# Static GRG-Schema

### The GRG Team\*

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#### **Abstract**

This document describes the Grid Research for Good (GRG) schema to represent static transmission networks.

# 1 Basic Concepts

This section defines the basic concepts used to model grid data. We first define data types for representing numerical values, variables, and object statuses. Then we define data types used to represent electrical values.

Throughout the document we adopt the symbol j to denote the complex imaginary unit, which satisfies the equation:  $j^2 = -1$ . For a complex number  $x \in \mathbb{C}$  we write  $\bar{x}$  to denote the conjugate of x. Additionally, for a list of elements  $A = \langle a_1, \ldots, a_n \rangle$ , we use the notation A[k] to indicate the  $k^{th}$  element of A,  $a_k$ .

For a JSON attribute, the keyword \$ref describes a *JSON Reference*, i.e., a reference to an object whose fragment part is a URI encoded JSON Pointer. In this document, all references are local to the schema, and their values reflect the document hierarchy.

### 1.1 Values

#### **Extended Number**

An *extended number* is a numeric data type whose value is either a number or one of the following: Inf, denoting  $\infty$ , -Inf denoting  $-\infty$ , NaN, standing for "not a number" and representing an undefined or unrepresentable value, or Null, to denote a value which is missing.

The following example illustrates the above concept by where x is assigned a numeric value, and y to a  $-\infty$ .

```
"x": 10.23,

"y": "-Inf"
```

#### **Extended Positive Number**

An *extended positive number* restricts the notion of extended number to non-negative values and the special values *Inf*, *NaN*, and *Null*.

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#### **Domain**

A domain is a collection of values used to describe valid assignments for a variable. We define three types of domains:

- Finite domains describing a collection of strings.
- Finite domains describing a collection of numbers.
- Bound domains describing a range  $[lb, ub] \subseteq \mathbb{R}$ .

```
__ GRG schema: domain -
"domain": {
    "type"
             : "object",
    "required": ["var"],
    "properties": {
        "var": {
            "oneOf": [
                "type"
                          : "array",
                "items" : {"type": "string"},
                "minItems": 1
            }, {
                "type"
                          : "array",
                "items" : {"type": "number"},
                "minItems": 1
                "type"
                         : "object",
                "required": ["lb", "ub"],
                "properties": {
                    "lb" : {"$ref": "#/values/extended number"},
                    "ub" : {"$ref": "#/values/extended_number"}
                "additionalProperties": false
            } ]
       }
    "additionalProperties": false
```

Following are examples of finite string domain (x), finite numerical domain (y), and bound domain (z).

```
"x": { "var": ["a", "b", "c"] },
"y": { "var": [1, 2, 3] },
"z": { "var": {"lb": 0, "ub": 10} }
```

### **Positive Domain**

A positive domain restricts the notion of domain to non-negative values.

#### **Abstract Value**

An abstract value is an extended numeric data type which can describe either a numeric value or a variable.

In the following code, x is a variable abstract value, and y is a numeric abstract value.

```
"x": { "var": {"lb": 0, "ub": 10} },
"y": 3.56
```

#### **Abstract Positive Value**

An abstract positive value restricts the notion of abstract value to non-negative numeric values and non negative variables.

#### **Status**

A status is a special boolean variable whose domain elements are "on" and "off".

In the following examples, x represents an unassigned status variable, and y represents a status element whose value is 'on'.

```
______Example: status _______

"x": { "var": ["on", "off"] }

"y": "on",
```

#### **GRG Pointer**

A *GRG pointer* is a string used to identify an object's value in the GRG document. A GRG pointer extends a JSON pointer by adopting the following prefixes:

- #, which refers to the document root.
- @, which refers to a JSON object in the same scope as the pointer itself.
- !, which refers to network elements (a shortcut for #/network/components).

```
"grg_pointer": {
    "type": "string",
    "pattern": "^(#|!|@)/.*"
}
```

In the following examples, the GRG pointers p1, p2, and p3 refer to the same value (br1). The pointer p4 refers to the first value of the array var in the object status of switch\_example.

```
_ Example: grg_pointer _
"network: {
    "components": {
        "switch_example" : {
            "type" : "switch",
            "subtype" : "breaker",
            "id"
                      : "br1",
            "link_1"
                      : "10",
            "link_2" : "11",
            "status" : {"var" : ["off", "on"]},
            "p1"
                      : "@/id"
    }
},
"p2": "#/network/components/switch_example/id",
"p3": "!/switch_example/id",
"p4": "!/switch_example/status/var/0
```

#### **Table**

A table is an object linking a list of GRG elements  $\langle e_1, \ldots, e_k \rangle$  to a set of tuples  $\{T_1, \ldots, T_n\}$ , where each  $T_i = \langle v_1, \ldots, v_k \rangle$  has values  $v_i$  (i = 1, ..., k). The elements are referred to as table *arguments*, and the set of value tuples as table *values*. In other words, a table expresses the relation between a list of elements and the set of possible values for such elements.

```
"table": {
    "type" : "object",
```

```
"required": ["arguments", "values"],
"properties": {
    "arguments": {
        "type" : "array",
"items" : {"$ref": "#/values/grg_pointer"},
        "minItems": 1, "uniqueItems": true
    "values": {
        "type" : "array":
        "items": {
             "type" : "array",
             "items": {
                 "oneOf": [
                     {"type": "#/values/abstract_value"},
                     {"type": "string"}
             "minItems": 1
        "minItems": 1
}
```

The following example describes three assignments for the elements x, y, and z:

```
x = 1, y = 12, z = 13

x = 2, y = 6, z = 20

x = 3, y = 10, z = 31
```

### 1.2 Electrical Values

This section defines the electrical values adopted by the GRG schema.

#### **Impedance**

Electrical *impedance* measures the opposition of a circuit to a current when a given voltage is applied. Impedance is represented as a complex quantity Z:

$$Z = R + jX, (1)$$

where R denotes the resistance, and X the reactance.

Table 1 maps the real and imaginary components of impedance to their GRG schema counterparts.

GRG name	Symbol	Unit
impedance	Z	Ohm $(\Omega)$
resistance	R	Ohm $(\Omega)$
reactance	X	Ohm $(\Omega)$

Table 1: Impedance: representation in the GRG impedance element and units.

Though the schema definition may seem complicated, the following example shows how simple it is to use:

```
"impedance" : {
    "reactance" : 6.52,
    "resistance" : 2.39
}
```

#### **Admittance**

Electrical *admittance* is a measure of how much a circuit allows current to flow. Admittance is represented by a complex quantity Y:

$$Y = G + jB, (2)$$

where G denotes conductance, and B denotes susceptance. These real and imaginary components are mapped to the GRG admittance object as shown in Table 2.

GRG name	Symbol	Unit
admittance	Y	Siemens $(S)$
conductance	G	Siemens $(S)$
susceptance	B	Siemens $(S)$

Table 2: Admittance: representation in the GRG admittance element and units.

The following example shows how to define an admittance in GRG format:

```
"shunt": {
    "conductance": 0,
    "susceptance": 2.3e-05
}
```

#### Power

Electric power is the rate at which electrical energy is transferred by an electric circuit. We define the complex power S as:

$$S = P + jQ, (3)$$

where P is the active (or real) power, and Q is the reactive power. Table 3 shows how these quantities are encoded in the GRG format.

GRG name	Symbol	Unit
power	S	
active	P	MegaWatt (MW)
reactive	Q	MegaVolt-Ampere Reactive (MVAR)

Table 3: Power: representation in the GRG format and units.

Active and reactive power are defined as variables with bound domains in the following example:

```
"power" : {
    "active" : { "var" {"lb": 0, "ub": 30.0} },
    "reactive" : { "var" {"lb": -14.0, "ub": 14.0} }
}
```

#### Voltage

Voltage is the difference in electric potential energy between two points per unit electric charge. We define the voltage phasor V as:

$$V = v \cdot e^{j\theta},\tag{4}$$

where v is the voltage magnitude, and  $\theta$  is the voltage phase angle. Table 4 connects the phasor components and units to their GRG representations.

GRG name	Symbol	Unit
voltage	V	
magnitude	v	kiloVolt (kV)
angle	$\theta$	Degrees

Table 4: Voltage: representation in the GRG format and units.

In the following example, magnitude and phase angle are defined as variables:

### 1.3 Limits

#### **Current Limits**

Transmission lines (see section AC Line) and transformers (see section Transformers) have limited current-carrying capacity, described as ranges of current values  $[I^{min}, I^{max})$  that may be sustained for a duration d.

A current limit is represented in GRG format according to Table 5.

GRG name	Symbol	Unit
min	$I^{\min}$	Ampere (A)
max	$I^{\max}$	Ampere (A)
duration	$\mid d \mid$	Seconds (sec)

Table 5: Current Limits: representation in the GRG format and units.

A current limit object is expressed as a *table* whose *arguments* are duration, min, max, and report. The report argument is a boolean field indicating whether the status of the branch should be signaled to the operator ('on') or not ('off').

```
— GRG schema: current_limits —
"current_limits": {
    "type" : "object",
    "required": ["position", "steps"],
    "additionalProperties": false,
    "properties": {
        "arguments":
            "type" : "array",
            "items": [
                {"enum":["duration"]}, {"enum":["min"]}, {"enum":["max"]}, {"enum":["report"]}
             1,
             "minItems": 4, "maxItems": 4, "additionalItems": "false"
         "values": {
             "type" : "array",
             "items": [
                 "type": "array",
                 "items": [
                     {"$ref": "#/values/extended_number"},
                     {"$ref": "#/values/extended_number"},
                     ("$ref": "#/values/extended_number"),
                     {"enum": ["on", "off"]}
                 "minItems": 4, "maxItems": 4, "additionalItems": "false"
          "minItemes": 1
       }
    }
```

An example of current limits is provided below. The branch can (1) carry up to 563 A indefinitely, or (2) carry between 563 A and 746 A indefinitely, but with a signal to the system operators, or (3) carry current in excess of 746 A for at most 6300 seconds before tripping the branch.

#### **Thermal Limits**

Transmission line and transformer limits can also be described in terms of power  $[P^{\min}, P^{\max})$  that may be safely carried for a given duration d. The GRG representation of a thermal limit is provided in Table 6.

GRG name	Symbol	Unit
min	$S^{\min}$	MegaWatt (MW)
max	$S^{\max}$	MegaWatt (MW)
duration	d	Seconds (sec)

Table 6: Thermal Limits: representation in the GRG format and units.

Similar to the current limit, a thermal limit object is expressed as a *table* whose *arguments* are: duration, min, max, and report. As with the current limit, report is a boolean indicating whether the status of the branch should be signaled to the operator ('on') or not ('off').

```
— GRG schema: thermal_limits -
"thermal_limits": {
    "type"
            : "object",
    "required": ["position", "steps"],
    "additionalProperties": false,
    "properties": {
        "arguments": {
            "type" : "array",
            "items": [
                {"enum":["duration"]}, {"enum":["min"]}, {"enum":["max"]}, {"enum":["report"]}
             ],
             "minItems": 4, "maxItems": 4, "additionalItems": "false"
         "values": {
             "type" : "array",
             "items": [
                 "type": "array",
                 "items": [
                     {"$ref": "#/values/extended_number"},
                      { "$ref": "#/values/extended_number" },
                     {"$ref": "#/values/extended_number"},
                     {"enum": ["on", "off"]}
                 "minItems": 4, "maxItems": 4, "additionalItems": "false"
             }
          "minItemes": 1
    }
```

# 2 Network Components

Having described the fundamental parameters of electrical devices like transmission lines, transformers, and generators, we now describe these components themselves.

### **AC** Line

An AC line connects network devices in two different points of the network. It has two sides: *side 1* is defined as the sending side, and *side 2* is defined as the receiving side. The current is positive when flowing from side 1 to side 2.

The currents  $I_1$  (at side 1) and  $I_2$  (at side 2) are given by:

$$I_1 = Y_1 \cdot V_1 + \frac{1}{Z}(V_1 - V_2) \tag{5}$$

$$I_2 = Y_2 \cdot V_2 + \frac{1}{Z}(V_1 - V_2),\tag{6}$$

where  $Y_1 = G_1 + jB_1$  and  $Y_2 = G_2 + jB_2$  are the admittances at sides 1 and 2, respectively, Z = R + jX is the line impedance, and  $V_1$  and  $V_2$  are the voltages at the connecting points. Figure 1 illustrates an AC line between nodes 1 and 2 (represented by the black points at the ends).

The power  $S_i$  at side i ( $i \in \{1, 2\}$ ) is given by:



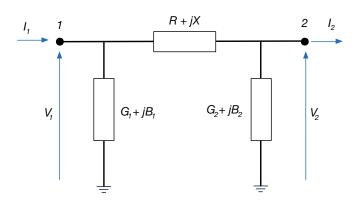


Figure 1: Illustration of an AC line.

Line current limits are monitored at both ends. The absolute value of current magnitude is compared to a sequence of current limits  $L_1 = L_{1_1}, \ldots, L_{1_n}$ , and  $L_2 = L_{2_1}, \ldots, L_{2_n}$ , where each  $L_{i_k}$   $(i \in \{1, 2\}, k \in \{1, \ldots, n\})$  is a current limit object, and for each  $L_{i_k}$ , (k > 1),  $I_{i_k}^{min} = I_{i_{k-1}}^{max}$ . Finally, the current limit durations are such that  $d_{i_1} = \infty$ , denoting that  $L_{i_1}$  is a permanent acceptable current limit.

```
__ GRG schema: ac_line _
"ac_line": {
   "type" : "object",
"required": ["type", "id", "link_1", "link_2", "voltage_level_1_id", "voltage_level_2_id",
                 "shunt_1", "shunt_2", "impedance", "current_limits_1", "current_limits_2"],
    "properties":
        "type"
                             : {"enum": ["ac_line"]},
                             : {"type": "string"},
        "description"
                             : {"type": "string"},
        "link_1"
                             : {"type": "string"},
                             : {"type": "string"},
        "voltage_level_1_id": {"type": "string"},
        "voltage_level_2_id": {"type": "string"},
        "shunt_1"
                            : {"$ref": "#/electrical_values/admittance"},
        "shunt 2"
                            : {"$ref": "#/electrical values/admittance"},
        "impedance"
                             : {"$ref": "#/electrical_values/impedance"},
                            : {"$ref": "#/limits/current_limits"},
        "current_limits_1"
        "current_limits_2"
                            : {"$ref": "#/limits/current_limits"},
        "thermal_limits_1" : {"$ref": "#/limits/thermal_limits"},
        "thermal_limits_2"
                             : {"$ref": "#/limits/thermal_limits"}
```

In the AC line GRG schema, type identifies the type of the object (i.e., an AC line), id is an unique identifier for the network component, and description is an optional field which can be used to describe the component. The

fields link\_1 and link\_2 describe the identifiers of the connecting network elements at the side 1 and side 2, respectively, of the line. voltage\_level\_1\_id and voltage\_level\_2\_id describe the identifiers of the voltage levels connected by the line. shunt\_1 and shunt\_2 define the admittances  $Y_1$  and  $Y_2$  at sides 1 and 2,respectively. impedance defines the impedance Z of the line. current\_limits\_1 and current\_limits\_2 describe collections of current limits associated to sides 1 and 2 of the line. Finally, thermal\_limits\_1 and thermal\_limits\_2 describe collections of thermal limits associated to sides 1 and 2 of the line. These last components are optional. A summary of these AC line components is provided in Table 7.

GRG name	symbol	unit
link_1	side 1	
link_2	side 2	
impedance→resistance	R	Ohm $(\Omega)$
impedance→reactance	X	Ohm $(\Omega)$
shunt_1→conductance	$G_1$	Siemens (S)
shunt_1→susceptance	$B_1$	Siemens (S)
shunt_2→conductance	$G_2$	Siemens (S)
shunt_2→susceptance	$B_2$	Siemens (S)
<pre>current_limits_1→values[k][0]</pre>	$d_{1_k}$	Seconds (sec)
current_limits_1→values[k][1]	$I_{1_k}^{\min}$	Ampere (A)
current_limits_1→values[k][2]	$I_{1_k}^{\max}$	Ampere (A)
current_limits_2→values[k][0]	$d_{2_k}$	Seconds (sec)
current_limits_2→values[k][1]	$I_{2_k}^{\mathrm min}$	Ampere (A)
current_limits_2→values[k][2]	$I_{2_k}^{\mathrm{max}}$	Ampere (A)
thermal_limits_1→values[k][0]	$d_{1_k}$	Seconds (sec)
thermal_limits_1→values[k][1]	$S_{1_k}^{\min}$	MegaWatt (MW)
thermal_limits_1→values[k][2]	$S_{1_k}^{max}$	MegaWatt (MW)
thermal_limits_2 \rightarrow values[k][0]	$d_{2_k}$	Seconds (sec)
thermal_limits_2 \rightarrow values[k][1]	$S_{2_k}^{\min}$	MegaWatt (MW)
thermal_limits_2 \rightarrow values[k][2]	$S_{2_k}^{\max}$	MegaWatt (MW)

Table 7: AC line: representation in the GRG format and units.

An example of an AC line in GRG format is provided in Figure 2.

```
__ Example: AC Line
"line_ln1" : {
   "type"
                        : "line",
                       : "ln1",
   "id"
                        : "9",
   "link_1"
   "link_2"
                       : "3",
    "voltage_level_1_id": "vl1",
    "voltage_level_2_id": "vl2",
    "current_limits_1" : {
        "arguments": ["duration", "min", "max", "report"},
       "current_limits_2" : {
        "arguments": ["duration", "min", "max", "report"},
        "values" : [["Inf", 0, 563, "off"]]
   "impedance"
                 : {"reactance" : 6.52, "resistance" : 2.39},
                 : {"conductance" : 0, "susceptance" : 2.3e-05},
: {"conductance" : 0, "susceptance" : 2.3e-05}
    "shunt_1"
    "shunt_2"
```

Figure 2: An example of a GRG AC Line.

#### 2.1 Transformers

#### **Two Winding Transformer**

A two winding transformer connects devices located at two different voltage levels of the network. We denote these voltage levels  $VL_1$  and  $VL_2$ , and their associated nominal voltage values  $v_1^{\text{nom}}$  and  $v_2^{\text{nom}}$ .

Most transformers come equipped with taps on their winding to adjust either the voltage transformation or the reactive flow through the transformer. The transformer voltage magnitude ratio  $r_k$ , phase shift  $\delta_k$ , impedance  $Z_k$ , and admittance  $Y_k$  all depend on the tap k.

We define *side 1* as the high voltage side, and *side 2* as the low voltage side. The current is positive when flowing from 1 to 2. The currents at sides 1 and 2 are:

$$I_1 = \rho_k' \cdot \left( Y_k \cdot V_1' + \frac{1}{Z_k} (V_1' - V_2) \right) \tag{8}$$

$$I_2 = \frac{1}{Z_k} (V_2 - V_1'), \tag{9}$$

where  $Y_k = G_k + jB_k$  is the admittance at side 1 of the transformer on tap k,  $Z_k = R_k + jX_k$  is the impedance of the transformer on tap k,  $V_1$  and  $V_2$  are the voltages at the connecting buses in  $VL_1$  and  $VL_2$ , respectively.  $V'_1$  is defined as  $(\rho'_k \cdot V_1)$ , and  $\rho'_k$  is a complex ratio defined for the k-th tap as:

$$\rho_k' = \left( \left( \frac{V_2^{\text{nom}}}{V_1^{\text{nom}}} \right) r_k \right) \cdot e^{j\delta_k}, \tag{10}$$

where  $V_1^{\text{nom}}$  and  $V_2^{\text{nom}}$  denote nominal voltage magnitudes at sides 1 and 2 of the transformer, respectively. Figure 3 illustrates a two winding transformer, where the points labeled 1 and 2 represent sides 1 and 2 connected by the branch.

The power  $S_i$  at sides i ( $i \in \{1, 2\}$ ) is given by:

$$S_i = \bar{I}_i \cdot V_i \tag{11}$$

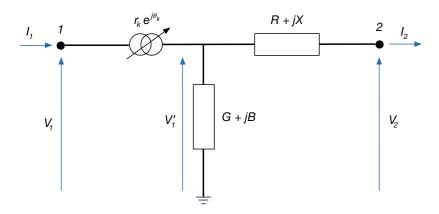


Figure 3: Illustration of a two winding transformer.

As with AC lines, transformers have current capacity limits, and the maximum absolute value of the current magnitude is monitored on both sides of the branch. Constraints are described through a sequence of current limits  $L_1 = L_{1_1}, \ldots, L_{1_n}$ , and  $L_2 = L_{2_1}, \ldots, L_{2_n}$ , where each  $L_{i_k}$  ( $i \in \{1,2\}, k \in \{1,\ldots,n\}$ ) is a current limit object, and for each  $L_{i_k}$ , (k > 1),  $I_{i_k}^{\min} = I_{i_{k-1}}^{\max}$ . Finally, the current limit durations are such that  $d_{i_1} = \infty$ , denoting that  $L_{i_1}$  is a permanent acceptable current limit.

```
"two_winding_transformer": {
    "type": "object",
    "required": ["type", "id", "link_1", "link_2", "voltage_level_1_id", "voltage_level_2_id",
    "tap_changer"],
```

```
"additionalProperties": false,
"properties": {
     "type"
                              : {"enum": ["two_winding_transformer"]},
    "id"
                            : {"type": "string"},
                            : {"type": "string"},
     "description"
     "link_1"
                             : {"type": "string"},
     "link_2"
                              : {"type": "string"},
     "voltage_level_1_id" : {"type": "string"},
     "voltage_level_2_id" : {"type": "string"},
    "current_limits_1" : {"$ref": "#/limits/current_limits"},
"current_limits_2" : {"$ref": "#/limits/current_limits"},
"thermal_limits_1" : {"$ref": "#/limits/thermal_limits"},
"thermal_limits_2" : {"$ref": "#/limits/thermal_limits"},
     "tap_changer": {
          "type": "object",
         "required"
                              : ["position", "impedance", "shunt", "tap_ratio", "angle_shift",
                                  "steps"],
         "additionalProperties": false,
         "properties": {
              "position"
                              : {"$ref": "#/values/abstract_value"},
              "impedance" : {"$ref": "#/electrical_values/impedance"},
                              : {"$ref": "#/electrical_values/admittance"},
              "tap_ratio" : {"$ref": "#/values/abstract_value"},
              "angle_shift": {"$ref": "#/values/abstract_value"},
                              : {"$ref": "#/values/table"}
              "steps"
    }
}
```

In the two winding transformer GRG schema, type identifies the type of the object (i.e., a two winding transformer), id is an unique identifier for the network component, and description is an optional field which can be used to describe the component. The fields link\_1 and link\_2 identify the connecting network elements at sides 1 and side 2 of the transformer; voltage\_level\_1\_id and voltage\_level\_2\_id describe the identifiers of the voltage levels connected by the branch. current\_limits\_1 and current\_limits\_2 describe collections of current limits associated to sides 1 and 2 of the line. The optional thermal\_limits\_1 and thermal\_limits\_2 describe collections of thermal limits associated to sides 1 and 2 of the line. Finally, tap\_changer describes the transformer taps. The position field describes the index of the tap step on which the transformer is positioned, and the steps is a table object describing the possible tuple assignments for the position index, the impedance (impedance), the admittance (shunt), the tap magnitude (tap\_ratio) and phase shift (angle\_shift) of the transformer's tap.

A summary of the two winding transformer components is provided in Table 8, and an example is provided in Figure 4.

#### Three winding Transformer

A three winding transformer connects devices located at three different voltage levels of the network. We denote these voltage levels  $VL_1$ ,  $VL_2$ , and  $VL_3$  and their associated nominal voltage values as  $v_1^{\text{nom}}$ ,  $v_2^{\text{nom}}$ , and  $v_3^{\text{nom}}$ , respectively.

We define *Side 1* as the high voltage side, *side 2* as the medium voltage side, and *side 3* as the low voltage side. The current is positive when flowing from 1 to 2 or 3.

The current at sides 1, 2, and 3 is given, respectively by:

$$I_1 = Y_k \cdot V_m + \frac{1}{Z_1} (V_1 - V_m) \tag{12}$$

$$I_2 = \frac{1}{\rho_{2_k}} \cdot \frac{1}{Z_{2_k}} (V_2 - V_m) \tag{13}$$

$$I_3 = \frac{1}{\rho_{3_k}} \cdot \frac{1}{Z_{3_k}} (V_3 - V_m), \tag{14}$$

GRG name	symbol	unit
link_1	side 1	
link_2	side 2	
current_limits_1→values[k][0]	$d_{1_k}$	Seconds (sec)
current_limits_1→values[k][1]	$I_{1_k}^{\min}$	Ampere (A)
current_limits_1→values[k][2]	$I_{1_k}^{\max}$	Ampere (A)
current_limits_2→values[k][0]	$d_{2_k}$	Seconds (sec)
current_limits_2→values[k][1]	$I_{2_k}^{\min n}$	Ampere (A)
current_limits_2→values[k][2]	$I_{2_k}^{\max}$	Ampere (A)
thermal_limits_1→values[k][0]	$d_{1_k}$	Seconds (sec)
thermal_limits_1→values[k][1]	$S_{1_k}^{\min}$	MegaWatt (MW)
thermal_limits_1→values[k][2]	$S_{1_k}^{\max}$	MegaWatt (MW)
thermal_limits_2→values[k][0]	$d_{2_k}$	Seconds (sec)
thermal_limits_2→values[k][1]	$S_{2_k}^{\min}$	MegaWatt (MW)
thermal_limits_2 \rightarrow values[k][2]	$S_{2_k}^{max}$	MegaWatt (MW)
tap_changer→position	$\mid k \mid$	
tap_changer→impedance→resistance	$R_k$	Ohm $(\Omega)$
tap_changer→impedance→reactance	$X_k$	Ohm $(\Omega)$
tap_changer -> shunt -> conductance	$G_k$	Siemens (S)
tap_changer→shunt→susceptance	$B_k$	Siemens (S)
tap_changer→tap_ratio	$r_k$	per unit
tap_changer -> angle_shift	$\delta_k$	degrees

Table 8: Two winding transformer: representation in the GRG format and units.

where  $Y_k = G_k + jB_k$  is the admittance at side 1 of the transformer with tap k;  $Z_{2_k} = R_2 + jX_2$  and  $Z_{3_k} = R_3 + jX_3$ are the impedance values of sides 2 and 3 of the transformer with tap k;  $V_1$ ,  $V_2$ , and  $V_3$  are the voltages at the connecting buses;  $V_m$  is the voltage phasor in the star middle point;  $\rho_{2_k}$  and  $\rho_{3_k}$  are the complex ratios on sides 2 and 3 of the transformer, defined as:

$$\rho_{2_k}' = \left( \left( \frac{V_2^{\text{nom}}}{V_1^{\text{nom}}} \right) r_{2_k} \right) \cdot e^{j\delta_{2_k}} \tag{15}$$

$$\rho_{2_k}' = \left( \left( \frac{V_2^{\text{nom}}}{V_1^{\text{nom}}} \right) r_{2_k} \right) \cdot e^{j\delta_{2_k}}$$

$$\rho_{3_k}' = \left( \left( \frac{V_3^{\text{nom}}}{V_1^{\text{nom}}} \right) r_{3_k} \right) \cdot e^{j\delta_{3_k}},$$

$$(15)$$

corresponding to the k-th tap; and  $V_1^{\text{nom}}$ ,  $V_2^{\text{nom}}$ , and  $V_3^{\text{nom}}$  denote the nominal voltage magnitudes at sides 1, 2, and 3 of the transformer. Figure 5 provides an illustration of a three winding transformer.

The power  $S_i$  at sides i ( $i \in \{1, 2, 3\}$ ) is given by:

$$S_i = \bar{I}_i \cdot V_i \tag{17}$$

```
"three_winding_transformer": {
    "type": "object",
    "required": ["type", "id", "link_1", "link_2", "link_3", "voltage_level_1_id", "voltage_level_2_id", "voltage_level_3_id", "impedance_1", "shunt"],
    "additionalProperties": false,
    "properties": {
         "type"
                                : {"enum": ["three_winding_transformer"]},
         "id"
                               : {"type": "string"},
         "description" : {"type": "string"},
         "link_1"
                               : {"type": "string"},
         "link_2"
                               : {"type": "string"},
                               : {"type": "string"},
         "voltage_level_1_id": {"type": "string"},
         "voltage_level_2_id": {"type": "string"},
"voltage_level_3_id": {"type": "string"},
```

```
Example: Two Winding Transformer __
"two_winding_transformer_tr1" : {
    "type" : "two_winding_transformer",
    "id"
                        : "tr1",
    "link_1"
                        : "11",
                        : "3",
    "link_2"
    "voltage_level_1_id": "vl2",
    "voltage_level_2_id": "vl3",
    "current_limits_1" : {
        "arguments": ["duration", "min", "max", "report"],
        "values"
            ["Inf", 0,
                          1029,
                                 "off"],
            [1200, 1029, 1342,
                                 "off"],
                                 "off"],
            [300,
                    1342, 1790,
                    1790, "Inf", "off"]
            [60,
        1
    },
    "tap_changer"
                     : {
                     : {"var" : [0, 1, 2]},
        "position"
        "impedance"
                    : {"reactance": {"var": [ 60.1 ] }, "resistance": {"var": [ 1.512] }},
        "shunt"
                     "tap_ratio" : {"var": [0.988, 1.00, 1.011]},
        "angle_shift": {"var": [0]},
        "steps": {
            "arguments": ["@/tap_changer/position", "@/tap_changer/impedance",
                           "@/tap_changer/shunt", "@/tap_changer/tap_ratio", "@/tap_changer/angle_shift"],
            [0, {"reactance":60.1, "resistance":1.512}, {"conductance":0, "susceptance":0}, 0.988, 0],
            [1, {"reactance":60.1, "resistance":1.512}, {"conductance":0, "susceptance":0}, 1.0, 0], [2, {"reactance":60.1, "resistance":1.512}, {"conductance":0, "susceptance":0}, 1.011, 0]
        }
   }
```

Figure 4: An example of a GRG Two Winding Transformer.

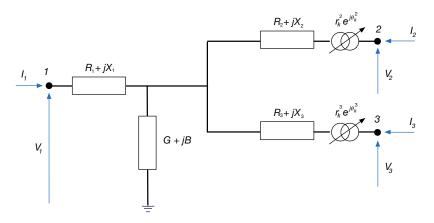


Figure 5: Illustration of a three winding transformer.

```
"current_limits_1" : {"$ref": "#/limits/current_limits"},
"current_limits_2" : {"$ref": "#/limits/current_limits"},
"current_limits_3" : {"$ref": "#/limits/current_limits"},
"thermal_limits_1" : {"$ref": "#/limits/thermal_limits"},
"thermal_limits_2" : {"$ref": "#/limits/thermal_limits"},
"thermal_limits_3" : {"$ref": "#/limits/thermal_limits"},
"shunt" : {"$ref": "#/electrical_values/admittance_rectangular"},
"impedance_1" : {"$ref": "#/electrical_values/impedance_rectangular"},
```

```
"tap changer": {
        "type": "object",
        "required": ["position", "steps"],
        "additionalProperties": false,
        "properties": {
            "position"
                           : {"$ref": "#/values/abstract_value"},
            "impedance_2" : {"$ref": "#/electrical_values/impedance"},
            "impedance_3" : {"$ref": "#/electrical_values/impedance"},
                          : {"$ref": "#/electrical_values/admittance"},
            "shunt_2"
            "shunt_3"
                           : {"$ref": "#/electrical_values/admittance"},
            "tap_ratio_2"
                           : {"$ref": "#/values/abstract_value"},
            "tap_ratio_3" : {"$ref": "#/values/abstract_value"},
            "angle_shift_2": {"$ref": "#/values/abstract_value"},
            "angle_shift_3": {"$ref": "#/values/abstract_value"},
                          : {"$ref" : "#/values/table"}
            "steps"
    }
}
```

In the three winding transformer GRG schema, type identifies the type of the object (i.e., a three windings transformer), id is an unique identifier for the network component, and description is an optional field which can be used to describe the component. The fields link\_1, link\_2, and link\_3 identify connecting network elements at sides 1, 2 and 3 of the transformer; voltage\_level\_1\_id, voltage\_level\_2\_id, and voltage\_level\_3\_id identify voltage levels connected to the branch; shunt defines the admittance Y; impedance\_1 defines the impedance  $Z_1$  of branch 1; and tap\_changer describes the transformer taps. position represents the index of the current tap step, and steps is a table with tuple assignments for position index, impedance\_2 and impedance\_3, tap\_ratio\_2 and tap\_ratio\_3, and phase shifts angle\_shift\_2 and angle\_shift\_3 corresponding to the  $k^{th}$  tap.

A summary of three windings transformer components is provided in Table 9, and Figure 6 provides an example.

### **Switch**

A switch is an electrical component that can interrupt the current in a circuit. There are two types of switches: *circuit breakers* and *disconnectors*. Circuit breakers can be switched on or off when they are energized, while disconnectors can be switched only when not energized. These are series devices with two sides denoted side 1 and side 2. Their operation satisfies the following:

$$s \cdot V_1 = s \cdot V_2,\tag{18}$$

where s is a binary variable denoting the switch status (1 for open, 0 for closed), and  $V_1$  and  $V_2$  are the voltages at sides 1 and 2 of the switch.

Figure 7 illustrates an open disconnector (a) and breaker (c), and a closed disconnector (b) and breaker (d).

```
GRG schema: switch -
"switch": {
   "type"
              : "object",
   "required": ["type", "subtype", "id", "status", "link_1", "link_2"],
   "additionalProperties": false,
    "properties": {
                    : {"enum": ["switch"]},
        "type"
                  : {"enum": ["breaker", "disconnector"]},
        "subtype"
        "description": {"type": "string"},
        "id"
                   : {"type": "string"},
        "status"
                    : {"$ref": "#/values/abstract_status"},
                     : {"type": "string"},
        "link_1"
                    : {"type": "string"}
        "link 2"
```

The field type identifies the type of the object (switch), subtype denotes whether the switch is a breaker or a disconnector, description is an optional field for describing the switch, id is a unique identifier, status denotes

GRG name	symbol	unit
link_1	side 1	
link_2	side 2	
impedance_1→resistance	$R_1$	Ohm $(\Omega)$
impedance_1→reactance	$X_1$	Ohm $(\Omega)$
<u>shunt</u> →conductance	G	Siemens (S)
<u>shunt</u> →susceptance	$\mid B \mid$	Siemens (S)
<pre>current_limits_1→values[k][0]</pre>	$d_{1_k}$	Seconds (sec)
<pre>current_limits_1→values[k][1]</pre>	$I_{1_k}^{\min}$	Ampere (A)
<pre>current_limits_1→values[k][2]</pre>	$I_{1_k}^{max}$	Ampere (A)
<pre>current_limits_2→values[k][0]</pre>	$d_{2_k}$	Seconds (sec)
<pre>current_limits_2→values[k][1]</pre>	$I_{2_k}^{\mathrm min}$	Ampere (A)
<pre>current_limits_2→values[k][2]</pre>	$I_{2_k}^{\max}$	Ampere (A)
<pre>current_limits_3→values[k][0]</pre>	$d_{3_k}$	Seconds (sec)
<pre>current_limits_3→values[k][1]</pre>	$I_{3_k}^{\mathrm min}$	Ampere (A)
<pre>current_limits_3→values[k][2]</pre>	$I_{3_k}^{\max}$	Ampere (A)
thermal_limits_1→values[k][0]	$d_{1_k}$	Seconds (sec)
thermal_limits_1→values[k][1]	$S_{1_k}^{\min}$	MegaWatt (MW)
thermal_limits_1→values[k][2]	$S_{1_k}^{max}$	MegaWatt (MW)
thermal_limits_2→values[k][0]	$d_{2_k}$	Seconds (sec)
thermal_limits_2→values[k][1]	$S_{2_k}^{\min}$	MegaWatt (MW)
thermal_limits_2→values[k][2]	$S_{2_k}^{\max}$	MegaWatt (MW)
thermal_limits_3→values[k][0]	$d_{3_k}$	Seconds (sec)
thermal_limits_3→values[k][1]	$S_{3_k}^{\min}$	MegaWatt (MW)
thermal_limits_3→values[k][2]	$S_{3_k}^{\max}$	MegaWatt (MW)
tap_changer - impedance_3 -> resistance	$\begin{bmatrix} S_{3_k}^{\text{max}} \\ R_k^3 \end{bmatrix}$	Ohm $(\Omega)$
tap_changer \rightarrow impedance_3 \rightarrow reactance	$X_k^3$	Ohm $(\Omega)$
tap_changer -> tap_ratio_3	$r_k^3$	per unit
tap_changer angle_shift_3	$egin{array}{c} X_k^3 \ r_k^3 \ \delta_k^3 \ \end{array}$	degrees

Table 9: Two windings transformer: representation in the GRG format and units.

whether the switch is open or closed, and  $link_1$  and  $link_2$  identify the connecting network elements at sides 1 and side 2 of the switch.

Table 10 summarizes switch components, and Figure 8 provides an example.

GRG name	symbol	unit
status	s	boolean

Table 10: Switch representation in GRG format and units.

## Bus

A bus is a set of equipment connected together. It could be a configured object or the result of a computation, depending of the context.

```
"bus": {
    "type" : "object",
    "required": ["type", "id", "voltage"],
    "additionalProperties": false,
    "properties": {
        "type" : {"enum": ["busbar"|"logical_bus"|"bus"]},
        "description": {"type": "string"},
        "id" : {"type": "string"},
```

```
: "three_windings_transformer",
    "type"
    "id"
                        : "tr1",
    "link_1"
                        : "2",
                        : "3",
    "link_2"
                        : "6",
    "link_3"
    "voltage_level_1_id": "vl1",
    "voltage_level_2_id": "vl2",
    "voltage_level_1_id": "vl3",
    "impedance_1"
                       : {"reactance" : 60.1, "resistance" : 1.512},
    "shunt"
                        : {"conductance" : 0, "susceptance" : 0},
    "tap_changer" : {
        "position"
                        : {"var" : [0]},
        "impedance_2"
                       : {"reactance": {"var": [ 60.1 ] }, "resistance": {"var": [ 1.512] }},
        "impedance_3"
                        : {"reactance": {"var": [ 60.1 ] }, "resistance": {"var": [ 1.512] }},
        "tap_ratio_2"
                        : {"var": [1.00]},
        "tap_ratio_3"
                        : {"var": [1.00]},
        "angle_shift_2" : {"var": [0]},
        "angle_shift_3" : {"var": [0]},
        "steps": {
            "arguments" : ["@tap_changer/position",
                           "@tap_changer/impedance_2", "@tap_changer/impedance_3", "@tap_changer/tap_ratio_2", "@tap_changer/tap_ratio_3",
                           "@tap_changer/angle_shift_2", "@tap_changer/angle_shift_3"],
            "values"
                        : [
            [0, {"reactance":60.1, "resistance":1.512}, {"reactance":60.1, "resistance":1.512},
                1.00, 1.00, 0, 0]
    }
```

Figure 6: An example of a GRG Three Windings Transformer.

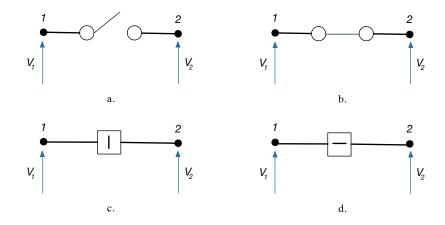


Figure 7: Illustration of an open (a) and close (b) disconnector, and an open (c) and close (d) breaker.

```
"link" : {"type": "string"}
    "voltage" : {"type" : "#/electrical_values/voltage"}
    "name" : {"type": "string"},
}
```

type identifies the type of the object. Depending on the network topology adopted, a bus can be represented as a busbar (node-breaker topology), logical bus (bus-breaker topology), or simply bus (bus-branch topology). description is an optional description field, and id is an unique identifier. The field link is active exclusively

```
"switch_vl1_br1" : {
    "type" : "switch",
    "subtype": "breaker",
    "id" : "br1",
    "link_1" : "10",
    "link_2" : "11",
    "status" : {"var" : ["off", "on"]}
}
```

Figure 8: An example of a GRG switch.

in the node-breaker and bus-breaker network topologies; it identifies the node at which the bus is connected. Finally, voltage refers to the bus voltage magnitude v and phase angle  $\theta$ , and and name denotes the bus name.

Table 11 tabulates the bus components, while Figure 9 contains an example of a bus in GRG format.

GRG name	symbol	unit
voltage→magnitude	v	kiloVolt (kV)
voltage→angle→lb	$\Theta^l$	Degrees
voltage→angle→ub	$\Theta^u$	Degrees

Table 11: Bus representation in GRG format and units.

```
"busbar_vll_bbrl" : {
    "type" : "busbar",
    "id" : "bbrl",
    "name" : "E",
    "link" : "0",
    "voltage" : {
        "angle" : {"var" : {"lb" : -30.0, "ub" : 30.0}},
        "magnitude" : {"var" : {"lb" : "-Inf", "ub" : "Inf"}}
}
```

Figure 9: An example of a GRG busbar.

### **Shunt**

A shunt capacitor or reactor is defined as an admittance:

$$I = -Y \cdot V$$
,

where Y = G + jB is the admittance, and V is the voltages at the connecting point. Figure 10 illustrates a shunt.

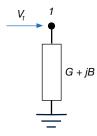


Figure 10: A shunt.

```
— GRG schema: shunt —
"shunt": {
    "type"
             : "object",
    "required": ["type", "id", "link", "shunt"],
    "additionalProperties": false,
    "properties": {
        "type"
                     : { "enum": ["shunt"] },
        "id"
                     : {"type": "string"},
        "description": {"type": "string"},
                    : {"type": "string"},
        "link"
                     : {"$ref": "#/electrical_values/admittance"}
        "shunt"
```

In the above schema, type identifies the type of the object (i.e., a shunt), id is a unique identifier, and description is an optional description field. The field link identifies the connecting network element (it can be either a node, if the network is in node-breaker topology or bus-breaker topology, or a bus, if the network is in a bus-branch topology). Finally, shunt defines the admittance Y.

Table 12 summarizes shunt components, while Figure 11 provides an example.

GRG name	symbol	unit
shunt→conductance	G	Siemens $(S)$
shunt→susceptance	B	Siemens $(S)$

Table 12: Shunt representation in the GRG format and units.

```
"shunt_vl1_s1": {
    "id" : s1
    "type": "shunt",
    "link": "7",
    "shunt": {"conductance": 0, "susceptance": 0.005039}
}
```

Figure 11: An example of a GRG shunt.

## Load

A Load consumes active power P and reactive power Q at its connection point, as illustrated in Figure 12.



Figure 12: A load.

```
"load": {
    "type": "object",
    "required": ["type", "id", "link", "demand"],
    "additionalProperties": false,
    "properties": {
        "type" : {"enum": ["load"]},
        "subtype" : {"enum": ["auxiliary", "undefined"]},
        "id" : {"type": "string"},
        "description": {"type": "string"},
```

In the load GRG schema, type identifies the type of the object (i.e., a load), subtype identifies the type of load: (auxiliary or undefined). The attribute id is an unique identifier, and description is an optional description field. The field link identifies the connecting network element (it can be either a node, if the network is in node-breaker topology or bus-breaker topology, or a bus, if the network is in a bus-branch topology). Finally, demand defines the power S consumed by the load.

Table 13 summarizes load components, while Figure 13 provides an example.

GRG name	symbol	unit
<u>demand</u> →active	P	MegaWatt (MW)
<u>demand</u> →reactive	Q	MegaVolt-Ampere Reactive (MVAR)

Table 13: Load representation in GRG format and units.

```
"load_vll_ldl" : {
    "type" : "load"
    "subtype": "undefined",
    "id" : "ldl",
    "link" : "7",
    "demand" : {
        "active" : {"var" : {"lb" : "-Inf", "ub" : "Inf"}},
        "reactive" : {"var" : {"lb" : "-Inf", "ub" : "Inf"}}
}
```

Figure 13: An example of a GRG load.

### Generator

A generator produces active power (P) and reactive power (Q), and supports voltage (V). Its output is limited according to a PQ-curve, which specifies minimum and maximum reactive power values for every active power value. More formally, a PQ-curve is a sequence of tuples:  $\langle P_k, Q_k^{\min}, Q_k^{\max} \rangle_{k=1}^n$  (with n>0) such that for each  $k< n, P_k < P_{k+1}$ , and  $Q_k^{\min} \leq Q_k^{\max}$ .

Figure 14 illustrates a generator (a) and feasible PQ region (shaded gray area) of its PQ-curve.

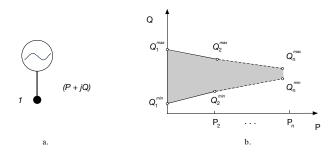


Figure 14: Illustration of a generator (a) and its PQ-curve (b).

```
"generator": {
    "type" : "object",
```

```
"required": ["type", "id", "link", "output"],
"additionalProperties": false,
"properties": {
    "type" : {"enum": ["generator"]},
    "subtype": {"enum": ["hydro", "wind", "thermal", "other", "nuclear", "solar"]},
           : {"type": "string"},
    "link"
            : {"type": "string"},
    "output" : {"$ref": "#/electrical_values/power"},
    "PQ_curve"
        "type": "object",
        "required": ["arguments", "values"],
        "additionalProperties": false,
        "properties": {
            "arguments": {
                "type": "array",
                "items": [
                    {"enum": ["active"]}, {"enum": ["reactive_lb"]}, {"enum": ["reactive_ub"]}
                ],
                "minItems": 3, "maxItems": 3, "additionalItems": false
            },
            "values": {
                "type": "array",
                "items": [
                {
                    "type": "array",
                    items": [
                        {"$ref": "#/values/extended_number"},
                        {"$ref": "#/values/extended_number"},
                        {"$ref": "#/values/extended_number"}
                    ],
                    "minItems": 3, "maxItems": 3, "additionalItems": false
                ],
                "minItemes": 1
            }
       }
   }
}
```

In the generator GRG schema, type identifies the type of the object (i.e., a generator), subtype identifies the type of generator, id is a unique identifier, and description is an optional description field. link identifies the connecting network element (a node if the network is in node-breaker topology or bus-breaker topology, or a bus if the network is in a bus-branch topology). The output field defines the power S produced by the generator. Finally, the PQ-curve is a table of active and reactive bounds, defining the feasible operating region.

Table 14 summarizes generator components, and Figure 15 provides an example.

GRG name	symbol	unit
output → active	P	MegaWatt (MW)
output→reactive	Q	MegaVolt-Ampere Reactive (MVAR)
PQ_curve $\rightarrow$ values[k][0]	$P_k$	MegaWatt (MW)
$PQ\_curve \rightarrow values[k][1]$	$Q_k^{\min}$	MegaVolt-Ampere Reactive (MVAR)
PQ_curve $\rightarrow$ values[k][2]	$Q_k^{\max}$	MegaVolt-Ampere Reactive (MVAR)

Table 14: Generator: representation in the GRG format and units.

# **Synchronous Condenser**

A synchronous condenser is a spinning machine that can compensate lagging current by either generating or absorbing reactive power.

Figure 15: An example of a GRG generator.

In the synchronous\_condenser GRG schema, type identifies the type of the object (i.e., a synchronous condenser), the attribute id is a unique identifier, and description is an optional description field. link identifies the connecting network element (a node if the network is in node-breaker topology or bus-breaker topology, or a bus if the network is in a bus-branch topology). output defines the reactive power (reactive) produced or absorbed by the condenser.

Table 15 summarizes synchronous condenser components, and Figure 16 provides an example.

GRG name	symbol	unit
output → reactive	Q	MegaVolt-Ampere Reactive (MVAR)

Table 15: Synchronous condenser representation in GRG format and units.

```
Example: Synchronous Condenser

"synchronous_condenser_v14_y1" : {
    "type" : "synchronous_condenser",
    "id" : "y1",
    "link" : "2",
    "output": {
        "reactive" : {"var" : {"lb" : 0, "ub" : 14.53}}
    }
}
```

Figure 16: An example of a GRG synchronous condenser.

# 3 Assignment and Mappings

An *assignment* is a JSON object which contains a list of value assignments for some network component. Assignments may be used to define a particular instance of a network, for example, by assigning values to a set of variables. The assignment schema is as follows.

The JSON reference refers to any of the components described in section 2, and the patternProperties specifies that zero or more component assignments can be specified.

We say that a network component field is *assigned* if its value is specified as an object in an assignment. An assignment example is shown in Figure 17.

Figure 17: An example of a GRG assignment.

A *mapping* is a set of assignments. It can be used to to define a particular instantiation of a network, or a desired network state, e.g., target values. Its schema is as follows.

```
"mappings": {
    "type": "object",
    "patternProperties": {
        "*": { "$ref": "#/assignment"}
    }
}
```

The patternProperties field specifies that zero or more set of component assignments can be specified. For each of these sets, an arbitrary number of component assignments can be specified. Figure 18 contains an example.

### 4 Networks

A GRG network is a collection of network components, along with a list of component assignments. When a network component is assigned, its value in the *assignments* block of the GRG document supersedes its value in the *network* block. The GRG schema for a network is shown below.

```
Example: Mappings
"mappings": {
    "target_points": {
        "#/network/components/substation_1/substation_components/voltage_level_1/
          voltage_level_components/generator_vl1_gn1": {
              "output" : {"active" : 0, "reactive" : 0}
         "#/network/components/substation_1/substation_components/voltage_level_1/
          voltage_level_components/load_vl1_ld1": {
             "demand" : {"active" : 4.1123, "reactive" : -1.8729}
    "starting_points": {
        "#/network/components/substation_1/substation_components/voltage_level_1/
          voltage_level_components/generator_vl1_gn1": {
              "output" : {"active" : 2.23, "reactive" : 0}
         }.
         "#/network/components/substation_1/substation_components/voltage_level_1/
          voltage_level_components/load_vl1_ld1": {
             "demand" : {"active" : 4.1123, "reactive" : -1.8729}
    }
```

Figure 18: An example of GRG mappings.

```
"network": {
    "type": "object",
    "required": ["id", "type", "subtype", "per_unit", "components"],
    "properties": {
        "id": {"type": "string"},
        "type": {"enum": ["network"]},
        "subtype": {"enum": ["node_breaker", "bus_breaker", "bus_branch"]},
        "per_unit": {"type": "boolean"},
        "description": {"type": "string"},
        "components": {"type": "string"},
        "assignments": {"$ref": "#/network/network_components"}
        "assignments": {"$ref": "#/assignments"},
    },
    "additionalProperties": false
}
```

The attribute type identifies the type of the object (i.e., a network). subtype indicates topology type, which defines the level of detail in descriptions of connections between components; description is an optional description field, and per\_unit indicates whether network component values are expressed in per unit or nominal value.

A network is organized as a set of substations connected via transmission lines. Together these comprise the network\_components block, as shown in the following schema fragment:

#### **Substation**

A *substation* is a collection of equipment located at a the same physical site and belonging to one Transmission System Operator (TSO). It is composed of several *voltage levels* and *transformers*. Its schema is as follows.

```
GRG schema: substation —
"substation": {
   "type" : "object",
    "required": ["type", "id", "substation_components"],
    "properties": {
        "type"
                    : {"enum": ["substation"]},
        "description": {"type": "string"},
               : {"type": "string"},
                    : {"type": "string"},
        "country"
                    : {"type": "string"},
        "TSO"
        "substation_components": {
            "patternProperties": {
                ".*": {
                    "oneOf": [
                       {"$ref": "#/network_components/voltage_level"},
                        { "$ref": "#/network_components/two_windings_transformer"}
                        { "$ref": "#/network_components/three_windings_transformer"}
               }
           }
       }
   }
```

The attribute type identifies the type of the object (i.e., a substation). The attributes country and TSO indicate the country in which the substation is located, along with its Transmission System Operator. Substation components are listed in the creatively-named substation\_components object.

# **Voltage Level**

A voltage level is a collection of equipment located in the same substation at the same nominal voltage value. Its schema is as follows.

```
____ GRG schema: voltage_level __
"voltage_level": {
    "type" : "object",
    "required": ["type", "id", "voltage"],
    "properties": {
                     : {"enum": ["voltage_level"]},
        "description": {"type": "string"},
                     : {"type": "string"},
        "voltage": {
            "type"
                          : "object",
            "required" : ["nominal_value", "upper_limit", "lower_limit"],
            "additionalProperties": false,
            "properties": {
                 "nominal_value": {"type": "number"},
                 "upper_limit" : {"type": "number"},
"lower_limit" : {"type": "number"}
        "voltage_level_components": {
            "oneOf": [
                 {"$ref": "#/network_components/bus"},
                 {"$ref": "#/network_components/shunt"},
                 {"$ref": "#/network_components/generator"},
                 { "$ref": "#/network_components/synchronous_condenser"}
                 {"$ref": "#/network_components/load"},
                 {"$ref": "#/network_components/switch"}
            1
        }
    }
```

The attribute type identifies the type of the object (i.e., a voltage\_level). voltage contains the nominal voltage  $V_{nom}$  along with voltage limits  $[V^L, V^U]$  for all components contained in the voltage level. The voltage level components are listed in voltage\_components.

Table 16 describes the voltage level element.

GRG name	Parameter	unit
voltage->nominal_value	$V_{nom}$	KiloVolt (KV)
voltage→lower_limit	$V^L$	KiloVolt (KV)
voltage→upper_limit	$V^U$	KiloVolt (KV)

Table 16: Voltage Level description.

# 5 Market

A market GRG block attaches operational costs to a network component. A cost JSON block represents a cost model for a component.

```
____ voltage_level definition ___
"market": {
    "type"
              : "object",
    "required": ["costs"],
    "properties": {
        "costs": {
            "patternProperties": {
                "#/.*": {
                "type": "object",
                "properties": {
                     "type": {"enum": ["polynomial"]},
                    "required": ["arguments", "coefficient"],
                    "arguments": {
                                  : "array",
                         "type"
                         "items"
                                  : {"$ref": "#/grg_pointer"},
                         "minItems": 1, "uniqueItems": true
                     "coefficients": {
                         "type" : "array":
                         "items": {
                             "type" : "array",
                             "items": {{"type": "#/abstract_value"}},
                             "minItems": 1
                         "minItems": 1
                    }
                }
           }
        }
    }
```

Each item in the costs block is named with a pointer to its associated network element. The arguments are pointers to network elements, and coefficient items define the associated cost polynomial. The i-th row of a coefficients array identifies the coefficients,  $a_{n-1}, \ldots, a_0$ , associated with the i-th  $x_i$  argument in the arguments array, generating the polynomial:

$$a_{n-1} x_i^{n-1} + \ldots + a_1 x_i + a_0$$

# 6 Units

A units object details the units adopted for each physical quantity. These may differ from unit associated to the description of various components in the previous sections. The JSON schema of units is defined below.

```
GRG schema: units —
"units": {
    "type": "object",
    "required": ["voltage", "current", "angle", "reactive_power", "active_power",
                  "impedance","resistance", "reactance", "conductance", "susceptance", "time"],
    "properties": {
        "voltage": {"enum": ["volt", "kilo_volt", "mega_volt", "pu"]},
        "current": {"enum": ["ampere", "kilo_ampere", "mega_ampere", "pu"]},
"angle" : {"enum": ["degree", "radian"]},
        "active_power": {"enum": ["watt", "kilo_watt", "mega_watt", "pu"]},
        "reactive_power": {"enum": ["volt_ampere_reactive", "mega_volt_ampre_reactive", "pu"]},
        "impedance": {"enum": ["ohm", "pu"]},
        "resistance": {"enum": ["ohm", "pu"]},
        "reactance": {"enum": ["ohm", "pu"]},
        "conductance": {"enum": ["siemens", "pu"]},
        "susceptance": {"enum": ["siemens", "pu"]},
        "time": {"enum": ["seconds", "minutes", "hours", "days", "months", "years"]}
    }
```

### 7 GRG Document

A *GRG document* is defined as a collection of JSON blocks, and includes a network block, a mapping block, a market block, and a units block. Its schema is as follows.

```
GRG schema: GRG document

"type": "object",
    "required": ["grid_version", "network", "units", "market", "mappings"],
    "additionalProperties": false,

"properties": {
        "grid_version": {"type": "string"},
        "description": {"type": "string"},
        "network": {"$ref": "#/network"},
        "mappings": {"$ref": "#/mappings"},
        "market": {"$ref": "#/market"},
        "units": {"$ref": "#/units"}
}
```

# 8 Network Topology

A network may be represented in one of three different topologies, from finer to coarser level of detail: node-breaker, bus-breaker, or bus-branch. Table 17 summarizes these representations, indicating which ones capture the voltage level topology (i.e., whether all the elements and their connections are physical ones) or not (i.e., merely logical connections); which switch types are captured, and the representation of buses. We will now discuss each representation in detail.

### 8.1 Node-Breaker Topology

A node-breaker topology contains the highest level of detail for a network. All components are physical elements, including busbar sections, breakers, and disconnectors. In this topology, a voltage level is a collection of network

	Node-breaker	Bus-breaker	Bus-branch
Topology	yes	yes	no
Breakers	yes	yes	no
Disconnectors	yes	no	no
Bus Type	busbar	logical bus	bus

Table 17: Network Topologies.

components and connection *nodes*. Nodes are logical connection points labeled with values in  $\mathbb{N} \cup \{0\}$ . Each component is directly connected to one node (if it is a bus, shunt, generator, or load), or to two nodes (if it is an AC line, transformer, or switch). The connection of a network component to a node is described in its link attribute (or link\_1 and link\_2 attributes for a connector). The set of nodes in a voltage level is described implicitly: It is the union of link values of all network components in that voltage level. Figure 19 (a) shows a voltage level in the node-breaker topology where breakers are illustrated as white squares, and disconnectors as pairs of white circles.

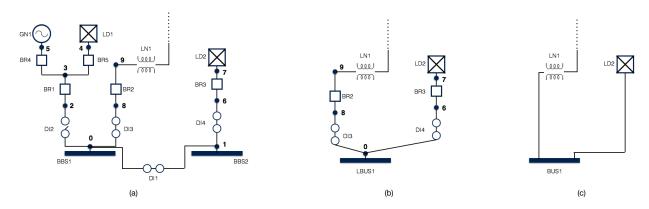


Figure 19: Illustration of a voltage level in node-breaker (a), bus-breaker (b), and bus-branch (c) topologies.

#### 8.2 Bus-Breaker Topology

A network in bus-breaker form also represents a voltage level as a collection of components connected through nodes. However, the bus-breaker representation contains no disconnectors. Algorithm 1 describes the procedure for constructing a bus-breaker topology from a network in node-breaker form. The algorithm accepts a node-breaker network  $\mathcal{N}$  as input. Lines (1–2) call the procedure Transform-VoltageLevel for each voltage level  $\mathcal{V}$  in the network  $\mathcal{N}$ . The result of this operation is to (1) merge busbars of the voltage level which are connected by closed disconnectors, (2) remove all disconnectors from the voltage level, and (3) remove components that have no path to a logical bus. Lines (6–12) show greater detail for the removal process of a set of disconnectors  $\mathcal{D}_{\mathcal{V}}$  of the voltage level  $\mathcal{V}$ . A disconnector is removed from the network by linking all voltage level components attached to its node on side 2 (link\_2) to its node on side 1 (link\_1) (lines 9–11). This operation may result in multiple busbars connected to the same node. In Figure 19 (a), for instance, busbars BBS1 and BBS2 will be connected to node 0 when disconnector DI1 is removed. The effect of the loop in lines 13–15 is to merge such busbar sets into single logical buses. This is done by preserving one busbar of the set B, changing its type to a logical bus, and removing all other busbars in B.

The effect of executing lines 16–18 is to remove all components of the voltage level for which there is no path through closed switches or non-assigned breakers to a logical bus of the voltage level. For instance, in Figure 19 (a), the breakers BR1, BR4, B5, the generator GN1, and the load LD1 have no closed path to a voltage level bus, since disconnector DI2 is open. Thus, these components are removed from the voltage level. The result of this operation is illustrated in Figure 19 (b).

Finally, in lines (3–5) of Algorithm 1, all lines and transformers (connectors) of the network are processed. As was done for voltage levels, a connector is removed if it has no closed path to logical buses on both sides.

Figure 19 (b) illustrates an example voltage level in the bus-breaker topology obtained from the node-breaker topology of Figure 19 (a).

#### **Algorithm 1:** Node-Breaker to Bus-Breaker( $\mathcal{N}$ )

### **Procedure** Transform-VoltageLevel(V)

```
6 foreach disconnectors d \in \mathcal{D}_{\mathcal{V}} do
          n_1 \leftarrow d[link_1];
          n_2 \leftarrow d[link\_2];
 8
         foreach component c \in \mathcal{V} s.t. c is connected to n_2 do
               Let link be link_i if c is a switch, line, or transformer, and link_i \neq n_2;
10
               c[link] \leftarrow n_1;
11
         Remove d from \mathcal{V};
12
   foreach busbar b \in \mathcal{B}_{\mathcal{V}} do
         Let B = \{b' \in \mathcal{B}_{\mathcal{V}} : b'[\mathit{link}] = b[\mathit{link}]\};
14
         Remove all b' \in B \setminus \{b\};
15
    foreach component c \in \mathcal{V} do
16
          if \not\exists path through close switches from c to some b \in \mathcal{B}_{\mathcal{V}} then
17
               Remove c from \mathcal{V};
18
```

# 8.3 Bus-Branch Topology

A network in bus-branch form differs from one in a node- or bus-breaker form in that switches are not represented, and all network components are directly connected to a bus. Thus, the bus-branch topology has no concept of connection nodes.

A bus-branch topology can be obtained from a node- or a bus-breaker topology by applying a variation of Algorithm 1. Rather than processing disconnectors (line 6), all switches of the voltage level are processed. Finally, after the algorithm is executed, the link attribute of each generator, load, and shunt, and the link\_1 and link\_2 attributes of lines and transformers are updated to take the ID of the bus to which they are connected.

Figure 19 (c) illustrates an example voltage level in the bus-branch topology, obtained from the bus-breaker topology of Figure 19 (b).

### 9 Per-Unit Transformations

This section describes all per-unit transformations for network components.

#### **AC** Line

The per-unit transformation of an AC line (see also Figure 1) is shown in Table 18. The nominal current magnitude  $I_{nom}$  of the AC line is defined as:

$$I_{\text{nom}} = \frac{S_{\text{nom}}}{V_{\text{nom}}},\tag{19}$$

where  $V_{nom}$  is voltage magnitude on either side of the line, and  $S_{nom}$  is the nominal power magnitude of the network. The nominal impedance of the AC line is defined as:

$$Z_{\text{nom}} = \frac{(V_{\text{nom}})^2}{S_{\text{nom}}} \tag{20}$$

GRG name	Parameter	Per-unit transformation
impedance→resistance	R	$\frac{1}{Z_{n \rho m}} \cdot R$
impedance→reactance	X	$\frac{1}{Z_{nom}} \cdot X$
shunt_1→conductance	$G_1$	$Z_{\mathrm nom} \cdot G_1$
shunt_1→susceptance	$B_1$	$Z_{\mathrm nom}\cdot B_1$
shunt_2→conductance	$G_2$	$Z_{\mathrm nom}\cdot G_2$
shunt_2→susceptance	$B_2$	$Z_{nom}\cdot B_2$
current_limits_1→values[k][1]	$S_{1_k}^{\min}$	$rac{1}{I_{{ m no}m}} \cdot I_{1k}^{{ m min}}$
current_limits_1 \rightarrow values[k][2]	$S_{1_k}^{\max}$	$rac{1}{I_{ ext{n}_{qm}}} \cdot I_{1_{k}}^{ ext{m}ax}$
<pre>current_limits_2 -&gt; values[k][1]</pre>	$S_{2_k}^{\min}$	$rac{1}{I_{nom}} \cdot I_{2_k}^{\min}$
<pre>current_limits_2 \rightarrow values[k][2]</pre>	$S_{2_k}^{\max}$	$rac{1}{I_{ exttt{n}_{om}}} \cdot I_{2_k}^{ exttt{max}}$
thermal_limits_1 \rightarrow values[k][1]	$S_{1_k}^{min}$	$rac{S_{ ext{n} ho m}^{m}}{S_{ ext{n} ho m}} \cdot S_{1k}^{ ext{min}}$
thermal_limits_1 \rightarrow values[k][2]	$S_{1_k}^{\max}$	$rac{1}{S_{ ext{n}qm}} \cdot S_{1_k}^{ ext{max}}$
thermal_limits_2 \rightarrow values[k][1]	$S_{2_k}^{min}$	$rac{S_{ ext{n} ho m}^{m}}{S_{ ext{n} ho m}} \cdot S_{2_{k}}^{ ext{min}}$
thermal_limits_2 \rightarrow values[k][2]	$S_{2_k}^{\mathrm max}$	$rac{1}{S_{\mathtt{n}om}} \cdot S_{2_k}^{\mathtt{m}ax}$

Table 18: AC line per-unit transformations.

### Two windings transformer

For a two windings transformer (see Figure 3), the per-unit transformation is defined in Table 19. The nominal current magnitudes  $I_{nom}^1$  on side 1 and  $I_{nom}^2$  on side 2 are defined as:

$$I_{\text{nom}}^1 = \frac{S_{\text{nom}}}{V_{\text{nom}}^1} \tag{21}$$

$$I_{\text{n}om}^2 = \frac{S_{\text{n}om}}{V_{\text{n}om}^2},\tag{22}$$

where  $V_{\mathrm{n}om}^1$  and  $V_{\mathrm{n}om}^2$  are the voltage magnitudes on sides 1 and 2 of the transformer. The nominal impedance magnitude on side 2 (low voltage side) of the transformer is defined as:

$$Z_{\text{nom}} = \frac{(V_{\text{nom}}^2)^2}{S_{\text{nom}}} \tag{23}$$

#### Three windings transformer

For a three windings transformer (see Figure 5), the per-unit transformation is defined in Table 20. The nominal impedance magnitude on side 1 (high voltage side) of the transformer is defined as:

$$Z_{\text{nom}} = \frac{(V_{\text{nom}}^1)^2}{S_{\text{nom}}},\tag{24}$$

where  $V_{\mathrm nom}^1, V_{\mathrm nom}^2$ , and  $V_{\mathrm nom}^3$  are voltage magnitudes at sides 1, 2, and 3 of the transformer.

### Bus

The per-unit transformation for a bus is defined in Table 21, where  $V_{nom}$  is voltage magnitude at the voltage level of the bus. If the network is in *flat* representation, then the voltage component of the bus is transformed in per-unit according to the description provided in the last three rows of Table 21.

### Shunt

For a shunt (see Figure 10), the per-unit transformation is defined in Table 22. The nominal impedance of the AC line is defined as:

$$Z_{\text{nom}} = \frac{(V_{\text{nom}})^2}{S_{\text{nom}}} \tag{25}$$

GRG name	Parameter	Per-unit transformation
tap_changer impedance resistance	$R_k$	$\frac{1}{Z_{nom}} \cdot R_k$
tap_changer→impedance→reactance	$X_k$	$\frac{1}{Z_{nom}} \cdot X_k$
tap_changer -> admittance -> conductance	$G_k$	$Z_{\mathrm nom} \cdot G_k$
tap_changer -> admittance -> susceptance	$B_k$	$Z_{nom} \cdot B_k$
tap_changer -> tap_ratio	$r_k$	$r_k$
tap_changer→angle_shift	$\delta_k$	$\frac{\pi}{1,80} \cdot \delta_k$
$tap\_changer \rightarrow steps \rightarrow values[k][1] \rightarrow impedance \rightarrow resistance$	$R_k$	$\frac{1}{Z_{n \rho m}} \cdot R_k$
$tap\_changer \rightarrow steps \rightarrow values[k][1] \rightarrow impedance \rightarrow reactance$	$X_k$	$\frac{1}{Z_{nom}} \cdot X_k$
$tap\_changer \rightarrow steps \rightarrow values[k][2] \rightarrow admittance \rightarrow conductance$	$G_k$	$Z_{\mathrm nom} \cdot G_k$
$tap\_changer \rightarrow steps \rightarrow values[k][2] \rightarrow admittance \rightarrow susceptance$	$B_k$	$Z_{nom} \cdot B_k$
tap_changer→steps→values[k][3]→tap_ratio	$r_k$	$r_k$
$tap\_changer \rightarrow steps \rightarrow values[k][4] \rightarrow angle\_shift$	$\delta_k$	$\frac{\pi}{180} \cdot \delta_k$
current_limits_1→values[k][1]	$I_{1_k}^{\mathrm min}$	$\frac{1}{I_{nom}} \cdot I_{1_k}^{\min}$
current_limits_1→values[k][2]	$I_{1_k}^{\mathrm max}$	$\frac{1}{I_{n_Qm}} \cdot I_{1_k}^{\max}$
current_limits_2→values[k][1]	$I_{2_k}^{\mathrm min}$	$rac{1}{I_{nom}} \cdot I_{2_k}^{min}$
current_limits_2→values[k][2]	$I_{2_k}^{\max}$	$rac{I_{n_Qm}}{I_{n_Qm}} \cdot I_{2_k}^{max}$
thermal_limits_1 \rightarrow values[k][1]	$S_{1_k}^{\min}$	$rac{1}{S_{n ho m}} \cdot S_{1k}^{\min}$
thermal_limits_1 \rightarrow values[k][2]	$S_{1_k}^{max}$	$rac{1}{S_{ ext{n}qm}} \cdot S_{1k}^{ ext{max}}$
thermal_limits_2 \rightarrow values[k][1]	$S_{2_k}^{-\kappa}$	$rac{1}{S_{n ho m}} \cdot S_{2_k}^{min}$
thermal_limits_2 \rightarrow values[k][2]	$S_{2_k}^{\overline{m}ax}$	$rac{1}{S_{\mathtt{n}om}} \cdot S_{2_k}^{\mathtt{m}ax}$

Table 19: Two windings transformer per-unit transformations.

#### Load

For a load, the per-unit transformation is defined in Table 23.

### Generator

For a generator, the per-unit transformation is defined in Table 24.

# **Synchronous Condenser**

For a synchronous condenser, the per-unit transformation is defined in Table 25.

# **Voltage Level**

Each voltage component of a voltage level is transformed according to Table 26.

GRG name	Parameter	Per-unit transformation
impedance_1→resistance	$R_1$	$\frac{1}{Z_{nom}} \cdot R$
impedance_1→reactance	$X_1$	$rac{rac{1}{Z_{\mathrm{n}om}} \cdot R}{rac{1}{Z_{\mathrm{n}om}} \cdot X}$
shunt→conductance	G	$Z_{\mathrm nom} \cdot G_1$
shunt→susceptance	B	$Z_{nom}\cdot B_1$
tap_changer -> steps -> impedance_2 -> resistance	$R_k^2$	$\frac{1}{Z_{n\rho m}}\cdot R_k^2$
tap_changer -> steps -> impedance_2 -> reactance	$X_k^2$	$\frac{1}{Z} \cdot X_k^2$
tap_changer -> steps -> impedance_3 -> resistance	$R_k^3$	$rac{rac{1}{Z_{nom}} \cdot X_k^2}{rac{1}{Z_{nom}} \cdot R_k^3}$
tap_changer->steps->impedance_3->reactance	$\begin{array}{c} R_{k}^{3} \\ X_{k}^{3} \\ r_{k}^{2} \\ \delta_{k}^{2} \\ r_{k}^{3} \\ \delta_{k}^{3} \\ R_{k}^{2} \\ X_{k}^{2} \end{array}$	$\frac{1}{Z} \cdot X_k^3$
tap_changer -> steps -> tap_ratio_2	$r_k^2$	$r_k^2$
tap_changer->steps->angle_shift_2	$\delta_k^2$	$\frac{\pi}{180} \cdot \delta_k^2$
tap_changer->steps->tap_ratio_3	$r_k^3$	$r_{\iota}^{3}$
tap_changer->steps->angle_shift_3	$\delta_k^3$	$\frac{\frac{\pi}{180} \cdot \delta_k^3}{\frac{1}{1} \cdot R^2}$
$   tap\_changer \rightarrow steps \rightarrow values[k][1] \rightarrow impedance\_2 \rightarrow resistance $	$R_k^2$	$\frac{\frac{1}{Z_{nom}} \cdot R_k^2}{\frac{1}{Z_n} \cdot X_n^2}$
tap_changer $\rightarrow$ steps $\rightarrow$ values[k][1] $\rightarrow$ impedance_2 $\rightarrow$ reactance	$X_k^2$	$\frac{1}{Z_{nom}} \cdot X_k^2$
tap_changer $\rightarrow$ steps $\rightarrow$ values[k][2] $\rightarrow$ impedance_3 $\rightarrow$ resistance	$R_k^3$	$\frac{\tilde{1}^{m}}{Z_{nom}} \cdot R_k^3$
tap_changer→steps→values[k][2]→impedance_3→reactance	$X_{k}^{3}$ $r_{k}^{2}$ $\delta_{k}^{2}$ $r_{k}^{3}$ $\delta_{k}^{3}$ $\delta_{k}^{3}$ $I_{1k}^{min}$	$\frac{17^m}{Z_{\text{nom}}} \cdot X_k^3$
tap_changer→steps→values[k][3]→tap_ratio_2	$r_k^2$	$T_k$
tap_changer $\rightarrow$ steps $\rightarrow$ values[k][4] $\rightarrow$ angle_shift_2	$\delta_k^2$	$\frac{\pi}{180} \cdot \delta_k^2$
tap_changer→steps→values[k][5]→tap_ratio_3	$r_k^3$	$r_k^3$
tap_changer $\rightarrow$ steps $\rightarrow$ values[k][6] $\rightarrow$ angle_shift_3	$\delta_k^3$	$rac{\pi}{180} \cdot \delta_k^3$
current_limits_1→values[k][1]	$I_{1_k}^{\mathrm min}$	$rac{1}{I_{nom}} \cdot I_{1_k}^{min}$
current_limits_1→values[k][2]	$I_{1_k}^{\mathrm max}$	$\frac{1}{x} \cdot \int_{0}^{\sin ax} dx$
<pre>current_limits_2→values[k][1]</pre>	$I_{2_k}^{\mathrm min}$	$rac{1}{I_{ exttt{nom}}} \cdot I_{2_k}^{ exttt{min}}$
current_limits_2→values[k][2]	$I_{2_k}^{\mathrm max}$	
current_limits_3→values[k][1]	$I_{3_k}^{\min n}$	$1  \tau min$
current_limits_3 \rightarrow values[k][2]	$I_{3_k}^{\max}$	<u>"I"</u> , I <sup>max</sup>
thermal_limits_1 \rightarrow values[k][1]	$S_{1_k}^{min}$	$rac{I_{ ext{no.}m}}{S_{ ext{no.}m}} \cdot rac{S_{ ext{min}}^{13_k}}{S_{1_k}^{min}}$
thermal_limits_1 \rightarrow values[k][2]	$S_{1_k}^{\max}$	
thermal_limits_2 \rightarrow values[k][1]	$S_{2_k}^{\min n}$	$rac{\overline{S_{ ext{nom}}} \cdot \overline{S_{1_k}}}{\overline{S_{ ext{nom}}}} \cdot \overline{S_{2_k}^{ ext{min}}}$
thermal_limits_2 \rightarrow values[k][2]	$S_{2_k}^{\overset{-\kappa}{\max}}$	T Cmax
thermal_limits_3 \rightarrow values[k][1]	$S_{3_k}^{\min}$	$rac{\overline{S_{n_om}}}{S_{n_om}} \cdot S_{2_k}^{min} \ S_{3_k}^{min}$
thermal_limits_3 \rightarrow values[k][2]	$S_{3_k}^{\max}$	$rac{1}{S_{\mathtt{n}om}} \cdot S_{3_k}^{\mathtt{m}ax}$

Table 20: Three windings transformer per-unit transformations.

GRG name	Parameter	Per-unit transformation
voltage→magnitude	v	$\frac{1}{V_{\mathrm{nom}}} \cdot v$
voltage→angle→lb	$\theta^l$	$rac{\pi}{180} \cdot  heta^l$
voltage→angle→ub	$\theta^u$	$\frac{\pi}{180} \cdot \theta^u$
voltage→nominal_value	$V_{nom}$	1
voltage→lower_limit	$V^L$	$\frac{1}{V_{n\rho m}} \cdot V^L$
voltage→upper_limit	$V^U$	$\frac{1}{V_{\mathtt{n}\alpha m}}\cdot V^U$

Table 21: Voltage component per-unit transformations.

GRG name	Parameter	Per-unit transformation
shunt→conductance	G	$\frac{1}{Z_{nom}} \cdot G$
shunt→susceptance	B	$\frac{1}{Z_{nom}} \cdot B$

Table 22: Shunt per-unit transformations.

GRG name	Parameter	Per-unit transformation
<u>demand</u> →active	P	$\frac{1}{S_{nom}} \cdot P$
<u>demand</u> →reactive	Q	$\frac{1}{S_{nom}} \cdot Q$

Table 23: Load per-unit transformations.

GRG name	Parameter	Per-unit transformation
output → active	P	$\frac{1}{S_{nom}} \cdot P$
output→reactive	Q	$\frac{1}{S_{nom}} \cdot Q$
PQ_curve→values[k][0]	$P_k$	$\frac{1}{S_{nom}} \cdot P_k$
PQ_curve→values[k][1]	$Q_k^{\mathrm min}$	$rac{1}{S_{nom}} \cdot Q_k^{min}$
PQ_curve→values[k][2]	$Q_k^{\mathrm max}$	$rac{1}{S_{nom}}\cdot Q_k^{ exttt{max}}$

Table 24: Generator per-unit transformations.

GRG name	Parameter	Per-unit transformation
output → reactive	Q	$\frac{1}{S} \cdot Q$

Table 25: Synchronous condenser per-unit transformations.

GRG name	Parameter	Per-unit transformation
voltage→nominal_value	$V_{nom}$	1
voltage→lower_limit	$V^L$	$\frac{1}{V_{n_{o}m}} \cdot V^L$
voltage→upper_limit	$V^U$	$\frac{1}{V_{nom}} \cdot V^U$

Table 26: Voltage Level per-unit transformations.