

Differential Geometry

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Chapter 1

Manifolds

Chapter 2

Scalar and Vector Fields

§1 Scalar Fields

Definition 1.1 (Scalar Field). Let M be a smooth manifold, $f \in C^{(\infty)}(M)$ is called a ***scalar field***.

The scalar field over a manifold, form an algebra.

§2 Vector Fields

Definition 2.1 (vector field). A ***vector field*** v over manifold M is a $C^{(\infty)}(M) \rightarrow C^{(\infty)}(M)$ map that satisfies

- (a) $\forall f, g \in C^{(\infty)}(M), \forall \lambda, \mu \in \mathbb{R}, v(\lambda f + \mu g) = \lambda v(f) + \mu v(g)$
(*linearity*).
- (b) $\forall f, g \in C^{(\infty)}(M), v(fg) = v(f)g + fv(g)$

The space of all vector fields on M is denoted by $\text{Vect}(M)$

Definition 2.2 (tangent vector). Let v be a vector field over M , p be a point on M . The tangent vector v_p at p is defined as a $C^{(\infty)}(M) \rightarrow C^{(\infty)}(M)$ map that satisfies

$$v_p(f) = v(f)(p). \quad (2-1)$$

The collection of tangent vectors at p is called the **tangent space** at p , denoted by $T_p M$.

The derivative of a path $\gamma: [0, 1] \rightarrow M$ (or $\mathbb{R} \rightarrow M$) in a smooth manifold is defined as:

$$\begin{aligned} \gamma'(t) &: C^{(\infty)}(M) \rightarrow \mathbb{R}; \\ \gamma'(t)(f) &= \frac{d}{dt} f \circ \gamma(t) \end{aligned} \quad (2-2)$$

We can see that $\gamma'(t) \in T_{\gamma(t)} M$.

§3 Covariant and Contravariant

Definition 3.1 (pullback). Let f be a scalar field over M , $\varphi \in C^{(\infty)}(M, N)$. Then the **pullback** of f by φ is defined as

$$\varphi^* f = f \circ \varphi \in C^{(\infty)}(N). \quad (3-1)$$

Fields that are pullbacked are **covariant** fields.

Definition 3.2 (pushforward). Let v_p be a tangent vector of M at p , $\varphi \in C^{(\infty)}(M, N)$, $q = \varphi(p)$. Then the **pushforward** of v_p by φ is defined as

$$(\varphi_* v)_q(f) = v_p(\varphi^* f). \quad (3-2)$$

Note that the pushforward of a vector field can only be obtained when φ is a diffeomorphism.

Fields that are pushforwarded are **contravariant** fields.

Mathematicians and physicists might have disagreement on whether a tangent vector is covariant or contravariant. This is because of that physicists might consider the coordinates (v^μ) of a tangent vector as a vector field, instead of linear combination of bases ∂_μ .

§4 Flows

Let a path $\gamma: \mathbb{R} \rightarrow M$ follow a vector field (a velocity field), that is

$$\gamma'(t) = v_{\gamma(t)}, \quad (4-1)$$

then we call γ the **integral curve** through $p := \gamma(0)$ of the vector field v .

Definition 4.1. Suppose v is an integrable vector field. Let $\varphi_t(p)$ be the point at time t on the integral curve through p .

$$\varphi_t: M \rightarrow M \quad (4-2)$$

is then called a **flow** generated by v .

$$\frac{d}{dt} \varphi_t(p) = v_{\varphi_t(p)}. \quad (4-3)$$

Chapter 3

Differential Forms

§5 1-forms

Definition 5.1 (1-form). A **1-form** ω on M is a $\text{Vect}(M) \rightarrow C^{(\infty)}(M)$ which satisfies that

$$(a) \quad \forall v, w \in \text{Vect}(M), \forall f, g \in C^{(\infty)}(M),$$

$$\omega(fv + gw) = f\omega(v) + g\omega(w). \quad (5-1)$$

The space of all 1-forms on M is denoted as $\Omega^1(M)$.

The operator d , when given a $C^{(\infty)}(M)$ function (which is called a **0-form**), would give a 1-form:

$$(df)(v) = v(f). \quad (5-2)$$

This is called the **exterior derivative** or **differential** of f .

The **cotangent vector** or **covector** is similar as the tangent vector:

$$\omega_p(v_p) = \omega(v)(p). \quad (5-3)$$

The space of cotangent vectors at p on M is denoted by T_p^*M .

1-forms are contravariant, that is, if $\varphi: M \rightarrow N$, then

$$(\varphi^* \omega_q)(v_p) = \omega_q(\varphi_* v_p), \quad (5-4)$$

where $\varphi(p) = q$.

bibliography

- [1] Javier P. Muniain John C. Baez. *Gauge Fields, Knots and Gravity (Series on Knots and Everything)*. Series on Knots and Everything. World Scientific Publishing Company, 1994. ISBN: 9789810217297,9810217293,9810220340.

Symbol List

Here listed the important symbols used in these notes

$\Omega^1(M)$, 5

$T_p M$, 3

$T_p^* M$, 5

$\text{Vect}(M)$, 2

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