

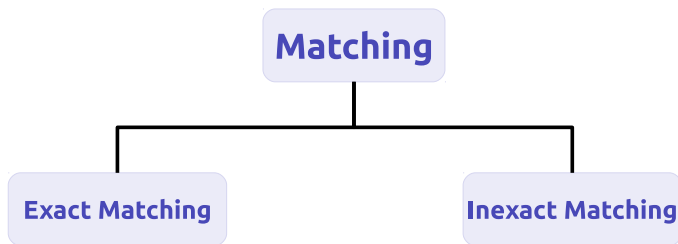
Graph Matching - Algorithms

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Overview

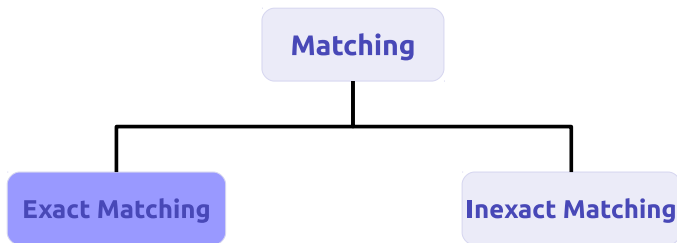


Goals

Exact Matching: Find an *edge preserving* mapping.

Inexact Matching: Find a mapping that minimizes matching costs.

Exact Matching



Exact Matching Complexity

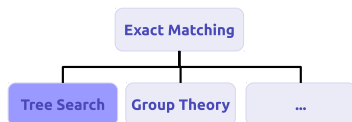
Graph Isomorphism : In NP, but unknown if P or NP complete.

Subgraph Isomorphism, Monomorphism, MCS... : NP complete.

There exists algorithms for special graphs with polynomial runtime.

Exact Matching

Tree-Search approach



Basic Idea

- Iteratively expand partial match by adding new pairs of matched nodes.
- The pair is chosen using some necessary conditions.
- Prune unfruitful search paths.
- If no further vertex pairs may be added due to constraint, undo last additions (backtracking)
- Algorithm stops if match has been found or all matchings that satisfy the constraints has been tried.

Exact Matching

Ullmann's Algorithm [J.R. Ullmann 1976]

- Tree-Search algorithm (Depth-Search-First)
- Uses adjacency matrices and additional constraints for matching and pruning.
- Application for graph isomorphism, subgraph isomorphism and monomorphism, also for MCS problem

Exact Matching

Ullmann's Algorithm

- Given: Two graphs $G_A(V_A, E_A)$ and $G_B(V_B, E_B)$ and their adjacency matrices: A and B
- Idea: $n = |V_a|$, $m = |V_b|$, $n \times m$ permutation matrix M with following form:
 - ▶ M contains only '0' and '1'
 - ▶ Exact one '1' in each row
 - ▶ Not more than one '1' in each column
- Permute adjacency matrix B by multiplying it with M , and compare adjacency.




Exact Matching

Ullmann's Algorithm

- $M \times B$: Move row j to row $i \ \forall M_{ij} = 1$

$$\begin{array}{|c|c|c|} \hline 0 & 1 & 0 \\ \hline 1 & 0 & 0 \\ \hline 0 & 0 & 1 \\ \hline \end{array} \times \begin{array}{|c|c|c|} \hline 0 & 1 & 1 \\ \hline 1 & 0 & 0 \\ \hline 1 & 0 & 0 \\ \hline \end{array} = \begin{array}{|c|c|c|} \hline 1 & 0 & 0 \\ \hline 0 & 1 & 1 \\ \hline 1 & 0 & 0 \\ \hline \end{array}$$

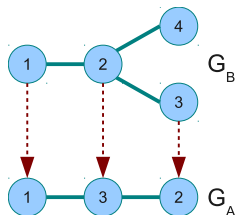
$M = M^T$
 $B = B^T$



- $(MB)^T$: Move column j to column i
- $M(MB)^T$: Move column j to column i and row j to row i

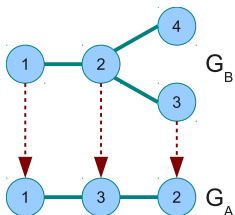
Exact Matching

Ullmann's Algorithm



Exact Matching

Ullmann's Algorithm



0	1	0	0
1	0	1	1
0	1	0	0
0	1	0	0

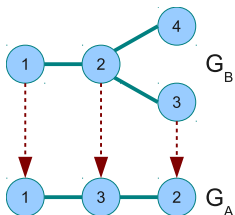
$$B=B^T$$

1	0	0	0
0	0	1	0
0	1	0	0

$$M$$

Exact Matching

Ullmann's Algorithm



0	1	0	0
1	0	1	1
0	1	0	0
0	1	0	0

$$B=B^T$$

1	0	0	0
0	0	1	0
0	1	0	0
0	0	0	0

$$M$$

$$\begin{aligned}
 M(MB)^T &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \times \left(\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \right)^T \\
 &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \\
 &= \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix} = C
 \end{aligned}$$

Exact Matching

Ullmann's Algorithm

Creating pairs of nodes by exchanging rows and columns (renaming).

Adjacency condition

Let $C = M(MB)^T$,

A is a (subgraph-) isomorphism iff

$$A_{ij} = 1 \Rightarrow C_{ij} = 1 \forall i, j$$

How do we get M?

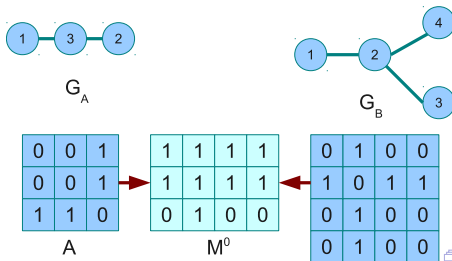
Exact Matching

Ullmann's Algorithm

- Build Startmatrix M^0 by setting all values to 1 (allow all permutations)
- Set values to 0 for all M_{ij}^0 where $\deg(B_j) < \deg(A_i)$ (remove impossible permutations)

$$M_{ij}^0 = \begin{cases} 1 & \text{if } \deg(B_j) \geq \deg(A_i) \\ 0 & \text{otherwise} \end{cases}, \forall i, j$$

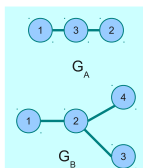
- Generate systematically permutation matrices M^d .



Exact Matching

Ullmann's Algorithm

1	1	1	1
1	1	1	1
0	1	0	0

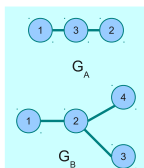


Exact Matching

Ullmann's Algorithm

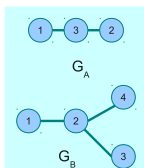
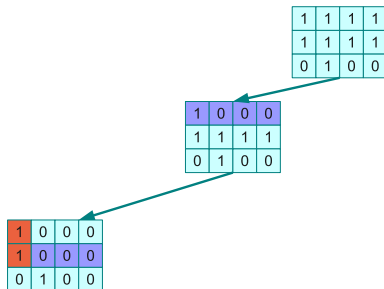
1	0	0	0
1	1	1	1
0	1	0	0

1	1	1	1
1	1	1	1
0	1	0	0



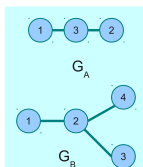
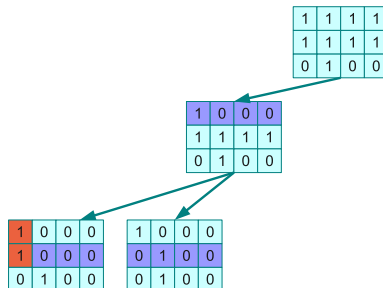
Exact Matching

Ullmann's Algorithm



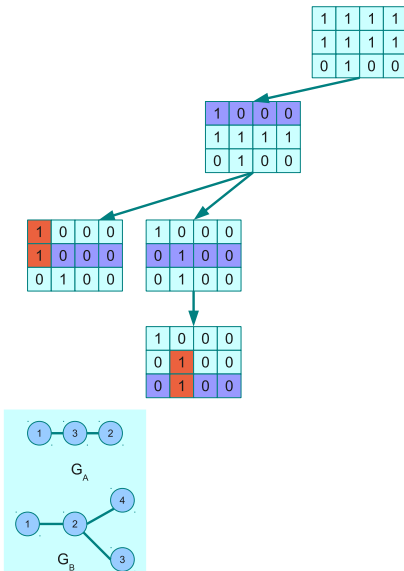
Exact Matching

Ullmann's Algorithm



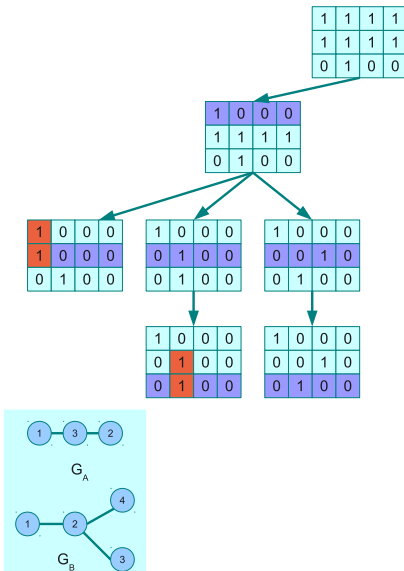
Exact Matching

Ullmann's Algorithm



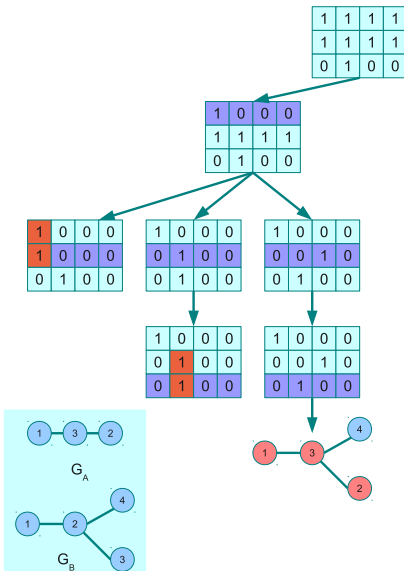
Exact Matching

Ullmann's Algorithm



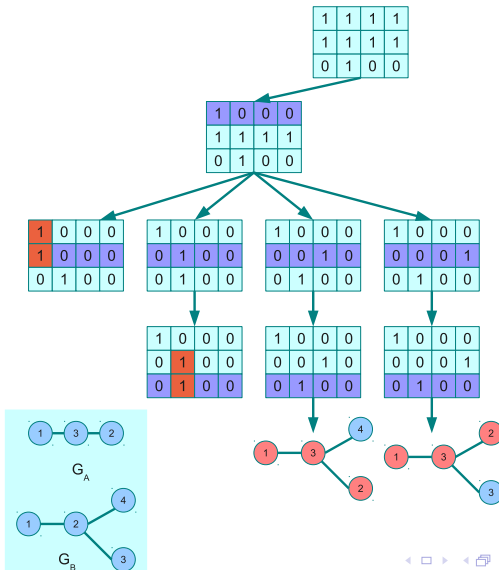
Exact Matching

Ullmann's Algorithm



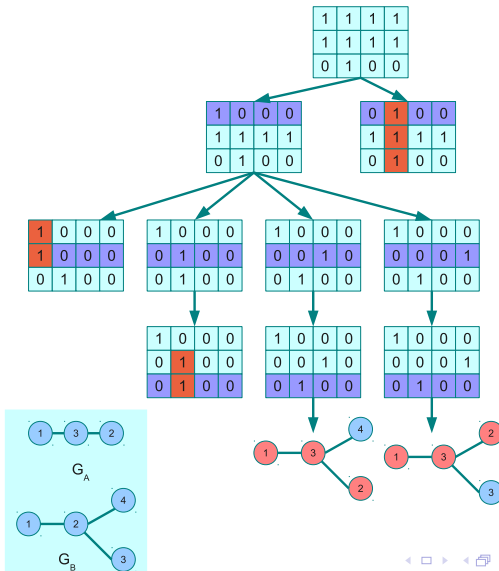
Exact Matching

Ullmann's Algorithm



Exact Matching

Ullmann's Algorithm



Exact Matching

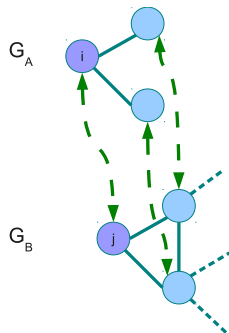
Ullmann's Algorithm V2

Refinement Procedure:

- For all neighbours in A there must be proper neighbours in B.
- Formally:

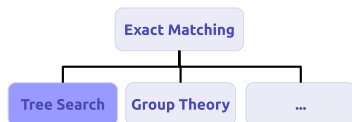
$$\forall k(A_{ik} = 1 \Rightarrow \exists p(M_{kp}B_{pj} = 1))$$

- Set $M_{ij}^d = 0$ where conditions are not complied.



Exact Matching

Tree-Search approaches

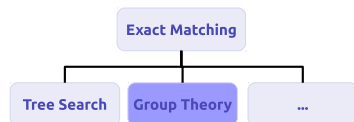


VF and VF2 algorithm

- Application for isomorphism and subgraph isomorphism
- VF algorithm defines a heuristic based on the analysis of the sets of nodes adjacent to the ones already considered in the partial mapping.

Exact Matching

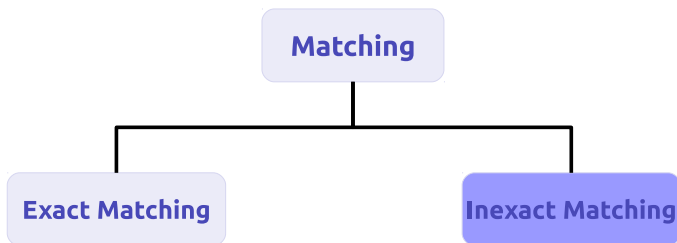
Group theory approach



McKay's Nauty

- Nauty - No automorphisms, yes?
- Application for isomorphism only
- It uses the property that the canonical labeling for isomorph graphs is identical.
- It constructs the automorphism group of each of the input graphs and derives a canonical labeling

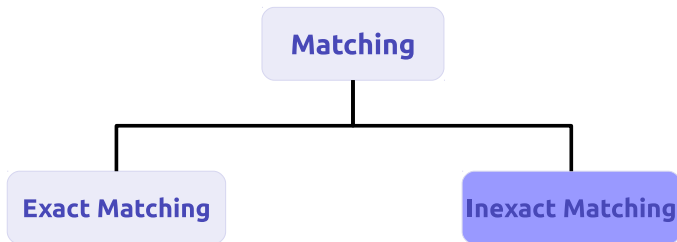
Inexact Matching



Reasons for using inexact matching

- Deformations in graphs (eg. noise, variability of patterns, nondeterministic elements...)
- Exact matching too expensive

Inexact Matching

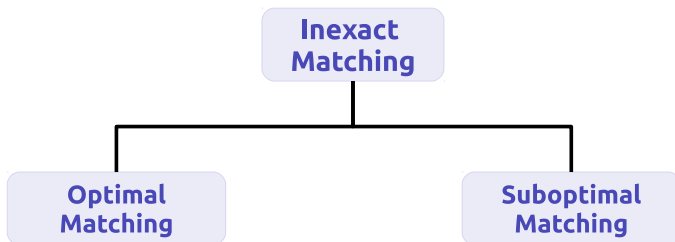


How

- Relax constraints - no edge preserving.
- Penalize graph differences.
- Find a mapping that minimizes matching costs.

Inexact Matching

Optimal and suboptimal inexact matching algorithms



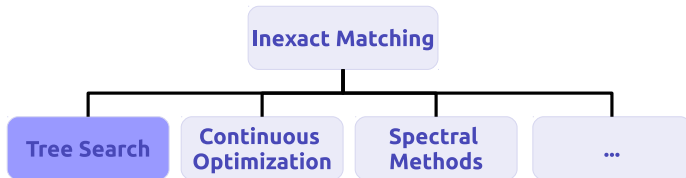
Runtime

Optimal Inexact Matching : More expensive than exact algorithms.

Suboptimal Inexact Matching : Usually polynomial matching time.

Inexact Matching

Tree-Search approaches



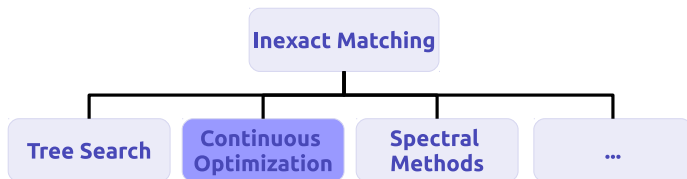
Tree Search with Backtracking

- Search guided by cost function.
- Heuristic estimate matching cost for remaining nodes.
- Prune unfruitful paths.



Inexact Matching

Continuous optimization approaches

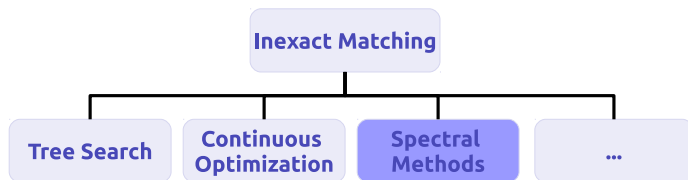


Continuous Optimization

- Idea:
 - ▶ Convert discrete optimization problem to a continuous, nonlinear optimization problem.
 - ▶ Use a nonlinear optimization algorithm.
 - ▶ Convert back to graph matching domain.
- Suboptimal Matching
- Polynomial Runtime

Inexact Matching

Spectral methods



Spectral Methods

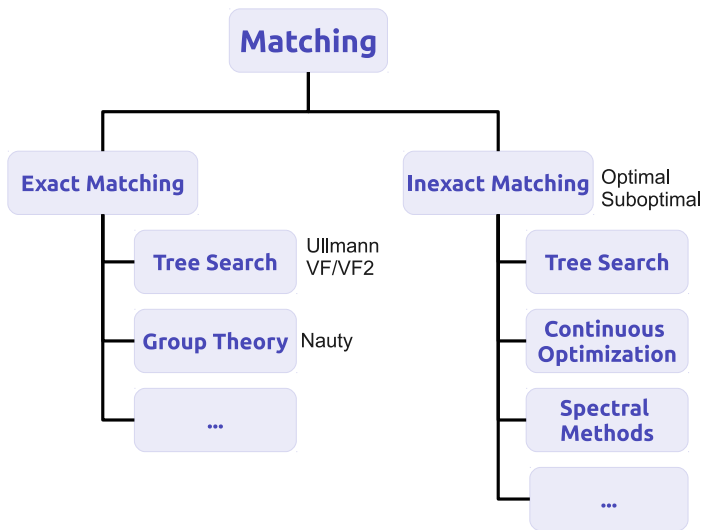
Uses property, that

- Eigenvalues and eigenvectors of adjacency matrix of a graph are invariant to node permutations.

- G_1, G_2 isomorph \Rightarrow

$$EW(Adj(G_1)) = EW(Adj(G_2)) \wedge EV(Adj(G_1)) = EV(Adj(G_2))$$

Recall



Literature

- D.Conte, *Thirty Years Of Graph Matching in Pattern Recognition*, International Journal of Pattern Recognition and Artificial Intelligence, Vol. 18, No. 3, p.265-298, (2004)
- Riesen K. Jiang X., Bunke H., *Exact and Inexact Graph Matching: Methodology And Applications*, Managing and Mining Graph Data, p.217-247, Springer Verlag (2010)

Thank you for your attention!

Questions?

