

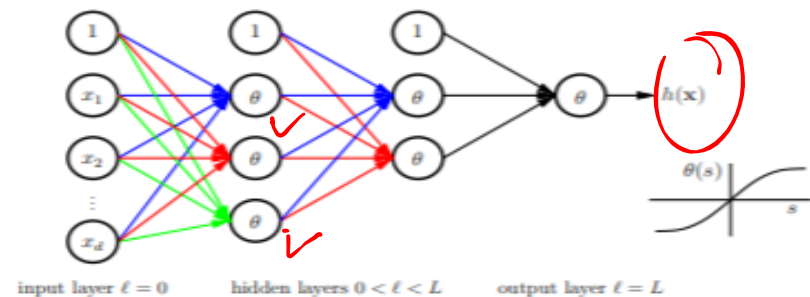
# Machine Learning from Data

Lecture 21: Spring 2021

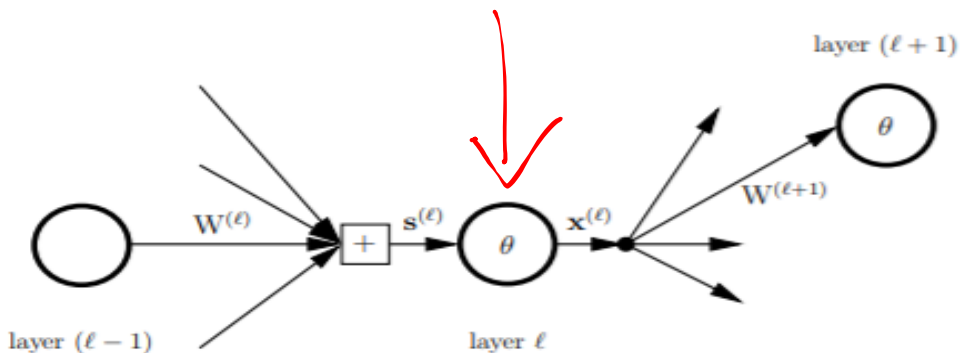
# Today's Lecture

- Neural Networks
  - Forward Propagation ✓
  - Backward Propagation
  - Overfitting

Recap



NN



layer  $\ell$  parameters

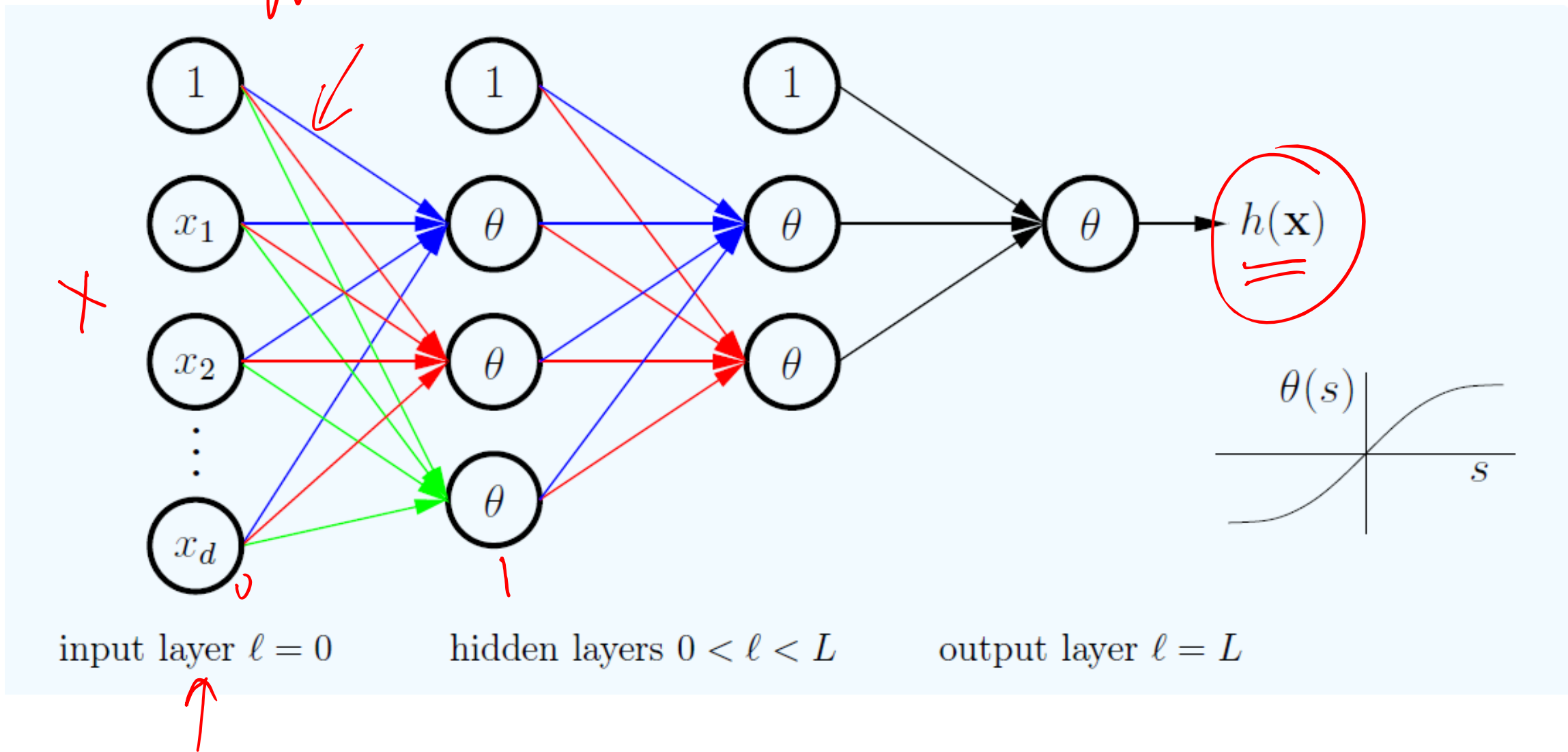
signals in	$\mathbf{s}^{(\ell)}$	$d^{(\ell)}$ dimensional input vector
outputs	$\mathbf{x}^{(\ell)}$	$d^{(\ell)} + 1$ dimensional output vector
weights in	$\mathbf{W}^{(\ell)}$	$(d^{(\ell-1)} + 1) \times d^{(\ell)}$ dimensional matrix
weights out	$\mathbf{W}^{(\ell+1)}$	$(d^{(\ell)} + 1) \times d^{(\ell+1)}$ dimensional matrix



layers  $\ell = 0, 1, 2, \dots, L$   
 layer  $\ell$  has "dimension"  $d^{(\ell)} \implies d^{(\ell)} + 1$  nodes

$$\mathbf{W}^{(\ell)} = \begin{bmatrix} \mathbf{w}_1^{(\ell)} & \mathbf{w}_2^{(\ell)} & \dots & \mathbf{w}_{d^{(\ell)}}^{(\ell)} \\ \vdots & \vdots & \ddots & \vdots \end{bmatrix}$$

$\mathbf{W}^{(1)} \quad \mathbf{W}^{(2)} \quad \dots \quad \mathbf{W}^{(L)}$



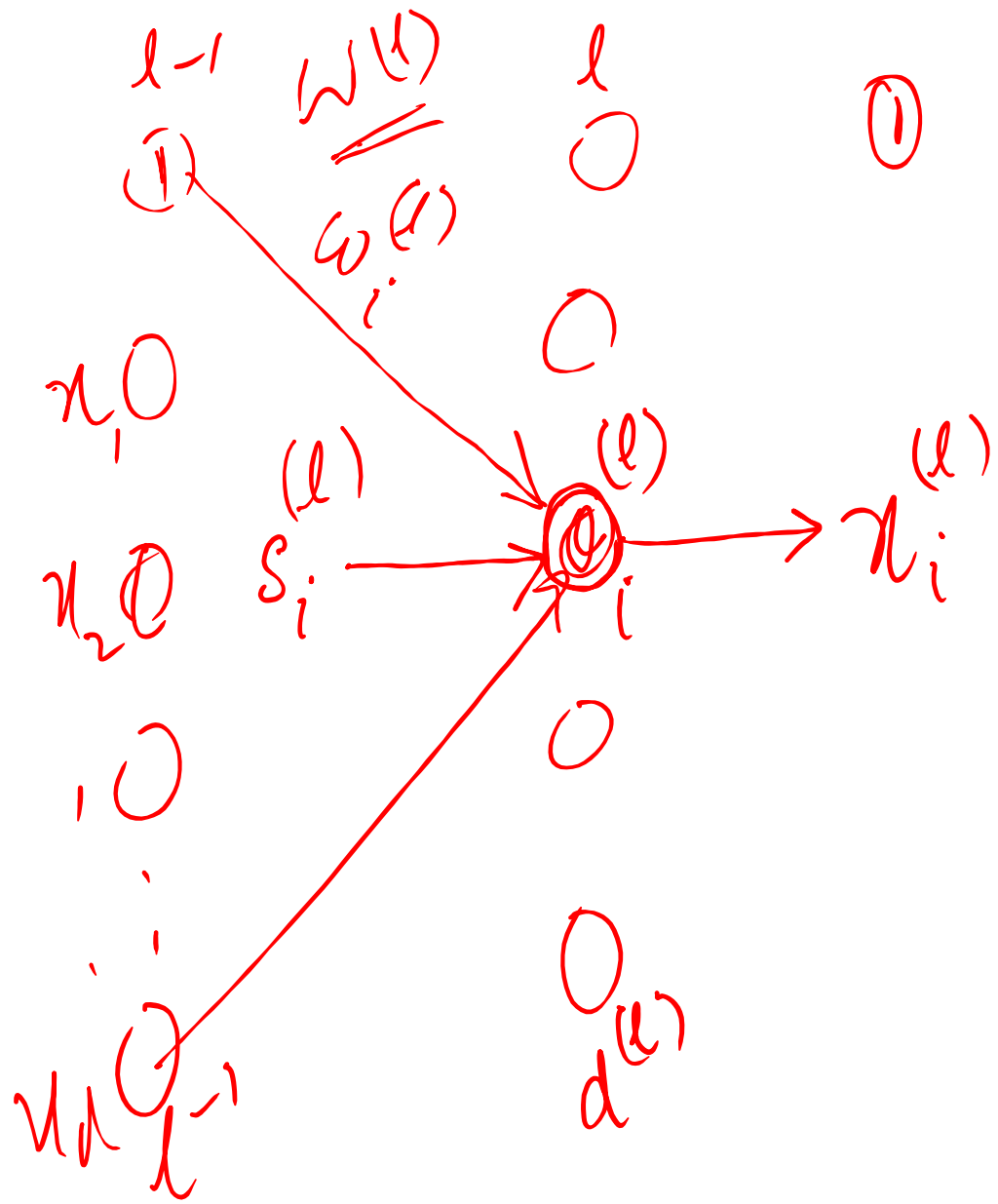


Diagram illustrating the hidden layer output function:

A circle node is connected to  $h(x)$ .

The hidden layer output vector  $S^{(l)}$  is defined as:

$$S^{(l)} = \begin{bmatrix} s_1^{(l)} \\ s_2^{(l)} \\ \vdots \\ s_{d^{(l)}}^{(l)} \end{bmatrix}$$

The input vector  $x^{(l)}$  is defined as:

$$x^{(l)} = \begin{bmatrix} 1 \\ x_1^{(l)} \\ x_2^{(l)} \\ \vdots \\ x_d^{(l)} \end{bmatrix}_{d^{(l)}+1}$$

$$W^{(l)} = \begin{bmatrix} w_1^{(l)} & w_2^{(l)} & \dots & w_d^{(l)} \end{bmatrix}$$

perception

$d$ -dimensional

$d^{(l-1)} + 1$

Forward Propagation Algorithm

$$W = \left\{ \begin{matrix} W^{(1)} \\ W^{(2)} \\ W^{(3)} \end{matrix} \right\}$$

$\nwarrow_{0,1}$   $\nwarrow_{1,2}$   $\nwarrow_{2,3}$

$$\theta_i^l \rightarrow s_i^{(l)} = (w_i^{(l)})^T x^{(l-1)}$$

weight of perception

linear signal

$x^{(l-1)}$

Signal

$$s^l = (w^{(l)})^T x^{(l-1)}$$

$$X^l = \begin{bmatrix} 1 \\ \theta(s^l) \end{bmatrix}$$

$$s^l = \begin{bmatrix} s_1^{(l)} \\ s_2^{(l)} \\ \vdots \\ s_d^{(l)} \end{bmatrix} = \begin{bmatrix} (w_1^{(l)})^T \\ (w_2^{(l)})^T \\ \vdots \\ (w_d^{(l)})^T \end{bmatrix} x^{(l-1)}$$

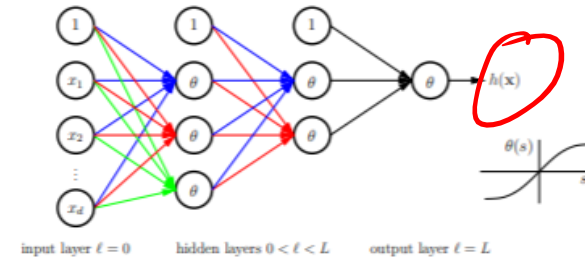




# The Linear Signal

Input  $\mathbf{s}^{(\ell)}$  is a linear combination (using weights) of the outputs of the previous layer  $\mathbf{x}^{(\ell-1)}$ .

$$\mathbf{s}^{(\ell)} = (\mathbf{W}^{(\ell)})^T \mathbf{x}^{(\ell-1)}$$



$$\begin{bmatrix} s_1^{(\ell)} \\ s_2^{(\ell)} \\ \vdots \\ s_j^{(\ell)} \\ \vdots \\ s_{d^{(\ell)}}^{(\ell)} \end{bmatrix} = \begin{bmatrix} (\mathbf{w}_1^{(\ell)})^T \text{---} \\ (\mathbf{w}_2^{(\ell)})^T \text{---} \\ \vdots \\ (\mathbf{w}_j^{(\ell)})^T \text{---} \\ \vdots \\ (\mathbf{w}_{d^{(\ell)}}^{(\ell)})^T \text{---} \end{bmatrix} \mathbf{x}^{(\ell-1)}$$

$$s_j^{(\ell)} = (\mathbf{w}_j^{(\ell)})^T \mathbf{x}^{(\ell-1)}$$

(recall the linear signal  $s = \mathbf{w}^T \mathbf{x}$ )

$$\mathbf{s}^{(\ell)} \xrightarrow{\theta} \mathbf{x}^{(\ell)}$$

# Forward prop. algo-

$$W = \{W_{\#}^{(1)} \quad W_{\#}^{(2)} \quad \dots \quad W_{\#}^{(L)}\}$$

1) Initialize  $x^{(0)} = x, l=0$   $h(x) \rightarrow \text{goal}$

2) Propagate, set  $l = l+1$   
$$\underline{s^l} = \left( W_{\#}^{(l)} \right)^T \underset{\uparrow}{x^{(l-1)}}$$

$$x^l = \begin{bmatrix} 1 \\ \sigma(s^l) \end{bmatrix}$$

Repeat

3)  $x^{(L)} \rightarrow \underline{h(x)} = x_1^{(L)}$

$$x = \begin{bmatrix} 1 \\ x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

## Forward Propagation: Computing $h(\mathbf{x})$

$$\mathbf{x} = \mathbf{x}^{(0)} \xrightarrow{w^{(1)}} \mathbf{s}^{(1)} \xrightarrow{\theta} \mathbf{x}^{(1)} \xrightarrow{w^{(2)}} \mathbf{s}^{(2)} \xrightarrow{\theta} \mathbf{x}^{(2)} \dots \xrightarrow{w^{(L)}} \mathbf{s}^{(L)} \xrightarrow{\theta} \mathbf{x}^{(L)} = h(\mathbf{x}).$$

Forward propagation to compute  $h(\mathbf{x})$ :

1:  $\mathbf{x}^{(0)} \leftarrow \mathbf{x}$

[Initialization] ✓

2: **for**  $\ell = 1$  to  $L$  **do**

[Forward Propagation] ✓

3:  $\mathbf{s}^{(\ell)} \leftarrow (\mathbf{W}^{(\ell)})^T \mathbf{x}^{(\ell-1)}$  ←

4:  $\mathbf{x}^{(\ell)} \leftarrow \begin{bmatrix} 1 \\ \theta(\mathbf{s}^{(\ell)}) \end{bmatrix}$  ←

5: **end for**

6:  $h(\mathbf{x}) = \mathbf{x}^{(L)}$

[Output]

Data

$$\begin{array}{ccc} x_1 & y_1 & \xrightarrow{NN} h(x_1) \\ x_2 & y_2 & \xrightarrow{NN} h(x_2) \end{array}$$

$$x_n \quad y_n \xrightarrow{NN} h(x_n)$$

$$w^{(1)} \quad w^{(2)} \quad w^{(3)} \dots w^{(L)}$$

$$E_{in}(h) = \frac{1}{N} \sum_{i=1}^N (h(x_n) - y_n)^2$$

$$E_{in}(h) = \frac{1}{N} \sum_{i=1}^N e(h(x_n), y_n)$$

Know  $\rightarrow$  W's  $\rightarrow$  find weights that minimize  $E_{in}$

$$W^{(0)} \leftarrow W^{(1)} - \alpha \frac{\partial E_{in}}{\partial W^{(1)}}$$

learning  
rate

$$\frac{\partial E_{in}}{\partial W^{(1)}} = \frac{1}{N} \sum_{n=1}^N \frac{\partial e(h(x_n), y_n)}{\partial W^{(1)}}$$

Summary  $\rightarrow$  Compute Output  $\times$   
 Creating weights  $\Leftrightarrow$  fitting data.

In practice

$$|W| = W^1 + W^2 + \dots + W^L$$

$$|V| = \text{No. of nodes } (O) \rightarrow \tanh$$

$E_{in} \rightarrow$  how many computations?

$$\frac{N|W| + N|V|}{}$$

$$w_{ij}^{(l)} \rightarrow$$

$$\frac{\partial E_{in}}{\partial w_{ij}^{(l)}}$$

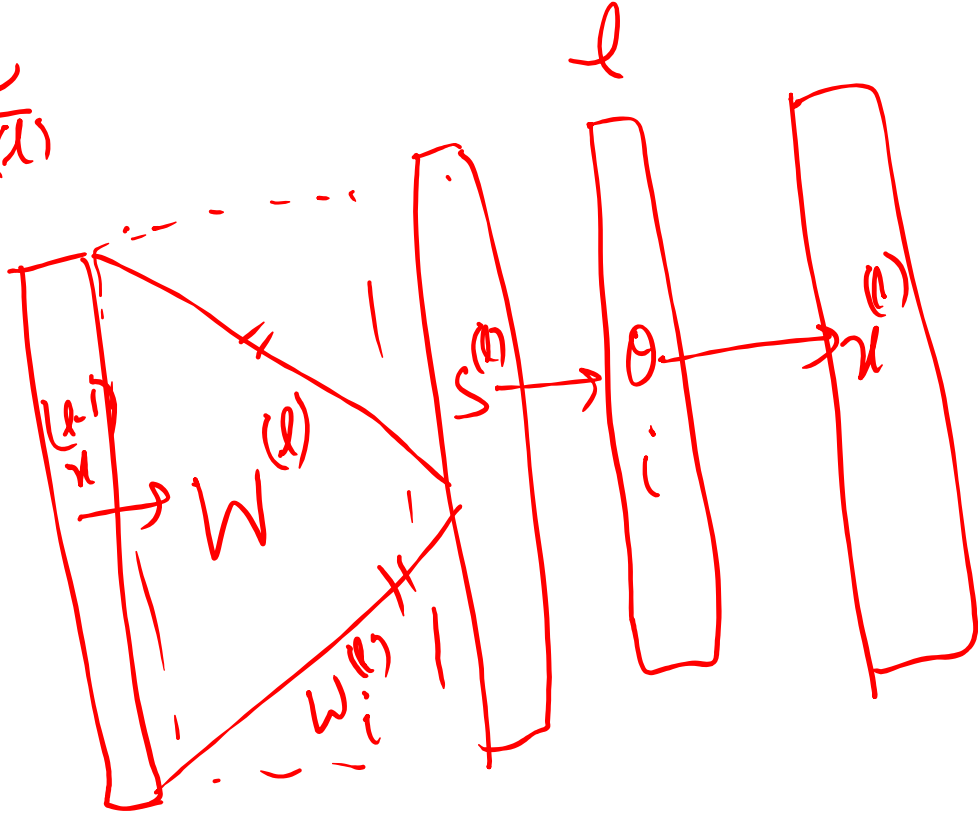
$$\frac{E_{in}(w_{ij}^{(l)} + \triangle) - E_{in}(w_{ij}^{(l)} - \triangle)}{2 \triangle}$$

tolerance

$$O\left((N|W| + N|V|) \underset{\uparrow}{|W|}\right)$$

# BACKPROPAGATION ALGORITHM

$$\frac{\partial \ell}{\partial W^{(l)}} \rightarrow$$



$$\frac{\partial \ell}{\partial W_i^{(l)}}$$

Chain Rule

$$\frac{\partial e}{\partial W_i^{(l)}} = \frac{\partial s_i^{(l)}}{\partial W_i^{(l)}} \times \frac{\partial e}{\partial s_i^{(l)}}$$

$$s_i^{(l)} = (W_i^{(l)})^T x^{(l-1)}$$

$$\frac{\partial s_i^{(l)}}{\partial W_i^{(l)}} = x^{(l-1)}$$

$$\therefore \frac{\partial e}{\partial W_i^{(l)}} = x^{(l-1)} \times \frac{\partial e}{\partial s_i^{(l)}}$$

→  $\frac{\partial e}{\partial W_i^{(l)}}$

$$\frac{\partial e}{\partial W^{(l)}} = \begin{bmatrix} x^{(l-1)} \frac{\partial e}{\partial s_1^{(l)}} & x^{(l-1)} \frac{\partial e}{\partial s_2^{(l)}} & \dots & x^{(l-1)} \frac{\partial e}{\partial s_d^{(l)}} \end{bmatrix}$$

$$\frac{\partial e}{\partial W^{(l)}} = \underbrace{x^{(l-1)}}_{\substack{\text{previous} \\ \text{layer}}} \left( \frac{\partial e}{\partial s^{(l)}} \right)^T \leftarrow \text{vector of derivatives}$$

$(\delta^{(l)})^T \rightarrow \text{sensitivity}$



$$\frac{\partial e}{\partial s^{(l)}}_i$$

$$\therefore \frac{\partial e}{\partial s^{(l)}_i} = \frac{\partial e}{\partial x^{(l)}_i} \times \frac{\partial x^{(l)}_i}{\partial s^{(l)}_i} \quad \left. \vphantom{\frac{\partial e}{\partial s^{(l)}_i}} \right\} x^{(l)}_i = \theta(s^{(l)}_i)$$

$$\therefore \frac{\partial e}{\partial s^{(l)}_i} = \theta'(s^{(l)}_i) \cdot \frac{\partial e}{\partial x^{(l)}_i}$$

$$\frac{\partial e}{\partial s^{(l)}} = \theta'(s^{(l)}) \otimes$$

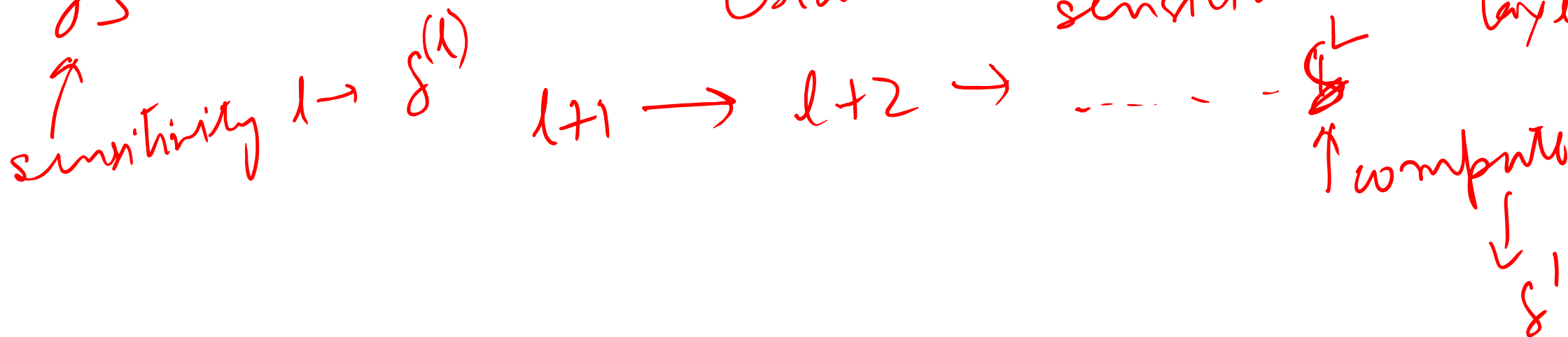
$$\left[ \frac{\partial e}{\partial x^{(l)}} \right]_1 \leftarrow d^{(l)}$$

$$\begin{aligned} \frac{\partial e}{\partial x^{(l)}} &= \sum_{k=1}^{d^{(l+1)}} \frac{\partial e}{\partial s^{(l+1)}_k} \cdot \frac{\partial s^{(l+1)}_k}{\partial x^{(l)}} \\ \therefore s^{(l+1)}_k &= (w^{(l+1)}_k)^T x^{(l)} \\ \frac{\partial e}{\partial x^{(l)}} &= \sum_{k=1}^{d^{(l+1)}} w^{(l+1)}_k \frac{\partial e}{\partial s^{(l+1)}_k} \end{aligned}$$

$$\frac{\partial e}{\partial x^{(l)}} = \underline{w^{(l+1)}} \delta^{(l+1)} \leftarrow \text{sensitivity}$$

$$\frac{\partial e}{\partial s^{(l)}} = \theta'(s^{(l)}) \otimes [w^{(l+1)} \delta^{(l+1)}]$$

Established a relation between sensitivities across layers.



$$1) \frac{\partial \mathcal{L}}{\partial w^{(l)}} = x^{(l-1)} (s')^T \checkmark$$

$$2) \delta^{(l)} = \theta'(s^{(l)}) \otimes [w^{(l+1)} s^{(l+1)}]^{d^{(l)}}$$

$(1 \times d^{(l-1)}) \times d^{(l)}$

## STOCHASTIC GRADIENT DESCENT

$$1) \text{ Pick } x_n$$

$$2) x_n = x^{(0)} \xrightarrow{w^{(1)}} s^{(1)} \xrightarrow{\theta} x^{(1)} \xrightarrow{\dots} s^{(2)} \xrightarrow{\theta} x^{(2)} \dots$$

$$\xrightarrow{\dots} x^{(L)} = h(x_n)$$

$$e(h(x_n), y_n)$$

3) Run BACKPROPAGATION

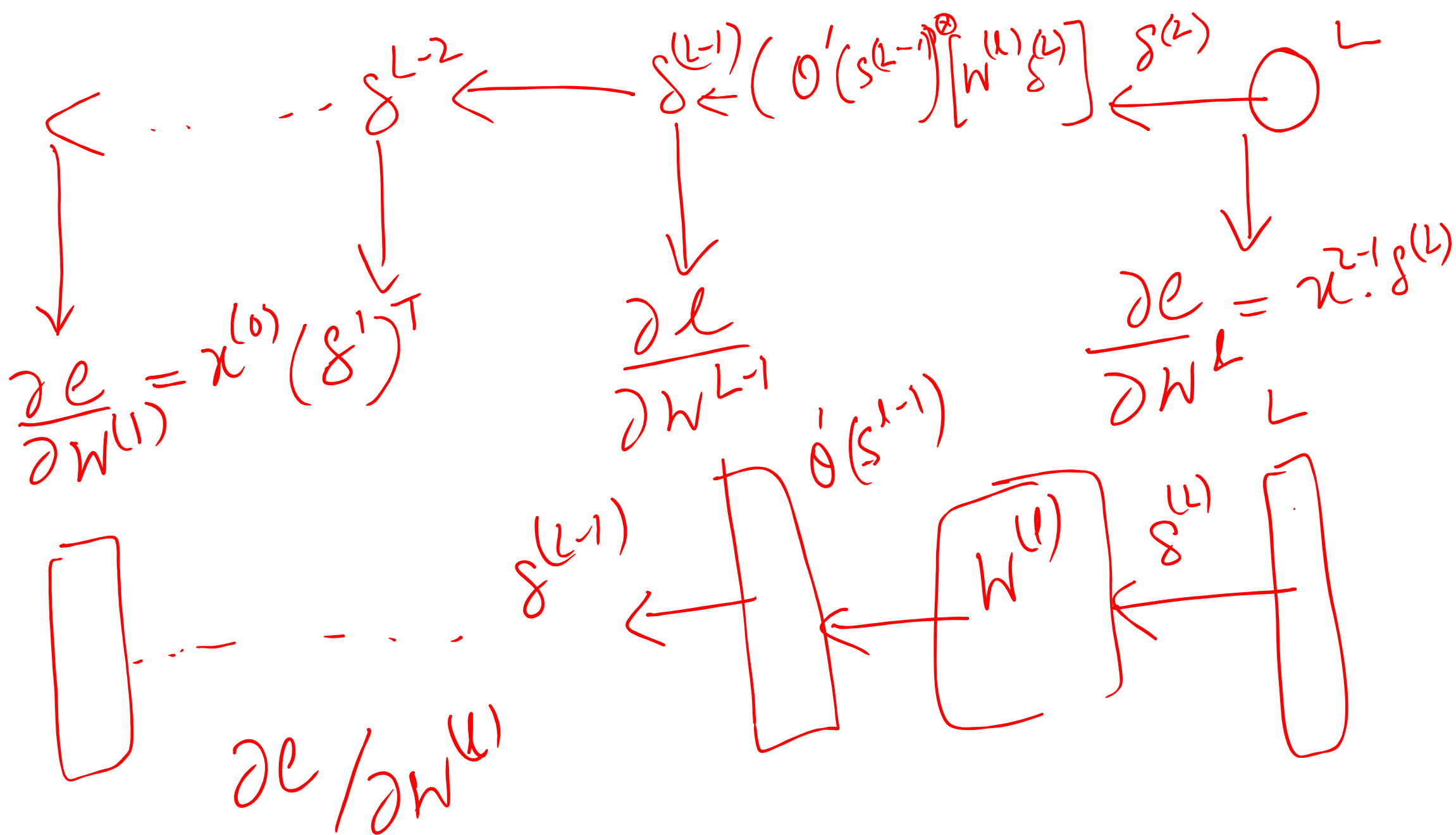
$$\delta^{(L)} = \frac{\partial e}{\partial s^{(L)}}, \quad e = (x^{(L)} - y_n)^2$$

$$\delta^{(L)} = \frac{\partial (x^{(L)} - y_n)^2}{\partial s^{(L)}} = 2(x^{(L)} - y_n) \cdot \frac{\partial x^{(L)}}{\partial s^{(L)}} = 2(x^{(L)} - y_n) \cdot \theta'(s^{(L)})$$

$$\delta^{(L)} = 2(x^{(L)} - y_n) (1 - \tanh^2(s^{(L)}))$$

$$= 2(x^{(L)} - y_n) (1 - (x^{(L)})^2)$$

$$\frac{\partial e}{\partial (w^{(L)})} = x^{(L-1)} \cdot \delta^{(L)}$$



Update step

$$W^{(n)} \leftarrow W^{(n)} - \eta \frac{\partial \mathcal{L}}{\partial W^{(n)}} \quad \checkmark$$

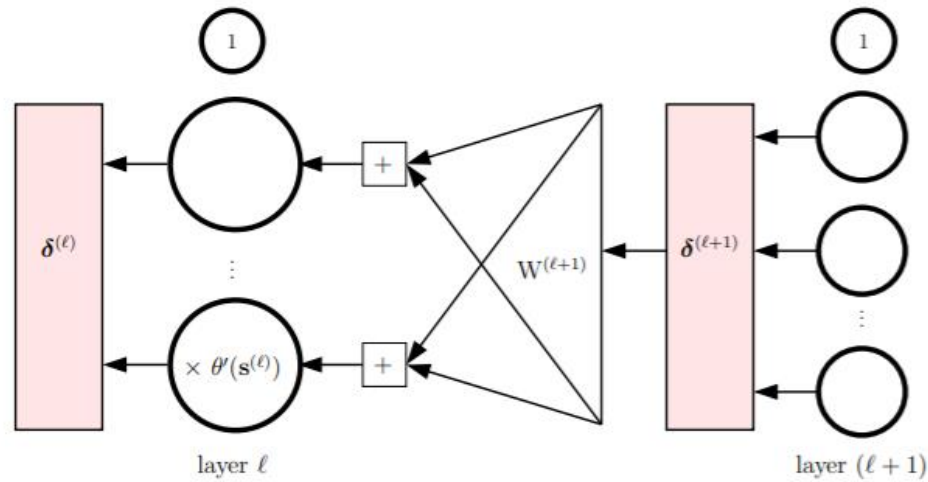
SGD, Batch grad. descent.

## Computing $\delta^{(\ell)}$ Using the Chain Rule

$$\delta^{(1)} \leftarrow \delta^{(2)} \dots \leftarrow \delta^{(L-1)} \leftarrow \delta^{(L)}$$

Multiple applications of the chain rule:

$$\Delta \mathbf{s}^{(\ell)} \xrightarrow{\theta} \Delta \mathbf{x}^{(\ell)} \xrightarrow{W^{(\ell+1)}} \Delta \mathbf{s}^{(\ell+1)} \dots \longrightarrow \Delta \mathbf{e}(\mathbf{x})$$



$$\delta^{(\ell)} = \theta'(\mathbf{s}^{(\ell)}) \otimes [W^{(\ell+1)}\delta^{(\ell+1)}]_1^{d^{(\ell)}}$$

$\downarrow$  don't use 0<sup>th</sup> component (bias)  
 $\uparrow$  componentwise multiplication

## The Backpropagation Algorithm

$$\delta^{(1)} \longleftarrow \delta^{(2)} \dots \longleftarrow \delta^{(L-1)} \longleftarrow \delta^{(L)}$$

**Backpropagation to compute sensitivities  $\delta^{(\ell)}$ :**

*(Assume  $\mathbf{s}^{(\ell)}$  and  $\mathbf{x}^{(\ell)}$  have been computed for all  $\ell$ )*

1:  $\delta^{(L)} \longleftarrow 2(x^{(L)} - y) \cdot \theta'(s^{(L)})$  [Initialization] ✓

2: **for**  $\ell = L - 1$  to 1 **do** [Back-Propagation]

3:   Compute (for tanh hidden node):

$$\theta'(\mathbf{s}^{(\ell)}) = \left[ 1 - \mathbf{x}^{(\ell)} \otimes \mathbf{x}^{(\ell)} \right]_1^{d^{(\ell)}}$$

4:    $\delta^{(\ell)} \longleftarrow \theta'(\mathbf{s}^{(\ell)}) \otimes [\mathbf{W}^{(\ell+1)} \delta^{(\ell+1)}]_1^{d^{(\ell)}}$   $\longleftarrow$  componentwise multiplication

5: **end for**



## Algorithm for Gradient Descent on $E_{\text{in}}$

**Algorithm to Compute  $E_{\text{in}}(\mathbf{w})$  and  $\mathbf{g} = \nabla E_{\text{in}}(\mathbf{w})$ :**

**Input:** weights  $\mathbf{w} = \{W^{(1)}, \dots, W^{(L)}\}$ ; data  $\mathcal{D}$ .

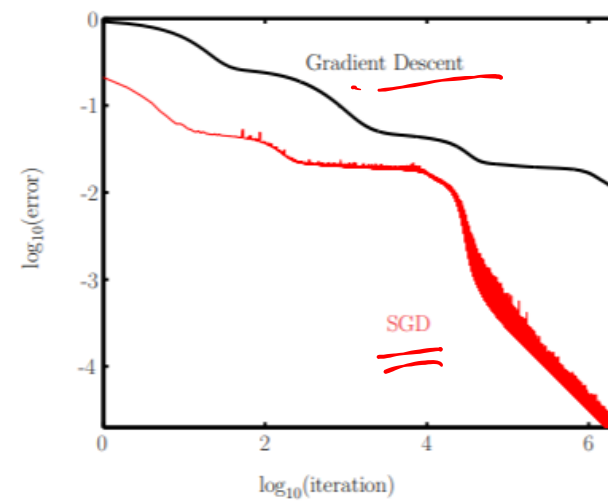
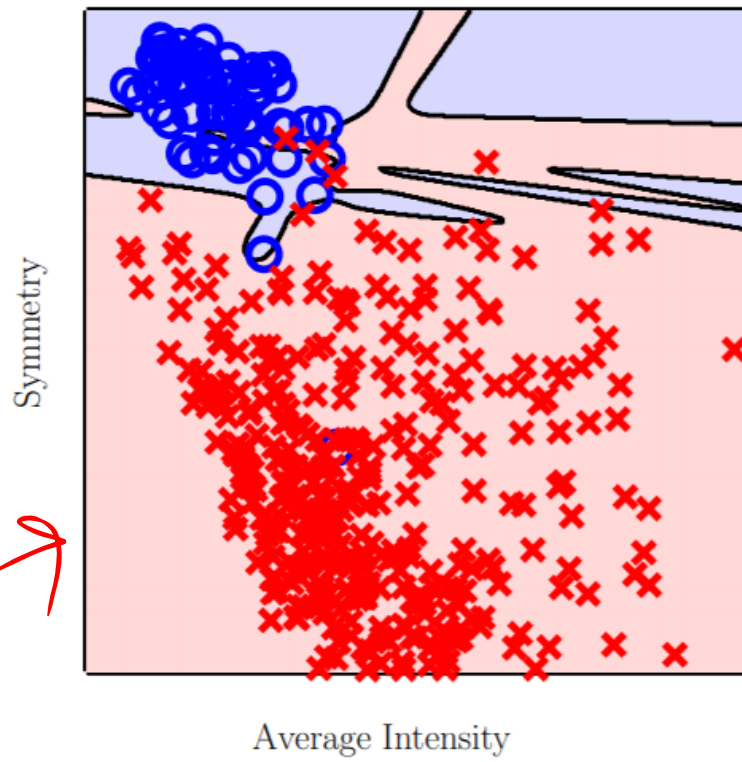
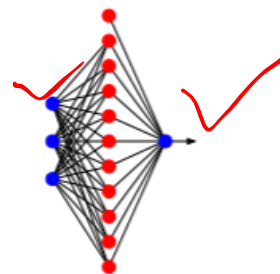
**Output:** error  $E_{\text{in}}(\mathbf{w})$  and gradient  $\mathbf{g} = \{G^{(1)}, \dots, G^{(L)}\}$ .

```
1: Initialize:  $E_{\text{in}} = 0$ ; for  $\ell = 1, \dots, L$ ,  $G^{(\ell)} = 0 \cdot W^{(\ell)}$  .
2: for Each data point  $\mathbf{x}_n$  ( $n = 1, \dots, N$ ) do
3:   Compute  $\mathbf{x}^{(\ell)}$  for  $\ell = 0, \dots, L$ . [forward propagation]
4:   Compute  $\boldsymbol{\delta}^{(\ell)}$  for  $\ell = 1, \dots, L$ . [backpropagation]
5:    $E_{\text{in}} \leftarrow E_{\text{in}} + \frac{1}{N}(\mathbf{x}_1^{(L)} - y_n)^2$ .
6:   for  $\ell = 1, \dots, L$  do
7:      $G^{(\ell)}(\mathbf{x}_n) = [\mathbf{x}^{(\ell-1)}(\boldsymbol{\delta}^{(\ell)})^T]$ 
8:      $G^{(\ell)} \leftarrow G^{(\ell)} + \frac{1}{N}G^{(\ell)}(\mathbf{x}_n)$ .
9:   end for
10: end for
```

Can do batch version or sequential version (SGD).

## Digits Data

Overfitting



Thanks!