

Liyuan Cao

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Education

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| 08/2016 – 08/2021 | Ph.D. in Industrial & Systems Engineering, Lehigh University – Advisor: Dr. Katya Scheinberg |
| 08/2014 – 05/2016 | M. Eng. in Industrial & Systems Engineering, Lehigh University |
| 09/2010 – 06/2014 | B.S. in Mechanical Engineering & Automation, Nanjing University of Aeronautics & Astronautic |

Academic Experience

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| 09/2021 - present | Boya Postdoc , Beijing International Center for Mathematical Research, Peking University |
| 08/2016 – 05/2021 | Research Assistant , Lehigh University – Derivative Free Optimization Theory and Software Development – Optimization Algorithms in Machine Learning – Hyperparameter Tuning for Machine Learning |

Publication

- [5] Berahas, A. S., **Cao, L.**, & Scheinberg, K. *Analysis of a Trust Region Method with Errors* (in preparation)
- [4] Berahas, A. S., **Cao, L.**, & Scheinberg, K. *Global Convergence Rate Analysis of a Generic Line Search Algorithm with Noise*. SIAM Journal on Optimization 31.2 (2021): 1489-1518
- [3] Berahas, A. S., **Cao, L.**, Choromanski, K., & Scheinberg, K. *A Theoretical and Empirical Comparison of Gradient Approximations in Derivative-Free Optimization*. Foundations of Computational Mathematics (2021): 1-54
- [2] Wang, Fenlan, and **Liyuan Cao**. *A New Algorithm for Quadratic Integer Programming Problems with Cardinality Constraint*. Japan Journal of Industrial and Applied Mathematics (2020): 1-12.
- [1] Berahas, A. S., **Cao, L.**, Choromanski, K., & Scheinberg, K. *Linear Interpolation Gives Better Gradients Than Gaussian Smoothing in Derivative-free Optimization*. arXiv preprint arXiv:1905.13043 (2019).

Presentations

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| 08/2021 | A Theoretical and Empirical Comparison of Gradient Approximations, MOPTA, Virtual Meeting |
| 11/2020 | Derivative Free Optimization Software for Hyperparameter Tuning, INFORMS Annual Meeting, Virtual Meeting |
| 02/2020 | Lagrange Polynomial in Interpolation, OptML Group Meeting, Lehigh University |
| 10/2019 | Derivative Approximation of Some Model-based Derivative Free Methods, INFORMS Annual Meeting, Seattle, WA |
| 09/2019 | Introduction to Computer Vision, OptML Group Meeting, Lehigh University |
| 08/2019 | A Comparison on Model-based Derivative Free Methods, Sixth International Conference on Continuous Optimization. ICCOPT 2019, Berlin, Germany |
| 11/2018 | Introduction to Natural Evolution Strategy, OptML Group Meeting, Lehigh University |
| 11/2018 | Applying Model-based Derivative Free Methods in Reinforcement Learning, INFORMS Annual Meeting, Phoenix, AZ |
| 03/2018 | Scaling Up Model-based Derivative Free Method, INFORMS Optimization Society Conference, Denver, CO |

Teaching Experience

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| 01/2020 – 12/2020 | Teaching Assistance , Lehigh University |
| 11/2018 – 12/2018 | – Worked as a TA for undergraduate, master's and doctoral level courses |
| 08/2016 – 12/2017 | – Gave tutorials on software and systems (AMPL, MATLAB, PyTorch, Linux) – Graded homework assignments and quizzes Courses: Production and Inventory Control (ISE 251), Product Quality (ISE 332), Introduction to Machine Learning (ISE 364), Introduction to Mathematical Optimization (ISE 406), Optimization Models and Applications (ISE426), Optimization in Machine Learning (ISE444), Optimization Algorithms and Software (ISE 455) |

Internship Experience

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| 04/2019 – 08/2019 | Hyperparameter Auto Tuning , Robert Bosch LLC in Sunnyvale, CA – Developed a method to automatically tune the hyperparameters of a machine learning task – Explored seven derivative free optimization algorithms and experimented with various data manipulation methods to reduce the time cost of hyperparameter auto tuning |
| 05/2018 – 08/2018 | Givens Program Intern , Argonne National Laboratory in Lemont, IL – Designed and coded a practical algorithm for derivative free multi-objective optimization – Increased algorithm efficiency by using a variety of practical methods – Achieved better numerical results against most state-of-the-art algorithms |
| 06/2016 – 08/2016 | Engineering Intern , Huakuo Auto&Eng Co., LTD in Shanghai, China – Learned Kuka robot programming language – Wrote algorithms to control robots to do locate-and-grab task – Studied laser engraving machines market and investigated their technical details to help the company make purchase decisions |

Other Activities

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| 2019 – 2020 | INFORMS Lehigh student chapter president |
| 2018 – 2019 | INFORMS Lehigh student chapter treasurer and secretary |

Technical Skills

- Programming Languages: Python, C++
- Software and Packages: MATLAB, LaTeX, AMPL, PyTorch, Spark, TensorFlow

Honors

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| 08/2016 | Dean's Doctoral Assistantship, Lehigh University |
| 05/2014 | Distinguished Student, Nanjing University of Aeronautics & Astronautic |
| 10/2013 | Distinguished Student, Nanjing University of Aeronautics & Astronautic |
| 10/2013 | National Scholarship, Nanjing University of Aeronautics & Astronautic |