

Given:
(Noisy) SISO system

**Choose optimization
criterion:**

- TD (with l_1 -trick) (3.12)
- FD (with l_1 -trick) (3.27)
- FD (without l_1 -trick) (3.18)
- WNLS (3.26)

Choose:

- Reference $M(\Omega)$
- Controller
structure $K(\Omega, \rho)$

