

Architecture & Design of Embedded Real-Time Systems (TI-AREM)

SW Architecture Styles and Two-Part Architecture Model

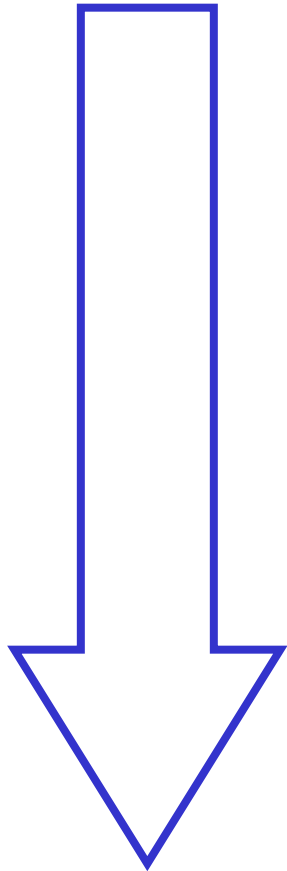
Agenda

State of the Art for SW architecture

- Architectural Styles
 - Pipes and Filters
 - Two-part architecture model

State of the Art for SW Architecture

High level



Low level

- **Architectural Styles**
 - Styles dominates a given architecture
 - Examples: Pipes and Filters, Layered Architectural Structure, Two-part architecture model
- **Architectural Patterns**
 - Address “System-wide” design problems
 - Are not dominating and are often combined with other design patterns
 - Examples: concurrency, persistency and memory p.
- **Design Patterns (GoF) – Mechanistic Design**
 - Design patterns have often a more local effect
 - Examples: Strategy pattern, State Pattern
- **Idioms**
 - Language near patterns and mechanism
 - Examples: Counted pointer for C++

Architectural Styles (Shaw&Garlan)(1)

- Five categories of **Architectural Styles**:
 - Dataflow systems
 - Batch sequential, **Pipes and filters**
 - Call-and-return systems
 - **OO systems**, Main program and subroutine, Hierarchical layers
 - Independent components
 - **Event systems**, Communicating processes
 - Virtual machines
 - Interpreters, Rule-based systems
 - Data-centered systems (repositories)
 - Databases, Hypertext systems, Blackboards

Architectural Styles (Shaw&Garlan)(2)

- Examples of **Architectural Styles**:
 - **Pipes and filters**
 - Data abstraction and Object-Oriented organization
 - **Event-based**, implicit invocation
 - Layered systems
 - Examples:
 - OSI model
 - Business oriented systems: presentation, business logic and model layer
 - Repositories
 - Interpreters
 - **Process control**

Buschmann's three Pattern Categories

Architecture patterns:

- Layers
 - Pipes & Filters
 - Blackboard
 - Broker
 - Model-View-Controller
 - Presentation-Abstraction-Control (PAC)
 - Microkernel
 - Reflection
- Shaw & Garlan Styles**

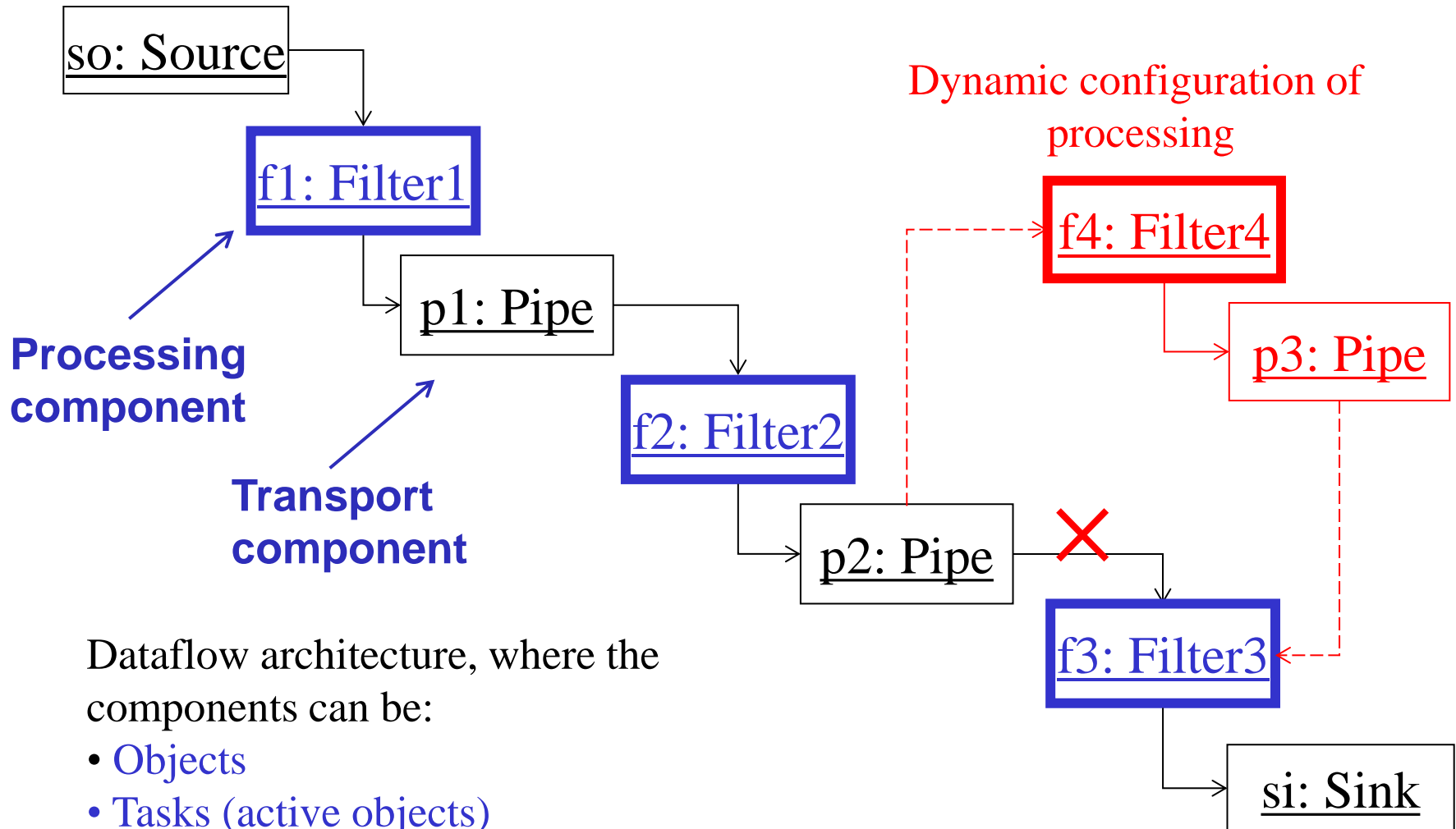
Design Patterns:

- Observer (GoF)
- Publisher-subscriber
- Strategy (GoF)
- Composite (GoF)
- Abstract Factory (GoF)
- Bridge (GoF)
- Proxy (GoF)
- Command Processor
- View Handler
- Master-slave

Idioms:

- Singleton (GoF)
- Factory Method (GoF)
- Counted pointer, Handle-Body
- Envelope-Letter

Pipes & Filters Architecture Style



Pipes and Filters Structure (CRC)

CRC= Class, Responsibility and Collaboration

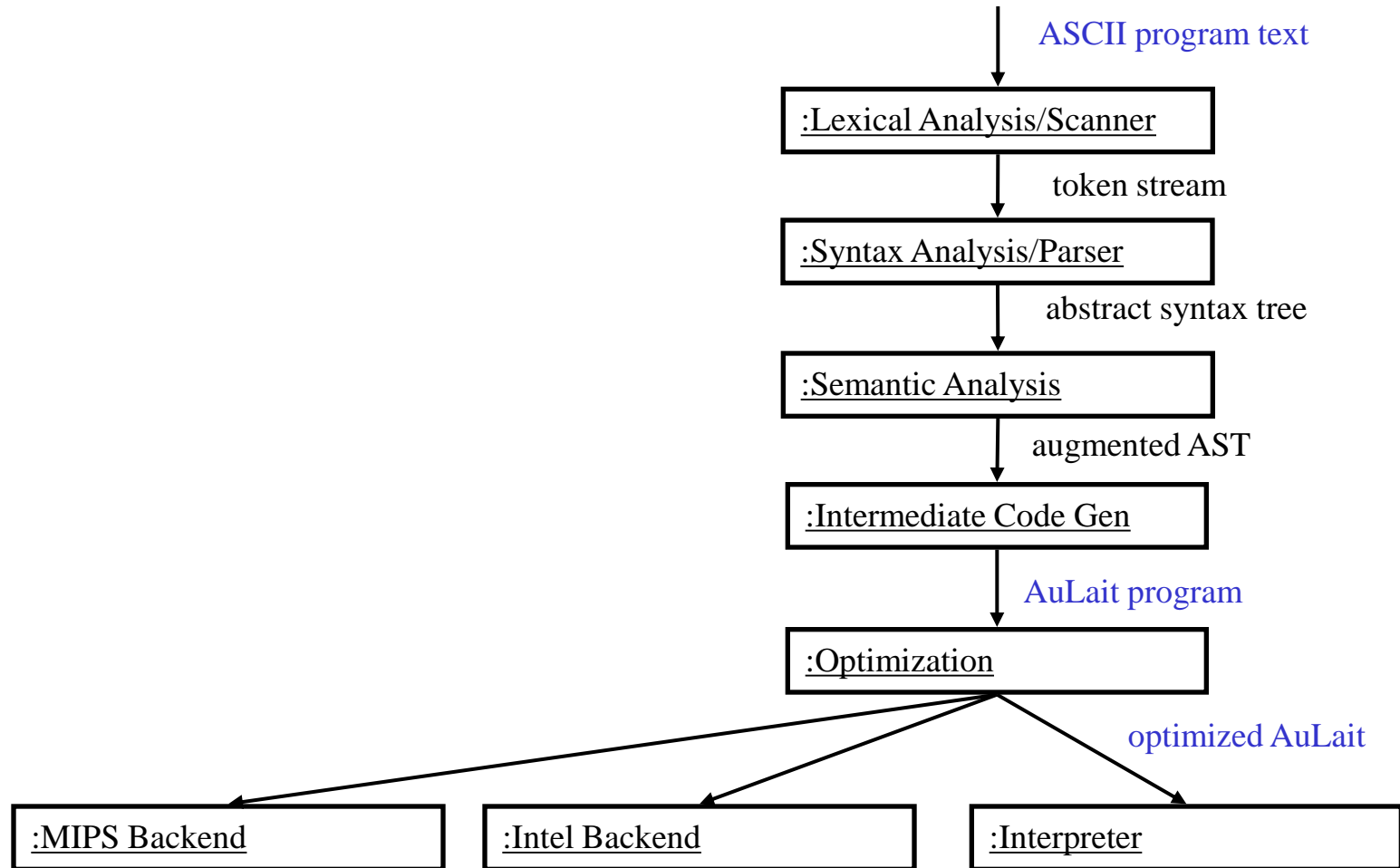
<i>Class</i> Filter	<i>Collaborators</i>
<i>Responsibility</i> Get input Perform function Set output	Pipe

<i>Class</i> Pipe	<i>Collaborators</i>
<i>Responsibility</i> Transfer data Buffer data and synchronize filters	Data Source Data Sink Filter

<i>Class</i> Data Source	<i>Collaborators</i>
<i>Responsibility</i> Deliver input to processing pipeline	Pipe

<i>Class</i> Data Sink	<i>Collaborators</i>
<i>Responsibility</i> Consumes output	Pipe

Pipes and Filters: Mocha Compiler Example

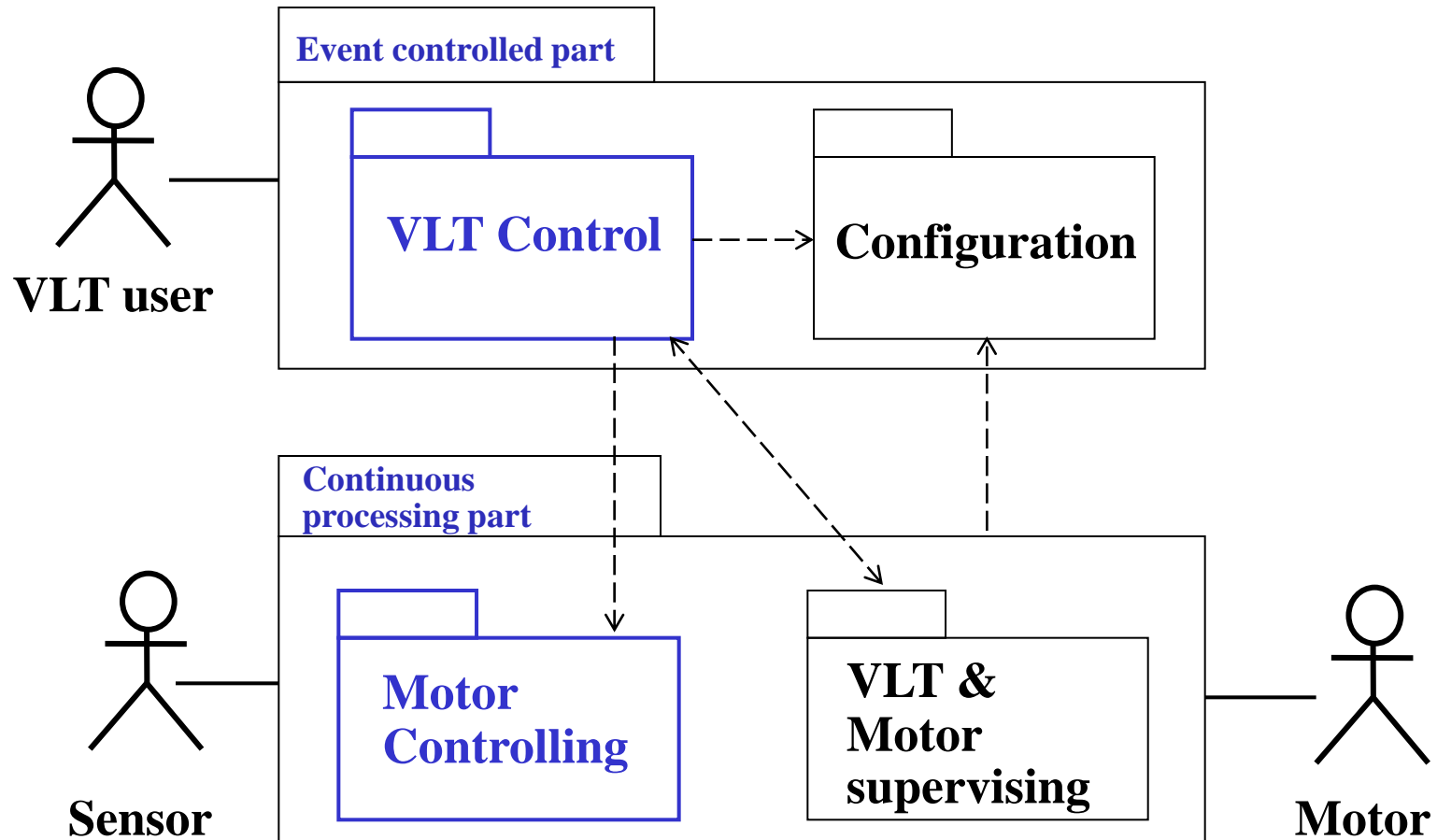


Two-Part Architecture Model Style

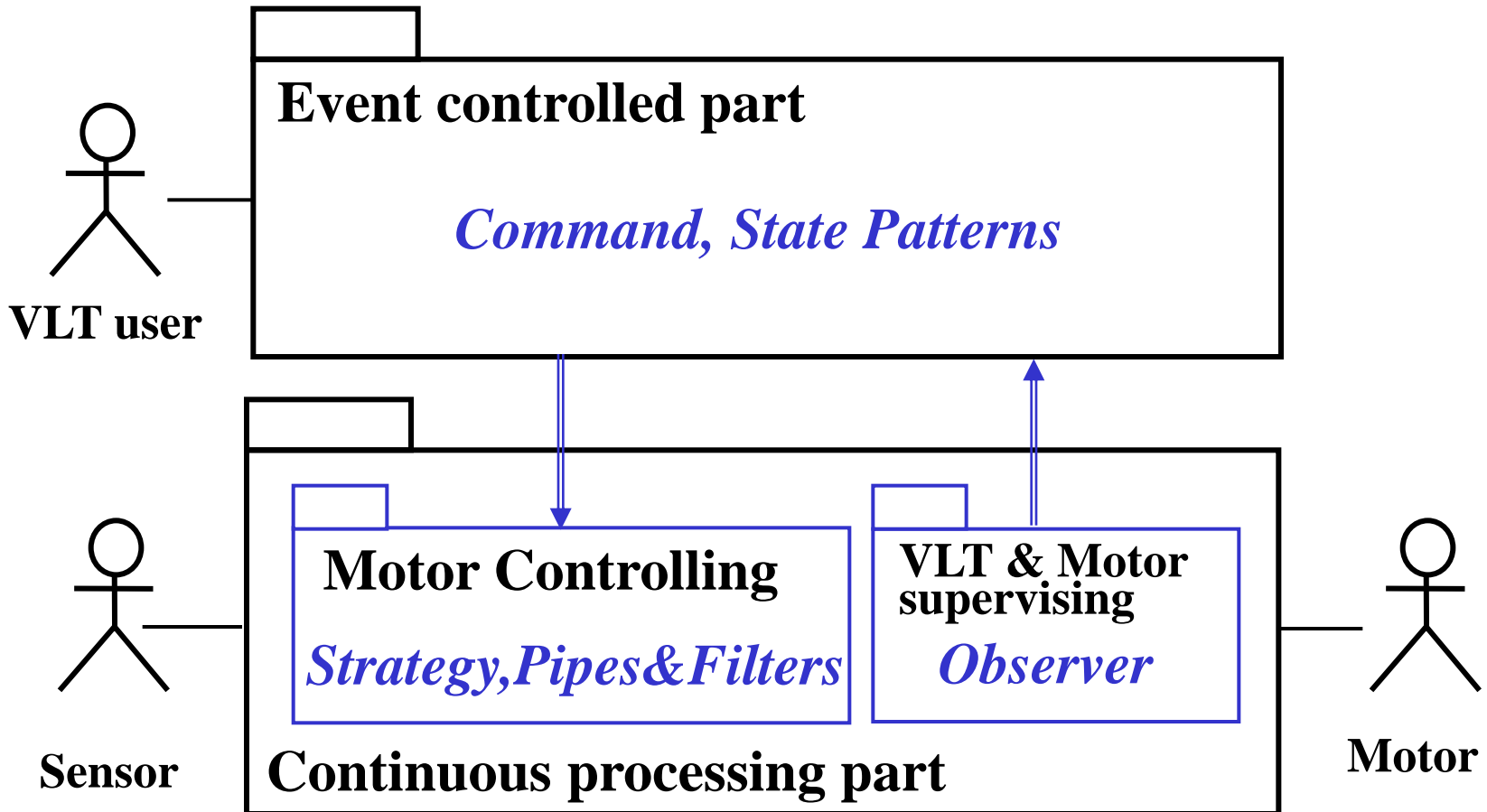
- Combines the following two ***Shaw&Garlan Architectural Styles***:
 - Event-based
 - Process Control (plus *pipes & filters* internal)
- This combination can be used for many embedded systems
- Examples:
 - control and regulation e.g. a frequency converter for controlling a motor
 - measuring instruments e.g. an oscilloscope or a noise-meter
 - audio/video: e.g. a CD player

Two Part Architectural Model Example

Danfoss frequency converter (called a VLT)

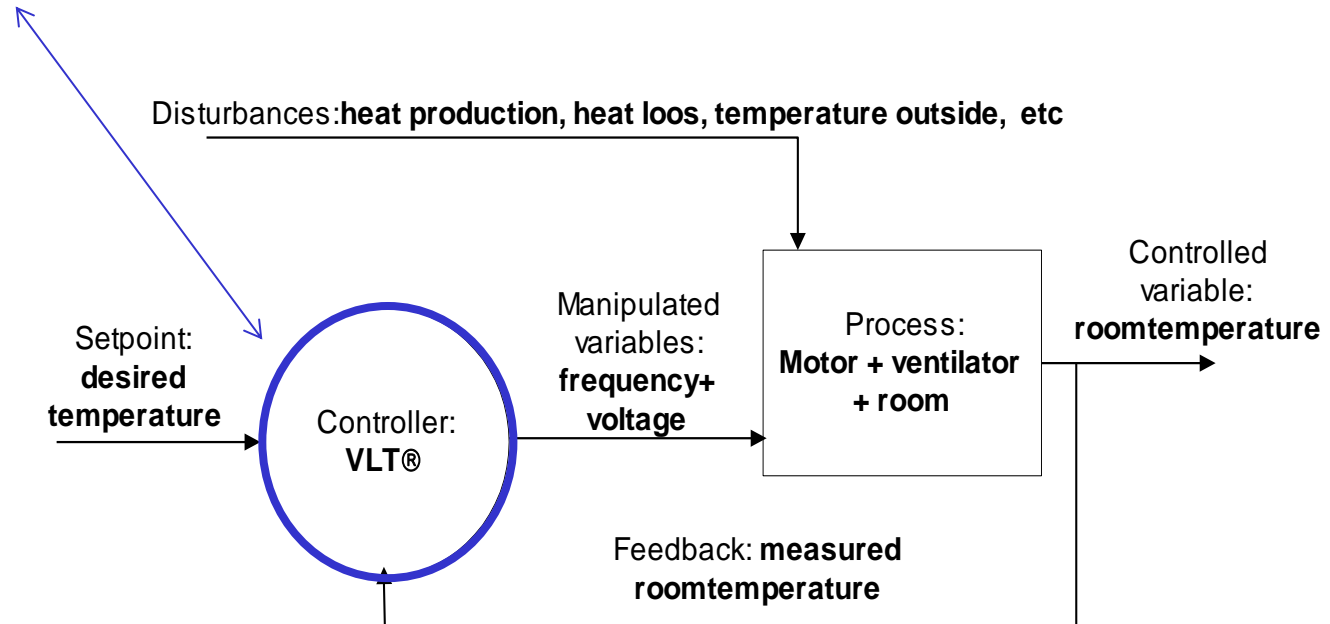


Used Design Patterns in the OO-VLT



Ventilator Control as Process Control Style

Danfoss frequency converter (VLT)

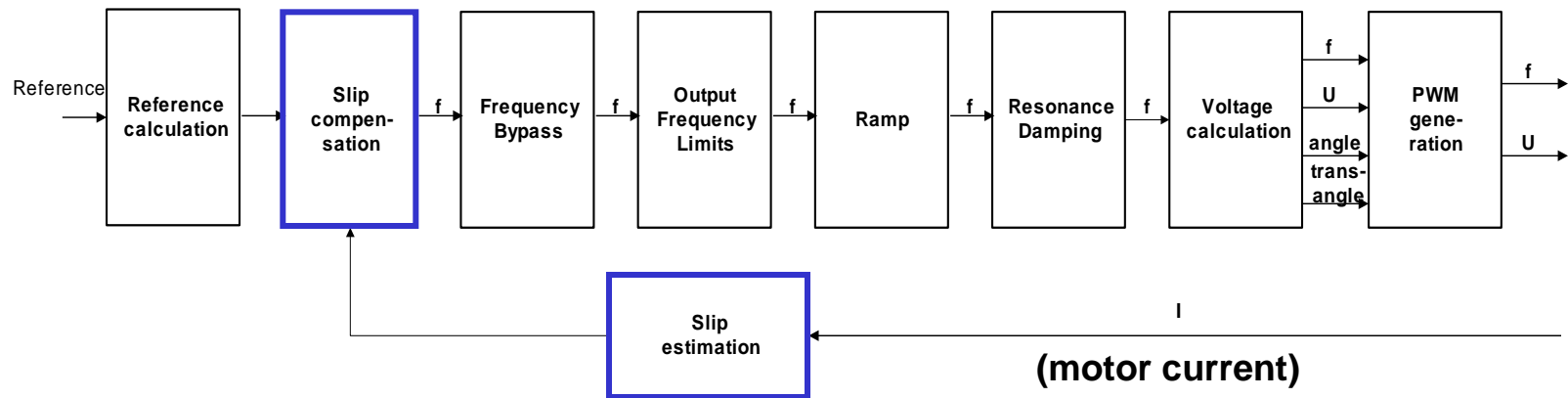


Example of “*closed-loop feedback*” control
Shaw & Garlan: Process Control Style

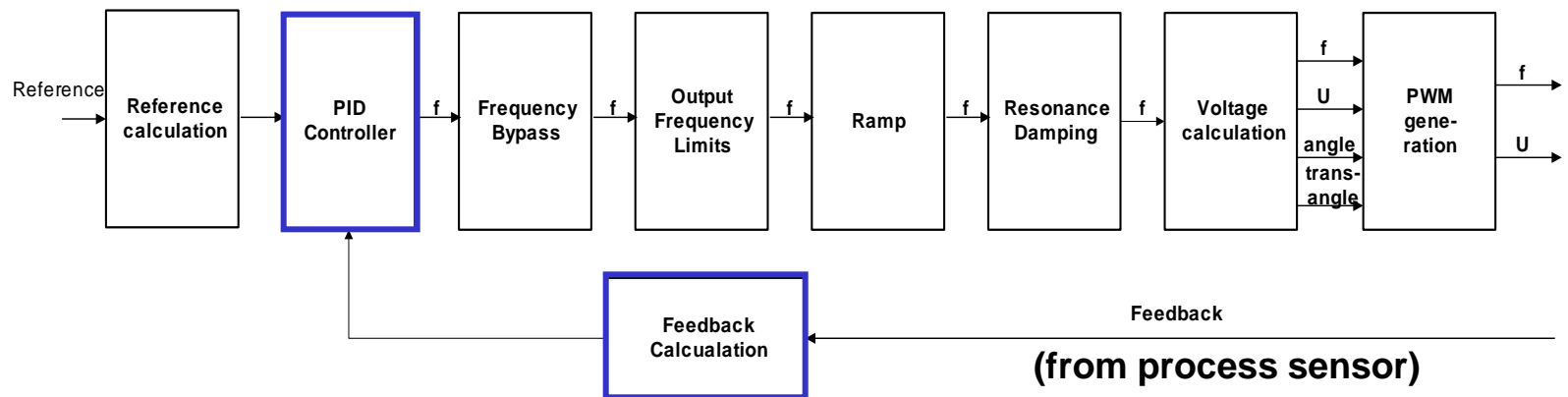
Frequency Converter Example

Block Diagrams with two different operating modes

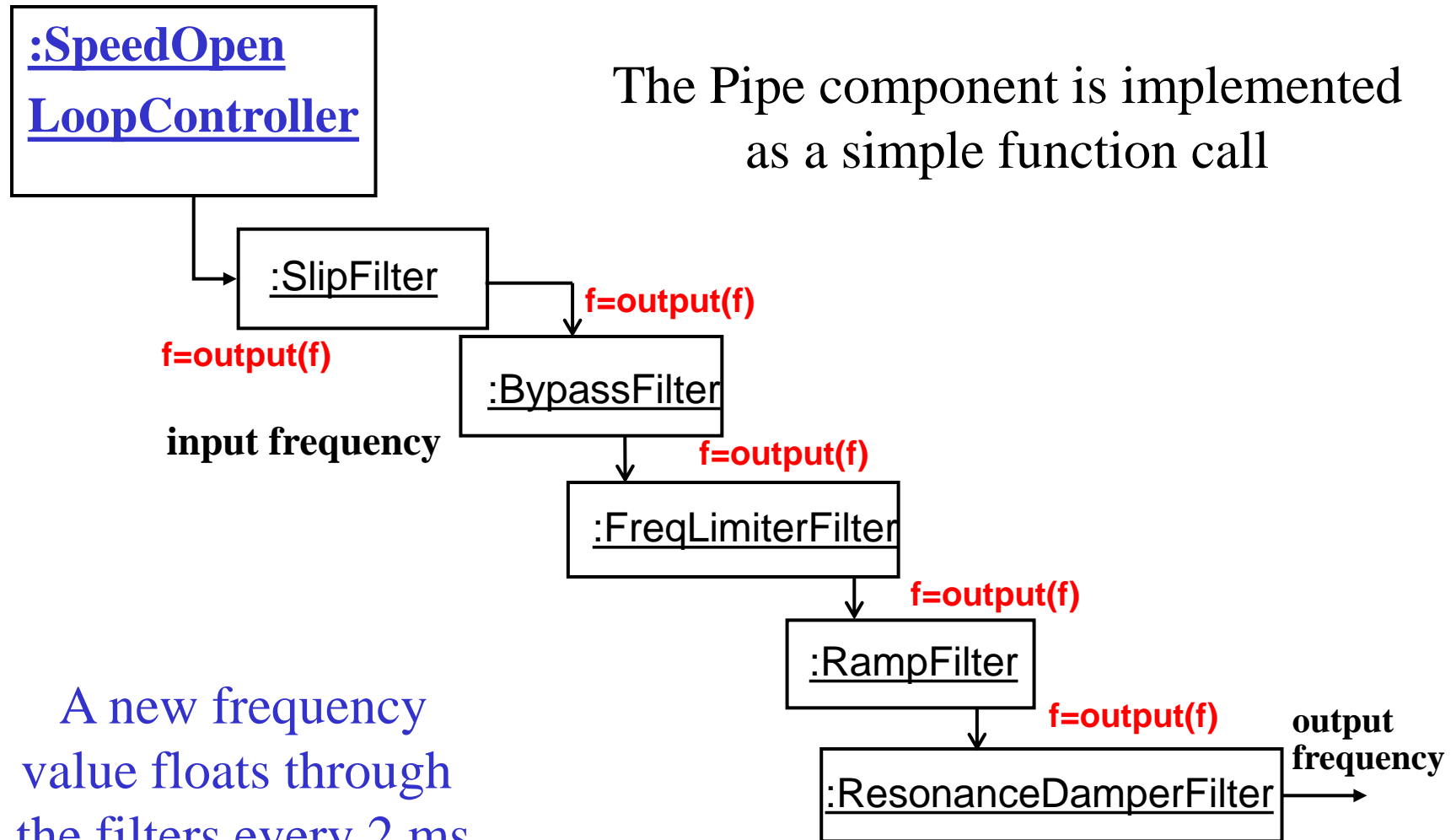
Speed Open loop controller:



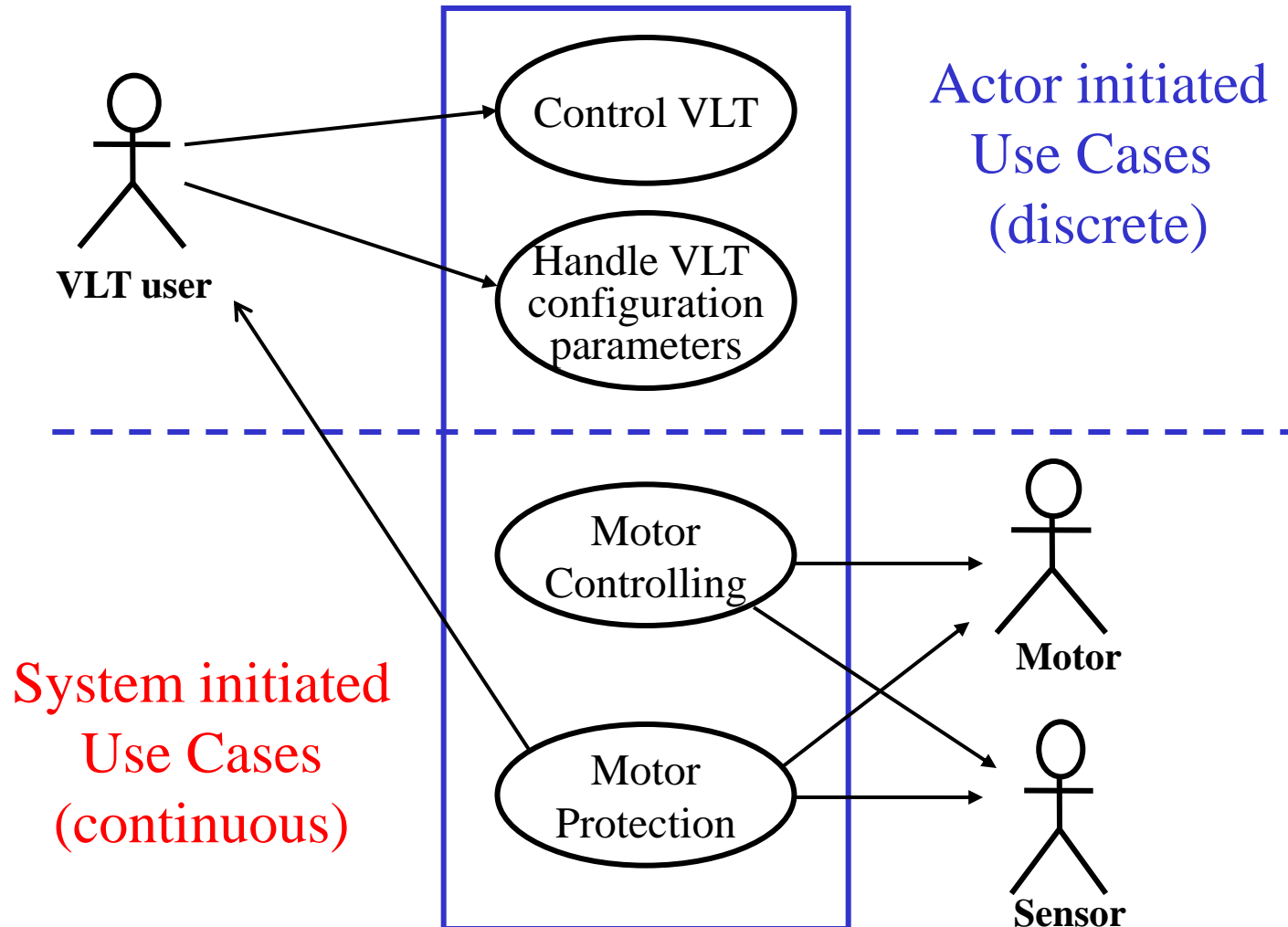
Process Closed Loop controller:



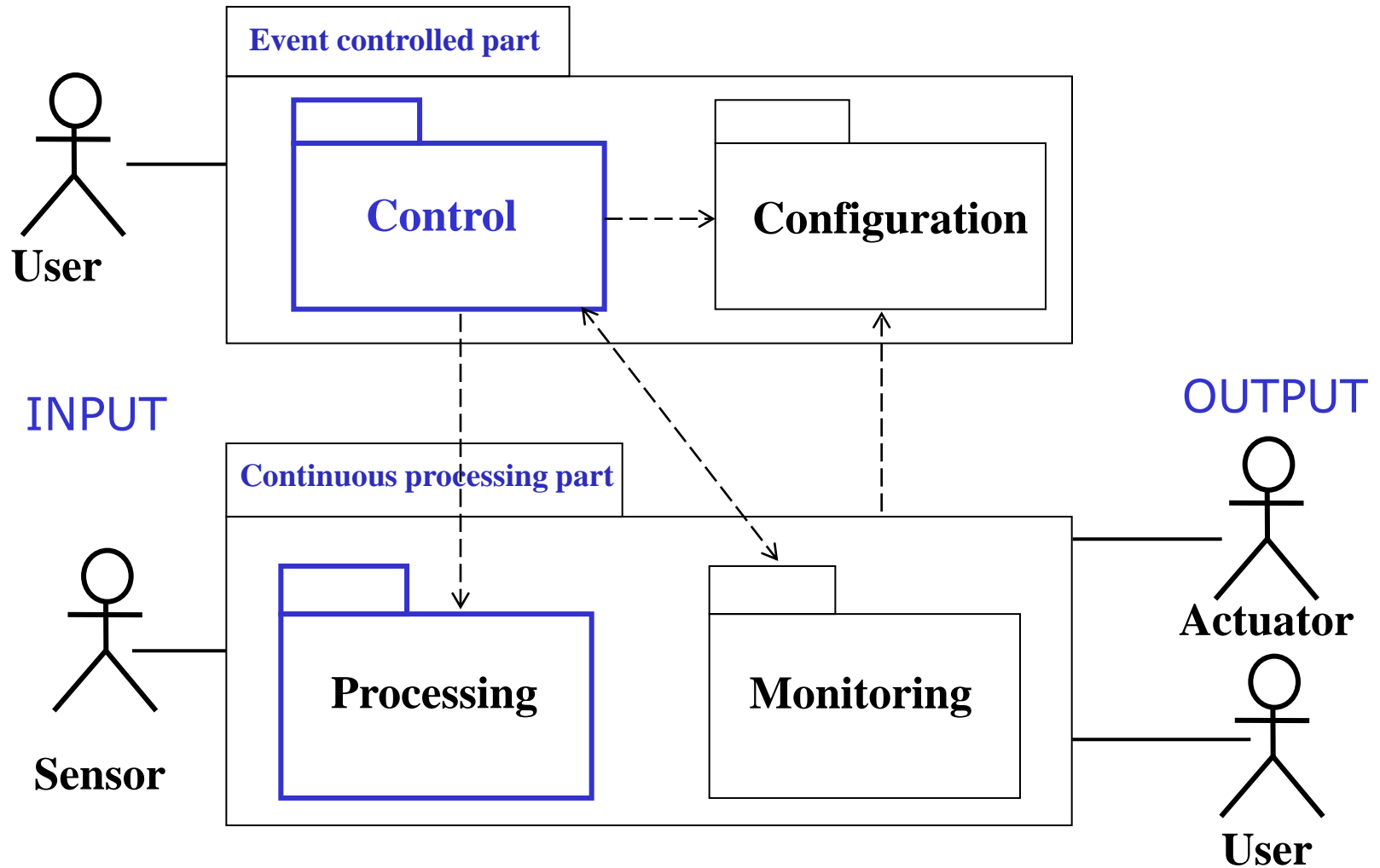
Object Diagram for SpeedOpenLoopController



Two types of VLT Use Cases



Architectural Style: Two-Part Architecture Model



Development towards a Framework

- The **first version** of the frequency converter software was developed for one specific type of frequency converters, where motor signals were generated by an ASIC (Application Specific Integrated Circuit)
- The SW architecture was defined by an OO model and implemented in C++
- A lot of existing C-code (i.e. ~80%) was wrapped in OO Wrapper classes
- The **second version** was modified for another frequency converter type, where the motor signals were generated by a DSP (Digital Signal Processor)
- Part of the architecture was modified, but the main architecture ideas, based on the two-part architecture model, was kept as the basic architecture
- The software has been developed towards a framework for motor controlling software, to be used for a whole family of frequency converters

Summary

- Architecture Styles and examples
 - Pipes and Filtes
 - Two-part architecture model for embedded systems

References

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