# MARK HEDLEY JONES

Experience in both research and commercial development environments Robotic system design, implementation, and development Hold a bachelor's, master's, and doctoral degrees

Nationality: New Zealand
Date of birth: October 1984
Language: English (Native), Japanese (N3)



# **SKILLS**

### Technical:

- Experience developing **ROS** based robotic systems across four multi-million dollar projects (7+ years)
- · Implementation of computer vision systems (OpenCV & Deep Learning) for real-time identification
- Designing mechanical components and modeling using CAD tools (SolidWorks, 6+ years)
- Software development in Linux (10+ years) with C/C++(7+ years), and Python (7+ years)
- · Electronic design (PCB/embedded) and including fail-safe system architecture

#### Communication:

- Managing a small research team (6-10 people) and presenting progress at board meetings
- Publishing research papers, presenting at international conferences, and writing theses
- · Mentoring post-graduate students and demonstrating in undergraduate laboratories

#### Miscellaneous:

- Financial management of project spending with direct control of company credit cards
- · Workshop competency including use of mills (manual & CNC), lathes, MIG welder

# **EMPLOYMENT**

# Software Engineer - Mapping & Simulation & Object Detection

SEQSENSE November 2018 - Present

Software engineering focusing on map creation, simulation environments, and object detection Developing and maintaining a 3D map generation system that runs across desktop, cloud, and our robot (real-time). Tasks include:

- creation of an on-line lidar-based mapping system to generate point-cloud-data (PCD) maps;
- development of an on-line object detection system based on lidar and camera inputs;
- developing and maintaining a simulation environment (Gazebo) that closely mimics robot behaviour;
- producing and maintaining accurate robot model definitions (URDF) from CAD models.

## Post-Doctoral Researcher - Autonomous Navigation

Robotics Plus Ltd., employed by The University of Auckland.

December 2017 - October 2018

Developed navigation software for heavy-duty vehicles used in outdoor environments. Tasks included:

- integrating and tuning real-time SLAM, point-cloud processing, and path-planning in orchards;
- selecting and integrating lidar, cameras, radars, compasses, encoders, IMUs, and GNSS systems;
- personally responsible for the safety of people and infrastructure regarding our autonomous vehicle;
- · development of a web-based graphical user interface to monitor and control our autonomous vehicle.

## Post-Doctoral Researcher - Robotic Hardware Development

Robotics Plus Ltd., employed by The University of Waikato.

March 2015 - December 2017

Designed and built a heavy-duty outdoor vehicle, fruit harvesting robot, pollination robot. Designed robotic systems (hardware & firmware) and managed a team of post-graduate researchers. Tasks included:

- · financial management, ordering, report writing, project planning, and resource coordination;
- component selection, vehicle design and assembly, electrical hardware integration and testing.
- managing a research team consisting of doctoral and masters students, coordinating between universities;
- developing ROS based systems to control robotic arms, precision spraying systems, and an electric vehicle;

# **Previously:**

Web Developer Department of Science & Engineering (The University of Waikato)

2013 - 2014

Developed an interactive tutorial web-app used by all 1st year electronic engineering students. (More)

Lab Demonstrator Department of Science & Engineering (The University of Waikato)

2013 - 2014

Managed electronics laboratories, demonstrated electronic concepts, and graded assignments and final exams.

#### Web Developer Self-employed

2010 - 2013

Built an online rental-property advertising company. Sourced investment, developed partnerships, marketing. (More)

Researcher Department of Biological Science (The University of Waikato)

2010

Created electric field simulations of an electro-fishing boat to improve its ability to catch pest fish species. (More)

#### Audio/Visual installation 021SOUNDTECH

2006 - 2007

Traveled across New Zealand installing high-end audio equipment into under-construction public venues.

#### **Assembly Technician RENNACS**

2005 - 2006

Assembled, soldered, flashed, tested, and debugged automotive fault-code readers.

## Further back:

Owner/operator of a property-maintenance business; owner/operator of a rental-property advertising website; farm-hand; house restoration; photo printing in a film processing lab; customer service at a delicatessen; cooking pizzas at a fast-food resturant; swimming pool maintenance and sample gathering; photo-cataloging high-voltage electrical substation equipment; painting tapestry canvases; computer assembly, repairs & maintenance.

# **EDUCATION**

- · Doctorate of Philosophy The Electrical Properties of Interfacial Double Layers
- 2011 2015
- Modelled electrical conductivity of implanted medical electrodes using circuit simulation tools
- Conducted automated electrical impedance measurements in a hospital operating theatre
- Developed software libraries to automate oscilloscopes and function generators
- · Masters of Engineering with First Class Honours

2009

- Simulated a novel design of high-frequency power sensor (170 GHz) to determine performance
- Built and measured the performance of scale models of RF sensors to verify simulation results
- Visited NIST, Boulder Colorado, to find understand sensor traceability testing at the US national level
- Bachelor of Science Major in Electronics focusing on Mechatronics

2005 - 2008

# **AWARDS & SCHOLARSHIPS**

Waikato Doctoral Scholarship	\$ 56 000 USD	2010
Agilent Technologies Research Scholarship	\$ 36 000 USD	2009
Summer Research Scholarship	\$ 5 000 USD	2008
ENZcon – best research paper		2011
<ul> <li>ENZcon – runner up best presentation</li> </ul>		2014

# **LICENCES / VISAS**

- Japanese Permanent Residency
- Japanese Drivers Licence
- New Zealand Drivers License

# **PHILOSOPHY**

The ability to teach yourself is more valuable than your education
Test ideas early and invest time in reducing the cost to re-test
Something isn't right just because other people are doing it
Truly novel solutions require creativity, not experience

# **PUBLICATIONS**

Please see my website for an up-to-date list of publications.

# REFEREES

Available upon request