How to play

Our version of "Conway game of life" works with universal sets of conditions for birth and survival.

1. To set conditions switch bits in birth/survival 8-bit inputs where value 1 on position N means that birth/survival will be fulfilled when cell has N neighbors.
2. After this click on keyboard element and use one of two [keyboard layouts](#keyboard-layouts) to move blinking cursor and change cells' states.
3. When you set initial field state press button "Simulation switch" and observe evolution!
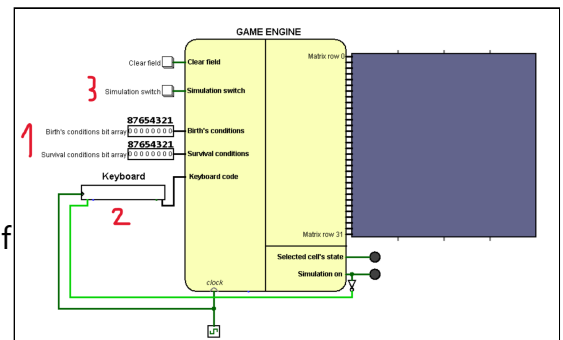
Documentation

Assembler

Short description

Due to optimization reasons CdM-8 has only one main task - iteration by Y,X positions and determination whether cell should be changed. After the all cells' processing CdM-8 send signal to [update generation]

In ASM code we use asect **constants like this:**

```
asect 8
constSample:

# ...

ldi r0, constSample  # r0 sets to 8
```

Often we save address value to its address:

```
ldi r0, IOAddr
st r0, r0
```

The reason for this action is PSEUDO WRITE **mode for some I/O registers**

RAM distribution

- 0xe0 - birth's conditions first byte
- 0xe8 - death's conditions first byte

Stack initial position - 0xe0

▼ Constants for this cells

```
# Internal data addresses
asect 0xe0
birthConditionsRowStart:

asect 0xe8
deathConditionsRowStart:
```

Cells referring to I/O regs.

Cells from `0xf0` to `0xff` are allocated for I/O registers.

See detailed description in Logisim topic

▶ Constants for I/O cells

```
# Asects for I/O registers
asect 0xf0
IOGameMode:

asect 0xf1
IOBirthConditions:

asect 0xf2
IODeathConditions:

asect 0xf3
IOY:

asect 0xf4
IOX:

asect 0xf5
IOBit:

asect 0xf6
IOEnvSum:

asect 0xf7
IONullRowsEnv:

asect 0xf8
IONullByteEnv:

asect 0xf9
IOInvertBitSignal:

asect 0xfa
IOUpdateGeneration:
```

Code description

Simulation start

This part just waits whilst user presses start button and after it loads game conditions to RAM using spreadByte subroutine

For optimized conditions checking survival conditions inverts to death's conditions. See how it works here

▶ Code

```
asect 0
br start


#=============================#
#     Place for subroutines    #
#=============================#
...
#==============================

start:
        # Move SP before I/O and field addresses
        setsp 0xd0


        # Waiting for IOGameMode I/O reg. != 0
        ldi r1, IOGameMode
        do
                ld r1, r0
                tst r0
        until nz

        ldi r1, gameMode
        st r1, r0

        # Read birth and death conditions from I/O regs.
        ldi r1, IOBirthConditions
        ld r1, r0
        ldi r1, birthConditionsRowStart
        jsr spreadByte
        ldi r1, IODeathConditions
        ld r1, r0
        ldi r1, deathConditionsRowStart
        jsr spreadByte
```

Main cycle

This part will repeats while simulations stays on.

Before cycle we update stable generation's buffer using save signal to `IOUpdateGeneration` referred to Logisim. As a result, we can get correct data for processing cells.

Main cycle iterates by `Y` (row index) in decreasing order `[31, 0]`.

In next paragraphs we use term **environment**. It means that we analyze mentioned cells and border of 1 cells from all sides.

We use to optimizations for skipping meaningless iterations:

1. If rows `Y-1`, `Y` and `Y+1` (rows environment) are null (flag from `IONullRowsEnv` referred to I/O register will be `1`) $\rArr$ we increment `Y`.
2. If rows environment isn't null we iterates by `X` in decreasing order `[31, 0]`, but divide iteration into 8 parts by 4 cells (we named it *half-byte environment*). If this half-byte environment is null (flag from `IONullHalfByteEnv` referred to I/O register will be `1`) $\rArr$ we skip this 4 cells

If both flags above are `0` we get state of selected cell and its environment's sum using `IOBit` and `IOEnvSum` addresses which are referred to I/O registers

For zero sum:

- Alive cell is killed immediately using save signal `IOInvertBitSignal` referred to Logisim
- Empty cell is skipped

For non-zero sum we call subroutine `processBit`

▶ Code

```
main:

    # Update stable generation's buffer to get new data from env. data
constructor
    ldi r0, IOUpdateGeneration
    st r0, r0

    # Count new cells' states
    ldi r3, 31 # row iterator
    do
        # If game mode = 0 we interrupt cycle and go to start code part
        # NEW GENERATION CAN BE COUNTED PARTITIONALLY
        ldi r0, IOGameMode
        ld r0, r0
        tst r0
        bz start

        push r3 # Save row iterator

        # Send Y to logisim
        ldi r0, IOY
```

```
                st r0, r3

                # If all rows in env. are null => skip this row
                ldi r3, IONullRowsEnv
                ld r3, r3
                tst r3
                bnz rowProcessed

                ldi r1, 31 # Bit index
                ldi r3, 8 # Half-bytes iterator
                do
                        push r3 # Save half-bytes in row iterator

                        # Send X to Logisim
                        ldi r0, IOX
                        st r0, r1

                        # Get half-byte env. (centre cells [x, x-3])
                        # If it is null => 4 cells will be skipped
                        ldi r0, IONullHalfByteEnv
                        ld r0, r0
                        tst r0
                        bnz skipHalfByte

                        # Iteration by half-byte
                        ldi r3, 4
                        do
                                push r1

                                # Send X to Logisim for every new cell
                                ldi r0, IOX
                                st r0, r1

                                # Read data for this cell
                                ldi r0, IOEnvSum
                                ld r0, r0
                                ldi r1, IOBit
                                ld r1, r1

                                # Check birth or death conditions and save bit
depends on conditions
                                if
                                        tst r0
                                is nz
                                        jsr processBit
                                else
                                        # If sum = 0 alive cell must die
                                        if
                                                tst r1
                                        is nz
                                                ldi r0, IOInvertBitSignal
                                                st r0, r0
                                        fi
                                fi

                                # Decrement X (bit index)
                                pop r1
                                dec r1
```

```
                                # Decrement half-byte iterator
                                dec r3
                        until z
                        br byteProcessed
                        skipHalfByte:
                                # If half-byte was skipped we descrease X by 4
                                ldi r0, -4
                                add r0, r1
                        byteProcessed:

                                # Get and decrement half-bytes in row iterator
                                pop r3
                                dec r3
                until z
                rowProcessed:

                # Get and decrement row iterator
                pop r3
                dec r3
        until mi
# Infinite simulation cycle
br main
```

Subroutines

spreadByte

- This subroutine spread byte from r0 into cells from r1 to r1 + 7. In other words spreadByte writes every bit of byte from r0 to cells from r1 to r1 + 7, writing the low order bit into r1 and the high oreder bit into r1 + 7.
- spreadByte is used to write game settings to the memory.
- Thanks to spreadByte we can easily decide what we should do with current cell without using loops.

▶ Code

```
spreadByte:
        # Iterator
        ldi r3, 0b00001000 # 8
        while
                tst r3
        is nz
                # The process of spreading byte
                # Get lower bit and save to current cell
                ldi r2, 0b00000001
                and r0, r2
                st r1, r2

                # Increment cell address, shift data byte and decrement iterator
                inc r1
                shra r0
                dec r3
        wend
rts
```

processBit

- This subroutine gets neighbors' sum in r0 and centre bit value in r1.
- Depending on bit value it chooses birth or death conditions
- Thanks to spreaded conditions we can simply add to conditions' begin address value r0 - 1 and check data by new address
- If there is 1 we should change value in selected cell so we send this signal to Logisim

▶ Code

```
processBit:
        # r0 - sum
        # r1 - bit
        # Send save signal to PSEUDO reg. IOInvertBitSignal if bit should be
inverted (we count that IOX and IOY regs. contain correct coords.)
        if
                tst r1
        is z
                ldi r2, birthConditionsRowStart
```

```
            else
                    ldi r2, deathConditionsRowStart
            fi
            # Check bit in spreaded space
            dec r0
            add r0, r2
            ld r2, r2
            # If there is 1 than we switch bit
            if
                    tst r2
            is nz
                    ldi r0, IOInvertBitSignal
                    st r0, r0
            fi
    rts
```

What to do if there is no neighbors?

We decided that alive cell should die and death cell cannot birth. Due to specific work with `sum` `= 0` this case for `bit` `= 1` is processed in main part:

```
    ...
            # Check birth or death conditions and save bit depends on conditions
            if
                    tst r0
            is nz
                    jsr processBit
            else
                    # If sum = 0 alive cell must die
                    if
                            tst r1
                    is nz
                            ldi r0, IOInvertBitSignal
                            st r0, r0
                    fi
            fi
    ...
```

Logisim

Main concept

Here you can see main jobs for Logisim part and logical ordered references for all of them:

1. Communication with user
    1. Controls
    2. Game screen
    3. Blinker for pretty cursor visualization
2. Storing game's data
    1. Random write buffer
    2. Stable generation's buffer
3. Constructing data for CPU
    1. Used I/O registers: cell and environment data
    2. Environment data constructor
4. Creating new generation by CPU signals
    1. Used I/O registers: cell and signals
    2. Row's bit invertor
    3. Random write buffer
    4. Stable generation's buffer

Engine circuit
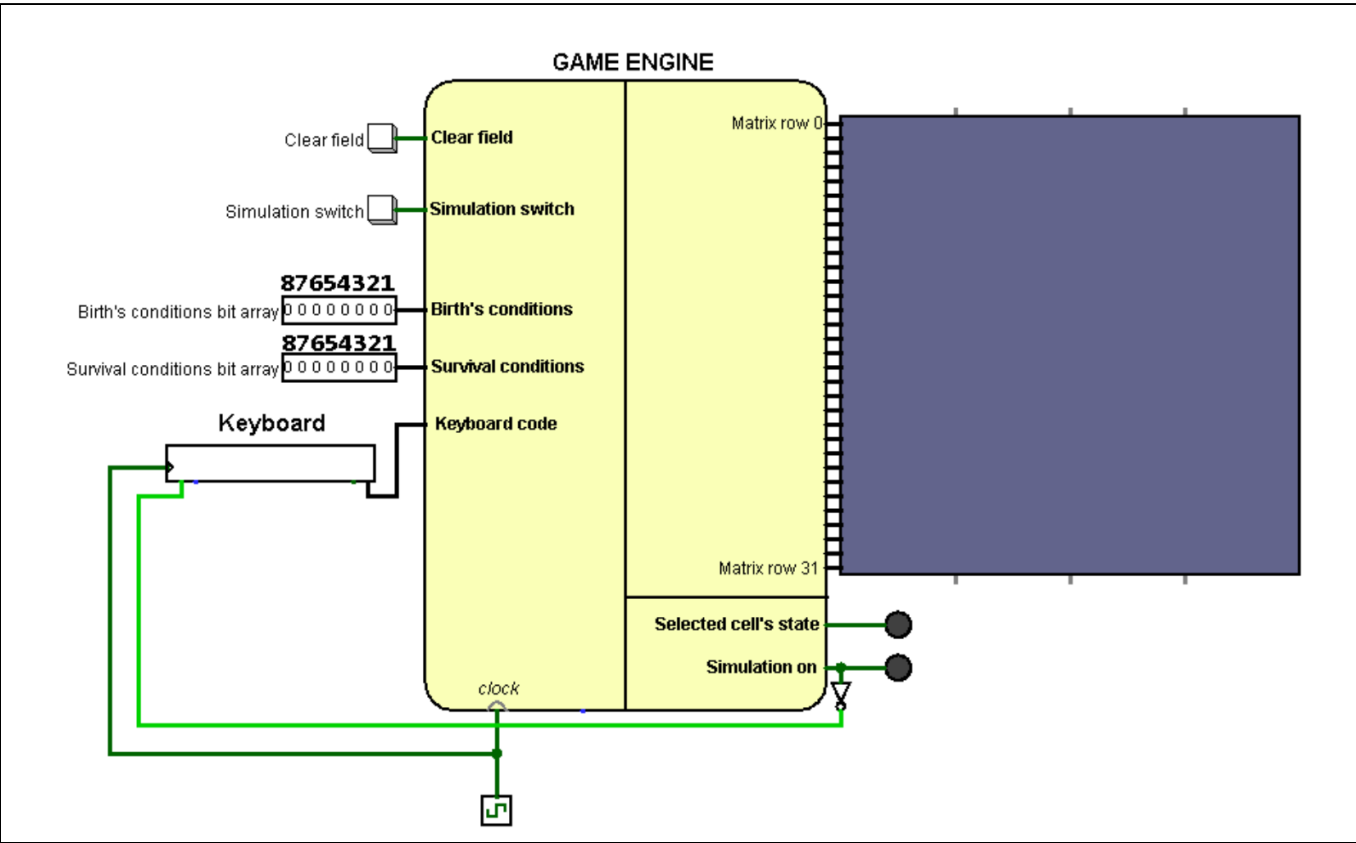
This circuit is main one element of game. It handles all inputs from user and gives finally 32 32-bit rows to matrix and outputs `simulation on` and `selected cell's state`.
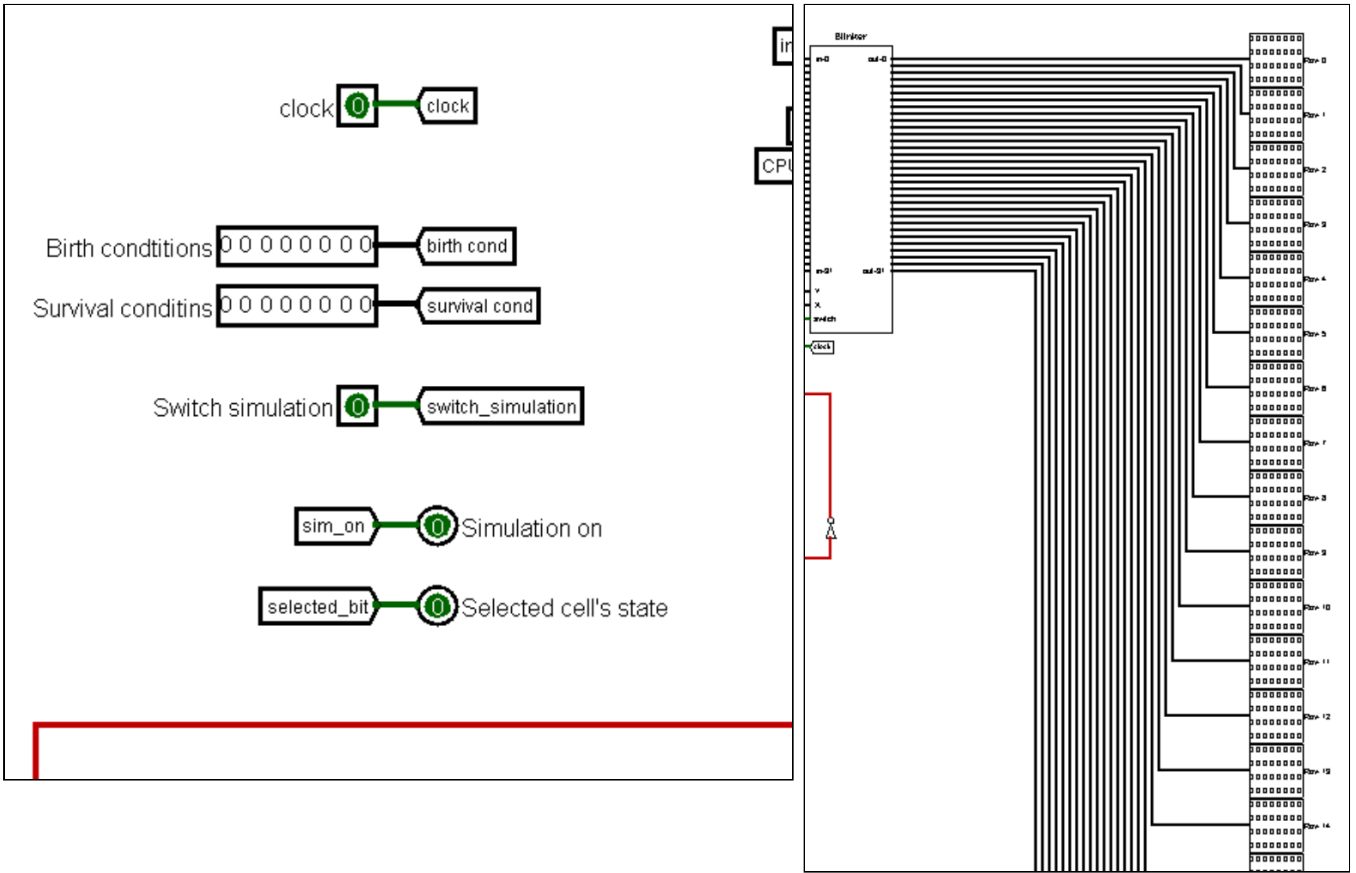
This circuit contains:

1. Most of all circuits below excepting binary selector with connected to them coordinates bus:
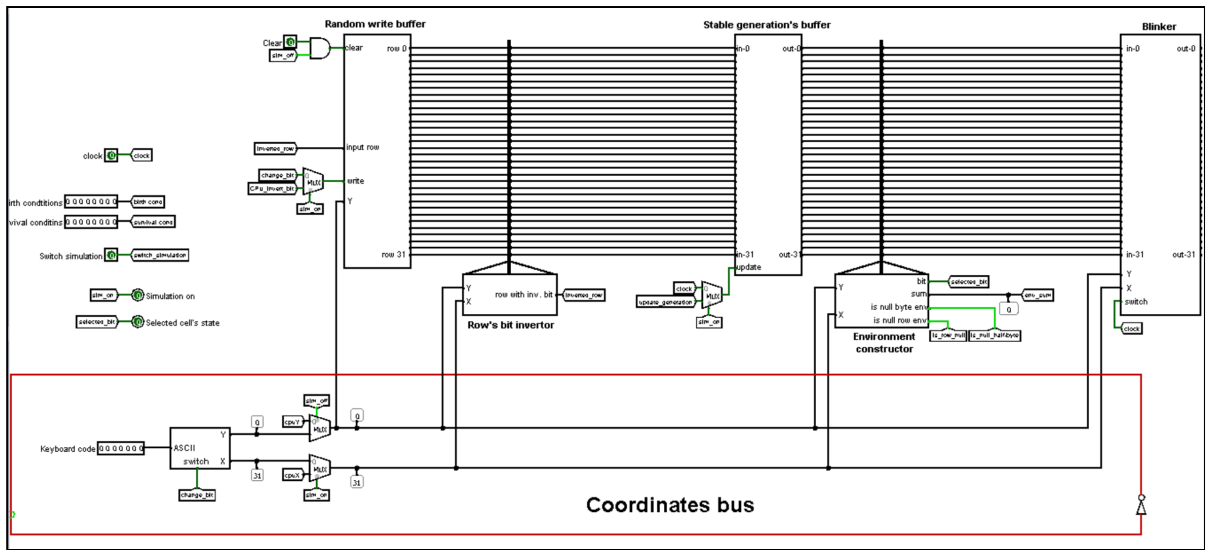
2. CdM-8 integration scheme with Harvard architecture:
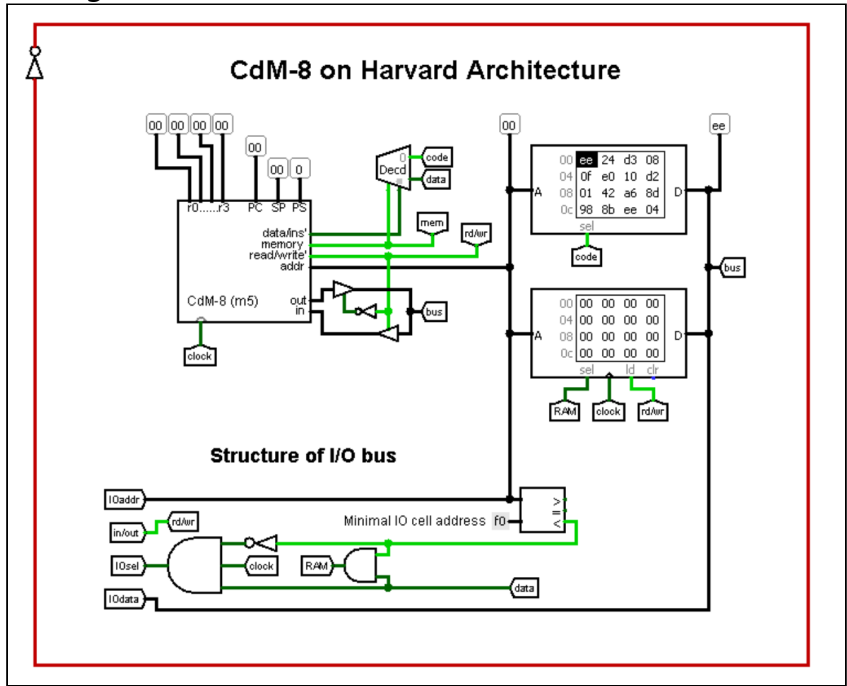
3. All I/O registers:
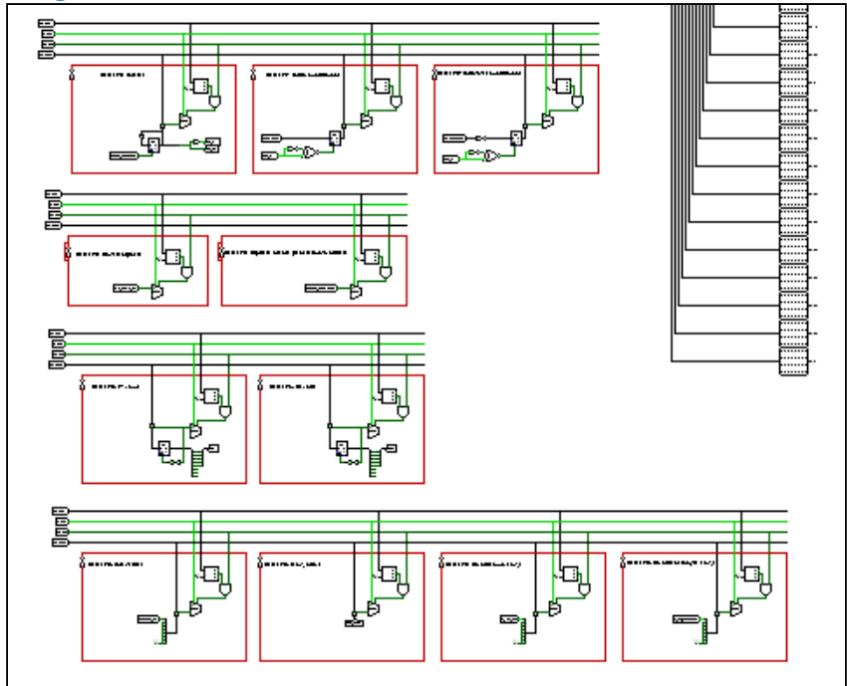
Coordinates bus

Most of circuits work with coordinates Y (row index) and X (bit index) and coordinates go from 2 sources:

- When simulation off they go from keyboard controller which handles user's inputs
- When simulation on they go from 2 I/O registers

Therefore we use two multiplexers that choose coordinates source depending on simulation state:
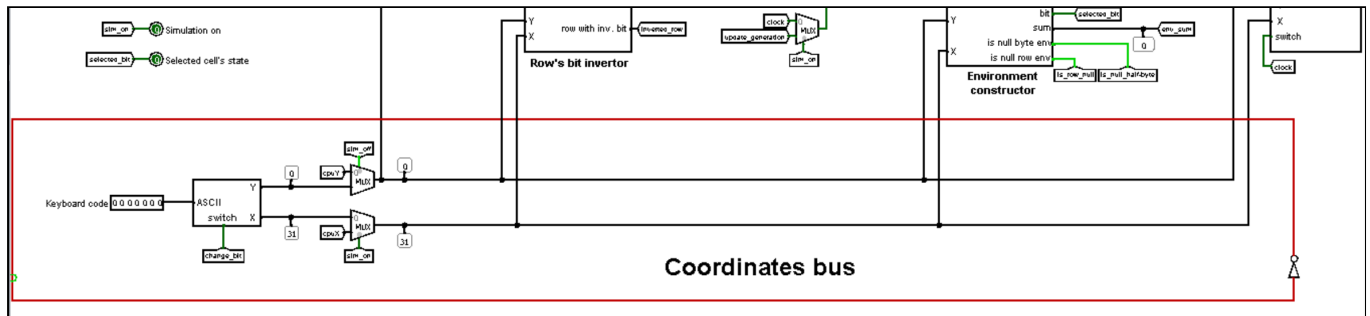
Controls

Main signals
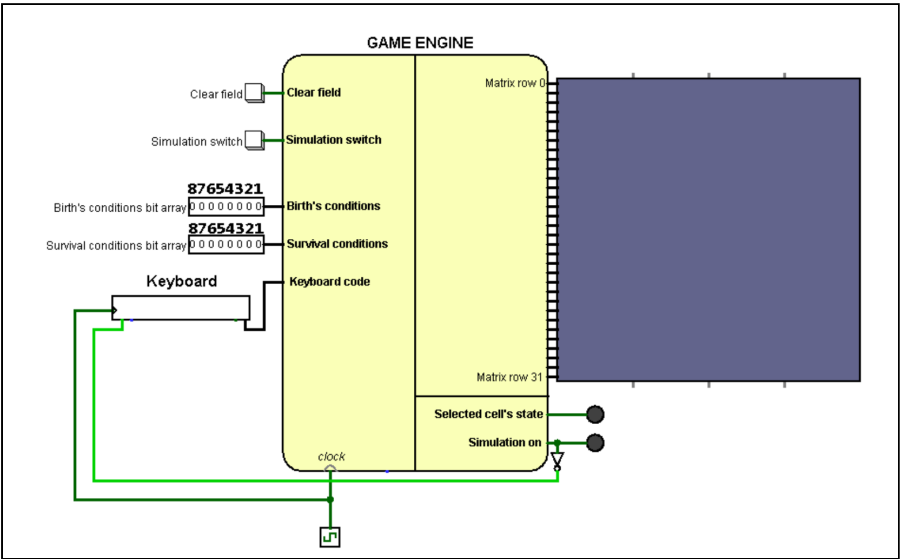
Simulations switch button switches between simulation and setting modes. **When we turn from simulation to setting mode we can get unfinished new generation**

Two 8-bit inputs let us set different conditions for birth and survival. Bit value `1` on position `N` means fulfilling of conditions when cell has `N` neighbors so this inputs represent bit arrays.

Clear button clears all field when simulation is off.

Keyboard Logisim circuit sends keys' ASCII codes to engine. See more below.

On bottom-right side we can see two LED indicators:

1. State of cell under the blinking cursor
2. Simulation state (when simulation is on indicator will light)

Keyboard

Logisim circuits keyboard handles keys' presses and send 7-bit ASCII codes to Keyboard controller inside engine circuit

All keys are working only while we are in the `setting` game mode

Keyboard layouts

Cursor moving:

KEY	DIRECTION	X DELTA	Y DELTA
NUM 1 / Z	bottom-left	-1	+1
NUM 2 / S	bottom	0	+1
NUM 3 / C	bottom-right	+1	+1
NUM 4 / A	left	-1	0

KEY	DIRECTION	X DELTA	Y DELTA
NUM 6 / D	right	+1	0
NUM 7 / Q	top-left	-1	-1
NUM 8 / W	top	0	-1
NUM 9 / E	top-right	+1	-1

On matrix cursor is marked by blinker

NUM 5 / Space - change state of selected cell in random write buffer using row's bit invertor

I/O registers

I/O bus have minor changes: selection of I/O addresses from CPU `addr` is detected by `less than` comparator's output with the second input `0xf0` (the first I/O cell address)
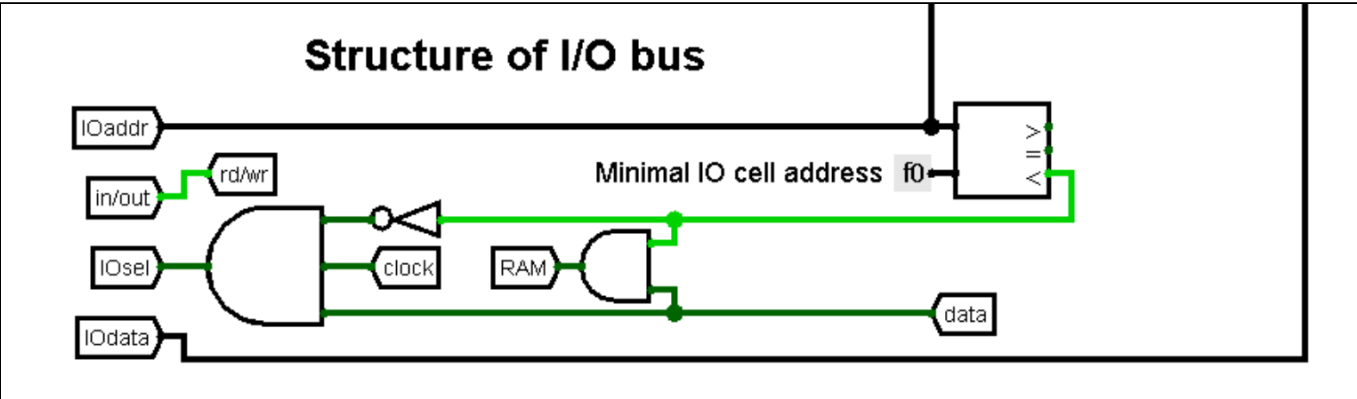
I/O registers' types

All types' names are regarding the CPU directions

Registers have trivial types of data direction: `READ ONLY` and `WRITE ONLY`.

PSEUDO WRITE

Besides these types we use one specific type - `PSEUDO WRITE`. CPU cannot write data to this "registers". Main goal for this type is handle `write` signal by CdM-8's `st` instruction.

Short description table

CELL ADDR.	ASSEMBLER LABEL	DATA DIRECTION	EXPLANATION TOPIC
0xf0	IOGameMode	READ ONLY	
0xf1	IOBirthConditions	READ ONLY	Link
0xf2	IODeathConditions	READ ONLY	
0xf3	IOY	WRITE ONLY	Link
0xf4	IOX	WRITE ONLY	
0xf5	IOBit	READ ONLY	
0xf6	IOEnvSum	READ ONLY	Link
0xf7	IONullRowsEnv	READ ONLY	
0xf8	IONullHalfByteEnv	READ ONLY	
0xf9	IOInvertBitSignal	PSEUDO WRITE	Link
0xfa	IOUpdateGeneration	PSEUDO WRITE	

List with descriptions

Simulation rules

- `0xf0` - READ ONLY - when simulation off this register will be `0`.
  - Trigger signal on this register will invert its value
  - Tunnels from this register are used for control data origins on coordinates bus and some other cases.
- `0xf1` - READ ONLY - birth conditions as bit array
- `0xf2` - READ ONLY - death conditions as bit array. This value is inverted version from survival conditions user input
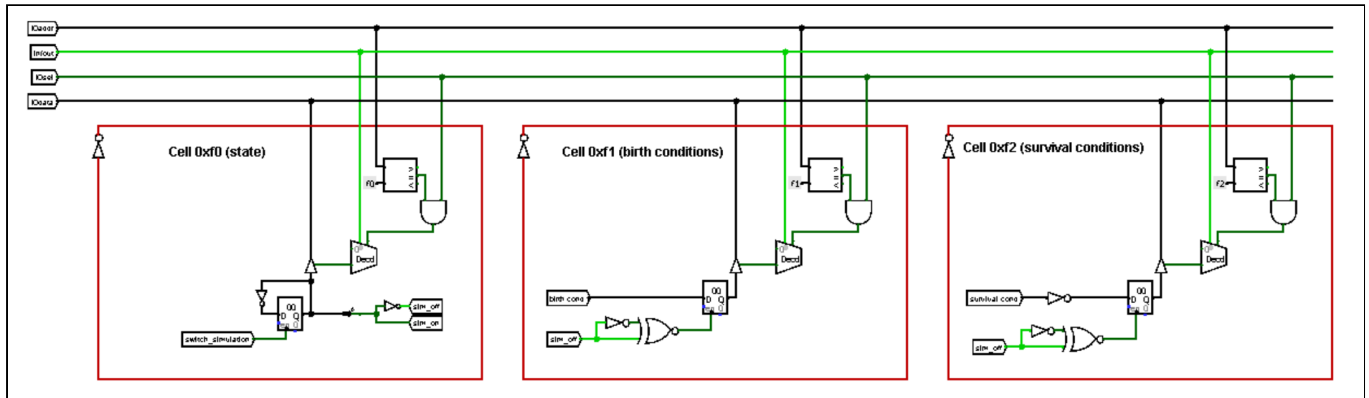
Processed cell

Coordinates from these registers are used in all Logisim components to tell what cell CPU is processing. When simulation on they capture coordinates bus:

- `0xf3` - WRITE ONLY - Y coordinate (processing row)
- `0xf4` - WRITE ONLY - X coordinate (bit index in row)
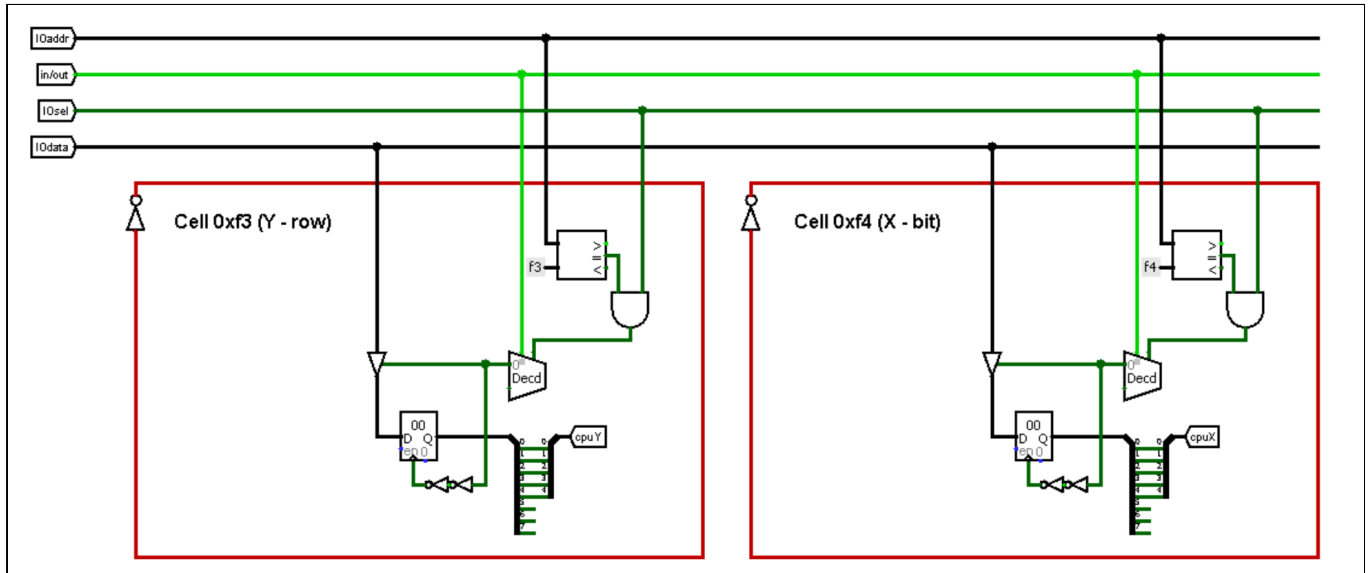
I/O "registers" with environment data

These "registers" aren't exist. There are just tunnels which are connected to environment constructor outputs:

- `0xf5` - READ ONLY - 1 when bit on position (Y, X) is 1
- `0xf6` - READ ONLY - sum of bits around cell (Y, X)
- `0xf7` - READ ONLY - 1 when rows $Y-1$, Y and $Y+1$ are null
- `0xf8` - READ ONLY - 1 when in rows $Y-1$, Y and $Y+1$ all bits from $X+1$ to $X-4$ are null
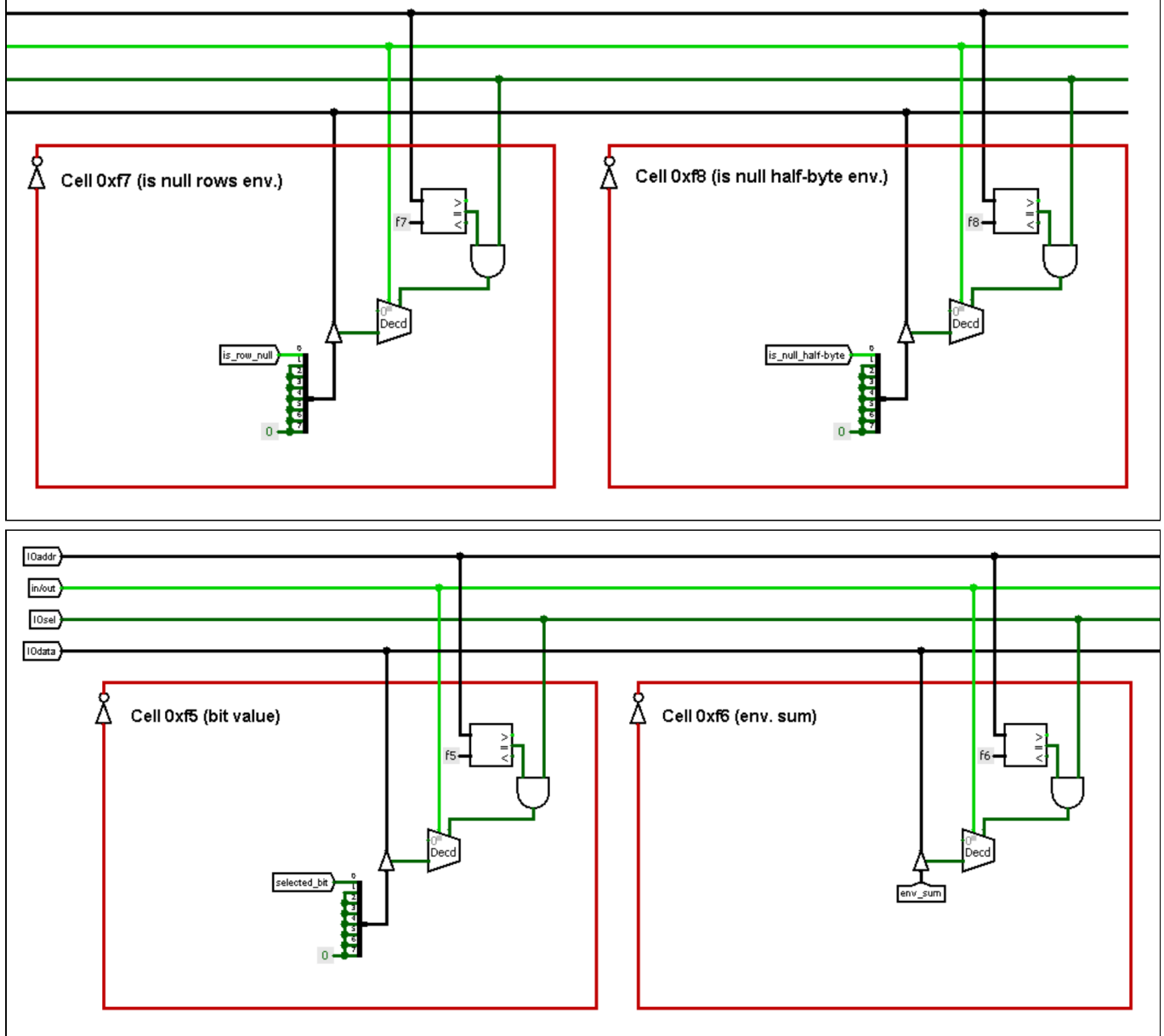
I/O "registers" for changing field

- `0xf9` - PSEUDO WRITE - save signal to this cell will trigger random write buffer and change cell `(Y, X)` using row's bit invertor
- `0xfa` - PSEUDO WRITE - save signal to this cell will update generation buffer
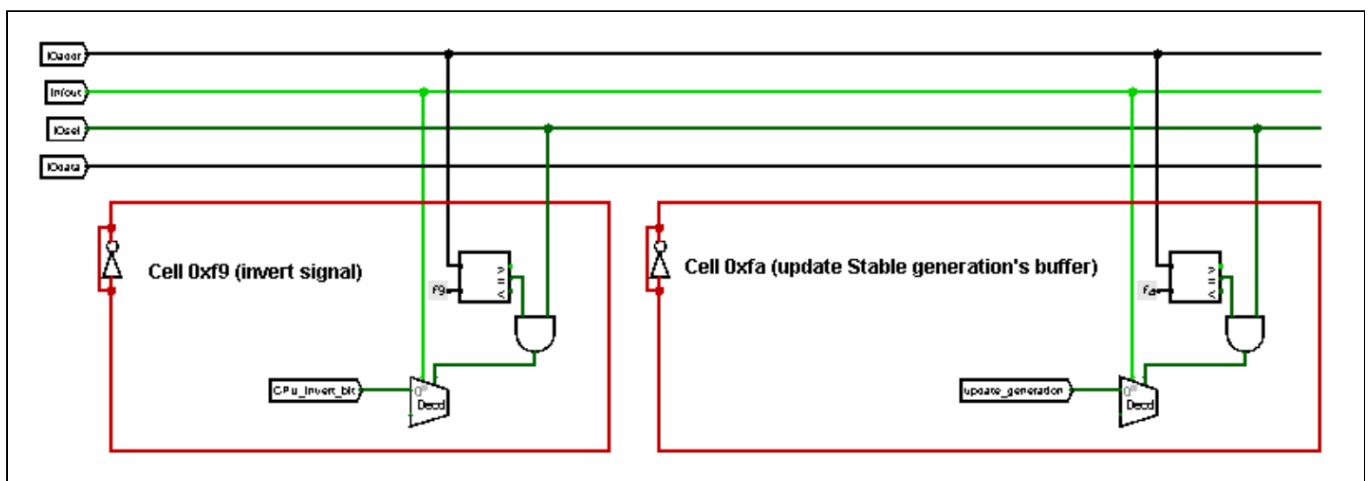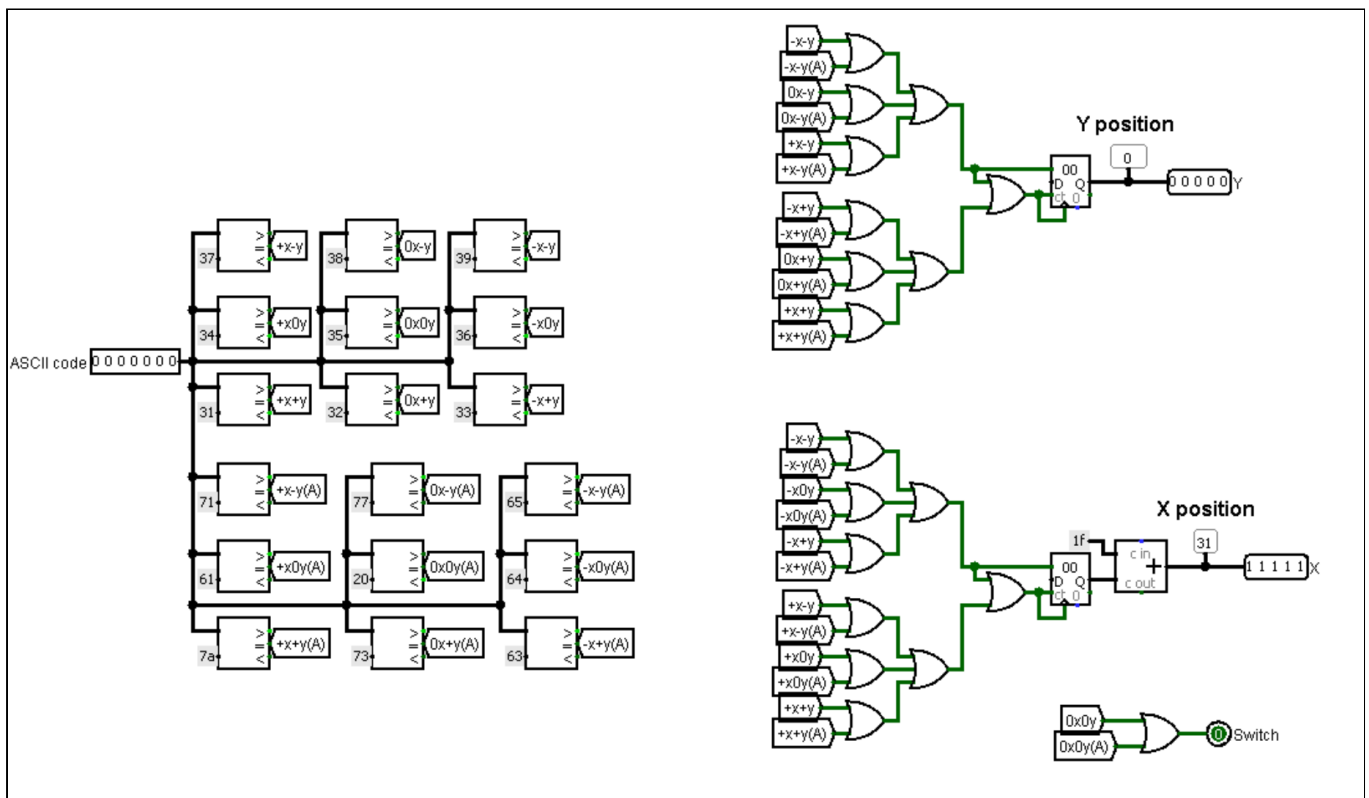
Elements description

Keyboard controller

This circuit considers 7-bit ASCII input as ASCII code and compares it with constants related to some keys and make list of actions:

- Cycled increment/decrement X/Y of cursor
- Send switch signal for switching the cell's state

See keyboard layouts here

Circuit screenshot:

Usage in Engine circuit: Keyboard controller gives user signals that are used while simulation if off:

- Y and X for [coordinates bus]
- Switch signal which is implemented as `Write row` in random write buffer
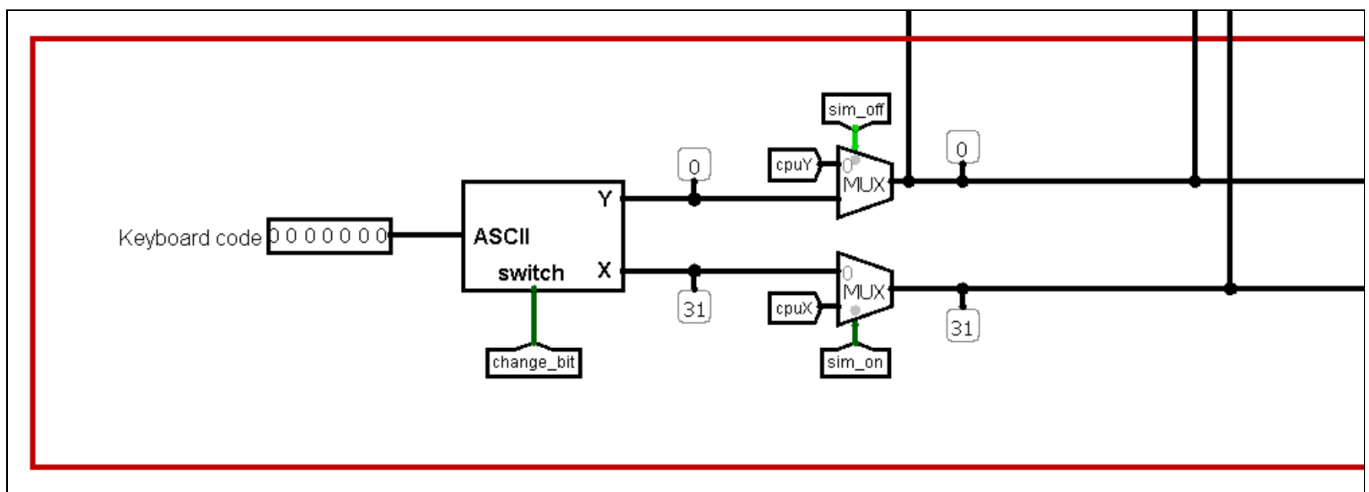
Random write buffer

This circuit saves 32-bit row to one of 32 registers and sends all 32 saved rows to outputs.

Trigger for registers is decoder with 5-bit selector `Y (row index)` and `Write row` enable input. So, buffer will save row from `Input row` to `Y`th register on rising of `Write row`.

Clear signal resets all registers.

Circuit screenshots:
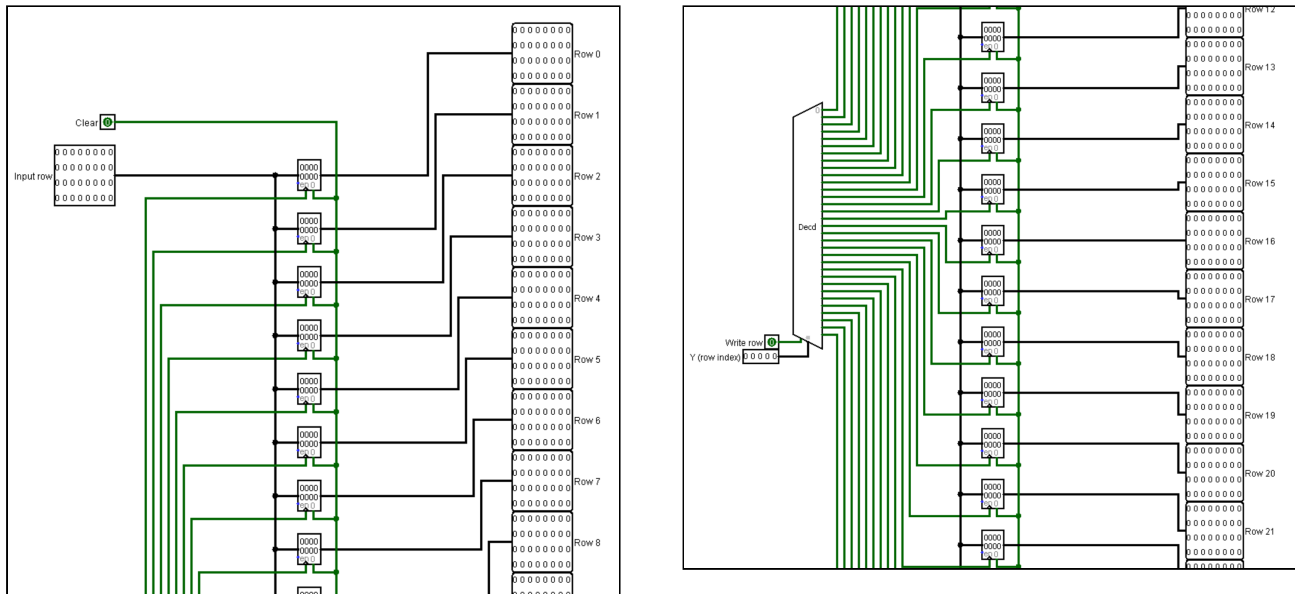
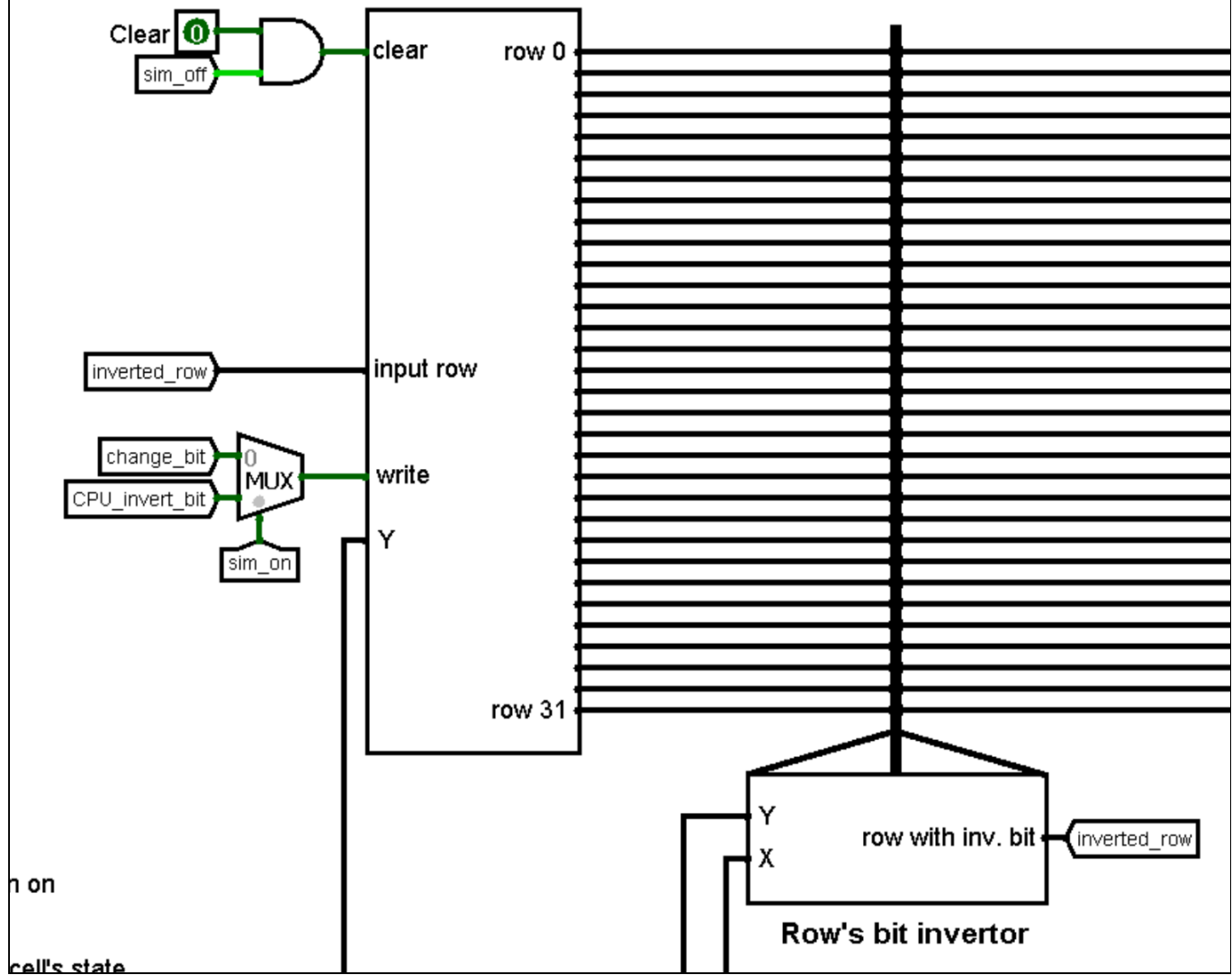**Usage in Engine circuit:** In engine we get input row through tunnel from row's bit invertor

Clear signal works while simulation is off.

Y data goes from coordinates bus

Write row signal goes:

- From keyboard controller when simulation is off
- From Register 0xf9 when simulation is on

Random write buffer

Clear **0**

sim_off

clear

row 0

inverted_row

input row

change_bit

CPU_invert_bit

0

MUX

write

sim_on

Y

row 31

Y

X

row with inv. bit

inverted_row

Row's bit invertor

on

cell's state

Stable generation's buffer

This buffer just saves 32 32-bit rows from inputs to registers and sends them to 32 outputs. Saving occurs on rising edge of input `Save generation trigger`
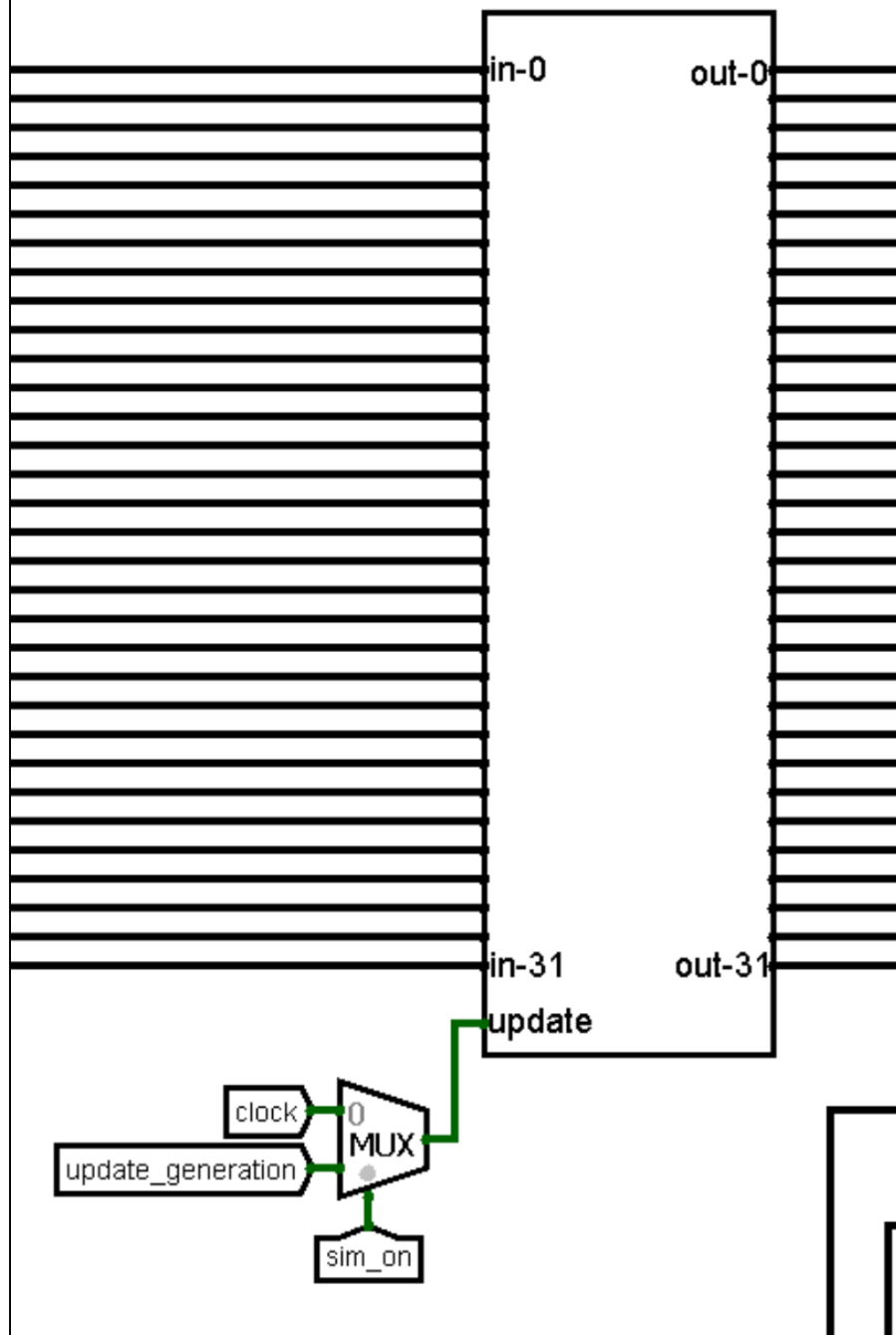
Circuit screenshot:
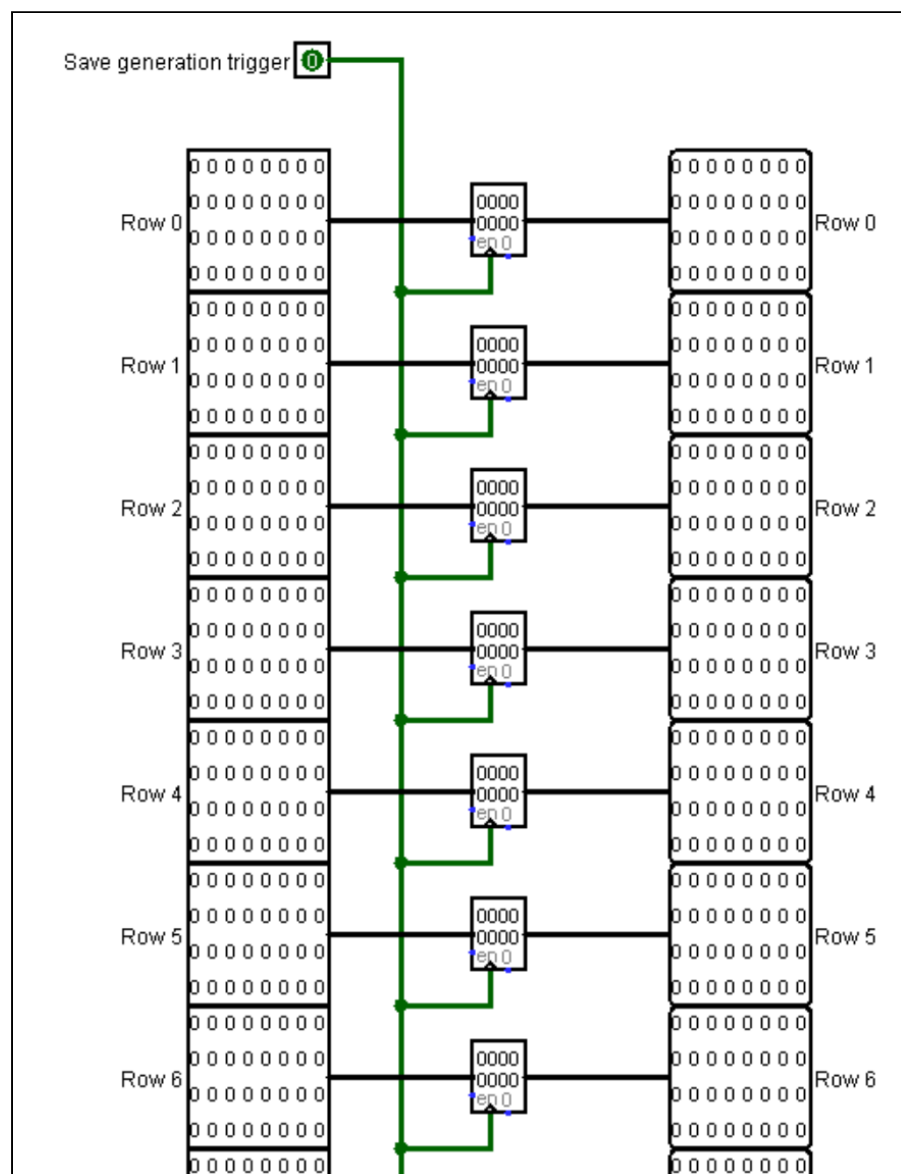
Circuit usage in Engine: Buffer update depends on simulation state:

- While simulation is off buffer is updated by `clock`
- While simulation is on buffer is updated after CdM-8 main cycle's full execution by signal from pseudo I/O register

Stable generation's buffer

in-0   out-0

in-31   out-31

update

clock ──┐ 0
        │ MUX
update_generation ──┘

sim_on

Environment data constructor

Job of this circuit is constructing data about cell's environment for CdM-8 to determine new cell's state.

It has 32 32-bit inputs for rows and 5-bit Y, X inputs and works by this steps:

1. Get rows Y-1, Y and Y using multiplexers
2. Right cycled shift 3 rows on X-1 positions to get X-1, X and X+1 bits on 0, 1 and 2 positions and X+2, X+3 and X+4 on 31, 30 and 29 positions
   1. Send bit 1 from middle row to centre bit output
   2. Use bits [0,2] from top and bottom rows and bits 0 and 2 from middle row as carry signals for 8 adders to get sum of cells surrounding centre bit
3. Shifted rows goes to 32-bit splitters with XORs. When all XORs send true flag is row env. null will be true
4. Bits [X-1, X+4] from all rows goes to next XORs. When these all send true flag is half-byte env. null will be true
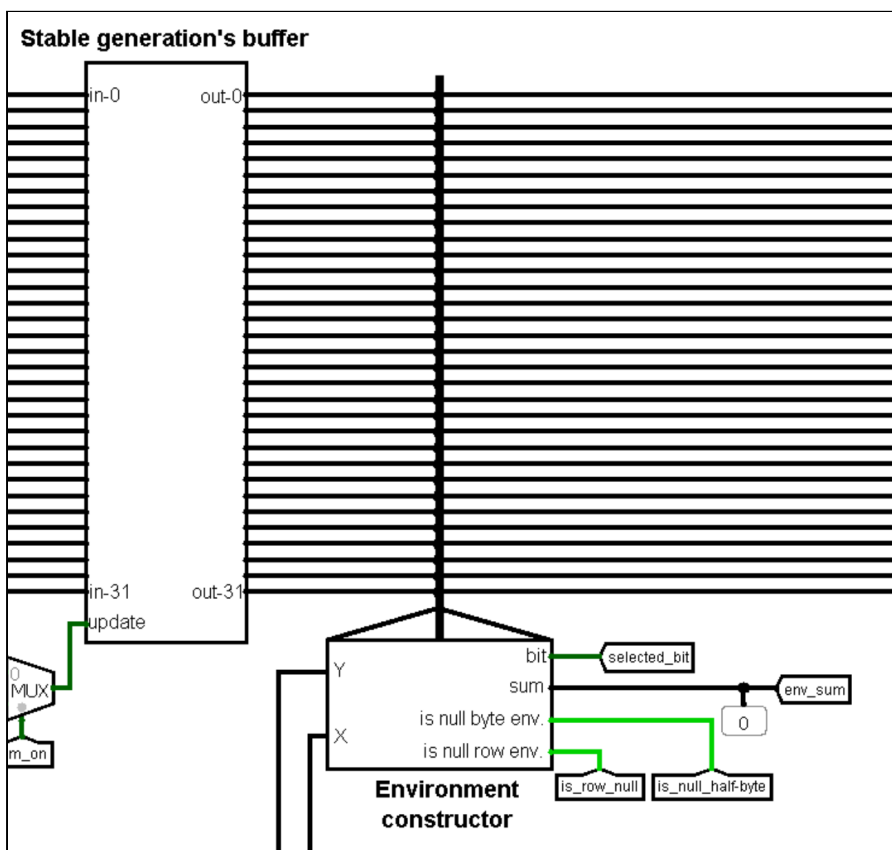
Circuit screenshots:
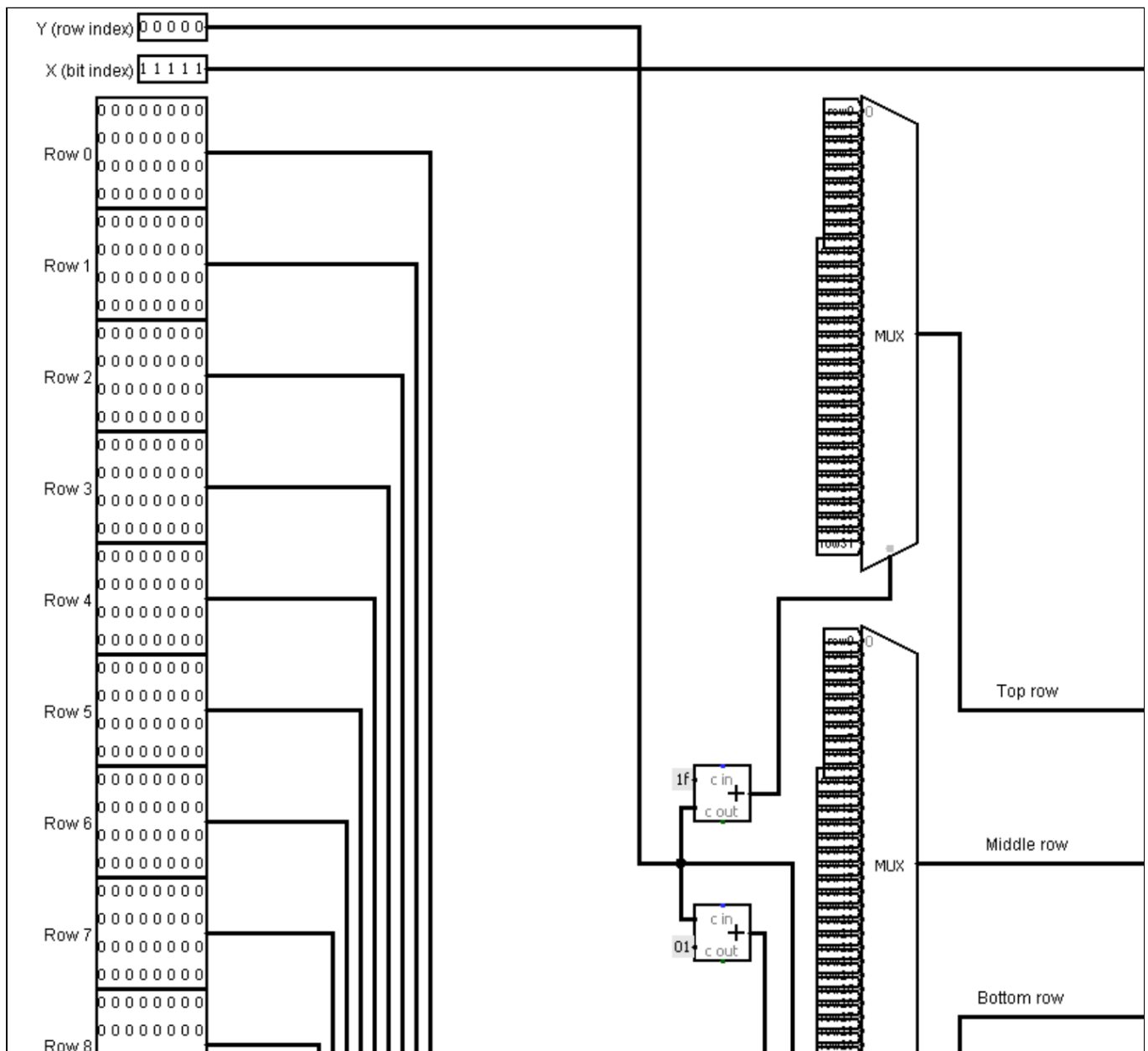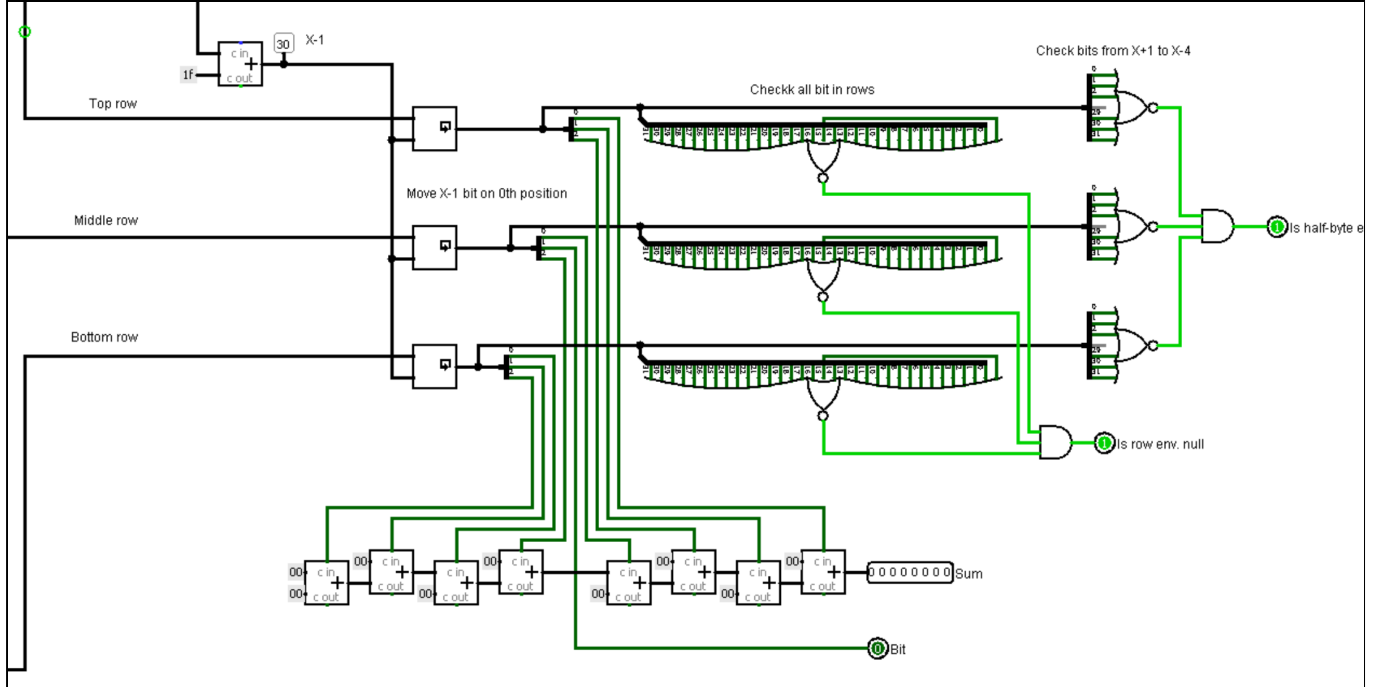
Usage in Engine circuit: Environment data constructor is connected to rows after stable generation's buffer to ensure that CPU with stable generation.

All outputs go through tunnels to I/O registers that are used in ASM main cycle

Y and X go from coordinates bus but while simulation is off environment data isn't used.

Row's bit invertor

This circuit gets 32 32-bit rows and 5 bit coordinates Y and X. Returns Y row with inverted bit on position X. **For inversion we use decoder constructed bit mask and XOR**

Circuit screenshots:
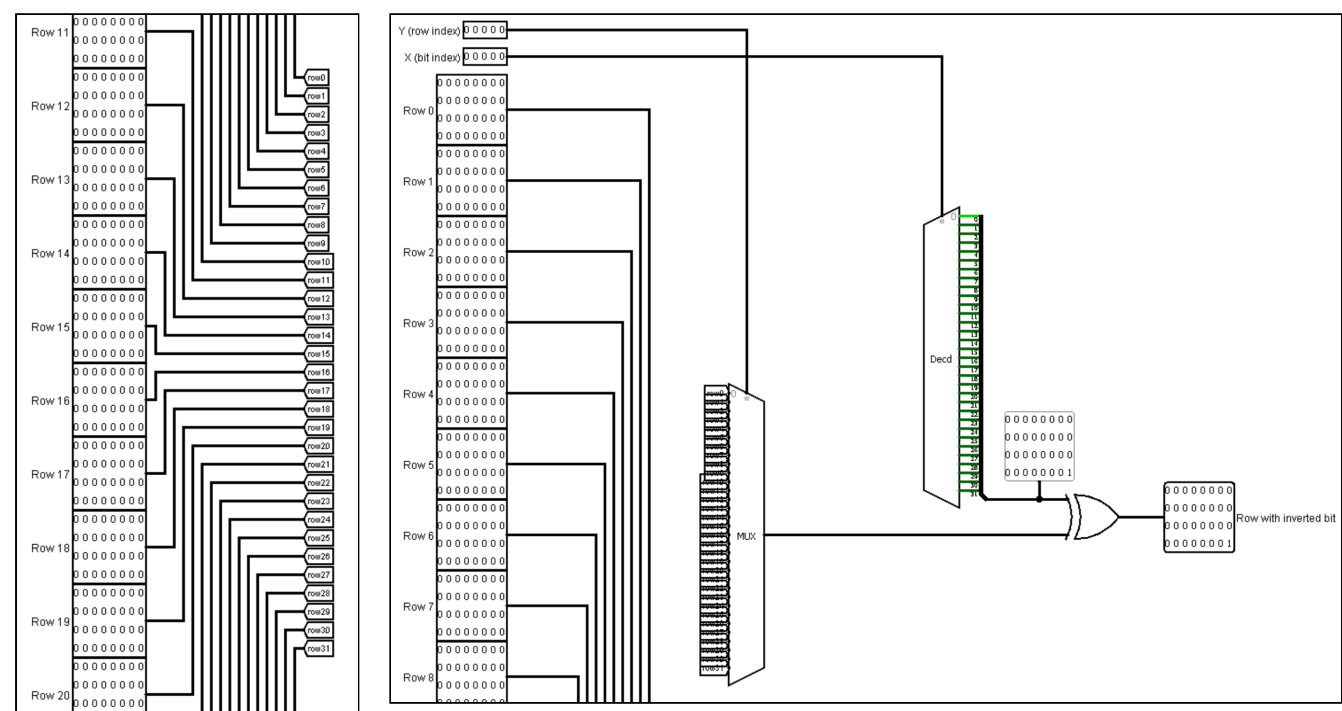
Usage in Engine circuit: 32 input rows goes from random write buffer and inverted row goes through tunnel to `input row` of random write buffer

Y and X go from coordinates bus
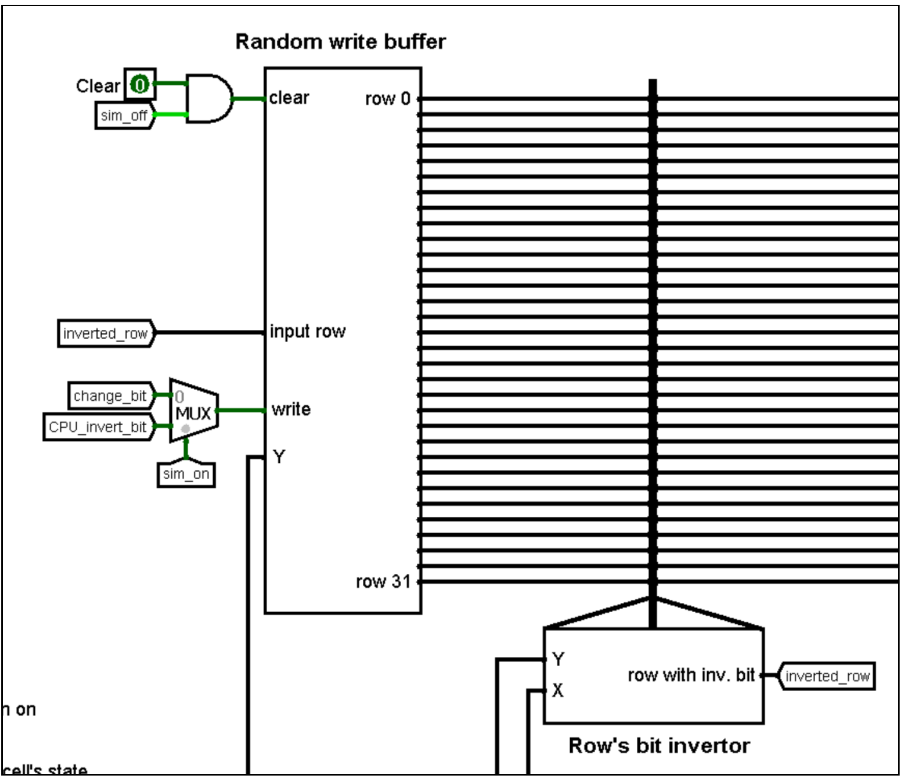
Binary selector

This circuit should choose one of two input values. `Binary selector` should choose second value if the `switch` input is `1` and first value otherwise.
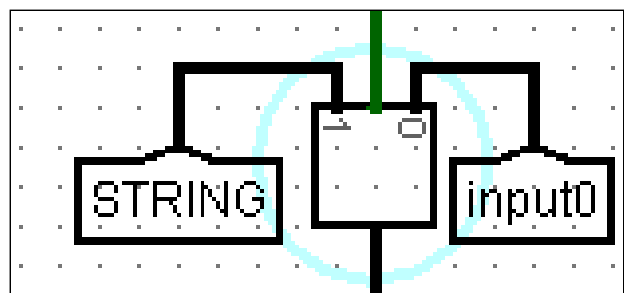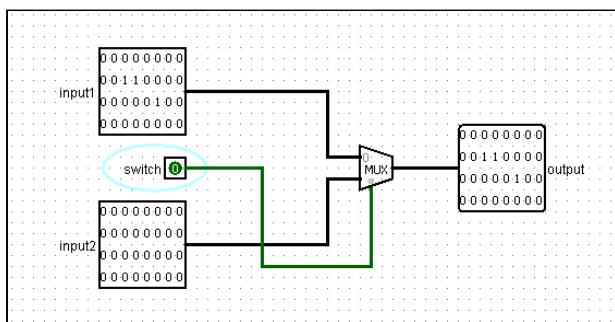
Inputs:

- input values: 2 32-bit rows
- `switch` - 1-bit

Outputs:

- selected value: 1 32-bit row

Circuit screenshot and its usage in Engine: Binary selector is used in blinker for convenient circuit composing.

Blinker

Blinker must switch value of X bit in Y row to opposite if the switch input is raised and return new row between others unchanged. **It is important that this circuit should not store new values in itself.**
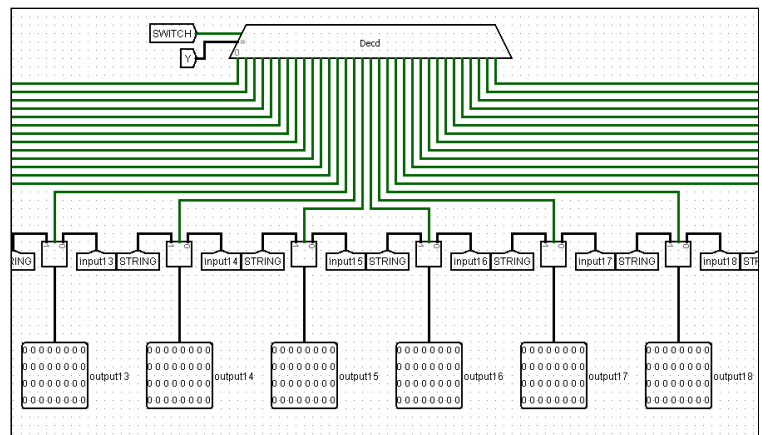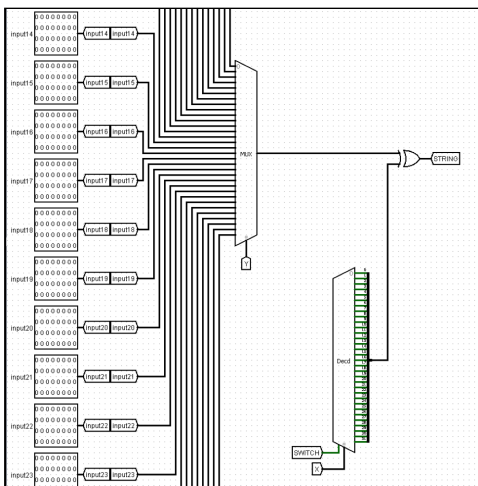
Inputs:

- matrix rows: 32 32-bit rows
- Y coordinate (row number) - 5-bit
- X coordinate (bit number in the row) - 5-bit
- switch - if this input is raised current bit must switch to opposite

Outputs:

- 32 32-bit outputs, in one of which one bit was changed

Circuit screenshots:

Usage in Engine circuit: In engine clock signal is used as switch. Y and X go from coordinates bus

Blinker

in-0   out-0

in-31   out-31

Y

X

switch

clock