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4. Training the Network

**El acceso de auditoría vence el Sep 22, 2019**

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## 4. Training the Network

Forward propagation is simply the summation of the previous layer's output multiplied by the weight of each wire, while back-propagation works by computing the partial derivatives of the cost function with respect to **every** weight or bias in the network. In back propagation, the network gets better at minimizing the error and predicting the output of the data being used for training by incrementally updating their weights and biases using stochastic gradient descent.

We are trying to estimate a continuous-valued function, thus we will use squared loss as our cost function and an identity function as the output activation function.  $f(x)$  is the activation function that is called on the input to our final layer output node, and  $\hat{a}$  is the predicted value, while  $y$  is the actual value of the input.

$$C = \frac{1}{2}(y - \hat{a})^2 \quad (5.1)$$

$$f(x) = x \quad (5.2)$$

When you're done implementing the function `train` (below and in your local repository), run the script and see if the errors are decreasing. If your errors are all

under 0.15 after the last training iteration then you have implemented the neural network training correctly.

You'll notice that the `train` function inherits from `NeuralNetworkBase` in the codebox below; this is done for grading purposes. In your local code, you implement the function directly in your Neural Network class all in one file. The rest of the code in `NeuralNetworkBase` is the same as in the original `NeuralNetwork` class you have locally.

**In this problem, you will see the network weights are initialized to 1. This is a bad setting in practice, but we do so for simplicity and grading here.**

**You will be working in the file `part2-nn/neural_nets.py` in this problem**

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## Implementing Train

0.0/5.0 puntos (calificable)

**Available Functions:** You have access to the NumPy python library as `np`, `rectified_linear_unit`, `output_layer_activation`, `rectified_linear_unit_derivative`, and `output_layer_activation_derivative`

**Note:** Functions `rectified_linear_unit_derivative`, and `output_layer_activation_derivative` can only handle scalar input. You will need to use `np.vectorize` to use them

```
class NeuralNetwork(NeuralNetworkBase):

    def train(self, x1, x2, y):

        ### Forward propagation ###
        input_values = np.matrix([[x1],[x2]]) # 2 by 1

        # Calculate the input and activation of the hidden layer
        hidden_layer_weighted_input = # TODO (3 by 1 matrix)
        hidden_layer_activation = # TODO (3 by 1 matrix)

        output = # TODO
        activated_output = # TODO
```

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Presione ESC y después TAB o haga clic afuera del editor de código para salir

Sin Responder

Enviar

Ha realizado 0 de 20 intentos

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|   | <a href="#">In this formula: output_layer_error = (activated_output - y) * output_layer_activation_derivativ...</a>  |    |
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