Comp6211e: Optimization for Machine Learning

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Lecture 6: Nesterov's Acceleration Method

Convex Optimization

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L-smooth

\( \shcap \cdot \strongly \convex \)

\( \shcap = \text{max eigvalue of Hessian matrix} \)

\( \shcap = \text{min} \cdot \cdot - \sqrt{----} \)
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In this lecture, we consider the general unconstrained convex optimization problem:

$$\min_{x\in\mathbb{R}^d} f(x).$$

First Order Optimization

We consider the the following form of recursion:

$$x_t = x_{t-1} + p_{t-1}$$
 shrinking factor (usually < /)
$$p_t = -\alpha_t \nabla f(x_t) + \beta_t p_{t-1} \text{ how fast to forget greensus gradient.}$$
| Learning rate (usually $\frac{1}{4}$)

We may refer to this class of methods as momentum methods, and it can be employed for general unconstrained optimization problems.

Reformulation

$$\begin{array}{c} (G_{t} \times_{t-1} + \widehat{J}_{t-1}) \Rightarrow \widehat{J}_{t-1} = X_{t} \times_{t-1} \\ \emptyset \mid \widehat{J}_{t} = -(X_{t} \nabla f(X_{t}) + \beta_{t} \sum_{t-1} + \widehat{J}_{t-1}) \Rightarrow \widehat{J}_{t} = -(X_{t} \nabla f(X_{t}) + \beta_{t} (X_{t} - X_{t-1}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ \text{Heavy Ball} \mid X_{t} = y_{t} - (X_{t} \nabla f(X_{t-1})) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ X_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) \\ Y_{t} = X_{t-1} + \beta_{t} (X_{t-1} - X_{t-2}) & \text{ if } Y_{t-1} + \beta_{t}$$

The momentum (Heavy Ball) method can be written as the following form:

$$\beta_t = \beta = 1 - \frac{1}{\sqrt{K}} \qquad y_t = x_{t-1} + \beta_t (x_{t-1} - x_{t-2})$$

$$x_t = y_t - \alpha_t \nabla f(x_{t-1}).$$

More aggressive using Nesterov's

Nesterov's Method

(1) Stochastic (CG not applicable)
(2) Non-smooth (CG not good in general).

Nesterov modified this equation as follows:

$$y_t = x_{t-1} + \beta_t(x_{t-1} - x_{t-2})$$

 $x_t = y_t - \alpha_t \nabla f(y_t).$

With this modification, one can prove the global convergence of the resulting algorithm for convex functions.

Algorithm

Algorithm 1: Nesterov's Acceleration Method

```
Input: f(x), x_0, \alpha_1, \beta_1, \alpha_2, \beta_2,...

Output: x_T

1 Let x_{-1} = x_0

2 for t = 1, ..., T do

3 Let y_t = x_{t-1} + \beta_t(x_{t-1} - x_{t-2})

Let x_t = y_t - \alpha_t \nabla f(y_t)

Return: x_T
```

Equivalent Formulation

For mula for
$$CG:$$
 $\mathcal{I}_t = - \propto_t \nabla f(x_t) + \beta_t \mathcal{I}_{t-1}$
 $\times_t = x_{t-1} + \mathcal{I}_t$

Note that equivalently, we may write Nesterov's method as follows, with a different choice of parameters.

Querage of historical gradients,
$$y_t = x_{t-1} + \beta_t p_{t-1} \qquad \text{new}.$$

$$p_t = \beta_t p_{t-1} - \alpha_t \nabla f(y_t)$$

$$x_t = x_{t-1} + p_t.$$

This can be compared to the heavy ball formulation.

Motivation: GD versus CG

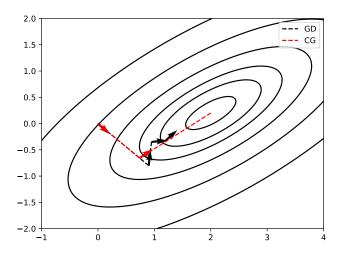


Figure: Gradient Descent and CG

Motivation: GD versus Accelerated Methods

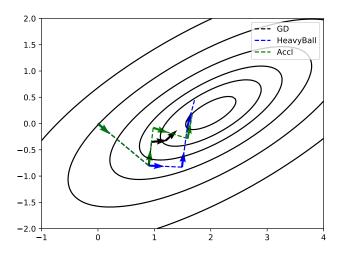


Figure: Gradient Descent, Heavy Ball, and Acceleration

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Sensitivity to β

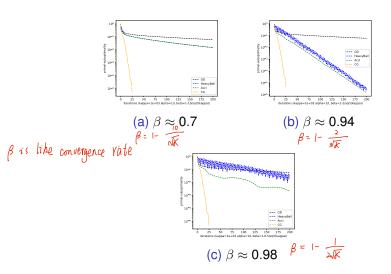


Figure: Convergence Comparisons with Fixed α

Sensitivity to α

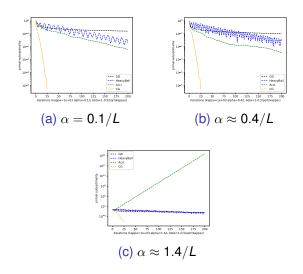


Figure: Convergence Comparisons with Fixed β

Convergence Analysis

Theorem

Assume f(x) is L-smooth and λ -strongly convex. Let $\eta \leq 1/L$ and $\theta = \sqrt{\eta \lambda}$. Let $\alpha_t = \eta \leq 1/L$ and $\beta_t = \beta = (1 - \theta)/(1 + \theta)$. Then

$$f(x_t) \leq f(x_*) + (1-\theta)^t \left[f(x_0) - f(x_*) + \frac{\lambda}{2} ||z - x_0||_2^2 \right]$$

$$\theta = \frac{1}{\sqrt{K}}$$
Convergence vate $\left| - \frac{1}{\sqrt{K}} \right|$

Proof: Estimation Sequence

Definition

A pair of sequences $\{(\phi_t(x), \lambda_t \ge 0\}$ is called an estimation sequence of function f(x), if for any $x \in \mathbb{R}^d$ and all $t \ge 0$:

$$\phi_t(x) \leq (1 - \lambda_t)f(x) + \lambda_t\phi_0(x).$$

Convergence Analysis with Estimation Sequence

If for an estimation sequence, we have the following property (upper bound of $f(x_t)$)

$$f(x_t) \leq \phi_t(v_t) = \min_{z} \phi_t(z).$$

then

$$f(\mathbf{x}_t) \leq (1 - \lambda_t)f(\mathbf{x}_*) + \lambda_t \phi_0(\mathbf{x}_*).$$

Estimation Sequence Lemma

Lemma

Let $x^+ = y - \eta \nabla f(y)$. We define

$$\phi(z;y) = f(x^+) - \frac{1}{2\eta} ||x^+ - y||_2^2 + \frac{1}{\eta} (y - x^+)^\top (z - x^+) + \frac{\lambda}{2} ||z - y||_2^2.$$

Then the following inequality holds:

$$\phi(z;y)\leq f(z).$$

Therefore if we define recursively

$$\phi_t(z) = (1 - \theta)\phi_{t-1}(z) + \theta\phi(z; y_t)$$

with

$$\phi_0(z) = f(x_0) + \frac{\lambda}{2} ||z - x_0||_2^2,$$

then $\{\phi_t, (1-\theta)^t\}$ is an estimation sequence.

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Proof of Second part

Since the following hold trivially at t = 0:

$$\phi_0(z) \leq (1-(1-\theta)^0)f(x)+(1-\theta)^0\phi_0(x).$$

and thus we can assume by induction that at t-1:

$$\phi_{t-1}(x) \le (1 - (1-\theta)^{t-1})f(x) + (1-\theta)^t \phi_0(x)$$
. Then

$$\phi_t(x) = (1 - \theta)\phi_{t-1}(x) + \theta\phi(x; y_t)$$

$$\leq (1 - \theta)[(1 - (1 - \theta)^{t-1})f(x) + (1 - \theta)^{t-1}\phi_0(x)] + \theta f(x)$$

$$= (1 - (1 - \theta)^t)f(x) + (1 - \theta)^t\phi_0(x).$$

Upper Bound

Lemma

We have

$$f(x_t) \leq \phi_t(v_t) = \min_{z} \phi_t(z).$$

<u>|Su</u>mmary

We have studied accelerated first order methods with momentum

- β is decaying term for the aggregated gradients.

In practice, careful tuning of α and β are important.

- Right setting of β can significantly improve convergence, but inappropriate setting can lead to oscillation
- The sensitivity to α is less severe with appropriate $\beta > 0$, because the gradients are aggregated.