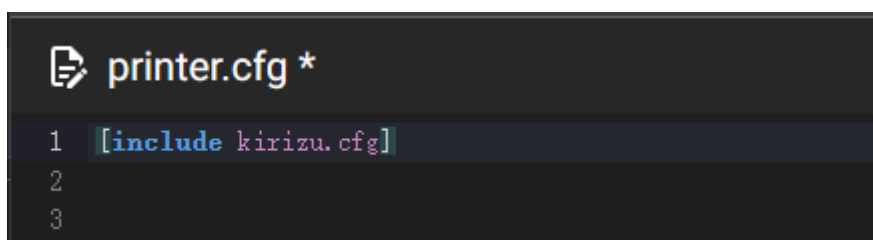
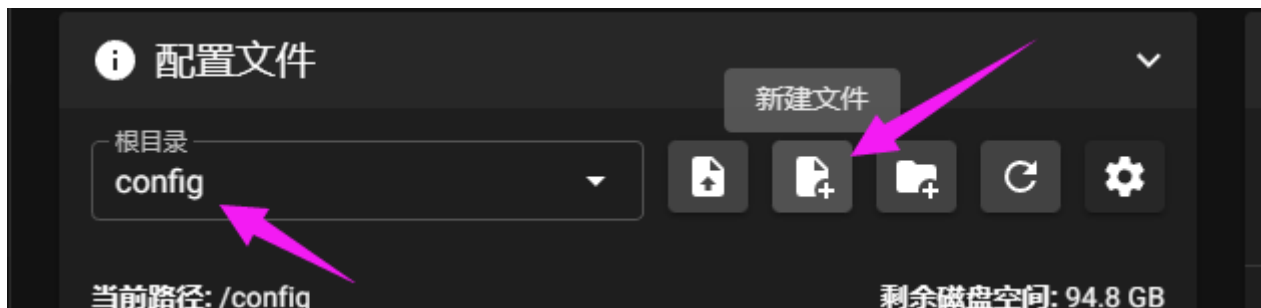


[!] 文档所有文件均可复制

首先在控制台新建一个文件，命名为“kirizu.cfg”，并且在printer.cfg中任意找个位置引入
`[include kirizu.cfg]`



归位代码

```
[gcode_macro G28]
rename_existing: G2800
variable_homing:False
gcode:
  SET_GCODE_VARIABLE MACRO=G28 VARIABLE=homing VALUE=True
  G2800 {rawparams}
  SET_GCODE_VARIABLE MACRO=G28 VARIABLE=homing VALUE=False
```

Z对齐代码

```
[gcode_macro Z_TILT_ADJUST]
rename_existing: Z_TILT_ADJUST_BASE
```

```
variable_probing:False
gcode:
  SET_GCODE_VARIABLE MACRO=Z_TILT_ADJUST VARIABLE=probing VALUE=True
  Z_TILT_ADJUST_BASE
  SET_GCODE_VARIABLE MACRO=Z_TILT_ADJUST VARIABLE=probing VALUE=False
```

床补代码

```
[gcode_macro BED_MESH_CALIBRATE]
rename_existing: BED_MESH_CALIBRATE_BASE
variable_probing:False
gcode:
  SET_GCODE_VARIABLE MACRO=BED_MESH_CALIBRATE VARIABLE=probing VALUE=True
  BED_MESH_CALIBRATE_BASE
  SET_GCODE_VARIABLE MACRO=BED_MESH_CALIBRATE VARIABLE=probing VALUE=False
```

比如我这里开启了所有功能，那么最终的配置文件为：

kirizu.cfg

```
1  [gcode_macro Z_TILT_ADJUST]
2  rename_existing: Z_TILT_ADJUST_BASE
3  variable_probing:False
4  gcode:
5      SET_GCODE_VARIABLE MACRO=Z_TILT_ADJUST VARIABLE=probing VALUE=True
6      Z_TILT_ADJUST_BASE
7      SET_GCODE_VARIABLE MACRO=Z_TILT_ADJUST VARIABLE=probing VALUE=False
8
9  [gcode_macro BED_MESH_CALIBRATE]
10 rename_existing: BED_MESH_CALIBRATE_BASE
11 variable_probing:False
12 gcode:
13     SET_GCODE_VARIABLE MACRO=BED_MESH_CALIBRATE VARIABLE=probing VALUE=True
14     BED_MESH_CALIBRATE_BASE
15     SET_GCODE_VARIABLE MACRO=BED_MESH_CALIBRATE VARIABLE=probing VALUE=False
16
17
18 [gcode_macro G28]
19 rename_existing: G2800
20 variable_homing:False
21 gcode:
22     SET_GCODE_VARIABLE MACRO=G28 VARIABLE=homing VALUE=True
23     G2800 {rawparams}
24     SET_GCODE_VARIABLE MACRO=G28 VARIABLE=homing VALUE=False
25
```

注意：如果你使用klicky需要执行以下操作，否则会和Klicky冲突：

将以下内容复制到 `kirizu.cfg` 文件中

```
[gcode_macro _HOME_Y]
gcode:
  G2800 Y0
[gcode_macro _HOME_X]
gcode:
  G2800 X0
```

找到 `klicky-macros.cfg` 文件，搜索 `G28 Z0`

```
839      _KlickyDebug msg="_Home_Z moving to Z endstop position G0 X{z_endstop_x} Y{z_endstop_y}
840      G0 X{z_endstop_x} Y{z_endstop_y} F{travel_feedrate}
841      _KlickyDebug msg="_Home_Z Homing Z G28 Z"
842      G28 Z0
843      _KlickyDebug msg="_Home_Z toolhead too low, raising it to {safe_z}mm from {printer.tool
844      G0 Z{safe_z} F{z_drop_feedrate}
845      {% endif %}
```

将其改为：

```
G2800 Z0
```

```
838      # location of z endstop
839      _KlickyDebug msg="_Home_Z moving to Z endstop position G0 X{z_endstop_x} Y{z_endstop_y} F{travel_feedrate}"
840      G0 X{z_endstop_x} Y{z_endstop_y} F{travel_feedrate}
841      _KlickyDebug msg="_Home_Z Homing Z G28 Z"
842      G2800 Z0
843      _KlickyDebug msg="_Home_Z toolhead too low, raising it to {safe_z}mm from {printer.toolhead.position.z}mm"
844      G0 Z{safe_z} F{z_drop_feedrate}
845      {% endif %}
846
847      _exit_point function=Home_Z
```

保存重启即可。