

optimized stiffened equivalent ellipsoidal shell; imposed normal displacement w (load set B) removed.

PA= 0.0 PB= 0.0 PX= 0.0; the shell is unloaded and has a residual dent. Θ x -0.00 Θ y 0.00 step 158 displacement w contours for residual dent Θ z -0.00 nonlinear w; cos(theta) imposed w along row no. 5 of shell segment no. 4 (see Fig.2) removed x subroutine usrfab.soccerball.plastic.src is used with NGCP = 1 Θ 9.900E+00 Θ Fig. 271 The optimized isogrid-stiffened equivalent ellipsoidal shell; Wimp=0.2 inch;

Fig. 271 The optimized isogrid-stiffened equivalent ellipsoidal shell; Wimp=0.2 inch; the optimum design is listed in columns 2 and 3 of Table 33. State of the shell at load set B (PB) step no. 158 in Run 4 (residual dent). (See Fig. 270). Load set B consists of a number of concentrated inward directed normal displacements applied along row 5 of shell segment 4 (Figs. 2, 169, 262) distributed in the circumferential direction as cos(theta) from theta = 0 to 90 degrees. This "cos(theta)" displacement distribution is used because it generates a residual dent that locally resembles the negative of the buckling modal deformation in Fig. 262, that is, the negative of the second linear buckling modal imperfection with n = 1 circumferential wave. Compare with Fig. 269. Here the residual dent is somewhat deeper than the depth, Wimp=0.2 inch, of each of the two axisymmetric buckling modal imperfections, mode 1 and mode 2, for which the optimum design was obtained.