




# Machine Learning from Data

Lecture 22: Spring 2021

# Today's Lecture

- Neural Networks and Overfitting
  - Approximation Vs Generalization 
  - Regularization and Early Stopping 
  - Minimizing in-sample error more efficiently 

# RECAP: Neural Networks and Fitting the Data

## Forward Propagation:

$$\mathbf{x} = \mathbf{x}^{(0)} \xrightarrow{W^{(1)}} \mathbf{s}^{(1)} \xrightarrow{\theta} \mathbf{x}^{(1)} \xrightarrow{W^{(2)}} \mathbf{s}^{(2)} \dots \xrightarrow{W^{(L)}} \mathbf{s}^{(L)} \xrightarrow{\theta} \mathbf{x}^{(L)} = h(\mathbf{x})$$

$$\mathbf{s}^{(\ell)} = (W^{(\ell)})^T \mathbf{x}^{(\ell-1)} \quad \mathbf{x}^{(\ell)} = \begin{bmatrix} 1 \\ \theta(\mathbf{s}^{(\ell)}) \end{bmatrix} \quad h(x)$$

(Compute  $h$  and  $E_{\text{in}}$ )

Choose  $W = \{W^{(1)}, W^{(1)}, \dots, W^{(L)}\}$  to minimize  $E_{\text{in}}$

## Gradient descent:

$$W(t+1) \leftarrow W(t) - \eta \nabla E_{\text{in}}(W(t))$$

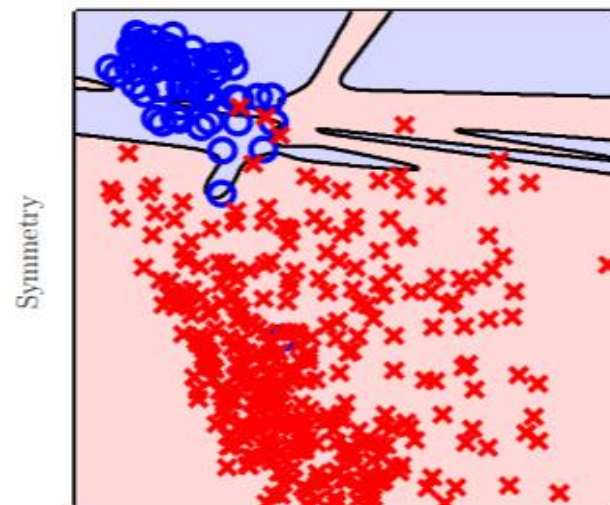
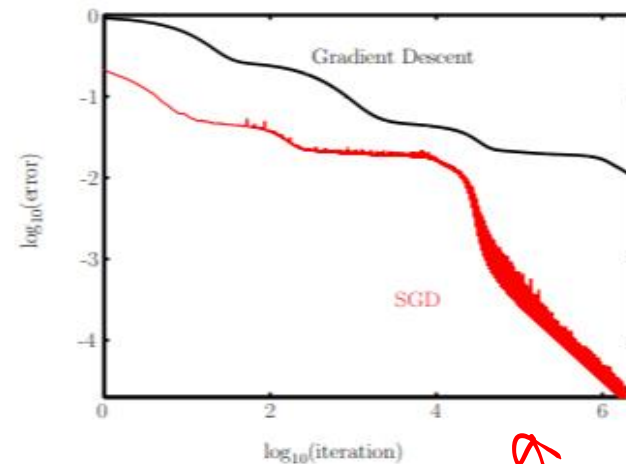
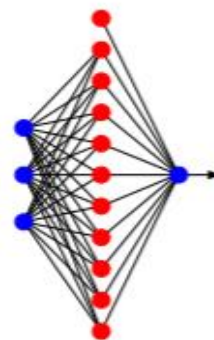
Compute gradient  $\rightarrow$  need  $\frac{\partial e}{\partial W^{(\ell)}} \rightarrow$  need  $\delta^{(\ell)} = \frac{\partial e}{\partial \mathbf{s}^{(\ell)}}$

$$\frac{\partial e}{\partial W^{(\ell)}} = \mathbf{x}^{(\ell-1)} (\delta^{(\ell)})^T$$

## Backpropagation:

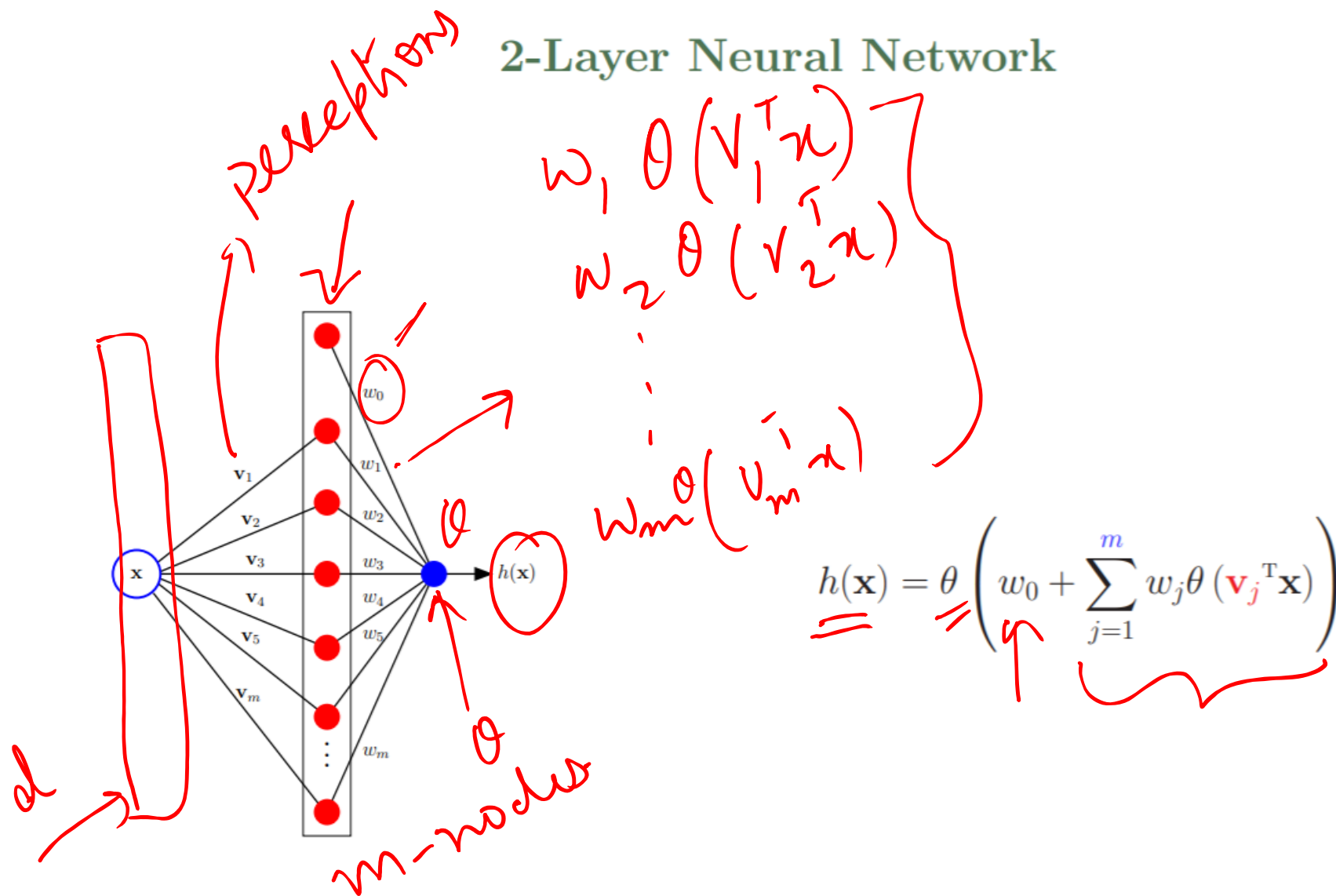
$$\delta^{(1)} \leftarrow \delta^{(2)} \dots \leftarrow \delta^{(L-1)} \leftarrow \delta^{(L)}$$

$$\delta^{(\ell)} = \theta'(\mathbf{s}^{(\ell)}) \otimes [W^{(\ell+1)} \delta^{(\ell+1)}]_1^{d^{(\ell)}}$$



Average Intensity

## 2-Layer Neural Network



# The Neural Network has a Tunable Transform

Linear models.

$$\Phi(x) = [1, \underline{\phi_1(x)}, \underline{\phi_2(x)}, \dots, \underline{\phi_m(x)}]$$

Neural Network

$$h(x) = \theta \left( w_0 + \sum_{j=1}^m w_j \theta(\mathbf{v}_j^T \mathbf{x}) \right)$$

feature transform fits the data.

Nonlinear Transform

$$h(x) = \theta \left( w_0 + \sum_{j=1}^d w_j \Phi_j(x) \right)$$

$\mathbb{R}^{E_{in} \times E_{out}}$

k-RBF-Network

$$h(x) = \theta \left( w_0 + \sum_{j=1}^k w_j \phi(\|x - \mu_j\|) \right)$$

Similarity

$\mu_j$ 's

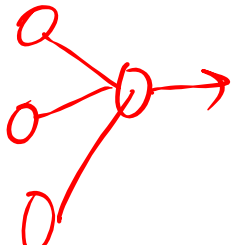
$$E_{in} = O\left(\frac{1}{m}\right)$$

approximation

Regression

$$E_{in} = O\left(\frac{1}{\sqrt{m}}\right)$$

$\theta = \text{sign}$



Generalization

$$h(x) = \theta(w_0 + \sum_{j=1}^m w_j \theta(V_j^T x))$$

$O(md)$

MLP:

$$d_{VC} = O(md \log(md))$$

$$m = \sqrt{N}$$

(convergence to optimal for MLP, just like  $k$ -NN)

*semi-parametric* because you still have to learn parameters.

tanh :

$$d_{VC} = O(md(m + d))$$

$$\bar{E}_{in} \in O\left(\frac{1}{m}\right)$$

$$\bar{E}_{in} \in O\left(\frac{1}{\sqrt{m}}\right)$$

$$\bar{E}_{out} \leq \bar{E}_{in} + O\left(\sqrt{\frac{drc \log N}{N}}\right), m = \sqrt{N}$$

$$\bar{E}_{in} \approx \frac{1}{N^{1/4}}$$

$$\bar{E}_{out}^*$$

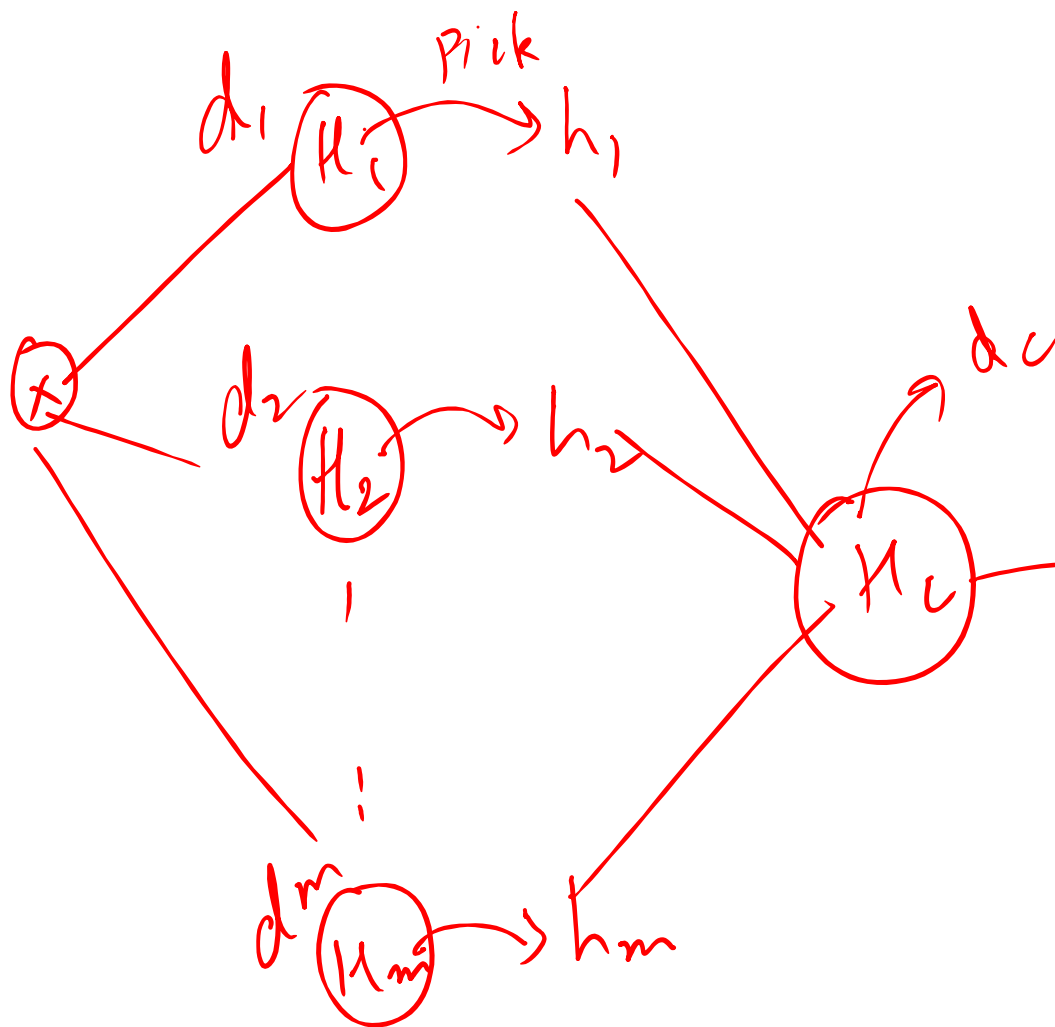
$$m = \sqrt{N}$$

$$\bar{E}_{out} \approx 0$$

Semi-parametric method.

$$\boxed{m}$$

Validation

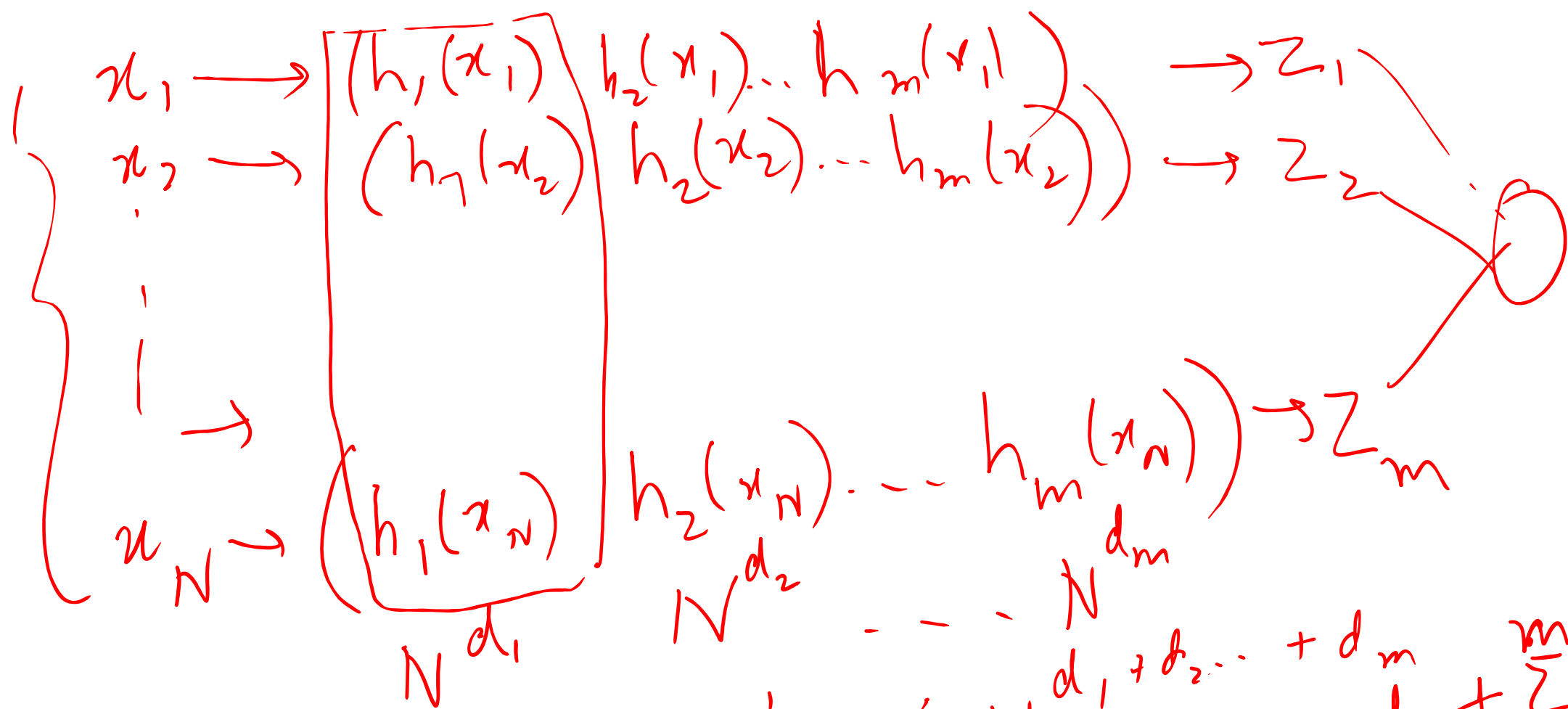


$$x \rightarrow (h_1(x) \ h_2(x) \ \dots \ h_m(x))$$

$$h(x) = h_c(h_1(x) \ h_2(x) \ \dots \ h_m(x))$$

# of dichotomies





# of configurations of  $z$ 's  $\leq N^{d_1 + d_2 + \dots + d_m}$

# of dichotomies  $\leq N^{d_c + \sum_{i=1}^m d_i}$

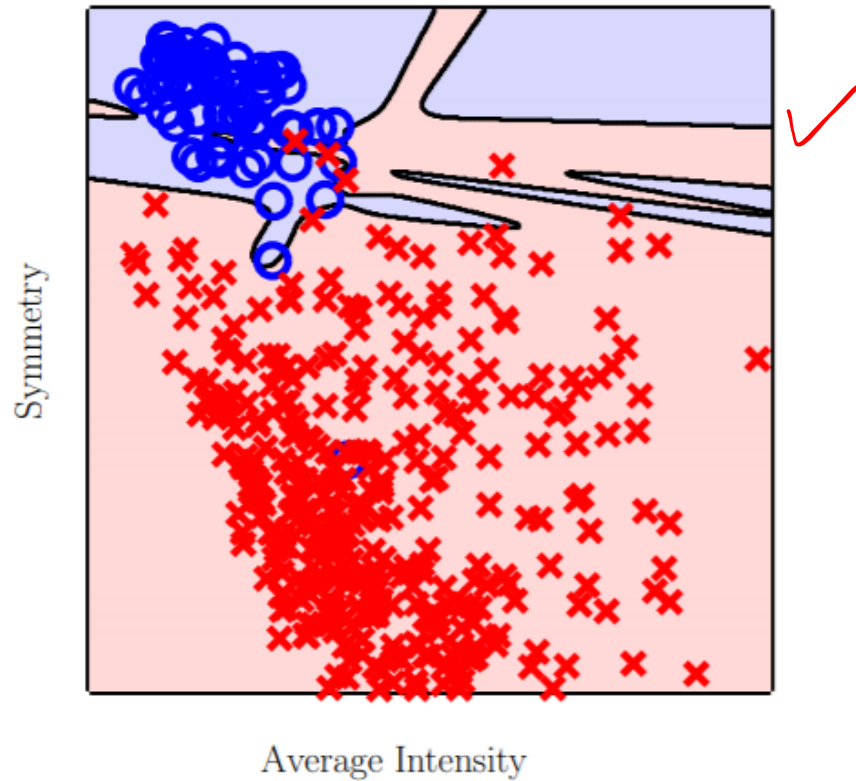
$D$

Lemma:  $N^D \leq 2^N$ ,  $N \in \Omega(D \log D)$   
If  $N > 2D \log_2 D$  then  $m(N) < 2^N$  &  $d_{vc} \leq 2D \log D$

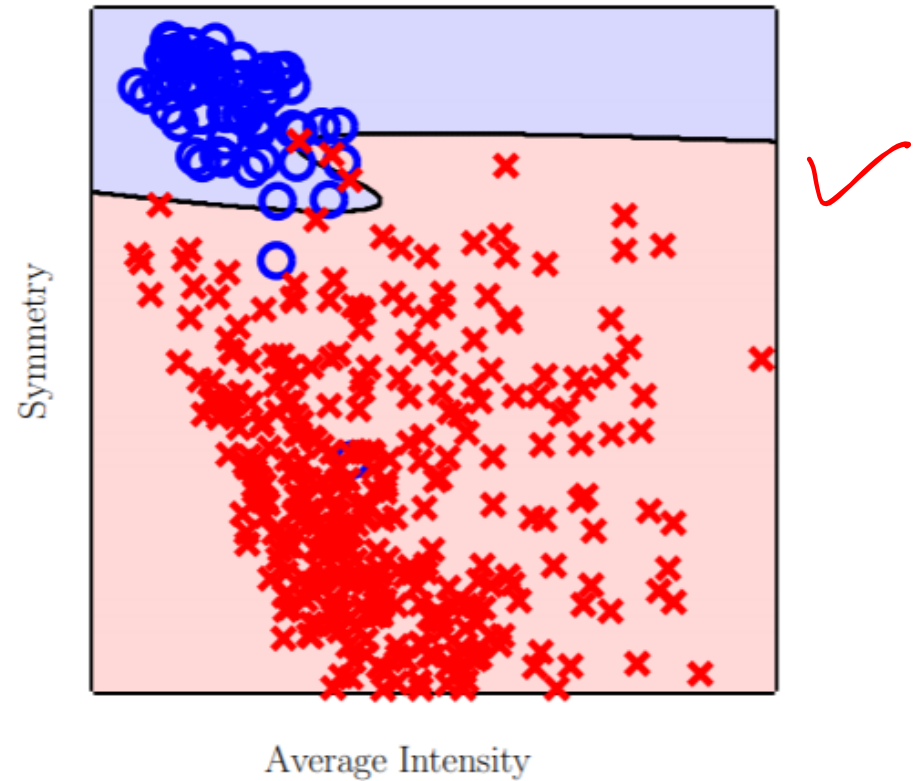
$$O\left(\sum d_i + d_c\right) \log\left(\sum d_i + d_c\right)$$

## Weight Decay with Digits Data

No Weight Decay



Weight Decay,  $\lambda = 0.01$



$$E_{\text{avg}} = E_{\text{in}} + \frac{\lambda}{N} \omega^T \omega$$

$$W = \{W^{(1)}, W^{(2)}, \dots, W^{(u)}\}$$

$$E_{\text{avg}} = E_{\text{in}} + \frac{\lambda}{N} \sum_{i,j} (w_{ij}^{(u)})^2$$

$$\frac{\partial E_{\text{avg}}}{\partial w_{ij}^{(u)}} = \frac{\partial E_{\text{in}}}{\partial w_{ij}^{(u)}} + \frac{\lambda}{N} 2 \cdot w_{ij}^{(u)}$$

$$\rightarrow \frac{\partial E_{\text{avg}}}{\partial W^{(u)}} = \frac{\partial E_{\text{in}}}{\partial W^{(u)}} + \frac{2\lambda}{N} W^{(u)}$$

$$W^{(u)} \leftarrow W^{(u)} - \eta \left( \frac{\partial E_{\text{in}}}{\partial W^{(u)}} + \frac{2\lambda}{N} W^{(u)} \right)$$

Back propagation



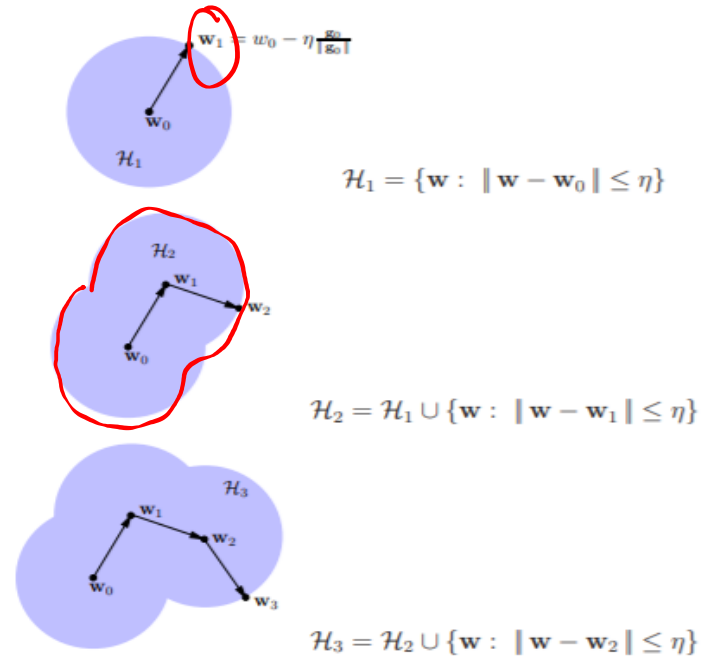
Hypothesis  
set

$$H_1 \subseteq H_2 \subseteq H_3 \dots \subseteq H_m$$

$$d_1 \leq d_2 \leq d_3 \dots \leq d_m.$$

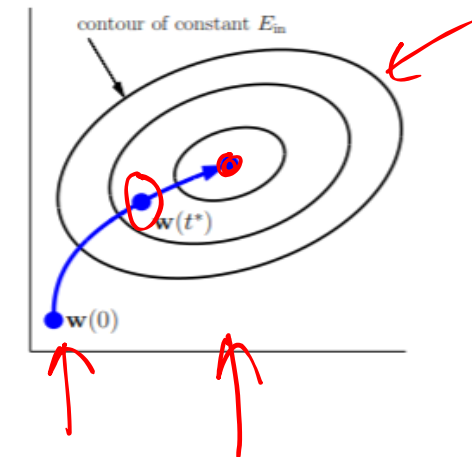
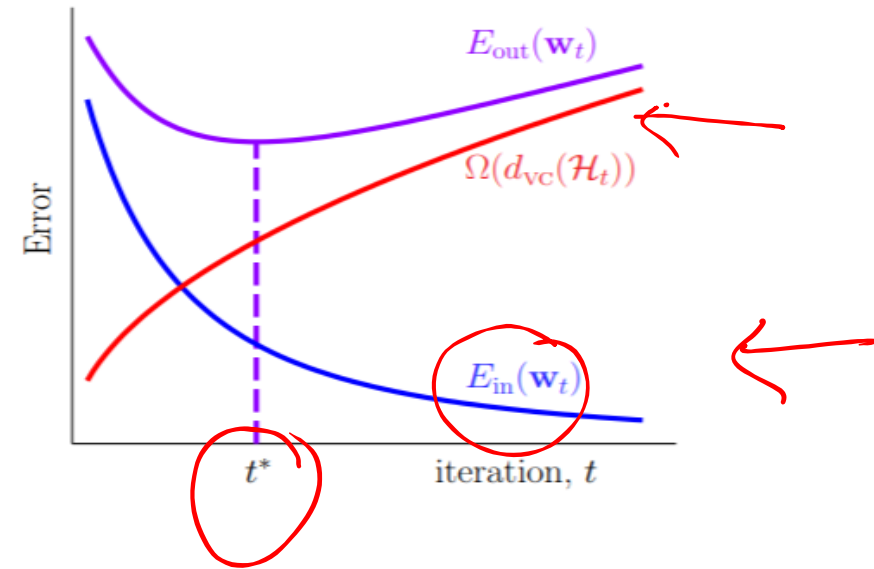
# Early Stopping

## Gradient Descent

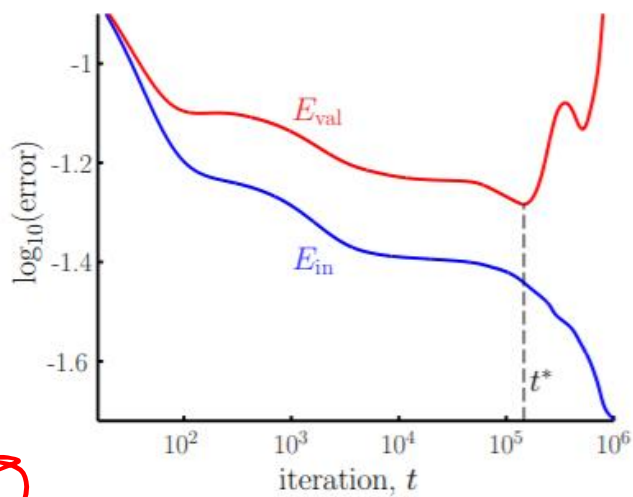


Each iteration explores a larger  $\mathcal{H}$

$$\mathcal{H}_1 \subset \mathcal{H}_2 \subset \mathcal{H}_3 \subset \mathcal{H}_4 \subset \dots$$

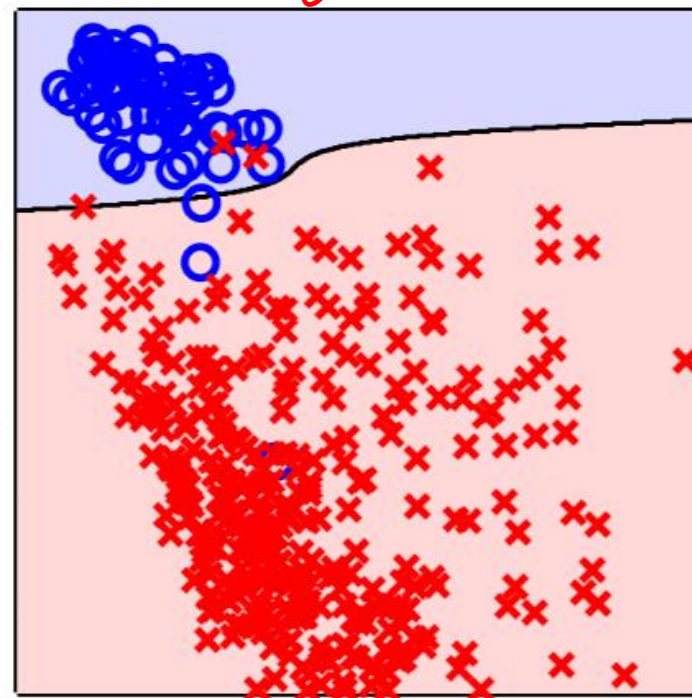


## Early Stopping on Digits Data



Use a validation set to determine  $t^*$   
Output  $\mathbf{w}^*$ , do not retrain with all the data till  $t^*$ .

Symmetry



Average Intensity





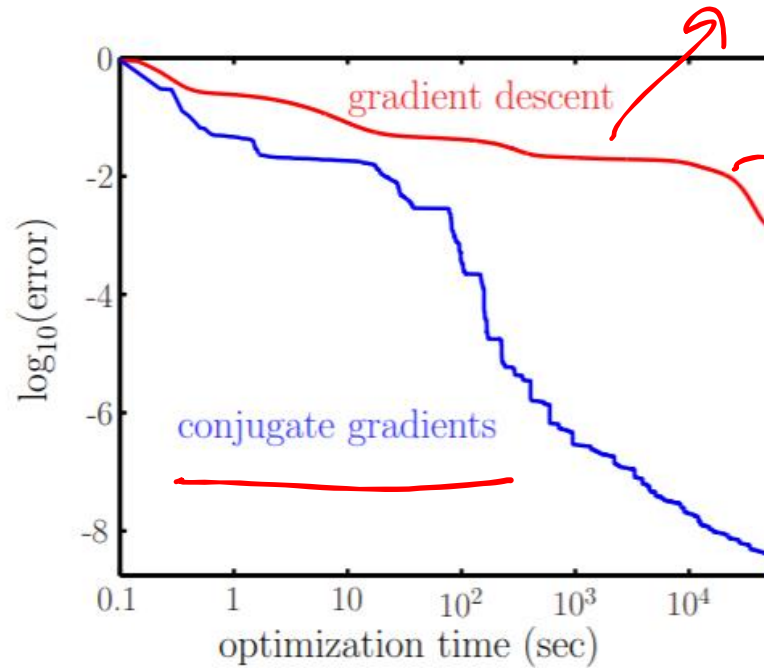
## Minimizing $E_{\text{in}}$

1. Use regression for classification
2. Use better algorithms than gradient descent

$$s^L \rightarrow \bigcirc \rightarrow h(x) = \theta(s^L)$$



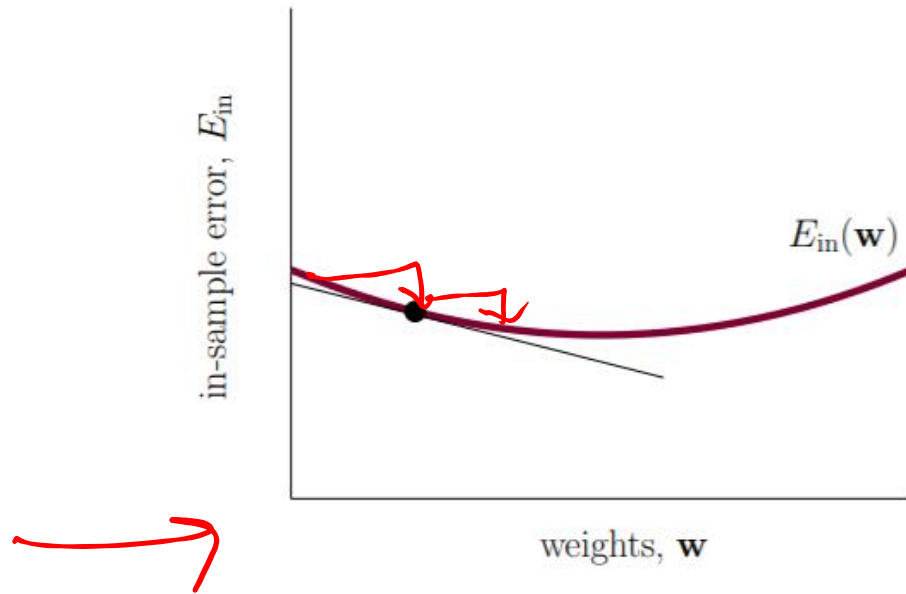
sign or  
tanh



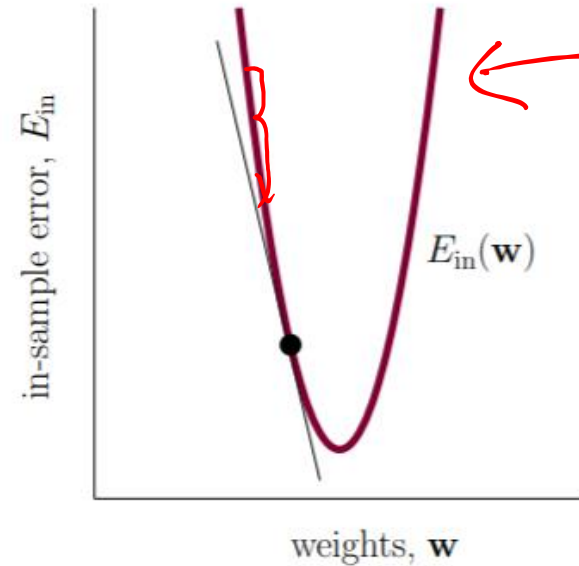
fast

- i) Direction (-ve of the grad.)
- ii) step size ( $\eta$ )

Determine the gradient  $\mathbf{g}$



Shallow: use large  $\eta$ .



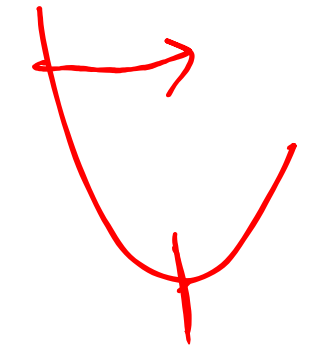
Deep: use small  $\eta$ .

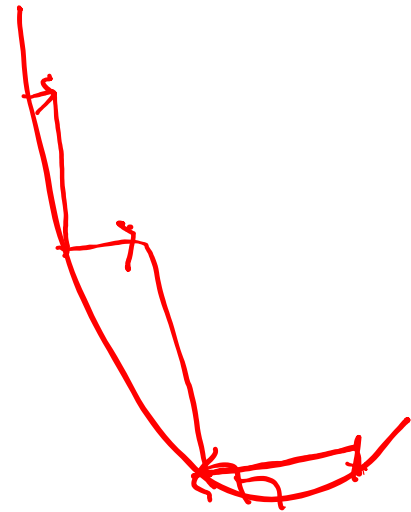
1) Start, take a step, check if  $E_{in}$  improves.  
 $\eta \rightarrow \eta \times \text{some factor } (\beta = 1.03)$

2) Take a bigger step & improve  $E_{in}$ .

3) If you worsen  $E_{in}$  then  
 $\eta \rightarrow \eta \times \alpha (< 1)$

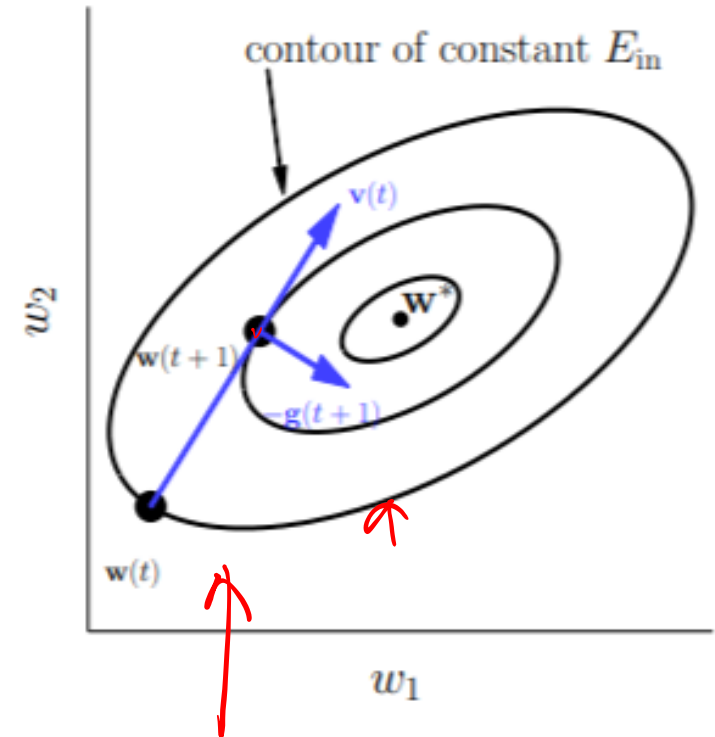
You may backtrack.

Variable  $\eta \rightarrow$  GD 

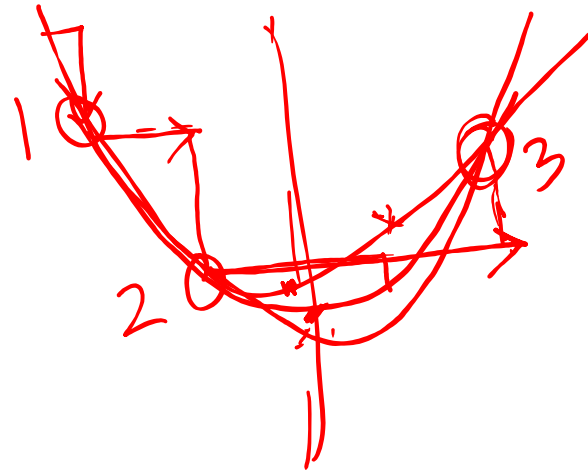


# Steepest Descent - Line Search

- 1: Initialize  $w(0)$  and set  $t = 0$ ;
- 2: **while** stopping criterion has not been met **do**
- 3:   Let  $\mathbf{g}(t) = \nabla E_{\text{in}}(\mathbf{w}(t))$ , and set  $\mathbf{v}(t) = -\mathbf{g}(t)$ .
- 4:   Let  $\eta^* = \text{argmin}_{\eta} E_{\text{in}}(\mathbf{w}(t) + \eta \mathbf{v}(t))$
- 5:    $\mathbf{w}(t+1) = \mathbf{w}(t) + \eta^* \mathbf{v}(t)$ .
- 6:   Iterate to the next step,  $t \leftarrow t + 1$ .
- 7: **end while**



How to accomplish the line search (step 4)? ✓  
Simple bisection (binary search) suffices in practice



- U shaped

Binary search

In practice 5-10 (9)

SGD  $\rightarrow$   $\propto n$   
 $\rightarrow$  small steps.

Method	Optimization Time		
	10 sec	1,000 sec	50,000 sec
Gradient Descent	0.079	0.0206	0.00144
<b>Stochastic Gradient Descent</b>	<b>0.0213</b>	<b>0.00278</b>	0.000022
Variable Learning Rate	0.039	0.014	0.00010
Steepest Descent	0.043	0.0189	<b>0.000012</b>

Steepest Descent  $\rightarrow$  line search  
 grad for  $\epsilon_{in}$

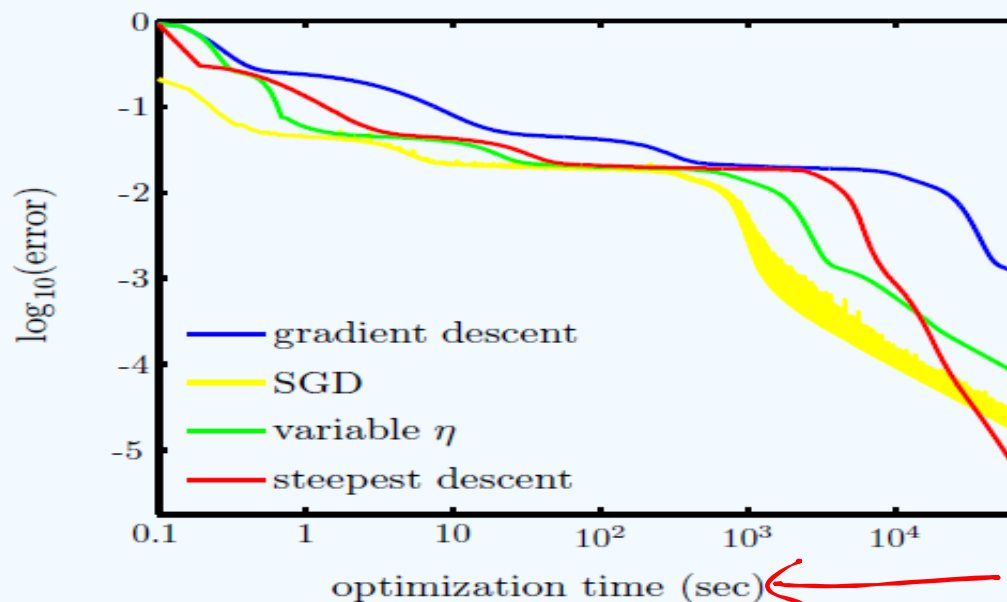
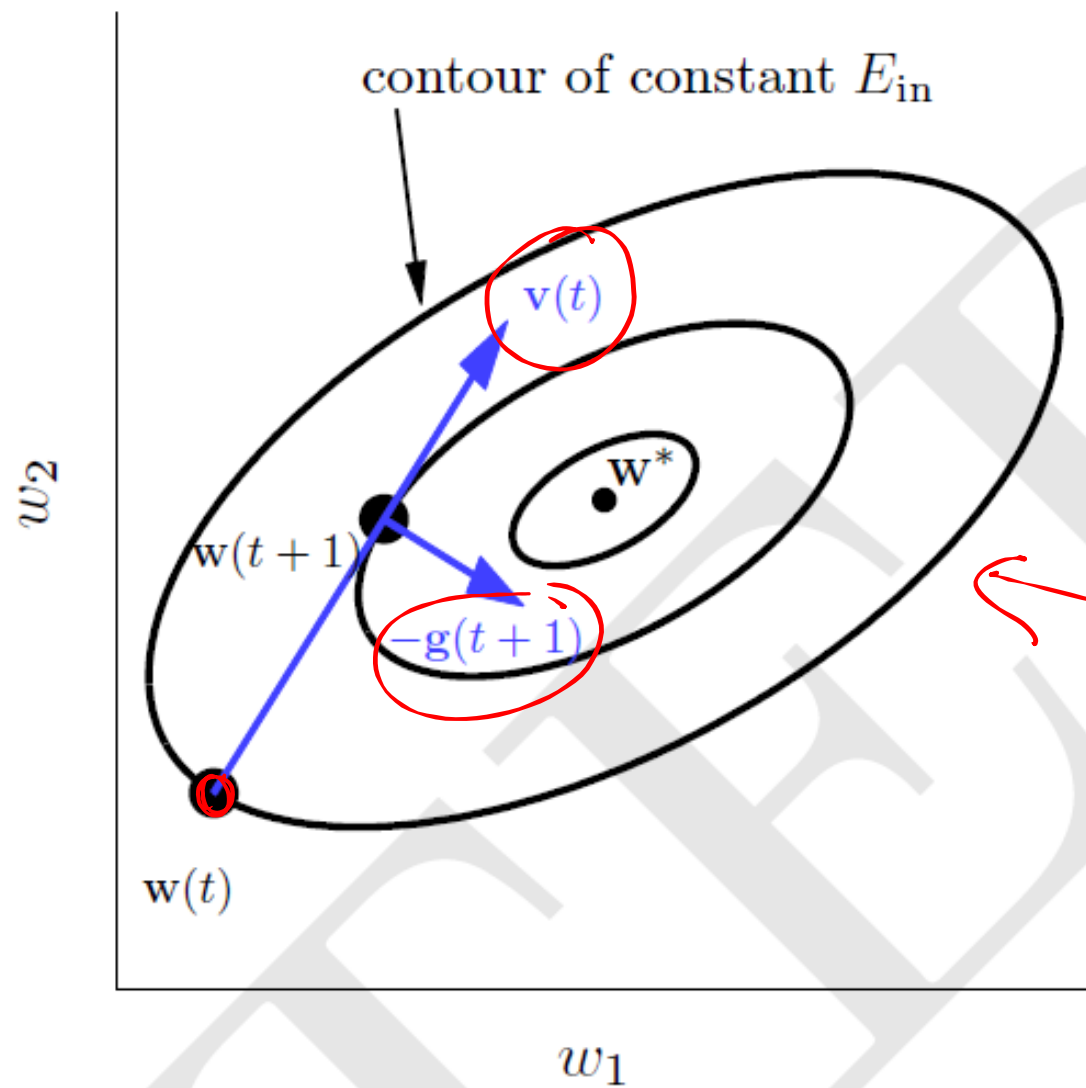
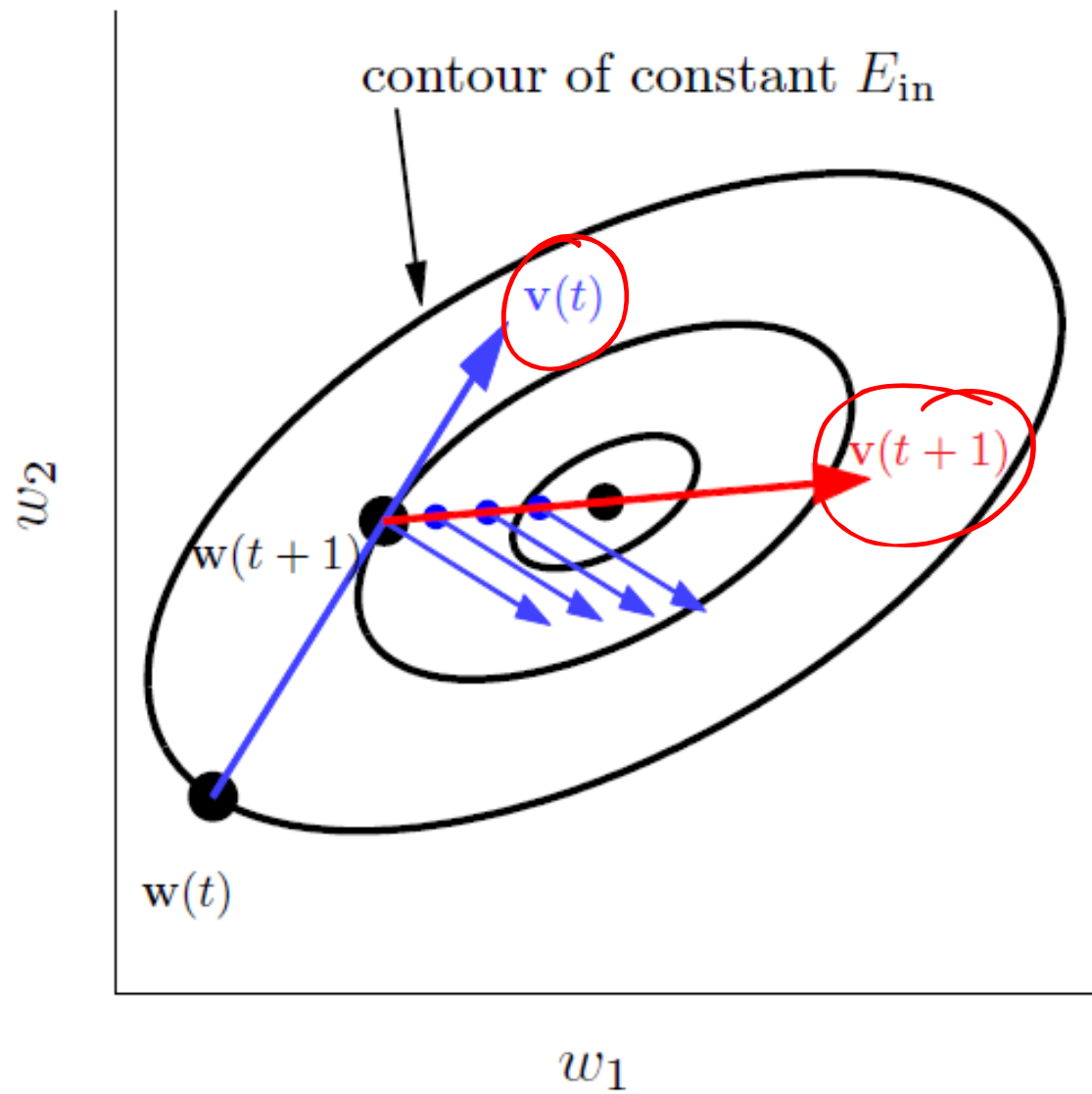


Figure 7.4: Gradient descent, variable learning rate and steepest descent using digits data and a 5 hidden unit 2-layer neural network with linear output. For variable learning rate,  $\alpha = 1.1$  and  $\beta = 0.8$ .



{ new grad  $\perp$   
prev. line  
search dir

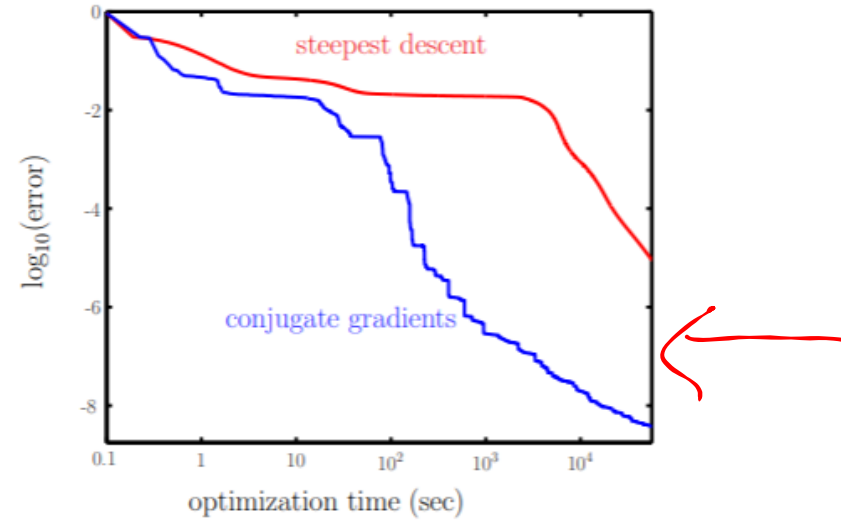
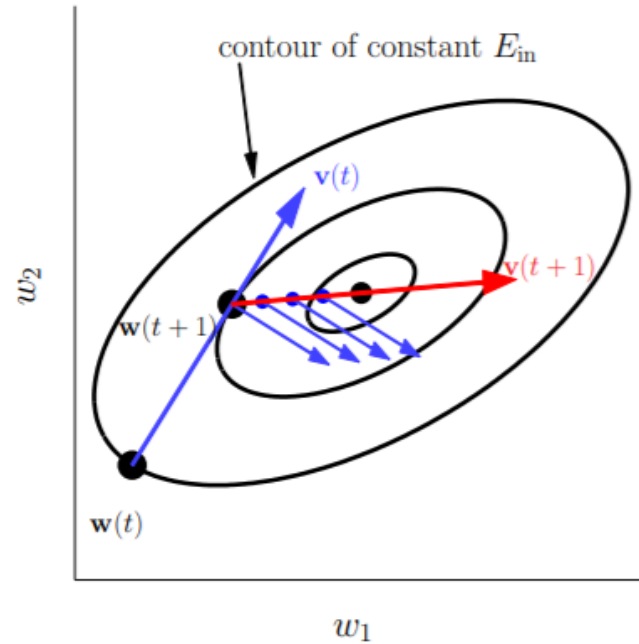


*d-steps.*



# Conjugate Gradients

1. Line search just like steepest descent.
2. Choose a better direction than  $-\mathbf{g}$



Method	Optimization Time		
	10 sec	1,000 sec	50,000 sec
Stochastic Gradient Descent	0.0203	0.000447	$1.6310 \times 10^{-5}$
Steepest Descent	0.0497	0.0194	0.000140
<b>Conjugate Gradients</b>	<b>0.0200</b>	<b><math>1.13 \times 10^{-6}</math></b>	<b><math>2.73 \times 10^{-9}</math></b>

Thanks!