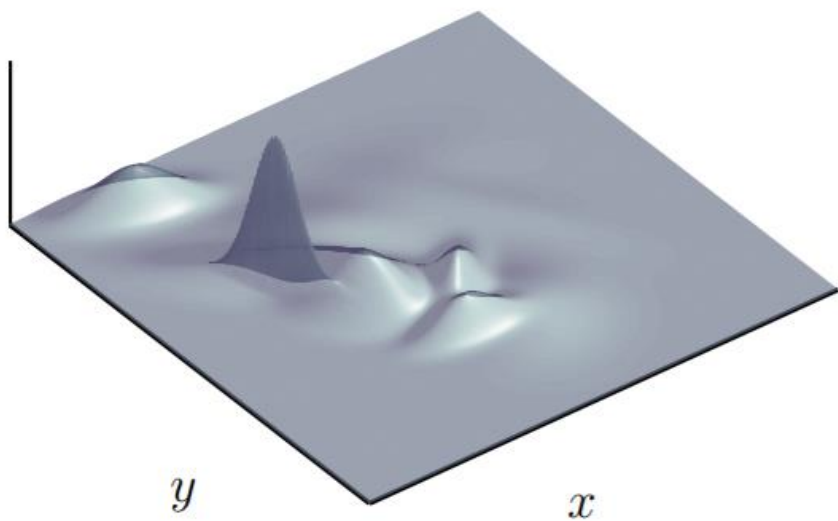
# E-M Algorithm

## E-M Algorithm for GMMs:

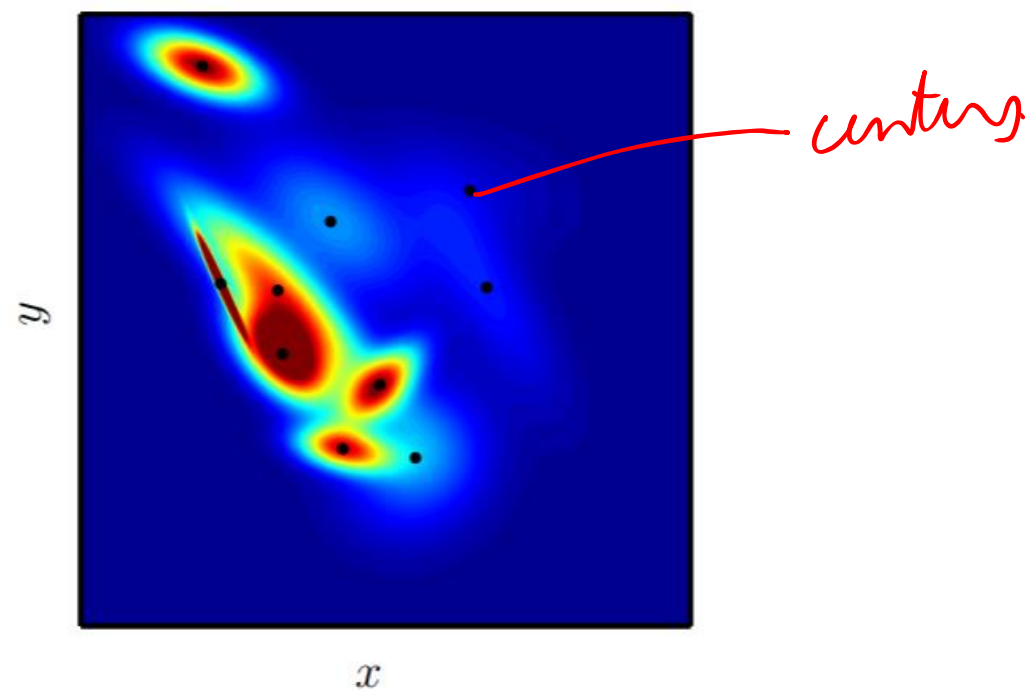
- 1: Start with estimates for the bump membership  $\gamma_{nj}$ .
- 2: Estimate  $w_j, \boldsymbol{\mu}_j, \Sigma_j$  given the bump memberships.
- 3: Update the bump memberships given  $w_j, \boldsymbol{\mu}_j, \Sigma_j$ ;
- 4: Iterate to step 2 until convergence.

## GMM on Digits Data

10-center GMM



Density Contours





Thanks!