
MRSD Project Course I: Printed Circuit Board Design and Fabrication

September 19, 2017

Acknowledgement

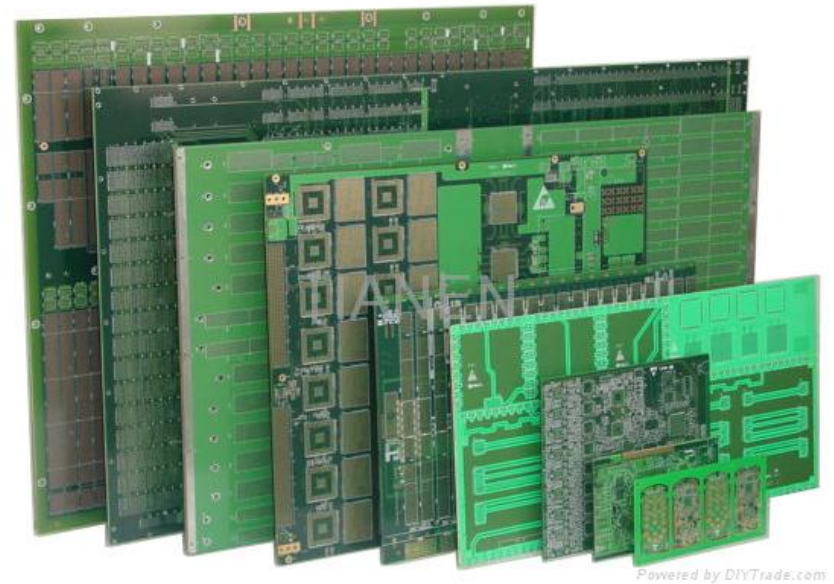
- Large portion of the material presented here was produced by Tom Lauwers

Questions to Answer

- **What is a Printed Circuit Board (PCB) and why are they instrumental to electronic devices?**
- **How do I design a PCB?**
 - What's an electrical schematic good for?
 - What's a "Layout"?
 - Where do parts come from?
- **How do I convert a system diagram into an electrical schematic?**
- **What are some important design considerations?**

The Printed Circuit Board (PCB)

- **Mechanical Mounting**
- **Electrical Connectivity**
 - Traces can form components
- **Many flavors**



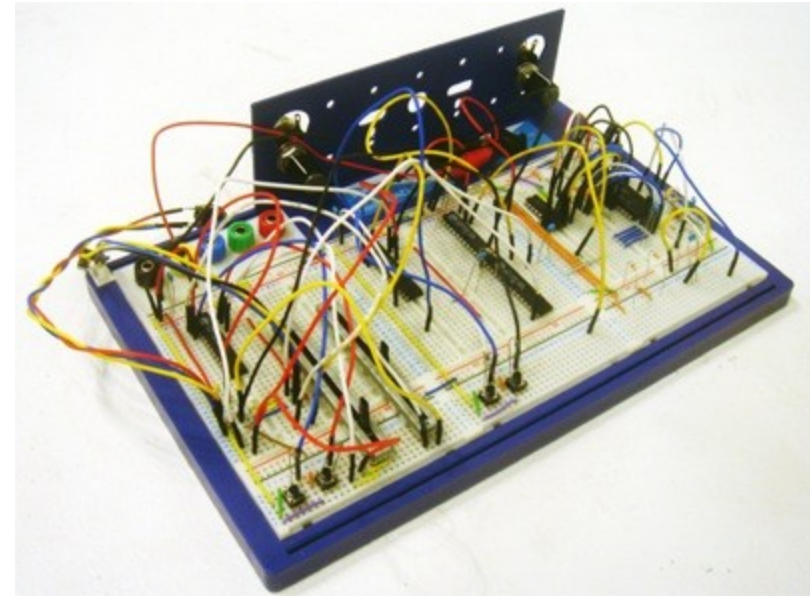
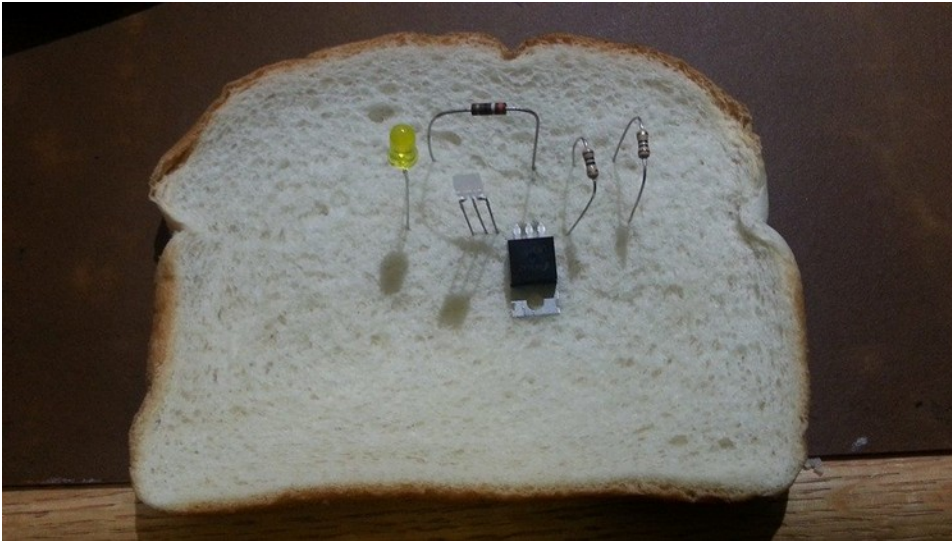
Who is this man?

- **Paul Eisler (1907-1995)**
- **Invented the PCB in 1936**
- **Used it in his radio**
- **Also invented rear-window defroster**



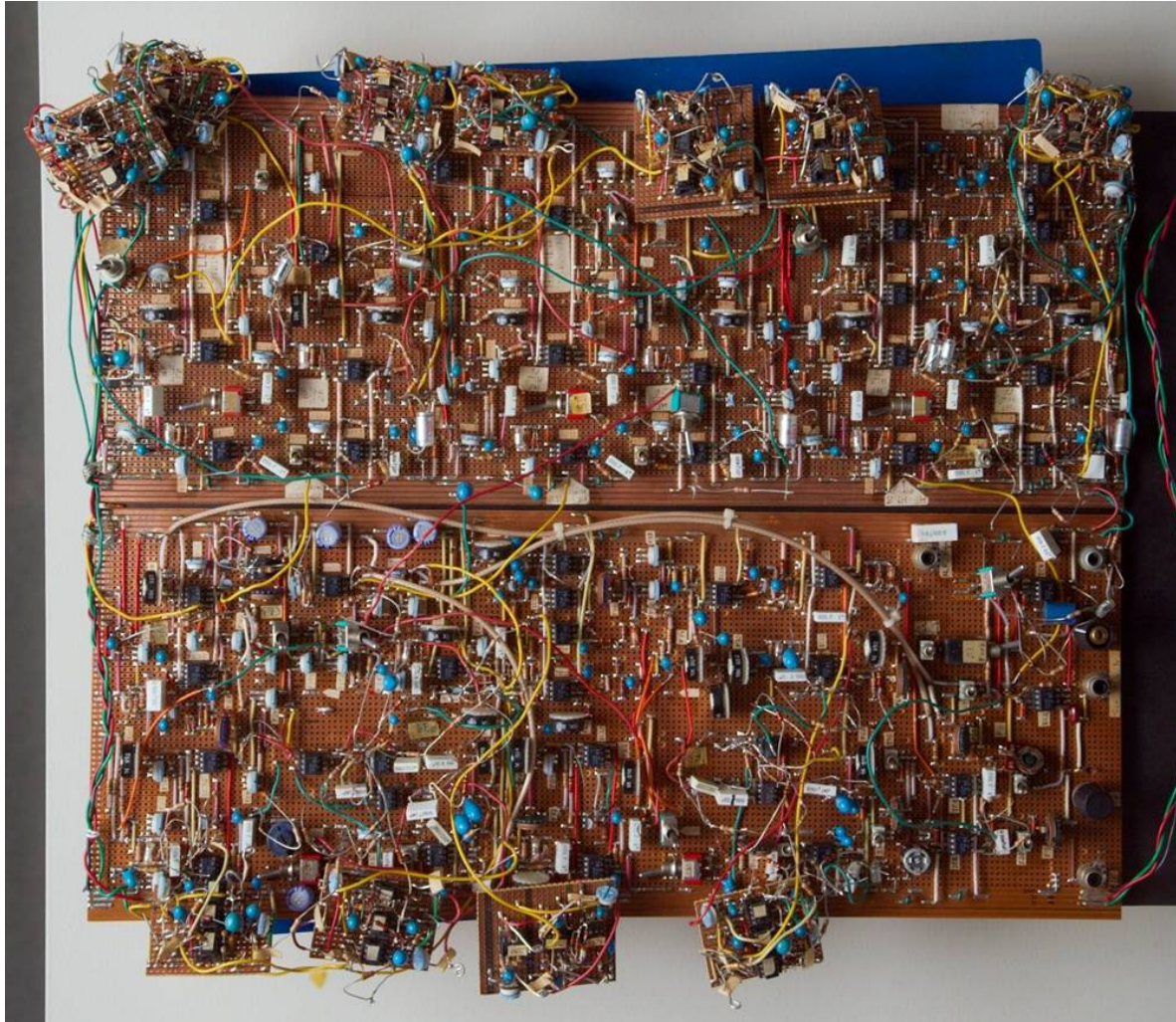
Which is Better?

This???

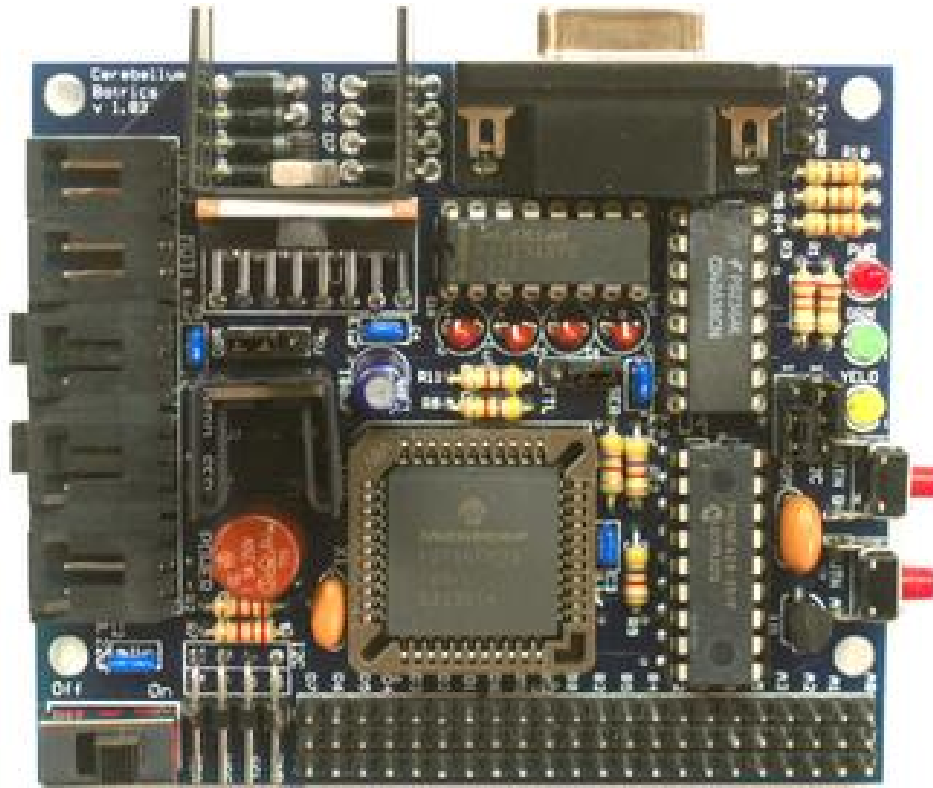


Which is Better?

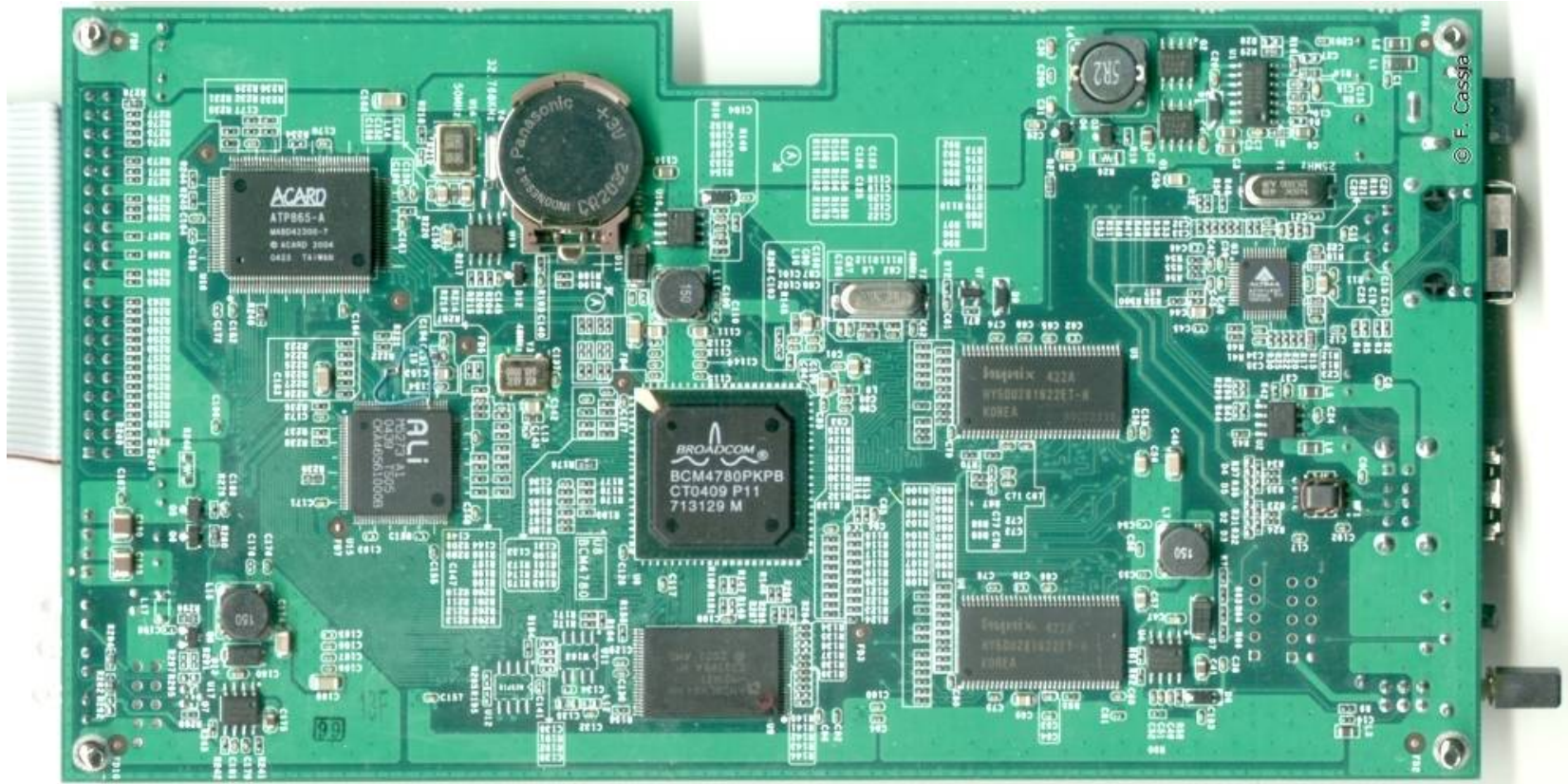
This???!?!?!!



This is Better.



This is Even Better*.

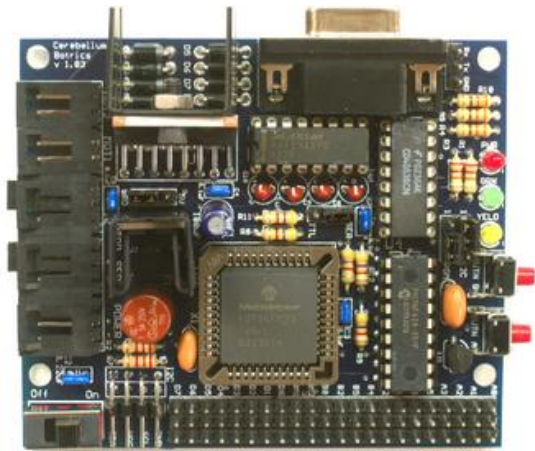


* - see next slide

Through-Hole Vs. Surface Mount

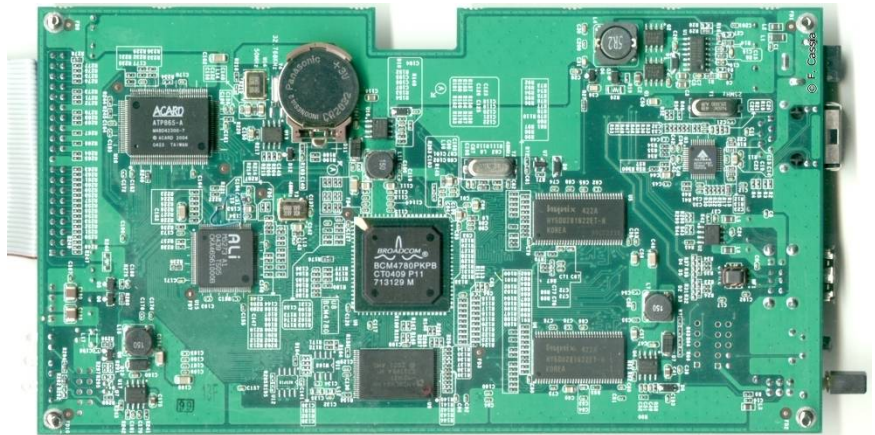
Through-Hole:

- Easy to solder
- Easier to fix circuits
- You don't lose components on the floor



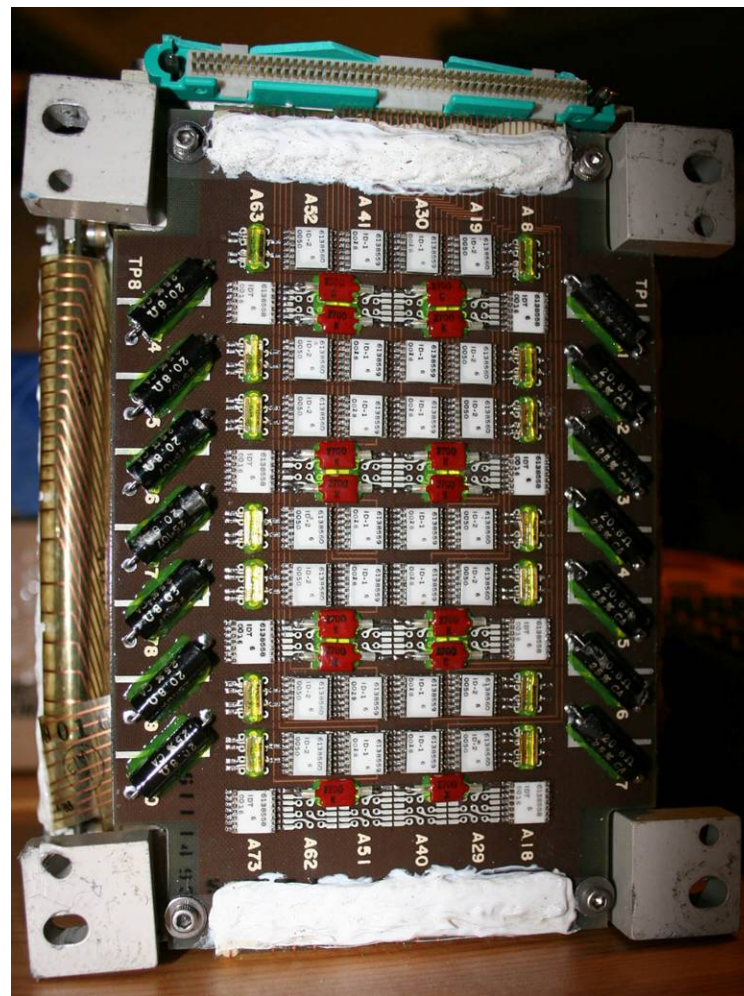
Surface Mount:

- Miniaturization
- From *small* to *ridiculous*
- Easier Automated Assembly
- PCB Fabrication is easier – fewer holes to drill
- Most cool parts are only Surface mount



Historical Digression

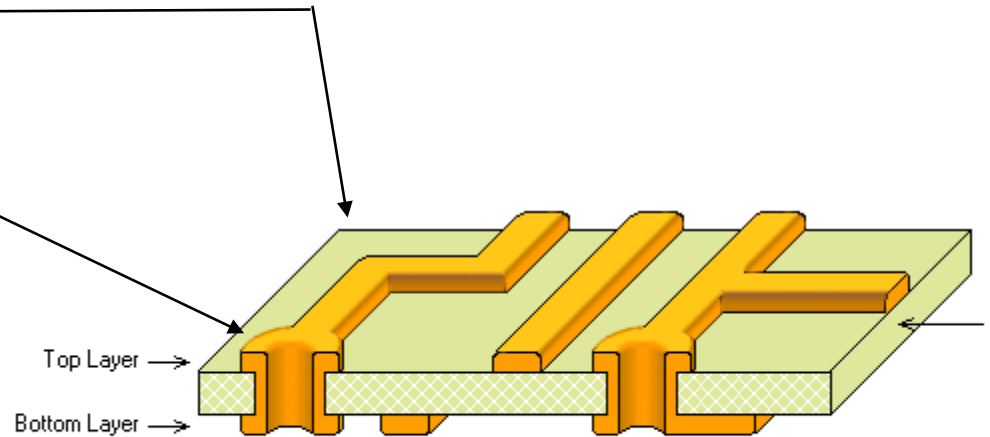
- First surface mount boards were developed for Saturn V flight computers
 - In 1964!
 - By IBM
- This module can hold 14,336 bytes
 - The Saturn V had 8 of them



Multi-layer Construction

- **PCBs have many layers:**

- **The dielectric**
- **Copper layers**
- **Vias**



- **Other Common Features**

- **Soldermask:** [usually green] overlay that insulates copper
- **Silkscreen:** [usually white] with text, logos, etc.
- **Multi-layer:** Many sandwiched copper/dielectric layers
“planes” are often implemented this way. Complex PCBs like motherboards might have 16 copper layers—or even more

PCB Materials

- PCBs are available in several grades

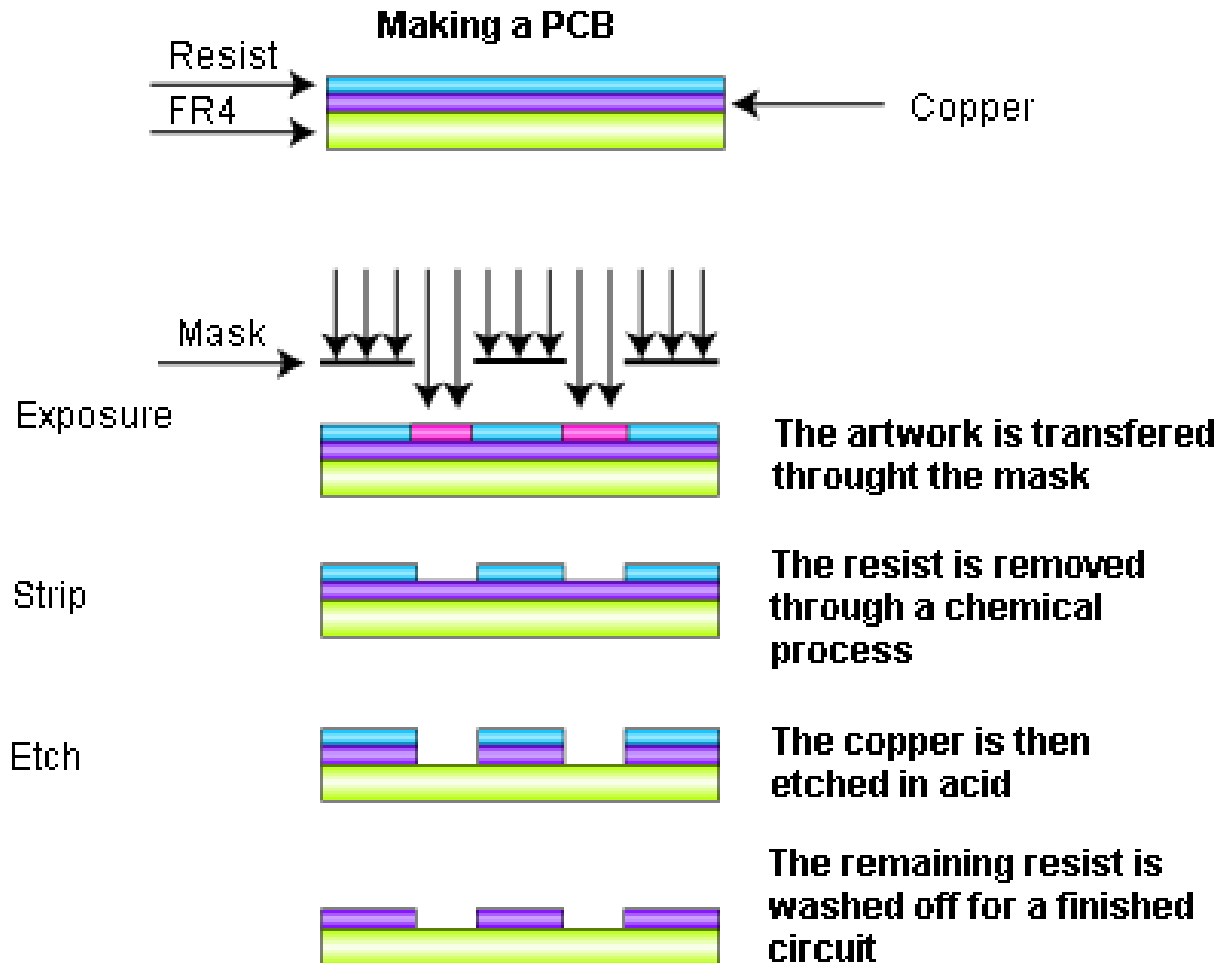
GRADE DESIGNATION	MATERIAL/COMMENTS
FR-1	Paper/phenolic: room temperature punchable, poor moisture resistance.
FR-2	Paper/phenolic: suitable for single-sided PCB consumer equipment, good moisture resistance.
FR-3	Paper/epoxy: designed for balance of good mechanical and electrical characteristics.
FR-4	Glass cloth/epoxy: excellent mechanical and electrical properties.
FR-5	Glass cloth/epoxy: high strength at elevated temperatures, self-extinguishing.
G10	Glass cloth/epoxy: high insulation resistance, highest bond strength of glass laminates, high humidity resistance.
G11	Glass cloth/epoxy: high flexural strength retention at high temperature, extreme resistance to solvents.

Modern PCB Fabrication Steps

- **Automated Fabrication:**

1. Clad dielectric with copper foil (~0.0015" thick)
2. Create copper traces using photolithography and chemical etching (remove excess foil)
3. Combine all layers if making >2 layer PCB
4. Drill holes in PCB
5. Plating to electrically connect all layers to vias
6. Soldermask applied to top/bottom
7. All copper surfaces plated (typically lead/lead-free solder, nickel, or gold)
8. Apply silkscreen
9. Post-process milling/board de-panelization

Modern PCB Fabrication



Implementing Systems with PCBs

- PCBs are a good way to implement *Interconnect*
 - Mechanical Mounting
 - Electrical Connectivity
- Many parts are designed to operate solely on PCBs
 - ICs (microcontrollers, regulators, motion controllers, modern sensors, etc.)
 - Discrete components shaped to fit
- Standalone devices interact with PCBs via electrical *connectors*

Custom PCBs in System Design: Benefits

- **Interconnect organization**

- Put all your electronic subsystems in one place
- Combine many “breakout boards” into single PCB
- Eliminate unnecessary electrical connectors
- Can increase reliability

- **Form Factor**

- Extreme miniaturization is possible
- PCB shape and part placement is definable
- Can fit very small or unusual shapes

- **Greater choice in component selection**

- Most modern parts not designed for standalone use
- Not limited to breakout boards, dev kits, or hobby parts
- Some electrical designs (high speed or analog) not possible or reliable using breadboards and dev kits

Custom PCBs in System Design: Drawbacks

- **Learning Curve**

- Takes a little more time to implement than COTS
- Requires knowledge of electronics to implement
- May require more testing/validation

- **Failure may be harder to mitigate if entire system is on a single PCB!**

- Can add additional, optional connectors to salvage
- Test complex subsystems beforehand if possible
- Iterating PCB 2-3 times not uncommon

- **Balancing cost/effort against a COTS system**

- For small design houses, turnaround on a design is generally 1-2 weeks
- More effort in design, less effort in assembly / wiring
- A single custom PCB may end up cheaper than 5 breakout boards

Designing PCBs with EagleCAD

Schematic Capture and Layout Design

PCB Design Software

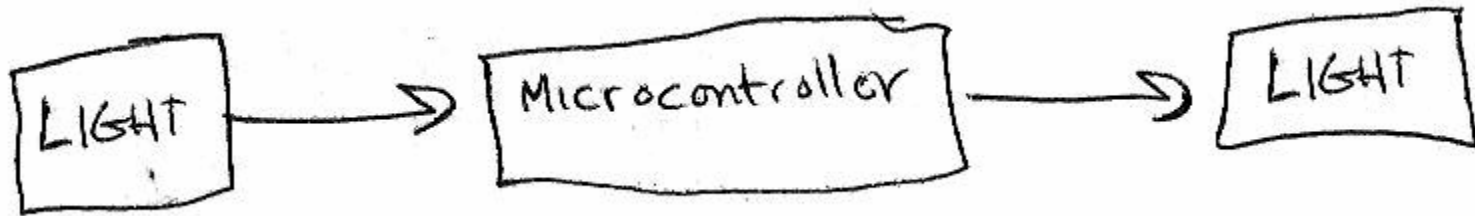
- **PCB CAD provides two separate (but linked) tools:**
 - Schematic capture / verification
 - Layout artwork / verification
- **Also provides ability to create parts libraries**
 - Basic building block links logical (schematic) diagrams to physical (layout) parts
- **Some common software packages:**
 - Eagle (Easily Accessible Graphical Layout Editor)
 - ORCAD
 - Altium Designer
 - PADs

Eagle CAD

- **In this class we'll be using EagleCAD**
 - Available at <http://www.cadsoftusa.com/>
 - Used by many--including Arduino designers
 - Commercial software
 - “free” version for non-commercial use
 - “free” restricted: 2-layer, 100mmx80mm size
- **An interesting alternative is DIPTRACE**
 - Available at <http://www.diptrace.com/>
 - Free, restricted version is also available
- **Also worth considering:**
 - KiCad EDA <http://kicad-pcb.org>
 - Altium CircuitMaker <http://circuitmaker.com/>
 - MRSD Wiki: <http://cmumrdsproject.wikispaces.com/Altium+Circuitmaker>

Schematics: A Picture is Worth a Thousand Words

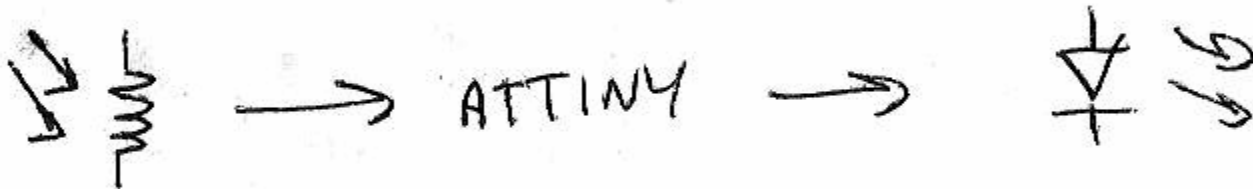
- Schematics represent circuits graphically
- Consider one very basic system:




- A little vague, but still a schematic
- A good schematic shows *what* and *how*

Adding Detail with Symbols

- Using specific symbols tells more information



A photocell is read by an ATTiny microcontroller which lights an LED

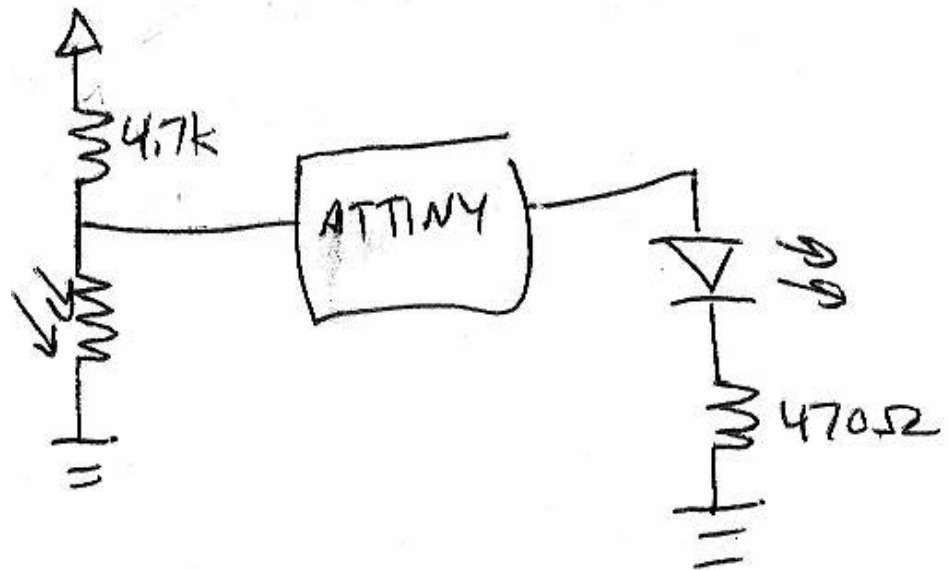
- Shows you've thought about *what* you're using
- But  is not really a valid electrical device

Adding Detail with Basic Circuits

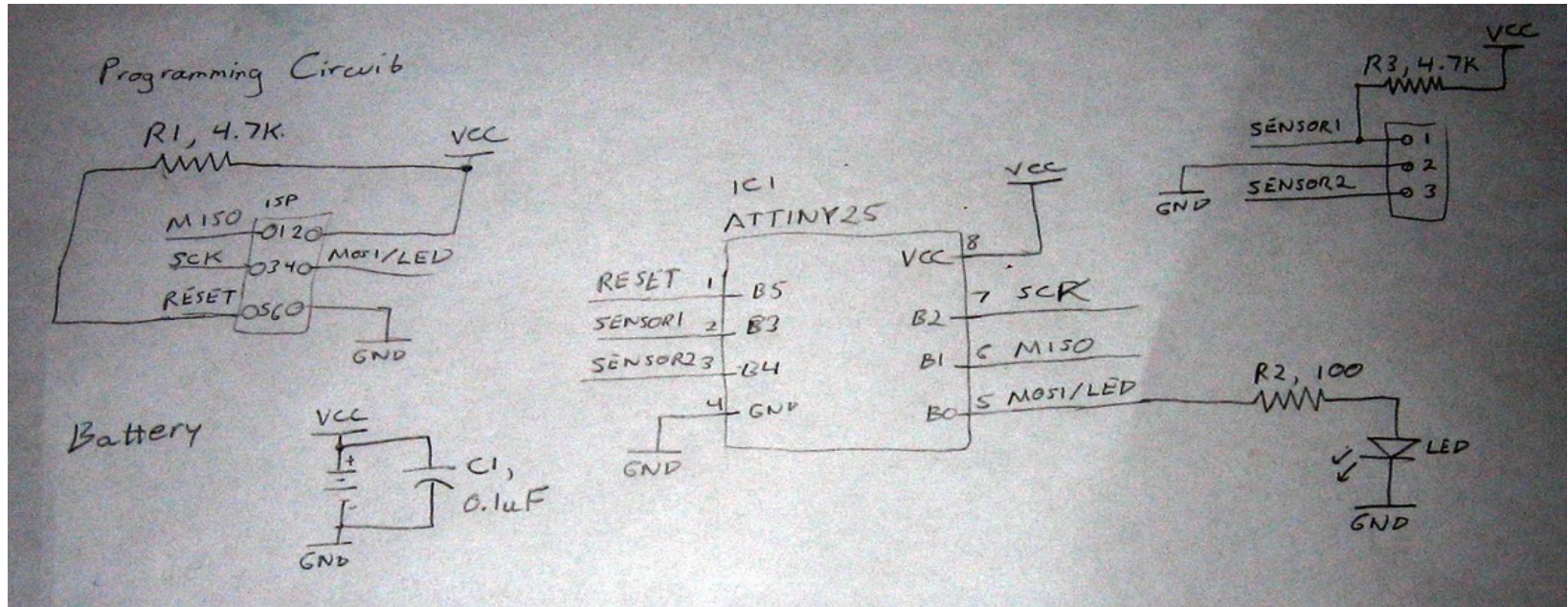
- Explaining *how* requires circuit diagrams

A photocell in a voltage divider is read by an ATTINY which outputs to an LED with a current-limiting resistor

But is this enough?

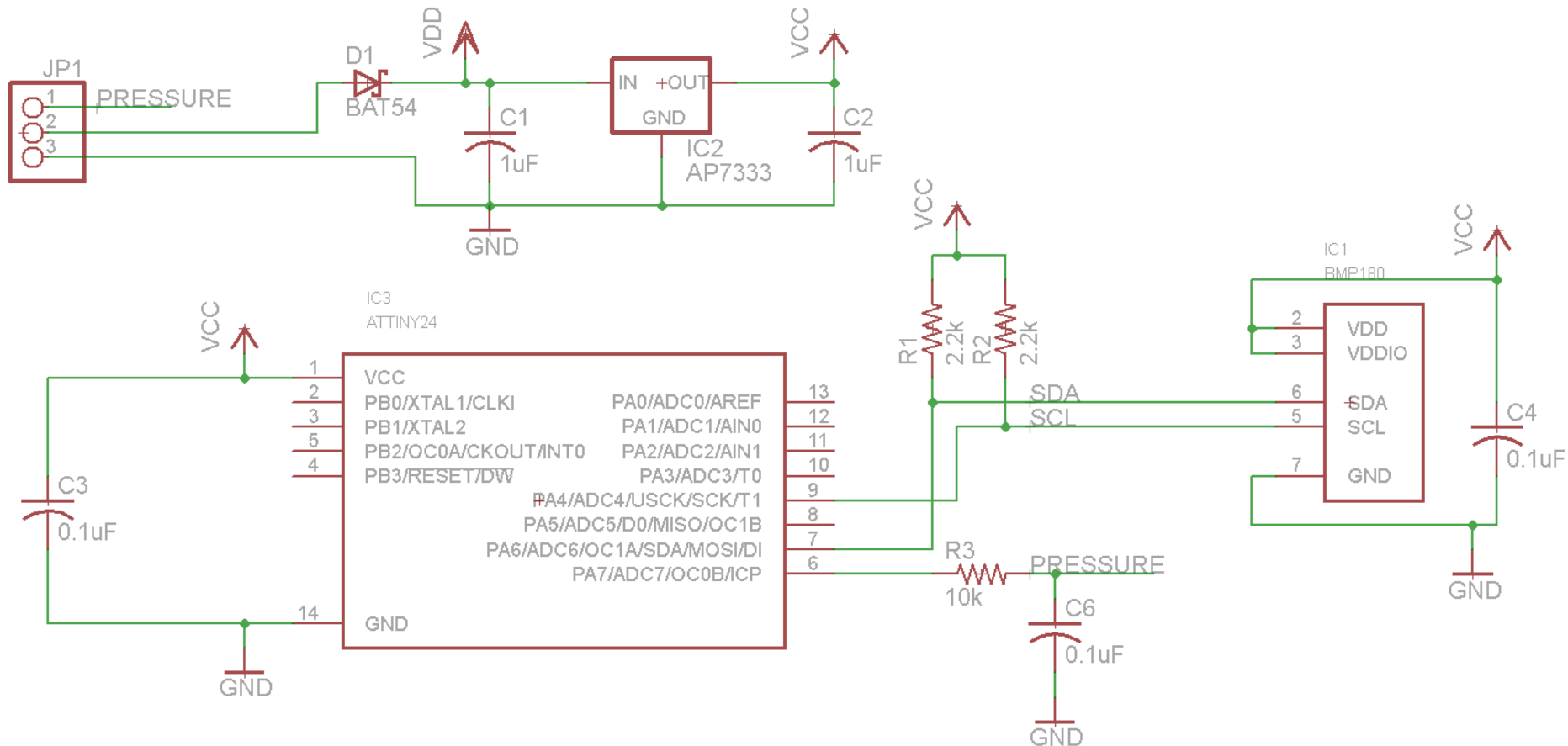


A complete schematic



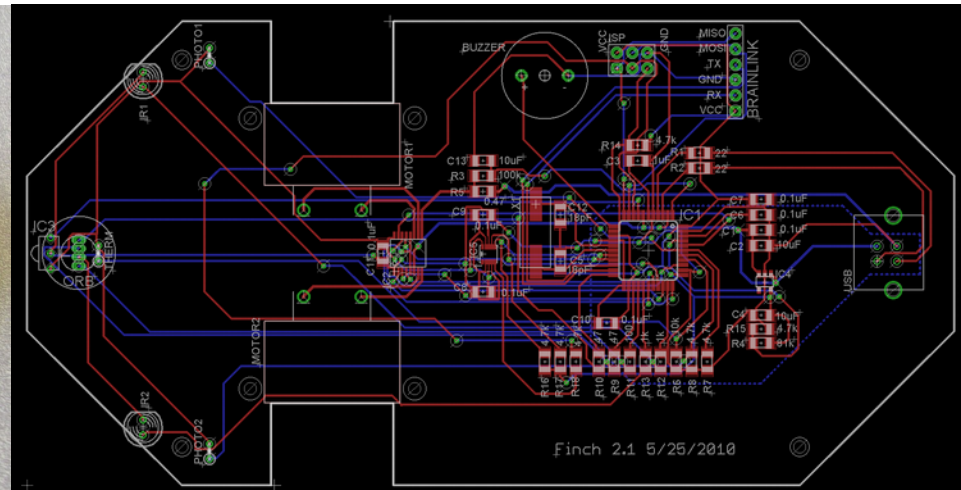
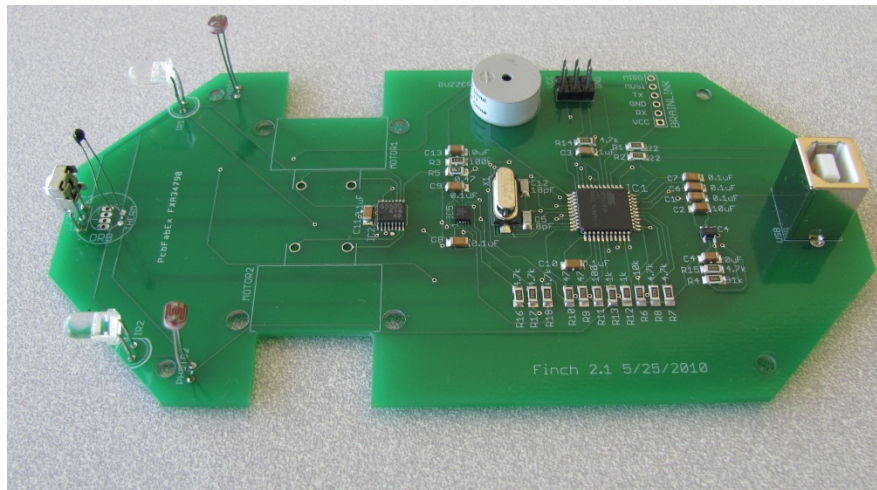
- Lots going on! *A complete schematic.*
- However, *layout* is not apparent

A Complete Schematic in Eagle



So I've Got my Schematic...

- Time to make a “Layout”
 - Scale representation of your PCB
- Layers
 - Copper in red and blue
 - Around holes it's in green
 - Designators in white
 - Holes marked with x's



Real World Layout Considerations

- **Design Rules**
- **Surface Mount and Through-hole**
- **Heat sinks**
- **Shape, mounting, and 2D representations of 3D parts**
- **Routing**

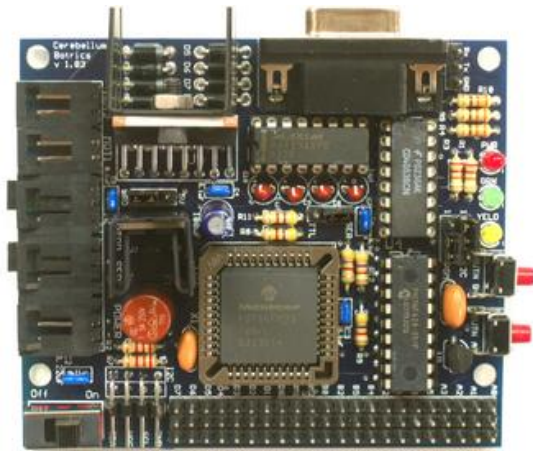
Design Rules

- Design Rules – “*Thou shalt nots*” for your circuit board
- Adjustable, but...they come from reality:
 - Advanced Circuits Capabilities
- Tell you things like:
 - How small traces can be
 - How small holes can be
 - Minimum distance between part, pad, trace, and the board's edge
 - Minimum distance between traces
 - And much more!
- You must address any violations flagged by the CAD software

Through-hole Vs. Surface Mount

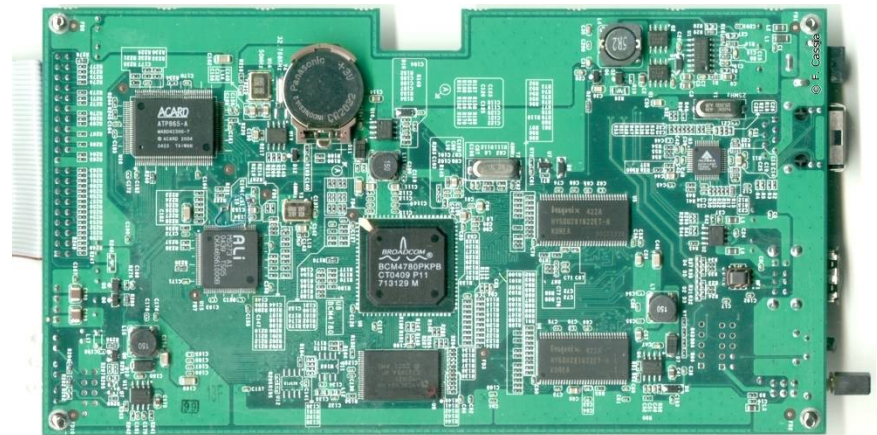
Through-Hole:

- Easy to solder
- Easier to fix circuits
- You don't lose components on the floor
- **Better for large connectors**



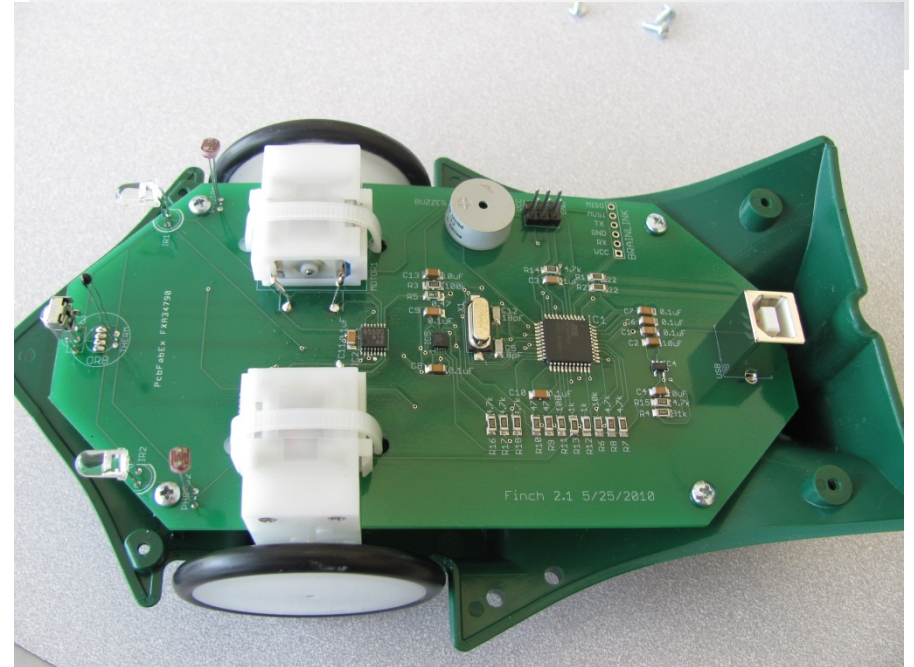
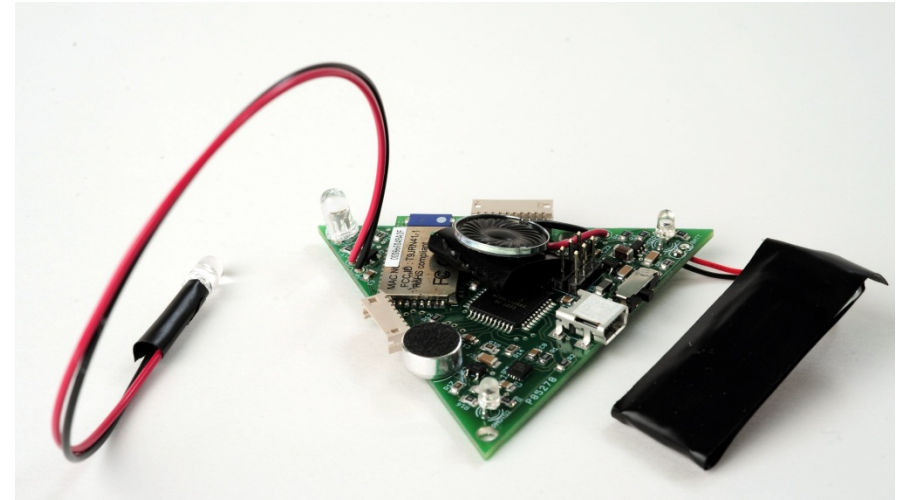
Surface Mount:

- Miniaturization
 - From small to ridiculous
- Easier Automated Assembly
- PCB Fab is easier – fewer holes to drill
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Shape, Mounting

- PCB does not need to be a rectangle
- Make sure you allow for a way to mount the board
- Keep in mind – 2D representation of a 3D part!



Heatsinking

- Some high current parts may require a heat sink
- Often much bigger than part
- Specified in datasheet
- Make sure to factor size of heat sink into your layout
- Location is also important
- **Insulate electrically !!!**



Routing

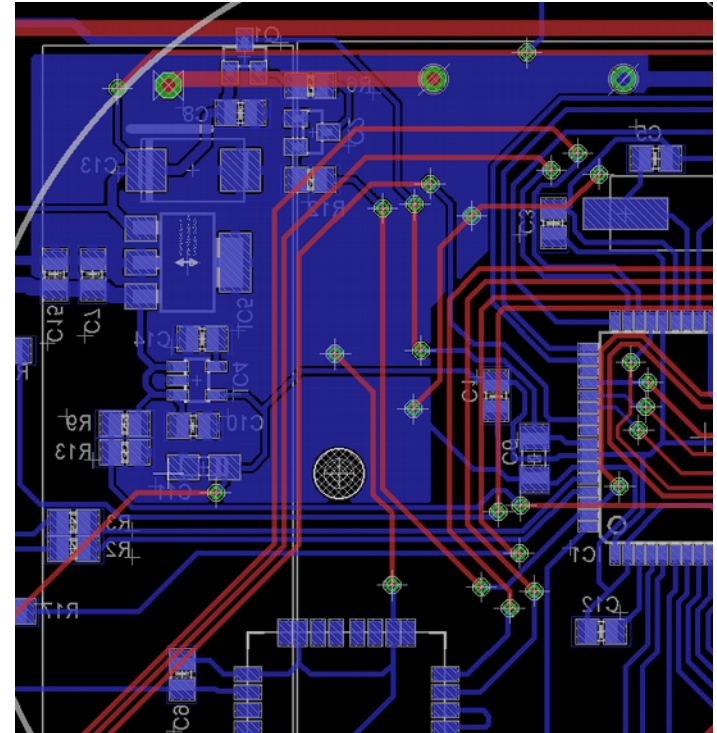
- **Definition:** *The process of making electrical connections between the different components by editing the physical (copper) representation of the nets created in your schematic*
- **Your “frenemy,” the autorouter**
 - Computers do the darnedest things
 - Fixing things may take as long as routing by hand
- **Routing by hand creates a much cleaner looking design**
 - However, it’s invaluable for large projects!

Trace Widths and Power

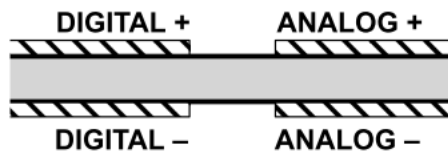
- All traces/wires have resistance
- Car jumper cables vs. Christmas lights
- Some traces need to be bigger than others
 - Wider traces carry more current (necessary for driving high-current devices like motors).
 - Thin trace carrying lots of current = FIRE
 - Wider traces have less noise (good for analog signals)
- Handy tool:
 - <http://www.4pcb.com/trace-width-calculator.html>
 - Understand issues with temperature

Planes

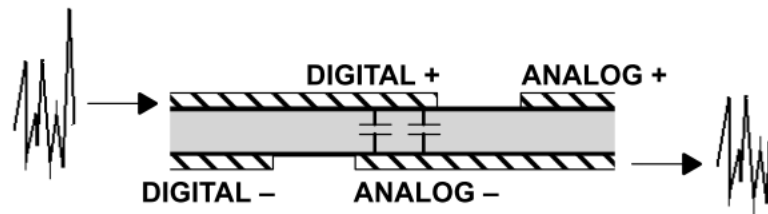
- Cover a large part of your board with copper connected to a net (typically ground)
- Used for:
 - Heat-sinking
 - Noise reduction
 - Simplify routing (one less net)



RIGHT



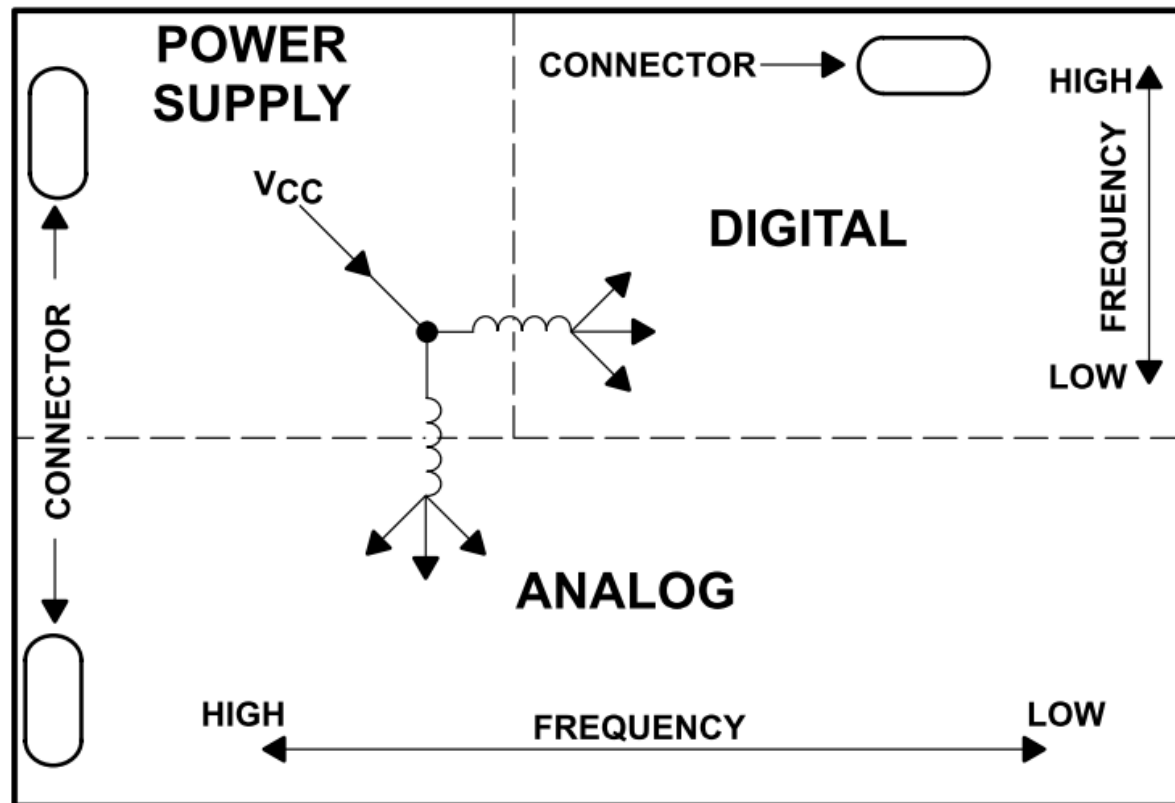
WRONG



Avoid coupling high-frequency digital noise into analog circuitry

Board Layout

- Careful placement prevents a lot of problems

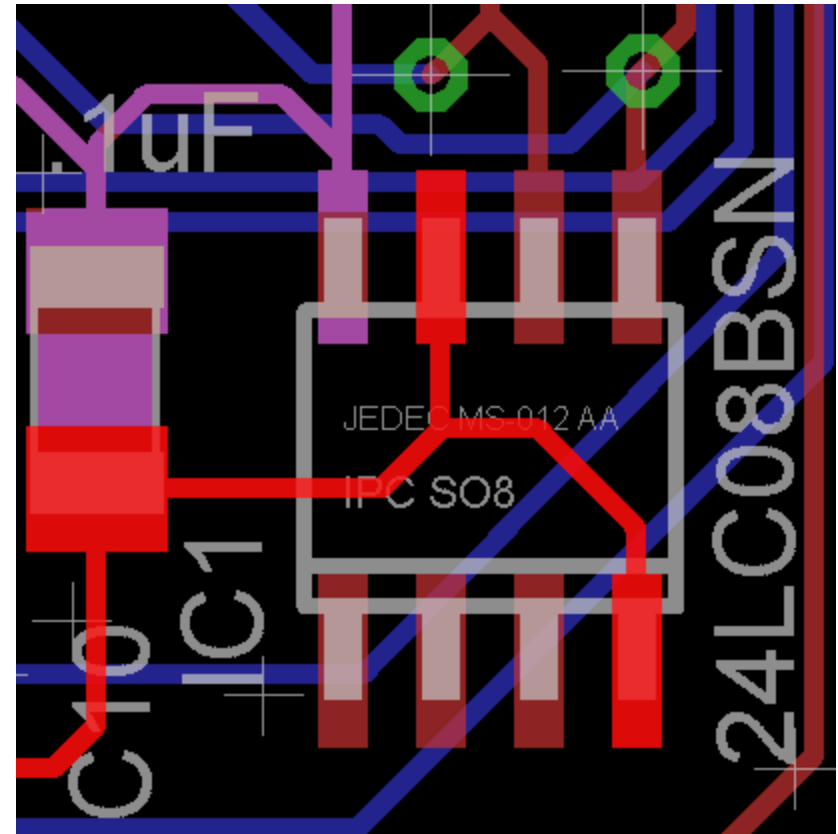
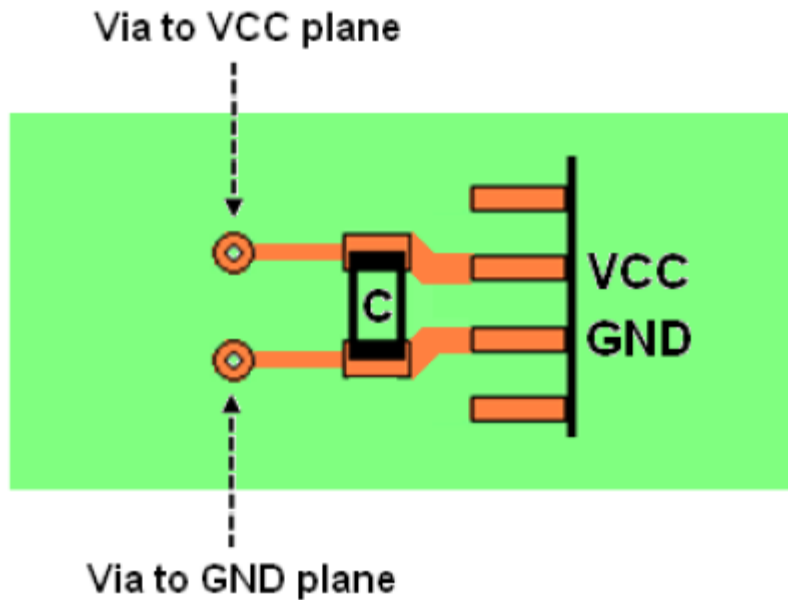


Slight Detour: Decoupling Capacitor Placement

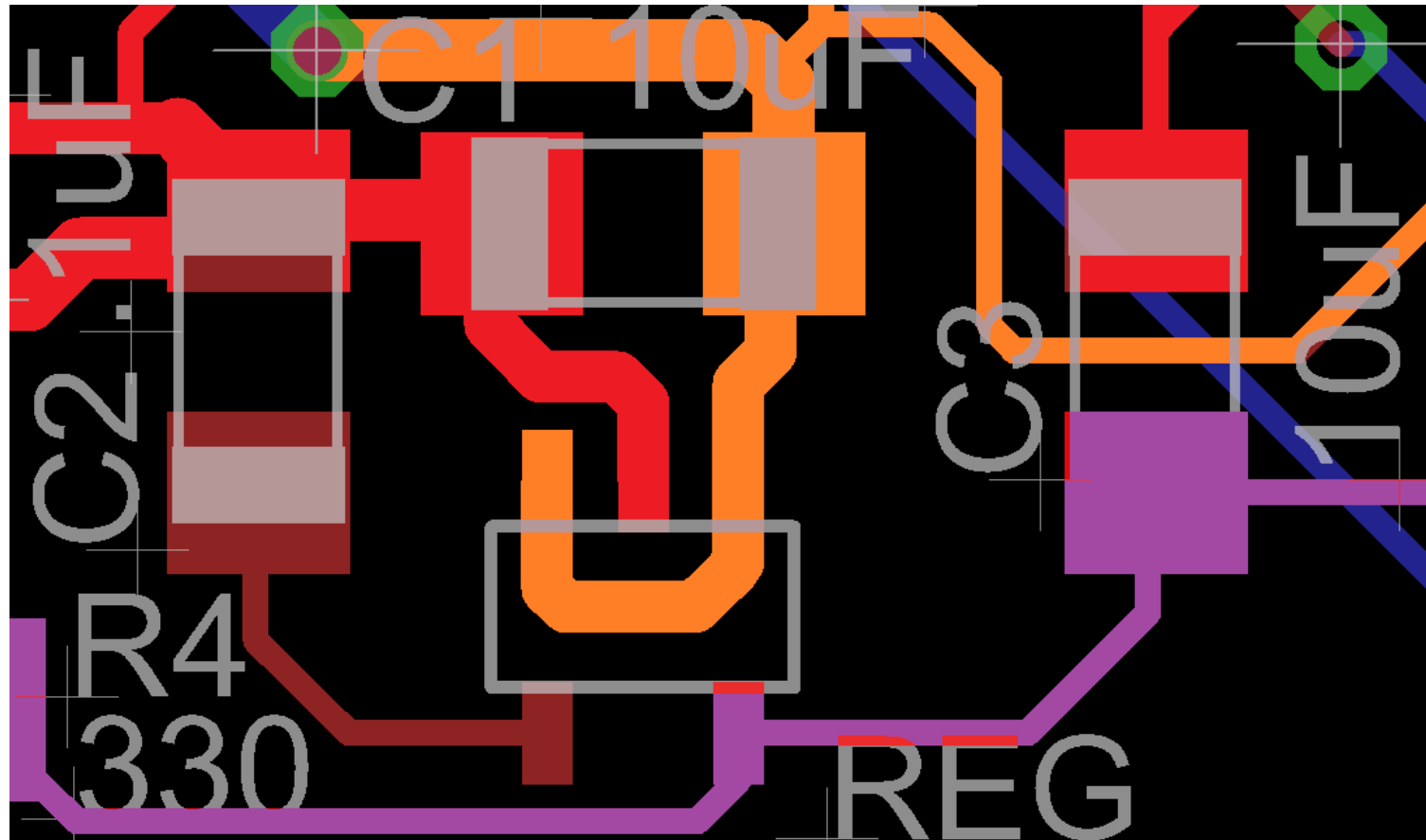
- Short traces (less than 0.5")
- At least one per IC
 - Usually one per pair of VCC/GND terminals on IC
- Can be on underside if you want to save space
- Following slides – a number of examples of good capacitor placement

Good IC Decoupling

- VCC = PURPLE
- GND = RED



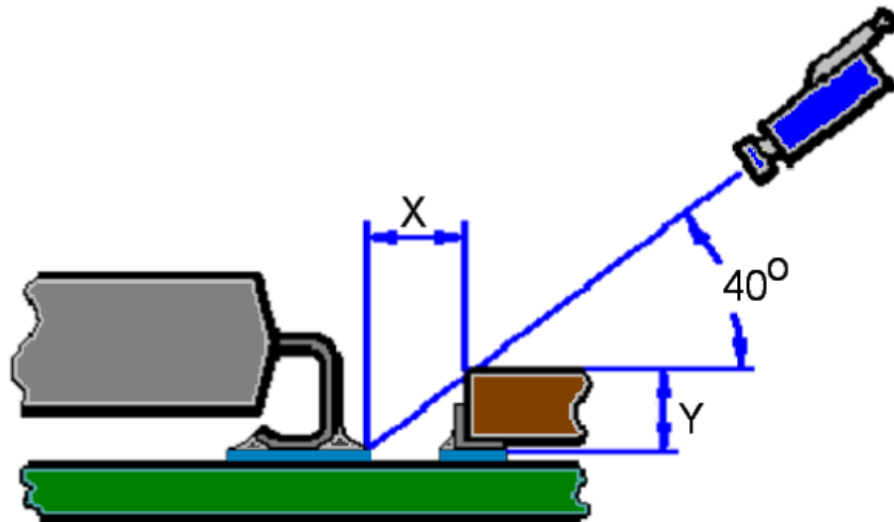
Good Input Capacitors for a Voltage Regulator



GND = Red, VDD = Yellow, VCC = Purple

Design for Testing

- Test points
- Tooling pins
 - Precise registration with test fixture
 - Push fingers
- Clearances for inspection



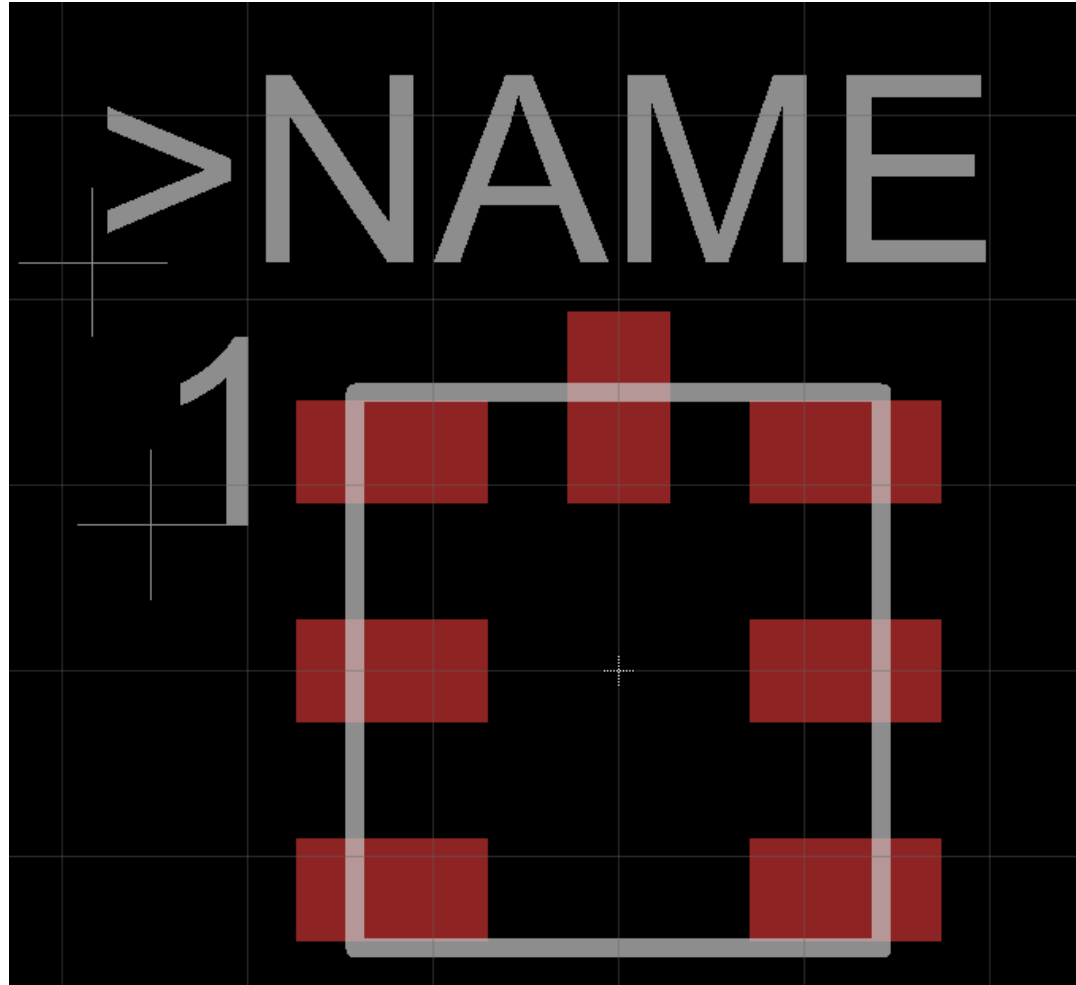
CAD Circuit Board Layout Process

- **Set DRC**
- **Place components**
- **Route electrical connections between them**
- **Place designators**
- **Verify results**

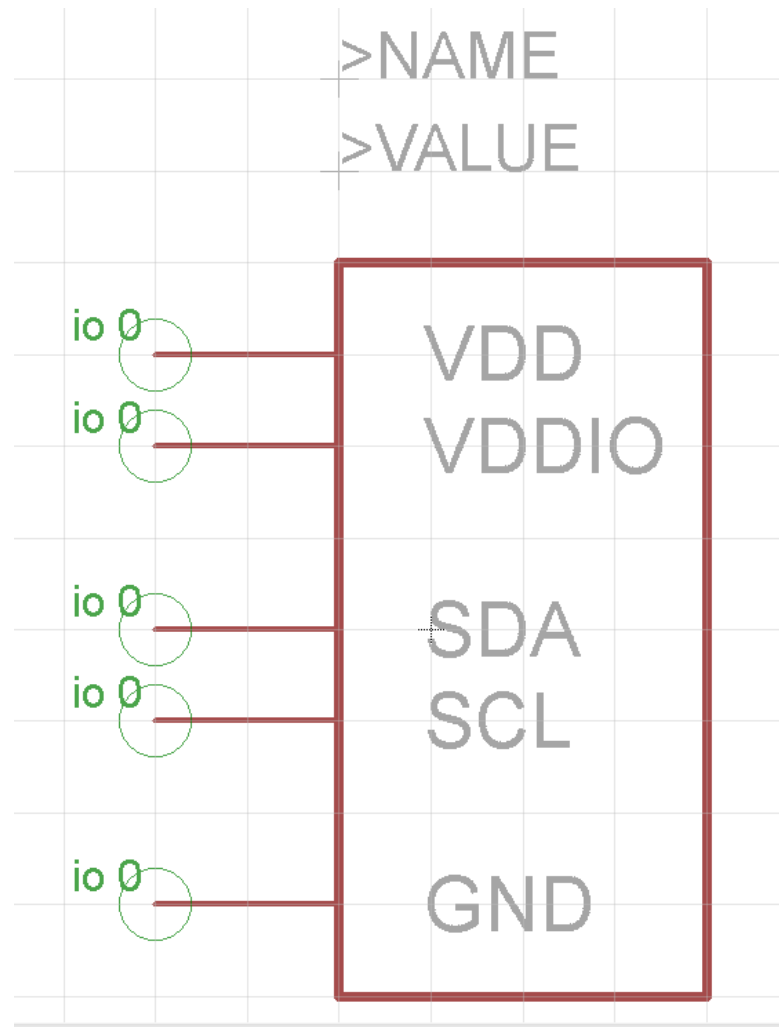
So where do parts come from?

- **Answer: Libraries!**
- **Every part is divided into three representations**
- **Package**
 - The physical representation of the part
 - What you see in Layout view
- **Symbol**
 - The logical representation of the part
 - What you see in Schematic View
- **Device**
 - A place to tie the package to the symbol
 - Lets you re-use common packages on different parts
 - Lets you re-use common symbols on package variants

Sample Package View



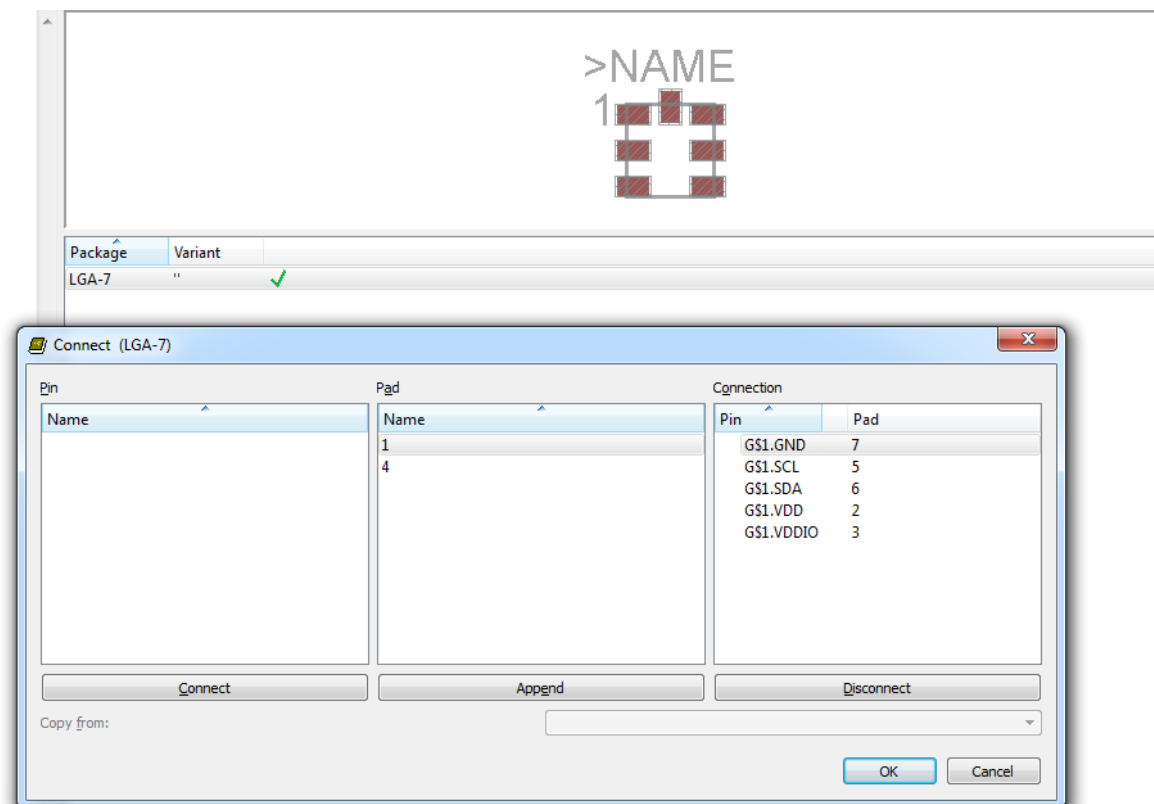
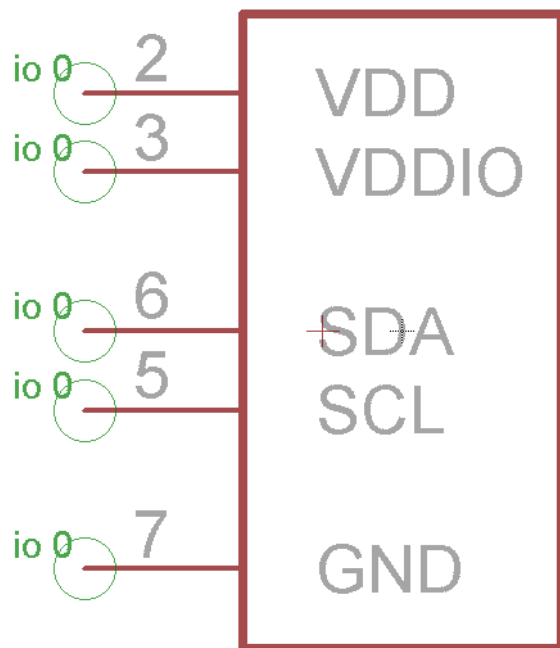
Sample Symbol View



Sample Device View

Add=next
Swap=0

G\$1
>VALUE



Where do libraries come from?

- **EAGLE standard libraries**
 - Some are great, some date from the time of disco
- **Online open-source libraries**
 - Contributed libraries on Eagle's site
 - Sparkfun, Adafruit, etc.
- **You!**
 - Complex or unusual parts are probably not in any library

Converting a System Diagram into an Electrical Schematic

Implementation Guidelines for 4 System Types

- **Control**
- **Sensing/Actuation**
- **Power**
- **Interconnect**

Implementing Control

- Choosing a microcontroller
 - AVR, PIC are popular choices
 - TI OMAP, Freescale, ARM7, ARM9...
 - Older architectures like 8051 or 16HC11
- Also OK to plan on using a *microcontroller board* and interfacing to its connectors
 - “Arduino shield”
 - Sensor/actuator boards (*a la L293 driver board*)
- Others (higher degree of integration/capability)
 - Raspberry PI, Beaglebone...

Implementing Control

- Don't forget the baggage
 - Usually specific programming infrastructure required ("toolchain")
 - A bunch of extra circuitry, specifically:
 - Required voltage regulation / decoupling
 - Programming connector (even if using a bootloader!)
- We usually use AVR due to availability of OSS `avr-gcc` compiler and `avr-dude` compiler. AVR Studio (windows only) also available free.
- Arduino
 - Uses AVR for the same reason
 - Also has bootloader / Processing interface for programming
 - If you like/need Arduino interface, consider making your own
 - 1.Download open source eagle files for your favorite Arduino version
 - 2.Modify design to add additional sensor/actuator interfaces to PCB
 - 3.Make PCB and re-release design files

Important Things to Remember on Control

- Voltage Compatibility
 - Modern ICs run at 3.3V or 1.8V, not 5V
 - If you need to hook up to a junky old sensor, may need level-shifting to prevent damage
- Make sure to add debugging output
 - Even a blinking LED helps iron out software kinks
 - A serial (or USB<->serial) port makes it even easier
- Basic system testing – aim for a few simple milestones
 - “Blink test” is a good first program
 - Each subsystem should be able to be independently tested and verified, even if only in debugging mode

Sensing and Actuation

- Sensing/Actuation lumps together subsystems that either:
 - Measure the physical world and produce digital or analog values for a controller, or
 - Take digital or analog values from a controller and effect change on the physical world
- Some sensors:
 - Light sensors (photocells, cameras, photodiodes, etc.)
 - Temperature sensors (thermistors, thermocouples, etc.)
 - Contact sensors (buttons, limit switches, pressure pads, etc.)
 - Rangefinders (IR pairs, IR rangefinders, sonar, laser rangefinders, etc.)
- Some actuators:
 - Light sources (LEDs, lamps, neon, etc.)
 - Motion (Motors, servos, steppers, solenoids, piezo elements, etc.)
 - Sound (speakers, buzzers, piezo elements, etc.)

Support Circuitry

- Most sensors/actuators require additional circuit elements to operate, such as:
 - Discrete components (capacitors, resistors)
 - Additional, non-logic level voltage sources (especially for motors)
 - Level translation
 - Communications protocols (e.g. RS232/485 to TTL)
 - Also commonly for old 5V components interfacing to modern ICs
 - Electrical connectors to connect off-board components
- Most devices explicitly tell you what support circuitry is needed in their **datasheets** (more on future lecture)

Actuators Brief: Motion Control

- Always use the least amount of control needed!
 - Only need to drive one direction? MOSFET/relay
 - Bi-directionality requires H-bridge & support circuits
- Aim for reasonable voltage/current
 - 5V/500mA is easier than 50V/50A
 - 24V@2A is easier than 2V@24A [why?]
- Many monolithic options available
 - Driving 1-4 motors can be as simple as one IC, a few capacitors, and your connectors
 - L293 == L298 with integrated flyback diodes
 - Many MOSFET designs / ICs do not require flyback
- For high power (>10W), it may be easier to look into hobby servos, off-board modules or motion control amps.

Implementing Power

- **Power** is mechanical work and also [**voltage X current**]
- All electromechanical devices require power to operate
- All modern electronics perform logical operations while generating heat
- When implementing a power system, understanding the **bounds** is essential:
 - Voltage ranges (min / max)
 - Current draw (quiescent / peak)
 - Storage capacity (mass / volume)
 - Runtime

Classifying Different Power Systems

Consider:

Voltage Current Capacity Runtime

- Digital watch
- Wireless sensor node
- R/C Car
- R/C Quadrotor
- Computer performing video analysis
- Electric car

How Power Affects PCBs

- May need multiple voltage sources
 - Motors may need higher voltage than logic
 - Different logic may require different voltages
- Current draw affects trace width and component size
 - Big currents require big traces
 - Regulators for 100mA much smaller than for 2A

Voltage Regulation

- Most systems designed to operate from a single source
 - Wall (A/C) via AC/DC converter
 - Battery pack
 - Source voltage is usually optimized for largest power consuming subsystem (e.g. motors)
- DC/DC converters used to create other subsystem voltages
 - Logic voltage levels (frequently 1.8V, 3.3V, 5V)
 - Analog supplies (+-5V, +-15V)
 - Other (500V photoflash bank, 5kV neon ballast)
- DC/DC converters also used to **regulate** voltages
 - Stable voltages are essential for logic ICs
 - Helps isolate subsystems from each other

Voltage Regulation

- **Linear Regulators**

- Can only step down voltages
- Dissipates excess as heat [voltage X subsystem current]
- Usually very clean signals
- Low cost and complexity
- Excellent for small voltage drops

- **Switching Regulators**

- Allows output voltage to be above and/or below input voltage
- Efficiencies typically 80-96%
- Higher cost
- Variable complexity – but Point of Load replacements available!
- Excellent for large voltage differences

Minimizing current can minimize power losses / regulator size

Linear vs. Switching Efficiency

- **Desired Output Voltage: 5V**

Input Voltage	Linear Efficiency	Switching Efficiency
5.5V	91%	80-90%
6V	83%	80-90%
12V	42%	80-90%
24V	21%	80-90%
3.3V	Not possible	80-90%

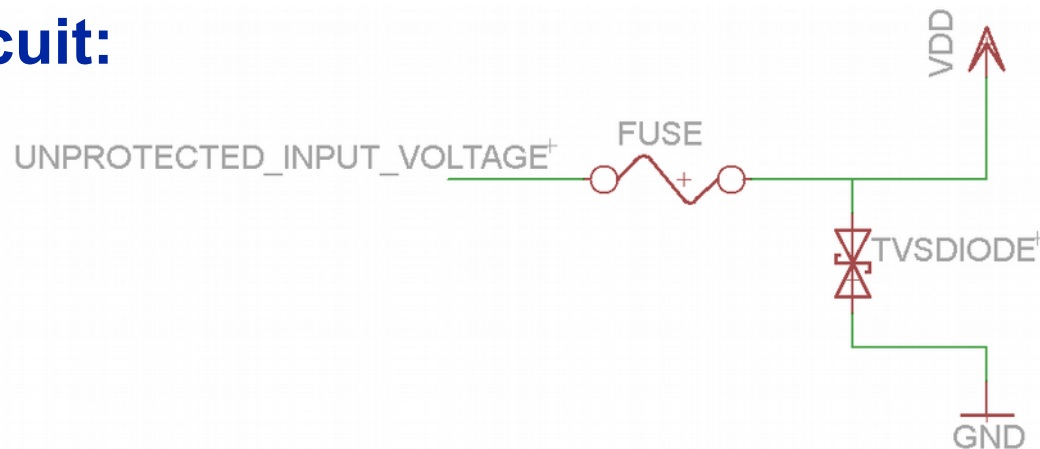
- **Efficiency is not everything. 21% efficiency might be just fine if you're drawing 500uA.**

Assembling a Power System

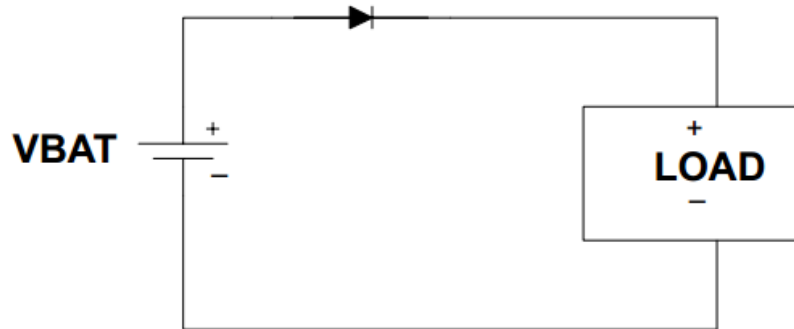
- Determine source voltage and current requirements
 - Optimize for primary power using subsystems
 - Add current to account for other subsystems *and conversion efficiencies*
- Determine voltages and current limits of regulated voltages
 - Primary power systems frequently run *unregulated*
 - May need several logic voltages or other supplies
- Other useful power system features
 - Switches (e.g. ON/OFF) are helpful
 - Fuses / breakers may be needed
 - Voltage and current monitoring
 - *Battery charge management*

Overvoltage and Reverse-voltage Protection

- **It's 3 AM, and you just plugged your robot in backwards. Would you like to:**
 - **A: Change a fuse?**
 - **B: Put out a small fire, go through the stages of grief, and then solder together new PCBs, order new parts, and explain to your professor why your project is going to be a week late because nobody from your group remembered this slide**
- **Here's a circuit:**

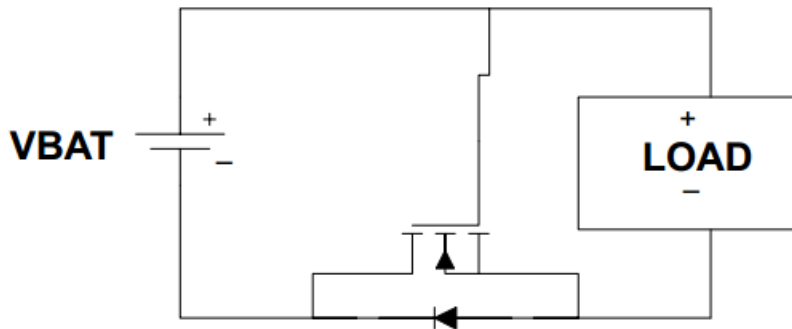


Reverse-Voltage Protection

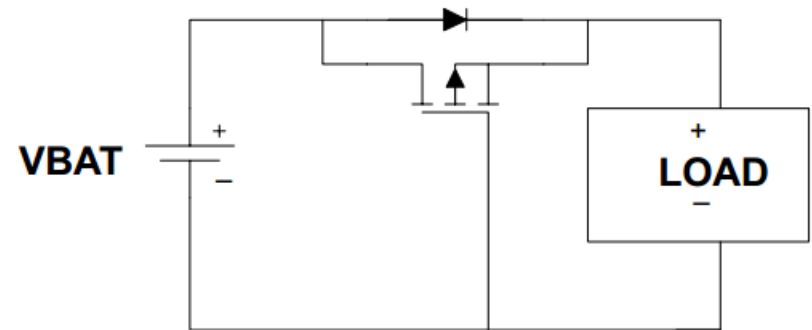


Diode in series with load

- Voltage drop
 - Batteries
 - Efficiency
- Use Schottky diode
 - Cost

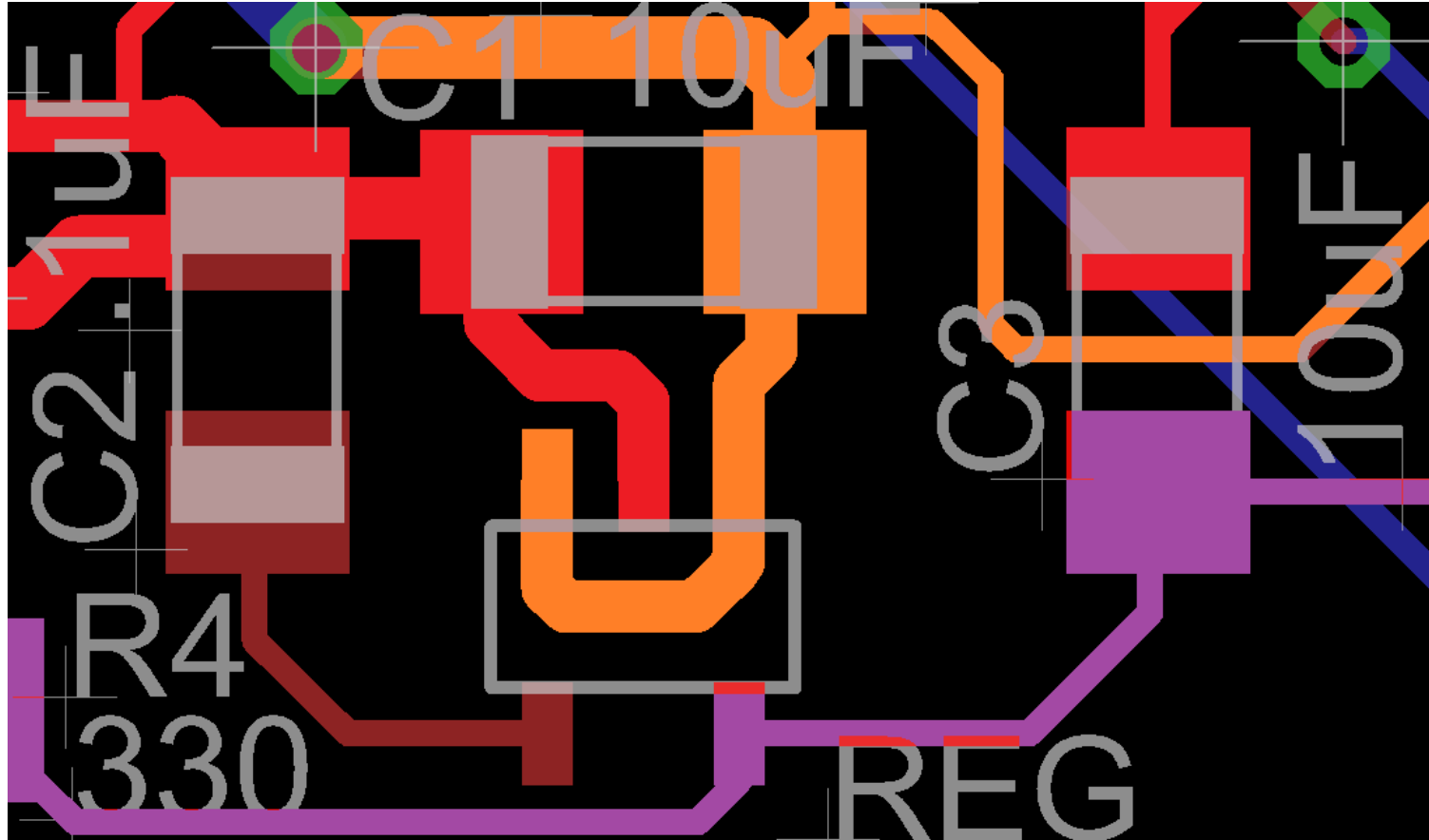


NMOS FET in the ground return path



PMOS FET in the power path

Don't Forget the Capacitors!

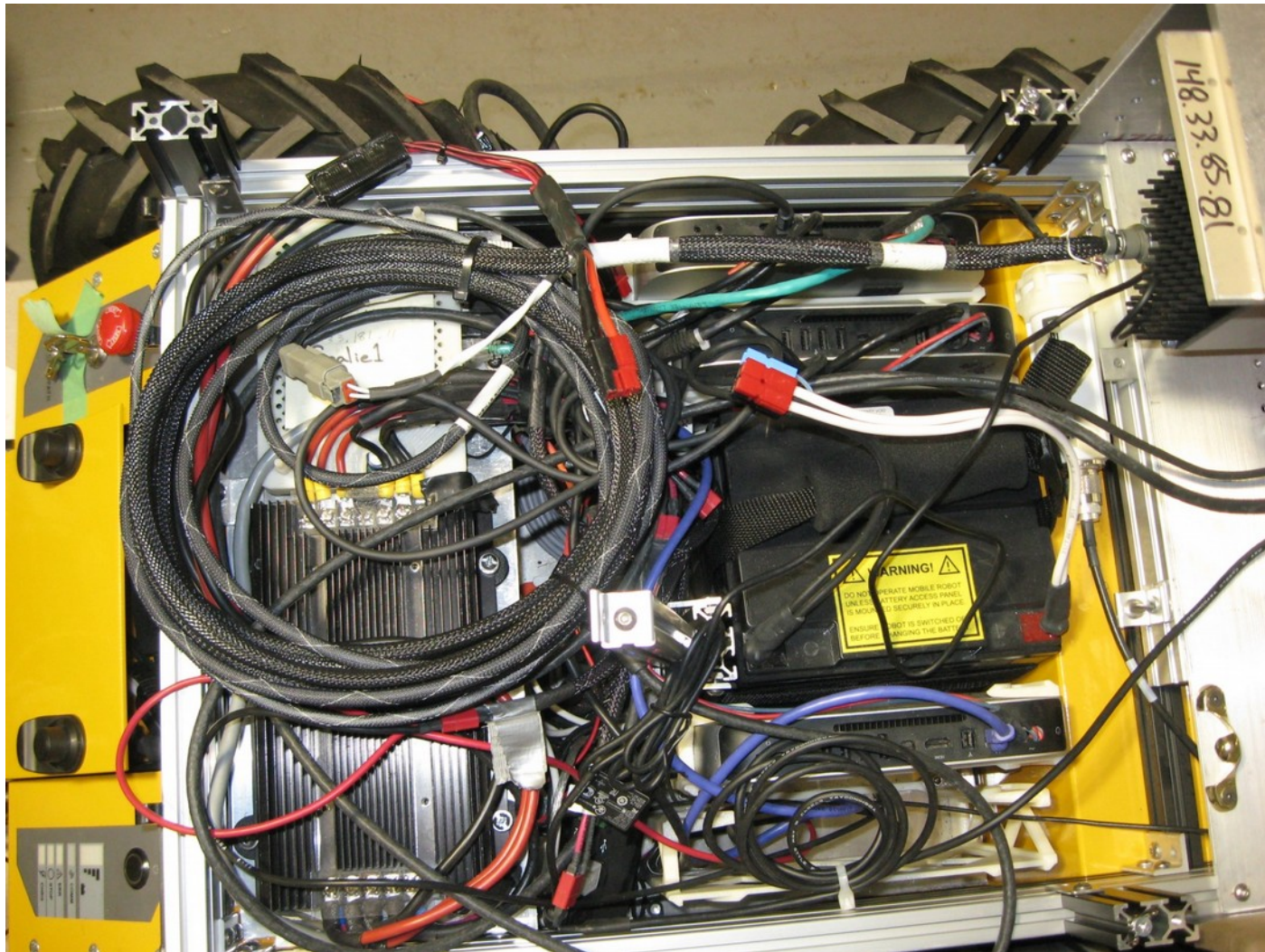


GND = Red, VDD = Yellow, VCC = Purple

Using Interconnect Appropriately

- Wire (and PCB traces) should be sized appropriately for current loads
 - '[PCB Trace Width Calculator](#)' is invaluable
 - Many wiring tables for various gauges show current capacity
 - Use stranded wire for connections!
- Avoid analog effects on your digital designs
 - Use short, thick traces for analog signals
 - Keep analog away from fast switching digital signals
 - Use ground planes or guard bands when appropriate
- Use appropriate connectors
 - Every connector is a potential point of failure
 - Observe current and connection cycle ratings
 - Use board-to-board when possible instead of board-wire-board

System Integration



Assignment Overview: Individual Assignment (Task3)

- **Due:** Tue Sep. 26th (One week from today)
- **Capture a hand-drawn schematic into Eagle, and make two layouts for it:**
 - One all through hole
 - One all surface mount
- **Create Eagle library versions of two parts from their datasheets**
- **Make sure to check out the two tutorials posted on Blackboard, and send questions to us**
- **Please, make sure that you**
 - Follow the file naming guidelines
 - Address any issues reported by ERC, DRC

Assignment Overview: Group Assignment (Task 6)

- **Due: Fri Oct. 6th**
- **Create a schematic and layout for a power distribution PCB**
 - Will need to choose appropriate regulators for each subsystem
 - Will need to design (from datasheet) Eagle library parts for those regulators
 - Will need to include OVP and RVP protection, and keep in mind the design considerations (like trace widths) mentioned in this presentation
 - Should be good preparation for the PCB you create for your own robots later in the semester

Teamwork and PCBs – Divvyng efficiently

- Schematic accumulation
 - Everyone can contribute subcircuits
 - One person in charge of overall schematic / collating contributions
- Part hunter
 - At least one person should be searching for parts
 - Parts should be **available** and **captured into Eagle**
- Verifier
 - Dedicated to finding logical errors in schematics or layout
 - Goes through internet/team created libraries and checks parts
- Layout and physical space planner
 - Determine board size and shape
 - Board mounting hole placement
 - Determine where all connectors should be located
 - Ensures parts sticking off board won't interfere with chassis