

# Lower Bounds for the Polynomial Calculus via the “Pigeon Dance”

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# Overview

We will present the result from A.A. Razborov, “Lower Bounds for the Polynomial Calculus”, in: Computational Complexity 7.4 (Dec. 2, 1998).

1 Introduction

2 The Pigeonhole Principle

3 The Pigeon Dance

4 Conclusion

# Background

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- Polynomial calculus is a strong proof system
- Provide a lower bound for it with the pigeonhole principle

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- Multiplication

$$\frac{f}{f \cdot x}$$

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- We construct polynomials such that their zeroes correspond to satisfying assignments
- Proving 1 from them is a *refutation*

## Example proof

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- Closest to  $xy + z$  we can prove is  $xy + y + z$

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- Similarly  $V_I, \Delta_I$  using subset of variables  $I$

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## Definition ( $\neg\mathcal{PHP}_n^m$ )

$$Q_i := 1 - \sum_{j \in [n]} x_{ij} \quad \text{for each } i \in [m]$$

$$Q_{i_1, i_2, j} := x_{i_1 j} x_{i_2 j} \quad \text{for each } i_1 \neq i_2 \in [m], j \in [n]$$



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- Proofs combine them into more complex ones
- Can only derive local constraints with small degrees
- Pigeons can fly away to escape local contradictions

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- Locally valid assignments are injections  $I \hookrightarrow [n]$
- Corresponding variable assignments are  $M_I$

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- Only works if whether  $t \in \Delta_I$  is independent of  $I \supseteq \text{dom}(t)$

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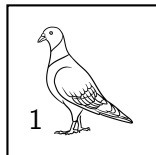
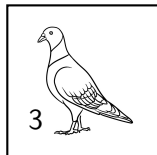
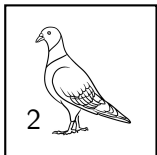
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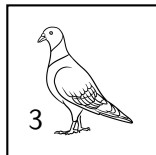
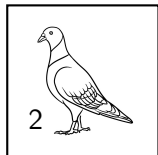
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- Repeat until all pigeons have moved once
- If a pigeon cannot find an empty hole, the dance is aborted

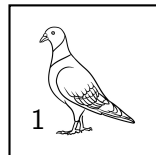
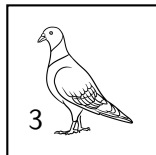
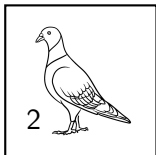
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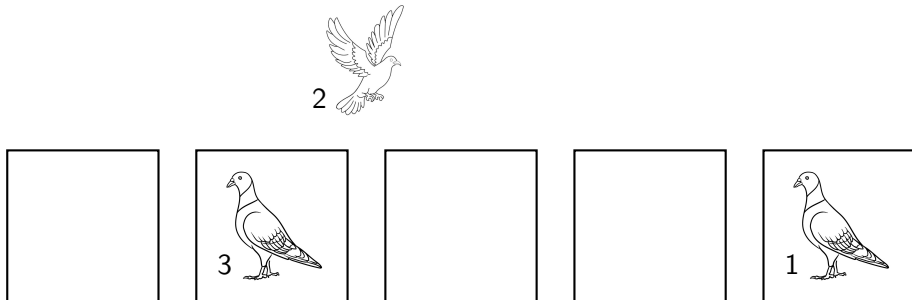


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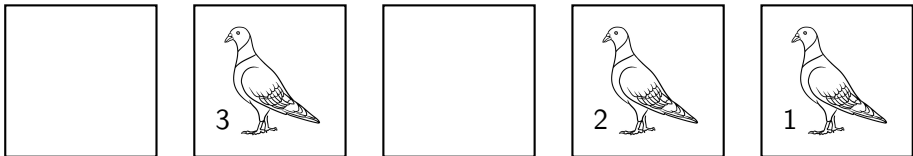




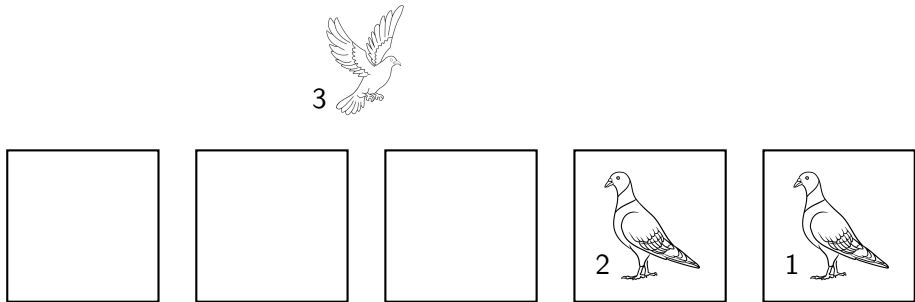
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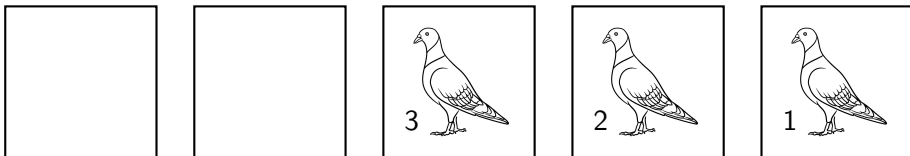
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- $\Delta_I$  is the set of terms that let pigeons complete the dance
- Whether  $t \in \Delta_I$  is independent of  $I$  since pigeons not in the dance do not affect it



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- Kill the first pigeon and moves its hole to the left
- $\text{Kill}(x_{i_1 j_1} \cdots x_{i_d, j_d}) = x_{i_2 j'_2} \cdots x_{i_d j'_d}$  with

$$j'_k := \begin{cases} j_k + 1, & \text{if } j_k < j_1 \\ j_k, & \text{if } j_k > j_1. \end{cases}$$

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## Theorem

$x_{i_1 j_1} \cdots x_{i_d j_d} \in \Delta_I$  if and only if there is a  $j' > j_1$  such that  $\text{Kill}(x_{i_1 j'} \cdots x_{i_d j_d}) \in \Delta_I$ .

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## Proof sketch

$\text{Kill}(x_{i_1 j'} \cdots x_{i_d j_d})$  effectively moves the first pigeon to an empty hole to its right and then kills it. This is the same as each step in the dance, where the first pigeon flies to some free hole to its right and then occupies it.  $\square$

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If  $t \in \Delta_I$  then the pigeons can complete their dance. During this the first pigeon will start at  $j$  and fly to  $j'$ . Killing the pigeon frees up  $j'$  so any other pigeon that wanted to use  $j$  can use it instead. □

# The lower bound

## Theorem

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At most

$$|\text{dom}(t)| \leq |I \setminus \{i\}| \leq \frac{n-1}{2}$$

pigeons involved in the dance, each occupying two holes. Place pigeon at unused hole and kill it there. The remaining pigeons can complete the dance since the moved hole was not used. □

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- Pick a  $j$  such that  $\text{Kill}(x_{ij}t) \in \Delta_I$
- Extend assignment to  $I$  with  $a(f) \neq 0$

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- This works since  $\Delta_I$  is linearly independent over  $M_I$