

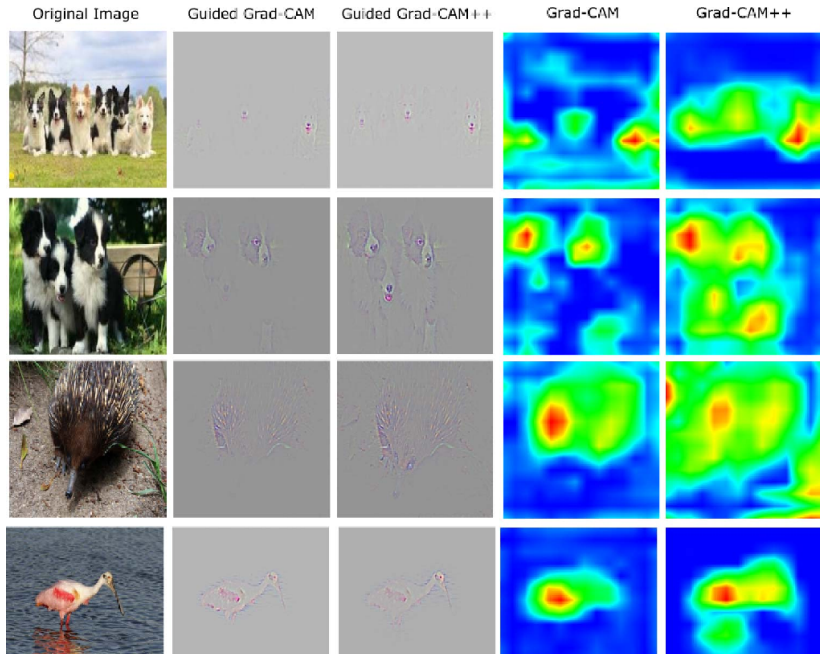
# Formal Concept Analysis, Lattice Polynomials and Approximation

Levan Tsinadze

Tbilisi State University

2022

# Why Formal Concept Analysis



# Aggregation of Common Features

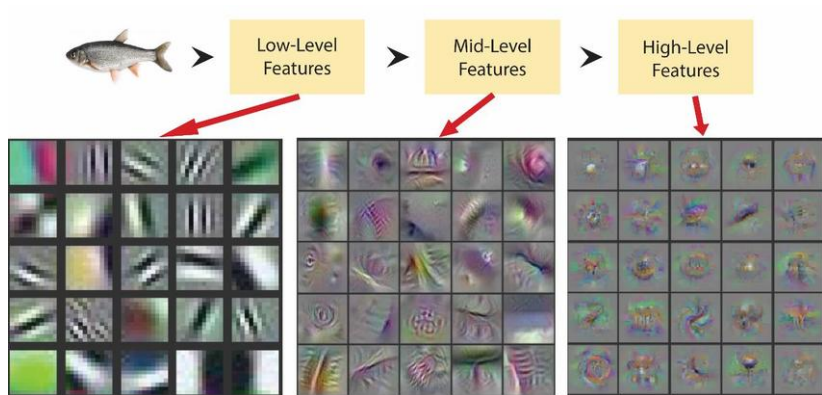


Figure: Hierarchical Aggregation of Features

# Concept Partial Order

As it is defined in [1]:

- ▶ Formal Context is a triple  $(G, M, I)$  where  $G$  and  $M$  are sets and  $I \subset G \times M$  is a relation between them which is called incidence relation,  $G$  is called objects and  $M$  attributes
- ▶ For subset of objects  $A \subset G$  define
$$A' = \{m \in M \mid (g, m) \in I \text{ for all } g \in A\}$$
- ▶ For subset of attributes  $B \subset M$  define
$$B' = \{g \in G \mid (g, m) \in I \text{ for all } m \in B\}$$
- ▶ A concept of the context  $(G, M, I)$  is a pair  $(A, B)$  where  $A \subset G$ ,  $B \subset M$  with properties  $A' = B$  and  $B' = A$
- ▶ For two concepts  $(A_1, B_1)$  and  $(A_2, B_2)$  define order
$$(A_1, B_1) \leq (A_2, B_2) \iff A_1 \subset A_2 \iff B_1 \subset B_2$$

# Example of Concepts

	leathery peel	sweet	sour	juicy	contains seeds	made from milk	sandwich filling
banana	×	×			×		
goat cheese						×	×
ice cream		×				×	
kiwifruit		×		×	×		
lemon	×		×	×	×		
orange	×	×		×	×		
strawberry		×		×	×		
yoghurt						×	

Figure: Incidence Table of Fruits.

# Hesse Diagram of Concepts

	s	t	u	v	w
A		×	×		
B	×			×	
C		×		×	×
D		×	×	×	×

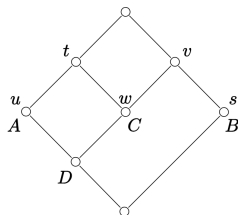


Figure: Cross-table and Hesse Diagram

Context with order might be visualized as a Hesse diagram

# Concept Lattice

Denote set of all concepts on context  $(G, M, I)$  as  $\mathcal{B}(G, M)$   
Then it is easy to prove that  $\mathcal{B}(G, M)$  is complete lattice with meet and join operations:

$$\bigvee_{j \in J} (A_j, B_j) = ((\bigcup_{j \in J} A_j)', \bigcap_{j \in J} B_j)$$

and

$$\bigwedge_{j \in J} (A_j, B_j) = (\bigcap_{j \in J} A_j, (\bigcup_{j \in J} B_j)')$$

With this we can refine context or reduce it, or find appropriate attributes for class of objects for clusterization, classification, knowledge discovery, etc.

# Formal Concept Analysis and Decision Trees

If we consider objects as in our dataset and attributes as features, we can define analysis of machine learning model and find similarities with formal concept analysis an machine learning architectures

- ▶ In [2] defined several methods for classification using Formal Concept Analysis
- ▶ In [3], [4], [5] Formal Concept Analysis is applied for decision tree classification and found different concept classification rules also conversion of lattice to the decision trees



# Piecewise Approximation Functions

In [13] neural networks are defined as continuous piecewise linear functions and representation of each finite piece as continuous piecewise linear functions with neural networks established. Which gives isomorphic functor  $F : \mathbf{NN} \rightarrow \mathbf{CPWL}$  among categories of neural networks and continuous piecewise linear functions.

For piecewise approximation defined on  $X$  as  $\mathcal{F} : X \times P \rightarrow Y$  where for each  $p \in P$  projection is basis:

$$\mathcal{F}|_{X \times \{p\}} = \varphi : X \rightarrow Y$$

we can define  $\mathcal{B} \subset 2^X$  as pieces or batches for which approximation happens on one particular basis function.

Define  $\mathcal{A} = (\mathcal{A}, \leq)$  partially ordered set and  $\alpha : \mathcal{F} \times 2^X \rightarrow \mathcal{A}$  which maps each pair  $(\varphi, B) = \varphi(B)$  to the single approximation  $A \in \mathcal{A}$

- For each  $B \in \mathcal{B}$  approximation happens on one particular basis function  $\varphi$
- $\cup \mathcal{B} = X$

For instance linear regression or neural network as piecewise universal approximator for  $l_2$  or  $l_1$  with  $\mathcal{A} = \mathbb{R}_+$

# Spetwise Approximation

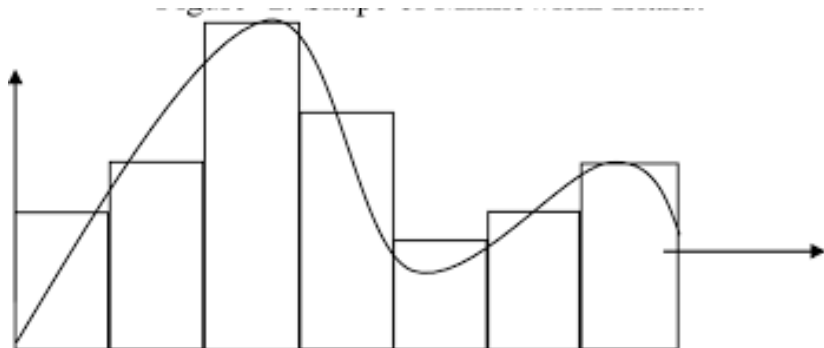
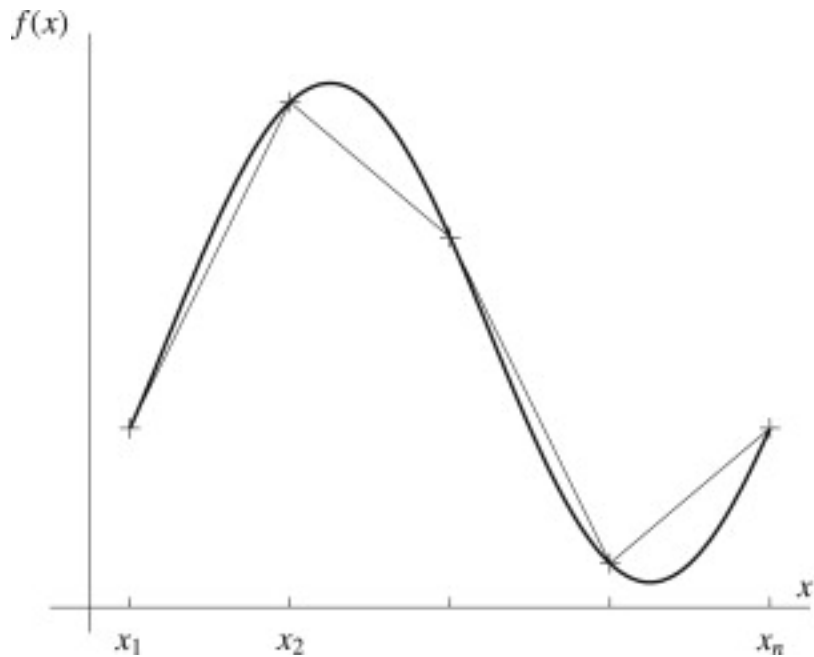


Figure: Step by step approximation (MLP).

## Priecwise Linear Approximation



# Sigmoid Approximation

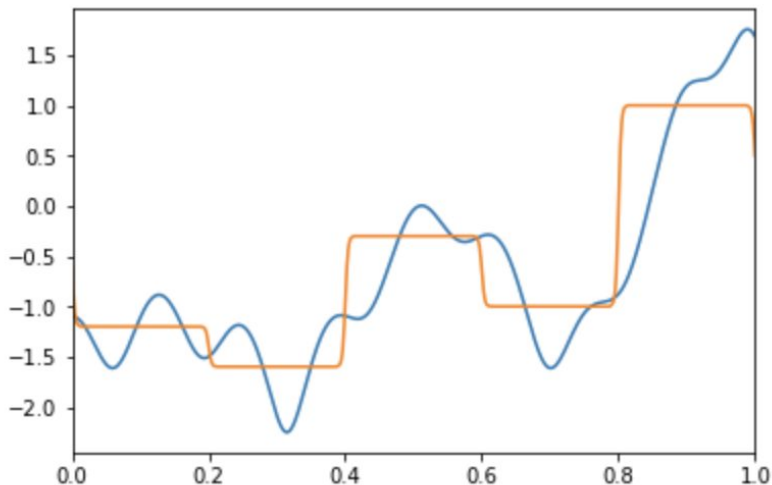


Figure: Piecewise continuous nonlinear approximation (Sigmoid).

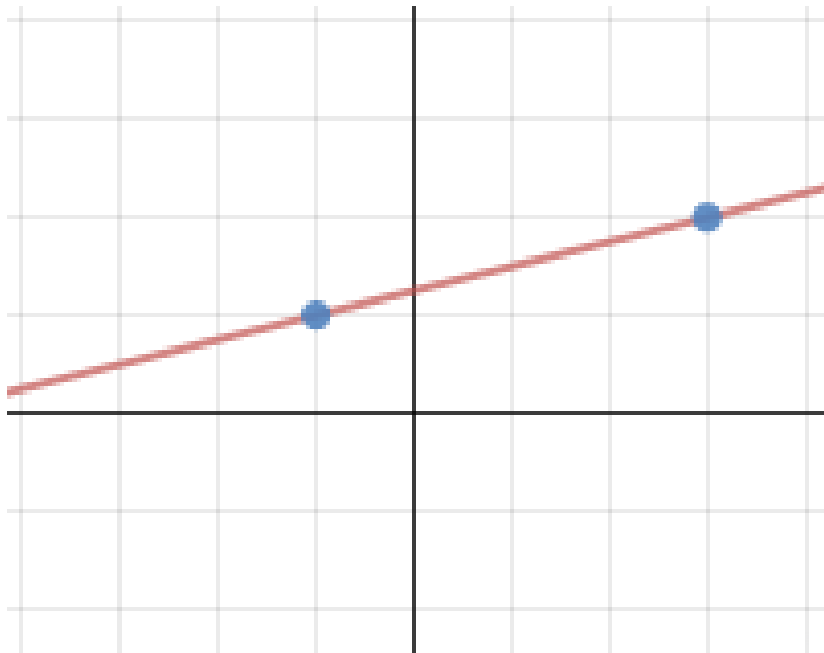
# Piecewise linear / continuous piecewise linear function as lattice polynomials

Consider pairs  $(\varphi, B)$  on batches and order:

- ▶  $(\varphi, B) \leq (\varphi, D)$  if  $\alpha(\varphi(B)) \leq \alpha(\varphi(D)) \iff B \subset D$
- ▶  $\varphi(x) \wedge \psi(y) = \mu(\{x, y\})$  where  $\varphi, \psi$  and  $\mu$  are basis of  $\mathcal{F}$

Of course  $\wedge$  operation is defined with respect to  $\mathcal{A}$  and it is more categorical limit which is unique up to isomorphism

## Data Fitting on Two Items



## Data Fitting on Two Items

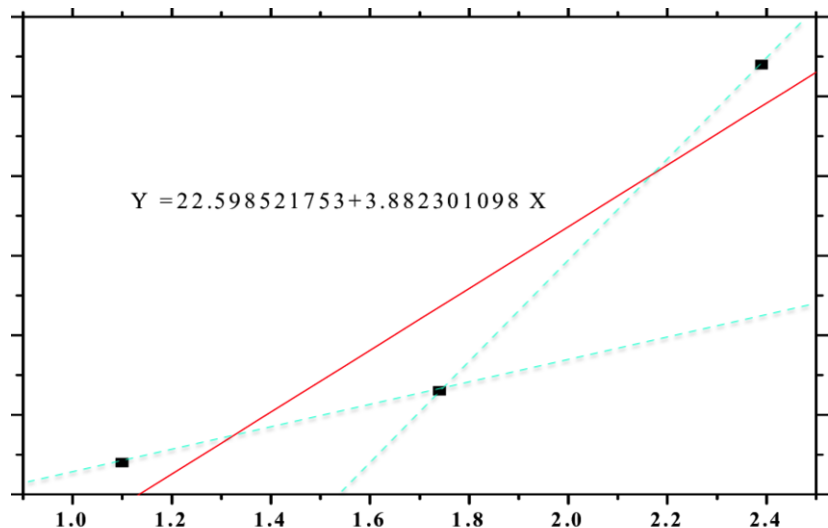


Figure: Approximation on three points.

# The Best Approximation Batches

Consider pairs  $(\varphi, B)$  on batches and order:

- ▶  $\bigwedge_{\varphi \in \mathcal{F}} (\varphi(B))$
- ▶  $\bigvee_{B \in \mathcal{B}} (\varphi, B)$

This gives the best approximation batches  $\mathcal{B}$  for  $\mathcal{F}$  function and  $\mathcal{A}$  approximation.



# Lattice Polynomial and Formal Concept

So we can consider neural network, linear regression and multi-linear regressions as:

- 1  $K(B) = \bigwedge_{\varphi \in \mathcal{F}} \varphi(B)$ . fitting on batch
- 2  $K(\mathcal{A}, \mathcal{F}) = \bigvee_{B \in \mathcal{B}} K(B)$  fitting on functions where  $\varphi(x) \vee \psi(x) = \max(\alpha(\varphi(x)), \alpha(\psi(x)))$  as in [6], [7] and [8] but towards approximation.

# Hierarchical Lattice Polynomials

If we define refinement of  $\mathcal{B}^l$  by the  $\mathcal{B}^{l+1}$ :

- 1 For each  $B^l \in \mathcal{B}^l$  there exists  $B^{l+1} \in \mathcal{B}^{l+1}$  such that  $B^{l+1} \subset B^l$
- 2 For each  $B^l \in \mathcal{B}^l$  we have  $\bigcup_{B^{l+1} \subset B^l} B^{l+1} = B^l$

We can distinguish layer of the lattice polynomial:

$$K^{l+1}(\mathcal{A}) = \bigvee_{B^{l+1} \in \mathcal{B}^{l+1}} K^l(B^{l+1})$$

# Representation Learning

For later layers we can investigate lattice polynomial of this layer:

$$K^{l+1}(\mathcal{A})$$

If we fix the layer  $l$  we can consider approximation / representation power of the appropriated polynomial

## Further Work 1

Investigate lattice polynomial and learning objective along with natural topology / metric / (quasi) uniform structures on  $X$  and  $Y$  spaces

- ▶ Investigate model capacity by amount of batches and memorization capacity [12]
- ▶ Investigation if kernel machines can be represented as a lattice polynomials
- ▶ Compare lattice polynomials of different models and analysis of similarities [9], [10]
- ▶ Investigate overparametrization [11]
- ▶ Self-supervised representation learning and transfer learning as lattice polynomials [27], [28], [29], [30], [31], [32], [33], [35], [36], [37], [38], [39], [40], [41], [42], [43], [44], [45], [46].
- ▶ Investigate (uniformly) continuous property for each lattice polynomial
- ▶ Compact and locally compact structures

## Further Work 2

- ▶ Completeness and completion of  $X$  and  $Y$  spaces
- ▶ Tropical geometry of machine learning and deep learning [16], [17]
- ▶ Analysis on generalization capacity and overfitting






Whole area for research.






# Thank You







# Questions








Thank You Angain









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