

Chapter 1: Tour of Cypress Bluetooth

After completing Chapter 1 (this chapter) you will understand a top-level view of the ModusToolbox Bluetooth ecosystem components, including the chips, modules, software, documentation, support infrastructure and development kits. You will have ModusToolbox installed and working on your computer and understand how to program an existing project into a kit.

1.1	TOUR OF MODUSTOOLBOX	2
1.1.1	MAKE/ BUILD INFRASTRUCTURE	2
1.2	PROXY SETTINGS	3
1.3	TOUR OF MODUSTOOLBOX IDE	7
1.3.1	FIRST LOOK	7
1.3.2	CUSTOMIZATION	9
1.3.3	BLUETOOTH SDK ARCHITECTURE.....	10
1.3.4	NEW APPLICATION WIZARD	12
1.3.5	QUICK PANEL	15
1.3.6	APPLICATIONS	16
1.3.7	DEVICE CONFIGURATION.....	20
1.3.8	LIBRARY MANAGER	21
1.3.9	RENAMING / COPYING PROJECTS	22
1.3.10	SHARING APPLICATIONS.....	23
1.4	COMMAND LINE INTERFACE (CLI)	28
1.4.1	MODUS SHELL	28
1.4.2	DOWNLOADING AN APPLICATION	29
1.4.3	MODUS CLI COMMANDS	30
1.5	TOUR OF DOCUMENTATION.....	31
1.5.1	IN MODUSTOOLBOX IDE.....	31
1.5.2	ON THE WEB.....	33
1.6	REPORTING ISSUES.....	35
1.7	TOUR OF BLUETOOTH.....	36
1.7.1	THE BLUETOOTH SPECIAL INTEREST GROUP (SIG)	36
1.7.2	CLASSIC BLUETOOTH	37
1.7.3	BLUETOOTH LOW ENERGY	38
1.7.4	BLUETOOTH HISTORY	38
1.8	TOUR OF CHIPS	39
1.9	TOUR OF PARTNERS.....	40
1.10	TOUR OF DEVELOPMENT KITS.....	41
1.10.1	CYPRESS CYW920819EVB-02	41
1.10.2	CYPRESS CYBT-213043-MESH	41
1.10.3	CYPRESS CYW920706WCDEVAL	41
1.10.4	CYPRESS CYW920719Q40EVB-01	41
1.11	EXERCISE(S)	42
	EXERCISE - 1.1 CREATE A FORUM ACCOUNT.....	42
	EXERCISE - 1.2 START MODUSTOOLBOX IDE, AND EXPLORE THE DOCUMENTATION	42
	EXERCISE - 1.3 PROGRAM A SIMPLE APPLICATION	43

1.1 Tour of ModusToolbox

ModusToolbox is a set of tools that allow you to develop, program, and debug applications for Cypress MCUs. ModusToolbox IDE is an Eclipse-based development environment that is included as part of the ModusToolbox software installer, but it is not the only supported environment. There is a command line interface (CLI) that can be used interchangeably with IDE applications. In addition, users can use ModusToolbox software with their own preferred IDE, such as Visual Studio Code or IAR.

For this class, we will focus on the ModusToolbox IDE with a little information on using the CLI.

For Windows, ModusToolbox software is installed, by default, in *C:/Users/<UserName>/ModusToolbox*. Once installed, the IDE will show up in Windows under *Start->All Programs->ModusToolbox 2.0*.

If you install ModusToolbox in a non-default location, you will need to set the *CY_TOOLS_PATHS* environment variable for your system to point to the *ModusToolbox/tools_2.0* folder or set that variable in each Makefile.

1.1.1 Make/ Build Infrastructure

ModusToolbox uses a GNU "make" based system to create, build, program, and debug projects. The installation provides a set of tools required for all the operations to work. Those tools include:

- Gnu Make 3.81 or newer
- Git 2.20 or newer
- Python3
- GCC
- OpenOCD with supports for Cypress devices
- Configurator tools
- Library manager
- New project GUI and CLI utilities
- ModusShell
- ModusToolbox IDE

These tools can be found in the ModusToolbox installation folder under *tools_<version>* except for ModusToolbox IDE which is under *ide_<version>*.

The general application development flow is as follows. All these steps can be done using an IDE or on the command line. You can even switch back and forth seamlessly between the two.

- Clone the *wiced_bt_sdk* (this is a shared library for all Bluetooth applications in a workspace – more on this later)
- Clone the application (either from a GitHub code example or a local set of files)
- Get the libraries required by the application
- Configure the device and its peripherals using configurators
- Write the application code
- Build/Program/Debug

1.2 Proxy Settings

When creating applications from inside a Cypress internal network, some proxy settings are necessary due to our security settings. This behavior will be improved in the future. The steps (for now) are:

1. Find the proxy host name and port number for your site. There is a list at:

<https://itsm.cypress.com/solutions/726105.portal>

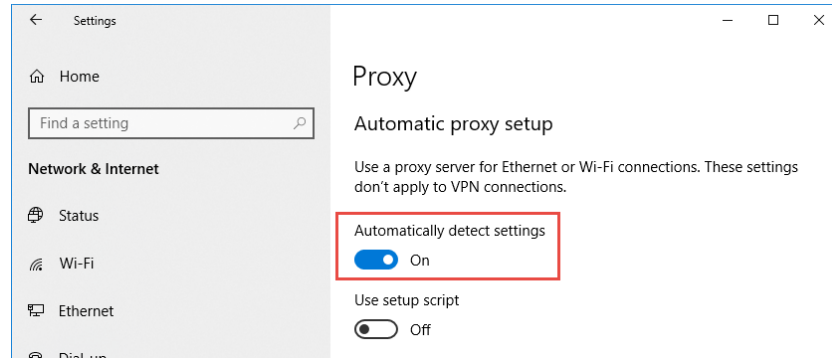
As of the writing of this manual, the list is:

Site	Proxy Server (FQDN)	IP Address	Port
Japan	jpkwswwp03.cysemi.com	10.128.174.5	74
	jpkwswwp04.cysemi.com	10.128.174.6	74
Thailand	thbkkwwp01.cysemi.com	10.249.155.66	74
	thbkkwwp02.cysemi.com	10.249.155.67	74
Frankfurt	dceuwwp03.cysemi.com	10.244.7.219	74
	dceuwwp04.cysemi.com	10.244.63.131	74
Munich	eumunwwp02.cysemi.com	10.244.63.130	74
Malaysia	pngwwp01.cysemi.com	10.249.20.2	74
	pngwwp02.cysemi.com	10.249.20.3	74
Taiwan	tpewwp01.cysemi.com	10.240.112.66(Taipei)	74
	tpewwp01.cysemi.com	10.240.128.66(Hsinchu)	74
Israel	isr-mwg01.cysemi.com	10.168.251.60	74
	isr-mwg02.cysemi.com	10.168.251.61	74
Austin	corp-webw105.cysemi.com	10.248.251.78	74
	corp-webw106.cysemi.com	10.248.251.79	74
Korea	seowwp01.cysemi.com	10.240.64.58	74
San Jose	csj-mwg01.cysemi.com	10.198.170.5	74
	csj-mwg02.cysemi.com	10.198.170.6	74
KYCC	kycc-mwg01.cysemi.com	10.198.32.58	74
WADC	cywa-mwg01.cysemi.com	10.198.0.18	74
CCOS	ccos-wg.cysemi.com	192.168.75.12	74
INDC	indc-mwg01.cysemi.com	10.249.64.19	74
	indc-mwg02.cysemi.com	10.249.64.19	74
CHDC	chdc-mwg01.cysemi.com	10.240.160.18	74
	chdc-mwg02.cysemi.com	10.240.160.19	74
CML	cml-wg01.cysemi.com	10.249.224.231	74
	cml-wg02.cysemi.com	10.249.224.232	74
UKR	ukr-mwg01.cysemi.com	172.23.194.115	74
	ukr-mwg02.cysemi.com	172.23.194.116	74
Coresite	dmz-webw101.cypress.com	10.247.88.203	74
	dmz-webw102.cypress.com	10.247.88.204	74
MSK	jpmskwwp01.cysemi.com	10.128.207.66	74
	jpmskwwp02.cysemi.com	10.128.207.67	74
ORDC	bigbro.cysemi.com	172.23.172.33	74

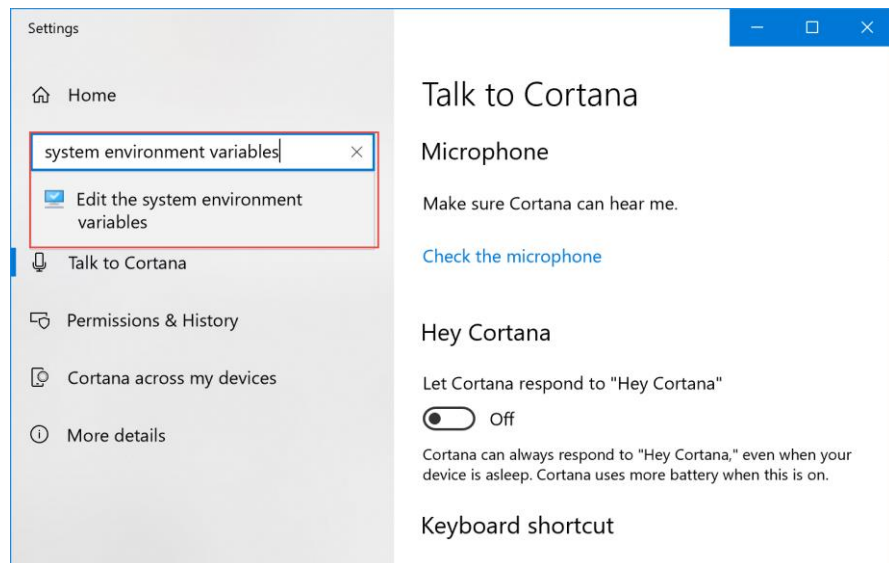
2. Make OS specific proxy and variable updates:

a. Windows:

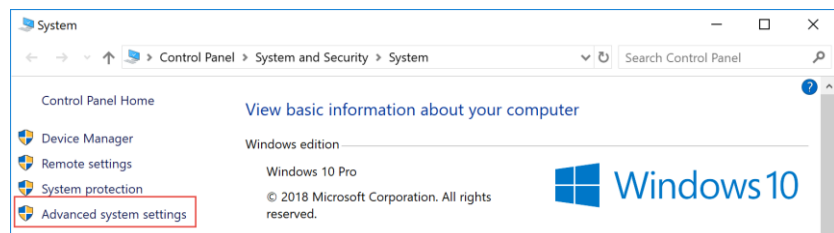
- i. Set the Windows proxy settings (Settings > Network & Internet > Proxy) to "Automatically Detect Settings"

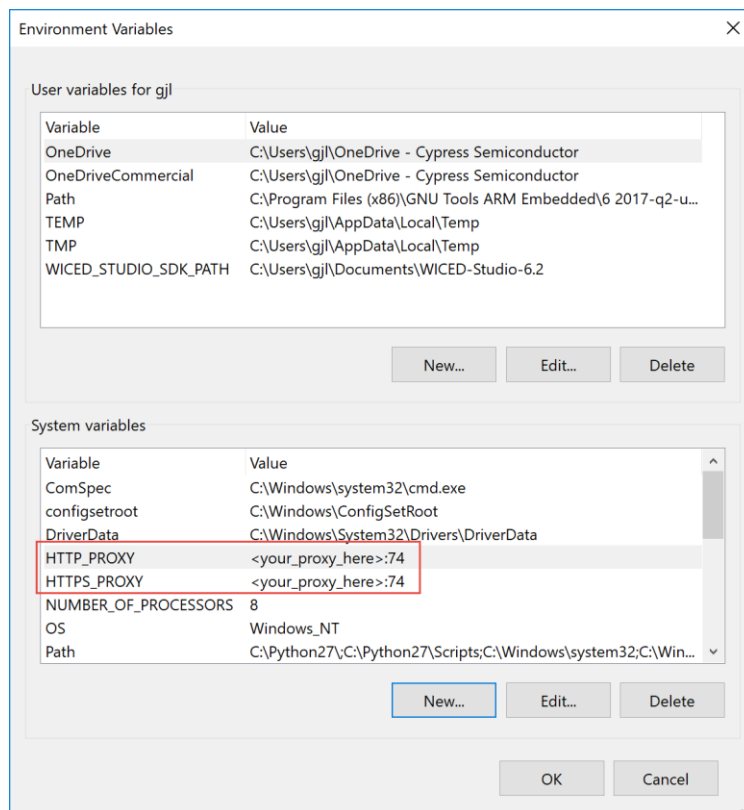
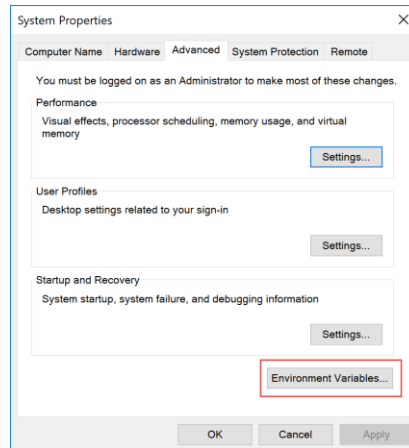


- ii. Create two Windows System variables with the proxy name and port number.
 1. Method 1: Open Settings > Search for "system environment variables" > Select "Edit the system environment variables" > Click "Environment Variables..."



2. Method 2: From a File Explorer window, Right click on "This Computer" or "My PC" and select "Properties" > Click Advanced System Settings > Click Environment Variables...





b. MacOS:

- i. Set "System Preferences > Network > Advanced > Proxies > Auto Proxy Discovery"
- ii. Open a terminal and check if the variables (http_proxy, https_proxy) are set in the terminal.

```
$ export | grep proxy
declare -x http_proxy="bigbro.ore.cypress.com:74/"
declare -x https_proxy="bigbro.ore.cypress.com:74/"
```

c. Linux:

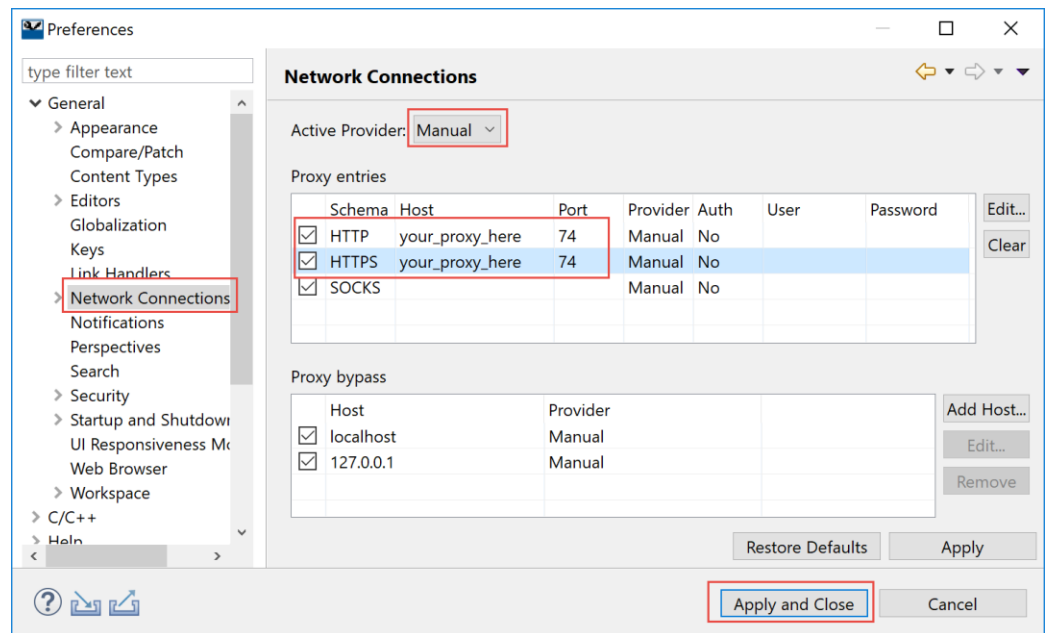
- i. Set the "Network Proxy" to "Manual"
- ii. Open a terminal and check if the variables are set in the terminal.

```
$ export | grep proxy
declare -x http_proxy="bigbro.ore.cypress.com:74/"
declare -x https_proxy="bigbro.ore.cypress.com:74/"
```

- iii. Setup CA Certification ([Development environment#SetupCypressCACertificates](#))

3. Start the ModusToolbox IDE

- a. Open menu item "Window > Preferences > General > Network Connections"
 - i. Set "Active Provider" to "Manual" and set HTTP and HTTPS to the correct proxy host and port for your location.

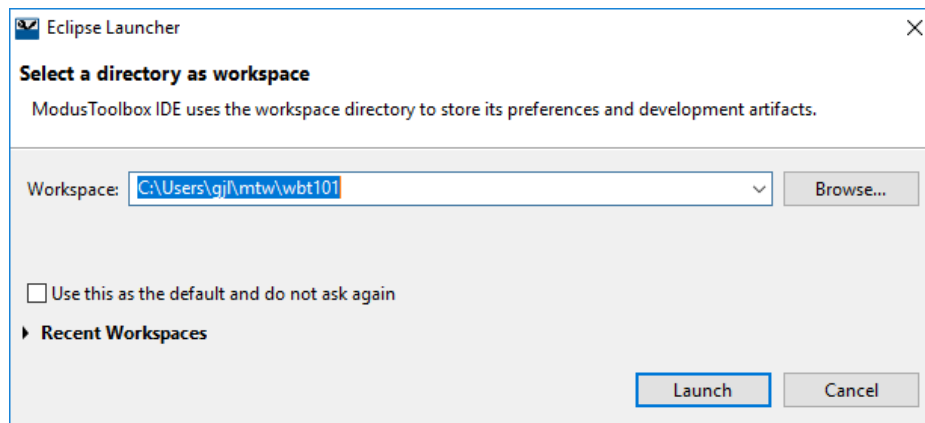


1.3 Tour of ModusToolbox IDE

1.3.1 First Look

When you first run the ModusToolbox IDE, you will create a Workspace to hold your applications. The default Workspace location is `C:/Users/<UserName>/mtw`, but you can have as many Workspaces as you want, and you can put them anywhere you want. I usually put each workspace under a folder inside `C:/Users/<UserName>/mtw` such as `wbt101` for exercise for this class.

Each time you open ModusToolbox IDE you will need to provide a workspace name such as the following:



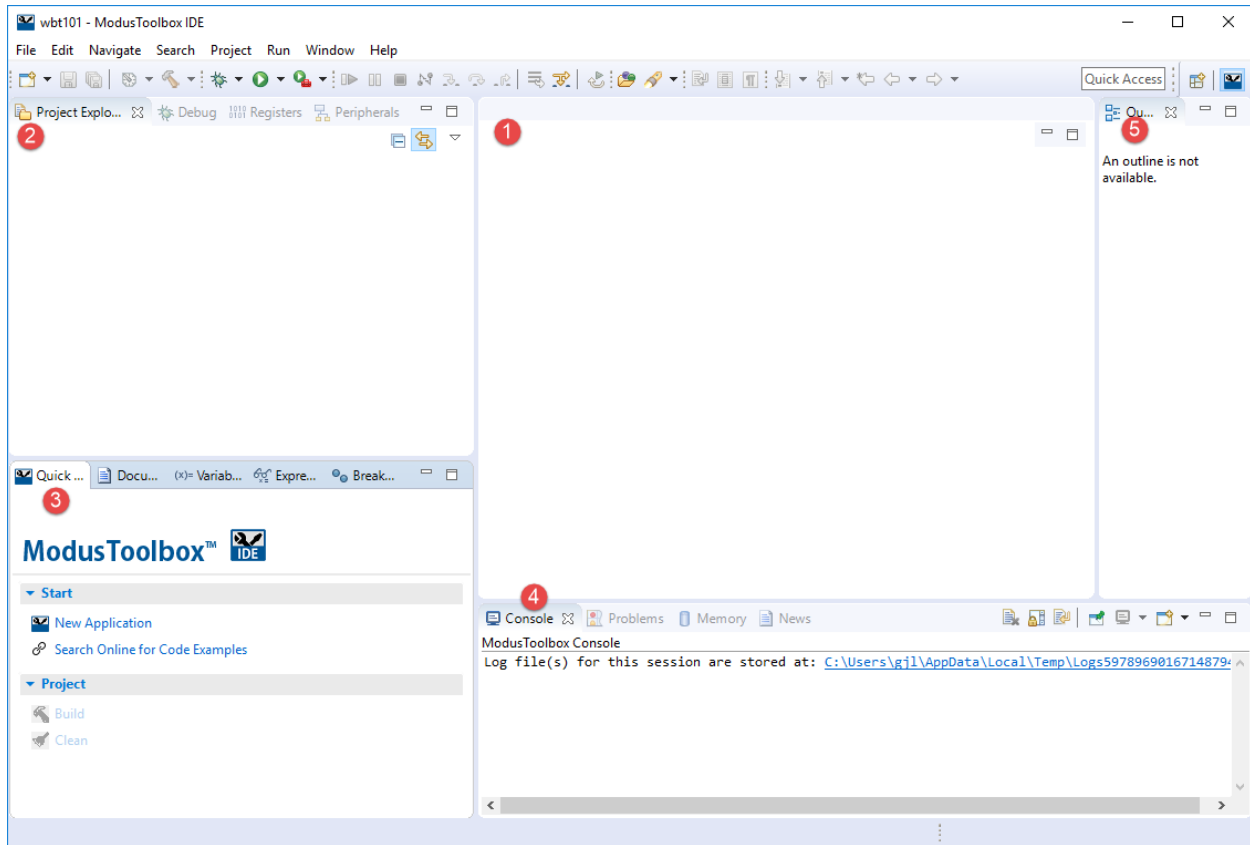
Whenever you want to switch to a different Workspace or create a new one, just use the menu item *File->Switch Workspace* and either select one from the list or select *Other...* to specify the name of an existing or new Workspace.

After clicking Launch, the IDE will start, and you will see the (empty) ModusToolbox perspective.

A perspective in Eclipse is a collection of views. The ModusToolbox perspective combines editing and debugging features. You can also create your own custom perspectives if you want a different set or arrangement of windows.

You can always get back to the ModusToolbox perspective by selecting it from the button in the upper right corner of the IDE, clicking the Open Perspective button and choosing ModusToolbox, or from *Window->Perspective->Open Perspective->Other->ModusToolbox*.

If you unintentionally change something in the perspective and want to reset to the default, you can use *Window->Perspective->Reset Perspective*.



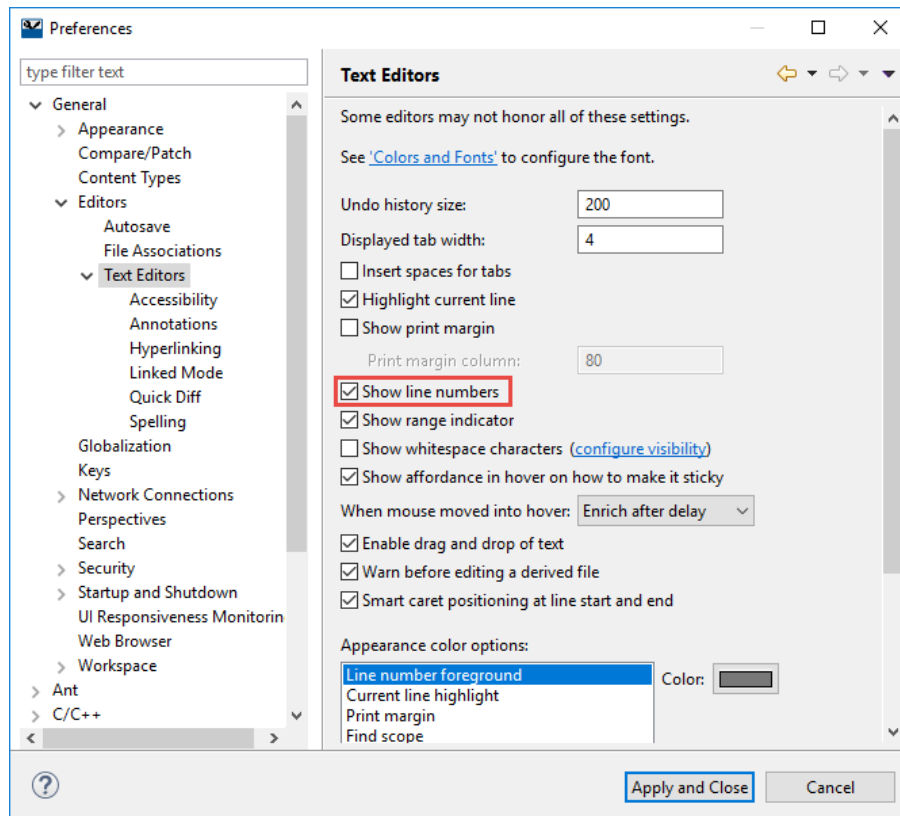
The major views are:

1. File Viewer/Editor
2. Project Explorer
3. Quick Panel
4. Console / Problems
5. Outline

If you close a view unintentionally, you can reopen it from the menu *Window->Show View*. Some of the views are under *Window->Show View->Other...* You can drag and drop windows and resize them as you desire.

1.3.2 Customization

Eclipse is extremely flexible – you can customize almost anything if you know where to look. A good place to start for general Eclipse settings is *Window->Preferences*. One that I always turn on is *General->Editors->Text Editors->Show line numbers*. Most of these settings are at the workspace level.



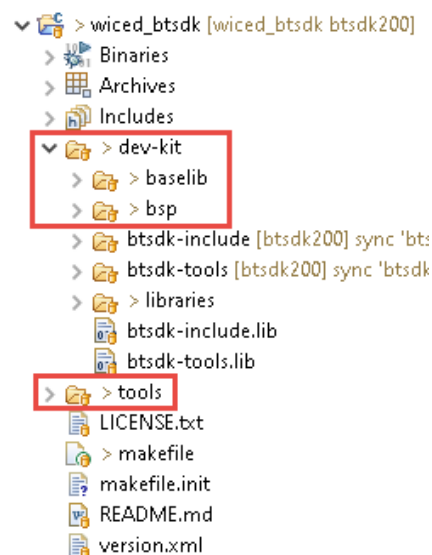
There are also project build settings which we will explore later.

1.3.3 Bluetooth SDK Architecture

The Bluetooth SDK is downloaded from GitHub just like the other project dependencies. In the case of the SDK, it is contained in a separate Eclipse project called `wiced_btstack`. This project referenced by all the applications in your workspace. That is, the `wiced_btstack` is shared among all applications in a single workspace.

The best practice is to create the `wiced_btstack` project first, but in future versions of the IDE and CLI the project will be created automatically for you if it isn't found. It doesn't matter which hardware you select for the `wiced_sdk` project – one copy will work for all boards – but the name must NOT be changed.

The SDK contains the base libraries for all the supported devices (`wiced_btstack/dev-kit/baselib`), board support packages (BSPs) for all of the supported boards (`wiced_btstack/dev-kit/bsp`), and Bluetooth tools such as ClientControl and BTSPy which you will use in later chapters (`wiced_btstack/tools`).



Since the SDK is shared among all applications in a workspace, any changes to files contained in the SDK will affect all applications in that workspace. This is especially important for the BSP since it contains the device configurator files.

Therefore, if you want to use the device configurator to change settings for an application without affecting other applications, you can do one of three things: (1) override the device configurator files for a single application; (2) create a custom BSP inside the `wiced_btstack`; or (3) create a new workspace with a new copy of the `wiced_btstack` that you can modify. The first is good when a single application requires a different configuration while 2 and 3 are better if you want a single custom configuration for multiple applications.

The steps to override the device configurator files for a single application are:

1. Copy the `wiced_btstack/dev-kit/bsp/TARGET_<bsp_name>/COMPONENT_bsp_design_modus` folder and its contents to the application's project folder (the folder with the top-level source code). Change the name to something unique that still starts with `COMPONENT_`. For example:

`COMPONENT_my_design_modus`

2. Disable the configurator files from the BSP and include your custom configurator files by adding the following to the makefile (the makefile already has a blank line that says `COMPONENTS +=` so you can add your component name to that line). Replace "my_design_modus" with whatever name you used for the folder (excluding `COMPONENTS_`).

```
COMPONENTS += my_design_modus
DISABLE_COMPONENTS += bsp_design_modus
```

3. Make sure your project is selected and open the device configurator from the Quick Panel. Make the required changes and save/exit the configurator.

The steps to create a custom BSP are:

1. Copy an existing BSP and paste it with a new name in the same folder, which is `wiced_btstack/dev-kit/bsp`.
2. Edit the makefile for the application to include the new BSP in the `TARGET`, `SUPPORTED_TARGETS`, and `TARGET_DEVICE_MAP` variables.
3. Make sure your project is selected and open the device configurator from the Quick Panel. Make the required changes and save/exit the configurator.



1.3.4 New Application Wizard

ModusToolbox IDE includes a wizard that sets up new applications with the required target hardware support, Bluetooth configuration code, middleware libraries, build, program and debug settings, and a "starter" application. Launch the wizard from the "New Application" button in the Quick Panel or use "New ModusToolbox Application" item in *the File->New menu*.

When you create a new application, the appropriate files for the application and its libraries are cloned from GitHub (you can use local application files as you will see later, but even in that case the libraries are pulled from a repository). This means that you can always get the latest version of a code example or library (or you can get older versions if you prefer). The downside is that you need an internet connection when creating an application.

There is a super-manifest file that contains a list of manifest files. The manifest files in turn, list the locations/versions of repos where the tools should search for applications and libraries. The default super-manifest and manifest files allow the tool to find all the SDK libraries, middleware libraries, code examples, and board support packages that are supported by Cypress. Both the super-manifest and manifest are XML files.

The default super-manifest can be found on GitHub in this repo:

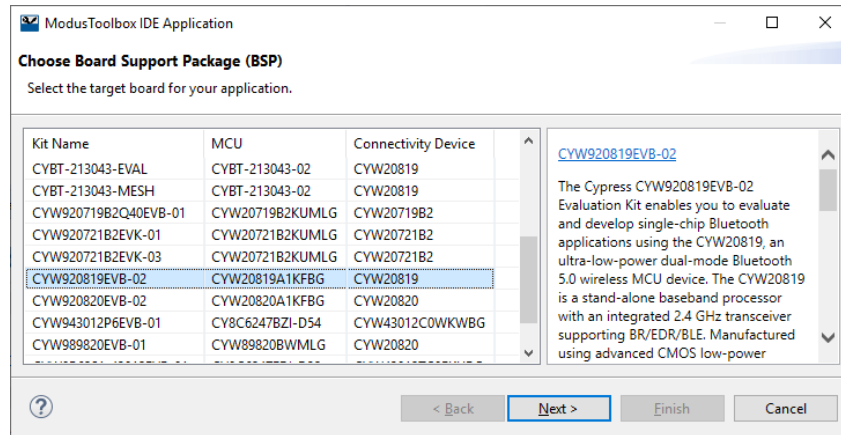
<https://github.com/cypresssemiconductorco/mtb-super-manifest>

View that file to see the location, contents, and format of the default manifest files.

If you want to include your own repos in the search path (e.g. to create/share your own BSPs, libraries, projects, etc.), you can create a file in `~/.modustoolbox/manifest.loc` that lists your own super-manifest file(s). Your super-manifest files can then point to your own manifest file(s). The paths in your `manifest.loc`, super-manifest and manifest(s) must point to an HTTP URL (which can, for example, be a GitHub repo or file). Eventually, it will be possible to specify a local file (e.g. [Error! Hyperlink reference not valid.](#)) as well as an HTTP path.

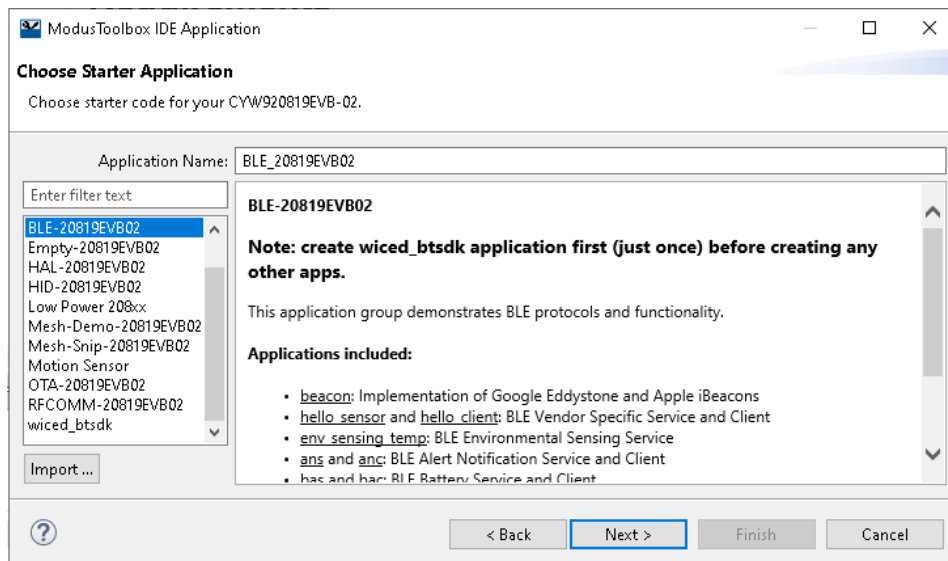
Board Support Package

First you must choose the "Board Support Package (BSP)". Note that it is possible for users to create custom Bluetooth SoC board support packages (BSPs) but that is beyond the scope of this course. The kits used in this course are the [CYBT-213043-MESH](#) and [CYW920819EVB-02](#).



Starter Application

Clicking "Next" lets you choose a starter application from a list of applications that support the selected hardware. You always begin with a starter application. These range in complexity from mostly empty to fully functional demos. For this class we will provide you with template starter applications for many of the exercises. You will access these using the "Import..." button in new application wizard.

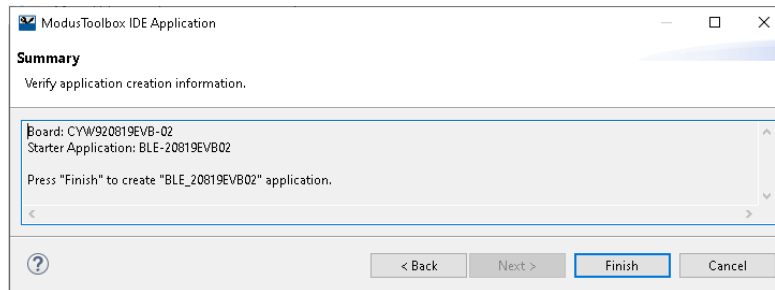


There is no real equivalent to the PSoC Creator empty project, but there is an Empty application that gives you just enough to get started. Unlike the PSoC Creator empty project, using this as a starting point is more of an expert-level approach since it doesn't provide much in the way of code. In most cases, we recommend starting with one of the code examples and modifying it as needed for your application.

Each starter application or set of applications includes a description and a default name, which you can modify if you wish (if you create multiple copies of the same template without changing the name the tool adds an incrementing number to each created project name).

Pressing "Next" takes you to the final step, where you verify your choices and press "Finish" to create the application.

The wizard does not prompt for a directory. ModusToolbox IDE uses Eclipse workspaces as containers for projects. All projects within a workspace reside at the top level of the workspace folder. You can choose any legal folder/file name for the project, but you cannot change its location on disk.



Once the application has been created, if you don't see all of the expected files, right click on the project name in the Workspace explorer and choose "Refresh".

Application Sets

Most starter applications are actually a "set" of applications instead of an individual application. For example, the BLE_20819EVB02 starter application contains 12 different BLE applications that are all created when you use that set as the starter application. For that reason, the name you provide is used as the prefix of the applications for that set. For example, BLE_20819EVB02 will give you projects called:

```
BLE_20819EVB02.anc
BLE_20819EVB02.ans
BLE_20819EVB02.bac
BLE_20819EVB02.bas
BLE_20819EVB02.beacon
...
```

On disk, this is done using hierarchy. For the example described above, the directory structure is:

```
BLE_20819EVB02/ble/anc/<application_files>
BLE_20819EVB02/ble/ans/<application_files>
BLE_20819EVB02/ble/bac/<application_files>
BLE_20819EVB02/ble/bas/<application_files>
BLE_20819EVB02/ble/beacon/<application_files>
...
```

The lowest level of the hierarchy is where the individual applications are stored. Got to that directory if you want to use the command line interface. Note that the middle level of the directory hierarchy (ble in this example) is not used in the Eclipse application name.

For the exercises in this class, we will use single application templates, so we will not include the extra hierarchy. In that case, the makefile is modified slightly from the starter applications – more on that later.

1.3.5 Quick Panel

Once you have created a new application the Quick Panel is populated with common commands so that you don't have to hunt for them. There are top level commands, application level commands, links to configurators, and links to launches (for program and debug). There is also a section with links to documentation.

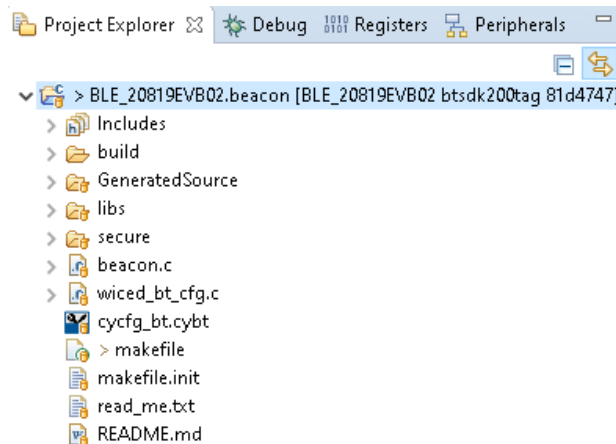
ModusToolbox™ IDE Quick Panel	Equivalent Menu Path
Start New Application	File -> New -> New ModusToolbox IDE Application
Search Online for Code Examples BLE_20819EV02.beacon Build BLE_20819EV02.beacon Application Clean BLE_20819EV02.beacon Application	Select application project in Project Explorer, then Project -> Build
Launches BLE_20819EV02.beacon Attach_JLink BLE_20819EV02.beacon Attach_KitProg3 BLE_20819EV02.beacon Program	Run->External Tools -> External Tools Configurations -> Program -> <appname>
Tools Library Manager Bluetooth Configurator (new configuration) Device Configurator (new configuration) Power Estimator	Double click *.cybt in the application project Double click design.modus in the BSP
Documentation WICED Bluetooth SDK Documentation	Help -> ModusToolbox General Documentation Help -> ModusToolbox IDE Documentation

1.3.6 Applications

At this point, we are ready to start developing the application. As mentioned before, a WICED Bluetooth application is the application project and the wiced_btsdk project. We looked briefly at wiced_btsdk earlier, so let's look at the application project now.

Project Explorer

In the project explorer window, you will see your application project and all its associated files.



The key parts of a project are:

- A folder with the name of the project
- Readme files (read_me.txt and/or README.md)
- Application configurator files (e.g. cycfg_bt.cybt for Bluetooth)
- A GeneratedSource folder with the output files from the application level configurators
- A libs folder
- makefile
- Stack configuration files (e.g. wiced_bt_cfg.c or app_bt_cfg.c)
- Application C source files

Readme

The first file to open in the file editor window will be the readme file included with the application, if there is one. This gives general information about the platform or the application that you started with.

Application Configurator Files

Files for configurators are distinguished by their file extension. For example, any file that ends with .cybt is a Bluetooth configurator file.

GeneratedSource Folder

When you save from a configurator, the tool generates firmware in the GeneratedSource folder. The following are the most interesting/useful files (e.g. cycfg_gatt_db.c and cycfg_gatt_db.h for BLE).



Remember that the Device Configuration files (generated from design.modus) go in the BSP so they will NOT be in the GeneratedSource folder in the application.

libs

For Bluetooth starter applications, this folder just contains a file named index.html. It is used to populate the links in the Documents tab in the quick panel.

makefile

The makefile is used in the application creation process – it defines everything that ModusToolbox needs to know to create/build/program the application. This file is interchangeable between ModusToolbox IDE and the Command Line Interface so once you create an application, you can go back and forth between the IDE and CLI at will.

Various build settings can be set in the makefile by the user to change the build system behavior. These can be "make" settings or they can be settings that are passed to the compiler. Some examples are:

- Target Device (`TARGET=CYW920819EVB-02`)
- Relative path to the wiced_btsdk (`CY_SHARED_PATH=$(CY_APP_PATH)/../../wiced_btsdk`)
- Method to generate the Bluetooth Device Address (`BT_DEVICE_ADDRESS?=default`)
- Enable OTA Firmware Upgrade (`OTA_FW_UPGRADE?=1`)
- Compiler Setting to Enabling Debug Trace Printing (`CY_APP_DEFINES+= -DWICED_BT_TRACE_ENABLE`)

You will get to experiment with some of these settings in later chapters.

In particular note the `../../` in the `CY_SHARED_PATH`. That accounts for the hierarchy in the Bluetooth starter applications. In the templates we use in later chapters, the hierarchy will be removed so that will be changed to just `../`

Stack Configuration Files

Many of the templates you will use in this class include `app_bt_cfg.c` and `app_bt_cfg.h`, which create static definitions of the stack configuration and buffer pools. You will edit the stack configuration, for example, to optimize the scanning and advertising parameters. The buffer pools determine the availability of various sizes of memory blocks for the stack, and you might edit those to optimize performance and RAM usage.

Note: The actual file names may vary in some code examples, but the definitions of the `wiced_bt_cfg_settings` struct and `wiced_bt_cfg_buf_pools` array are required.

Application C file

All starter applications include at least one C source file that starts up the application (from the `application_start()` function) and then implements other application functionality. The actual name of this file varies according to the starter application used to create the application. It is usually the same name as the template but there are exceptions to that rule. For example, in the templates provided for this class this top-level file is always called `app.c`.

Note: MESH examples are implemented with a library called `mesh_app_lib`. The library includes the `application_start()` function in `mesh_application.c` inside the library. This is because the application itself is very regimented, and the developer does not really "own" the way devices interact. The user part of the application is restricted to activity supported by the device's capabilities, such as dimming the light with a PWM or controlling a door lock solenoid.

The application C file begins with various `#include` lines depending on the resources used in your application. These header files can be found in the SDK under `wiced_btsdk/dev-kit/baselib/20819A1/include`. A few examples are shown below. The first 4 are usually required in any project. The "hal" includes are only needed if the specific peripheral are used in the project, e.g. `wiced_hal_i2c.h` is required if you are using I2C.

```
#include "wiced.h"                // Basic formats like stdint, wiced_result_t, WICED_FALSE, WICED_TRUE
#include "wiced_platform.h"        // Platform file for the kit
#include "sparcommon.h"            // Common application definitions
#include "wiced_bt_stack.h"        // Bluetooth Stack
#include "wiced_bt_dev.h"          // Bluetooth Management
#include "wiced_bt_ble.h"          // BLE
#include "wiced_bt_gatt.h"         // BLE GATT database
#include "wiced_bt_uuid.h"         // BLE standard UUIDs
#include "wiced_rtos.h"            // RTOS
#include "wiced_bt_app_common.h"   // Miscellaneous helper functions including wiced_bt_app_init
#include "wiced_transport.h"       // HCI UART drivers
#include "wiced_bt_trace.h"        // Trace message utilities
#include "wiced_timer.h"           // Built-in timer drivers
#include "wiced_hal_i2c.h"         // I2C drivers
#include "wiced_hal_adc.h"         // ADC drivers
#include "wiced_hal_pwm.h"         // PWM drivers
#include "wiced_hal_puart.h"       // PUART drivers
#include "wiced_rtos.h"            // RTOS functions
#include "wiced_hal_nvrाम.h"       // NVRAM drivers
#include "wiced_hal_wdog.h"        // Watchdog
#include "wiced_spar_utils.h"      // Required for stdio functions such as snprintf and sprintf
#include <stdio.h>                  // Stdio C functions such as snprintf and sprintf
```

After the includes list you will find the `application_start()` function, which is the main entry point into the application. That function typically does a minimal amount of initialization, starts the Bluetooth stack and registers a stack callback function by calling `wiced_bt_stack_init()`. Note that the configuration parameters from `app_bt_cfg.c` are provided to the stack here. The callback function is called by the stack whenever it has an event that the user's application might need to know about. It typically controls the rest of the application based on Bluetooth events.

Most application initialization is done once the Bluetooth stack has been enabled. That event is called `BTM_ENABLED_EVT` in the callback function. The full list of events from the Bluetooth stack can be found in the file `wiced_btsdk/dev-kit/baselib/20819A1/include/wiced_bt_dev.h`.

A minimal C file for an application will look something like this:

```
#include "sparcommon.h"
#include "wiced_platform.h"
#include "wiced_bt_dev.h"
#include "wiced_bt_stack.h"
#include "app_bt_cfg.h"

wiced_bt_dev_status_t app_bt_management_callback( wiced_bt_management_evt_t event,
wiced_bt_management_evt_data_t *p_event_data );

void application_start(void)
{
    wiced_bt_stack_init( app_bt_management_callback, &wiced_bt_cfg_settings,
                        wiced_bt_cfg_buf_pools );
}

wiced_result_t app_bt_management_callback( wiced_bt_management_evt_t event,
wiced_bt_management_evt_data_t *p_event_data )
{
    wiced_result_t status = WICED_BT_SUCCESS;

    switch( event )
    {
        case BTM_ENABLED_EVT:                // Bluetooth Controller and Host Stack Enabled

            if( WICED_BT_SUCCESS == p_event_data->enabled.status )
            {
                /* Initialize and start your application here once the BT stack is running */
            }
            break;

        default:
            break;
    }

    return status;
}
```

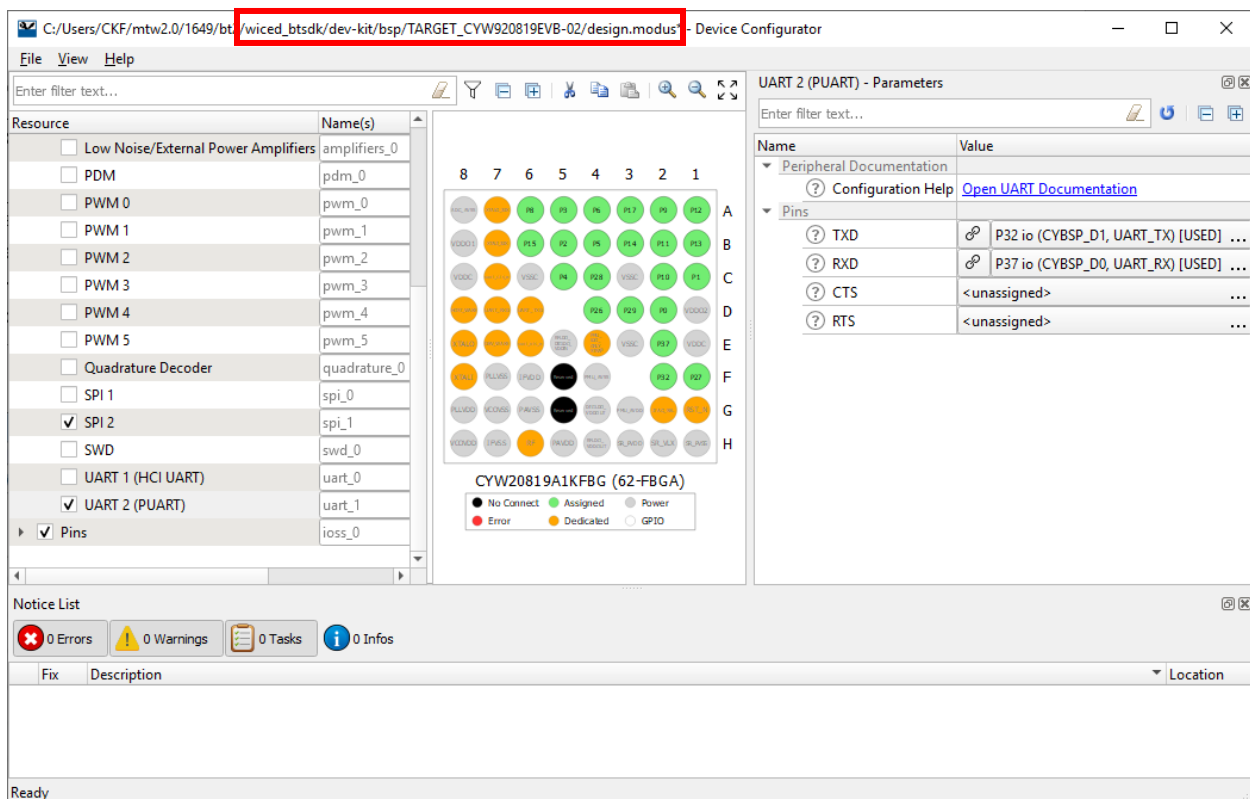
1.3.7 Device Configuration

The design.modus file is the database of configuration choices for the device. It is the source document for the Device Configurator tool which presents a list of pins and peripherals on the device that you can set up. As mentioned earlier, the design.modus file is shared by all applications in a workspace that use a given BSP. Keep that in mind if you chose to edit the design.modus file.

As described earlier, you can override the design.modus for a single application. You will use this method in the exercises in the next chapter.

To launch the Device Configurator click on the link in the Quick Panel or double-click on the design.modus file either in the BSP (wiced_btSDK/dev-kit/bsp/<BSP Name>) or in your application if you are using the override method. As you can see there are sections for Peripherals and Pins on the left. When you enable a peripheral or pin, the upper right-hand panel allows you to select configuration options and to open the documentation for that element. In some cases, you can launch a secondary configurator from that window (Bluetooth is one of those cases).

It is a good idea to look at the path at the top of the configurator window to verify you are editing the file from the expected location (either in the BSP or in the application).



Once you save the configurator information (*File->Save*) it creates/updates the Generated Source files in the project BSP or the local copy if you are using the override method.

1.3.8 Library Manager

There is a Library Manager that is intended to add/remove individual libraries from an application. However, for BT applications, the libraries are all currently shared (from wiced_btSDK) so the library manager isn't very useful (at least not yet).

Instead, the way to add a new library to an application is as follows (you will get to try this out in later chapters):

1. Add the appropriate include in your source code.
2. Add the library name to the COMPONENTS variable in the makefile.
3. Add the path to the library to the SEARCH_LIBS_AND_INCLUDES variable in the makefile.

For example, to add the over-the-air (OTA) firmware upgrade library, you would add:

1. source code:

```
#include "wiced_bt_ota_firmware_upgrade.h"
```

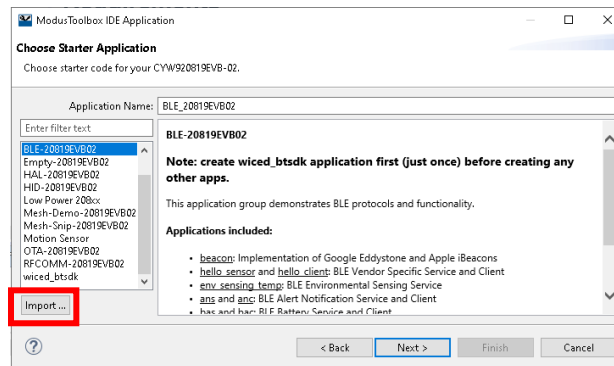
2. makefile:

```
COMPONENTS+=fw_upgrade_lib
.
.
.
SEARCH_LIBS_AND_INCLUDES+=$(CY_SHARED_PATH)/dev-kit/libraries/btSDK-ota
```

Note: for future reference, the required makefile edits are also shown at the bottom of the README.md file in the wiced_btSDK project or BT starter applications.

1.3.9 Renaming / Copying Projects

You can easily create a new application from an existing one using the "Import..." button in the new application wizard after selecting the target hardware.



After clicking on Import, just select the application folder to import (the folder containing the makefile).

If you do this for a single application that has additional hierarchy (such as most of the starter application code examples) you need to modify the path in the makefile after importing since the import will not maintain the additional hierarchy. That is, the CY_SHARED_PATH will need to be modified to the following:

```
CY_SHARED_PATH=$(CY_APP_PATH)/../wiced_btstack
```

After updating the makefile, build the project to get the Launches populated in the Quick Panel.

Note that if you provide the top-level folder of an entire set of applications, the hierarchy will be maintained so everything will work as-is.

Alternately, you can rename a single project from inside the Eclipse IDE by right clicking on the project in the project explorer and selecting "Rename" (don't rename wiced_btstack though – that will break things). This renames the project as it shows up in Eclipse, but it does NOT change the name of the folders in the filesystem. The Eclipse project name can be found in the .project file inside the project folder.

You can also copy/paste but you must keep the relative path to the wiced_btstack the same (or else change the path in the makefile to match the new relative path). This is difficult to get just right inside the IDE so it is easier to copy/paste from a file window (Windows explorer, etc.) and then update the project name in the .project file. Once you do that, you can import the project into Eclipse using *File > Import > General > Existing Projects into Workspace*.

After either a rename or a copy/paste, the Launches section for the new project in the Quick Panel will be empty. The launches can be recreated from the command line (more on the CLI in a minute) by running the command:

```
make eclipse CY_IDE_PRJNAME=<IDE project name>
```

where <IDE project name> is the name of the new project.

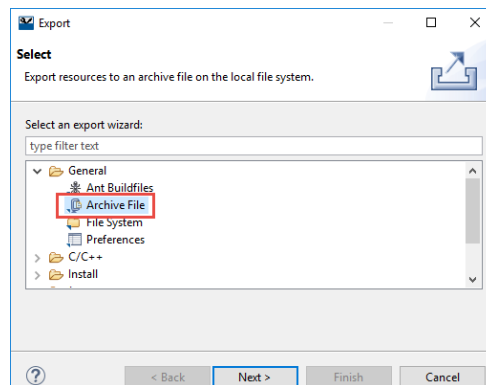
1.3.10 Sharing Applications

Applications can be shared by checking them into revision control systems such as Git.

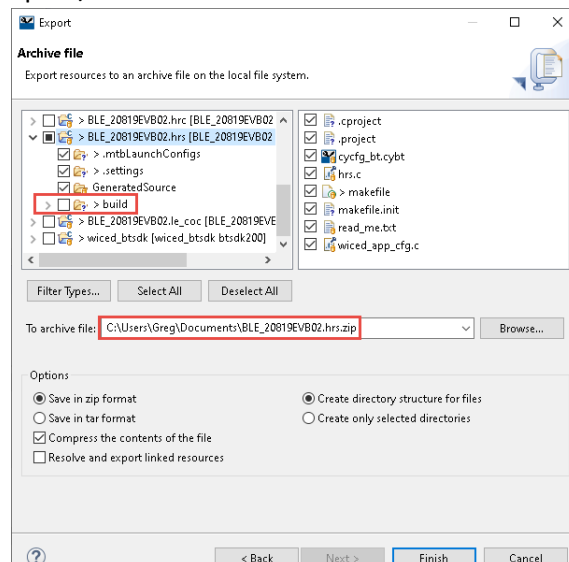
Another way to share an application is to export from ModusToolbox IDE into an archive file. This captures a full copy of the application that can then be imported as an existing project into another workspace. However, once you import from the archive file, any existing hierarchy, such as the hierarchy in most of the Bluetooth starter applications, will be flattened. In order for the resulting project to be built, a change is required in the makefile to update the relative path to the wiced_btstk. You'll see that step in the next section. The steps to export into an archive file are:

Export to Archive

1. Select the project or projects to be exported. Note that you may or may not want to export the wiced_btstk project. It is often easier to re-create it in a new workspace.
2. Choose *File->Export->General->Archive File* and click Next.



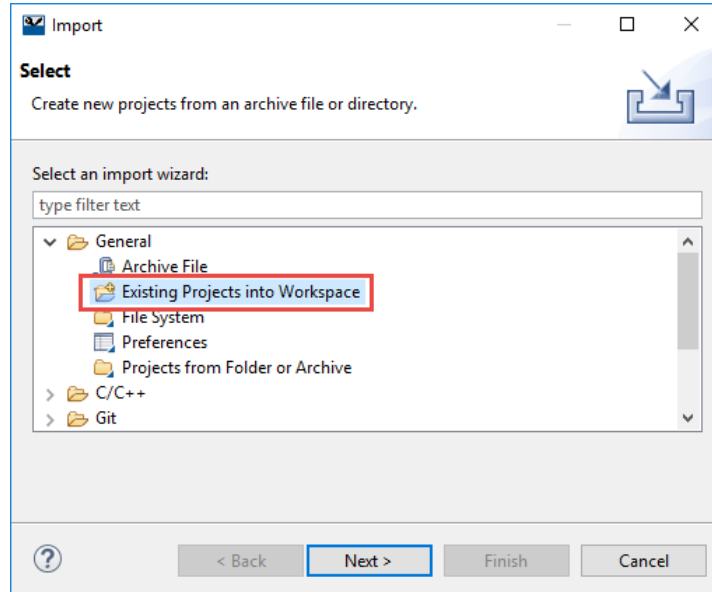
3. Uncheck the build folder if it exists to save space (this contains build output files).
4. Enter the desired file path/name for the archive file.



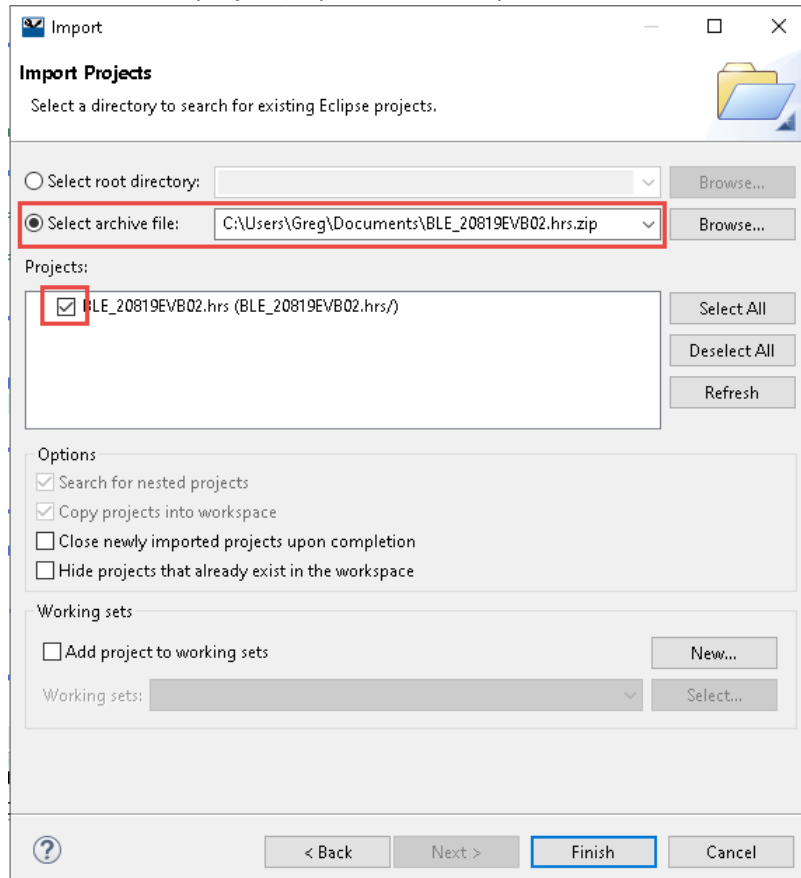
5. Click Finish.

Import from Archive

1. Create a new workspace if you don't have one already.
2. Create the wiced_btstack project using the normal method in the new workspace unless you are importing it from the archive.
3. In the new workspace choose *File->Import->General->Existing Projects into Workspace*.
 - a. DO NOT choose *File->Import->General->Archive File!*



4. Choose *Select archive file* and specify the path to the zip file.
5. Check the box next to the project(s) you want to import.



6. Click Finish.
7. While the project name will be the same, the hierarchy will be different from the starting project. For the example shown above, the hierarchy of the starting project is:

<workspace>/BLE_20819EVB02/ble/hrs/<project files>

After importing using this method, the hierarchy of the new project will be:

<workspace>/BLE_20819EVB02.hrs/<project files>

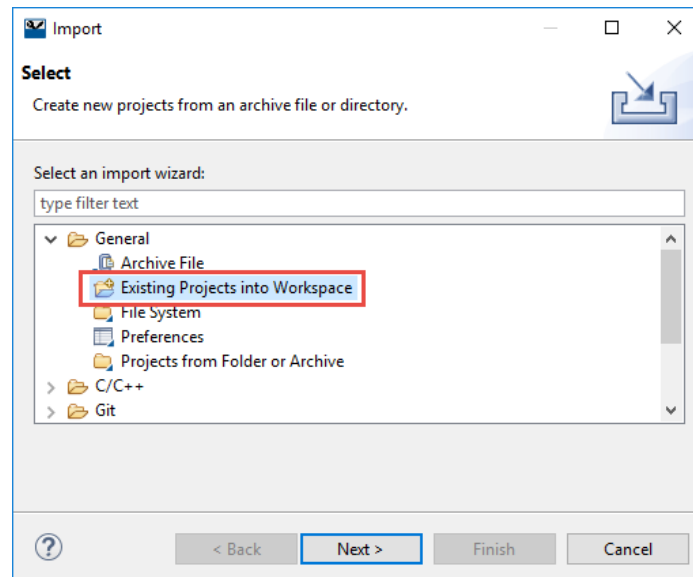
Due to this change, the wiced_btstack path is now ../wiced_btstack instead of ../../../wiced_btstack. Therefore, to allow the new project to be built, open the makefile and change the CY_SHARED_PATH as follows:

CY_SHARED_PATH=\$(CY_APP_PATH)/../wiced_btstack

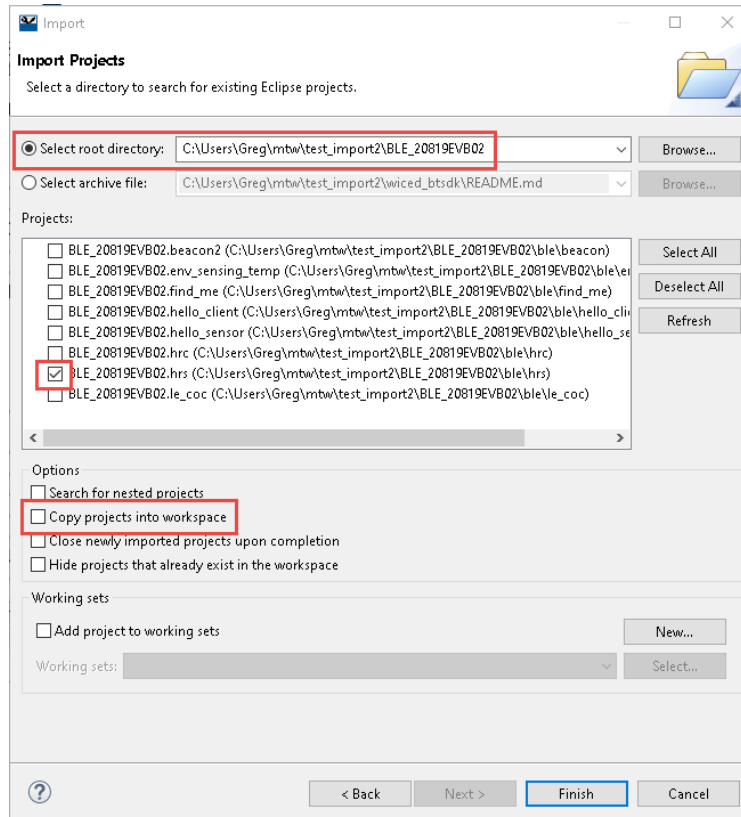
Import from Filesystem

Yet another way to share a full application is to copy the project in a file window (e.g. windows explorer) to the new workspace and then import from inside Eclipse without copying the project to the workspace. This method will keep the existing folder hierarchy so that the makefile need not be changed.

1. Create a new workspace if you don't have one already.
2. Create the wiced_btstack project using the normal method in the new workspace unless you are importing it from the old workspace.
3. Copy the desired project or projects and their associated hierarchy to the new workspace using the filesystem (e.g Windows explorer). You can change the names of folders if you wish during this step. Remember that the project name in Eclipse will be taken from the .project file in the project directory.
4. In the new workspace choose *File->Import->General->Existing Projects into Workspace* and click Next.



5. Choose the path to the project or projects to be imported. This should be the path to where you copied the project(s) in the NEW workspace.
6. Check the box next to the project or projects you want to import.
7. Uncheck the box *Copy projects into workspace* since you already copied the to the workspace using the filesystem.



8. Click Finish.
9. This will maintain the hierarchy of the original project(s) so you can build without any updates to the makefile.

1.4 Command Line Interface (CLI)

In addition to the ModusToolbox IDE, there is a command line interface that can be used for most, if not all, operations including downloading applications, running configurators, building, programming, and even debugging.

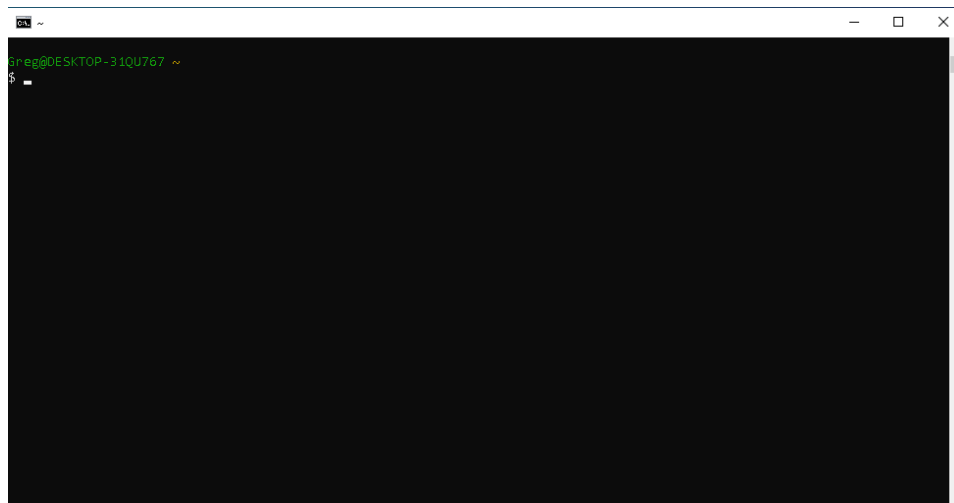
The make/build system works the same in both environments so once you have an application setup in the IDE, you can go back and forth between the command line and IDE at will.

If you start from the IDE, the application is automatically capable of command line operations. If you start from the command line, you can run an operation to allow the application to be imported into the IDE. In either case, once you have it setup, you can use both methods interchangeably depending on what you want to do.

1.4.1 Modus Shell

Modus Shell is a Cygwin environment that is setup for ModusToolbox. If you already have Cygwin installed and it has make and git, you can use Cygwin directly. If not, Modus Shell is a very convenient option.

To run Modus Shell, go to the tools directory (<install>/ModusToolbox/tools_<version>/modus-shell) and double click on Cygwin.bat. This will launch the shell. It is Linux based, so you can use any Linux commands.



1.4.2 Downloading an Application from a Repository

There is a tool called project-creator that can be used to setup an application to use on the command line. In fact, there is both a GUI version of this tool (project-creator.exe) and a command-line version (project-creator-cli.exe). The GUI version works just like the new application wizard and is a very easy way to setup an application which can then be used in the command line interface. The command line version requires a few arguments, but if you run it with no arguments it will print help information.

Both tools can be found in the ModusToolbox installation at:

```
<install_folder>/ModusToolbox/tools_<version>/project-creator
```

If you want to setup an application manually without using one of the project creator tools, you can use Git and make commands to download an application and its dependencies from their repositories (typically on GitHub). You can find all of the available code examples at:

<https://github.com/cypresssemiconductorco/Code-Examples-BT-SDK-for-ModusToolbox>.

For example, you could run these commands from Modus Shell to download and build the Empty Bluetooth code example (the make commands will be explained in the next section):

Make a Directory to Hold the Applications (i.e. a Workspace)

```
mkdir my_workspace
```

```
cd my_workspace
```

Download the BTSDK (only need to do this once per workspace)

```
git clone https://github.com/cypresssemiconductorco/wiced_bt sdk
```

```
cd wiced_bt sdk
```

```
make getlibs
```

```
cd ..
```

Download the application (or application group)

```
git clone https://github.com/cypresssemiconductorco/mtb-examples-CYW920819EVB-02-btsdk-empty
```

```
cd Empty_20819EVB02/template/empty_wiced_bt
```

```
make getlibs
```

Build the Application

```
make build
```

1.4.3 Modus CLI Commands

To run ModusToolbox CLI commands, you must first change to the directory with your application's project (the directory with the makefile). For example:

```
cd C:/Users/Greg/mtw/wbt101/BLE_20819EVB02/ble/beacon
```

Once in the application's project folder, you can run make with various arguments such as:

make help

Print top level information and options of the make system.

make help CY_HELP=build

Print help information about the build make target.

make build

Build the application.

make build VERBOSE=true

Build the application with verbose output messages.

make program

Build the application and then program it to the target device.

make qprogram

Program the application using the existing build output files.

make clean

Clean the application.

make getlibs

Search for library files in the project (*.lib) and download the associated libraries.

make config_bt

Run the Bluetooth configurator. If an existing .cybt file exists it will open it. If not, it will allow you to create a new one once the tool launches.

make config_bt design

Run the device configurator. This will open the configurator file from the BSP for your target device. Remember that the BSP is in a location that may be shared between applications so be careful when editing this file.

make eclipse CY_IDE_PRJNAME=my_project

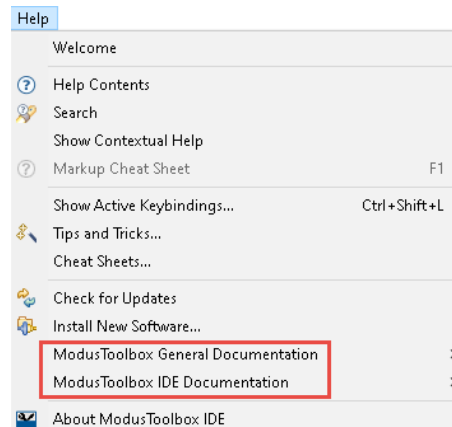
Create Eclipse launch targets to allow importing to the IDE.

There are many other options and variables available. Explore the make help output to find out what else is possible.

1.5 Tour of Documentation

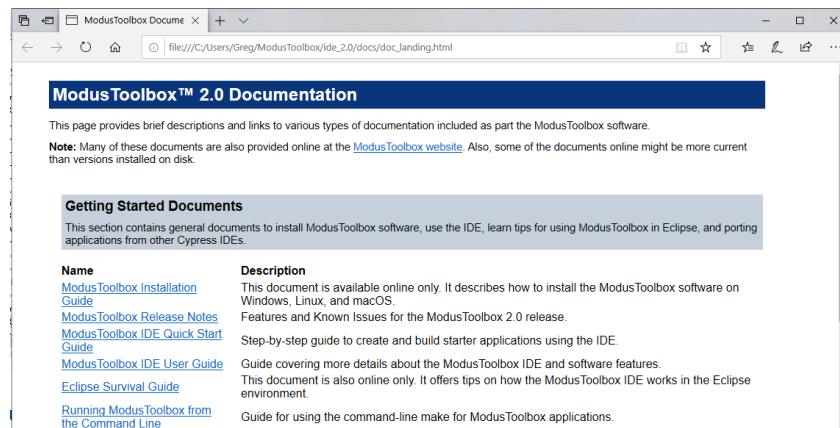
1.5.1 In ModusToolbox IDE

In the ModusToolbox IDE Help menu there are 2 items of particular interest:

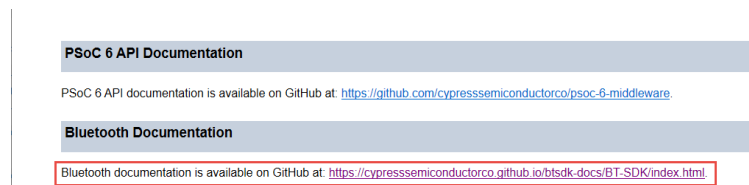


ModusToolbox General Documentation

The first item of interest has a link to the ModusToolbox Documentation Index which is a web page that looks like this:

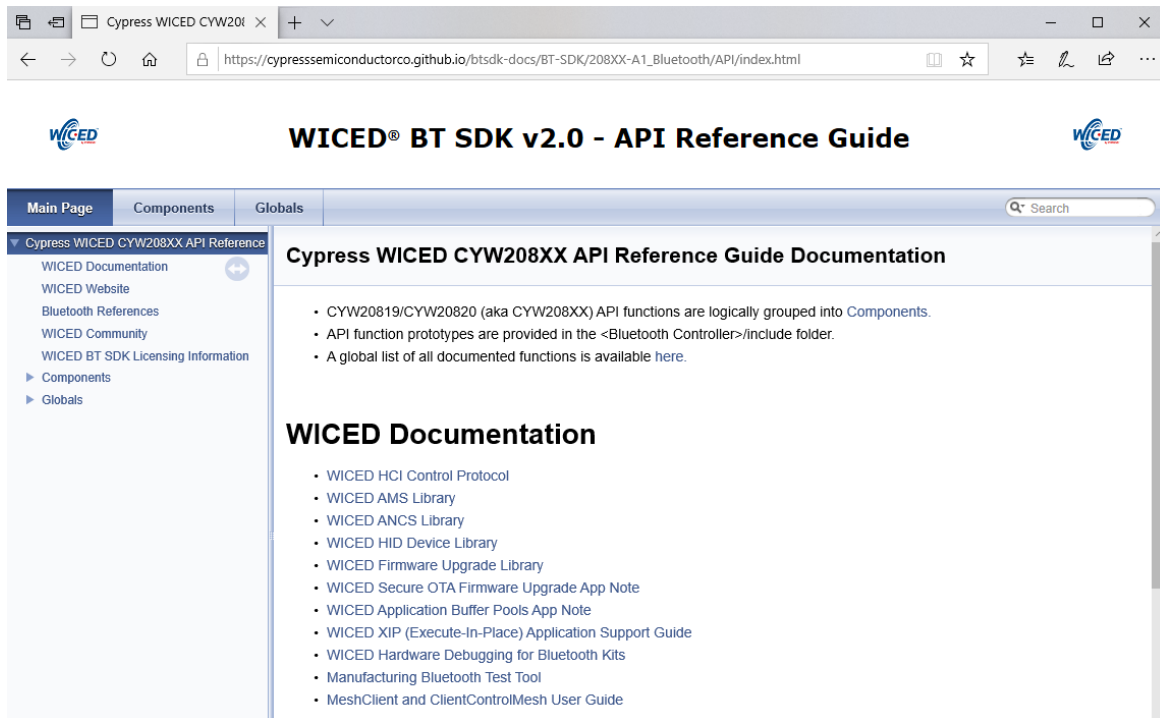


At the bottom of that page you will find a link to the BT SDK API guide.





The Bluetooth Documentation link takes you to a page where you select from a list of Bluetooth devices. This page is also available directly from a link in the Quick Panel. Once you select your device, you will get to this page:



The documentation on the right is useful for specific topics while the section on the left is invaluable for understanding the API functions, data types, enumerations, macros, etc.

ModusToolbox IDE Documentation

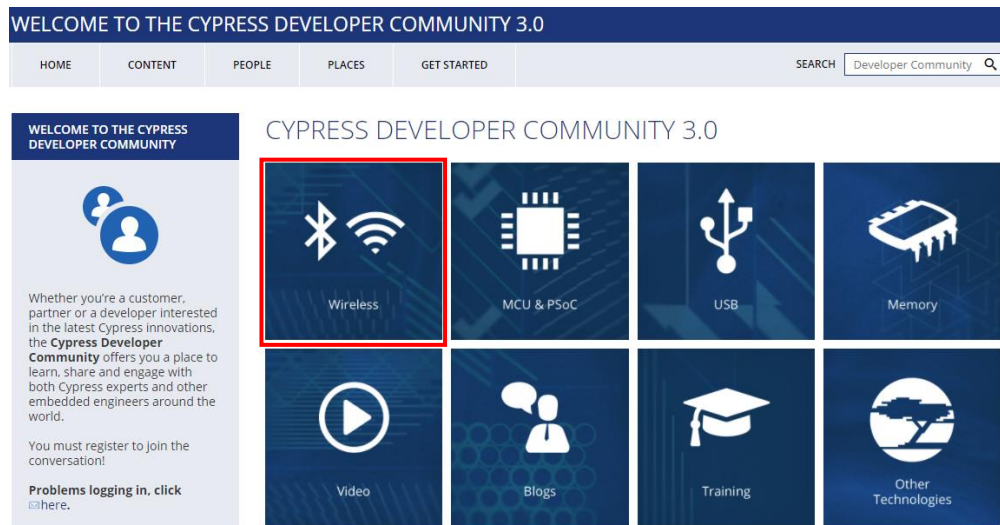
The second item on the Help Menu if interest contains documents for:

- Quick Start Guide
- User Guide
- Eclipse IDE Survival Guide

The third item contains tips and tricks on using the Eclipse IDE with Cypress devices intended for those who have relatively little experience with Eclipse.

1.5.2 On the Web


Navigating to "www.cypress.com > Design Support > Community" will take you to the following site (the direct link is <https://community.cypress.com/welcome>):



Clicking on the *Wireless* icon will take you to the page as shown below. From this page, you will find links to pages that allow you to download ModusToolbox, search for answers, ask questions, etc.



From the Wireless Connectivity page, click on ModusToolbox Bluetooth to get to the page where you can find downloads for ModusToolbox IDE and information on the BT SDK as well as links to product guides, code examples, videos, etc.



ModusToolbox BT SDK

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 - [CYW20819 Product Guide](#)
 - [CYW20820 Product Guide](#)
 - [CYW89820 Product Guide](#)
 - [CYW20721B2 Product Guide](#)
 - [Installation Guide](#)
 - [Quick Start Guide](#)
 - [Eclipse IDE Survival Guide](#)

- ### BLUETOOTH DESIGNS
- [Elderly Fall Detection With Supervised Learning \(ML\)](#)
 - [Pollution Parameters Monitoring System](#)
 - [Predictive Maintenance System](#)
 - [Smart Home Garden](#)
 - [Tire Pressure Monitoring System \(TPMS\)](#)
 - [Water Density Mapping For Plants](#)

- ### RECENT BLOG POSTS
- [Bluetooth Mesh Workshop Notes Available on](#)



ModusToolbox simplifies embedded systems development by delivering flexibility and easy-to-use tools within a familiar integrated development environment (IDE) under Windows®, macOS®, and Linux®. In addition, it provides a sophisticated platform for system peripheral configuration as well as application-specific configurators for Bluetooth®, CapSense®, and others. For more information on ModusToolbox, go to the [ModusToolbox Community Page](#)

Bluetooth SDK

The BT SDK is targeted for the CYW20719B2, CYW20721B2, CYW20819, CYW20820 and CYW89820 ultra low power Bluetooth 5.0 SoCs. ModusToolbox 2.0 with the Bluetooth SDK 2.0 provides a complete development environment to allow you to quickly create Bluetooth enabled IoT solutions like audio devices, beacons and trackers, hid devices, smart watches, medical devices, and home automation platforms. The BT SDK includes the following:

Bluetooth firmware

- Platform and board support packages
- Utilities including BTSpY trace, Manufacturing Bluetooth test tool, Client Control, and Mesh Client control
- Peer apps for OTA and Mesh
- A rich set of WICED™ connectivity APIs that allow for simplified programming of BT/BLE connectivity
- Various sample applications that serve as examples of how to utilize the BT/BLE APIs
- More complex code examples that utilize various APIs and middleware to create a more complete solution

Notes for Installing BT SDK 2.0 with ModusToolbox 2.0:

- Within the ModusToolbox IDE, click the "New Application" link in the Quick Panel
-Alternatively, you can select File -> New -> ModusToolbox IDE Application
- Next, select the evaluation board you are using with BT SDK 2.0
- Now you will select *wiced_btstack* while noting that this project contains the actual SDK which is used by all BT SDK 2.0 applications.
-You will need to create this project just once in the working directory
-Do not change the name of this project as all BT SDK 2.0 applications use the same project name within their application makefiles.
-This step can take up to 15 minutes, but will not need to be invoked again once initially executed
- After the *wiced_btstack* project is created, again click the "New Application" link and then the evaluation board followed by the application you wish to use within BT SDK 2.0.

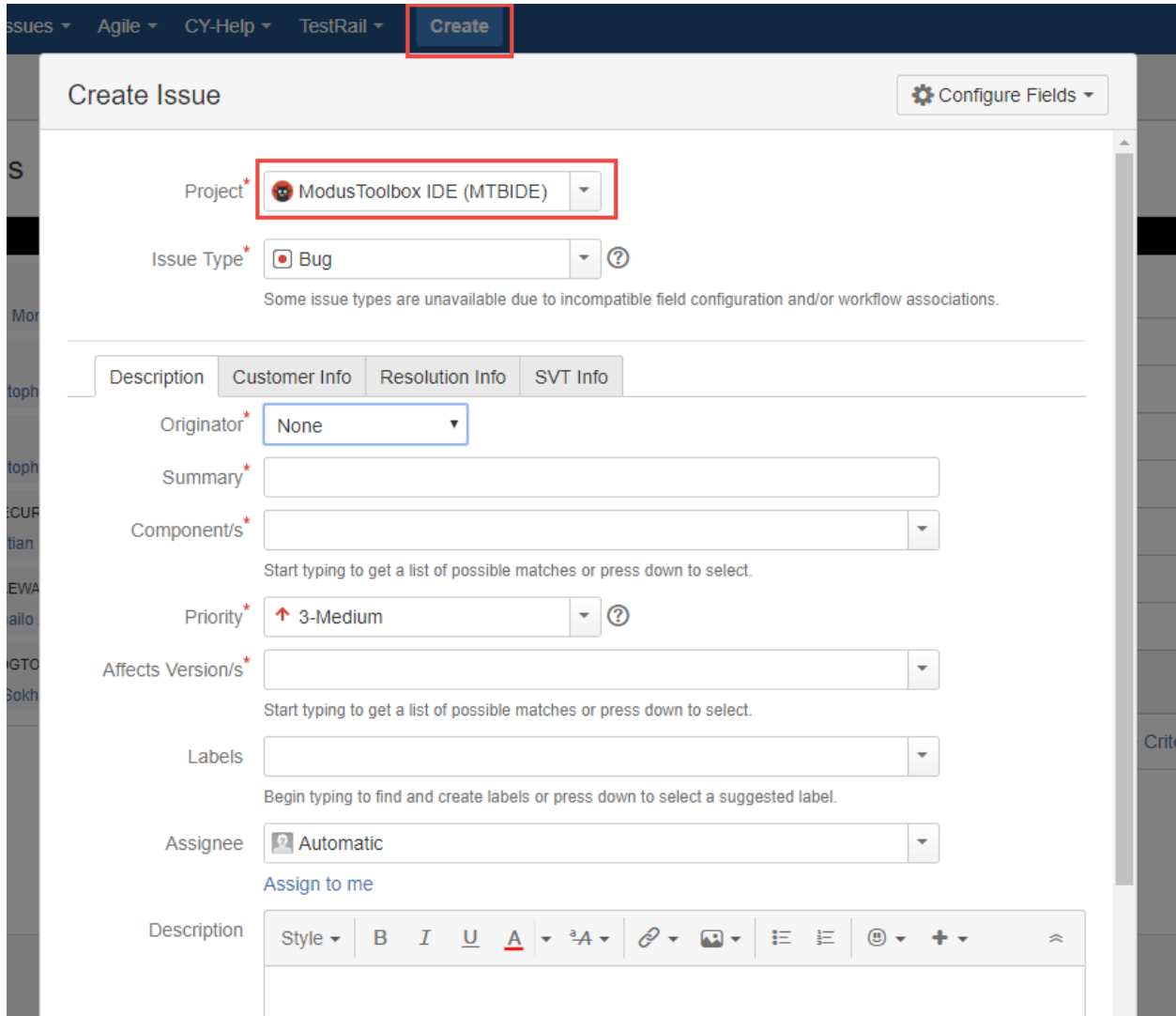
Downloads
ModusToolbox 2.0 (Linux Installer)

1.6 Reporting Issues

If you are a Cypress employee and you find an issue in ModusToolbox (bug, missing or confusing documentation, enhancement request), please use a "JIRA" to report it:

jira.cypress.com

Click on Create to start submitting a JIRA. Use the project type of "MTBIDE" or "BTSDK", depending on the issue and then fill in as many details as you can to report the issue.



The screenshot shows the "Create Issue" form in the Cypress JIRA system. The "Project" dropdown is set to "ModusToolbox IDE (MTBIDE)" and the "Issue Type" is "Bug". The "Originator" is "None", "Priority" is "3-Medium", and "Assignee" is "Automatic". The "Description" field is empty with a rich text editor toolbar visible. The "Labels" field is empty. The "Affects Version/s" field is empty. The "Component/s" field is empty. The "Summary" field is empty. The "Resolution Info" and "SVT Info" tabs are visible. The "Configure Fields" button is in the top right corner.

Non-Cypress employees can ask questions and report issues in the developer community.

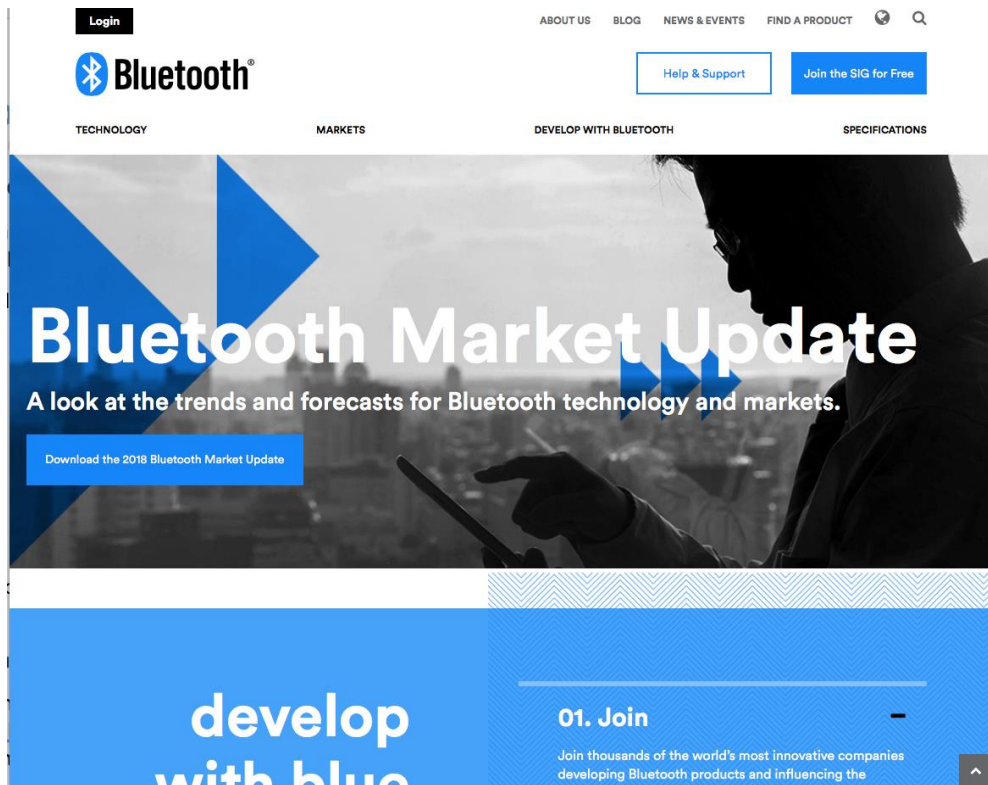
1.7 Tour of Bluetooth

Bluetooth is a short-range wireless standard that runs on the 2.4 GHz ISM (Industrial, Scientific, and Medical) band modulation. It is controlled by the Bluetooth Special Interest Group (SIG).

Discussions about Bluetooth are typically divided into *Classic Bluetooth* and *Bluetooth Low Energy*.

1.7.1 The Bluetooth Special Interest Group (SIG)

The Bluetooth Special Interest Group is an industry consortium that owns the specifications for Bluetooth. All the Bluetooth documentation is available at www.bluetooth.org. You can register for an account on that website.



The current Bluetooth Specification is Version 5.1 is a ~3000 page long document that can be downloaded from the Bluetooth SIG website at <https://www.bluetooth.com/specifications/bluetooth-core-specification>

At the core of everything Bluetooth

The *Bluetooth*® Core Specification defines the technology building blocks that developers use to create the interoperable devices that make up the thriving Bluetooth ecosystem. The Bluetooth specification is overseen by the Bluetooth Special Interest Group (SIG) and is regularly updated and enhanced by [Bluetooth SIG Working Groups](#) to meet evolving technology and market needs.

The documents in the “Informative document showing changes” column are provided as a courtesy to help readers identify changes between two versions of a Bluetooth specification. When implementing specifications, use the adopted versions in the “Adopted Version” column.

Adopted Version		Status	Adoption Date	Informative document showing changes
CS	Core Specification	5.1 Active	21 Jan 2019	CS_5.1_showing_changes_from_CS_5 🔒
CSS	Core Specification Supplement	8 Active	21 Jan 2019	CSS_8_showing_changes_from_CSS_7 🔒

1.7.2 Classic Bluetooth

Classic Bluetooth uses 79 channels with a channel spacing of 1 MHz. It has three main speeds – Basic Rate (BR) and two Extended Data Rates (EDR). Each of these uses a different modulation scheme.

Mode	Speed	Modulation
Basic Rate	1 Mbps	GFSK (Gaussian Frequency Shift Keying)
Extended Data Rate	2 Mbps	$\pi/4$ DQPSK (Differential Quadrature Phase Shift Keying)
Extended Data Rate	3 Mbps	8DPSK (Octal Differential Phase Shift Keying)

The range is dependent on the transmission power which is divided into four classes:

Class	Max Permitted Power		Typical Range (m)
	(mW)	(dBm)	
1	100	20	100
2	2.5	4	10
3	1	0	1
4	0.5	-3	0.5

1.7.3 Bluetooth Low Energy

Bluetooth Low Energy (BLE) uses 40 channels with a channel spacing of 2 MHz (and so it shares the same range of frequencies with Bluetooth Classic). It provides much lower power consumption than Classic Bluetooth. Lower power is not achieved by reducing range (i.e. transmission power) but rather by staying actively connected for short bursts and being idle most of the time. This requires devices to agree on a connection interval. This connection interval can be varied to trade off the frequency of data transmitted vs. power. Therefore, BLE is excellent for data that can be sent in occasional bursts such as sensor states (i.e. temperature, state of a door, state of a light, etc.) but is not good for continuous streaming of data such as audio. BLE typically transmits data up to 1 Mbps, but 2 Mbps can be achieved in Bluetooth version 5 with shorter range.

1.7.4 Bluetooth History

Bluetooth Spec	Year	Major Features
1.0	1999	Initial standard.
1.1	2002	Many bug fixes. Addition of RSSI and non-encrypted channels.
1.2	2003	Faster connection and discovery. Adaptive Frequency Hopping (AFH) Host Control Interface (HCI) Addition of flow control and retransmission.
2.0 + EDR	2004	Addition of EDR (up to 3 Mbps).
2.1 + EDR	2007	Addition of Secure Simple Pairing (SPP) and enhanced security. Extended Inquiry Response (EIR).
3.0 + HS	2009	Addition of HS which uses Bluetooth for negotiation and establishment, then uses an 802.11 link for up to 24 Mbps. This is called Alternative MAC/PHY (AMP). Addition of Enhanced Retransmission Mode (ERTM) and Streaming Mode (SM) for reliable and unreliable channels.
4.0 + LE	2010	Addition of BLE. Addition of Generic Attribute Profile (GATT). Addition of Security Manager (SM) with AES encryption.
4.1	2013	Incremental software update.
4.2	2014	LE secure connections with data packet length extension. Link Layer privacy. Internet Protocol Support Profile (SPP) version 6.
5	2016	LE up to 2 Mbps for shorter range, or 4x range with lower data rate. LE increased packet lengths to achieve 8x data broadcasting capacity.
5.1	2019	Mesh-based model hierarchy Angle of Arrival (AoA) and Angle of Departure (AoD) for tracking Advertising Channel Index GATT Cacheing

1.8 Tour of Chips

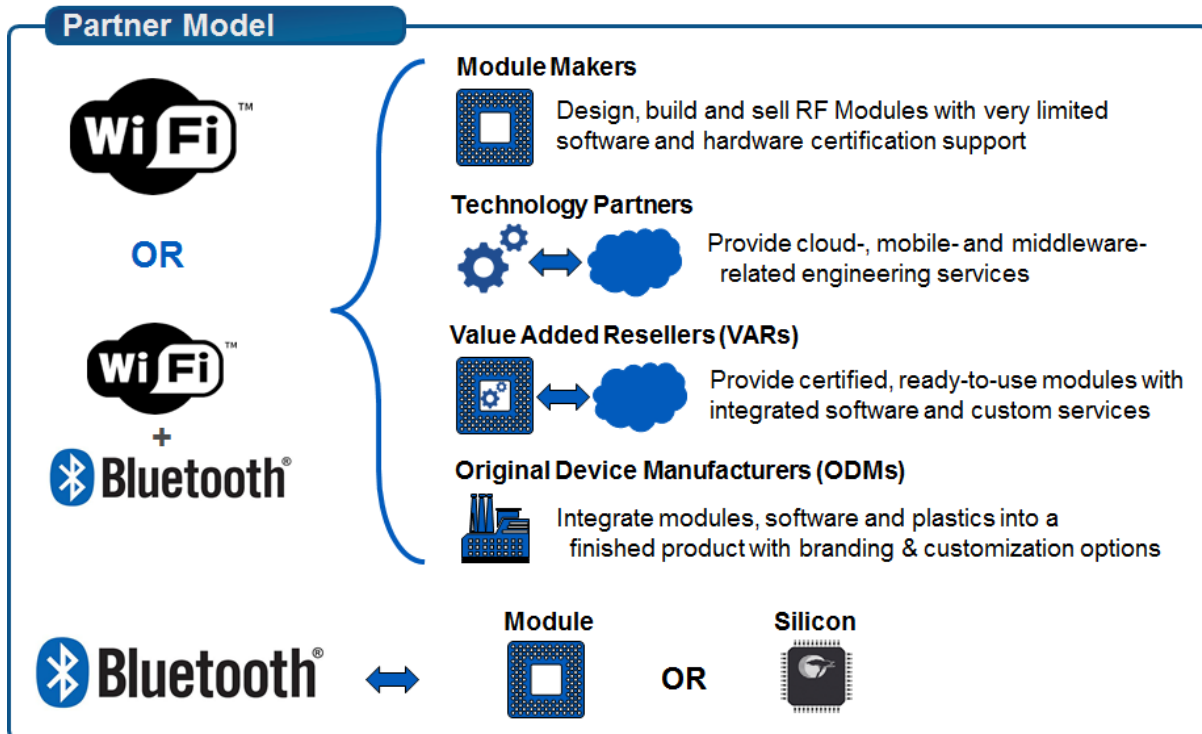
Device	Key Features	Notes
CYW20706	<ul style="list-style-type: none"> • Bluetooth BR, EDR and LE 5.x • ARM Cortex-M3 • 848 kB ROM • 352 kB RAM (data and patches) • 2 kB NVRAM 	WICED Studio
CYW20719	<ul style="list-style-type: none"> • Bluetooth BR, EDR and LE 5.x • 2 Mbps LE v5 • 96 MHz ARM Cortex-M4 • Single Precision FPU • 2 MB ROM • 1 MB On-Chip Flash • 512 kB RAM 	ModusToolbox
CYW20819	<ul style="list-style-type: none"> • Bluetooth BR, EDR and LE 5.x • BR/EDR 2 Mbps and 3Mbps • LE 2Mbps • Ultra-low power • 96 MHz ARM Cortex-M4 • 1 MB ROM • 256 kB On-Chip Flash • 176 kB RAM 	ModusToolbox
PSoC 4 BLE	<ul style="list-style-type: none"> • BLE 4.2 • 48 MHz ARM Cortex-M0 • 256 kB On-Chip Flash • 32 kB RAM 	PSoC Creator
PSoC 6 BLE	<ul style="list-style-type: none"> • BLE 5.x • 150 MHz ARM Cortex-M4 & M0+ • 1MB or 2 MB On-Chip Flash • 288 KB RAM 	ModusToolbox PSoC Creator

This class covers only the WICED Bluetooth SoC devices, not the PSoC BLE devices.

The Cypress CYW20819 is an ultra-low power (ULP), highly integrated, and dual-mode Bluetooth wireless MCU. By leveraging the all-inclusive development platform ModusToolbox, it allows you to implement the industry's smallest-footprint, lowest-power Bluetooth Low Energy (BLE) and dual mode Bluetooth applications quickly. CYW20819 is a Bluetooth 5.x compliant SoC with support for Bluetooth Basic Rate (BR), Enhanced Data Rate (EDR), and BLE.

The CYW20819 employs the highest level of integration to eliminate all critical external components, thereby minimizing the device's footprint and the costs associated with implementing Bluetooth solutions. A 96 MHz CM4 CPU coupled with 256 kB on-chip flash and 1 MB ROM for stack and profiles offers significant processing power and flash space to customers for their applications. CYW20819 is the optimal solution for a range of battery-powered single/dual mode Bluetooth internet of things applications such as home automation, HID, wearables, audio, asset tracking, and so on.

1.9 Tour of Partners



A global partner ecosystem enables you to get the level of support you need for your IoT application



An IoT Selector Guide including partner modules available can be found in the Community at:

<https://community.cypress.com/docs/DOC-3021>

1.10 Tour of Development Kits

1.10.1 [Cypress CYW920819EVb-02](#)

- Bluetooth 5.x plus 2 Mbps LE from v5
- 96 MHz ARM Cortex-M4
- Integrated transceiver
- 1 MB ROM, 256 kB On-Chip Flash, 176 kB SRAM
- 1 User Button, 2 User LEDs
- USB JTAG Programmer/Debugger



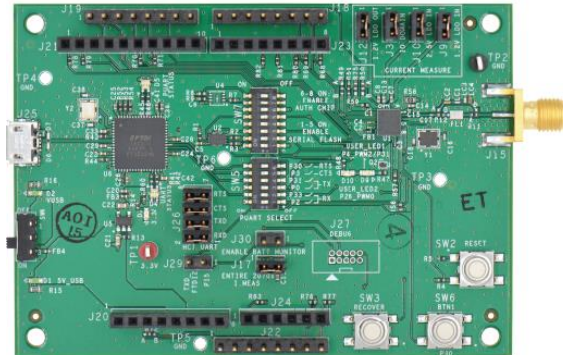
1.10.2 [Cypress CYBT-213043-MESH](#)

- Bluetooth Mesh kit with 20819 module
- Each kit contains 4 boards to evaluate mesh networks
- 1 User Button, RGB LED, ambient light sensor, PIR motion sensor



1.10.3 [Cypress CYW920706WCDEVAL](#)

- Monolithic, Single-chip, Bluetooth 5.x + HS
- ARM Cortex-M3 processor
- Integrated transceiver
- 848 kB ROM, 352 kB SRAM (data and patches), 2 kB NVRAM, 512 kB External Serial Flash
- 1 User Button, 2 User LEDs
- USB JTAG Programmer/Debugger



1.10.4 [Cypress CYW920719Q40EVb-01](#)

- Bluetooth 5.x plus 2 Mbps LE from v5
- 96 MHz ARM Cortex-M4
- Integrated transceiver
- 2 MB ROM, 1 MB On-Chip Flash, 512 kB SRAM
- 1 User Button, 2 User LEDs
- USB JTAG Programmer/Debugger



1.11 Exercise(s)

Exercise - 1.1 Create a Forum Account

1. Go to <https://community.cypress.com/welcome>
2. Click "Log in" from the top right corner of the page and login to your Cypress account. If you do not have an account, you will need to create one first.
3. Once you are logged in, click the "Wireless" icon and then explore.

Exercise - 1.2 Start ModusToolbox IDE, and Explore the Documentation

1. If you are on a Cypress internal network, set the environment variables before starting the IDE. See section 1.2
2. Run ModusToolbox IDE and create a new workspace.
3. If you are on a Cypress internal network, set the required settings in ModusToolbox IDE. See section 1.2
4. Explore the different documents available in the Help menu such as the *ModusToolbox IDE Help*, *Quick Start Guide*, *User Guide* and *Eclipse IDE Survival Guide*.
5. Open and explore the *ModusToolbox Documentation Index* page. Be sure to look at the *CYW920819EVB-02 Kit* link and the *Bluetooth Documentation -> CYW208XX API Reference*.

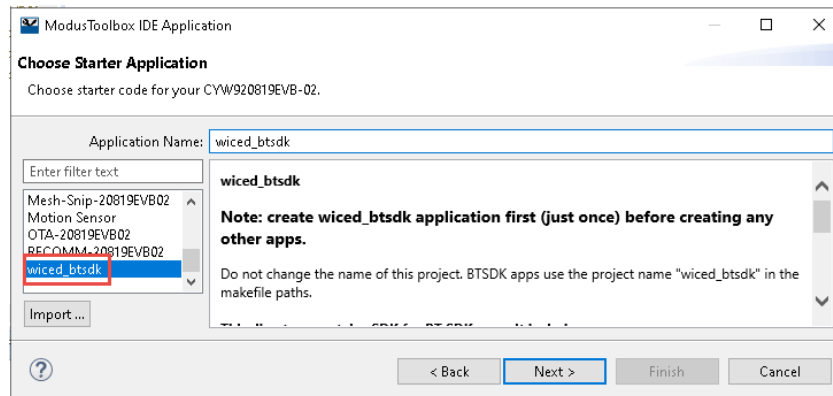
Questions to answer:

1. Where is the WICED API documentation for the PWM located?

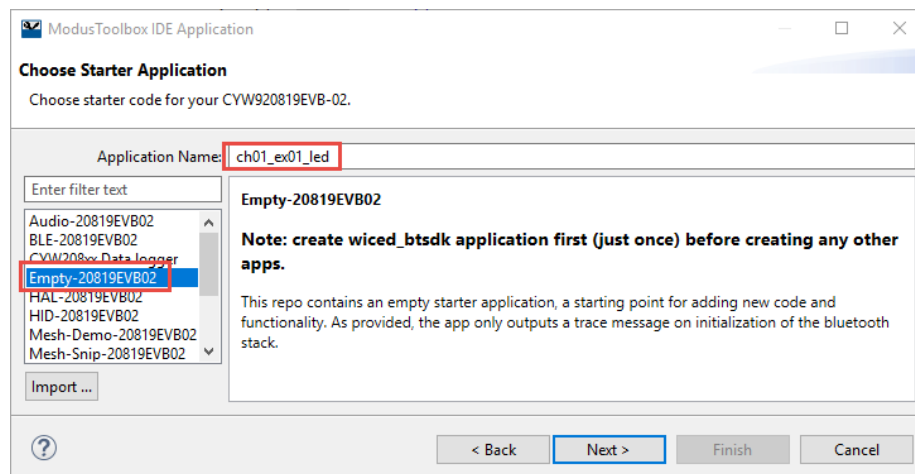
Exercise - 1.3 Program a Simple Application

In this exercise, you will install the wiced_btstack, create a new application, and then build/program it to a kit.

1. In the Quick Panel tab click "New Application".
2. Select the CYW920819EVB-02 kit and click "Next >".
3. Select "wiced_btstack".

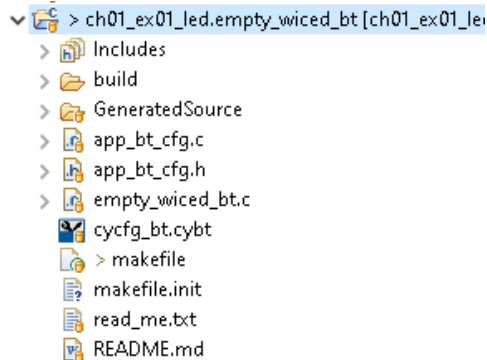


4. Click "Next >"
5. Click "Finish" (it will take a few minutes to download the SDK. Remember you only need this step once per workspace since the SDK is shared).
6. Once that's done, click "New Application" again.
7. Select the CYW920819EVB-02 kit and click "Next >".
8. Select "Empty-20819EVB02"
9. Change the application name to **ch01_ex01_led**.



Note: you can call the application anything you like but it will really help if you maintain an alphabetically sortable naming scheme – you are going to create quite a few projects.

10. Click "Next ". Verify the presented device, board, and example, then click "Finish". When the application has been created, the Project Explorer window in Eclipse should look like the following screenshot (ModusToolbox IDE adds ".empty_wiced_bt" to the project name because, as you learned earlier, some starter applications actually contain a set of applications):



11. Open the top-level C file which in this case is called empty_wiced_bt.c.
12. Add the following line in the application_start function:

```
wiced_hal_gpio_set_pin_output(WICED_GPIO_PIN_LED_1, GPIO_PIN_OUTPUT_LOW);
```

13. Connect your CYW920819EVB-02 kit to a USB port on your computer.
14. In the Quick Panel, look in the "Launches" section and click the "ch01_ex01_led.empty_wiced_bt Program" link.
15. Once the build and program operations are done, you should see "Download succeeded" in the Console window and LED1 (the yellow user LED) should be on.