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Basic Concepts of PDE's.

· Motivation:

-when your problem is zero-dimensional, such as a point-mass suspended on spring:

The result can only depend on one variable such as time: y(t) y(t) oscillation of mass.

-But many real-life problems have higher dimensions.

E.g. A string/rope's motion:

fixed oscillation in time: dy

Here, the answer (the rope's height y) is a function of space x, and time t.

E.g. Heat diffusion:

T=50°C

Metal Plate.

Bunsen

Time = 2

T=1/00°C

T=50°C

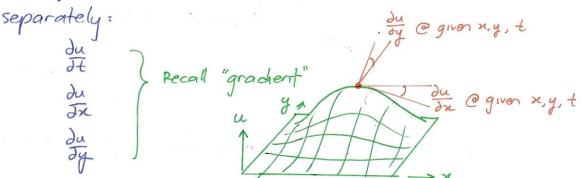
Here, the temperate of the metal plate can change according to 2 spatial directions and time: T(x,y,t)

· What is PDE

· Partial Differential Equation is basically a De where the variable of interest depends an ≥ 2 variables.

or the "unknown function"

· Specifically, we take the derivative of unknown function u(x,y,t,...) in terms of each independent variable



· The "d" notation let's you know it's a partial derivative (i.e. u can change with respect to other variables.)

· Order, Homogeneity and Linearity:

- · Like ODE, 2nd-order PDE is the most useful for engineering.
- · It is linear if we don't have multiplication of u or its derivative to each other.
- · Homogeneous if any terms without in or its obrivative = 0.

 Examples of important 2nd-order PDE:

. ID wave eqn:
$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}$$

• 2D wave eqn:
$$\frac{\partial^2 u}{\partial t^2} = c^2 \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

· 3D Laplace egn:
$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0$$

What is meant by "important".

· Concept of Solution in PDE

- Fundamentally: any in that satisfies the PDE is a solution.

$$\frac{6\cdot q}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

Solution (1)
$$u=x^2-y^2$$

$$\frac{\partial u}{\partial x} = 2x \qquad \frac{\partial u}{\partial y} = -2y$$

$$\frac{\partial^2 u}{\partial x^2} = 2 \qquad \frac{\partial^2 u}{\partial y^2} = -2$$

$$\therefore \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 2 - 2 = 0$$

$$\frac{\partial u}{\partial x} = e^{x} \cos y \qquad \frac{\partial u}{\partial y} = -e^{x} \sin y$$

$$\frac{\partial u}{\partial x^{2}} = e^{x} \cos y \qquad \frac{\partial^{2} u}{\partial y^{2}} = -e^{x} \cos y$$

$$\frac{\partial^{2} u}{\partial x^{2}} + \frac{\partial^{2} u}{\partial y^{2}} = e^{x} \cos y - e^{x} \cos y = 0$$

Solution (3)

$$\frac{\partial u}{\partial n} = \frac{2\pi}{n^2 + y^2}$$

$$\frac{\partial}{\partial x} = \frac{2\pi}{\pi^2 + y^2}$$

$$\frac{\partial u}{\partial y} = \frac{2y}{\pi^2 + y^2}$$

$$\frac{\partial u}{\partial y} = \frac{2y}{\pi^2 + y^2}$$

$$\frac{\partial \hat{u}}{\partial x^2} = -\frac{2(x^2 - y^2)}{(x^2 + y^2)^2} \quad \frac{\partial^2 u}{\partial y^2} = -\frac{2(y^2 - x^2)}{(x^2 + y^2)^2}$$

$$= \frac{2(x^2 - y^2)}{(x^2 + y^2)^2}$$

- For homog, linear PDE, if u, uz are solutions in region R, then: $u_3 = c_1 u_1 + c_2 u_2$ is also a solution. -key message:

olf you think ODE had a lot of solutions,

PDE have even more!

oPDE solutions can come

from very different functions. (e.g. poly,

trig. 10g).

*In general, more complex

equation = bigger solution

space.

- Bounding conditions:

· In ODE, we have IVP that uses initial conditions (y(t=0)=...) to find constants c, c2 ... etc. (or can be)

. In PDE, since u(t, x,y...) is a function of time and space, we need initial condition (u(t=0)) and boundary conditions (u(no, yo)) to find/bound the problem. 2 * Discuss concept of B.C.

· How to Solve PDE .

(1) Some PDE can be solve like ODE ... if you're lucky:

$$\frac{6q}{2n^2} \frac{\partial^2 u(x,y)}{\partial x^2} - u(x,y) = u_{xx} - u = 0$$

Although u=u(x,y), the PDE only involves 3x2:

- · Solve like u"-u=0 -> u=Aex +Bex
- · Don't forget A, B can be function of y:

$$u(x,y) = A(y)e^{x} + B(y)e^{-x}$$

But A = A(x,y) it wouldn't behave like const. in $\frac{\partial}{\partial x}$.

But A = A(y) is like a const. towards $\frac{\partial}{\partial x}$.

uny = - ux.

Here the key is that we can play substitution of variable

I integrate in y In |p| = -y + C(x) & const.

I since P= In , integrate P to got u:

 $u(x,y) = f(x)e^{-y} + g(y)$; $f(x) = \int c(x) dx$

(2) In general, it is not so easy to solve PDE.

In fact, mathematicians / scientists devote careers to solving specific important PDE (eg. wave egn, heat egn, Navier-Stokes).

This course will focus on PDE related to wave equations only (i.e. model of vibrating string).