

# Algebraic Topology

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# Chapter 1

## Homotopy and Fundamental Group

### §1 Homotopy

**Definition 1.1** (Homotopy).  $f, g \in C(X, Y)$ . If  $\exists H \in C(X \times [0, 1], Y)$  s.t.  $H(x, 0) = f(x)$ ,  $H(x, 1) = g(x)$ , then we say  $f$  and  $g$  are **homotopic**, denoted by  $f \simeq g: X \rightarrow Y$  or just  $X \rightarrow Y$ .  $H$  is called a **homotopy** between  $f$  and  $g$ , denoted by  $H: f \simeq g$  or  $f \simeq_H g$ .

For  $t \in [0, 1]$ ,  $h_t: X \rightarrow Y; x \mapsto H(x, t)$  is called a ***t*-slice**.

If  $f$  is homotopic to a constant mapping, we say that  $f$  is **null-homotopic**.

A **linear homotopy** is a homotopy between two functions to  $Y \subseteq \mathbb{R}^n$  that change linearly, i.e.

$$H(x, t) = (1 - t)f(x) + tg(x).$$

**Theorem 1.1** (Maps to convex set are homotopic).  $f, g \in C(X, Y)$ . If  $Y$  is a convex set in  $\mathbb{R}^n$ , then  $f \simeq g$ .

**Proof.** Consider linear homotopy. □

**Theorem 1.2.** Homotopic relation is an equivalence relation.

**Proof.** *reflexivity.*  $f \simeq f$ , just take  $H(x, t) = f(x)$  for any  $t$  (Such homotopy is called a **constant homotopy**).

*Symmetry.*  $f \simeq g$  then  $g \simeq f$ . Just take  $\bar{H}(x, t) = H(x, 1 - t)$  (Here  $\bar{H}$  is called the inverse of  $H$ ).

*Transitivity.*  $f \simeq g \wedge g \simeq h \rightarrow f \simeq h$ . Let

$$H_1 H_2(x, 2t) = \begin{cases} H_1(x, 2t) & t \in [0, 1/2], \\ H_2(x, 2t - 1) & t \in [1/2, 1]. \end{cases}$$

We can see that  $H_1 H_2$  is also a homotopy (see Theorem 11.6 in Point Set Topology) □

Hence, we can define **homotopy classes** on  $C(X, Y)$ , denoted by  $[X, Y]$ .

As you might expect after reading the proof of Theorem 1.2, the homotopies between mappings within a homotopy class form a group.

**Theorem 1.3.**  $f_1 \simeq f_2: X \rightarrow Y$ ,  $g_1 \simeq g_2: Y \rightarrow Z$ , then  $g_1 \circ f_1 \simeq g_2 \circ f_2: X \rightarrow Z$ .

**Proof.** Let  $F: f_1 \simeq f_2$ ,  $G: g_1 \simeq g_2$ . Define:

$$\mathbf{F}: X \times [0, 1] \rightarrow Y \times [0, 1]; x \mapsto (F(x, t), t).$$

It can be verified tht  $G \circ \mathbf{F}: g_1 \circ f_1 \simeq g_2 \circ f_2: X \rightarrow Z$ . □

**Theorem 1.4** (All mappings to a path-connected space are null-homotopic). *If  $Y$  is path-connected,  $y_0 \in Y$ , then  $[X, Y] = [x \mapsto y_0]$  (i.e. homotopy class of constant mapping to  $\{y_0\}$ )*

**Proof.** □

**Definition 1.2** (Homotopy relative to a set). Let  $A \subseteq X$ ,  $H: f \simeq g$ . If  $\forall a \in A$ ,  $\forall t \in [0, 1]$ ,  $f(a) = g(a) = H(a, t)$ , we say that  $f$  and  $g$  are **homotopic relative to  $A$** , denoted by  $H: f \simeq g \text{ rel } A$ .

# bibliography

- [1] 尤承业. 基础拓扑学讲义. 北京: 北京大学出版社, 1997. ISBN: 9787301031032.
- [2] 熊金诚, ed. 点集拓扑讲义. 2nd ed. 北京: 高等教育出版社, 1998. ISBN: 9787040062823.

# Symbol List

Here listed the important symbols used in this notes

$$f \simeq g, \textcolor{red}{1}$$

$$f \simeq_H g, \textcolor{red}{1}$$

$$\bar{H}, \textcolor{red}{1}$$

$$H: f \simeq g, \textcolor{red}{1}$$

$$H: f \simeq g \operatorname{rel} A, \textcolor{red}{2}$$

$$[X, Y], \textcolor{red}{2}$$



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