

Point Set Topology

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1 Topological Spaces and Continuous Mappings

1.1 Metric Space

Definition 1.1. function

$$d: X^2 \rightarrow \mathbb{R} \quad (1-1)$$

$\forall x_1, x_2, x_3 \in X$ satisfied:

- a) $d(x_1, x_2) = 0 \Leftrightarrow x_1 = x_2$;
- b) $d(x_1, x_2) = d(x_2, x_1)$ (symmetry);
- c) $d(x_1, x_3) \leq d(x_1, x_2) + d(x_2, x_3)$ (Triangle inequality),

is called a **metric** or **distance** in X . Such X is said to be equipped with metric d , $(X; d)$ is called a **metric space**.

Some examples:

- $(\mathbb{R}^n; d_p)$, where $d_p(x_1, x_2) = \left(\sum_{i=1}^n |x_1^i - x_2^i|^p \right)^{1/p}$, while $d_\infty(x_1, x_2) = \max_{1 \leq i \leq n} |x_1^i - x_2^i|$.
- Similarly we can define metric spaces as $(C[a, b]; d_p)$ or $C_p[a, b]$. $d_p(f, g) = \left(\int_a^b |f - g|^p dx \right)^{\frac{1}{p}}$. C_∞ is called a **Chebyshev metric**.
- On class $\tilde{\mathfrak{R}}[a, b]$ over $\mathfrak{R}[a, b]$ similar metric can be defined. Functions are considered of one same class if they are equivalent except on a set not larger than null set.

Hilbert space denoted by $(\mathbb{H}; d)$ is defined as:

$$\mathbb{H} = \left\{ x = (x_1, x_2, \dots) \mid \forall i \in \mathbb{Z}_+ \left(\forall x_i \in \mathbb{R} \wedge \sum_{i=1}^{\infty} x_i^2 < \infty \right) \right\} \quad (1-2)$$

equipped with a metric d :

$$d: \mathbb{H}^2 \rightarrow \mathbb{R}; x, y \mapsto \sqrt{\sum_{i=1}^{\infty} (x_i - y_i)^2}. \quad (1-3)$$

To justify this definition, we need to introduce a lemma:

Lemma 1.

$$\forall n \in \mathbb{Z} \forall u \in \mathbb{R}^n \forall v \in \mathbb{R}^n \left(\sum_{i=1}^n u_i v_i \leq \sqrt{\sum_{i=1}^n u_i^2} \sqrt{\sum_{i=1}^n v_i^2} \right) \quad (1-4)$$

This is called **Schwarz inequality**.

Proof. If $\forall i = 1, \dots, n (v_i = 0)$ the equivalence has already been satisfied, therefore the following consider the situation that $\exists i \in \{1, \dots, n\} (v_i \neq 0)$. $\forall \lambda \in \mathbb{R}$

$$\sum_{i=1}^n (u_i + \lambda v_i)^2 = \sum_{i=1}^n u_i^2 + 2\lambda \sum_{i=1}^n u_i v_i + \lambda^2 \sum_{i=1}^n v_i^2 \geq 0$$

has at most one root. Hence $\Delta \leq 0$ will lead to the inequality 1-4. \square

Apply this inequality to $\sum_{i=1}^n (u_i + v_i)^2 = \sum_{i=1}^n u_i^2 + \sum_{i=1}^n v_i^2 + 2 \sum_{i=1}^n u_i v_i$ we can get

$$\sum_{i=1}^n (u_i + v_i)^2 \leq \sum_{i=1}^n u_i^2 + \sum_{i=1}^n v_i^2 + 2 \sqrt{\sum_{i=1}^n u_i^2} \sqrt{\sum_{i=1}^n v_i^2} = \left(\sqrt{\sum_{i=1}^n u_i^2} + \sqrt{\sum_{i=1}^n v_i^2} \right)^2,$$

in which substitute u_i, v_i by $x_i - y_i, x_i + y_i$ will result in triangle inequality. The inequality holds as the n limits to $+\infty$.

A metric space $(X; d)$ is called **discrete** if

$$\forall x \in X \left(\exists \delta_x \in \mathbb{R}_+ (\forall y \in X (y \neq x \rightarrow d(x, y) > \delta_x)) \right).$$

Lemma 2. If $(X; d)$ is a metric space, then $\forall a, b, u, v, |d(a, b) - d(u, v)| \leq d(a, u) + d(b, v)$.

Proof. Without loss of generality, we assume that $d(a, b) > d(u, v)$. According to the triangle inequality (see def. 1.1), $d(a, b) \leq d(a, u) + d(u, v) + d(v, b)$, which is to prove. \square

Definition 1.2. $\delta \in \mathbb{R}_+, a \in X$. Set

$$B(a; \delta) = \{x \in X \mid d(a, x) < \delta\}$$

is then called a **ball** with centre $a \in X$, and a radius of δ , or a **δ -ball** of point a .

Definition 1.3. An **open set** $G \subset X$ in metric space $(X; d)$ satisfies: $\forall x \in G, \exists B(x; \delta)$, s.t. $B(x; \delta) \subset G$.

Definition 1.4. A set $F \subset X$ in metric space $(X; d)$ is said to be a **closed set** if its complement $\mathbb{C}_X(F)$ is open.

It can be proved that \emptyset and X itself is both open and closed.

Proposition 1. a) An infinite union of open sets is an open set.

b) A finite intersection of open sets is an open set.

c) A finite union of closed sets is a closed set.

d) An infinite intersection of closed sets is a closed set.

- Proof.** a) If open sets $G_\alpha \subset X, \forall \alpha \in A, \forall a \in \bigcap_{\alpha \in A} G_\alpha, \exists \alpha_0 \in A, a \in G_{\alpha_0},$
 $\exists B(a; \delta) \subset G_{\alpha_0} \subset \bigcap_{\alpha \in A} G_\alpha.$
- b) Open sets $G_1 \cup G_2 \subset X, a \in G_1 \cap G_2,$ therefore $\exists \delta_1, \delta_2 \in \mathbb{R}_+, B(a; \delta_1) \subset G_1, B(a; \delta_2) \subset G_2,$ without loss of generality, let $\delta_1 \geq \delta_2, a \in B(a; \delta_1) \cap B(a; \delta_2) = B(a; \delta_2) \subset G_1 \cap G_2.$
- c) Just consider $\mathbb{C}_X(\bigcap_{\alpha \in A} F_\alpha) = \bigcup_{\alpha \in A} \mathbb{C}_X(F_\alpha)$ and a).
- d) Similarly, $\mathbb{C}_X(F_1 \cup F_2) = \mathbb{C}_X(F_1) \cap \mathbb{C}_X(F_2).$

□

1.2 Topological Space and Continuous Mapping

Definition 1.5. We say X is equipped with a **topological space** or equipped with **topology** if we assigned a $\mathcal{T} \subset 2^X$, which has got the following properties:

- a) $\emptyset \in \mathcal{T}; X \in \mathcal{T}.$
- b) $\forall \alpha \in A (G_\alpha \in \mathcal{T}) \rightarrow \bigcup_{\alpha \in A} G_\alpha \in \mathcal{T}.$
- c) $G_1 \in \mathcal{T} \wedge G_2 \in \mathcal{T} \rightarrow G_1 \cap G_2 \in \mathcal{T}.$

Then we call $(X; \mathcal{T})$ a **topological space**. Every $G \in \mathcal{T}$ is called an **open set**.

Definition 1.6. A topology \mathcal{T}_d insisting of the open sets in a metric space $(X; d)$ is called a **topology induced by metric d** .

A trivial example of topological space is **trivial topology**, which consists only of empty set and the space itself, i.e. $\mathcal{T} = \{\emptyset, X\}$. Another trivial example of topological space is **discrete topology**, which consists of all the subsets of the space i.e. $\mathcal{T} = 2^X$.

A **cofinite space** is a base set X equipped with a topology \mathcal{T} defined as follows:

$$\mathcal{T} = \{U \in 2^X \mid U = \emptyset \vee \mathbb{C}_X U \text{ is finite}\} \quad (1-5)$$

Proposition 2. The set \mathcal{T} under definition 1-5 is a topology.

Proof. a) $\emptyset \in \mathcal{T}, X \in \mathcal{T}.$

- b) $\forall i \in I (|\mathbb{C}_X A_i| \in \mathbb{N}) \rightarrow \forall i_0 \in I (|\bigcap_{i \in I} \mathbb{C}_X A_i| \leq |\mathbb{C}_X A_{i_0}|),$ therefore $\bigcup_{i \in I} A_i \in \mathcal{T}.$
- c) $\forall A \in \mathcal{T} \forall B \in \mathcal{T} (A \cap B = \emptyset \in \mathcal{T} \vee \mathbb{C}_X(A \cap B) = \mathbb{C}_X A \cup \mathbb{C}_X B \text{ is finite}),$ therefore $\forall A \in \mathcal{T} \forall B \in \mathcal{T} (A \cap B \in \mathcal{T}).$

□

Similarly, *countable complement space* can be defined.

Definition 1.7. Let $(X; \mathcal{T})$ be a topological space. If there exists a metric $d: X^2 \rightarrow \mathbb{R}$ s.t. $(X; \mathcal{T})$ is induced by d then call $(X; \mathcal{T})$ a ***metrizable space***, $(X; d)$ is its ***metrization***.

Definition 1.8. Let $(X; \mathcal{T})$, $(Y; \mathcal{S})$ be two topological space. A mapping f is said to be continuous if

$$\forall V \in \mathcal{S} (\exists U \in \mathcal{T} (U = f^{-1}(V))).$$

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