← Recurrent Neural Networks

Quiz, 10 questions

1 point

1.

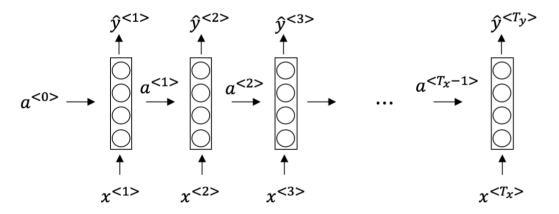
Suppose your training examples are sentences (sequences of words). Which of the following refers to the j^{th} word in the i^{th} training example?

- $x^{< i > (j)}$
- (j) < i >
- $x^{< j > (i)}$

1 point

2.

Consider this RNN:



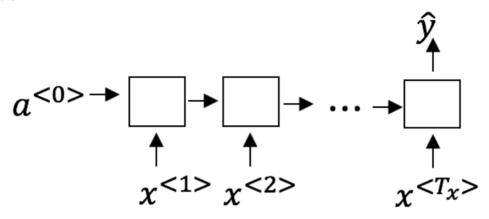
This specific type of architecture is appropriate when (check all that apply):

- \bigcirc $T_x = T_y$
- $\bigcirc \quad T_x < T_y$
- $\bigcap T_x > T_y$
- $T_x = 1$

1 point 3.

To which of these tasks would you apply a many-to-one RNN architecture? (Check all that apply). Recurrent $Neural\ Networks$

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Speech recognition (input an audio clip and output a transcript)

Sentiment classification (input a piece of text and output a 0/1 to denote positive or negative sentiment)

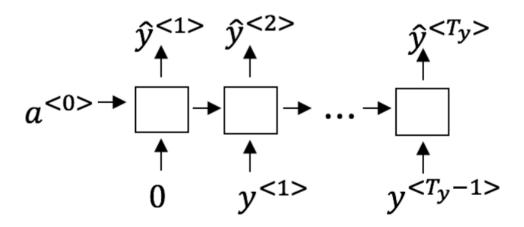
Image classification (input an image and output a label)

Gender recognition from speech (input an audio clip and output a label indicating the speaker's gender)

1 point

4

You are training this RNN language model.



At the t^{th} time step, what is the RNN doing? Choose the best answer.



Estimating
$$P(y^{<1>},y^{<2>},\ldots,y^{< t-1>})$$

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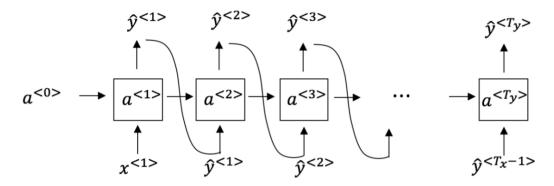
Estimating
$$P(y^{< t>} \mid y^{< 1>}, y^{< 2>}, \ldots, y^{< t-1>})$$

Estimating
$$P(y^{< t>} \mid y^{< 1>}, y^{< 2>}, \ldots, y^{< t>})$$

1 point

5.

You have finished training a language model RNN and are using it to sample random sentences, as follows:



What are you doing at each time step t?

- (i) Use the probabilities output by the RNN to pick the highest probability word for that timestep as $\hat{y}^{< t>}$. (ii) Then pass the ground-truth word from the training set to the next time-step.
- (i) Use the probabilities output by the RNN to randomly sample a chosen word for that timestep as $\hat{y}^{< t>}$. (ii) Then pass the ground-truth word from the training set to the next time-step.
- (i) Use the probabilities output by the RNN to pick the highest probability word for that timestep as $\hat{y}^{< t>}$. (ii) Then pass this selected word to the next time-step.
- (i) Use the probabilities output by the RNN to randomly sample a chosen word for that timestep as $\hat{y}^{< t>}$. (ii) Then pass this selected word to the next time-step.

1 point

6.

You are training an RNN, and find that your weights and activations are all taking on the value of NaN ("Not a Number"). Which of these is the most likely cause of this problem?

- Vanishing gradient problem.
- Exploding gradient problem.
- ReLU activation function g(.) used to compute g(z), where z is too large.
- Sigmoid activation function g(.) used to compute g(z), where z is too large.

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7.

Suppose you are training a GRU. You have a 10000 word vocabulary, and are using an LSTM with 100-dimensional activations $a^{< t>}$. What is the dimension of Γ_u at each time step?

- 1
- 100
- 300
- 10000

1 point

8.

Here're the update equations for the GRU.

GRU

$$\tilde{c}^{< t>} = \tanh(W_c[\Gamma_r * c^{< t-1>}, x^{< t>}] + b_c)$$

$$\Gamma_u = \sigma(W_u[\ c^{< t-1>}, x^{< t>}] + b_u)$$

$$\Gamma_r = \sigma(W_r[c^{< t-1>}, x^{< t>}] + b_r)$$

$$c^{< t>} = \Gamma_u * \tilde{c}^{< t>} + (1 - \Gamma_u) * c^{< t-1>}$$

$$a^{< t>} = c^{< t>}$$

Alice proposes to simplify the GRU by always removing the Γ_u . I.e., setting Γ_u = 1. Betty proposes to simplify the GRU by removing the Γ_r . I. e., setting Γ_r = 1 always. Which of these models is more likely to work without vanishing gradient problems even when trained on very long input sequences?

- Alice's model (removing Γ_u), because if $\Gamma_r \approx 0$ for a timestep, the gradient can propagate back through that timestep without much decay.
- Alice's model (removing Γ_u), because if $\Gamma_r \approx 1$ for a timestep, the gradient can propagate back through that timestep without much decay.
- Betty's model (removing Γ_r), because if $\Gamma_u \approx 0$ for a timestep, the gradient can propagate back through that timestep without much decay.
- Betty's model (removing Γ_r), because if $\Gamma_u \approx 1$ for a timestep, the gradient can propagate back through that timestep without much decay.

LSTM

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Here are the equations for the GRU and the LSTM:

GRU

$\tilde{c}^{<t>} = \tanh(W_c[\Gamma_r * c^{<t-1>}, x^{<t>}] + b_c)$ $\tilde{c}^{<t>} = \tanh(W_c[\alpha^{<t-1>}, x^{<t>}] + b_c)$ $\Gamma_u = \sigma(W_u[c^{<t-1>}, x^{<t>}] + b_u)$ $\Gamma_u = \sigma(W_u[\alpha^{<t-1>}, x^{<t>}] + b_u)$ $\Gamma_r = \sigma(W_r[c^{<t-1>}, x^{<t>}] + b_r)$ $\Gamma_f = \sigma(W_f[\alpha^{<t-1>}, x^{<t>}] + b_f)$ $C^{<t>} = \Gamma_u * \tilde{c}^{<t>} + (1 - \Gamma_u) * c^{<t-1>}$ $\Gamma_o = \sigma(W_o[\alpha^{<t-1>}, x^{<t>}] + b_o)$ $C^{<t>} = \Gamma_u * \tilde{c}^{<t>} + \Gamma_f * c^{<t-1>}$ $C^{<t>} = \Gamma_u * \tilde{c}^{<t>} + \Gamma_f * c^{<t-1>}$ $C^{<t>} = \Gamma_u * \tilde{c}^{<t>} + \Gamma_f * c^{<t-1>}$ $C^{<t>} = \Gamma_u * \tilde{c}^{<t>} + \Gamma_f * c^{<t-1>}$

From these, we can see that the Update Gate and Forget Gate in the LSTM play a role similar to _____ and ____ in the GRU. What should go in the the blanks?

 $igcap \Gamma_u$ and $1-\Gamma_u$

 Γ_u and Γ_r

 $1-\Gamma_u$ and Γ_u

 Γ_r and Γ_u

1 point

10.

You have a pet dog whose mood is heavily dependent on the current and past few days' weather. You've collected data for the past 365 days on the weather, which you represent as a sequence as $x^{<1>},\ldots,x^{<365>}$. You've also collected data on your dog's mood, which you represent as $y^{<1>},\ldots,y^{<365>}$. You'd like to build a model to map from $x\to y$. Should you use a Unidirectional RNN or Bidirectional RNN for this problem?

- Bidirectional RNN, because this allows the prediction of mood on day t to take into account more information.
- Bidirectional RNN, because this allows backpropagation to compute more accurate gradients.
- Unidirectional RNN, because the value of $y^{< t>}$ depends only on $x^{< 1>},\dots,x^{< t>}$, but not on $x^{< t+1>},\dots,x^{< 365>}$
- Unidirectional RNN, because the value of $y^{< t>}$ depends only on $x^{< t>}$, and not other days' weather.

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