Point Set Topology

Hoyan Mok

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Chapter 1

Topological Spaces and Continuous Mappings

§1 Metric Space

Definition 1.1. function

$$d\colon X^2 \to \mathbb{R} \tag{1-1}$$

 $\forall x_1, x_2, x_2 \in X$ satisfied:

- a) $d(x_1, x_2) = 0 \Leftrightarrow x_1 = x_2;$
- b) $d(x_1, x_2) = d(x_2, x_1)$ (symmetry);
- c) $d(x_1, x_3) \leq d(x_1, x_2) + d(x_2, x_3)$ (Triangle inequality),

is called a **metric** or **distance** in X. Such X is said to be equiped with metric d, (X, d) is called a **metric** space.

Some examples:

- $(\mathbb{R}^n; d_p)$, where $d_p(x_1, x_2) = \left(\sum_{i=1}^n |x_1^i x_2^i|^p\right)^{1/p}$, while $d_{\infty}(x_1, x_2) = \max_{1 \le i \le n} |x_1^i x_2^i|$.
- Similarly we can define metric spaces as $(C[a,b];d_p)$ or $C_p[a,b]$. $d_p(f,g) = \left(\int_a^b |f-g|^p dx\right)^{\frac{1}{p}}$. C_{∞} is called a **Chebyshev metric**.
- On class $\mathfrak{R}[a,b]$ over $\mathfrak{R}[a,b]$ similar metric can be defined. Functions are considered of one same class if they are equivalent expect on a set not larger than null set.

Hilbert space denoted by $(\mathbb{H}; d)$ is defined as:

$$\mathbb{H} = \left\{ x = (x_1, x_2, \dots) \mid \forall i \in \mathbb{Z}_+ \left(\forall x_i \in \mathbb{R} \land \sum_{i=1}^{\infty} x_1^2 < \infty \right) \right\}$$
 (1-2)

equiped with a metirc d:

$$d: \mathbb{H}^2 \to \mathbb{R}; x, y \mapsto \sqrt{\sum_{i=1}^{\infty} (x_i - y_i)^2}.$$
 (1-3)

To justify this definition, we need to introduce a lemma:

Lemma 1.

$$\forall n \in \mathbb{Z} \forall \boldsymbol{u} \in \mathbb{R}^n \forall \boldsymbol{v} \in \mathbb{R}^n \left(\sum_{i=1}^n u_i v_i \le \sqrt{\sum_{i=1}^n u_i^2} \sqrt{\sum_{i=1}^n v_i^2} \right)$$
 (1-4)

This is called Schwarz inequality.

Proof. If $\forall i = 1, \dots, n(v_i = 0)$ the equivalence has already been satisfied, therefore the following considers the situation that $\exists i \in \{1, \dots, n\} (v_i \neq 0)$. $\forall \lambda \in \mathbb{R}$, the quadratic polynomial of λ

$$\sum_{i=1}^{n} (u_i + \lambda v_i)^2 = \sum_{i=1}^{n} u_i^2 + 2\lambda \sum_{i=1}^{n} u_i v_i + \lambda^2 \sum_{i=1}^{n} v_i^2 \ge 0$$

has at most one root. Hence $\Delta \leq 0$ will lead to the inequality 1-4.

Apply this inequality to $\sum_{i=1}^{n} (u_i + v_i)^2 = \sum_{i=1}^{n} u_i^2 + \sum_{i=1}^{n} v_i^2 + 2 \sum_{i=1}^{n} v_i \sum_{i=1}^{n} u_i$ we can get

$$\sum_{i=1}^{n} (u_i + v_i)^2 \le \sum_{i=1}^{n} u_i^2 + \sum_{i=1}^{n} v_i^2 + 2\sqrt{\sum_{i=1}^{n} u_i^2} \sqrt{\sum_{i=1}^{n} v_i^2} = \left(\sqrt{\sum_{i=1}^{n} u_i^2} + \sqrt{\sum_{i=1}^{n} v_i^2}\right)^2,$$

in which substitude u_i, v_i by $x_i - y_i, x_i + y_i$ will result in triangle inequality. The inequality holds as the n limits to $+\infty$.

Definition 1.2. Let (X, d) be a metric space, the **distant** between a non-empty set $\emptyset \neq A \in \mathscr{P}(X)$ and a point x is defined as:

$$d(A, x) = \inf\{d(x, y) \mid y \in A\},\$$

and we let d(x, A) = d(A, x). Also, the **distant** between two non-empty sets A, B is defined as:

$$d(A, B) = \inf\{d(x, y) \mid x \in A \land y \in B\}.$$

A metric space (X, d) is called **discrete** if

$$\forall x \in X \ (\exists \delta_x \in \mathbb{R}_+ (\forall y \in X (y \neq x \to d(x, y) > \delta_x))).$$

Lemma 2. If (X,d) is a metric space, then $\forall a,b,u,v, |d(a,b)-d(u,v)| \leq d(a,u)+d(b,v)$.

Proof. Without loss of generality, we assume that d(a,b) > d(u,v). According to the triangle inequality (see def. 1.1), $d(a,b) \le d(a,u) + d(u,v) + d(v,b)$, which is to prove.

Definition 1.3. $\delta \in \mathbb{R}_+, a \in X$. Set

$$B(a; \delta) = \{ x \in X \mid d(a, x) < \delta \}$$

is then called a **ball** with centre $a \in X$, and a radius of δ , or a δ -**ball** of point a.

Definition 1.4. An open set $G \subset X$ in metric space (X,d) satisfies: $\forall x \in G, \exists B(x;\delta), \text{ s.t.}$ $B(x;\delta) \subset G$.

Definition 1.5. A set $F \subset X$ in metric space (X, d) is said to be a **closed set** if its complement $\mathcal{C}_X(F)$ is open.

It can be proved that \emptyset and X itself is both open and closed.

Proposition 1. a) An infinite union of open sets is an open set.

- b) A finite intersection of open sets is an open set.
- c) A finite union of closed sets is a closed set.
- d) An infinite intersection of closed sets is a closed set.

a) If open sets $G_{\alpha} \subset X, \forall \alpha \in A, \forall a \in \bigcap_{\alpha \in A} G_{\alpha}, \exists \alpha_0 \in A, a \in G_{\alpha_0}, \exists B(a; \delta) \subset G_{\alpha_0} \subset G_{\alpha_0}$

- b) Open sets $G_1 \cup G_2 \subset X$, $a \in G_1 \cap G_2$, therefore $\exists \delta_1, \delta_2 \in \mathbb{R}_+$, $B(a; \delta_1) \subset G_1$, $B(a; \delta_2) \subset G_2$, without loss of generality, let $\delta_1 \geq \delta_2$, $\mathbb{R} \leq a \in B(a; \delta_1) \cap B(a; \delta_2) = B(a; \delta_2) \subset G_1 \cap G_2$.
- c) Just consider $\mathcal{C}_X \left(\bigcap_{\alpha \in A} F_{\alpha} \right) = \bigcup_{\alpha \in A} \mathcal{C}_X (F_{\alpha})$ and a).
- d) Similarly, $\mathcal{C}_X(F_1 \cup F_2) = \mathcal{C}_X(F_1) \cap \mathcal{C}_X(F_2)$.

$\S 2$ Topological Space

Definition 2.1. We say X is equiped with a topological space or equiped with topology if we assigned a $\mathcal{T} \subset 2^X$, which has got the following proporties:

- a) $\emptyset \in \mathcal{T}; X \in \mathcal{T}$.
- b) $\forall \alpha \in A(G_{\alpha} \in \mathscr{T}) \to \bigcup_{\alpha \in A} G_{\alpha} \in \mathscr{T}.$ c) $G_1 \in \mathscr{T} \land G_2 \in \mathscr{T} \to G_1 \cap G_2 \in \mathscr{T}.$

Then we call (X, \mathcal{T}) a topological space. Every $G \in \mathcal{T}$ is called an open set.

Definition 2.2. A topology \mathcal{T}_d insisting of the open sets in a metric space (X,d) is called a topology induced by metric d.

A trivial example of topological space is **trivial topology**, which consists only of empty set and the space itself, i.e. $\mathscr{T} = \{\emptyset, X\}$. Another trivial example of topological space is **discrete topology**, which consists of all the subsets of the space i.e. $\mathcal{T} = 2^X$.

A *cofinite space* is a base set X equiped with a topology $\mathscr T$ defined as follows:

$$\mathscr{T} = \{ U \in 2^X \mid U = \varnothing \lor \mathcal{C}_X U \text{ is finite} \}$$
 (2-1)

Proposition 2. The set \mathcal{I} under definition 2-1 is a topology.

a) $\emptyset \in \mathcal{T}, X \in \mathcal{T}$.

- b) $\forall i \in I (|C_X A_i| \in \mathbb{N}) \to \forall i_0 \in I (|\bigcap_{i \in I} C_X A_i| \le |C_X A_{i_0}|)$, therefore $\bigcup_{i \in I} A_i \in \mathscr{T}$.
- c) $\forall A \in \mathcal{T} \forall B \in \mathcal{T}(A \cap B) = \emptyset \in \mathcal{T} \vee \mathcal{C}_X(A \cap B) = \mathcal{C}_X A \cup \mathcal{C}_X B$ is finite), therefore $\forall A \in \mathcal{T} \forall B \in \mathcal{T} \cup \mathcal{C}_X B$ $\mathscr{T}(A \cap B \in \mathscr{T}).$

Similarly, *countable complement space* can be defined.

Let X be equiped with two topology $\mathscr{T}_1, \mathscr{T}_2$. $\mathscr{T}_1 \cup \mathscr{T}_2$ is possibly not a topology of X. For example, $\mathscr{T}_1 = \{(x, +\infty) \mid x \in \mathbb{R}\} \cup \{\varnothing, \mathbb{R}\} \text{ and } \mathscr{T}_2 = \{(-\infty, y) \mid y \in \mathbb{R}\} \cup \{\varnothing, \mathbb{R}\} \text{ are both }$ topologies of \mathbb{R} , but there union $T_1 \cup T_2$ is not.

Theorem 2.1. Let X be equiped with two topology $\mathscr{T}_1, \mathscr{T}_2$. Their intersection $\mathscr{T}_1 \cap \mathscr{T}_2$ is also a topology on X.

Proof. a) $\{\emptyset, X\} \subset \mathcal{T}_1 \land \{\emptyset, X\} \subset \mathcal{T}_2 \rightarrow \{\emptyset, X\} \subset \mathcal{T}_1 \cap \mathcal{T}_2$.

b)
$$\forall \alpha \in A(G_{\alpha} \in \mathscr{T}_1 \cap \mathscr{T}_2) \to \bigcup_{\alpha \in A} G_{\alpha} \in \mathscr{T}_1 \land \bigcup_{\alpha \in A} G_{\alpha} \in \mathscr{T}_2.$$

c)
$$\forall G_1 \in \mathscr{T}_1 \cap \mathscr{T}_2 \forall G_2 \in \mathscr{T}_1 \cap \mathscr{T}_2 \big(G_1 \cap G_2 \in \mathscr{T}_1 \wedge G_1 \cap G_2 \in \mathscr{T}_2 \big)$$

Definition 2.3. Let (X, \mathcal{T}) be a topological space. If there exists a metric $d: X^2 \to \mathbb{R}$ s.t. (X, \mathcal{T}) is induced by d then call (X, \mathcal{T}) a **metrizable space**, (X, d) is its **metrization**.

§3 Neighbourhood

Definition 3.1. Let (X, \mathcal{F}) be a topological space. A set U(x) is said to be a **neighbourhood** of a point $x \in X$ if $\exists G \in \mathscr{T}(G \subseteq U(x) \land x \in G)$. If $U(x) \in \mathscr{T}$, it is called an **open neighbourhood**. Subset class $\{U(x) \subseteq X \mid U(x) \text{ is a neighbourhood of } x\}$ is called the **neighbourhood system** of point x, denoted by \mathcal{U}_x

Theorem 3.1. Let (X, \mathcal{T}) be a topological space, U is a subset of X. U is an open set iff $\forall x \in U$, U is a neighbourhood of x.

Proof. The necessity is trivial. $\forall x \in U \exists V(x)$ s.t. V(x), being a subset of U, is an open neighbourhood of x. By definition of topology, $\bigcup_{x\in U}V(x)\in \mathscr{T}. \ \forall x\in U(x\in\bigcup_{x\in U}V(x))\to U\subseteq V,$ while $\forall x\in U(V(x)\subseteq U)\to\bigcup_{x\in U}V(x)\subseteq U,$ therefore $U=\bigcup_{x\in U}V(x)\in \mathscr{T}.$

$$\forall x \in U(V(x) \subseteq U) \to \bigcup_{x \in U} V(x) \subseteq U, \text{ therefore } U = \bigcup_{x \in U} V(x) \in \mathscr{T}.$$

Theorem 3.2. Let (X, \mathcal{F}) be a topological space, \mathcal{U}_x is a neighbourhood system of point $x \in X$.

$$\forall U \in \mathscr{U}_x \forall V \in \mathscr{U}_x (U \cap V \in \mathscr{U}_x)$$

Proof. $\forall U \in \mathscr{U}_x \forall V \in \mathscr{U}_x \exists U_0 \in \mathscr{T} \exists V_0 \in \mathscr{T}(U_0 \subseteq U \land V_0 \subseteq V \land x \in U_0 \cap V_0)$, By definition of topology, $\mathcal{T} \ni U_0 \cap V_0 \subseteq U \cap V$.

In history topologies were once built on neighbourhood systems. The following theorem shows the way.

Theorem 3.3. Let X be a set and $\forall x \in X$ a collection of subsets $\mathscr{U}_x \in \mathscr{P}(X)$ is appointed, satisfying:

- $(1) \ \forall x \in X \big(\mathscr{U}_x \neq \varnothing \land \forall U \in \mathscr{U}_x (x \in U) \big);$
- (2) $\forall x \in X \forall U \in \mathscr{U}_x \forall V \in \mathscr{U}_x (U \cap V \in \mathscr{U}_x);$
- (3) $\forall x \in X \forall U \in \mathscr{U}_x \forall V \in \mathscr{P}(X)(U \subseteq V \to V \in \mathscr{U}_x);$
- $(4) \ \forall x \in X \forall U \in \mathscr{U}_x \exists V \in \mathscr{U}_x \big(V \subseteq U \land \forall y \in V (V \in \mathscr{U}_y) \big),$

then there exists only one topology \mathscr{T} on X s.t. $\forall x \in X$, \mathscr{U}_x is the neighbourhood system of x in (X,\mathscr{T}) .

Proof. Let $\mathscr{T} = \{G \in \mathscr{P}(X) \mid \forall x \in G(G \in \mathscr{U}_x)\}.$

- a) Obviously $\emptyset \in \mathcal{F}$. Since the condition (1) and the condition (3) in theorem 3.3, $X \in \mathcal{F}$.
- b) Let $A, B \in \mathcal{F}$. Consider the condition (2) in theorem 3.3 applied to $x \in A \cap B$.
- c) Let $\forall i \in I(G_i \in \mathscr{T})$. $\forall x \in \bigcup_{i \in I} G_i$, there must exists a $i \in I$ s.t. $x \in G_i$ and $G_i \in \mathscr{U}_x$. Since the condition (3) in theorem 3.3, $G_i \subseteq \bigcup_{i \in I} G_i$ has implied $\bigcup_{i \in I} G_i \in \mathscr{U}_x$.

These tells that \mathcal{T} is a topology on X.

The condition (4) in theorem 3.3 tells that there always exists a $G \subset U$ for all $x \in X$ and $U \in \mathcal{U}_x$ s.t. $G \in \mathcal{T}$. Therefore \mathcal{U}_x must be a subset of the neighbourhood system of x.

For all neighbourhood U of $x \in X$, there must be a open neighbourhood subset $G \subseteq U$, which is also a member of \mathcal{U}_x . Since the condition (3) in theorem 3.3, $U \in \mathcal{U}_x$. Therefore the neighbourhood system of x must be a subset of \mathcal{U}_x .

Therefore, \mathcal{U}_x is the neighbourhood system of x.

Now prove the uniqueness. Let there be another topology \mathscr{T}' . Since theorem 3.1, $\forall U(G \in \mathscr{T}' \leftrightarrow \forall x \in G(G \in \mathscr{U}_x))$. Therefore $\mathscr{T}' = \mathscr{T}$.

§4 Continuous Mappings

Definition 4.1. A mapping $f: X \to Y$, where X,Y is respectively equiped with topology $\mathscr{T}_X, \mathscr{T}_Y$, is said to be **continuous** at $x_0 \in X$ (let $y_0 = f(x_0) \in Y$), if $\forall U(y_0), \exists U(x_0) \text{ s.t. } f(U(x_0)) \subset U(y_0)$. It is **continuous** in X if it is continuous at each point $x \in X$.

The set of continuous mappings from X into Y can be denoted by C(X,Y) or C(X) when Y is clear.

It can be easily proved that an identify function $e_X : X \to X$ where X is equiped with a topology \mathscr{T} is a continuous function.

Theorem 4.1. (criterion of continuity)

Let (X,\mathcal{T}) , $(Y;\mathcal{L})$ be two topological space. A mapping $f:X\to Y$ is continuous iff

$$\forall V \in \mathscr{S}(\exists U \in \mathscr{T}(U = f^{-1}(V))).$$

Proof. \to : It is obvious if $f^{-1}(G_Y) = \emptyset$. If $f^{-1}(G_Y) \neq \emptyset$ and $\forall x_0 \in f^{-1}(G_Y)$, since $f \in C(X,Y)$, for $G_Y \in \mathscr{S}$, $\exists U(x_0)$ s.t $f(U(x_0)) \subset G_Y$. Also notice that $f(U(x_0)) \subset G_Y \Rightarrow U(x_0) \subset f^{-1}(G_Y)$, therefore $f^{-1}(G_Y)$ is open (Theorem 3.1).

 $\leftarrow: \forall x_0 \in X$, let $y_0 = f(x_0), f^{-1}(U(y_0)) \in \mathcal{F}$ if $U(y_0) \in \mathcal{S} \cap \mathcal{U}_{y_0}$. Notice that $x_0 \in f^{-1}(U(y_0)), f^{-1}(U(y_0))$ is a neighbourhood of x_0 , therefore $f \in C(X,Y)$.

Theorem 4.2. Let (X, \mathcal{T}_X) , (Y, \mathcal{T}_Y) , (Z, \mathcal{T}_Z) be topological spaces. If $f: X \to Y$ and $g: Y \to Z$ are both continuous, $g \circ f: X \to Z$ is also continuous.

Proof.

$$\forall W \in \mathscr{T}_Z \left(g^{-1}(W) \in \mathscr{T}_Y \right) \to \forall W \in \mathscr{T}_Z \left(f^{-1}(g^{-1}(W)) \right)$$

Since $f^{-1}(g^{-1}(W)) = (g \circ f)^{-1}(W)$, the theorem has been proved.

Definition 4.2. (X, \mathcal{I}_X) and (Y, \mathcal{I}_Y) are both topological spaces. A bijective mapping $f: X \to Y$ is a **homeomorphism** if $f \in C(X, Y) \land f^{-1} \in C(Y, X)$.

Definition 4.3. Two topological spaces (X, \mathcal{T}_X) and (Y, \mathcal{T}_Y) are said to be **homeomorphic** if there exists a homeomorphism $f: X \to Y$.

Homeomorphic topological spaces are identical with respect to their topological propoties since the theorem 4.1 has shown that their open sets correspond to each other. In fact homeomorphic relations are equivalent relations.

§5 Closure

Definition 5.1. Let X be a topological space and A be a subset of X. Let $x \in X$. If $\forall U \in \mathscr{U}_x \big(U \cap (A - \{x\}) \neq \varnothing \big)$, then x is called a *accumulation point*, *cluster point* or *limit point* of A. The set $A' := \{x \in X \mid x \text{ is a accumulation point of } A\}$ is called the *derived set* of A. A point $a \in A$ is called a *isolated point* of A if $a \notin A'$.

Theorem 5.1. Let X be a topological space and A, B be subsets of X. 1) $A \subseteq B \to A' \subseteq B'$; 2) $(A \cup B)' = A' \cup B'$; 3) $(A')' \subseteq A \cup A'$.

Proof. 1) When $A \subseteq B$, $U \cap (A - \{x\}) \subseteq U \cap (B - \{x\})$.

- 2) $(A \cup B)' = \{x \in X \mid \forall U \in \mathcal{U}_x (U \cap (A \cup B \{x\}) \neq \emptyset)\}$. Also $U \cap (A \cup B \{x\}) = U \cap (X \{x\}) \cap (A \cup B) = (U \cap A \{x\}) \cup (U \cap B \{x\})$.
- 3) If $x \notin A \cup A'$, then $\exists G \in \mathscr{U}_x \cap \mathscr{T}(G \cap (A \{x\})) = G \cap A = \varnothing)$. $\forall y \in G$, G itself is a neighbourhood of y that $G \cap (A \{y\}) = G \cap A = \varnothing$, therefore $y \notin A'$. This means that G is a neighbourhood of x that $G \cap (A' \{x\}) = G \cap A' = \varnothing$, i.e. $x \notin (A')'$.

Definition 5.2. Let (X, \mathcal{T}) be a topological space and F be a subset of X. F is said to be **closed** iff $\mathcal{C}_X(F) \in \mathcal{T}$. The collection all closed sets is denoted by \mathcal{F} .

Theorem 5.2. Let (X,\mathcal{F}) be a topological space and F be a subset of X. F is closed iff $F'\subseteq F$.

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Proof. \to : If $x \notin F$ then $x \in \mathcal{C}_X(F)$, which is open in (X, \mathscr{T}) . Then $\mathcal{C}_X(F)$ is a neighbourhood that $\mathcal{C}_X(F) \cap (F - \{x\}) = \mathcal{C}_X(F) \cap F = \varnothing$, i.e. $x \notin F'$.

 \leftarrow : $\forall x \notin F(x \notin F')$, then there exists an open neighbourhood U of x that $U \cap F = \emptyset$, then $\mathcal{C}_X(F)$ is always a neighbourhood of its elements, since theorem 3.1, $\mathcal{C}_X(F) \in \mathscr{T}$.

Definition 5.3. Let (X, \mathcal{T}) be a topological space and A be a subset of X. Set $\overline{A} := A \cup A'$ is called a *closure* of A.

Theorem 5.3. Let (X, \mathcal{T}) be a topological space and A be a subset of X. Let $x \in X$.

$$x \in \overline{A} \leftrightarrow \forall U \in \mathscr{U}(x)(U \cap A \neq \varnothing).$$

Proof. \rightarrow : If $x \in A$ then $\{x\} \subseteq U \cap A$, else if $x \in A'$ then $U \cap A \supset (U - \{x\}) \cap A \neq \emptyset$. \leftarrow : If $\exists U \in \mathscr{U}(x) ((U - \{x\}) \cap A = \emptyset) \land x \notin A$, then there exists a $U \in \mathscr{U}(x)$ s.t. $U \cap A = \emptyset$. \square

Theorem 5.4. Let (X, \mathcal{T}) be a topological space and A be a subset of X. A is closed in (X, \mathcal{T}) iff $A = \overline{A}$.

Proof. Since theorem 5.2, A is closed iff $A' \subseteq A$, which iff $A = A \cup A' = \overline{A}$.

Corollary 1. Let (X, \mathcal{F}) be a topological space and A be a subset of X. \overline{A} is always closed.

Proof. Since (3) of theorem 5.1, $\overline{\overline{A}} = \overline{A}$.

Lemma 3. Let (X, \mathcal{T}) be a topological space and A, B be subsets of X. $A \subseteq B \to \overline{A} \subseteq \overline{B}$.

Proof.
$$A \subseteq B \to A' \subseteq B'$$
 ((1) of theorem 5.1), so $A \cup A' \subseteq B \cup B'$, i.e. $\overline{A} \subseteq \overline{B}$.

We can say that the closure of a set is the smallest closed set containing it, as long as we prove the following theorem:

Theorem 5.5. Let (X, \mathcal{T}) be a topological space and A be a subset of X.

$$\overline{A} = \bigcap_{F \in \mathscr{F} \land A \subseteq F} F.$$

Proof. Since \overline{A} itself is closed (corollary 1), $\bigcap_{F \in \mathscr{F} \land A \subseteq F} F \subseteq \overline{A}$. On the other hand, $\bigcap_{F \in \mathscr{F} \land A \subseteq F} F$ is closed, so $\overline{\bigcap_{F \in \mathscr{F} \land A \subseteq F} F} = \bigcap_{F \in \mathscr{F} \land A \subseteq F} F$. Therefore, $A \subseteq \bigcap_{F \in \mathscr{F} \land A \subseteq F} F \to \overline{A} \subseteq \bigcap_{F \in \mathscr{F} \land A \subseteq F} F$ (Lemma 3).

Theorem 5.6. Let (X,d) be a metric space and A be a non-empty subset of X.

- 1) $\forall x \in X, x \in A' \leftrightarrow d(x, A \{x\}) = 0.$
- 2) $\forall x \in X, x \in \overline{A} \leftrightarrow d(x, A) = 0.$

Proof. 1) We have $x \in A'$ iff $\forall \varepsilon \in \mathbb{R}_+ (B(x,\varepsilon) \cap (A - \{x\}) \neq \varnothing)$, which is established iff $\forall \varepsilon \in \mathbb{R}_+ \exists y \in A - \{x\} (d(x,y) < \varepsilon)$.

2) We only need to substitude $A - \{x\}$ with A in 1).

Theorem 5.7. Let (X, \mathcal{T}) and (Y, \mathcal{S}) be two topological spaces, and $f: X \to Y$. Note the collections of closed sets in X and Y by \mathscr{F}_X , \mathscr{F}_Y . The statements below are equivalent:

- (1) $f \in C(X, Y)$.
- (2) $\forall F \in \mathscr{F}_Y(f^{-1}(F) \in \mathscr{F}_X).$
- (3) $\forall A \in \mathscr{P}(X)(f(\overline{A}) \subseteq \overline{f(A)}).$
- $(4) \ \forall B \in \mathscr{P}(Y)(\overline{f^{-1}(B)} \subseteq f^{-1}(\overline{B})).$

Proof. (1) \rightarrow (2): Only to notice that $f^{-1}(\mathbb{C}_Y F) = \mathbb{C}_X f^{-1}(F)$.

- (2) \rightarrow (3): $\forall A \in \mathscr{P}(X)$ we have $f(A) \subseteq \overline{f(A)}$, so $A \subseteq f^{-1}(\overline{f(A)})$. By (2) we know that $f^{-1}(\overline{f(A)})$ is closed, therefore $\overline{A} \subseteq \overline{f^{-1}(\overline{f(A)})} = f^{-1}(\overline{f(A)})$, so $f(\overline{A}) \subseteq \overline{f(A)}$.
- (3) \rightarrow (4): By (3) we know that $\forall B \in \mathscr{P}(Y), f(\overline{f^{-1}(B)}) \subseteq \overline{f(f^{-1}(B))}$. Also $f(f^{-1}(B)) \subseteq B$ (equality satisfied when f is surjective), then $f(\overline{f^{-1}(B)}) \subseteq \overline{B}$, so $\overline{f^{-1}(B)} \subseteq f^{-1}(\overline{B})$.
 - $(4) \to (1)$: $\forall G \in \mathscr{S}, \, \mathcal{C}_Y G \in \mathscr{F}_Y$, so by (3), we have

$$\overline{\mathbb{C}_X f^{-1}(G)} = \overline{f^{-1}(\mathbb{C}_Y G)} \subseteq f^{-1}(\overline{\mathbb{C}_Y G}) = f^{-1}(\mathbb{C}_Y G) = \mathbb{C}_X f^{-1}(G).$$

However by the definition of closure $\mathbb{C}_X f^{-1}(G) \subseteq \overline{\mathbb{C}_X f^{-1}(G)}$. Therefore $\mathbb{C}_X f^{-1}(G) = \overline{\mathbb{C}_X f^{-1}(G)}$, which means $\mathbb{C}_X f^{-1}(G)$ is closed (theorem 5.4), i.e. $f^{-1}(G)$ is open.

§6 Interior Points and Boundary

Definition 6.1. Let (X, \mathcal{T}) be a topological space and A be a subset of X. We call x an *interior point* of A if A is a neighbourhood of x. We call x an *exterior point* of A if $\mathcal{C}_X(A)$ is a neighbourhood of x. The sets of all interior points of A is the *interior* of A, noted by int A.

Theorem 6.1. Let (X, \mathcal{F}) be a topological space and A be a subset of X. int $A = \mathbb{C}_X(\overline{\mathbb{C}_X(A)})$, $\overline{A} = \mathbb{C}_X(\inf \mathbb{C}_X(A))$.

Proof. $x \in \text{int } A$ implies an open set G which is a subset of A and $x \in G$. The complement of G is closed, thus its closure is $\mathcal{C}_X(G)$ itself. $\mathcal{C}_X(A) \subseteq \mathcal{C}_X(G) \to \overline{\mathcal{C}_X(A)} \subseteq \mathcal{C}_X(G)$ (Lemma 3), therefore $x \notin \overline{\mathcal{C}_X(A)}$, which is the first equation to prove.

To prove the second one only need to replace the A with $\mathcal{C}_X(A)$ in the first equation.

Theorem 6.2. Let (X, \mathcal{T}) be a topological space and G be a subset of X.

$$G \in \mathscr{T} \leftrightarrow \operatorname{int} G = G$$

Proof. G is open iff the complement of G is closed. And $C_X(G) = \overline{C_X(G)}$. The complement of the both size of this equation and Theorem 6.1 give the proof of the theorem.

With the proporties of closure and Theorem 6.1 the following statements should be easy to prove:

Theorem 6.3. Let (X, \mathcal{T}) be a topological space and A, B be subsets of X. $int(A \cap B) = int A \cap int B$, int(int A) = int A,

$$int A = \bigcup_{G \in \mathscr{T} \land G \subseteq A} G.$$

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Therefore we can say that the interior of A is the largest open set contianed in A.

Definition 6.2. Let (X, \mathcal{T}) be a topological space and A be a subset of X. A point x is said to be a **boundary point** of A if $\forall U \in \mathcal{U}(x) \big(U \cap A \neq \emptyset \wedge U \cap \mathcal{C}_X(A) \neq \emptyset \big)$. The set of all boundary points of A is called the **boundary** of A, noted by ∂A .

Theorem 6.4. Let (X, \mathcal{T}) be a topological space and A be a subset of X. (1) $\partial A = \overline{A} \cap \overline{\mathbb{C}_X(A)}$; (2) int $A = \overline{A} - \partial A$; (3) $\overline{A} = \operatorname{int} A \cup \partial A$.

Proof. (1): Apply Theorem 5.3 to both A and $\mathcal{C}_X(A)$.

 $(2): \operatorname{int} A \cup \partial A = A \cup (\overline{A} \cap \overline{\mathbb{C}_X(A)}) = \overline{A} \cap \left(\operatorname{int} A \cup \mathbb{C}_X(\operatorname{int} A)\right) = \overline{A}.$

$$(3) \ \overline{A} - \partial A = \overline{A} - (\overline{A} \cap \overline{\mathbb{C}_X(A)}) = \overline{A} \cap \mathbb{C}_X(\overline{\mathbb{C}_X(A)}) = \overline{A} \cap \operatorname{int} A = \operatorname{int} A.$$

§7 Basis

Definition 7.1 (Basis). Let (X, \mathcal{T}) be a topological space and \mathcal{B} be a subset of \mathcal{T} . If $\forall G \in \mathcal{T} \exists \mathcal{B}_G \in \mathcal{P}(\mathcal{B}) \big(G = \cup \mathcal{B}_G \big)$, then we call \mathcal{B} a **basis** or a **base** of the topology \mathcal{T} . We call the minimum topology of which \mathcal{B} is a basis the **closure** of basis \mathcal{B} .

Theorem 7.1. Let (X, \mathcal{T}) be a topological space and \mathcal{B} be a subset of \mathcal{T} . \mathcal{B} is a basis of \mathcal{T} iff $\forall x \in X \forall U \in \mathcal{U}_x \exists B \in \mathcal{B}(x \in B \land B \subseteq U)$.

Proof. \to : $U \in \mathcal{U}_x$ implies an open set $G \in \mathcal{P}(U)$ that contians x, which is the union of elements in \mathcal{B} . Therefore there exists a $B \in \mathcal{B}$, which is the subset of U and it contians x.

 \leftarrow : $\forall G \in \mathcal{T}$, it is a neighbourhood of all the points in G. For all x in G assign a $B_x \in \mathcal{B}$ which contians x and is the subset of G, so that G is the Union of all the B_x .

Theorem 7.2. Let \mathscr{B} be a basis of a topological space (X, \mathscr{T}) .

$$\forall B_1 \in \mathscr{B} \, \forall B_2 \in \mathscr{B} \, \forall x \in B_1 \cap B_2 \, \exists B \in \mathscr{B} \, (x \in B \subseteq B_1 \cap B_2).$$

Proof. By definition of topology and basis, B_1 and B_2 are both open and their intersection $B_1 \cap B_2$ is open as well. Then there exists a collections of sets in \mathscr{B} whose union is $B_1 \cap B_2$, there must be at least a set B that contians x.

The topology \mathscr{T} on X is determinded if the basis \mathscr{B} is given, that is, if the union of \mathscr{B} is X and it satisfies Theorem 7.2, then \mathscr{T} , which is defined by the collection of the unions of Bs in \mathscr{B} , is the *only* topology on X such that \mathscr{B} is a basis of it.

For example, *lower limit topology* \mathcal{I}_{ℓ} on \mathbb{R} is defined by giving a basis:

$$\mathscr{B}_{\ell} = \{ [a, b) \mid a, b \in \mathbb{R} \land a < b \},$$

and $(\mathbb{R}, \mathcal{T}_{\ell})$ is called the *lower limit topological space*, the *Sorgenfrey line* or the *arrow*, denoted by \mathbb{R}_{ℓ} .

It is obvious that $\mathscr{T} \subsetneq \mathscr{T}_{\ell}$, where \mathscr{T} is the standard topology on \mathbb{R} .

Definition 7.2. Let (X, \mathcal{T}) be a topological space and \mathcal{L} be a subset of \mathcal{T} . If the collection \mathcal{B} of the finite intersections of the non-empty sets in \mathcal{L} is a basis of \mathcal{T} , i.e.

$$\mathscr{B} = \left\{ \bigcap_{i=1}^{n} S_i \mid S_i \in \mathscr{S}, \ i = 1, \dots, n, \ n \in \mathbb{N}_+ \right\},\,$$

then we call \mathscr{S} a subbasis or a subbase of \mathscr{T} .

A set X, given a collection $\mathscr S$ of subsets whose union is X itself, can be equiped with only one topology $\mathscr T$ so that $\mathscr S$ is a subbasis of the topology.

Theorem 7.3. Let $(X, \mathcal{T}_X), (Y, \mathcal{T}_Y)$ be two topological space and $f: X \to Y$. The following statements are equivalent:

- (1) $f \in C(X,Y)$;
- (2) There exists a basis \mathscr{B}_Y of Y that $\forall B \in \mathscr{B}_Y(f^{-1}(B) \in \mathscr{T}_X)$;
- (3) There exists a subbasis \mathscr{S}_Y of Y that $\forall S \in \mathscr{S}_Y (f^{-1}(S) \in \mathscr{T}_X)$.

Proof. It is almost obvious that $(1) \rightarrow (2)$ and $(1) \rightarrow (3)$. Since

$$f^{-1}\left(\bigcup_{B\in\mathscr{B}_Y} B\right) = \bigcup_{B\in\mathscr{B}_Y} f^{-1}(B)$$
$$f^{-1}\left(\bigcap_{k=1,S_k\in\mathscr{S}} S_k\right) = \bigcap_{k=1,S_k\in\mathscr{S}} f^{-1}(S_k)$$

 $(2) \rightarrow (1)$ and $(3) \rightarrow (2)$ can be proved.

Definition 7.3. Let X be a topological space, $x \in X$ and \mathscr{U}_x be a neighbourhood system of x. If $\mathscr{V}_x \subseteq U_x$, and $\forall U \in \mathscr{U}_x \exists V \in \mathscr{V}_x (V \subseteq U)$, then we call \mathscr{V}_x a basis of \mathscr{U}_x or a basis at point x. If $\mathscr{W}_x \subseteq U_x$, If the collection \mathscr{V}_x of the finite intersections of the non-empty sets in \mathscr{W}_x is a **basis** of \mathscr{U}_x , i.e.

$$\mathscr{V}_x = \left\{ \bigcap_{i=1}^n W_i \mid W_i \in \mathscr{W}_x, \ i = 1, \dots, n, \ n \in \mathbb{N}_+ \right\},\,$$

then we call \mathcal{W}_x a **subbasis** of \mathcal{U}_x or of the point x.

There is also a theorem that is similar with the Theorem 7.3.

Theorem 7.4. Let $(X, \mathcal{T}_X), (Y, \mathcal{T}_Y)$ be two topological space and $f: X \to Y$. $x \in X$, $y = f(x) \in Y$. The following statements are equivalent:

- (1) f is continuous at point x;
- (2) There exists a basis \mathcal{V}_y at y that $\forall V \in \mathcal{V}_y(f^{-1}(V) \in \mathcal{U}_x)$;
- (3) There exists a subbasis \mathcal{W}_y at y that $\forall W \in \mathcal{W}_y(f^{-1}(W) \in \mathcal{U}_x)$.

The proof of this theorem is similar to the proof of the Theorem 7.3

Theorem 7.5. Let X be a topological space and $x \in X$.

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(1) If \mathcal{B} is a basis of X, then

$$\mathscr{B}_x = \{ B \in \mathscr{B} \mid x \in B \}$$

is a basis at point x.

(2) If \mathcal{S} is a subbasis of X, then

$$\mathscr{S}_x = \{ S \in \mathscr{S} \mid x \in S \}$$

 $is\ a\ subbasis\ at\ point\ x.$

Proof. From Theorem 7.1 (1) can be easily derived. Let \mathcal{B}_x be $\{B \in \mathcal{B} \mid x \in B\}$ where

$$\mathscr{B} = \left\{ \bigcap_{i=1}^{n} S_i \mid S_i \in \mathscr{S}, \ i = 1, \dots, n, \ n \in \mathbb{N}_+ \right\}.$$

Let

$$\tilde{\mathscr{B}}_x = \left\{ \bigcap_{i=1}^n S_i \mid S_i \in \mathscr{S}_x, \ i = 1, \cdots, n, \ n \in \mathbb{N}_+ \right\}.$$

We need to prove that $\tilde{\mathscr{B}}_x = \mathscr{B}_x$. If $U \in \mathscr{B}_x$ then $x \in U$ and $\exists \mathscr{S}_U \subseteq \mathscr{S}$ and $\cup \mathscr{S}_U = U$. Since $\forall S_U \in \mathscr{S}_U (x \in S_U)$ hence $\mathscr{S}_U \subseteq \mathscr{S}_x$. Therefore $\cup \mathscr{S}_U = U \in \tilde{\mathscr{B}}_x$. This is the proof of $\mathscr{B}_x \subseteq \tilde{\mathscr{B}}_x$, and $\tilde{\mathscr{B}}_x \subseteq \mathscr{B}_x$ can be proved similarly.

Chapter 2

Basic Properties of Topological Spaces

§8 Seperability

Seperabilities are some properties that describe how to can distinguish points in a topological space with their neighbourhoods. Since they are some additional properties to our definition, they are often call "axioms".

Definition 8.1 (T_0 or Kolmogorov). Let (X, \mathcal{T}) be a topological space. If $\forall x \in X \ \forall y \in X (x \neq y)$, $\exists U \in \mathcal{U}(x) \ \exists V \in \mathcal{U}(y) \ \text{s.t.} \ x \notin V \lor y \notin U$, we say that (X, \mathcal{T}) is a T_0 **space** or **Kolmogorov space**.

Definition 8.2 (T_1 or Fréchet). Let (X, \mathcal{T}) be a topological space. If $\forall x \in X \ \forall y \in X (x \neq y)$, $\exists U \in \mathcal{U}(x) \ \exists V \in \mathcal{U}(y) \ \text{s.t.} \ x \notin V \land y \notin U$, we say that (X, \mathcal{T}) is a T_1 **space** or **Fréchet space**.

Theorem 8.1 (Finite subspaces are closed iff T_1). Topological space (X, \mathcal{T}) is T_1 iff $\forall F \in 2^X$, card $F \in \mathbb{N} \to \mathbb{C}_X F \in \mathcal{T}$.

Corollary 2. Let X be T_1 , and $A \in 2^X$, $a \in A$. If a is a accumulation point of A, then $\forall U \in \mathcal{U}(a)$, card $U \cap A \geq \omega$.

Definition 8.3 (T_2 or Hausdorff). Let (X, \mathcal{T}) be a topological space. If $\forall x \in X \ \forall y \in X (x \neq y)$, $\exists U \in \mathcal{U}(x) \ \exists V \in \mathcal{U}(y) \ \text{s.t.} \ U \cap V = \emptyset$, we say that (X, \mathcal{T}) is a T_2 **space** or **Hausdorff space**.

Theorem 8.2 (The uniqueness of limit in T_2). Let X be T_2 , $\langle x_n \rangle \in X^{\mathbb{N}}$. If a, b are both limits of $\langle x_n \rangle$, then a = b.

Chapter 3

Product Spaces and Quotient Spaces

§9 Product Space

Definition 9.1 (Product space). Let $(X_1, \mathcal{T}_1, (X_2, \mathcal{T}_2))$ be two topological spaces. The topology \mathcal{T} of the **product space** $(X_1 \times X_2, \mathcal{T})$ is defined by the closure of basis $\mathcal{B} = \{U_1 \times U_2 \mid U_1 \in \mathcal{T}_1 \land U_2 \in \mathcal{T}_2\}$.

By definition, we can tell that the projection mappings $\pi_1: X_1 \times X_2 \to X_1; (x_1, x_2) \mapsto x_1$ is continuous, so is π_2 .

Theorem 9.1. $f: Y \to X_1 \times X_2 \in C(Y, X_1 \times X_2) \iff \pi_1 \circ f \in C(Y, X_1) \land \pi_2 \circ f \in C(Y, X_2).$

§10 Quotient Space

Definition 10.1 (Quotient space). Let (X, \mathcal{T}) be a topological space, \sim be a equivalence relation of $X, p: X \to X / \sim; x \mapsto [x]$. The topological space $(X / \sim, p(\mathcal{T}))$ is called the **quotient space** of X with respect to \sim . Here p is called a **quotient map** associated to \sim .

Theorem 10.1. $f \in C(X/\sim,Y) \iff f \circ p \in C(X,Y)$.

Definition 10.2 (Quotient map). $f: X \to Y$ is called a *quotient map* if:

- $(1) f \in C(X,Y);$
- (2) f(X) = Y;
- (3) $f^{-1}(V) \in \mathscr{T}_X \to V \in \mathscr{T}_Y$.

We can consider fibres of f be equivalence classes of X, in that way, $X/\sim_f \simeq Y$ (Y and X/\sim_f are homeomorphic).

Theorem 10.2 (Continuous surjective to Hausdorff space is quotient). Let Y be a Hausdorff space. If $f \in C(X,Y)$ is surjective, then f is a quotient map.

Theorem 10.3 (Composition of quotient maps is quotient). If $f: X \to Y$ and $g: Y \to Z$ are both quotient, then $g \circ f$ is also quotient.

Definition 10.3 (Quotient space divided by a subset). $A \subseteq X$. If we define \sim by $x \sim y \iff (x \in A \land y \in A) \lor (x \notin A \land y \notin A)$, we denote the quotient space X/\sim by X/A.

Definition 10.4 (Topological cone). The *topological cone* of X is defined as $CX := X \times [0,1]/X \times \{1\}$.

Fig. 3.1 illustrates a topological cone.

Definition 10.5 (Gluing). X and Y are both subspaces of Z, f is a surjective map from X to Y (f(X) = Y). Define \sim_f on Z as: $x \sim y \iff x = y \vee y = f(x)$. Then $Z_f := Z/\sim_f$ is called the **gluing** of X and Y along f.

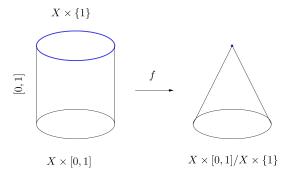


Figure 3.1: A topological cone

Chapter 4

Topological Manifolds

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Symbol List

Here listed the important symbols used in this notes

CX, 14	$\mathscr{T}, \frac{3}{3}$
d, 1	X/A, 14 X/\sim , 13
H, 1	$Z_f, \frac{14}{}$

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