

Table 8, p.14 of 18

The postscript file is called "metafile.ps" (Fig. 26)..)

**cleanup** (clean up BIGBOSOR4 files called "test" and generate the version of test.ALL and test.DOC with proper annotation throughout.)

(Next, we wish to obtain a plot of the critical GENERAL buckling mode from execution of BIGBOSOR4 and BOSORPLOT for the case with all factors of safety greater than 1.0:)

(Copy the BIGBOSOR4 input file for GENERAL buckling, test.BEHX2, into test.ALL because BIGBOSOR4 input files must always have the three-letter suffix, ".ALL":)

cp test.BEHX2 test.ALL

**bigbosorall** (Start "batch" run for GENERAL buckling. The output file that you want to inspect is called test.OUT. This will be a very, very long file, so search specifically for the string, "EIGENVALUE()", typed with the "(" at the end of the string. You will find the following output there:

---

```
***** CRITICAL EIGENVALUE AND WAVENUMBER *****
EIGCRT= 2.0048E+00; NO. OF CIRC. WAVES, NWVCRT= 300
*****
```

---

```
***** EIGENVALUES AND MODE SHAPES *****
EIGENVALUE(CIRC. WAVES)
=====
2.5384E+00( 100)
2.0644E+00( 200)
2.0048E+00( 300)
2.1052E+00( 400)
2.2525E+00( 500)
=====
```

---

**bosorplot** (obtain a plot of the critical GENERAL buckling mode. The postscript file is called "metafile.ps" (Fig. 27)..)

**cleanup** (clean up BIGBOSOR4 files called "test.\*")

(Next, return to the "genoptcase" directory, and continue processing the SPECIFIC case called "test".)

cd /home/progs/genoptcase

(Next, do a convergence study of the prediction of local buckling vs the number of modules, NMODULL, used in the local buckling model). *see p.16*

**cleanspec** (clean up the SPECIFIC files, test.\*)

(Edit the test.BEG file to change the number of modules used for local buckling from NMODULL = 1 to NMODULL = 2 .)

**begin** (execute BEGIN, using the file, test.BEG, for input Table 14 with Table 27 changes in factors of safety and with NMODULL changed from 1 to 2)

**change** (execute CHANGE, using the file, test.CHG for input (Table 29))

**decide** (execute DECIDE, using the file, test.DEC, for input (Table 15))

**mainsetup** (execute MAINSETUP, using the file, test.OPT, for input. Make sure that NPRINT = 2 and ITYPE = 2 in test.OPT.)

**optimize** (generate the test.OPM file for the fixed design)

cp test.BEHX1 /home/progs/bigbosor4/workspace/test.ALL (LOCAL buckling input)

cd /home/progs/bigbosor4/workspace

**bigbosor4log** (activate BIGBOSOR4 commands)

**bigbosorall** (execute BIGBOSOR4)

(Search for the string, "EIGENVALUE(" and find eigenvalue vx. circumferential waves)

```

bosorplot      (get the file, metafile.ps, for 700 circ. waves (Fig. 28))
cleanup        (clean up BIGBOSOR4 files, test.*)

cd /home/progs/genoptcase

cleanspec      (clean up the SPECIFIC files, test.*)

(Edit the test.BEG file to change the number of modules used for
local buckling from NMODULL = 2 to NMODULL = 3 .)

begin          (execute BEGIN, using the file, test.BEG, for input)
change         (execute CHANGE, using the file, test.CHG for input (Table 29))
decide         (execute DECIDE, using the file, test.DEC, for input (Table 15))
mainsetup      (execute MAINSETUP, using the file, test.OPT, for input.
               Make sure that NPRINT = 2 and ITYPE = 2 in test.OPT.)
optimize       (generate the test.OPM file for the fixed design)

cp test.BEHX1 /home/progs/bigbosor4/workspace/test.ALL (LOCAL buckling input)

cd /home/progs/bigbosor4/workspace

bigbosor4log  (activate BIGBOSOR4 commands)
bigbosorall   (execute BIGBOSOR4)

(Search for the string, "EIGENVALUE(" and find eigenvalue vx. circumferential
waves)

bosorplot      (get the file, metafile.ps, for 700 circ. waves (Fig. 29))
cleanup        (clean up BIGBOSOR4 files, test.*)

cd /home/progs/genoptcase

cleanspec      (clean up the SPECIFIC files, test.*)

(Edit the test.BEG file to change the number of modules used for
local buckling from NMODULL = 3 to NMODULL = 13 (maximum permitted).)

begin          (execute BEGIN, using the file, test.BEG, for input)
change         (execute CHANGE, using the file, test.CHG for input (Table 29))
decide         (execute DECIDE, using the file, test.DEC, for input (Table 15))
mainsetup      (execute MAINSETUP, using the file, test.OPT, for input.
               Make sure that NPRINT = 2 and ITYPE = 2 in test.OPT.)
optimize       (generate the test.OPM file for the fixed design)

cp test.BEHX1 /home/progs/bigbosor4/workspace/test.ALL (LOCAL buckling input)

cd /home/progs/bigbosor4/workspace

bigbosor4log  (activate BIGBOSOR4 commands)
bigbosorall   (execute BIGBOSOR4)

(Search for the string, "EIGENVALUE(" and find eigenvalue vx. circumferential
waves)

bosorplot      (get the file, metafile.ps, for 700 circ. waves (Fig. 30))
cleanup        (clean up BIGBOSOR4 files, test.*)

```

[Next we wish to compare predictions for local buckling of the optimized
design listed in Table 28 from a BIGBOSOR4 model and from a PANDA2 model.
For local buckling of a truss-core sandwich, PANDA2 uses a single discretized

see p.16

# Table 8, p.16 of 18

module model that very much resembles the single general buckling module used in this "trusscomp" project. A sketch of the single module model used in PANDA2 is presented on page 1 of Table 7. The output for local buckling from PANDA2 for the optimum design obtained in the "nasatruss" project appears at the top of page 3 of Table 7. We wish to generate that type of output from PANDA2 for the optimum "trusscomp" design listed in Table 28. Then we want to compare the PANDA2 predictions with those from BIGBOSOR4 for the optimum "trusscomp" configuration modeled as is done for general buckling, that is, a multi-module model with only six shell segments in each module, as depicted in Fig. 4 and at the top of Fig. 6. The following run stream will accomplish this.]

[First, find where the "nasatruss" files, nasatruss.BEG, nasatruss.DEC, and nasatruss.OPT are stored. (e.g. ...genopt/case/truss3) The "nasatruss" files that we want are contained in the nasatruss.tar file. Copy this file to a working space for PANDA2 executions and "untar" it:

```
cp /home/progs/panda2/case/truss3/nasatruss.tar /home/progs/panda2/workspace/.
cd /home/progs/panda2/workspace
tar xvf nasatruss.tar
```

[Find nasatruss.BEG, nasatruss.DEC, nasatruss.OPT, and copy these files to files with a relevant name, such as comprtruss.BEG, etc:]

```
cp nasatruss.BEG comprtruss.BEG
cp nasatruss.DEC comprtruss.DEC
cp nasatruss.OPT comprtruss.OPT
```

(Edit the comprtruss.BEG file by replacing three values there with the appropriate optimized values listed on the first page of Table 28. The three quantities in the nasatruss.BEG file,

```
3.700000      $ pitch of truss core, b
0.7000000     $ width over which truss core contacts each face sheet, b2
1.400000      $ height of truss, h
```

must be replaced by the following optimum values from the "trusscomp" project:

```
2.810600      $ pitch of truss core, b
1.000400      $ width over which truss core contacts each face sheet, b2
0.888720      $ height of truss, h
```

The rest of the comprtruss file needs no further changes. The comprtruss.DEC file needs no changing. In the comprtruss.OPT file make sure that the initial imperfection components are all zero and that ITYPE = 2 (analysis of a fixed design). Then give the following commands:]

```
panda2log      (activate the PANDA2 command set)
begin          (use comprtruss.BEG as input)
setup          (no input required from the user)
decide         (use comprtruss.DEC as input)
mainsetup      (use comprtruss.OPT, suitably edited, as input)
pandaopt       (execute PANDA2 in the fixed design (ITYPE=2) mode)
```

[Inspect the test.OPM file. In particular, we are interested in local buckling results for which the PANDA2 single discretized module model is used. Search for the string, "EIGOLD". This will lead you to the following output in the test.OPM file obtained from the execution of pandaopt:]

---

BUCKLING LOAD FACTORS FROM BOSOR4-TYPE DISCRETIZED MODEL...				
(skin-stringer discretized module of local buckling)				
AXIAL	BUCKLING	KNOCKDOWN FOR	KNOCKDOWN FOR	BUCKLING
HALF-	LOAD FACTOR	TRANSVERSE SHEAR	IN-PLANE SHEAR	LOAD FACTOR
WAVES	BEFORE KNOCKDOWN	DEFORMATION	LOADING AND/OR	AFTER KNOCKDOWN
			ANISOTROPY	
M	EIGOLD	KSTAR	KNOCK	EIGOLD*KSTAR*KNOCK
57	1.26900E+00	1.00000E+00	9.97192E-01	1.26543E+00
61	1.24883E+00	1.00000E+00	9.97192E-01	1.24532E+00
66	1.24861E+00	1.00000E+00	9.97192E-01	1.24510E+00

```

71      1.23999E+00      1.00000E+00      9.97192E-01      1.23651E+00
76      1.25295E+00      1.00000E+00      9.97192E-01      1.24943E+00
Buckling load factor before t.s.d.= 1.2365E+00 After t.s.d.= 1.1674E+00
70      1.23999E+00      9.44586E-01      9.97192E-01      1.16736E+00
-----
```

(The critical local buckling mode has 70 axial half-waves over the 96-inch length of the cylindrical shell.

This same PANDA2 output appears at the bottom of Table 31. Next, we want to compare these PANDA2 results with "equivalent" results from our use of the "trusscomp" project procedures.)

(Next, return to the "genoptcase" directory, and continue processing the SPECIFIC case called "test".)

```
cd /home/progs/genoptcase
```

```
genoptlog      (activate the GENOPT commands)
```

```
cleanspec      (clean up the "test" files)
```

[Edit the begin file, test.BEG, listed in Table 14. Set very small values for ENOODL and DNOODL, as follows:  
0.1851110E+00 \$ axial modulus of a corner "noodle": ENOODL  
0.5700000E-08 \$ weight density of the "noodle" material: DNOODL  
This gets rid of the effect of the "noodles", which are not present in the PANDA2 model of the composite truss-core sandwich.]

```
begin          (execute begin, using the suitably edited test.BEG file)
```

```
change         (execute CHANGE with the test.CHG file listed in Table 29 as input)
```

```
decide        (execute DECIDE with test.DEC in Table 15 as input)
```

```
mainsetup     (execute MAINSETUP with test.OPT as listed at the top of Table 28 as input)
```

```
optimize       (execute OPTIMIZE in the ITYPE=2 mode of operation)
```

[OPTIMIZE with ITYPE = 2 generates the two valid input files for BIGBOSOR4, test.BEHX1 and test.BEHX2. Now we are interested only in the file, test.BEHX2 (general buckling model). That is because the general buckling single module (6 shell segments) is very similar to the discretized single module model used by PANDA2 for computing local buckling.)

```
cp /home/progs/genoptcase/test.BEHX2 /home/progs/bigbosor4/workspace/test.ALL
```

```
cd /home/progs/bigbosor4/workspace
```

```
bigbosor4log   (activate BIGBOSOR4 commands)
```

```
bigbosorall    (execute BIGBOSOR4 with test.ALL as input)
```

[This execution of bigbosorall will yield the output file, test.OUT which contains the following general buckling loads:]

```
***** CRITICAL EIGENVALUE AND WAVENUMBER *****
EIGCRT= 1.9480E+00; NO. OF CIRC. WAVES, NWVCRT= 300
*****
```

```
***** EIGENVALUES AND MODE SHAPES *****
EIGENVALUE(CIRC. WAVES)
=====
```

```
2.4656E+00( 100)
2.0161E+00( 200)
1.9480E+00( 300)
2.0364E+00( 400)
2.1631E+00( 500)
=====
```

[The eigenvalues above are slightly lower than those listed for general buckling on page 2 of Table 28 because we have taken away the "noodles" by suitably editing the test.BEG file, as described earlier.]

# Table 8, p.18 of 18

[For now we are not interested in the general buckling eigenvalues because we want to simulate local buckling with use of the general buckling "trusscomp" model. To obtain local buckling eigenvalues we must compute results for a much higher range of wave numbers. PANDA2 estimates that there are about 70 axial half-waves along the 96-inch length of the cylindrical shell. 70 axial half-waves over the 96-inch length of the cylindrical shell corresponds to 7000 circumferential waves around the "huge torus" (see Appendix 1 for an explanation of the factor of 100). In order to explore the high-N range of wave numbers, we must edit the test.ALL file. However, the version of test.ALL generated by SUBROUTINE BEHX2, called test.BEHX2, is not properly annotated. Therefore, it is difficult for the user to find where to do the suitable editing. In order to obtain a suitably annotated test.ALL file, you must type the following command:]

cleanup	(deletes unneeded BIGBOSOR4 "test" files and generates a properly annotated test.ALL file and a properly annotated test.DOC file. Table 18 is an abridged version, except for the "noodle" axial stiffness, ENOODL, and density, DNOODL, and therefore also the "noodle" prebuckling loads.)
---------	--

[In the properly annotated test.ALL file we find the following lines:]

---

H	\$ GLOBAL DATA BEGINS...
0	\$ NLAST = plot options (-1=none, 0=geometry, 1=u,v,w)
N	\$ Are there any regions for which you want expanded plots?
100	\$ NOB = starting number of circ. waves (buckling analysis)
100	\$ NMINB = minimum number of circ. waves (buckling analysis)
500	\$ NMAXB = maximum number of circ. waves (buckling analysis)
100	\$ INCRB = increment in number of circ. waves (buckling)
1	\$ NVEC = number of eigenvalues for each wave number

---

[We arrive at this section in the very long test.ALL file by searching for the string, "NOB" (N - zero - B). We wish now to change these input data to the values listed near the top of Table 31. Note that nothing else in the test.ALL file need be changed. We are simply exploring a different range of circumferential wave numbers for buckling of exactly the same model as that used for the prediction of general buckling modes of the type shown in Fig. 27. In the new input we want to obtain 3 eigenvalues for each circumferential wave number. Why is that? Because the first two eigenvalues might well correspond to edge buckling, not to real local buckling of a complete (360-degree) cylindrical shell. (See the small inserts in the two figures in Appendix 1 for samples of edge buckling.) We execute BIGBOSORALL again:]

bigbosorall	(execute BIGBOSOR4)
bosorplot	(execute BOSORPLOT repeatedly until you see everthing you want to see.)

[Inspect the test.OUT file. Search for the string, "EIGENVALUE(" and find the output similar to that listed in the middle of Table 31. Figures 34, 35, and 36 show the critical first, second, and third eigenvalues. The first two eigenvalues correspond to edge buckling, which we are not interested in. The third eigenvalue represents true local buckling.]

---

end of runstream in "trusscomp"/"test"

# Table 9 trusscomp.INP (14 pages)

```

5 $ starting prompt index in the file trusscomp.PRO
5 $ increment for prompt index
0 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
Please read the report:
y      $ Are there more lines in the "help" paragraph?

y      $ Are there more lines in the "help" paragraph?
"Use of GENOPT and BIGBOSOR4 to obtain optimum designs
y      $ Are there more lines in the "help" paragraph?
of a cylindrical shell with a composite truss-core
y      $ Are there more lines in the "help" paragraph?
sandwich wall", David Bushnell, June 20, 2009
y      $ Are there more lines in the "help" paragraph?

y      $ Are there more lines in the "help" paragraph?
This GENOPT case is for a cylindrical shell the wall of
y      $ Are there more lines in the "help" paragraph?
which is a truss-core sandwich. Each segment of a truss-
y      $ Are there more lines in the "help" paragraph?
core sandwich module is a composite laminate. Hence, the
y      $ Are there more lines in the "help" paragraph?
name, "trusscomp". A truss-core module here consists of
y      $ Are there more lines in the "help" paragraph?
22 shell segments of the type used in BIGBOSOR4. General
y      $ Are there more lines in the "help" paragraph?
and local buckling load factors are determined from
y      $ Are there more lines in the "help" paragraph?
BIGBOSOR4. The shell is modeled as a part of a "huge
y      $ Are there more lines in the "help" paragraph?
torus". A membrane prebuckled state is assumed to exist.
y      $ Are there more lines in the "help" paragraph?
The axial resultant in each module segment is assumed to
y      $ Are there more lines in the "help" paragraph?
be proportional to the axial stiffness of that segment.
y      $ Are there more lines in the "help" paragraph?
Local buckling is determined from a single module.
y      $ Are there more lines in the "help" paragraph?
General buckling is determined from a number of analogous
y      $ Are there more lines in the "help" paragraph?
simpler modules strung together. The stress constraints
y      $ Are there more lines in the "help" paragraph?
are computed from a much simplified version of the code
y      $ Are there more lines in the "help" paragraph?
in SUBROUTINE STRTHX of BIGBOSOR4, simplified because
y      $ Are there more lines in the "help" paragraph?
the prebuckled state is a membrane state. The stresses
y      $ Are there more lines in the "help" paragraph?
are computed in each layer in each truss-core sandwich,
y      $ Are there more lines in the "help" paragraph?
segment.
y      $ Are there more lines in the "help" paragraph?

y      $ Are there more lines in the "help" paragraph?
Occasionally an optimization run with SUPEROPT may
y      $ Are there more lines in the "help" paragraph?
abort early. If this happens, inspect the end of the
y      $ Are there more lines in the "help" paragraph?
xxx.OUT file to see if there are any error messages. You
y      $ Are there more lines in the "help" paragraph?
may have to modify your inequality constraints in the
y      $ Are there more lines in the "help" paragraph?
xxx*DEC file (input to "DECIDE") in order to avoid
y      $ Are there more lines in the "help" paragraph?
an early and unexpected termination of the SUPEROPT run.
y      $ Are there more lines in the "help" paragraph?
Most of the early terminations of the SUPEROPT run can
y      $ Are there more lines in the "help" paragraph?
be avoided by increasing the lower bound of the thickness
y      $ Are there more lines in the "help" paragraph?
of the truss-core, that is, increasing the lower bound
y      $ Are there more lines in the "help" paragraph?
of the variable called "HEIGHT".
n      $ Are there more lines in the "help" paragraph?
1 $ Type of prompt: 0="help" paragraph, 1=one-line prompt

LENGTH   $ Name of a variable in the users program (defined below)
2 $ Role of the variable in the users program
2 $ type of variable: 1 =integer, 2 =floating point

```

Input for  
GENTEXT

Note: GENTEXT  
destroys old versions  
behavior. New  
struct. new

Therefore, make sure  
you save old versions  
of behavior. New &  
struct. new that you  
want to have for  
future use.

Table 9, p 2 of 14

```

n      $ Is the variable LENGTH an array?
length of the cylindrical shell
Y      $ Do you want to include a "help" paragraph?
NOTE: the cylindrical shell is assumed to be simply
Y      $ Any more lines in the "help" paragraph?
supported along its two curved ends.
n      $ Any more lines in the "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $10
      0 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
Next you will be asked to provide the fraction
Y      $ Are there more lines in the "help" paragraph?
of the shell axial length to be used in the
Y      $ Are there more lines in the "help" paragraph?
local buckling analysis. If the shell is
Y      $ Are there more lines in the "help" paragraph?
subjected to uniform end shortening (axial
Y      $ Are there more lines in the "help" paragraph?
compression), then this fraction of the total
Y      $ Are there more lines in the "help" paragraph?
shell length can be estimated by assuming that
Y      $ Are there more lines in the "help" paragraph?
the critical buckling mode will have approximately
Y      $ Are there more lines in the "help" paragraph?
square buckles. The portion of the truss-core
Y      $ Are there more lines in the "help" paragraph?
sandwich most likely to buckle may well have the
Y      $ Are there more lines in the "help" paragraph?
longest unsupported width. Suppose the total
Y      $ Are there more lines in the "help" paragraph?
length of the cylindrical shell is 100 inches.
Y      $ Are there more lines in the "help" paragraph?
Suppose the width of the segment of the truss-core
Y      $ Are there more lines in the "help" paragraph?
sandwich most likely to buckle locally is 2 inches.
Y      $ Are there more lines in the "help" paragraph?
Then, for square buckles, the critical local buckling
Y      $ Are there more lines in the "help" paragraph?
mode will have approximately 50 half-waves along
Y      $ Are there more lines in the "help" paragraph?
the total axial length of the cylindrical shell.
Y      $ Are there more lines in the "help" paragraph?
In order to save computer time you don't want to
Y      $ Are there more lines in the "help" paragraph?
have to search over a large range of axial half-waves.
Y      $ Are there more lines in the "help" paragraph?
Therefore, in this example, choose a fraction, FACLEN,
Y      $ Are there more lines in the "help" paragraph?
of axial length equal to about 1/10th (FACLEN=0.1). Then
Y      $ Are there more lines in the "help" paragraph?
the critical local buckling mode will have about 5 axial
Y      $ Are there more lines in the "help" paragraph?
half-waves over the length,  $0.1 \times \text{LENGTH} = 10$  inches,
Y      $ Are there more lines in the "help" paragraph?
and you can establish the range of axial half-waves
Y      $ Are there more lines in the "help" paragraph?
to be covered to be from 1 to 10 axial halfwaves.
Y      $ Are there more lines in the "help" paragraph?
(MLOWL = 1, MHIGHL = 10). The probable critical
Y      $ Are there more lines in the "help" paragraph?
buckling mode will probably be somewhere in the
Y      $ Are there more lines in the "help" paragraph?
middle of this range.
n      $ Are there more lines in the "help" paragraph?
      1 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
FACLEN $ Name of a variable in the users program (defined below)
      2 $ Role of the variable in the users program
      2 $ type of variable: 1 =integer, 2 =floating point
n      $ Is the variable FACLEN an array?
fraction of LENGTH for local buckling
Y      $ Do you want to include a "help" paragraph?
If the cylindrical shell is subjected to axial compression
Y      $ Any more lines in the "help" paragraph?
set FACLEN such that if the local buckles are square the
Y      $ Any more lines in the "help" paragraph?
critical local buckling mode will fall in the middle of
Y      $ Any more lines in the "help" paragraph?
the range of axial wave numbers, MLOWL to MHIGHL, that
Y      $ Any more lines in the "help" paragraph?

```

# Table 9, p. 3 of 14

you will later establish during this interactive session.

n \$ Any more lines in the "help" paragraph?

y \$ Any more variables for role types 1 or 2 ? \$20

1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt

RADIUS \$ Name of a variable in the users program (defined below)

2 \$ Role of the variable in the users program

2 \$ type of variable: 1 =integer, 2 =floating point

n \$ Is the variable RADIUS an array?

radius of the cylindrical shell

y \$ Do you want to include a "help" paragraph?

This is the radius to the INNER face sheet of the

y \$ Any more lines in the "help" paragraph?

truss-core sandwich wall.

n \$ Any more lines in the "help" paragraph?

y \$ Any more variables for role types 1 or 2 ? \$25

1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt

PITCH \$ Name of a variable in the users program (defined below)

1 \$ Role of the variable in the users program

n \$ Is the variable PITCH an array?

circumferential width of a single module

y \$ Do you want to include a "help" paragraph?

A single module consists essentially of one "upside-

y \$ Any more lines in the "help" paragraph?

down" trapezoid and its adjacent "right-side-up"

y \$ Any more lines in the "help" paragraph?

neighbor. There are 22 shell segments in the single

y \$ Any more lines in the "help" paragraph?

truss-core sandwich module. (See Figs. 1 and 2).

y \$ Any more lines in the "help" paragraph?

PITCH is called "b" in Fig. 1.

n \$ Any more lines in the "help" paragraph?

y \$ Any more variables for role types 1 or 2 ? \$30

1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt

BCROWN \$ Name of a variable in the users program (defined below)

1 \$ Role of the variable in the users program

n \$ Is the variable BCROWN an array?

circumferential width of the trapezoid crown

y \$ Do you want to include a "help" paragraph?

BCROWN is the width of the narrow horizontal face of

y \$ Any more lines in the "help" paragraph?

the trapezoid. BCROWN is called "b2" in Fig. 1.

n \$ Any more lines in the "help" paragraph?

y \$ Any more variables for role types 1 or 2 ? \$35

1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt

HEIGHT \$ Name of a variable in the users program (defined below)

1 \$ Role of the variable in the users program

n \$ Is the variable HEIGHT an array?

height of the truss-core sandwich

y \$ Do you want to include a "help" paragraph?

HEIGHT is measured from the middle surface of the

y \$ Any more lines in the "help" paragraph?

bottom face sheet to the middle surface of the top

y \$ Any more lines in the "help" paragraph?

face sheet. HEIGHT is called "h" in Fig. 1.

n \$ Any more lines in the "help" paragraph?

y \$ Any more variables for role types 1 or 2 ? \$40

1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt

RACUTE \$ Name of a variable in the users program (defined below)

1 \$ Role of the variable in the users program

n \$ Is the variable RACUTE an array?

local radius from base to side of trapezoidal tool

y \$ Do you want to include a "help" paragraph?

RACUTE is the transition radius by means of which

y \$ Any more lines in the "help" paragraph?

the base surface of the trapezoidal tool is smoothly

y \$ Any more lines in the "help" paragraph?

faired into the sloping side walls of the trapezoidal

y \$ Any more lines in the "help" paragraph?

tool. The trapezoidal tool is the object around which

y \$ Any more lines in the "help" paragraph?

the layers of the core laminate are laid up. RACUTE

y \$ Any more lines in the "help" paragraph?

is the radius that spans the acute angle from trapezoid

y \$ Any more lines in the "help" paragraph?

base to trapezoid sloping sides. RACUTE is similar

y \$ Any more lines in the "help" paragraph?

to the dimension called "R1" in Fig. 1.

y \$ Any more lines in the "help" paragraph?

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```

(R1 = RACUTE + total thickness of shell segment 5).
n      $ Any more lines in the "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $45
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
ROBTUS  $ Name of a variable in the users program (defined below)
1  $ Role of the variable in the users program
n      $ Is the variable ROBTUS an array?
local radius from side to crown of trapezoidal tool
Y      $ Do you want to include a "help" paragraph?
ROBTUS is the radius that fairs each side wall of the
Y      $ Any more lines in the "help" paragraph?
trapezoidal tool into the crown of the trapezoidal
Y      $ Any more lines in the "help" paragraph?
tool. The trapezoidal tool is the object around which
Y      $ Any more lines in the "help" paragraph?
the core laminate is laid up. ROBTUS is the radius
Y      $ Any more lines in the "help" paragraph?
that spans the obtuse angle from trapezoid crown to
Y      $ Any more lines in the "help" paragraph?
trapezoid sloping sides. ROBTUS is similar
Y      $ Any more lines in the "help" paragraph?
to the dimension called "R2" in Fig. 1.
Y      $ Any more lines in the "help" paragraph?
(R2 = ROBTUS + total thickness of shell segment 2).
n      $ Any more lines in the "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $50
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
ENOODL  $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
2  $ type of variable: 1 =integer, 2 =floating point
n      $ Is the variable ENOODL an array?
axial modulus of a corner "noodle"
Y      $ Do you want to include a "help" paragraph?
ENOODL is the axial modulus of the "noodle"
Y      $ Any more lines in the "help" paragraph?
material. A "noodle" is the material that is
Y      $ Any more lines in the "help" paragraph?
fills a "corner" between adjacent trapezoidal
Y      $ Any more lines in the "help" paragraph?
core segments. Each truss-core sandwich module has
Y      $ Any more lines in the "help" paragraph?
four "noodles", two at the bottom and two at the top
Y      $ Any more lines in the "help" paragraph?
of the single module. The "noodles" fit into the
Y      $ Any more lines in the "help" paragraph?
sort of triangular gaps adjacent to the slanted
Y      $ Any more lines in the "help" paragraph?
core walls and the bottom and top face sheets. For
Y      $ Any more lines in the "help" paragraph?
example, one of the "triangular" gaps shown in Fig. 1
Y      $ Any more lines in the "help" paragraph?
is the small region enclosed by shell segments 2, 3,
Y      $ Any more lines in the "help" paragraph?
4, and 5. ENOODL is the axial modulus of the
Y      $ Any more lines in the "help" paragraph?
material that fills each of the four "triangular"
Y      $ Any more lines in the "help" paragraph?
prismatic cavities in the single truss-core sandwich
Y      $ Any more lines in the "help" paragraph?
module.
n      $ Any more lines in the "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $55
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
DNOODL  $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
2  $ type of variable: 1 =integer, 2 =floating point
n      $ Is the variable DNOODL an array?
weight density of the "noodle" material
Y      $ Do you want to include a "help" paragraph?
ENOODL is the density analogous to that of
Y      $ Any more lines in the "help" paragraph?
aluminum's weight density of 0.1 lb/in^3. Usually,
Y      $ Any more lines in the "help" paragraph?
the "noodle" will be made from the same material
Y      $ Any more lines in the "help" paragraph?
as one of the layers in the truss-core. If so,
Y      $ Any more lines in the "help" paragraph?
just use the same value for DNOODL as you will

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Y \$ Any more lines in the "help" paragraph?  
 use later for the material density of one  
 Y \$ Any more lines in the "help" paragraph?  
 of the layers in the truss-core laminate.  
 n \$ Any more lines in the "help" paragraph?  
 Y \$ Any more variables for role types 1 or 2 ? \$60  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 EFOUND \$ Name of a variable in the users program (defined below)  
 2 \$ Role of the variable in the users program  
 2 \$ type of variable: 1 =integer, 2 =floating point  
 n \$ Is the variable EFOUND an array?  
 elastic foam "Winkler" foundation stiffness  
 Y \$ Do you want to include a "help" paragraph?  
 EFOUND is used only for the LOCAL buckling analysis.  
 Y \$ Any more lines in the "help" paragraph?  
 The volume inside the truss-core sandwich may  
 Y \$ Any more lines in the "help" paragraph?  
 be filled with an elastic foam that is bonded  
 Y \$ Any more lines in the "help" paragraph?  
 to the face sheets and sloping side walls of  
 Y \$ Any more lines in the "help" paragraph?  
 the core. A Winkler foundation is assumed. A Winkler  
 Y \$ Any more lines in the "help" paragraph?  
 foundation reacts only normal to the shell surface;  
 Y \$ Any more lines in the "help" paragraph?  
 it is like an array of closely spaced springs  
 Y \$ Any more lines in the "help" paragraph?  
 oriented normal to the shell surface. Units of the  
 Y \$ Any more lines in the "help" paragraph?  
 foundation stiffness, K, are force per length  
 Y \$ Any more lines in the "help" paragraph?  
 cubed (lb/in\*\*3, for example). IMPORTANT NOTE:  
 Y \$ Any more lines in the "help" paragraph?  
 The elastic foundation is assumed to be connected  
 Y \$ Any more lines in the "help" paragraph?  
 to GROUND. Therefore, the elastic foam inside each  
 Y \$ Any more lines in the "help" paragraph?  
 truss core module CANNOT TRANSLATE AND ROTATE AS  
 Y \$ Any more lines in the "help" paragraph?  
 A RIGID BODY. Hence, the elastic foam is assumed  
 Y \$ Any more lines in the "help" paragraph?  
 to be present ONLY IN THE LOCAL BUCKLING ANALYSIS.  
 Y \$ Any more lines in the "help" paragraph?  
 Still, it is probably somewhat unconservative to  
 Y \$ Any more lines in the "help" paragraph?  
 include a non-zero EFOUND in your model unless  
 Y \$ Any more lines in the "help" paragraph?  
 you use a significantly conservative value for  
 Y \$ Any more lines in the "help" paragraph?  
 EFNOOD, that is, an underestimate of what you think  
 Y \$ Any more lines in the "help" paragraph?  
 EFNOOD might actually be. It is probably best first  
 Y \$ Any more lines in the "help" paragraph?  
 to optimize with EFNOOD = 0.0, then re-optimize  
 Y \$ Any more lines in the "help" paragraph?  
 with some small non-zero value of EFNOOD later.  
 n \$ Any more lines in the "help" paragraph?  
 Y \$ Any more variables for role types 1 or 2 ? \$65  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 EFNOOD \$ Name of a variable in the users program (defined below)  
 2 \$ Role of the variable in the users program  
 2 \$ type of variable: 1 =integer, 2 =floating point  
 n \$ Is the variable EFNOOD an array?  
 elastic "noodle" Winkler foundation modulus  
 Y \$ Do you want to include a "help" paragraph?  
 EFNOOD is used only for the LOCAL buckling analysis.  
 Y \$ Any more lines in the "help" paragraph?  
 EFNOOD is the effective elastic foundation stiffness  
 Y \$ Any more lines in the "help" paragraph?  
 that supports the segments of the single module  
 Y \$ Any more lines in the "help" paragraph?  
 that form sort of triangular shaped gaps adjacent  
 Y \$ Any more lines in the "help" paragraph?  
 to the slanted walls of the truss-core and the  
 Y \$ Any more lines in the "help" paragraph?  
 bottom and top face sheets. EFNOOD is a "noodle"  
 Y \$ Any more lines in the "help" paragraph?  
 property. A Winkler foundation is assumed. A Winkler

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y      $ Any more lines in the "help" paragraph?
foundation reacts only normal to the shell surface;
y      $ Any more lines in the "help" paragraph?
it is like an array of closely spaced springs
y      $ Any more lines in the "help" paragraph?
oriented normal to the shell surface. Units of the
y      $ Any more lines in the "help" paragraph?
foundation stiffness, K, are force per length
Y      $ Any more lines in the "help" paragraph?
cubed (lb/in**3, for example). Note that the same
y      $ Any more lines in the "help" paragraph?
comment applies to EFNOOD that occurs in the "help"
Y      $ Any more lines in the "help" paragraph?
paragraph associated with the variable, EFOUND.
Y      $ Any more lines in the "help" paragraph?
( NOTE: IF YOU WANT TO SEE ALL THE "HELP" PARAGRAPHS
Y      $ Any more lines in the "help" paragraph?
ASSOCIATED WITH ALL THE PROBLEM VARIABLES, INSPECT
Y      $ Any more lines in the "help" paragraph?
THE XXX.PRO FILE, IN WHICH "XXX" REPRESENTS THE
Y      $ Any more lines in the "help" paragraph?
GENERIC NAME OF THIS CASE).
n      $ Any more lines in the "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $70
EMOD1   1 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
        $ Name of a variable in the users program (defined below)
        2 $ Role of the variable in the users program
        2 $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable EMOD1 an array?
Y      $ Do you want to establish new dimensions for EMOD1 ?
        1 $ Number of dimensions in the array, EMOD1
material type
        10 $ Max. allowable number of rows NROWS in the array, EMOD1
elastic modulus in the fiber direction
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $80
EMOD2   1 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
        $ Name of a variable in the users program (defined below)
        2 $ Role of the variable in the users program
        2 $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable EMOD2 an array?
n      $ Do you want to establish new dimensions for EMOD2 ?
elastic modulus transverse to fibers
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $85
G12     1 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
        $ Name of a variable in the users program (defined below)
        2 $ Role of the variable in the users program
        2 $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable G12 an array?
n      $ Do you want to establish new dimensions for G12 ?
in-plane shear modulus
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $90
G13     1 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
        $ Name of a variable in the users program (defined below)
        2 $ Role of the variable in the users program
        2 $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable G13 an array?
n      $ Do you want to establish new dimensions for G13 ?
out-of-plane x-z shear modulus
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $95
G23     1 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
        $ Name of a variable in the users program (defined below)
        2 $ Role of the variable in the users program
        2 $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable G23 an array?
n      $ Do you want to establish new dimensions for G23 ?
out-of-plane y-z shear modulus
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $100
NU      1 $ Type of prompt: 0="help" paragraph, 1=one-line prompt
        $ Name of a variable in the users program (defined below)
        2 $ Role of the variable in the users program
        2 $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable NU an array?
n      $ Do you want to establish new dimensions for NU ?

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minor (small) Poisson ratio
Y      $ Do you want to include a "help" paragraph?
NU is the "NU21" Poisson ratio, governed by the
Y      $ Any more lines in the "help" paragraph?
equation, E1*NU21 = E2*NU12. (Same input as for
Y      $ Any more lines in the "help" paragraph?
BOSOR4 and PANDA2).
n      $ Any more lines in the "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $105
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
ALPHA1 $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
2  $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable ALPHA1 an array?
n      $ Do you want to establish new dimensions for ALPHA1 ?
coef. of thermal expansion along the fibers
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $110
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
ALPHA2 $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
2  $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable ALPHA2 an array?
n      $ Do you want to establish new dimensions for ALPHA2 ?
coef. of thermal expansion transverse to fibers
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $115
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
TEMCUR $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
2  $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable TEMCUR an array?
n      $ Do you want to establish new dimensions for TEMCUR ?
curing temperature difference
Y      $ Do you want to include a "help" paragraph?
TEMCUR is the difference between the temperature
Y      $ Any more lines in the "help" paragraph?
at which the material "sets" during curing and the
Y      $ Any more lines in the "help" paragraph?
service ("room") temperature. Use a POSITIVE number.
n      $ Any more lines in the "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $120
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
DENSTY $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
2  $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable DENSTY an array?
n      $ Do you want to establish new dimensions for DENSTY ?
weight density of material
Y      $ Do you want to include a "help" paragraph?
For example, Aluminum = 0.1 lb/in^3
n      $ Any more lines in the "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $125
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
THICK $ Name of a variable in the users program (defined below)
1  $ Role of the variable in the users program
Y      $ Is the variable THICK an array?
Y      $ Do you want to establish new dimensions for THICK ?
1  $ Number of dimensions in the array, THICK
layer type (thickness, layup angle, material type)
30 $ Max. allowable number of rows NROWS in the array, THICK
layer type thickness
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $135
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
ANGLE $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
2  $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable ANGLE an array?
n      $ Do you want to establish new dimensions for ANGLE ?
layer type layup angle
n      $ Do you want to include a "help" paragraph?
Y      $ Any more variables for role types 1 or 2 ?    $140
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
MATTYP $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
1  $ type of variable: 1 =integer, 2 =floating point
Y      $ Is the variable MATTYP an array?

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n      $ Do you want to establish new dimensions for MATTYP ?  
layer type material type  
n      $ Do you want to include a "help" paragraph?  
Y      $ Any more variables for role types 1 or 2 ?      $145  
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt  
LAYTYP  $ Name of a variable in the users program (defined below)  
2  $ Role of the variable in the users program  
1  $ type of variable: 1 =integer, 2 =floating point  
Y      $ Is the variable LAYTYP an array?  
Y      $ Do you want to establish new dimensions for LAYTYP ?  
2  $ Number of dimensions in the array, LAYTYP  
layer number  
90 $ Max. allowable number of rows NROWS in the array, LAYTYP  
shell segment number  
50 $ Max. allowable number of columns NCOLS in the array, LAYTYP  
layer type  
y      $ Do you want to include a "help" paragraph?  
LAYTYP(layer no., segment no.) identifies the type of  
Y      $ Any more lines in the "help" paragraph?  
that particular layer in "segment no." of the single  
Y      $ Any more lines in the "help" paragraph?  
module model. LAYTYP(layer no., segment no.) points  
Y      $ Any more lines in the "help" paragraph?  
to the layer with a certain thickness, THICK, layup  
Y      $ Any more lines in the "help" paragraph?  
angle, ANGLE, and material type, MATTYP.  
n      $ Any more lines in the "help" paragraph?  
Y      $ Any more variables for role types 1 or 2 ?      $160  
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt  
NLAYRF  $ Name of a variable in the users program (defined below)  
2  $ Role of the variable in the users program  
1  $ type of variable: 1 =integer, 2 =floating point  
n      $ Is the variable NLAYRF an array?  
number of layers in each face sheet  
y      $ Do you want to include a "help" paragraph?  
This is the number of layers, such that when  
y      $ Any more lines in the "help" paragraph?  
added to the number of layers wrapped around the  
y      $ Any more lines in the "help" paragraph?  
trapezoidal tool (NLAYRC, the next role 2 variable),  
y      $ Any more lines in the "help" paragraph?  
gives the total number of layers in the laminate  
y      $ Any more lines in the "help" paragraph?  
that forms the wall of the horizontal shell  
y      $ Any more lines in the "help" paragraph?  
segments that run along the base and crown of  
y      $ Any more lines in the "help" paragraph?  
each trapezoidal segment of the truss-core  
y      $ Any more lines in the "help" paragraph?  
sandwich structure.  
n      $ Any more lines in the "help" paragraph?  
Y      $ Any more variables for role types 1 or 2 ?      $165  
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt  
NLAYRC  $ Name of a variable in the users program (defined below)  
2  $ Role of the variable in the users program  
1  $ type of variable: 1 =integer, 2 =floating point  
n      $ Is the variable NLAYRC an array?  
number of layers around trapezoidal tool  
y      $ Do you want to include a "help" paragraph?  
NLAYRC is the number of layers wrapped around the trapezoidal  
y      $ Any more lines in the "help" paragraph?  
tool, that is, the number of layers in the truss core.  
y      $ Any more lines in the "help" paragraph?  
For the upper and lower face sheets NLAYRC is added to  
y      $ Any more lines in the "help" paragraph?  
the number of layers, NLAYRF, to form the total number  
y      $ Any more lines in the "help" paragraph?  
of layers in the horizontal shell segment walls.  
y      $ Any more lines in the "help" paragraph?  
The number of layers in the truss-core webs will be  
y      $ Any more lines in the "help" paragraph?  
2 x NLAYRC.  
n      $ Any more lines in the "help" paragraph?  
Y      $ Any more variables for role types 1 or 2 ?      $170  
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt  
INTEXT  $ Name of a variable in the users program (defined below)  
2  $ Role of the variable in the users program  
1  $ type of variable: 1 =integer, 2 =floating point
```

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n      $ Is the variable INTEXT an array?
0=pressure on top face sheet; 1=bottom face sheet
y      $ Do you want to include a "help" paragraph?
INTEXT = 0 means pressure acts on the top face sheet.
y      $ Any more lines in the "help" paragraph?
INTEXT = 1 means pressure acts on the bottom face sheet.
y      $ Any more lines in the "help" paragraph?
In the model used here the circumferential resultant
y      $ Any more lines in the "help" paragraph?
in each face sheet is assumed to be (PRESS x RADIUS)/2.
y      $ Any more lines in the "help" paragraph?
in which PRESS is the applied pressure (negative for
y      $ Any more lines in the "help" paragraph?
external pressure), and RADIUS is the radius of the
y      $ Any more lines in the "help" paragraph?
cylindrical shell..
n      $ Any more lines in the "help" paragraph?
y      $ Any more variables for role types 1 or 2 ?    $175
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
NSEGS   $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
1  $ type of variable: 1 =integer, 2 =floating point
n      $ Is the variable NSEGS an array?
number of segments in module
y      $ Do you want to include a "help" paragraph?
NSEGS must be 22 for the truss-core sandwich module.
y      $ Any more lines in the "help" paragraph?
At present NSEGS is set equal to 22 in SUBROUTINE BOSDEC.
y      $ Any more lines in the "help" paragraph?
Therefore, the value you provide here is overwritten.
y      $ Any more lines in the "help" paragraph?
You may feel that NSEGS should not be an input variable
y      $ Any more lines in the "help" paragraph?
because the user must always specify NSEGS = 22 for
y      $ Any more lines in the "help" paragraph?
now. However, perhaps this will change in the future.
n      $ Any more lines in the "help" paragraph?
y      $ Any more variables for role types 1 or 2 ?    $180
0  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
You will next be asked to provide the number of modules
y      $ Are there more lines in the "help" paragraph?
to be used in the model for general buckling (NMODULG)
y      $ Are there more lines in the "help" paragraph?
and for local buckling (NMODULL). As of now NMODULG is
y      $ Are there more lines in the "help" paragraph?
computed in SUBROUTINE BOSDEC. Therefore, the value of
y      $ Are there more lines in the "help" paragraph?
NMODULG that you provide here will not be used. However,
y      $ Are there more lines in the "help" paragraph?
it is possible that in the future SUBROUTINE BOSDEC may
y      $ Are there more lines in the "help" paragraph?
be changed. Hence, NMODULG is retained as an input datum.
y      $ Are there more lines in the "help" paragraph?
Use a number for NMODULG such as NMODULG = 13 (NOTE: you
y      $ Are there more lines in the "help" paragraph?
are not allowed to use NMODULG > 13). For local buckling
y      $ Are there more lines in the "help" paragraph?
you should use NMODULL = 1 until you have a preliminary
y      $ Are there more lines in the "help" paragraph?
optimum design. Then, to refine the design, possibly
y      $ Are there more lines in the "help" paragraph?
optimize again with NMODULL = 10 or something like that.
y      $ Are there more lines in the "help" paragraph?
NOTE: The computer time increases significantly the
y      $ Are there more lines in the "help" paragraph?
higher the value of NMODULL.
n      $ Are there more lines in the "help" paragraph?
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
NMODULG   $ Name of a variable in the users program (defined below)
2  $ Role of the variable in the users program
1  $ type of variable: 1 =integer, 2 =floating point
n      $ Is the variable NMODULG an array?
number of modules for general buckling
y      $ Do you want to include a "help" paragraph?
Use a number such as NMODULG = 13 (NOTE: you are
y      $ Any more lines in the "help" paragraph?
not permitted to use NMODULG > 13). The computer
y      $ Any more lines in the "help" paragraph?

```

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time required for a SUPEROPT optimization increases  
 with increase in NMODULG. However, it is probably  
 best always to use the maximum value of NMODULG  
 that is permitted (NMODULG = 13) because you will  
 be less likely to obtain an unconservative design.  
 The value, NMODULG = 13, produces a BIGBOSOR4 model  
 with a total of 286 shell segments ( $286 = 22 \times 13$ ),  
 which is close to the maximum number of shell  
 segments (295) that BIGBOSOR4 can presently handle.  
 \$ Any more lines in the "help" paragraph?  
 \$ Any more variables for role types 1 or 2 ? \$190  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 NMODULL \$ Name of a variable in the users program (defined below)  
 2 \$ Role of the variable in the users program  
 1 \$ type of variable: 1 =integer, 2 =floating point  
 \$ Is the variable NMODULL an array?  
 number of modules for local buckling  
 \$ Do you want to include a "help" paragraph?  
 NMODULL is the number of modules, each of which  
 contains NSEGS shell segments. In this application  
 the best answer is usually 1 (that is, one module).  
 That is because the buckling (or stress) model  
 that consists of NSEGS shell segments is used  
 for obtaining LOCAL behavior, such as local  
 buckling. Only one module of NSEGS shell segments  
 is needed for the determination of LOCAL  
 behavior. However, there seems to be some dependence  
 of the local buckling load on the number of modules,  
 NMODULL, used in the model for local buckling. Hence,  
 after you have optimized with the use of NMODULL = 1  
 you may want to check the optimum design with use of  
 NMODULL = 10 or something like that.  
 \$ Is the variable MLOWG an array?  
 low end of the M-range for general buckling  
 \$ Do you want to include a "help" paragraph?  
 MLOWG should be 1 (an integer). Later it will be  
 multiplied by 100 because of the "huge torus" model.  
 The "huge torus" model is described in Part 12.2.2  
 of the paper, "Optimization of an axially compressed  
 ring and stringer stiffened cylindrical shell with  
 a general buckling modal imperfection", AIAA Paper  
 2007-2216, 48th AIAA Structures Meeting, Honolulu,  
 Hawaii, April 2007.  
 \$ Any more lines in the "help" paragraph?  
 \$ Any more lines in the "help" paragraph?

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y \$ Any more variables for role types 1 or 2 ? \$200  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
MHIGHG \$ Name of a variable in the users program (defined below)  
2 \$ Role of the variable in the users program  
1 \$ type of variable: 1 =integer, 2 =floating point  
n \$ Is the variable MHIGHG an array?  
high end of the M-range for general buckling  
y \$ Do you want to include a "help" paragraph?  
Perhaps one should give a value 10 (or something  
y \$ Any more lines in the "help" paragraph?  
like that). It depends on how many axial halfwaves  
y \$ Any more lines in the "help" paragraph?  
you think will correspond to the critical general  
y \$ Any more lines in the "help" paragraph?  
buckling mode. That number depends on the axial  
y \$ Any more lines in the "help" paragraph?  
bending stiffness of the cylindrical shell wall,  
y \$ Any more lines in the "help" paragraph?  
the length of the cylindrical shell, and the  
y \$ Any more lines in the "help" paragraph?  
radius of the cylindrical shell. Use at least  
y \$ Any more lines in the "help" paragraph?  
double the value of what you think is the critical  
y \$ Any more lines in the "help" paragraph?  
value, that is, the value that corresponds to the  
y \$ Any more lines in the "help" paragraph?  
lowest general buckling load. You may have to  
y \$ Any more lines in the "help" paragraph?  
adjust the value of MHIGHG as your project proceeds.  
n \$ Any more lines in the "help" paragraph?  
y \$ Any more variables for role types 1 or 2 ? \$205  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
MLOWL \$ Name of a variable in the users program (defined below)  
2 \$ Role of the variable in the users program  
1 \$ type of variable: 1 =integer, 2 =floating point  
n \$ Is the variable MLOWL an array?  
low end of the range of local buckling waves  
y \$ Do you want to include a "help" paragraph?  
You should use MLOWL = 1 because the axial length of  
y \$ Any more lines in the "help" paragraph?  
the portion of the cylindrical shell to be used in the  
y \$ Any more lines in the "help" paragraph?  
LOCAL buckling analysis is equal to LENGTH x FACLEN,  
y \$ Any more lines in the "help" paragraph?  
in which LENGTH is the actual axial length of the  
y \$ Any more lines in the "help" paragraph?  
cylindrical shell, and FACLEN is the fraction of  
y \$ Any more lines in the "help" paragraph?  
LENGTH to be included in the local buckling model.  
n \$ Any more lines in the "help" paragraph?  
y \$ Any more variables for role types 1 or 2 ? \$210  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
MHIGHL \$ Name of a variable in the users program (defined below)  
2 \$ Role of the variable in the users program  
1 \$ type of variable: 1 =integer, 2 =floating point  
n \$ Is the variable MHIGHL an array?  
high end of the M-range for local buckling  
y \$ Do you want to include a "help" paragraph?  
We're referring here to the range of axial halfwaves  
y \$ Any more lines in the "help" paragraph?  
to be used in the search for the critical LOCAL  
y \$ Any more lines in the "help" paragraph?  
buckling load of the single truss-core sandwich  
y \$ Any more lines in the "help" paragraph?  
module. Use a number such as 10 and adjust it later  
y \$ Any more lines in the "help" paragraph?  
if necessary.  
n \$ Any more lines in the "help" paragraph?  
n \$ Any more variables for role types 1 or 2 ? \$  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
PX \$ Name of a variable in the users program (defined below)  
3 \$ Role of the variable in the users program  
total axial load ( $2 \times \pi \times r \times$  resultant)  
y \$ Do you want to include a "help" paragraph?  
PX =  $2 \times \pi \times r \times$  axial resultant. Units = lb,  
y \$ Any more lines in the "help" paragraph?  
for example. PX is negative for axial compression.  
y \$ Any more lines in the "help" paragraph?

Table 9, p. 12 of 14

The axial resultant in each shell segment is computed  
 y \$ Any more lines in the "help" paragraph?  
 as if the shell were subject to uniform end shortening  
 y \$ Any more lines in the "help" paragraph?  
 and the prebuckled state is a membrane state (no  
 y \$ Any more lines in the "help" paragraph?  
 imperfections, no bending, no end "boundary layers").  
 n \$ Any more lines in the "help" paragraph?  
 y \$ Any more variables for role type 3 ? \$225  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 PRESS \$ Name of a variable in the users program (defined below)  
 3 \$ Role of the variable in the users program  
 pressure (negative for external pressure)  
 n \$ Do you want to include a "help" paragraph?  
 y \$ Any more variables for role type 3 ? \$230  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 PX0 \$ Name of a variable in the users program (defined below)  
 3 \$ Role of the variable in the users program  
 total "Load Set B" load  
 y \$ Do you want to include a "help" paragraph?  
 PX0 =  $2 \times \pi \times r \times Nx_0$ , in which  $Nx_0$  is an  
 y \$ Any more lines in the "help" paragraph?  
 axial stress resultant.  $PX_0$  = positive for axial  
 y \$ Any more lines in the "help" paragraph?  
 tension. Load Set B is the load set that is NOT to be  
 y \$ Any more lines in the "help" paragraph?  
 multiplied by the buckling eigenvalue.  
 n \$ Any more lines in the "help" paragraph?  
 y \$ Any more variables for role type 3 ? \$235  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 PRESSO \$ Name of a variable in the users program (defined below)  
 3 \$ Role of the variable in the users program  
 "Load Set B" pressure (external=negative)  
 y \$ Do you want to include a "help" paragraph?  
 PRESSO is positive for internal pressure. Load Set B  
 y \$ Any more lines in the "help" paragraph?  
 is the load set that is NOT to be multiplied by  
 y \$ Any more lines in the "help" paragraph?  
 the buckling eigenvalue.  
 n \$ Any more lines in the "help" paragraph?  
 n \$ Any more variables for role type 3 ? \$  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 LOCBUK \$ Name of a variable in the users program (defined below)  
 4 \$ Role of the variable in the users program  
 n \$ Do you want to reset the number of columns in LOCBUK ?  
 local buckling load factor  
 n \$ Do you want to include a "help" paragraph?  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 LOCBUKA \$ Name of a variable in the users program (defined below)  
 5 \$ Role of the variable in the users program  
 allowable for local buckling load factor  
 y \$ Do you want to include a "help" paragraph?  
 Usually, you supply 1.0 for LOCBUKA because LOCBUK is  
 y \$ Any more lines in the "help" paragraph?  
 a buckling load FACTOR, that is, a quantity that is  
 y \$ Any more lines in the "help" paragraph?  
 to be multiplied by the design loads, PX and PRESS,  
 y \$ Any more lines in the "help" paragraph?  
 in order to obtain the buckling load.  
 n \$ Any more lines in the "help" paragraph?  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 LOCBUKF \$ Name of a variable in the users program (defined below)  
 6 \$ Role of the variable in the users program  
 factor of safety for local buckling  
 y \$ Do you want to include a "help" paragraph?  
 In this "huge torus" model of the shell there cannot  
 y \$ Any more lines in the "help" paragraph?  
 exist any specified initial imperfection. Therefore,  
 y \$ Any more lines in the "help" paragraph?  
 you should probably use a factor of safety of 1.5  
 y \$ Any more lines in the "help" paragraph?  
 or something like that.  
 n \$ Any more lines in the "help" paragraph?  
 2 \$ Indicator (1 or 2 or 3) for type of constraint  
 y \$ Any more variables for role type 4 ? \$255  
 1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
 GENBUK \$ Name of a variable in the users program (defined below)  
 4 \$ Role of the variable in the users program

Table 9, p. 13 of 14

```

n      $ Do you want to reset the number of columns in GENBUK ?
general buckling load factor
n      $ Do you want to include a "help" paragraph?
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
GENBUKA $ Name of a variable in the users program (defined below)
5  $ Role of the variable in the users program
allowable for general buckling load factor
y      $ Do you want to include a "help" paragraph?
Usually, you supply 1.0 for GENBUKA because GENBUK is
Y      $ Any more lines in the "help" paragraph?
a buckling load FACTOR, that is, a quantity that is
Y      $ Any more lines in the "help" paragraph?
to be multiplied by the design loads, PX and PRESS,
Y      $ Any more lines in the "help" paragraph?
in order to obtain the buckling load.
n      $ Any more lines in the "help" paragraph?
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
GENBUKF $ Name of a variable in the users program (defined below)
6  $ Role of the variable in the users program
general buckling factor of safety
y      $ Do you want to include a "help" paragraph?
In this "huge torus" model of the shell there cannot
y      $ Any more lines in the "help" paragraph?
exist any specified initial imperfection. Therefore,
Y      $ Any more lines in the "help" paragraph?
you should probably use a factor of safety of 2.0
Y      $ Any more lines in the "help" paragraph?
or something like that.
n      $ Any more lines in the "help" paragraph?
2  $ Indicator (1 or 2 or 3) for type of constraint           $270
y      $ Any more variables for role type 4 ?
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
STRM1  $ Name of a variable in the users program (defined below)
4  $ Role of the variable in the users program
Y      $ Do you want to reset the number of columns in STRM1 ?
2  $ Number of dimensions in the array, STRM1
number of stress constraints
6  $ Max. allowable number of columns NCOLS in the array, STRM1
stress component in material 1
y      $ Do you want to include a "help" paragraph?
For a composite laminate there are 6 stress components
y      $ Any more lines in the "help" paragraph?
for which stress constraints are generated:
y      $ Any more lines in the "help" paragraph?
1. maximum tensile stress in the fiber direction
y      $ Any more lines in the "help" paragraph?
2. maximum compressive stress in the fiber direction
y      $ Any more lines in the "help" paragraph?
3. maximum tensile stress transverse to the fibers
y      $ Any more lines in the "help" paragraph?
4. maximum compressive stress transverse to the fibers
y      $ Any more lines in the "help" paragraph?
5. maximum in-plane shear stress
y      $ Any more lines in the "help" paragraph?
6. maximum effective (VonMises) stress for an
y      $ Any more lines in the "help" paragraph?
isotropic layer.
n      $ Any more lines in the "help" paragraph?
1  $ Type of prompt: 0="help" paragraph, 1=one-line prompt
STRM1A $ Name of a variable in the users program (defined below)
5  $ Role of the variable in the users program
allowable stress in material 1
y      $ Do you want to include a "help" paragraph?
For a composite laminate there are 6 stress components
y      $ Any more lines in the "help" paragraph?
for which stress constraints are generated:
y      $ Any more lines in the "help" paragraph?
1. maximum tensile stress in the fiber direction:
y      $ Any more lines in the "help" paragraph?
    STRM1A(i,1), in which "i" is the load set number
y      $ Any more lines in the "help" paragraph?
2. maximum compressive stress in the fiber direction:
y      $ Any more lines in the "help" paragraph?
    STRM1A(i,2), in which "i" is the load set number
y      $ Any more lines in the "help" paragraph?
3. maximum tensile stress transverse to the fibers:
y      $ Any more lines in the "help" paragraph?
    STRM1A(i,3), in which "i" is the load set number

```

Table 9, p.14 of 14

Y \$ Any more lines in the "help" paragraph?  
4. maximum compressive stress transverse to the fibers:  
Y \$ Any more lines in the "help" paragraph?  
STRM1A(i,4), in which "i" is the load set number  
Y \$ Any more lines in the "help" paragraph?  
5. maximum in-plane shear stress:  
Y \$ Any more lines in the "help" paragraph?  
STRM1A(i,5), in which "i" is the load set number  
Y \$ Any more lines in the "help" paragraph?  
6. maximum effective (VonMises) stress for an  
Y \$ Any more lines in the "help" paragraph?  
isotropic layer:  
Y \$ Any more lines in the "help" paragraph?  
STRM1A(i,6), in which "i" is the load set number  
n \$ Any more lines in the "help" paragraph?  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
STRM1F \$ Name of a variable in the users program (defined below)  
6 \$ Role of the variable in the users program  
factor of safety for stress in material 1  
Y \$ Do you want to include a "help" paragraph?  
In this "huge torus" model of the shell there cannot  
Y \$ Any more lines in the "help" paragraph?  
exist any specified initial imperfection. Therefore,  
Y \$ Any more lines in the "help" paragraph?  
you should probably use a factor of safety of 1.5  
Y \$ Any more lines in the "help" paragraph?  
or something like that.  
n \$ Any more lines in the "help" paragraph?  
3 \$ Indicator (1 or 2 or 3) for type of constraint  
Y \$ Any more variables for role type 4 ? \$290  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
STRM2 \$ Name of a variable in the users program (defined below)  
4 \$ Role of the variable in the users program  
n \$ Do you want to reset the number of columns in STRM2 ?  
stress component in material 2  
n \$ Do you want to include a "help" paragraph?  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
STRM2A \$ Name of a variable in the users program (defined below)  
5 \$ Role of the variable in the users program  
allowable for stress in material 2  
n \$ Do you want to include a "help" paragraph?  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
STRM2F \$ Name of a variable in the users program (defined below)  
6 \$ Role of the variable in the users program  
factor of safety for stress in material 2  
n \$ Do you want to include a "help" paragraph?  
3 \$ Indicator (1 or 2 or 3) for type of constraint  
n \$ Any more variables for role type 4 ? \$  
1 \$ Type of prompt: 0="help" paragraph, 1=one-line prompt  
WEIGHT \$ Name of a variable in the users program (defined below)  
7 \$ Role of the variable in the users program  
weight/area of the truss-core sandwich wall  
Y \$ Do you want to include a "help" paragraph?  
WEIGHT = weight per surface area of the truss-core  
Y \$ Any more lines in the "help" paragraph?  
sandwich shell wall.  
n \$ Any more lines in the "help" paragraph?

Input for GENTEXT

# Table 10 part of the trusscomp. DEF file

C	ARRAY ?	NUMBER OF (ROWS,COLS)	PROMPT	ROLE	NUMBER	NAME	DEFINITION OF VARIABLE
C						(trusscomp.PRO)	
<hr/>							
C	n	( 0, 0 )	2	10	LENGTH	= length of the cylindrical shell	
C	n	( 0, 0 )	2	20	FACLEN	= fraction of LENGTH for local buckling	
C	n	( 0, 0 )	2	25	RADIUS	= radius of the cylindrical shell	
C	n	( 0, 0 )	1	30	PITCH	= circumferential width of a single module	
C	n	( 0, 0 )	1	35	BCROWN	= circumferential width of the trapezoid crown	
C	n	( 0, 0 )	1	40	HEIGHT	= height of the truss-core sandwich	
C	n	( 0, 0 )	1	45	RACUTE	= local radius from base to side of trapezoidal too»	
I							
C	n	( 0, 0 )	1	50	ROBTUS	= local radius from side to crown of trapezoidal too»	
ol							
C	n	( 0, 0 )	2	55	ENOODL	= axial modulus of a corner "noodle"	
C	n	( 0, 0 )	2	60	DNOODL	= weight density of the "noodle" material	
C	n	( 0, 0 )	2	65	EFOUND	= elastic foam foundation stiffness	
C	n	( 0, 0 )	2	70	EFOOD	= elastic "noodle" Winkler foundation modulus	
C	n	( 0, 0 )	2	75	IEMOD1	= material type in EMOD1(IEMOD1)	
C	y	( 10, 0 )	2	80	EMOD1	= elastic modulus in the fiber direction	
C	y	( 10, 0 )	2	85	EMOD2	= elastic modulus transverse to fibers	
C	y	( 10, 0 )	2	90	G12	= in-plane shear modulus	
C	y	( 10, 0 )	2	95	G13	= out-of-plane x-z shear modulus	
C	y	( 10, 0 )	2	100	G23	= out-of-plain y-z shear modulus	
C	y	( 10, 0 )	2	105	NU	= minor (small) Poisson ratio	
C	y	( 10, 0 )	2	110	ALPHA1	= coef. of thermal expansion along the fibers	
C	y	( 10, 0 )	2	115	ALPHA2	= coef. of thermal expansion transverse to fibers	
C	y	( 10, 0 )	2	120	TEMCUR	= curing temperature difference	
C	y	( 10, 0 )	2	125	DENSTY	= weight density of material	
C	n	( 0, 0 )	2	130	ITHICK	= layer type (thickness, layup angle, material type) »	
in	THICK(ITHICK)						
C	y	( 30, 0 )	1	135	THICK	= layer type thickness	
C	y	( 30, 0 )	2	140	ANGLE	= layer type layup angle	
C	y	( 30, 0 )	2	145	MATTYP	= layer type material type	
C	n	( 0, 0 )	2	150	JLAYTYP	= shell segment number in LAYTYP(ILAYTYP, JLAYTYP)	
C	n	( 0, 0 )	2	155	ILAYTYP	= layer number in LAYTYP(ILAYTYP, JLAYTYP)	
C	y	( 90, 50 )	2	160	LAYTYP	= layer type	
C	n	( 0, 0 )	2	165	NLAYRF	= number of layers in each face sheet	
C	n	( 0, 0 )	2	170	NLAYRC	= number of layers around trapezoidal tool	
C	n	( 0, 0 )	2	175	INTEXT	= 0 = pressure on top face sheet; 1 = bottom face sh»	
eeet							
C	n	( 0, 0 )	2	180	NSEGS	= number of segments in module	
C	n	( 0, 0 )	2	190	NMODULG	= number of modules for general buckling	
C	n	( 0, 0 )	2	195	NMODULL	= number of modules for local buckling	
C	n	( 0, 0 )	2	200	MLONG	= low end of the M-range for general buckling	
C	n	( 0, 0 )	2	205	MHIGHG	= high end of the M-range for general buckling	
C	n	( 0, 0 )	2	210	MLOWL	= low end of the range of local buckling waves	
C	r	( 0, 0 )	2	215	MHIGHL	= high end of the M-range for local buckling	
C	n	( 0, 0 )	2	220	NCASES	= Number of load cases (number of environments) in»	
PX(NCASES)							
C	y	( 20, 0 )	3	225	PX	= total axial load (2 x pi x r x resultant)	
C	y	( 20, 0 )	3	230	PRESS	= pressure (negative for external pressure)	
C	y	( 20, 0 )	3	235	PXO	= total "Load Set B" load	
C	y	( 20, 0 )	3	240	PRESS0	= "Load Set B" pressure (external=negative)	
C	y	( 20, 0 )	4	245	LOCBUK	= local buckling load factor	
C	y	( 20, 0 )	5	250	LOCBUKA	= allowable for local buckling load factor	
C	y	( 20, 0 )	6	255	LOCBUKF	= factor of safety for local buckling	
C	y	( 20, 0 )	4	260	GENBUK	= general buckling load factor	
C	y	( 20, 0 )	5	265	GENBUKA	= allowable for general buckling load factor	
C	y	( 20, 0 )	6	270	GENBUKF	= general buckling factor of safety	
C	n	( 0, 0 )	2	275	JSTRM1	= number of stress constraints in STRM1(NCASES, JSTRM1)	
M1)							
C	y	( 20, 6 )	4	280	STRM1	= stress component in material 1	
C	y	( 20, 6 )	5	285	STRM1A	= allowable stress in material 1	
C	y	( 20, 6 )	6	290	STRM1F	= factor of safety for stress in matl 1	
C	y	( 20, 6 )	4	295	STRM2	= stress component in material 2	
C	y	( 20, 6 )	5	300	STRM2A	= allowable for stress in material 2	
C	y	( 20, 6 )	6	305	STRM2F	= factor of safety for stress in material 2	
C	n	( 0, 0 )	7	310	WEIGHT	= weight/area of the truss-core sandwich wall	
C							

This list (of the entire trusscomp. DEF file)  
are created automatically by GENTEXT.  
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# Table II trusscomp.PRO file (6 pages)

5.0

Please read the report:

"Use of GENOPT and BIGBOSOR4 to obtain optimum designs of a cylindrical shell with a composite truss-core sandwich wall", David Bushnell, June 20, 2009

This GENOPT case is for a cylindrical shell the wall of which is a truss-core sandwich. Each segment of a truss-core sandwich module is a composite laminate. Hence, the name, "trusscomp". A truss-core module here consists of 22 shell segments of the type used in BIGBOSOR4. General and local buckling load factors are determined from BIGBOSOR4. The shell is modeled as a part of a "huge torus". A membrane prebuckled state is assumed to exist. The axial resultant in each module segment is assumed to be proportional to the axial stiffness of that segment. Local buckling is determined from a single module. General buckling is determined from a number of analogous simpler modules strung together. The stress constraints are computed from a much simplified version of the code in SUBROUTINE STRTHX of BIGBOSOR4, simplified because the prebuckled state is a membrane state. The stresses are computed in each layer in each truss-core sandwich, segment.

Occasionally an optimization run with SUPEROPT may abort early. If this happens, inspect the end of the xxx.OUT file to see if there are any error messages. You may have to modify your inequality constraints in the xxx\*DEC file (input to "DECIDE") in order to avoid an early and unexpected termination of the SUPEROPT run. Most of the early terminations of the SUPEROPT run can be avoided by increasing the lower bound of the thickness of the truss-core, that is, increasing the lower bound of the variable called "HEIGHT".

10.1 length of the cylindrical shell: LENGTH

10.2

NOTE: the cylindrical shell is assumed to be simply supported along its two curved ends.

15.0

Next you will be asked to provide the fraction of the shell axial length to be used in the local buckling analysis. If the shell is subjected to uniform end shortening (axial compression), then this fraction of the total shell length can be estimated by assuming that the critical buckling mode will have approximately square buckles. The portion of the truss-core sandwich most likely to buckle may well have the longest unsupported width. Suppose the total length of the cylindrical shell is 100 inches. Suppose the width of the segment of the truss-core sandwich most likely to buckle locally is 2 inches. Then, for square buckles, the critical local buckling mode will have approximately 50 half-waves along the total axial length of the cylindrical shell. In order to save computer time you don't want to have to search over a large range of axial half-waves. Therefore, in this example, choose a fraction, FACLEN, of axial length equal to about 1/10th (FACLEN=0.1). Then the critical local buckling mode will have about 5 axial half-waves over the length,  $0.1 \times \text{LENGTH} = 10$  inches, and you can establish the range of axial half-waves to be covered to be from 1 to 10 axial halfwaves. (MLOWL = 1, MHIGHL = 10). The probable critical buckling mode will probably be somewhere in the middle of this range.

20.1 fraction of LENGTH for local buckling: FACLEN

20.2

If the cylindrical shell is subjected to axial compression set FACLEN such that if the local buckles are square the critical local buckling mode will fall in the middle of

This is the prompting file used during the execution of BEGIN.  
It is produced automatically by GENTEXT.  
The text in it is created by the GENOPT user, but this text is arranged in this format by GENTEXT.

the range of axial wave numbers, MLOWL to MHIGHL, that you will later establish during this interactive session.

Table 11, p. 2 of 6

25.1 radius of the cylindrical shell: RADIUS

25.2

This is the radius to the INNER face sheet of the truss-core sandwich wall.

30.1 circumferential width of a single module: PITCH

30.2

A single module consists essentially of one "upside-down" trapezoid and its adjacent "right-side-up" neighbor. There are 22 shell segments in the single truss-core sandwich module. (See Figs. 1 and 2). PITCH is called "b" in Fig. 1.

35.1 circumferential width of the trapezoid crown: BCROWN

35.2

BCROWN is the width of the narrow horizontal face of the trapezoid. BCROWN is called "b2" in Fig. 1.

40.1 height of the truss-core sandwich: HEIGHT

40.2

HEIGHT is measured from the middle surface of the bottom face sheet to the middle surface of the top face sheet. HEIGHT is called "h" in Fig. 1.

45.1 local radius from base to side of trapezoidal tool: RACUTE

45.2

RACUTE is the transition radius by means of which the base surface of the trapezoidal tool is smoothly faired into the sloping side walls of the trapezoidal tool. The trapezoidal tool is the object around which the layers of the core laminate are laid up. RACUTE is the radius that spans the acute angle from trapezoid base to trapezoid sloping sides. RACUTE is similar to the dimension called "R1" in Fig. 1.  
(R1 = RACUTE + total thickness of shell segment 5).

50.1 local radius from side to crown of trapezoidal tool: ROBTUS

50.2

ROBTUS is the radius that fairs each side wall of the trapezoidal tool into the crown of the trapezoidal tool. The trapezoidal tool is the object around which the core laminate is laid up. ROBTUS is the radius that spans the obtuse angle from trapezoid crown to trapezoid sloping sides. ROBTUS is similar to the dimension called "R2" in Fig. 1.  
(R2 = ROBTUS + total thickness of shell segment 2).

55.1 axial modulus of a corner "noodle": ENOODL

55.2

ENOODL is the axial modulus of the "noodle" material. A "noodle" is the material that is fills a "corner" between adjacent trapezoidal core segments. Each truss-core sandwich module has four "noodles", two at the bottom and two at the top of the single module. The "noodles" fit into the sort of triangular gaps adjacent to the slanted core walls and the bottom and top face sheets. For example, one of the "triangular" gaps shown in Fig. 1 is the small region enclosed by shell segments 2, 3, 4, and 5. ENOODL is the axial modulus of the material that fills each of the four "triangular" prismatic cavities in the single truss-core sandwich module.

60.1 weight density of the "noodle" material: DNOODL

60.2

DNOODL is the density analogous to that of aluminum's weight density of 0.1 lb/in<sup>3</sup>. Usually, the "noodle" will be made from the same material as one of the layers in the truss-core. If so, just use the same value for DNOODL as you will use later for the material density of one of the layers in the truss-core laminate.

65.1 elastic foam "Winkler" foundation stiffness: EFCUND

# Table II, p.3 of 6

65.2

EFOUND is used only for the LOCAL buckling analysis. The volume inside the truss-core sandwich may be filled with an elastic foam that is bonded to the face sheets and sloping side walls of the core. A Winkler foundation is assumed. A Winkler foundation reacts only normal to the shell surface; it is like an array of closely spaced springs oriented normal to the shell surface. Units of the foundation stiffness, K, are force per length cubed (lb/in\*\*3, for example). IMPORTANT NOTE: The elastic foundation is assumed to be connected to GROUND. Therefore, the elastic foam inside each truss core module CANNOT TRANSLATE AND ROTATE AS A RIGID BODY. Hence, the elastic foam is assumed to be present ONLY IN THE LOCAL BUCKLING ANALYSIS. Still, it is probably somewhat unconservative to include a non-zero EFOUND in your model unless you use a significantly conservative value for EFNOOD, that is, an underestimate of what you think EFNOOD might actually be. It is probably best first to optimize with EFNOOD = 0.0, then re-optimize with some small non-zero value of EFNOOD later.

70.1 elastic "noodle" Winkler foundation modulus: EFNOOD  
 70.2

EFNOOD is used only for the LOCAL buckling analysis. EFNOOD is the effective elastic foundation stiffness that supports the segments of the single module that form sort of triangular shaped gaps adjacent to the slanted walls of the truss-core and the bottom and top face sheets. EFNOOD is a "noodle" property. A Winkler foundation is assumed. A Winkler foundation reacts only normal to the shell surface; it is like an array of closely spaced springs oriented normal to the shell surface. Units of the foundation stiffness, K, are force per length cubed (lb/in\*\*3, for example). Note that the same comment applies to EFNOOD that occurs in the "help" paragraph associated with the variable, EFOUND.  
 (NOTE: IF YOU WANT TO SEE ALL THE "HELP" PARAGRAPHS ASSOCIATED WITH ALL THE PROBLEM VARIABLES, INSPECT THE XXX.PRO FILE, IN WHICH "XXX" REPRESENTS THE GENERIC NAME OF THIS CASE).

75.1 Number IEMOD1 of rows in the array EMOD1: IEMOD1  
 80.1 elastic modulus in the fiber direction: EMOD1  
 85.1 elastic modulus transverse to fibers: EMOD2  
 90.1 in-plane shear modulus: G12  
 95.1 out-of-plane x-z shear modulus: G13  
 100.1 out-of-plane y-z shear modulus: G23  
 105.1 minor (small) Poisson ratio: NU  
 105.2

NU is the "NU21" Poisson ratio, governed by the equation,  $E1 \cdot NU21 = E2 \cdot NU12$ . (Same input as for BOSOR4 and PANDA2).

110.1 coef. of thermal expansion along the fibers: ALPHA1  
 115.1 coef. of thermal expansion transverse to fibers: ALPHA2  
 120.1 curing temperature difference: TEMCUR  
 120.2

TEMCUR is the difference between the temperature at which the material "sets" during curing and the service ("room") temperature. Use a POSITIVE number.

125.1 weight density of material: DENSTY  
 125.2  
 For example, Aluminum = 0.1 lb/in^3

130.1 Number ITHICK of rows in the array THICK: ITHICK  
 135.1 layer type thickness: THICK  
 140.1 layer type layup angle: ANGLE  
 145.1 layer type material type: MATTYP  
 150.1 Number JLAYTYP of columns in the array, LAYTYP: JLAYTYP  
 155.1 Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP  
 160.1 layer type: LAYTYP  
 160.2  
 LAYTYP(layer no., segment no.) identifies the type of

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that particular layer in "segment no." of the single module model. LAYTYP(layer no., segment no.) points to the layer with a certain thickness, THICK, layup angle, ANGLE, and material type, MATTYP.

165.1 number of layers in each face sheet: NLAYRF  
165.2

This is the number of layers, such that when added to the number of layers wrapped around the trapezoidal tool (NLAYRC, the next role 2 variable), gives the total number of layers in the laminate that forms the wall of the horizontal shell segments that run along the base and crown of each trapezoidal segment of the truss-core sandwich structure.

170.1 number of layers around trapezoidal tool: NLAYRC  
170.2

NLAYRC is the number of layers wrapped around the trapezoidal tool, that is, the number of layers in the truss core. For the upper and lower face sheets NLAYRC is added to the number of layers, NLAYRF, to form the total number of layers in the horizontal shell segment walls. The number of layers in the truss-core webs will be  $2 \times NLAYRC$ .

175.1 0=pressure on top face sheet; 1=bottom face sheet: INTEXT  
175.2

INTEXT = 0 means pressure acts on the top face sheet.  
INTEXT = 1 means pressure acts on the bottom face sheet.  
In the model used here the circumferential resultant in each face sheet is assumed to be  $(PRESS \times RADIUS)/2$ . in which PRESS is the applied pressure (negative for external pressure), and RADIUS is the radius of the cylindrical shell..

180.1 number of segments in module: NSEGS  
180.2

NSEGS must be 22 for the truss-core sandwich module. At present NSEGS is set equal to 22 in SUBROUTINE BOSDEC. Therefore, the value you provide here is overwritten. You may feel that NSEGS should not be an input variable because the user must always specify NSEGS = 22 for now. However, perhaps this will change in the future.

185.0  
You will next be asked to provide the number of modules to be used in the model for general buckling (NMODULG) and for local buckling (NMODULL). As of now NMODULG is computed in SUBROUTINE BOSDEC. Therefore, the value of NMODULG that you provide here will not be used. However, it is possible that in the future SUBROUTINE BOSDEC may be changed. Hence, NMODULG is retained as an input datum. Use a number for NMODULG such as NMODULG = 13 (NOTE: you are not allowed to use NMODULG > 13). For local buckling you should use NMODULL = 1 until you have a preliminary optimum design. Then, to refine the design, possibly optimize again with NMODULL = 10 or something like that. NOTE: The computer time increases significantly the higher the value of NMODULL.

190.1 number of modules for general buckling: NMODULG  
190.2

Use a number such as NMODULG = 13 (NOTE: you are not permitted to use NMODULG > 13). The computer time required for a SUPEROPT optimization increases with increase in NMODULG. However, it is probably best always to use the maximum value of NMODULG that is permitted (NMODULG = 13) because you will be less likely to obtain an unconservative design. The value, NMODULG = 13, produces a BIGBOSOR4 model with a total of 286 shell segments ( $286 = 22 \times 13$ ), which is close to the maximum number of shell segments (295) that BIGBOSOR4 can presently handle.

195.1 number of modules for local buckling: NMODULL  
195.2

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NMODULL is the number of modules, each of which contains NSEGS shell segments. In this application the best answer is usually 1 (that is, one module). That is because the buckling (or stress) model that consists of NSEGS shell segments is used for obtaining LOCAL behavior, such as local buckling. Only one module of NSEGS shell segments is needed for the determination of LOCAL behavior. However, there seems to be some dependence of the local buckling load on the number of modules, NMODULL, used in the model for local buckling. Hence, after you have optimized with the use of NMODULL = 1 you may want to check the optimum design with use of NMODULL = 10 or something like that.

200.1 low end of the M-range for general buckling: MLOWG  
200.2

MLOWG should be 1 (an integer). Later it will be multiplied by 100 because of the "huge torus" model. The "huge torus" model is described in Part 12.2.2 of the paper, "Optimization of an axially compressed ring and stringer stiffened cylindrical shell with a general buckling modal imperfection", AIAA Paper 2007-2216, 48th AIAA Structures Meeting, Honolulu, Hawaii, April 2007.

205.1 high end of the M-range for general buckling: MHIGHG  
205.2

Perhaps one should give a value 10 (or something like that). It depends on how many axial halfwaves you think will correspond to the critical general buckling mode. That number depends on the axial bending stiffness of the cylindrical shell wall, the length of the cylindrical shell, and the radius of the cylindrical shell. Use at least double the value of what you think is the critical value, that is, the value that corresponds to the lowest general buckling load. You may have to adjust the value of MHIGHG as your project proceeds.

210.1 low end of the range of local buckling waves: MLOWL  
210.2

You should use MLOWL = 1 because the axial length of the portion of the cylindrical shell to be used in the LOCAL buckling analysis is equal to LENGTH x FACLEN, in which LENGTH is the actual axial length of the cylindrical shell, and FACLEN is the fraction of LENGTH to be included in the local buckling model.

215.1 high end of the M-range for local buckling: MHIGHL  
215.2

We're referring here to the range of axial halfwaves to be used in the search for the critical LOCAL buckling load of the single truss-core sandwich module. Use a number such as 10 and adjust it later if necessary.

220.1 Number NCASES of load cases (environments): NCASES  
225.1 total axial load ( $2 \times \pi \times r \times$  resultant): PX  
225.2

PX =  $2 \times \pi \times r \times$  axial resultant. Units = lb, for example. PX is negative for axial compression. The axial resultant in each shell segment is computed as if the shell were subject to uniform end shortening and the prebuckled state is a membrane state (no imperfections, no bending, no end "boundary layers").

230.1 pressure (negative for external pressure): PRESS  
235.1 total "Load Set B" load: PX0  
235.2

PX0 =  $2 \times \pi \times r \times Nx0$ , in which Nx0 is an axial stress resultant. PX0 = positive for axial tension. Load Set B is the load set that is NOT to be multiplied by the buckling eigenvalue.

240.1 "Load Set B" pressure (external=negative): PRESS0  
240.2 PRESS0 is positive for internal pressure. Load Set B

is the load set that is NOT to be multiplied by the buckling eigenvalue.

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245.0 local buckling load factor: LOCBUK

250.1 allowable for local buckling load factor: LOCBUKA

250.2

Usually, you supply 1.0 for LOCBUKA because LOCBUK is a buckling load FACTOR, that is, a quantity that is to be multiplied by the design loads, PX and PRESS, in order to obtain the buckling load.

255.1 factor of safety for local buckling: LOCBUKF

255.2

In this "huge torus" model of the shell there cannot exist any specified initial imperfection. Therefore, you should probably use a factor of safety of 1.5 or something like that.

260.0 general buckling load factor: GENBUK

265.1 allowable for general buckling load factor: GENBUKA

265.2

Usually, you supply 1.0 for GENBUKA because GENBUK is a buckling load FACTOR, that is, a quantity that is to be multiplied by the design loads, PX and PRESS, in order to obtain the buckling load.

270.1 general buckling factor of safety: GENBUKF

270.2

In this "huge torus" model of the shell there cannot exist any specified initial imperfection. Therefore, you should probably use a factor of safety of 2.0 or something like that.

275.1 Number JSTRM1 of columns in the array, STRM1: JSTRM1

280.0 stress component in material 1: STRM1

280.2

For a composite laminate there are 6 stress components for which stress constraints are generated:

1. maximum tensile stress in the fiber direction
2. maximum compressive stress in the fiber direction
3. maximum tensile stress transverse to the fibers
4. maximum compressive stress transverse to the fibers
5. maximum in-plane shear stress
6. maximum effective (VonMises) stress for an isotropic layer.

285.1 allowable stress in material 1: STRM1A

285.2

For a composite laminate there are 6 stress components for which stress constraints are generated:

1. maximum tensile stress in the fiber direction: STRM1A(i,1), in which "i" is the load set number
2. maximum compressive stress in the fiber direction: STRM1A(i,2), in which "i" is the load set number
3. maximum tensile stress transverse to the fibers: STRM1A(i,3), in which "i" is the load set number
4. maximum compressive stress transverse to the fibers: STRM1A(i,4), in which "i" is the load set number
5. maximum in-plane shear stress: STRM1A(i,5), in which "i" is the load set number
6. maximum effective (VonMises) stress for an isotropic layer: STRM1A(i,6), in which "i" is the load set number

290.1 factor of safety for stress in material 1: STRM1F

290.2

In this "huge torus" model of the shell there cannot exist any specified initial imperfection. Therefore, you should probably use a factor of safety of 1.5 or something like that.

295.0 stress component in material 2: STRM2

300.1 allowable for stress in material 2: STRM2A

305.1 factor of safety for stress in material 2: STRM2F

310.0 weight/area of the truss-core sandwich wall: WEIGHT

310.2

WEIGHT = weight per surface area of the truss-core sandwich shell wall.

# Table 12 behavior\_trusscomp (19 pages)

```
C=DECK      BEHAVIOR.NEW
C This library contains the skeletons of
C subroutines called SUBROUTINE BEHXn, n = 1,
C 2, 3, . . . that will yield predictions
C of behavioral responses of various systems
C to environments (loads).
C
C You may complete the subroutines by writing
C algorithms that yield the responses,
C each of which plays a part in constraining
C the design to a feasible region. Examples
C of responses are: stress, buckling, drag,
C vibration, deformation, clearances, etc.
C
C A skeleton routine called SUBROUTINE OBJECT
C is also provided for any objective function
C (e.g. weight, deformation, conductivity)
C you may wish to create.
C
C A skeleton routine called SUBROUTINE USRCON
C is also provided for any user-written
C constraint condition you may wish to write:
C This is an INEQUALITY condition that
C involves any program variables. However,
C note that this kind of thing is done
C automatically in the program DECIDE, so
C try DECIDE first to see if your particular
C constraint conditions can be accommodated
C more easily there.
C
C Please note that you do not have to modify
C BEHAVIOR.NEW in any way, but may instead
C prefer to insert your subroutines into the
C skeletal libraries ADDCODEn.NEW, n=1,2, ...
C and appropriate common blocks, dimension
C and type statements and calls to these
C subroutines in the library STRUCT.NEW.
C This strategy is best if your FORTRAN
C input to GENOPT contains quite a bit
C of software previously written by
C yourself or others, and/or the generation
C of behavioral constraints is more easily
C accomplished via another architecture
C than that provided for in the
C BEHAVIOR.NEW library. (See instructions
C in the libraries ADDCODEn.NEW and
C STRUCT.NEW for this procedure.)
C
C The two test cases provided with GENOPT
C provide examples of each method:
C   PLATE (test case 1): use of BEHAVIOR.NEW
C   PANEL (test case 2): use of ADDCODEn.NEW
C                   and STRUCT.NEW.
C
C SEVEN ROLES THAT VARIABLES IN THIS SYSTEM OF PROGRAMS PLAY
C
C A variable can have one of the following roles:
C
C   1 = a possible decision variable for optimization,
C       typically a dimension of a structure.
C   2 = a constant parameter (cannot vary as design evolves),
C       typically a control integer or material property,
C       but not a load, allowable, or factor of safety,
C       which are asked for later.
C   3 = a parameter characterizing the environment, such
C       as a load component or a temperature.
C   4 = a quantity that describes the response of the
C       structure, (e.g. stress, buckling load, frequency)
C   5 = an allowable, such as maximum allowable stress,
C       minimum allowable frequency, etc.
C   6 = a factor of safety
C   7 = the quantity that is to be minimized or maximized,
C       called the "objective function" (e.g. weight).
C =====
C
C NAMES, DEFINITIONS, AND ROLES OF THE VARIABLES:
C
C YOU ARE USING WHAT I HAVE CALLED "GENOPT" TO GENERATE AN
```

C OPTIMIZATION PROGRAM FOR A PARTICULAR CLASS OF PROBLEMS.  
C THE NAME YOU HAVE CHOSEN FOR THIS CLASS OF PROBLEMS IS: trusscomp

C "GENOPT" (GENeral OPTimization) was written during 1987-1988  
C by Dr. David Bushnell, Dept. 93-30, Bldg. 251, (415)424-3237  
C Lockheed Missiles and Space Co., 3251 Hanover St.,  
C Palo Alto, California, USA 94304

C The optimizer used in GENOPT is called ADS, and was  
C written by G. Vanderplaats [3]. It is based on the method  
C of feasible directions [4].

C ABSTRACT

C "GENOPT" has the following purposes and properties:

1. Any relatively simple analysis is "automatically" converted into an optimization of whatever system can be analyzed with fixed properties. Please note that GENOPT is not intended to be used for problems that require elaborate data-base management systems or large numbers of degrees of freedom.
2. The optimization problems need not be in fields nor jargon familiar to me, the developer of GENOPT. Although all of the example cases (See the cases in the directories under genopt/case) are in the field of structural analysis, GENOPT is not limited to that field.
3. GENOPT is a program that writes other programs. These programs, WHEN AUGMENTED BY USER-SUPPLIED CODING, form a program system that should be user-friendly in the GENOPT-user's field. In this instance the user of GENOPT must later supply FORTRAN coding that calculates behavior in the problem class called "trusscomp".

C 4. Input data and textual material are elicited from the user of GENOPT in a general enough way so that he or she may employ whatever data, definitions, and "help" paragraphs will make subsequent use of the program system thus generated easy by those less familiar with the class of problems "trusscomp" than the GENOPT user.

C 5. The program system generated by GENOPT has the same general architecture as previous programs written for specific applications by the developer [7 - 16]. That is, the command set is:

- BEGIN (User supplies starting design, loads, control integers, material properties, etc. in an interactive-help mode.)
- DECIDE (User chooses decision and linked variables and inequality constraints that are not based on behavior.)
- MAINSETUP (User chooses output option, whether to perform analysis of a fixed design or to optimize, and number of design iterations.)
- OPTIMIZE (The program system performs, in a batch mode, the work specified in MAINSETUP.)
- SUPEROPT (Program tries to find the GLOBAL optimum design as described in Ref.[11] listed below (Many OPTIMIZEs in one run.))
- CHANGE (User changes certain parameters)
- CHOOSEPLOT (User selects which quantities to plot vs. design iterations.)
- DIPLOT (User generates plots)
- CLEANSPEC (User cleans out unwanted files.)

Table 12, p. 2 of 19

```

C A typical runstream is:
C GENOPTLOG (activate command set)
C BEGIN (provide starting design, loads, etc.)
C DECIDE (choose decision variables and bounds)
C MAINSETUP (choose print option and analysis type)
C OPTIMIZE (launch batch run for n design iterations)
C OPTIMIZE (launch batch run for n design iterations)
C OPTIMIZE (launch batch run for n design iterations)
C OPTIMIZE (launch batch run for n design iterations)
C OPTIMIZE (launch batch run for n design iterations)
C CHANGE (change some variables for new starting pt)
C OPTIMIZE (launch batch run for n design iterations)
C OPTIMIZE (launch batch run for n design iterations)
C OPTIMIZE (launch batch run for n design iterations)
C CHOOSEPLOT (choose which variables to plot)
C DIPLOT (plot variables v. iterations)
C CHOOSEPLOT (choose additional variables to plot)
C DIPLOT (plot more variables v design iterations)
C CLEANSPEC (delete extraneous files for specific case)

```

```

C IMPORTANT: YOU MUST ALWAYS GIVE THE COMMAND "OPTIMIZE"
C SEVERAL TIMES IN SUCCESSION IN ORDER TO OBTAIN
C CONVERGENCE! AN EXPLANATION OF WHY YOU MUST DO
C THIS IS GIVEN ON P 580-582 OF THE PAPER "PANDA2,
C PROGRAM FOR MINIMUM WEIGHT DESIGN OF STIFFENED,
C COMPOSITE LOCALLY BUCKLED PANELS", Computers and
C Structures, Vol. 25, No. 4, pp 469-605 (1987).

```

C Due to introduction of a "global" optimizer, SUPEROPT,  
C described in Ref.[11], you can now use the runstream

```

C BEGIN (provide starting design, loads, etc.)
C DECIDE (choose decision variables and bounds)
C MAINSETUP (choose print option and analysis type)
C SUPEROPT (launch batch run for "global" optimization)
C CHOOSEPLOT (choose which variables to plot)
C DIPLOT (plot variables v. iterations)

```

```

C "Global" is in quotes because SUPEROPT does its best to find
C a true global optimum design. The user is strongly urged to
C execute SUPEROPT/CHOOSEPLOT several times in succession in
C order to determine an optimum that is essentially just as
C good as the theoretical true global optimum. Each execution
C of the series,
C     SUPEROPT
C     CHOOSEPLOT

```

C does the following:

C 1. SUPEROPT executes many sets of the two processors,  
C OPTIMIZE and AUTOCHANGE (AUTOCHANGE gets a new random  
C "starting" design), in which each set does the following:

```

C     OPTIMIZE (perform k design iterations)
C     AUTOCHANGE (get new starting design randomly)

```

C SUPEROPT keeps repeating the above sequence until the  
C total number of design iterations reaches about 270.  
C The number of OPTIMIZES per AUTOCHANGE is user-provided.

C 2. CHOOSEPLOT allows the user to plot stuff and resets the  
C total number of design iterations from SUPEROPT to zero.  
C After each execution of SUPEROPT the user MUST execute  
C CHOOSEPLOT: before the next execution of SUPEROPT the  
C total number of design iterations MUST be reset to zero.

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C =====

C TABLE 1 "GENOPT" COMMANDS

C =====

C HELPG (get information on GENOPT.)  
C GENTEXT (GENOPT user generate a prompt file, program  
C fragments [see TABLE 5], programs [see  
C TABLE 4], and this and other files  
C [see TABLE 5 and the rest of this file.])  
C GENPROGRAMS (GENOPT user generate absolute elements:  
BEGIN.EXE, DECIDE.EXE, MAINSETUP.EXE,

OPTIMIZE.EXE, CHANGE.EXE, STORE.EXE,  
CHOOSEPLOT.EXE, DIPILOT.EXE.)

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```

C BEGIN (end user provide starting data.)
C DECIDE (end user choose decision variables, bounds,
C           linked variables, inequality constraints.)
C MAINSETUP (end user set up strategy parameters.)
C OPTIMIZE (end user perform optimization, batch mode.)
C SUPEROPT (Program tries to find the GLOBAL optimum
C             design as described in Ref.[11] listed
C             above (Many OPTIMIZES in one run.)

C CHANGE (end user change some parameters.)
C CHOOSEPLOT (end user choose which variables to plot v.
C               design iterations.)
C DIPLOT (end user obtain plots.)
C INSERT (GENOPT user add parameters to the problem.)
C CLEANGEN (GENOPT user cleanup your GENeric files.)
C CLEANSPEC (end user cleanup your SPECific case files)

```

C Please consult the following sources for more  
C information about GENOPT:

1. GENOPT.STORY and HOWTO.RUN and GENOPT.NEWS
  2. Sample cases: (in the directory, genopt/case)
  3. NAME.DEF file, where NAME is the name chosen by the GENOPT-user for a class of problems. (In this case NAME = trusscomp)
  4. GENOPT.HLP file (type HELPG)

C=====

C TABLE 2 GLOSSARY OF VARIABLES USED IN "trusscomp"

C	ARRAY	NUMBER OF (ROWS,COLS)	PROMPT	DEFINITION OF VARIABLE
C	?	ROLE	NUMBER (trusscomp.PRO)	
=====				
C	n	( 0, 0)	2	10 LENGTH = length of the cylindrical shell
C	n	( 0, 0)	2	20 FACLEN = fraction of LENGTH for local buck
C	n	( 0, 0)	2	25 RADIUS = radius of the cylindrical shell
C	n	( 0, 0)	1	30 PITCH = circumferential width of a single
C	n	( 0, 0)	1	35 BCROWN = circumferential width of the trap
C	n	( 0, 0)	1	40 HEIGHT = height of the truss-core sandwich
C	n	( 0, 0)	1	45 RACUTE = local radius from base to side of
C	n	( 0, 0)	1	50 ROBTUS = local radius from side to crown o
C	n	( 0, 0)	2	55 ENOODL = axial modulus of a corner "noodle"
C	n	( 0, 0)	2	60 DNOODL = weight density of the "noodle" ma
C	n	( 0, 0)	2	65 EFOUND = elastic foam foundation stiffness
C	n	( 0, 0)	2	70 EFNODD = elastic "noodle" Winkler foundati
C	n	( 0, 0)	2	75 IEMOD1 = material type in EMOD1(IEMOD1)
C	y	( 10, 0)	2	80 EMOD1 = elastic modulus in the fiber dire
C	y	( 10, 0)	2	85 EMOD2 = elastic modulus transverse to fib
C	y	( 10, 0)	2	90 G12 = in-plane shear modulus
C	y	( 10, 0)	2	95 G13 = out-of-plane x-z shear modulus
C	y	( 10, 0)	2	100 G23 = out-of-plain y-z shear modulus
C	y	( 10, 0)	2	105 NU = minor (small) Poisson ratio
C	y	( 10, 0)	2	110 ALPHA1 = coef. of thermal expansion along
C	y	( 10, 0)	2	115 ALPHA2 = coef. of thermal expansion transv
C	y	( 10, 0)	2	120 TEMCUR = curing temperature difference
C	y	( 10, 0)	2	125 DENSTY = weight density of material
C	n	( 0, 0)	2	130 ITHICK = layer type (thickness, layup angle
C	y	( 30, 0)	1	135 THICK = layer type thickness
C	y	( 30, 0)	2	140 ANGLE = layer type layup angle
C	y	( 30, 0)	2	145 MATTYP = layer type material type
C	n	( 0, 0)	2	150 JLAYTYP = shell segment number in LAYTYP(IL
C	n	( 0, 0)	2	155 ILAYTYP = layer number in LAYTYP(ILAYTYP,JL
C	y	( 90, 50)	2	160 LAYTYP = layer type
C	n	( 0, 0)	2	165 NLAYRF = number of layers in each face she
C	n	( 0, 0)	2	170 NLAYRC = number of layers around trapezoid
C	n	( 0, 0)	2	175 INTEXT = 0 =pressure on top face sheet; 1
C	n	( 0, 0)	2	180 NSEGS = number of segments in module
C	n	( 0, 0)	2	190 NMODULG = number of modules for general buc
C	n	( 0, 0)	2	195 NMODULL = number of modules for local buckl
C	n	( 0, 0)	2	200 MLOWG = low end of the M-range for genera
C	n	( 0, 0)	2	205 MHIGHG = high end of the M-range for gener
C	n	( 0, 0)	2	210 MLOWL = low end of the range of local buc
C	n	( 0, 0)	2	215 MHIGHL = high end of the M-range for local
C	n	( 0, 0)	2	220 NCASES = Number of load cases (number of e

Table 12, p. 6 of 19

C	Y	(	20,	0)	3	225	PX	= total axial load ( $2 \times \pi \times r \times re$
C	Y	(	20,	0)	3	230	PRESS	= pressure (negative for external p
C	Y	(	20,	0)	3	235	PX0	= total "Load Set B" load
C	Y	(	20,	0)	3	240	PRESS0	= "Load Set B" pressure (external=n
C	Y	(	20,	0)	4	245	LOCBUK	= local buckling load factor
C	Y	(	20,	0)	5	250	LOCBUKA	= allowable for local buckling load
C	Y	(	20,	0)	6	255	LOCBUKF	= factor of safety for local buckli
C	Y	(	20,	0)	4	260	GENBUK	= general buckling load factor
C	Y	(	20,	0)	5	265	GENBUKA	= allowable for general buckling lo
C	Y	(	20,	0)	6	270	GENBUKF	= general buckling factor of safety
C	n	(	0,	0)	2	275	JSTRM1	= number of stress constraints in S
C	Y	(	20,	6)	4	280	STRM1	= stress component
C	Y	(	20,	6)	5	285	STRM1A	= allowable stress in material 1
C	Y	(	20,	6)	6	290	STRM1F	= factor of safety for stress in ma
C	Y	(	20,	6)	4	295	STRM2	= stress in material 2
C	Y	(	20,	6)	5	300	STRM2A	= allowable for stress in material
C	Y	(	20,	6)	6	305	STRM2F	= factor of safety for stress in ma
C	n	(	0,	0)	7	310	WEIGHT	= weight of the truss-core sandwich

C=DECK BEHX1

SUBROUTINE BEHX1

1 (IFILE,NPRINX,IMODX,IFAST,ILOADX,PHRASE)

C PURPOSE: OBTAIN local buckling load factor

C YOU MUST WRITE CODE THAT, USING  
C THE VARIABLES IN THE LABELLED  
C COMMON BLOCKS AS INPUT, ULTIMATELY  
C YIELDS THE RESPONSE VARIABLE FOR  
C THE ith LOAD CASE, ILOADX:

C LOCBUK(ILOADX)

C AS OUTPUT. THE ith CASE REFERS  
C TO ith ENVIRONMENT (e.g. load com-  
C bination).

C DEFINITIONS OF INPUT DATA:

C IMODX = DESIGN CONTROL INTEGER:

C IMODX = 0 MEANS BASELINE DESIGN

C IMODX = 1 MEANS PERTURBED DESIGN

C IFAST = 0 MEANS FEW SHORTCUTS FOR PERTURBED DESIGNS

C IFAST = 1 MEANS MORE SHORTCUTS FOR PERTURBED DESIGNS

C IFILE = FILE FOR OUTPUT LIST:

C NPRINX= OUTPUT CONTROL INTEGER:

C NPRINX=0 MEANS SMALLEST AMOUNT

C NPRINX=1 MEANS MEDIUM AMOUNT

C NPRINX=2 MEANS LOTS OF OUTPUT

C ILOADX = ith LOADING COMBINATION  
C PHRASE = local buckling load factor

C OUTPUT:

C LOCBUK(ILOADX)

C CHARACTER\*80 PHRASE

C INSERT ADDITIONAL COMMON BLOCKS:

COMMON/FV01/LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS  
REAL LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS

COMMON/FV13/EMOD1(10),IEMOD1

REAL EMOD1

COMMON/FV14/EMOD2(10),G12(10),G13(10),G23(10),NU(10),ALPHA1(10)

REAL EMOD2,G12,G13,G23,NU,ALPHA1

COMMON/FV20/ALPHA2(10),TEMCUR(10),DENSTY(10)

REAL ALPHA2,TEMCUR,DENSTY

COMMON/FV23/THICK(30),ITHICK

REAL THICK

COMMON/IV01/MATTYP(30)

INTEGER MATTYP

COMMON/IV02/LAYTYP(90,50),ILAYTYP,JLAYTYP

INTEGER LAYTYP

COMMON/IV03/NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG

INTEGER NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG

COMMON/FV24/ANGLE(30)

REAL ANGLE

COMMON/FV25/PX(20)

REAL PX

Table 12, p. 7 of 19

```

COMMON/FV31/LOCBUK(20), LOCBUKA(20), LOCBUKF(20)
REAL LOCBUK, LOCBUKA, LOCBUKF
COMMON/FV34/GENBUK(20), GENBUKA(20), GENBUKF(20)
REAL GENBUK, GENBUKA, GENBUKF
COMMON/FV37/STRM1(20,6), JSTRM1, STRM1A(20,6), STRM1F(20,6)
REAL STRM1, STRM1A, STRM1F
COMMON/FV40/STRM2(20,6), STRM2A(20,6), STRM2F(20,6)
REAL STRM2, STRM2A, STRM2F
COMMON/IV10/MHIGHG, MLOWL, MHIGHL
INTEGER MHIGHG, MLOWL, MHIGHL
COMMON/FV09/ENOODL, DNOODL, EFOUND, EFNOOD, WEIGHT
REAL ENOODL, DNOODL, EFOUND, EFNOOD, WEIGHT
COMMON/FV26/PRESS(20), PX0(20), PRESS0(20)
REAL PRESS, PX0, PRESS0

C
C
C INSERT SUBROUTINE STATEMENTS HERE.

C
COMMON/INSTAB/INDIC
COMMON/EIGB4M/EIGCOM(200), EIGNEG(200), EIGCRN
COMMON/WWEB4M/NWVCOM(200), NWVNEG(200), IWAVEB, NWVCRN
COMMON/EIGBUK/EIGCRT
COMMON/NWVBUK/NWVCRT
COMMON/BUCKN/N0BX, NMINBX, NMAXBX, INCRBX
COMMON/BUCKN0/N0B, NMAXB
COMMON/RBEGX/RBIG0, RBIGL, RBIGG
COMMON/PRMOUT/IFILE3, IFILE4, IFILE8, IFILE9, IFIL11
COMMON/EIGALL/EIG0, EIG1, EIG2, EIG3, EIG4
COMMON/WAVALL/NWAV0, NWAV1, NWAV2, NWAV3, NWAV4
COMMON/NUMPAR/IPARX, IVARX, IALLOW, ICONSX, NDECX, NLINKX, NESCAP, ITYPEX
common/caseblock/CASE
CHARACTER*28 CASE
CHARACTER*35 CASA

C PI = 3.1415927
C
INDIC = 4
RAVE = 100.*LENGTH*FACLEN/PI
RBIG0 = RAVE
RBIGL = RAVE -FLOAT(NMODULL)*PITCH/2.
N0B = MLOWL*100
NMAXBX = MHIGHL*100

C
CALL BOSDEC(0, 24, ILOADX, INDIC) ←
CALL B4READ ←
CALL GASP(DUM1, DUM2, -2, DUM3) ←
CALL BOSDEC(1, 24, ILOADX, INDIC) ←

C
IF (ITYPEX.EQ.2) THEN
  Get CASE.BEHX1 file for input for BIGBOSOR4...
CASE.BEHX1 is an input file for BIGBOSOR4 for behavior no. 1:
local buckling load
  I=INDEX(CASE, ' ')
  IF(I.NE.0) THEN
    CASA=CASE(:I-1)//'.BEHX1'
  ELSE
    CASA=CASE//'.BEHX1'
  ENDIF
  OPEN(UNIT=61, FILE=CASA, STATUS='UNKNOWN')
  CALL BOSDEC(1, 61, ILOADX, INDIC)
  CLOSE(UNIT=61)
  WRITE(IFILE, '(/,/,A,A,/,A)')
1 ' BIGBOSOR4 input file for:',
1 ' local buckling load',
1 ' CASA
ENDIF

C
CALL B4READ ←
IF (IMODX.EQ.0) THEN
  NOBX = N0B
  NMINBX = NOB
  NMAXBX = NMAXB
  INCRBX = 100
ELSE
  NOBX = NWAV1
  NMINBX = NWAV1
  NMAXBX = NWAV1
  INCRBX = 100

```

BOSDEC creates an  
input file for  
BIGBOSOR4

BIGBOSOR4  
preprocessor

GENOPT user added  
this to the "shaketa1"  
BEHX1 created automatically  
by GENTEXT.

Table 12, p. 8 of 19

BIGBOSCR4 Mainprocessor



```
ENDIF
REWIND IFILE9
CALL STOCM1(IFILE9)
CALL STOCM2(IFILE9)
CALL B4MAIN
CALL GASP(DUM1,DUM2,-2,DUM3)
IF (IMODX.EQ.0) THEN
  EIG1 = EIGCRT
  NWAV1= NWVCRT
ENDIF

C
IF (IMODX.EQ.0) THEN
  WRITE(IFILE,'(/,A)')
  1 ' LOCAL BUCKLING LOAD FACTORS AND MODES (BEHX1)'
  DO 10 I = 1,IWAVEB
    WRITE(IFILE,'(A,1P,E12.4,A,I4,A)')
    1 ' ,EIGCOM(I),(' ,NWVCOM(I),')
10 CONTINUE
  WRITE(IFILE,'(A,1P,E12.4)')
  1' Critical buckling load factor, LOCBUK=',EIGCRT
  WRITE(IFILE,'(A,I5)')
  1' Critical number of circumferential waves, NWVCRT=',NWVCRT
ENDIF
C234567890123456789012345678901234567890123456789012
C
LOCBUK(ILOADX) = EIGCRT
C
RETURN
END

C
C
C
C=C=DECK      BEHX2
SUBROUTINE BEHX2
  1 (IFILE,NPRINX,IMODX,IFAST,ILOADX,PHRASE)
C
C PURPOSE: OBTAIN general buckling load factor
C
C YOU MUST WRITE CODE THAT, USING
C THE VARIABLES IN THE LABELED
C COMMON BLOCKS AS INPUT, ULTIMATELY
C YIELDS THE RESPONSE VARIABLE FOR
C THE ith LOAD CASE, ILOADX:
C
C   GENBUK(ILOADX)
C
C AS OUTPUT. THE ith CASE REFERS
C TO ith ENVIRONMENT (e.g. load com-
C bination).
C
C DEFINITIONS OF INPUT DATA:
C   IMODX = DESIGN CONTROL INTEGER:
C     IMODX = 0 MEANS BASELINE DESIGN
C     IMODX = 1 MEANS PERTURBED DESIGN
C   IFAST = 0 MEANS FEW SHORTCUTS FOR PERTURBED DESIGNS
C   IFAST = 1 MEANS MORE SHORTCUTS FOR PERTURBED DESIGNS
C   IFILE = FILE FOR OUTPUT LIST:
C   NPRINX= OUTPUT CONTROL INTEGER:
C     NPRINX=0 MEANS SMALLEST AMOUNT
C     NPRINX=1 MEANS MEDIUM AMOUNT
C     NPRINX=2 MEANS LOTS OF OUTPUT
C
C   ILOADX = ith LOADING COMBINATION
C   PHRASE = general buckling load factor
C
C OUTPUT:
C
C   GENBUK(ILOADX)
C
CHARACTER*80 PHRASE
C INSERT ADDITIONAL COMMON BLOCKS:
COMMON/FV01/LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
REAL LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
COMMON/FV13/EMOD1(10),IEMOD1
REAL EMOD1
COMMON/FV14/EMOD2(10),G12(10),G13(10),G23(10),NU(10),ALPHA1(10)
REAL EMOD2,G12,G13,G23,NU,ALPHA1
```

```

COMMON/FV20/ALPHA2(10),TEMCUR(10),DENSTY(10)
REAL ALPHA2,TEMCUR,DENSTY
COMMON/FV23/THICK(30),ITHICK
REAL THICK
COMMON/IV01/MATTYP(30)
INTEGER MATTYP
COMMON/IV02/LAYTYP(90,50),ILAYTYP,JLAYTYP
INTEGER LAYTYP
COMMON/IV03/NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
INTEGER NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
COMMON/FV24/ANGLE(30)
REAL ANGLE
COMMON/FV25/PX(20)
REAL PX
COMMON/FV31/LOCBUK(20),LOCBUKA(20),LOCBUKF(20)
REAL LOCBUK,LOCBUKA,LOCBUKF
COMMON/FV34/GENBUK(20),GENBUKA(20),GENBUKF(20)
REAL GENBUK,GENBUKA,GENBUKF
COMMON/FV37/STRM1(20,6),JSTRM1,STRM1A(20,6),STRM1F(20,6)
REAL STRM1,STRM1A,STRM1F
COMMON/FV40/STRM2(20,6),STRM2A(20,6),STRM2F(20,6)
REAL STRM2,STRM2A,STRM2F
COMMON/IV10/MHIGHHG,MLOWL,MHIGHL
INTEGER MHIGHHG,MLOWL,MHIGHL
COMMON/FV09/ENOODL,DNOODL,EFOUND,EFNODD,WEIGHT
REAL ENOODL,DNOODL,EFOUND,EFNODD,WEIGHT
COMMON/FV26/PRESS(20),PX0(20),PRESS0(20)
REAL PRESS,PX0,PRESS0

```

C  
C  
C

INSERT SUBROUTINE STATEMENTS HERE.

C  
C

PI = 3.1415927

INDIC = 4  
RAVE = 100.\*LENGTH/PI  
RBIGG = RAVE - 0.707\*RADIUS  
N0B = MLOWG\*100  
NMAXB = MHIGHHG\*100  
CALL BOSDEC(0,24,ILOADX,INDIC)  
CALL B4READ  
CALL GASP(DUM1,DUM2,-2,DUM3)

CALL BOSDEC(2,24,ILOADX,INDIC)

IF (ITYPEX.EQ.2) THEN  
Get CASE.BEHX2 file for input for BIGBOSOR4...  
CASE.BEHX2 is an input file for BIGBOSOR4 for behavior no. 2:  
general buckling load  
I=INDEX(CASE,' ')  
IF(I.NE.0) THEN  
  CASA=CASE(:I-1)//'.BEHX2'  
ELSE  
  CASA=CASE//'.BEHX2'  
ENDIF  
OPEN(UNIT=61,FILE=CASA,STATUS='UNKNOWN')  
CALL BOSDEC(2,61,ILOADX,INDIC)  
CLOSE(UNIT=61)  
WRITE(UNIT=61,FILE=CASA,STATUS='UNKNOWN')  
'BIGBOSOR4 input file for:',  
'general buckling load',  
1   CASA

Table 12, p. 9 of 19

GENOPT user added  
This to the "skeletal" BEHX2  
created automatically by  
GENTEXT

# Table 12, p.10 of 19

GENOPT user code

```

ENDIF
C
CALL B4READ
IF (IMODX.EQ.0) THEN
  NOBX = NOB
  NMINBX = NOB
  NMAXBX = NMAXB
  INCRBX = 100
ELSE
  NOBX = NWAV2
  NMINBX = NWAV2
  NMAXBX = NWAV2
  INCRBX = 100
ENDIF
REWIND IFILE9
CALL STOCM1(IFILE9)
CALL STOCM2(IFILE9)
CALL B4MAIN
CALL GASP(DUM1,DUM2,-2,DUM3)
IF (IMODX.EQ.0) THEN
  EIG2 = EIGCRT
  NWAV2= NWVCRT
ENDIF
C
IF (IMODX.EQ.0) THEN
  WRITE(IFILE,'(/,A)')
  1 ' GENERAL BUCKLING LOAD FACTORS AND MODES (BEHX2)'
  DO 10 I = 1,IWAVEB
    WRITE(IFILE,'(A,1P,E12.4,A,I4,A)')
    1 , ,EIGCOM(I),('NWVCOM(I),')
  10 CONTINUE
  WRITE(IFILE,'(A,1P,E12.4)')
  1' Critical buckling load factor, GENBUK=',EIGCRT
  WRITE(IFILE,'(A,I5)')
  1' Critical number of circumferential waves, NWVCRT=',NWVCRT
ENDIF
C
GENBUK(ILOADX) = EIGCRT
C
RETURN
END
C
C
C
C

```

```

C=DECK BEHX3
SUBROUTINE BEHX3
 1 (IFILE,NPRINX,IMODX,IFAST,ILOADX,JCOL,PHRASE)
C
C PURPOSE: OBTAIN stress component
C
C YOU MUST WRITE CODE THAT, USING
C THE VARIABLES IN THE LABELLED
C COMMON BLOCKS AS INPUT, ULTIMATELY
C YIELDS THE RESPONSE VARIABLE FOR
C THE ith LOAD CASE, ILOADX:
C
C     STRM1(ILOADX,JCOL)
C
C AS OUTPUT. THE ith CASE REFERS
C TO ith ENVIRONMENT (e.g. load com-
C bination).
C THE jth COLUMN (JCOL)
C INDEX IS DEFINED AS FOLLOWS:
C     number of stress constraints
C
C DEFINITIONS OF INPUT DATA:
C     IMODX = DESIGN CONTROL INTEGER:
C     IMODX = 0 MEANS BASELINE DESIGN
C     IMODX = 1 MEANS PERTURBED DESIGN
C     IFAST = 0 MEANS FEW SHORTCUTS FOR PERTURBED DESIGNS
C     IFAST = 1 MEANS MORE SHORTCUTS FOR PERTURBED DESIGNS
C     IFILE = FILE FOR OUTPUT LIST:
C     NPRINX= OUTPUT CONTROL INTEGER:
C     NPRINX=0 MEANS SMALLEST AMOUNT
C     NPRINX=1 MEANS MEDIUM AMOUNT
C     NPRINX=2 MEANS LOTS OF OUTPUT
C

```

Table 12, p. 11 of 19

```

C ILOADX = ith LOADING COMBINATION
C JCOL = jth column of STRM1
C JCOL = number of stress constraints
C PHRASE = stress component
C
C OUTPUT:
C
C     STRM1(ILOADX,JCOL)
C
C     CHARACTER*80 PHRASE
C INSERT ADDITIONAL COMMON BLOCKS:
COMMON/FV01/LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
REAL LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
COMMON/FV13/EMOD1(10),IEMOD1
REAL EMOD1
COMMON/FV14/EMOD2(10),G12(10),G13(10),G23(10),NU(10),ALPHA1(10)
REAL EMOD2,G12,G13,G23,NU,ALPHA1
COMMON/FV20/ALPHA2(10),TEMCUR(10),DENSTY(10)
REAL ALPHA2,TEMCUR,DENSTY
COMMON/FV23/THICK(30),ITHICK
REAL THICK
COMMON/IV01/MATTYP(30)
INTEGER MATTYP
COMMON/IV02/LAYTYP(90,50),ILAYTYP,JLAYTYP
INTEGER LAYTYP
COMMON/IV03/NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
INTEGER NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
COMMON/FV24/ANGLE(30)
REAL ANGLE
COMMON/FV25/PX(20)
REAL PX
COMMON/FV31/LOCBUK(20),LOCBUKA(20),LOCBUKF(20)
REAL LOCBUK,LOCBUKA,LOCBUKF
COMMON/FV34/GENBUK(20),GENBUKA(20),GENBUKF(20)
REAL GENBUK,GENBUKA,GENBUKF
COMMON/FV37/STRM1(20,6),JSTRM1,STRM1A(20,6),STRM1F(20,6)
REAL STRM1,STRM1A,STRM1F
COMMON/FV40/STRM2(20,6),STRM2A(20,6),STRM2F(20,6)
REAL STRM2,STRM2A,STRM2F
COMMON/IV10/MHIGHG,MLOWL,MHIGHL
INTEGER MHIGHG,MLOWL,MHIGHL
COMMON/FV09/ENOODL,DNOODL,EFOUND,EFOOD,WEIGHT
REAL ENOODL,DNOODL,EFOUND,EFOOD,WEIGHT
COMMON/FV26/PRESS(20),PX0(20),PRESS0(20)
REAL PRESS,PX0,PRESS0

```

```

C
C
C INSERT SUBROUTINE STATEMENTS HERE.

```

```

COMMON/NLAYRX/NLAYER(50)
COMMON/STRANX/EPSX,EPSY1,EPSY3,EPSY5
DIMENSION EPSY(50)
CHARACTER*15 MODE(7)

MODE(1) = ' 0 deg. tension'
MODE(2) = ' 0 deg. comp.'
MODE(3) = '90 deg. tension'
MODE(4) = '90 deg. comp.'
MODE(5) = ' in-plane shear'
MODE(6) = 'von Mises yield'
MODE(7) = ' no failure'

PI = 3.1415927
DTR = PI/180.

EPSY(1) = EPSY1
EPSY(2) = EPSY5
EPSY(3) = EPSY3
EPSY(4) = EPSY5
EPSY(5) = EPSY5
EPSY(6) = EPSY1
EPSY(7) = EPSY5
EPSY(8) = EPSY3
EPSY(9) = EPSY5
EPSY(10) = EPSY5
EPSY(11) = EPSY5
EPSY(12) = EPSY5
EPSY(13) = EPSY5

```

GENOPT user added  
this to the "skeletal"  
BEHX3 created automatically  
by GENTEXT.

Table 12, p. 12 of 19

GENOPT user wrote  
this part of BEK#3

```

EPSY(14) = EPSY5
EPSY(15) = EPSY1
EPSY(16) = EPSY5
EPSY(17) = EPSY3
EPSY(18) = EPSY1
EPSY(19) = EPSY5
EPSY(20) = EPSY5
EPSY(21) = EPSY5
EPSY(22) = EPSY3

C
S1MAX = 0.
S1MIN = 0.
S2MAX = 0.
S2MIN = 0.
S12MAX= 0.
SEFFMX= 0.

C DO 300 ISEG = 1,NSEGS
C
EX = EPSX
EY = EPSY(ISEG)
EXY = 0.

C NLAY = NLAYER(ISEG)
C DO 200 ILAYER = 1,NLAY
C
LTYPE = LAYTYP(ILAYER,ISEG)
M = MATTYP(LTYPE)
IF (M.NE.1) GO TO 200
A1T = -ALPHA1(M)*TEMCUR(M)
A2T = -ALPHA2(M)*TEMCUR(M)
ARG = ANGLE(LTYPE)*DTR
CARG = COS(ARG)
SARG = SIN(ARG)
C2 = CARG**2
S2 = SARG**2
SC = CARG*SARG

C E1, E2, E12 ARE STRAIN COMPONENTS IN MATERIAL COORDINATES...
C
E1 = C2*EX + S2*EY + SC*EXY
E2 = S2*EX + C2*EY - SC*EXY
E12= -2.*SC*(EX - EY) + (C2-S2)*EXY

C
U12 = NU(M)
U21 = 0.
IF (EMOD2(M).GT.0.) U21 = U12*EMOD1(M)/EMOD2(M)
UD = 1. - U12*U21

C SIG1, SIG2, SIG12 = STRESS COMPONENTS IN MATERIAL COORDINATES...
C
SIG1 = ( EMOD1(M)*(E1-A1T) +U12*EMOD1(M)*(E2-A2T))/UD
SIG2 = (U12*EMOD1(M)*(E1-A1T) + EMOD2(M)*(E2-A2T))/UD
SIG12= G12(M)*E12

C Determine if the material M is isotropic, and if so, compute
C the effective (VonMises) stress:
DIFF1 = 1.
DIFF2 = 1.
SIGEFF = 0.
ISOMAT = 0
C234567890123456789012345678901234567890123456789012
IF (EMOD1(M).GT.0.) DIFF1 =ABS(EMOD1(M) -EMOD2(M))/ABS(EMOD1(M))
GISO = EMOD1(M)/(2.*(1.+U12))
IF (G12(M).GT.0.) DIFF2 = ABS(G12(M) - GISO)/ABS(G12(M))
IF (DIFF1.LT.0.05.AND.DIFF2.LT.0.1) ISOMAT = 1
IF (ISOMAT.EQ.1)
1 SIGEFF = SQRT(SIG1**2 +SIG2**2 -SIG1*SIG2 +3.*SIG12**2)

C
IF (ISOMAT.EQ.0) THEN
S1MAX = MAX(S1MAX,SIG1)
S1MIN = MIN(S1MIN,SIG1)
S2MAX = MAX(S2MAX,SIG2)
S2MIN = MIN(S2MIN,SIG2)
S12MAX = MAX(S12MAX,ABS(SIG12))
ELSE
SEFFMX = MAX(SEFFMX,SIGEFF)

```

Table 12, p. 13 of 19

```

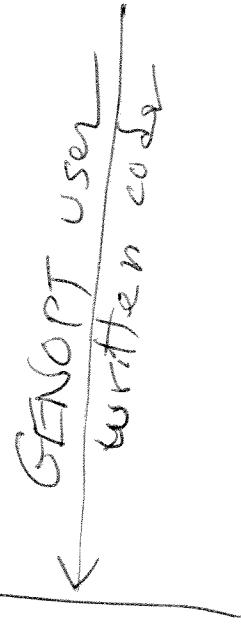
        ENDIF
C      200 CONTINUE
C      300 CONTINUE
C
C      IF (S1MIN.GT.0.0) S1MIN = 0.0
C      IF (S2MIN.GT.0.0) S2MIN = 0.0
C      S1MIN = ABS(S1MIN)
C      S2MIN = ABS(S2MIN)
C
C      IF (SEFFMX.EQ.0.0) THEN
C          STRM1(ILOADX,1) = S1MAX
C          STRM1(ILOADX,2) = S1MIN
C          STRM1(ILOADX,3) = S2MAX
C          STRM1(ILOADX,4) = S2MIN
C          STRM1(ILOADX,5) = S12MAX
C      ELSE
C          STRM1(ILOADX,6) = SEFFMX
C      ENDIF
C
C      IF (IMODX.EQ.0.AND.JCOL.EQ.1) THEN
C          WRITE(IFILE,'(/,A)')
C          1 ' Maximum stress components from BEHX3 (Material type 1):'
C          IF (SEFFMX.EQ.0.0) THEN
C              DO 400 I = 1,5
C                  WRITE(IFILE,'(A,1P,E14.6)') MODE(I),STRM1(ILOADX,I)
C          400 CONTINUE
C      ELSE
C          WRITE(IFILE,'(A,1P,E14.6)') MODE(6),STRM1(ILOADX,6)
C      ENDIF
C      ENDIF
C
C      RETURN
C      END
C
C
C
C

```

```

C=DECK      BEHX4
SUBROUTINE BEHX4
 1 (IFILE,NPRINX,IMODX,IFAST,ILOADX,JCOL,PHRASE)
C
C PURPOSE: OBTAIN stress in material 2
C
C YOU MUST WRITE CODE THAT, USING
C THE VARIABLES IN THE LABELED
C COMMON BLOCKS AS INPUT, ULTIMATELY
C YIELDS THE RESPONSE VARIABLE FOR
C THE ith LOAD CASE, ILOADX:
C
C     STRM2(ILOADX,JCOL)
C
C AS OUTPUT. THE ith CASE REFERS
C TO ith ENVIRONMENT (e.g. load com-
C bination).
C     THE jth COLUMN (JCOL)
C     INDEX IS DEFINED AS FOLLOWS:
C         number of stress constraints
C
C DEFINITIONS OF INPUT DATA:
C     IMODX = DESIGN CONTROL INTEGER:
C         IMODX = 0 MEANS BASELINE DESIGN
C         IMODX = 1 MEANS PERTURBED DESIGN
C     IFAST = 0 MEANS FEW SHORTCUTS FOR PERTURBED DESIGNS
C     IFAST = 1 MEANS MORE SHORTCUTS FOR PERTURBED DESIGNS
C     IFILE = FILE FOR OUTPUT LIST:
C     NPRINX= OUTPUT CONTROL INTEGER:
C         NPRINX=0 MEANS SMALLEST AMOUNT
C         NPRINX=1 MEANS MEDIUM AMOUNT
C         NPRINX=2 MEANS LOTS OF OUTPUT
C
C     ILOADX = ith LOADING COMBINATION
C     JCOL    = jth column of STRM2
C     JCOL    = number of stress constraints
C     PHRASE = stress in material 2
C
C OUTPUT:
C

```



```

C      STRM2(ILOADX,JCOL)
C
C      CHARACTER*80 PHRASE
C      INSERT ADDITIONAL COMMON BLOCKS:
COMMON/FV01/LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
REAL LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
COMMON/FV13/EMOD1(10),IEMOD1
REAL EMOD1
COMMON/FV14/EMOD2(10),G12(10),G13(10),G23(10),NU(10),ALPHA1(10)
REAL EMOD2,G12,G13,G23,NU,ALPHA1
COMMON/FV20/ALPHA2(10),TEMCUR(10),DENSTY(10)
REAL ALPHA2,TEMCUR,DENSTY
COMMON/FV23/THICK(30),ITHICK
REAL THICK
COMMON/IV01/MATTYP(30)
INTEGER MATTYP
COMMON/IV02/LAYTYP(90,50),ILAYTYP,JLAYTYP
INTEGER LAYTYP
COMMON/IV03/NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
INTEGER NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
COMMON/FV24/ANGLE(30)
REAL ANGLE
COMMON/FV25/PX(20)
REAL PX
COMMON/FV31/LOCBUK(20),LOCBUKA(20),LOCBUKF(20)
REAL LOCBUK,LOCBUKA,LOCBUKF
COMMON/FV34/GENBUK(20),GENBUKA(20),GENBUKF(20)
REAL GENBUK,GENBUKA,GENBUKF
COMMON/FV37/STRM1(20,6),JSTRM1,STRM1A(20,6),STRM1F(20,6)
REAL STRM1,STRM1A,STRM1F
COMMON/FV40/STRM2(20,6),STRM2A(20,6),STRM2F(20,6)
REAL STRM2,STRM2A,STRM2F
COMMON/IV10/MHIGHG,MLOWL,MHIGHL
INTEGER MHIGHG,MLOWL,MHIGHL
COMMON/FV09/ENOODL,DNOODL,EFOUND,EFOOD,WEIGHT
REAL ENOODL,DNOODL,EFOUND,EFOOD,WEIGHT
COMMON/FV26/PRESS(20),PX0(20),PRESS0(20)
REAL PRESS,PX0,PRESS0

```

```

C
C      INSERT SUBROUTINE STATEMENTS HERE.
C
COMMON/NLAYRX/NLAYER(50)
COMMON/STRANX/EPSX,EPSY1,EPSY3,EPSY5
DIMENSION EPSY(50)
CHARACTER*15 MODE(7)

```

```

C      MODE(1) = '0 deg. tension'
MODE(2) = '0 deg. comp.'
MODE(3) = '90 deg. tension'
MODE(4) = '90 deg. comp.'
MODE(5) = 'in-plane shear'
MODE(6) = 'von Mises yield'
MODE(7) = 'no failure'

```

```

C      PI = 3.1415927
DTR = PI/180.

```

```

C
EPSY(1) = EPSY1
EPSY(2) = EPSY5
EPSY(3) = EPSY3
EPSY(4) = EPSY5
EPSY(5) = EPSY5
EPSY(6) = EPSY1
EPSY(7) = EPSY5
EPSY(8) = EPSY3
EPSY(9) = EPSY5
EPSY(10) = EPSY5
EPSY(11) = EPSY5
EPSY(12) = EPSY5
EPSY(13) = EPSY5
EPSY(14) = EPSY5
EPSY(15) = EPSY1
EPSY(16) = EPSY5
EPSY(17) = EPSY3
EPSY(18) = EPSY1
EPSY(19) = EPSY5
EPSY(20) = EPSY5

```

Table 12, p. 14 of 19

Genopt User-written  
 (almost a copy of the  
 code written in BEAM3)

Table 12, p. 15 of 19

```

EPSY(21) = EPSY5
EPSY(22) = EPSY3
C
S1MAX = 0.
S1MIN = 0.
S2MAX = 0.
S2MIN = 0.
S12MAX= 0.
SEFFMX= 0.
C
DO 300 ISEG = 1,NSEGS
C
EX = EPSX
EY = EPSY(ISEG)
EXY = 0.
C
NLAY = NLAYER(ISEG)
C
DO 200 ILAYER = 1,NLAY
C
LTYPE = LAYTYP(ILAYER,ISEG)
M = MATTYP(LTYPE)
IF (M.NE.2) GO TO 200
A1T = -ALPHA1(M)*TEMCUR(M)
A2T = -ALPHA2(M)*TEMCUR(M)
ARG = ANGLE(LTYPE)*DTR
CARG = COS(ARG)
SARG = SIN(ARG)
C2 = CARG**2
S2 = SARG**2
SC = CARG*SARG
C
E1, E2, E12 ARE STRAIN COMPONENTS IN MATERIAL COORDINATES...
C
E1 = C2*EX + S2*EY + SC*EXY
E2 = S2*EX + C2*EY - SC*EXY
E12= -2.*SC*(EX - EY) + (C2-S2)*EXY
C
U12 = NU(M)
U21 = 0.
IF (EMOD2(M).GT.0.) U21 = U12*EMOD1(M)/EMOD2(M)
UD = 1. - U12*U21
C
SIG1, SIG2, SIG12 = STRESS COMPONENTS IN MATERIAL COORDINATES...
C
SIG1 = ( EMOD1(M)*(E1-A1T) +U12*EMOD1(M)*(E2-A2T) )/UD
SIG2 = (U12*EMOD1(M)*(E1-A1T) + EMOD2(M)*(E2-A2T))/UD
SIG12= G12(M)*E12
C
Determine if the material M is isotropic, and if so, compute
the effective (VonMises) stress:
DIFF1 = 1.
DIFF2 = 1.
SIGEFF = 0.
ISOMAT = 0
C234567890123456789012345678901234567890123456789012
IF (EMOD1(M).GT.0.) DIFF1 =ABS(EMOD1(M)-EMOD2(M))/ABS(EMOD1(M))
GISO = EMOD1(M)/(2.*1.+U12)
IF (G12(M).GT.0.) DIFF2 = ABS(G12(M)-GISO)/ABS(G12(M))
IF (DIFF1.LT.0.05.AND.DIFF2.LT.0.1) ISOMAT = 1
IF (ISOMAT.EQ.1)
1 SIGEFF = SQRT(SIG1**2 +SIG2**2 -SIG1*SIG2 +3.*SIG12**2)
C
IF (ISOMAT.EQ.0) THEN
  S1MAX = MAX(S1MAX,SIG1)
  S1MIN = MIN(S1MIN,SIG1)
  S2MAX = MAX(S2MAX,SIG2)
  S2MIN = MIN(S2MIN,SIG2)
  S12MAX = MAX(S12MAX,ABS(SIG12))
ELSE
  SEFFMX = MAX(SEFFMX,SIGEFF)
ENDIF
C
200 CONTINUE
300 CONTINUE
C
IF (S1MIN.GT.0.0) S1MIN = 0.0
IF (S2MIN.GT.0.0) S2MIN = 0.0

```

GEKOPT user wrote this  
 (almost a copy of GENOPT user  
 written code in BEHX3)

Table 12, p. 16 of 19

```
C          S1MIN = ABS(S1MIN)
C          S2MIN = ABS(S2MIN)
C
C          IF (SEFFMX.EQ.0.0) THEN
C              STRM2(ILOADX,1) = S1MAX
C              STRM2(ILOADX,2) = S1MIN
C              STRM2(ILOADX,3) = S2MAX
C              STRM2(ILOADX,4) = S2MIN
C              STRM2(ILOADX,5) = S12MAX
C          ELSE
C              STRM2(ILOADX,6) = SEFFMX
C          ENDIF
C
C          IF (IMODX.EQ.0.AND.JCOL.EQ.1) THEN
C              WRITE(IFILE,'(/,A)')
C              1 ' Maximum stress components from BEHX4 (Material type 2):'
C              IF (SEFFMX.EQ.0.0) THEN
C                  DO 400 I = 1,5
C                      WRITE(IFILE,'(A,1P,E14.6)' MODE(I),STRM2(ILOADX,I))
C                  CONTINUE
C              ELSE
C                  WRITE(IFILE,'(A,1P,E14.6)' MODE(6),STRM2(ILOADX,6))
C              ENDIF
C          ENDIF
C
C          RETURN
C      END
C
C
C
C=DECK      USRCON
SUBROUTINE USRCON(INUMTT,IMODX,CONMAX,ICONSX,IPOINC,CONSTX,
1 WORDCX,WORDMX,PCWORD,CPLOTX,ICARX,IFILEX)
C PURPOSE: GENERATE USER-WRITTEN
C INEQUALITY CONSTRAINT CONDITION
C USING ANY COMBINATION OF PROGRAM
C VARIABLES.
C YOU MUST WRITE CODE THAT, USING
C THE VARIABLES IN THE LABELLED
C COMMON BLOCKS AS INPUT, ULTIMATELY
C YIELDS A CONSTRAINT CONDITION,
C CALLED "CONX" IN THIS ROUTINE.
DIMENSION WORDCX(*),WORDMX(*),IPOINC(*),CONSTX(*)
DIMENSION PCWORD(*),CPLOTX(*)
CHARACTER*80 WORDCX,WORDMX,PCWORD
C INSERT ADDITIONAL COMMON BLOCKS:
COMMON/FV01/LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
REAL LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
COMMON/FV13/EMOD1(10),IEMOD1
REAL EMOD1
COMMON/FV14/EMOD2(10),G12(10),G13(10),G23(10),NU(10),ALPHA1(10)
REAL EMOD2,G12,G13,G23,NU,ALPHA1
COMMON/FV20/ALPHA2(10),TEMCUR(10),DENSTY(10)
REAL ALPHA2,TEMCUR,DENSTY
COMMON/FV23/THICK(30),ITHICK
REAL THICK
COMMON/IV01/MATTYP(30)
INTEGER MATTYP
COMMON/IV02/LAYTYP(90,50),ILAYTYP,JLAYTYP
INTEGER LAYTYP
COMMON/IV03/NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
INTEGER NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
COMMON/FV24/ANGLE(30)
REAL ANGLE
COMMON/FV25/PX(20)
REAL PX
COMMON/FV31/LOCBUK(20),LOCBUKA(20),LOCBUKF(20)
REAL LOCBUK,LOCBUKA,LOCBUKF
COMMON/FV34/GENBUK(20),GENBUKA(20),GENBUKF(20)
REAL GENEUK,GENBUKA,GENBUKF
COMMON/FV37/STRM1(20,6),JSTRM1,STRM1A(20,6),STRM1F(20,6)
REAL STRM1,STRM1A,STRM1F
COMMON/FV40/STRM2(20,6),STRM2A(20,6),STRM2F(20,6)
REAL STRM2,STRM2A,STRM2F
COMMON/IV10/MHIGHG,MLOWL,MHIGHL
INTEGER MHIGHG,MLOWL,MHIGHL
COMMON/FV09/ENOODL,DNOODL,EFOUND,EFNOOD,WEIGHT
```

~~GenOpt user written code~~

Created automatically by GENTEXT

Table 12, p.17 of 19

```
REAL ENOODL,DNOODL,EFOUND,EFNOOD,WEIGHT
COMMON/FV26/PRESS(20),PX0(20),PRESS0(20)
REAL PRESS,PX0,PRESS0

C CONX = 0.0
C
C INSERT USER-WRITTEN STATEMENTS
C HERE. THE CONSTRAINT CONDITION
C THAT YOU CALCULATE IS CALLED "CONX"
C
IF (CONX.EQ.0.0) RETURN
IF (CONX.LT.0.0) THEN
    WRITE(IFILEX,' CONX MUST BE GREATER THAN ZERO.')
    CALL EXIT
ENDIF

C DO NOT CHANGE THE FOLLOWING STATEMENTS, EXCEPT WORDC
C
ICARX = ICARX + 1
INUMTT = INUMTT + 1
WORDCX(ICARX) = ' USER: PROVIDE THIS.'
CPLOTX(ICARX) = CONX - 1.
CALL BLANKX(WORDCX(ICARX),IENDP)
PCWORD(ICARX) = WORDCX(ICARX)(1:IENDP)//' -1'
IF (IMODX.EQ.0.AND.CONX.GT.CONMAX) GO TO 200
IF (IMODX.EQ.1.AND.IPOINC(INUMTT).EQ.0) GO TO 200
ICONSX = ICONSX + 1
IF (IMODX.EQ.0) IPOINC(INUMTT) = 1
CONSTX(ICONSX) = CONX
WORDMX(ICONSX) = WORDCX(ICARX)(1:IENDP)//' -1'
200 CONTINUE
C END OF USRCON
C
C
C RETURN
END

C=DECK      USRLNK
SUBROUTINE USRLNK(VARI,I,VARIAB)
C Purpose: generate user-written
C linking conditions using any
C combination of decision variables.
C You must write code that, using
C the variables in the subroutine
C argument VARIAB as input, ultimately
C yield a value for the linked variable
C VARI.
C
C VARI is the Ith entry of the array
C VARIAB. You have decided that this
C is to be a linked variable with user
C defined linking. It is linked to
C the decision variables in the array
C VARIAB.
C An example will provide the simplest
C explanation of this:
C Let's say that the 5th decision
C variable candidate (I=5) is linked
C to the decision variable candidates
C 2 and 7. (You used DECIDE to select
C these as decision variables.
C In this case VARI is equal to
C VARIAB(I). You then write your
C linking equation in the form
C VARI=f(VARIAB(2),VARIAB(7)).
C Use the index I in an IF statement if
C you have more than one user-defined
C linked variable.
C
C
REAL VARI,VARIAB(50)
INTEGER I
C
C INSERT USER-WRITTEN DECLARATION
C STATEMENTS HERE.
```

Created entirely by GENTEXT

C INSERT USER-WRITTEN  
 C STATEMENTS HERE.  
 C  
 C END OF USRLNK  
 RETURN  
 END  
 C=DECK OBJECT  
 SUBROUTINE OBJECT(IFILE,NPRINX,IMODX,OBJGEN,PHRASE)  
 PURPOSE: weight of the truss-core sandwich module  
 C  
 YOU MUST WRITE CODE THAT, USING  
 THE VARIABLES IN THE LABELLED  
 COMMON BLOCKS AS INPUT, ULTIMATELY  
 YIELDS THE OBJECTIVE FUNCTION  
 WEIGHT  
 AS OUTPUT. MAKE SURE TO INCLUDE AT  
 THE END OF THE SUBROUTINE, THE  
 STATEMENT: OBJGEN = WEIGHT  
 C  
 C DEFINITIONS OF INPUT DATA:  
 IMODX = DESIGN CONTROL INTEGER:  
 IMODX = 0 MEANS BASELINE DESIGN  
 IMODX = 1 MEANS PERTURBED DESIGN  
 IFAST = 0 MEANS FEW SHORTCUTS FOR PERTURBED DESIGNS  
 IFAST = 1 MEANS MORE SHORTCUTS FOR PERTURBED DESIGNS  
 IFILE = FILE FOR OUTPUT LIST:  
 NPRINX= OUTPUT CONTROL INTEGER:  
 NPRINX=0 MEANS SMALLEST AMOUNT  
 NPRINX=1 MEANS MEDIUM AMOUNT  
 NPRINX=2 MEANS LOTS OF OUTPUT  
 C  
 C DEFINITION OF PHRASE:  
 PHRASE = weight of the truss-core sandwich module  
 C  
 CHARACTER\*80 PHRASE  
 C INSERT ADDITIONAL COMMON BLOCKS:  
 COMMON/FV01/LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS  
 REAL LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS  
 COMMON/FV13/EMOD1(10),IEMOD1  
 REAL EMOD1  
 COMMON/FV14/EMOD2(10),G12(10),G13(10),G23(10),NU(10),ALPHA1(10)  
 REAL EMOD2,G12,G13,G23,NU,ALPHA1  
 COMMON/FV20/ALPHA2(10),TEMCUR(10),DENSTY(10)  
 REAL ALPHA2,TEMCUR,DENSTY  
 COMMON/FV23/THICK(30),ITHICK  
 REAL THICK  
 COMMON/IV01/MATTYP(30)  
 INTEGER MATTYP  
 COMMON/IV02/LAYTYP(90,50),ILAYTYP,JLAYTYP  
 INTEGER LAYTYP  
 COMMON/IV03/NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLONG  
 INTEGER NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLONG  
 COMMON/FV24/ANGLE(30)  
 REAL ANGLE  
 COMMON/FV25/PX(20)  
 REAL PX  
 COMMON/FV31/LOCBUK(20),LOCBUKA(20),LOCBUKF(20)  
 REAL LOCBUK,LOCBUKA,LOCBUKF  
 COMMON/FV34/GENBUK(20),GENBUKA(20),GENBUKF(20)  
 REAL GENBUK,GENBUKA,GENBUKF  
 COMMON/FV37/STRM1(20,6),JSTRM1,STRM1A(20,6),STRM1F(20,6)  
 REAL STRM1,STRM1A,STRM1F  
 COMMON/FV40/STRM2(20,6),STRM2A(20,6),STRM2F(20,6)  
 REAL STRM2,STRM2A,STRM2F  
 COMMON/IV10/MHIGHG,MLOWL,MHIGHL  
 INTEGER MHIGHG,MLOWL,MHIGHL  
 COMMON/FV09/ENOOL,DNOOL,EFOUND,EFOOD,WEIGHT  
 REAL ENOOL,DNOOL,EFOUND,EFOOD,WEIGHT  
 COMMON/FV26/PRESS(20),PX0(20),PRESS0(20)  
 REAL PRESS,PX0,PRESS0  
 C  
 C INSERT SUBROUTINE STATEMENTS HERE.  
 C

Table 12, p.18 of 19  
The objective is computed.

Created by GENOPT

GENOPT User  
 added this

```

COMMON/GEOM2X/RP1(50),RP2(50),ZP1(50),ZP2(50),RPC(50),ZPC(50)
C
C      WGTALL = 0.
C
C      DO 300 ISEG = 1,NSEGS
C
C2345678901234567890123456789012345678901234567890123456789012
C      ARING1 = 0.
C      ARING2 = 0.
C      SEGLNG = SQRT((RP2(ISEG) -RP1(ISEG))**2 +(ZP2(ISEG) -ZP1(ISEG))**2)
C      IF (ISEG.EQ.2.OR.ISEG.EQ.10.OR.ISEG.EQ.16.OR.ISEG.EQ.20) THEN
C          SEGLNG = RADOBT*2.*PHI
C          ARING2 = AREA2
C      ENDIF
C      IF (ISEG.EQ.5.OR.ISEG.EQ.9.OR.ISEG.EQ.14.OR.ISEG.EQ.21) THEN
C          SEGLNG = RADACU*2.*ALPHA
C          ARING1 = AREA1
C      ENDIF
C
C      NLAY = NLAYER(ISEG)
C      WTHICK = 0.
C      DO 200 ILAYER = 1,NLAY
C          LTYPE = LAYTYP(ILAYER,ISEG)
C          M = MATTYP(LTYPE)
C          WTHICK = WTHICK + THICK(LTYPE)*DENSTY(M)
200  CONTINUE
C
C      WGTALL = WGTALL + WTHICK*SEGLNG +(ARING1+ARING2)*DNOODL
C
300  CONTINUE
C
C      WEIGHT = WGTALL/PITCH
C
C      IF (IMODX.EQ.0) THEN
C          WRITE(IFILE,'(/,A,1P,E14.6,/,A,/,1P6E12.4)')
C          1 ' Objective =weight per surface area from OBJECT =',WEIGHT,
C          1 ' PHI,ALPHA,AREA1,AREA2,RADACU,RADOBT=',
C          1 ' PHI,ALPHA,AREA1,AREA2,RADACU,RADOBT
C      ENDIF
C
C      OBJGEN =WEIGHT
C
C      RETURN
C
END
C
C

```

Table 12, p. 19 of 19

GENOPT user  
written code

End of BEHAVIOR.TRUSSCOMP  
file.

# Table 13a bosdec.trusscomp (13 pages)

An abridged version of the file, `bosdec.trusscomp`, which generates valid input files for BIGBOSOR4 for "huge torus" models of the axially compressed cylindrical shell with a composite truss-core sandwich wall construction. Two types of "huge torus" models are constructed: 1. a "huge torus" model for local buckling (`INDX = 1`), and 2. a "huge torus" model for general buckling (`INDX = 2`).

```

C=DECK      BOSDEC
C
C PURPOSE IS TO SET UP BIGBOSOR4 INPUT FILE FOR "trusscomp"
C
C SUBROUTINE BOSDEC(INDX,IFIL14,ILOADX,INDIC)
C Insert labelled common blocks: trusscomp.COM
COMMON/FV01/LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
REAL LENGTH,FACLEN,RADIUS,PITCH,BCROWN,HEIGHT,RACUTE,ROBTUS
COMMON/FV13/EMOD1(10),IEMOD1
REAL EMOD1
COMMON/FV14/EMOD2(10),G12(10),G13(10),G23(10),NU(10),ALPHA1(10)
REAL EMOD2,G12,G13,G23,NU,ALPHA1
COMMON/FV20/ALPHA2(10),TEMCUR(10),DENSTY(10)
REAL ALPHA2,TEMCUR,DENSTY
COMMON/FV23/THICK(30),ITHICK
REAL THICK
COMMON/IV01/MATTYP(30)
INTEGER MATTYP
COMMON/IV02/LAYTYP(90,50),ILAYTYP,JLAYTYP
INTEGER LAYTYP
COMMON/IV03/NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
INTEGER NLAYRF,NLAYRC,INTEXT,NSEGS,NMODULG,NMODULL,MLOWG
COMMON/FV24/ANGLE(30)
REAL ANGLE
COMMON/FV25/PX(20)
REAL PX
COMMON/FV31/LOCBUK(20),LOCBUKA(20),LOCBUKF(20)
REAL LOCBUK,LOCBUKA,LOCBUKF
COMMON/FV34/GENBUK(20),GENBUKA(20),GENBUKF(20)
REAL GENBUK,GENBUKA,GENBUKF
COMMON/FV37/STRM1(20,6),JSTRM1,STRM1A(20,6),STRM1F(20,6)
REAL STRM1,STRM1A,STRM1F
COMMON/FV40/STRM2(20,6),STRM2A(20,6),STRM2F(20,6)
REAL STRM2,STRM2A,STRM2F
COMMON/IV10/MHIGHG,MLOWL,MHIGHL
INTEGER MHIGHG,MLOWL,MHIGHL
COMMON/FV09/ENOODL,DNOODL,EFOUND,EFOOD,WEIGHT
REAL ENOODL,DNOODL,EFOUND,EFOOD,WEIGHT
COMMON/FV26/PRESS(20),PX0(20),PRESS0(20)
REAL PRESS,PX0,PRESS0
C end of welded.COM
COMMON/MODULX/MODULL,MODULG
COMMON/CSKINY/CSKIN1(6,6,295)
COMMON/BUCKN0/N0B,NMAXB
COMMON/RBEGX/RBIG0,RBIGL,RBIGG
COMMON/NLAYRX/NLAYER(50)
COMMON/STRANX/EPSX,EPSY1,EPSY3,EPSY5
COMMON/GEOM1X/RADACU,RADOBT,PHI,ALPHA,AREA1,AREA2
COMMON/GEOM2X/RL1(50),RL2(50),ZL1(50),ZL2(50),RLC(50),ZLC(50)
DIMENSION RP1(50),RP2(50),ZP1(50),ZP2(50),RPC(50),ZPC(50)
DIMENSION R1(50),R2(50),Z1(50),Z2(50),RC(50),ZC(50),SROT(50)
DIMENSION FOUND(50),PRESUR(50),ZVAL(50),ZRING(50),ZNORM(50)
DIMENSION NSHAPE(50),NNODES(50),NRING(50),IRING(300),NSUR(50)
DIMENSION DRADIA(50),DAXIAL(50),RGAREA(50),FN10(50),FN20(50)
DIMENSION IDISP(50,4),JPREV(50,2),JNODPV(50,2)
DIMENSION NPREV(50),NODPFV(50,2),NGRND(50),NODGRD(50,2)
DIMENSION NTYPE(50),IPTRNG(50)
DIMENSION RCURV1(50),RCURV2(50),ZCURV1(50),ZCURV2(50)
DIMENSION RCURVC(50),ZCURVC(50)
DIMENSION NLAYR2(10),LAYTP2(90,10)
COMMON/PRMOUT/IFILE3,IFILE4,IFILE8,IFILE9,IFILE11
REWIND IFIL14
C
WRITE(IFILE4,3)
3 FORMAT(''***** BOSDEC *****'')
1' The purpose of BOSDEC is to set up an input file, NAME.ALL,''

```

```

1' for a cylindrical shell. NAME is your name for/
1' the case. The file NAME.ALL is a BOSOR4 input "deck" used/
1' by SUBROUTINE B4READ.'/
1' ****
C
NSEGS = 22
PI = 3.1415927
IF (INDX.EQ.0) THEN
  NMODUL = 1
  RBEG = RBIGO
ENDIF
IF (INDX.EQ.1) THEN
  NMODUL = NMODULL
  RBEG = RBIGL
ENDIF
IF (INDX.EQ.2) THEN
  NMODUL = NMODULG
  RBEG = RBIGG
ENDIF
C
IF (INDX.EQ.0.OR.INDX.EQ.1.OR.INDX.EQ.2) THEN
C
  CALL MOVER(0.,0,SROT,1,50)
  CALL MOVER(0.,0,ZRING,1,50)
  CALL MOVER(0.,0,ZNORM,1,50)
  CALL MOVER(0.,0,DRADIA,1,50)
  CALL MOVER(0.,0,DAXIAL,1,50)
  CALL MOVER(0.,0,RGAREA,1,50)
  CALL MOVER(0.,0,PRESUR,1,50)
  CALL MOVER(0.,0,FOUND,1,50)
  CALL MOVER(0.,0,FN10,1,50)
  CALL MOVER(0.,0,FN20,1,50)
  CALL MOVER(0.,0,IPTRNG,1,50)
  CALL MOVER(1, 0, IDISP,1,200)
  CALL MOVER(0, 0,JPREV,1,100)
  CALL MOVER(0, 0,JNODPV,1,100)
  CALL MOVER(0, 0,NPREV,1,50)
  CALL MOVER(0, 0,NODPRV,1,100)
  CALL MOVER(0, 0,NGRND,1,50)
  CALL MOVER(0, 0,NODGRD,1,100)
FNOOD1 = 0.
FNOOD2 = 0.
FNOODL = 0.
PRESS1 = PRESS(ILOADX)
C
C Single truss-core sandwich 22 segment module model...
C
SWIDTH = 0.5*PITCH - BCROWN ← $ in Fig. 1
IF (SWIDTH.LT.0.0) THEN
  WRITE(IFILE4,'(/,A,,A,,A,1P,E12.4,,A,1P,E12.4,,A)')
  ' **** RUN ABORT ****'
  ' 0.5*PITCH -BCROWN is negative. Illegal configuration',
  ' Single module width, PITCH =',PITCH,
  ' Width of truss core crown, BCROWN=',BCROWN,
  ' ****'
  CALL ERREX
ENDIF
TWOPHI = ATAN(HEIGHT/SWIDTH)
PHI = TWOPHI/2.
SPHI = SIN(PHI)
CPHI = COS(PHI)
ZVAL(1) = 0.
DO 5 I = 1,NLAYRC
  LINdex = LAYTYP(I,1)
  ZVAL(1) = ZVAL(1) + THICK(LINDEX)
CONTINUE
RADACU = RACUTE +ZVAL(1) ← RADACU = R1 in Figs. 10 & 8§1
RADOBT = ROBTUS +ZVAL(1) ← RADOBT = R2 in Figs. 10 & 8§1
DWIDTH = RADACU/TAN(PHI) ← d in Figs. 10 & 1
TWOALP = PI - TWOPHI
ALPHA = TWOALP/2.
CWIDTH = RADOBT/TAN(ALPHA) ←
GAMMA = PI/2. - TWOPHI
CTWOPH = COS(TWOPHI)
STWOPH = SIN(TWOPHI)
CGAMMA = COS(GAMMA)
SGAMMA = SIN(GAMMA)
AREA1 = DWIDTH*RADACU -ALPHA*RADACU**2 ← Fig. 7 (top)

```

core in fig

See Figs. 10-13 for  
 $\phi, \alpha, \chi$

|||

Table 13<sup>a</sup>, p. 3 of 13

Fig. 7 (bottom)

```
C AREA2 = CWIDTH*RADOBT - PHI*RADOBT**2
C IMODEL = 1 is the elaborate model used for local buckling
C IMODEL = 1
C NSEGSM = 22
C IF (IMODX.EQ.0) MODULL = NMODUL
C MODULS = MODULL
C
C IF (INDX.EQ.2) THEN
C IMODEL = 2 is the simpler model used for general buckling
C   IMODEL = 2
C   NSEGSM = 6
C The number of modules, "MODULG" should be such that the
C model for general buckling subtends close to 90 degrees
C of circumference...
C   IF (IMODX.EQ.0) MODULG = (PI/1.89)*RADIUS/PITCH
C   MODULS = MODULG
C   IF (NSEGSM*MODULS.GT.288) THEN
C     WRITE(IFI4,'(/,A,/A,2I5,/A,/A,)')
C     1   '***** RUN ABORT *****',
C     1   ' MODULS, MSEGS = NSEGSM*MODULS = ',MODULS,NSEGSM*MODULS,
C     1   ' MSEGS = Too many segments. Maximum number is 288.',
C     1   '*****',
C C234567890123456789012345678901234567890123456789012
C   CALL ERREX
C   ENDIF
C ENDIF
C
C IF (IMODEL.EQ.1.AND.NMODUL.GT.13) THEN
C   WRITE(IFI4,'(/,A,/A,I10,/A,/A)')
C   1   '***** RUN ABORT *****',
C   1   ' NMODUL = ',NMODUL,
C   1   ' Too many modules. Maximum number of modules is 13.',
C   1   '*****',
C   CALL ERREX
C ENDIF
C
C IF (INDX.EQ.1.OR.INDX.EQ.2) THEN
C   C111MD = CSKIN1(2,2,1) - CSKIN1(1,2,1)**2/CSKIN1(1,1,1)
C   C113MD = CSKIN1(2,2,3) - CSKIN1(1,2,3)**2/CSKIN1(1,1,3)
C   C115MD = CSKIN1(2,2,5) - CSKIN1(1,2,5)**2/CSKIN1(1,1,5)
C   TOTLNG = 2.*PI*RADIUS/PITCH
C   ARC2 = 4.*RADOBT*2.*PHI
C   ARC5 = 4.*RADACU*2.*ALPHA
C   RATIO5 = C115MD/C111MD
C   IF (IMODEL.EQ.1) THEN
C     RATIO3 = C113MD/C111MD
C     EANODD = ENOIDL*(AREA1 + AREA2) ← axial stiffness of "noodle"
C   ELSE
C     FL4 = DWIDTH - CWIDTH
C     FL3 = DWIDTH + CWIDTH
C     EANODD = ENOIDL*(AREA1 + AREA2)
C   1   +C115MD*(ARC1 + ARC2 + FL4 - FL3 - 2.*DWIDTH) ← Fig. 6 (bottom)
C   AREA = EANODD/ENOIDL
C   ENDIF
C ENDIF
C
C INDX = 1 means SUBROUTINE BOSDEC generates LOCAL buckling model
C INDX = 2 means SUBROUTINE BOSDEC generates GENERAL buckling model
C IMODEL = model index used for buckling:
C   IMODEL = 1 means LOCAL buckling
C   IMODEL = 2 means GENERAL buckling
C
C MODEL2 = the model used for GENERAL buckling
C IMODUL = the module number in a multi-module model
C MODULS = number of modules in the model
C RBEG = horizontal radius to the beginning of the first module
C   in the multi-module model, where
C   1. for the LOCAL buckling model:
C     RBEG = RBIGL = RAVE - FLOAT(NMODULL)*PITCH/2.
C     in which RAVE = 100.*LENGTH*FACLEN/PI
C   2. for the GENERAL buckling model:
C     RBEG = RBIGG = RAVE - 0.707*RADIUS
C     in which RAVE = 100.*LENGTH/PI
C
C where
C NMODULL = number of modules in the local buckling model
C PITCH = the module width, b, shown in Fig. 1
C LENGTH = the total length of the cylindrical shell
```

```

C      FACLEN = fraction of LENGTH used for local buckling model
C      RADIUS = radius of the cylindrical shell measured to
C                  the innermost face sheet.
C
C      BETA   = angle shown in Fig. 9
C      ISEGST = number of shell segments in all the previous modules
C      IRGST  = number of discrete rings in all the previous modules
C      NLAYRC = number of layers in the truss-core wrap, Fig.8
C      NLAYRF = number of layers in each added face sheet, Fig.8
C      ZVAL   = distance from the leftmost shell segment surface
C                  to the shell segment reference surface as we
C                  "travel" along the shell segment
C      NLAYER(i) = number of layers in the ith shell segment
C                  in the model for local buckling (IMODEL=1)
C      LAYTYP(i,j) = layer type (layer index) for layer i, segment j
C                  for IMODEL=1 (local buckling model)
C      NLAYR2(i) = number of layers in the ith shell segment
C                  in the model for general buckling (IMODEL=2)
C      LAYTP2(i,j) = layer type (layer index) for layer i, segment j
C                  for IMODEL=2 (general buckling model)
C
C      R1(i),R2(i),Z1(i),Z2(i),RC(i),ZC(i) =
C                  (r,z) end points and center of curvature (rc,zc)
C                  for the ith shell segment as if the module were
C                  flat, as is shown in Fig.1 and in Figs. 10 - 13
C      RCURV1(i),RCURV2(i),ZCURV1(i),ZCURV2(i),RCURVC(i),ZCURVC(i) =
C                  (r,z) end points and center of curvature (rc,zc)
C                  for the ith shell segment as if the module were
C                  curved, as is shown in Fig. 2
C      RP1(i),RP2(i),ZP1(i),ZP2(i),RPC(i),ZPC(i) =
C                  (r,z) end points and center of curvature (rc,zc)
C                  for the ith shell segment as if the module were
C                  curved, as is shown in Fig.2, for module number
C                  IMODUL. (See Fig. 9)
C
C      IRING  = global discrete ring number
C      NTYPE   = type of callout used for the location of ring
C                  attachment point to the ith shell segment.
C                  NOTE: NTYPE(i) = 1 is always used in this project.
C                  NTYPE(i) = 1 means that the location of the ring
C                  attachment point to the shell segment is identified
C                  by its nodal point number within that shell segment.
C                  BIGBOSOR4 had to be modified to do this. Until now
C                  BIGBOSOR4 only permitted callout locations to be
C                  identified by either radial (r) or axial (z) numbers.
C                  The modification to BIGBOSOR4 was needed to avoid input
C                  errors in BIGBOSOR4 caused by lack of monotonicity
C                  of r-values or z-values within a single shell segment.
C
C      IPTRNG = nodal point number of the attachment point of the
C                  discrete ring to the ith shell segment
C     ZNORM   = distance from the ring attachment point to the ring
C                  centroid, measured normal to the ith shell segment.
C                  Fig. 2 shows locations of the centroids of the
C                  eight discrete rings used in each module of the
C                  local buckling model. A detailed view of the
C                  relationship of the ring attachment point and the
C                  ring centroid is given at the top of Fig. 7.
C
C      AREA1  = cross section area shown at the top of Fig. 7
C      AREA2  = cross section area shown at the bottom of Fig. 7
C
C      The total cross section area of a "noodle" is
C      AREA1 + AREA2. In the local buckling model there
C      are two discrete rings for each noodle, one
C      attached to curved shell segments such as
C      that shown at the top of Fig. 7 and the other
C      attached to curved shell segments such as
C      that shown at the bottom of Fig. 7. In the general
C      buckling model there is only one discrete ring
C      for each noodle, modeled as displayed in Fig. 6.
C
C      C111MD = axial stiffness of shell segments such as Segment 1
C                  in Fig. 1. In the "huge torus" model this becomes
C                  the circumferential stiffness, as follows:
C                  C111MD = CSKIN1(2,2,1) - CSKIN1(1,2,1)**2/CSKIN1(1,1,1)
C
C      C113MD = axial stiffness of shell segments such as Segment 3

```

```

C in Fig. 1. In the "huge torus" model this becomes
C the circumferential stiffness, as follows:
C C113MD = CSKIN1(2,2,3) - CSKIN1(1,2,3)**2/CSKIN1(1,1,3)
C
C C115MD = axial stiffness of shell segments such as Segment 5
C in Fig. 1. In the "huge torus" model this becomes
C the circumferential stiffness, as follows:
C C115MD = CSKIN1(2,2,5) - CSKIN1(1,2,5)**2/CSKIN1(1,1,5)
C
C The "axial" stiffness of each of the 22 shell segments
C in the elaborate local buckling module model consist of
C various combinations of C111MD, C113MD, and C115MD. Once
C the "axial" stiffness of each segment is determined,
C the "axial" resultant in that segment can be computed
C with use of the assumption that each segment of the
C module and each discrete ring carries its share of
C "axial" load in proportion to its "axial" stiffness.
C This model presumes that the cylindrical shell is
C subjected to uniform end shortening, and that the
C prebuckled state of the shell is a membrane state.
C
C DO 125 IMODUL = 1,MODULS
C
C FMODUL = IMODUL - 1
C BETA = FMODUL*PITCH/RADIUS ← β in Fig. 9
C SBETA = SIN(BETA)
C CBETA = COS(BETA)
C RSTART = RBEG ← RBEG in Fig. 9 & 1
C
C IF (IMODEL.EQ.1) THEN
C   ISEGST = 22*(IMODUL - 1)
C   IRGST = 8*(IMODUL - 1)
C ELSE
C   ISEGST = 6*(IMODUL - 1)
C   IRGST = 4*(IMODUL - 1)
C ENDIF
C
C IF (IMODEL.EQ.1) THEN
C
C begin elaborate 22-segment model used for local buckling:
C IMODEL = 1
C
C IF (IMODUL.EQ.1) THEN
C   NSHAPE(1) = 2
C   SROT(1) = 1.
C   NSUR(1) = -1
C   NRING(1) = 0
C   IF (INDX.EQ.1) FOUND(1) = EFOUND
C   IF (INTEXT.EQ.1) PRESUR(1) = PRESS1
C   FN10(1) = PRESS1*RADIUS/2. ← meridional resultant in
C   NNODES(1) = 11
C   NLAYER(1) = NLAYRC + NLAYRF
C   ZVAL(1) = 0.
C   DO 1 I = 1,NLAYRC
C     LINEX = LAYTYP(I,1)
C     ZVAL(1) = ZVAL(1) + THICK(LINDEX)
C   CONTINUE
C   ZRING(1) = 0.
C   IRING(1+ISEGST) = 0
C   NTYPE(1) = 1
C   R1ORIG = RSTART + SWIDTH + CWIDTH
C   R1(1) = R1ORIG
C   Z1(1) = 0.
C   R2(1) = RSTART + SWIDTH + BCROWN - CWIDTH
C   Z2(1) = 0.
C   RC(1) = RSTART
C   ZC(1) = -RADIUS
C new "CURVED MODULE" section:
C   RAD1 = RADIUS + Z1(1)
C   RAD2 = RADIUS + Z2(1)
C   BETA1 = (R1(1)-RSTART)/RAD1
C   BETA2 = (R2(1)-RSTART)/RAD2
C   RCURV1(1) = RSTART + RAD1*SIN(BETA1)
C   RCURV2(1) = RSTART + RAD2*SIN(BETA2)
C   RCURVC(1) = RC(1)
C   ZCURV1(1) = Z1(1) - RAD1*(1. - COS(BETA1))
C   ZCURV2(1) = Z2(1) - RAD2*(1. - COS(BETA2))
C   ZCURVC(1) = ZC(1)
C   RADO = RCURV1(1)

```

Table 13<sup>a</sup>, p. 6 of 13

```

ZED0 = ZCURV1(1)
C end "CURVED MODULE" section
    ENDIF
C     End of "IMODUL.EQ.1" condition
C
    DRAD1 = RCURV1(1) - RAD0
    DZED1 = ZCURV1(1) - ZED0
    DRAD2 = RCURV2(1) - RAD0
    DZED2 = ZCURV2(1) - ZED0
    DRADC = RCURVC(1) - RAD0
    DZEDC = ZCURVC(1) - ZED0
    RP1(1) = RAD0 + RADIUS*SBETA + DRAD1*CBETA + DZED1*SBETA
    ZP1(1) = ZED0 - RADIUS*(1.-CBETA) - DRAD1*SBETA + DZED1*CBETA
    RP2(1) = RAD0 + RADIUS*SBETA + DRAD2*CBETA + DZED2*SBETA
    ZP2(1) = ZED0 - RADIUS*(1.-CBETA) - DRAD2*SBETA + DZED2*CBETA
    RPC(1) = RAD0 + RADIUS*SBETA + DRADC*CBETA + DZEDC*SBETA
    ZPC(1) = ZED0 - RADIUS*(1.-CBETA) - DRADC*SBETA + DZEDC*CBETA
    IF (INDX.EQ.1.AND.IMODUL.EQ.1) THEN
        RL1(1) = RP1(1)
        ZL1(1) = ZP1(1)
        RL2(1) = RP2(1)
        ZL2(1) = ZP2(1)
        RLC(1) = RPC(1)
        ZLC(1) = ZPC(1)
    ENDIF
C
    IF (IMODUL.EQ.1) THEN
        NSHAPE(2) = 2
    (many lines skipped to save space) ← See .., GENOPT/case/trusscomp/b
C         end of elaborate 22-segment model used for local buckling,
C         IMODEL = 1
C
C         ELSE
C
C begin simplified model used for general buckling, IMODEL = 2:
C
    IF (IMODUL.EQ.1) THEN
        NSHAPE(1) = 2
        SROT(1) = 1.
        NSUR(1) = -1
        NRING(1) = 1
        RGAREA(1) = AREA
        IF (INDX.EQ.1) FOUND(1) = EFOUND
        IF (INTEXT.EQ.1) PRESUR(1) = PRESS1
        FN10(1) = PRESS1*RADIUS/2.
        NNODES(1) = 11
        NLAYR2(1) = NLAYRC + NLAYRF
        LAYR21 = NLAYR2(1)
        DO 26 I = 1, LAYR21
            LAYTP2(I,1) = LAYTYP(I,1)
26      CONTINUE
        ZVAL(1) = 0.
        DO 28 I = 1, NLAYRC
            LINDEX = LAYTYP(I,1)
            ZVAL(1) = ZVAL(1) + THICK(LINDEX)
28      CONTINUE
        ZRING(1) = 0.
        NTYPE(1) = 1
        IPTRNG(1) = NNODES(1)
        R1(1) = RSTART + SWIDTH
        Z1(1) = 0.
        R2(1) = RSTART + SWIDTH + BCROWN
        Z2(1) = 0.
        RC(1) = RSTART
        ZC(1) = -RADIUS
C new "CURVED MODULE" section:
        RAD1 = RADIUS + Z1(1)
        RAD2 = RADIUS + Z2(1)
        BETA1 = (R1(1)-RSTART)/RAD1
        BETA2 = (R2(1)-RSTART)/RAD2
        RCURV1(1) = RSTART + RAD1*SIN(BETA1)
        RCURV2(1) = RSTART + RAD2*SIN(BETA2)
        RCURVC(1) = RC(1)
        ZCURV1(1) = Z1(1) - RAD1*(1. - COS(BETA1))
        ZCURV2(1) = Z2(1) - RAD2*(1. - COS(BETA2))
        ZCURVC(1) = ZC(1)

```

See .., GENOPT/case/trusscomp/b  
bosdec. trusscomp

Table 13<sup>a</sup>, p. 7 of 13

```

RAD0 = RCURV1(1)
ZED0 = ZCURV1(1)
C end "CURVED MODULE" section
ENDIF
C End of "IMODUL.EQ.1" condition
C
IRING(1+ISEGST) = 1 + IRGST
DRAD1 = RCURV1(1) - RAD0
DZED1 = ZCURV1(1) - ZED0
DRAD2 = RCURV2(1) - RAD0
DZED2 = ZCURV2(1) - ZED0
DRADC = RCURVC(1) - RAD0
DZEDC = ZCURVC(1) - ZED0
RP1(1) = RAD0 +RADIUS*SBETA +DRAD1*CBETA +DZED1*SBETA
ZP1(1) = ZED0 -RADIUS*(1.-CBETA) -DRAD1*SBETA +DZED1*CBETA
RP2(1) = RAD0 +RADIUS*SBETA +DRAD2*CBETA +DZED2*SBETA
ZP2(1) = ZED0 -RADIUS*(1.-CBETA) -DRAD2*SBETA +DZED2*CBETA
RPC(1) = RAD0 +RADIUS*SBETA +DRADC*CBETA +DZEDC*SBETA
ZPC(1) = ZED0 -RADIUS*(1.-CBETA) -DRADC*SBETA +DZEDC*CBETA
C
IF (IMODUL.EQ.1) THEN
  NSHAPE(2) = 2

(lines skipped to save space)

C
C end of simplified model used for general buckling, IMODEL = 2
C
ENDIF
C End of "IF (MODEL.EQ.1)....ELSE ...ENDIF" condition
C
C2345678901234567890123456789012345678901234567890123456789012
C
C Next, the "axial" resultant carried by each shell segment
C and by each discrete ring is computed from the assumption
C that the cylindrical shell is subjected to uniform end
C shortening, from the assumption that the prebuckled state
C is a membrane state, and from the knowledge of the "axial"
C stiffness of each shell segment and of each discrete ring ("noodle").
C The "axial" resultants in the cylindrical shell become the
C hoop (circumferential) resultants in the "huge torus" model
C of the cylindrical shell. In the BIGBOSOR4 model these hoop
C resultants are called "FN20".
C
IF (IMODUL.EQ.1.AND.(INDX.EQ.1.OR.INDX.EQ.2)) THEN
C Get huge torus hoop resultants carried by each segment
  IF (IMODEL.EQ.1) THEN
    SLANT7 = SQRT((R2(7) - R1(7))**2 + (Z2(7) - Z1(7))**2)
    SLANT4 = SQRT((R2(4) - R1(4))**2 + (Z2(4) - Z1(4))**2)
    DR18 = R2(18) - R1(18)
    DR6 = R2(6) - R1(6)
    DR3 = R2(3) - R1(3)
C234567890123456789012345678901234567890123456789012
    DENOM=(RATIO5*(ARC2 +ARC5) +2.*DR18 +2.*DR6 +4.*DR3*RATIO3
    1      +RATIO5*4.* (SLANT7 +SLANT4) +4.*EANOOD/C111MD)*TOTLNG
    ELSE
      SLANT = SQRT((R2(3) - R1(3))**2 + (Z2(3) - Z1(3))**2)
      DR1 = BCROWN
      DR2 = PITCH - BCROWN
      DENOM=(2.*DR1 +2.*DR2
    1      +RATIO5*4.*SLANT +4.*EANOOD/C111MD)*TOTLNG
    ENDIF
C
  FNX1 = "axial" resultant in Segment 1 of the model shown in Fig. 1
  C
  FNX5 = "axial" resultant in Segment 5 of the model shown in Fig. 1
C
  FNX1 = PX(ILOADX)/DENOM
  FNX5 = RATIO5*FNX1
C
  IF (IMODEL.EQ.1) THEN
C
    This branch is for the elaborate 22-segment module model.
    See Fig. 1 for the arrangement of each of the 22 segments
    in the elaborate module model used for local buckling.
C
    FNX3 = RATIO3*FNX1
    FNOOD1 = ENOODL*AREA1*FNX1/C111MD
    FNOOD2 = ENOODL*AREA2*FNX1/C111MD

```

Table 13<sup>a</sup>, p. 8 of 13

$FN20 = \text{circumferential resultant in the "huge torus" model}$

```

FN20(1) = FNX1
FN20(2) = FNX5
FN20(3) = FNX3
FN20(4) = FNX5
FN20(5) = FNX5
FN20(6) = FNX1
FN20(7) = 2.*FNX5
FN20(8) = FNX3
FN20(9) = FNX5
FN20(10) = FNX5
FN20(11) = FNX5
FN20(12) = 2.*FNX5
FN20(13) = FNX5
FN20(14) = FNX5
FN20(15) = FNX1
FN20(16) = FNX5
FN20(17) = FNX3
FN20(18) = FNX1
FN20(19) = FNX5
FN20(20) = FNX5
FN20(21) = FNX5
FN20(22) = FNX3

```

```

C The strain components, EPSX, EPSY1, EPSY3, EPSY5 are used to
C compute the stresses in each layer of each shell segment. The
C following definitions apply:
C
C FNX1 = "axial" resultant in shell segment 1 in Fig. 1 ← circumferential
C C111MD = "axial" stiffness of shell segment 1 in Fig. 1 in the "huge torus" model
C FN10 = "circumferential" resultant in each face sheet.
C EPSX = "axial" strain (assumed to be the same for all shell
C segments)
C EPSY1 = "circumferential" strain in "segment 1 type"
C shell segments
C EPSY3 = "circumferential" strain in "segment 3 type"
C shell segments
C EPSY5 = "circumferential" strain in "segment 5 type"
C shell segments
C
C Remember, in the "huge torus" model of the cylindrical
C shell "axial" is actually the circumferential component,
C and "circumferential" is actually the meridional component.
C

```

```

EPSX = FNX1/C111MD
EPSY1 = FN10(1) -EPSX*CSKIN1(1,2,1)/CSKIN1(2,2,1)
EPSY3 = FN10(3) -EPSX*CSKIN1(1,2,3)/CSKIN1(2,2,3)
EPSY5 = -EPSX*CSKIN1(1,2,5)/CSKIN1(2,2,5)

```

```

C ELSE
C
C This branch is for the simplified 6-segment module model.
C See Fig. 6, top, for the arrangement of each of the 6 segments
C in the module model for general buckling.
C

```

```

FN20(1) = FNX1
FN20(2) = FNX1
FN20(3) = 2.*FNX5
FN20(4) = 2.*FNX5
FN20(5) = FNX1
FN20(6) = FNX1
FNOODL = EANOOD*FNX1/C111MD
ENDIF
ENDIF

```

```
C2345678901234567890123456789012345678901234567890123456789012
```

```
C Next, we generate a valid input data file, *.ALL, for BIGBOSOR4
```

```
C Global input before segment data...
```

```

IF (IMODUL.EQ.1) THEN
  MSEGS = MODULS*NSEGSM
  IF (INDX.EQ.0.OR.INDX.EQ.1) WRITE(IFIL14,'(A)')
  1   ' local buckling from single module model (INDIC=4)'
  1   ' IF (INDX.EQ.2) WRITE(IFIL14,'(A)')
  1   ' general buckling from multiple module model (INDIC=4)'
  1   ' WRITE(IFIL14,'(A,I3,A)')
  1   ' 4, 1, 0, 0, ',MSEGS,' $ INDIC,NPRT,ISTRESS,IPRE,NSEG'
ENDIF

```

Table 13<sup>a</sup>, p. 9 of 13

```

C
C Segment data...
    MAXTYP = 0
    MAXMAT = 0
C
C First, provide the input for each of the NSEGSM shell segments
C in the next module...
C
    DO 100 ISEG = 1,NSEGSM
    I = ISEG
    WRITE(IFIL14,'(A,4I6)'' H $ Segment number ',I,I,I,I
    WRITE(IFIL14,'(I4,A,I3,A)') NNODES(ISEG),', 3, ',NSHAPE(ISEG),
    '$ NMESH,NTYPEH,NSHAPE'
    1 ' $ NMESH,NTYPEH,NSHAPE'
    WRITE(IFIL14,'(1P,4E14.6,A)') RP1(I),ZP1(I),RP2(I),ZP2(I),
    1 ' $ R1,Z1,R2,Z2,
    IF (NSHAPE(ISEG).EQ.2) THEN
        WRITE(IFIL14,'(1P,3E14.6,A)') RPC(ISEG),ZPC(ISEG),SROT(ISEG),
    1 ' $ RC,ZC,SROT'
    ENDIF
C2345678901234567890123456789012345678901234567890123456789012
    WRITE(IFIL14,'(A,1P,E14.6,A)') 0, 3, ',ZVAL(ISEG),
    1 ' $ IMP,NTYPEZ,ZVAL'
    WRITE(IFIL14,'(A)')' N $ do not print r(s), etc.'
    IF (IMODEL.EQ.1) THEN
        NRLOAD = 8*MODULS
    ELSE
        NRLOAD = 4*MODULS
    ENDIF
    IF (NRING(ISEG).EQ.0) THEN
        WRITE(IFIL14,'(I5,1PE14.6,A,2I4,A)') NRING(ISEG),FOUND(ISEG),
    1 ' , 2, ',NRLOAD,NTYPE(ISEG),'$ NRINGS,K,NSTRES,NRLOAD,NTYPE'
    ELSE
        WRITE(IFIL14,'(3I5,A)') NRING(ISEG),NTYPE(ISEG),
    1   IPRTRNG(ISEG),', 2 $ NRINGS,NTYPE,IPOINT,NTYPER'
        RAREA = RGAREA(ISEG)
C
C You may want to modify the values for discrete ring bending
C moments of inertia, FMOMTS, FMOMTN, FMOMSN, and the torsional
C stiffness, GJ. I just assumed these formulas without much thought.
C
        FMOMTS = RAREA**2/8.
        FMOMTN = RAREA**2/8.
        FMOMSN = 0.
        ZMERID = 0.
        GJ = FMOMTS*ENOIDL/2.6
        RGWGT = RAREA*DNOODL
        WRITE(IFIL14,'(1P,3E14.6,A)') ENOIDL,RAREA,FMOMTS,
    1 ' $ ERING,AREA,Is'
        WRITE(IFIL14,'(1P,3E14.6,A)') FMOMTN,FMOMSN,ZNORM(ISEG),
    1 ' $ In,Isn,ZNORM'
        WRITE(IFIL14,'(1P,3E14.6,A)') ZMERID,GJ,RGWGT,
    1 ' $ ZMERID,GJ,RWGT'
        WRITE(IFIL14,'(1P,E14.6,A,2I4,A)') FOUND(ISEG),
    1   ', 2, ',NRLOAD,NTYPE(ISEG),'$ K,NSTRES,NRLOAD,NTYPE'
    ENDIF
C
    IF (NTYPE(ISEG).EQ.1)
    1 WRITE(IFIL14,'(A,I4,A)') 1, ',NNODES(ISEG),
    1 ' $ IPOINT(1),IPOINT(2)'
    IF (NTYPE(ISEG).EQ.2)
    1 WRITE(IFIL14,'(1P,2E14.6,A)') ZP1(ISEG),ZP2(ISEG),
    1 ' $ Z1(ISEG),Z2(ISEG)'
    IF (NTYPE(ISEG).EQ.3)
    1 WRITE(IFIL14,'(1P,2E14.6,A)') RP1(ISEG),RP2(ISEG),
    1 ' $ R1(ISEG),R2(ISEG)'
    WRITE(IFIL14,'(1P,4E14.6,A)') FN10(I),FN10(I),FN20(I),FN20(I),
    1 ' $ FN10,FN10,FN20,FN20'
C
C2345678901234567890123456789012345678901234567890123456789012
    IF (ISEG.EQ.1.AND.IMODUL.EQ.1) THEN
C
C Note that in the BIGBOSOR4 INDIC = 4 branch the prebuckling forces
C in ALL the rings in the multi-segment model are read in with the
C data for the first shell segment.
C
        WRITE(IFIL14,'((4I5))') (I,I=1,NRLOAD)
C
        IF (IMODEL.EQ.1) THEN

```

C Elaborate 22-segment local buckling module model:  
C FNOOD1 and FNOOD2 are the prebuckling forces in the discrete rings  
C ("noodles") with cross section areas, AREA1 and AREA2, respectively.  
C (Fig. 7)

Table 13<sup>a</sup>, p. 10 of 13

```

C DO 90 KMODUL = 1,MODULS
      WRITE(IFIL14,'(1P4E14.6,A)') FNOOD2,FNOOD1,FNOOD1,FNOOD2,
1       '$ FNOOD2,FNOOD1,FNOOD1,FNOOD2'
      WRITE(IFIL14,'(1P4E14.6,A)') FNOOD1,FNOOD2,FNOOD2,FNOOD1,
1       '$ FNOOD1,FNOOD2,FNOOD2,FNOOD1'
90     CONTINUE
ELSE
C Simplified 6-segment general buckling module model:
C FNOODL is the prebuckling force in the discrete ring ("noodle")
C with cross section area, AREA1 + AREA2. (Fig. 6)
C
DO 92 KMODUL = 1,MODULS
      WRITE(IFIL14,'(1P4E14.6,A)') FNOODL,FNOODL,FNOODL,FNOODL,
1       '$ FNOODL,FNOODL,FNOODL,FNOODL'
92     CONTINUE
ENDIF
ENDIF
C End of (ISEG.EQ.1.AND.IMODUL.EQ.1) condition
C2345678901234567890123456789012345678901234567890123456789012
      WRITE(IFIL14,'(A)')' N $ do not print prestresses'
C
IF (IMODEL.EQ.1) THEN
      NLAY = NLAYER(ISEG)
ELSE
      NLAY = NLAYR2(ISEG)
ENDIF
WRITE(IFIL14,'(A3,A)')' 4, ',NLAY,' $ NWALL,NLAYER'
MAXMT1 = MAXMAT
MAXTP1 = MAXTYP
DO 95 ILAYER = 1,NLAY
IF (IMODEL.EQ.1) THEN
      LTYPE = LAYTYP(ILAYER,ISEG)
ELSE
      LTYPE = LAYTP2(ILAYER,ISEG)
ENDIF
WRITE(IFIL14,'(I3,A)') LTYPE,' $ layer index'
IF (LTYPE.GT.MAXTYP) THEN
      WRITE(IFIL14,'(A)')' Y $ is this a new layer type?'
      IF (ANGLE(LTYPE).GT.90.0.OR.ANGLE(LTYPE).LT.-90.0) THEN
          WRITE(IFILE4,'(/,A,,A,,A,,A,)')
1       ' ***** RUN ABORT *****',
1       ' Layup angle out of range. Layup angle must be in the',
1       ' range, -90.0 .LE. (layup angle) .LE. +90.0 degrees.',
1       ' *****',
          CALL ERREX
ENDIF
IF (ANGLE(LTYPE).GT.0.0) ANGLE2 = -(90.0 - ANGLE(LTYPE))
IF (ANGLE(LTYPE).LT.0.0) ANGLE2 = 90.0 + ANGLE(LTYPE)
IF (ANGLE(LTYPE).EQ.0.0) ANGLE2 = 90.0
IF (ANGLE(LTYPE).EQ.90.0) ANGLE2 = 0.0
WRITE(IFIL14,'(1P2E14.6,I3,A)') THICK(LTYPE),
1       ANGLE2,MATTYP(LTYPE),' $ thickness,angle,material'
MAXTYP = MAX(MAXTYP,LTYPE)
MAXMAT = MAX(MAXMAT,MATTYP(LTYPE)))
ELSE
      WRITE(IFIL14,'(A)')' N $ is this a new layer type?'
ENDIF
95    CONTINUE
C
IF (MAXTP1.LT.MAXTYP.AND.MAXMAT.LE.MAXMT1) THEN
      WRITE(IFIL14,'(A)')' N $ Is this material new?'
ENDIF
IF (MAXMAT.GT.MAXMT1) THEN
      MAXMTP = MAXMT1 + 1
DO 97 IMATL = MAXMTP,MAXMAT
      WRITE(IFIL14,'(A)')' Y $ Is this material new?'
      WRITE(IFIL14,'(1P4E14.6,A)') EMOD1(IMATL),EMOD2(IMATL),
1       G12(IMATL),NU(IMATL),' $ E1,E2,G12,NU'
      WRITE(IFIL14,'(1P4E14.6,A)') ALPHA1(IMATL),ALPHA2(IMATL),
1       TEMCUR(IMATL),DENSTY(IMATL),' $ A1,A2,TEMPTUR,DENS'
      IF (IMATL.EQ.1) THEN

```

```

1      WRITE(IFIL14,'(1P3E14.6,A)') STRM1A(ILOADX,1),
1      STRM1A(ILOADX,2),STRM1A(ILOADX,3),' $ S(1),S(2),S(3)'
1      WRITE(IFIL14,'(1P2E14.6,A)') STRM1A(ILOADX,4),
1      STRM1A(ILOADX,5),' $ S(4),S(5)'
1      GO TO 96
1      ENDIF
1      IF (IMATL.EQ.2) THEN
1          WRITE(IFIL14,'(1P3E14.6,A)') STRM2A(ILOADX,1),
1          STRM2A(ILOADX,2),STRM2A(ILOADX,3),' $ S(1),S(2),S(3)'
1          WRITE(IFIL14,'(1P2E14.6,A)') STRM2A(ILOADX,4),
1          STRM2A(ILOADX,5),' $ S(4),S(5)'
1          GO TO 96
1          ENDIF
1          WRITE(IFILE4,'(/,A,/A,/A,/A)')
1          ,***** RUN ABORT *****
1          ' Material type out of range. Only 2 material types are',
1          ' permitted in this model.',
1          ,*****
1          CALL ERREX
96      CONTINUE
97      CONTINUE
C2345678901234567890123456789012345678901234567890123456789012
ENDIF
WRITE(IFIL14,'(A)')' 0 $ no additional smeared stiffeners'
WRITE(IFIL14,'(A)')' Y $ do you want output for all nodes?'
WRITE(IFIL14,'(A)')' N $ do you want to print out Cij?'
WRITE(IFIL14,'(A)')' N $ do you want to print out loads?'
C
100    CONTINUE
C
125    CONTINUE
C
WRITE(IFIL14,'(A)')' H $ GLOBAL DATA BEGINS...
WRITE(IFIL14,'(A)')' 0 $ NLAST'
WRITE(IFIL14,'(A)')' N $ any expanded plots?'
NMINB = NOB
INCRB = 100
NVEC = 1
WRITE(IFIL14,'(5I6,A)') NOB,NMINB,NMAXB,INCRB,NVEC,
1      '$ NOB,NMINB,NMAXB,INCRB,NVEC'
WRITE(IFIL14,'(A)')' H $ CONSTRAINT CONDITIONS FOLLOW....'
WRITE(IFIL14,'(I6,A)') MSEGS,' $ how many segments?'
C
C Next, generate the BIGBOSOR4 input for all the constraint
C conditions (connections to ground and segment junctions)
C in the multi-module model.
C
DO 400 IMODUL = 1,MODULS
C
IF (IMODEL.EQ.1) THEN
C
C Do the input for the elaborate 22-segment local buckling
C model in this branch.
C
C Begin IMODEL = 1 logic for connections to ground, junctions
C
NGRND(1) = 0
IF (IMODUL.EQ.1) THEN
    NGRND(1) = 1
    NODGRD(1,1) = 1
    IF (INDX.EQ.1) IDISP(1,1) = 1
    IF (INDX.EQ.2) IDISP(1,1) = 0
    IDISP(1,2) = 0
ELSE
    NPREV(1) = 1
    NODPRV(1,1) = 1
    JPREV(1,1) = 8 + NSEGSM*(IMODUL - 2)
    JNODPV(1,1) = NNODES(8)
ENDIF
C
NPREV(2) = 1
NODPRV(2,1) = 1
JPREV(2,1) = 1 + NSEGSM*(IMODUL - 1)
JNODPV(2,1) = NNODES(1)
C
C (lines skipped to save space)
C
C End IMODEL = 1 logic for connections to ground, junctions

```

Table 13<sup>a</sup>, p. 12 of 13

```

C
C
C Do the input for the simpler 6-segment local buckling
C model in this branch.
C
C Begin IMODEL = 2 logic for connections to ground, junctions
C
    NGRND(1) = 0
    IF (IMODUL.EQ.1) THEN
        NGRND(1) = 1
        NODGRD(1,1) = 1
        IDISP(1,1) = 0
        IDISP(1,2) = 0
        IDISP(1,3) = 0
        IDISP(1,4) = 0
    ELSE
        NPREV(1) = 1
        NODPRV(1,1) = 1
        JPREV(1,1) = 2 + NSEGSM*(IMODUL - 2)
        JNODPV(1,1) = NNODES(2)
    ENDIF
C
    (lines skipped to save space)

    JPREV(6,1) = 3 + NSEGSM*(IMODUL - 1)
    JNODPV(6,1) = NNODES(3)
    NODPRV(6,2) = NNODES(6)
    JPREV(6,2) = 4 + NSEGSM*(IMODUL - 1)
    JNODPV(6,2) = NNODES(4)
C
    NPREV(4) = 1
    NODPRV(4,1) = 1
    JPREV(4,1) = 2 + NSEGSM*(IMODUL - 1)
    JNODPV(4,1) = NNODES(2)
C
C End IMODEL = 2 logic for connections to ground, junctions
C
    ENDIF
C
C End of IMODEL = 1 and IMODEL = 2 logic for ground, junctions
C
    DO 300 I = 1,NSEGSM
C
        WRITE(IFIL14,'(A,4I6)')
        1  H $ CONSTRAINT CONDITIONS FOR SEGMENT ',I,I,I,I
        WRITE(IFIL14,'(A)')' 0 $ number of poles'
        WRITE(IFIL14,'(I3,A)') NGRND(I), '$ connect to ground'
        IF (NGRND(I).GT.0) THEN
            NGRNDI = NGRND(I)
            DO 150 J = 1,NGRNDI
                WRITE(IFIL14,'(I3,A)') NODGRD(I,J), '$ node to ground'
                WRITE(IFIL14,'(4I3,A)')
                1   IDISP(I,1),IDISP(I,2),IDISP(I,3),IDISP(I,4),
                1   '$ IUSTAR,IVSTAR,IWSTAR,ICHI'
                WRITE(IFIL14,'(A)')' 0., 0. $ D1,D2'
                WRITE(IFIL14,'(A)')' Y $ is constraint same for buck.?
        150   CONTINUE
        ENDIF
C2345678901234567890123456789012345678901234567890123456789012
C
        IF (I.LE.1.AND.IMODUL.EQ.1) THEN
            WRITE(IFIL14,'(A)')' N $ joined to previous segments?'
        ELSE
            WRITE(IFIL14,'(A)')' Y $ joined to previous segments?'
            WRITE(IFIL14,'(I3,A)') NPREV(I), '$ connects to prev.segs'
            NPREVI = NPREV(I)
            DO 200 J = 1,NPREVI
                WRITE(IFIL14,'(I3,A)') NODPRV(I,J), '$ node current seg'
                WRITE(IFIL14,'(I3,A)') JPREV(I,J), '$ prev.segment no.'
                WRITE(IFIL14,'(I3,A)') JNODPV(I,J), '$ node in prev.seg.'
                WRITE(IFIL14,'(A)')' 1, 1, 1, 1 $ IU,IV,IW,ICHI'
                WRITE(IFIL14,'(A)')' 0., 0. $ D1,D2'
                WRITE(IFIL14,'(A)')' Y $ is constraint same for buck.?
C2345678901234567890123456789012345678901234567890123456789012
        200   CONTINUE
        ENDIF
C

```

```
C      300    CONTINUE
C      400    CONTINUE
C      WRITE(IFIL14,'(A)')' N $ are rigid body motions possible?'
C      DO 450 ISEG = 1,MSEGS
        WRITE(IFIL14,'(A)')' Y $ do you want to list seg. output?'
450    CONTINUE
      WRITE(IFIL14,'(A)')' Y $ do you want to list ring forces?'
C      ENDIF
C End of "INDX.EQ.0.OR.INDX.EQ.1.OR.INDX.EQ.2" condition
C      RETURN
END
```

Table 13<sup>a</sup>, p. 13 of 13

End of bosdec, trusscomp

"bosdec" = "bosor deck"

# Table 13b from bosdec.trusscomp (3 pages)

From bosdec.trusscomp: Connections to ground and some junctions

```

C   Next, generate the BIGBOSOR4 input for all the constraint
C   conditions (connections to ground and segment junctions)
C   in the multi-module model.
C
C   The connections to ground (NGRND(i) > 0), where
C   i = the shell segment number, are governed by the
C   array, IDISP(i,j), where j is an index for which displacement
C   component is constrained or not constrained.
C
C   IDISP(i,j) = 1 means that the jth displacement component is
C   constrained to be zero.
C   IDISP(i,j) = 0 means that the jth displacement component is
C   free
C
C   In BIGBOSOR4 [10] there are 4 displacement components:
C
C   IDISP(i,1) refers to USTAR, the radial (horizontal) displacement
C   IDISP(i,2) refers to VSTAR, the circumferential displacement
C   IDISP(i,3) refers to WSTAR, the axial (vertical) displacement
C   IDISP(i,4) refers to CHI, the meridional rotation
C
C   The entire array, IDISP(i,j), i = 1,NSEGS, j = 1,4,
C   is initially set equal to unity when SUBROUTINE BOSDEC is
C   called from SUBROUTINE BEHX1 (local buckling: IMODEL = 1) and
C   called from SUBROUTINE BEHX2 (general buckling: IMODEL = 2). In
C   the following code IDISP(i,j) is reset to zero in certain of
C   the shell segments:
C
C   For LOCAL buckling (IMODEL = 1) in Segments 1, 8, 15, and 21
C   For GENERAL buckling (IMODEL = 2) in Segments 1 and 2 and 5
C
C   The following code from bosdec.trusscomp is abridged so that
C   only the shell segments with constraints to ground are included.
C
        DO 400 IMODUL = 1,MODULS
C
        IF (IMODEL.EQ.1) THEN
C
C Do the input for the elaborate 22-segment local buckling
C model in this branch.
C
C Begin IMODEL = 1 logic for connections to ground, junctions
C
        NGRND(1) = 0
        IF (IMODUL.EQ.1) THEN
            NGRND(1) = 1
            NODGRD(1,1) = 1
            IDISP(1,2) = 0
        ELSE
            NPREV(1) = 1
            NODPRV(1,1) = 1
            JPREV(1,1) = 8 + NSEGSM*(IMODUL - 2)
            JNODPV(1,1) = NNODES(8)
        ENDIF
C
        (lines skipped to save space)
C
        NGRND(8) = 0
        IF (IMODUL.EQ.MODULS) THEN
            NGRND(8) = 1
            NODGRD(8,1) = NNODES(8)
            IDISP(8,3) = 0
            IDISP(8,4) = 0
        ENDIF
        NPREV(8) = 1
        NODPRV(8,1) = 1
        JPREV(8,1) = 6 + NSEGSM*(IMODUL - 1)
        JNODPV(8,1) = NNODES(6)
C
        (lines skipped to save space)
C
        NGRND(15) = 0
        IF (IMODUL.EQ.1) THEN
            NGRND(15) = 1
            NODGRD(15,1) = NNODES(15)
            IDISP(15,2) = 0

```

# Table 13b (p. 2 of 3)

```

NPREV(15) = 1
ELSE
    NPREV(15) = 2
    NODPRV(15,2) = NNODES(15)
    JPRev(15,2) = 21 +NSEGSM*(IMODUL - 2)
    JNODPV(15,2) = NNODES(21)
ENDIF
NODPRV(15,1) = 1
JPRev(15,1) = 14 +NSEGSM*(IMODUL - 1)
JNODPV(15,1) = NNODES(14)

C (lines skipped to save space)
C
    NGRND(21) = 0
    IF (IMODUL.EQ.MODULS) THEN
        NGRND(21) = 1
        NODGRD(21,1) = NNODES(21)
        IDISP(21,3) = 0
        IDISP(21,4) = 0
    ENDIF
    NPRev(21) = 1
    NODPRV(21,1) = 1
    JPRev(21,1) = 12 +NSEGSM*(IMODUL - 1)
    JNODPV(21,1) = NNODES(12)

C (lines skipped to save space)
C
C End IMODEL = 1 logic for connections to ground, junctions
C
    ELSE
C Do the input for the simpler 6-segment local buckling
C model in this branch.
C
C Begin IMODEL = 2 logic for connections to ground, junctions
C
    NGRND(1) = 0
    IF (IMODUL.EQ.1) THEN
        NGRND(1) = 1
        NODGRD(1,1) = 1
        IDISP(1,3) = 0
        IDISP(1,4) = 0
    ELSE
        NPRev(1) = 1
        NODPRV(1,1) = 1
        JPRev(1,1) = 2 +NSEGSM*(IMODUL - 2)
        JNODPV(1,1) = NNODES(2)
    ENDIF

    NGRND(2) = 0
    IF (IMODUL.EQ.MODULS) THEN
        NGRND(2) = 1
        NODGRD(2,1) = NNODES(2)
        IDISP(2,1) = 0
        IDISP(2,4) = 0
    ENDIF
    NPRev(2) = 1
    NODPRV(2,1) = 1
    JPRev(2,1) = 1 +NSEGSM*(IMODUL - 1)
    JNODPV(2,1) = NNODES(1)

    NGRND(5) = 0
    IF (IMODUL.EQ.1) THEN
        NGRND(5) = 1
        NODGRD(5,1) = NNODES(5)
        IDISP(5,3) = 0
        IDISP(5,4) = 0
        NPRev(5) = 1
    ELSE
        NPRev(5) = 2
        NODPRV(5,2) = NNODES(5)
        JPRev(5,2) = 4 +NSEGSM*(IMODUL - 2)
        JNODPV(5,2) = NNODES(4)
    ENDIF
    NODPRV(5,1) = 1
    JPRev(5,1) = 3 +NSEGSM*(IMODUL - 1)
    JNODPV(5,1) = NNODES(3)

```

C

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(lines skipped to save space)  
C End IMODEL = 2 logic for connections to ground, junctions  
C       ENDIF  
C  
C End of IMODEL = 1 and IMODEL = 2 logic for ground, junctions

Table 13b (p. 3 of 3)

# Table 14 Input for "BEGIN" test. BEG (4 pages)

n 96 \$ Do you want a tutorial session and tutorial output?  
 0.1000000 \$ length of the cylindrical shell: LENGTH  
 48.00000 \$ fraction of LENGTH for local buckling: FACLEN  
 5.192400 \$ radius of the cylindrical shell: RADIUS  
 2.339900 \$ circumferential width of a single module: PITCH  
 1.417200 \$ circumferential width of the trapezoid crown: BCROWN  
 0.1000000 \$ height of the truss-core sandwich: HEIGHT  
 0.1000000 \$ local radius from base to side of trapezoidal tool: RACUTE  
 0.1000000 \$ local radius from side to crown of trapezoidal tool: ROBTUS  
 0.1851110E+08 \$ axial modulus of a corner "noodle": ENOODL  
 0.5700000E-01 \$ weight density of the "noodle" material: DNOODL  
 0 \$ elastic foam "Winkler" foundation stiffness: EFOUND  
 0 \$ elastic "noodle" Winkler foundation modulus: EFNOOD  
 1 \$ Number IEMOD1 of rows in the array EMOD1: IEMOD1  
 0.1851110E+08 \$ elastic modulus in the fiber direction: EMOD1( 1)  
 1640000. \$ elastic modulus transverse to fibers: EMOD2( 1)  
 870600.0 \$ in-plane shear modulus: G12( 1)  
 870600.0 \$ out-of-plane x-z shear modulus: G13( 1)  
 870600.0 \$ out-of-plain y-z shear modulus: G23( 1)  
 0.2660000E-01 \$ minor (small) Poisson ratio: NU( 1)  
 0.2500000E-06 \$ coef. of thermal expansion along the fibers: ALPHA1( 1)  
 0.1620000E-04 \$ coef. of thermal expansion transverse to fibers: ALPHA2( 1)  
 240 \$ curing temperature difference: TEMCUR( 1) see p.16  
 0.5700000E-01 \$ weight density of material: DENSTY( 1)  
 7 \$ Number ITHICK of rows in the array THICK: ITHICK  
 0.0052 \$ layer type thickness: THICK( 1)  
 0.0052 \$ layer type thickness: THICK( 2)  
 0.0052 \$ layer type thickness: THICK( 3)  
 0.0052 \$ layer type thickness: THICK( 4)  
 0.0052 \$ layer type thickness: THICK( 5)  
 0.0156 \$ layer type thickness: THICK( 6)  
 0.0156 \$ layer type thickness: THICK( 7)  
 45 \$ layer type layup angle: ANGLE( 1)  
 -45 \$ layer type layup angle: ANGLE( 2)  
 90 \$ layer type layup angle: ANGLE( 3)  
 45 \$ layer type layup angle: ANGLE( 4)  
 -45 \$ layer type layup angle: ANGLE( 5)  
 0 \$ layer type layup angle: ANGLE( 6)  
 90 \$ layer type layup angle: ANGLE( 7)  
 1 \$ layer type material type: MATTYP( 1)  
 1 \$ layer type material type: MATTYP( 2)  
 1 \$ layer type material type: MATTYP( 3)  
 1 \$ layer type material type: MATTYP( 4)  
 1 \$ layer type material type: MATTYP( 5)  
 1 \$ layer type material type: MATTYP( 6)  
 1 \$ layer type material type: MATTYP( 7)  
 22 \$ Number JLAYTYP of columns in the array, LAYTYP: JLAYTYP  
 12 \$ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP  
 1 \$ layer type: LAYTYP( 1, 1)  
 2 \$ layer type: LAYTYP( 2, 1)  
 3 \$ layer type: LAYTYP( 3, 1)  
 2 \$ layer type: LAYTYP( 4, 1)  
 1 \$ layer type: LAYTYP( 5, 1)  
 4 \$ layer type: LAYTYP( 6, 1)  
 5 \$ layer type: LAYTYP( 7, 1)  
 6 \$ layer type: LAYTYP( 8, 1)  
 7 \$ layer type: LAYTYP( 9, 1)  
 6 \$ layer type: LAYTYP( 10, 1)  
 5 \$ layer type: LAYTYP( 11, 1)  
 4 \$ layer type: LAYTYP( 12, 1)  
 5 \$ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP  
 1 \$ layer type: LAYTYP( 1, 2)  
 2 \$ layer type: LAYTYP( 2, 2)  
 3 \$ layer type: LAYTYP( 3, 2)  
 2 \$ layer type: LAYTYP( 4, 2)  
 1 \$ layer type: LAYTYP( 5, 2)  
 7 \$ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP  
 4 \$ layer type: LAYTYP( 1, 3)  
 5 \$ layer type: LAYTYP( 2, 3)  
 6 \$ layer type: LAYTYP( 3, 3)  
 7 \$ layer type: LAYTYP( 4, 3)  
 6 \$ layer type: LAYTYP( 5, 3)  
 5 \$ layer type: LAYTYP( 6, 3)  
 4 \$ layer type: LAYTYP( 7, 3)  
 5 \$ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP  
 1 \$ layer type: LAYTYP( 1, 4)  
 2 \$ layer type: LAYTYP( 2, 4)  
 3 \$ layer type: LAYTYP( 3, 4)

# Table 14 test.BEG(p. 2 of 4)

```

2   $ layer type: LAYTYP( 4, 4)
1   $ layer type: LAYTYP( 5, 4)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
2   $ layer type: LAYTYP( 1, 5)
1   $ layer type: LAYTYP( 2, 5)
3   $ layer type: LAYTYP( 3, 5)
1   $ layer type: LAYTYP( 4, 5)
2   $ layer type: LAYTYP( 5, 5)
12  $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
1   $ layer type: LAYTYP( 1, 6)
2   $ layer type: LAYTYP( 2, 6)
3   $ layer type: LAYTYP( 3, 6)
2   $ layer type: LAYTYP( 4, 6)
1   $ layer type: LAYTYP( 5, 6)
4   $ layer type: LAYTYP( 6, 6)
5   $ layer type: LAYTYP( 7, 6)
6   $ layer type: LAYTYP( 8, 6)
7   $ layer type: LAYTYP( 9, 6)
6   $ layer type: LAYTYP(10, 6)
5   $ layer type: LAYTYP(11, 6)
4   $ layer type: LAYTYP(12, 6)
10  $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
1   $ layer type: LAYTYP( 1, 7)
2   $ layer type: LAYTYP( 2, 7)
3   $ layer type: LAYTYP( 3, 7)
2   $ layer type: LAYTYP( 4, 7)
1   $ layer type: LAYTYP( 5, 7)
2   $ layer type: LAYTYP( 6, 7)
1   $ layer type: LAYTYP( 7, 7)
3   $ layer type: LAYTYP( 8, 7)
1   $ layer type: LAYTYP( 9, 7)
2   $ layer type: LAYTYP(10, 7)
7   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
4   $ layer type: LAYTYP( 1, 8)
5   $ layer type: LAYTYP( 2, 8)
6   $ layer type: LAYTYP( 3, 8)
7   $ layer type: LAYTYP( 4, 8)
6   $ layer type: LAYTYP( 5, 8)
5   $ layer type: LAYTYP( 6, 8)
4   $ layer type: LAYTYP( 7, 8)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
1   $ layer type: LAYTYP( 1, 9)
2   $ layer type: LAYTYP( 2, 9)
3   $ layer type: LAYTYP( 3, 9)
2   $ layer type: LAYTYP( 4, 9)
1   $ layer type: LAYTYP( 5, 9)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
2   $ layer type: LAYTYP( 1,10)
1   $ layer type: LAYTYP( 2,10)
3   $ layer type: LAYTYP( 3,10)
1   $ layer type: LAYTYP( 4,10)
2   $ layer type: LAYTYP( 5,10)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
2   $ layer type: LAYTYP( 1,11)
1   $ layer type: LAYTYP( 2,11)
3   $ layer type: LAYTYP( 3,11)
1   $ layer type: LAYTYP( 4,11)
2   $ layer type: LAYTYP( 5,11)
10  $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
1   $ layer type: LAYTYP( 1,12)
2   $ layer type: LAYTYP( 2,12)
3   $ layer type: LAYTYP( 3,12)
2   $ layer type: LAYTYP( 4,12)
1   $ layer type: LAYTYP( 5,12)
2   $ layer type: LAYTYP( 6,12)
1   $ layer type: LAYTYP( 7,12)
3   $ layer type: LAYTYP( 8,12)
1   $ layer type: LAYTYP( 9,12)
2   $ layer type: LAYTYP(10,12)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
2   $ layer type: LAYTYP( 1,13)
1   $ layer type: LAYTYP( 2,13)
3   $ layer type: LAYTYP( 3,13)
1   $ layer type: LAYTYP( 4,13)
2   $ layer type: LAYTYP( 5,13)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
1   $ layer type: LAYTYP( 1,14)
2   $ layer type: LAYTYP( 2,14)

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Table 14

test.BEG (p. 3 of 4)

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3   $ layer type: LAYTYP( 3,14)
2   $ layer type: LAYTYP( 4,14)
1   $ layer type: LAYTYP( 5,14)
12  $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
1   $ layer type: LAYTYP( 1,15)
2   $ layer type: LAYTYP( 2,15)
3   $ layer type: LAYTYP( 3,15)
2   $ layer type: LAYTYP( 4,15)
1   $ layer type: LAYTYP( 5,15)
5   $ layer type: LAYTYP( 6,15)
4   $ layer type: LAYTYP( 7,15)
6   $ layer type: LAYTYP( 8,15)
7   $ layer type: LAYTYP( 9,15)
6   $ layer type: LAYTYP(10,15)
4   $ layer type: LAYTYP(11,15)
5   $ layer type: LAYTYP(12,15)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
2   $ layer type: LAYTYP( 1,16)
1   $ layer type: LAYTYP( 2,16)
3   $ layer type: LAYTYP( 3,16)
1   $ layer type: LAYTYP( 4,16)
2   $ layer type: LAYTYP( 5,16)
7   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
4   $ layer type: LAYTYP( 1,17)
5   $ layer type: LAYTYP( 2,17)
6   $ layer type: LAYTYP( 3,17)
7   $ layer type: LAYTYP( 4,17)
6   $ layer type: LAYTYP( 5,17)
5   $ layer type: LAYTYP( 6,17)
4   $ layer type: LAYTYP( 7,17)
12  $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
4   $ layer type: LAYTYP( 1,18)
5   $ layer type: LAYTYP( 2,18)
6   $ layer type: LAYTYP( 3,18)
7   $ layer type: LAYTYP( 4,18)
6   $ layer type: LAYTYP( 5,18)
5   $ layer type: LAYTYP( 6,18)
4   $ layer type: LAYTYP( 7,18)
2   $ layer type: LAYTYP( 8,18)
1   $ layer type: LAYTYP( 9,18)
3   $ layer type: LAYTYP(10,18)
1   $ layer type: LAYTYP(11,18)
2   $ layer type: LAYTYP(12,18)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
1   $ layer type: LAYTYP( 1,19)
2   $ layer type: LAYTYP( 2,19)
3   $ layer type: LAYTYP( 3,19)
2   $ layer type: LAYTYP( 4,19)
1   $ layer type: LAYTYP( 5,19)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
1   $ layer type: LAYTYP( 1,20)
2   $ layer type: LAYTYP( 2,20)
3   $ layer type: LAYTYP( 3,20)
2   $ layer type: LAYTYP( 4,20)
1   $ layer type: LAYTYP( 5,20)
5   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
2   $ layer type: LAYTYP( 1,21)
1   $ layer type: LAYTYP( 2,21)
3   $ layer type: LAYTYP( 3,21)
1   $ layer type: LAYTYP( 4,21)
2   $ layer type: LAYTYP( 5,21)
7   $ Number ILAYTYP of rows in this column of LAYTYP: ILAYTYP
4   $ layer type: LAYTYP( 1,22)
5   $ layer type: LAYTYP( 2,22)
6   $ layer type: LAYTYP( 3,22)
7   $ layer type: LAYTYP( 4,22)
6   $ layer type: LAYTYP( 5,22)
5   $ layer type: LAYTYP( 6,22)
4   $ layer type: LAYTYP( 7,22)
7   $ number of layers in each face sheet: NLAYRF
5   $ number of layers around trapezoidal tool: NLAYRC
0   $ 0=pressure on top face sheet; 1=bottom face sheet: INTEXT
22  $ number of segments in module: NSEGS
13  $ number of modules for general buckling: NMODULG
1   $ number of modules for local buckling: NMODULL
1   $ low end of the M-range for general buckling: MLOWG
5   $ high end of the M-range for general buckling: MHIGHG
1   $ low end of the range of local buckling waves: MLOWL

```