

Table 1,33 (5 pages) p. 1 of 5
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The numbers of the references [] given in the CHAPTER headings correspond to those listed at the end of the paper:
Bushnell, D.

"Optimization of an axially compressed ring and stringer stiffened cylindrical shell with a general buckling modal imperfection", AIAA Paper 2007-2216, 48th AIAA SDM Meeting, Honolulu, Hawaii, April 2007

The overall structure of PANDA2 and its use are described in the first PANDA2 paper, Ref.[1A], cited in the April 2007 paper just identified. Ref.[1A] is the following paper:
Bushnell, D.,

"PANDA2 - Program for minimum weight design of stiffened, composite, locally buckled panels", COMPUTERS AND STRUCTURES, Vol. 25, No. 4, pp 469-605, 1987

Concepts such as "wide-column" buckling, "discretized module model", "stringer pop-off", "constitutive matrices" "reduction factor for transverse shear deformation (t.s.d.)" "smeared stiffeners", "neutral surface", "overall and local static response to uniform pressure", "knockdown factors for anisotropy and in-plane shear loading", "crippling of stiffener parts", and "local postbuckling" are described there, with many early PANDA2 examples provided.

The string, "PANDA-type theory" often occurs. This refers to the theory presented in Ref. [1B] of the April 2007 citation listed first. Ref.[1B] contains the theory given in the paper:
Bushnell, D.,

"Theoretical basis of the PANDA computer program for preliminary design of stiffened panels under combined in-plane loads", COMPUTERS & STRUCTURES, v. 27, No. 4, pp 541-563 (1987).

The theory used for local postbuckling behavior appears in Ref. [1C] of the April 2007 paper cited first (above).
Ref. [1C] is the following paper:

Bushnell, D.,
"Optimization of composite, stiffened, imperfect panels under combined loads for service in the postbuckling regime", Computer Methods in Applied Mechanics and Engineering, Vol. 103 (1993) 43-114

The theory used for imperfection sensitivity appears in Refs. [1E] and [1D] of the first-cited paper above.
Refs. [1E] and [1D] are the following two papers:

Bushnell, D. and Bushnell, W. D.,
"Approximate method for the optimum design of ring and stringer stiffened cylindrical panels and shells with local, inter-ring, and general buckling modal imperfections" Computers and Structures, Vol. 59, No. 3, pp 489-527 (1996)

Bushnell, D.,
"Recent enhancements to PANDA2" AIAA Paper 96-1337-CP, Proc. of the AIAA 37th Structures, Structural Dynamics and Materials Conference, pp 126-182, April, 1996.

The last paper cited also describes the "global" optimizer, "SUPEROPT", implementation of Sanders shell equations into PANDA2, implementation of the Arbocz theory for imperfection sensitivity, implementation of isogrid geometry, and implementation of various truss-core geometries, with examples.

The theories used in PANDA2 for the analysis of sandwich walls are given in Ref.[1F] of the first-cited paper above.
Ref. [1K] is the following paper:

Bushnell, D.,
"Optimum design via PANDA2 of composite sandwich panels with honeycomb or foam cores", AIAA Paper 97-1142, Proc. 38th AIAA Structures, Structural Dynamics and Materials Conference, pp 2163-2202, April, 1997

The "alternate" (double-trigonometric series expansion buckling theory) and the discretized "skin"-ring module model are described in Ref. [1G] of the first-cited paper.

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Ref. [1G] is the following paper:
Bushnell, D., Jiang, H., and Knight, N.F.,
"Additional buckling solutions in PANDA2", Proceedings of the
40th AIAA SDM Conference, AIAA Paper 99-1233, pp 302-345
April 1999

Details of the strategy used in PANDA2 for accounting for initial buckling modal imperfections are described and listed in a table in Ref. [1K]. Ref. [1K] is the following paper:
Bushnell, D. and Rankin, C.C.,
"Difficulties in optimization of imperfect stiffened cylindrical shells",
AIAA Paper 1943, 47th AIAA Structures, Structural Dynamics and Materials Meeting, Newport RI, April 2006

ENTERING SUBROUTINE STRUCT
***** TABLE OF CONTENTS *****
CHAPTER 1 Compute the 6×6 constitutive matrices [C] for individual model segments and various combinations thereof (skin with smeared stiffener sets [1A]).
CHAPTER 2 Do PANDA-type [1B] general buckling analysis to get Donnell factors for later use, if appropriate.
CHAPTER 3 Do various PANDA-type [1B] general buckling analyses needed for later computation of effective length of the panel. Compute the effective length.
CHAPTER NEW Compute wide-column buckling from discretized skin-stringer module model (Figs. 20b,c & 22b,c in [1A]) with only N_x ($N_y=0$, $N_{xy}=0$). The purpose is to obtain a knockdown factor, WIDKNK, for smearing the stringers in an inter-ring buckling mode.
CHAPTER 4 Compute axisymmetric prebuckling "hungry-horse" state of the curved panel or cylindrical shell. (See Ref. [1E]).
CHAPTER 5 Get static response of panel to normal pressure [1A].
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CHAPTER 7 Compute distribution of loads in panel module skin-stringer segments, neglecting redistribution due to initial buckling modal imperfections (See Section 10 of [1A]).
CHAPTER 8 Do PANDA-type local, inter-ring, general buckling analyses and PANDA-type stringer web and ring web buckling analyses to get knockdown factors to compensate for lack of in-plane shear N_{xy} loading and anisotropy in discretized BOSOR4-type models. (See Section 11 of [1A] and Item No. 81 in [1L]).
CHAPTER 9 Do BOSOR4-type "skin"-ring buckling analyses to compute knockdown factor to compensate for inherent unconservativeness of models with smeared rings. (See Items 509, 511, 522, and 605 in [1L]; "skin"=skin+smeared stringers).
CHAPTER 10 Compute knockdown factors and prebuckling bending associated with initial general, inter-ring, local buckling modal imperfections. (See Ref. [1E]).
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CHAPTER 10.2 Compute knockdown factor and prebuckling bending associated with inter-ring buckling modal initial imperfection.
CHAPTER 10.3 Compute knockdown factor and prebuckling bending associated with local buckling modal initial imperfection.
CHAPTER 10.4 Present a summary of imperfection sensitivity results. (See Section 13 and Table 9 of [1K])
CHAPTER 11 Get change in stress resultants, N_x , N_y , N_{xy} in various segments of the skin-stringer module during prebuckling bending of the imperfect shell. Also, do PANDA-type [1B] local, inter-ring, general buckling analyses and PANDA-type stringer web and ring web buckling analyses to get knockdown

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- factors to compensate for the lack of in-plane shear N_{xy} loading and anisotropy in discretized BOSOR4-type models. (See Section 11 in [1A])
- CHAPTER 12 List prebuckled state of the initially imperfect and loaded and bent panel or shell. This section includes the redistribution of N_x , N_y , N_{xy} in the various segments of the stiffened shell structure.
- CHAPTER 13 List prebuckling stress resultants, N_x , N_y , needed for the discretized single-module skin-stringer model used for local buckling and bending-torsion buckling (BOSOR4-type model: see Figs. 18, 20, 22, 97, and 98 of [1A], for examples).
- CHAPTER 14 Compute local buckling from BOSOR4-type discretized skin-stringer single module model. See Section 12.2 in [1A].
- CHAPTER 15 Compute bending-torsion (low-m) buckling from BOSOR4-type discretized skin-stringer single module model. See Section 12.2 in [1A].
- CHAPTER 16 Compute post-local buckling from the Koiter theory given in Ref. [1C]. (Figs. 23, 24 in [1A] and Fig. 6 in [1C]).
- CHAPTER 17 Compute stresses in layers and at various locations in skin-stringer module model, including local post-buckling, if any. Compute stringer popoff constraints [1A]. SUBROUTINE STRTHK is used.
- CHAPTER 18 Present summary of state of loaded imperfect panel and give effective stiffnesses of possibly locally postbuckled skin-stringer module. These effective stiffnesses (Table 12 of Ref. [18]) are used later for overall buckling and inter-ring buckling.
- CHAPTER 19 Do wide-column inter-ring buckling analysis with possibly locally postbuckled skin-stringer module model. (See Fig. 20c of [1A]).
- CHAPTER 20 Compute width-wise wide column buckling and lateral-torsional buckling load factors from the possibly locally postbuckled skin-stringer module model (inter-ring buckling modes). See panda2.news Item Numbers 379 and 381 in [1L].
- CHAPTER 20b Compute high-m buckling of single discretized skin-stringer module (same model as used in CHAPTER 14 except explored in the range of high numbers of axial halfwaves). See panda2.news Item Number 682.
- CHAPTER 21 Compute "skin"-ring buckling load factor for computing knockdown to compensate for inherent unconservativeness of smeared ring models. (See bottom row in Fig. 30 of Ref. [1G]. Also see panda2.news Items 509, 511, 522, 532, 605, 617, 619, 632, 633, 676.)
- CHAPTER 22 Compute "skin"-ring buckling load factors for:
1. medium-n inter-ring buckling mode (See rightmost three mode shapes in top row of Fig. 30 of Ref. [1G]),
 2. high-n inter-ring buckling mode (See rightmost mode shape in middle row of Fig. 30, Ref. [1G]),
 3. low-n inter-ring buckling mode (See leftmost mode shape in top row of Fig. 30, Ref. [1G]).
- CHAPTER 23 Compute stresses in layers and at various locations in modules for both positive and negative imperfection amplitudes from SUBROUTINE STRCON (local postbuckling neglected).
- CHAPTER 24 Present short summary of redistribution of stress resultants, N_x , N_y , N_{xy} , caused by prebuckling bending of an initially imperfect shell. See Section 6.0 in [1K].
- CHAPTER 25 Compute buckling load factors from PANDA-type theory for the various segments of a stringer and a ring. Typical buckling modes are displayed in Figs. 5 and 6 of Ref. [1B].
- CHAPTER 26 Compute local, inter-ring, general buckling load factors from PANDA-type models [1B] and from "alternative" (double-trigonometric series expansion) models, Ref. [1G]. Also compute sandwich wall behavior [1F], if applicable.
- CHAPTER 27 Compute the objective function (e.g. WEIGHT).
- CHAPTER 28 Present design, loading, and margins for the current load set and subcase. (See Table 6 in [18])

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CHAPTER 1 Compute the 6×6 constitutive matrices [C] for individual model segments and various combinations thereof (skin with smeared stiffener sets [1A]). See Section 8 in [1A], Eq.(8.1) on p.495 of [1A].

*** BEGIN SUBROUTINE GETCIJ (CONSTIT. LAW: SEGS AND SMEARED ***
 See Section 8, pp 494-503 of Reference [1A]. First the 6×6 integrated constitutive coefficients C_{ij} (Eq.8.1) and thermal loading are found for each segment in the skin-stringer module then for the skin-ring module, then for the skin with smeared stringers only, then for the skin with smeared rings only, and finally for the skin with both stringers and rings smeared.

CONSTITUTIVE MATRIX C(i,j) FOR SKIN-STRINGER MODULE
 M {ET}

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UNIQUE SKIN-STRINGER MODULE iSEGMENT NO. 1: PANEL SKIN
 M {ET}
 7.0553E+05 2.1166E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 2.1166E+05 7.0553E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 2.4694E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 2.4235E+02 7.2706E+01 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 7.2706E+01 2.4235E+02 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 8.4823E+01 0.0000E+00 0.0000E+00
 E+00

UNIQUE SKIN-STRINGER MODULE iSEGMENT NO. 2: STRINGER BASE
 M {ET}
 7.0553E+05 2.1166E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 2.1166E+05 7.0553E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 2.4694E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 2.4235E+02 7.2706E+01 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 7.2706E+01 2.4235E+02 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 8.4823E+01 0.0000E+00 0.0000E+00
 E+00

UNIQUE SKIN-STRINGER MODULE iSEGMENT NO. 3: STRINGER WEB
 M {ET}
 1.9942E+06 5.9827E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 5.9827E+05 1.9942E+06 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 6.9798E+05 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 5.4729E+03 1.6419E+03 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 1.6419E+03 5.4729E+03 0.0000E+00 0.0000E+00 0.0000E+00
 E+00
 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 1.9155E+03 0.0000E+00 0.0000E+00
 E+00

Location of skin-stringer module centroid, ECCN= 4.0732E-01
 Effective skin-stringer module EI per length
 of circumferential arc of the panel, EIEFF= 4.9955E+05
 Inter-ring skin-stringer single module treated as an Euler column: buckling load/circ.arclength, FNCRIT= 1.9721E+03
 Compare FNCRIT to the wide-column buckling load. That gives you an idea what the combined knockdown factor should be for (1) smearing the stringers, + (2) the effect of t.s.d. The effective length of the Euler column is B(2)= 5.0000E+01

C(i,j) with smeared stringers only...
 {ET}

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Reference surface is at the refer. surface of the skin midway between the stringers.newsITEM 27»

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4	1.0891E+06	2.1166E+05	0.0000E+00	4.1776E+05	0.0000E+00	0.0000E+00	0.0000E+00	0.0000»
E+00	2.1166E+05	7.0553E+05	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	0.0000»
E+00	0.0000E+00	0.0000E+00	2.4694E+05	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	0.0000»
E+00	4.1776E+05	0.0000E+00	0.0000E+00	5.9804E+05	7.2706E+01	0.0000E+00	0.0000E+00	0.0000»
E+00	0.0000E+00	0.0000E+00	0.0000E+00	7.2706E+01	2.4235E+02	0.0000E+00	0.0000E+00	0.0000»
E+00	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	4.8974E+02	0.0000E+00	0.0000»

C(i,j) with smeared stringers and reduced stiffness
for Segment 1 of the panel skin.

If FSLOC.LT.0.95 (post-local-buckling allowed) the following C(i,j) are used for the prediction of preliminary general instability, the purpose of which is to establish, for flat panels, how much any axial bowing amplitude grows under the applied axial load.

1.0891E+06	2.1166E+05	0.0000E+00	4.1776E+05	0.0000E+00	0.0000E+00
2.1166E+05	7.0553E+05	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00
0.0000E+00	0.0000E+00	2.4694E+05	0.0000E+00	0.0000E+00	0.0000E+00
4.1776E+05	0.0000E+00	0.0000E+00	5.9804E+05	7.2706E+01	0.0000E+00
0.0000E+00	0.0000E+00	0.0000E+00	7.2706E+01	2.4235E+02	0.0000E+00
0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00	4.8974E+02

LOCATION OF THE NEUTRAL PLANE FOR AXIAL LOADING
AND C(i,j) WITH SMEARED STIFFENERS. Reference surface for the
following C(i,j) is the neutral plane for axial loading.
Negative d corresponds to a neutral plane that lies above
the plane of the reference surf. of the lowest panel skin.
See Fig. 15a on page 502 of Reference [1].
d = -4.0732E-01

1.0891E+06	2.1166E+05	0.0000E+00	-2.5864E+04	-8.6213E+04	0.0000E+00
2.1166E+05	7.0553E+05	0.0000E+00	-8.6213E+04	-2.8738E+05	0.0000E+00
0.0000E+00	0.0000E+00	2.4694E+05	0.0000E+00	0.0000E+00	-1.0058E+05
-2.5864E+04	-8.6213E+04	0.0000E+00	4.3842E+05	3.5189E+04	0.0000E+00
-8.6213E+04	-2.8738E+05	0.0000E+00	3.5189E+04	1.1730E+05	0.0000E+00
0.0000E+00	0.0000E+00	-1.0058E+05	0.0000E+00	0.0000E+00	4.1459E+04

**** END SUBROUTINE GETCIJ (CONSTIT. LAW: SEGS AND SMEARED ***

Table 1.34

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CHAPTER 13 Get prebuckling stress resultants, N_x , N_y , needed
for the discretized single-module skin-stringer
model used for local buckling and bending-torsion
buckling (BOSOR4-type model: see Figs. 18, 20,
22, 97, and 98 of [1A], for examples of the
discretized single skin-stringer BOSOR4-type
module model.).

Effective circumferential radius of curvature, RADNEW= 7.0711E+07
External Stringer

MODULE WITH RECTANGULAR STIFFENER

```

Segment No. 3 -----> !   ^
!   !
!   !
Seg. No. 2-.      !   h
.
.
.
Segment No. 1-.    .   !   !   .-Seg. No. 4
.   .   !   V   .(same as Seg. 1)
-----  

!<---- b2 ----->!  

!<-- Module width = stiffener spacing, b -->!

```

EXPLODED VIEW, SHOWING LAYERS and (SEGMENT, NODE) NUMBERS

(3, 11)

Layer No. 1 -----> ! <----- Layer No. k

Layer No. 1-.

Layer No. 1-. . .

. -Layer No. 1

. . .

(3, 1)

=====

(1, 1) (1, 11) (2, 1) (2, 6) (2, 11) (4, 1) (4, 11)

Layer No. m Layer No. n Layer No. m

Single panel module

=====
BEGIN: PREBUCKLING STRESS RESULTANTS USED IN THE
DISCRETIZED SINGLE MODULE MODEL, WITH TOUICK - 0

```

PREBUCKLING STRESS RESULTANTS AT THE FIRST NODE
IN THE DISCRETIZED SINGLE MODULE SEGMENT NO. 1 .....
  "Total." loads, Nx(var),Ny(var),Nxy(var) = -6.2598E+02 2.1273E-05 5.0000E+00
  "Fixed " loads, Nx(fix),Ny(fix),Nxy(fix) = 0.0000E+00 0.0000E+00 0.0000E+00
PREBUCKLING STRESS RESULTANTS AT THE FIRST NODE
IN THE DISCRETIZED SINGLE MODULE SEGMENT NO. 2 .....
  "Total." loads, Nx(var),Ny(var),Nxy(var) = -6.2598E+02 2.1273E-05 5.0000E+00
  "Fixed " loads, Nx(fix),Ny(fix),Nxy(fix) = 0.0000E+00 0.0000E+00 0.0000E+00
PREBUCKLING STRESS RESULTANTS AT THE FIRST NODE
IN THE DISCRETIZED SINGLE MODULE SEGMENT NO. 3 .....
  "Total." loads, Nx(var),Ny(var),Nxy(var) = -1.7694E+03 0.0000E+00 4.5355E-06
  "Fixed " loads, Nx(fix),Ny(fix),Nxy(fix) = 0.0000E+00 0.0000E+00 0.0000E+00

```

AXIAL CURVATURE CHANGES FROM SOURCES OTHER THAN INITIAL IMPERFECTIONS (FROM EPSLOD(4) AND ETHERM(4))

"Eigenvalue" axial curvature change
 CURVAR = EPSLOD(4) - FFIABT*ETHERM(4) = 4.4996E-11
 "Fixed" axial curvature change
 CURFIX = EPSSLDF(4) = 0.0000E+00

```

PREBUCKLING AXIAL RESULTANTS IN STRINGER WEB: SEGMENT NO. 3
  "Eigenvalue" axial resultant, Nx(var)=
-1.7694E+03 -1.7694E+03 -1.7694E+03 -1.7694E+03 -1.7694E+03 -1.7694E+03
-1.7694E+03 -1.7694E+03 -1.7694E+03 -1.7694E+03 -1.7694E+03
  " fixed " axial resultant, Nx(fix)=
  0.0000E+00   0.0000E+00   0.0000E+00   0.0000E+00   0.0000E+00   0.0000E+00
  0.0000E+00   0.0000E+00   0.0000E+00   0.0000E+00   0.0000E+00
PREBUCKLING STRESS RESULTANTS AT THE FIRST NODE
IN THE DISCRETIZED SINGLE MODULE SEGMENT NO. 4

```

Table 1.34 (end)

"Total." loads, Nx(var), Ny(var), Nxy(var) = -6.2598E+02 2.1273E-05 5.0000E+00
"Fixed" loads, Nx(fix), Ny(fix), Nxy(fix) = 0.0000E+00 0.0000E+00 0.0000E+00

END: PREBUCKLING STRESS RESULTANTS USED IN THE
DISCRETIZED SINGLE MODULE MODEL WITH IQUICK = 0...
=====

Table 1.35

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CHAPTER 14 Compute local buckling from BOSOR4-type discretized skin-stringer single module model. See Section 12.2 (upper table on p. 511) and Figs. 46c and 98b in [1A], for examples.

EXPLANATION OF FOLLOWING CALCULATIONS (LOAD SET NO. 1):
 Eigenvalues corresponding to local buckling of the skin obtained from the BOSOR4-discretized panel module model are calculated for a range of axial wavenumbers. All four edges of the panel are assumed to be simply supported, even if you indicated "clamped" in your input, and the in-plane loading is assumed to be uniform (N_1 , N_2 , N_{12}), even if you provided for axial load N_x varying in the L2 (circumferential) direction.

***** BEGIN SUBROUTINE LOCAL (INITIAL LOCAL BUCKLING SEARCH) *****
 BUCKLING LOAD FACTORS FROM BOSOR4-TYPE DISCRETIZED MODEL...

(skin-stringer discretized module of local buckling)

AXIAL HALF- WAVES	BUCKLING LOAD FACTOR BEFORE KNOCKDOWN	KNOCKDOWN FOR TRANSVERSE SHEAR DEFORMATION	KNOCKDOWN FOR IN-PLANE SHEAR LOADING AND/OR LOADING	BUCKLING LOAD FACTOR AFTER KNOCKDOWN
M	EIGOLD	KSTAR	KNOCK	EIGOLD*KSTAR*KNOCK
7	2.62633E-01	1.00000E+00	1.00000E+00	2.62633E-01
8	2.66073E-01	1.00000E+00	1.00000E+00	2.66073E-01
6	2.70452E-01	1.00000E+00	1.00000E+00	2.70452E-01
7	2.62633E-01	1.00000E+00	1.00000E+00	2.62633E-01

***** END SUBROUTINE LOCAL (INITIAL LOCAL BUCKLING SEARCH) *****
 ***** END OF LOCAL BUCKLING EIGENVALUE CALC. *****

critical number of
axial halfwaves

Compare with STAGS prediction (0.25038)
 of linear buckling given in
 Figs. 1.43 & 1.44.

Compare with BIGBOSOR4

prediction in Fig. 1.50 (0.26503)

Search over M
for the minimum
eigenvalue

Table 1.36

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CHAPTER 15 Compute bending-torsion (low-m) buckling from BOSOR4-type discretized skin-stringer single module model. See Section 12.2 (lower table on p. 511) in [1A], for example.

```
**** BEGIN SUBROUTINE LOCAL (LOW-M LOCAL BUCKLING SEARCH) ****
BUCKLING LOAD FACTORS FROM BOSOR4-TYPE DISCRETIZED MODEL...
(skin-stringer discretized module of local buckling)
AXIAL   BUCKLING      KNOCKDOWN FOR      KNOCKDOWN FOR      BUCKLING
HALF-    LOAD FACTOR    TRANSVERSE SHEAR    IN-PLANE SHEAR    LOAD FACTOR
WAVES   BEFORE KNOCKDOWN   DEFORMATION      LOADING AND/OR AFTER KNOCKDOWN
                                         ANISOTROPY
M       EIGOLD          KSTAR            KNOCK           EIGOLD*KSTAR*KNOCK
1       1.28972E+00     1.00000E+00    1.00000E+00    1.28972E+00
2       6.18522E-01     1.00000E+00    1.00000E+00    6.18522E-01
3       4.35163E-01     1.00000E+00    1.00000E+00    4.35163E-01
4       3.43649E-01     1.00000E+00    1.00000E+00    3.43649E-01
5       2.94503E-01     1.00000E+00    1.00000E+00    2.94503E-01
6       2.70450E-01     1.00000E+00    1.00000E+00    2.70450E-01
7       2.62632E-01     1.00000E+00    1.00000E+00    2.62632E-01
8       2.62632E-01     1.00000E+00    1.00000E+00    2.62632E-01
Buckling load factor from SUB. LOCAL, EIGITR(4)= 2.6263E-01
Number of axial halfwaves between rings, NLLOW= 7
**** END SUBROUTINE LOCAL (LOW-M LOCAL BUCKLING SEARCH) ****
**** END OF LOW-AXIAL-WAVENUMBER CHECK FOR ****
***** LOCAL BUCKLING *****
```

Searching for a different minimum eigenvalue vs M than that found in the previous table. In this case a "low-m" minimum different from that already found at M=7 was not discovered, but often there is a low-m minimum in other cases. PANDAR always checks if IQUICK=0.

Table 1.37 (1 of 6)

riks.axial.realstiff.chap16.opm

CHAPTER 16 Compute post-local buckling from the Koiter theory given in Ref.[1C]. See Figs. 23, 24, and Figs. 47-49 in [1A], Fig. 6 in [1C], and Fig. 4 in Bushnell, D.

"Optimization of an axially compressed ring and stringer stiffened cylindrical shell with a general buckling modal imperfection", AIAA Paper 2007-2216, 48th AIAA SDM Meeting, Honolulu, Hawaii, April 2007

```
*** BEGIN CALCULATIONS RELATING TO THE KOITER THEORY ***
*** See Ref.[3]: Bushnell, D., "Optimization of composite,
*** stiffened, imperfect panels under combined loads for
*** service in the posbuckling regime", CMAME, vol.103,
*** pp 43-114 (1993)
** BEGIN SUBROUTINE INTMOD (INTEGRALS OF PRODUCTS OF MODES) **
SUB.INTMOD computes the quantities given on pp 58 and 59 of
the paper just cited.
**** END SUBROUTINE INTMOD (INTEGRALS OF PRODUCTS OF MODES) ****
```

EXPLANATION OF FOLLOWING CALCULATIONS (LOAD SET NO. 1):

Corresponding to M= 7 waves from the local buckling analysis above, the distributions of Nx, Ny, and Nxy in the locally imperfect and additionally deformed panel are next calculated. The maximum stress components in the deformed skin as well as in the stiffener segments are also computed. In addition, the tangent membrane stiffness CTAN in the locally deformed skin is calculated. CTAN is needed for subsequent calculation of the load factor corresponding to wide column panel buckling (buckling between rings) and general instability.

BEFORE POSSIBLE CHANGE: INITIAL LOCAL IMPERFECTION W0= 0.0064203213
 AFTER POSSIBLE CHANGE: INITIAL LOCAL IMPERFECTION W0= 0.0064203213
 IF W0 WAS CHANGED, SEE PANDA2.NEWS ITEM 141 FOR WHY IT WAS

***** BEGIN SUBROUTINE KOIT2 (KOITER THEORY POSTBUCKLING) *****

***** ENTERING KOITER BRANCH, SUBROUTINE KOIT2 *****
 This subroutine is an implementation of the theory described in the PANDA2 paper by David Bushnell:

"Optimization of composite, stiffened, imperfect panels under combined loads for service in the postbuckling regime", Computer Methods in Applied Mechanics and Engineering, Vol. 103 (1993) 43-114 (volume in honor of Besselings 65th birthday).

NOTE: Computations herein do not include the effect of "hungry-horse" adjustments to the hoop resultant in the panel skin: FNYADJ= 0.0000E+00 for Load Set A and FNYAD0= 0.0000E+00 for Load Set B.
 unless a negative eigenvalue is computed in SUBROUTINE EIGKOI.

BIFURCATION BUCKLING EIGENVALUE FROM KOITER-TYPE THEORY				
AXIAL	ITER.	SLOPE	DSLOPE	EIGKOI
WAVES	NO.	m	dm	
7	1	4.9279E-03	3.9279E-03	2.5842E-01
7	2	4.9278E-03	-1.6139E-07	2.5843E-01
7	3	4.9278E-03	4.2720E-10	2.5843E-01

LOCAL BIFURCATION BUCKLING LOAD FACTOR ESTIMATES
 AND AMPLITUDE W0 OF LOCAL IMPERFECTION, W0*(buckling mode)
 Critical number of axial half-waves = 7
 Slope of buckling nodal lines from Koiter Theory, m= 4.93E-03
 Knockdown factor for C44, C45, C55 for transv.shear= 1.00E+00
 Local buckling load Factor from Koiter-type Theory = 2.58E-01
 Load Factor from BOSOR4-type panel module model = 2.63E-01
 BOSOR4-type load factor without knockdowns for
 effects of anisotropy [e.g. C(4,6)] of the skin,
 transverse shear def., or in-plane shear loading = 2.63E-01
 Amplitude W0 of local imperfection = 6.4203E-03

ENTERING "NEWTON", LABEL=8002; IMOD= 0

NONLINEAR POST-LOCAL BUCKLING BEHAVIOR WITH
 INITIAL LOCAL IMPERFECTION IGNORED (W0 = 0):

Table 1.37 (2 of 6)

SUBROUTINE NEWTON CALLED FROM KOIT2 AT LABEL= 8002
 NEWTON ITERATIONS BEGIN; SLOPE= 4.9278E-03; a= 0.0000E+00; f= 0.0000E+00
 Imperfection, Wo= 0.0000E+00; Load Perturbation= 0.0000E+00
 ITER SLOPE DSLOPE a da f df
 1 1.9068E-02 1.4140E-02 0.0000E+00 0.0000E+00 1.7754E-01 1.9957E-05
 2 1.9066E-02 -2.0675E-06 0.0000E+00 0.0000E+00 1.7753E-01 4.2679E-13
 3 1.9066E-02 1.2917E-09 0.0000E+00 0.0000E+00 1.7753E-01 1.6658E-19
 LEAVING "NEWTON", LABEL=8002; IMOD, NOCONV= 0 0
 SOLN FROM "NEWTON": F,AL,M; N= 1.7753E-01 0.0000E+00 1.9066E-02 4.8361E-02
 ENTERING "NEWTON", LABEL=8004; IMOD= 0

NONLINEAR POST-LOCAL BUCKLING BEHAVIOR WITH
 INITIAL LOCAL IMPERFECTION INCLUDED (Wo = 6.4203E-03):

SUBROUTINE NEWTON CALLED FROM KOIT2 AT LABEL= 8004
 NEWTON ITERATIONS BEGIN; SLOPE= 1.9066E-02; a= 0.0000E+00; f= 1.7753E-01
 Imperfection, Wo= 6.4203E-03; Load Perturbation= 0.0000E+00
 ITER SLOPE DSLOPE a da f df
 1 2.0445E-02 1.3787E-03 0.0000E+00 0.0000E+00 1.7254E-01 -4.9858E-03
 2 2.0486E-02 4.1479E-05 0.0000E+00 0.0000E+00 1.7233E-01 -2.1076E-04
 3 2.0486E-02 5.2972E-08 0.0000E+00 0.0000E+00 1.7233E-01 -3.6972E-07
 LABEL= 8004 CONVERGENCE OF LOCAL STATE SUCCESSFUL! IMOD= 0
 SOLUTION FROM "NEWTON", F,AL,M= 1.7233E-01 0.0000E+00 2.0486E-02
 LEAVING "NEWTON", LABEL=8004; IMOD, NOCONV= 0 0
 SOLN FROM "NEWTON": F,AL,M; N= 1.7233E-01 0.0000E+00 2.0486E-02 4.8361E-02
 ENTERING "NEWTON", LABEL=8004; IMOD= 0

NONLINEAR POST-LOCAL BUCKLING BEHAVIOR WITH
 INITIAL LOCAL IMPERFECTION INCLUDED (Wo = 6.4203E-03):

SUBROUTINE NEWTON CALLED FROM KOIT2 AT LABEL= 8004
 NEWTON ITERATIONS BEGIN; SLOPE= 2.0486E-02; a= 0.0000E+00; f= 1.7233E-01
 Imperfection, Wo= 6.4203E-03; Load Perturbation= 0.0000E+00
 ITER SLOPE DSLOPE a da f df
 1 2.0486E-02 1.8494E-09 0.0000E+00 0.0000E+00 1.7233E-01 8.1784E-09
 2 2.0486E-02 4.3593E-10 0.0000E+00 0.0000E+00 1.7233E-01 -7.3751E-09
 3 2.0486E-02 4.3593E-10 0.0000E+00 0.0000E+00 1.7233E-01 -7.3751E-09
 LABEL= 8004 CONVERGENCE OF LOCAL STATE SUCCESSFUL! IMOD= 0
 SOLUTION FROM "NEWTON", F,AL,M= 1.7233E-01 0.0000E+00 2.0486E-02
 LEAVING "NEWTON", LABEL=8004; IMOD, NOCONV= 0 0
 SOLN FROM "NEWTON": F,AL,M; N= 1.7233E-01 0.0000E+00 2.0486E-02 4.8361E-02

NEWTON ITERATIONS BEGIN IN SUBROUTINE ENERGY
 CALLED FROM SUBROUTINE KOIT2 AT LABEL = 8010.
 PURPOSE IS TO OBTAIN NEW SOLUTION ALLOWING THE AXIAL
 HALFWAVELENGTH OF THE LOCAL POSTBUCKLED PATTERN TO CHANGE.

ITER.	UNKNOWNS IN THE LOCAL POSTBUCKLING PROBLEM						
	NO.	AMPLITUDE	FLATTENING	NODAL LINE	$\pi^{**2} * n^{**2} / 4L^{**2}$	AXIAL HALFWAVELENGTH	
	f	a	SLOPE, m	N	OF BUCKLES, (L/n)		
0	1.72333E-01	-1.00000E-04	2.04861E-02	4.83611E-02	7.14285E+00		
1	1.64532E-01	-1.00000E-04	1.99007E-02	5.26533E-02	6.84552E+00		
2	1.63890E-01	-1.00000E-04	1.98338E-02	5.33099E-02	6.80324E+00		
3	1.63839E-01	-1.00000E-04	1.98298E-02	5.33428E-02	6.80114E+00		

CONVERGENCE SUCCESSFUL!

YES CONVERGENCE IN "ENERGY", LABEL=8010: IMOD,F,AL,M,N= 0
 1.6384E-01 -1.0000E-04 1.9830E-02 5.3343E-02

VALUES FOR UNPERTURBED DESIGN: F,A,M,N= 1.64E-01 -1.00E-04 1.98E-02 5.33E-02
 ENTERING "NEWTON", LABEL=8240; IMOD= 0

NONLINEAR POST-LOCAL BUCKLING BEHAVIOR WITH
 INITIAL LOCAL IMPERFECTION INCLUDED (Wo = 6.4203E-03):

SUBROUTINE NEWTON CALLED FROM KOIT2 AT LABEL= 8240
 NEWTON ITERATIONS BEGIN; SLOPE= 1.9830E-02; a= -1.0000E-04; f= 1.6384E-01
 Imperfection, Wo= 6.4203E-03; Load Perturbation= 0.0000E+00
 ITER SLOPE DSLOPE a da f df
 1 1.9830E-02 2.9702E-07 -1.0000E-04 0.0000E+00 1.6381E-01 -3.3447E-05
 2 1.9830E-02 5.9995E-10 -1.0000E-04 0.0000E+00 1.6381E-01 -3.6227E-09
 3 1.9830E-02 5.9995E-10 -1.0000E-04 0.0000E+00 1.6381E-01 -3.6227E-09
 LABEL= 8240 CONVERGENCE OF LOCAL STATE SUCCESSFUL! IMOD= 0
 SOLUTION FROM "NEWTON", F,AL,M= 1.6381E-01 -1.0000E-04 1.9830E-02
 LEAVING "NEWTON", LABEL=8240; IMOD, NOCONV= 0 0
 SOLN FROM "NEWTON": F,AL,M; N= 1.6381E-01 -1.0000E-04 1.9830E-02 5.3343E-02
 AMPLITUDES: F00, F = 0.163838819 0.163805366
 VALUES FOR UNPERTURBED DESIGN: F,A,M,N= 1.64E-01 -1.00E-04 1.98E-02 5.33E-02

///

Table 1.37 (3 of 6)

LOCAL DEFORMATION CHARACTERISTICS:

Average axial strain(not including thermal), EXAVE = -1.3767E-03
 Initial local imperfection amplitude, Wo= 6.4203E-03
 Slope of local buckling nodal lines in skin M = 1.9830E-02
 Parameter "a" in the expression f*(phi +a*phi**3) = -1.0000E-04
 Amplitude f in the expression f*(phi +a*phi**3) = 1.6381E-01
 Normal displacement amplitude between stringers W = 1.6379E-01
 Number of axial halfwaves at local bifurcation = 7
 Number of axial halfwaves in postbuckled regime = 7.3517E+00
 Convergence characteristic, NOCONV = 0

RESULTS FOR 7.3517E+00 AXIAL WAVES...

LOCAL DEFORMATION PARAMETERS:

SLOPE, a, f = 1.9830E-02 -1.0000E-04 1.6381E-01

APPLIED STRESS RESULTANTS (Load set A):

Nx, Ny, Nxy = -1.0000E+03 0.0000E+00 5.0000E+00

APPLIED STRESS RESULTANTS (Load set B):

Nxo, Nyo, Nxyo = 0.0000E+00 0.0000E+00 0.0000E+00

STRAIN AND STRESS FROM APPLIED LOADS:

AVERAGE STRAIN COMPONENTS:

EPS1, EPS2, EPS12 = -1.3767E-03 -1.2405E-04 4.5582E-05

AVERAGE RESULTANTS IN SKIN:

N1SKIN, N2SKIN, N12SKIN = -4.7188E+02 -4.6931E-06 5.0000E+00

NOTE: N1SKIN includes average of Nx in skin and stringer base.

 PERTURB THE APPLIED AXIAL LOAD, Nx...
 ENTERING "NEWTON", LABEL=8250; IMOD= 0

SUBROUTINE NEWTON CALLED FROM KOIT2 AT LABEL= 8250
 NEWTON ITERATIONS BEGIN; SLOPE= 1.9830E-02; a= -1.0000E-04; f= 1.6381E-01
 Imperfection, Wo= 6.4203E-03; Load Perturbation= 2.0000E+01

ITER	SLOPE	DSLOPE	a	da	f	df
1	1.9810E-02	-2.0051E-05	-1.0000E-04	0.0000E+00	1.6608E-01	2.2791E-03
2	1.9811E-02	6.5840E-07	-1.0000E-04	0.0000E+00	1.6604E-01	-4.4482E-05
3	1.9811E-02	-1.3789E-09	-1.0000E-04	0.0000E+00	1.6604E-01	-2.2989E-08

 LABEL= 8250 CONVERGENCE OF LOCAL STATE SUCCESSFUL! IMOD= 0
 SOLUTION FROM "NEWTON", F,AL,M= 1.6604E-01 -1.0000E-04 1.9811E-02
 LEAVING "NEWTON", LABEL=8250; IMOD,NOCONV= 0 0
 SOLN FROM "NEWTON": F,AL,M; N= 1.6604E-01 -1.0000E-04 1.9811E-02 5.3343E-02

 PERTURB THE APPLIED HOOP LOAD, Ny...
 ENTERING "NEWTON", LABEL=8260; IMOD= 0

SUBROUTINE NEWTON CALLED FROM KOIT2 AT LABEL= 8260
 NEWTON ITERATIONS BEGIN; SLOPE= 1.9830E-02; a= -1.0000E-04; f= 1.6381E-01
 Imperfection, Wo= 6.4203E-03; Load Perturbation= 1.2956E+01

ITER	SLOPE	DSLOPE	a	da	f	df
1	2.0899E-02	1.0689E-03	-1.0000E-04	0.0000E+00	1.6533E-01	1.5243E-03
2	2.0889E-02	-9.7240E-06	-1.0000E-04	0.0000E+00	1.6531E-01	-2.0100E-05
3	2.0889E-02	-2.5115E-09	-1.0000E-04	0.0000E+00	1.6531E-01	3.7026E-09

 LABEL= 8260 CONVERGENCE OF LOCAL STATE SUCCESSFUL! IMOD= 0
 SOLUTION FROM "NEWTON", F,AL,M= 1.6531E-01 -1.0000E-04 2.0889E-02
 LEAVING "NEWTON", LABEL=8260; IMOD,NOCONV= 0 0
 SOLN FROM "NEWTON": F,AL,M; N= 1.6531E-01 -1.0000E-04 2.0889E-02 5.3343E-02

 PERTURB THE APPLIED IN-PLANE SHEAR LOAD, Nxy...
 ENTERING "NEWTON", LABEL=8270; IMOD= 0

SUBROUTINE NEWTON CALLED FROM KOIT2 AT LABEL= 8270
 NEWTON ITERATIONS BEGIN; SLOPE= 1.9830E-02; a= -1.0000E-04; f= 1.6381E-01
 Imperfection, Wo= 6.4203E-03; Load Perturbation= 4.5346E+00

ITER	SLOPE	DSLOPE	a	da	f	df
1	3.7815E-02	1.7984E-02	-1.0000E-04	0.0000E+00	1.6387E-01	6.0118E-05
2	3.7799E-02	-1.5854E-05	-1.0000E-04	0.0000E+00	1.6385E-01	-1.5150E-05
3	3.7799E-02	-1.1534E-09	-1.0000E-04	0.0000E+00	1.6385E-01	7.0969E-09

 LABEL= 8270 CONVERGENCE OF LOCAL STATE SUCCESSFUL! IMOD= 0
 SOLUTION FROM "NEWTON", F,AL,M= 1.6385E-01 -1.0000E-04 3.7799E-02
 LEAVING "NEWTON", LABEL=8270; IMOD,NOCONV= 0 0
 SOLN FROM "NEWTON": F,AL,M; N= 1.6385E-01 -1.0000E-04 3.7799E-02 5.3343E-02

 3X3 MATRICES FOR STRAIN AND FORCE CHANGE...

EMAT, THE STRAIN-CHANGE MATRIX	NMAT, THE FORCE-CHANGE MATRIX
d(EPS1) d(EPS2) d(EPS12)	d(N1skin) d(N2skin) d(N12skn)
dNx -3.013E-05 -5.173E-06 6.450E-07	-8.442E+00 7.931E-06 -4.768E-07
dNy -3.351E-06 -2.693E-05 1.828E-06	1.285E+00 -1.296E+01 -4.768E-07

Table 1.37 (4 of 6)

dN_{xy} -2.126E-07 -8.822E-07 4.134E-05 8.148E-02 -4.109E-06 4.535E+00

TANGENT STIFFNESS BEFORE SYMMETRIZATION
 AVERAGE SKIN TANGENT STIFFNESS MATRIX
 (Segments 1 and 2 averaged), CTAN...
 2.9468E+05 -8.4278E+04 1.6876E+03
 -8.4293E+04 4.9222E+05 1.0069E+04
 1.0951E+03 7.3171E+03 1.0984E+05

TANGENT STIFFNESS AFTER SYMMETRIZATION
 AVERAGE SKIN TANGENT STIFFNESS MATRIX
 (Segments 1 and 2 averaged), CTAN...
 2.9468E+05 -8.4285E+04 1.3913E+03
 -8.4285E+04 4.9222E+05 8.6930E+03
 1.3913E+03 8.6930E+03 1.0984E+05

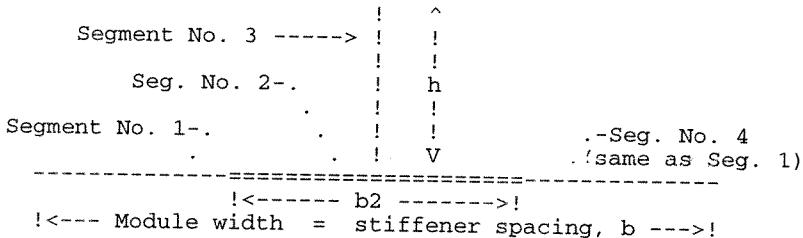
(APPLIED LOAD) / (BUCKLING LOAD) = 3.8695E+00

NORMALIZED AVERAGE SKIN TANGENT STIFFNESS MATRIX
 $(CTAN(i,i)/CX(i,i,1), i=1,2,3) = 4.1766E-01 \quad 6.9765E-01 \quad 4.4481E-01$
 TANGENT POISSON RATIO
 $CTAN(1,2)/CTAN(1,1) = -2.8603E-01$
 NORMALIZED AVERAGE (N_{1skin}, N_{12skn}) COUPLING
 $CTAN(1,3)/CX(1,1,1) = 1.9721E-03$
 NORMALIZED AVERAGE (N_{2skin}, N_{12skn}) COUPLING
 $CTAN(2,3)/CX(2,2,1) = 1.2321E-02$

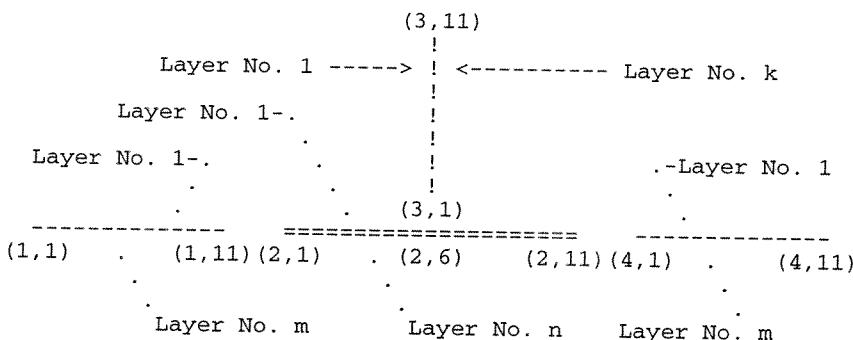
Average tangent stiffnesses of the panel skin
 have been calculated by integration of the local tangent
 stiffnesses, C_{11TAN} , C_{12TAN} , C_{22TAN} , and C_{33TAN} with
 Simpsons rule integration:
 Average axial tangent stiffness, $CTAN(1,1) = 3.3991E+05$
 Average (1,2) tangent stiffness, $CTAN(1,2) = 8.2013E+03$
 Average hoop tangent stiffness, $CTAN(2,2) = 4.9154E+05$
 Average shear tangent stiffness, $CTAN(3,3) = 1.0968E+05$
 These tangent stiffness components affect wide column,
 general instability, and panel instability load factors.

External Stringer

MODULE WITH RECTANGULAR STIFFENER...



EXPLODED VIEW, SHOWING LAYERS and (SEGMENT, NODE) NUMBERS



LOCALLY DEFORMED STATE IN THE PANEL MODULE SHOWN ABOVE
 PANEL MODULE HAS 4 SEGMENTS

Nodal Disp.	Membrane Strains			Resultants			N_{xy}	C_{11TAN}	C_{12TAN}	»
	Point W	Ex	Ey	Exy	N_x	N_y				
C_{22TAN}	C_{33TAN}									

Table 1.37 (5 of 6)

Locally Deformed State for Segment Number 1											
1	1.64E-01	1.67E-04	-5.00E-05	2.02E-05	1.07E+02	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»	.92E+05 1.10E+05
2	1.62E-01	1.38E-04	-4.13E-05	2.02E-05	8.84E+01	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»	.92E+05 1.10E+05
3	1.58E-01	5.37E-05	-1.61E-05	2.02E-05	3.45E+01	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»	.92E+05 1.10E+05
4	1.50E-01	-7.86E-05	2.36E-05	2.02E-05	-5.04E+01	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»	.92E+05 1.10E+05
5	1.40E-01	-2.48E-04	7.44E-05	2.02E-05	-1.59E+02	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»	.92E+05 1.10E+05
6	1.28E-01	-4.41E-04	1.32E-04	2.02E-05	-2.83E+02	2.13E-05	5.00E+00	1.47E+05	0.00E+00	4»	.92E+05 1.10E+05
7	1.13E-01	-6.43E-04	1.93E-04	2.02E-05	-4.13E+02	2.13E-05	5.00E+00	2.48E+05	0.00E+00	4»	.92E+05 1.10E+05
8	9.68E-02	-8.37E-04	2.51E-04	2.02E-05	-5.37E+02	2.13E-05	5.00E+00	3.46E+05	0.00E+00	4»	.92E+05 1.10E+05
9	7.97E-02	-1.01E-03	3.03E-04	2.02E-05	-6.49E+02	2.13E-05	5.00E+00	4.33E+05	0.00E+00	4»	.92E+05 1.10E+05
10	6.23E-02	-1.15E-03	3.46E-04	2.02E-05	-7.41E+02	2.13E-05	5.00E+00	5.05E+05	0.00E+00	4»	.92E+05 1.10E+05
11	4.52E-02	-1.26E-03	3.78E-04	2.02E-05	-8.08E+02	2.13E-05	5.00E+00	5.58E+05	1.03E+04	4»	.92E+05 1.10E+05
Locally Deformed State for Segment Number 2											
1	4.52E-02	-1.26E-03	3.78E-04	2.02E-05	-8.08E+02	2.13E-05	5.00E+00	5.58E+05	1.03E+04	4»	.92E+05 1.10E+05
2	3.16E-02	-1.32E-03	3.96E-04	2.02E-05	-8.47E+02	2.13E-05	5.00E+00	5.88E+05	2.11E+04	4»	.92E+05 1.10E+05
3	1.96E-02	-1.35E-03	4.06E-04	2.02E-05	-8.70E+02	2.13E-05	5.00E+00	6.06E+05	2.76E+04	4»	.92E+05 1.10E+05
4	9.73E-03	-1.37E-03	4.11E-04	2.02E-05	-8.80E+02	2.13E-05	5.00E+00	6.14E+05	3.05E+04	4»	.92E+05 1.10E+05
5	2.91E-03	-1.38E-03	4.13E-04	2.02E-05	-8.84E+02	2.13E-05	5.00E+00	6.16E+05	3.14E+04	4»	.92E+05 1.10E+05
6	-3.13E-17	-1.38E-03	4.13E-04	2.02E-05	-8.84E+02	2.13E-05	5.00E+00	6.17E+05	3.15E+04	4»	.92E+05 1.10E+05
7	-2.91E-03	-1.38E-03	4.13E-04	2.02E-05	-8.84E+02	2.13E-05	5.00E+00	6.16E+05	3.14E+04	4»	.92E+05 1.10E+05
8	-9.73E-03	-1.37E-03	4.11E-04	2.02E-05	-8.80E+02	2.13E-05	5.00E+00	6.14E+05	3.05E+04	4»	.92E+05 1.10E+05
9	-1.96E-02	-1.35E-03	4.06E-04	2.02E-05	-8.70E+02	2.13E-05	5.00E+00	6.06E+05	2.76E+04	4»	.92E+05 1.10E+05
10	-3.16E-02	-1.32E-03	3.96E-04	2.02E-05	-8.47E+02	2.13E-05	5.00E+00	5.88E+05	2.11E+04	4»	.92E+05 1.10E+05
11	-4.52E-02	-1.26E-03	3.78E-04	2.02E-05	-8.08E+02	2.13E-05	5.00E+00	5.58E+05	1.03E+04	4»	.92E+05 1.10E+05
Locally Deformed State for Segment Number 3											
1	-3.01E-04	-1.38E-03	4.13E-04	6.50E-12	-2.50E+03	-2.84E-05	4.54E-06	1.99E+06	5.98E+05	1»	.99E+06 6.98E+05
2	-2.25E-03	-1.38E-03	4.13E-04	6.50E-12	-2.50E+03	-2.84E-05	4.54E-06	1.99E+06	5.98E+05	1»	.99E+06 6.98E+05
3	-4.01E-03	-1.38E-03	4.13E-04	6.50E-12	-2.50E+03	6.45E-06	4.54E-06	1.99E+06	5.98E+05	1»	.99E+06 6.98E+05
4	-5.63E-03	-1.37E-03	4.12E-04	6.50E-12	-2.50E+03	-5.13E-06	4.54E-06	1.99E+06	5.97E+05	1»	.99E+06 6.98E+05
5	-7.13E-03	-1.37E-03	4.12E-04	6.50E-12	-2.49E+03	-1.67E-05	4.54E-06	1.99E+06	5.97E+05	1»	.99E+06 6.98E+05
6	-8.54E-03	-1.37E-03	4.12E-04	6.50E-12	-2.49E+03	-3.99E-05	4.54E-06	1.99E+06	5.96E+05	1»	.99E+06 6.98E+05
7	-9.88E-03	-1.37E-03	4.11E-04	6.50E-12	-2.49E+03	6.62E-06	4.54E-06	1.98E+06	5.95E+05	1»	.99E+06 6.98E+05
8	-1.12E-02	-1.37E-03	4.11E-04	6.50E-12	-2.49E+03	-3.97E-05	4.54E-06	1.98E+06	5.94E+05	1»	.99E+06 6.98E+05
9	-1.25E-02	-1.37E-03	4.10E-04	6.50E-12	-2.48E+03	-4.86E-06	4.54E-06	1.98E+06	5.94E+05	1»	.99E+06 6.98E+05
10	-1.37E-02	-1.37E-03	4.10E-04	6.50E-12	-2.48E+03	-3.96E-05	4.54E-06	1.98E+06	5.93E+05	1»	.99E+06 6.98E+05
11	-1.50E-02	-1.36E-03	4.09E-04	6.50E-12	-2.47E+03	-3.95E-05	4.54E-06	1.97E+06	5.91E+05	1»	.99E+06 6.98E+05
Locally Deformed State for Segment Number 4											
1	-4.52E-02	-1.26E-03	3.78E-04	2.02E-05	-8.08E+02	2.13E-05	5.00E+00	5.58E+05	1.03E+04	4»	.92E+05 1.10E+05
2	-6.23E-02	-1.15E-03	3.46E-04	2.02E-05	-7.41E+02	2.13E-05	5.00E+00	5.05E+05	0.00E+00	4»	.92E+05 1.10E+05
3	-7.97E-02	-1.01E-03	3.03E-04	2.02E-05	-6.49E+02	2.13E-05	5.00E+00	4.33E+05	0.00E+00	4»	.92E+05 1.10E+05

Table 1.37 (6 of 6)

.92E+05	1.10E+05											
4	-9.68E-02	-8.37E-04	2.51E-04	2.02E-05	-5.37E+02	2.13E-05	5.00E+00	3.46E+05	0.00E+00	4»		
.92E+05	1.10E+05											
5	-1.13E-01	-6.43E-04	1.93E-04	2.02E-05	-4.13E+02	2.13E-05	5.00E+00	2.48E+05	0.00E+00	4»		
.92E+05	1.10E+05											
6	-1.28E-01	-4.41E-04	1.32E-04	2.02E-05	-2.83E+02	2.13E-05	5.00E+00	1.47E+05	0.00E+00	4»		
.92E+05	1.10E+05											
7	-1.40E-01	-2.48E-04	7.44E-05	2.02E-05	-1.59E+02	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»		
.92E+05	1.10E+05											
8	-1.50E-01	-7.86E-05	2.36E-05	2.02E-05	-5.04E+01	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»		
.92E+05	1.10E+05											
9	-1.58E-01	5.37E-05	-1.61E-05	2.02E-05	3.45E+01	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»		
.92E+05	1.10E+05											
10	-1.62E-01	1.38E-04	-4.13E-05	2.02E-05	8.84E+01	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»		
.92E+05	1.10E+05											
11	-1.64E-01	1.67E-04	-5.00E-05	2.02E-05	1.07E+02	2.13E-05	5.00E+00	7.06E+04	0.00E+00	4»		
.92E+05	1.10E+05											

AVERAGE AXIAL RESULTANT IN SKIN, Nsknave= -473.766022

NOTE: Nsknave includes Nx averaged in skin and stringer base.

AVERAGE AXIAL RESULTANT OVERALL, Nx(ave)= -1000.

AVERAGE STRESS RESULTANTS IN STIFFENER PARTS

FROM LOAD SET A (eigenvalue loads)..

STRINGER BASE : AXIAL, TRANSVERSE, IN-PLANE SHEAR=	-8.6613E+02	2.1273E-05	5.0000E+00
--	-------------	------------	------------

STRINGER WEB : AXIAL, TRANSVERSE, IN-PLANE SHEAR=	-2.4894E+03	-2.8410E-05	4.5355E-06
---	-------------	-------------	------------

STRINGER FLANGE: AXIAL, TRANSVERSE, IN-PLANE SHEAR=	0.0000E+00	0.0000E+00	0.0000E+00
---	------------	------------	------------

FROM LOAD SET B (fixed applied loads)..

STRINGER BASE : AXIAL, TRANSVERSE, IN-PLANE SHEAR=	0.0000E+00	0.0000E+00	0.0000E+00
--	------------	------------	------------

STRINGER WEB : AXIAL, TRANSVERSE, IN-PLANE SHEAR=	0.0000E+00	0.0000E+00	0.0000E+00
---	------------	------------	------------

STRINGER FLANGE: AXIAL, TRANSVERSE, IN-PLANE SHEAR=	0.0000E+00	0.0000E+00	0.0000E+00
---	------------	------------	------------

RESULTANTS FROM THERMAL LOADING:

STRINGER BASE : AXIAL, TRANSVERSE, IN-PLANE SHEAR=	0.0000E+00	0.0000E+00	0.0000E+00
--	------------	------------	------------

STRINGER WEB : AXIAL, TRANSVERSE, IN-PLANE SHEAR=	0.0000E+00	0.0000E+00	0.0000E+00
---	------------	------------	------------

STRINGER FLANGE: AXIAL, TRANSVERSE, IN-PLANE SHEAR=	0.0000E+00	0.0000E+00	0.0000E+00
---	------------	------------	------------

***** END SUBROUTINE KOIT2 (KOITER THEORY POSTBUCKLING) *****

***** END OF NONLINEAR EQUILIBRIUM CALCS. *****

Table 1.38 (1083)

riks.axial.realstiff.chap17.opm

CHAPTER 17 Compute stresses in layers and at various locations in skin-stringer module model, including local post-buckling, if any. Compute stringer popoff constraints (Figs. 5 - 7 in [1A]). Local post-buckling such as that shown in Figs. 48 & 49 of [1A] is included. Therefore, SUBROUTINE STRTHK is used.

***** BEGIN SUBROUTINE STRTHK (POSTBUCKLING STRESSES) *****
External Stringer

MODULE WITH RECTANGULAR STIFFENER

```

          !   ^
Segment No. 3 -----> !   !
          !   !
          !   !
Seg. No. 2-.      !   h
          !   !
          !   !
Segment No. 1-.    .   !   !           .-Seg. No. 4
          .   !   V           .(same as Seg. 1)
-----  

          !<----- b2 ----->!
!<-- Module width = stiffener spacing, b -->!

```

EXPLODED VIEW, SHOWING LAYERS and (SEGMENT, NODE) NUMBERS

(3,11)

Layer No. 1 -----> ! <----- Layer No. k

Layer No. 1-.

Layer No. 1-.

Layer No. 1-.

--Layer No. 1

(3,1)

(1,1) . (1,11) (2,1) . (2,6) (2,11) (4,1) . (4,11)

Layer No. m Layer No. n Layer No. m

Start calculation of stresses in the panel module depicted above...
(Segment numbering below refers to the **BOTTMOST** of the sketches above.)

STRESSES AT CRITICAL NODES IN SEGMENTS OF MODULE...

BUCK. LOCATION IN PANEL		WINDING	IN-PLANE STRESSES IN MATL COORDS.			MODE OF	TRANSVERSE »			
CRACKING ALLOWABLE MATERIAL			SIG1	SIG2	SIG12	FAILURE	(1.0 means i»)			
MODE	SEG.	NODE LAYER	Z	ANGLE						
nactive)		STRESS	TYPE							
POS	1	1	1	-3.21E-02	0.0	-1.3392E+04	-1.2793E+04	2.4901E+02	no failure	0.0000»
E+00				1						
NEG	1	1	1	-3.21E-02	0.0	1.6722E+04	1.2793E+04	-9.3254E+01	no failure	0.0000»
E+00				1						
POS	1	1	1	3.21E-02	0.0	1.6722E+04	1.2793E+04	-9.3254E+01	no failure	0.0000»
E+00				1						
NEG	1	1	1	3.21E-02	0.0	-1.3392E+04	-1.2793E+04	2.4901E+02	no failure	0.0000»
E+00				1						
POS	1	3	1	-3.21E-02	0.0	-1.3841E+04	-1.1923E+04	-1.8895E+03	no failure	0.0000»
E+00				1						
NEG	1	3	1	-3.21E-02	0.0	1.4915E+04	1.1922E+04	2.0452E+03	no failure	0.0000»
E+00				1						
POS	1	3	1	3.21E-02	0.0	1.4915E+04	1.1923E+04	2.0452E+03	no failure	0.0000»
E+00				1						
NEG	1	3	1	3.21E-02	0.0	-1.3841E+04	-1.1922E+04	-1.8895E+03	no failure	0.0000»
E+00				1						
POS	1	5	1	-3.21E-02	0.0	-1.5094E+04	-1.0063E+04	-3.6249E+03	no failure	0.0000»
E+00				1						
NEG	1	5	1	-3.21E-02	0.0	1.0131E+04	1.0063E+04	3.7807E+03	no failure	0.0000»
E+00				1						
POS	1	5	1	3.21E-02	0.0	1.0131E+04	1.0063E+04	3.7807E+03	no failure	0.0000»
E+00				1						
NEG	1	5	1	3.21E-02	0.0	-1.5094E+04	-1.0063E+04	-3.6249E+03	no failure	0.0000»
E+00				1						
POS	1	7	1	-3.21E-02	0.0	-1.6270E+04	-7.0182E+03	-4.9215E+03	no failure	0.0000»
E+00				1						

Table 1.38 (2 of 3)

NEG E+00	1	7	1	-3.21E-02 1	0.0	3.4145E+03	7.0177E+03	5.0772E+03	no failure	0.0000»
POS E+00	1	7	1	3.21E-02 1	0.0	3.4147E+03	7.0182E+03	5.0772E+03	no failure	0.0000»
NEG E+00	1	7	1	3.21E-02 1	0.0	-1.6270E+04	-7.0177E+03	-4.9215E+03	no failure	0.0000»
POS E+00	1	9	1	-3.21E-02 1	0.0	-1.6428E+04	-2.8577E+03	-5.5535E+03	no failure	0.0000»
NEG E+00	1	9	1	-3.21E-02 1	0.0	-3.7901E+03	2.8572E+03	5.7093E+03	no failure	0.0000»
POS E+00	1	9	1	3.21E-02 1	0.0	-3.7899E+03	2.8577E+03	5.7093E+03	no failure	0.0000»
NEG E+00	1	9	1	3.21E-02 1	0.0	-1.6428E+04	-2.8572E+03	-5.5535E+03	no failure	0.0000»
POS E+00	1	11	1	-3.21E-02 1	0.0	-1.5008E+04	2.2690E+03	-5.2712E+03	no failure	0.0000»
NEG E+00	1	11	1	-3.21E-02 1	0.0	-1.0173E+04	-2.2690E+03	5.4270E+03	no failure	0.0000»
POS E+00	1	11	1	3.21E-02 1	0.0	-1.0173E+04	-2.2690E+03	5.4270E+03	no failure	0.0000»
NEG E+00	1	11	1	3.21E-02 1	0.0	-1.5008E+04	2.2690E+03	-5.2712E+03	no failure	0.0000»
POS E+00	2	1	1	-3.21E-02 1	0.0	-1.5007E+04	2.2704E+03	-5.2712E+03	no failure	0.0000»
NEG E+00	2	1	1	-3.21E-02 1	0.0	-1.0173E+04	-2.2704E+03	5.4270E+03	no failure	0.0000»
POS E+00	2	1	1	3.21E-02 1	0.0	-1.0173E+04	-2.2704E+03	5.4270E+03	no failure	0.0000»
NEG E+00	2	1	1	3.21E-02 1	0.0	-1.5007E+04	2.2704E+03	-5.2712E+03	no failure	0.0000»
POS E+00	2	6	1	-3.21E-02 1	0.0	-8.0877E+03	1.8931E+04	-1.0268E+03	no failure	0.0000»
NEG E+00	2	6	1	-3.21E-02 1	0.0	-1.9446E+04	-1.8931E+04	1.1826E+03	no failure	0.0000»
POS E+00	2	6	1	3.21E-02 1	0.0	-1.9446E+04	-1.8931E+04	1.1826E+03	no failure	0.0000»
NEG E+00	2	6	1	3.21E-02 1	0.0	-8.0877E+03	1.8931E+04	-1.0268E+03	no failure	0.0000»
POS E+00	2	11	1	-3.21E-02 1	0.0	-1.0173E+04	-2.2704E+03	-5.2712E+03	no failure	0.0000»
NEG E+00	2	11	1	-3.21E-02 1	0.0	-1.5007E+04	2.2704E+03	5.4270E+03	no failure	0.0000»
POS E+00	2	11	1	3.21E-02 1	0.0	-1.5007E+04	2.2704E+03	5.4270E+03	no failure	0.0000»
NEG E+00	2	11	1	3.21E-02 1	0.0	-1.0173E+04	-2.2704E+03	-5.2712E+03	no failure	0.0000»
POS E+00	3	1	1	-9.07E-02 2	0.0	-1.2281E+04	4.7578E+03	-3.1225E+03	no failure	0.0000»
NEG E+00	3	1	1	-9.07E-02 2	0.0	-1.5253E+04	-4.7578E+03	3.1225E+03	no failure	0.0000»
POS E+00	3	1	1	9.07E-02 2	0.0	-1.5253E+04	-4.7578E+03	3.1225E+03	no failure	0.0000»
NEG E+00	3	1	1	9.07E-02 2	0.0	-1.2281E+04	4.7578E+03	-3.1225E+03	no failure	0.0000»

Maximum in-plane tensile force in stringer web
tending to peel the faying flange from the panel skin:

***** STRINGER POPOFF MARGIN *****

Segment number in the discretized model = 3

Nodal point number in the discrete model = 1

Peel force that varies axially as $\cos(nx) = 2.5902E+02$

Peel force that varies axially as $\sin(nx) = 2.5902E+02$

Peel force used in popoff constraint, FPOP= $7.7707E+01$

Maximum allowable peel force, FPOPMAX = $1.00000E+06$

Stringer popoff margin=FPOPMAX/FPOP - 1.0 = $1.2868E+04$

***** END OF STRINGER POPOFF CALCULATIONS *****

POS E+00	3	6	1	-9.07E-02 2	0.0	-1.1462E+04	2.0327E+03	-2.0962E+03	no failure	0.0000»
NEG E+00	3	6	1	-9.07E-02 2	0.0	-1.5988E+04	-2.0327E+03	2.0962E+03	no failure	0.0000»
POS E+00	3	6	1	9.07E-02 2	0.0	-1.5988E+04	-2.0327E+03	2.0962E+03	no failure	0.0000»
NEG E+00	3	6	1	9.07E-02 2	0.0	-1.1462E+04	2.0327E+03	-2.0962E+03	no failure	0.0000»
POS E+00	3	11	1	-9.07E-02 2	0.0	-1.0715E+04	4.3798E+01	-2.0025E+03	no failure	0.0000»
NEG	3	11	1	9.07E-02 2	0.0	-1.6559E+04	-4.3798E+01	2.0025E+03	no failure	0.0000»

Table 1.38 (3 of 3)

E+00	POS	3	11	1	9.07E-02	0.0	-1.6559E+04	-4.3798E+01	2.0025E+03	no failure	0.0000»
E+00	NEG	3	11	1	9.07E-02	0.0	-1.0715E+04	4.3798E+01	-2.0025E+03	no failure	0.0000»
E+00	POS	4	1	1	3.21E-02	0.0	-1.0173E+04	-2.2690E+03	-5.2712E+03	no failure	0.0000»
E+00	NEG	4	1	1	3.21E-02	0.0	-1.5008E+04	2.2690E+03	5.4270E+03	no failure	0.0000»
E+00	POS	4	1	1	3.21E-02	0.0	-1.5008E+04	2.2690E+03	5.4270E+03	no failure	0.0000»
E+00	NEG	4	1	1	3.21E-02	0.0	-1.0173E+04	-2.2690E+03	-5.2712E+03	no failure	0.0000»
E+00	POS	4	6	1	3.21E-02	0.0	6.9266E+03	8.6850E+03	-4.3420E+03	no failure	0.0000»
E+00	NEG	4	6	1	3.21E-02	0.0	-1.5753E+04	-8.6850E+03	4.4978E+03	no failure	0.0000»
E+00	POS	4	6	1	3.21E-02	0.0	-1.5753E+04	-8.6850E+03	4.4978E+03	no failure	0.0000»
E+00	NEG	4	6	1	3.21E-02	0.0	6.9266E+03	8.6850E+03	-4.3420E+03	no failure	0.0000»
E+00	POS	4	11	1	3.21E-02	0.0	1.6722E+04	1.2793E+04	-9.3254E+01	no failure	0.0000»
E+00	NEG	4	11	1	3.21E-02	0.0	-1.3392E+04	-1.2793E+04	2.4901E+02	no failure	0.0000»
E+00	POS	4	11	1	3.21E-02	0.0	-1.3392E+04	-1.2793E+04	2.4901E+02	no failure	0.0000»
E+00	NEG	4	11	1	3.21E-02	0.0	1.6722E+04	1.2793E+04	-9.3254E+01	no failure	0.0000»
Margin=	4.0521E+01	eff.stress:matl=1,SKN,Dseg=2,node=6,layer=1,z=0.0321; MID.;FS=1.									
Margin=	1.2868E+04	stringer popoff margin:(allowable/actual)-1, web 1 MID.;FS=1.									
Margin=	2.5509E+00	eff.stress:matl=2,STR,Dseg=3,node=11,layer=1,z=0.0907; MID.;FS=1.									
***** END SUBROUTINE	STRTHK (POSTBUCKLING STRESSES)	*****									

Table 1.39

riks.axial.realstiff.chap18.opm

CHAPTER 18 Present summary of state of loaded imperfect panel and give effective stiffnesses of possibly locally postbuckled skin-stringer module. These effective stiffnesses are used later for overall buckling and inter-ring buckling. See Table 12 in the paper

Bushnell, D.

"Optimization of an axially compressed ring and stringer stiffened cylindrical shell with a general buckling modal imperfection", AIAA Paper 2007-2216, 48th AIAA SDM Meeting, Honolulu, Hawaii, April 2007

PANEL OVERALL & LOCAL IMPERFECTIONS AND DEFORMATION

General out-of-roundness of cylindrical panel, WIMPG1 =	0.0000E+00
General initial buckling modal imperfection amplitude=	0.0000E+00
General modified imperfection amplitude, Wimp(global)=	0.0000E+00
Local initial imperfection amplitude, Wimp(local) =	6.4203E-03
Panel (inter-ring) initial imp. ampl., Wimp(panel) =	1.0000E-10
Bowing due to temperature effects, W(residual) =	0.0000E+00
Overall (inter-ring in cyl) bowing from pressure ,Wp =	0.0000E+00
Inter-ring bowing (flat panel) from pressure, WPRESR =	0.0000E+00
Maximum local "pillowing" between stringers, WLPRES =	0.0000E+00
Inter-ring bowing due to postbuckling effects, WDELKP =	0.0000E+00
Amplitude factor for bowing except from press,AMPLIT =	4.6960E+00
Amplitude factor for bowing due to pressure, AMPLT2 =	4.6960E+00
Amplitude factor for inter-ring bowing, AMPLT3 =	1.0000E+00
Eccentricity of application of axial loads, ECC =	0.0000E+00

*** BEGIN SUBROUTINE LOCAL (HI-M POST-POSTBUCKLING SEARCH) ***
LABEL NO. IN STRUCT= 9360

BUCKLING LOAD FACTORS FROM BOSOR4-TYPE DISCRETIZED MODEL...

(skin-stringer discretized module of local buckling)

AXIAL HALF- WAVES	BUCKLING LOAD FACTOR BEFORE KNOCKDOWN	KNOCKDOWN FOR TRANSVERSE SHEAR DEFORMATION	KNOCKDOWN FOR IN-PLANE SHEAR LOADING AND/OR	BUCKLING LOAD FACTOR AFTER KNOCKDOWN	
				ANISOTROPY	EIGOLD*KSTAR*KNOCK
M	EIGOLD	KSTAR	KNOCK		
14	1.00677E+00	1.00000E+00	1.00000E+00	1.00677E+00	
15	1.04732E+00	1.00000E+00	1.00000E+00	1.04732E+00	
14	1.00677E+00	1.00000E+00	1.00000E+00	1.00677E+00	

Buckling load factor from SUB. LOCAL, EIGITR(6)= 1.0068E+00
Number of axial halfwaves between rings,NPP= 14

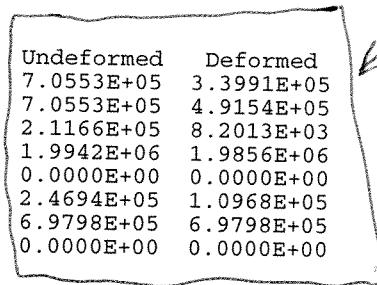
**** END SUBROUTINE LOCAL (HI-M POST-POSTBUCKLING SEARCH) ****

***** BEGIN SUBROUTINE MODE (HI-M POST-POSTBUCKLING MODE) *****
***** END SUBROUTINE MODE (HI-M POST-POSTBUCKLING MODE) *****

Margin= 6.7749E-03 Hi-axial-wave post-post-buckling of module - 1; M=14 : FS=1.
***** THE HI-AXIAL-WAVE POST-POST BUCKL. MARGIN COMPUTED:
Hi-axial-wave post-post-buckling of module - 1; M=14 ;FS=1.
***** CONSTRAINT NO. 6; LOAD SET NO. 1; SUBCASE NO. 1

*** BEGIN SUBROUTINE DEFCIJ (POST-LOCALLY BUCKLED CS(i,j)) ****
Effective stiffnesses of undeformed and of
locally deformed module segments:

Effective axial stiffness of panel SKIN + BASE =	7.0553E+05	3.3991E+05
Effective hoop stiffness of panel SKIN + BASE =	7.0553E+05	4.9154E+05
Effective (1,2) stiffness of panel SKIN + BASE =	2.1166E+05	8.2013E+03
Effective axial stiffness of stringer WEB =	1.9942E+06	1.9856E+06
Effective axial stiffness of stringer FLANGE =	0.0000E+00	0.0000E+00
Effective shear stiffness of panel SKIN + BASE =	2.4694E+05	1.0968E+05
Effective shear stiffness of stringer WEB =	6.9798E+05	6.9798E+05
Effective shear stiffness of stringer FLANGE =	0.0000E+00	0.0000E+00



Integrated stringer stiffnesses...

Effective axial stiffness of stringer, STIFL = 3.8212E+05
Effective first moment, Int[STIF*zdz], STIFM = 4.1543E+05
Effective second moment, Int[STIF*z**2dz], STIFMM= 5.9387E+05

Constitutive law, CS(i,j), for locally deformed
panel with smeared stringers and rings....

7.2614E+05	8.1117E+03	0.0000E+00	4.1543E+05	0.0000E+00	0.0000E+00
8.1117E+03	4.9154E+05	0.0000E+00	0.0000E+00	0.0000E+00	0.0000E+00
0.0000E+00	0.0000E+00	1.0968E+05	0.0000E+00	0.0000E+00	0.0000E+00
4.1543E+05	0.0000E+00	0.0000E+00	5.9412E+05	7.2706E+01	0.0000E+00
0.0000E+00	0.0000E+00	0.0000E+00	7.2706E+01	2.4235E+02	0.0000E+00

Table 1.39 (end)

0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 0.0000E+00 4.8974E+02
*** END SUBROUTINE DEFCIJ (POST-LOCALLY BUCKLED CS(I,J)) ***

Table 1.40

riks.axial.realstiff.chap19.opm

CHAPTER 19 Do wide-column inter-ring buckling analysis with possibly locally postbuckled skin-stringer module model. (See Figs. 20c, 22c, 46d, and 67 of [1A], for examples.).

*** BEGIN SUBROUTINE BUCKLE (WIDE-COLUMN BUCKLING - MODULE) ***
*** END SUBROUTINE BUCKLE (WIDE-COLUMN BUCKLING - MODULE) ***

*** BEGIN SUBROUTINE MODE (WIDE-COLUMN BUCKLING MODE SHAPE) ***
NUMBER OF AXIAL HALFWAVES = 1
AMPLITUDE OF BUCKLING MODE AT STRINGER BASE, WSTR = 8.8045E-01
AMPLITUDE OF BUCKLING MODE BETWEEN STRINGERS, WSKIN = 1.0000E+00
RATIO OF BUCKLING MODAL DISPLACEMENTS, WSTR/WSKIN = 8.8045E-01
AMPLIT.OF BUCKLING MODE AT STRINGER WEB TIP, WTIP = 7.9258E-18
AMPLIT.OF BUCKLING MODE AT STRINGER MIDWEB, WMID = 2.0203E-18
*** END SUBROUTINE MODE (WIDE-COLUMN BUCKLING MODE SHAPE) ***

WIDE COLUMN BUCKLING (DISCRETE MODULE MODEL) = 1.3470E+00
WIDE COLUMN BUCKLING (PANDA-TYPE MODEL) = 1.2706E+00
DISCRETE MODEL BEING SET EQUAL TO PANDA-TYPE MODEL.

WIDE COLUMN PANEL BUCKLING LOAD FACTOR = 1.2706E+00
~~ISKIN = 0~~. WIDE COLUMN BUCKLING IS IGNORED IF ISKIN = 1.
~~IWIDE = 0~~. WIDE COLUMN BUCKLING IS IGNORED IF IWIDE = 0.
ITIP = 0. MODE OF BUCKLING IS STRINGER SIDESWAY IF ITIP=1
*** END OF WIDE COLUMN BUCKLING CALCULATIONS ***

we do not use the "wide column"
model in this case.

Table 1.41

riks.axial.realstiff.chap20.opm

```
*****
CHAPTER 20 Compute width-wise wide column buckling and
lateral-torsional buckling load factors from the
possibly locally postbuckled skin-stringer module
model (inter-ring buckling modes).
See panda2.news Item Numbers 379 and 381 in [1L].
```

EXPLANATION OF FOLLOWING CALC. (LOAD SET NO. 1):

Next, the load factor for $m=??$ lateral-torsional buckling is computed from the discretized panel module model. The analysis takes into account local deformation of the panel module cross section, the redistribution of axial stress resultants N_x over the discretized module cross section, and the axial "softening" of a locally post-buckled skin-stringer discretized module.

Effective axial length of the panel, AXLEN2= 5.0000E+01
 LATERAL-TORSIONAL BUCKLING: Search for critical load...

Number of axial halfwaves= 1; Buckling load factor= 2.4724E+00 ←

NUMBER OF AXIAL HALFWAVES = 1
 AMPLITUDE OF BUCKLING MODE AT STRINGER BASE, WSTR = 9.5198E-09
 AMPLITUDE OF BUCKLING MODE BETWEEN STRINGERS, WSKIN = 1.0000E+00
 RATIO OF BUCKLING MODAL DISPLACEMENTS, WSTR/WSKIN = 9.5198E-09
 AMPLIT.OF BUCKLING MODE AT STRINGER WEB TIP, WTIP = 7.3842E-01
 AMPLIT.OF BUCKLING MODE AT STRINGER MIDWEB, WMID = 3.7471E-01
 Number of axial halfwaves= 2; Buckling load factor= 1.3509E+00 ←

NUMBER OF AXIAL HALFWAVES = 2
 AMPLITUDE OF BUCKLING MODE AT STRINGER BASE, WSTR = 3.6169E-13
 AMPLITUDE OF BUCKLING MODE BETWEEN STRINGERS, WSKIN = 1.0000E+00
 RATIO OF BUCKLING MODAL DISPLACEMENTS, WSTR/WSKIN = 3.6169E-13
 AMPLIT.OF BUCKLING MODE AT STRINGER WEB TIP, WTIP = 6.4926E-01
 AMPLIT.OF BUCKLING MODE AT STRINGER MIDWEB, WMID = 3.3092E-01
 Number of axial halfwaves= 3; Buckling load factor= 1.1078E+00 ←

NUMBER OF AXIAL HALFWAVES = 3
 AMPLITUDE OF BUCKLING MODE AT STRINGER BASE, WSTR = 6.5310E-16
 AMPLITUDE OF BUCKLING MODE BETWEEN STRINGERS, WSKIN = 1.0000E+00
 RATIO OF BUCKLING MODAL DISPLACEMENTS, WSTR/WSKIN = 6.5310E-16
 AMPLIT.OF BUCKLING MODE AT STRINGER WEB TIP, WTIP = 5.3484E-01
 AMPLIT.OF BUCKLING MODE AT STRINGER MIDWEB, WMID = 2.7472E-01
 Number of axial halfwaves= 4; Buckling load factor= 9.9091E-01 ←

NUMBER OF AXIAL HALFWAVES = 4
 AMPLITUDE OF BUCKLING MODE AT STRINGER BASE, WSTR = 4.2289E-16
 AMPLITUDE OF BUCKLING MODE BETWEEN STRINGERS, WSKIN = 1.0000E+00
 RATIO OF BUCKLING MODAL DISPLACEMENTS, WSTR/WSKIN = 4.2289E-16
 AMPLIT.OF BUCKLING MODE AT STRINGER WEB TIP, WTIP = 4.2514E-01
 AMPLIT.OF BUCKLING MODE AT STRINGER MIDWEB, WMID = 2.2090E-01
 Margin= 7.0817E-03 (m=3 lateral-torsional buckling load factor)/(FS)-1; FS=1.1 } This mode is
 *** THE LATERAL-TORSIONAL BUCKLING MARGIN JUST COMPUTED:
 $(m=3 \text{ lateral-torsional buckling load factor})/(FS)-1; FS=1.1$

***** CONSTRAINT NO. 7; LOAD SET NO. 1; SUBCASE NO. 1
 LATERAL-TORSIONAL BUCKLING LOAD FACTOR = 1.1078E+00
 *** END OF LATERAL-TORSIONAL BUCKLING CALCULATIONS ***

} Judged by PANDA2

To be a form of
 local skin buckling
 rather than "lateral-
 torsional" buckling
 because the stringer
 tip sideways (WTIP)
 is less than 1/2 the
 amplitude of the skin
 deflection, WSKIN.

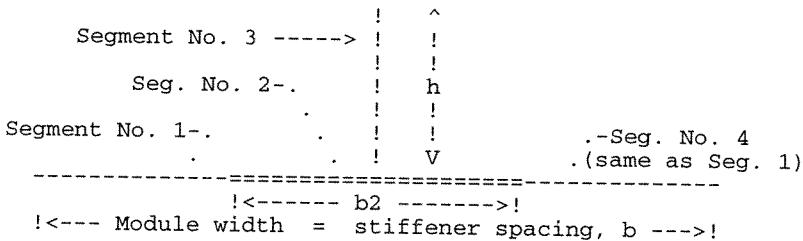
Table 1.42

riks.axial.realstiff.chap23.opm

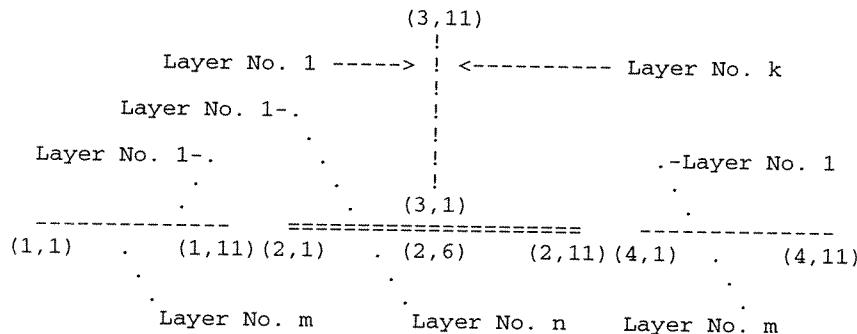
CHAPTER 23 Compute stresses in layers and at various locations in modules for both positive and negative imperfection amplitudes from SUBROUTINE STRCON (local postbuckling neglected). See [1L] (panda2.news) Items 36b,d,w, 41b, and Section E of Table 122.6 in Item 122.

***** BEGIN SUBROUTINE STRCON (IQUICK = 1 TYPE STRESSES) *****
External Stringer

MODULE WITH RECTANGULAR STIFFENER...



EXPLODED VIEW, SHOWING LAYERS and (SEGMENT, NODE) NUMBERS



Start calculation of stresses in the panel module depicted above...

(Segment numbering below refers to the **TOPMOST** of the sketches above.)
SEG.NODE LAYER THICKNESS WINDING IN-PLANE STRESSES IN MATL COORDS.

NO.	NO.	COORDINATE CRACKING	ANGLE STRESS (z)	SIG1 (deg)	SIG2	SIG12	STATUS	FAILURE	MODE OF
0									(1..)

0 means inactive)

positive imperfection factor

skin-stringer module stresses:

Stresses from sinxsiny or cosx cosy deformations (at peaks and valleys):

SKN 1	1	-3.2102E-02	0.0000E+00	-8.6601E+02	8.8840E+03	7.7878E+01	OK	no failur»
e	1.000		1					

SKN 1	1	3.2102E-02	0.0000E+00	-1.8634E+04	-8.8840E+03	7.7878E+01	OK	no failur»
e	1.000		1					

Stresses from sinxcosy or cosxsiny deformations (at nodal lines):

SKN 1	1	-3.2102E-02	0.0000E+00	-9.7500E+03	4.4796E-04	-4.7058E+03	OK	no failur»
e	1.000		1					

SKN 1	1	3.2102E-02	0.0000E+00	-9.7500E+03	4.4796E-04	4.8616E+03	OK	no failur»
e	1.000		1					

STR 2	1	-3.2102E-02	0.0000E+00	-9.7500E+03	4.4796E-04	-4.7058E+03	OK	no failur»
e	1.000		1					

STR 2	1	3.2102E-02	0.0000E+00	-9.7500E+03	4.4796E-04	4.8616E+03	OK	no failur»
e	1.000		1					

STR 3	ROOT 1	0.0000E+00	0.0000E+00	-9.7500E+03	-1.9169E-04	2.4992E-05	OK	no failur»
e	1.000		2					

STR 3	TIP 1	0.0000E+00	0.0000E+00	-9.7500E+03	1.9210E-04	2.4992E-05	OK	no failur»
e	1.000		2					

negative imperfection factor
skin-stringer module stresses:

Stresses from sinxsiny or cosx cosy deformations (at peaks and valleys):

SKN 1	1	-3.2102E-02	0.0000E+00	-1.8634E+04	-8.8840E+03	7.7878E+01	OK	no failur»
e	1.000		1					

SKN 1	1	3.2102E-02	0.0000E+00	-8.6601E+02	8.8840E+03	7.7878E+01	OK	no failur»
e	1.000		1					

Table 1.42 (end)

Stresses from sinxcosy or cosxsiny deformations (at nodal lines):

SKN	1	1	-3.2102E-02	0.0000E+00	-9.7500E+03	4.4796E-04	4.8616E+03	OK	no failur»	
e			1.000		1					
SKN	1	1	3.2102E-02	0.0000E+00	-9.7500E+03	4.4796E-04	-4.7058E+03	OK	no failur»	
e			1.000		1					
STR	2	1	-3.2102E-02	0.0000E+00	-9.7500E+03	4.4796E-04	4.8616E+03	OK	no failur»	
e			1.000		1					
STR	2	1	3.2102E-02	0.0000E+00	-9.7500E+03	4.4796E-04	-4.7058E+03	OK	no failur»	
e			1.000		1					
STR	3	ROOT	1	0.0000E+00	0.0000E+00	-9.7500E+03	-1.9169E-04	2.4992E-05	OK	no failur»
e			1.000		2					
STR	3	TIP	1	0.0000E+00	0.0000E+00	-9.7500E+03	1.9210E-04	2.4992E-05	OK	no failur»
e			1.000		2					

Margin= 6.0943E+01 eff.stress:matl=1,SKN,Iseg=1,allnode,layer=1,z=-0.0321;-MID.;FS=1.
 Margin= 5.1539E+00 eff.stress:matl=2,STR,Iseg=3,at:TIP,layer=1,z=0.;-MID.;FS=1.
 ***** END SUBROUTINE STRCON (IQUICK = 1 TYPE STRESSES) *****
 **** END OF STRESS CALCULATIONS ***

Table 1.43

riks.axial.realstiff.chap25.opm

```
*****
CHAPTER 25 Compute buckling load factors from PANDA-type
theory for the various segments of a stringer and
a ring. Typical buckling modes are displayed in
Figs. 5 and 6 of Ref.[1B].
```

```
***** BEGIN SUBROUTINE STFEIG (BUCKLING IN STIFFENERS) *****
ENTERING STFEIG: MIDEND= 1
IMOD= 0, Wavenumbers: MSKIN= 5, NSKIN= 1
```

STRINGER:

*** BUCKLING (short wavelength buckling) of parts of the panel module cross section perpendicular to generator ***

NOTE: The segment numbering scheme used here corresponds to that used when the user provides input data. It may differ from that used for the discretized module model.

Please see ITEM 272 in the file panda2/doc/panda2.news.

STIFFENER	MODULE	PRELOAD	RESULTANT	BUCKLING	BUCKLING	NO. OF BUCKLING	»
-----------	--------	---------	-----------	----------	----------	-----------------	---

COMMENT							
TYPE	SEGMENT	RESULTANT	FROM LOAD (LOAD SET B)	LOAD FACTOR SET A (no transverse (average))	LOAD FACTOR (with transverse (ave.))	HALFWAVES BETWEEN STIFFENERS	

Prebuck.resultant along stringer axis at root and tip of web:

At root of web: -2.4983E+03; At tip of web: -2.4748E+03

Knockdown factor to account for in-plane shearing of web and any anisotropic properties of the web, FKNOCK(5)= 1.0000E+00

Entering CRIPL:

Eigenvalue preload at web root and tip= -2.4983E+03 -2.4748E+03
Fixed preload at web root and tip= 0.0000E+00 0.0000E+00

M = SQRT(SQRT((EFOUND+C(5,5)*FACT**2)/C(4,4)))*A0/3.1415927= 5

IN SUB. ENDBUK: EIG= 2.2915E+00

In CRIPL, before SHRDL: LAMBDA, SHRLOD, T, GT(1), GT(2)=

2.2915E+00 -2.4894E+03 1.8147E-01 3.8460E+06 3.8460E+06

ISEG, ISRIDY, NMINSR, NWAVE, NMAXSR, FKNOCK= 3 1 6 5 8 1.0000E+00

NOTE: If FKNOCK is less than 0.99 the stringer web buckling WILL be recorded as a margin even if the critical number of axial halfwaves lies within the range, NMINSR - NMAXSR

Margin= 1.2915E+00 buckling margin stringer Iseg.3 . Local halfwaves=5 .MID.;FS=1.
stringer 3 0.0000E+00 -2.4894E+03 2.2915E+00 5

Note: no overall axial bending in the PANDA2 model in this case

RING:

```
***** END SUBROUTINE STFEIG (BUCKLING IN STIFFENERS) *****
LABEL NO. IN STRUCT= 9565
```

```
***** BEGIN SUBROUTINE STFEIG (NO POSTBUCKLING EFFECT) *****
```

ENTERING STFEIG: MIDEND= 1
IMOD= 0, Wavenumbers: MSKIN= 5, NSKIN= 1

STRINGER:

*** BUCKLING (short wavelength buckling) of parts of the panel module cross section perpendicular to generator ***

NOTE: The segment numbering scheme used here corresponds to that used when the user provides input data. It may differ from that used for the discretized module model.

Please see ITEM 272 in the file panda2/doc/panda2.news.

STIFFENER	MODULE	PRELOAD	RESULTANT	BUCKLING	BUCKLING	NO. OF BUCKLING	»
-----------	--------	---------	-----------	----------	----------	-----------------	---

COMMENT							
TYPE	SEGMENT	RESULTANT	FROM LOAD (LOAD SET B)	LOAD FACTOR SET A (no transverse (average))	LOAD FACTOR (with transverse (ave.))	HALFWAVES BETWEEN STIFFENERS	

Prebuck.resultant along stringer axis at root and tip of web:

At root of web: -1.7694E+03; At tip of web: -1.7694E+03

Knockdown factor to account for in-plane shearing of web and any anisotropic properties of the web, FKNOCK(5)= 1.0000E+00

Entering CRIPL:

Eigenvalue preload at web root and tip= -1.7694E+03 -1.7694E+03

neglecting effect of local post-buckling of panel skin

less load in stringer because of neglect of load shedding by post-buckled skin.

Table 1.43(end)

Fixed preload at web root and tip= 0.0000E+00 0.0000E+00
M = SQRT(SQRT((EFOUND+C(5,5)*FACT**2)/C(4,4)))*A0/3.1415927= 5
IN SUB. ENDBUK: EIG= 3.2126E+00
In CRIPL, before SHRRED: LAMBDA, SHRLOD, T, GT(1), GT(2)=
3.2126E+00 -1.7694E+03 1.8147E-01 3.8460E+06 3.8460E+06
ISEG, ISRIDY, NMINSR, NWAVE, NMAXSR, FKNOCK= 3 1 6 5 8 1.0000E+00
NOTE: If FKNOCK is less than 0.99 the stringer web buckling
WILL be recorded as a margin even if the critical number
of axial halfwaves lies within the range, NMINSR - NMAXSR
Margin= 2.2126E+00 buckling margin stringer Iseg.3 . Local halfwaves=5 .NOPO;FS=1.
stringer 3 0.0000E+00 -1.7694E+03 3.2126E+00 5

RING:

***** END SUBROUTINE STFEIG (NO POSTBUCKLING EFFECT) *****
*** END OF STIFFENER SEGMENT BUCKLING (if any) ***

Table 1.44

riks.axial.realstiff.chap26.opm

```
*****
CHAPTER 26 Compute local, inter-ring, general buckling load
factors from PANDA-type models [1B] and from
"alternative" (double-trigonometric series
expansion) models, Ref.[1G]. Also compute
sandwich wall behavior [1F], if applicable.
```

```
*** BEGIN SUBROUTINE BUCPAN (PANDA-TYPE BUCKLING LOADS) ***
```

```
Local buckling, C11= 2.3544E+05, radius, R= 7.0711E+05
***** ENTERING GENSTB: PANDA-type buckling model *****
PANDA-type buckling theory is described in the journal paper:
D. Bushnell, "Theoretical basis of the PANDA computer program"
Computers & Structures, Vol. 27, No. 4, pp. 541-563, 1987
Also see Items 415 and 443 in ...panda2/doc/panda2.news.
Initial imperfections for general, panel, local buckling=
Total out-of-roundness + modal, W0GLOB = 1.0000E-10
Out-of-roundness, WG1 = 0.0000E+00
General buckling modal, WG2 = 0.0000E+00
Inter-ring buckling modal, W0PAN = 1.0000E-10
Local buckling modal, W0LOC = 1.0000E-02
***** NOTE: Panel is modelled as if it were flat. *****
***** Donnell theory is used in this section (ISAND=0)
```

```
Load Set A: Nx, Ny, Nxy= -3.0561E+02 2.1273E-05 5.0000E+00
Load Set B: Nx0, Ny0, Nxy0= 0.0000E+00 0.0000E+00 0.0000E+00
```

```
Test for direction panel is long: TEST=(A/B)*SQRT(C55N/(C44N*C44MLT))=5.00E+00
If TEST > 0.99 then d = 0; c = SLOPE (panel is long in x-direction, Fig.(9a).
If TEST < 0.99 then d = SLOPE; c = 0. (panel is long in y-direction, Fig.(9b).
See Eq. (51) and Fig. 9 of "Theoretical basis..." paper (1987).
```

```
EIGMNC= 6.58E-01 1.00E+17 3.13E-01 1.00E+17 1.00E+17 2.11E+00 1.00E+17
SLOPEX= 2.00E-02 0.00E+00 1.00E-02 0.00E+00 0.00E+00 7.00E-02 0.00E+00
MWAVEEX= 2 0 5 0 0 1 0
NWAVEEX= 1 0 1 0 0 1 0
TESTX = 5.00E+00 0.00E+00 5.00E+00 0.00E+00 0.00E+00 5.00E+00 0.00E+00
Before refinement (before CALL EIG), EIGVAL,CSLOPE= 3.1303E-01 1.0000E-02
After refinement (after CALL EIG), EIGVAL,CSLOPE= 3.1303E-01 1.0000E-02
NOTE: The buckling nodal line slopes, SLOPEX, are as
defined in Fig. 9a or Fig. 9b of the 1987 "Theoretical
basis of the PANDA...", if NWAVEEX > 0; that is, there
has not yet been any inversion of SLOPEX when 9b holds.
```

```
LOCAL BUCKLING FROM PANDA-TYPE THEORY [1B] AFTER KNOCKDOWN FOR t.s.d.:
EIGLOC = 3.1303E-01(m= 5,n= 1)
```

```
general buckling: smeared stiffeners, C11= 7.2614E+05, radius, R= 7.0711E+05
***** ENTERING GENSTB: PANDA-type buckling model *****
***** Donnell theory is used in this section (ISAND=0)
Load Set A: Nx, Ny, Nxy= -1.0000E+03 0.0000E+00 5.0000E+00
Load Set B: Nx0, Ny0, Nxy0= 0.0000E+00 0.0000E+00 0.0000E+00
EIGMNC= 1.52E+00 1.80E+00 1.52E+00 1.00E+17 1.00E+17 1.52E+00 1.00E+17
SLOPEX= 0.00E+00 0.00E+00 0.00E+00 0.00E+00 0.00E+00 0.00E+00 0.00E+00
MWAVEEX= 1 1 1 0 0 1 0
NWAVEEX= 1 2 1 0 0 1 0
TESTX = 2.61E-02 2.61E-02 2.61E-02 0.00E+00 0.00E+00 2.61E-02 0.00E+00
Before refinement (before CALL EIG), EIGVAL,CSLOPE= 1.5164E+00 0.0000E+00
After refinement (after CALL EIG), EIGVAL,CSLOPE= 1.5164E+00 0.0000E+00
```

```
General buckling loads AFTER knockdown for t.s.d.
Number of circumferential halfwaves in buckling pattern= 1.0000E+00
Buckling load factor BEFORE knockdown for smeared stringers= 1.5164E+00
Buckling load factor AFTER knockdown for smeared stringers= 1.0994E+00
```

```
General buckling load factor before and after knockdown:
EIGGEN(before modification by 5 factors below) = 1.0994E+00
Knockdown factor from modal imperfection(s) = 1.0000E+00
Knockdown factor for smearing rings on cyl. shell = 1.0000E+00
Knockup factor to avoid twice accounting for t.s.d.= 1.0000E+00
1st modifying factor, FKNMOD=1 or 1/(EIG9X*FMDK9) = 1.0000E+00
2nd modifying factor, EIGMR9=1 or EIGGNX/EIGGEN = 1.0000E+00
After knockdn, EIGGEN*FKNOCK(9)*(RNGKNK/SHRFCT)*FKNMOD*EIGMR9= 1.0994E+00
in which
EIG9X = lambda(ARBOCZ)/lambda(original PANDA-type theory)= 1.0000E+00
```

lowest eigenvalue
& mode shape for
local buckling

lowest
eigenvalue &
mode shape
for general
buckling

Table 1.44 (end)

lambda(ARBOCZ) = perfect panel buckling from ARBOCZ theory
lambda(PANDA) = perfect panel buckling from PANDA theory

FMDKD9 = 1 or 0.9/EIG9X = 0.0000E+00

EIGGNX = eigenvalue for perfect panel from alternate solution

→ 12 1.09942E+00 buckling load factor simp-support general buck;M=1;N=1;slope=0.
Margin= -5.2321E-04 buck.(DONL);simp-support general buck;M=1;N=1;slope=0.;FS=1.1

Table 1.45

riks.axial.realstiff.chap28.opm

CHAPTER 28 Present design, loading, and margins for the current load set and subcase. See Table 6 in Bushnell, D.

"Optimization of an axially compressed ring and stringer stiffened cylindrical shell with a general buckling modal imperfection", AIAA Paper 2007-2216, 48th AIAA SDM Meeting, Honolulu, Hawaii, April 2007

0

SUMMARY OF INFORMATION FROM OPTIMIZATION ANALYSIS									
VAR.	DEC.	ESCAPE	LINK.	LINKING	LOWER CURRENT	UPPER	DEFINITION		
NO.	VAR.	VAR.	TO	CONSTANT	BOUND	VALUE	BOUND		
1	N	N	N	0	0.00E+00	0.00E+00	1.0000E+01	0.00E+00	B(STR):stiffener s»
pacing, b:	STR	seg=NA,	layer=NA						
2	N	N	N	0	0.00E+00	0.00E+00	3.0000E+00	0.00E+00	B2(STR):width of st»
ringer base, b2 (must be > 0, see									
3	Y	N	N	0	0.00E+00	2.00E-01	2.1139E+00	1.00E+01	H(STR):height of s»
tiffener (type H for sketch), h:									
4	Y	Y	N	0	0.00E+00	1.00E-02	6.4203E-02	1.00E+00	T(1)(SKN):thickness f»
or layer index no.(1): SKN seg=1									
5	Y	Y	N	0	0.00E+00	1.00E-02	1.8147E-01	1.00E+00	T(2)(STR):thickness f»
or layer index no.(2): STR seg=3									
BUCKLING LOAD FACTORS FOR LOCAL BUCKLING FROM KOITER v. BOSOR4 THEORY:									
Local buckling load factor from KOITER theory = 2.5843E-01 (flat skin)									
Local buckling load factor from BOSOR4 theory = 2.6252E-01 (flat skin)									

***** LOAD SET NO. 1 *****

ICASE = 1 (ICASE=1 MEANS PANEL MIDLENGTH)
(ICASE=2 MEANS PANEL ENDS)

APPLIED LOADS IN LOAD SET A ("eigenvalue" loads):

Applied axial stress resultant, Nx= -1.0000E+03
Applied circumferential stress resultant, Ny= 0.0000E+00
Applied in-plane shear resultant, Nxy= 5.0000E+00
Applied axial moment resultant, Mx= 0.0000E+00
Applied circumferential moment resultant, My= 0.0000E+00
Applied pressure (positive for upward), p = 0.0000E+00

APPLIED LOADS IN LOAD SET B (fixed uniform loads):

Applied axial stress resultant, Nx0= 0.0000E+00
Applied circumferential stress resultant, Ny0= 0.0000E+00
Applied in-plane shear resultant, Nxy0= 0.0000E+00

NOTE: "F.S." means "Factor of Safety";
"DONL" means "Donnell shell theory used.";
"SAND" means "Sanders shell theory used." panda2.news ITEM 128
"Dseg" means "Segment numbering used in discretized model"
"Iseg" means "Segment numbering used for input data." ITEM 272

0 MARGINS FOR CURRENT DESIGN: LOAD CASE NO. 1, SUBCASE NO. 1

NO.	VALUE	DEFINITION
1	3.13E-01	Local buckling from discrete model-1.. M=7 axial halfwaves;FS=0.2
2	2.92E-01	Local buckling from Koiter theory,M=7 axial halfwaves;FS=0.2
3	4.05E+01	eff.stress:matl=1,SKN,Dseg=2,node=6,layer=1,z=0.0321; MID.;FS=1.
4	1.29E+04	stringer popoff margin:(allowable/actual)-1, web 1 MID.;FS=1.
5	2.55E+00	eff.stress:matl=2,STR,Dseg=3,node=11,layer=1,z=0.0907; MID.;FS=1.
6	6.77E-03	Hi-axial-wave post-post-buckling of module - 1; M=14 ;FS=1.
7	7.08E-03	(m=3 lateral-torsional buckling load factor)/(FS)-1;FS=1.1
8	6.09E+01	eff.stress:matl=1,SKN,Iseg=1,allnode,layer=1,z=-0.0321;-MID.;FS=1
9	5.15E+00	eff.stress:matl=2,STR,Iseg=3,at:TIP,layer=1,z=0. ;-MID.;FS=1.
10	1.29E+00	buckling margin stringer Iseg.3 . Local halfwaves=5 .MID.;FS=1.
11	2.21E+00	buckling margin stringer Iseg.3 . Local halfwaves=5 .NOPO;FS=1.
12	-5.23E-04	buck.(DONL);simp-support general buck;M=1;N=1;slope=0.;FS=1.1
13	3.66E+00	buck.(DONL);rolling only of stringers;M=14;N=0;slope=0.;FS=1.4
14	7.25E+02	(Max.allowable ave.axial strain)/(ave.axial strain) -1; FS=1.
15	1.11E-01	0.3333 *(Stringer spacing, b) / (Stringer base width, b2)-1;FS=1.
16	-5.23E-04	buck.(SAND);simp-support general buck;M=1;N=1;slope=0.;FS=1.1
***** ALL 1 LOAD SETS PROCESSED *****		

See Table 1.35

"→" = "most critical margins"

0

SUMMARY OF INFORMATION FROM OPTIMIZATION ANALYSIS

VAR.	DEC.	ESCAPE	LINK.	LINKING	LOWER	CURRENT	UPPER	DEFINITION	
NO.	VAR.	VAR.	TO	CONSTANT	BOUND	VALUE	BOUND		
1	N	N	N	0	0.00E+00	0.00E+00	1.0000E+01	0.00E+00	B(STR):stiffener s»

Table 1.45 (end)

pacing, b: STR seg=NA, layer=NA
 2 N N N 0 0.00E+00 0.00E+00 3.0000E+00 0.00E+00 B2(STR):width of str
 ringer base, b2 (must be > 0, see 3 Y N N 0 0.00E+00 2.00E-01 2.1139E+00 1.00E+01 H(STR):height of str
 stiffener (type H for sketch), h:
 4 Y Y N 0 0.00E+00 1.00E-02 6.4203E-02 1.00E+00 T(1)(SKN):thickness f
 or layer index no.(1): SKN seg=1
 5 Y Y N 0 0.00E+00 1.00E-02 1.8147E-01 1.00E+00 T(2)(STR):thickness f
 or layer index no.(2): STR seg=3

***** DESIGN OBJECTIVE *****

0 CURRENT VALUE OF THE OBJECTIVE FUNCTION:

VAR. NO.	RNG NO.	SEG. NO.	CURRENT	DEFINITION
			VALUE	
0	0	2.564E+01	WEIGHT OF THE ENTIRE PANEL	

TOTAL WEIGHT OF SKIN = 1.6051E+01
 TOTAL WEIGHT OF SUBSTIFFENERS = 0.0000E+00
 TOTAL WEIGHT OF STRINGERS = 9.5903E+00
 TOTAL WEIGHT OF RINGS = 0.0000E+00
 SPECIFIC WEIGHT (WEIGHT/AREA) OF STIFFENED PANEL= 1.0256E-02

***** DESIGN OBJECTIVE *****

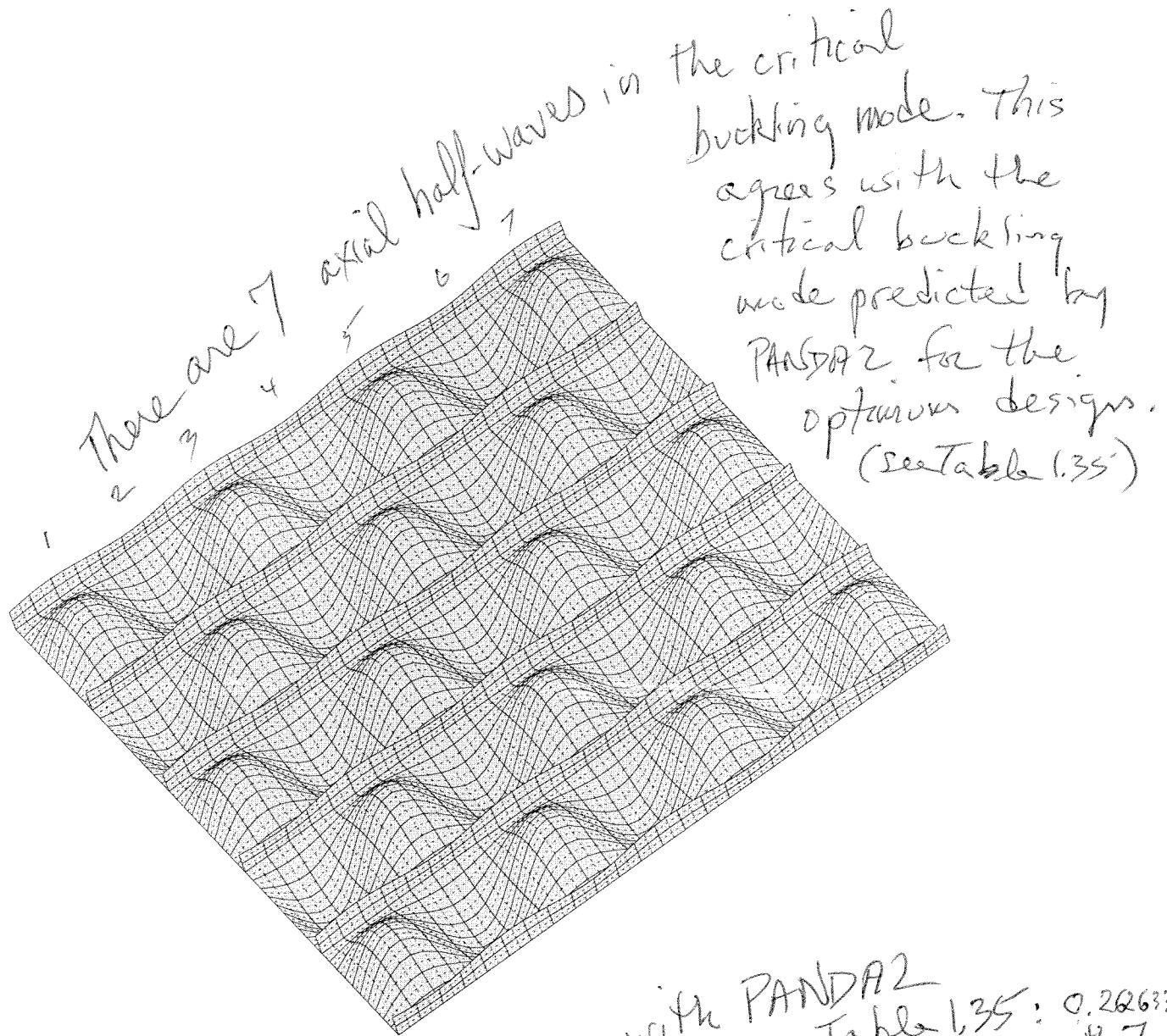
Table 1.46 riks. STG (riks. radial, real stiff, 3 bay, stg)
 (riks. linear, deformable edges, no stiff)

n	\$ Do you want a tutorial session and tutorial output?
1	\$ Choose type of STAGS analysis (1,3,4,5,6), INDIC
0	\$ Restart from ISTART load step (0=1st nonlinear soln), ISTART
0.2600000	\$ Local buckling load factor from PANDA2, EIGLOC
y	\$ Are the dimensions in this case in inches?
0	\$ Nonlinear (0) or linear (1) kinematic relations?, ILIN
0	\$ Type 1 for closed (360-deg) cyl. shell, 0 otherwise, ITOTAL
50	\$ X-direction length of the STAGS model of the panel: XSTAGS
50	\$ Panel length in the plane of the screen, L2
y	\$ Is the nodal point spacing uniform along the stringer axis?
51	\$ Number of nodes in the X-direction: NODEX
-1000.	\$ Resultant (e.g. lb/in) normal to the plane of screen, Nx
0	\$ Resultant (e.g. lb/in) in the plane of the screen, Ny
0	\$ In-plane shear in load set A, Nxy
0	\$ Normal pressure in STAGS model in Load Set A, p
0	\$ Resultant (e.g. lb/in) normal to the plane of screen, Nx0
0	\$ Resultant (e.g. lb/in) in the plane of the screen, Ny0
0	\$ Normal pressure in STAGS model in Load Set B, p0
1	\$ Starting load factor for Load System A, STLD(1)
0	\$ Load factor increment for Load System A, STEP(1)
1	\$ Maximum load factor for Load System A, FACM(1)
0	\$ Starting load factor for Load System B, STLD(2)
0	\$ Load factor increment for Load System B, STEP(2)
0	\$ Maximum load factor for Load System B, FACM(2)
1	\$ How many eigenvalues do you want? NEIGS
480	\$ Choose element type (410 or 411 or 480) for panel skin
n	\$ Have you obtained buckling modes from STAGS for this case?
6	\$ Number of stringers in STAGS model of the flat panel
0	\$ Number of rings in the STAGS model of the panel
n	\$ Are there rings at the ends of the panel?
10	\$ Number of finite elements between adjacent stringers
25	\$ Number of finite elements between adjacent rings
3	\$ Stringer model: 1 or 2 or 3 or 4 or 5 (Type H(elp))
3	\$ Ring model: 1 or 2 or 3 or 4 or 5 (Type H(elp))
0	\$ Reference surface of cyl: 1=outer, 0=middle, -1=inner
n	\$ Do you want to use fasteners (they are like rigid links)?
n	\$ Are the stringers to be "smeared out"?
y	\$ Are the rings to be "smeared out"?
5	\$ Number of nodes over height of stiffener webs, NODWEB
5	\$ Number of nodes over width of stringer flange, NDFLGS
5	\$ Number of nodes over width of ring flange, NDFLGR
n	\$ Do you want stringer(s) with a high nodal point density?
n	\$ Do you want ring(s) with a high nodal point density?
n	\$ Is there plasticity in this STAGS model?
n	\$ Do you want to use the "least-squares" model for torque?
n	\$ Is stiffener sidesway permitted at the panel edges?
n	\$ Do you want symmetry conditions along the straight edges?
0	\$ Edges normal to screen (0) in-plane deformable; (1) rigid

note

input for STAGSUNIT

output from STAGS processor, STAPL
 riks.linbuck.realstiff.shg.pdf



solution scale = 0.4334E+01
 mode 1, pcr = 0.25038E+00
 step 0 eigenvector deformed geometry
 linear buckling of perfect shell

compare with PANDA2 prediction listed in Table 1.35 : 0.262633
 with 7 axial halfwaves.

$\Theta_x -35.84$
 $\Theta_y -13.14$
 $\Theta_z 35.63$

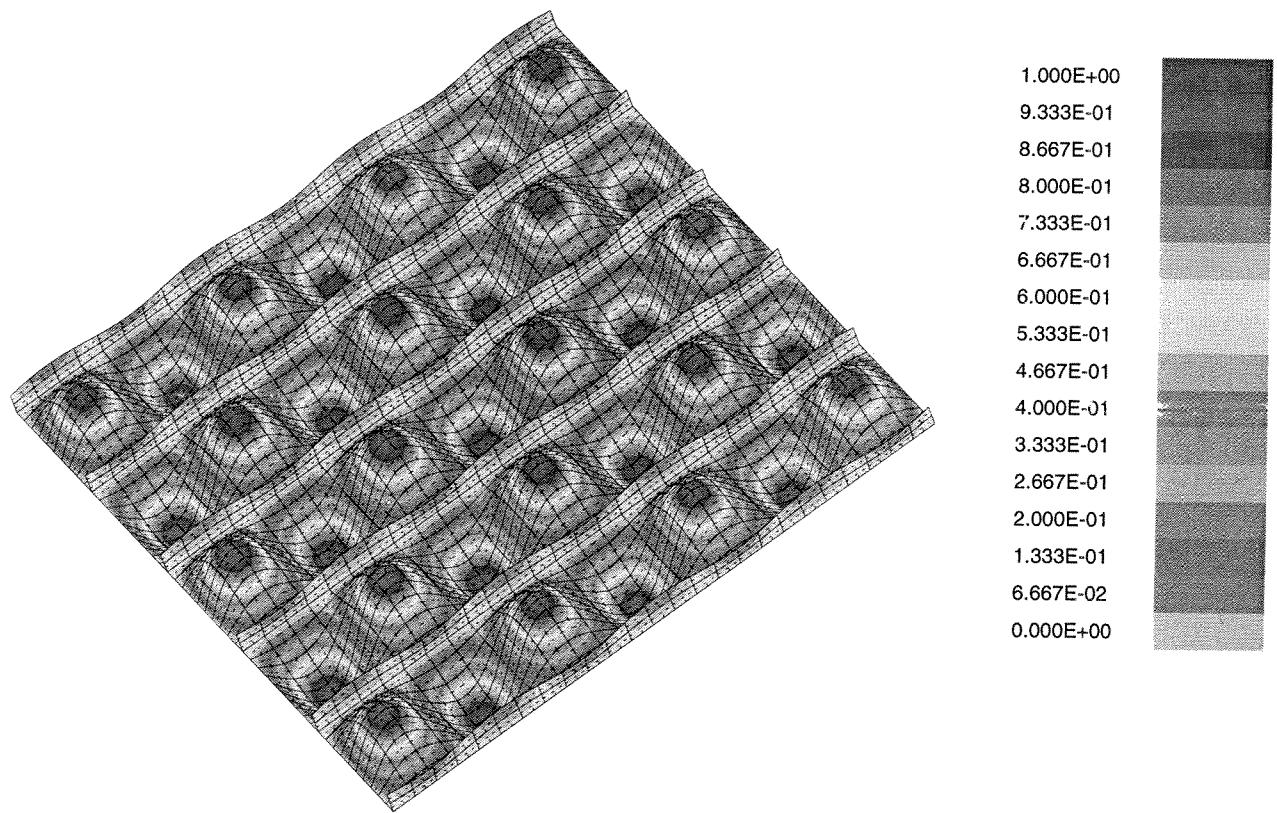
y z
 x
 ✓

132

1.140E+01

Fig. 1.43

riks.linbuck.realsuff.5bay.wfringe.pdf



solution scale = 0.4334E+01

mode 1, pcr = 0.25038E+00

step 0 eigenvector vecnlngthcontours

linear buckling of perfect shell,fringe plot of modal displacement

Minimum value = 0.00000E+00, Maximum value = 1.00000E+00

Θ_x -35.84
 Θ_y -13.14
 Θ_z 35.63

y z x

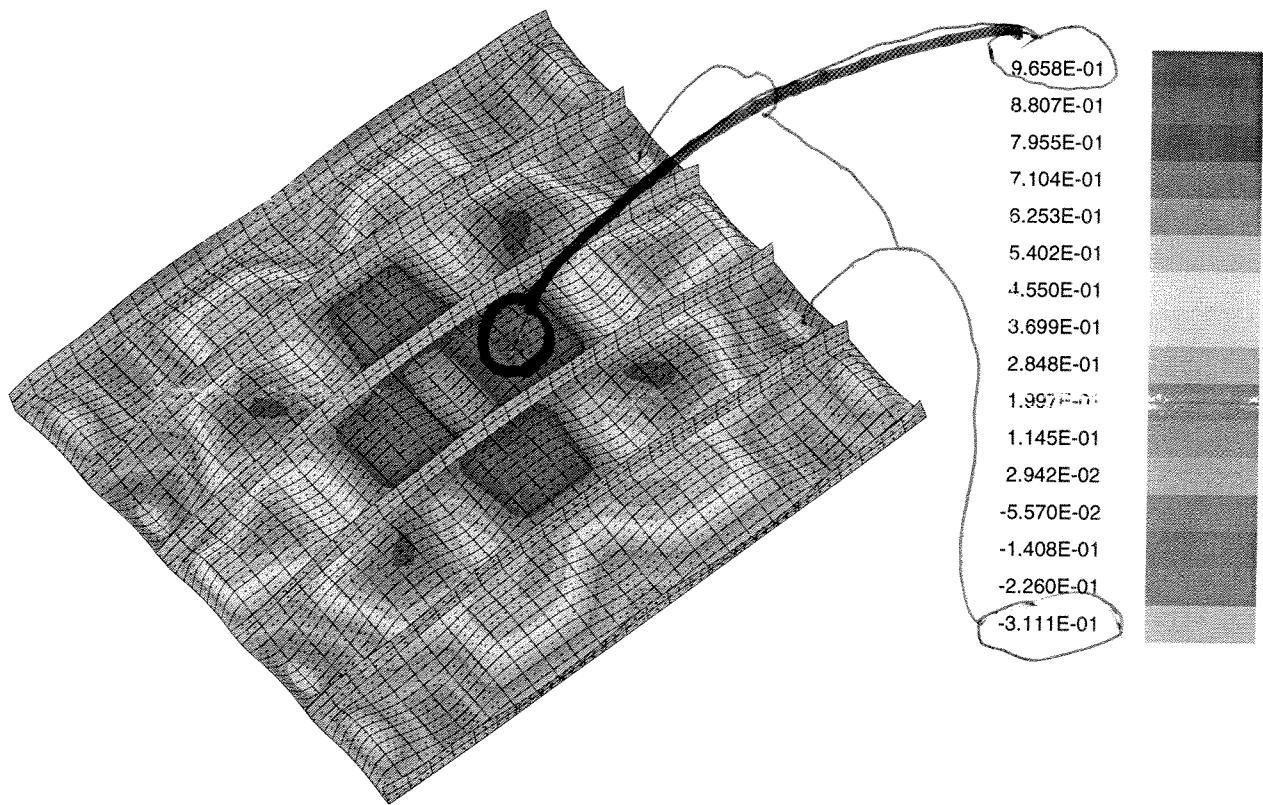
133

1.369E+01

Fig. 1.44

riks.postbuck.realstiff.5bay.step38.~~.pdf~~

Note: PANDA2 does not predict
the overall axial bowing
evident in this figure.



solution scale = 0.4264E+01

PA= 9.68825E-01 PB= 0.00000E+00 PX= 0.00000E+00

step 38 displacement w contours

nonlinear w same view as linear buckling mode

Minimum value = -3.11076E-01, Maximum value = 9.65784E-01

Θ_x -35.84
 Θ_y -13.14
 Θ_z 35.63

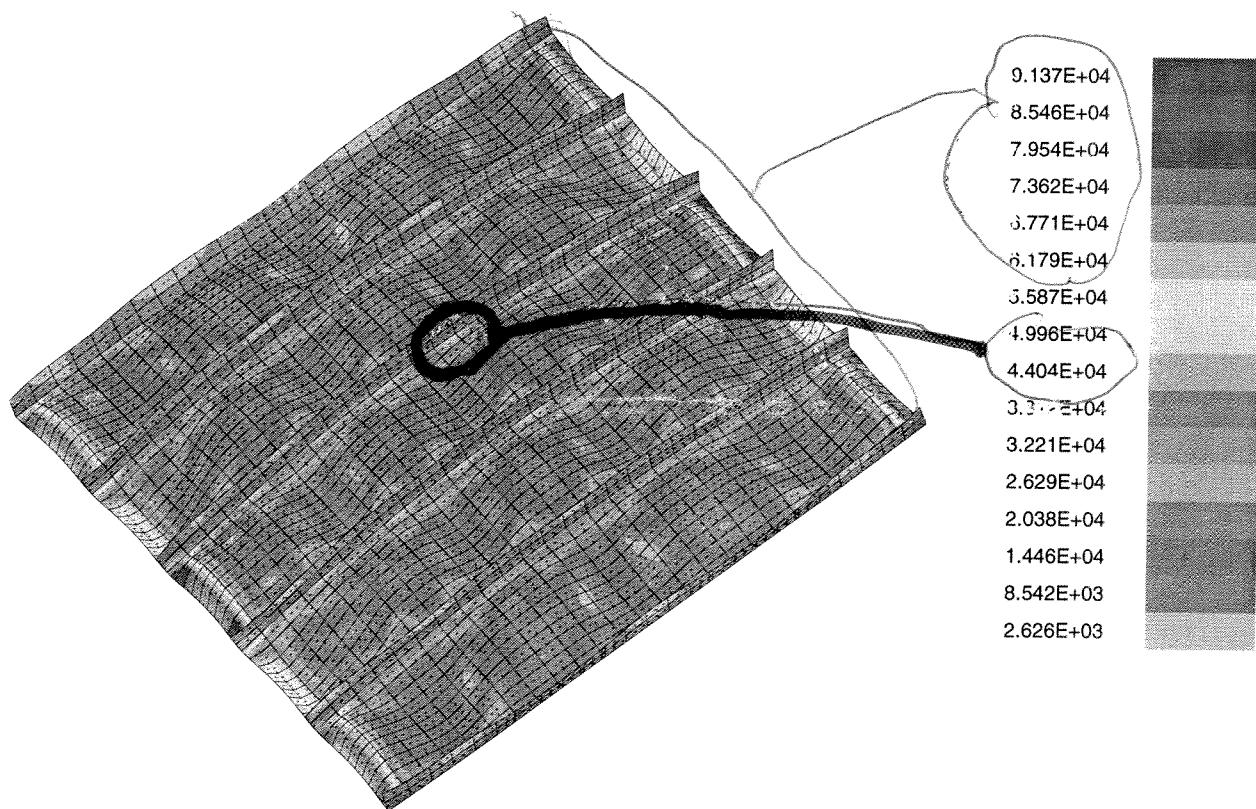
y z x

1.369E+01

134

Fig. 1.45

^{postbuck.}
 riks, realstiff, 5 bay, step 38, seffinnerfiber, pdf



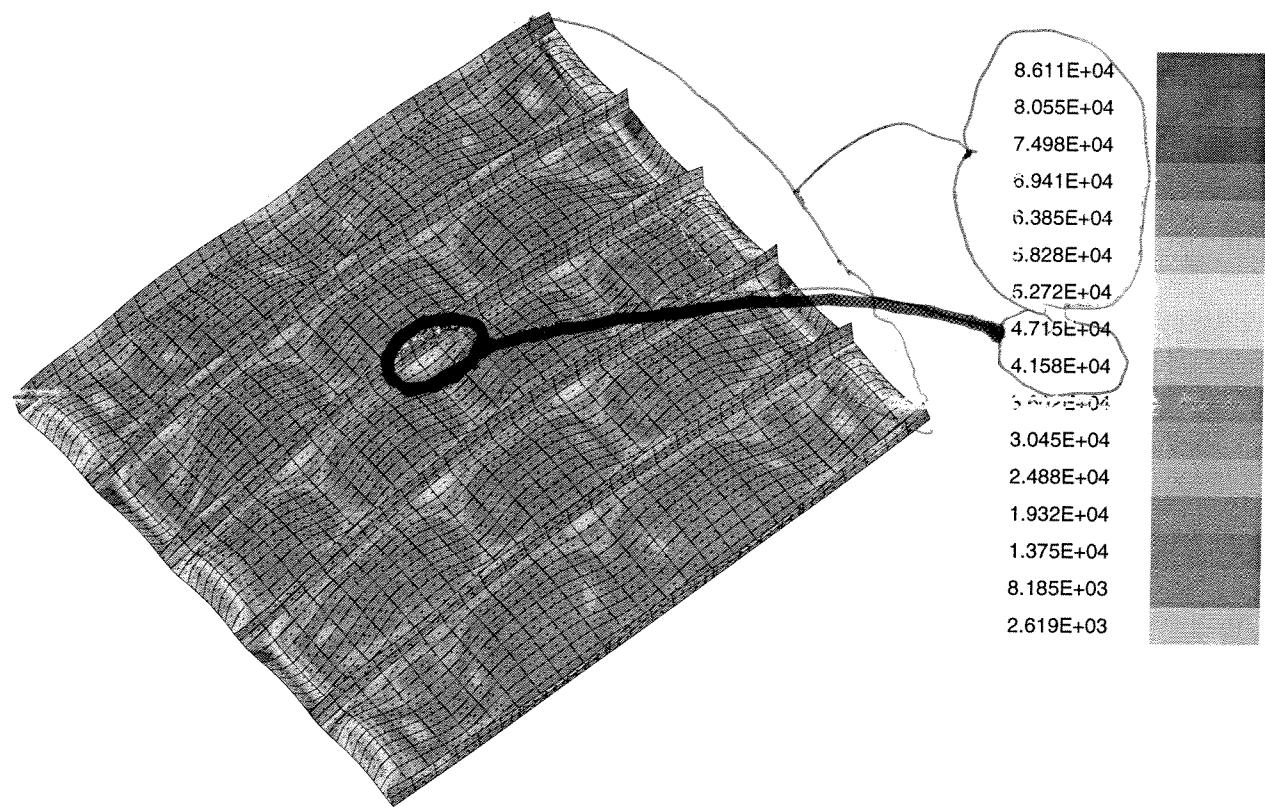
solution scale = 0.4264E+01
 PA= 9.68825E-01 PB= 0.00000E+00 PX= 0.00000E+00
 step 38 fabrication system ,seff, layer 1, inner fiber
 nonlinear effective stress - inner fiber same view a linear buckling mode
 Minimum value = 2.62592E+03, Maximum value = 9.13732E+04

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Θ_x -35.84 y z
 Θ_y -13.14 x
 Θ_z 35.63

Fig. 146

riks, postbuck, realstiff, 5bay, step38, seffouterfiber, pdf



solution scale = 0.4264E+01

PA= 9.68825E-01 PB= 0.00000E+00 PX= 0.00000E+00

step 38 fabrication system ,seff, layer 1, outer fiber

nonlinear effective stress - inner fiber same view a linear buckling mode

Minimum value = 2.61913E+03, Maximum value = 8.61127E+04

Θ_x -35.84
 Θ_y -13.14
 Θ_z 35.63

y z x

1.369E+01

outer
136

Fig. 1.97

riks.STG = riks.linear.rigidedges.stg Table 1.47

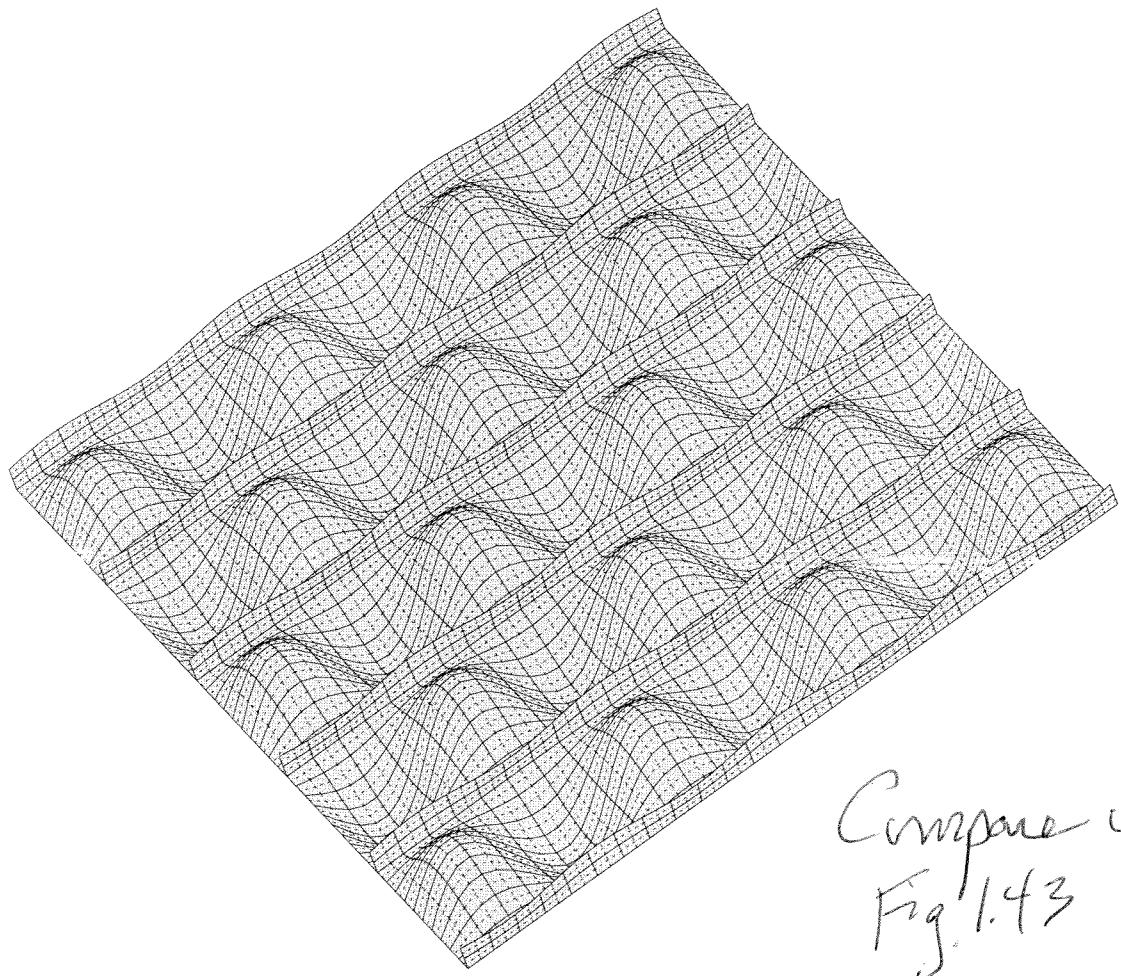
```

n      $ Do you want a tutorial session and tutorial output?
1      $ Choose type of STAGS analysis (1,3,4,5,6), INDIC
0      $ Restart from ISTARTth load step (0=1st nonlinear soln), ISTART
0.2600000 $ Local buckling load factor from PANDA2, EIGLOC
y      $ Are the dimensions in this case in inches?
0      $ Nonlinear (0) or linear (1) kinematic relations?, ILIN
0      $ Type 1 for closed (360-deg) cyl. shell, 0 otherwise, ITOTAL
50     $ X-direction length of the STAGS model of the panel: XSTAGS
50     $ Panel length in the plane of the screen, L2
y      $ Is the nodal point spacing uniform along the stringer axis?
51     $ Number of nodes in the X-direction: NODEX
-1000. $ Resultant (e.g. lb/in) normal to the plane of screen, Nx
0      $ Resultant (e.g. lb/in) in the plane of the screen, Ny
0      $ In-plane shear in load set A, Nxy
0      $ Normal pressure in STAGS model in Load Set A, p
0      $ Resultant (e.g. lb/in) normal to the plane of screen, Nx0
0      $ Resultant (e.g. lb/in) in the plane of the screen, Ny0
0      $ Normal pressure in STAGS model in Load Set B, p0
1      $ Starting load factor for Load System A, STLD(1)
0      $ Load factor increment for Load System A, STEP(1)
1      $ Maximum load factor for Load System A, FACM(1)
0      $ Starting load factor for Load System B, STLD(2)
0      $ Load factor increment for Load System B, STEP(2)
0      $ Maximum load factor for Load System B, FACM(2)
1      $ How many eigenvalues do you want? NEIGS
480    $ Choose element type (410 or 411 or 480) for panel skin
n      $ Have you obtained buckling modes from STAGS for this case?
6      $ Number of stringers in STAGS model of the flat panel
0      $ Number of rings in the STAGS model of the panel
n      $ Are there rings at the ends of the panel?
10     $ Number of finite elements between adjacent stringers
25     $ Number of finite elements between adjacent rings
3      $ Stringer model: 1 or 2 or 3 or 4 or 5 (Type H(elp))
3      $ Ring model: 1 or 2 or 3 or 4 or 5 (Type H(elp))
0      $ Reference surface of cyl: 1=outer, 0=middle, -1=inner
n      $ Do you want to use fasteners (they are like rigid links)?
n      $ Are the stringers to be "smeared out"?
y      $ Are the rings to be "smeared out"?
5      $ Number of nodes over height of stiffener webs, NODWEB
5      $ Number of nodes over width of stringer flange, NDFLGS
5      $ Number of nodes over width of ring flange, NDFLGR
n      $ Do you want stringer(s) with a high nodal point density?
n      $ Do you want ring(s) with a high nodal point density?
n      $ Is there plasticity in this STAGS model?
n      $ Do you want to use the "least-squares" model for torque?
n      $ Is stiffener sidesway permitted at the panel edges?
n      $ Do you want symmetry conditions along the straight edges?
1      $ Edges normal to screen (0) in-plane deformable; (1) rigid

```

Note

riks.linbuck.realstiff.5bay.rigidedges.pdf



Compare with
Fig. 1.43

solution scale = 0.4334E+01

mode 1, pcr = 0.25038E+00

step 0 eigenvector deformed geometry

linear buckling of perfect shell

$\Theta_x -35.84$
 $\Theta_y -13.14$
 $\Theta_z 35.63$

y z x

1.140E+01

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Fig. 1.48

riks, STG = riks, nonlinear, rigid edges, stg

Table 1.48

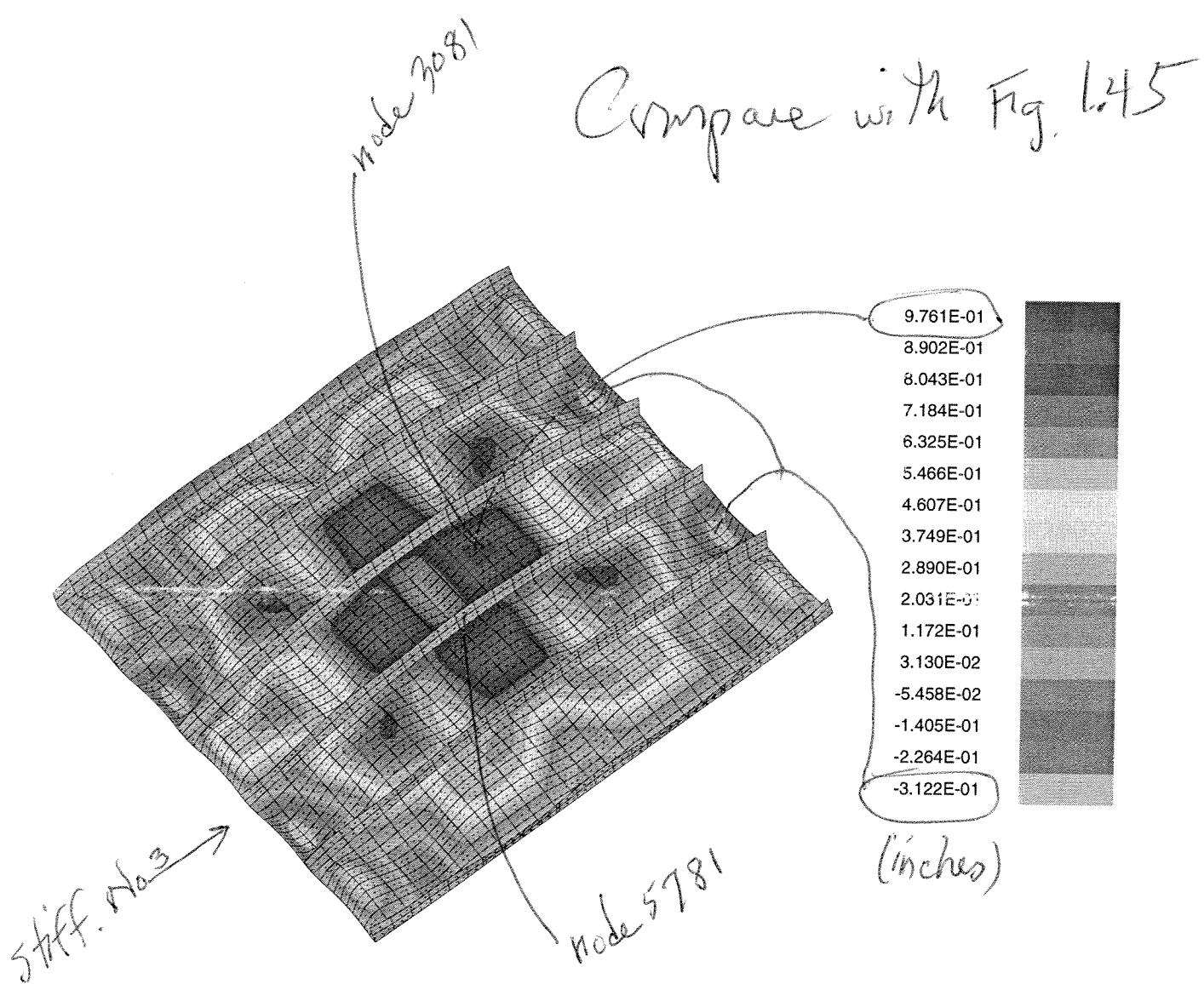
```

n      $ Do you want a tutorial session and tutorial output?
3      $ Choose type of STAGS analysis (1,3,4,5,6), INDIC
0      $ Restart from ISTARTth load step (0=1st nonlinear soln), ISTART
0.2600000 $ Local buckling load factor from PANDA2, EIGLOC
y      $ Are the dimensions in this case in inches?
0      $ Nonlinear (0) or linear (1) kinematic relations?, ILIN
0      $ Type 1 for closed (360-deg) cyl. shell, 0 otherwise, ITOTAL
50     $ X-direction length of the STAGS model of the panel: XSTAGS
50     $ Panel length in the plane of the screen, L2
y      $ Is the nodal point spacing uniform along the stringer axis?
51     $ Number of nodes in the X-direction: NODEX
-1000.000 $ Resultant (e.g. lb/in) normal to the plane of screen, Nx
0      $ Resultant (e.g. lb/in) in the plane of the screen, Ny
0      $ In-plane shear in load set A, Nxy
0      $ Normal pressure in STAGS model in Load Set A, p
0      $ Resultant (e.g. lb/in) normal to the plane of screen, Nx0
0      $ Resultant (e.g. lb/in) in the plane of the screen, Ny0
0      $ Normal pressure in STAGS model in Load Set B, p0
0.5000000E-01 $ Starting load factor for Load System A, STLD(1)
0.5000000E-01 $ Load factor increment for Load System A, STEP(1)
1.000000 $ Maximum load factor for Load System A, FACM(1)
0      $ Starting load factor for Load System B, STLD(2)
0      $ Load factor increment for Load System B, STEP(2)
0      $ Maximum load factor for Load System B, FACM(2)
1      $ How many eigenvalues do you want? NEIGS
480    $ Choose element type (410 or 411 or 480) for panel skin
y      $ Have you obtained buckling modes from STAGS for this case?
y      $ Do you want to provide initial imperfection(s)?
0.1000000E-01 $ Amplitude of initial buckling modal imperfection, WIMPL( 1)
1      $ Run number for which this buckling mode was computed, IRUN( 1)
0      $ Load step number at which this buckling mode was computed, ISTEP( 1)
1      $ Mode number at the load step ISTEP of the run IRUN: IMODE( 1)
n      $ Do you want to provide another imperfection?
6      $ Number of stringers in STAGS model of the flat panel
0      $ Number of rings in the STAGS model of the panel
n      $ Are there rings at the ends of the panel?
10     $ Number of finite elements between adjacent stringers
25     $ Number of finite elements between adjacent rings
3      $ Stringer model: 1 or 2 or 3 or 4 or 5(Type H(elp))
3      $ Ring model: 1 or 2 or 3 or 4 or 5 (Type H(elp))
0      $ Reference surface of cyl: 1=outer, 0=middle, -1=inner
n      $ Do you want to use fasteners (they are like rigid links)?
n      $ Are the stringers to be "smeared out"?
y      $ Are the rings to be "smeared out"?
5      $ Number of nodes over height of stiffener webs, NODWEB
5      $ Number of nodes over width of stringer flange, NDFLGS
5      $ Number of nodes over width of ring flange, NDFLGR
n      $ Do you want stringer(s) with a high nodal point density?
n      $ Do you want ring(s) with a high nodal point density?
n      $ Is there plasticity in this STAGS model?
n      $ Do you want to use the "least-squares" model for torque?
n      $ Is stiffener sidesway permitted at the panel edges?
n      $ Do you want symmetry conditions along the straight edges?
1      $ Edges normal to screen (0) in-plane deformable; (1) rigid

```



Riks, postbuck, realstiff, 5key, step26, rigidedges, pdf



solution scale = 0.4219E+01

PA= 9.71414E-01 PB= 0.00000E+00 PX= 0.00000E+00

step 26 displacement w contours

nonlinear w same view as linear buckling mode

Minimum value = -3.12245E-01, Maximum value = 9.76060E-01

Θ_x -35.84
 Θ_y -13.14
 Θ_z 35.63

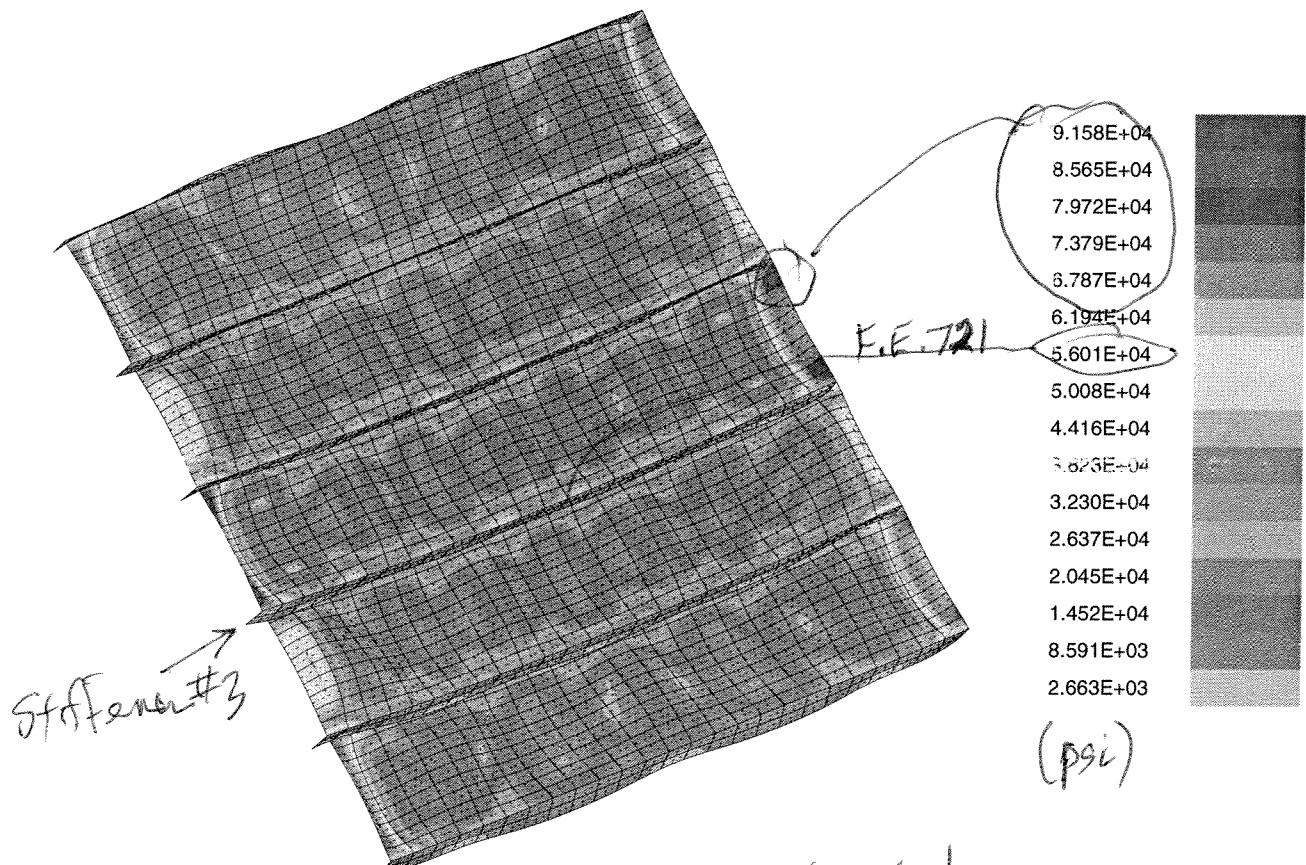
y z x

140

Fig. 1.49(a)

riks, postbuck, realstiff, 5bay, step26, rigidedges, seffinnerfiber, pdf

Compare with Fig. 1.46



solution scale = 0.3848E+01

PA= 9.70000E-01 PB= 0.00000E+00 PX= 0.00000E+00

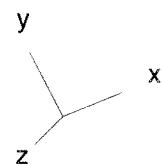
step 26 fabrication system ,seff, layer 1, inner fiber

nonlinear effective stress - inner fiber

Minimum value = 2.66314E+03, Maximum value = 9.15753E+04

Θ_x 24.00
 Θ_y -22.00
 Θ_z 30.00

1.283E+01

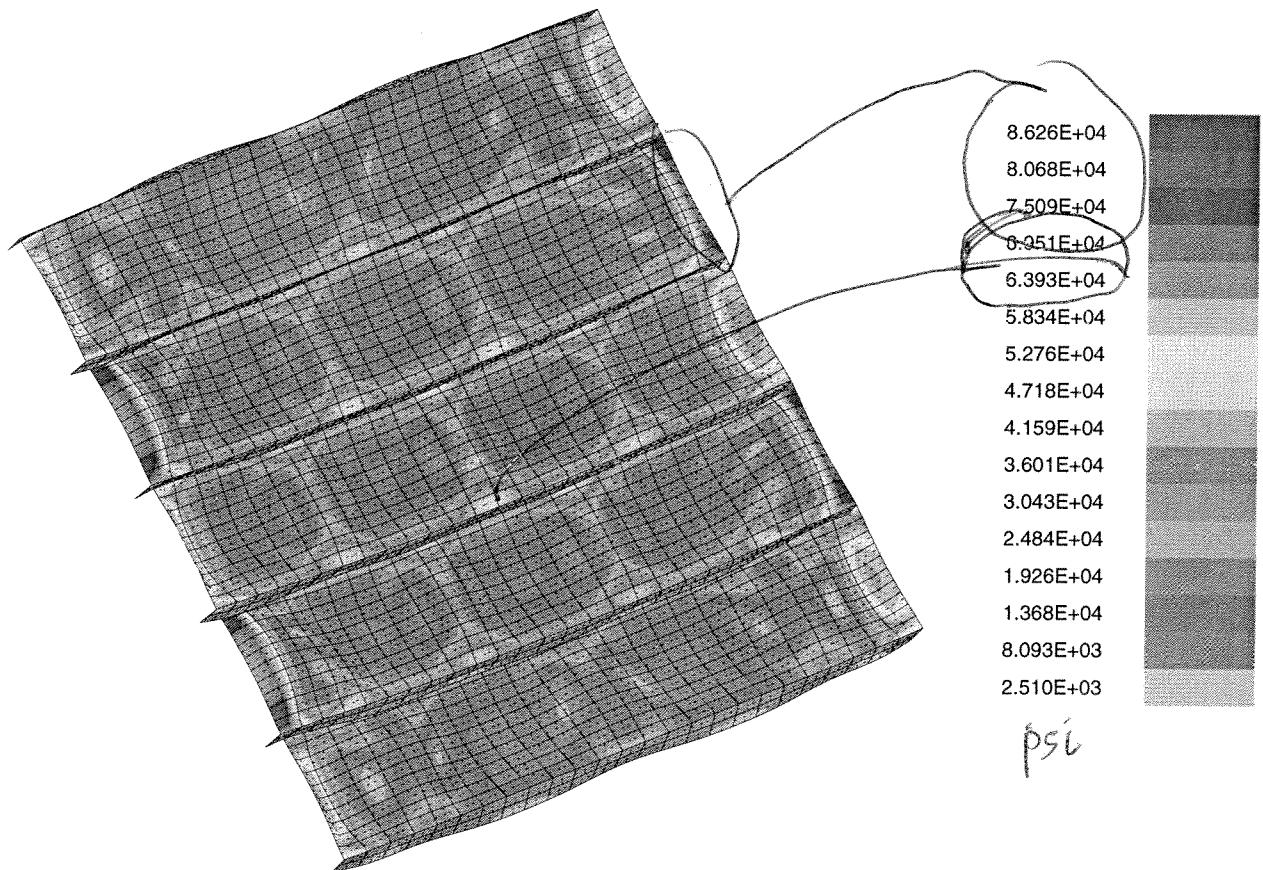


141

Fig. 1.49(b)

riks.postbuck.realstiff.5bay.step26.rigidedges.seffouterfiber.pdf

Compare with Fig. 1.47



solution scale = 0.3848E+01

PA= 9.70000E-01 PB= 0.00000E+00 PX= 0.00000E+00

step 26 fabrication system ,seff, layer 1, outer fiber

nonlinear effective stress - inner fiber - outer

Minimum value = 2.50977E+03, Maximum value = 8.62594E+04

Θ_x 24.00
 Θ_y -22.00
 Θ_z 30.00

1.283E+01

y
x
z

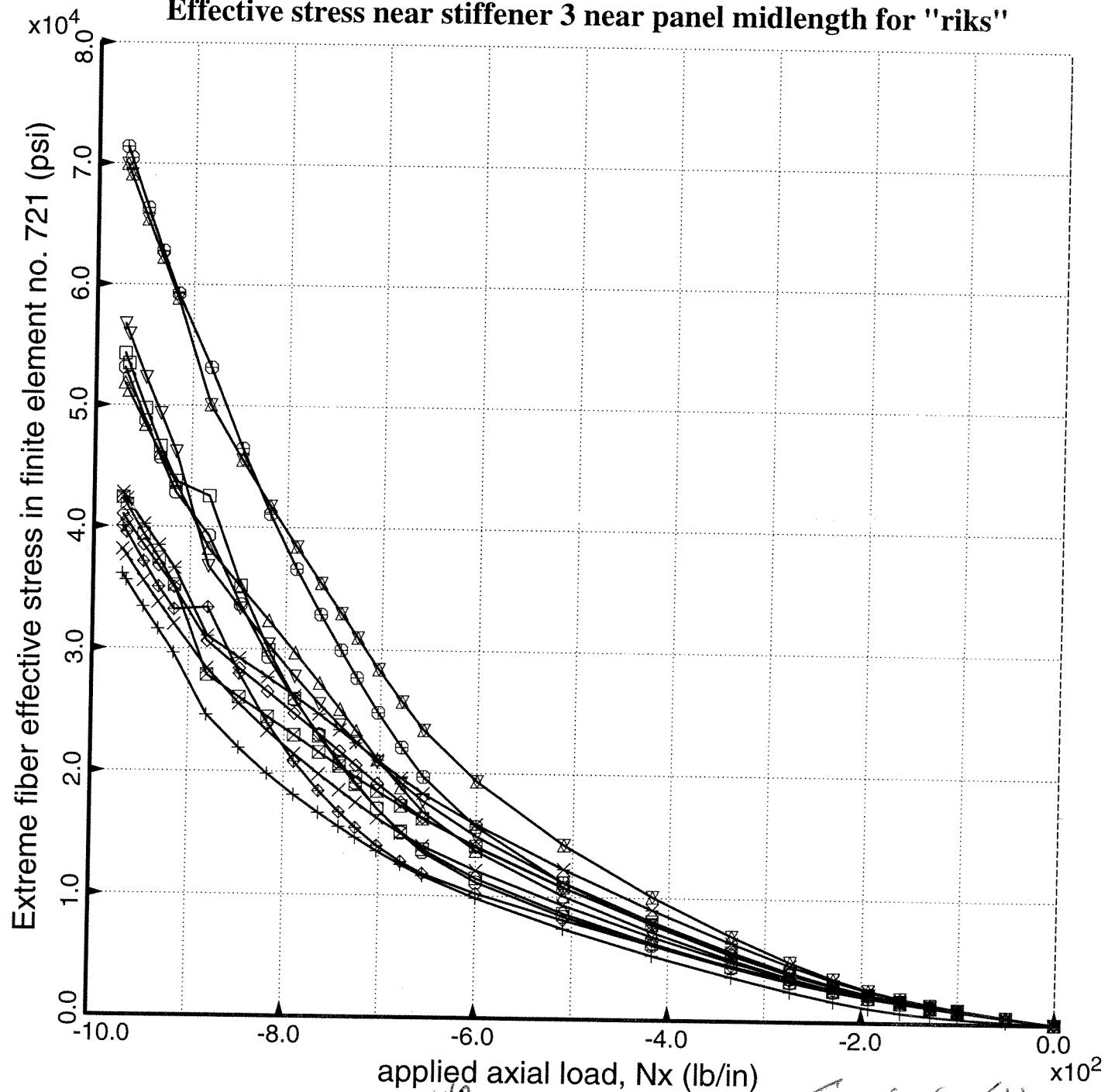
142

Fig. 1.49(c)

Riks. sigma-bar, near stiff. [input]
PBS

- Effective stress at integration pt. 1 of F.E. no. 721; bottom fiber near stiffener 3
- Effective stress at integration pt. 2 of F.E. no. 721; bottom fiber near stiffener 3
- △ Effective stress at integration pt. 3 of F.E. no. 721; bottom fiber near stiffener 3
- + Effective stress at integration pt. 4 of F.E. no. 721; bottom fiber near stiffener 3
- ×
- ◊ Effective stress at integration pt. 5 of F.E. no. 721; bottom fiber near stiffener 3
- ▽ Effective stress at integration pt. 6 of F.E. no. 721; bottom fiber near stiffener 3
- ☒ Effective stress at integration pt. 7 of F.E. no. 721; bottom fiber near stiffener 3
- ✳ Effective stress at integration pt. 8 of F.E. no. 721; bottom fiber near stiffener 3
- ◊ Effective stress at integration pt. 9 of F.E. no. 721; bottom fiber near stiffener 3
- ◊ Effective stress at integration pt. 1 of F.E. no. 721; top fiber near stiffener 3
- ⊕ Effective stress at integration pt. 2 of F.E. no. 721; top fiber near stiffener 3
- ☒ Effective stress at integration pt. 3 of F.E. no. 721; top fiber near stiffener 3

Effective stress near stiffener 3 near panel midlength for "riks"



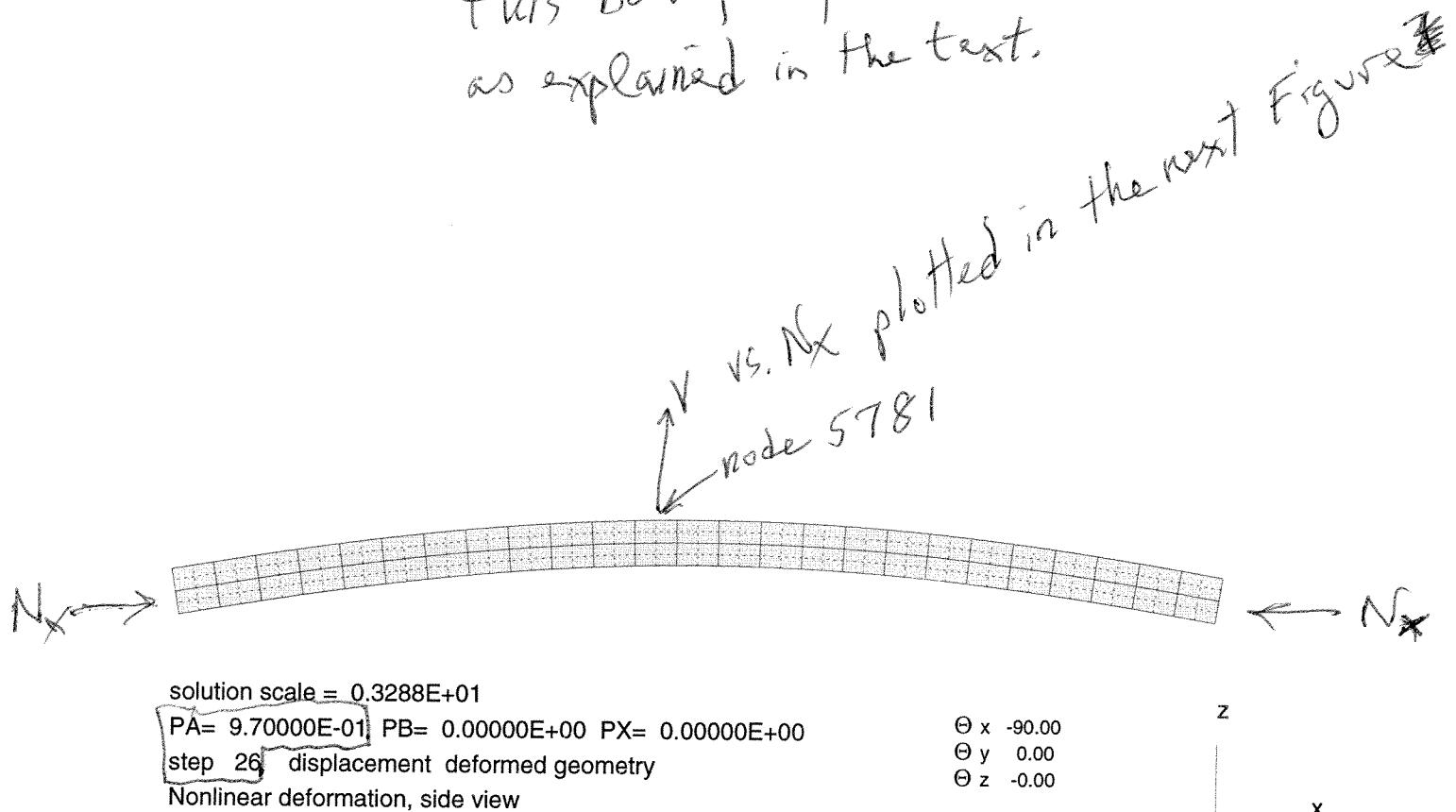
143

Fig. 1.49(d)

riks.postback.realstiff.sbay, sideview, stiffno3.pdf

output from STAPL
for Shell Unit #4 =
stiffener #3.

PANDA2 does not predict
this bowing deformation,
as explained in the text.



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Fig. 1.50

Table 1.49(a) riks.stiffno3.v.input

```

# riks.stiffno3.v.input (input to the application, /home/progs/bin/plotps.linux )
# This is a typical file from which a postscript file, riks.stiffno3.v.ps, is generated.
# The "x,y" input data come from STAGS results generated via the STAGS processor
# called "xytrans" after completion of a STAGS nonlinear equilibrium run.
# In order to generate a postscript file that can be sent to a printer,
# type the command:
#   /home/progs/bin/plotps.linux < riks.stiffno3.v.input > riks.stiffno3.v.ps
# Global directives, load-deflection curve for "riks" with axial loading
=title(STAGS model of "riks": max. v displacement vs. axial load, Nx)
=xlabel(applied axial load, Nx (lb/in))
=ylabel(v disp.(in) at midlength of Stiffener no. 3: Nodal pt. 5781)
# data set 1 Prediction from STAGS model generated via STAGSUNIT.
+legend(Prediction from STAGS model generated via STAGSUNIT)
+setmarker( 0)
  0.000000E+00  0.000000E+00
-5.000000E+01  2.339285E-04
-1.000000E+02  6.946952E-04
-1.284573E+02  1.185467E-03
-1.597499E+02  2.131595E-03
-1.927910E+02  3.989119E-03
-2.291033E+02  7.634806E-03
-2.738815E+02  1.471948E-02
-3.345164E+02  2.809446E-02
-4.169353E+02  5.212735E-02
-5.092850E+02  8.738476E-02
-5.998217E+02  1.328658E-01
-6.549292E+02  1.700641E-01
-6.775533E+02  1.910600E-01
-7.023360E+02  2.168599E-01
-7.247554E+02  2.433638E-01
-7.419851E+02  2.653049E-01
-7.635771E+02  2.945822E-01
-7.895001E+02  3.331663E-01
-8.174851E+02  3.798206E-01
-8.472409E+02  4.358896E-01
-8.809984E+02  5.086458E-01
-9.158069E+02  5.963151E-01
-9.322494E+02  6.411988E-01
-9.480286E+02  6.863829E-01
-9.659609E+02  7.412923E-01
-9.700000E+02  7.543517E-01

```

maximum local buckling lobe amplitude

$$\text{is } 0.9761 - 0.7543 = 0.2218 \text{ inch.}$$

See Fig. 1.49

at $N_x = -970 \text{ lb/in.}$

Compare with Fig. 1.53

riks,stiffno3,v. {input}
PS}

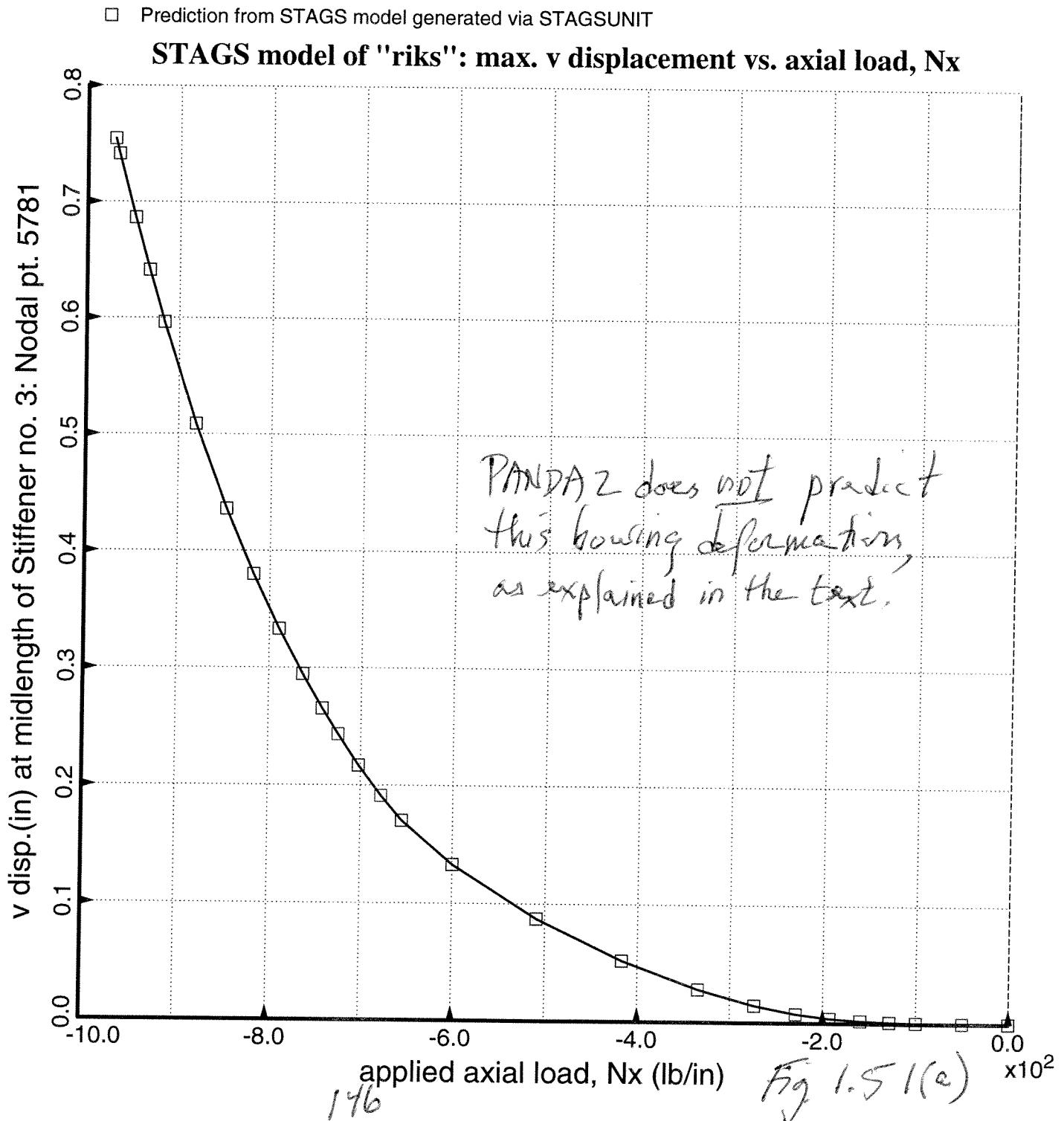


Table 1.49(b) riks, stiffno3andbuckle, input

```

# riks.stiffno3andbuckle.input (input to the application, /home/progs/bin/plotps.linux )
# This is a typical file from which a postscript file, riks.stiffno3andbuckle.ps, is generated.
# The "x,y" input data come from STAGS results generated via the STAGS processor
# called "xytrans" after completion of a STAGS nonlinear equilibrium run.
# In order to generate a postscript file that can be sent to a printer,
# type the command:
# ./home/progs/bin/plotps.linux < riks.stiffno3andbuckle.input > riks.stiffno3andbuckle.ps
# Global directives, load-deflection curve for "riks" with axial loading
=title(STAGS "riks": Compare average bowing & max.w vs. axial load, Nx)
=xlabel(applied axial load, Nx (lb/in))
=ylabel(bowing at midlength (Node 5781) and max. normal disp. w (in) (Node 3081))
# data set 1 Prediction from STAGS model generated via STAGSUNIT.
+legend(Bowing at panel midlength of Stiffener No. 3)
+setmarker( 0)
  0.000000E+00    0.000000E+00
-5.000000E+01    2.339285E-04
-1.000000E+02    6.946952E-04
-1.284573E+02    1.185467E-03
-1.597499E+02    2.131595E-03
-1.927910E+02    3.989119E-03
-2.291033E+02    7.634806E-03
-2.738815E+02    1.471948E-02
-3.345164E+02    2.809446E-02
-4.169353E+02    5.212735E-02
-5.092850E+02    8.738476E-02
-5.998217E+02    1.328658E-01
-6.549292E+02    1.700641E-01
-6.775533E+02    1.910600E-01
-7.023360E+02    2.168599E-01
-7.247554E+02    2.433638E-01
-7.419851E+02    2.653049E-01
-7.635771E+02    2.945822E-01
-7.895001E+02    3.331663E-01
-8.174851E+02    3.798206E-01
-8.472409E+02    4.358896E-01
-8.809984E+02    5.086458E-01
-9.158069E+02    5.963151E-01
-9.322494E+02    6.411988E-01
-9.480286E+02    6.863829E-01
-9.659609E+02    7.412923E-01
-9.700000E+02    7.543517E-01

# data set 2 Prediction from STAGS model generated via STAGSUNIT.
+legend(Maximum normal displacement w at outward buckling lobe)
+setmarker( 1)
  0.000000E+00    0.000000E+00
-5.000000E+01    1.622746E-03
-1.000000E+02    4.306890E-03
-1.284573E+02    6.713517E-03
-1.597499E+02    1.063850E-02
-1.927910E+02    1.695922E-02
-2.291033E+02    2.700202E-02
-2.738815E+02    4.288540E-02
-3.345164E+02    6.774538E-02
-4.169353E+02    1.059752E-01
-5.092850E+02    1.565847E-01
-5.998217E+02    2.188193E-01
-6.549292E+02    2.692950E-01
-6.775533E+02    2.975111E-01
-7.023360E+02    3.309633E-01
-7.247554E+02    3.644846E-01
-7.419851E+02    3.915611E-01
-7.635771E+02    4.269995E-01
-7.895001E+02    4.731238E-01
-8.174851E+02    5.285127E-01
-8.472409E+02    5.947390E-01
-8.809984E+02    6.796541E-01
-9.158069E+02    7.575121E-01
-9.322494E+02    8.047718E-01
-9.480286E+02    8.531822E-01
-9.659609E+02    9.115831E-01
-9.700000E+02    9.253268E-01

```

riks.stiffno3andbuckle.{^{input}_{ps}}

- Bowing at panel midlength of Stiffener No. 3
- Maximum normal displacement w at outward buckling lobe

STAGS "riks": Compare average bowing & max.w vs. axial load, Nx

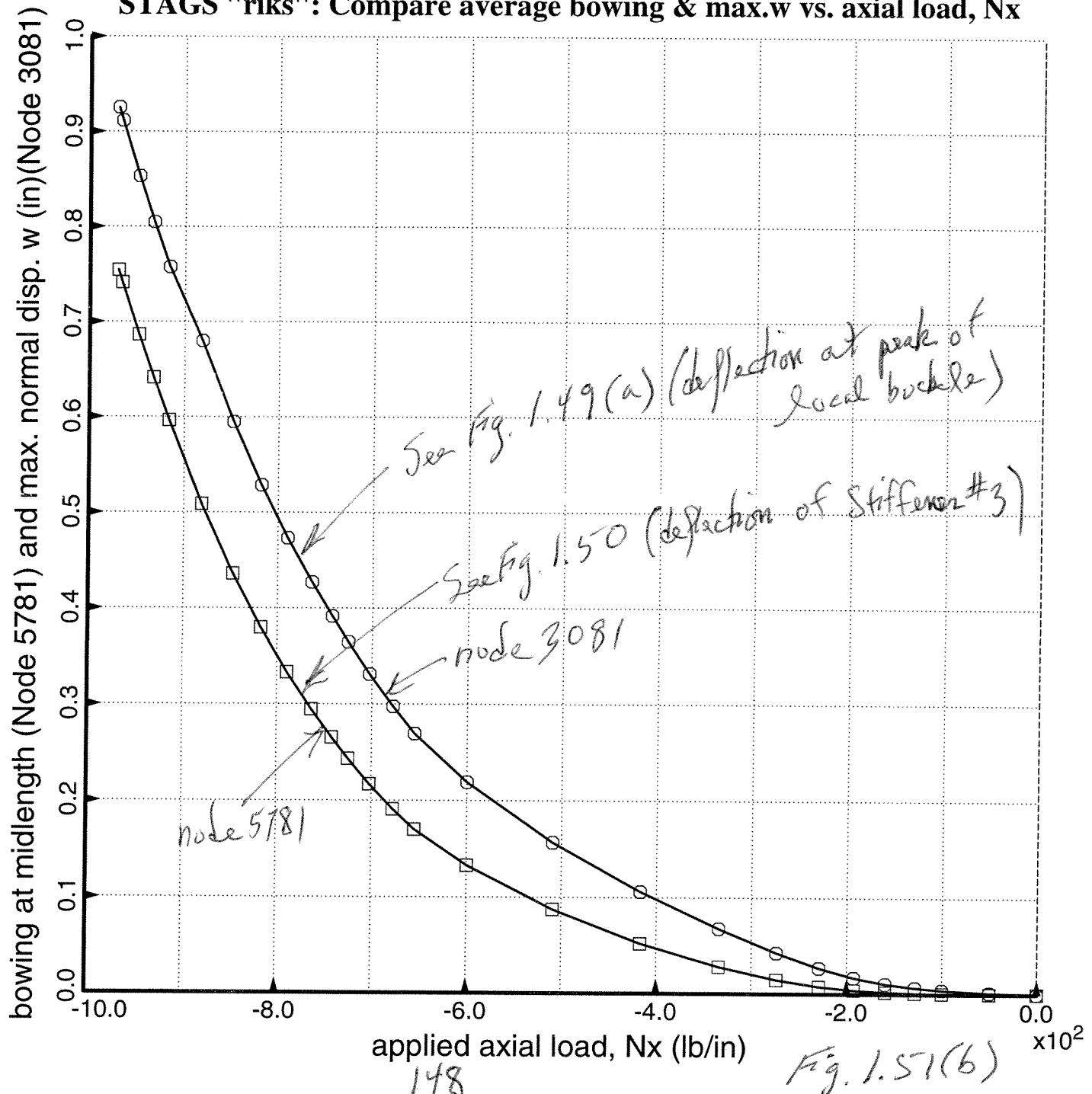


Table 1.5(a) riks, CHG (Input for CHANGE)

n	\$ Do you want a tutorial session and tutorial output?	
y	\$ Do you want to change any values in Parameter Set No. 1?	
3	\$ Number of parameter to change (1, 2, 3, . . .)	
2.113900	\$ New value of the parameter	
y	\$ Want to change any other parameters in this set?	stiffener height
4	\$ Number of parameter to change (1, 2, 3, . . .)	
0.6420300E-01	\$ New value of the parameter	
y	\$ Want to change any other parameters in this set?	skin thickness
5	\$ Number of parameter to change (1, 2, 3, . . .)	
0.1814700	\$ New value of the parameter	
n	\$ Want to change any other parameters in this set?	stiffener
n	\$ Do you want to change values of "fixed" parameters?	
n	\$ Do you want to change values of allowables?	thickness

This is a good way to
Save an optimum design.

Table 1.50(b) riks.opt3 (input for MAINSETUP=riks.opt)

```

n      $ Do you want a tutorial session and tutorial output?
→ -50.000 $ Resultant (e.g. lb/in) normal to the plane of screen, Nx( 1)
0      $ Resultant (e.g. lb/in) in the plane of the screen, Ny( 1)
0      $ In-plane shear in load set A, Nxy( 1)
n      $ Does the axial load vary in the L2 direction?
0.000000 $ Applied axial moment resultant (e.g. in-lb/in), Mx( 1)
0.000000 $ Applied hoop moment resultant (e.g. in-lb/in), My( 1)
Y      $ Want to include effect of transverse shear deformation?
0      $ IQUICK = quick analysis indicator (0 or 1)
Y      $ Do you want to vary M for minimum local buckling load?
N      $ Do you want to choose a starting M for local buckling?
Y      $ Do you want to perform a "low-axial-wavenumber" search?
1.000000 $ Factor of safety for general instability, FSGEN( 1)
0.2000000 $ Minimum load factor for local buckling (Type H for HELP), FSLOC( 1)
1.000000 $ Minimum load factor for stiffener buckling (Type H), FSBSTR( 1)
1.000000 $ Factor of safety for stress, FSSTR( 1)
Y      $ Do you want "flat skin" discretized module for local buckling?
N      $ Do you want wide-column buckling to constrain the design?
0.000000 $ Resultant (e.g. lb/in) normal to the plane of screen, Nx0( 1)
0.000000 $ Resultant (e.g. lb/in) in the plane of the screen, Ny0( 1)
0      $ Axial load applied along the (0=neutral plane), (1=panel skin)
0.000000 $ Uniform applied pressure [positive upward. See H(elp)], p( 1)
0.000000 $ Out-of-roundness, Wimpq1=(Max.diameter-Min.diam)/4, Wimpq1( 1)
0.000000 $ Initial buckling modal general imperfection amplitude, Wimpq2( 1)
0.010000 $ Initial local imperfection amplitude (must be positive), Wloc( 1)
Y      $ Do you want PANDA2 to change imperfection amplitudes (see H(elp))?( 1)
50     $ Axial halfwavelength of typical general buckling mode, AXLWAV( 1)
Y      $ Do you want PANDA2 to find the general imperfection shape?( 1)
1.000000 $ Maximum allowable average axial strain (type H for HELP)( 1)
N      $ Is there any thermal "loading" in this load set (Y/N)?
Y      $ Do you want a "complete" analysis (type H for "Help")?
N      $ Want to provide another load set ?
N      $ Do you want to impose minimum TOTAL thickness of any segment?
N      $ Do you want to impose maximum TOTAL thickness of any segment?
N      $ Use reduced effective stiffness in panel skin (H(elp), Y or N)?
0      $ NPRINT= output index (-1=min. 0=good, 1=ok, 2=more, 3=too much)
1      $ Index for type of shell theory (0 or 1 or 2), ISAND
Y      $ Does the postbuckling axial wavelength of local buckles change?
Y      $ Want to suppress general buckling mode with many axial waves?
N      $ Do you want to double-check PANDA-type eigenvalues [type (H)elp]?
0      $ Choose (0=transverse inextensional; 1=transverse extensional)
1      $ Choose ICONSV = -1 or 0 or 1 or H(elp), ICONSV
3      $ Choose type of analysis (ITYPE = 1 or 2 or 3 or 4 or 5)
Y      $ Do you want to prevent secondary buckling (mode jumping)?
n      $ Do you want to use the "alternative" buckling solution?
1      $ Choose one of the load sets: ILOAD
1      $ Choose one of the sub cases (1 or 2): ICASE
-50.00000 $ Increment in axial resultant Nx: DNX
0      $ Increment in hoop resultant Ny: DNY
0      $ Increment in shear resultant Nxy: DNXY
0      $ Increment in axial moment resultant Mx: DMX
0      $ Increment in circumferential moment resultant My: DMY
0      $ Increment in pressure, p: DP
0      $ Starting multiplier for temperature distribution, TMULT
0      $ Multiplier increment for temperature distribution, DTMULT
20     $ Maximum number of load steps, NSTEPS

```

test simulation of optimized panel with PANDA2