

# REGRESSION IN R

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# WHY A PART ON SIMPLE REGRESSION

- ▶ some machine learning concepts are based on regression
- ▶ I would like to remind you how simple regression in R works.
- ▶ I also want to show the constraints
- ▶ In a next step we will learn, how to coop with that

# VARIABLES OF THE MTCARS DATASET

Help for the mtcars dataset:

?mtcars

- ▶ mpg - Miles/(US) gallon
- ▶ cyl - Number of cylinders
- ▶ disp - Displacement (cu.in.)
- ▶ hp - Gross horsepower
- ▶ drat - Rear axle ratio
- ▶ wt - Weight (1000 lbs)
- ▶ qsec - 1/4 mile time
- ▶ vs - Engine (0 = V-shaped, 1 = straight)
- ▶ am - Transmission (0 = automatic, 1 = manual)
- ▶ gear - Number of forward gears
- ▶ carb - Number of carburetors

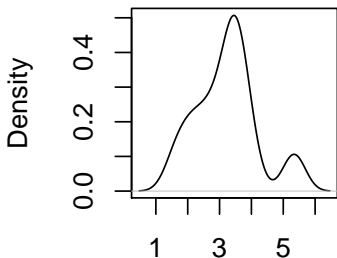
## DATASET MTCARS

	mpg	cyl	displacement	hp	drat	wt	qsec	vs	am
Mazda RX4	21.0	6	160.0	110	3.90	2.620	16.46	0	
Mazda RX4 Wag	21.0	6	160.0	110	3.90	2.875	17.02	0	
Datsun 710	22.8	4	108.0	93	3.85	2.320	18.61	1	
Hornet 4 Drive	21.4	6	258.0	110	3.08	3.215	19.44	1	
Hornet Sportabout	18.7	8	360.0	175	3.15	3.440	17.02	0	
Valiant	18.1	6	225.0	105	2.76	3.460	20.22	1	
Duster 360	14.3	8	360.0	245	3.21	3.570	15.84	0	
Merc 240D	24.4	4	146.7	62	3.69	3.190	20.00	1	
Merc 230	22.8	4	140.8	95	3.92	3.150	22.90	1	
Merc 280	19.2	6	167.6	123	3.92	3.440	18.30	1	
Merc 280C	17.8	6	167.6	123	3.92	3.440	18.90	1	
Merc 450SE	16.4	8	275.8	180	3.07	4.070	17.40	0	
Merc 450SL	17.3	8	275.8	180	3.07	3.730	17.60	0	
Merc 450SLC	15.2	8	275.8	180	3.07	3.780	18.00	0	
Cadillac Fleetwood	10.4	8	472.0	205	2.93	5.250	17.98	0	
Lincoln Continental	10.4	8	460.0	215	3.00	5.424	17.82	0	

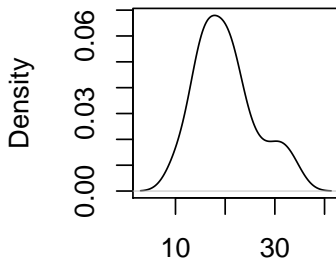
## DISTRIBUTIONS OF TWO VARIABLES OF MTCARS

```
par(mfrow=c(1,2))  
plot(density(mtcars$wt)); plot(density(mtcars$mpg))
```

**density.default(x = mtcars\$wt); density.default(x = mtcars\$mpg)**



N = 32 Bandwidth = 0.3455



N = 32 Bandwidth = 2.477

# A SIMPLE REGRESSION MODEL

DEPENDENT VARIABLE - MILES PER GALLON (MPG)

INDEPENDENT VARIABLE - WEIGHT (WT)

```
m1 <- lm(mpg ~ wt,data=mtcars)
m1

##
## Call:
## lm(formula = mpg ~ wt, data = mtcars)
##
## Coefficients:
## (Intercept)          wt
##      37.285      -5.344
```

# GET THE MODEL SUMMARY

```
summary(m1)

##
## Call:
## lm(formula = mpg ~ wt, data = mtcars)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -4.5432 -2.3647 -0.1252  1.4096  6.8727
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)  37.2851     1.8776   19.858 < 2e-16 ***
## wt          -5.3445     0.5591   -9.559 1.29e-10 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 3.046 on 30 degrees of freedom
```

# THE MODEL FORMULA

## MODEL WITHOUT INTERCEPT

```
m2 <- lm(mpg ~ - 1 + wt,data=mtcars)
summary(m2)$coefficients
```

```
##      Estimate Std. Error  t value    Pr(>|t|)
## wt  5.291624   0.5931801  8.920771 4.55314e-10
```

## ADDING FURTHER VARIABLES

```
m3 <- lm(mpg ~ wt + cyl,data=mtcars)
summary(m3)$coefficients
```

```
##              Estimate Std. Error  t value    Pr(>|t|)
## (Intercept) 39.686261   1.7149840 23.140893 3.043182e-20
## wt          -3.190972   0.7569065 -4.215808 2.220200e-04
## cyl         -1.507795   0.4146883 -3.635972 1.064282e-03
```



# THE COMMAND `as.formula`

```
?as.formula
```

```
class(fo <- mpg ~ wt + cyl)
```

```
## [1] "formula"
```

```
m3 <- lm(fo,data=mtcars)
```

# THE COMMAND `MODEL.MATRIX`

`?model.matrix`

- ▶ See `Matrix::sparse.model.matrix` for increased efficiency on large dimension data.

# FURTHER POSSIBILITIES TO SPECIFY THE FORMULA

## INTERACTION EFFECT

# effect of cyl and interaction effect:

```
m3a<-lm(mpg~wt*cyl,data=mtcars)
```

# only interaction effect:

```
m3b<-lm(mpg~wt:cyl,data=mtcars)
```

## TAKE THE LOGARITHM

```
m3d<-lm(mpg~log(wt),data=mtcars)
```

## A MODEL WITH INTERACTION EFFECT

-disp - Displacement (cu.in.)

```
m3d<-lm(mpg~wt*disp,data=mtcars)
m3dsum <- summary(m3d)
m3dsum$coefficients
```

##	Estimate	Std. Error	t value	Pr(> t )
## (Intercept)	44.08199770	3.123062627	14.114990	2.955567e-14
## wt	-6.49567966	1.313382622	-4.945763	3.216705e-05
## disp	-0.05635816	0.013238696	-4.257078	2.101721e-04
## wt:disp	0.01170542	0.003255102	3.596022	1.226988e-03

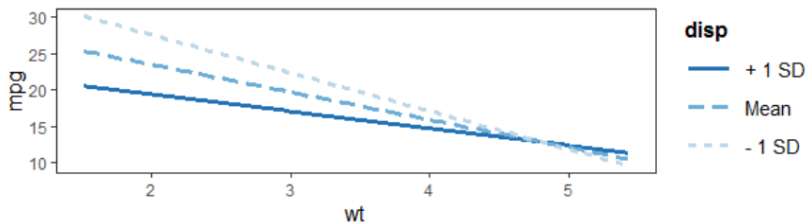
# EXPLORING INTERACTIONS

```
install.packages("jtools")
```

```
library(jtools)
```

```
interact_plot(m3d, pred = "wt", modx = "disp")
```

- ▶ With a continuous moderator (in our case disp) you get three lines — 1 standard deviation above and below the mean and the mean itself.



## EXAMPLE: OBJECT ORIENTATION

- ▶ m3 is now a special regression object
- ▶ Various functions can be applied to this object

```
predict(m3) # Prediction  
resid(m3)  # Residuals
```

##	Mazda RX4	Mazda RX4 Wag	Datsun 710	Horn
##	22.27914	21.46545	26.25203	
##	Hornet Sportabout	Valiant		
##	16.64696	19.59873		

##	Mazda RX4	Mazda RX4 Wag	Datsun 710	Horn
##	-1.2791447	-0.4654468	-3.4520262	
##	Hornet Sportabout	Valiant		
##	2.0530424	-1.4987281		

# MAKE MODEL PREDICTION

```
pre <- predict(m1)
head(mtcars$mpg)
```

```
## [1] 21.0 21.0 22.8 21.4 18.7 18.1
```

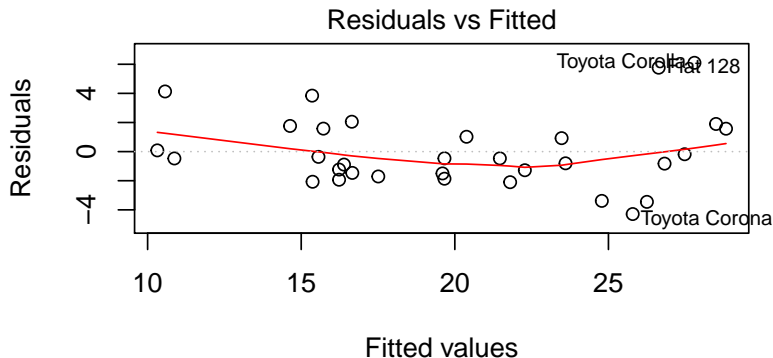
```
head(pre)
```

```
##           Mazda RX4      Mazda RX4 Wag      Datsun 710      Horn
##           23.28261        21.91977        24.88595
## Hornet Sportabout        Valiant
##           18.90014        18.79325
```

# RESIDUAL PLOT - MODEL ASSUMPTIONS VIOLATED?

- ▶ the case if a deviation pattern from line

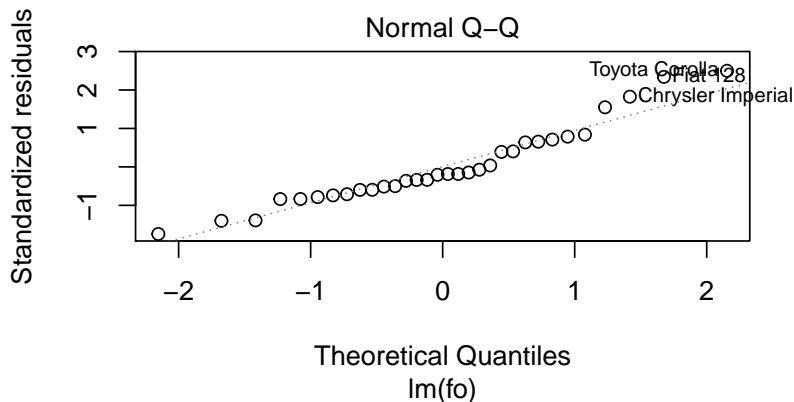
```
plot(m3,1)
```





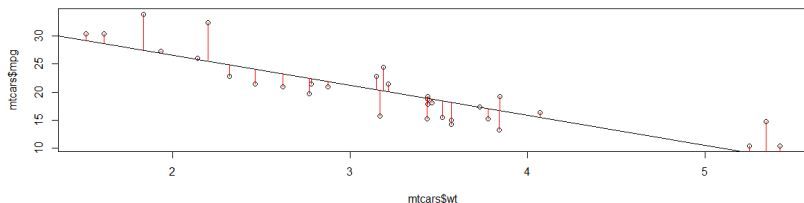
# RESIDUAL PLOT

```
plot(m3,2)
```



# REGRESSION DIAGNOSTIC WITH BASE-R

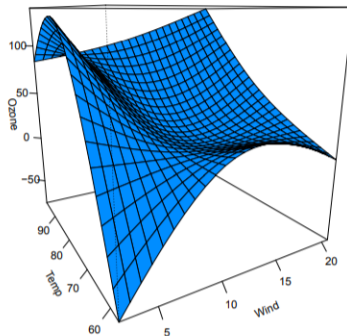
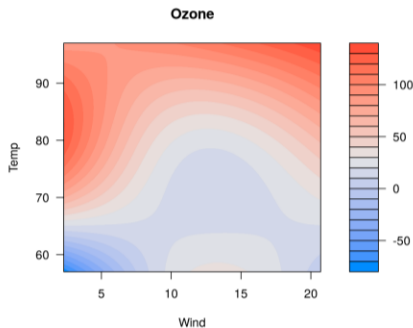
```
plot(mtcars$wt,mtcars$mpg)  
abline(m1)  
segments(mtcars$wt, mtcars$mpg, mtcars$wt, pre, col="red")
```



# THE VISREG-PACKAGE

```
install.packages("visreg")
```

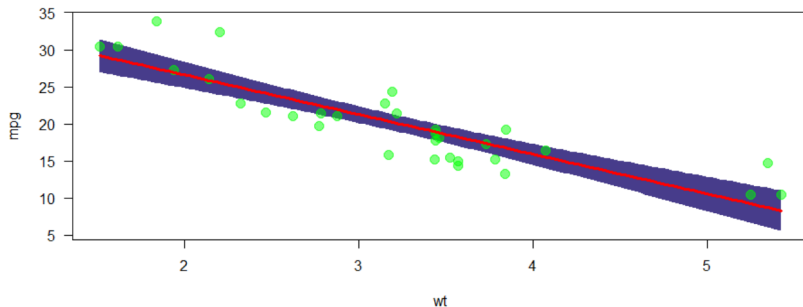
```
library(visreg)
```



# THE VISREG-PACKAGE

- ▶ The default-argument for type is conditional.
- ▶ Scatterplot of mpg and wt plus regression line and confidence bands

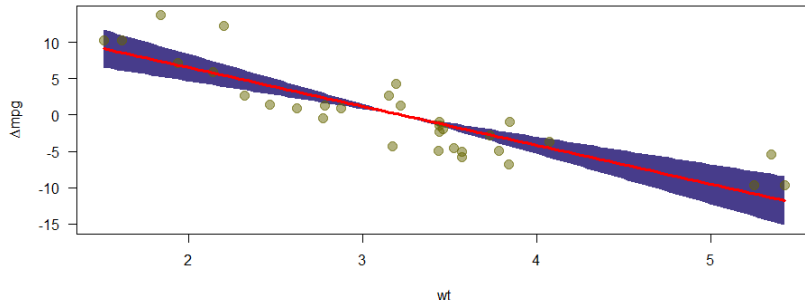
```
visreg(m1, "wt", type = "conditional")
```



## VISUALISATION WITH VISREG

- ▶ Second argument - Specification covariate for visualisation
- ▶ plot shows the effect on the expected value of the response by moving the x variable away from a reference point on the x-axis (for numeric variables, the mean).

```
visreg(m1, "wt", type = "contrast")
```



# REGRESSION WITH FACTORS

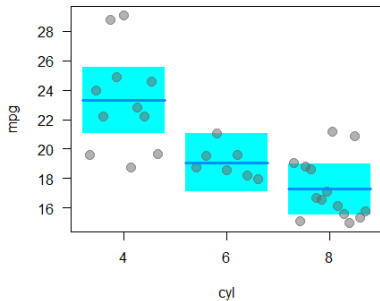
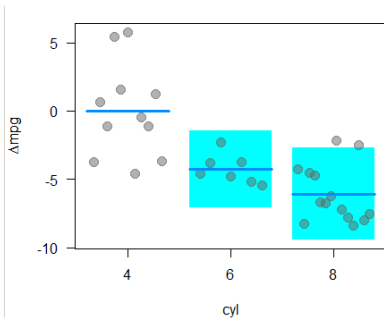
- The effects of factors can also be visualized with visreg:

```
mtcars$cyl <- as.factor(mtcars$cyl)
m4 <- lm(mpg ~ cyl + wt, data = mtcars)
# summary(m4)
```

##	Estimate	Std. Error	t value	Pr(> t )
## (Intercept)	33.990794	1.8877934	18.005569	6.257246e-17
## cyl6	-4.255582	1.3860728	-3.070244	4.717834e-03
## cyl8	-6.070860	1.6522878	-3.674214	9.991893e-04
## wt	-3.205613	0.7538957	-4.252065	2.130435e-04

# EFFECTS OF FACTORS

```
par(mfrow=c(1,2))  
visreg(m4, "cyl", type = "contrast")  
visreg(m4, "cyl", type = "conditional")
```



# THE COMMAND MODEL.MATRIX

?model.matrix



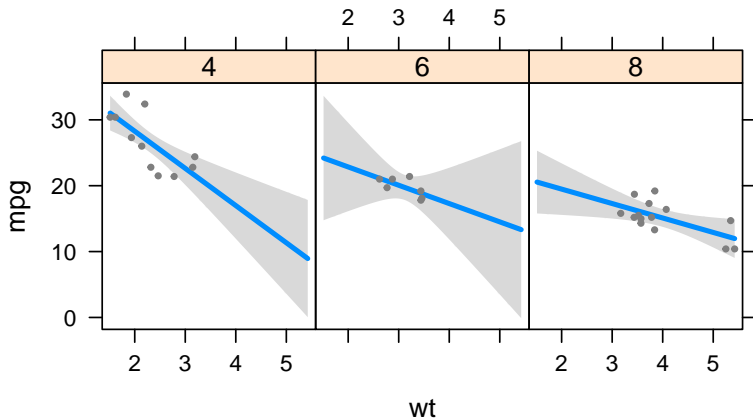
# THE PACKAGE VISREG - INTERACTIONS

```
m5 <- lm(mpg ~ cyl*wt, data = mtcars)
# summary(m5)
```

##	Estimate	Std. Error	t value	Pr(> t )
## (Intercept)	39.571196	3.193940	12.3894599	2.058359e-12
## cyl6	-11.162351	9.355346	-1.1931522	2.435843e-01
## cyl8	-15.703167	4.839464	-3.2448150	3.223216e-03
## wt	-5.647025	1.359498	-4.1537586	3.127578e-04
## cyl6:wt	2.866919	3.117330	0.9196716	3.661987e-01
## cyl8:wt	3.454587	1.627261	2.1229458	4.344037e-02

## CONTROL OF THE GRAPHIC OUTPUT WITH LAYOUT.

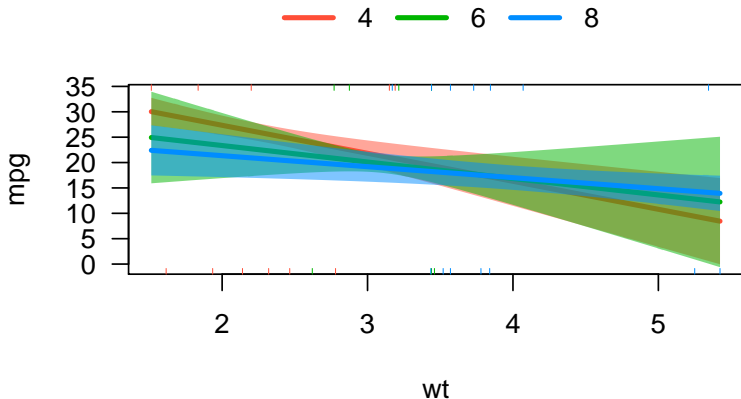
```
visreg(m5, "wt", by = "cyl", layout=c(3,1))
```



# THE PACKAGE VISREG - INTERACTIONS OVERLAY

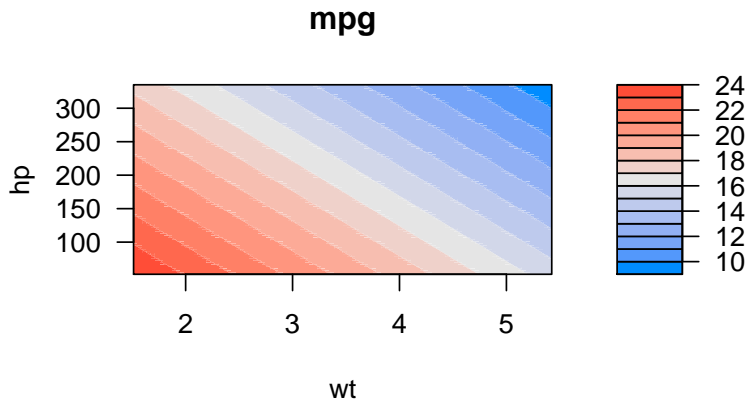
```
m6 <- lm(mpg ~ hp + wt * cyl, data = mtcars)
```

```
visreg(m6, "wt", by="cyl", overlay=TRUE, partial=FALSE)
```



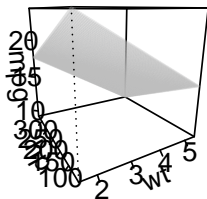
# THE PACKAGE VISREG - VISREG2D

```
visreg2d(m6, "wt", "hp", plot.type = "image")
```



# THE PACKAGE VISREG - SURFACE

```
visreg2d(m6, "wt", "hp", plot.type = "persp")
```



# PRODUCING NICE TABLE OUTPUT WITH PACKAGE STARGAZER

```
library(stargazer)
stargazer(m3, type="html")
```

## EXAMPLE HTML OUTPUT:

	<i>Dependent variable:</i>
	mpg
wt	-3.125*** (0.911)
cyl	-1.510*** (0.422)
am	0.176 (1.304)
Constant	39.418*** (2.641)
Observations	32
R <sup>2</sup>	0.830
Adjusted R <sup>2</sup>	0.812

# EXERCISE

- ▶ Install the package `AmesHousing` and create a processed Version of the Ames housing data with the variables `Sale_Price`, `Gr_Liv_Area` and `TotRms_AbvGrd`
- ▶ Create a suitable regression model with `Sale_Price` as dependent and `Gr_Liv_Area` and `TotRms_AbvGrd` as independent variables. What do you think?

# MULTICOLLINEARITY

- ▶ As  $p$  increases we are more likely to capture multiple features that have some multicollinearity.
- ▶ When multicollinearity exists, we often see high variability in our coefficient terms.
- ▶ E.g. we have a correlation of 0.801 between Gr\_Liv\_Area and TotRms\_AbvGrd
- ▶ Both variables are strongly correlated to the response variable (Sale\_Price).

```
cor(ames_data[,c("Sale_Price", "Gr_Liv_Area", "TotRms_AbvGrd")])
```

```
##           Sale_Price Gr_Liv_Area TotRms_AbvGrd
## Sale_Price      1.0000000    0.7067799    0.4954744
## Gr_Liv_Area     0.7067799    1.0000000    0.8077721
## TotRms_AbvGrd   0.4954744    0.8077721    1.0000000
```



# MULTICOLLINEARITY

```
ames_data <- AmesHousing::make_ames()

lm(Sale_Price ~ Gr_Liv_Area + TotRms_AbvGrd, data = ames_data)

##
## Call:
## lm(formula = Sale_Price ~ Gr_Liv_Area + TotRms_AbvGrd, data = 
##
## Coefficients:
##      (Intercept)      Gr_Liv_Area  TotRms_AbvGrd
##           42767.6             139.4          -11025.9
```

- ▶ When we fit a model with both these variables we get a positive coefficient for Gr\_Liv\_Area but a negative coefficient for TotRms\_AbvGrd, suggesting one has a positive impact to Sale\_Price and the other a negative impact.

## SEPERATED MODELS

- ▶ If we refit the model with each variable independently, they both show a positive impact.
- ▶ The Gr\_Liv\_Area effect is now smaller and the TotRms\_AbvGrd is positive with a much larger magnitude.

```
lm(Sale_Price ~ Gr_Liv_Area, data = ames_data)$coefficients
```

```
## (Intercept) Gr_Liv_Area  
##    13289.634    111.694
```

```
lm(Sale_Price ~ TotRms_AbvGrd, data = ames_data)$coefficients
```

```
## (Intercept) TotRms_AbvGrd  
##    18665.40    25163.83
```

- ▶ This is a common result when collinearity exists.
- ▶ Coefficients for correlated features become over-inflated and can fluctuate significantly.

# CONSEQUENCES

- ▶ One consequence of these large fluctuations in the coefficient terms is **overfitting**, which means we have high variance in the bias-variance tradeoff space.
- ▶ We can use tools such as variance inflation factors (Myers, 1994) to identify and remove those strongly correlated variables, but it is not always clear which variable(s) to remove.
- ▶ Nor do we always wish to remove variables as this may be removing signal in our data.

# THE PROBLEM - OVERFITTING

- Our model doesn't generalize well from our training data to unseen data.

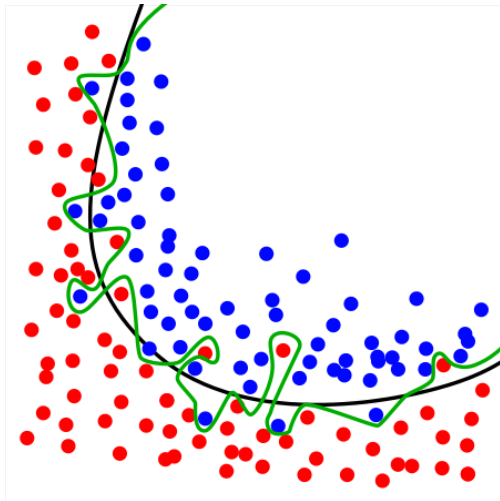


## THE SIGNAL AND THE NOISE

- ▶ In predictive modeling, you can think of the “signal” as the true underlying pattern that you wish to learn from the data.
- ▶ “Noise,” on the other hand, refers to the irrelevant information or randomness in a dataset.

*the signal and the  
and the noise and  
the noise and the  
noise and the noi  
why so many and  
predictions fail—  
but some don't th  
and the noise and  
the noise and the*

## OVERFITTING.



The green line represents an overfitted model and the black line represents a regularized model. While the green line best follows the training data, it

# WHAT CAN BE DONE AGAINST OVERFITTING

- ▶ Cross Validation
- ▶ Train with more data
- ▶ Remove features
- ▶ Regularization - e.g. ridge and lasso regression
- ▶ Ensembling - e.g. bagging and boosting

# CROSS-VALIDATION

- ▶ Cross-validation is a powerful preventative measure against overfitting.
- ▶ Use your initial training data to generate multiple mini train-test splits. Use these splits to tune your model.

## CROSS VALIDATION IN R

```
library(tidyverse)
library(caret)

data("swiss")

training.samples <- swiss$Fertility %>%
createDataPartition(p = 0.8, list = FALSE)
train.data <- swiss[training.samples, ]
test.data <- swiss[-training.samples, ]

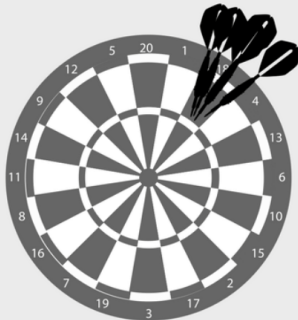
# Build the model
model <- lm(Fertility ~., data = train.data)
# Make predictions and compute the R2, RMSE and MAE
predictions <- model %>% predict(test.data)
```



# K-FOLD CROSS VALIDATION

# THE BIAS VARIANCE TRADEOFF

**High Bias**  
Low Variance



**High bias**, low variance algorithms train models that are consistent, but inaccurate *on average*.

**High Variance**  
Low Bias



**High variance**, low bias algorithms train models that are accurate *on average*, but inconsistent.

# GOOD LITERATURE FOR LINEAR REGRESSION IN R

## USEFUL PDF DOCUMENT:

J H Maindonald - **Using R for Data Analysis and Graphics**  
**Introduction, Code and Commentary**

- ▶ Introduction to R
- ▶ Data analysis
- ▶ Statistical models
- ▶ Inference concepts
- ▶ Regression with one predictor
- ▶ Multiple linear regression
- ▶ Extending the linear model
- ▶ ...

# LINKS - LINEAR REGRESSION

- ▶ Regression - **r-bloggers**
- ▶ The complete book of **Faraway**- very intuitive
- ▶ Good introduction on **Quick-R**
- ▶ **Multiple regression**
- ▶ **15 Types of Regression you should know**
- ▶ **ggeffects - Create Tidy Data Frames of Marginal Effects for 'ggplot' from Model Outputs**

# SHINY APP - DIAGNOSTICS FOR SIMPLE LINEAR REGRESSION

[https://gallery.shinyapps.io/slr\\_diag/](https://gallery.shinyapps.io/slr_diag/)

Diagnostics for simple linear regression

Select a trend:

- ☐ Linear up
- ☐ Linear down
- ☐ Curved up
- ☐ Curved down
- ☒ Fan-shaped

☒ Show residuals

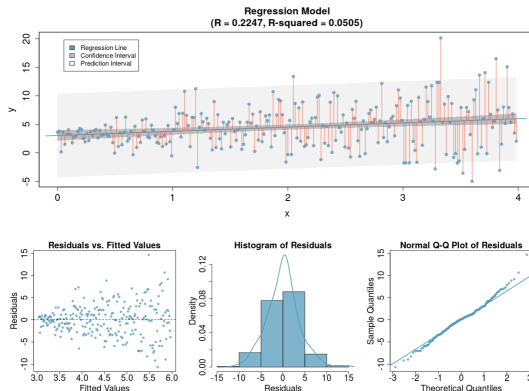
This applet uses ordinary least squares (OLS) to fit a regression line to the data with the selected trend. The applet is designed to help you practice evaluating whether or not the linear model is an appropriate fit to the data. The three diagnostic plots on the lower half of the page are provided to help you identify undesirable patterns in the residuals that may arise from non-linear trends in the data.

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Shiny App - Simple Linear Regression

# RESOURCES

- ▶ machine learning iteration