

Table 9, p. 8 of 12

C23456789012345678901234567890123456789012345678901234567890123456789012

C      BUCKL(ILOADX) = EIGCRT  
C      RETURN  
C      END

C  
C  
C  
C      C=DECK      BEHX2      stress analysis

SUBROUTINE BEHX2  
1 (IFILE,NPRINX,IMODX,IFAST,ILOADX,JCOL,PHRASE)

C      PURPOSE: OBTAIN effective stress in shell segment

C      YOU MUST WRITE CODE THAT, USING  
C      THE VARIABLES IN THE LABELLED  
C      COMMON BLOCKS AS INPUT, ULTIMATELY  
C      YIELDS THE RESPONSE VARIABLE FOR  
C      THE ith LOAD CASE, ILOADX:

C      STRESS(ILOADX,JCOL)

C      AS OUTPUT. THE ith CASE REFERS  
C      TO ith ENVIRONMENT (e.g. load com-  
C      bination).

C      THE jth COLUMN (JCOL)  
C      INDEX IS DEFINED AS FOLLOWS:  
C      shell segment number

C      DEFINITIONS OF INPUT DATA:

C      IMODX = DESIGN CONTROL INTEGER:

C      IMODX = 0 MEANS BASELINE DESIGN

C      IMODX = 1 MEANS PERTURBED DESIGN

C      IFAST = 0 MEANS FEW SHORTCUTS FOR PERTURBED DESIGNS

C      IFAST = 1 MEANS MORE SHORTCUTS FOR PERTURBED DESIGNS

C      IFILE = FILE FOR OUTPUT LIST:

C      NPRINX= OUTPUT CONTROL INTEGER:

C      NPRINX=0 MEANS SMALLEST AMOUNT

C      NPRINX=1 MEANS MEDIUM AMOUNT

C      NPRINX=2 MEANS LOTS OF OUTPUT

C      ILOADX = ith LOADING COMBINATION

C      JCOL = jth column of STRESS

C      JCOL = shell segment number

C      PHRASE = effective stress in shell segment

C      OUTPUT:

C      STRESS(ILOADX,JCOL)

C      CHARACTER\*80 PHRASE

C      INSERT ADDITIONAL COMMON BLOCKS:

COMMON/FV06/ZSPH(15),IZSPH

REAL ZSPH

COMMON/FV07/ZCYL(15),IZCYL

REAL ZCYL

COMMON/FV08/ZREFSP(15),IZREFSP

REAL ZREFSP

COMMON/FV09/THKSPH(15)

REAL THKSPH

COMMON/FV10/ZREFCY(15),IZREFCY

REAL ZREFCY

COMMON/FV11/THKCYL(15)

REAL THKCYL

COMMON/FV12/PRESS(20)

REAL PRESS

COMMON/FV15/BUCKL(20),BUCKLA(20),BUCKLF(20)

REAL BUCKL,BUCKLA,BUCKLF

COMMON/FV18/STRESS(20,10),JSTRESS,STRESA(20,10),STRESSF(20,10)

REAL STRESS,STRESA,STRESSF

COMMON/IV01/NODSPH,NODCYL,NPTSPH,NPTCYL,NBUKLO,NBUKHI

INTEGER NODSPH,NODCYL,NPTSPH,NPTCYL,NBUKLO,NBUKHI

COMMON/FV01/RADIUS,LENGTH,EMOD,NU,DENSTY,WEIGHT

REAL RADIUS,LENGTH,EMOD,NU,DENSTY,WEIGHT

C  
C      61

GENOPT user creates

GenText creates this part

Table 9, p. 9 of 12

C INSERT SUBROUTINE STATEMENTS HERE.

```

C COMMON/STRCON/STFMXS(295), STFMXR(295), SKNMAX(295)
C COMMON/IBIGX2/ISTFMS(295), ISTMFR(295), ISKNMX(295)
C COMMON/ENDUVX/ENDUV, STRMAX, ARCLEN
C COMMON/INSTAB/INDIC
C COMMON/PRMOUT/IFILE3, IFILE4, IFILE8, IFILE9, IFIL11
C COMMON/NUMPAR/IPARX, IVARX, IALLOW, ICONSX, NDECX, NLINKX, NESCAP, ITYPEX
C common/caseblock/CASE
C CHARACTER*28 CASE
C CHARACTER*35 CASA

C INDIC = 0 means "stress analysis"
C CALL BOSDEC(2,24,ILOADX,INDIC)

C IF (ITYPEX.EQ.2) THEN
C   Get CASE.BEHX2 file for input for BIGBOSOR4...
C   CASE.BEHX2 is an input file for BIGBOSOR4 for behavior no. 2:
C   maximum effective stress
C     I=INDEX(CASE,' ')
C     IF(I.NE.0) THEN
C       CASA=CASE(:I-1)//'.BEHX2'
C     ELSE
C       CASA=CASE//'.BEHX2'
C     ENDIF
C     OPEN(UNIT=61,FILE=CASA,STATUS='UNKNOWN')
C     CALL BOSDEC(2,61,ILOADX,INDIC)
C     CLOSE(UNIT=61)
C     WRITE(IFILE,'(//,,A,A,,A)')
C     1 ' BIGBOSOR4 input file for:',
C     1 ' maximum effective stress (INDIC=0)',
C     1 CASA
C   ENDIF

C CALL B4READ
C CALL B4MAIN
C CALL GASD(DUM1,DUM2,-2,DUM3)

C IF (JCOL.EQ.1) THEN
C   DO 9 I = 1,2
C     WRITE(IFILE,'(A,1P,E12.4,,A,I4)')
C     1 ' Shell skin maximum effective stress,           SKNMAX=',
C     1 ' SKNMAX(I),' at nodal point',ISKNMX(I)
C   9 CONTINUE
C   WRITE(IFILE,10) STRMAX
C 10 FORMAT(/,
C    1' ***** MAXIMUM EFFECTIVE STRESS IN ISOTROPIC WALL *****',/,
C    1' STRMAX=',1P,E12.4,,/
C    1' *****',)
C   ENDIF

C   STRESS(ILOADX,JCOL) = SKNMAX(JCOL)

C RETURN
C END

C=DECK      USRCON
SUBROUTINE USRCON(INUMTT,IMODX,CONMAX,ICONSX,IPOINC,CONSTX,
  1 WORDCX,WORDMX,PCWORD,CPLTX,ICARX,IFILEX)
C PURPOSE: GENERATE USER-WRITTEN
C INEQUALITY CONSTRAINT CONDITION
C USING ANY COMBINATION OF PROGRAM
C VARIABLES.
C YOU MUST WRITE CODE THAT, USING
C THE VARIABLES IN THE LABELLED
C COMMON BLOCKS AS INPUT, ULTIMATELY
C YIELDS A CONSTRAINT CONDITION,
C CALLED "CONX" IN THIS ROUTINE.
  DIMENSION WORDCX(*),WORDMX(*),IPOINC(*),CONSTX(*)
  DIMENSION PCWORD(*),CPLTX(*)
  CHARACTER*80 WORDCX,WORDMX,PCWORD
C INSERT ADDITIONAL COMMON BLOCKS:
  COMMON/FV06/ZSPH(15),IZSPH
  REAL ZSPH

```

# Table 9, p. 10 of 12

```

COMMON/FV07/ZCYL(15), IZCYL
REAL ZCYL
COMMON/FV08/ZREFSP(15), IZREFSP
REAL ZREFSP
COMMON/FV09/THKSPH(15)
REAL THKSPH
COMMON/FV10/ZREFCY(15), IZREFCY
REAL ZREFCY
COMMON/FV11/THKCYL(15)
REAL THKCYL
COMMON/FV12/PRESS(20)
REAL PRESS
COMMON/FV15/BUCKL(20), BUCKLA(20), BUCKLF(20)
REAL BUCKL, BUCKLA, BUCKLF
COMMON/FV18/STRESS(20,10), JSTRESS, STRESA(20,10), STRESSF(20,10)
REAL STRESS, STRESA, STRESSF
COMMON/IV01/NODSPH, NODCYL, NPTSPH, NPTCYL, NBUKLO, NBUKHI
INTEGER NODSPH, NODCYL, NPTSPH, NPTCYL, NBUKLO, NBUKHI
COMMON/FV01/RADIUS, LENGTH, EMOD, NU, DENSTY, WEIGHT
REAL RADIUS, LENGTH, EMOD, NU, DENSTY, WEIGHT

C
C      CONX = 0.0
C
C      INSERT USER-WRITTEN STATEMENTS
C      HERE. THE CONSTRAINT CONDITION
C      THAT YOU CALCULATE IS CALLED "CONX"
C
C      IF (CONX.EQ.0.0) RETURN
C      IF (CONX.LT.0.0) THEN
C          WRITE(IFILEX,*)' CONX MUST BE GREATER THAN ZERO.'
C          CALL EXIT
C      ENDIF
C
C      DO NOT CHANGE THE FOLLOWING STATEMENTS, EXCEPT WORDC
C
C      ICARX = ICARX + 1
C      INUMTT = INUMTT + 1
C      WORDCX(ICARX) = ' USER: PROVIDE THIS.'
C      CPLOTX(ICARX) = CONX - 1.
C      CALL BLANKX(WORDCX(ICARX),IENDP)
C      PCWORD(ICARX) = WORDCX(ICARX)(1:IENDP)//' -1'
C      IF (IMODX.EQ.0.AND.CONX.GT.CONMAX) GO TO 200
C      IF (IMODX.EQ.1.AND.IPOINC(INUMTT).EQ.0) GO TO 200
C      ICONSX = ICONSX + 1
C      IF (IMODX.EQ.0) IPOINC(INUMTT) = 1
C      CONSTX(ICONSX) = CONX
C      WORDMX(ICONSX) = WORDCX(ICARX)(1:IENDP)//' -1'
200  CONTINUE
C      END OF USRCON
C
C      RETURN
C      END
C
C
C=DECK      USRLNK
SUBROUTINE USRLNK(VARI,I,VARIAB)
C Purpose: generate user-written
C linking conditions using any
C combination of decision variables.
C You must write conde that, using
C the variables in the subroutine
C argument VARIAB as input, ultimately
C yield a value for the linked variable
C VARI.
C
C VARI is the Ith entry of the array
C VARIAB. You have decided that this
C is to be a linked variable with user
C defined linking. It is linked to
C the decision variables in the array
C VARIAB.
C An example will provide the simplest
C explanation of this:
C Let's say that the 5th decision
C variable candidate (I=5) is linked
C to the decision variable candidates

```

GENTEXT creates this part

# Table 9, p. 11 of 12

```

C 2 and 7. (You used DECIDE to select
C these as decision variables.
C In this case VARI is equal to
C VARIAB(I). You then write your
C linking equation in the form
C VARI=f(VARIAB(2),VARIAB(7)).
C Use the index I in an IF statement if
C you have more than one user-defined
C linked variable.
C
C
REAL VARI,VARIAB(50)
INTEGER I
C
C INSERT USER-WRITTEN DECLARATION
C STATEMENTS HERE.
C
C INSERT USER-WRITTEN
C STATEMENTS HERE.
C
C END OF USRLNK
RETURN
END
C=DECK OBJECT
SUBROUTINE OBJECT(IFILE,NPRINX,IMODX,OBJGEN,PHRASE)
C PURPOSE: weight of the BIGBOSOR4 model
C
C YOU MUST WRITE CODE THAT, USING
C THE VARIABLES IN THE LABELLED
C COMMON BLOCKS AS INPUT, ULTIMATELY
C YIELDS THE OBJECTIVE FUNCTION
C WEIGHT
C AS OUTPUT. MAKE SURE TO INCLUDE AT
C THE END OF THE SUBROUTINE, THE
C STATEMENT: OBJGEN = WEIGHT
C
C DEFINITIONS OF INPUT DATA:
C IMODX = DESIGN CONTROL INTEGER:
C IMODX = 0 MEANS BASELINE DESIGN
C IMODX = 1 MEANS PERTURBED DESIGN
C IFAST = 0 MEANS FEW SHORTCUTS FOR PERTURBED DESIGNS
C IFAST = 1 MEANS MORE SHORTCUTS FOR PERTURBED DESIGNS
C IFILE = FILE FOR OUTPUT LIST:
C NPRINX= OUTPUT CONTROL INTEGER:
C NPRINX=0 MEANS SMALLEST AMOUNT
C NPRINX=1 MEANS MEDIUM AMOUNT
C NPRINX=2 MEANS LOTS OF OUTPUT
C
C DEFINITION OF PHRASE:
C PHRASE = weight of the BIGBOSOR4 model
C
CHARACTER*80 PHRASE
C INSERT ADDITIONAL COMMON BLOCKS:
COMMON/FV06/ZSPH(15),IZSPH
REAL ZSPH
COMMON/FV07/ZCYL(15),IZCYL
REAL ZCYL
COMMON/FV08/ZREFSP(15),IZREFSP
REAL ZREFSP
COMMON/FV09/THKSPH(15)
REAL THKSPH
COMMON/FV10/ZREFCY(15),IZREFCY
REAL ZREFCY
COMMON/FV11/THKCYL(15)
REAL THKCYL
COMMON/FV12/PRESS(20)
REAL PRESS
COMMON/FV15/BUCKL(20),BUCKLA(20),BUCKLF(20)
REAL BUCKL,BUCKLA,BUCKLF
COMMON/FV18/STRESS(20,10),JSTRESS,STRESSA(20,10),STRESSF(20,10)
REAL STRESS,STRESSA,STRESSF
COMMON/IV01/NODSPH,NODCYL,NPTSPH,NPTCYL,NBUKLO,NBUKHI
INTEGER NODSPH,NODCYL,NPTSPH,NPTCYL,NBUKLO,NBUKHI
COMMON/FV01/RADIUS,LENGTH,EMOD,NU,DENSTY,WEIGHT
REAL RADIUS,LENGTH,EMOD,NU,DENSTY,WEIGHT

```

*the objective is computed*

*GENTEXT creates this part*

Table 9, p. 12 of 12

C C INSERT SUBROUTINE STATEMENTS HERE.

C → COMMON/TOTMAX/TOTMAS

C WEIGHT = TOTMAS

C OBJGEN =WEIGHT

C C RETURN  
C C END

↓ GENOPT user creates this

end of "fleshed out" version of  
the library, behavior.new

in BIGBOSOR4 "TOTMAS" is the  
total mass of the multi-segment  
model. I used weight density rather  
than mass density. Therefore, in this  
application TOTMAS is the total weight.

# Table 10 (8 pages)      bosdec, submarine

```

C=DECK      BOSDEC
C
C PURPOSE IS TO SET UP BIGBOSOR4 INPUT FILE FOR "trusscomp"
C
SUBROUTINE BOSDEC(INDX,IFIL14,ILOADX,INDIC)
C Insert labelled common blocks: submarine.COM
COMMON/FV06/ZSPH(15),IZSPH
REAL ZSPH
COMMON/FV07/ZCYL(15),IZCYL
REAL ZCYL
COMMON/FV08/ZREFSP(15),IZREFSP
REAL ZREFSP
COMMON/FV09/THKSPH(15)
REAL THKSPH
COMMON/FV10/ZREFCY(15),IZREFCY
REAL ZREFCY
COMMON/FV11/THKCYL(15)
REAL THKCYL
COMMON/FV12/PRESS(20)
REAL PRESS
COMMON/FV15/BUCKL(20),BUCKLA(20),BUCKLF(20)
REAL BUCKL,BUCKLA,BUCKLF
COMMON/FV18/STRESS(20,10),JSTRESS,STRESSA(20,10),STRESSF(20,10)
REAL STRESS,STRESSA,STRESSF
COMMON/IV01/NODSPH,NODCYL,NPTSPH,NPTCYL,NBUKLO,NBUKHI
INTEGER NODSPH,NODCYL,NPTSPH,NPTCYL,NBUKLO,NBUKHI
COMMON/FV01/RADIUS,LENGTH,EMOD,NU,DENSTY,WEIGHT
REAL RADIUS,LENGTH,EMOD,NU,DENSTY,WEIGHT
C end of submarine.COM
COMMON/PRMOUT/IFILE3,IFILE4,IFILE8,IFILE9,IFIL11
DIMENSION NSHAPE(2),NNODES(2),IHVALU(4,2),HVALU(4,2)
DIMENSION R1(2),Z1(2),R2(2),Z2(2),RC(2),ZC(2)
DIMENSION NZVALU(2),Z(15,2),ZVAL(15,2),TVAL(15,2)
DIMENSION IDISP(2,4)
C
REWIND IFIL14
C
WRITE(IFILE4,3)
3 FORMAT(//' **** BOSDEC ****',/
1' The purpose of BOSDEC is to set up an input file, NAME.ALL,/'
1' for a cylindrical shell. NAME is your name for'
1' the case. The file NAME.ALL is a BOSOR4 input "deck" used'
1' by SUBROUTINE B4READ.')
1' ****')
C234567890123456789012345678901234567890123456789012
C
C Generate a valid input data file, *.ALL, for BIGBOSOR4
C
C Global input before segment data...
NPRT = 1
NSEG = 2
ISTRES = 0
IF (INDX.EQ.2) ISTRES = 1
IF (INDX.EQ.1) WRITE(IFIL14,'(A)')
1' buckling of tank (INDIC=1)'
IF (INDX.EQ.2) WRITE(IFIL14,'(A)')
1' effective stress (INDIC=0)'
WRITE(IFIL14,'(4I3,A)') INDIC,NPRT,ISTRES,NSEG,
1' $ INDIC,NPRT,ISTRES,NSEG'
C
NTYPEH = 1
NHVALU = 4
NSHAPE(1) = 2
NSHAPE(2) = 1
NNODES(1) = NODSPH
NNODES(2) = NODCYL
C
IHVALU(1,1) = 1
IHVALU(2,1) = NODSPH/2
IHVALU(3,1) = NODSPH/2 + 1
IHVALU(4,1) = NODSPH - 1
IHVALU(1,2) = 1
IHVALU(2,2) = NODCYL/2
IHVALU(3,2) = NODCYL/2 + 1
IHVALU(4,2) = NODCYL - 1
C
HVALU(1,1) = 1.

```

BOSDEC generates  
input files for  
BIGBOSOR4

# Table 10 (P. 2 of 4)

```
HVALU(2,1) = 1.
HVALU(3,1) = 0.5
HVALU(4,1) = 0.5
HVALU(1,2) = 0.5
HVALU(2,2) = 0.5
HVALU(3,2) = 1.
HVALU(4,2) = 1.
```

C

```
R1(1) = 0.
Z1(1) = 0.
R2(1) = RADIUS
Z2(1) = RADIUS
RC(1) = 0.
SROT = -1.
ZC(1) = RADIUS
R1(2) = RADIUS
Z1(2) = RADIUS
R2(2) = RADIUS
Z2(2) = RADIUS + LENGTH/2.
```

C

```
NTYPEZ = 1
NTYPE = 2
NZVALU(1) = NPTSPH
NZVALU(2) = NPTCYL
DO 10 I = 1,NPTSPH
Z(I,1) = ZSPH(I)
ZVAL(I,1) = ZREFSP(I)
TVAL(I,1) = THKSPH(I)
10 CONTINUE
DO 20 I = 1,NPTCYL
Z(I,2) = ZCYL(I)
ZVAL(I,2) = ZREFCY(I)
TVAL(I,2) = THKCYL(I)
20 CONTINUE
```

C

```
DO 100 ISEG = 1,NSEG
I = ISEG
WRITE(IFIL14,'(A,4I6)') H $ Segment number ',I,I,I,I
WRITE(IFIL14,'(3I4,A)') NNODES(ISEG),NTYPEH,NHVALU,
1' $ NMESH,NTYPEH,NHVALU'
WRITE(IFIL14,'(4I4,A)') (IHALU(K,ISEG),K=1,NHVALU),
1' $ (IHALU(K,ISEG), K=1,NHVALU)'
WRITE(IFIL14,'(1P,4E14.6,A)') (HVALU(K,ISEG),K=1,NHVALU),
1' $ (HVALU(K,ISEG), K=1,NHVALU)'
WRITE(IFIL14,'(I4,A)') NSHAPE(ISEG),
1' $ indicator for meridian geometry'
WRITE(IFIL14,'(1P,4E14.6,A)') R1(I),Z1(I),R2(I),Z2(I),
1' $ R1,Z1,R2,Z2'
IF (NSHAPE(ISEG).EQ.2) THEN
    WRITE(IFIL14,'(1P,3E14.6,A)') RC(ISEG),ZC(ISEG),SROT,
1' $ RC,ZC,SROT'
ENDIF
WRITE(IFIL14,'(A)') 0 $ indicator for imperfection'
WRITE(IFIL14,'(3I4,A)') NTYPEZ,NZVALU(ISEG),NTYPE,
1' $ NTYPEZ,NZVALU,NTYPE'
NZVAL = NZVALU(ISEG)
WRITE(IFIL14,'(1P,(4E14.6))') (Z(K,ISEG),K=1,NZVAL)
WRITE(IFIL14,'(1P,(4E14.6))') (ZVAL(K,ISEG),K=1,NZVAL)
WRITE(IFIL14,'(A)') N $ do you want to print r(s), etc.?
C234567890123456789012345678901234567890123456789012
WRITE(IFIL14,'(A)') 0, 0, 0, 1 $ NRINGS,K,LINTYP,DISAB'
WRITE(IFIL14,'(A)')
1' 1, 2, 0, 0 $ NLTYPE,NPSTAT,NLOAD(1),NLOAD(2)'
WRITE(IFIL14,'(A)')
1' 1, -1., -1., 2 $ NLOAD(3),PN(1),PN(2),NTYPE'
WRITE(IFIL14,'(1P,2E14.6,A)') Z1(ISEG),Z2(ISEG),
1' $ Z(1),Z(2) callouts'
WRITE(IFIL14,'(A)') 2 $ NWALL = 2 for isotropic'
WRITE(IFIL14,'(1P,3E14.6,A)') EMOD,NU,DENSTY,
1' $ E, U, SM'
WRITE(IFIL14,'(A)') 0., 0, -1, 1 $ ALPHA,NRS,NSUR,NTYPET'
WRITE(IFIL14,'(2I4,A)') NZVALU(ISEG),NTYPE,
1' $ NTVALU, NTYPE'
NZVAL = NZVALU(ISEG)
WRITE(IFIL14,'(1P,(4E14.6))') (Z(K,ISEG),K=1,NZVAL)
WRITE(IFIL14,'(1P,(4E14.6))') (TVAL(K,ISEG),K=1,NZVAL)
WRITE(IFIL14,'(A)') N $ do you want to print refsurf etc.?
```

# Table 10 (p. 3 of 4)

```

      WRITE(IFIL14,'(A)')' N $ do you want to print C(i,j)?'
      WRITE(IFIL14,'(A)')' N $ do you want to print loads?'
C2345678901234567890123456789012345678901234567890123456789012
C
C 100  CONTINUE
C
C Next, do global data after all the segments...
C
      WRITE(IFIL14,'(A)')' H $ GLOBAL DATA BEGINS...'
      NLAST = 0
      IF (INDX.EQ.2) NLAST = 1
      WRITE(IFIL14,'(I4A)') NLAST,' $ NLAST'
      WRITE(IFIL14,'(A)')' N $ any expanded plots?'
      IF (INDX.EQ.1) THEN
        NMINB = NBUKLO
        NMAXB = NBUKHI
        INCRB = 1
        NVEC = 1
        WRITE(IFIL14,'(5I6,A)') NMINB,NMINB,NMAXB,INCRB,NVEC,
1      '$ NOB,NMINB,NMAXB,INCRB,NVEC'
      ENDIF
      IF (INDX.EQ.1) THEN
        P = 0.
        DP = ABS(PRESS(ILOADX))
      ENDIF
      IF (INDX.EQ.2) THEN
        P = ABS(PRESS(ILOADX))
      ENDIF
      DP = ABS(PRESS(ILOADX))
      WRITE(IFIL14,'(1P,2E14.6,A)') P,DP,' $ P,DP'
      IF (INDX.EQ.1)
1      WRITE(IFIL14,'(A)')' 0., 0., 0., 0. $ TEMP,DTEMP,OMEGA,DOMEGA'
      IF (INDX.EQ.2)
1      WRITE(IFIL14,'(A)')' 0., 0., 1., 0., 0. $ TEMP,DTEMP,NSTEPS,...'
C2345678901234567890123456789012345678901234567890123456789012
      WRITE(IFIL14,'(A)')' H $ CONSTRAINT CONDITIONS FOLLOW....'
      WRITE(IFIL14,'(I6,A)') NSEG,' $ how many segments?'
C
C Next, generate the BIGBOSOR4 input for all the constraint
C conditions (connections to ground and segment junctions)
C in the multi-segment model.
C
C The connections to ground are governed by the array,
C IDISP(i,j), in which i is the shell segment number,
C and j is the index for which displacement component is
C constrained or not constrained.
C
C IDISP(i,j) = 1 means that the jth displacement component is
C constrained to be zero.
C IDISP(i,j) = 0 means that the jth displacement component is
C free
C
C In BIGBOSOR4 [10] there are 4 displacement components:
C
C IDISP(i,1) refers to USTAR, the radial (horizontal) displacement
C IDISP(i,2) refers to VSTAR, the circumferential displacement
C IDISP(i,3) refers to WSTAR, the axial (vertical) displacement
C IDISP(i,4) refers to CHI, the meridional rotation
C
C constraints to ground at the midlength of the cylindrical
C are symmetry conditions:
C
      IDISP(2,1) = 1
      IDISP(2,2) = 0
      IDISP(2,3) = 0
      IDISP(2,4) = 1
C
      WRITE(IFIL14,'(A)')
1      ' H $ CONSTRAINT CONDITIONS FOR SEGMENT 1 1 1 1'
      WRITE(IFIL14,'(A)')' 1, 1, 0 $ one pole, IPOLE, to ground'
C2345678901234567890123456789012345678901234567890123456789012
      WRITE(IFIL14,'(A)')' N $ joined to other lower segments?'
      WRITE(IFIL14,'(A)')
1      ' H $ CONSTRAINT CONDITIONS FOR SEGMENT 2 2 2 2'
      WRITE(IFIL14,'(A)')' 0, 1 $ number of poles, numb. to ground'
      WRITE(IFIL14,'(I6,A)') NODCYL,' $ node connected to ground'
      WRITE(IFIL14,'(4I4,A)') (IDISP(2,K),K=1,4),
1      '$ IUSTAR,IVSTAR,IWSTAR,ICHI'

```

## Table 10 (P. 9 of 4)

```
WRITE(IFIL14,'(A)')' 0., 0. $ D1,D2'
WRITE(IFIL14,'(A)')' Y $ constraint same for prebuck & buck?
WRITE(IFIL14,'(A)')' Y $ joined to lower segments?
WRITE(IFIL14,'(A)')' 1, 1, 1 $ how many?, INODE, JSEG'
WRITE(IFIL14,'(I6,A)') NODSPH,' $ jseg node of the junction'
WRITE(IFIL14,'(A)')' 1, 1, 1, 1, 0., 0. $ connection cond.'
WRITE(IFIL14,'(A)')' Y $ constraint same for prebuck & buck?
WRITE(IFIL14,'(A)')' H $ RIGID BODY CONSTRAINT CONDITIONS'
WRITE(IFIL14,'(A)')' Y $ is rigid body motion possible?
WRITE(IFIL14,'(A)')' Y $ want to prevent rigid body motion?
WRITE(IFIL14,'(A)')' 2 $ Segment no. to prevent rigid body'
WRITE(IFIL14,'(I6,A)') NODCYL,' $ node to prevent rigid body'
WRITE(IFIL14,'(A)')' 1, 1, 0, 1 $ rigid body for n=0 waves'
WRITE(IFIL14,'(A)')' 1, 1, 0, 1 $ rigid body for n=1 waves'
WRITE(IFIL14,'(A)')' Y $ list output for segment 1?
WRITE(IFIL14,'(A)')' Y $ list output for segment 2?
WRITE(IFIL14,'(A)')' Y $ list output for discrete rings?
```

C

```
RETURN
END
```

end of BOSDEC

# Table II (4 pages)

doer.MLL (Input for BIGBOSOR4)

```

buckling of tank (INDIC=1)
1   $ INDIC = analysis type indicator
1   $ NPRT = output options (1=minimum, 2=medium, 3=maximum)
0   $ ISTRES= output control (0=resultants, 1=sigma, 2=epsilon)
2   $ NSEG = number of shell segments (less than 295)

H   $
H   $ SEGMENT NUMBER    1   1   1   1   1   1   1   1
H   $ NODAL POINT DISTRIBUTION FOLLOWS...
91  $ NMESH = number of node points (5 = min.; 98 = max.)( 1)
1   $ NTYPEH= control integer (1 or 3) for nodal point spacing
4   $ NHVALU= number of callouts for nodal point spacing
1   $ IHVALU(I)= Ith callout for nodal point spacing, IHVALU( 1)
45  $ IHVALU(I)= Ith callout for nodal point spacing, IHVALU( 2)
46  $ IHVALU(I)= Ith callout for nodal point spacing, IHVALU( 3)
90  $ IHVALU(I)= Ith callout for nodal point spacing, IHVALU( 4)
1.000000 $ HVALU=meridional arc length between nodal points,HVALU( 1)
1.000000 $ HVALU=meridional arc length between nodal points,HVALU( 2)
0.5000000 $ HVALU=meridional arc length between nodal points,HVALU( 3)
0.5000000 $ HVALU=meridional arc length between nodal points,HVALU( 4)

H   $ REFERENCE SURFACE GEOMETRY FOLLOWS...
2   $ NSHAPE= indicator (1,2 or 4) for geometry of meridian
0.000000 $ R1     = radius at beginning of segment (see p. 66)
0.000000 $ Z1     = global axial coordinate at beginning of segment
20.000000 $ R2     = radius at end of segment
20.000000 $ Z2     = global axial coordinate at end of segment
0.000000 $ RC     = radius from axis of rev. to center of curvature
20.000000 $ ZC     = axial coordinate of center of curvature
-1.000000 $ SROT=indicator for direction of increasing arc (-1. or +1.)

H   $ IMPERFECTION SHAPE FOLLOWS...
0   $ IMP   = indicator for imperfection (0=none, 1=some)
H   $ REFERENCE SURFACE LOCATION RELATIVE TO WALL
1   $ NTYPEZ= control (1 or 3) for reference surface location
5   $ NZVALU= number of meridional callouts for ref. surf.
2   $ NTYPE = control for meaning of callout (2=z, 3=r)
0.000000 $ Z(I)   = axial coordinate of Ith callout, z( 1)
10.00000 $ Z(I)   = axial coordinate of Ith callout, z( 2)
13.00000 $ Z(I)   = axial coordinate of Ith callout, z( 3)
16.00000 $ Z(I)   = axial coordinate of Ith callout, z( 4)
20.00000 $ Z(I)   = axial coordinate of Ith callout, z( 5)
0.6250000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 1)
0.6250000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 2)
0.7250000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 3)
0.8250000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 4)
1.000000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 5) } see Fig. 9

N   $ Do you want to print out r(s), r'(s), etc. for this segment?
H   $ DISCRETE RING INPUT FOLLOWS...
0   $ NRINGS= number (max=20) of discrete rings in this segment
0   $ K=elastic foundation modulus (e.g. lb/in**3) in this seg.
H   $ LINE LOAD INPUT FOLLOWS...
0   $ LINTYP= indicator (0, 1, 2 or 3) for type of line loads
H   $ DISTRIBUTED LOAD INPUT FOLLOWS...
1   $ IDISAB= indicator (0, 1, 2 or 3) for load set A and B
H   $ SURFACE LOAD INPUT FOR LOAD SET "A" FOLLOWS
1   $ NLTYPE=control (0,1,2,3) for type of surface loading
2   $ NPSTAT= number of meridional callouts for surface loading
0   $ NLOAD(1)=indicator for meridional traction (0=none, 1=some)
0   $ NLOAD(2)=indicator for circumferential traction
1   $ NLOAD(3)=indicator for normal pressure (0=none, 1=some)
-1.000000 $ PN(i)  = normal pressure (p.74) at ith callout, PN( 1)
-1.000000 $ PN(i)  = normal pressure (p.74) at ith callout, PN( 2)
2   $ NTYPE = control for meaning of loading callout (2=z, 3=r)
0.000000 $ Z(I)   = axial coordinate of Ith loading callout, z( 1)
20.00000 $ Z(I)   = axial coordinate of Ith loading callout, z( 2)

H   $ SHELL WALL CONSTRUCTION FOLLOWS...
2   $ NWALL=index (1, 2, 4, 5, 6, 7, 8, 9, 10) for wall construction
0.1600000E+08 $ E      = Young's modulus for skin
0.2500000 $ U      = Poisson's ratio for skin
0.1600000 $ SM =mass density of skin (e.g. alum.=.00025 lb-sec**2/in**4)
0.000000 $ ALPHA = coefficient of thermal expansion
0   $ NRS  = control (0 or 1) for addition of smeared stiffeners
-1  $ NSUR = control for thickness input (0 or 1 or -1)
1   $ NTYPET= index (1 or 3) for type of input for thickness
5   $ NTVALU= number of callouts along segment for thickness
2   $ NTYPE = control for meaning of thickness callout (2=z, 3=r)
0.000000 $ Z(I)   = axial coordinate of Ith thickness callout, z( 1)
10.00000 $ Z(I)   = axial coordinate of Ith thickness callout, z( 2)
13.00000 $ Z(I)   = axial coordinate of Ith thickness callout, z( 3)
16.00000 $ Z(I)   = axial coordinate of Ith thickness callout, z( 4)

```

This is the properly annotated version  
of a BTG BOSOR4 input file.

# Table 11 (P. 2 of 4)

```

20.00000 $ Z(I) = axial coordinate of Ith thickness callout, z( 5)
1.250000 $ TVAL(i) = thickness at Ith callout, TVAL( 1)
1.250000 $ TVAL(i) = thickness at Ith callout, TVAL( 2)
1.450000 $ TVAL(i) = thickness at Ith callout, TVAL( 3)
1.650000 $ TVAL(i) = thickness at Ith callout, TVAL( 4)
2.000000 $ TVAL(i) = thickness at Ith callout, TVAL( 5) } see Fig. 9

N $ Do you want to print out ref. surf. location and thickness?
N $ Do you want to print out the C(i,j) at meridional stations?
N $ Do you want to print out distributed loads along meridian?

H $
H $ SEGMENT NUMBER      2      2      2      2      2      2      2      2
H $ NODAL POINT DISTRIBUTION FOLLOWS...
51 $ NMESH = number of node points (5 = min., 98 = max.)( 2)
1 $ NTYPEH= control integer (1 or 3) for nodal point spacing
4 $ NHVALU= number of callouts for nodal point spacing
1 $ IHVALU(I)= Ith callout for nodal point spacing, IHVALU( 1)
25 $ IHVALU(I)= Ith callout for nodal point spacing, IHVALU( 2)
26 $ IHVALU(I)= Ith callout for nodal point spacing, IHVALU( 3)
50 $ IHVALU(I)= Ith callout for nodal point spacing, IHVALU( 4)

0.500000 $ HVALU=meridional arc length between nodal points,HVALU( 1)
0.500000 $ HVALU=meridional arc length between nodal points,HVALU( 2)
1.000000 $ HVALU=meridional arc length between nodal points,HVALU( 3)
1.000000 $ HVALU=meridional arc length between nodal points,HVALU( 4)

H $ REFERENCE SURFACE GEOMETRY FOLLOWS...
1 $ NSHAPE= indicator (1,2 or 4) for geometry of meridian
20.00000 $ R1     = radius at beginning of segment (see p. 66)
20.00000 $ Z1     = global axial coordinate at beginning of segment
20.00000 $ R2     = radius at end of segment
40.00000 $ Z2     = global axial coordinate at end of segment

H $ IMPERFECTION SHAPE FOLLOWS...
0 $ IMP    = indicator for imperfection (0=none, 1=some)
H $ REFERENCE SURFACE LOCATION RELATIVE TO WALL
1 $ NTYPEZ= control (1 or 3) for reference surface location
5 $ NZVALU= number of meridional callouts for ref. surf.
2 $ NTYPE = control for meaning of callout (2=z, 3=r)

20.00000 $ Z(I)   = axial coordinate of Ith callout, z( 1)
22.00000 $ Z(I)   = axial coordinate of Ith callout, z( 2)
25.00000 $ Z(I)   = axial coordinate of Ith callout, z( 3)
30.00000 $ Z(I)   = axial coordinate of Ith callout, z( 4)
40.00000 $ Z(I)   = axial coordinate of Ith callout, z( 5)
1.000000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 1)
1.100000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 2)
1.200000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 3)
1.250000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 4)
1.250000 $ ZVAL   = distance from leftmost surf. to ref. surf.,ZVAL( 5) } see Fig. 9

N $ Do you want to print out r(s), r'(s), etc. for this segment?
H $ DISCRETE RING INPUT FOLLOWS...
0 $ NRINGS= number (max=20) of discrete rings in this segment
0 $ K=elastic foundation modulus (e.g. lb/in**3) in this seg.

H $ LINE LOAD INPUT FOLLOWS...
0 $ LINTYP= indicator (0, 1, 2 or 3) for type of line loads
H $ DISTRIBUTED LOAD INPUT FOLLOWS...
1 $ IDISAB= indicator (0, 1, 2 or 3) for load set A and B
H $ SURFACE LOAD INPUT FOR LOAD SET "A" FOLLOWS
1 $ NLTYPE=control (0,1,2,3) for type of surface loading
2 $ NPSTAT= number of meridional callouts for surface loading
0 $ NLOAD(1)=indicator for meridional traction (0=none, 1=some)
0 $ NLOAD(2)=indicator for circumferential traction
1 $ NLOAD(3)=indicator for normal pressure (0=none, 1=some)

-1.000000 $ PN(i)  = normal pressure (p.74) at ith callout, PN( 1)
-1.000000 $ PN(i)  = normal pressure (p.74) at ith callout, PN( 2)
2 $ NTYPE = control for meaning of loading callout (2=z, 3=r)
20.00000 $ Z(I)   = axial coordinate of Ith loading callout, z( 1)
40.00000 $ Z(I)   = axial coordinate of Ith loading callout, z( 2)

H $ SHELL WALL CONSTRUCTION FOLLOWS...
2 $ NWALL=index (1, 2, 4, 5, 6, 7, 8, 9, 10) for wall construction
0.1600000E+08 $ E     = Young's modulus for skin
0.2500000 $ U     = Poisson's ratio for skin
0.1600000 $ SM =mass density of skin (e.g. alum.=.00025 lb-sec**2/in**4)
0.000000 $ ALPHA = coefficient of thermal expansion
0 $ NRS  = control (0 or 1) for addition of smeared stiffeners
-1 $ NSUR = control for thickness input (0 or 1 or -1)
1 $ NTYPET= index (1 or 3) for type of input for thickness
5 $ NTVVALU= number of callouts along segment for thickness
2 $ NTYPE = control for meaning of thickness callout (2=z, 3=r)
20.00000 $ Z(I)   = axial coordinate of Ith thickness callout, z( 1)
22.00000 $ Z(I)   = axial coordinate of Ith thickness callout, z( 2)
25.00000 $ Z(I)   = axial coordinate of Ith thickness callout, z( 3)

```

# Table II (P. 3 of 9)

30.00000 \$ Z(I) = axial coordinate of Ith thickness callout, z( 4)  
 40.00000 \$ Z(I) = axial coordinate of Ith thickness callout, z( 5)  
 2.000000 \$ TVAL(i) = thickness at Ith callout, TVAL( 1)  
 2.200000 \$ TVAL(i) = thickness at Ith callout, TVAL( 2) } see Fig. 9  
 2.400000 \$ TVAL(i) = thickness at Ith callout, TVAL( 3)  
 2.500000 \$ TVAL(i) = thickness at Ith callout, TVAL( 4)  
 2.500000 \$ TVAL(i) = thickness at Ith callout, TVAL( 5)  
 N \$ Do you want to print out ref. surf. location and thickness?  
 N \$ Do you want to print out the C(i,j) at meridional stations?  
 N \$ Do you want to print out distributed loads along meridian?  
 H \$  
 H \$ GLOBAL DATA BEGINS...  
 0 \$ NLAST = plot options (-1=none, 0=geometry, 1=u,v,w)  
 N \$ Are there any regions for which you want expanded plots?  
 0 \$ N0B = starting number of circ. waves (buckling analysis)  
 0 \$ NMNINB = minimum number of circ. waves (buckling analysis)  
 10 \$ NMNAXB = maximum number of circ. waves (buckling analysis)  
 1 \$ INCRB = increment in number of circ. waves (buckling)  
 1 \$ NVEC = number of eigenvalues for each wave number  
 0.000000 \$ P = pressure or surface traction multiplier  
 15000.00 \$ DP = pressure or surface traction multiplier increment  
 0.000000 \$ TEMP = temperature rise multiplier  
 0.000000 \$ DTEMP = temperature rise multiplier increment  
 0.000000 \$ OMEGA = angular vel. about axis of revolution (rad/sec)  
 0.000000 \$ DOMEGA = angular velocity increment (rad/sec)  
 H \$ CONSTRAINT CONDITIONS FOLLOW....  
 2 \$ How many segments in the structure?  
 H \$  
 H \$ CONSTRAINT CONDITIONS FOR SEGMENT NO. 1 1 1 1  
 H \$ POLES INPUT FOLLOWS...  
 1 \$ Number of poles (places where r=0) in SEGMENT( 1)  
 1 \$ IPOLE = nodal point number of pole, IPOLE( 1)  
 H \$ INPUT FOR CONSTRAINTS TO GROUND FOLLOWS...  
 0 \$ At how many stations is this segment constrained to ground?  
 H \$ JUNCTION CONDITION INPUT FOLLOWS...  
 N \$ Is this segment joined to any lower-numbered segments?  
 H \$  
 H \$ CONSTRAINT CONDITIONS FOR SEGMENT NO. 2 2 2 2  
 H \$ POLES INPUT FOLLOWS...  
 0 \$ Number of poles (places where r=0) in SEGMENT( 2)  
 H \$ INPUT FOR CONSTRAINTS TO GROUND FOLLOWS...  
 1 \$ At how many stations is this segment constrained to ground?  
 51 \$ INODE = nodal point number of constraint to ground, INODE( 1)  
 1 \$ IUSTAR=axial displacement constraint (0 or 1 or 2)  
 0 \$ IVSTAR=circumferential displacement (0=free, 1=0, 2=imposed)  
 0 \$ IWSTAR=radial displacement (0=free, 1=constrained, 2=imposed)  
 1 \$ ICHI=meridional rotation (0=free, 1=constrained, 2=imposed)  
 0.000000 \$ D1 = radial component of offset of ground support  
 0.000000 \$ D2 = axial component of offset of ground support  
 Y \$ Is this constraint the same for both prebuckling and buckling?  
 H \$ JUNCTION CONDITION INPUT FOLLOWS...  
 Y \$ Is this segment joined to any lower-numbered segments?  
 1 \$ At how many stations is this segment joined to previous segs.?  
 1 \$ INODE = node in current segment (ISEG) of junction, INODE( 1)  
 1 \$ JSEG = segment no. of lowest segment involved in junction  
 91 \$ JNODE = node in lowest segmnt (JSEG) of junction  
 1 \$ IUSTAR= axial displacement (0=not slaved, 1=slaved)  
 1 \$ IVSTAR= circumferential displacement (0=not slaved, 1=slaved)  
 1 \$ IWSTAR= radial displacement (0=not slaved, 1=slaved)  
 1 \$ ICHI = meridional rotation (0=not slaved, 1=slaved)  
 0.000000 \$ D1 = radial component of juncture gap  
 0.000000 \$ D2 = axial component of juncture gap  
 Y \$ Is this constraint the same for both prebuckling and buckling?  
 H \$ RIGID BODY CONSTRAINT INPUT FOLLOWS...  
 Y \$ Given existing constraints, are rigid body modes possible?  
 Y \$ Do you wish to prevent rigid body motion?  
 2 \$ ISEG = segment no. at which to prevent rigid body motion  
 51 \$ INODE = node no. at which to prevent rigid body motion  
 1 \$ IUSTAR= axial n=0 rigid body constraint (0=none, 1=some)  
 1 \$ IVSTAR= circ. n=0 rigid body constraint (usually equals 1)  
 0 \$ IWSTAR= radial n=0 rigid body constraint (usually equals 0)  
 1 \$ ICHI = meridional rot. rigid body constraint  
 1 \$ IUSTAR= axial n=1 rigid body constraint (usually equals 1)  
 1 \$ IVSTAR= circ. n=1 rigid body constraint (usually equals 1)  
 0 \$ IWSTAR= radial n=1 rigid body constraint (usually equals 0)  
 1 \$ ICHI = meridional rot. rigid body constraint  
 H \$ "GLOBAL3" QUESTIONS (AT END OF CASE)...  
 Y \$ Do you want to list output for segment( 1)

Table II (P. 4 of 4)

Y            \$ Do you want to list output for segment( 2)  
Y            \$ Do you want to list forces in the discrete rings, if any?

end of doer. ALL file.

Table 12 (2 pages)      Ober. ALL

buckling of tank (INDIC=1)

```

1 1 0 2 $ INDIC,NPRT,ISTRES,NSEG
H $ Segment number      1     1     1     1
91 1 4 $ NMESH,NTYPEH,NHVALU
1 45 46 90 $ (IHVALU(K,ISEG), K=1,NHVALU)
1.000000E+00 1.000000E+00 5.000000E-01 5.000000E-01 $ (HVALU(K,ISEG), K=1,NHVALU)
2 $ indicator for meridian geometry
0.000000E+00 0.000000E+00 2.000000E+01 2.000000E+01 $ R1,Z1,R2,Z2
0.000000E+00 2.000000E+01 -1.000000E+00 $ RC,ZC,SROT
0 $ indicator for imperfection
1 5 2 $ NTYPEZ,NZVALU,NTYPE
0.000000E+00 1.000000E+01 1.300000E+01 1.600000E+01
2.000000E+01
6.250000E-01 6.250000E-01 7.250000E-01 8.250000E-01
1.000000E+00

N $ do you want to print r(s), etc.?
0, 0, 0, 1 $ NRINGS,K,LINTYP,DISAB
1, 2, 0, 0 $ NLTYPE,NPSTAT,NLOAD(1),NLOAD(2)
1, -1., -1., 2 $ NLOAD(3),PN(1),PN(2),NTYPE
0.000000E+00 2.000000E+01 $ Z(1),Z(2) callouts
2 $ NWALL = 2 for isotropic
1.600000E+07 2.500000E-01 1.600000E-01 $ E, U, SM
0., 0, -1, 1 $ ALPHA,NRS,NSUR,NTYPET
5 2 $ NTVALU, NTYPE
0.000000E+00 1.000000E+01 1.300000E+01 1.600000E+01
2.000000E+01
1.250000E+00 1.250000E+00 1.450000E+00 1.650000E+00
2.000000E+00

N $ do you want to print refsurf etc.?
N $ do you want to print C(i,j)?
N $ do you want to print loads?
H $ Segment number      2     2     2     2
51 1 4 $ NMESH,NTYPEH,NHVALU
1 25 26 50 $ (IHVALU(K,ISEG), K=1,NHVALU)
5.000000E-01 5.000000E-01 1.000000E+00 1.000000E+00 $ (HVALU(K,ISEG), K=1,NHVALU)
1 $ indicator for meridian geometry
2.000000E+01 2.000000E+01 2.000000E+01 4.000000E+01 $ R1,Z1,R2,Z2
0 $ indicator for imperfection
1 5 2 $ NTYPEZ,NZVALU,NTYPE
2.000000E+01 2.200000E+01 2.500000E+01 3.000000E+01
4.000000E+01
1.000000E+00 1.100000E+00 1.200000E+00 1.250000E+00
1.250000E+00

N $ do you want to print r(s), etc.?
0, 0, 0, 1 $ NRINGS,K,LINTYP,DISAB
1, 2, 0, 0 $ NLTYPE,NPSTAT,NLOAD(1),NLOAD(2)
1, -1., -1., 2 $ NLOAD(3),PN(1),PN(2),NTYPE
2.000000E+01 4.000000E+01 $ Z(1),Z(2) callouts
2 $ NWALL = 2 for isotropic
1.600000E+07 2.500000E-01 1.600000E-01 $ E, U, SM
0., 0, -1, 1 $ ALPHA,NRS,NSUR,NTYPET
5 2 $ NTVALU, NTYPE
2.000000E+01 2.200000E+01 2.500000E+01 3.000000E+01
4.000000E+01
2.000000E+00 2.200000E+00 2.400000E+00 2.500000E+00
2.500000E+00

N $ do you want to print refsurf etc.?
N $ do you want to print C(i,j)?
N $ do you want to print loads?
H $ GLOBAL DATA BEGINS...
0 $ NLAST
N $ any expanded plots?
0 0 10 1 1 $ NOB,NMINB,NMAXB,INCRB,NVEC
0.000000E+00 1.500000E+04 $ P,DP
0., 0., 0., 0. $ TEMP,DTEMP,OMEGA,DOMEGA
H $ CONSTRAINT CONDITIONS FOLLOW....
2 $ how many segments?
H $ CONSTRAINT CONDITIONS FOR SEGMENT 1 1 1 1
1, 1, 0 $ one pole, IPOLE, to ground
N $ joined to other lower segments?
H $ CONSTRAINT CONDITIONS FOR SEGMENT 2 2 2 2
0, 1 $ number of poles, numb. to ground
51 $ node connected to ground
1 0 0 1 $ IUSTAR,IVSTAR,IWSTAR,ICHI
0., 0. $ D1,D2
Y $ constraint same for prebuck & buck?
Y $ joined to lower segments?
1, 1, 1 $ how many?, INODE, JSEG

```

by

as produced by

Ober. ALL

This is the version of Ober. ALL

BOSDEC.

## Table 12 (p. 2 of 2)

91 \$ jseg node of the junction  
1, 1, 1, 0., 0. \$ connection cond.  
Y \$ constraint same for prebuck & buck?  
H \$ RIGID BODY CONSTRAINT CONDITIONS  
Y \$ is rigid body motion possible?  
Y \$ want to prevent rigid body motion?  
2 \$ Segment no. to prevent rigid body  
51 \$ node to prevent rigid body  
1, 1, 0, 1 \$ rigid body for n=0 waves  
1, 1, 0, 1 \$ rigid body for n=1 waves  
Y \$ list output for segment 1?  
Y \$ list output for segment 2?  
Y \$ list output for discrete rings?

end of doer. ABL

# Table 13

## doer. BEG

```

n      $ Do you want a tutorial session and tutorial output?
20.00000 $ radius of the tank: RADIUS
40.00000 $ total length of the cylinder: LENGTH
0.1600000E+08 $ elastic modulus of the shell wall: EMOD
0.2500000 $ Poisson ratio of the shell wall: NU
0.1600000
91       $ weight density of the shell wall: DENSTY
51       $ number of nodal points in the dome: NODSPH
5        $ number of nodal points in the cylinder: NODCYL
5        $ number of axial callouts in the dome: NPTSPH
5        $ Number IZSPH of rows in the array ZSPH: IZSPH
0.000000 $ axial location of callout in the dome: ZSPH( 1)
10.00000 $ axial location of callout in the dome: ZSPH( 2)
13.00000 $ axial location of callout in the dome: ZSPH( 3)
16.00000 $ axial location of callout in the dome: ZSPH( 4)
20.00000 $ axial location of callout in the dome: ZSPH( 5)
5        $ Number of axial callouts in the cylinder: NPTCYL
5        $ Number IZCYL of rows in the array ZCYL: IZCYL
20.00000 $ axial location of callout in the cylinder: ZCYL( 1)
22.00000 $ axial location of callout in the cylinder: ZCYL( 2)
25.00000 $ axial location of callout in the cylinder: ZCYL( 3)
30.00000 $ axial location of callout in the cylinder: ZCYL( 4)
40.00000 $ axial location of callout in the cylinder: ZCYL( 5)
5        $ Number IZREFSP of rows in the array ZREFSP: IZREFSP
0.6250000 $ location of ref. surf. in the dome: ZREFSP( 1)
0.6250000 $ location of ref. surf. in the dome: ZREFSP( 2)
0.7250000 $ location of ref. surf. in the dome: ZREFSP( 3)
0.8250000 $ location of ref. surf. in the dome: ZREFSP( 4)
1.000000 $ location of ref. surf. in the dome: ZREFSP( 5)
1.250000 $ wall thickness in the dome: THKSPH( 1)
1.250000 $ wall thickness in the dome: THKSPH( 2)
1.450000 $ wall thickness in the dome: THKSPH( 3)
1.650000 $ wall thickness in the dome: THKSPH( 4)
2.000000 $ wall thickness in the dome: THKSPH( 5)
5        $ Number IZREFCY of rows in the array ZREFCY: IZREFCY
1.000000 $ location of the ref. surf. in the cylinder: ZREFCY( 1)
1.100000 $ location of the ref. surf. in the cylinder: ZREFCY( 2)
1.200000 $ location of the ref. surf. in the cylinder: ZREFCY( 3)
1.250000 $ location of the ref. surf. in the cylinder: ZREFCY( 4)
1.250000 $ location of the ref. surf. in the cylinder: ZREFCY( 5)
2.000000 $ thickness of the cylindrical shell: THKCYL( 1)
2.200000 $ thickness of the cylindrical shell: THKCYL( 2)
2.400000 $ thickness of the cylindrical shell: THKCYL( 3)
2.500000 $ thickness of the cylindrical shell: THKCYL( 4)
2.500000 $ thickness of the cylindrical shell: THKCYL( 5)
0        $ low end of range of buckling circ. waves: NBUKLO
10       $ high end of range of buckling circ. waves: NBUKHI
1        $ Number NCASES of load cases (environments): NCASES
15000.00 $ uniform external pressure: PRESS( 1)
1.000000 $ allowable buckling load (Use 1.0): BUCKLA( 1)
1.300000 $ factor of safety for buckling: BUCKLF( 1)
2        $ Number JSTRESS of columns in the array, STRESS: JSTRESS
120000  $ maximum allowable effective stress: STRESSA( 1, 1)
120000  $ maximum allowable effective stress: STRESSA( 1, 2)
1.000000 $ factor of safety for stress: STRESSF( 1, 1)
1.000000 $ factor of safety for stress: STRESSF( 1, 2)

```

input for BEGFI

# Table 14 (2 pages)      doer, DEC

n	\$ Do you want a tutorial session and tutorial output?
3	\$ Choose a decision variable (1, 2, 3, ...)
0.6250000	\$ Lower bound of variable no. ( 3 )
1.500000	\$ Upper bound of variable no. ( 3 )
Y	\$ Any more decision variables (Y or N) ?
4	\$ Choose a decision variable (1, 2, 3, ...)
0.6250000	\$ Lower bound of variable no. ( 4 )
2.500000	\$ Upper bound of variable no. ( 4 )
Y	\$ Any more decision variables (Y or N) ?
5	\$ Choose a decision variable (1, 2, 3, ...)
0.6250000	\$ Lower bound of variable no. ( 5 )
2.500000	\$ Upper bound of variable no. ( 5 )
Y	\$ Any more decision variables (Y or N) ?
8	\$ Choose a decision variable (1, 2, 3, ...)
1.250000	\$ Lower bound of variable no. ( 8 )
2.500000	\$ Upper bound of variable no. ( 8 )
Y	\$ Any more decision variables (Y or N) ?
9	\$ Choose a decision variable (1, 2, 3, ...)
1.250000	\$ Lower bound of variable no. ( 9 )
2.500000	\$ Upper bound of variable no. ( 9 )
Y	\$ Any more decision variables (Y or N) ?
10	\$ Choose a decision variable (1, 2, 3, ...)
1.250000	\$ Lower bound of variable no. (10)
2.500000	\$ Upper bound of variable no. (10)
Y	\$ Any more decision variables (Y or N) ?
11	\$ Choose a decision variable (1, 2, 3, ...)
0.6250000	\$ Lower bound of variable no. (11)
1.500000	\$ Upper bound of variable no. (11)
Y	\$ Any more decision variables (Y or N) ?
12	\$ Choose a decision variable (1, 2, 3, ...)
0.6250000	\$ Lower bound of variable no. (12)
1.500000	\$ Upper bound of variable no. (12)
Y	\$ Any more decision variables (Y or N) ?
13	\$ Choose a decision variable (1, 2, 3, ...)
0.6250000	\$ Lower bound of variable no. (13)
1.500000	\$ Upper bound of variable no. (13)
Y	\$ Any more decision variables (Y or N) ?
16	\$ Choose a decision variable (1, 2, 3, ...)
1.250000	\$ Lower bound of variable no. (16)
3.000000	\$ Upper bound of variable no. (16)
Y	\$ Any more decision variables (Y or N) ?
17	\$ Choose a decision variable (1, 2, 3, ...)
1.250000	\$ Lower bound of variable no. (17)
3.000000	\$ Upper bound of variable no. (17)
Y	\$ Any more decision variables (Y or N) ?
18	\$ Choose a decision variable (1, 2, 3, ...)
1.250000	\$ Lower bound of variable no. (18)
2.500000	\$ Upper bound of variable no. (18)
Y	\$ Any more decision variables (Y or N) ?
19	\$ Choose a decision variable (1, 2, 3, ...)
1.250000	\$ Lower bound of variable no. (19)
2.500000	\$ Upper bound of variable no. (19)
n	\$ Any more decision variables (Y or N) ?
Y	\$ Any linked variables (Y or N) ?
14	\$ Choose a linked variable (1, 2, 3, ...)
1	\$ Choose type of linking (1=polynomial; 2=user-defined)
19	\$ To which variable is this variable linked?
0.5000000	\$ Assign a value to the linking coefficient, C(j)
1	\$ To what power is the decision variable raised?
n	\$ Any other decision variables in the linking expression?
n	\$ Any constant C0 in the linking expression?
Y	\$ Any more linked variables (Y or N) ?
15	\$ Choose a linked variable (1, 2, 3, ...)
1	\$ Choose type of linking (1=polynomial; 2=user-defined)
19	\$ To which variable is this variable linked?
0.5000000	\$ Assign a value to the linking coefficient, C(j)
1	\$ To what power is the decision variable raised?
n	\$ Any other decision variables in the linking expression?
n	\$ Any constant C0 in the linking expression?
Y	\$ Any more linked variables (Y or N) ?
20	\$ Choose a linked variable (1, 2, 3, ...)
1	\$ Choose type of linking (1=polynomial; 2=user-defined)
19	\$ To which variable is this variable linked?
1.000000	\$ Assign a value to the linking coefficient, C(j)
1	\$ To what power is the decision variable raised?
n	\$ Any other decision variables in the linking expression?
n	\$ Any constant C0 in the linking expression?
Y	\$ Any more linked variables (Y or N) ?

Input for DECIDE

See Table 16

$$ZREFCY(4) = \frac{1}{2} THKCYL(4)$$

$$ZREFCY(5) = \frac{1}{2} THKCYL(4)$$

$$THKCYL(5) = THKCYL(4)$$

the cyl. segment

The reference  
surface is the  
middle surface  
of the cyl.  
segment  
10 inches  
upper +  
middle +  
lower

The upper 10 inches  
of the cyl. segment  
has constant thick-  
ness

Table 14 (p. 2 of 2)

n	\$ Any inequality relations among variables? (type H)
Y	\$ Any escape variables (Y or N) ?
Y	\$ Want to have escape variables chosen by default?

Input for DECIDE

## Table 15

### doer, OPT

Note →

```
n      0      $ Do you want a tutorial session and tutorial output?  
n      2      $ Choose an analysis you DON'T want (1, 2,...), IBEHAV  
n      2      $ NPRINT= output index (0=GOOD, 1=ok, 2=debug, 3=too much)  
n      5      $ Choose type of analysis (1=opt., 2=fixed, 3=sensit.) ITYPE  
n      5      $ How many design iterations in this run (3 to 25)?  
n      2      $ Take "shortcuts" for perturbed designs (Y or N)?  
n      2      $ Choose 1 or 2 or 3 or 4 or 5 for IDESIGN  
n      1      $ Choose 1 or 2 or 3 or 4 or 5 for move limits, IMOVE  
y      1      $ Do you want default (RATIO=10) for initial move limit jump?  
y      1      $ Do you want the default perturbation (dx/x = 0.05)?  
n      1      $ Do you want to have dx/x modified by GENOPT?  
n      1      $ Do you want to reset total iterations to zero (Type H)?
```

Input for MAIN SETUP  
for analysis of a fixed design

# Table 16 (Bpp.) doer.OPM / output from "OPTIMIZE"

```

n      $ Do you want a tutorial session and tutorial output?
0      $ Choose an analysis you DON'T want (1, 2...), IBEHAV
2      $ NPRINT= output index (0=GOOD, 1=ok, 2=debug, 3=too much)
2      $ Choose type of analysis (1=opt., 2=fixed, 3=sensit.) ITYPE
5      $ How many design iterations in this run (3 to 25)?
n      $ Take "shortcuts" for perturbed designs (Y or N)?
3      $ Choose 1 or 2 or 3 or 4 or 5 for IDESIGN
4      $ Choose 1 or 2 or 3 or 4 or 5 for move limits, IMOVE
y      $ Do you want default (RATIO=10) for initial move limit jump?
y      $ Do you want the default perturbation (dx/x = 0.05)?
n      $ Do you want to have dx/x modified by GENOPT?
n      $ Do you want to reset total iterations to zero (Type H)?

```

\*\*\*\*\* END OF THE doer.OPM FILE \*\*\*\*\*  
\*\*\*\*\* JUNE, 2009 VERSION OF GENOPT \*\*\*\*\*  
\*\*\*\*\* BEGINNING OF THE doer.OPM FILE \*\*\*\*\*

## \*\*\*\*\* MAIN PROCESSOR \*\*\*\*\*

The purpose of the mainprocessor, OPTIMIZE, is to perform, in a batch mode, the work specified by MAINSETUP for the case called doer. Results are stored in the file doer.OPM. Please inspect doer.OPM before doing more design iterations.

STRUCTURAL ANALYSIS FOR DESIGN ITERATION NO. 0								
	VAR. DEC.	ESCAPE	LINK.	LINKING	LOWER	CURRENT	UPPER	DEFINITION
0								
	VAR. NO.	VAR.	VAR.	TO	CONSTANT	BOUND	VALUE	
n	1	N	N	N	0	0.00E+00	0.00E+00	6.2500E-01
the dome:	ZREFSP(1)							0.00E+00
n	2	N	N	N	0	0.00E+00	0.00E+00	6.2500E-01
the dome:	ZREFSP(2)							0.00E+00
n	3	Y	N	N	0	0.00E+00	6.25E-01	7.2500E-01
the dome:	ZREFSP(3)							1.50E+00
n	4	Y	N	N	0	0.00E+00	6.25E-01	8.2500E-01
the dome:	ZREFSP(4)							2.50E+00
n	5	Y	N	N	0	0.00E+00	6.25E-01	1.0000E+00
the dome:	ZREFSP(5)							2.50E+00
me:	THKSPH(1)							wall thickness in the do»
me:	THKSPH(2)							wall thickness in the do»
me:	THKSPH(3)							wall thickness in the do»
me:	THKSPH(4)							wall thickness in the do»
me:	THKSPH(5)							wall thickness in the do»
f.	11	Y	N	N	0	0.00E+00	6.25E-01	1.0000E+00
in the cylinder:	ZREFCY(1)							1.50E+00
f.	12	Y	N	N	0	0.00E+00	6.25E-01	1.1000E+00
in the cylinder:	ZREFCY(2)							1.50E+00
f.	13	Y	N	N	0	0.00E+00	6.25E-01	1.2000E+00
in the cylinder:	ZREFCY(3)							1.50E+00
f.	14	N	N	Y	19	5.00E-01	0.00E+00	1.2500E+00
in the cylinder:	ZREFCY(4)							0.00E+00
f.	15	N	N	Y	19	5.00E-01	0.00E+00	1.2500E+00
in the cylinder:	ZREFCY(5)							0.00E+00
ical shell:	THKCYL(1)							thickness of the cylindr»
ical shell:	THKCYL(2)							thickness of the cylindr»
ical shell:	THKCYL(3)							thickness of the cylindr»
ical shell:	THKCYL(4)							thickness of the cylindr»
ical shell:	THKCYL(5)							thickness of the cylindr»
BEHAVIOR FOR 1 ENVIRONMENT (LOAD SET)								
CONSTRAINT NUMBER	BEHAVIOR VALUE	DEFINITION						

The starting design.  
See Table 16 of [13].

# Table 16, p. 2 of 3

BEHAVIOR FOR LOAD SET NUMBER, ILOADX= 1

BIGBOSOR4 input file for: buckling load (INDIC=1)  
doer.BEHX1

WEIGHT OF THE BIGBOSOR4 MODEL OF THE TANK  
TOTMAS = 1.5458E+03

BUCKLING LOAD FACTORS AND MODES (BEHX1)

5.1170E+00(	0)
5.0881E+00(	1)
2.3019E+00(	2)
1.8904E+00(	3) ← critical eigenvalue & mode
2.9298E+00(	4)
4.4143E+00(	5)
5.6151E+00(	6)
6.1995E+00(	7)
7.0420E+00(	8)
8.1151E+00(	9)
9.3925E+00(	10)

Critical buckling load factor, BUCKL= 1.8904E+00

Critical number of circumferential waves, NWVCRT= 3  
1 1.890413 tank buckling eigenvalue: BUCKL(1 )

BEHAVIOR OVER J = shell segment number

BIGBOSOR4 input file for: maximum effective stress (INDIC=0)  
doer.BEHX2

Shell skin maximum effective stress, at nodal point 38	SKNMAX= 1.2234E+05
Shell skin maximum effective stress, at nodal point 18	SKNMAX= 1.0877E+05

\*\*\*\*\* MAXIMUM EFFECTIVE STRESS IN ISOTROPIC WALL \*\*\*\*\*

STRMAX= 1.2234E+05

\*\*\*\*\*

2 122343.1 effective stress in shell segment: STRESS(1 ,1 )

shell segment ① (fig. 1)

shell segment ② (fig. 1)

BIGBOSOR4 input file for: maximum effective stress (INDIC=0)  
doer.BEHX2

3 108771.6 effective stress in shell segment: STRESS(1 ,2 )

\*\*\*\*\* RESULTS FOR LOAD SET NO. 1 \*\*\*\*\*

PARAMETERS WHICH DESCRIBE BEHAVIOR (e.g. stress, buckling load)

BEH. CURRENT

NO. VALUE DEFINITION

1	1.890E+00	tank buckling eigenvalue: BUCKL(1 )
2	1.223E+05	effective stress in shell segment: STRESS(1 ,1 )
3	1.088E+05	effective stress in shell segment: STRESS(1 ,2 )

\*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\*

The phrase, "NOT APPLY", for MARGIN VALUE means that that particular margin value is exactly zero.

\*\*\* END NOTE \*\*\* END NOTE \*\*\* END NOTE \*\*\* END NOTE \*\*\*

\*\*\*\*\* RESULTS FOR LOAD SET NO. 1 \*\*\*\*\*

MARGINS CORRESPONDING TO CURRENT DESIGN (F.S.= FACTOR OF SAFETY)

MARGIN CURRENT

NO. VALUE DEFINITION

1	4.542E-01	(BUCKL(1 )/BUCKLA(1 )) / BUCKLF(1 )-1; F.S.= 1.30
2	-1.083E-01	(STRESSA(1 ,1 )/STRESS(1 ,1 )) / STRESSF(1 ,1 )-1; F.S.= 1.10
3	2.935E-03	(STRESSA(1 ,2 )/STRESS(1 ,2 )) / STRESSF(1 ,2 )-1; F.S.= 1.10

\*\*\*\*\* DESIGN OBJECTIVE \*\*\*\*\*

CURRENT VALUE OF THE OBJECTIVE FUNCTION:

VAR. CURRENT

NO. VALUE DEFINITION

1	1.546E+03	weight of the BIGBOSOR4 model: WEIGHT
---	-----------	---------------------------------------

(16)

# Table 16 (p. 3 of 3)

\*\*\*\*\* DESIGN OBJECTIVE \*\*\*\*\*  
 \*\*\*\*\* ALL 1 LOAD CASES PROCESSED \*\*\*\*\*  
 \*\*\*\*\*

PARAMETERS WHICH ARE ALWAYS FIXED. NONE CAN BE DECISION VARIAB.

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	2.000E+01	radius of the tank: RADIUS
2	4.000E+01	total length of the cylinder: LENGTH
3	1.600E+07	elastic modulus of the shell wall: EMOD
4	2.500E-01	Poisson ratio of the shell wall: NU
5	1.600E-01	weight density of the shell wall: DENSTY
6	0.000E+00	axial location of callout in the dome: ZSPH(1 )
7	1.000E+01	axial location of callout in the dome: ZSPH(2 )
8	1.300E+01	axial location of callout in the dome: ZSPH(3 )
9	1.600E+01	axial location of callout in the dome: ZSPH(4 )
10	2.000E+01	axial location of callout in the dome: ZSPH(5 )
11	2.000E+01	axial location of callout in the cylinder: ZCYL(1 )
12	2.200E+01	axial location of callout in the cylinder: ZCYL(2 )
13	2.500E+01	axial location of callout in the cylinder: ZCYL(3 )
14	3.000E+01	axial location of callout in the cylinder: ZCYL(4 )
15	4.000E+01	axial location of callout in the cylinder: ZCYL(5 )

PARAMETERS WHICH ARE ENVIRONMENTAL FACTORS (e.g. loads, temps.)

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.500E+04	uniform external pressure: PRESS(1 )

PARAMETERS WHICH ARE CLASSIFIED AS ALLOWABLES (e.g. max. stress)

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.000E+00	allowable buckling load (Use 1.0): BUCKLA(1 )
2	1.200E+05	maximum allowable effective stress: STRESSA(1 ,1 )
3	1.200E+05	maximum allowable effective stress: STRESSA(1 ,2 )

PARAMETERS WHICH ARE FACTORS OF SAFETY

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.300E+00	factor of safety for buckling: BUCKLF(1 )
2	1.100E+00	factor of safety for stress: STRESSF(1 ,1 )
3	1.100E+00	factor of safety for stress: STRESSF(1 ,2 )

0 INEQUALITY CONSTRAINTS WHICH MUST BE SATISFIED

DESCRIPTION OF FILES USED AND GENERATED IN THIS RUN:

doer.NAM = This file contains only the name of the case.  
 doer.OPM = Output data. Please list this file and inspect  
           carefully before proceeding.  
 doer.OPP = Output file containing evolution of design and  
           margins since the beginning of optimization cycles.  
 doer.CBL = Labelled common blocks for analysis.  
           (This is an unformatted sequential file.)  
 doer.OPT = This file contains the input data for MAINSETUP  
           as well as OPTIMIZE. The batch command OPTIMIZE  
           can be given over and over again without having  
           to return to MAINSETUP because doer.OPT exists.  
 URPROMPT.DAT= Prompt file for interactive input.

For further information about files used and generated  
 during operation of GENOPT, give the command HELPG FILES.

Menu of commands: CHOOSEPLOT, OPTIMIZE, MAINSETUP, CHANGE,  
 DECIDE, SUPEROPT

IN ORDER TO AVOID FALSE CONVERGENCE OF THE DESIGN, BE SURE TO  
 RUN "OPTIMIZE" MANY TIMES DURING AN OPTIMIZATION AND/OR USE  
 THE "GLOBAL" OPTIMIZING SCRIPT, "SUPEROPT".

\*\*\*\*\* END OF doer.OPM FILE \*\*\*\*\*

Output from BIGBOSOR4 (bosorplot)

## doer..R,Z\_RingLocation

Axial Station

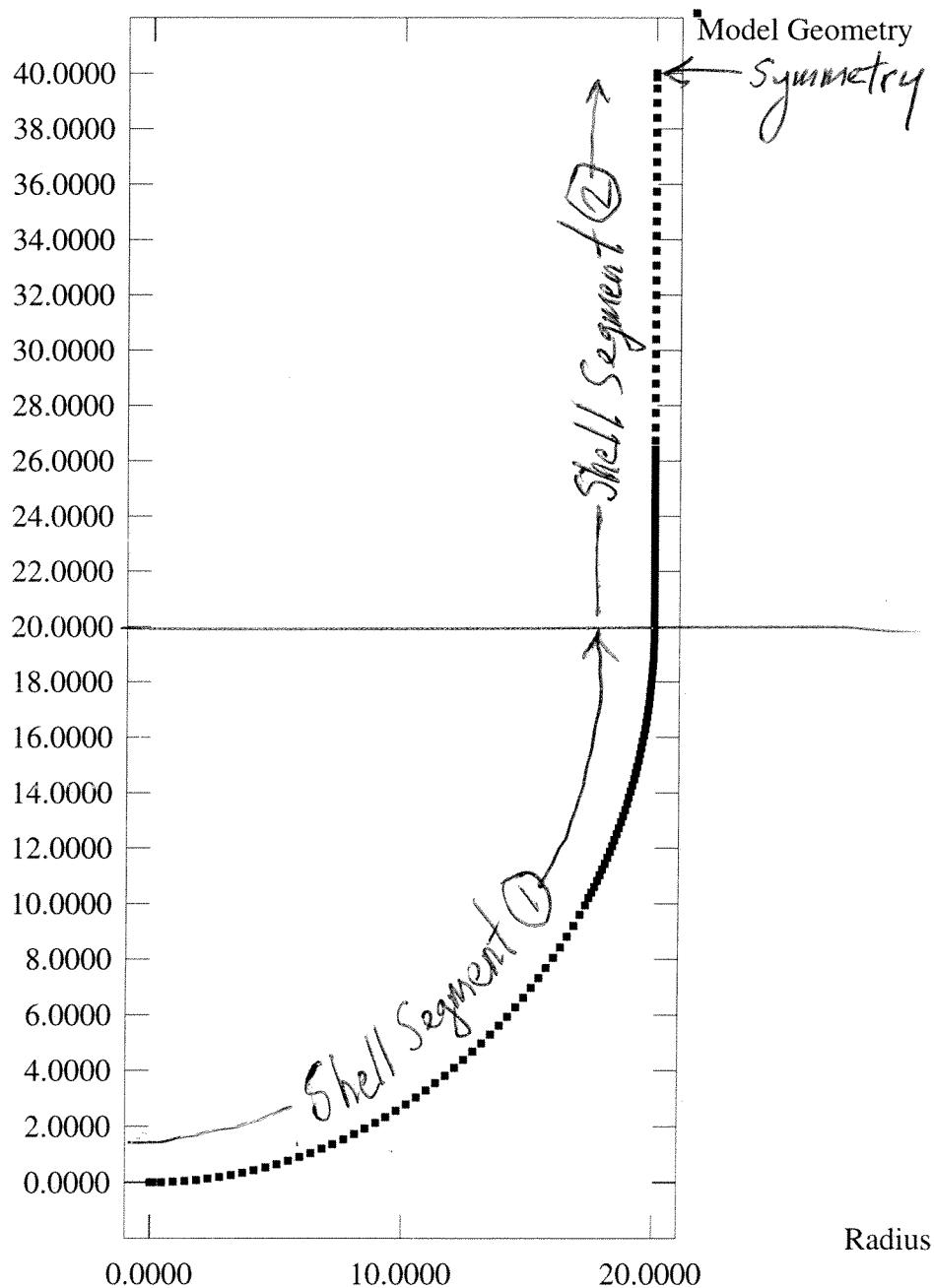
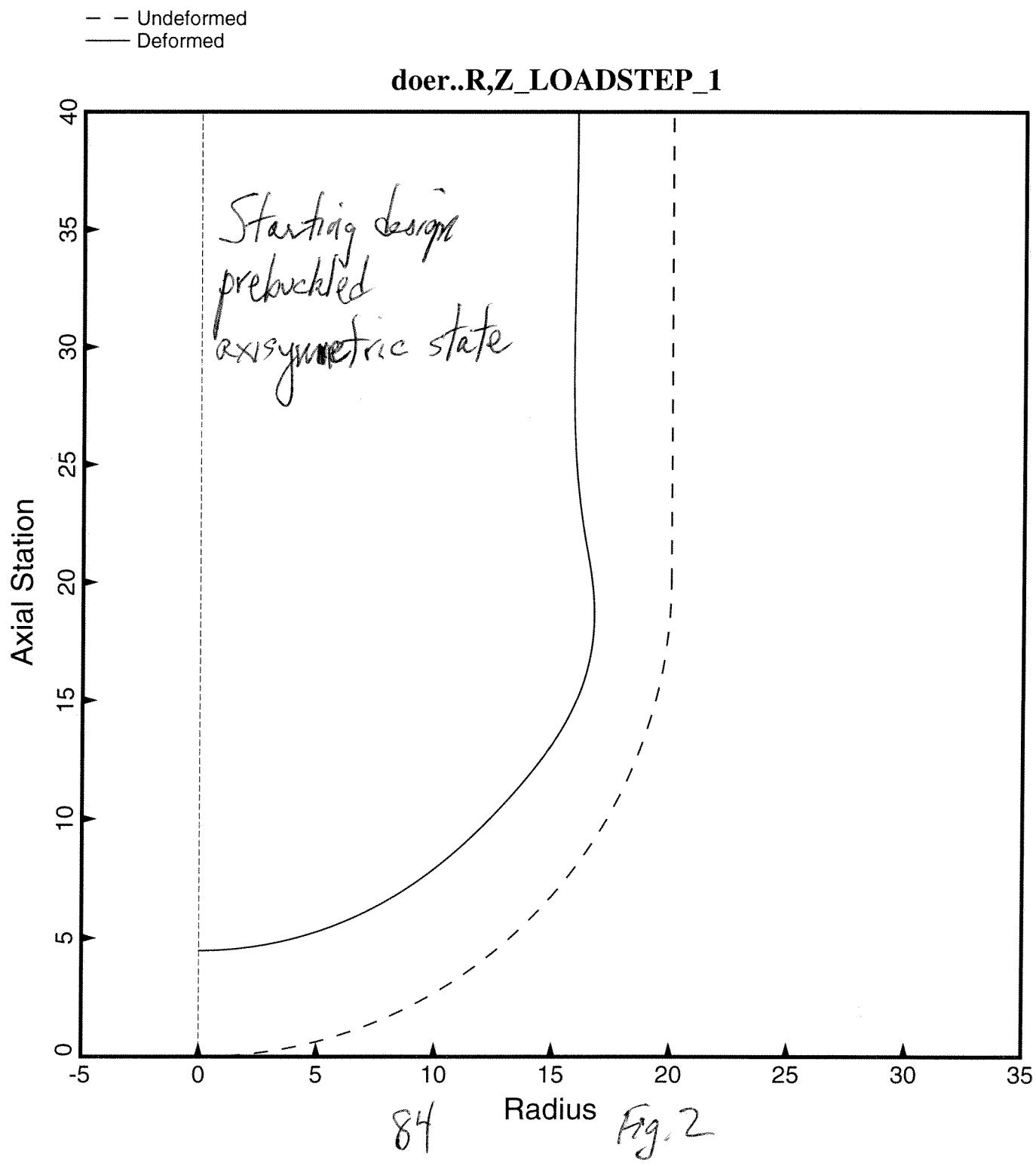
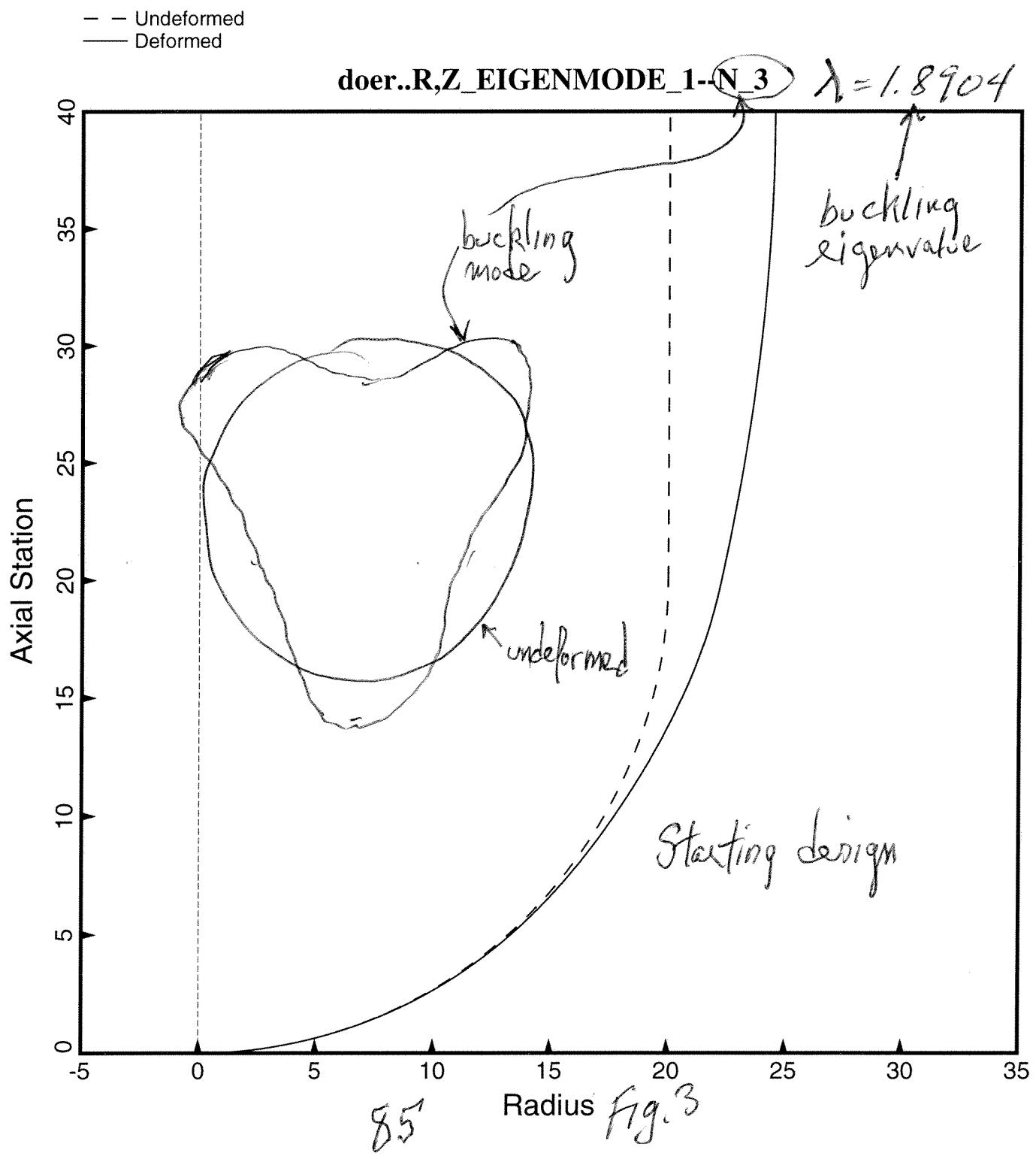


Fig. 1

Output from BIGBOSUR4 (bosopplot)

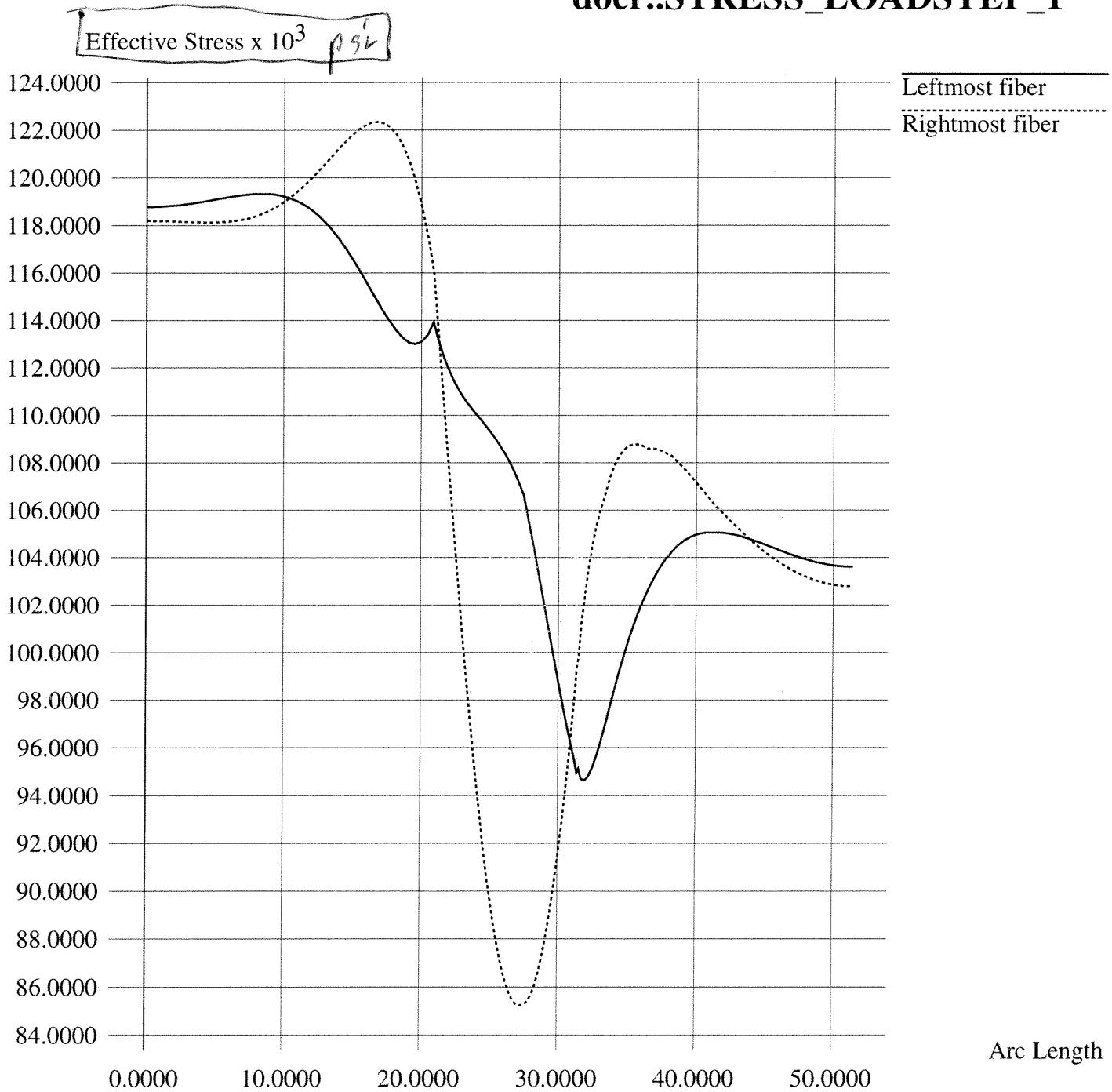


Output from BIGBOSOR4 (bosplot)  
Starting design



Output from BIGBOSOR4 (Starting design)

doer..STRESS\_LOADSTEP\_1



Starting design  
86

Fig.4

## Table 17 door. OPT

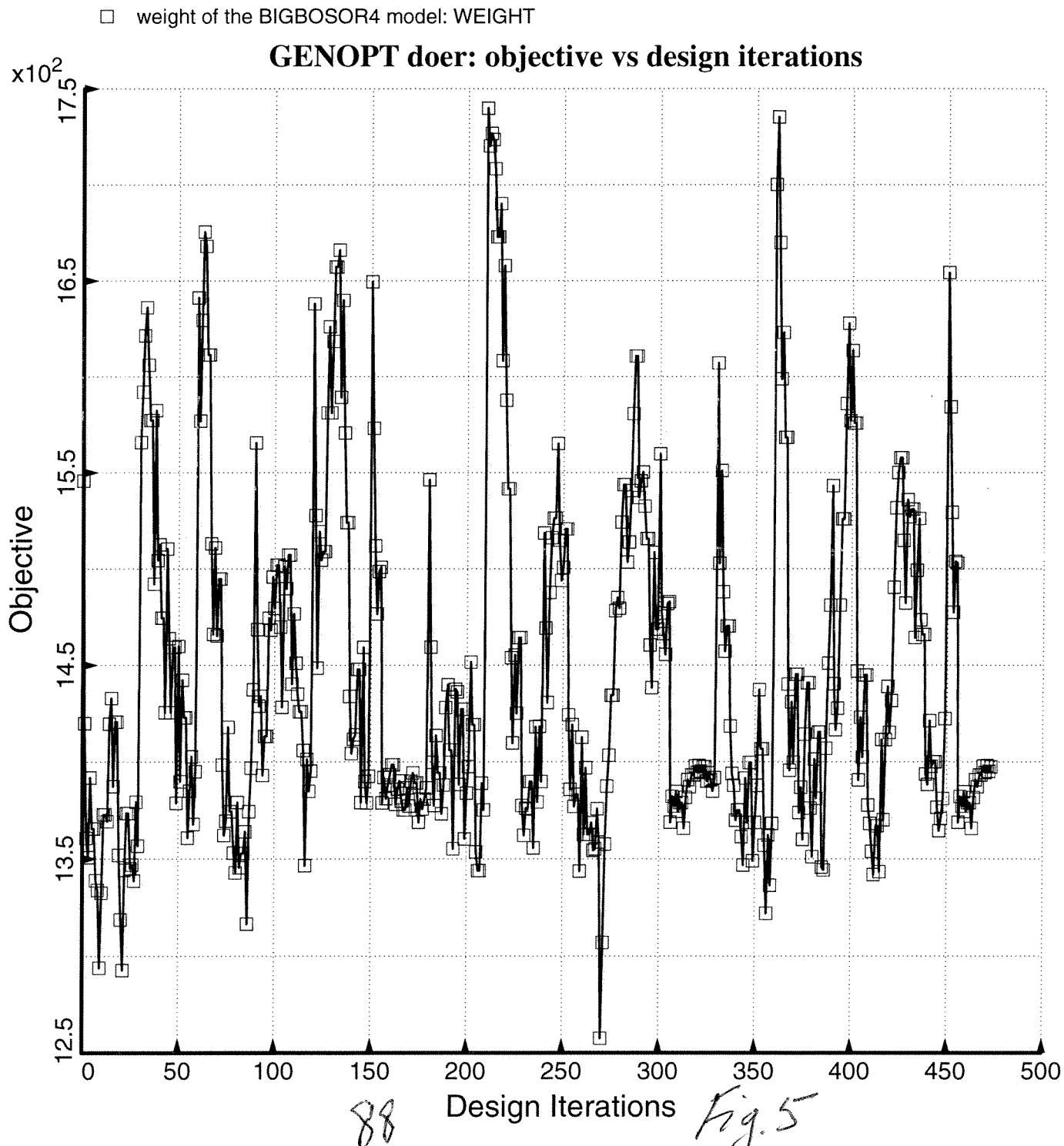
Note →

n	\$ Do you want a tutorial session and tutorial output?
0	\$ Choose an analysis you DON'T want (1, 2,...), IBEHAV
0	\$ NPRINT= output index (0=GOOD, 1=ok, 2=debug, 3=too much)
1	\$ Choose type of analysis (1=opt., 2=fixed, 3=sensit.) ITYPE
5	\$ How many design iterations in this run (3 to 25)?
n	\$ Take "shortcuts" for perturbed designs (Y or N)?
2	\$ Choose 1 or 2 or 3 or 4 or 5 for IDESIGN
1	\$ Choose 1 or 2 or 3 or 4 or 5 for move limits, IMOVE
y	\$ Do you want default (RATIO=10) for initial move limit jump?
y	\$ Do you want the default perturbation ( $dx/x = 0.05$ )?
n	\$ Do you want to have $dx/x$ modified by GENOPT?
n	\$ Do you want to reset total iterations to zero (Type H)?

input to mansetup for  
optimization

Output from SUPEROPT/CHOOSEPLOT/DIPLOT

doer, 5, ps



# Table 18 (3 ~~to~~ pages) doer.OPTM

```

n      $ Do you want a tutorial session and tutorial output?
0      $ Choose an analysis you DON'T want (1, 2...), IBEHAV
2      $ NPRINT= output index (0=GOOD, 1=ok, 2=debug, 3=too much)
2      $ Choose type of analysis (1=opt., 2=fixed, 3=sensit.) ITYPE
5      $ How many design iterations in this run (3 to 25)?
n      $ Take "shortcuts" for perturbed designs (Y or N)?
2      $ Choose 1 or 2 or 3 or 4 or 5 for IDESIGN
1      $ Choose 1 or 2 or 3 or 4 or 5 for move limits, IMOVE
y      $ Do you want default (RATIO=10) for initial move limit jump?
y      $ Do you want the default perturbation (dx/x = 0.05)?
n      $ Do you want to have dx/x modified by GENOPT?
n      $ Do you want to reset total iterations to zero (Type H)?

```

\*\*\*\*\* END OF THE doer.OPT FILE \*\*\*\*\*  
\*\*\*\*\* JUNE, 2009 VERSION OF GENOPT \*\*\*\*\*  
\*\*\*\*\* BEGINNING OF THE doer.OPM FILE \*\*\*\*\*

\*\*\*\*\* MAIN PROCESSOR \*\*\*\*\*  
The purpose of the mainprocessor, OPTIMIZE, is to perform,  
in a batch mode, the work specified by MAINSETUP for the case  
called doer. Results are stored in the file doer.OPM.  
Please inspect doer.OPM before doing more design iterations.

## STRUCTURAL ANALYSIS FOR DESIGN ITERATION NO. 0:

VAR.	DEC.	ESCAPE	LINK.	LINKING	LOWER	CURRENT	UPPER	DEFINITION
NO.	VAR.	VAR.		TO	CONSTANT	BOUND	VALUE	
1	N	N	N	0	0.00E+00	0.00E+00	6.2500E-01	0.00E+00 location of ref. surf. i»
n	the dome:	ZREFSP(1 )						
2	N	N	N	0	0.00E+00	0.00E+00	6.2500E-01	0.00E+00 location of ref. surf. i»
n	the dome:	ZREFSP(2 )						
3	Y	N	N	0	0.00E+00	6.25E-01	6.6694E-01	1.50E+00 location of ref. surf. i»
n	the dome:	ZREFSP(3 )						
4	Y	N	N	0	0.00E+00	6.25E-01	6.4444E-01	2.50E+00 location of ref. surf. i»
n	the dome:	ZREFSP(4 )						
5	Y	N	N	0	0.00E+00	6.25E-01	7.7483E-01	2.50E+00 location of ref. surf. i»
n	the dome:	ZREFSP(5 )						
6	N	N	N	0	0.00E+00	0.00E+00	1.2500E+00	0.00E+00 wall thickness in the do»
me:	THKSPH(1 )							
7	N	N	N	0	0.00E+00	0.00E+00	1.2500E+00	0.00E+00 wall thickness in the do»
me:	THKSPH(2 )							
8	Y	N	N	0	0.00E+00	1.25E+00	1.3091E+00	2.50E+00 wall thickness in the do»
me:	THKSPH(3 )							
9	Y	N	N	0	0.00E+00	1.25E+00	1.2500E+00	2.50E+00 wall thickness in the do»
me:	THKSPH(4 )							
10	Y	N	N	0	0.00E+00	1.25E+00	1.5676E+00	2.50E+00 wall thickness in the do»
me:	THKSPH(5 )							
11	Y	N	N	0	0.00E+00	6.25E-01	9.9422E-01	1.50E+00 location of the ref. sur»
f.	in the cylinder:	ZREFCY(1 )						
12	Y	N	N	0	0.00E+00	6.25E-01	1.0948E+00	1.50E+00 location of the ref. sur»
f.	in the cylinder:	ZREFCY(2 )						
13	Y	N	N	0	0.00E+00	6.25E-01	8.3843E-01	1.50E+00 location of the ref. sur»
f.	in the cylinder:	ZREFCY(3 )						
14	N	N	Y	19	5.00E-01	0.00E+00	1.0898E+00	0.00E+00 location of the ref. sur»
f.	in the cylinder:	ZREFCY(4 )						
15	N	N	Y	19	5.00E-01	0.00E+00	1.0898E+00	0.00E+00 location of the ref. sur»
f.	in the cylinder:	ZREFCY(5 )						
16	Y	Y	N	0	0.00E+00	1.25E+00	1.9048E+00	3.00E+00 thickness of the cylindr»
ical shell:	THKCYL(1 )							
17	Y	Y	N	0	0.00E+00	1.25E+00	2.1159E+00	3.00E+00 thickness of the cylindr»
ical shell:	THKCYL(2 )							
18	Y	Y	N	0	0.00E+00	1.25E+00	1.9536E+00	2.50E+00 thickness of the cylindr»
ical shell:	THKCYL(3 )							
19	Y	Y	N	0	0.00E+00	1.25E+00	2.1796E+00	2.50E+00 thickness of the cylindr»
ical shell:	THKCYL(4 )							
20	N	N	Y	19	1.00E+00	0.00E+00	2.1796E+00	0.00E+00 thickness of the cylindr»
ical shell:	THKCYL(5 )							
BEHAVIOR FOR 1 ENVIRONMENT (LOAD SET)								

CONSTRAINT NUMBER	BEHAVIOR VALUE	DEFINITION
-------------------	----------------	------------

*Output from  
"OPTIMIZE"*

*Optimum design  
after one execution  
of SUPEROPT*

# Table 18 (p. 2 of 3)

BEHAVIOR FOR LOAD SET NUMBER, ILOADX= 1

BIGBOSOR4 input file for: buckling load (INDIC=1)  
doer.BEHX1

WEIGHT OF THE BIGBOSOR4 MODEL OF THE TANK  
TOTMAS = 1.3688E+03

BUCKLING LOAD FACTORS AND MODES (BEHX1)

5.0503E+00(	0)
5.0362E+00(	1)
1.8694E+00(	2)
1.3044E+00(	3) <i>critical eigenvalue &amp; mode</i>
1.9491E+00(	4)
2.9185E+00(	5)
4.0596E+00(	6)
5.1299E+00(	7)
5.8542E+00(	8)
6.6359E+00(	9)
7.5675E+00(	10)

Critical buckling load factor, BUCKL= 1.3044E+00

Critical number of circumferential waves, NWVCRT= 3  
1 1.304394 tank buckling eigenvalue: BUCKL(1 )

BEHAVIOR OVER J = shell segment number

BIGBOSOR4 input file for: maximum effective stress (INDIC=0)  
doer.BEHX2

Shell skin maximum effective stress,  
at nodal point 75 SKNMAX= 1.2597E+05  
Shell skin maximum effective stress,  
at nodal point 33 SKNMAX= 1.2356E+05

\*\*\*\*\* MAXIMUM EFFECTIVE STRESS IN ISOTROPIC WALL \*\*\*\*\*

STRMAX= 1.2597E+05

\*\*\*\*\*

effective stress in shell segment: STRESS(1 ,1 )

\*\*\*\*\*

*Abit too high, perhaps*

*shell segment ①*

*shell segment ②*

BIGBOSOR4 input file for: maximum effective stress (INDIC=0)

doer.BEHX2 3 123558.8 effective stress in shell segment: STRESS(1 ,2 )

\*\*\*\*\* RESULTS FOR LOAD SET NO. 1 \*\*\*\*\*

PARAMETERS WHICH DESCRIBE BEHAVIOR (e.g. stress, buckling load)

BEH. CURRENT  
NO. VALUE

DEFINITION

1	1.304E+00	tank buckling eigenvalue: BUCKL(1 )
2	1.260E+05	effective stress in shell segment: STRESS(1 ,1 )
3	1.236E+05	effective stress in shell segment: STRESS(1 ,2 )

\*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\*

The phrase, "NOT APPLY", for MARGIN VALUE means that that particular margin value is exactly zero.

\*\*\* END NOTE \*\*\* END NOTE \*\*\* END NOTE \*\*\* END NOTE \*\*\*

\*\*\*\*\* RESULTS FOR LOAD SET NO. 1 \*\*\*\*\*

MARGINS CORRESPONDING TO CURRENT DESIGN (F.S.= FACTOR OF SAFETY)

MARGIN CURRENT

NO. VALUE

DEFINITION

1	3.380E-03	(BUCKL(1 )/BUCKLA(1 )) / BUCKLF(1 )-1; F.S.= 1.30
2	-4.738E-02	(STRESSA(1 ,1 )/STRESS(1 ,1 )) / STRESSF(1 ,1 )-1; F.S.= 1.00
3	-2.880E-02	(STRESSA(1 ,2 )/STRESS(1 ,2 )) / STRESSF(1 ,2 )-1; F.S.= 1.00

*Compare with p. 2 of Table 22*

\*\*\*\*\* DESIGN OBJECTIVE \*\*\*\*\*

CURRENT VALUE OF THE OBJECTIVE FUNCTION:

VAR. CURRENT

NO. VALUE

DEFINITION

1	1.369E+03	weight of the BIGBOSOR4 model: WEIGHT
---	-----------	---------------------------------------

(1b)

# Table 18 (p. 3 of 3)

```
*****
***** DESIGN OBJECTIVE *****
***** ALL 1 LOAD CASES PROCESSED *****
*****
```

PARAMETERS WHICH ARE ALWAYS FIXED. NONE CAN BE DECISION VARIAB.

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	2.000E+01	radius of the tank: RADIUS
2	4.000E+01	total length of the cylinder: LENGTH
3	1.600E+07	elastic modulus of the shell wall: EMOD
4	2.500E-01	Poisson ratio of the shell wall: NU
5	1.600E-01	weight density of the shell wall: DENSTY
6	0.000E+00	axial location of callout in the dome: ZSPH(1 )
7	1.000E+01	axial location of callout in the dome: ZSPH(2 )
8	1.300E+01	axial location of callout in the dome: ZSPH(3 )
9	1.600E+01	axial location of callout in the dome: ZSPH(4 )
10	2.000E+01	axial location of callout in the dome: ZSPH(5 )
11	2.000E+01	axial location of callout in the cylinder: ZCYL(1 )
12	2.200E+01	axial location of callout in the cylinder: ZCYL(2 )
13	2.500E+01	axial location of callout in the cylinder: ZCYL(3 )
14	3.000E+01	axial location of callout in the cylinder: ZCYL(4 )
15	4.000E+01	axial location of callout in the cylinder: ZCYL(5 )

PARAMETERS WHICH ARE ENVIRONMENTAL FACTORS (e.g. loads, temps.)

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.500E+04	uniform external pressure: PRESS(1 )

PARAMETERS WHICH ARE CLASSIFIED AS ALLOWABLES (e.g. max. stress)

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.000E+00	allowable buckling load (Use 1.0): BUCKLA(1 )
2	1.200E+05	maximum allowable effective stress: STRESSA(1 ,1 )
3	1.200E+05	maximum allowable effective stress: STRESSA(1 ,2 )

PARAMETERS WHICH ARE FACTORS OF SAFETY

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.300E+00	factor of safety for buckling: BUCKLF(1 )
2	1.000E+00	factor of safety for stress: STRESSF(1 ,1 )
3	1.000E+00	factor of safety for stress: STRESSF(1 ,2 )

0 INEQUALITY CONSTRAINTS WHICH MUST BE SATISFIED

DESCRIPTION OF FILES USED AND GENERATED IN THIS RUN:

doer.NAM = This file contains only the name of the case.  
doer.OPM = Output data. Please list this file and inspect  
carefully before proceeding.  
doer.OPP = Output file containing evolution of design and  
margins since the beginning of optimization cycles.  
doer.CBL = Labelled common blocks for analysis.  
(This is an unformatted sequential file.)  
doer.OPT = This file contains the input data for MAINSETUP  
as well as OPTIMIZE. The batch command OPTIMIZE  
can be given over and over again without having  
to return to MAINSETUP because doer.OPT exists.  
URPROMPT.DAT= Prompt file for interactive input.

For further information about files used and generated  
during operation of GENOPT, give the command HELPG FILES.

Menu of commands: CHOOSEPLOT, OPTIMIZE, MAINSETUP, CHANGE,  
DECIDE, SUPEROPT

IN ORDER TO AVOID FALSE CONVERGENCE OF THE DESIGN, BE SURE TO  
RUN "OPTIMIZE" MANY TIMES DURING AN OPTIMIZATION AND/OR USE  
THE "GLOBAL" OPTIMIZING SCRIPT, "SUPEROPT".

\*\*\*\*\* END OF doer.OPM FILE \*\*\*\*\*

Table 19      doer, CHG

n	\$ Do you want a tutorial session and tutorial output?
y	\$ Do you want to change any values in Parameter Set No. 1?
1	\$ Number of parameter to change (1, 2, 3, . . .)
0.6250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
2	\$ Number of parameter to change (1, 2, 3, . . .)
0.6250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
3	\$ Number of parameter to change (1, 2, 3, . . .)
0.6669400	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
4	\$ Number of parameter to change (1, 2, 3, . . .)
0.6444400	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
5	\$ Number of parameter to change (1, 2, 3, . . .)
0.7748300	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
6	\$ Number of parameter to change (1, 2, 3, . . .)
1.250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
7	\$ Number of parameter to change (1, 2, 3, . . .)
1.250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
8	\$ Number of parameter to change (1, 2, 3, . . .)
1.309100	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
9	\$ Number of parameter to change (1, 2, 3, . . .)
1.250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
10	\$ Number of parameter to change (1, 2, 3, . . .)
1.567600	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
11	\$ Number of parameter to change (1, 2, 3, . . .)
0.9942200	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
12	\$ Number of parameter to change (1, 2, 3, . . .)
1.0948000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
13	\$ Number of parameter to change (1, 2, 3, . . .)
0.838430	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
14	\$ Number of parameter to change (1, 2, 3, . . .)
1.089800	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
15	\$ Number of parameter to change (1, 2, 3, . . .)
1.089800	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
16	\$ Number of parameter to change (1, 2, 3, . . .)
1.904800	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
17	\$ Number of parameter to change (1, 2, 3, . . .)
2.115900	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
18	\$ Number of parameter to change (1, 2, 3, . . .)
1.953600	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
19	\$ Number of parameter to change (1, 2, 3, . . .)
2.179600	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
20	\$ Number of parameter to change (1, 2, 3, . . .)
2.179600	\$ New value of the parameter
n	\$ Want to change any other parameters in this set?
n	\$ Do you want to change values of any "fixed" parameters?
n	\$ Do you want to change any loads?
n	\$ Do you want to change values of allowables?
n	\$ Do you want to change any factors of safety?

Always use CHANGE to save optimum designs.  
The optimum design listed in Table 18 is preserved.

input for CHANGE for optimized  
design after one execution of SUPEROPT.

## Table 20 doer.OPT

Note

n 0  
0  
1  
15  
n  
1  
3  
y  
y  
n  
n

```
$ Do you want a tutorial session and tutorial output?  
$ Choose an analysis you DON'T want (1, 2,...), IBEHAV  
$ NPRINT= output index (0=GOOD, 1=ok, 2=debug, 3=too much)  
$ Choose type of analysis (1=opt., 2=fixed, 3=sensit.) ITYPE  
$ How many design iterations in this run (3 to 25)?  
$ Take "shortcuts" for perturbed designs (Y or N)?  
$ Choose 1 or 2 or 3 or 4 or 5 for IDESIGN  
$ Choose 1 or 2 or 3 or 4 or 5 for move limits, IMOVE  
$ Do you want default (RATIO=10) for initial move limit jump?  
$ Do you want the default perturbation (dx/x = 0.05)?  
$ Do you want to have dx/x modified by GENOPT?  
$ Do you want to reset total iterations to zero (Type H)?
```

input to mainsetup for  
more optimization

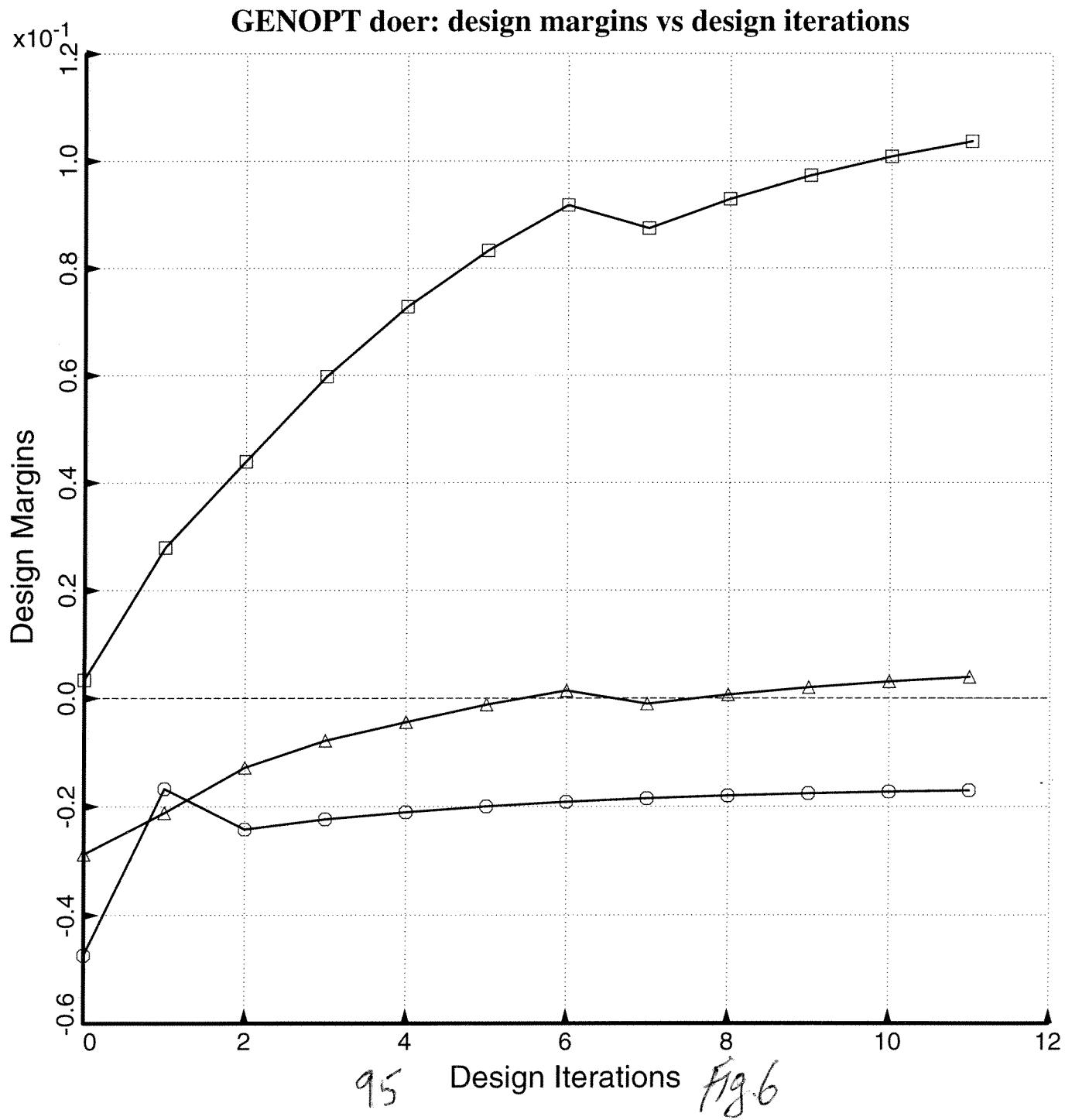
Table 21 doze.CPL

n	\$ Do you want a tutorial session and tutorial output?
y	\$ Any design variables to be plotted v. iterations (Y or N) ?
2	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
3	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
4	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
5	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
7	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
8	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
9	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
10	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
11	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
12	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
13	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
14	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
16	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
17	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
18	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
y	\$ Any more design variables to be plotted (Y or N) ?
19	\$ Choose a variable to be plotted v. iterations (1,2,3,...)
n	\$ Any more design variables to be plotted (Y or N) ?
y	\$ Any design margins to be plotted v. iterations (Y or N) ?
1	\$ Choose a margin to be plotted v. iterations (1,2,3,...)
y	\$ Any more margins to be plotted (Y or N) ?
2	\$ Choose a margin to be plotted v. iterations (1,2,3,...)
y	\$ Any more margins to be plotted (Y or N) ?
3	\$ Choose a margin to be plotted v. iterations (1,2,3,...)
n	\$ Any more margins to be plotted (Y or N) ?
0.3000000	\$ Give maximum value (positive) to be included in plot frame.

input for CHOOSEPLOT  
for generating the next  
three figures via DIPILOT

doer. 3. ps

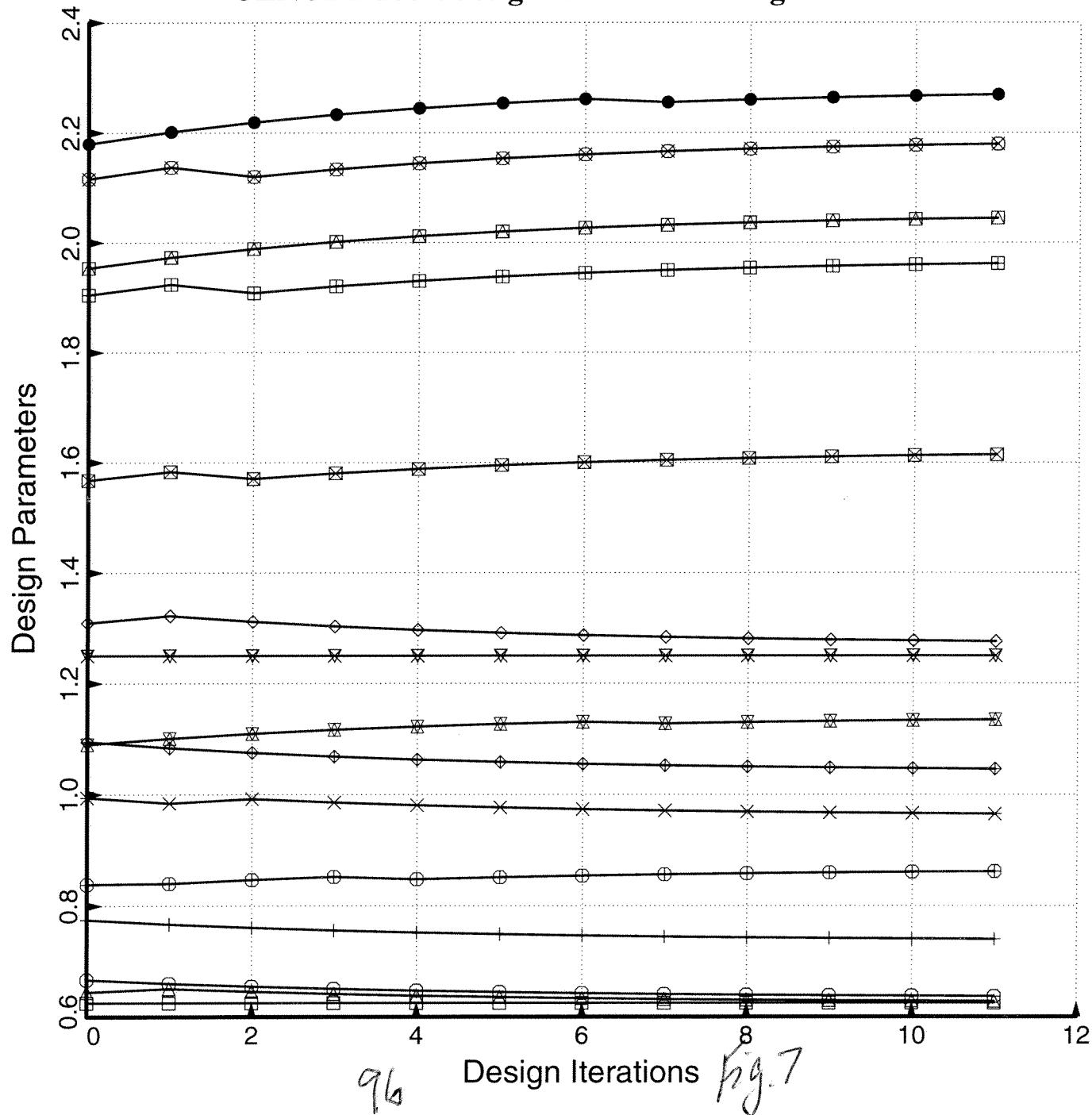
- (BUCKL(1 )/BUCKLA(1 )) / BUCKLF(1 )-1; F.S.= 1.30
- (STRESSA(1 ,1 )/STRESS(1 ,1 )) / STRESSF(1 ,1 )-1; F.S.= 1.00
- △ (STRESSA(1 ,2 )/STRESS(1 ,2 )) / STRESSF(1 ,2 )-1; F.S.= 1.00



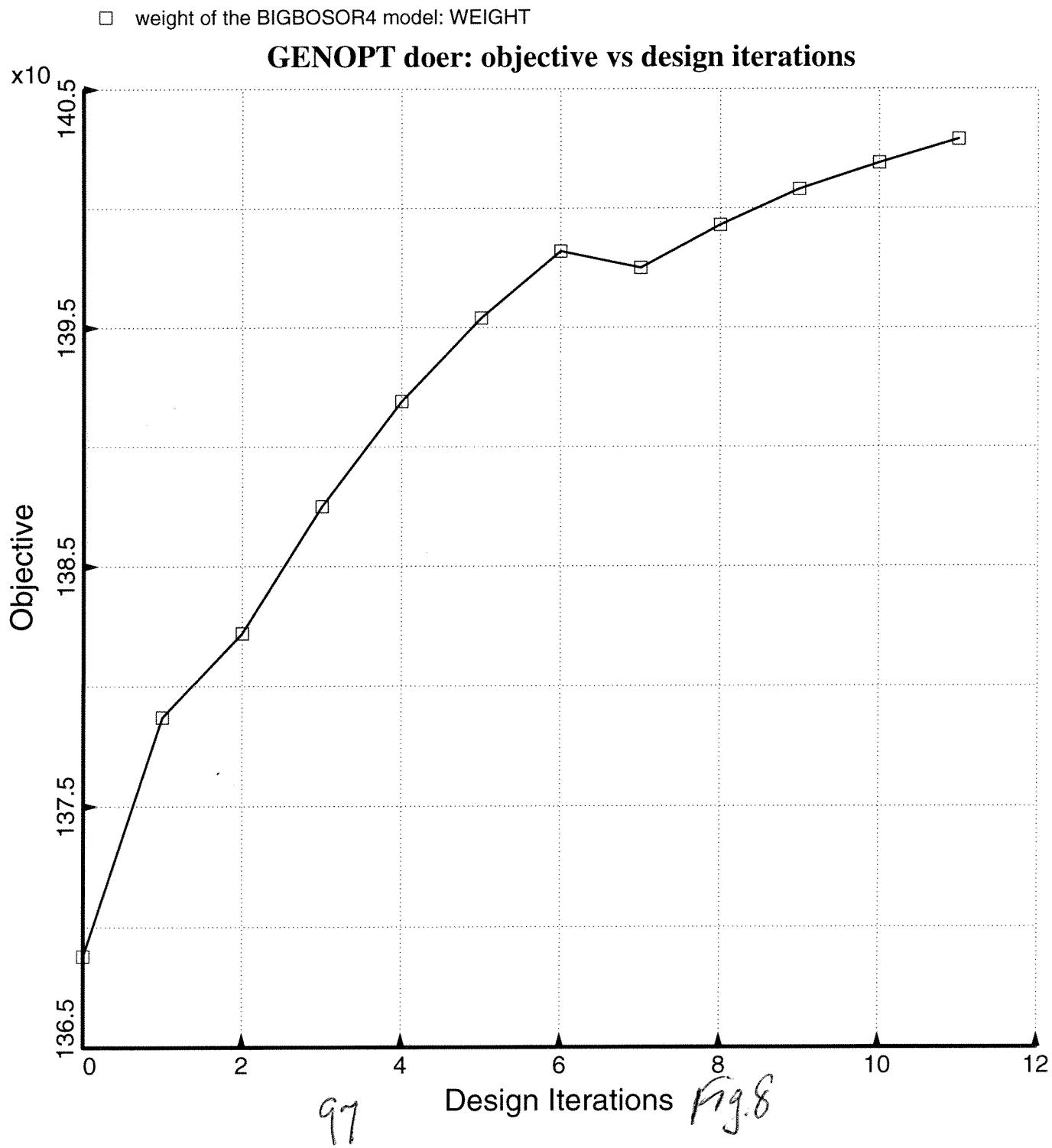
- location of ref. surf. in the dome: ZREFSP(2 )
- location of ref. surf. in the dome: ZREFSP(3 )
- location of ref. surf. in the dome: ZREFSP(4 )
- location of ref. surf. in the dome: ZREFSP(5 )
- wall thickness in the dome: THKSPH(2 )
- wall thickness in the dome: THKSPH(3 )
- wall thickness in the dome: THKSPH(4 )
- wall thickness in the dome: THKSPH(5 )
- location of the ref. surf. in the cylinder: ZREFCY(1 )
- location of the ref. surf. in the cylinder: ZREFCY(2 )
- location of the ref. surf. in the cylinder: ZREFCY(3 )
- location of the ref. surf. in the cylinder: ZREFCY(4 )
- thickness of the cylindrical shell: THKCYL(1 )
- thickness of the cylindrical shell: THKCYL(2 )
- thickness of the cylindrical shell: THKCYL(3 )
- thickness of the cylindrical shell: THKCYL(4 )

doer. 4. PS

GENOPT doer: design variables vs design iterations



doer.5.ps



# Table 22 (3pp) doer.OPT

```

n      $ Do you want a tutorial session and tutorial output?
0      $ Choose an analysis you DON'T want (1, 2...), IBEHAV
2      $ NPRINT= output index (0=GOOD, 1=ok, 2=debug, 3=too much)
2      $ Choose type of analysis (1=opt., 2=fixed, 3=sensit.) ITYPE
15     $ How many design iterations in this run (3 to 25)?
n      $ Take "shortcuts" for perturbed designs (Y or N)?
1      $ Choose 1 or 2 or 3 or 4 or 5 for IDESIGN
3      $ Choose 1 or 2 or 3 or 4 or 5 for move limits, IMOVE
y      $ Do you want default (RATIO=10) for initial move limit jump?
y      $ Do you want the default perturbation (dx/x = 0.05)?
n      $ Do you want to have dx/x modified by GENOPT?
n      $ Do you want to reset total iterations to zero (Type H)?

```

\*\*\*\*\* END OF THE doer.OPT FILE \*\*\*\*\*  
\*\*\*\*\* JUNE, 2009 VERSION OF GENOPT \*\*\*\*\*  
\*\*\*\*\* BEGINNING OF THE doer.OPM FILE \*\*\*\*\*

*Output from "OPTIMIZE"*

\*\*\*\*\* MAIN PROCESSOR \*\*\*\*\*  
The purpose of the mainprocessor, OPTIMIZE, is to perform,  
in a batch mode, the work specified by MAINSETUP for the case  
called doer. Results are stored in the file doer.OPM.  
Please inspect doer.OPM before doing more design iterations.

## STRUCTURAL ANALYSIS FOR DESIGN ITERATION NO. 0:

0	STRUCTURAL ANALYSIS WITH UNPERTURBED DECISION VARIABLES								
	VAR.	DEC.	ESCAPE	LINK.	LINKING	LOWER	CURRENT	UPPER	DEFINITION
	NO.	VAR.	VAR.	TO	CONSTANT	BOUND	VALUE	BOUND	
n	1	N	N	N	0	0.00E+00	0.00E+00	6.2500E-01	0.00E+00
n	the dome:	ZREFSP(1)			0	0.00E+00	0.00E+00	6.2500E-01	0.00E+00
n	2	N	N	N	0	0.00E+00	0.00E+00	6.2500E-01	0.00E+00
n	the dome:	ZREFSP(2)			0	0.00E+00	6.25E-01	6.3706E-01	1.50E+00
n	3	Y	N	N	0	0.00E+00	6.25E-01	6.3706E-01	1.50E+00
n	the dome:	ZREFSP(3)			0	0.00E+00	6.25E-01	6.2800E-01	2.50E+00
n	4	Y	N	N	0	0.00E+00	6.25E-01	6.2800E-01	2.50E+00
n	the dome:	ZREFSP(4)			0	0.00E+00	6.25E-01	7.4011E-01	2.50E+00
n	5	Y	N	N	0	0.00E+00	6.25E-01	7.4011E-01	2.50E+00
n	the dome:	ZREFSP(5)			0	0.00E+00	0.00E+00	1.2500E+00	0.00E+00
me:	THKSPH(1)				0	0.00E+00	0.00E+00	1.2500E+00	0.00E+00
me:	THKSPH(2)				0	0.00E+00	0.00E+00	1.2500E+00	0.00E+00
me:	THKSPH(3)				0	0.00E+00	1.25E+00	1.2758E+00	2.50E+00
me:	THKSPH(4)				0	0.00E+00	1.25E+00	1.2500E+00	2.50E+00
me:	THKSPH(5)				0	0.00E+00	1.25E+00	1.6144E+00	2.50E+00
f.	11	Y	N	N	0	0.00E+00	6.25E-01	9.6499E-01	1.50E+00
f.	in the cylinder:	ZREFCY(1)			0	0.00E+00	6.25E-01	1.0457E+00	1.50E+00
f.	12	Y	N	N	0	0.00E+00	6.25E-01	1.0457E+00	1.50E+00
f.	in the cylinder:	ZREFCY(2)			0	0.00E+00	6.25E-01	8.6174E-01	1.50E+00
f.	13	Y	N	N	0	0.00E+00	6.25E-01	8.6174E-01	1.50E+00
f.	in the cylinder:	ZREFCY(3)			0	0.00E+00	5.00E-01	1.1346E+00	0.00E+00
f.	14	N	N	Y	19	5.00E-01	0.00E+00	1.1346E+00	0.00E+00
f.	in the cylinder:	ZREFCY(4)			0	0.00E+00	5.00E-01	0.00E+00	0.00E+00
f.	15	N	N	Y	19	5.00E-01	0.00E+00	1.1346E+00	0.00E+00
f.	in the cylinder:	ZREFCY(5)			0	0.00E+00	1.25E+00	1.9620E+00	3.00E+00
ical shell:	THKCYL(1)				0	0.00E+00	1.25E+00	2.1794E+00	3.00E+00
ical shell:	THKCYL(2)				0	0.00E+00	1.25E+00	2.0447E+00	2.50E+00
ical shell:	THKCYL(3)				0	0.00E+00	1.25E+00	2.2693E+00	2.50E+00
ical shell:	THKCYL(4)				0	0.00E+00	1.25E+00	2.2693E+00	0.00E+00
ical shell:	THKCYL(5)				19	1.00E+00	0.00E+00	2.2693E+00	0.00E+00
BEHAVIOR FOR 1 ENVIRONMENT (LOAD SET)									
CONSTRAINT	BEHAVIOR	DEFINITION							
NUMBER	VALUE								

# Table 22(p. 2 of 3)

BEHAVIOR FOR LOAD SET NUMBER, ILOADX= 1

BIGBOSOR4 input file for: buckling load (INDIC=1)  
doer.BEHX1

WEIGHT OF THE BIGBOSOR4 MODEL OF THE TANK  
TOTMAS = 1.4029E+03

BUCKLING LOAD FACTORS AND MODES (BEHX1)

5.0469E+00(	0)
5.0282E+00(	1)
1.9429E+00(	2)
1.4347E+00(	3) ← critical eigenvalue & mode
2.1787E+00(	4)
3.2639E+00(	5)
4.4859E+00(	6)
5.2346E+00(	7)
5.7873E+00(	8)
6.5147E+00(	9)
7.4054E+00(	10)

Critical buckling load factor, BUCKL= 1.4347E+00

Critical number of circumferential waves, NWVCRT= 3  
1 1.434749 tank buckling eigenvalue: BUCKL(1 )

BEHAVIOR OVER J = shell segment number

BIGBOSOR4 input file for: maximum effective stress (INDIC=0)  
doer.BEHX2

Shell skin maximum effective stress,  
at nodal point 73 SKNMAX= 1.2208E+05  
Shell skin maximum effective stress,  
at nodal point 33 SKNMAX= 1.1953E+05

\*\*\*\*\* MAXIMUM EFFECTIVE STRESS IN ISOTROPIC WALL \*\*\*\*\*

STRMAX= 1.2208E+05  
\*\*\*\*\*  
2 122083.0 effective stress in shell segment: STRESS(1 , 1 )

BIGBOSOR4 input file for: maximum effective stress (INDIC=0)  
doer.BEHX2

3 119530.0 effective stress in shell segment: STRESS(1 , 2 )

\*\*\*\*\* RESULTS FOR LOAD SET NO. 1 \*\*\*\*\*

PARAMETERS WHICH DESCRIBE BEHAVIOR (e.g. stress, buckling load)

BEH.	CURRENT	
NO.	VALUE	DEFINITION
1	1.435E+00	tank buckling eigenvalue: BUCKL(1 )
2	1.221E+05	effective stress in shell segment: STRESS(1 , 1 )
3	1.195E+05	effective stress in shell segment: STRESS(1 , 2 )

\*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\*

The phrase, "NOT APPLY", for MARGIN VALUE means that that particular margin value is exactly zero.

\*\*\* END NOTE \*\*\* END NOTE \*\*\* END NOTE \*\*\* END NOTE \*\*\*\*\*

\*\*\*\*\* RESULTS FOR LOAD SET NO. 1 \*\*\*\*\*

MARGINS CORRESPONDING TO CURRENT DESIGN (F.S.= FACTOR OF SAFETY)

MARGIN CURRENT		
NO.	VALUE	DEFINITION
1	1.037E-01	(BUCKL(1 )/BUCKLA(1 )) / BUCKLF(1 )-1; F.S.= 1.30
2	-1.706E-02	(STRESSA(1 , 1 )/STRESS(1 , 1 )) / STRESSF(1 , 1 )-1; F.S.= 1.00
3	3.932E-03	(STRESSA(1 , 2 )/STRESS(1 , 2 )) / STRESSF(1 , 2 )-1; F.S.= 1.00

\*\*\*\*\* DESIGN OBJECTIVE \*\*\*\*\*

\*\*\*\*\* CURRENT VALUE OF THE OBJECTIVE FUNCTION: \*\*\*\*\*

VAR.	CURRENT	
NO.	VALUE	DEFINITION
1	1.403E+03	weight of the BIGBOSOR4 model: WEIGHT

Compare  
with  
p. 2 of  
Table 18

# Table 22 (p. 3 of 3)

```
*****
***** DESIGN OBJECTIVE *****
***** ALL 1 LOAD CASES PROCESSED *****
*****
```

PARAMETERS WHICH ARE ALWAYS FIXED. NONE CAN BE DECISION VARIAB.

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	2.000E+01	radius of the tank: RADIUS
2	4.000E+01	total length of the cylinder: LENGTH
3	1.600E+07	elastic modulus of the shell wall: EMOD
4	2.500E-01	Poisson ratio of the shell wall: NU
5	1.600E-01	weight density of the shell wall: DENSTY
6	0.000E+00	axial location of callout in the dome: ZSPH(1 )
7	1.000E+01	axial location of callout in the dome: ZSPH(2 )
8	1.300E+01	axial location of callout in the dome: ZSPH(3 )
9	1.600E+01	axial location of callout in the dome: ZSPH(4 )
10	2.000E+01	axial location of callout in the dome: ZSPH(5 )
11	2.000E+01	axial location of callout in the cylinder: ZCYL(1 )
12	2.200E+01	axial location of callout in the cylinder: ZCYL(2 )
13	2.500E+01	axial location of callout in the cylinder: ZCYL(3 )
14	3.000E+01	axial location of callout in the cylinder: ZCYL(4 )
15	4.000E+01	axial location of callout in the cylinder: ZCYL(5 )

PARAMETERS WHICH ARE ENVIRONMENTAL FACTORS (e.g. loads, temps.)

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.500E+04	uniform external pressure: PRESS(1 )

PARAMETERS WHICH ARE CLASSIFIED AS ALLOWABLES (e.g. max. stress)

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.000E+00	allowable buckling load (Use 1.0): BUCKLA(1 )
2	1.200E+05	maximum allowable effective stress: STRESSA(1 ,1 )
3	1.200E+05	maximum allowable effective stress: STRESSA(1 ,2 )

PARAMETERS WHICH ARE FACTORS OF SAFETY

VAR.	CURRENT	DEFINITION
NO.	VALUE	
1	1.300E+00	factor of safety for buckling: BUCKLF(1 )
2	1.000E+00	factor of safety for stress: STRESSF(1 ,1 )
3	1.000E+00	factor of safety for stress: STRESSF(1 ,2 )

## 0 INEQUALITY CONSTRAINTS WHICH MUST BE SATISFIED

### DESCRIPTION OF FILES USED AND GENERATED IN THIS RUN:

doer.NAM = This file contains only the name of the case.  
doer.OPM = Output data. Please list this file and inspect  
carefully before proceeding.  
doer.OPP = Output file containing evolution of design and  
margins since the beginning of optimization cycles.  
doer.CBL = Labelled common blocks for analysis.  
(This is an unformatted sequential file.)  
doer.OPT = This file contains the input data for MAINSETUP  
as well as OPTIMIZE. The batch command OPTIMIZE  
can be given over and over again without having  
to return to MAINSETUP because doer.OPT exists.  
URPROMPT.DAT= Prompt file for interactive input.

For further information about files used and generated  
during operation of GENOPT, give the command HELP FILES.

Menu of commands: CHOOSEPLOT, OPTIMIZE, MAINSETUP, CHANGE,  
DECIDE, SUPEROPT

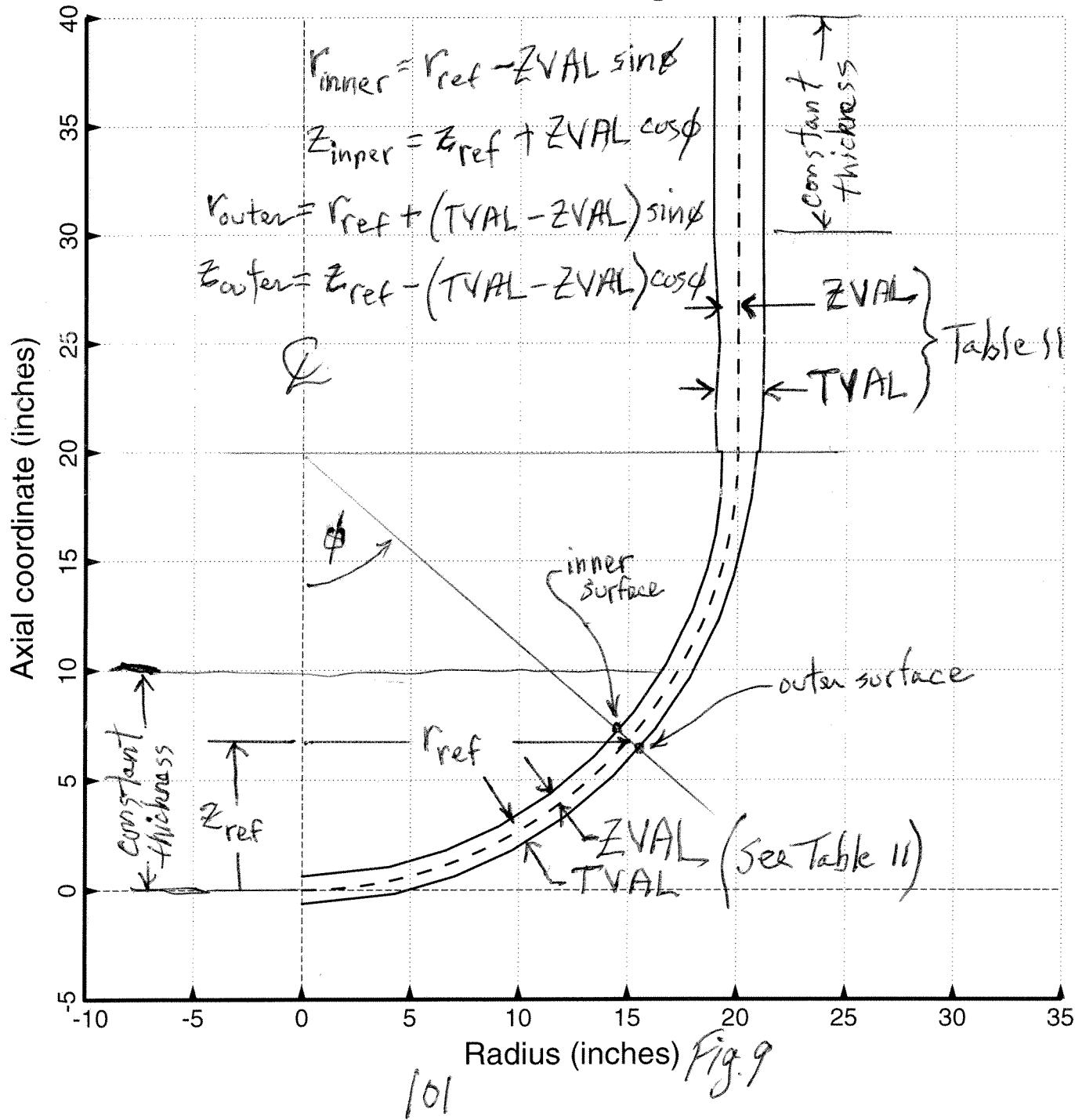
IN ORDER TO AVOID FALSE CONVERGENCE OF THE DESIGN, BE SURE TO  
RUN "OPTIMIZE" MANY TIMES DURING AN OPTIMIZATION AND/OR USE  
THE "GLOBAL" OPTIMIZING SCRIPT, "SUPEROPT".

\*\*\*\*\* END OF doer.OPM FILE \*\*\*\*\*

Output from /home/progs/bin/plotps.linux

- Undeformed inner (leftmost) surface of the doer tank
- Undeformed outer (rightmost) surface of the doer tank
- - Undeformed reference surface of the doer tank

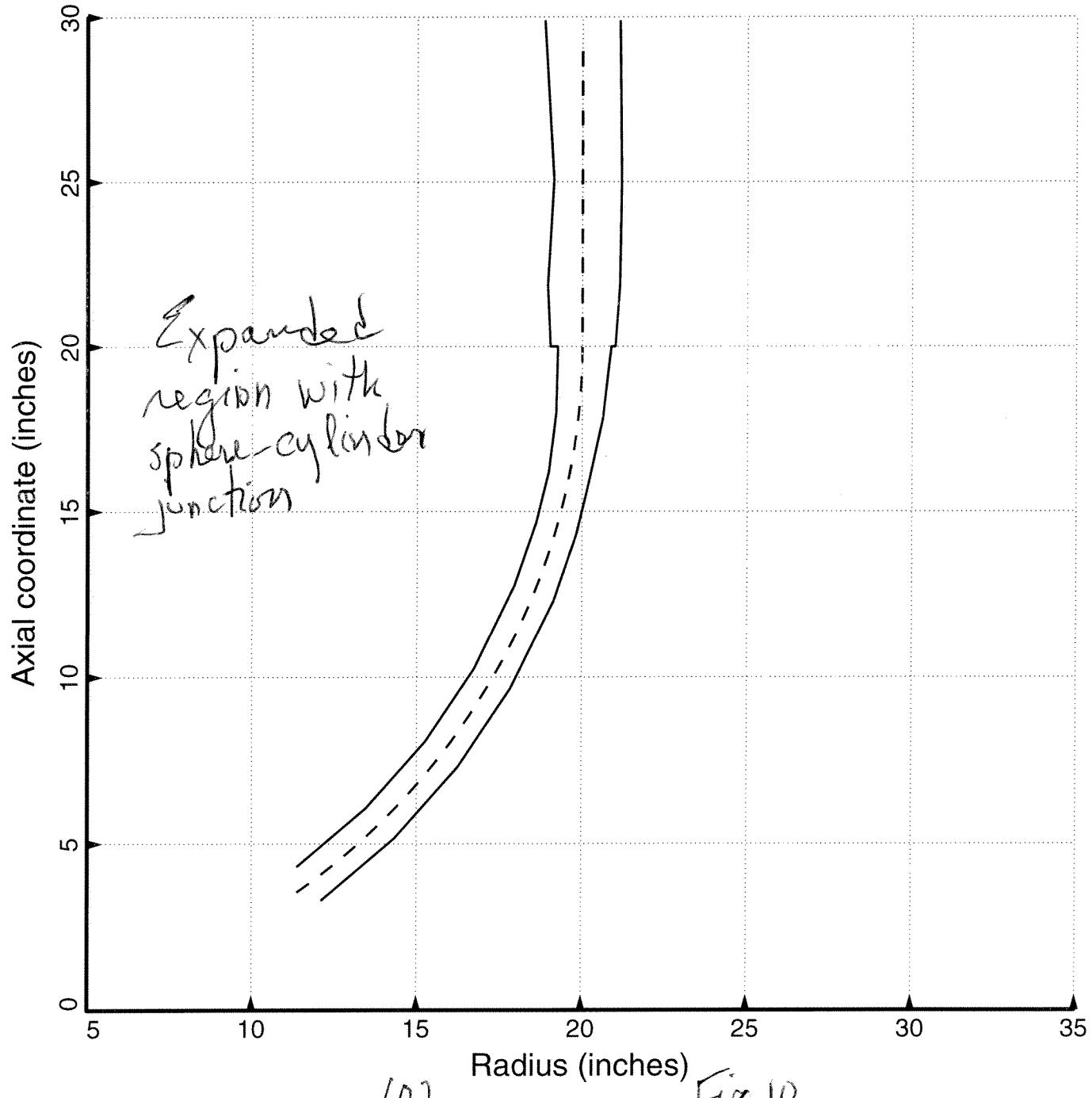
### Thickness distribution in the optimized doer tank



Output from /home/progs/bin/plotps.linux

- Undeformed inner (leftmost) surface of the doer tank
- Undeformed outer (rightmost) surface of the doer tank
- - Undeformed reference surface of the doer tank

**Thickness distribution in the optimized doer tank**



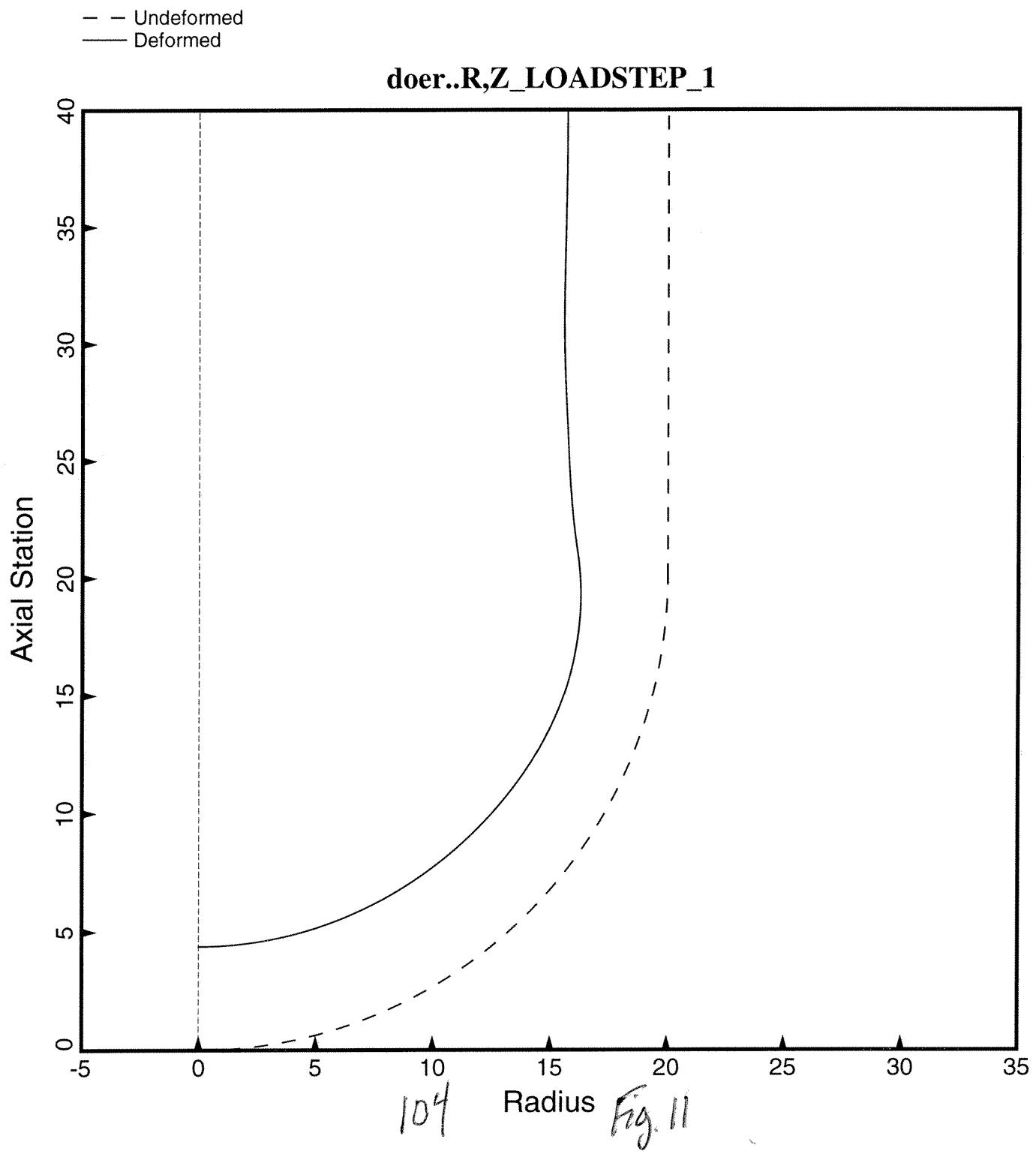
## Table 23 dae.CHG

n	\$ Do you want a tutorial session and tutorial output?
y	\$ Do you want to change any values in Parameter Set No. 1?
1	\$ Number of parameter to change (1, 2, 3, . .)
0.6250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
2	\$ Number of parameter to change (1, 2, 3, . .)
0.6250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
3	\$ Number of parameter to change (1, 2, 3, . .)
0.6370600	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
4	\$ Number of parameter to change (1, 2, 3, . .)
0.6280000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
5	\$ Number of parameter to change (1, 2, 3, . .)
0.7401100	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
6	\$ Number of parameter to change (1, 2, 3, . .)
1.250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
7	\$ Number of parameter to change (1, 2, 3, . .)
1.250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
8	\$ Number of parameter to change (1, 2, 3, . .)
1.275800	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
9	\$ Number of parameter to change (1, 2, 3, . .)
1.250000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
10	\$ Number of parameter to change (1, 2, 3, . .)
1.614400	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
11	\$ Number of parameter to change (1, 2, 3, . .)
0.9649900	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
12	\$ Number of parameter to change (1, 2, 3, . .)
1.0457000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
13	\$ Number of parameter to change (1, 2, 3, . .)
0.861740	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
14	\$ Number of parameter to change (1, 2, 3, . .)
1.134600	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
15	\$ Number of parameter to change (1, 2, 3, . .)
1.134600	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
16	\$ Number of parameter to change (1, 2, 3, . .)
1.962000	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
17	\$ Number of parameter to change (1, 2, 3, . .)
2.179400	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
18	\$ Number of parameter to change (1, 2, 3, . .)
2.044700	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
19	\$ Number of parameter to change (1, 2, 3, . .)
2.269300	\$ New value of the parameter
y	\$ Want to change any other parameters in this set?
20	\$ Number of parameter to change (1, 2, 3, . .)
2.269300	\$ New value of the parameter
n	\$ Want to change any other parameters in this set?
n	\$ Do you want to change values of any "fixed" parameters?
n	\$ Do you want to change any loads?
n	\$ Do you want to change values of allowables?
n	\$ Do you want to change any factors of safety?

Always save optimum designs  
this way. The optimum design  
picked in Table 22 is preserved.

Input for CHANGE

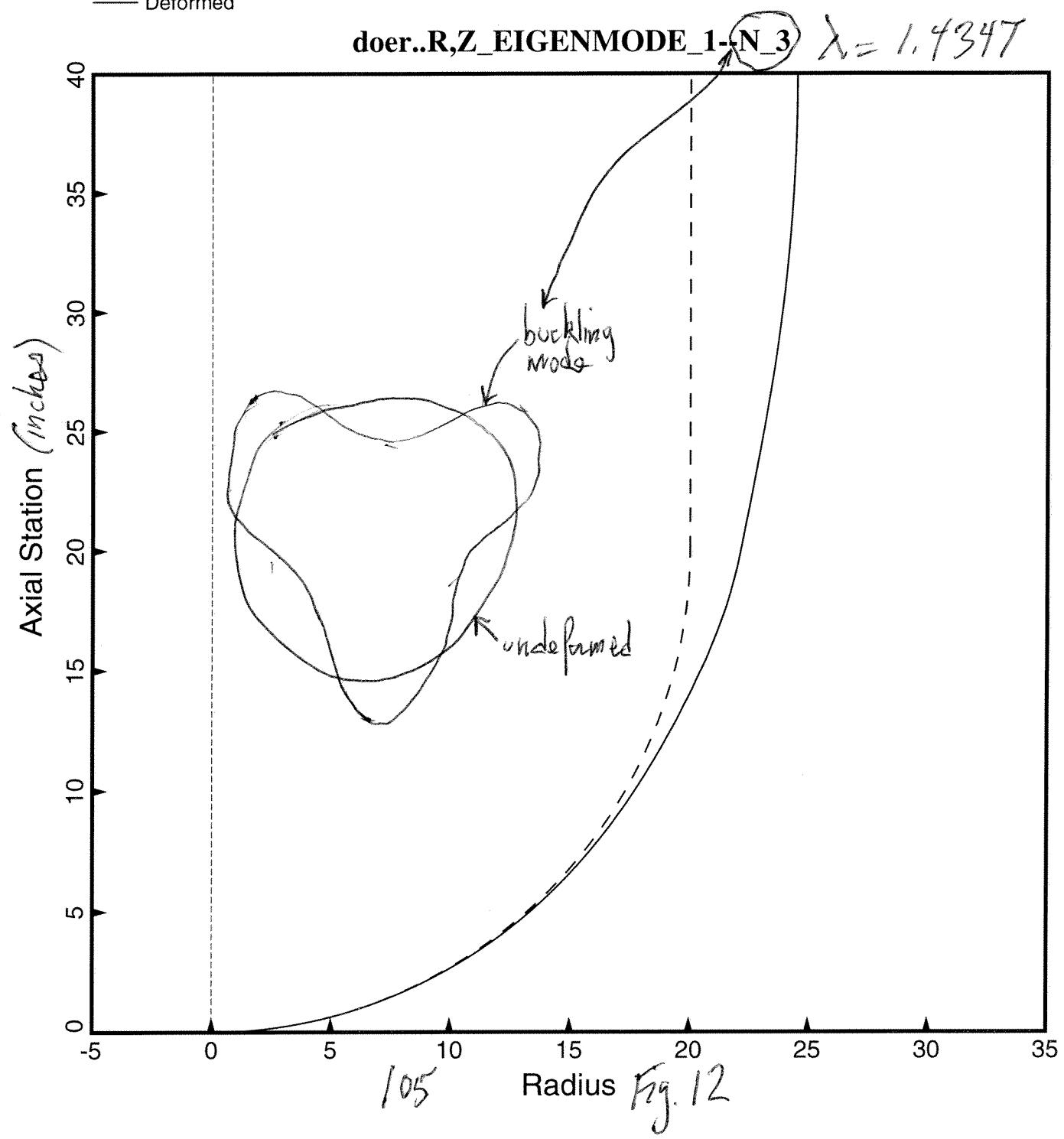
Output from BIGBOSUR4  
for the optimized design



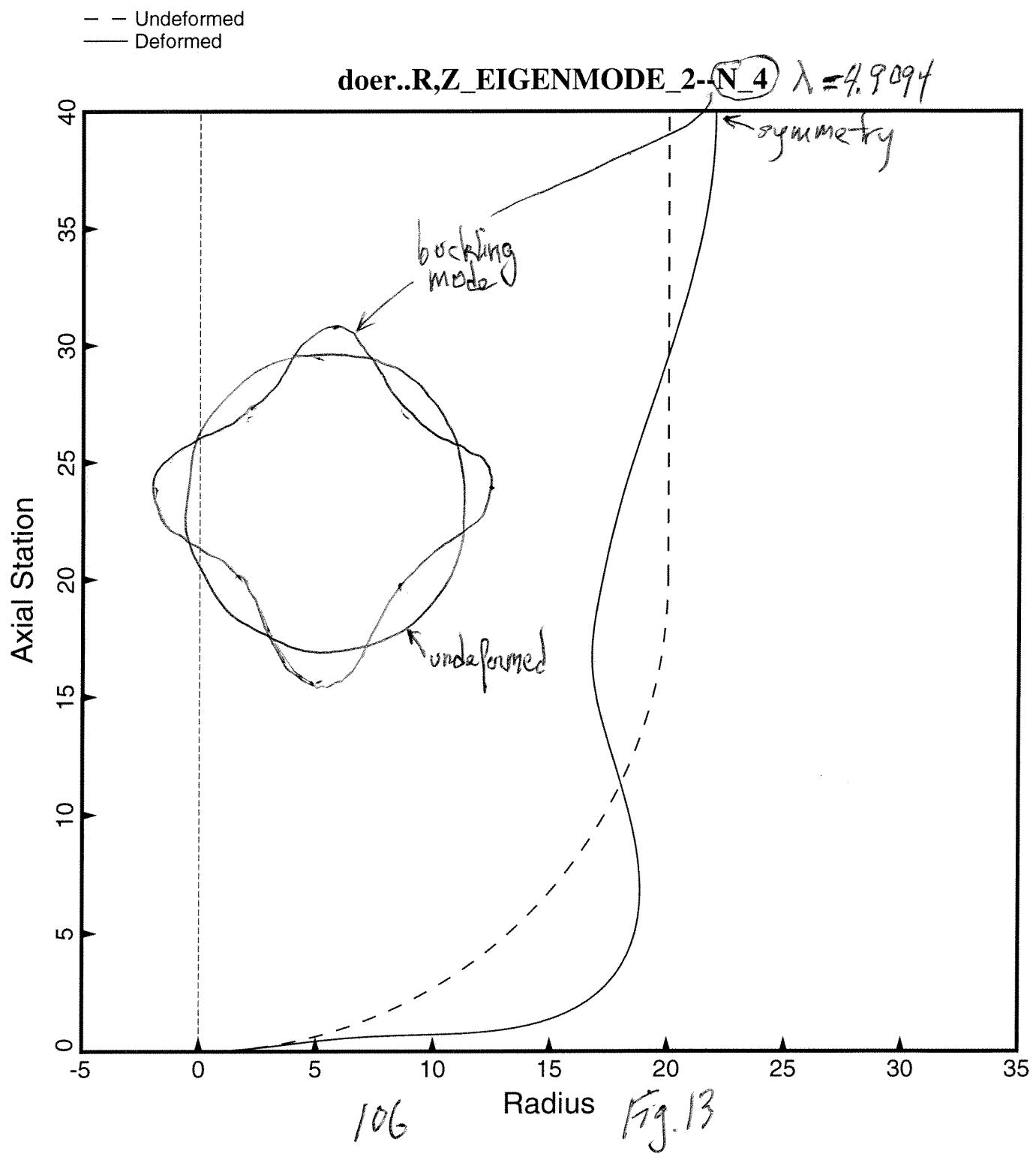
Output from BIGBOSOR4 for  
the optimized design

-- Undeformed  
— Deformed

doer..R,Z\_EIGENMODE\_1-N\_3  $\lambda = 1.4347$

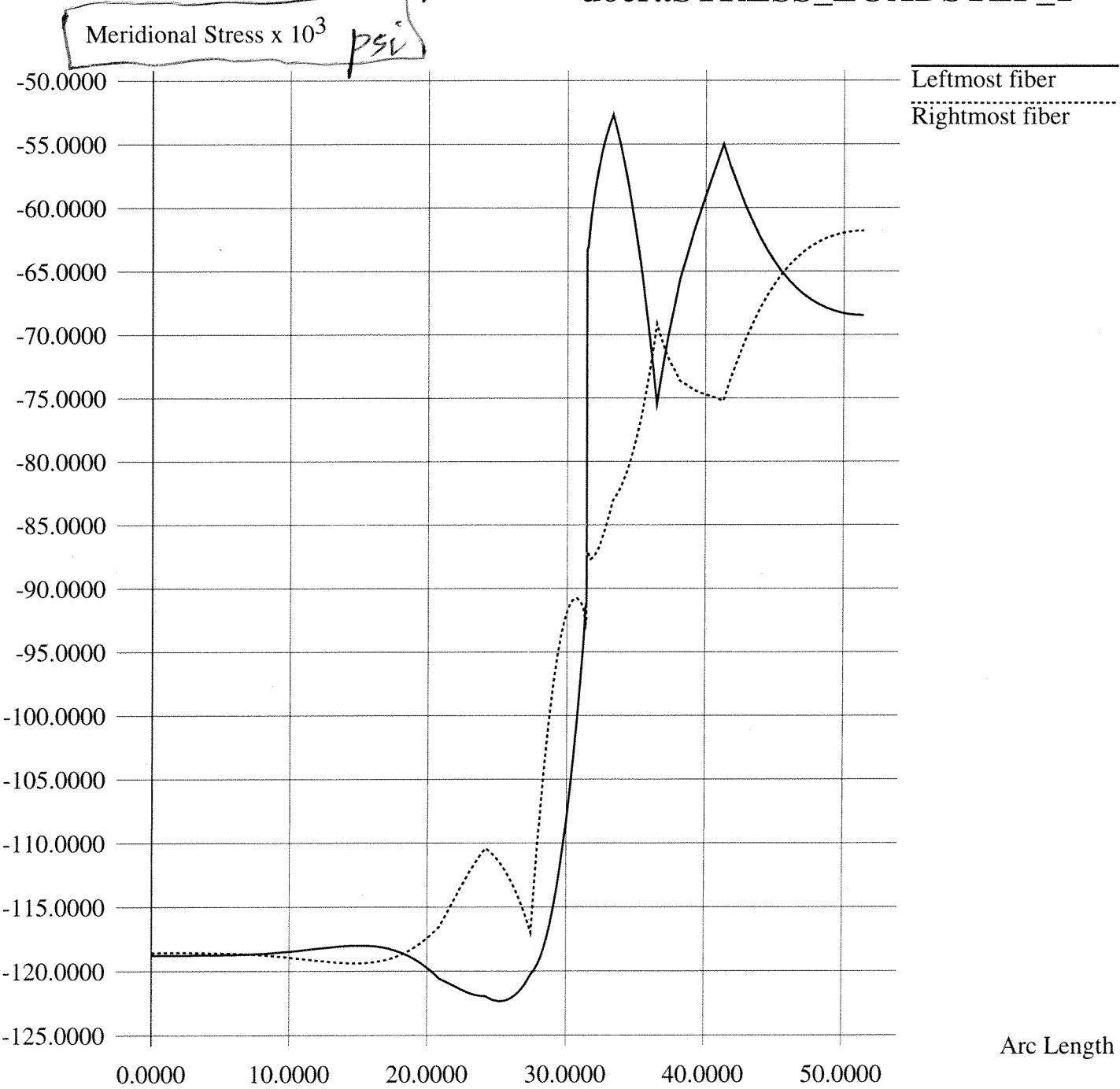


Output from BIGBOSCF for the optimized design



*Output from BIGBOSOR4 for the  
optimized design*

**doer..STRESS\_LOADSTEP\_1**



*Fig. 14*

Output from BIGBOSOR4 for the optimized design.

doer..STRESS\_LOADSTEP\_1

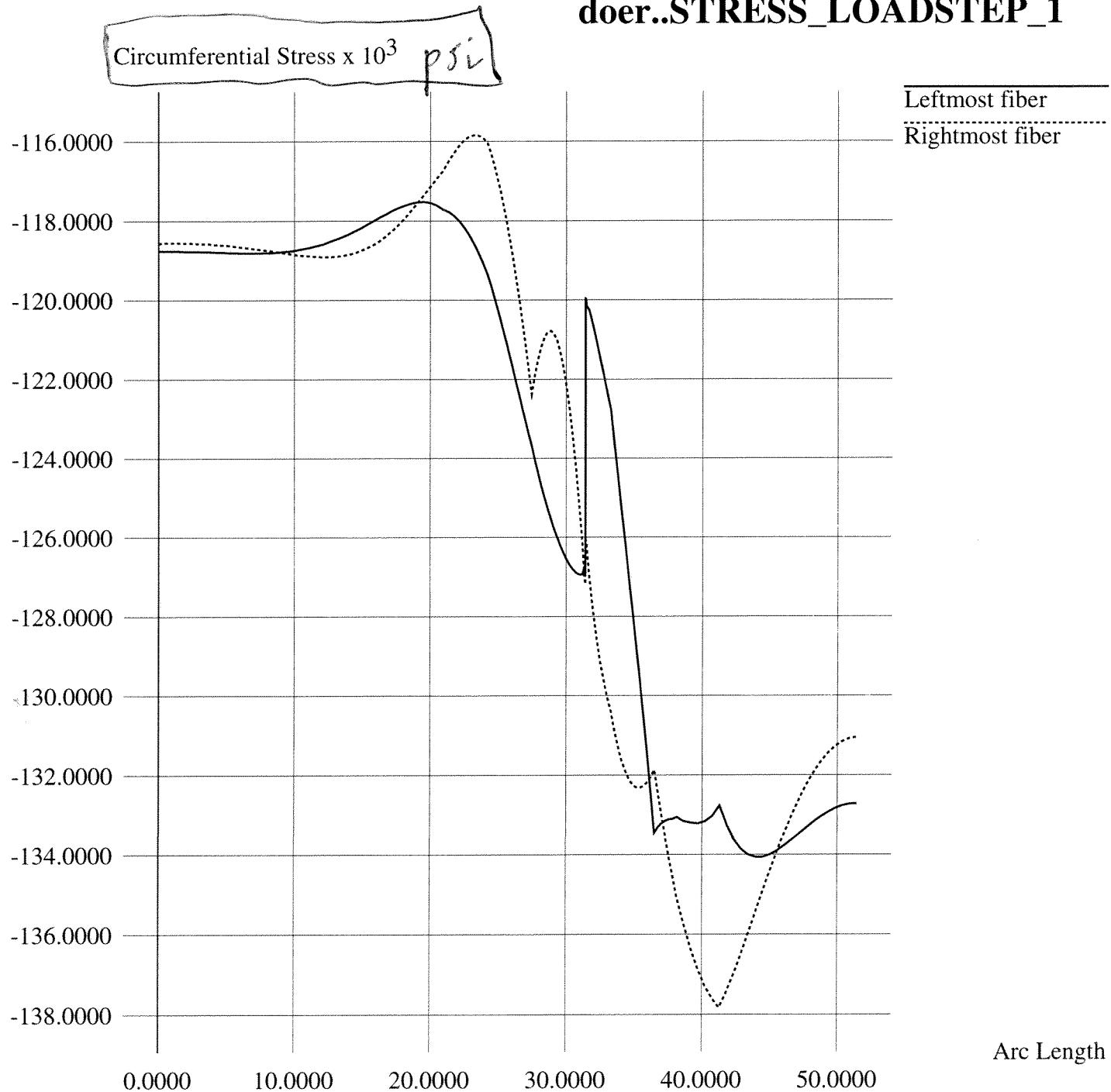


Fig. 15

108

Output from BIGBOSORT for the  
optimized design

doer..STRESS\_LOADSTEP\_1

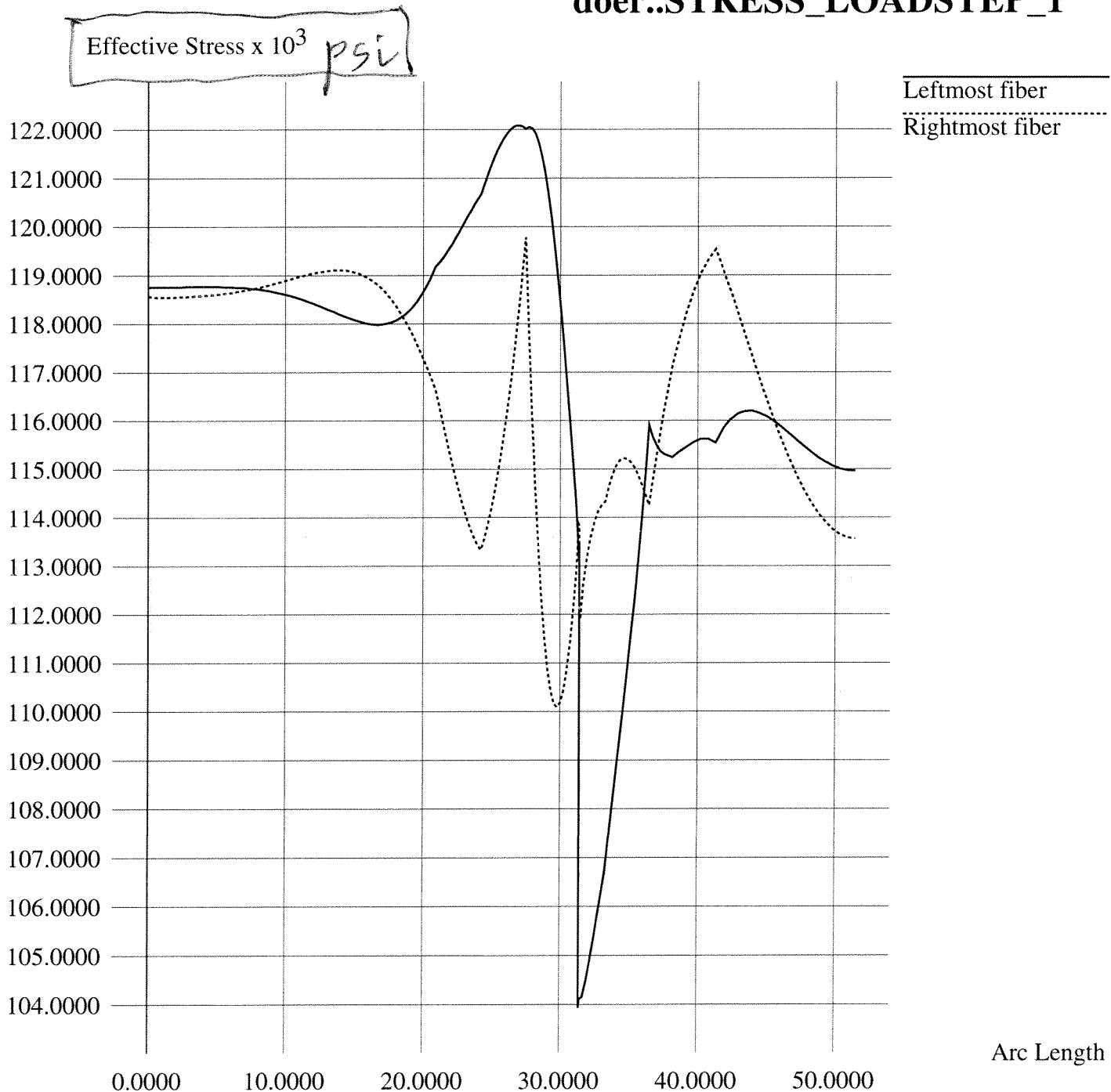


Fig. 16

Table 24 (2pp) b6, BEG (10 callouts for each shell segment)

n	\$ Do you want a tutorial session and tutorial output?
20.00000	\$ radius of the tank: RADIUS
40.00000	\$ total length of the cylinder: LENGTH
0.1600000E+08	\$ elastic modulus of the shell wall: EMOD
0.2500000	\$ Poisson ratio of the shell wall: NU
0.1600000	\$ weight density of the shell wall: DENSTY
91	\$ number of nodal points in the dome: NODSPH
91	\$ number of nodal points in the cylinder: NODCYL
10	\$ number of axial callouts in the dome: NPTSPH
10	\$ Number IZSPH of rows in the array ZSPH: IZSPH
0.000000	\$ axial location of callout in the dome: ZSPH( 1)
10.00000	\$ axial location of callout in the dome: ZSPH( 2)
12.00000	\$ axial location of callout in the dome: ZSPH( 3)
14.00000	\$ axial location of callout in the dome: ZSPH( 4)
15	\$ axial location of callout in the dome: ZSPH( 5)
16	\$ axial location of callout in the dome: ZSPH( 6)
17	\$ axial location of callout in the dome: ZSPH( 7)
18	\$ axial location of callout in the dome: ZSPH( 8)
19	\$ axial location of callout in the dome: ZSPH( 9)
20.00000	\$ axial location of callout in the dome: ZSPH(10)
10	\$ Number of axial callouts in the cylinder: NPTCYL
10	\$ Number IZCYL of rows in the array ZCYL: IZCYL
20.00000	\$ axial location of callout in the cylinder: ZCYL( 1)
21	\$ axial location of callout in the cylinder: ZCYL( 2)
22.00000	\$ axial location of callout in the cylinder: ZCYL( 3)
23	\$ axial location of callout in the cylinder: ZCYL( 4)
24	\$ axial location of callout in the cylinder: ZCYL( 5)
25.00000	\$ axial location of callout in the cylinder: ZCYL( 6)
26	\$ axial location of callout in the cylinder: ZCYL( 7)
28	\$ axial location of callout in the cylinder: ZCYL( 8)
30.00000	\$ axial location of callout in the cylinder: ZCYL( 9)
40.00000	\$ axial location of callout in the cylinder: ZCYL(10)
10	\$ Number IZREFSP of rows in the array ZREFSP: IZREFSP
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 1)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 2)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 3)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 4)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 5)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 6)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 7)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 8)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP( 9)
0.6250000	\$ location of ref. surf. in the dome: ZREFSP(10)
1.250000	\$ wall thickness in the dome: THKSPH( 1)
1.250000	\$ wall thickness in the dome: THKSPH( 2)
1.250000	\$ wall thickness in the dome: THKSPH( 3)
1.250000	\$ wall thickness in the dome: THKSPH( 4)
1.250000	\$ wall thickness in the dome: THKSPH( 5)
1.250000	\$ wall thickness in the dome: THKSPH( 6)
1.250000	\$ wall thickness in the dome: THKSPH( 7)
1.250000	\$ wall thickness in the dome: THKSPH( 8)
1.250000	\$ wall thickness in the dome: THKSPH( 9)
1.250000	\$ wall thickness in the dome: THKSPH(10)
10	\$ Number IZREFCY of rows in the array ZREFCY: IZREFCY
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 1)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 2)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 3)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 4)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 5)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 6)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 7)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 8)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY( 9)
1.250000	\$ location of the ref. surf. in the cylinder: ZREFCY(10)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 1)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 2)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 3)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 4)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 5)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 6)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 7)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 8)
2.500000	\$ thickness of the cylindrical shell: THKCYL( 9)
2.500000	\$ thickness of the cylindrical shell: THKCYL(10)
0	\$ low end of range of buckling circ. waves: NBUKLO
5	\$ high end of range of buckling circ. waves: NBUKHI
1	\$ Number NCASES of load cases (environments): NCASES
15000.00	\$ uniform external pressure: PRESS( 1)

## Table 24 (p. 2 of 2)

1.000000	\$ allowable buckling load (Use 1.0): BUCKLA( 1)
1.300000	\$ factor of safety for buckling: BUCKLF( 1)
2	\$ Number JSTRESS of columns in the array, STRESS: JSTRESS
120000	\$ maximum allowable effective stress: STRESSA( 1, 1)
120000	\$ maximum allowable effective stress: STRESSA( 1, 2)
1.000000	\$ factor of safety for stress: STRESSF( 1, 1)
1.000000	\$ factor of safety for stress: STRESSF( 1, 2)

input for BEGIN

Table 25 (3pp per DEC (10 callouts for each shell segment))

n	\$ Do you want a tutorial session and tutorial output?
3	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. ( 3 )
1.500000	\$ Upper bound of variable no. ( 3 )
Y	\$ Any more decision variables (Y or N) ?
4	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. ( 4 )
1.500000	\$ Upper bound of variable no. ( 4 )
Y	\$ Any more decision variables (Y or N) ?
5	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. ( 5 )
1.500000	\$ Upper bound of variable no. ( 5 )
Y	\$ Any more decision variables (Y or N) ?
6	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. ( 6 )
1.500000	\$ Upper bound of variable no. ( 6 )
Y	\$ Any more decision variables (Y or N) ?
7	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. ( 7 )
1.500000	\$ Upper bound of variable no. ( 7 )
Y	\$ Any more decision variables (Y or N) ?
8	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. ( 8 )
1.500000	\$ Upper bound of variable no. ( 8 )
Y	\$ Any more decision variables (Y or N) ?
9	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. ( 9 )
1.500000	\$ Upper bound of variable no. ( 9 )
Y	\$ Any more decision variables (Y or N) ?
10	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. (10)
1.500000	\$ Upper bound of variable no. (10)
Y	\$ Any more decision variables (Y or N) ?
13	\$ Choose a decision variable (1,2,3,...)
1.250000	\$ Lower bound of variable no. (13)
2.500000	\$ Upper bound of variable no. (13)
Y	\$ Any more decision variables (Y or N) ?
14	\$ Choose a decision variable (1,2,3,...)
1.250000	\$ Lower bound of variable no. (14)
2.500000	\$ Upper bound of variable no. (14)
Y	\$ Any more decision variables (Y or N) ?
15	\$ Choose a decision variable (1,2,3,...)
1.250000	\$ Lower bound of variable no. (15)
2.500000	\$ Upper bound of variable no. (15)
Y	\$ Any more decision variables (Y or N) ?
16	\$ Choose a decision variable (1,2,3,...)
1.250000	\$ Lower bound of variable no. (16)
2.500000	\$ Upper bound of variable no. (16)
Y	\$ Any more decision variables (Y or N) ?
17	\$ Choose a decision variable (1,2,3,...)
1.250000	\$ Lower bound of variable no. (17)
2.500000	\$ Upper bound of variable no. (17)
Y	\$ Any more decision variables (Y or N) ?
18	\$ Choose a decision variable (1,2,3,...)
1.250000	\$ Lower bound of variable no. (18)
2.500000	\$ Upper bound of variable no. (18)
Y	\$ Any more decision variables (Y or N) ?
19	\$ Choose a decision variable (1,2,3,...)
1.250000	\$ Lower bound of variable no. (19)
2.500000	\$ Upper bound of variable no. (19)
Y	\$ Any more decision variables (Y or N) ?
20	\$ Choose a decision variable (1,2,3,...)
1.250000	\$ Lower bound of variable no. (20)
2.500000	\$ Upper bound of variable no. (20)
Y	\$ Any more decision variables (Y or N) ?
21	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. (21)
1.500000	\$ Upper bound of variable no. (21)
Y	\$ Any more decision variables (Y or N) ?
22	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. (22)
1.500000	\$ Upper bound of variable no. (22)
Y	\$ Any more decision variables (Y or N) ?
23	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. (23)
1.500000	\$ Upper bound of variable no. (23)
Y	\$ Any more decision variables (Y or N) ?
24	\$ Choose a decision variable (1,2,3,...)

# Table 25 (p. 2 of 3)

0.6250000	\$ Lower bound of variable no. (24)
1.500000	\$ Upper bound of variable no. (24)
Y 25	\$ Any more decision variables (Y or N) ?
0.6250000	\$ Choose a decision variable (1,2,3,...)
1.500000	\$ Lower bound of variable no. (25)
Y 26	\$ Upper bound of variable no. (25)
0.6250000	\$ Any more decision variables (Y or N) ?
1.500000	\$ Choose a decision variable (1,2,3,...)
Y 27	\$ Lower bound of variable no. (26)
0.6250000	\$ Upper bound of variable no. (26)
1.500000	\$ Any more decision variables (Y or N) ?
Y 28	\$ Choose a decision variable (1,2,3,...)
0.6250000	\$ Lower bound of variable no. (27)
1.500000	\$ Upper bound of variable no. (27)
Y 31	\$ Any more decision variables (Y or N) ?
1.250000	\$ Choose a decision variable (1,2,3,...)
3.000000	\$ Lower bound of variable no. (31)
Y 32	\$ Upper bound of variable no. (31)
1.250000	\$ Any more decision variables (Y or N) ?
3.000000	\$ Choose a decision variable (1,2,3,...)
Y 33	\$ Lower bound of variable no. (32)
1.250000	\$ Upper bound of variable no. (32)
Y 34	\$ Any more decision variables (Y or N) ?
1.250000	\$ Choose a decision variable (1,2,3,...)
2.500000	\$ Lower bound of variable no. (34)
Y 35	\$ Upper bound of variable no. (34)
1.250000	\$ Any more decision variables (Y or N) ?
2.500000	\$ Choose a decision variable (1,2,3,...)
Y 36	\$ Lower bound of variable no. (35)
1.250000	\$ Upper bound of variable no. (35)
Y 37	\$ Any more decision variables (Y or N) ?
1.250000	\$ Choose a decision variable (1,2,3,...)
2.500000	\$ Lower bound of variable no. (37)
Y 38	\$ Upper bound of variable no. (37)
1.250000	\$ Any more decision variables (Y or N) ?
2.500000	\$ Choose a decision variable (1,2,3,...)
Y 39	\$ Lower bound of variable no. (38)
1.250000	\$ Upper bound of variable no. (38)
Y 40	\$ Any more decision variables (Y or N) ?
n	\$ Choose a decision variable (1,2,3,...)
Y 29	\$ Lower bound of variable no. (39)
1	\$ Upper bound of variable no. (39)
39	\$ Any more decision variables (Y or N) ?
0.5000000	\$ Choose a linked variable (1,2,3,...)
1	\$ Choose type of linking (1=polynomial; 2=user-defined)
n	\$ To which variable is this variable linked?
n	\$ Assign a value to the linking coefficient, C(j)
Y 30	\$ To what power is the decision variable raised?
1	\$ Any other decision variables in the linking expression?
39	\$ Any constant C0 in the linking expression?
0.5000000	\$ Any more linked variables (Y or N) ?
1	\$ Choose a linked variable (1,2,3,...)
n	\$ Choose type of linking (1=polynomial; 2=user-defined)
n	\$ To which variable is this variable linked?
Y 40	\$ Assign a value to the linking coefficient, C(j)
1	\$ To what power is the decision variable raised?
39	\$ Any other decision variables in the linking expression?
1.000000	\$ Any constant C0 in the linking expression?
1	\$ Any more linked variables (Y or N) ?
n	\$ Choose a linked variable (1,2,3,...)
	\$ Choose type of linking (1=polynomial; 2=user-defined)
	\$ To which variable is this variable linked?
	\$ Assign a value to the linking coefficient, C(j)
	\$ To what power is the decision variable raised?
	\$ Any other decision variables in the linking expression?

↑ See Table 14 for an explanation of this input.

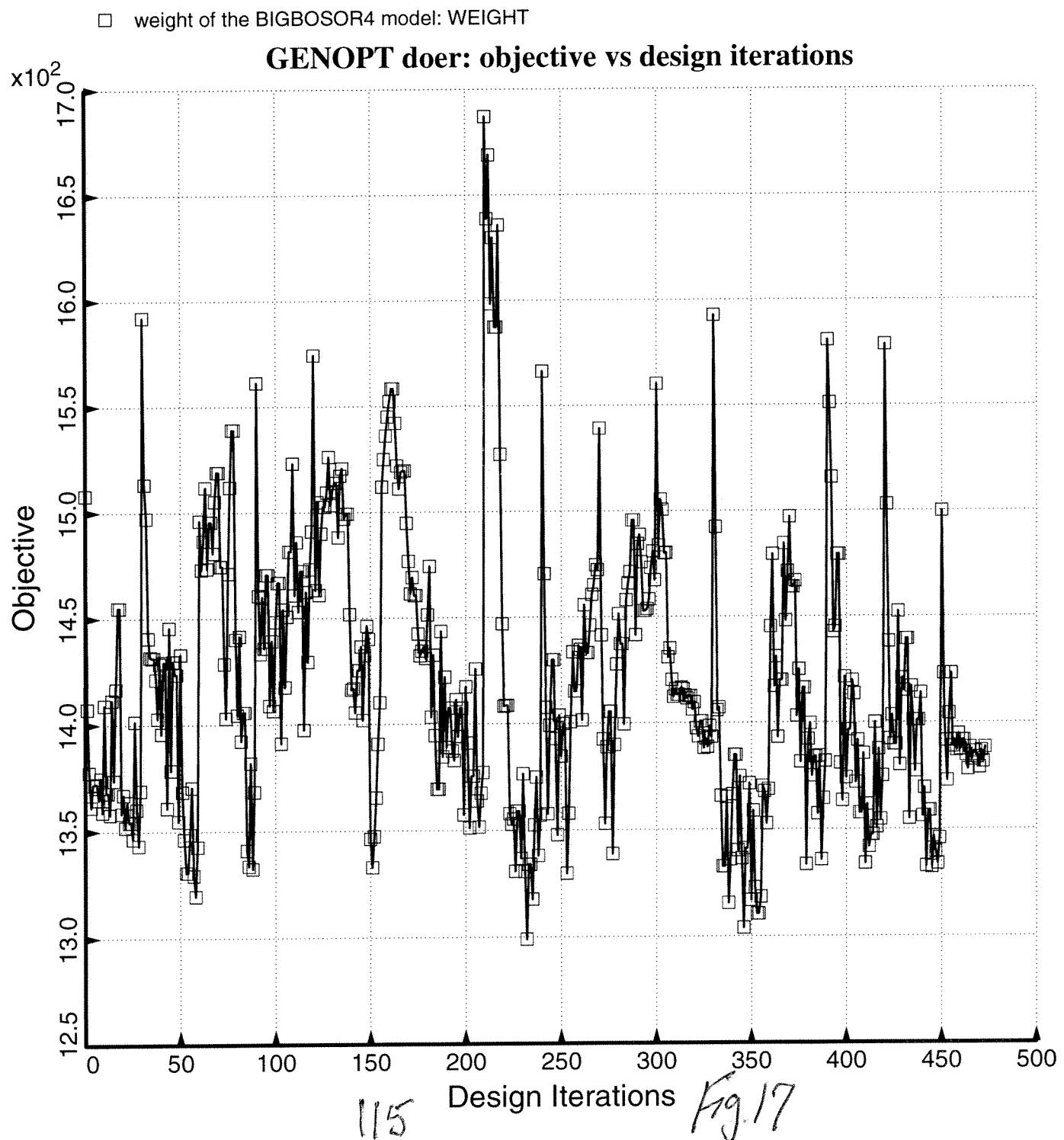
## Table 25 (p. 3 of 3)

n	\$ Any constant C0 in the linking expression?
n	\$ Any more linked variables (Y or N) ?
n	\$ Any inequality relations among variables? (type H)
y	\$ Any escape variables (Y or N) ?
y	\$ Want to have escape variables chosen by default?

input for DECIDE

Output from SUPEROPT/CHOOSEPLOT/DIPLOT

10 callouts for each shell segment



# Table 26 (4 pages) doer.OPT (output from OPTIMIZE)

```

n      $ Do you want a tutorial session and tutorial output?
0      $ Choose an analysis you DON'T want (1, 2...), IBEHAV
2      $ NPRINT= output index (0=GOOD, 1=ok, 2=debug, 3=too much)
2      $ Choose type of analysis (1=opt., 2=fixed, 3=sensit.) ITYPE
5      $ How many design iterations in this run (3 to 25)?
n      $ Take "shortcuts" for perturbed designs (Y or N)?
2      $ Choose 1 or 2 or 3 or 4 or 5 for IDESIGN
1      $ Choose 1 or 2 or 3 or 4 or 5 for move limits, IMOVE
y      $ Do you want default (RATIO=10) for initial move limit jump?
y      $ Do you want the default perturbation (dx/x = 0.05)?
n      $ Do you want to have dx/x modified by GENOPT?
n      $ Do you want to reset total iterations to zero (Type H)?

```

\*\*\*\*\* END OF THE doer.OPT FILE \*\*\*\*\*  
\*\*\*\*\* JUNE, 2009 VERSION OF GENOPT \*\*\*\*\*  
\*\*\*\*\* BEGINNING OF THE doer.OPM FILE \*\*\*\*\*

\*\*\*\*\* MAIN PROCESSOR \*\*\*\*\*

The purpose of the mainprocessor, OPTIMIZE, is to perform,  
in a batch mode, the work specified by MAINSETUP for the case  
called doer. Results are stored in the file doer.OPM.  
Please inspect doer.OPM before doing more design iterations.

STRUCTURAL ANALYSIS FOR DESIGN ITERATION NO. 0:

	STRUCTURAL ANALYSIS WITH UNPERTURBED DECISION VARIABLES	DEFINITION
0	VAR. DEC. ESCAPE LINK. LINKED LOWER CURRENT UPPER DEFINITION	BOUND BOUND
	NO. VAR. VAR. TO CONSTANT BOUND VALUE	
1	N N N 0 0.00E+00 0.00E+00 6.2500E-01 0.00E+00 location of ref. surf. i»	
n the dome: ZREFSP(1 )		
2	N N N 0 0.00E+00 0.00E+00 6.2500E-01 0.00E+00 location of ref. surf. i»	
n the dome: ZREFSP(2 )		
3	Y N N 0 0.00E+00 6.25E-01 6.2501E-01 1.50E+00 location of ref. surf. i»	
n the dome: ZREFSP(3 )		
4	Y N N 0 0.00E+00 6.25E-01 6.3533E-01 1.50E+00 location of ref. surf. i»	
n the dome: ZREFSP(4 )		
5	Y N N 0 0.00E+00 6.25E-01 6.6382E-01 1.50E+00 location of ref. surf. i»	
n the dome: ZREFSP(5 )		
6	Y N N 0 0.00E+00 6.25E-01 7.9746E-01 1.50E+00 location of ref. surf. i»	
n the dome: ZREFSP(6 )		
7	Y N N 0 0.00E+00 6.25E-01 8.5627E-01 1.50E+00 location of ref. surf. i»	
n the dome: ZREFSP(7 )		
8	Y N N 0 0.00E+00 6.25E-01 8.5121E-01 1.50E+00 location of ref. surf. i»	
n the dome: ZREFSP(8 )		
9	Y N N 0 0.00E+00 6.25E-01 9.2385E-01 1.50E+00 location of ref. surf. i»	
n the dome: ZREFSP(9 )		
10	Y N N 0 0.00E+00 6.25E-01 9.5028E-01 1.50E+00 location of ref. surf. i»	
n the dome: ZREFSP(10)		
11	N N N 0 0.00E+00 0.00E+00 1.2500E+00 0.00E+00 wall thickness in the do»	
me: THKSPH(1 )		
12	N N N 0 0.00E+00 0.00E+00 1.2500E+00 0.00E+00 wall thickness in the do»	
me: THKSPH(2 )		
13	Y N N 0 0.00E+00 1.25E+00 1.2611E+00 2.50E+00 wall thickness in the do»	
me: THKSPH(3 )		
14	Y N N 0 0.00E+00 1.25E+00 1.2500E+00 2.50E+00 wall thickness in the do»	
me: THKSPH(4 )		
15	Y N N 0 0.00E+00 1.25E+00 1.2936E+00 2.50E+00 wall thickness in the do»	
me: THKSPH(5 )		
16	Y N N 0 0.00E+00 1.25E+00 1.6258E+00 2.50E+00 wall thickness in the do»	
me: THKSPH(6 )		
17	Y N N 0 0.00E+00 1.25E+00 1.6748E+00 2.50E+00 wall thickness in the do»	
me: THKSPH(7 )		
18	Y N N 0 0.00E+00 1.25E+00 1.5124E+00 2.50E+00 wall thickness in the do»	
me: THKSPH(8 )		
19	Y N N 0 0.00E+00 1.25E+00 1.6510E+00 2.50E+00 wall thickness in the do»	
me: THKSPH(9 )		
20	Y N N 0 0.00E+00 1.25E+00 1.9692E+00 2.50E+00 wall thickness in the do»	
me: THKSPH(10)		
21	Y N N 0 0.00E+00 6.25E-01 1.2681E+00 1.50E+00 location of the ref. sur»	
f. in the cylinder: ZREFCY(1 )		
22	Y N N 0 0.00E+00 6.25E-01 7.3318E-01 1.50E+00 location of the ref. sur»	
f. in the cylinder: ZREFCY(2 )		
23	Y N N 0 0.00E+00 6.25E-01 1.0341E+00 1.50E+00 location of the ref. sur»	

optimum design.

# Table 26 (p. 2 of 4)

f. in the cylinder: ZREFCY(3 )							← optimum design
24 Y N N 0	0.00E+00	6.25E-01	6.2500E-01	1.50E+00	location of the ref. sur»		
f. in the cylinder: ZREFCY(4 )							
25 Y N N 0	0.00E+00	6.25E-01	9.5432E-01	1.50E+00	location of the ref. sur»		
f. in the cylinder: ZREFCY(5 )							
26 Y N N 0	0.00E+00	6.25E-01	1.2219E+00	1.50E+00	location of the ref. sur»		
f. in the cylinder: ZREFCY(6 )							
27 Y N N 0	0.00E+00	6.25E-01	1.3482E+00	1.50E+00	location of the ref. sur»		
f. in the cylinder: ZREFCY(7 )							
28 Y N N 0	0.00E+00	6.25E-01	1.0119E+00	1.50E+00	location of the ref. sur»		
f. in the cylinder: ZREFCY(8 )							
29 N N Y 39	5.00E-01	0.00E+00	1.0661E+00	0.00E+00	location of the ref. sur»		
f. in the cylinder: ZREFCY(9 )							
30 N N Y 39	5.00E-01	0.00E+00	1.0661E+00	0.00E+00	location of the ref. sur»		
f. in the cylinder: ZREFCY(10)							
31 Y N N 0	0.00E+00	1.25E+00	2.3681E+00	3.00E+00	thickness of the cylindr»		
ical shell: THKCYL(1 )							
32 Y N N 0	0.00E+00	1.25E+00	1.5889E+00	3.00E+00	thickness of the cylindr»		
ical shell: THKCYL(2 )							
33 Y N N 0	0.00E+00	1.25E+00	2.1644E+00	2.50E+00	thickness of the cylindr»		
ical shell: THKCYL(3 )							
34 Y Y N 0	0.00E+00	1.25E+00	1.4285E+00	2.50E+00	thickness of the cylindr»		
ical shell: THKCYL(4 )							
35 Y Y N 0	0.00E+00	1.25E+00	2.2717E+00	2.50E+00	thickness of the cylindr»		
ical shell: THKCYL(5 )							
36 Y Y N 0	0.00E+00	1.25E+00	2.5000E+00	2.50E+00	thickness of the cylindr»		
ical shell: THKCYL(6 )							
37 Y Y N 0	0.00E+00	1.25E+00	2.4991E+00	2.50E+00	thickness of the cylindr»		
ical shell: THKCYL(7 )							
38 Y Y N 0	0.00E+00	1.25E+00	1.9986E+00	2.50E+00	thickness of the cylindr»		
ical shell: THKCYL(8 )							
39 Y Y N 0	0.00E+00	1.25E+00	2.1322E+00	2.50E+00	thickness of the cylindr»		
ical shell: THKCYL(9 )							
40 N N Y 39	1.00E+00	0.00E+00	2.1322E+00	0.00E+00	thickness of the cylindr»		
ical shell: THKCYL(10)							

BEHAVIOR FOR 1 ENVIRONMENT (LOAD SET)

CONSTRAINT NUMBER	BEHAVIOR VALUE	DEFINITION
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BEHAVIOR FOR LOAD SET NUMBER, ILOADX= 1

BIGBOSOR4 input file for: buckling load (INDIC=1)  
doer.BEHX1

WEIGHT OF THE BIGBOSOR4 MODEL OF THE TANK  
TOTMAS = 1.3923E+03

\*\*\*\*\*

BUCKLING LOAD FACTORS AND MODES (BEHX1)

5.0683E+00( 0)  
5.0412E+00( 1)  
1.9042E+00( 2)  
1.3301E+00( 3) ← critical  
1.9886E+00( 4)  
2.9995E+00( 5)

Critical buckling load factor, BUCKL= 1.3301E+00

Critical number of circumferential waves, NWVCRT= 3  
1 1.330093 tank buckling eigenvalue: BUCKL(1)

BEHAVIOR OVER J = shell segment number

BIGBOSOR4 input file for: maximum effective stress (INDIC=0)  
doer.BEHX2

Shell skin maximum effective stress,

at nodal point 66 SKNMAX= 1.2528E+05

Shell skin maximum effective stress,

at nodal point 52 SKNMAX= 1.2468E+05

\*\*\*\*\* MAXIMUM EFFECTIVE STRESS IN ISOTROPIC WALL \*\*\*\*\*

STRMAX= 1.2528E+05

\*\*\*\*\*

2 125277.0 effective stress in shell segment: STRESS(1,1)

BIGBOSOR4 input file for: maximum effective stress (INDIC=0)

"oscillatory" optimum thicknesses probably not good. We are using shell theory, thin and the cylinder is very thick. In this model the callouts corresponding to these four values are spaced at 1-inch intervals. The variation in thickness from callout to callout is approximately the same as the callout spacing. Thin shell theory not appropriate.

# Table 26 (p. 3 of 4)

doer.BEHX2

3

124684.9

effective stress in shell segment: STRESS(1,2)

\*\*\*\*\* RESULTS FOR LOAD SET NO. 1 \*\*\*\*\*

PARAMETERS WHICH DESCRIBE BEHAVIOR (e.g. stress, buckling load)

BEH.	CURRENT	DEFINITION
NO.	VALUE	
1	1.330E+00	tank buckling eigenvalue: BUCKL(1)
2	1.253E+05	effective stress in shell segment: STRESS(1,1)
3	1.247E+05	effective stress in shell segment: STRESS(1,2)

\*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\* NOTE \*\*\*\*\*

The phrase, "NOT APPLY", for MARGIN VALUE means that that particular margin value is exactly zero.

\*\*\* END NOTE \*\*\* END NOTE \*\*\* END NOTE \*\*\* END NOTE \*\*\*

\*\*\*\*\* RESULTS FOR LOAD SET NO. 1 \*\*\*\*\*

MARGINS CORRESPONDING TO CURRENT DESIGN (F.S. = FACTOR OF SAFETY)

MARGIN CURRENT

NO.	VALUE	DEFINITION
1	2.315E-02	(BUCKL(1)/BUCKLA(1)) / BUCKLF(1)-1; F.S. = 1.30
2	-4.212E-02	(STRESSA(1,1)/STRESS(1,1)) / STRESSF(1,1)-1; F.S. = 1.00
3	-3.757E-02	(STRESSA(1,2)/STRESS(1,2)) / STRESSF(1,2)-1; F.S. = 1.00

\*\*\*\*\* DESIGN OBJECTIVE \*\*\*\*\*

CURRENT VALUE OF THE OBJECTIVE FUNCTION:

VAR. CURRENT

NO.	VALUE	DEFINITION
1	1.392E+03	weight of the BIGBOSOR4 model: WEIGHT

\*\*\*\*\* DESIGN OBJECTIVE \*\*\*\*\*

\*\*\*\*\* ALL 1 LOAD CASES PROCESSED \*\*\*\*\*

PARAMETERS WHICH ARE ALWAYS FIXED. NONE CAN BE DECISION VARIAB.

VAR. CURRENT

NO.	VALUE	DEFINITION
1	2.000E+01	radius of the tank: RADIUS
2	4.000E+01	total length of the cylinder: LENGTH
3	1.600E+07	elastic modulus of the shell wall: EMOD
4	2.500E-01	Poisson ratio of the shell wall: NU
5	1.600E-01	weight density of the shell wall: DENSTY
6	0.000E+00	axial location of callout in the dome: ZSPH(1)
7	1.000E+01	axial location of callout in the dome: ZSPH(2)
8	1.200E+01	axial location of callout in the dome: ZSPH(3)
9	1.400E+01	axial location of callout in the dome: ZSPH(4)
10	1.500E+01	axial location of callout in the dome: ZSPH(5)
11	1.600E+01	axial location of callout in the dome: ZSPH(6)
12	1.700E+01	axial location of callout in the dome: ZSPH(7)
13	1.800E+01	axial location of callout in the dome: ZSPH(8)
14	1.900E+01	axial location of callout in the dome: ZSPH(9)
15	2.000E+01	axial location of callout in the dome: ZSPH(10)
16	2.000E+01	axial location of callout in the cylinder: ZCYL(1)
17	2.100E+01	axial location of callout in the cylinder: ZCYL(2)
18	2.200E+01	axial location of callout in the cylinder: ZCYL(3)
19	2.300E+01	axial location of callout in the cylinder: ZCYL(4)
20	2.400E+01	axial location of callout in the cylinder: ZCYL(5)
21	2.500E+01	axial location of callout in the cylinder: ZCYL(6)
22	2.600E+01	axial location of callout in the cylinder: ZCYL(7)
23	2.800E+01	axial location of callout in the cylinder: ZCYL(8)
24	3.000E+01	axial location of callout in the cylinder: ZCYL(9)
25	4.000E+01	axial location of callout in the cylinder: ZCYL(10)

PARAMETERS WHICH ARE ENVIRONMENTAL FACTORS (e.g. loads, temps.)

VAR. CURRENT

NO.	VALUE	DEFINITION
1	1.500E+04	uniform external pressure: PRESS(1)

PARAMETERS WHICH ARE CLASSIFIED AS ALLOWABLES (e.g. max. stress)

# Table 26 (p. 4 of 4)

VAR. NO.	CURRENT VALUE	DEFINITION
1	1.000E+00	allowable buckling load (Use 1.0): BUCKLA(1 )
2	1.200E+05	maximum allowable effective stress: STRESSA(1 ,1 )
3	1.200E+05	maximum allowable effective stress: STRESSA(1 ,2 )

PARAMETERS WHICH ARE FACTORS OF SAFETY

VAR. NO.	CURRENT VALUE	DEFINITION
1	1.300E+00	factor of safety for buckling: BUCKLF(1 )
2	1.000E+00	factor of safety for stress: STRESSF(1 ,1 )
3	1.000E+00	factor of safety for stress: STRESSF(1 ,2 )

## 0 INEQUALITY CONSTRAINTS WHICH MUST BE SATISFIED

### DESCRIPTION OF FILES USED AND GENERATED IN THIS RUN:

doer.NAM = This file contains only the name of the case.

doer.OPM = Output data. Please list this file and inspect carefully before proceeding.

doer.OPP = Output file containing evolution of design and margins since the beginning of optimization cycles.

doer.CBL = Labelled common blocks for analysis.  
(This is an unformatted sequential file.)

doer.OPT = This file contains the input data for MAINSETUP as well as OPTIMIZE. The batch command OPTIMIZE can be given over and over again without having to return to MAINSETUP because doer.OPT exists.

URPROMPT.DAT= Prompt file for interactive input.

For further information about files used and generated during operation of GENOPT, give the command HELPG FILES.

Menu of commands: CHOOSEPLOT, OPTIMIZE, MAINSETUP, CHANGE, DECIDE, SUPEROPT

IN ORDER TO AVOID FALSE CONVERGENCE OF THE DESIGN, BE SURE TO RUN "OPTIMIZE" MANY TIMES DURING AN OPTIMIZATION AND/OR USE THE "GLOBAL" OPTIMIZING SCRIPT, "SUPEROPT".  
\*\*\*\*\* END OF doer.OPM FILE \*\*\*\*\*

end of doer.OPM