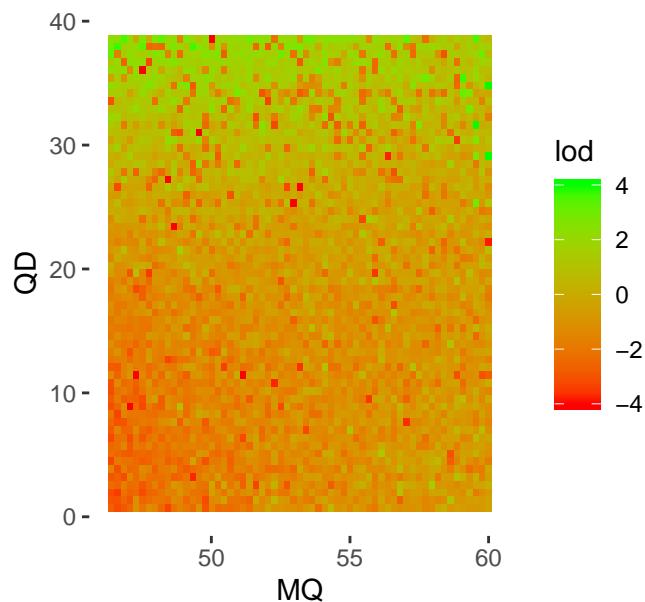
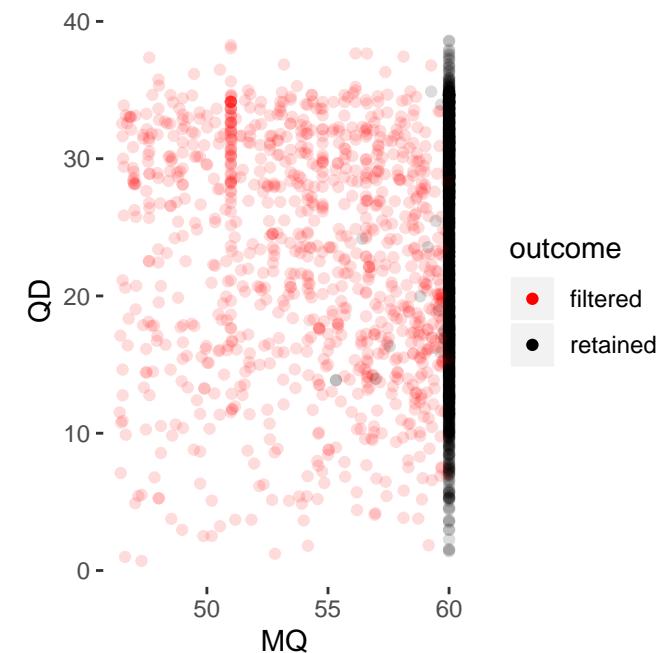


model PDF

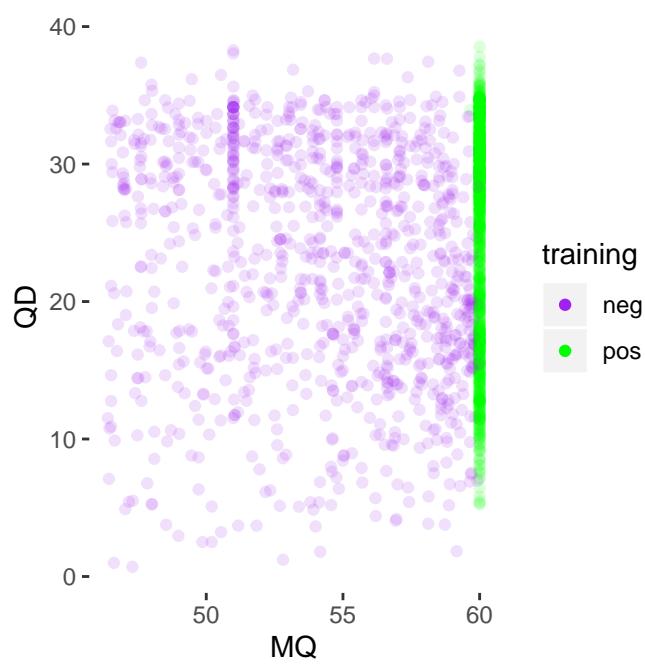


QD



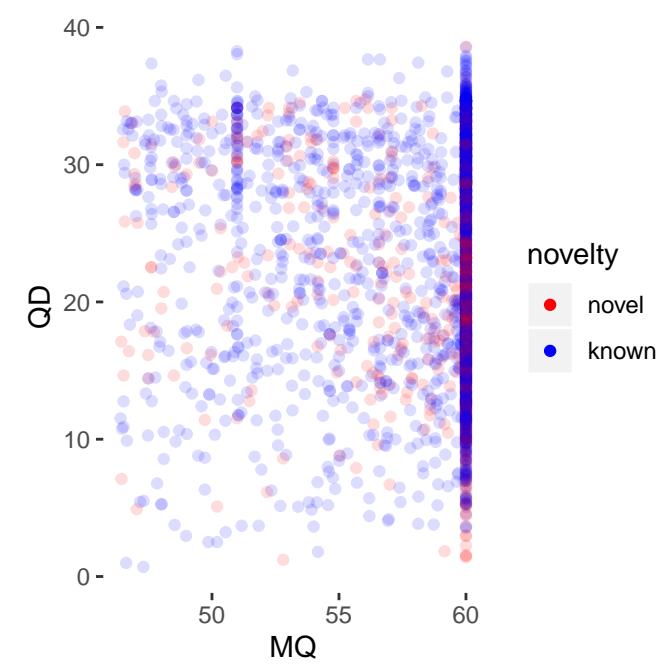
outcome

- filtered
- retained



training

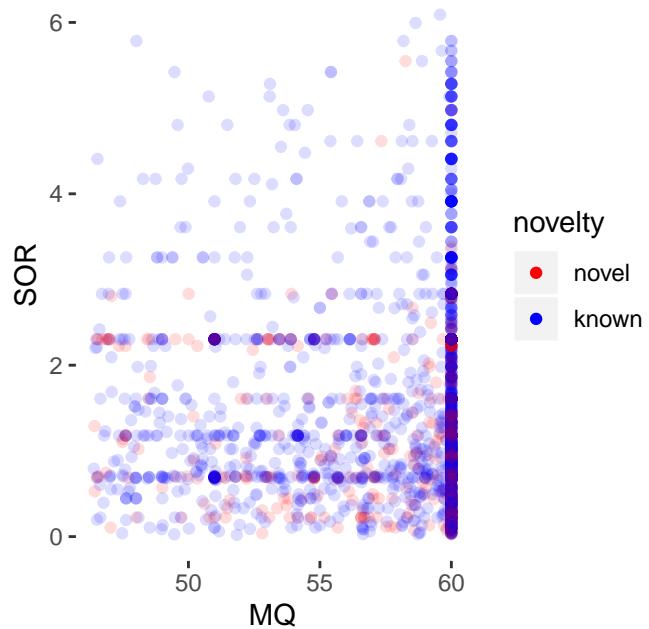
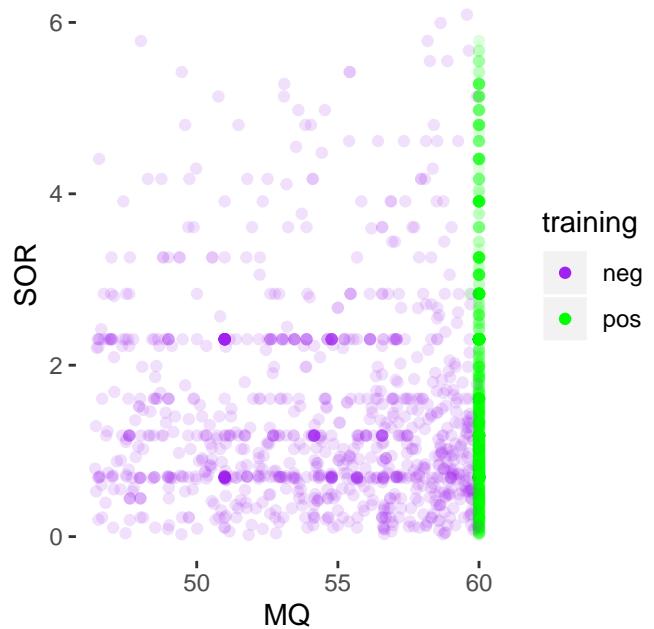
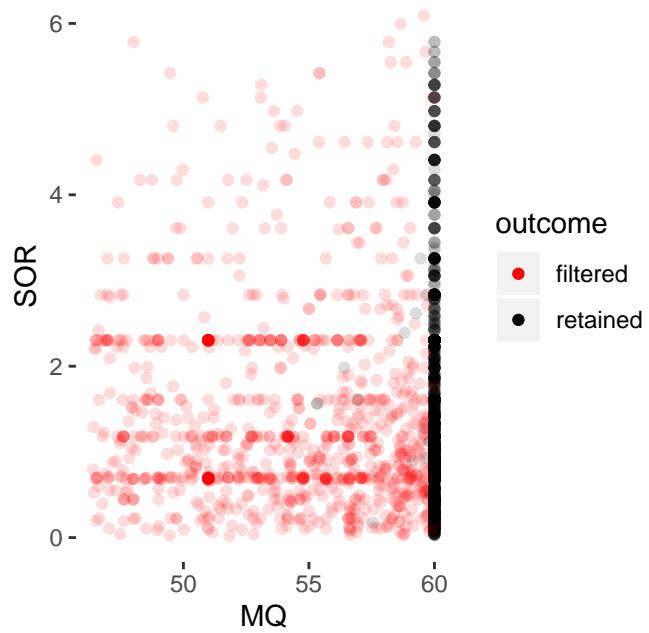
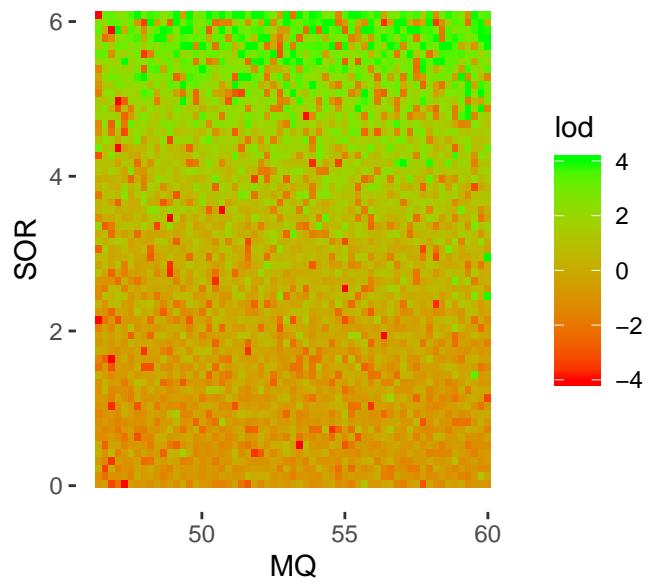
- neg
- pos



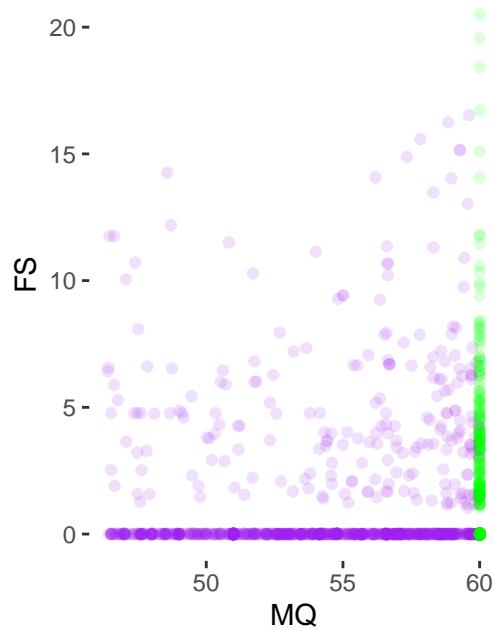
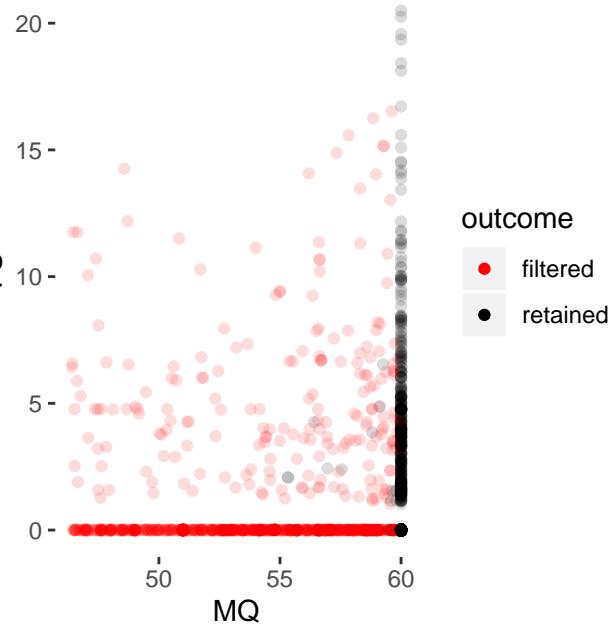
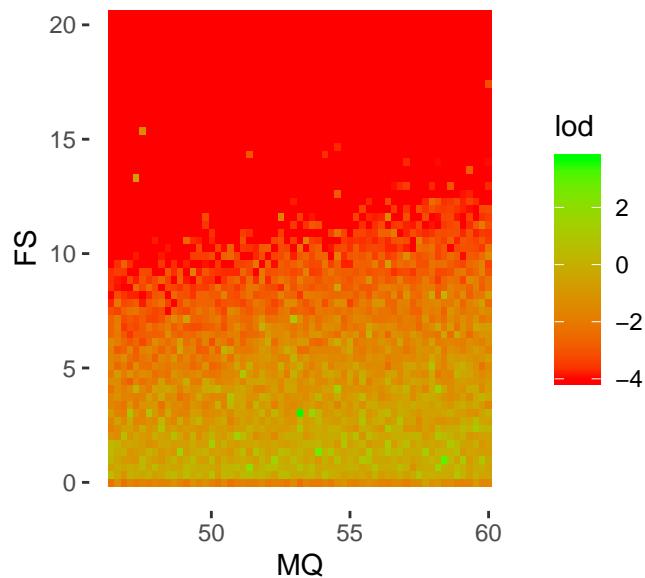
novelty

- novel
- known

model PDF

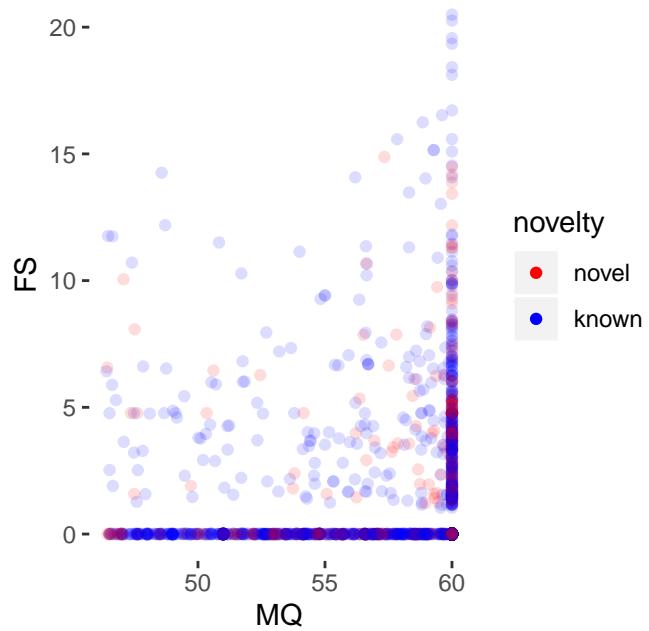


model PDF



training

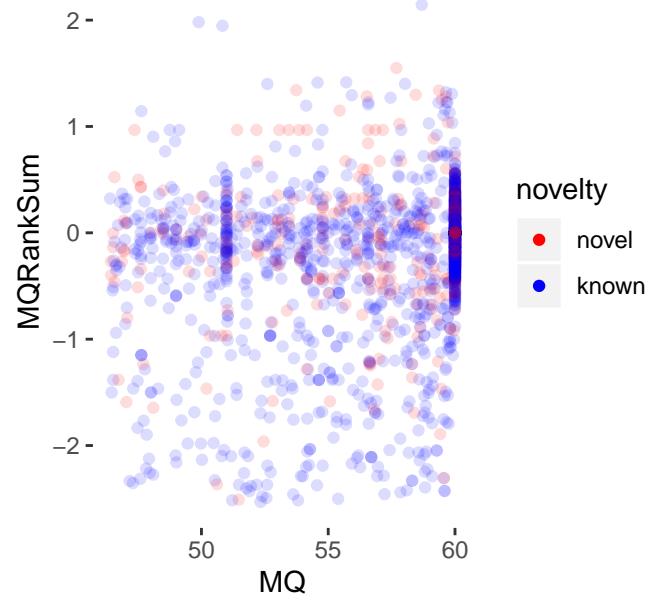
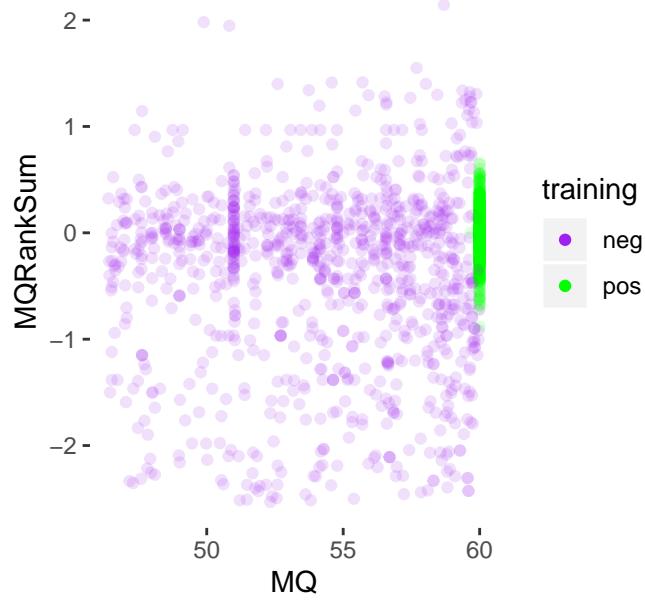
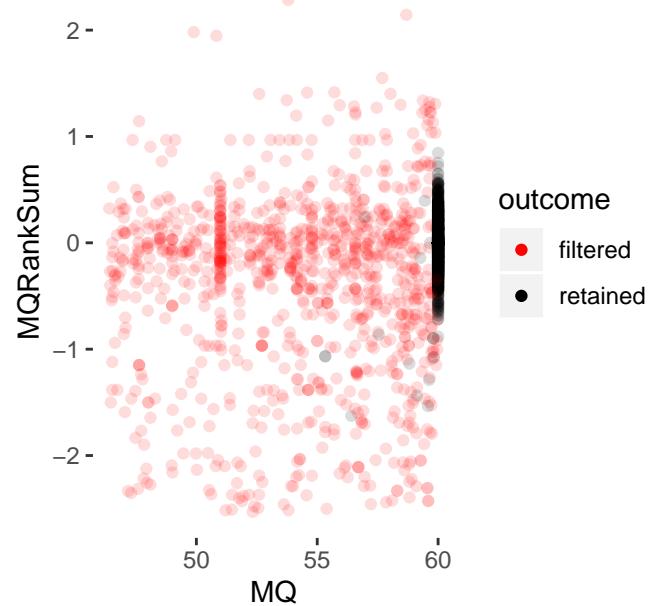
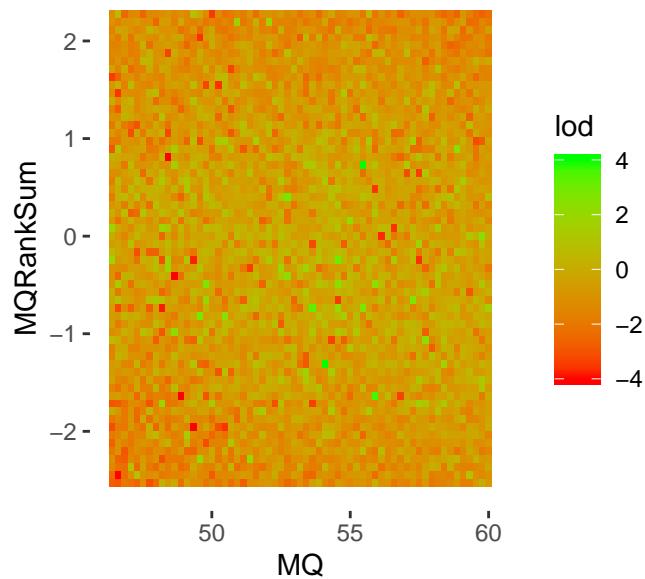
- neg
- pos



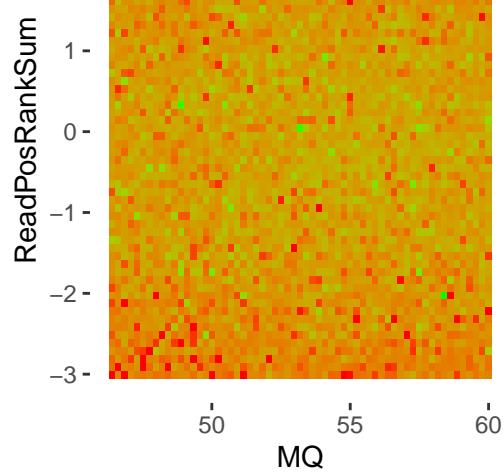
novelty

- novel
- known

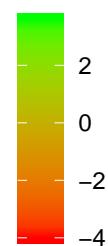
model PDF



model PDF



lod



3

2

1

0

-1

-2

-3

ReadPosRankSum

-3

-2

-1

0

1

2

3

50

55

60

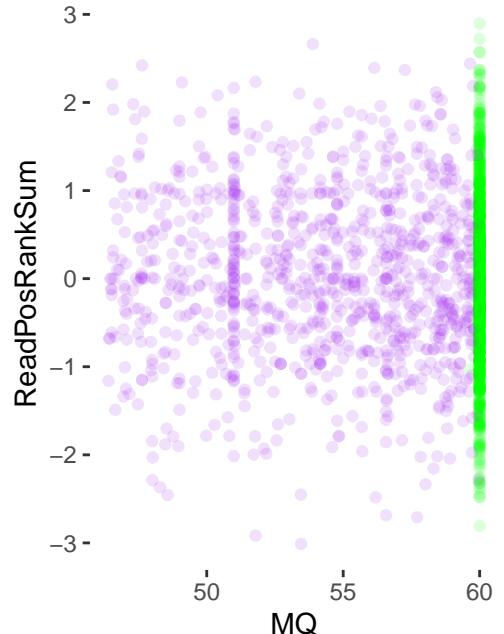
50

55

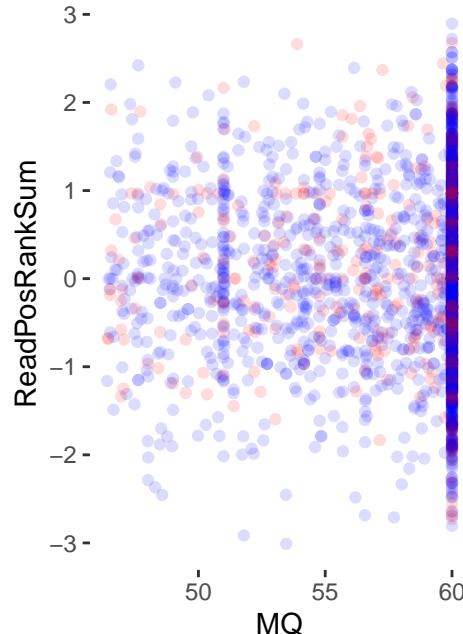
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MQ

outcome



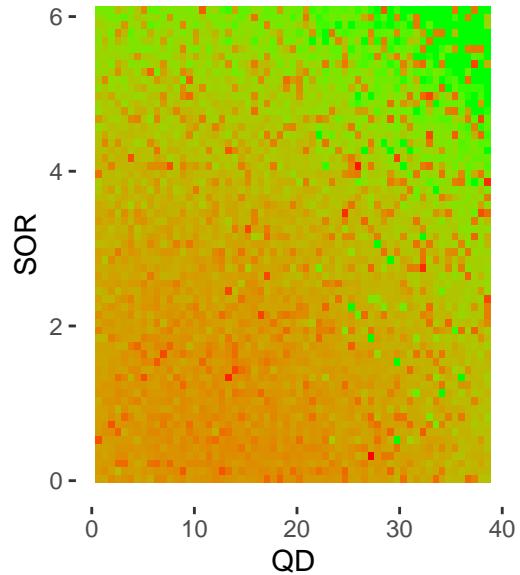
training



novelty

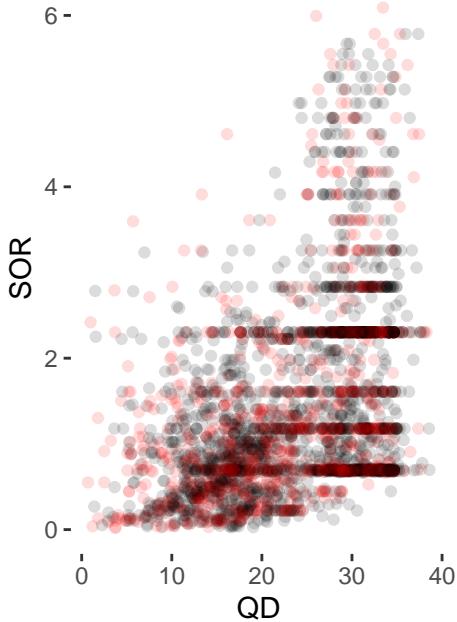


model PDF



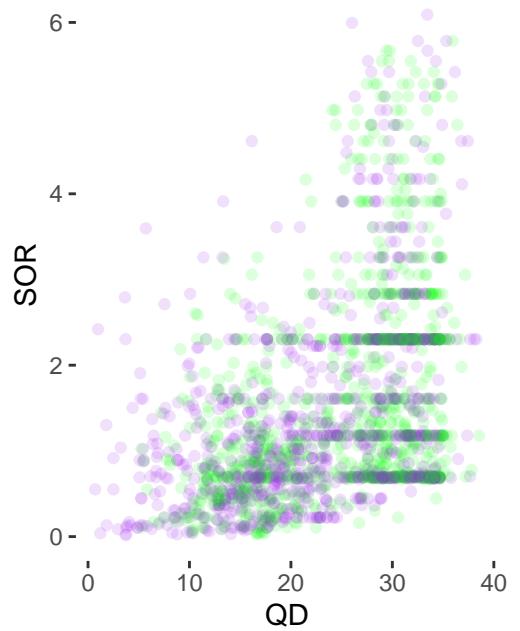
lod

4
2
0
-2
-4



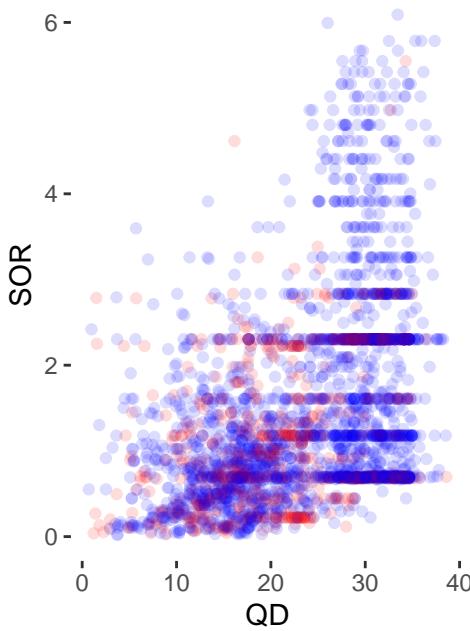
outcome

- filtered
- retained



training

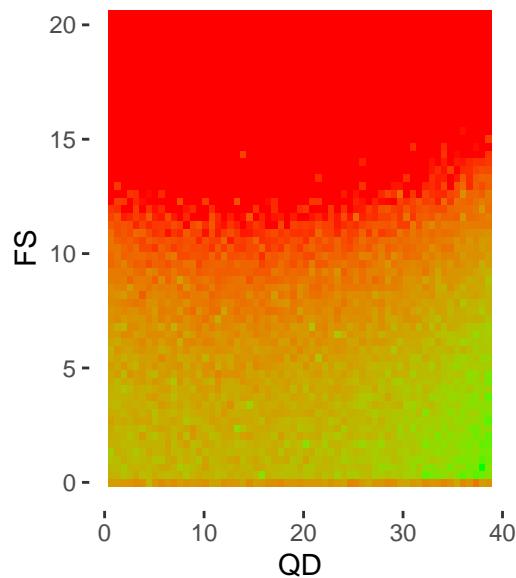
- neg
- pos



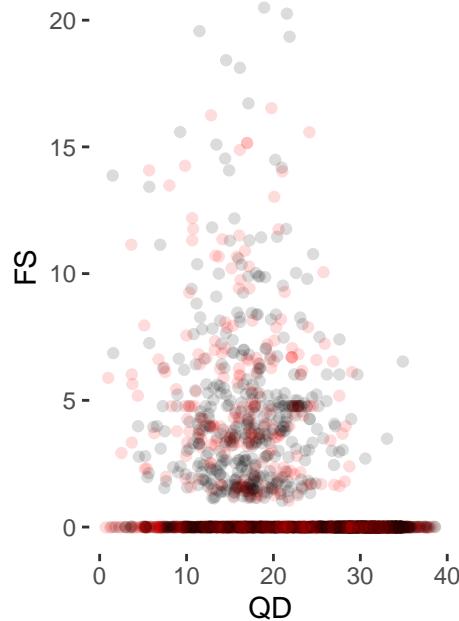
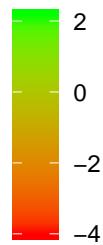
novelty

- novel
- known

model PDF

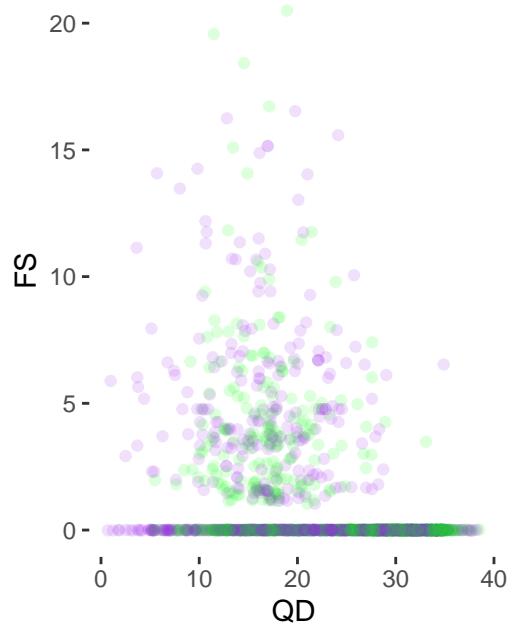


lod

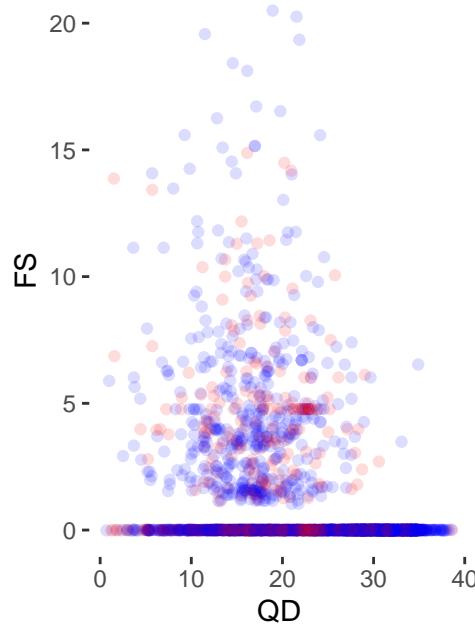


outcome

- filtered
- retained



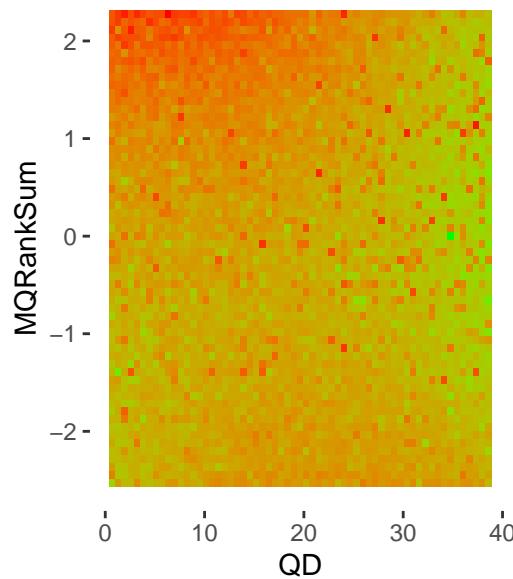
training



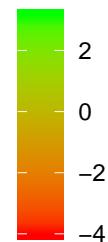
novelty



model PDF



lod



MQRankSum

2

1

0

-1

-2

-3

-4

2

1

0

-1

-2

-3

-4

2

1

0

-1

-2

-3

-4

2

1

0

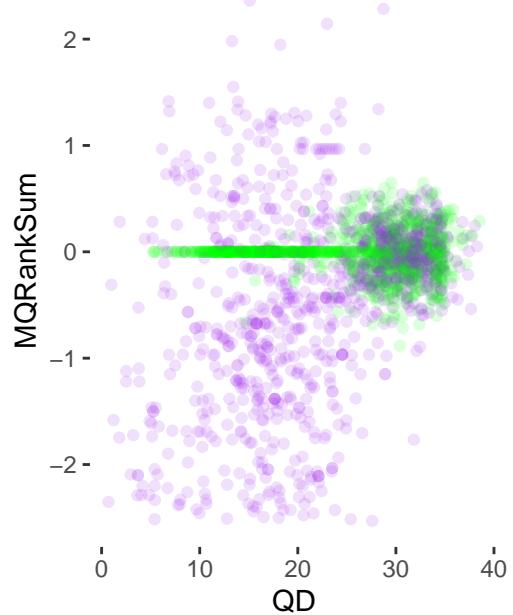
-1

-2

-3

-4

outcome



training



MQRankSum

2

1

0

-1

-2

-3

-4

2

1

0

-1

-2

-3

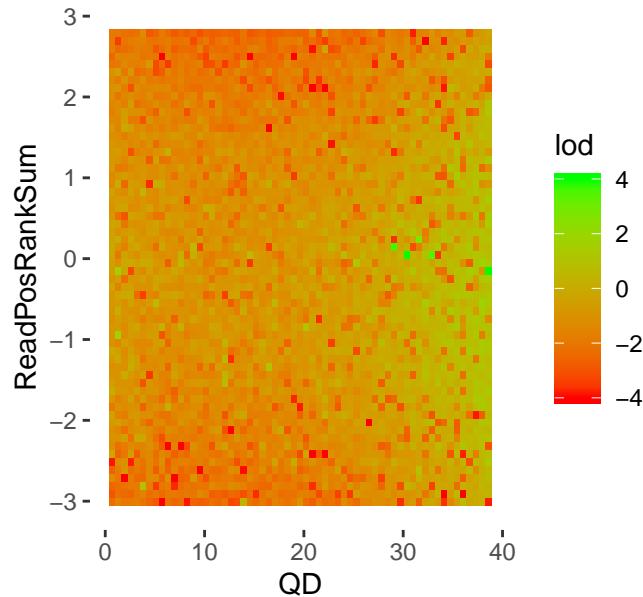
-4

novelty

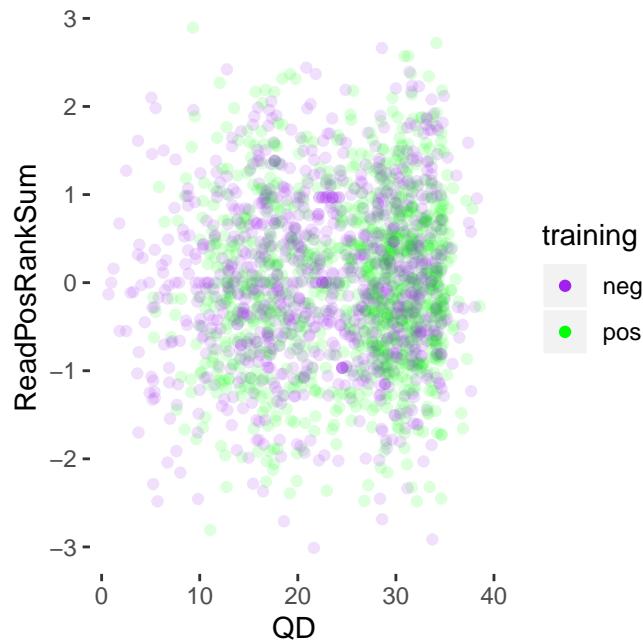
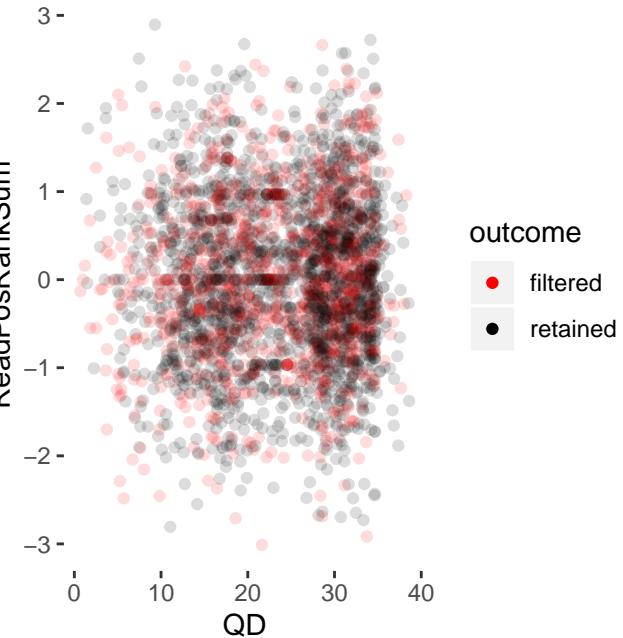


QD

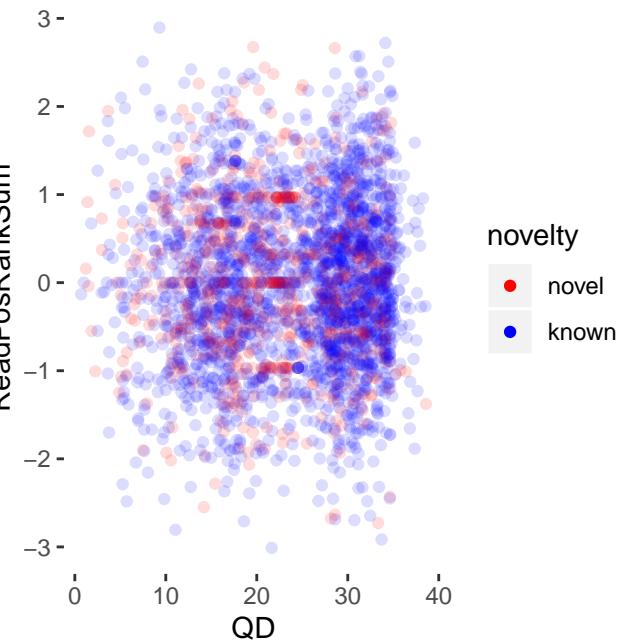
model PDF



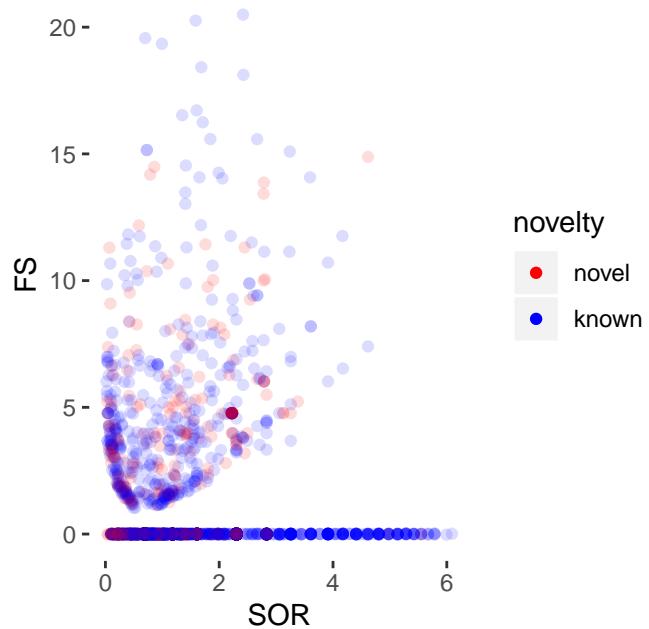
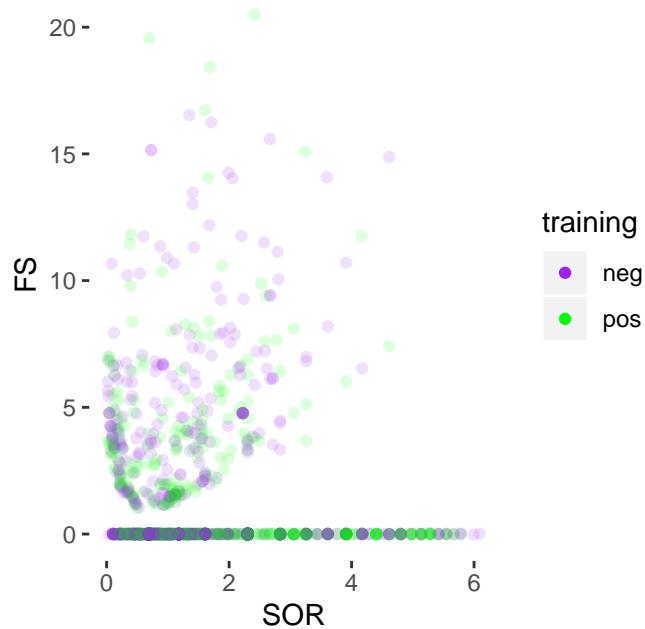
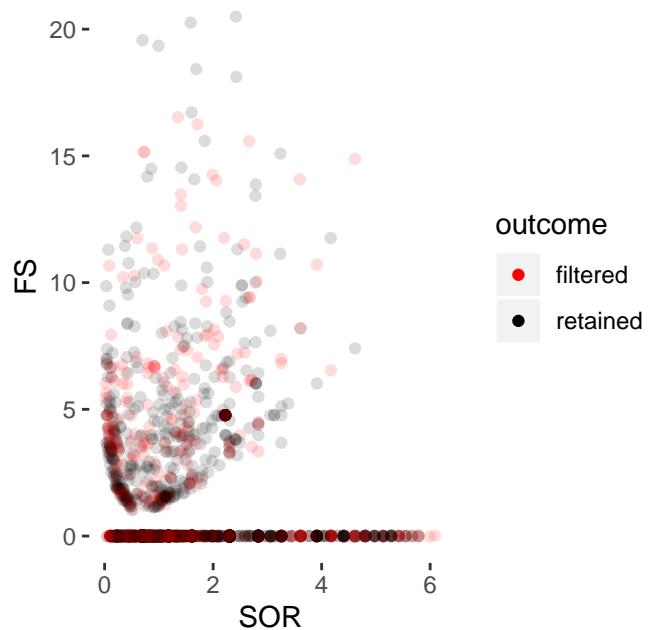
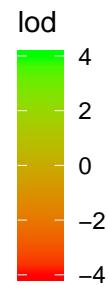
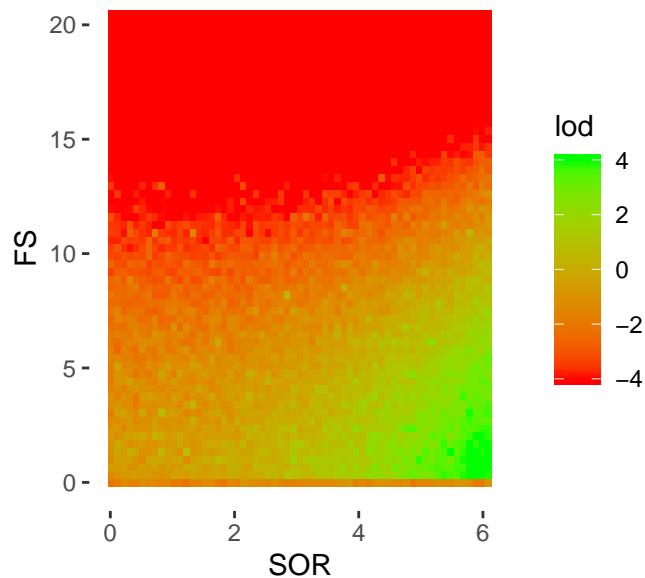
ReadPosRankSum



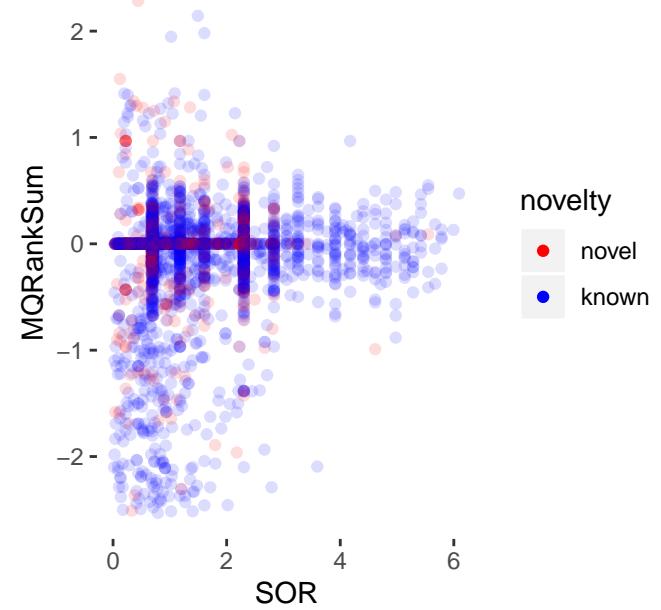
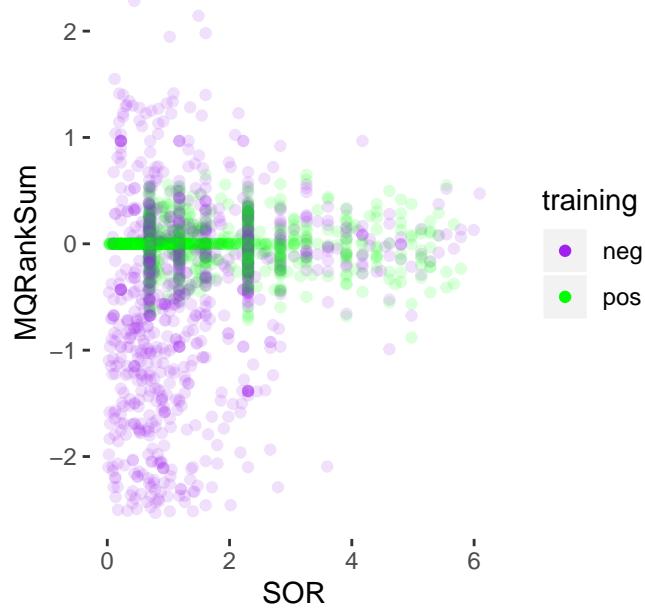
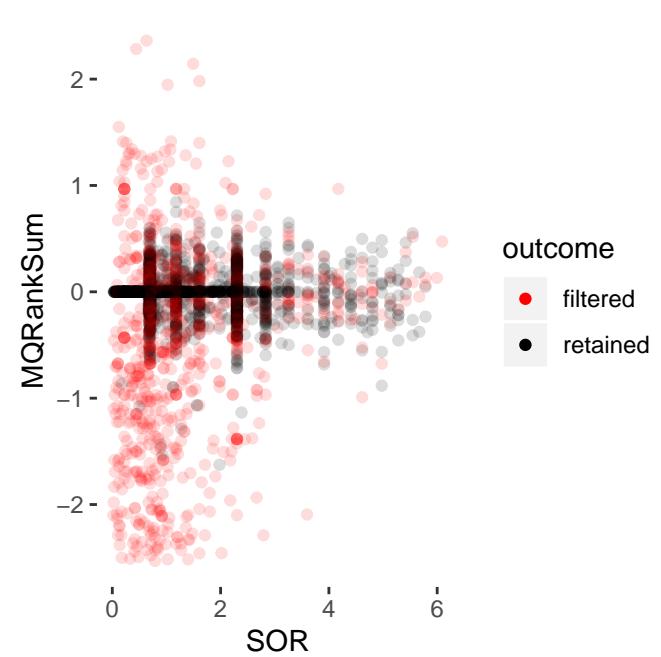
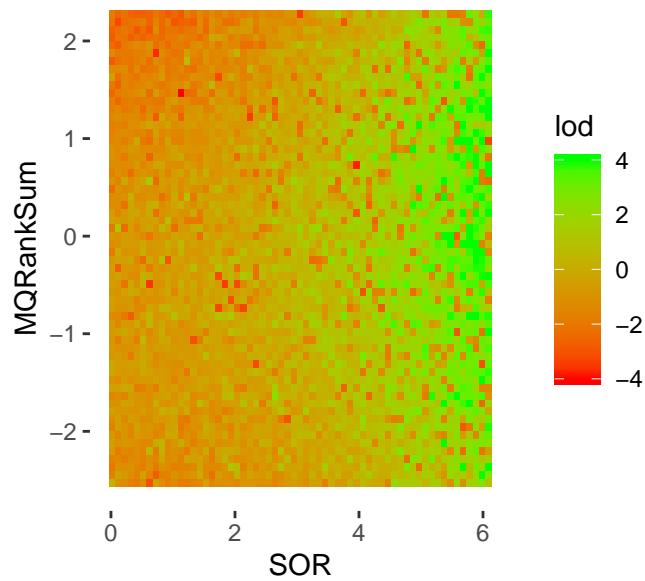
ReadPosRankSum



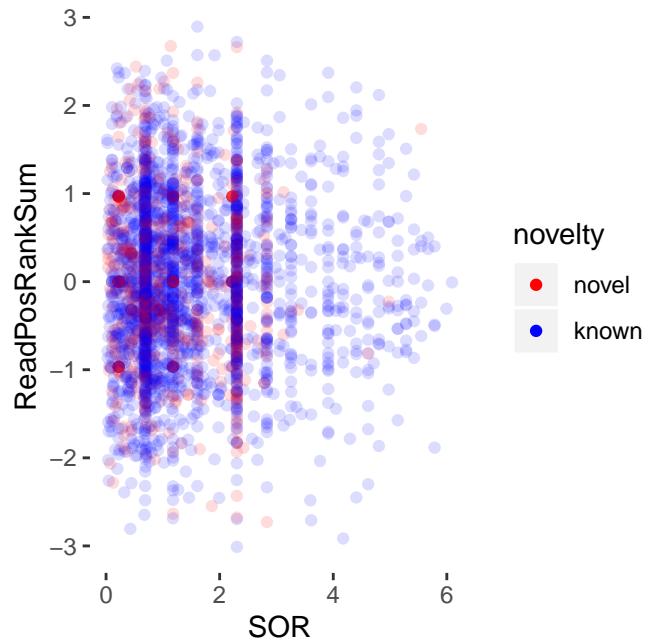
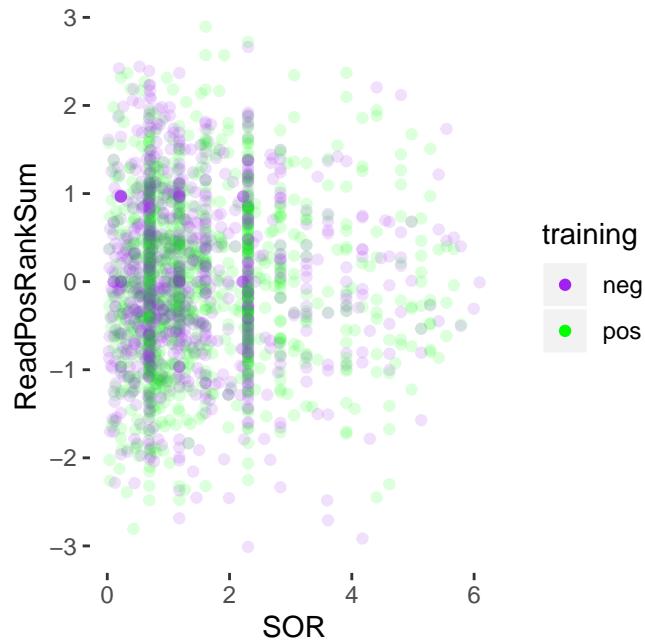
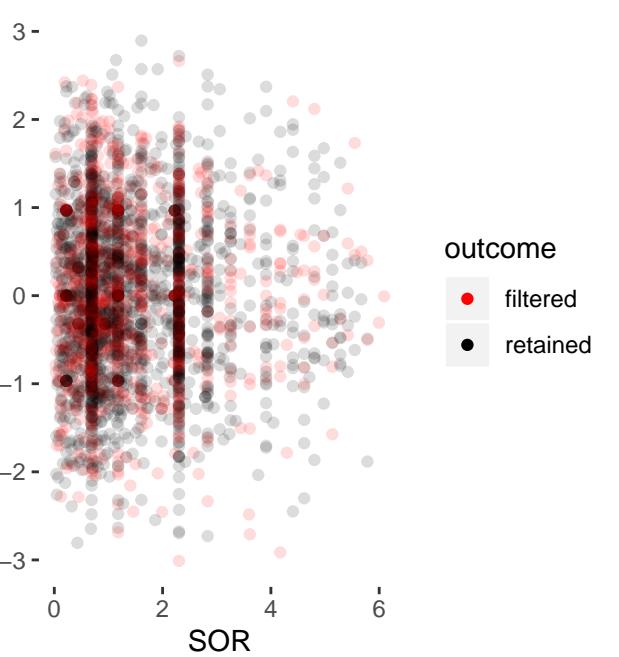
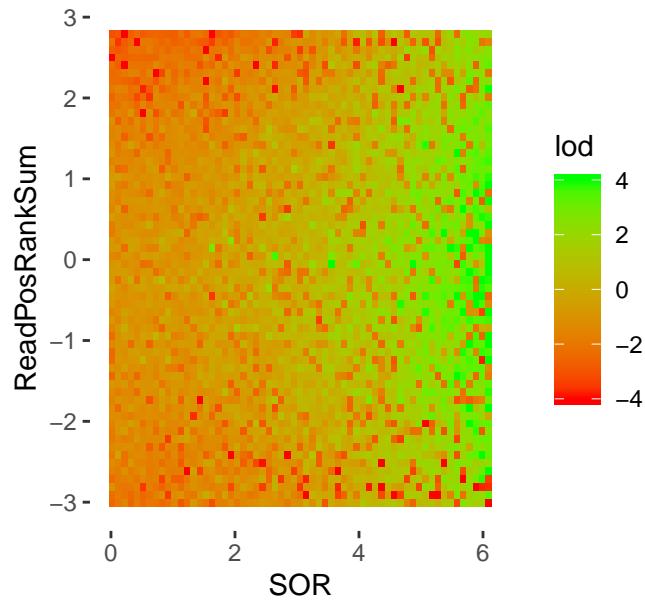
model PDF



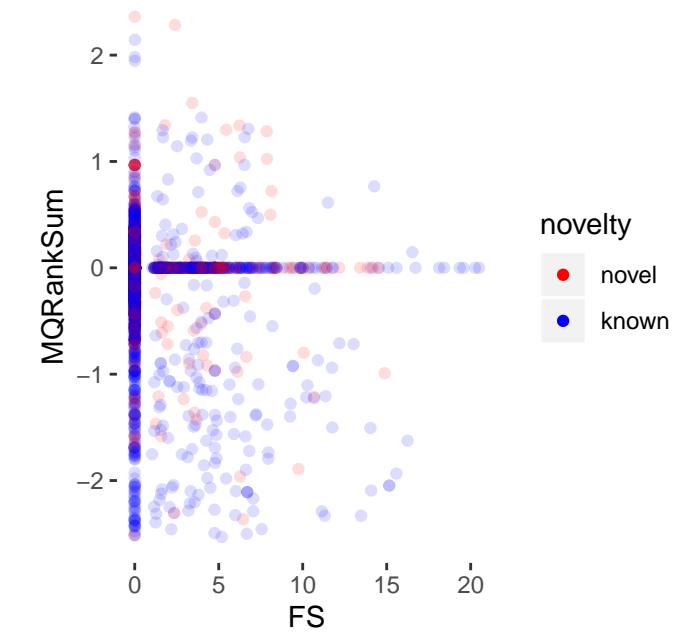
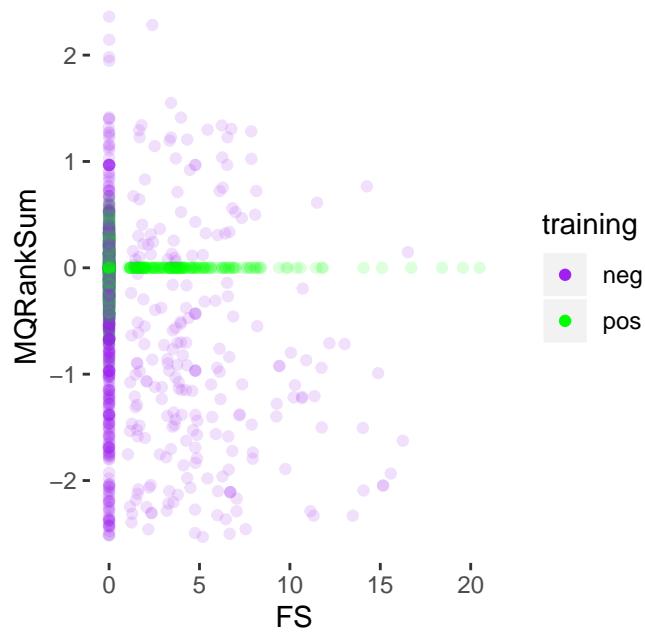
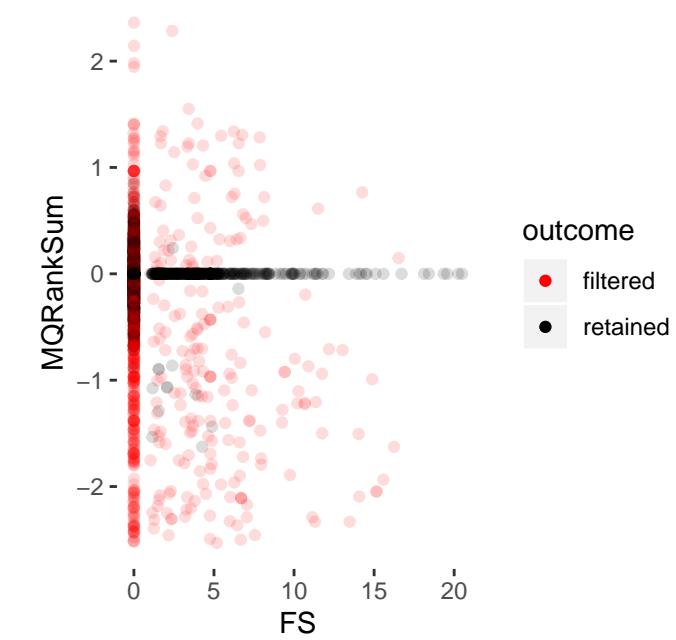
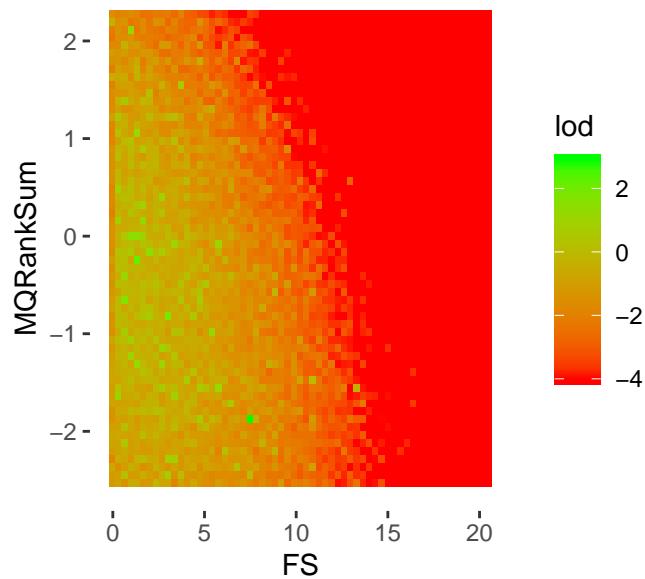
model PDF



model PDF

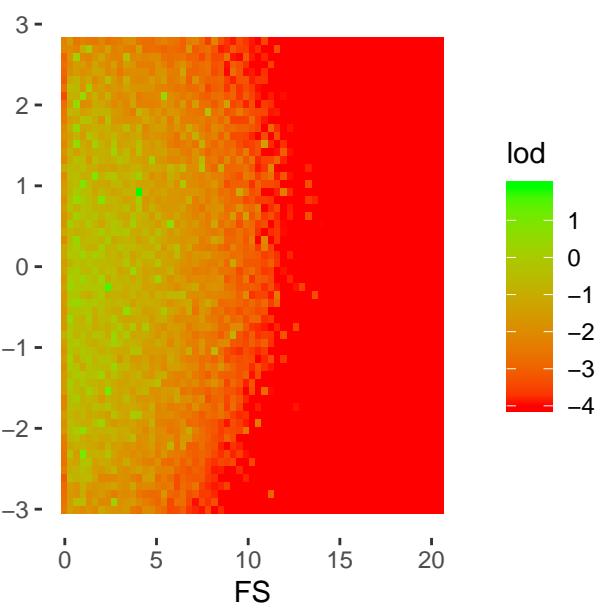


model PDF

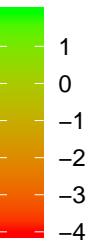


model PDF

ReadPosRankSum



lod



0 5 10 15 20
FS

3

2

1

0

-1

-2

-3

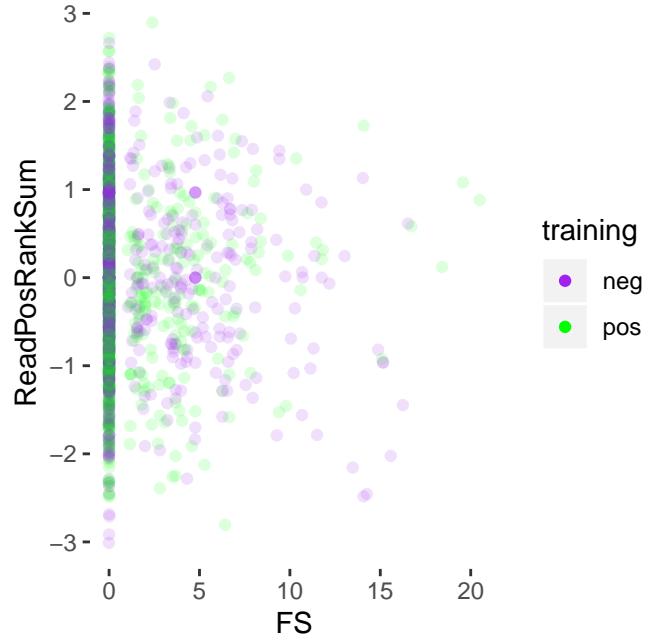
-2 -1 0 1 2 3
ReadPosRankSum

0 5 10 15 20
FS

outcome

- filtered (red circle)
- retained (black circle)

ReadPosRankSum



training

- neg (purple)
- pos (green)

0 5 10 15 20
FS

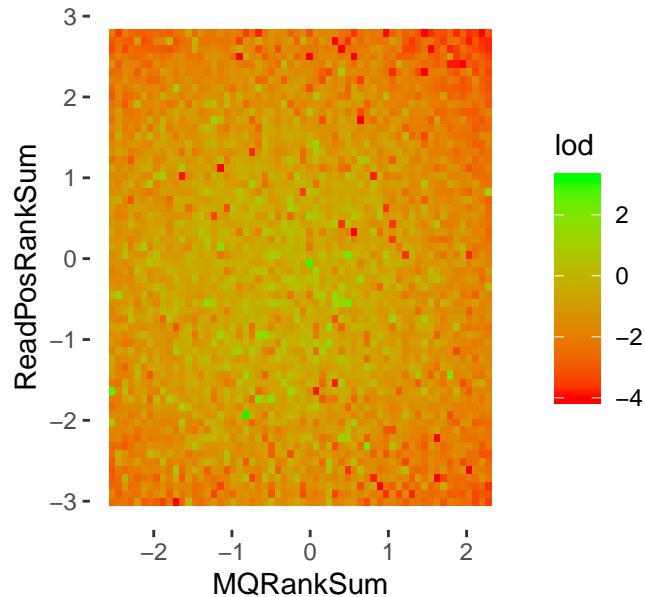
3 2 1 0 -1 -2 -3
ReadPosRankSum

0 5 10 15 20
FS

novelty

- novel (red)
- known (blue)

model PDF



3 -

ReadPosRankSum

2 -

1 -

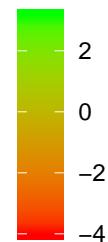
0 -

-1 -

-2 -

-3 -

lod



2
0
-2
-4

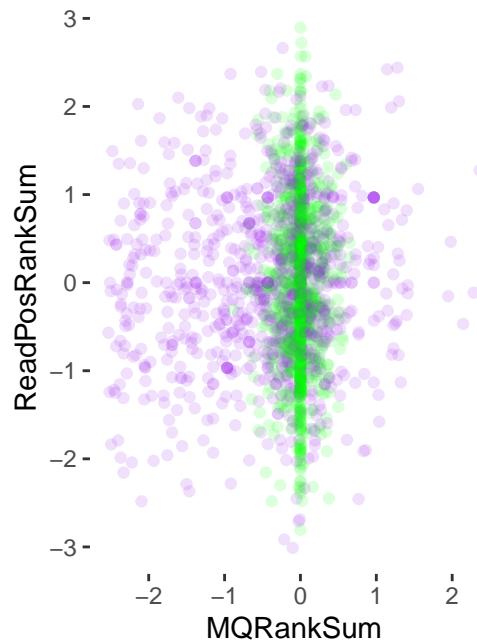
-2 -1 0 1 2

MQRankSum

outcome



● filtered
● retained



training



novelty



● novel
● known

