Automatic Memory Management

Lecture 17

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Lecture Outine

- Why Automatic Memory Management?
- Garbage Collection
- Three Techniques
 - Mark and Sweep
 - Stop and Copy
 - Reference Counting

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Why Automatic Memory Management?

- Storage management is still a hard problem in modern programming
- C and C++ programs have many storage bugs
 - forgetting to free unused memory
 - dereferencing a dangling pointer
 - overwriting parts of a data structure by accident
 - and so on...
- Storage bugs are hard to find
 - a bug can lead to a visible effect far away in time and program text from the source

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Type Safety and Memory Management

- · Can types prevent errors in programs with manual allocation and deallocation of memory?
 - some fancy type systems (linear types) were designed for this purpose but they complicate programming significantly
- Currently, if you want type safety then you must use automatic memory management

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Automatic Memory Management

- · This is an old problem:
 - studied since the 1950s for LISP
- · There are well-known techniques for completely automatic memory management
- · Became mainstream with the popularity of Java

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The Basic Idea

- When an object is created, unused space is automatically allocated
 - In Cool, new objects are created by new X
- After a while there is no more unused space
- Some space is occupied by objects that will never be used again
 - This space can be freed to be reused later

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The Basic Idea (Cont.)

- How can we tell whether an object will "never be used again"?
 - in general, impossible to tell
 - we will use heuristics
- Observation: a program can use only the objects that it can find:

```
let x : A \leftarrow \text{new } A \text{ in } \{x \leftarrow y; ...\}
```

 After x ← y there is no way to access the newly allocated object

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Garbage

- · An object x is reachable if and only if:
 - a register contains a pointer to x, or
 - another reachable object y contains a pointer to x
- You can find all reachable objects by starting from registers and following all the pointers
- · An unreachable object can never be used
 - such objects are garbage

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Reachability is an Approximation

Consider the program:

 $x \leftarrow \text{new } A;$ $y \leftarrow \text{new } B$ $x \leftarrow y;$

if alwaysTrue() then $x \leftarrow \text{new } A \text{ else } x.\text{foo}() \text{ fi}$

- After x ← y
 - assuming y becomes dead ...
 - the first object A is unreachable
 - the object \tilde{B} is reachable (through x)
 - thus B is not garbage and is not collected
 - · but object B is never going to be used

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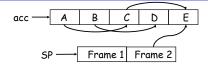
Tracing Reachable Values in Coolc

- In coolc, the only register is the accumulator
 - it points to an object
 - and this object may point to other objects, etc.
- · The stack is more complex
 - each stack frame contains pointers
 - · e.g., method parameters
 - each stack frame also contains non-pointers
 - e.g., return address
 - if we know the layout of the frame we can find the pointers in it

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A Simple Example



- In Coolc we start tracing from acc and stack
 - These are the roots
- Note B and D are unreachable from acc and stack
 - Thus we can reuse their storage

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Elements of Garbage Collection

- Every garbage collection scheme has the following steps
 - 1. Allocate space as needed for new objects
 - 2. When space runs out:
 - a) Compute what objects might be used again (generally by tracing objects reachable from a set of "root" registers)
 - b) Free the space used by objects not found in (a)
- Some strategies perform garbage collection before the space actually runs out

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Mark and Sweep

- · When memory runs out, GC executes two phases
 - the mark phase: traces reachable objects
 - the sweep phase: collects garbage objects
- · Every object has an extra bit: the mark bit
 - reserved for memory management
 - initially the mark bit is 0
 - set to 1 for the reachable objects in the mark phase

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The Mark Phase

```
let todo = { all roots }
while todo \neq \emptyset do
    pick v \in todo
    todo \leftarrow todo - \{v\}
    if mark(v) = 0 then
                                 (* v is unmarked yet *)
       mark(v) \leftarrow 1
       let v_1,...,v_n be the pointers contained in v
       todo \leftarrow todo \cup \{v_1,...,v_n\}
   fi
od
                                                          14
```

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The Sweep Phase

- · The sweep phase scans the heap looking for objects with mark bit 0
 - these objects were not visited in the mark phase
 - they are garbage
- · Any such object is added to the free list
- · The objects with a mark bit 1 have their mark bit reset to 0

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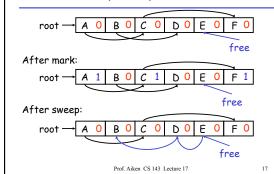
The Sweep Phase (Cont.)

```
(* sizeof(p) is the size of block starting at p *)
p ← bottom of heap
while p < top of heap do
  if mark(p) = 1 then
     mark(p) \leftarrow 0
  else
     add block p...(p+sizeof(p)-1) to freelist
  fi
 p \leftarrow p + sizeof(p)
```

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Mark and Sweep Example



Details

- · While conceptually simple, this algorithm has a number of tricky details
 - typical of GC algorithms
- · A serious problem with the mark phase
 - it is invoked when we are out of space
 - yet it needs space to construct the todo list
 - the size of the todo list is unbounded so we cannot reserve space for it a priori

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Mark and Sweep: Details

- The todo list is used as an auxiliary data structure to perform the reachability analysis
- There is a trick that allows the auxiliary data to be stored in the objects themselves
 - pointer reversal: when a pointer is followed it is reversed to point to its parent
- Similarly, the free list is stored in the free objects themselves

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Evaluation of Mark and Sweep

- · Space for a new object is allocated from the new list
 - a block large enough is picked
 - an area of the necessary size is allocated from it
 - the left-over is put back in the free list
- Mark and sweep can fragment the memory
- · Advantage: objects are not moved during GC
 - no need to update the pointers to objects
 - works for languages like C and C++

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Another Technique: Stop and Copy

- · Memory is organized into two areas
 - old space: used for allocation
 - new space: used as a reserve for GC

heap pointer
old space new space

- The heap pointer points to the next free word in the old space
 - · allocation just advances the heap pointer

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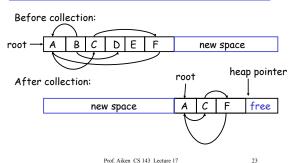
Stop and Copy Garbage Collection

- · Starts when the old space is full
- Copies all reachable objects from old space into new space
 - garbage is left behind
 - after the copy phase the new space uses less space than the old one before the collection
- After the copy the roles of the old and new spaces are reversed and the program resumes

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Example of Stop and Copy Garbage Collection

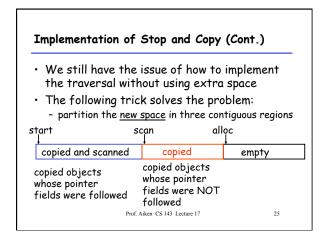


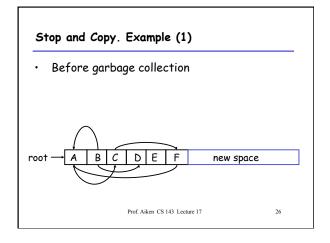
Implementation of Stop and Copy

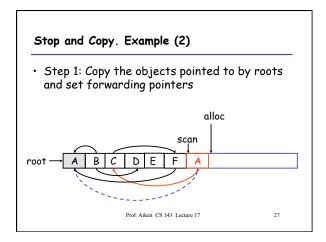
- We need to find all the reachable objects, as for mark and sweep
- As we find a reachable object we copy it into the new space
 - And we have to fix ALL pointers pointing to it!
- As we copy an object we store in the old copy a forwarding pointer to the new copy
 - when we later reach an object with a forwarding pointer we know it was already copied

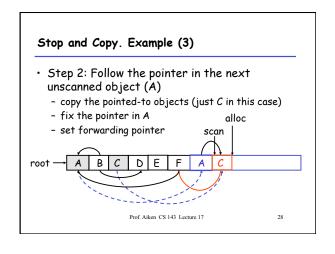
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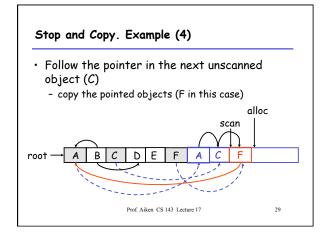
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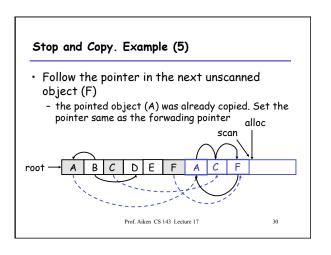






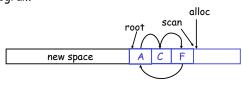






Stop and Copy. Example (6)

- · Since scan caught up with alloc we are done
- Swap the role of the spaces and resume the program



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The Stop and Copy Algorithm

```
while scan \( \phi \) alloc do

let O be the object at scan pointer
for each pointer p contained in O do
find O' that p points to
if O' is without a forwarding pointer
copy O' to new space (update alloc pointer)
set 1st word of old O' to point to the new copy
change p to point to the new copy of O'
else
set p in O equal to the forwarding pointer
fi
end for
increment scan pointer to the next object

od
```

Details of Stop and Copy

- As with mark and sweep, we must be able to tell how large an object is when we scan it
 - and we must also know where the pointers are inside the object
- We must also copy any objects pointed to by the stack and update pointers in the stack
 - this can be an expensive operation

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Evauation of Stop and Copy

- Stop and copy is generally believed to be the fastest GC technique
- · Allocation is very cheap
 - just increment the heap pointer
- Collection is relatively cheap
 - especially if there is a lot of garbage
 - only touch reachable objects
- But some languages do not allow copying

- C, C++

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Why Doesn't C Allow Copying?

- Garbage collection relies on being able to find all reachable objects
 - and it needs to find all pointers in an object
- In C or C++ it is impossible to identify the contents of objects in memory
 - E.g., a sequence of two memory words might be
 A list cell (with data and next fields)
 - · A binary tree node (with left and right fields)
 - Thus we cannot tell where all the pointers are

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Conservative Garbage Collection

- But it is Ok to be <u>conservative</u>:
 - if a memory word looks like a pointer it is considered a
 - · it must be aligned
 - · it must point to a valid address in the data segment
 - all such pointers are followed and we overestimate the set of reachable objects
- But we still cannot move objects because we cannot update pointers to them
 - what if what we thought is a pointer is actually an account number?

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Reference Counting

- Rather that wait for memory to be exhausted, try to collect an object when there are no more pointers to it
- Store in each object the number of pointers to that object
 - this is the reference count
- · Each assignment operation manipulates the reference count

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Implementation of Reference Counting

- new returns an object with reference count 1
- Let rc(x) be the reference count of x
- Assume x, y point to objects o, p
- Every assignment x ← y must be changed:

```
rc(p) \leftarrow rc(p) + 1
rc(o) \leftarrow rc(o) - 1
if(rc(o) == 0) then mark o as free
x ← y
```

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Evaluation of Reference Counting

- Advantages:
 - easy to implement
 - collects garbage incrementally without large pauses in the execution
- Disadvantages:
 - cannot collect circular structures
 - manipulating reference counts at each assignment is very slow

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Evaluation of Garbage Collection

- Automatic memory management prevents serious storage bugs
- But reduces programmer control
 - e.g., layout of data in memory
 - e.g., when is memory deallocated
- Pauses problematic in real-time applications
- Memory leaks possible (even likely)

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Evaluation of Garbage Collection

- · Garbage collection is very important
- · Researchers are working on advanced garbage collection algorithms:
 - concurrent: allow the program to run while the collection is happening
 - generational: do not scan long-lived objects at every collection
 - parallel: several collectors working in parallel

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