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Introduction

Realization of "Conway's game of life" using Logisim and CdM-8.

"Conway's game of life" is a cellural automaton. This is an auto-playable game. Player set an initial condition and then only can observe the development.

Rules:

1. The field of "Game of life" is a grid of square cells. Each cell has two conditions it can be live or dead.
2. Every cell has 8 neighbors, which are the cells that are horizontally, vertically, or diagonally adjacent.
3. Any live cell with less than two neighbors dies because of underpopulation.
4. Any dead cell with three neighbors becomes a live.
5. Any live cell with two or three neighbors continues to live.
6. Any live cell with more than three neighbors dies because of overpopulation.

Problem statement

We have made 2 powerful improvements and 2 concept changes from the basic technical task.

Improvements:

1. We have composed a toroidal cycled field with size **32*32**
2. We have extended simulation rules choice using 2 8-bit inputs as bit-arrays.
Now you can set birth or surviving for any combination of neighbors count from **1** to **8**.

Concept changes:

1. We have decided to use Logisim keyboard handling circuit for cursor moving and cell changing instead of a joystick.
2. Video buffer (named **random write buffer**) has been made asynchronous.
Besides, we have add **clear** input to it.

Other components wasn't mentioned in basic technical project. Here you can see our addition for the technical project.

Extension of technical project

Realization of "Conway's game of life" has two main parts, Logisim part and Assembler part.

Logisim part is responsible for:

1. User interface. Player can set his own simulation rules and start a new game or clean the field with special buttons.
2. Display. Display represented by matrix with size **32x32**. Matrix has two different colors for dead and alive cells.
3. Constructing environment data for current cell.
4. Storing current generation and new generation of our simulation.

Assembler:

1. Spreads simulation rules.
2. Iterates by all rows and skip null rows.
3. Iterates by cells in every row which have significant environment.
4. Gets cell's environment data and sends invert signal if it is necessary.
5. Interrupts field processing if static generation was reached.

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Analogue

We have found 3 interesting versions of "Conway's game of life" in the Internet

1. [Version is full madden in Logisim with toroidal field 16*16](#). Works fast but small field doesn't allow construct a lot of setups. For example "[Pulsar](#)" or "[Copperhead](#)":
2. [Web version](#) - fast and convenient. Has endless field. Alas, we do not have similar capacities
3. In [this video](#) you can see Turing machine, 1D and 3D versions, wire version and so on.

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User guide

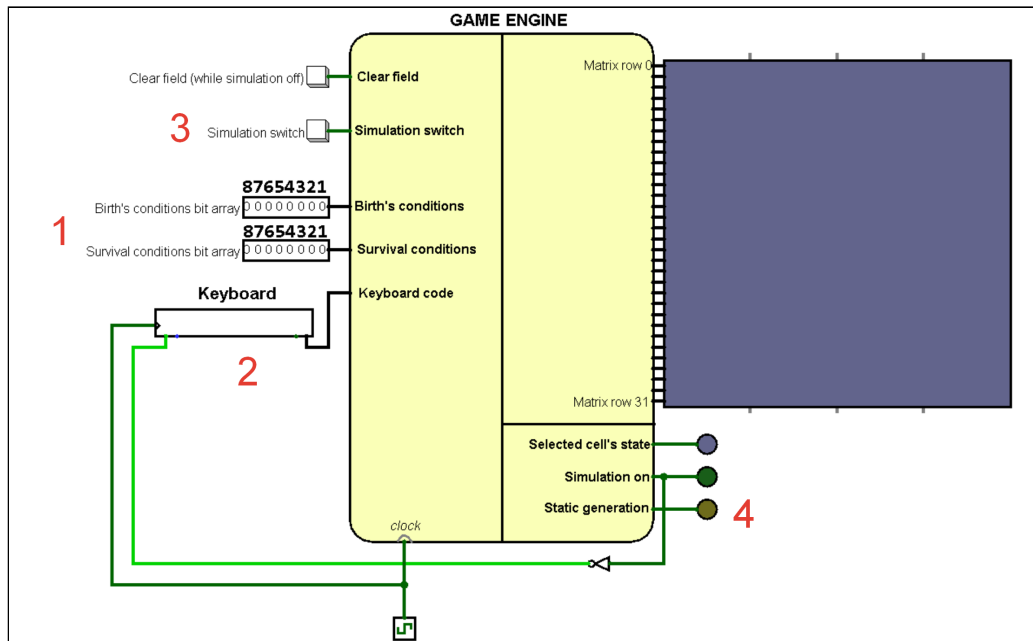
Our version of "Conway's game of life" works with universal sets of conditions for birth and survival.

1. To set conditions switch bits in birth/survival 8-bit inputs where value 1 on position **N** means that birth/survival will be fulfilled when cell has **N** neighbors.
2. After this click on keyboard element and use one of two keyboard layouts to move blinking cursor and change cells' states.

KEY	DIRECTION
NUM 7 / Q	top-left
NUM 8 / W	top
NUM 9 / E	top-right
NUM 4 / A	left
NUM 6 / D	right
NUM 1 / Z	bottom-left
NUM 2 / S	bottom
NUM 3 / C	bottom-right

NUM 5 / **Space** - change state of selected cell

3. When you have set initial field state press button "Simulation switch" and observe evolution! **You can stop simulation and edit field at any time. But if CPU cursor has processed some cells you would get half-counted generation**
4. If the next generation is the same as previous simulation will be interrupted with yellow LED-indicator lights up.



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Documentation

Special terms

There are some special terms that are used in different places below:

1. **Environment** is cell or cells' set with a border one cell wide on all sides. E.g.:
 - for cell (Y, X) environment will be $[(Y-1, X-1), (Y-1, X), (Y-1, X+1), (Y, X-1), (Y, X), (Y, X+1), (Y+1, X-1), (Y+1, X), (Y+1, X+1)]$ with **centre bit** (Y, X) (term **centre bit** is meaningful only for one cell's environment)
 - environment for full row (all X in range $[0, 31]$) Y will be full rows $Y-1, Y$ and $Y+1$
2. **Environment sum** is a sum of cells' values from environment border
3. **Significant environment** is an environment which has at least one cell with value **1** (including border cells)
4. **Static generation** is a field setup and rules under which no changes are possible

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Assembler

Short description

Due to optimization reasons CdM-8 has only 2 main tasks: iteration by **Y,X** positions and determination whether cell should be changed. After the all cells' processing CdM-8 send signal to **update generation PSEUDO WRITE register**

In ASM code we use **asect constants like this:**

```
asect 8
constSample:

# ...

ldi r0, constSample # r0 sets to 8
```

Often we save address value to its address:

```
ldi r0, IOAddr
st r0, r0
```

The reason for this action is **PSEUDO WRITE mode for some I/O registers**

RAM distribution

- **0xd0** - flag for checking non-static generation
- **0xe0** - birth's **spreaded** conditions first byte
- **0xe8** - death's **spreaded** conditions first byte

Stack initial position - **0xd0**

▼ Constants for this cells

```
# Internal data addresses
aset 0xe0
birthConditionsRowStart:

aset 0xe8
deathConditionsRowStart:

aset 0xd0
isNonStaticGeneration:
```

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Cells referring to I/O regs.

Cells from **0xf0** to **0xff** are allocated for I/O registers.

See detailed description in [Logisim topic](#)

► Constants for I/O cells

```
# Asects for I/O registers
aset 0xf0
IOGameMode:

aset 0xf1
IOBirthConditions:

aset 0xf2
IODeathConditions:

aset 0xf3
IOY:

aset 0xf4
IOX:

aset 0xf5
IOBit:

aset 0xf6
IOEnvSum:

aset 0xf7
IONullRowsEnv:
```

```

asect 0xf8
IONextSignificantX:

asect 0xf9
IOInvertBitSignal:

asect 0xfa
IOUpdateGeneration:

```

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Code description

Simulation start

This part just waits whilst user presses start button and after it loads game conditions to RAM using [spreadByte subroutine](#)

For optimized conditions checking survival conditions [inverts](#) to death's conditions. See how this optimization works [here](#).

► Code

```

asect 0
br start

#=====#
#   Place for subroutines   #
#=====#
...
#=====#

start:
    # Move SP before destributed cells
    setsp 0xd0

    # Waiting for IOGameMode I/O reg. != 0
    ldi r1, IOGameMode
    do
        ld r1, r0
        tst r0
    until nz

```

```

ldi r1, gameMode
st r1, r0

# Read birth and death conditions from I/O regs.
ldi r1, IOBirthConditions
ld r1, r0
ldi r1, birthConditionsRowStart
jsr spreadByte
ldi r1, IODeathConditions
ld r1, r0
ldi r1, deathConditionsRowStart
jsr spreadByte

```

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Main cycle

This part will repeats while simulations stays on.

Before cycle we reset flag in cell `isNonStaticGeneration` and update stable generation's buffer using save signal to `IOUpdateGeneration` referred to [Logisim](#). As a result, we can get correct data for processing cells.

Main cycle iterates by `Y` (row index) in decreasing order [`31`, `0`].

We use two optimizations for skipping meaningless iterations:

1. If rows `Y-1`, `Y` and `Y+1` (rows environment) are null (flag from `IONullRowsEnv` referred to [I/O register](#) will be `1`) then we decrement `Y`.
2. If rows environment isn't null we iterates by `X` with significant environment (surrounding sum > 0 or centre bit = 1) which are received from `IONextSignificantX` [I/O register](#). When new received `X` >= current `X` we end cycle for this row

For every significant (`Y`, `X`) combination we get state of selected cell and its environment's sum using `IOBit` and `IOEnvSum` addresses which are referred to [I/O registers](#)

For zero sum:

- Alive cell is killed immediately using save signal **IOInvertBitSignal** referred to Logisim
- Empty cell is skipped

For non-zero sum we call **subroutine processBit**

If there are no changed cells (value in **isNonStaticGeneration will stay 0) we make a conclusion that there is a static generation so we stop simulation using save signal to game mode I/O register and interrupt main cycle.**

► Code

```
main:

    # Reset flag for non-static
    ldi r0, isNonStaticGeneration
    ldi r1, 0
    st r0, r1

    # Update stable generation's buffer to get new data from env. data
    constructor
    ldi r0, IOUpdateGeneration
    st r0, r0

    # Count new cells' states
    ldi r3, 31 # row iterator
    do
        # If game mode = 0 we interrupt cycle and go to start code
        part

        # NEW GENERATION CAN BE COUNTED PARTITIONALLY
        ldi r0, IOGameMode
        ld r0, r0
        tst r0
        bz start

        push r3 # Save row iterator

        # Send Y to logisim
        ldi r0, IOY
        st r0, r3

        # If all rows in env. are null => skip this row
        ldi r3, IONullRowsEnv
        ld r3, r3
        tst r3
        bnz rowProcessed
```

```

ldi r1, 0 # Value for searching first significant X

# Send X to Logisim
ldi r0, IOX
st r0, r1

# Get the first X with significant env.
ldi r3, IONextSignificantX
ld r3, r2

do
    # Save current X
    move r2, r1
    push r1

    # Send X to Logisim
    ldi r0, IOX
    st r0, r1

    # Read data for this cell
    ldi r0, IOEnvSum
    ld r0, r0
    ldi r1, IOBit
    ld r1, r1

    # Check birth or death conditions and save bit
depends on conditions
    if
        tst r0
    is nz
        jsr processBit
    else
        # If sum = 0 alive cell must die
        if
            tst r1
        is nz
            ldi r0, IOInvertBitSignal
            st r0, r0

            # Set flag for non-static generation
to its address (!= 0)
            ldi r0, isNonStaticGeneration
            st r0, r0
        fi
    fi

    # Get the next X with significant env. lower than
current
    pop r1
    ld r3, r2

```

```

                                # If new X greater of equal => cycle ends
                                cmp r2, r1
until ge
rowProcessed:

                                # Get and decrement row iterator
                                pop r3
                                dec r3

                                until mi
# Go to main cycle begin if generation isn't static
ldi r0, isNonStaticGeneration
ld r0, r0
tst r0
bnz main
# Otherwise reset game mode and go to start
ldi r0, IOGameMode
st r0, r0
br start

halt
end

```

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Subroutines

spreadByte

- This subroutine spread byte from **r0** into cells from **r1** to **r1 + 7**. In other words **spreadByte** writes every bit of byte from **r0** to cells from **r1** to **r1 + 7**, writing the low order bit into **r1** and the high order bit into **r1 + 7**.
- **spreadByte** is used to write game settings to the memory.
- Thanks to **spreadByte** we can easily decide what we should do with current cell without using loops.

► Code

```

spreadByte:
    # Iterator
    ldi r3, 0b00001000 # 8
    while
        tst r3

```



```

        stays nz
            # The process of spreading byte
            # Get lower bit and save to current cell
            ldi r2, 0b00000001
            and r0, r2
            st r1, r2

            # Increment cell address, shift data byte and decrement
iterator
            inc r1
            shra r0
            dec r3
        wend
    rts

```

processBit

- This subroutine gets neighbors' sum in **r0** and centre bit value in **r1**.
- Depending on bit value it chooses birth or death conditions
- Thanks to [spreaded conditions](#) we can simply add to conditions' begin address value **r0 - 1** and check data by new address
- If there is **1** we should change value in selected cell so [we send this signal to Logisim](#) and set flag in **isNonStaticGeneration** to non-zero value.

► Code

```

processBit:
    # r0 - sum
    # r1 - bit
    # Send save signal to PSEUDO reg. IOInvertBitSignal if bit should be
    # inverted (we count that IOX and IOY regs. contain correct coords.)
    if
        tst r1
    is z
        ldi r2, birthConditionsRowStart
    else
        ldi r2, deathConditionsRowStart
    fi
    # Check bit in spreaded space
    dec r0
    add r0, r2
    ld r2, r2
    # If there is 1 than we switch bit
    if

```

```

                                tst r2
is nz
                                ldi r0, IOInvertBitSignal
                                st r0, r0

                                # Set flag for non-static generation to its address (!= 0)
                                ldi r0, isNonStaticGeneration
                                st r0, r0
fi
rts

```

What to do if there is no neighbors?

We decided that alive cell should die and death cell cannot birth. Due to specific work with `sum = 0` this case for `bit = 1` is processed in [main part](#):

```

...
    # Check birth or death conditions and save bit depends on conditions
    if
        tst r0
    is nz
        jsr processBit
    else
        # If sum = 0 alive cell must die
        if
            tst r1
        is nz
            ldi r0, IOInvertBitSignal
            st r0, r0

            # Set flag for non-static generation to its address
            ldi r0, isNonStaticGeneration
            st r0, r0
        fi
    fi
fi
...

```

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Logisim

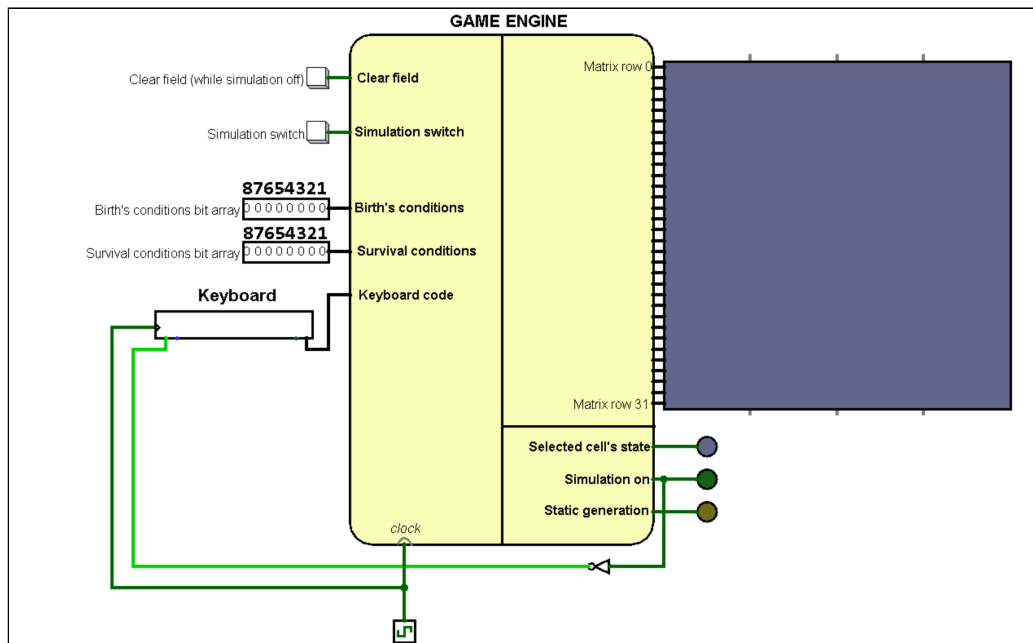
Main concept

Here you can see main jobs for Logisim part and logical ordered references for all of them:

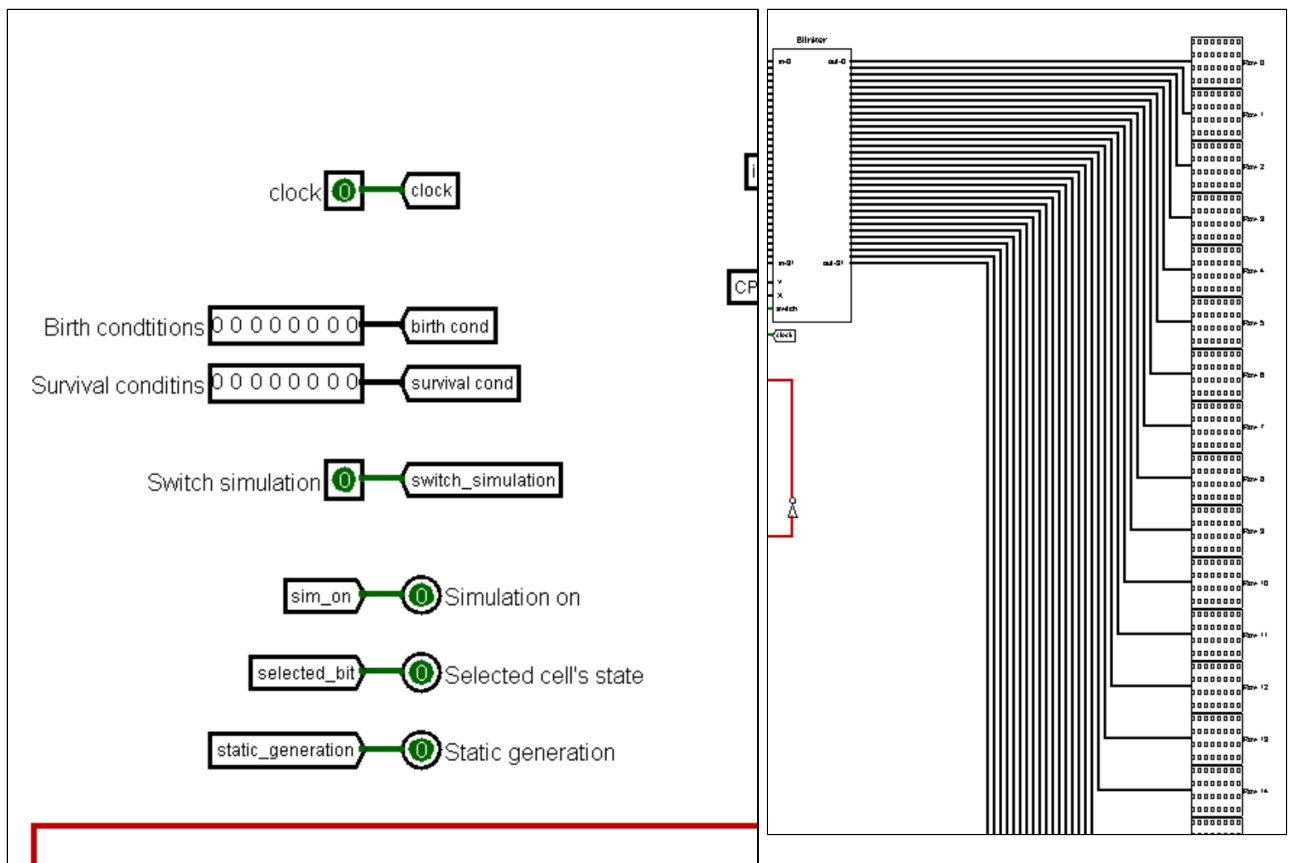
1. Communication with user
 1. [Controls](#)
 2. [Game screen](#)
 3. [Blinker](#) for pretty cursor visualization
2. Storing game's data
 1. [Random write buffer](#)
 2. [Stable generation's buffer](#)
3. Constructing data for CPU
 1. Used I/O registers: [cell](#) and [environment data](#)
 2. [Environment data constructor](#)
4. Creating new generation by CPU signals
 1. Used I/O registers: [cell](#) and [signals](#)
 2. [Row's bit inverter](#)
 3. [Random write buffer](#)
 4. [Stable generation's buffer](#)

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Engine circuit

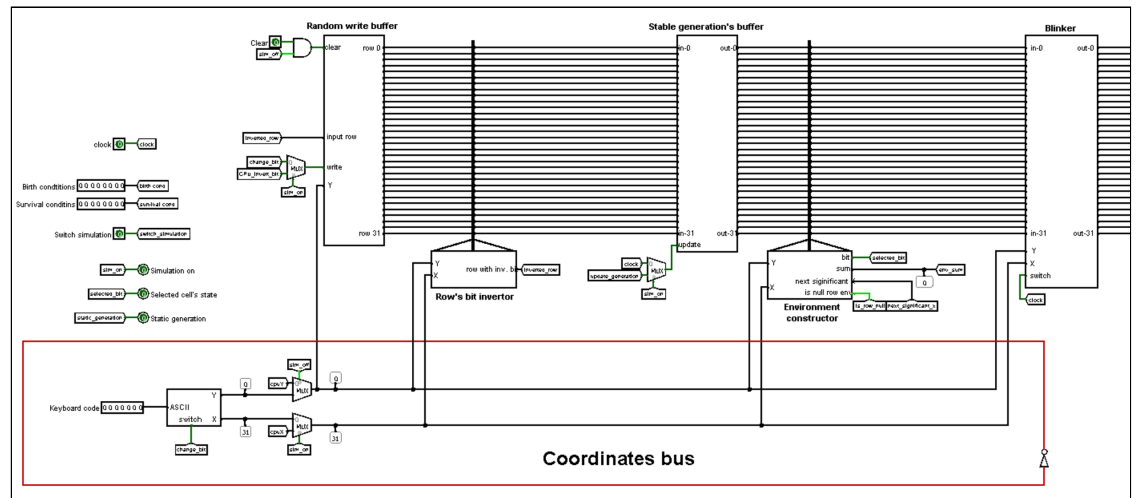


This circuit is main one element of game. It handles **all inputs from user** and gives finally 32 32-bit rows to matrix and outputs **simulation on**, **selected cell's state** and **static generation**.

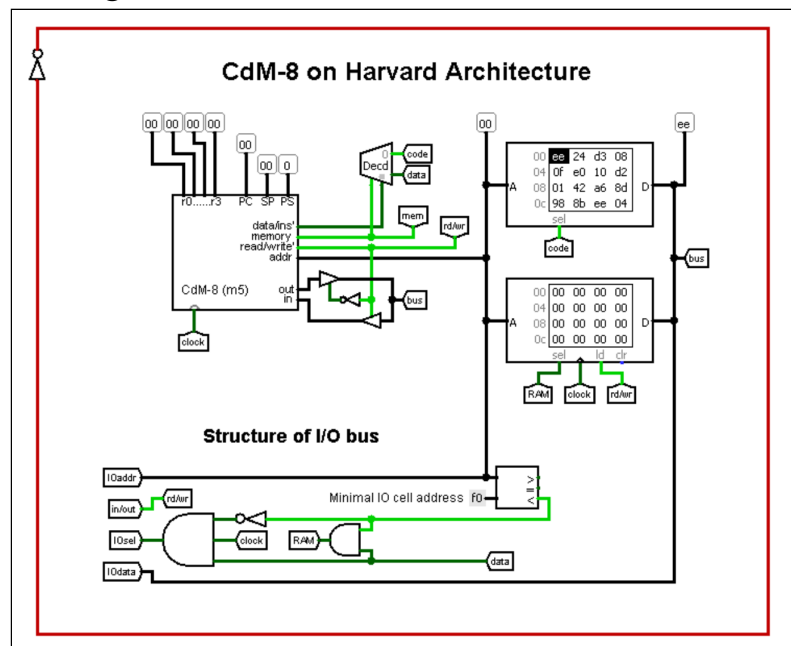


This circuit contains:

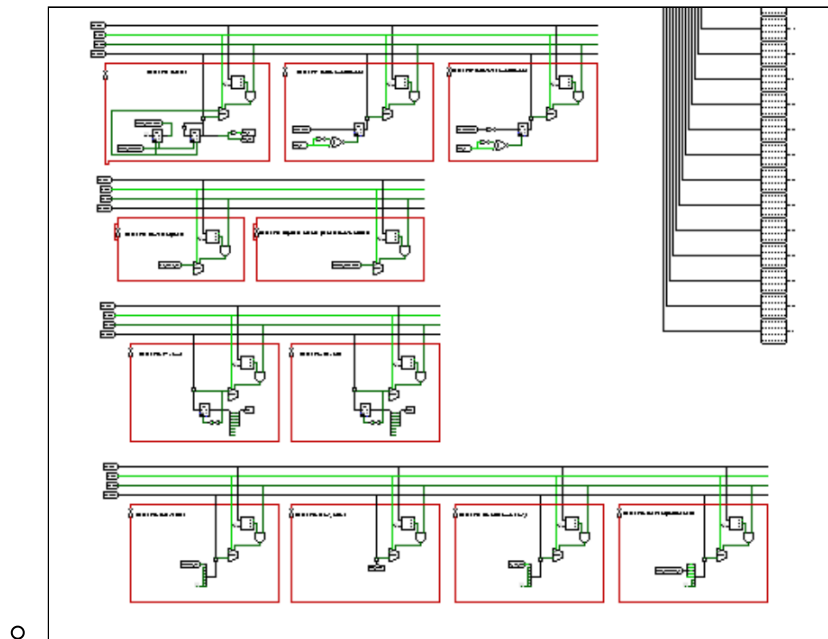
1. Most of all circuits described below with connected to them **coordinates bus** (excepting *binary selector* and *row environment mask*):



2. CdM-8 integration scheme with Harvard architecture:



3. All **I/O registers**:

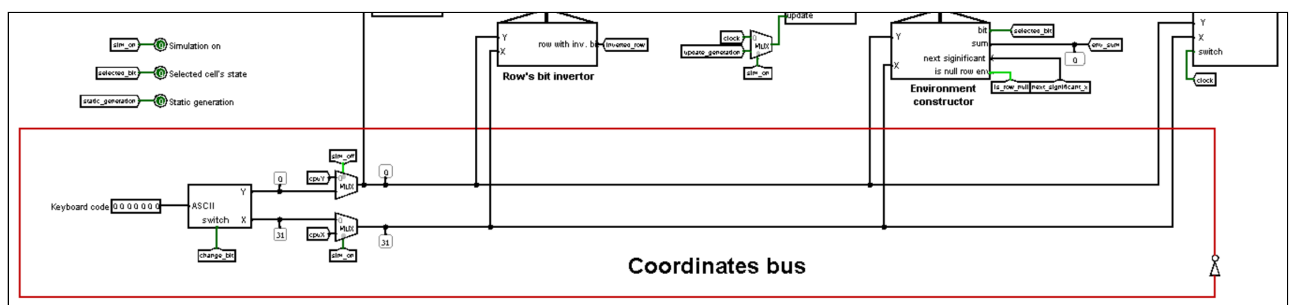


Coordinates bus

Most of circuits work with coordinates **Y** (row index) and **X** (bit index) and coordinates go from 2 sources:

- When simulation off they go from **keyboard controller** which handles user's inputs
- When simulation on they go from **2 I/O registers**

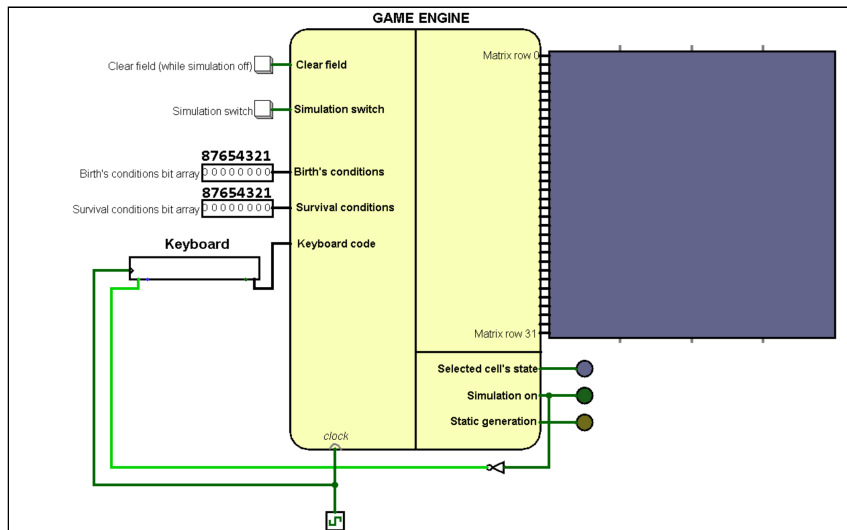
Therefore we use two multiplexers that choose coordinates source depending on simulation state:



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Controls

Main signals



Simulations switch button switches between simulation and setting modes.

When we turn from simulation to setting mode we can get unfinished new generation

Two 8-bit inputs let us set different conditions for birth and survival. Bit value **1** on position **N** means fulfilling of conditions when cell has **N** neighbors so this inputs represent bit arrays.

Clear button clears all field when simulation off.

Keyboard Logisim circuit sends keys' ASCII codes to engine. See more below.

On bottom-right side we can see 3 LED indicators:

1. State of cell under the blinking cursor
2. Simulation state (when simulation on indicator will light)
3. Static generation flag. When static generation was reached simulations interrupts and this indicator lights up

Keyboard

Logisim circuits keyboard handles keys' presses and send 7-bit ASCII codes to [Keyboard controller](#) inside engine circuit

All keys are working only while we are in the **setting** game mode

Keyboard layouts

Cursor moving:

KEY	DIRECTION	X DELTA	Y DELTA
NUM 7 / Q	top-left	+1	-1
NUM 8 / W	top	0	-1
NUM 9 / E	top-right	-1	-1
NUM 4 / A	left	+1	0
NUM 6 / D	right	-1	0
NUM 1 / Z	bottom-left	+1	+1
NUM 2 / S	bottom	0	+1
NUM 3 / C	bottom-right	-1	+1

Deltas defined as shown above because in matrix top-left cell has **X = 31** and **Y = 0**

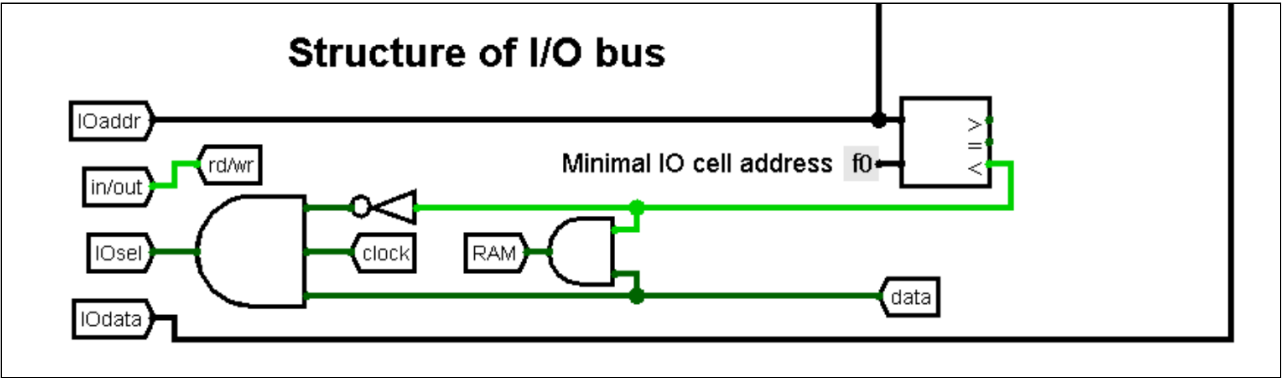
Cursor position on matrix is marked by [blinker](#)

NUM 5 / **Space** - change state of selected cell in [random write buffer](#) using row's bit inverter

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I/O registers

I/O bus have minor changes: selection of I/O addresses from CPU **addr** is detected by **less than** comparator's output with the second input **0xf0** (the first I/O cell address)



I/O registers' types

All types' names are regarding the CPU directions

Registers have trivial types of data direction: **READ ONLY** and **WRITE ONLY**.

PSEUDO WRITE

Besides these types we use one specific type - **PSEUDO WRITE**. CPU cannot write data to this "registers". Main goal for this type is handling **write** signal by CdM-8's **st** instruction.

Short description table

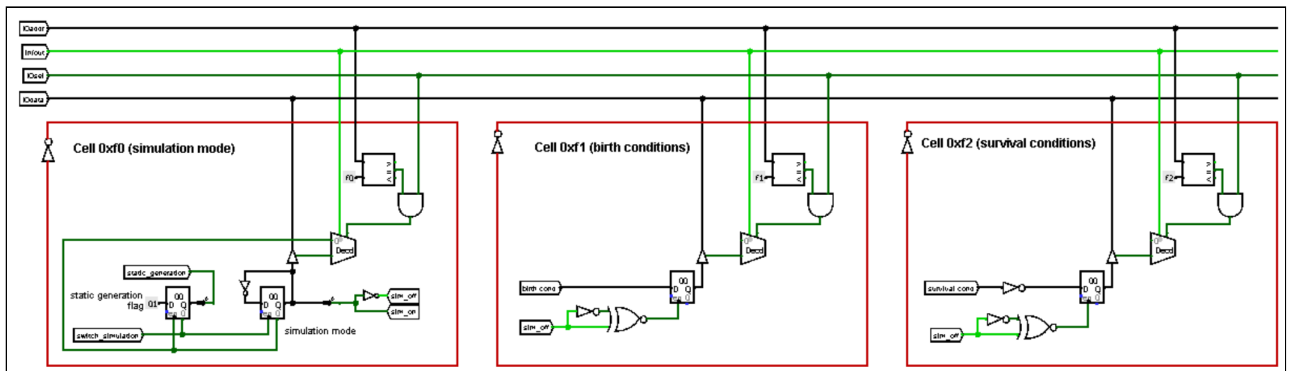
CELL ADDR.	ASSEMBLER LABEL	DATA DIRECTION	EXPLANATION TOPIC
0xf0	IOGameMode	READ ONLY / PSEUDO WRITE	Link
0xf1	IOBirthConditions	READ ONLY	
0xf2	IODeathConditions	READ ONLY	

CELL ADDR.	ASSEMBLER LABEL	DATA DIRECTION	EXPLANATION TOPIC
0xf3	IOY	WRITE ONLY	Link
0xf4	IOX	WRITE ONLY	
0xf5	IOBit	READ ONLY	Link
0xf6	IOEnvSum	READ ONLY	
0xf7	IONullRowsEnv	READ ONLY	
0xf8	IONextSignificantX	READ ONLY	
0xf9	IOInvertBitSignal	PSEUDO WRITE	Link
0xfa	IOUpdateGeneration	PSEUDO WRITE	

List with descriptions

Simulation rules

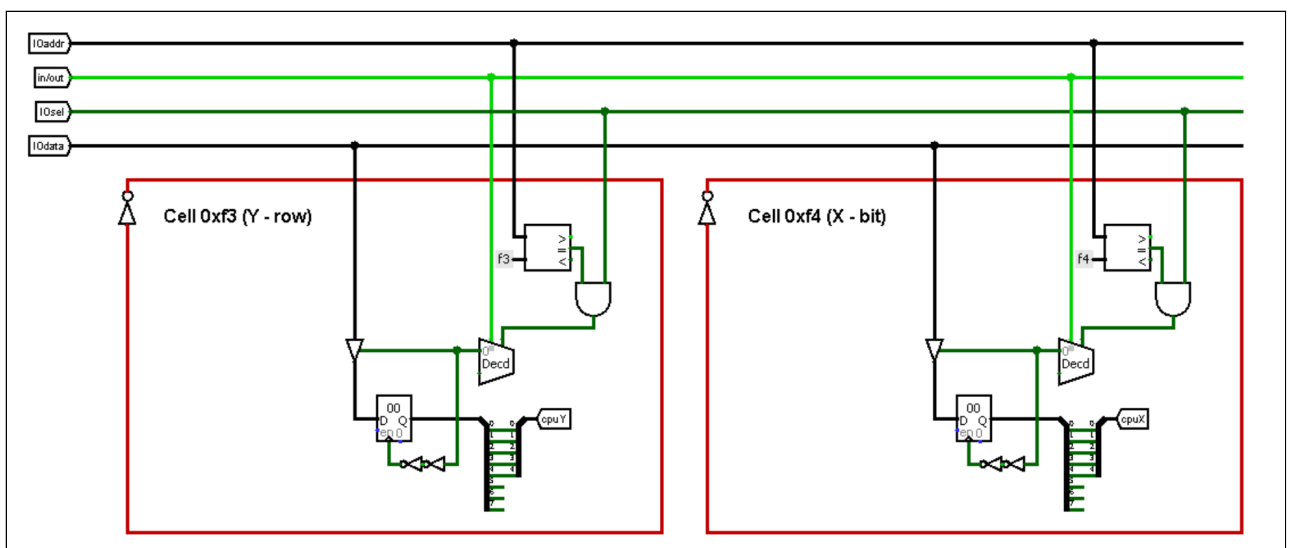
- **0xf0** - READ ONLY / PSEUDO WRITE - when simulation off this register will be **0**.
 - Trigger signal on this register will invert its value and reset static generation flag-register.
 - Tunnels from this register are used for control data origins on coordinates bus and some other cases.
 - Save signal from CPU will reset this register (turn off simulation) and set static generation flag-register to **1**. This feature is used in [CPU main cycle](#) for interrupting simulation
- **0xf1** - READ ONLY - birth conditions as bit array
- **0xf2** - READ ONLY - death conditions as bit array. This value is inverted version from survival conditions user input



Processed cell

Coordinates from these registers are used in all Logisim components to tell what cell CPU is processing. When simulation on they capture coordinates bus:

- **0xf3** - WRITE ONLY - Y coordinate (processing row)
- **0xf4** - WRITE ONLY - X coordinate (bit index in row)

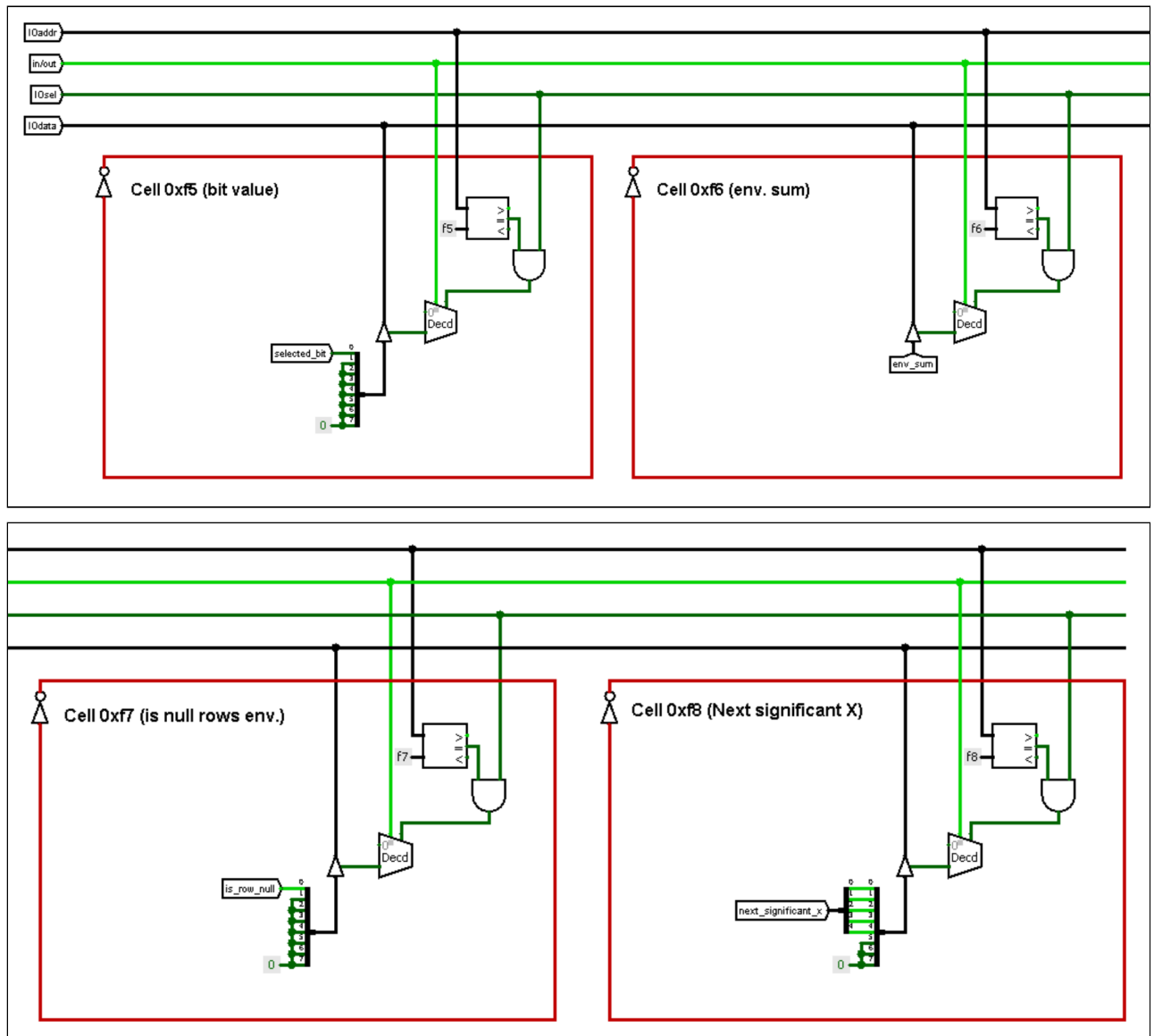


I/O "registers" with environment data

These "registers" aren't exist. There are just tunnels which are connected to [environment constructor outputs](#):

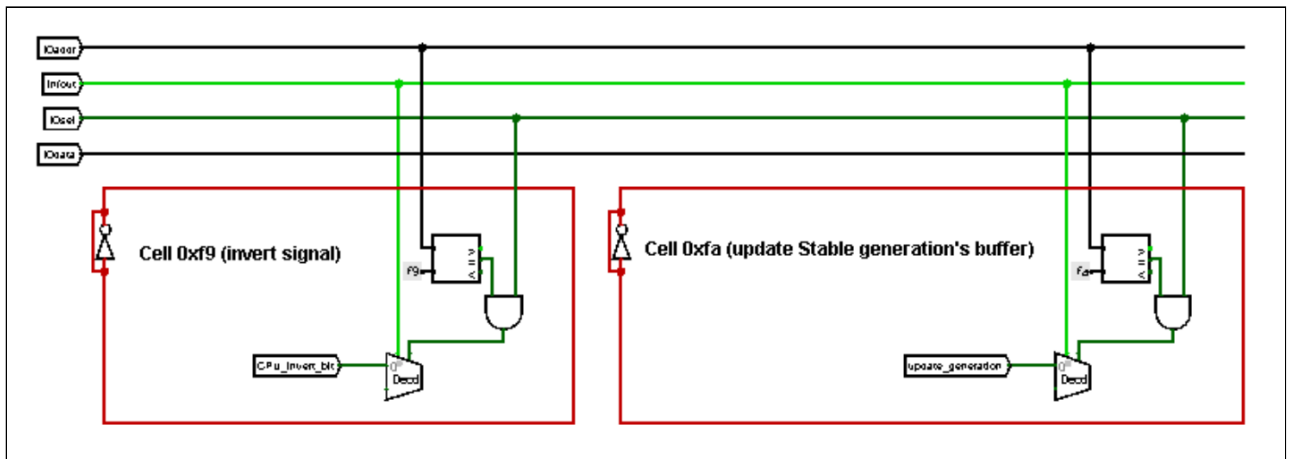
- **0xf5** - READ ONLY - 1 when bit on position (Y, X) is 1
- **0xf6** - READ ONLY - sum of bits around cell (Y, X)
- **0xf7** - READ ONLY - 1 when rows Y-1, Y and Y+1 are null
- **0xf8** - READ ONLY - next X which satisfy some of conditions:

- Cell (Y, X) isn't 0
- sum of bits around cell (Y, X) greater than 0



I/O "registers" for changing field

- 0xf9 - PSEUDO WRITE - save signal to this cell will trigger **random write buffer** and change cell (Y, X) using **row's bit inverter**
- 0xfa - PSEUDO WRITE - save signal to this cell will update **stable generation's buffer**



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Elements description

Keyboard controller

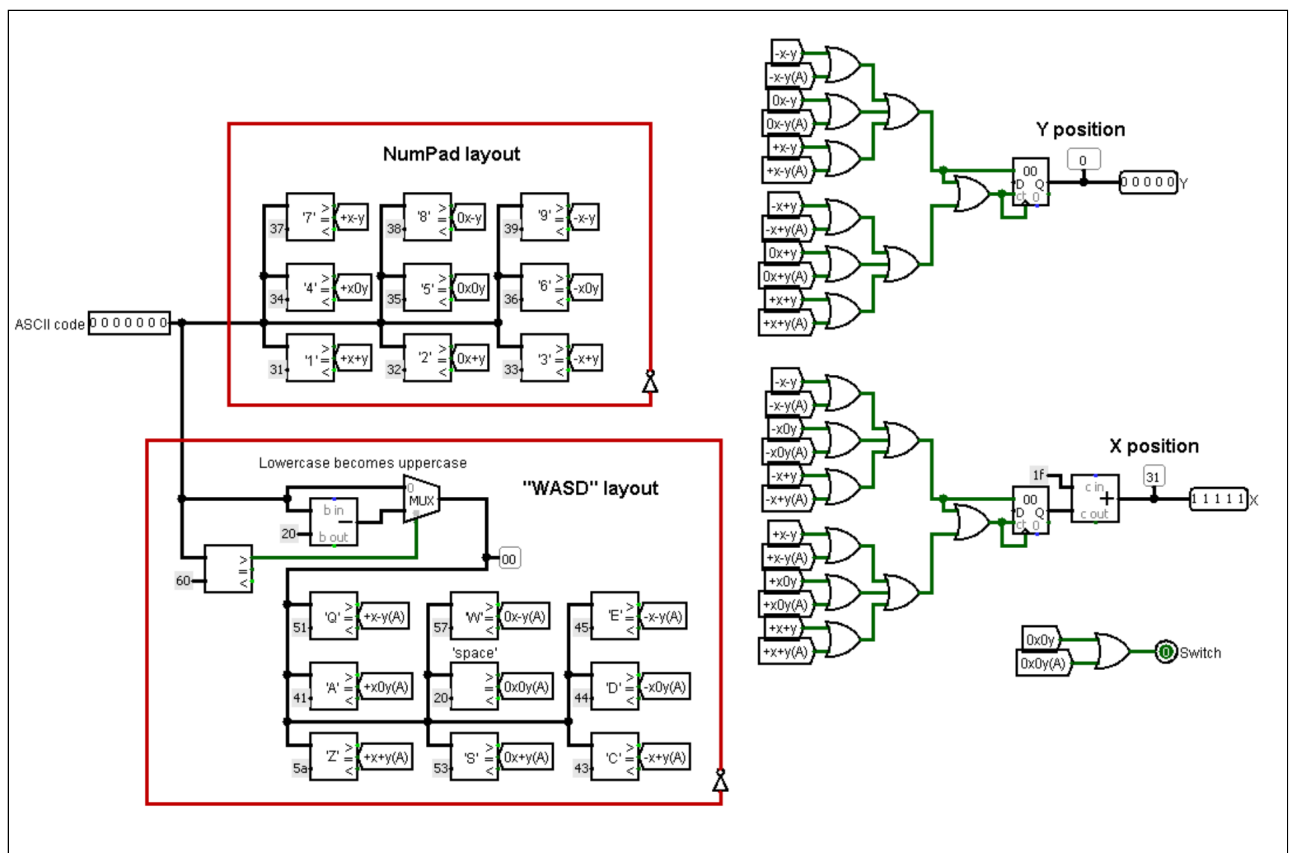
This circuit considers 7-bit ASCII input as ASCII code and compares it with constants related to some keys and make list of actions:

- Cycled increment/decrement X/Y of cursor
- Send switch signal for switching the cell's state

See keyboard layouts [here](#)

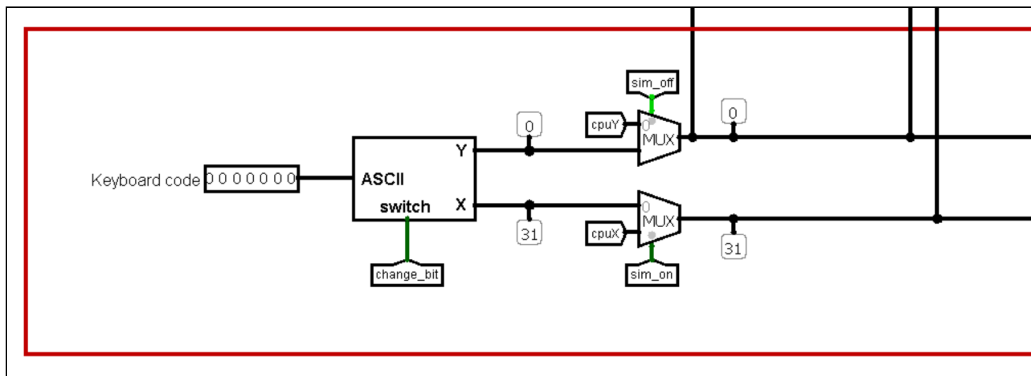
For letters layout lowercase letters are transformed to uppercase using comparator, subtractor and multiplexer

Circuit screenshot:



Usage in Engine circuit: Keyboard controller gives user signals that are used while simulation if off:

- Y and X for [coordinates bus](#)
- Switch signal which is implemented as [Write row](#) in [random write buffer](#)



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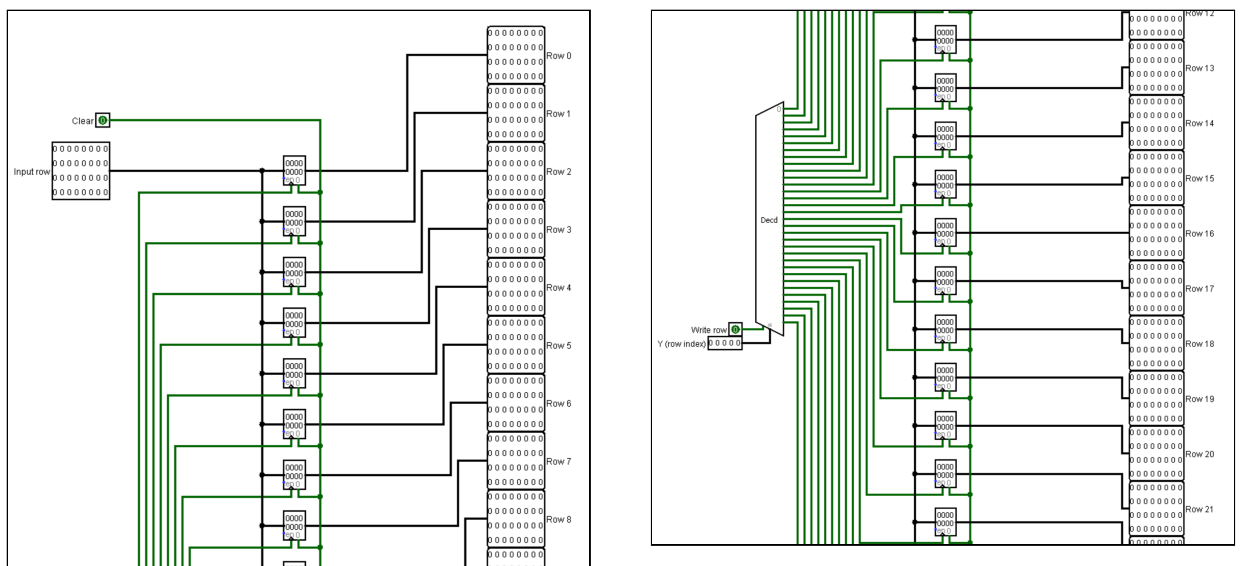
Random write buffer

This circuit saves 32-bit row to one of 32 registers and sends all 32 saved rows to outputs.

Trigger for registers is decoder with 5-bit selector **Y (row index)** and **Write row** enable input. So, buffer will save row from **Input row** to **Y**th register on rising of **Write row**.

Clear signal resets all registers.

Circuit screenshots:



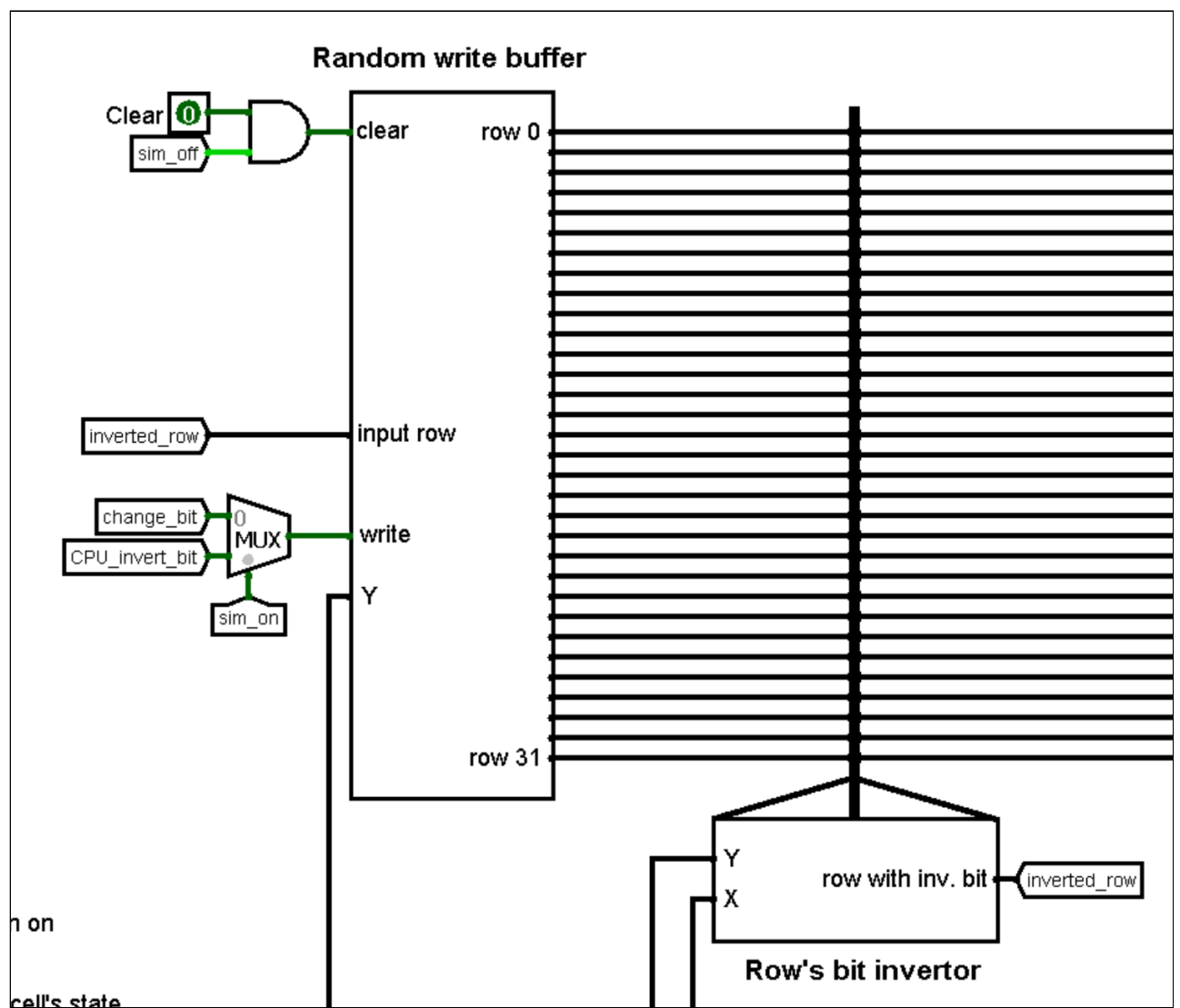
Usage in Engine circuit: In engine we get input row through tunnel from [row's bit inverter](#)

Clear signal works while simulation off.

Y data goes from [coordinates bus](#)

Write row signal goes:

- From [keyboard controller](#) when simulation off
- From CPU through **PSEUDO WRITE** [register](#) when simulation on

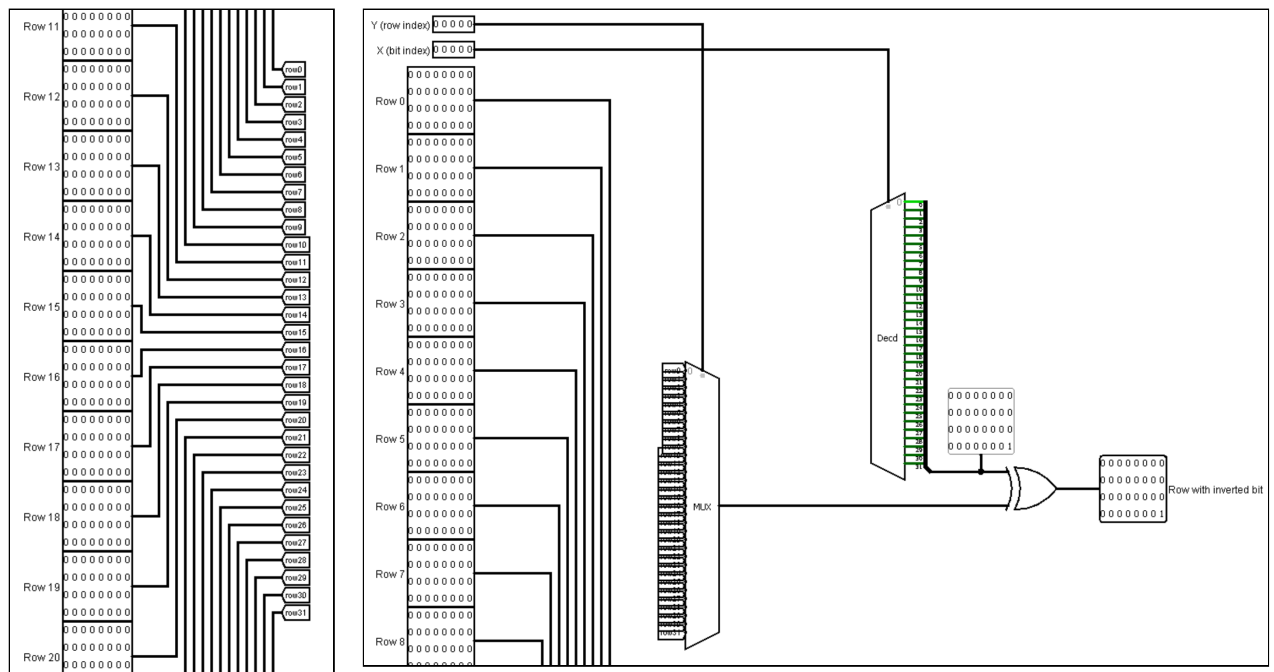


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Row's bit invertor

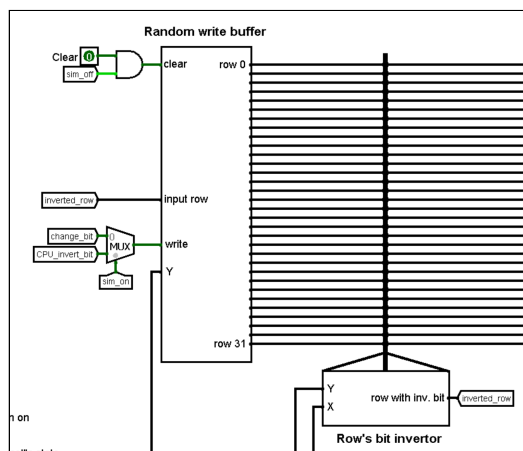
This circuit gets 32 32-bit rows and 5-bit coordinates Y and X. Returns Y row with inverted bit on position X. **For inversion we use decoder constructed bit mask and XOR**

Circuit screenshots:



Usage in Engine circuit: 32 input rows goes from [random write buffer](#) and inverted row goes through tunnel to [input row](#) of [random write buffer](#)

Y and X go from [coordinates bus](#)

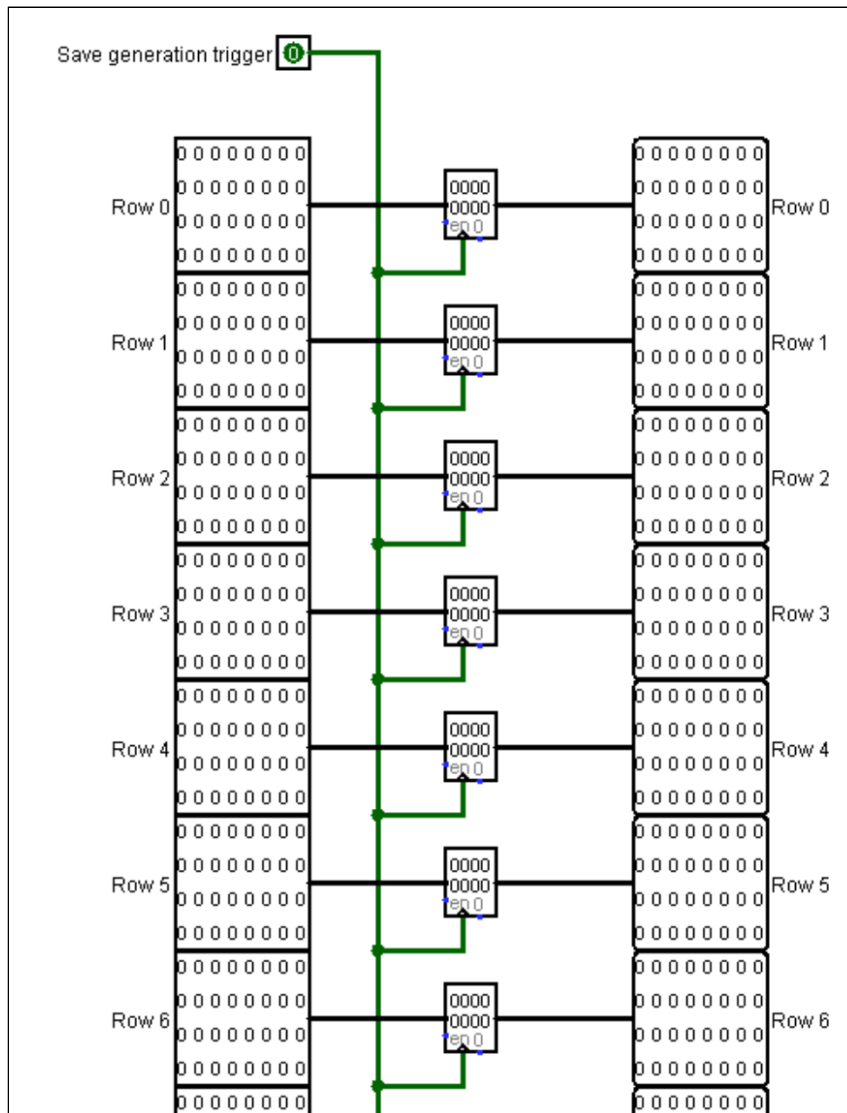


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Stable generation's buffer

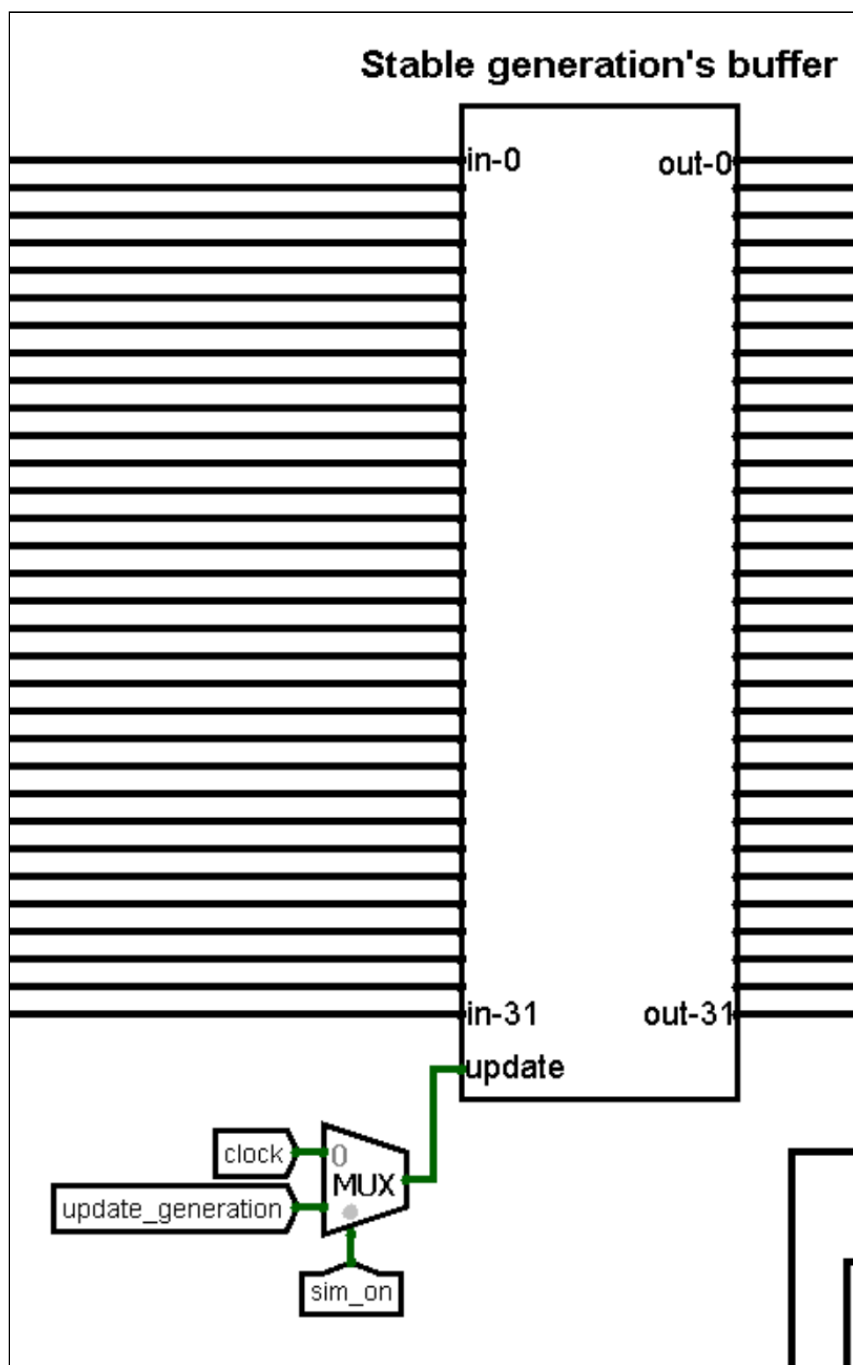
This buffer just saves 32 32-bit rows from inputs to registers and sends them to 32 outputs. Saving occurs on rising edge of input **Save generation trigger**

Circuit screenshot:



Circuit usage in Engine: Buffer update depends on simulation state:

- While simulation off buffer is updated by **clock**
- While simulation on buffer is updated after **CdM-8 main cycle's full execution** by signal from **pseudo I/O register**

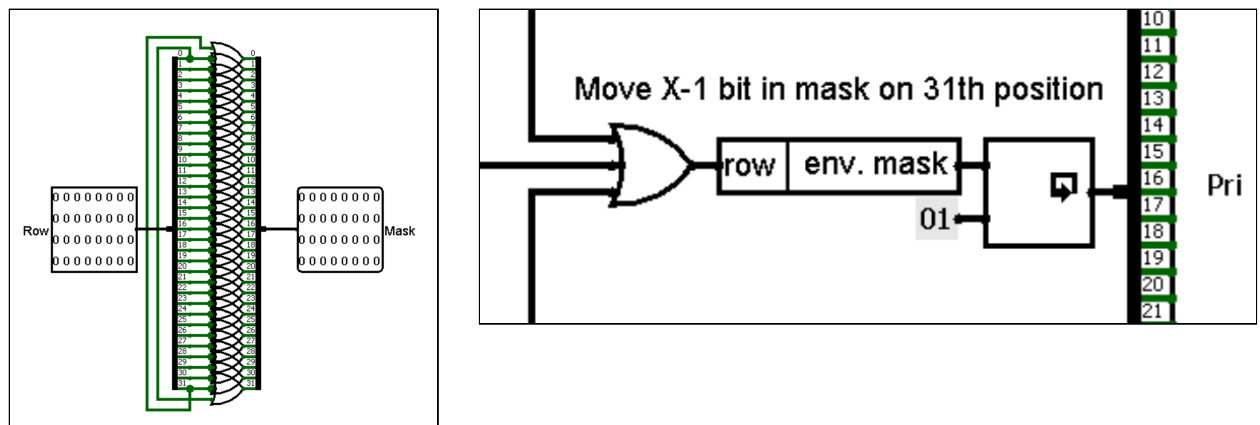


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Row environment mask

This circuit gets 1 32-bit row and gives 1 32-bit row where i bit is 1 when in input row at least one of $i-1$, i , $i+1$ bits is 1 (OR gate on splitter outputs). So, result row let us easily detect bit with significant environment.

Circuit screenshot and its usage: this circuit is used in [environment data constructor](#) for detecting next X with significant environment by priority encoder.



Environment data constructor

Purpose of this circuit is constructing data about cell's environment for [optimized new generation's counting in CdM-8](#).

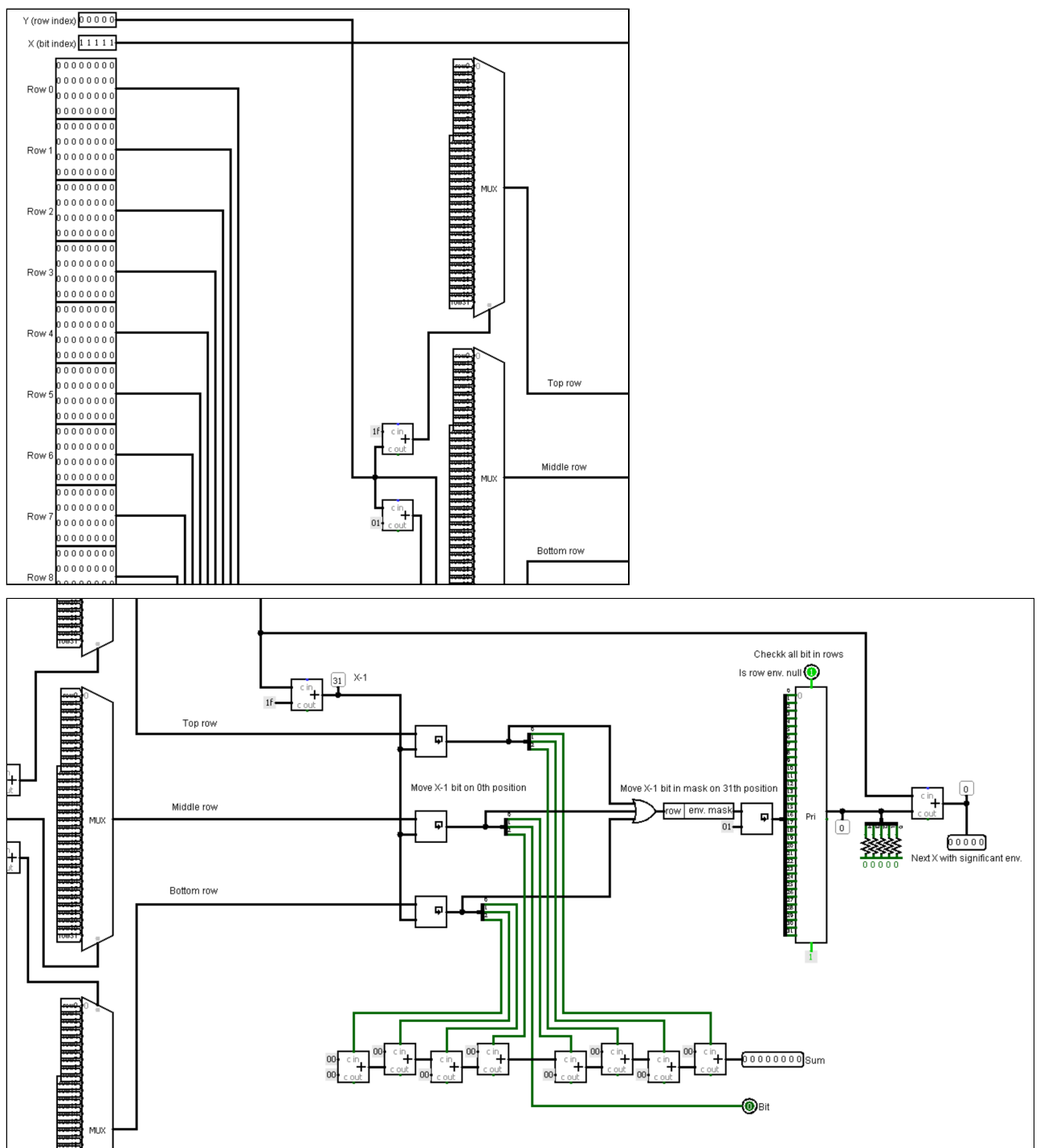
It has 32 32-bit inputs for rows and 5-bit Y , X inputs and works by this steps:

1. Get rows $Y-1$, Y and $Y+1$ using multiplexers
2. Right cycled shift 3 rows on $X-1$ positions to get $X-1$, X and $X+1$ bits on 0, 1 and 2 positions
 1. Send bit 1 from middle row to centre bit output
 2. Use bits [0, 2] from top and bottom rows and bits 0 and 2 from middle row as carry signals for 8 8-bit adders to get sum of cells surrounding centre bit
3. Get common row from $Y-1$, Y and $Y+1$ rows using OR gate for analyzing environment. It is named **environment row**
4. Construct environment mask from environment row using [row environment mask circuit](#) and shift it right on 1 bit to get $X-1$ bit on the 31th position

5. This row goes to priority encoder that determines 2 values:

1. If environment mask row is null encoder send true on **is row env.**
null output
2. Index of highest indexed bit which is **1** after sum with **X** input give us next **X** with significant environment. This value goes to **Next X with significant env.**

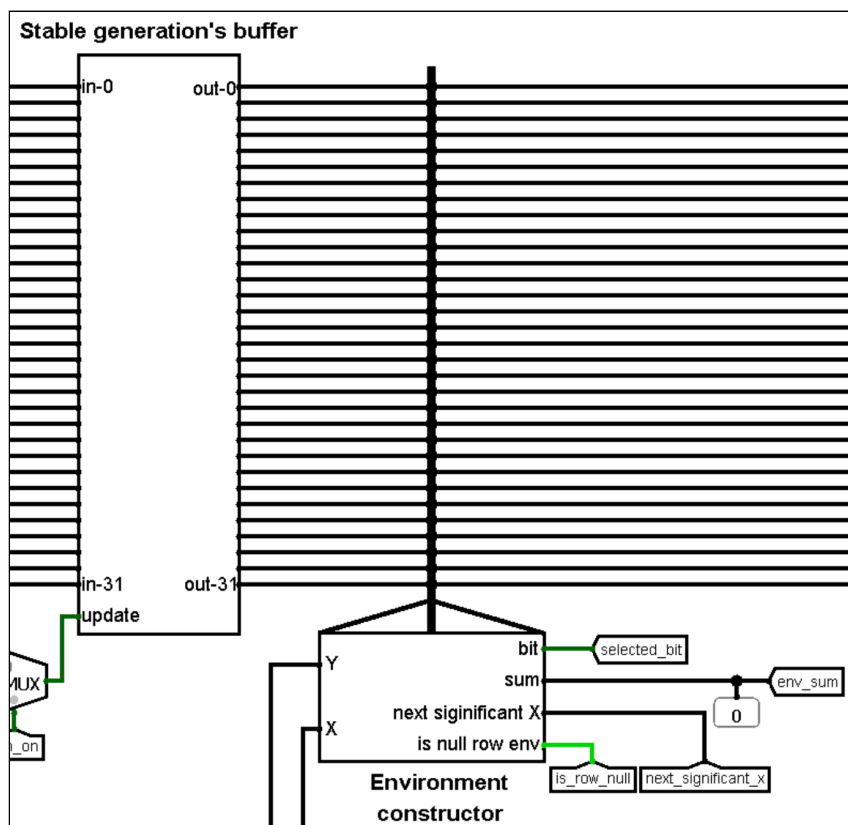
Circuit screenshots:



Usage in Engine circuit: Environment data constructor is connected to rows after [stable generation's buffer](#) to ensure that CPU works with stable generation.

All outputs go through tunnels to [I/O registers](#) that are used in [ASM main cycle](#)

Y and X go from [coordinates bus](#) but while simulation off environment data isn't used.



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Binary selector

This circuit should choose one of two input values. **Binary selector** should choose second value if the **switch** input is **1** and first value otherwise.

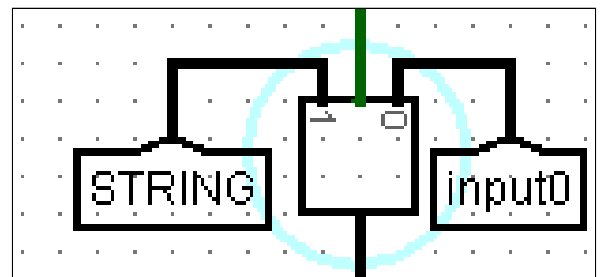
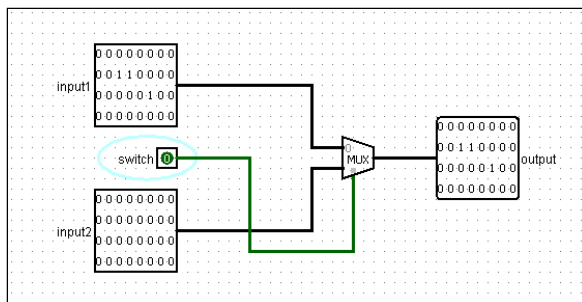
Inputs:

- input values: 2 32-bit rows
- **switch** - 1-bit

Outputs:

- selected value: 1 32-bit row

Circuit screenshot and its usage: Binary selector is used in **blinker** for convenient circuit composing.



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Blinker

Blinker must switch value of **X** bit in **Y** row to opposite if the **switch** input is raised and return new row between others unchanged. **It is important that this circuit should not store new values in itself.**

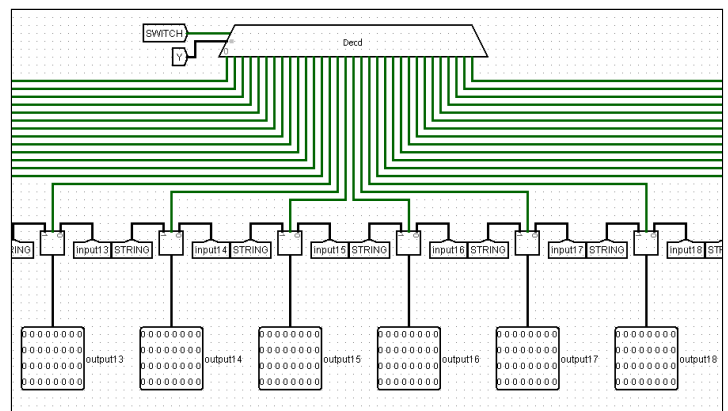
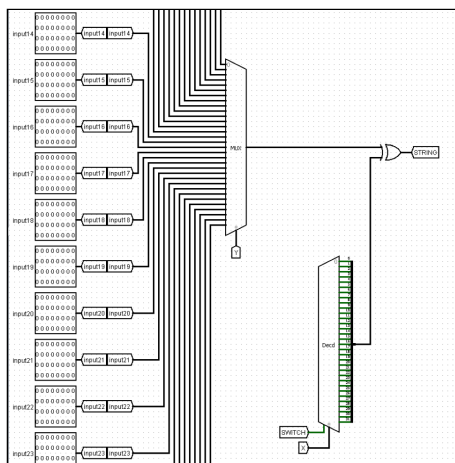
Inputs:

- matrix rows: 32 32-bit rows
- **Y** coordinate (row number) - 5-bit
- **X** coordinate (bit number in the row) - 5-bit
- **switch** - if this input is raised current bit must switch to opposite

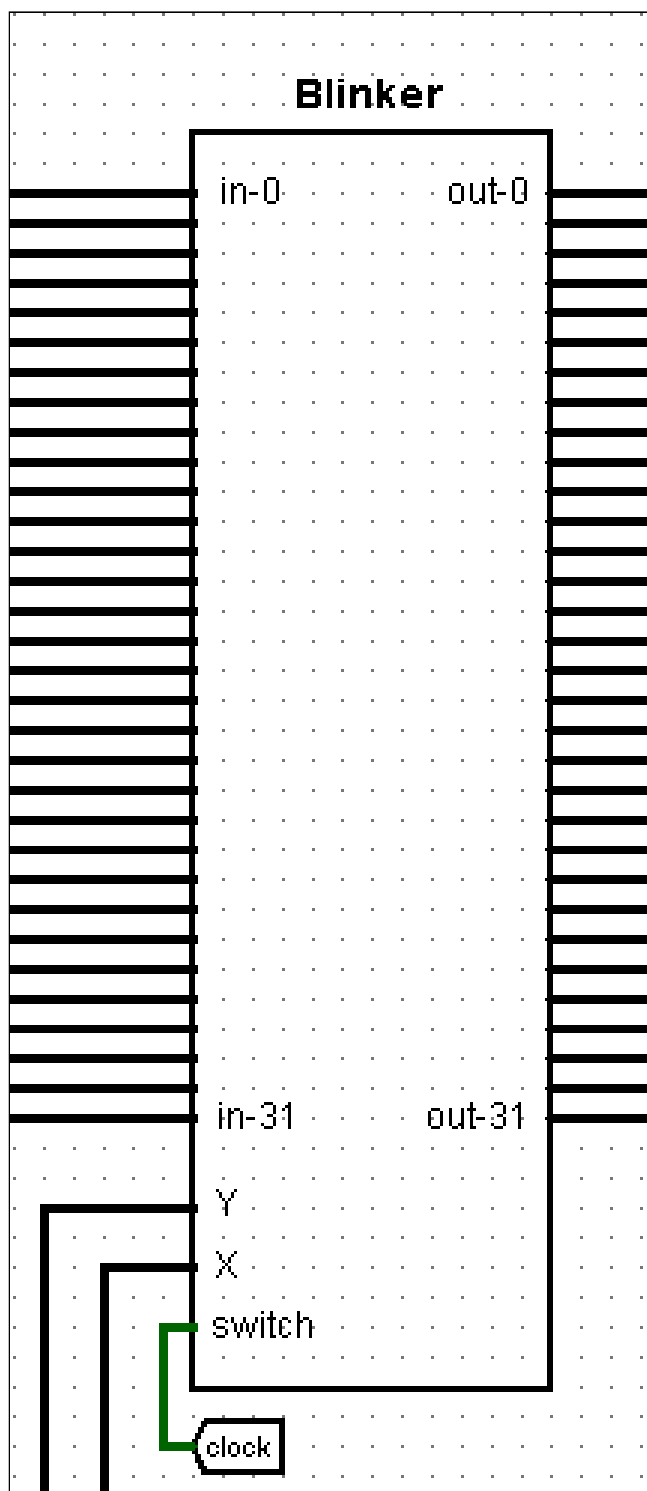
Outputs:

- 32 32-bit outputs, in one of which one bit was changed

Circuit screenshots:



Usage in Engine circuit: Input **switch** handles clock signal. Y and X go from **coordinates bus**



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Conclusion

The version described above works in direct proportion to the number of cells. So, for the large setups one frame processing can take up to 200 seconds. It's long, but there are no ways for the significant optimization saving this architecture.

Therefore, we declare that we have done optimally working version of "Conway's game of life" with an enlarged field and the ability to change birth and survival conditions.

[Here](#) you can see different interesting setups.