

optimized stiffened equivalent ellipsoidal shell; multiplier, PB=0, for inward cos(theta) normal line Igad. PA= 0.0 PB= 0.0 PX= 0.0; the shell is unloaded and has a residual dent.  $\Theta$  x -0.00 Step 67 displacement w contours for residual dent (PB = 0.)  $\Theta$  y 0.00 Normalized Pi z -0.00 Normalized PB = 0. Open Signature (PB = 0.)  $\Theta$  z -0.00 Normalized PB = 0. Open

Fig. 265 The optimized isogrid-stiffened equivalent ellipsoidal shell; Wimp=0.2 inch; the optimum design is listed in columns 2 and 3 of Table 33. State of the shell at load set B (PB) step no. 67 in Run 2 (residual dent). (See Fig. 263). Load set B consists of a number of concentrated inward directed normal loads applied along row 2 of shell segment 2 (Figs. 2, 169, 258, 259, and 264) distributed in the circumferential direction as cos(theta) from theta = 0 to 90 degrees. This "cos(theta)" load distribution is used because it generates a residual dent that locally resembles the negative of the buckling modal deformation in Figs. 258 and 259, that is, the negative of the linear buckling modal imperfection with n = 1 circumferential wave. Compare with Fig. 240. Here the residual dent is significantly deeper than the depth, Wimp=0.2 inch, of each of the two axisymmetric buckling modal imperfections, mode 1 and mode 2, for which the optimum design was obtained.