Volumetric Fog

Implementing Fog Effects in a 3-Dimensional Environment

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Outline

- Introduction
- Challenges
- Implementation and Results
- Video Demonstration
- Conclusion/Q&A

Introduction

Introduction

- Since 2000's: Rapid advances in computing
- Volumetric effects
  - Depth
  - Realism
  - Explosions, fire, smoke, rain, fog, dust, shafts of light/shadow, etc.
- Implementation of volumetric effects
  - High-level methodology is widely known
  - Low-level details are not generally available

Introduction

- Focus: Implementing volumetric fog
- Volumetric Fog:
  - Simulates interaction between light and atmosphere
  - Challenging to implement
    - *Mathematically complex*
    - *Computationally expensive*

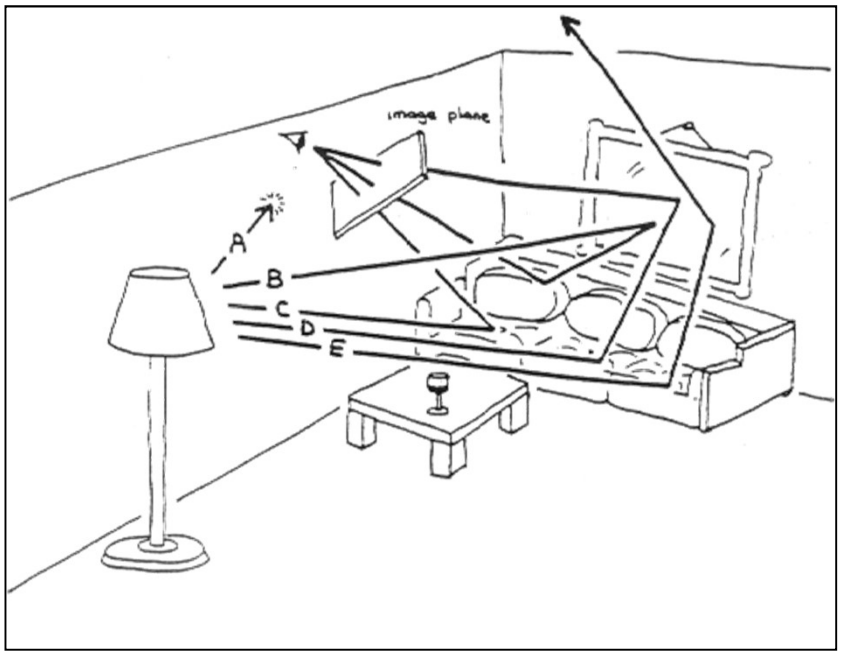
Introduction

- Three Goals:
  - Understand volumetric fog
  - Build an interactive system
  - Share what we've learned

Challenges

Challenges – Illumination Model

- Local Illumination
- Global Illumination
- Volumetric Illumination



Sources: [1] – [4]

Image Source:
https://www.siggraph.org/education/materials/HyperGraph/illumin/illum1.htm

Challenges – Understanding Fog

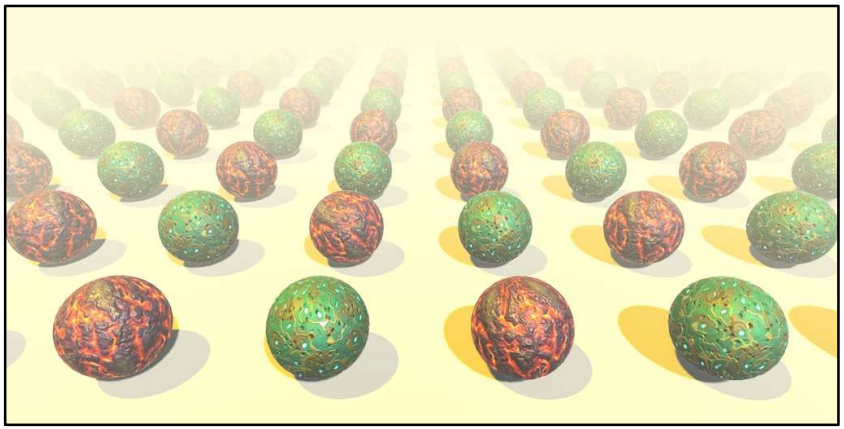
- Characteristics of fog
  - Reduced visibility
  - Thickness / height
  - Variations in density
  - Lifting / evaporating
  - Drifting / swirling
  - Variations over time

Sources: [5] – [6]

Five Methods

Method 1: Distance-Based Fog

- Surface shaders
- Blends object color with sky color
- Real-time performance
- Downside: simplicity



Sources: [7] – [9]

Image Source:
https://catlikecoding.com/unity/tutorials/rendering/part-14/

Method 2: Billboarding

- Particle effects on a 2D surface
- Always facing the camera
- Supports local effects
- Downsides:
  - One viewing angle
  - Hard edges

Sources: [7], [10]

Image Source:
http://blog.wolfire.com/2010/04/Soft-Particles

Method 3: Particle Emission

- Many small particles
- Good visual quality
- Highly dynamic effects
- Downside:
  - Overhead

Sources: [7], [11] – [13]

Image Source:
https://www.youtube.com/watch?v=lekE0Ez_go0

Method 4: Post-Effect Image-Based

- Popularized by Unreal Engine 3.0 & CryEngine
- Uses photography post-processing techniques
- Excellent results under the right conditions
- Weaknesses:
  - Not physics based
  - No support for close lights
  - Fog / transparent objects
  - Directionality

Sources: [7]

Image Source: https://www.gamasutra.com/blogs/BartlomiejWronski/20141208/226295/Atmospheric_scattering_and_volumetric_fog_algorithm__part_1.php

Method 5: Volumetric Fog

- Current technique
- Post-effect
  - After depths, normal, and colors calculated
- GPU: per-pixel calculations
  - Raymarching

Sources: [7]

Image Source:
https://gkan.artstation.com/projects/o1bRO

Method 5: Volumetric Fog

- Photo-realistic
- Simulate real world
- Support multiple lights
- Current implementations
  - Several tradeoffs
  - Some limitations

Sources: [7]

Image Source:
https://gkan.artstation.com/projects/o1bRO

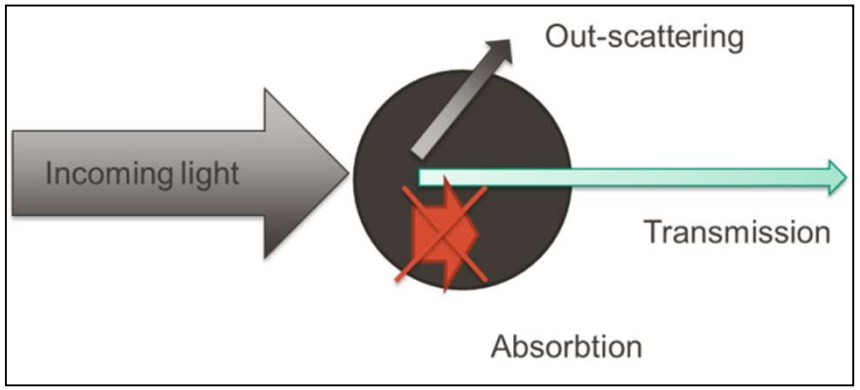
Summary

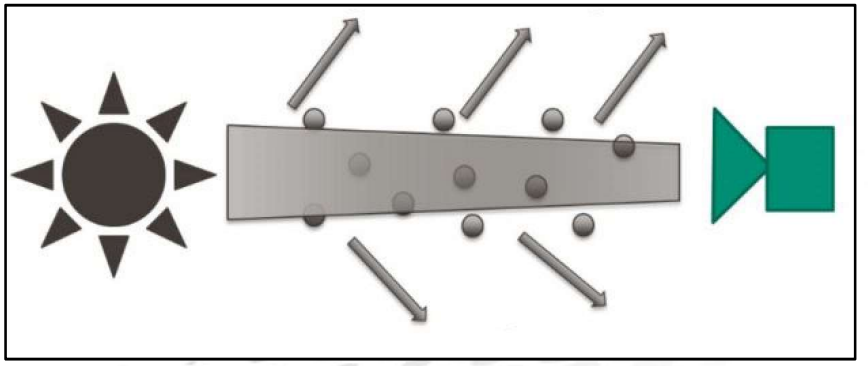
- Five methods for generating fog
  - Merits / trade offs
- Our focus: Volumetric approach to simulating fog
  - Most recently developed
  - Follows and approximates real-life physics
  - Results in visually appealing / realistic fog

Volumetric Considerations

Implementation – Considerations

- **Atmospheric Absorption and Scattering of Light**
  - **Light-Particle Interaction**
  - **Occurs over entire distance traveled**
  - **Beer-Lambert Law**





Sources: [14] – [17]

Image Source: https://bartwronski.files.wordpress.com/2014/08/bwronski_volumetric_fog_siggraph2014.pdf

Implementation – Considerations

Beer-Lambert Law

$$I = I_0 * e^{-\beta e * x}$$

Where

I_0 – Initial light intensity

x – Distance traveled through the participating medium

βe – (the extinction coefficient) Sum of the scattering and absorption coefficients

If βe is a function of x, then the equation becomes:

$$I_{(A \to B)} = I_0 * e^{-\int_A^B \beta e(x)\, dx}$$

Sources: [14] – [17]

Implementation – Considerations

Beer-Lambert Law (Our Implementation)

$$I_{pixel} = I_0 * \sum_{i=0}^{n} F_1(x,y,z) * \cdots * F_j(x,y,z)$$

Where

I_0 – Initial light intensity

$F_j(x,y,z)$ – Attenuation factors (for each feature implemented)

Implementation – Considerations

- **At each raymarching step (1 to n), we determine the density and color of the fog**
  - **Return these values for every pixel and frame rendered**

- **The final color of each pixel is determined by the equation:**

$$PixelColor = Color * (1 - d) + fogColor * d$$

Where

color – original color value for the pixel

d – total fog density for the pixel

Implementation And Results

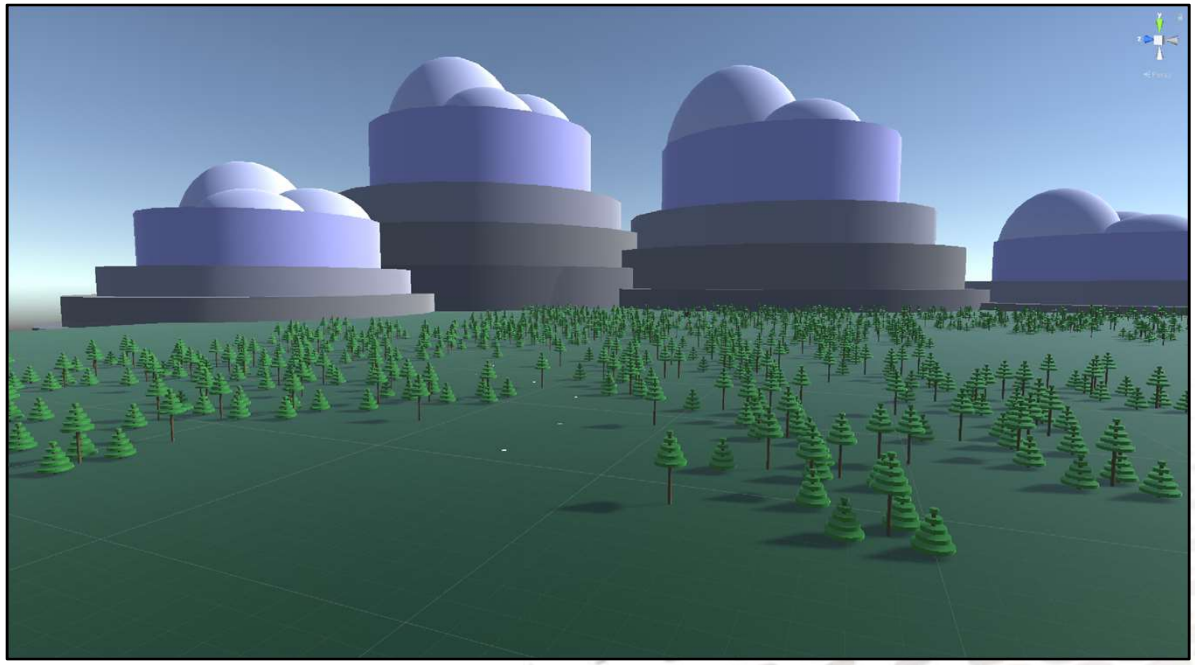
Base Scene

- Here is a simple forest scene with mountains…

Image Source:
https://pngtree.com/freebackground/mountain-landscape-range-forest_619115.html

Base Scene

- Hundreds of 3D primitives
  - Ground plane
  - Mountains
  - Trees (two sizes)
  - Shed and lamp post
  - Cookie trail



Density Attenuation Factors

- Factor 1: Constant depth fog
- Factor 2: Height density
- Factor 3: Edge density
- Factor 4: Variable-density

Fog Density – Implementation

- Basic user input:
  - Number of steps to use in raymarching (from 2 to 256)
  - Depth at which the fog becomes to dense to see through
  - Scene-wide fog or localized (placed in a box in the scene)
- From the scene:
  - Distance to the fragment (linear value from 0 to 1)
- Using this information, we calculate:
  - Size of each step
  - Density of the fog to accumulate each step

Depth Fog – Implementation

- Goal: Constant density fog
- Desired Result: Fog that uniformly obscures objects with distance
- Uniform density for each raymarching step
- Final density: sum of fog values calculated at each step

$$I_{pixel} = I_0 * \sum_{i=0}^{n} F_{depth}(x, y, z)$$

Image Source:
https://www.videoblocks.com/video/working-tractor-in-the-distance-during-the-fog-rvdxkvbggivx9p4pv

Depth Fog – Results

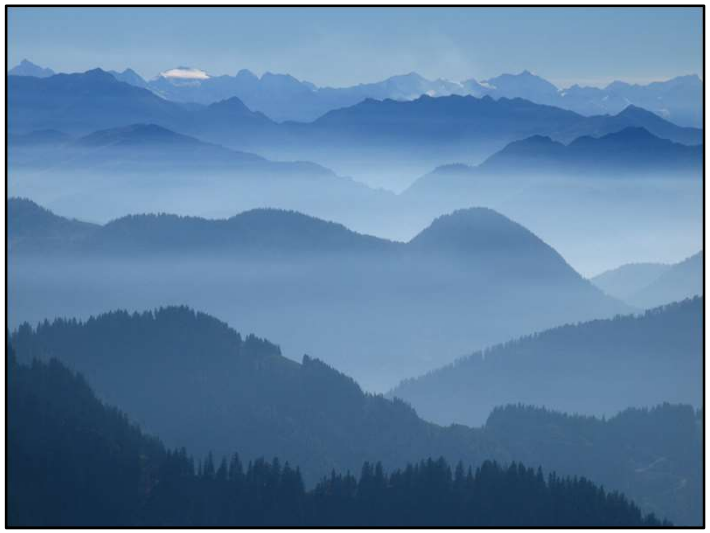
- Close objects appear normal
- Distant objects appear faded and indistinct
- Most distant objects are completely obscured

Real World

Generated

Height Density – Implementation

- Observation: Density varies with altitude.
  - Thicker at bottom
  - Thins at the top
- User provides three values:
  - Height
  - Distance
  - Linear or exponential

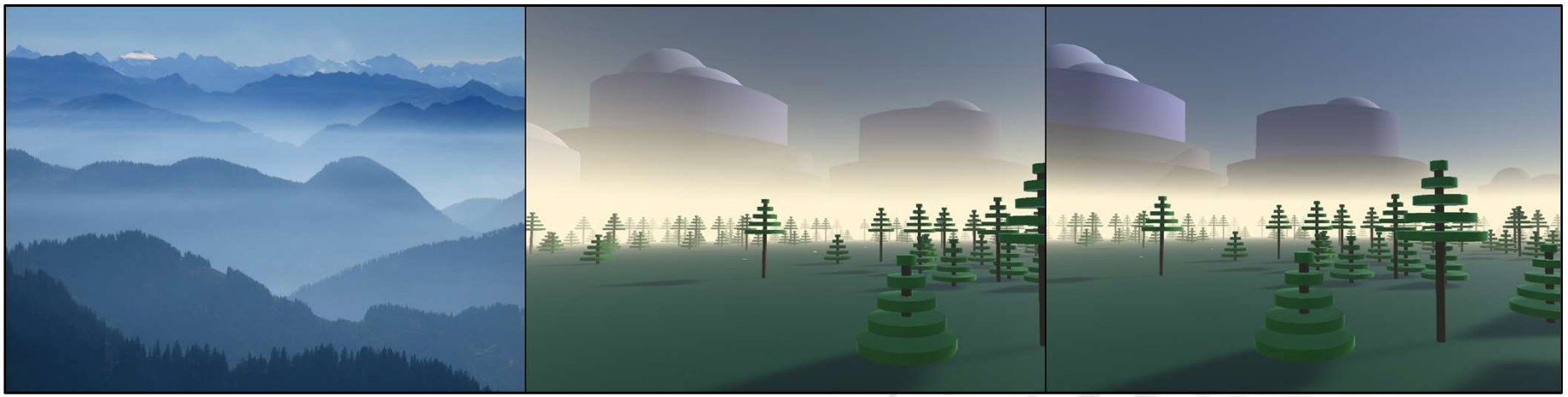


$$I_{pixel} = I_0 * \sum_{i=0}^{n} F_{depth} * F_{height}$$

Image Source:
https://naturfotografen-forum.de/o21898-Blaue%20Stunde%20ND

Height Density – Results

- Two functions shown:
  - Linear (center)
  - Exponential (right)
- Bottom: Constant density fog
- Top: Varies with altitude



Real World Linear Exponential

Edge Density – Implementation

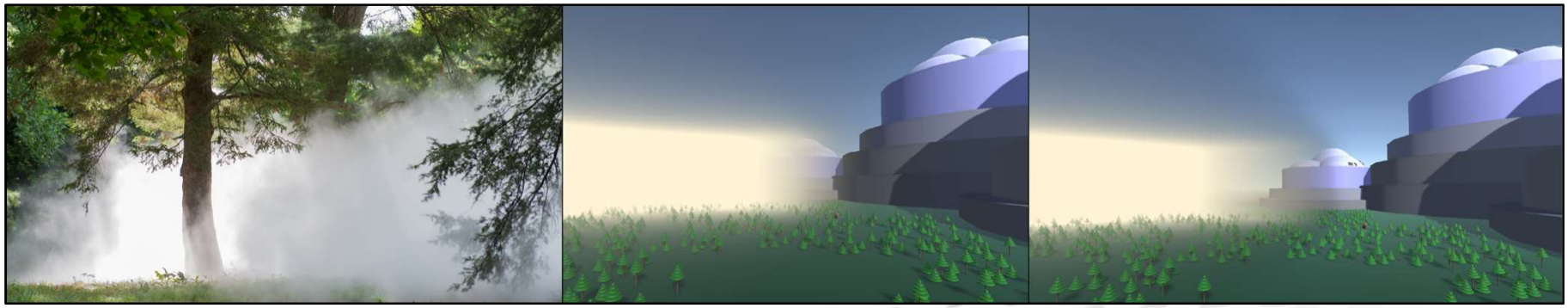
- **Observation: Density varies at the fog edge.**
- **Similar mechanism to the height density**
- **User provides two values per direction**
  - **Distance**
  - **Linear or exponential**

$$I_{pixel} = I_0 * \sum_{i=0}^{n} F_{depth} * F_{height} * F_{edge}$$

Image Source:
https://www.videoblocks.com/video/working-tractor-in-the-distance-during-the-fog-rvdxkvbggivx9p4pv

Edge Density – Results

- Two functions shown:
  - Linear (center)
  - Exponential (right)
- Difference between the two is subtle
  - Exponential function falls off over a shorter distance



Real World Linear Exponential

Variable-Density – Implementation

- **Observation: Density varies as position and time change.**
- **Changes in visibility**
- **Observe fog motion**

Image Source:
http://wikilovesearth.org/wle-2015-cloudy-and-foggy-nature/

Variable-Density – Implementation

- Simplex noise function
  - HLSL implementation
  - Pseudorandom in 2D/3D/4D
  - Simple function call
  - Values in range 0 to 1

- User provides:
  - Noise strength

Image Source:
http://wikilovesearth.org/wle-2015-cloudy-and-foggy-nature/

Variable-Density – Implementation

- Step density is modified by a factor of the noise strength times the random noise value

$$I_{pixel} = I_0 * \sum_{i=0}^{n} F_{depth} * F_{height} * F_{edge} * F_{random}$$

Image Source:
http://wikilovesearth.org/wle-2015-cloudy-and-foggy-nature/

Drifting Fog – Implementation

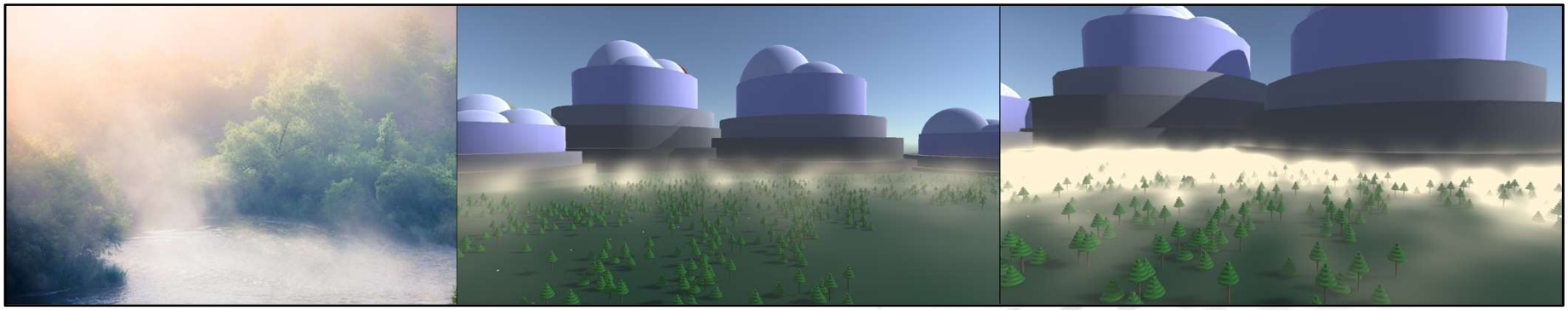
- Builds on variable-density
- User provides:
  - Velocity vector
- Velocity * _Time.x

$$I_{pixel} = I_0 * \sum_{i=0}^{n} F_{depth} * F_{height} * F_{edge} * F_{random}$$

Image Source:
http://wikilovesearth.org/wle-2015-cloudy-and-foggy-nature/

Variable-Density – Results

- Two different scenarios shown below:
  - Thin, wispy ground fog (center)
  - Thicker, rolling fog (right)
- Ground fog: Patchy, cloud-like appearance
- Rolling fog: Objects fade in and out with drift



Real World | Thin Ground Fog | Thicker Rolling Fog

Fog Color

- Base color
- Shadows
- Ambient fog
- Multiple lights

Fog Color – Implementation

- Real world: Color of fog based on light interactions
- Initially: One light
- Fog color is light color multiplied by step density
- Results accumulated for each pixel and blended with original pixel color

Image Source:
http://www.shainblumphoto.com/project/symphony-of-the-fog/

Fog Color – Results

- Fog and game objects:
  - Both directly affected by scene lighting

Real World

Generated

Shadows – Implementation

- High dynamic lighting
  - Crepuscular rays
- Shadow maps
  - Passed to shader using a command buffer
  - Get shadow status by location
  - User: shadow strength
- Multiply the lit fog color by both shadow strength and shadow status

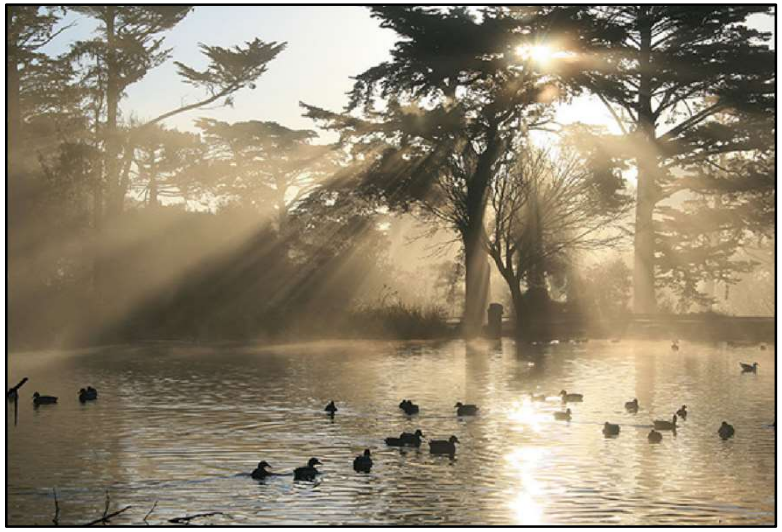
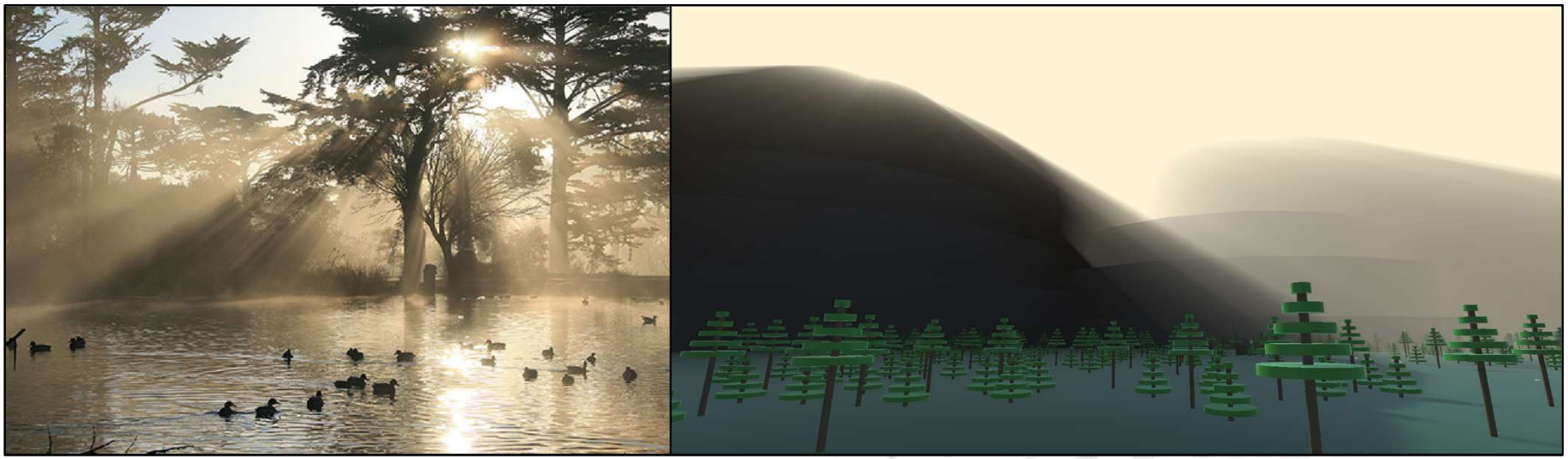


Image Source:
https://astrobob.areavoices.com/2011/07/10/crepuscular-rays-a-tale-of-sunbeams-diverging-in-the-blue-sky/

Shadows – Results

- Partial success:
  - Generated fog displays shafts of light and shadow
- Future improvements:
  - Scattering functions (Raleigh, Mie, others)



Real World

Generated

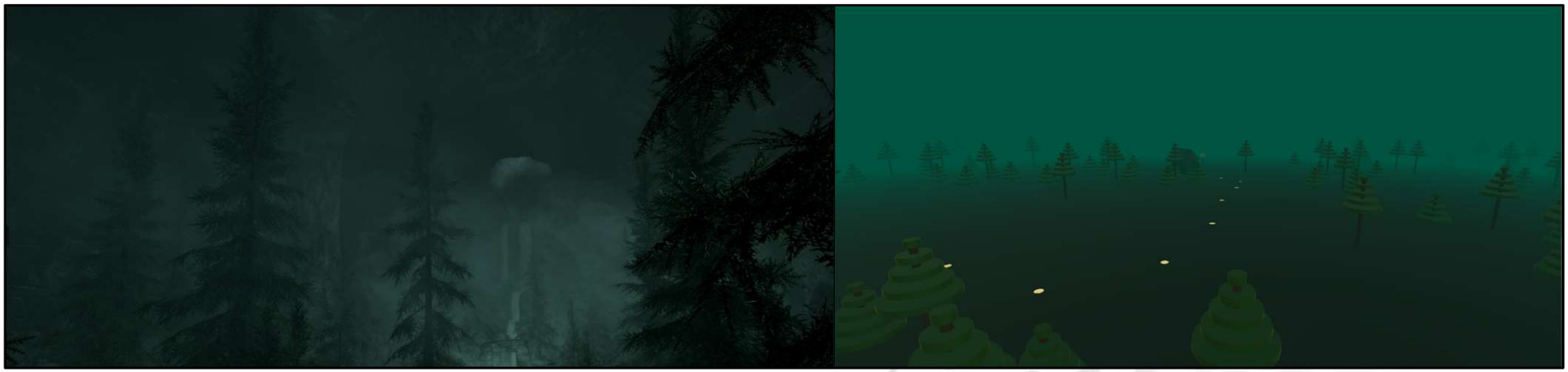
Ambient Fog – Implementation

- Not natural occurrence
- Useful effect in movies and games
- User provides two values:
  - Intensity
  - Color
- Linear interpolation
  - Step color
  - Ambient color

Image Source:
https://www.nexusmods.com/skyrimspecialedition/mods/11197/

Ambient Fog – Results

- Effect we are replicating (Skyrim)
  - Glowing blue-green fog in a cave with low lighting
- Directional light disabled (no scene lighting)
  - Glowing green fog
  - Useful in lit fog: Can modify fog color



Borrowed from the game, *Skyrim*

Generated

Point Light – Implementation

- Inputs from light source:
  - Location
  - Range
  - Intensity
  - Color
- Three attenuation factors from the user:
  - Constant
  - Linear
  - Exponential

Image Source:
http://www.romeofthewest.com/2009/01/dense-fog.html

Point Light – Implementation

- **Process:**

1. **Direction to point light**
2. **Distance to point light**

If in point light's range:

3. **Point light intensity at the current location**
4. **Linearly interpolate between step color and point light color**

Image Source:
http://www.romeofthewest.com/2009/01/dense-fog.html

Multiple Lights/Point Light – Results

- Visual quality can approximate the real world
- Result does not exactly match reality
  - Extra light attenuation factors – *Artistic endeavor*

Real World

Generated

Results – Performance

- Goal
  - Demonstrate a highly performant fog simulation
  - Running at a full HD resolution of 1920 x 1080
  - Game scene of moderate complexity
- Results
  - Achieved our performance goals (see video)
- Analysis
  - Largest performance detractor: variable density/noise
  - Variable density can decrease frame rates by up to ~75%

Video Demonstration

Conclusion

- Researched and implemented a system for generating volumetric fog
  - General process is widely known, however…
  - Optimizations generally are not known (trade secrets)

Conclusion

- **Future Improvements**
  - **Model: Linear method of stacking effects may impact ability to deliver advanced features (reality: fog aspects are interrelated)**
  - **Model: Add support for multiple overlapping fogs.**
  - **Optimization: Explore optimizations for variable-density fog (noise function)**

Conclusion

- Future Improvements (Continued)
  - Feature: Need support for additional light types, such as spots, and more lights in the scene
  - Feature: Improved shadows in fog (shadow cascades / perspective aliasing)
  - Usability: Interface

Conclusion

- Good progress on many aspects / features of fog
  - Entire scene or localized fog
  - Linear / exponential height density
  - Edge density for localized fog
  - Shadowed fog
  - Noisy / variable-density fog
  - Others…

Conclusion

- Available (by quarter's end) for researcher's and enthusiasts to use as a starting point in their own projects
  - UW Bothell's Digital Future Lab (DFL) has shown interest

Questions?

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