

# Architecture and Design of Embedded Real-Time Systems (TI-AREM)

GoF State Pattern - Updated a Behavioral Pattern

Version: 25-2-2015



#### State Pattern – Behavioral Pattern

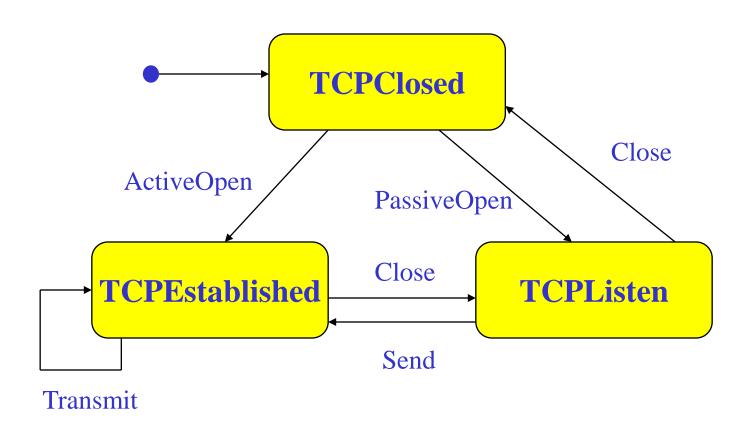
#### **Intent:**

Allow an object to alter its behavior when its internal state changes. The object will appear to change its class (its state).

An implementation technique for realizing a state machine described by a UML State Diagram. Each state is implemented as a class with the events as operations.

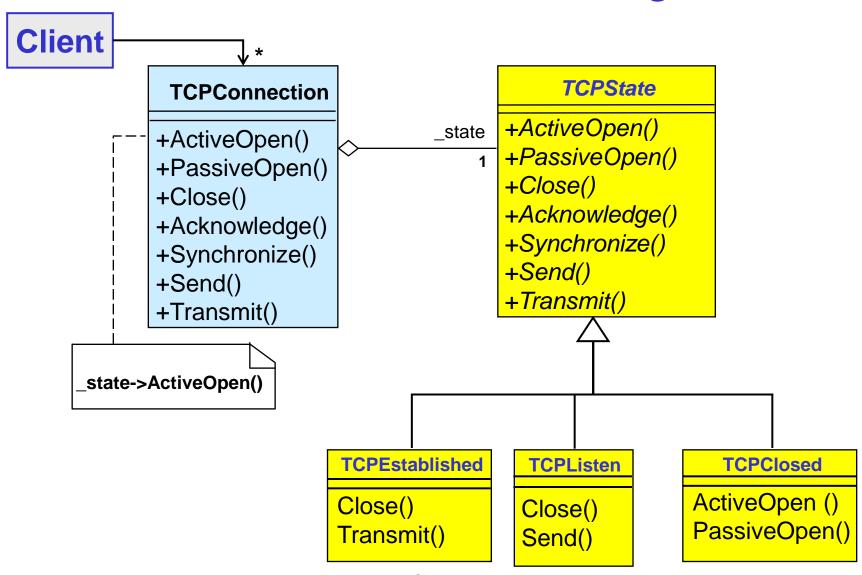


## TCP State Diagram Example



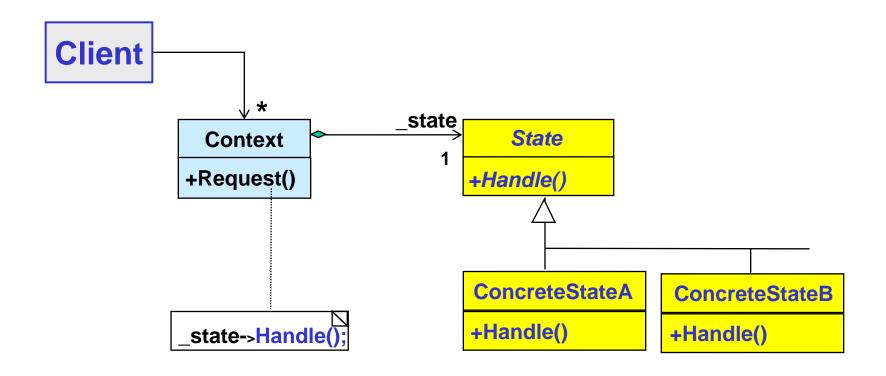


## State Pattern Class Diagram



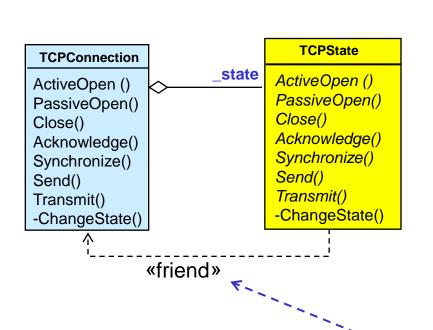


#### State Pattern - GoF Structure





## State Pattern – C++ Example (1)



```
class TCPConnection
 public:
   TCPConnection(); // constructor
   void ActiveOpen();
   void PassiveOpen();
   void Close();
   void Acknowledge();
   void Synchronize();
   void Send();
   void Transmit();
   void ProcessOctet(TCPOctetStream*);
 private:
   friend class TCPState;
   void ChangeState(TCPState*);
   TCPState* _state;
Slide 6
```



## State Pattern – C++ Example (2)

```
{ _state = TCPClosed::Instance(); }
TCPConnection::TCPConnection()
                                          { _state->ActiveOpen(this); }
void TCPConnection::ActiveOpen ()
void TCPConnection::PassiveOpen ()
                                          { _state->PassiveOpen(this); }
void TCPConnection::Close ()
                                          { _state->Close(this); }
void TCPConnection::Acknowledge ()
                                          { _state->Acknowledge(this); }
void TCPConnection::Synchronize ()
                                          { _state->Synchronize(this); }
void TCPConnection::ChangeState (TCPState* s) { _state = s; }
```



## State Pattern – C++ Example (3)

```
class TCPState
                                             Notice!
public:
  virtual void ActiveOpen(TCPConnection*);
  virtual void PassiveOpen(TCPConnection*);
  virtual void Close(TCPConnection*);
  virtual void Acknowledge(TCPConnection*);
  virtual void Synchronize(TCPConnection*);
  virtual void Send(TCPConnection*);
  virtual void Transmit(TCPConnection*, TCPOctetStream*);
protected:
  TCPState() { }
  void ChangeState(TCPConnection*, TCPState*);
};
```



## State Pattern – C++ Example (4)

#### Implementation of **TCPState** with **default code**:

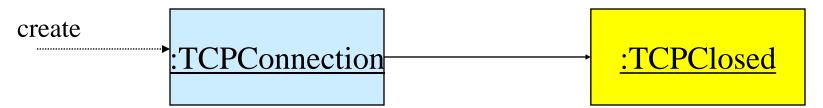
```
void TCPState::ActiveOpen (TCPConnection*)
                                               { default(); }
void TCPState::PassiveOpen (TCPConnection*)
                                               { default(); }
void TCPState::Close (TCPConnection*)
                                               { default(); }
void TCPState::Acknowledge (TCPConnection*)
                                               { default(); }
void TCPState::Synchronize (TCPConnection*)
                                               { default(); }
void TCPState::Send (TCPConnection*)
                                               { default(); }
void TCPState::Transmit (TCPConnection*, TCPOctetStream*) { default();}
void TCPState::ChangeState (TCPConnection* t, TCPState* s)
    t->ChangeState(s);
```



## State Pattern – C++ Example (5)

```
TCPConnection::TCPConnection()
{
   _state = TCPClosed::Instance(); // start state
}
```

#### TCPClosed state object





## State Pattern – C++ Example (6)

```
1.1 ActiveOpen→
1 ActiveOpen→
             CPConnection
                                             :TCPClosed
                            ←1.1.2.1 ChangeState
                                   1.1.2 ChangeState
                                                      1.1.1 Instance
 void TCPConnection::ActiveOpen ()
                                               TCPEstablished
   state->ActiveOpen(this);
void TCPClosed::ActiveOpen (TCPConnection* t)
    // send SYN, receive SYN, ACK, etc.
   ChangeState(t, TCPEstablished::Instance()); // state shift
```



## State Pattern – C++ Example (7)

```
void TCPClosed::PassiveOpen (TCPConnection* t)
  ChangeState(t, TCPListen::Instance());
void TCPEstablished::Transmit (TCPConnection* t, TCPOctetStream* o)
  t->ProcessOctet(o);
                             // no state change
void TCPEstablished::Close (TCPConnection* t)
  // send FIN, receive ACK of FIN
  ChangeState(t, TCPListen::Instance());
```



## State Pattern – C++ Example (8)

#### Singleton pattern

```
class Singleton
{
public:
    static Singleton* Instance();
protected:
    Singleton();
private:
    static Singleton* _instance;
};
```

```
Singleton* Singleton::_instance = 0;

Singleton* Singleton::Instance ()
{
    if (_instance == 0)
    {
        _instance = new Singleton;
    }
    return _instance;
}
```



## State Pattern – C++ Example (9)

#### Singleton pattern used on TCPClosed class

```
class TCPClosed: public TCPState
public:
  static TCPState* Instance();
  virtual void ActiveOpen(TCPConnection*);
  virtual void PassiveOpen(TCPConnection*);
protected:
   TCPClosed();
private:
   static TCPState* _instance;
```

```
TCPState*
    TCPClosed::_instance = 0;

TCPState* TCPClosed::Instance()
{
    if (_instance = = 0)
    {
        _instance = new TCPClosed;
    }
    return _instance;
}
```



### State Pattern Implementation Details (1)

#### **TCPState**

ActiveOpen ()
PassiveOpen()
Close()
Acknowledge()
Synchronize()
Send()
Transmit()

#### 1. Design choice 1.

- All event operations specified as pure virtual (C++)
- Requires that all operations are defined in the subclasses (forced by the compiler)
- 2. Design choice 2.
  - All event operations have default implementation in superclass
  - Only necessary to implement event operations for the actual state



### State Pattern Implementation Details (2)

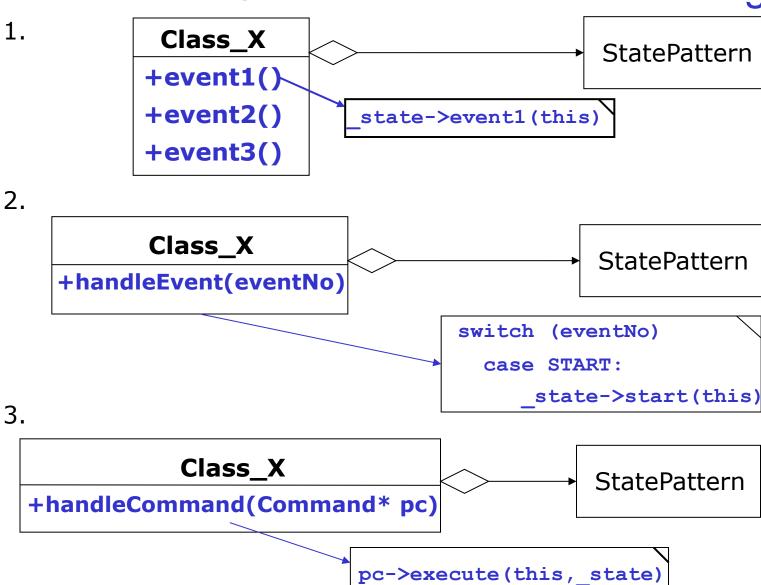
#### Event parameters, guard, entry and exit actions

```
void TCPClosed::event1(TCPConnection* t,type parameter1)
{
    if ( t->guard1() )
    {
        exit(); // explicit call of exit action
        t->action_1();
        ChangeState(t,TCPListen::Instance());
    }
}
```

```
void TCPConnection::ChangeState(State* pS)
{
    _state= pS;
    _state->entry(this); // call "entry" in new state
}
```

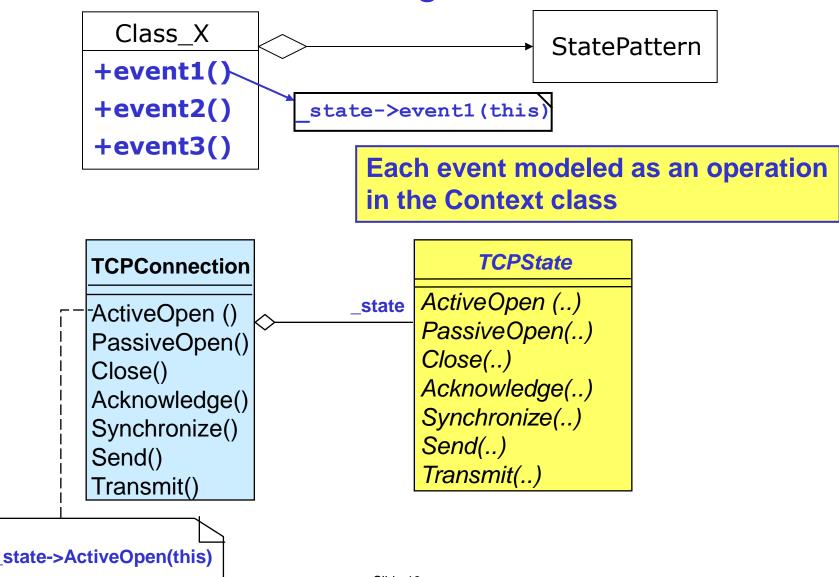


### Three Solutions for Event Handling



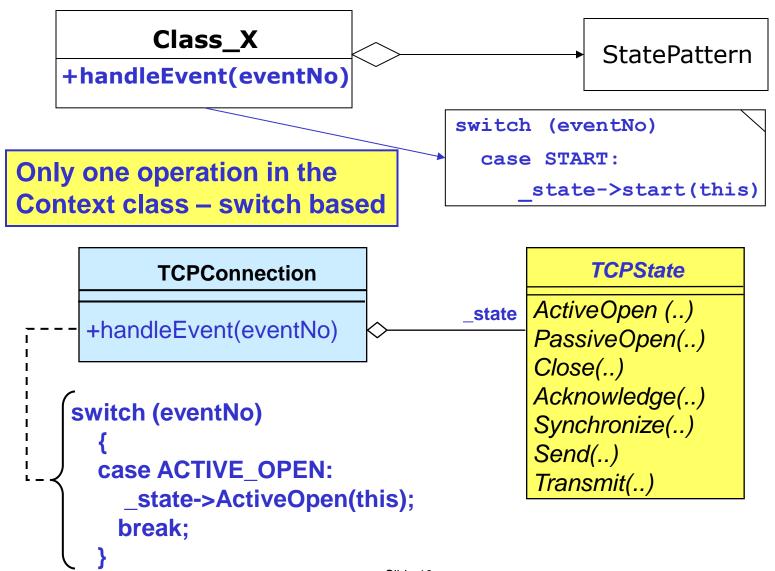


#### Event Handling - Solution 1.



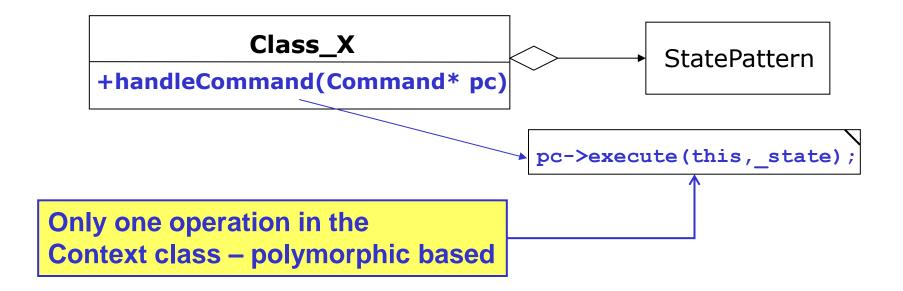


### Event Handling - Solution 2.





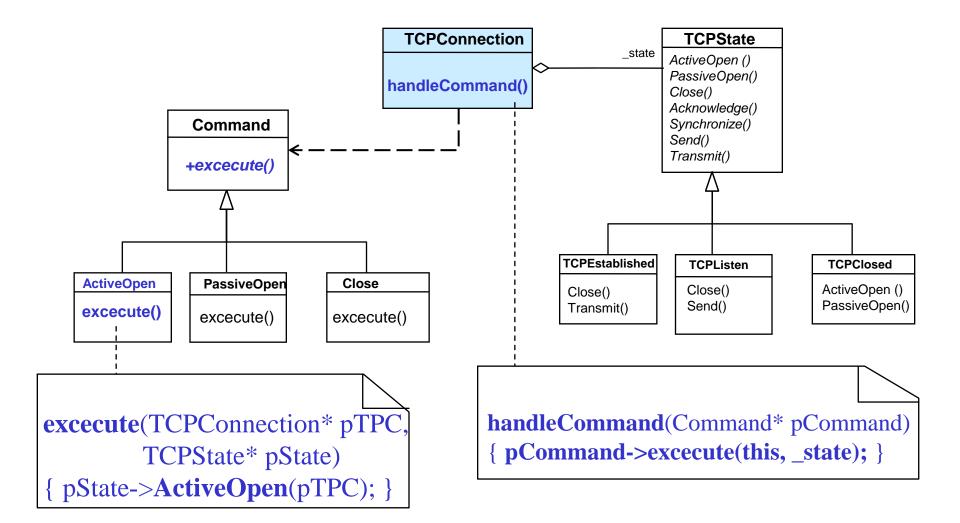
### Event Handling - Solution 3.



An example of the Command Pattern used in concert with the State Pattern

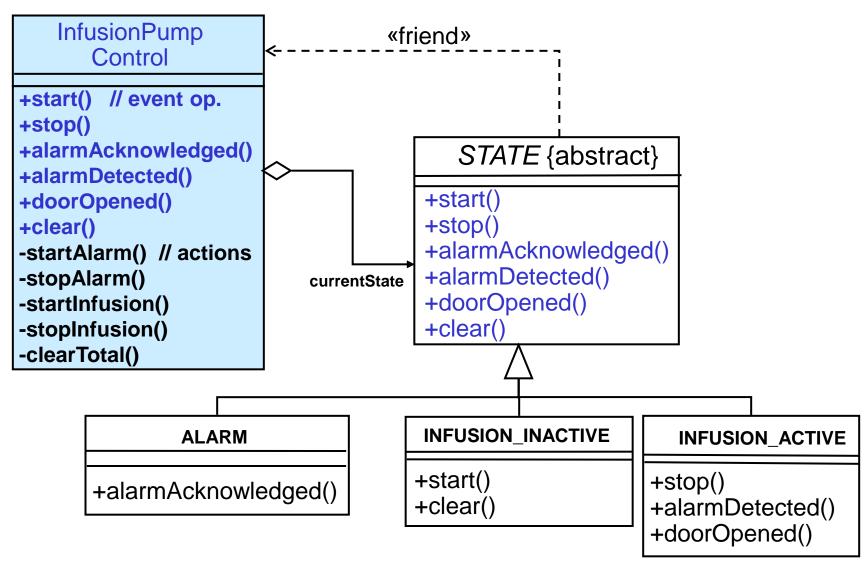


### Command (GoF) & State Pattern (C++)



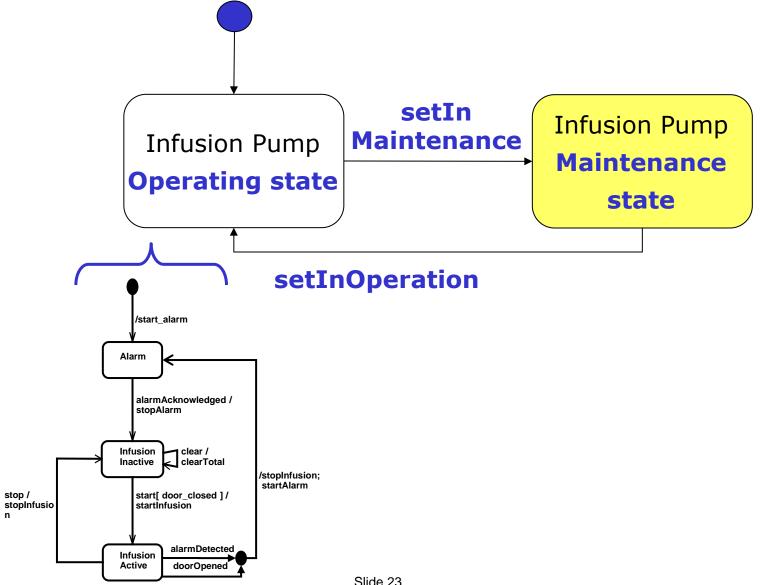


### State Pattern – Infusion Pump Example

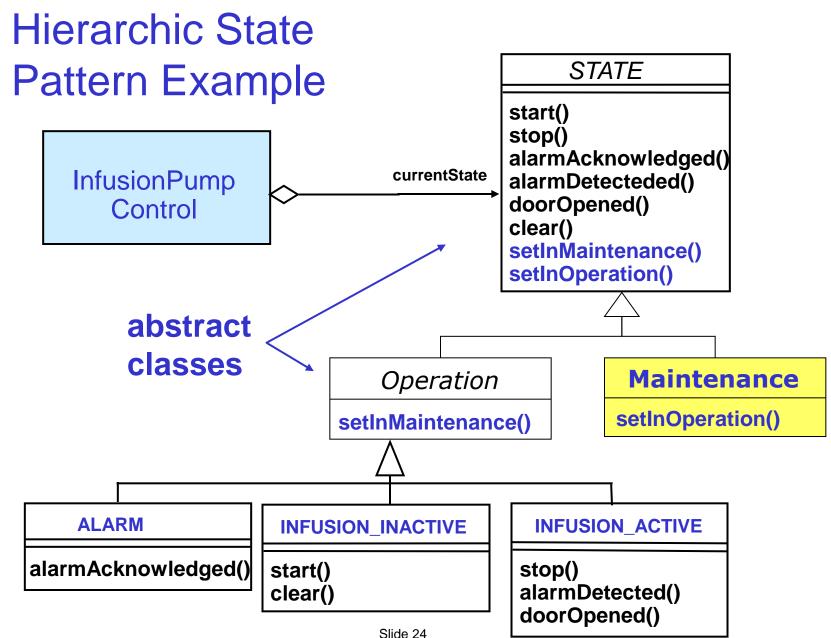




### Example with Hierarchic State Machine (1)

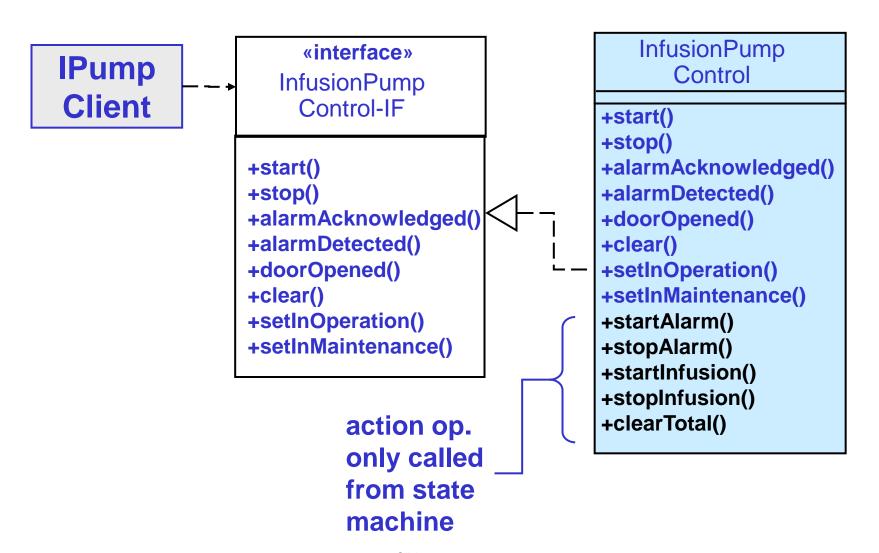








#### Definition of Interface





### Discussion of State Pattern Implementation

#### Disadvantages

- Results in many small classes
- Breaks encapsulation (of the state machine class)

#### Advantages

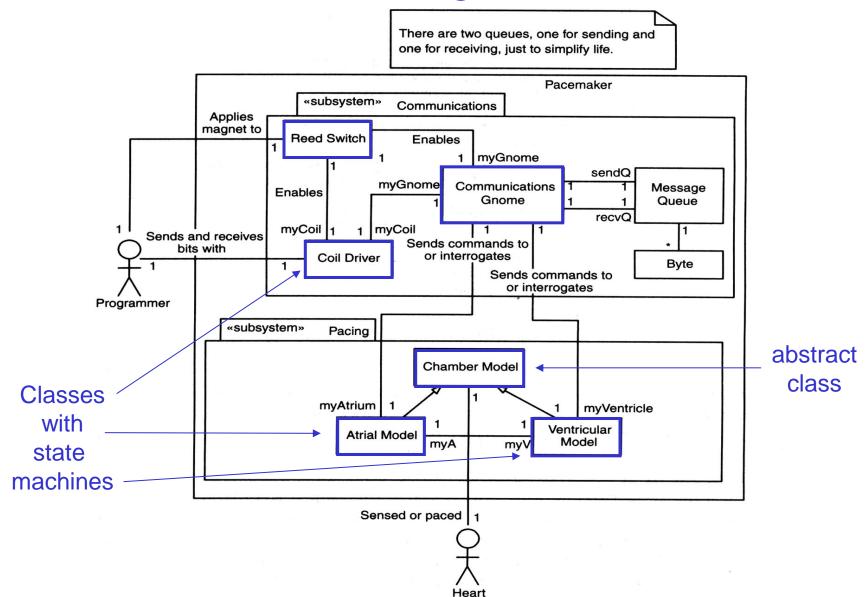
- Easy to implement most UML state diagram notations (guards, event parameters, entry, exit)
- Easy to implement hierarchic state machines
- State Pattern can be reverse engineered from code
- All state handling logic in separate state classes
- Easy to extend with new states

#### Recommendation:

Very useful for nontrivial flat and hierarchical state machines



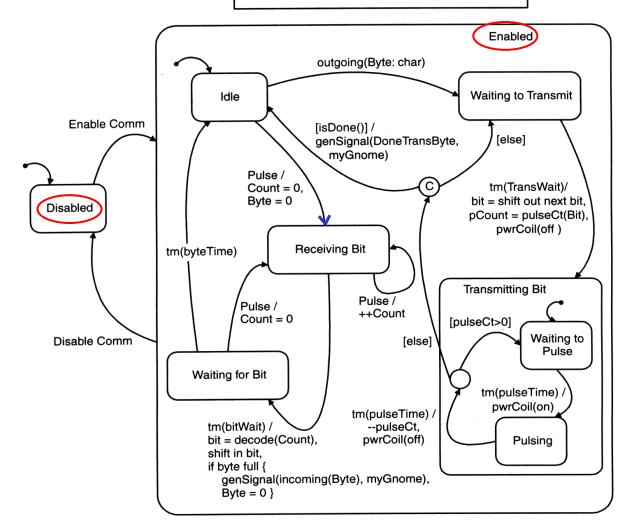
## Pacemaker – Class Diagram





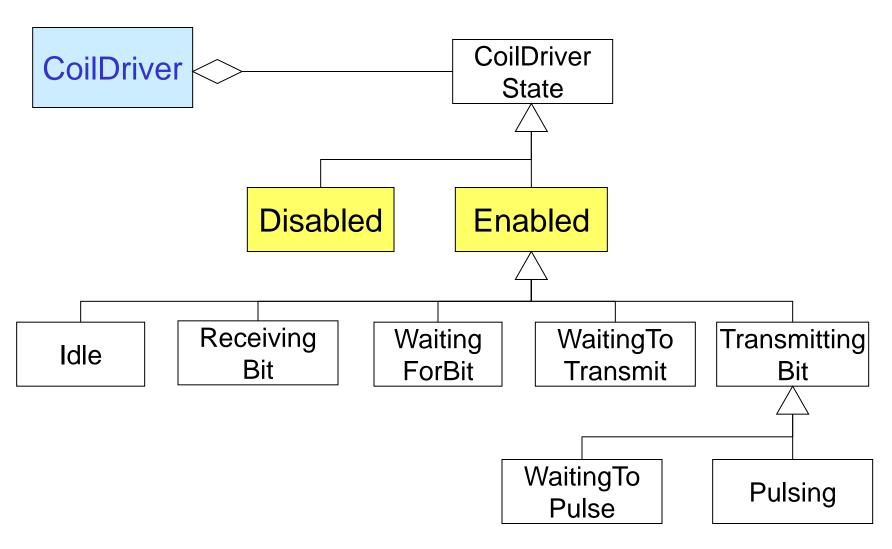
#### Pacemaker – State Diagram for Class Coil Driver

Coil Driver sends and receives a bit at a time by pulsing the coil a specific number of bits (to send) or counting the pulses (to receive). It communicates with the Communications Gnome a byte at a time.



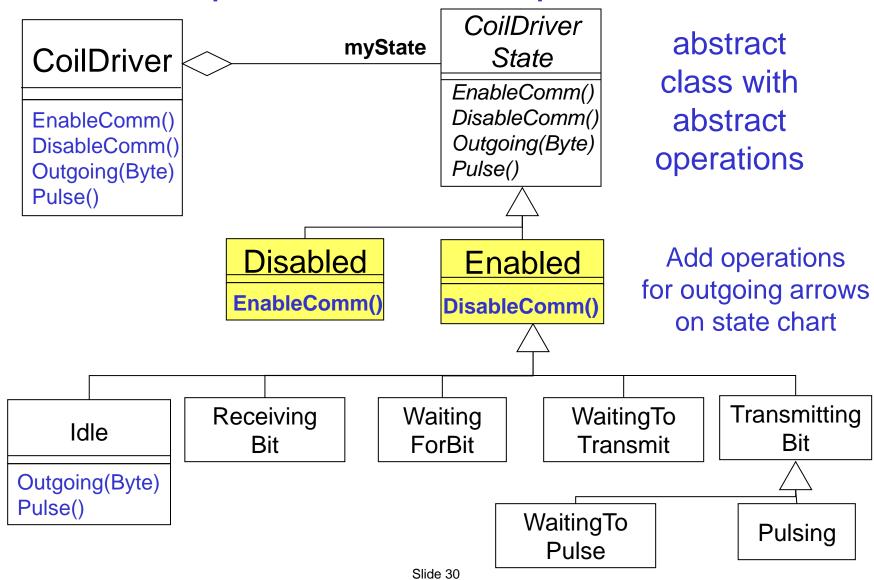


### Step 1: Construct Class Hierarchy





### Step 2: Add Event Operations



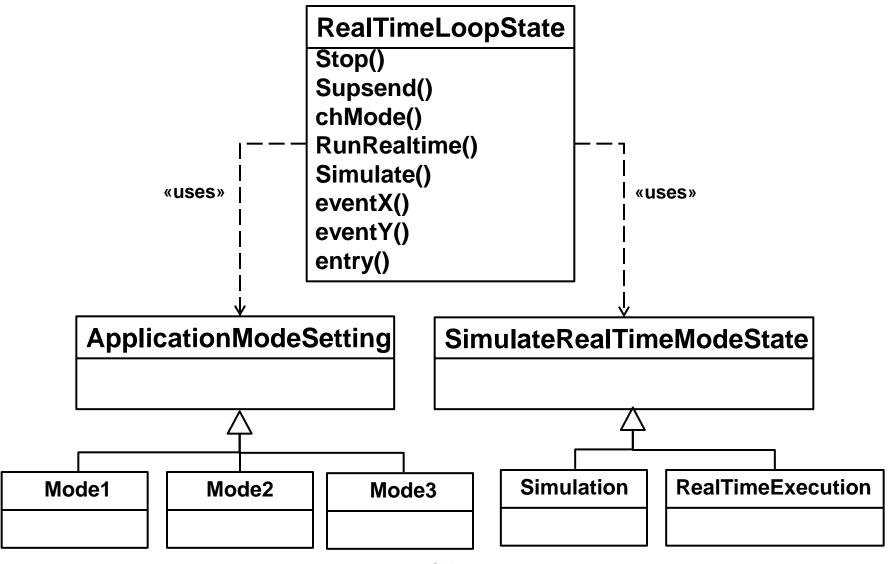


#### Solution for a Parallel State Machine

Example of a **Example from exercise 3** State Machine for the Real Time Loop RealTimeLoop **ApplicationModeSetting** Mode2 eventX/responseM2eventX Mode1 eventY/responseM2eventY chMode eventX/responseM1 eventX chMode Mode3 hMode eventX/responseM3eventX SimulateRealTimeState RunRealTime RealTimeExecution Simulation Simulate



#### Parallel State Machine Classes





## Context Class - EmbeddedSystemX

```
EmbeddedSystemState* pState;
ApplicationModeSetting* pS1;
SimulateRealTimeModeState* pS2;

changeState(EmbeddedSystemState *pS);
changeStateS1(ApplicationModeSetting* pS1);
changeStateS2(SimulateRealTimeModeState* pS2);
getStateS1(): ApplicationModeSetting*;
getStateS2(): SimulateRealTImeModeState*
```

Addition of 2 new pointers pS1 and pS2 on the "context class" : One for each parallel substate



## RealTimeLoopState code

```
RealTimeLoopState::entry(EmbeddedSystemX *pX)
  pX->changeStateS1(Mode1::Instance());
  pX->changeStateS2(RealTimeExecution::Instance());
RealTimeLoopState::chMode(EmbeddedSystemX *pX)
   (pX->getStateS1())->chMode(pX);
RealTimeLoopState::Simulate(EmbeddedSystemX *pX)
   (pX->getStateS2())->Simulate(pX);
```



State Pattern

Summary

