

Machine Learning from Data

Lecture 13: Spring 2021

Today's Lecture

- Validation and Model Selection
 - Validation Set
 - Model Selection
 - Cross validation

Regularization (Recap)

Regularization combats the effects of noise by putting a leash on the algorithm.

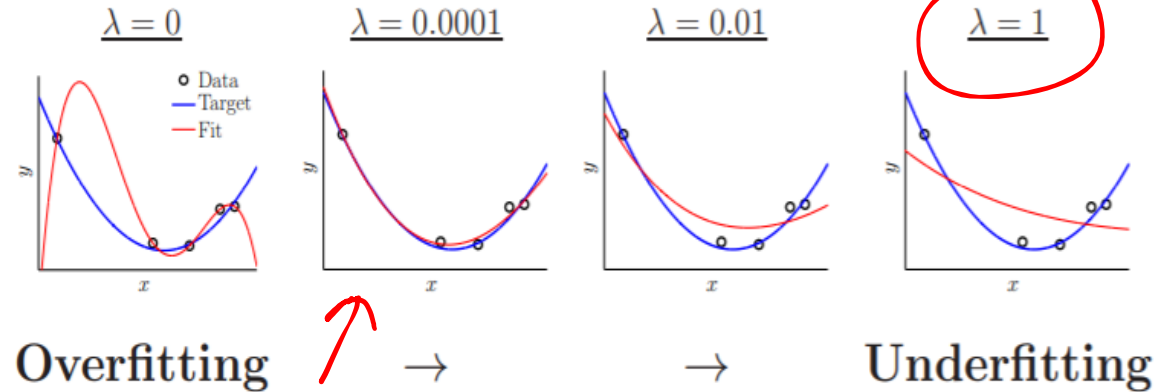
$$E_{\text{aug}}(h) = E_{\text{in}}(h) + \frac{\lambda}{N} \Omega(h)$$

$\Omega(h) \rightarrow$ smooth, simple h

noise is rough, complex.

Different regularizers give different results

can choose λ , the **amount** of regularization.



Optimal λ balances approximation and generalization, bias and variance.

Validation

$$E_{\text{out}}(g) = E_{\text{in}}(g) + \underbrace{\text{overfit penalty}}$$

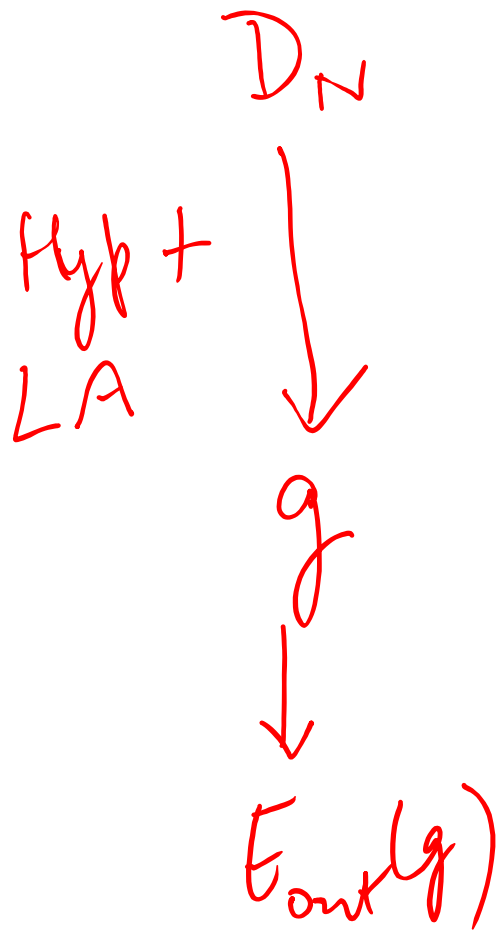
VC bounds this using a complexity error bar $\Omega(\mathcal{H})$

regularization estimates this through a heuristic complexity penalty $\Omega(g)$

Validation goes directly for the jugular:

$$E_{\text{out}}(g) = E_{\text{in}}(g) + \underbrace{\text{overfit penalty}}_{\text{validation estimates this directly}}$$

In-sample estimate of E_{out} is the Holy Grail of learning from data.



$e(g(x), y)$
 $e(g)$
 $E[e(g)] = E_{out}(g)$
 $\underline{Var(e(g))}$

Test data set
 x_1, x_2, \dots, x_K
 $\downarrow \quad \downarrow \quad \downarrow$
 $e_1 \quad e_2 \quad e_K$

$$E_{test} = \frac{1}{K} \sum_{k=1}^K e_k$$

$$E[E_{test}] = E\left[\frac{1}{K} \sum_{k=1}^K e_k\right]$$

$$= \frac{1}{K} \sum_{k=1}^K E(e_k)$$

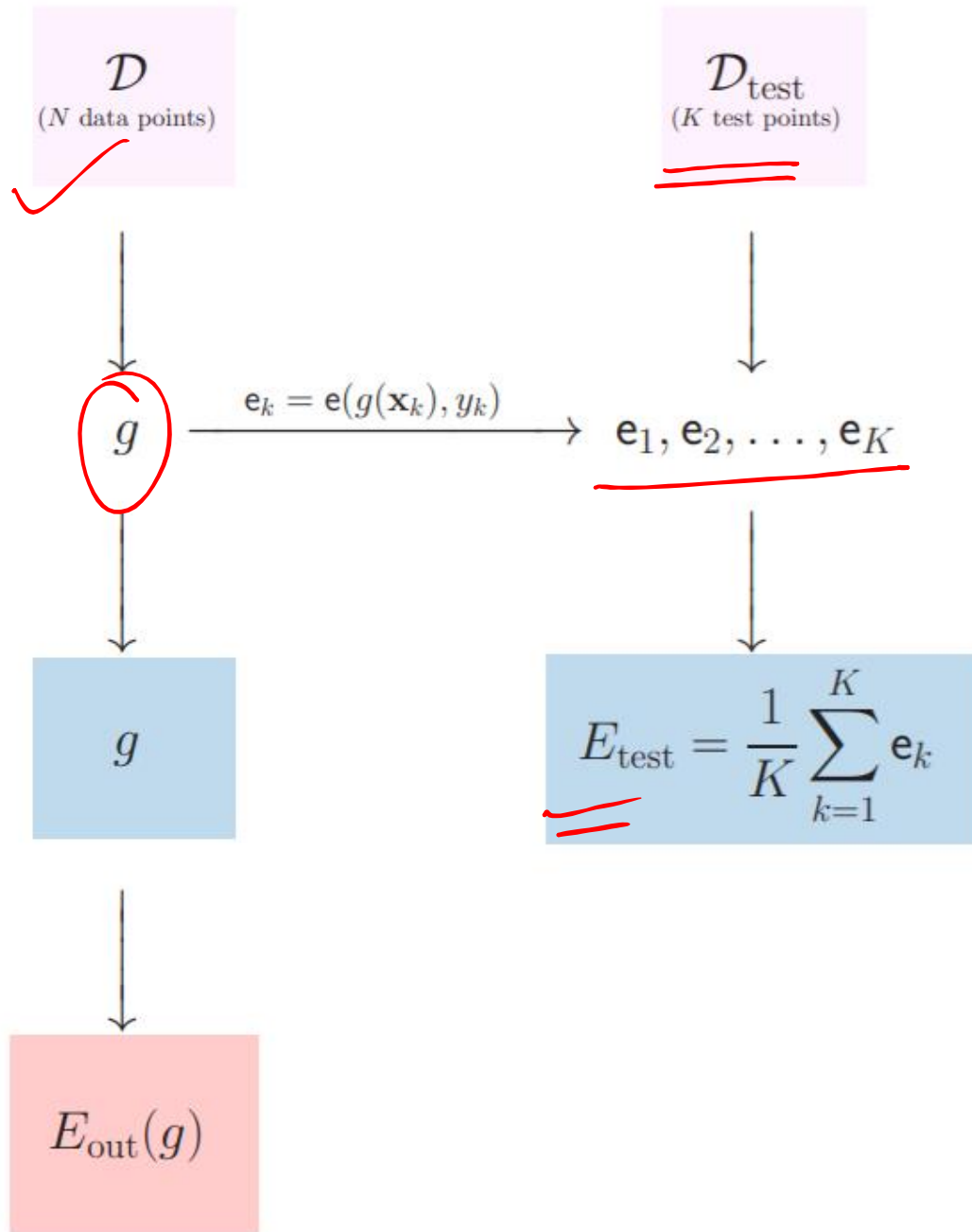
$$= \frac{1}{K} E_{out}(g)$$

$$\text{Var}(E_{\text{test}}) = \text{Var}\left[\frac{1}{K} \sum_{k=1}^K e_k\right]$$

$$= \frac{1}{K^2} \text{Var}\left[\sum_{k=1}^K e_k\right]$$

$$\text{Var}(E_{\text{test}}) = \frac{1}{K^2} \cdot K \cdot \text{Var}(e_k) = \frac{1}{K} \text{Var}(e_k)$$

$$E_{\text{out}} \approx E_{\text{test}} \pm \frac{1}{\sqrt{K}} \sqrt{\text{Var}(e_k)}$$



E_{test} is an estimate for $E_{\text{out}}(g)$

$$\mathbb{E}_{\mathcal{D}_{\text{test}}}[\mathbf{e}_k] = E_{\text{out}}(g)$$

$$\begin{aligned} \mathbb{E}[E_{\text{test}}] &= \frac{1}{K} \sum_{k=1}^K \mathbb{E}[\mathbf{e}_k] \\ &= \frac{1}{K} \sum_{k=1}^K E_{\text{out}}(g) = E_{\text{out}}(g) \end{aligned}$$

$\mathbf{e}_1, \dots, \mathbf{e}_K$ are independent

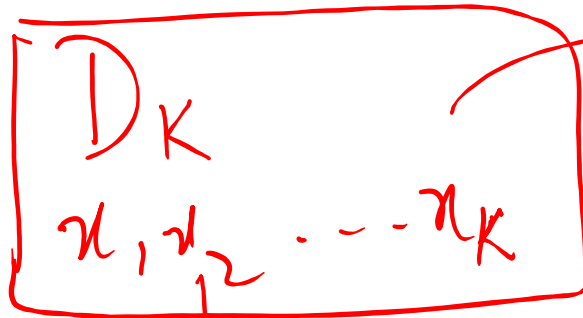
$$\text{Var}[E_{\text{test}}] = \frac{1}{K^2} \sum_{k=1}^K \text{Var}[\mathbf{e}_k]$$

$$= \frac{1}{K} \text{Var}[e]$$

decreases like $\frac{1}{K}$
bigger $K \Rightarrow$ more reliable E_{test} .

Validation

D_N



validation set

Training set



g^- (deficient hypothesis)

$E_{out}(g^-)$

$e_1(g^-), e_2(g^-), \dots, e_K(g^-)$

$$E_{val} = \frac{1}{K} \sum_{k=1}^K e_k(g^-)$$

$E[E_{val}] = E_{out}(g^-)$

$Var[E_{val}] = \left(\frac{1}{K} \right) Var(e(g^-))$

The Validation Set

\mathcal{D}
(N data points)

$\mathcal{D}_{\text{train}}$
($N - K$ training points)

\mathcal{D}_{val}
(K validation points)

g^-

$$e_k = e(g^-(\mathbf{x}_k), y_k)$$

$\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_K$

g^-

$$E_{\text{val}} = \frac{1}{K} \sum_{k=1}^K e_k$$

$E_{\text{out}}(g^-)$

E_{val} is an estimate for $E_{\text{out}}(g^-)$

$$\mathbb{E}_{\mathcal{D}_{\text{val}}}[\mathbf{e}_k] = E_{\text{out}}(g^-)$$

$$\mathbb{E}[E_{\text{test}}] = \frac{1}{K} \sum_{k=1}^K \mathbb{E}[\mathbf{e}_k]$$

$$= \frac{1}{K} \sum_{k=1}^K E_{\text{out}}(g^-) = E_{\text{out}}(g^-)$$

$\mathbf{e}_1, \dots, \mathbf{e}_K$ are independent

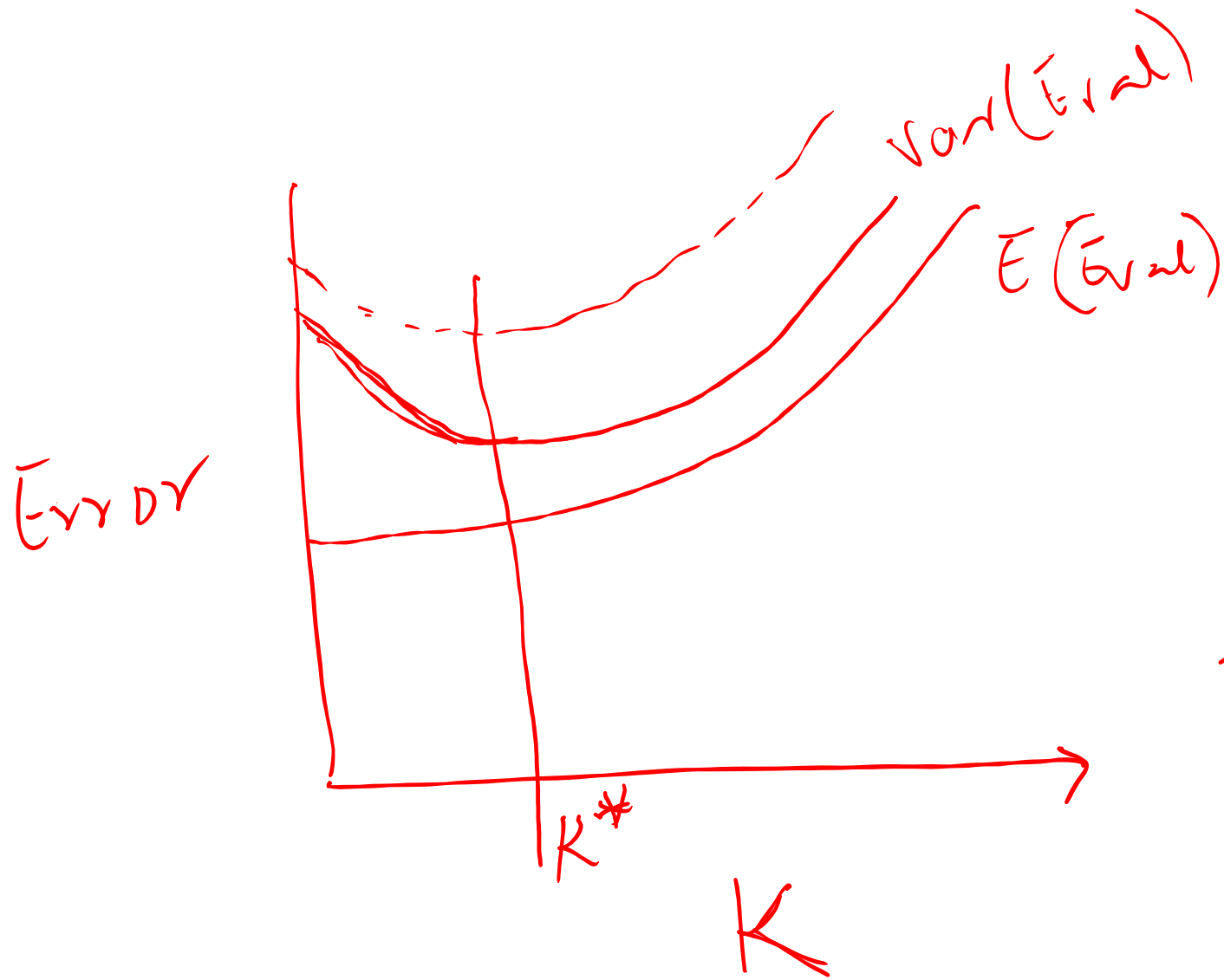
$$\text{Var}[E_{\text{val}}] = \frac{1}{K^2} \sum_{k=1}^K \text{Var}[\mathbf{e}_k]$$

$$= \frac{1}{K} \text{Var}[e(g^-)]$$

decreases like $\frac{1}{K}$
depends on g^- , not \mathcal{H}
bigger $K \Rightarrow$ more reliable E_{val} ?

no data

$K=N$



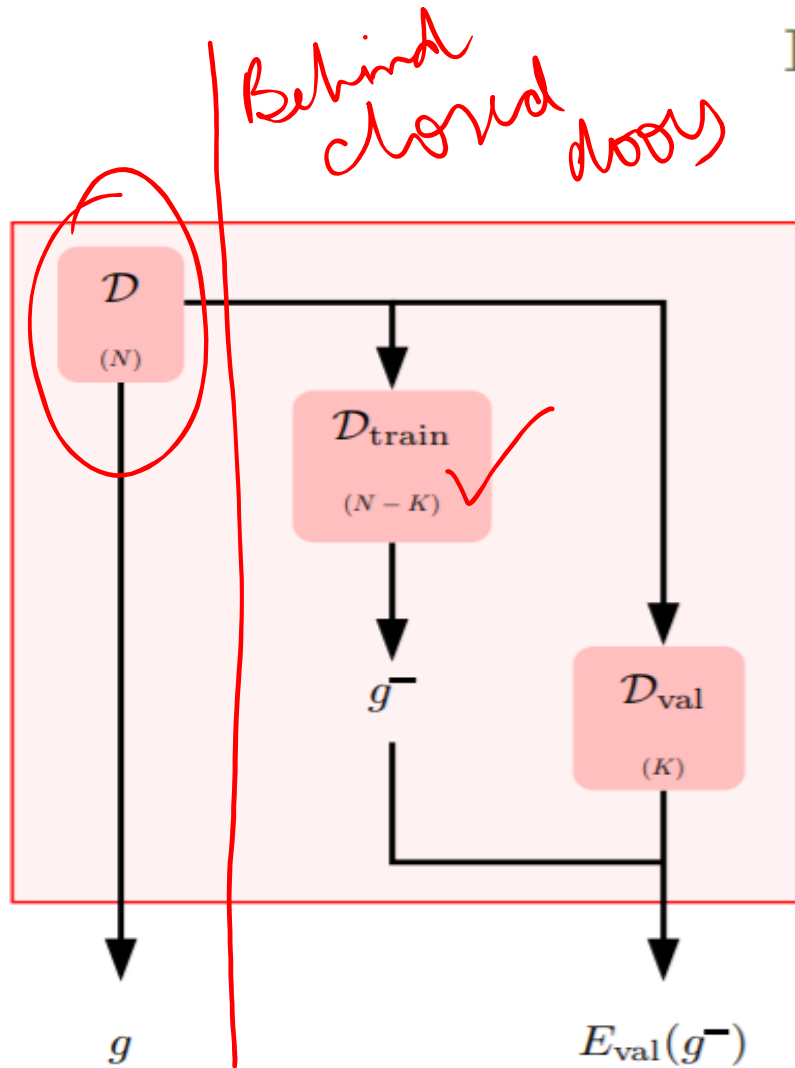
$g^- \rightarrow \text{work}$
 (alg^-)

In practice,

$$K^* \simeq \frac{N}{5} \text{ or}$$

20%

Restoring \mathcal{D}

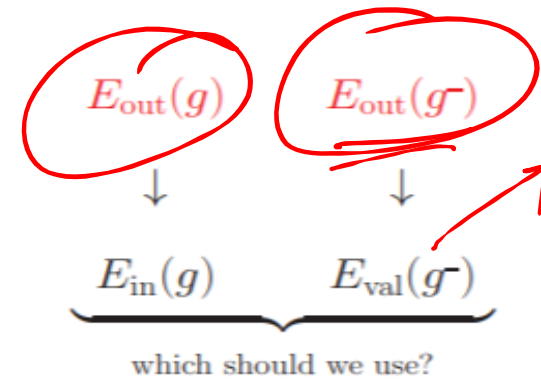


Primary goal: output best hypothesis. ✓

g was trained on *all* the data. → N

Secondary goal: estimate $E_{\text{out}}(g)$.

g^- is behind closed doors.



E

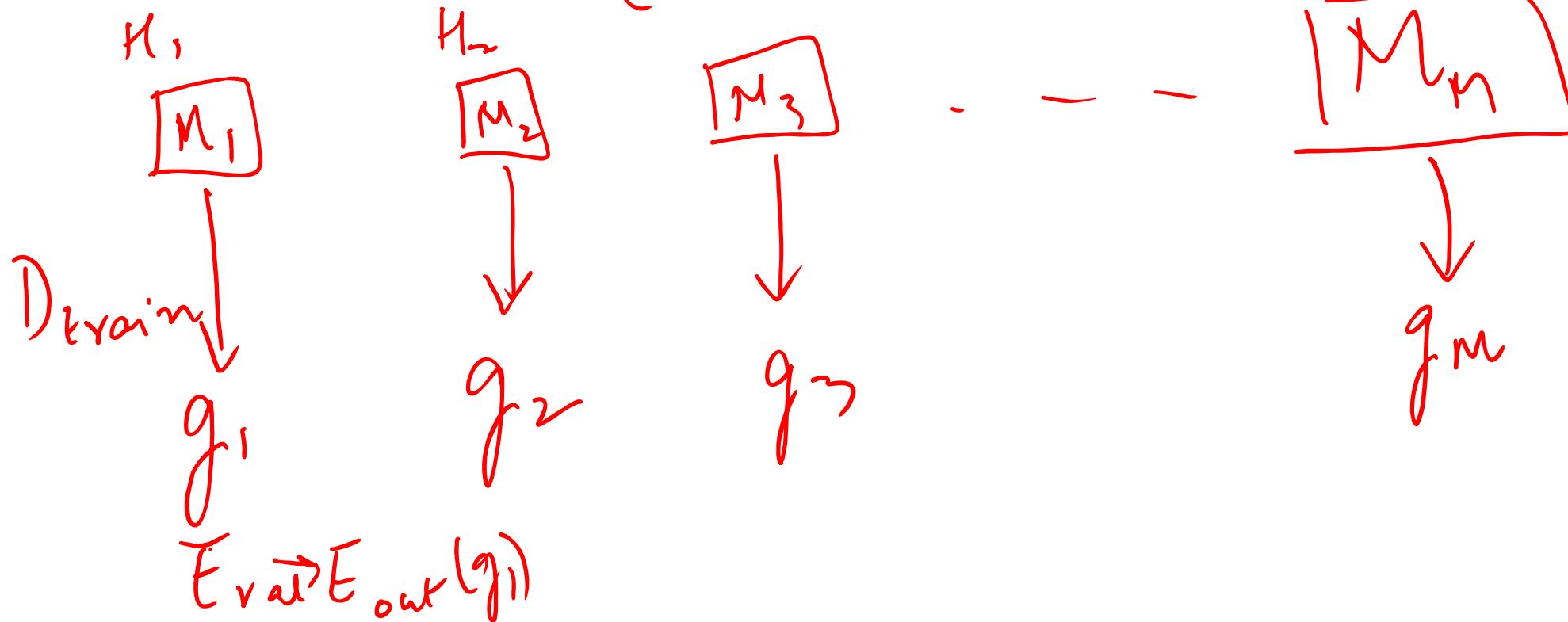
E_{val} vs E_{in}

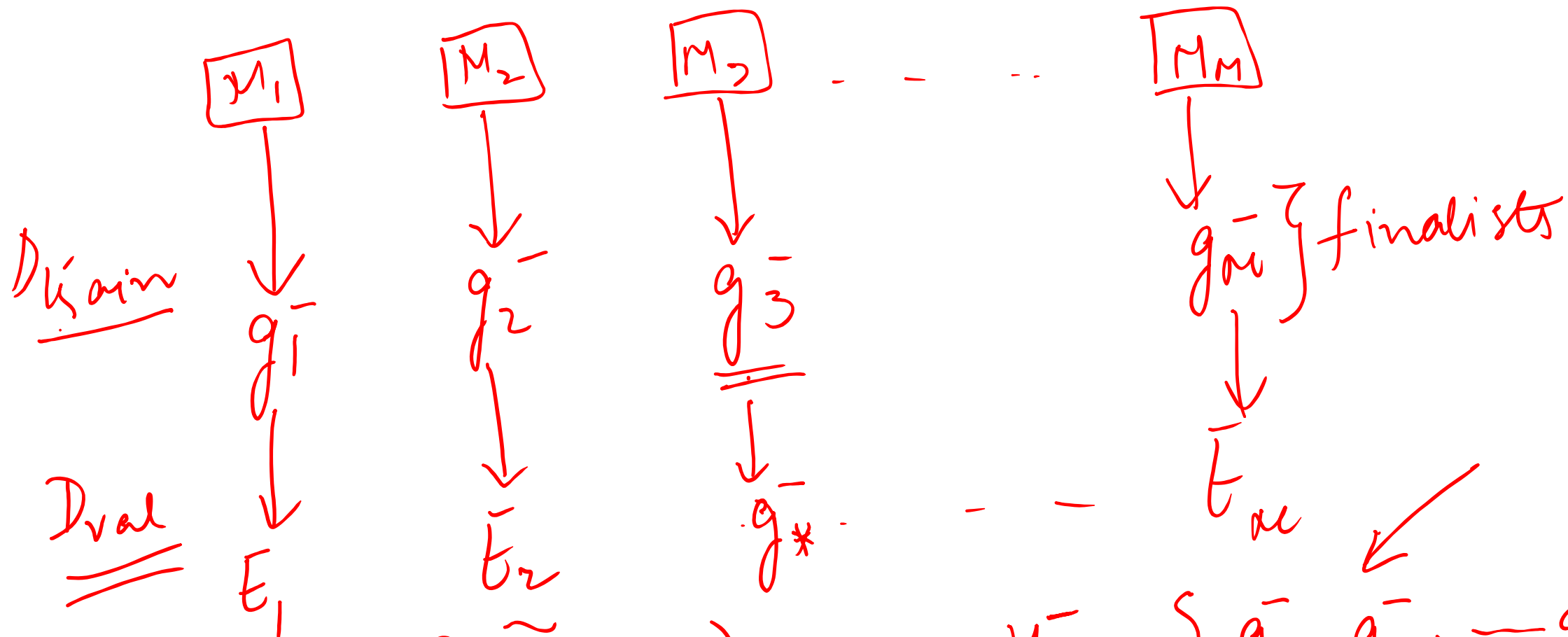
$$E_{out}(g) \leq E_{in}(g) + O\left(\sqrt{\frac{d_{VC} \ln N}{N}}\right) \leftarrow n\text{-set}$$

$$E_{out}(g) \leq \underbrace{E_{out}(g^*)}_{\uparrow} \leq E_{val} + O\left(\frac{1}{\sqrt{K}}\right) \rightarrow \text{single hypothesis}$$

Model Selection

- $D_N \rightarrow D_{N-K} \text{ (train)} \quad \underline{D_{\text{train}}}$
 $D_K \text{ (validation)} \quad D_{\text{val}}$





$$E_{out}(g_i^-) \approx E_{out}(g_i^-)$$

finite sets

finite

$$E_{out}(g_i^-) \leq E_{val}(g_i^-) + O\left(\sqrt{\frac{\ln M}{K}}\right)$$

$M^- = \{g_1^-, g_2^-, \dots, g_M^-\}$

$$E_{out}(g_*) \leq E_{out}(g_{**}) \leq E_{val}(g_{**}) + O\left(\sqrt{\frac{\ln M}{K}}\right)$$

λ

$\lambda_1 = 0$

h_1

$\lambda_2 = 0.001$

h_2

$\lambda_M = 0.1$

h_M

D_{train}

g_1

D_{val}

E_1

E_2 ✓

E_M

g

g

Validation (general philosophy)

\downarrow
 $g^-(y)$
 \downarrow
 E_{out}

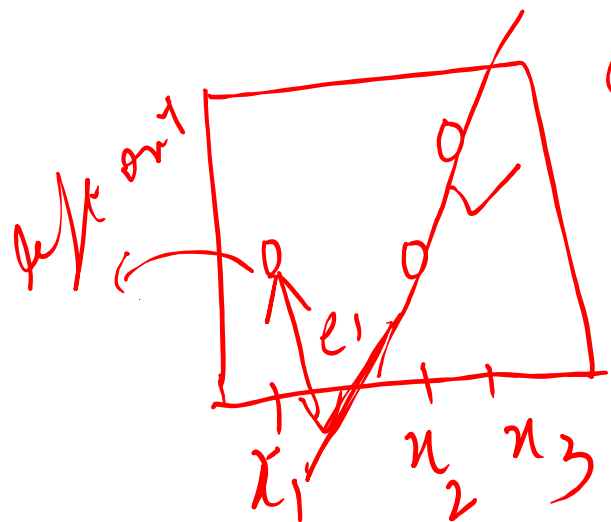
$g \approx g^-$
 $K, N-K$

$$E_{out}(g) \approx E_{out}(g^-) \approx E_{val}(g^-) + O\left(\frac{1}{\sqrt{K}}\right)$$

\uparrow K small \uparrow \nwarrow K big \nearrow
tight tight

Can we ^{have} $K=1$?

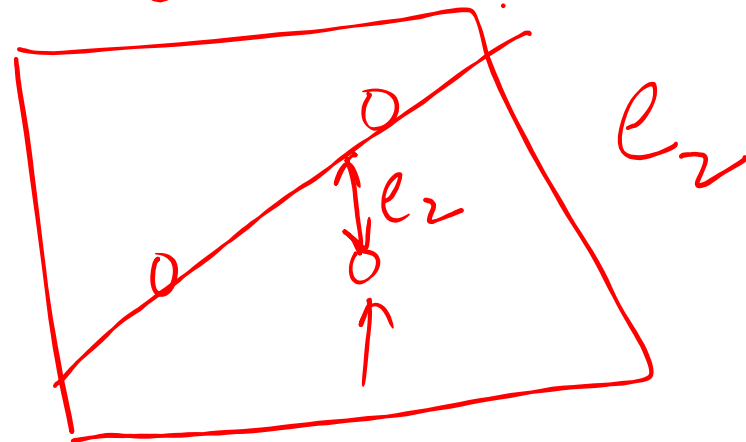
CROSS VALIDATION. ($K=1?$)



$$E(e_1) = E_{\text{out}}(g_1^-)$$

$$E(e_2) = E_{\text{out}}(g_2^-)$$

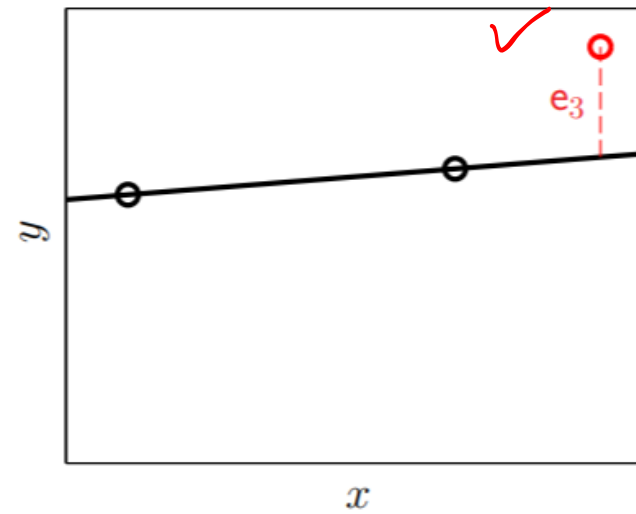
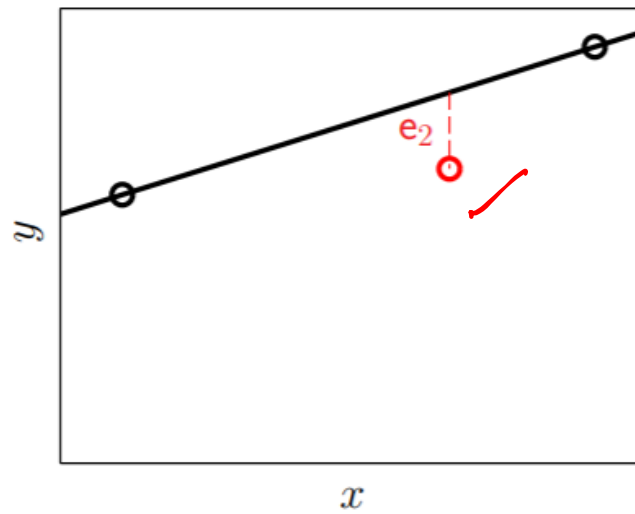
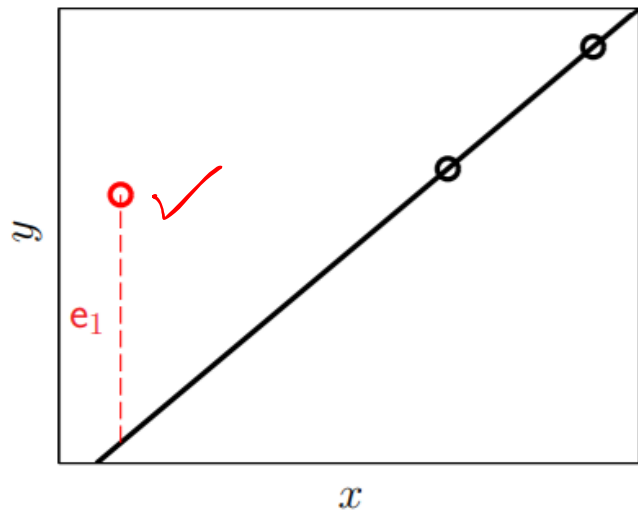
$$E(e_3) = E_{\text{out}}(g_3^-)$$



Pick all of them \rightarrow An average

$$E_{\text{CV}} = \frac{1}{N} \sum_{n=1}^N \textcircled{e_n} \rightarrow \text{leave one out}$$

(x_n, y_n)



$$\underline{\underline{E_{cv} = \frac{1}{N} \sum_{n=1}^N e_n}}$$

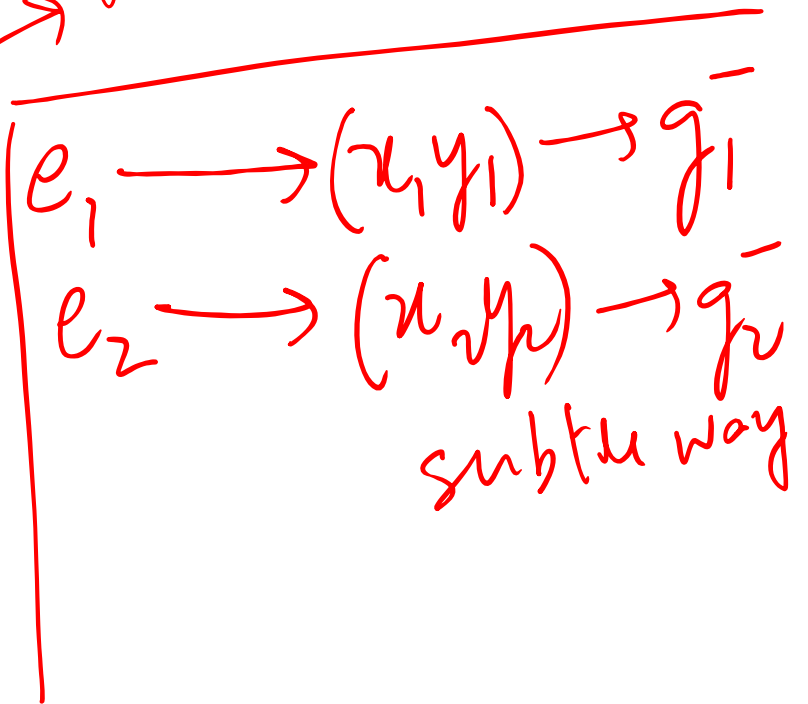
Theorem $\underbrace{E_N[E_{cr}]}_{\text{average}} = E_{out}(N-1)$

$\underbrace{E_{out}(g)}_{\text{average}} \leq E_{cr}$ & .

$E_{out} \leq E_{cr} + O\left(\frac{1}{\sqrt{N}}\right)$

N 's $\rightarrow e_1 e_2 e_3 \dots e_N$

Assume almost independent.



K-fold cross validation.

N -data points $\rightarrow N$ regression problems

$\therefore N+1$ Training sets.

10 fold CV $\rightarrow 10\%$ of your data



Analytically \rightarrow Regression

$E_w(\lambda_1)$ $E_w(\lambda_2)$...

→ Digits data
① Get features: Symmetry & Intensity.

② PLA

③ $\begin{bmatrix} 1 \\ x_1 \\ x_2 \end{bmatrix} \xrightarrow{\Phi}$

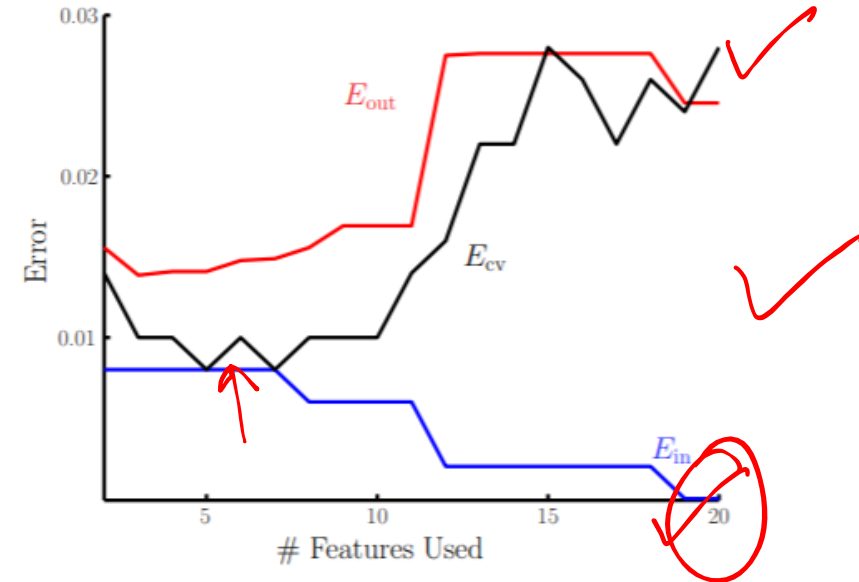
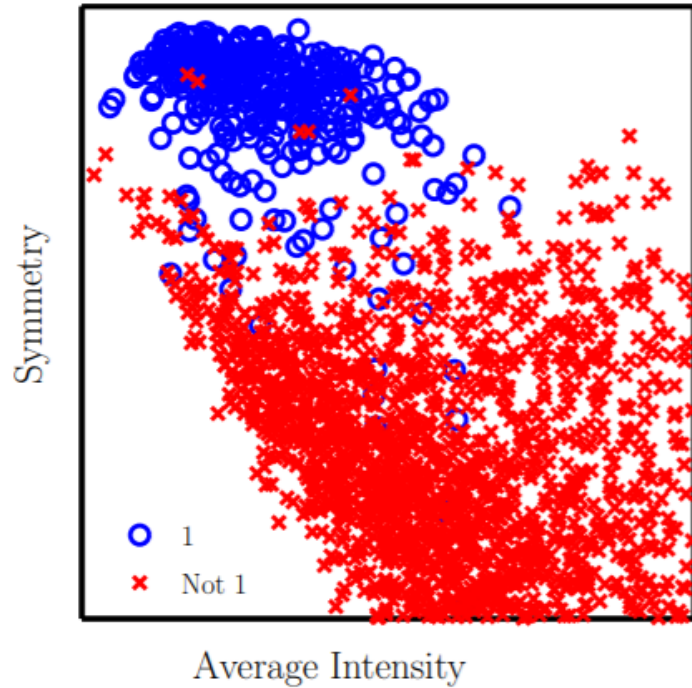
$\begin{bmatrix} 1 \\ x_1 \\ x_2 \\ \vdots \\ 1 \\ x_1^3 \\ x_2^3 \\ \vdots \end{bmatrix}$ } 20 dim in Z space ✓

④ Model selection
 $M_1 \rightarrow \begin{bmatrix} 1 \\ z_1 \end{bmatrix}$ $M_2 \rightarrow \begin{bmatrix} 1 \\ z_2 \end{bmatrix}$... M_{20}

⑤ CV to pick M_i

Digits Problem: '1' Versus 'Not 1'

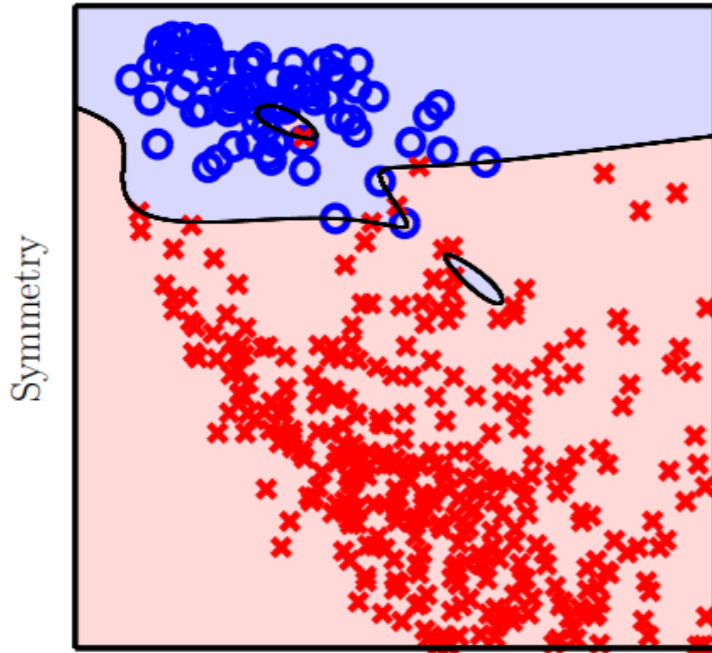
2 cases



$$\left. \begin{aligned} \mathbf{x} &= (1, x_1, x_2) \\ \mathbf{z} &= (1, x_1, x_2, x_1^2, x_1x_2, x_2^2, x_1^3, x_1^2x_2, x_1x_2^2, x_2^3, \dots, x_1^5, x_1^4x_2, x_1^3x_2^2, x_1^2x_2^3, x_1x_2^4, x_2^5) \end{aligned} \right\}$$

5th order polynomial transform \rightarrow 20 dimensional non linear feature space

Validation Wins In the Real World

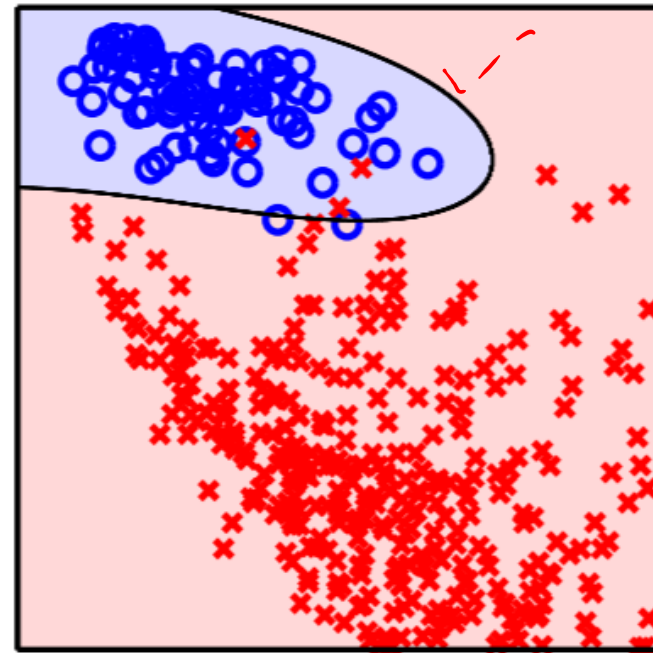


Average Intensity

no validation (20 features)

$$E_{\text{in}} = 0\%$$

$$E_{\text{out}} = 2.5\%$$



Average Intensity

cross validation (6 features)

$$E_{\text{in}} = 0.8\%$$

$$E_{\text{out}} = \underline{\underline{1.5\%}}$$

Thanks!