Differential Geometry

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Chapter 1

Manifolds

Chapter 2

Scalar and Vector Fields

§1 Scalar Fields

Definition 1.1 (Scalar Field). Let M be a smooth manifold, $f \in C^{(\infty)}(M)$ is called a *scalar field*.

The scalar field over a manifold, form an algebra.

§2 Vector Fields

Definition 2.1 (vector field). A *vector field* v over manifold M is a $C^{(\infty)}(M) \to C^{(\infty)}(M)$ map that satisfies

- (a) $\forall f, g \in C^{(\infty)}(M), \ \forall \lambda, \mu \in \mathbb{R}, \ v(\lambda f + \mu g) = \lambda v(f) + \mu v(g)$ (linearity).
- (b) $\forall f, g \in C^{(\infty)}(M), v(fg) = v(f)g + fv(g)$

Definition 2.2 (tangent vector). Let v be a vector field over M, p be a point on M. The tangent vector v_p at p is defined as a $C^{(\infty)}(M) \to C^{(\infty)}(M)$ map that satisfies

$$v_p(f) = v(f)(p). \tag{2-1}$$

The collection of tangent vectors at p is called the **tangent space** at p, denoted by T_pM .

The derivative of a path $\gamma \colon [0,1] \to M$ (or $\mathbb{R} \to M$) in a smooth manifold is defined as:

$$\gamma'(t) \colon C^{(\infty)}(M) \to \mathbb{R};$$

$$\gamma'(t)(f) = \frac{\mathrm{d}}{\mathrm{d}t} f \circ \gamma(t)$$
(2-2)

We can see that $\gamma'(t) \in T_{\gamma(t)}M$.

§3 Covariant and Contravariant

Definition 3.1 (pullback). Let f be a scalar field over $M, \varphi \in C^{(\infty)}(M, N)$. Then the **pullback** of f by φ is defined as

$$\varphi^* f = f \circ \varphi \in C^{(\infty)}(N). \tag{3-1}$$

Fields that are pullbacked are *covariant* fields.

Definition 3.2 (pushforward). Let v_p be a tangent vector of M at $p, \varphi \in C^{(\infty)}(M, N), q = \varphi(p)$. Then the **pushforward** of v_p by φ is defined as

$$(\varphi_* v)_q(f) = v_p(\varphi^* f). \tag{3-2}$$

Note that the pushforward of a vector field can only be obtained when φ is a diffeomorphism.

Fields that are pushforwarded are *contravariant* fields.

Mathematicians and physicists might have disagreement on whether a tangent vector is covariant or contravariant. This is because of that physicists might consider the coordinates (v^{μ}) of a tangent vector as a vector field, instead of linear combination of bases ∂_{μ} .

§4 Flows

Let a path γ : \mathbb{R} follows a vector field (a velocity field), that is

$$\gamma'(t) = v_{\gamma(t)},\tag{4-1}$$

then we call γ the *integral curve* through p := gamma(0) of the vector field v.

Definition 4.1. Suppose v is an integrable vector field. Let $\varphi_t(p)$ be the point at time t on the integral curve through p.

$$\varphi_t \colon M \to M$$
 (4-2)

is then called a flow generated by v.

$$\frac{\mathrm{d}}{\mathrm{d}t}\varphi_t(p) = v_{\varphi_t(p)}. \tag{4-3}$$

Chapter 3

Differential Forms

§5 1-forms

Definition 5.1 (1-form). A **1-form** $d\omega$ on M is a $\mathrm{Vect}(M) \to C^{(\infty)}(M)$ which satisfies that

(a)
$$\forall v, w \in \text{Vect}(M), \forall f, g \in C^{(\infty)}(M),$$

$$d\omega(fv + gw) = fd\omega(v) + gd\omega(w) \tag{5-1}$$

Symbol List

Here listed the important symbols used in these notes

 T_pM , 3

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