Package 'paropt'

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Type Package

Title Parameter Optimizing of ODE-Systems

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BugReports https://github.com/Konrad1991/paropt

Description Enable optimization of parameters of ordinary differential equations.
Therefore, using 'SUNDIALS' to solve the ODE-System (see Hindmarsh, Alan C., Peter N. Brown, Keith E. Grant, Steven L. Lee, Radu Serban, Dan E. Shumaker, and Carol S. Woodward. (2005) <doi:10.1145/1089014.1089020>).
Furthermore, for optimization the particle swarm algorithm is used (see: Akman, Devin, Olcay Akman, and Elsa Schaefer. (2018) <doi:10.1155/2018/9160793> and Sengupta, Saptarshi, Sanchita Basak, and Richard Peters. (2018) <doi:10.3390/make1010010>).

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Imports Rcpp (>= 1.0.4), ast2ast, methods

LinkingTo Rcpp, RcppArmadillo, RcppThread, ast2ast

Suggests knitr, rmarkdown, tinytest, deSolve

VignetteBuilder knitr

RoxygenNote 7.2.1

Encoding UTF-8

R topics documented:

| optimize | *Optimize parameters of ode-systems* |

Description

Optimize parameters used in an ode equation in order to match values defined in the state-data.frame

Usage

```
optimize(
  ode,
  lb,
  ub,
  npop,
  ngen,
  reltol,
  abstol,
  error,
  states,
  solvertype,
  verbose
)
```

Arguments

ode	the ode-system for which the parameter should be optimized.
lb	a data.frame containing the lower bounds for the parameters.
ub	a data.frame containing the upper bounds for the parameters.
npop	a number defining the number of particles used by the Particle Swarm Optimizer. The default value is 40.
ngen	a number defining the number of generations the Particle Swarm Optimizer (PSO) should run. The default value is 10000
reltol	a number defining the relative tolerance used by the ode-solver. The default value is 1e-06
abstol	a vector containing the absolute tolerance(s) for each state used by the ode-solver. The default value is 1e-08
error	a number defining a sufficient small error. When the PSO reach this value optimization is stopped. The default value is 0.0001
states	a data.frame containing the predetermined course of the states. The data.frame is used to extract the initial values of the states. Furthermore, the ode-solver returns *in silico* values of the states at the timepoints which has to be defined in the first column

solvertype	a string defining the type of solver which should be used "bdf" or "adams" are the possible values. The default value is "bdf".
	"bdf" is an abbreviation for Backward Differentiation Formulas. "adams" is an abbreviation for the Adams-Moulton algorithm
verbose	A logical value defining whether the output during compilation should be shown or not. The default value is FALSE

Details

The ode system: _____
The ode system is an R function which accepts four arguments and returns nothing.

1. the first argument is **t** whichdefines the (time-) point of then independent variable at which the ode-system is evaluated.

2. the second argument is a vector called **y** which defines the current states at timepoint **t**

3. the third argument is a vector called **ydot** which should be filled with the derivative (left hand side) of the ode-system. **do not return the vector**

4. the last argument is called **parameter** and is a vector containing the current parameter-set which is tested by the optimization algorithm.
   If the parameters can change over time. The already interpolated value is passed to the ode-system.

```
# theoretical Example: The parameter 'a' can change over time whereas 'b' is constant over time.
  parameter_set <- data.frame(
          time = c(0, 10, 20, 30, 40),
          a = c(1, 2, 3, 4, 5),
          b = c(1, NA, NA, NA, NA, NA))
  t <- 5
# Interpolation would result in 1.5 for parameter 'a'
  parameter <- c(1.5, 1) # 'a', 'b'
  y <- 1
  ydot <- vector(length(1))
  ode(t, y, ydot, parameter)
```

- The function returns nothing. It is only necessary to fill the vector **ydot**. Check the package *ast2ast* for more details how this works.

- The R function is translated to a C++ function using the package *ast2ast*, see also ast2ast on CRAN and ast2ast::translate(). Therefore, if you are starting the simulation for the first time the function has to be compiled. This can require a bit of time.

The boundaries: _____
The lower and upper boundaries are defined as data.frames that contain 'time' as the first column.
The subsequent columns contain the information of the parameter.

```
# Here some examples
# all parameters are constant over the entire integration_time
```

```
  example1 <- data.frame(
                     time = 0,
                     a = 0,
                     b = 0.1,
                     c = 0.2,
                     d = 0.2)
# The parameter a, b, and c are constant whereas the parameter d can change over time
  example2 <- data.frame(
                 time = c(0, 5, 10, 15),
                 a = c(0, NA, NA, NA),
                 b = c(0.1, NA, NA, NA),
                 c = c(0.2, NA, NA, NA),
                 d = c(0, 0.1, 0.2, 1))
# The parameter a, b are constant
# whereas parameter c and d can change over time.
# However, d is not known for all points of c
  example3 <- data.frame(
                   time = c(0, 5, 10, 15, 20, 25),
                   a = c(0, NA, NA, NA, NA, NA),
                   b = c(0.1, NA, NA, NA, NA, NA),
                   c = c(0.2, 0.2, 0, 0, 0, 0),
                   d = c(0, 0.1, 0.2, 1, NA, NA))
```

The states data.frame: _____

The states are defined as a data.frame that contains the 'time' as the first column. The subsequent
columns are the individual states.

```
# Here some examples
# Only the initial values are defined.
  example1 <- data.frame(
                     time = seq(0, 100, 0.5),
                     prey = c(10, rep(NA, 200)),
                     predator = c(10, rep(NA, 200)))
# All values are defined at each timepoint
  example2 <- data.frame(
                 time =  seq(0, 100, 0.5),
                 prey =  c(10, runif(200)),
                 predator =  c(10, runif(200)) )
# Only the values for prey are known and are used during optimization
  example3 <- data.frame(
                 time =  seq(0, 100, 0.5),
                 prey =  c(10, runif(200)),
                 predator =  c(10, rep(NA, 200)) )
```

solvertype: _____

For solving the ode system the SUNDIALS Software is used check the [Sundials homepage](#) for more
informations. The solver-type which is used during optimization: "bdf", "adams". bdf is an abbre-
viation for Backward Differentiation Formulas and adams means Adams-Moulton. All solvers are
used in the NORMAL-Step method in a for-loop using the time-points defined in the first column

of the 'states' data.frame. The bdf solver use the SUNLinSol_Dense as linear solver.

Value

A list is returned which contains three elements. The first one is the error of the best particle. Subsequently, a data.frame with the best parameters is included in the list. The last element are the *in silico* states returned from the ode-solver using the parameter-set at index 2.

Note

- The error between the defined states and the *in silico* states is a relative error calculated using the following equation:
$error = \frac{1}{num\_of\_comparisons} \sum_{n=1}^{num\_of\_states} |in\_silico_n - measured_n|$
- The optimization algorithms runs in parallel. Therefore, the ode-system should not contain any printing terms or random number generators.
- a particle swarm algorithm is used for optimization.

See Also

solve(), ast2ast::translate()

Examples

```
## Not run:
# Optimize (all parameters are constant)
ode <- function(t, y, ydot, parameter) {
  a_db = at(parameter, 1)
  b_db = at(parameter, 2)
  c_db = at(parameter, 3)
  d_db = at(parameter, 4)
  predator_db = at(y,1)
  prey_db = at(y, 2)
  ydot[1] = predator_db*prey_db*c_db - predator_db*d_db
  ydot[2] = prey_db*a_db - prey_db*predator_db*b_db
}
path <- system.file("examples", package = "paropt")
states <- read.table(paste(path,"/states_LV.txt", sep = ""), header = TRUE)
lb <- data.frame(time = 0, a = 0.8, b = 0.3, c = 0.09, d = 0.09)
ub <- data.frame(time = 0, a = 1.3, b = 0.7, c = 0.4, d = 0.7)
set.seed(1)
res <- paropt::optimize(ode,
                        lb = lb, ub = ub,
                        reltol = 1e-06, abstol = c(1e-08, 1e-08),
                        error = 0.0001,
                        npop = 40, ngen = 1000,
                        states = states)


# Optimize (parameter a,b and c are constant. d is variable!)
r <- function(a) {
  c(a, rep(NA, 3))
```

```
  }

  lb <- data.frame(time = c(0, 20, 60, 80),
                   a = r(0.8), b = r(0.3), c = r(0.09), d = 0.1)
  ub <- data.frame(time = c(0, 20, 60, 80),
                   a = r(1.3), b = r(0.7), c = r(0.4), d = 0.6)
  set.seed(1)
  res <- paropt::optimize(ode,
                          lb = lb, ub = ub,
                          reltol = 1e-06, abstol = c(1e-08, 1e-08),
                          error = 0.0001,
                          npop = 40, ngen = 10000,
                          states = states)

  ## End(Not run)
```

---

solve   *Solves an ode-system*

Description

Solves an ode equation and calculate an error based on the difference on a user-defined state-data.frame.

Usage

```
solve(
  ode,
  parameter,
  reltol,
  abstol,
  states,
  solvertype,
  verbose
)
```

Arguments

ode	the ode-system for which the parameter should be optimized.
parameter	a data.frame containing the parameters.
reltol	a number defining the relative tolerance used by the ode-solver. The default value is 1e-06
abstol	a vector containing the absolute tolerance(s) for each state used by the ode-solver. The default value is 1e-08
states	a data.frame containing the predetermined course of the states. The data.frame is used to extract the initial values of the states. Furthermore, the ode-solver returns *in silico* values of the states at the timepoints which has to be defined in the first column

solvertype	a string defining the type of solver which should be used "bdf" or "adams" are the possible values. The default value is "bdf". "bdf" is an abbreviation for Backward Differentiation Formulas. "adams" is an abbreviation for the Adams-Moulton algorithm
verbose	A logical value defining whether the output during compilation should be shown or not. The default value is FALSE

Details

The ode system: _____

The ode system is an R function which accepts four arguments and returns nothing.

1. the first argument is **t** whichdefines the (time-) point of then independent variable at which the ode-system is evaluated.

2. the second argument is a vector called **y** which defines the current states at timepoint **t**

3. the third argument is a vector called **ydot** which should be filled with the derivative (left hand side) of the ode-system. **do not return the vector**

4. the last argument is called **parameter** and is a vector containing the current parameter-set which is tested by the optimization algorithm.
   If the parameters can change over time. The already interpolated value is passed to the ode-system.

```
# theoretical Example: The parameter 'a' can change over time whereas 'b' is constant over time.
  parameter_set <- data.frame(
    time = c(0, 10, 20, 30, 40),
    a = c(1, 2, 3, 4, 5),
    b = c(1, NA, NA, NA, NA, NA))
  t <- 5
  # Interpolation would result in 1.5 for parameter 'a'
  parameter <- c(1.5, 1) # 'a', 'b'
  y <- 1
  ydot <- vector(length(1))
  ode(t, y, ydot, parameter)
```

- The function returns nothing. It is only necessary to fill the vector **ydot**. Check the package *ast2ast* for more details how this works.

- The R function is translated to a C++ function using the package *ast2ast*, see also ast2ast on CRAN and ast2ast::translate(). Therefore, if you are calling 'solve' for the first time the function has to be compiled. This can require a bit of time.

The parameters: _____

The lower and upper boundaries are defined as a data.frame that contains 'time' as the first column.
The subsequent columns contain the information of the parameter.

```
# Here some examples
```

```
    # all parameters are constant over the entire integration_time
    example1 <- data.frame(
      time = 0,
      a = 0.4,
      b = 1.1,
      c = 0.1,
      d = 0.4)
  # The parameter a, b, and c are constant whereas the parameter d can change over time
    example2 <- data.frame(
      time = c(0, 5, 10, 15),
      a = c(0.4, NA, NA, NA),
      b = c(1.1, NA, NA, NA),
      c = c(0.1, NA, NA, NA),
      d = c(0.4, 0.5, 0.3, 0.4))
    # The parameter a, b are constant
    # whereas parameter c and d can change over time.
    # However, d is not known for all points of c
    example3 <- data.frame(
      time = c(0, 5, 10, 15, 20, 25),
      a = c(1.1, NA, NA, NA, NA, NA),
      b = c(0.1, NA, NA, NA, NA, NA),
      c = c(0.2, 0.2, 0, 0, 0, 0),
      d = c(0, 0.1, 0.2, 1, NA, NA))
```

The states data.frame:

The states are defined as a data.frame that contains the 'time' as the first column. The subsequent columns are the individual states.

```
    # Here some examples
    # Only the initial values are defined.
    example1 <- data.frame(
      time = seq(0, 100, 0.5),
      prey = c(10, rep(NA, 200)),
      predator = c(10, rep(NA, 200)))
    # All values are defined at each timepoint
    example2 <- data.frame(
      time =  seq(0, 100, 0.5),
      prey =  c(10, runif(200)),
      predator =  c(10, runif(200)) )
    # Only the values for prey are known and are used during optimization
    example3 <- data.frame(
      time =  seq(0, 100, 0.5),
      prey =  c(10, runif(200)),
      predator =  c(10, rep(NA, 200)) )
```

solvertype:

For solving the ode system the SUNDIALS Software is used check the Sundials homepage for more informations. The solver-type which is used during optimization: "bdf", "adams". bdf is an abbre-

viation for Backward Differentiation Formulas and adams means Adams-Moulton. All solvers are used in the NORMAL-Step method in a for-loop using the time-points defined in the first column of the 'states' data.frame. The bdf solver use the SUNLinSol_Dense as linear solver.

Value

A list is returned which contains two elements. The first one is the error of the best particle. The other element is a data.frame containing the *in silico* states returned from the ode-solver using the parameter-set passed by the user..

Note

- The error between the defined states and the *in silico* states is a relative error calculated using the following equation:
$$error = \frac{1}{num\_of\_comparisons} \sum_{n=1}^{num\_of\_states} |in\_silico_n - measured_n|$$

See Also

optimize(), ast2ast::translate()

Examples

```
   ## Not run:
# Solve an ode-system
ode <- function(t, y, ydot, parameter) {
  a_db = at(parameter, 1)
  b_db = at(parameter, 2)
  c_db = at(parameter, 3)
  d_db = at(parameter, 4)
  predator_db = at(y,1)
  prey_db = at(y, 2)
  ydot[1] = predator_db*prey_db*c_db - predator_db*d_db
  ydot[2] = prey_db*a_db - prey_db*predator_db*b_db
}
path <- system.file("examples", package = "paropt")
states <- read.table(paste(path,"/states_LV.txt", sep = ""), header = TRUE)
parameter <- data.frame(time = 0, a = 1.1, b = 0.4, c = 0.1, d = 0.4)
res <- paropt::solve(ode,
                     parameter = parameter,
                     reltol = 1e-06, abstol = c(1e-08, 1e-08),
                     states = states, verbose = FALSE)

## End(Not run)
```

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