



ECE 425 - Mobile Robotics

## Pre-Lab 01 - Locomotion Pseudocode

W	int	bor	1	$Q_{-}$	1 C
VV	11 11	ıeı	- 1	О-	ıε

Team	Robot	Go-To-Angle (1 pts)	Go-To-Goal (1 pts)	Square (1 pts)	Circle (1 pts)	Figure Eight (1 pts)
		(1 pts)	(1 pts)	(1 pts)	(1 pts)	(1 pts)





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