

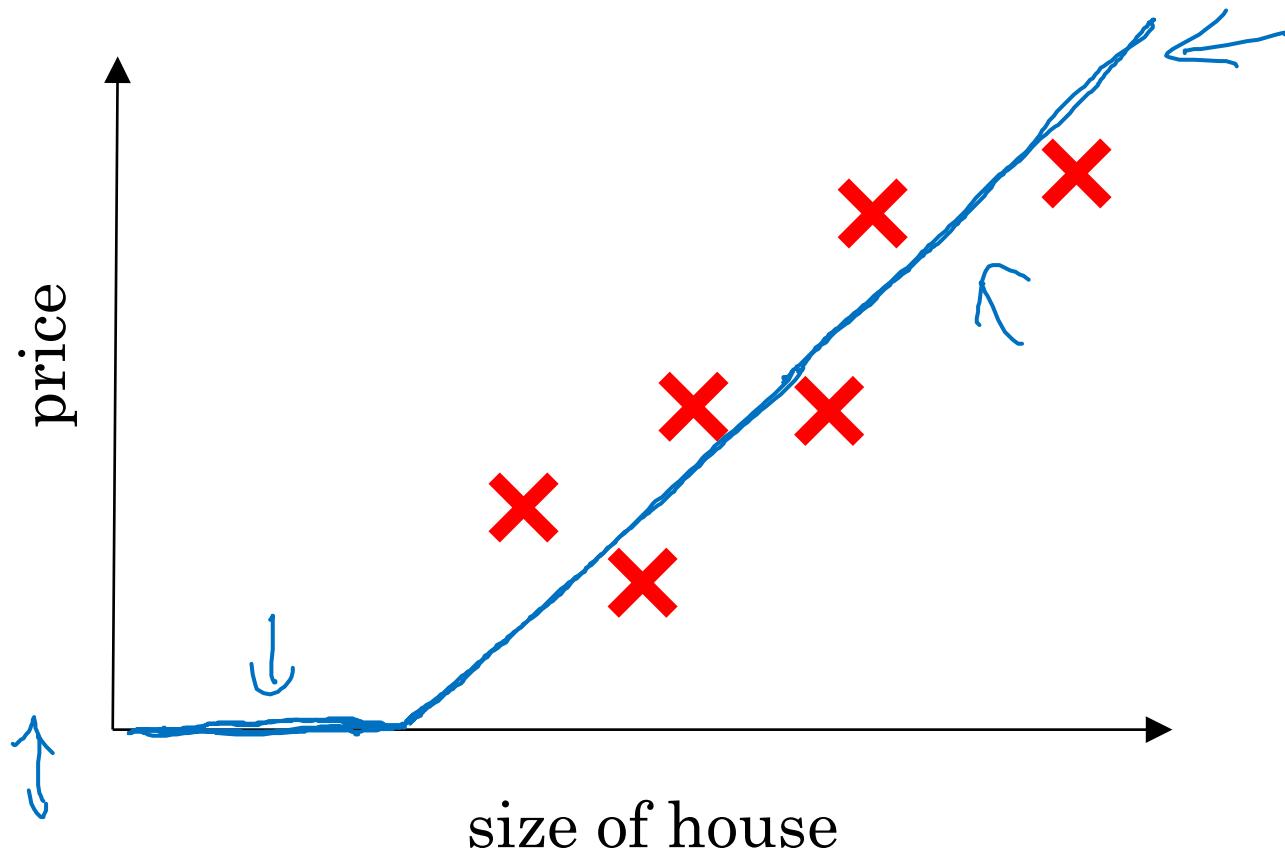


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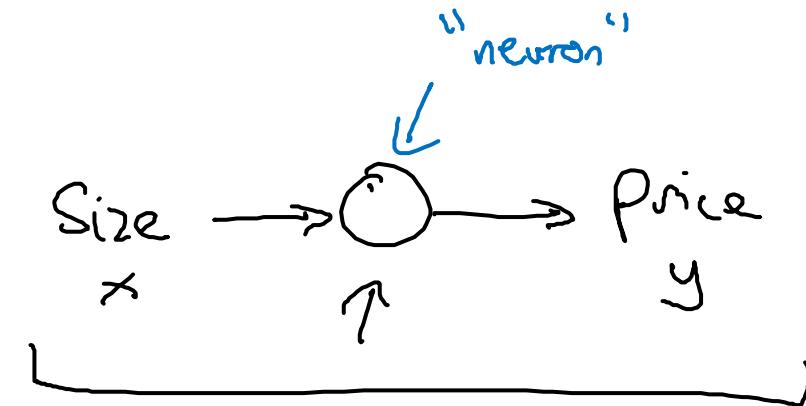
Introduction to Deep Learning

What is a Neural Network?

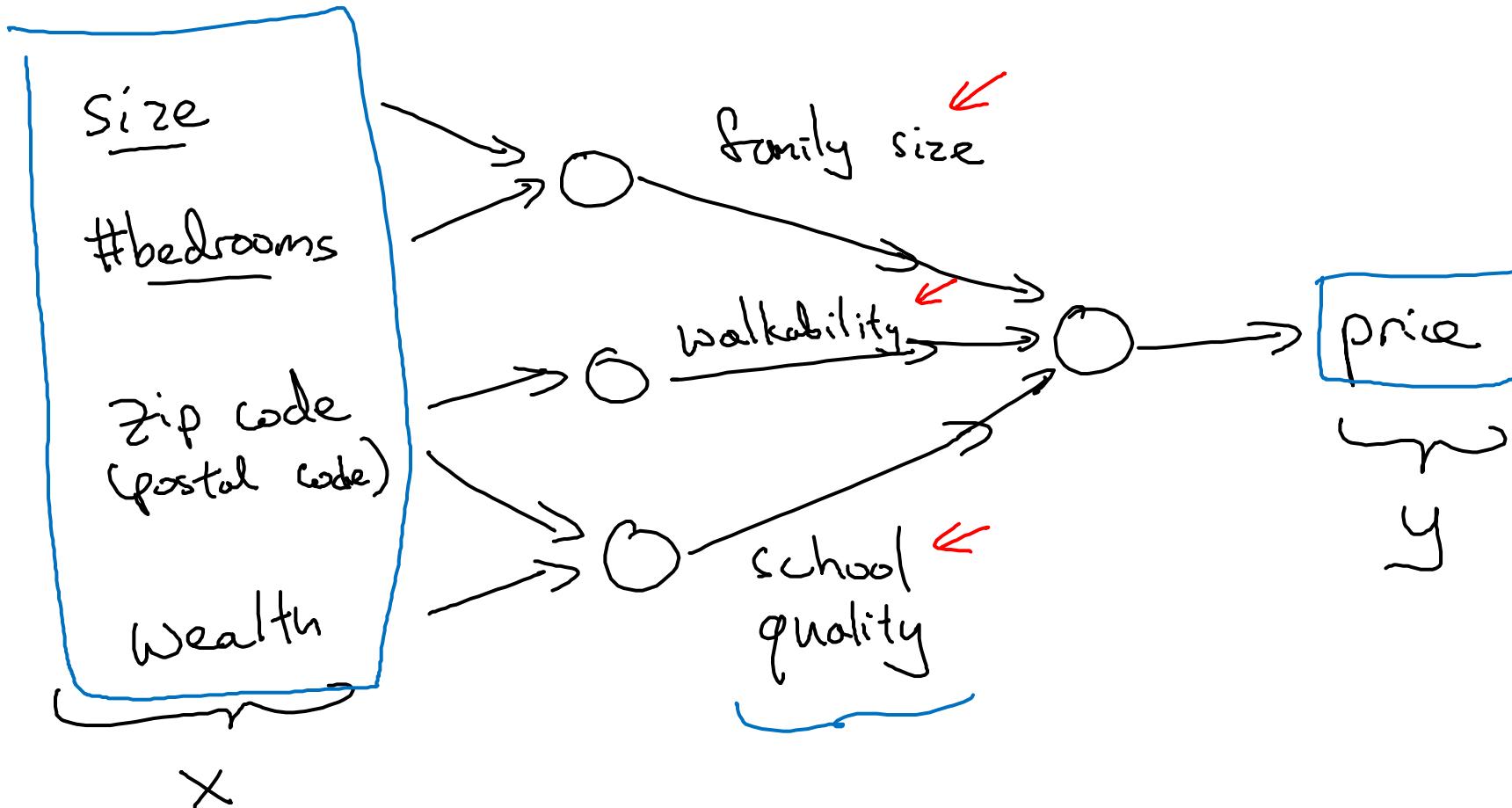
Housing Price Prediction



ReLU
Rectified
Linear
Unit

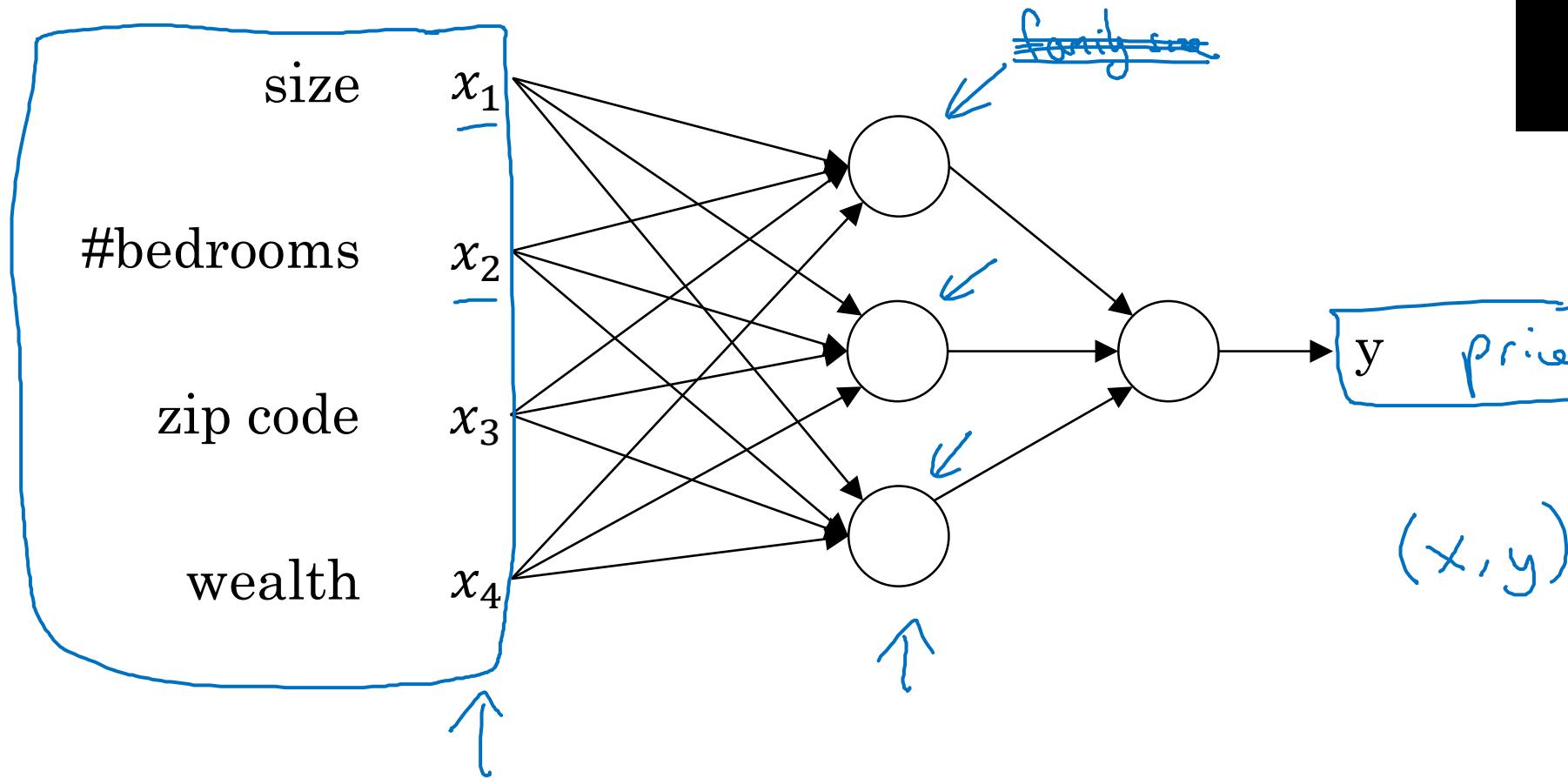


Housing Price Prediction



Housing Price Prediction

Drawing of
previous Image





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Introduction to Deep Learning

Supervised Learning with Neural Networks

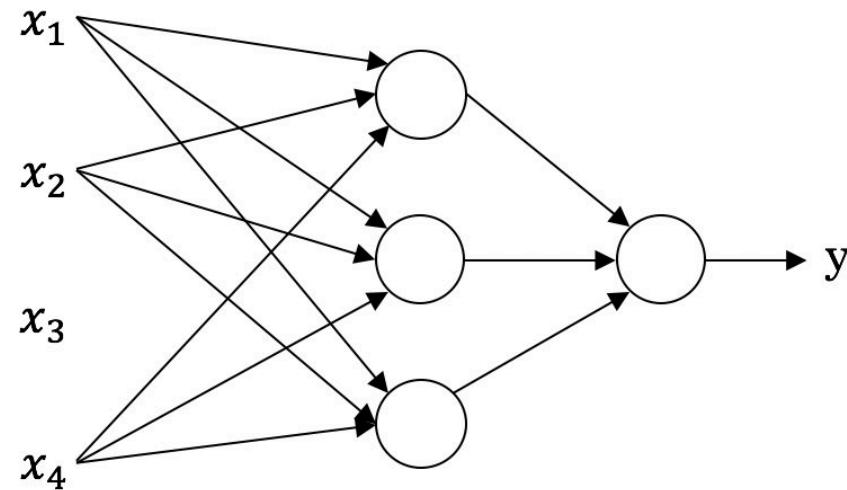
Supervised Learning

Input(x)	Output (y)	Application
Home features	Price	Real Estate
Ad, user info	Click on ad? (0/1)	Online Advertising
Image	Object (1,...,1000)	Photo tagging
Audio	Text transcript	Speech recognition
<u>English</u>	Chinese	Machine translation
<u>Image, Radar info</u>	Position of other cars	Autonomous driving

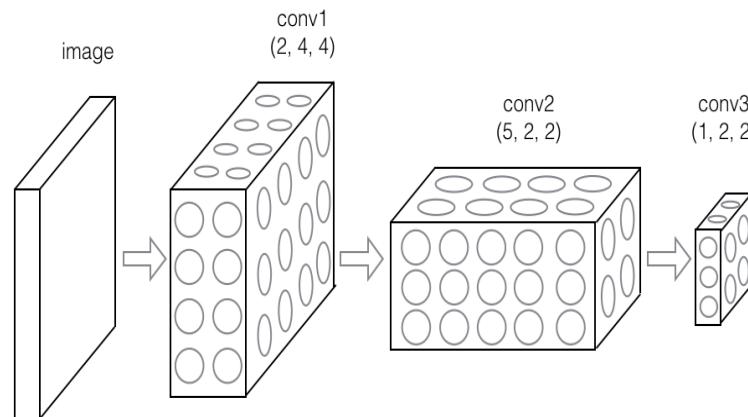
Annotations:

- A blue arrow points from "Input(x)" to "Home features".
- A blue arrow points from "Input(x)" to "Ad, user info".
- A blue arrow points from "Input(x)" to "Image".
- A blue arrow points from "Input(x)" to "Audio".
- A blue arrow points from "Input(x)" to "English".
- A blue arrow points from "Input(x)" to "Image, Radar info".
- A blue arrow points from "Output (y)" to "Price".
- A blue arrow points from "Output (y)" to "Click on ad? (0/1)".
- A blue arrow points from "Output (y)" to "Object (1,...,1000)".
- A blue arrow points from "Output (y)" to "Text transcript".
- A blue arrow points from "Output (y)" to "Chinese".
- A blue arrow points from "Output (y)" to "Position of other cars".
- A blue brace groups "Real Estate" and "Online Advertising" under the heading "Standard NN".
- A blue brace groups "Photo tagging" and "Speech recognition" under the heading "CNN".
- A blue brace groups "Machine translation" and "Autonomous driving" under the heading "RNN".
- A blue brace groups "Autonomous driving" and "Custom Hybrid" under the heading "Custom Hybrid".

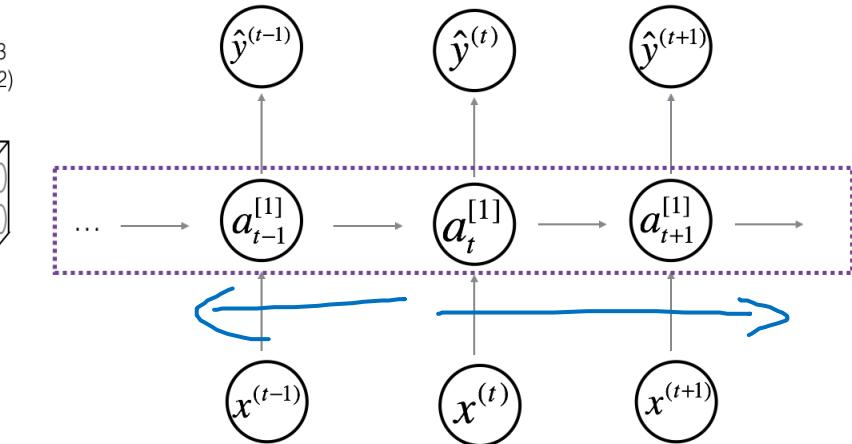
Neural Network examples



Standard NN



Convolutional NN



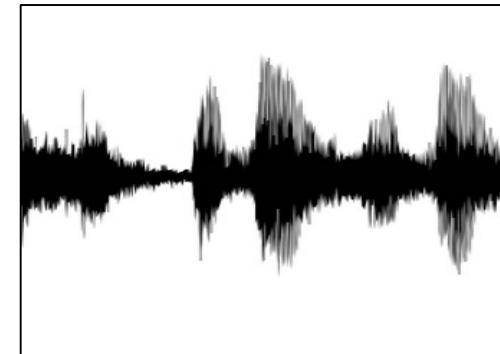
Recurrent NN

Supervised Learning

Structured Data

Size	#bedrooms	...	Price (1000\$)
2104	3		400
1600	3		330
2400	3		369
:	:		:
3000	4		540

Unstructured Data



Audio

Image

User Age	Ad Id	...	Click
41	93242		1
80	93287		0
18	87312		1
:	:		:
27	71244		1

Four scores and seven years ago...

Text

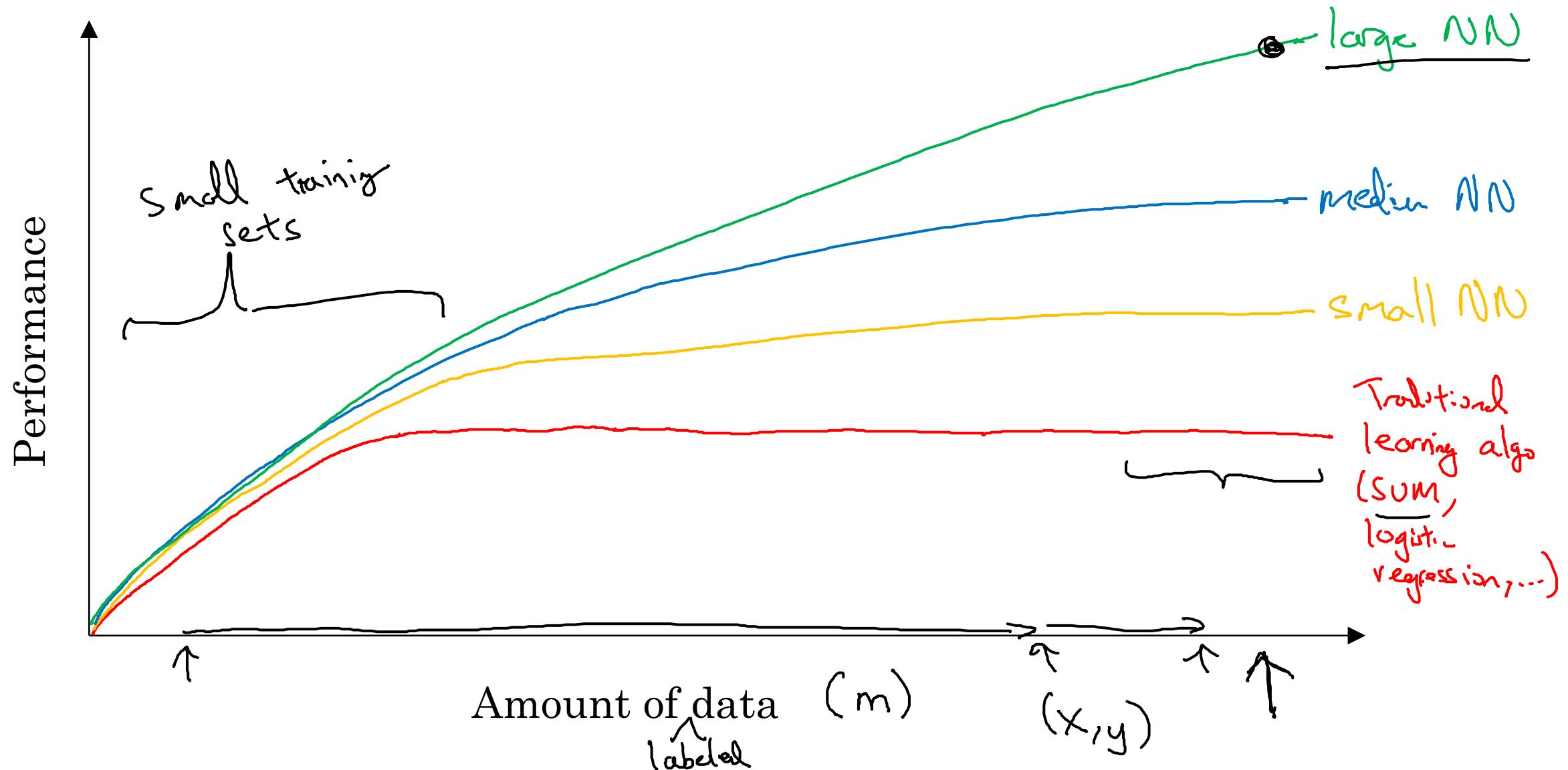


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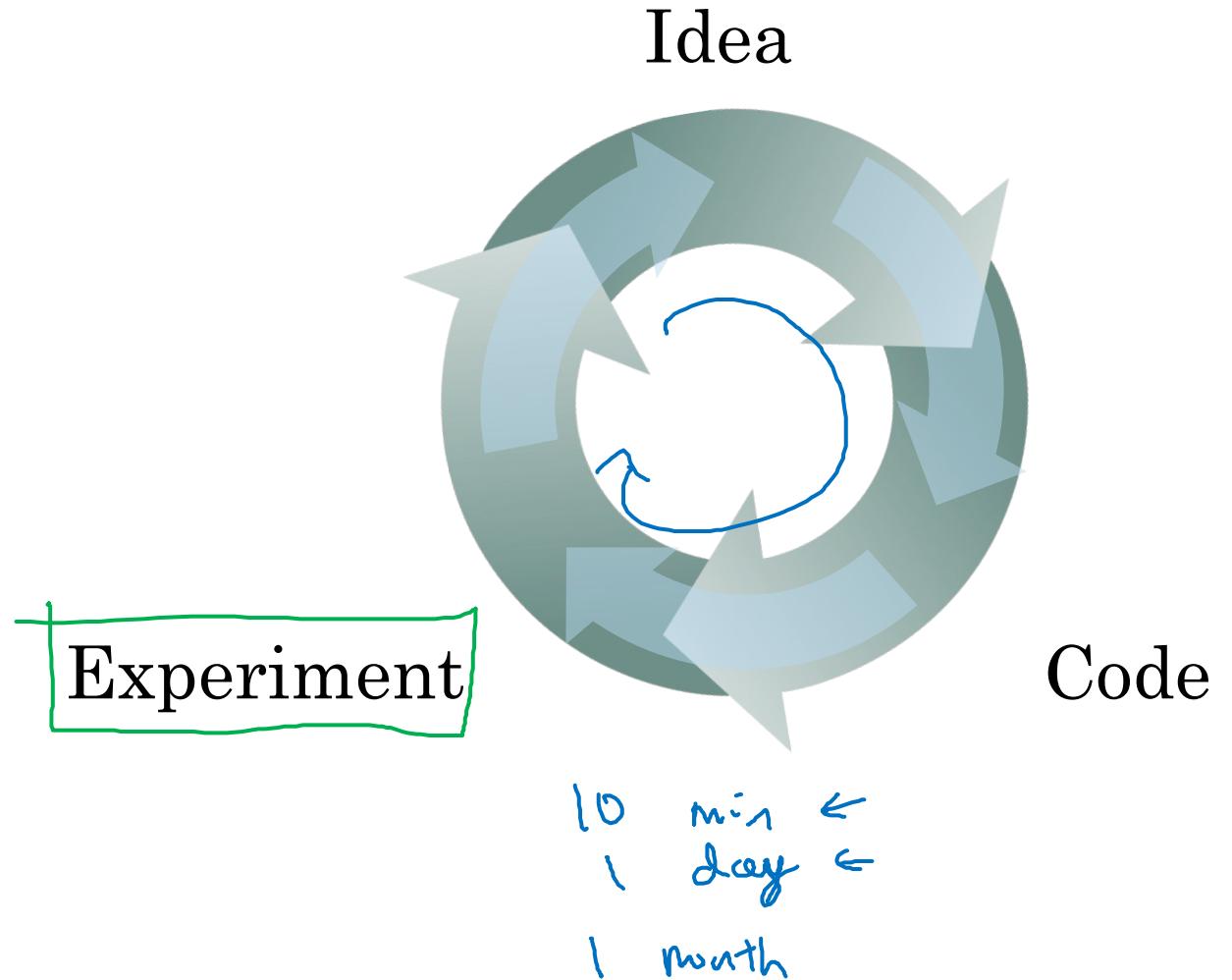
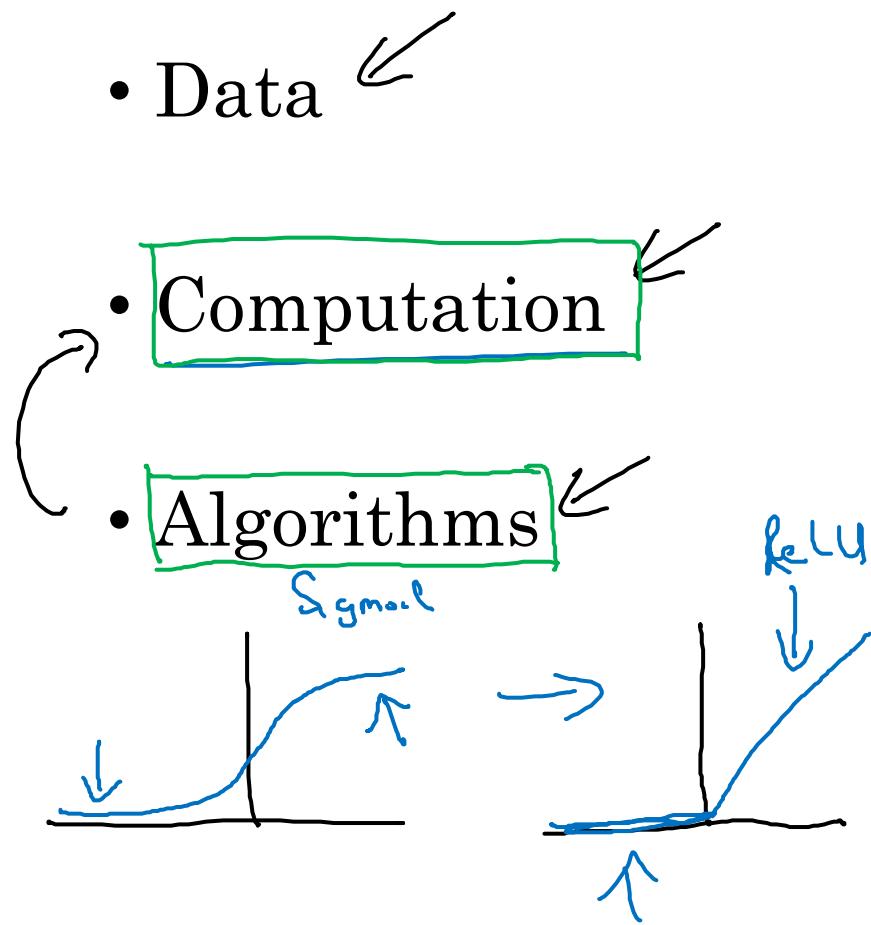
Introduction to Neural Networks

Why is Deep Learning taking off?

Scale drives deep learning progress



Scale drives deep learning progress





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Introduction to Neural Networks

About this Course

Courses in this Specialization

1. Neural Networks and Deep Learning ←
2. Improving Deep Neural Networks: Hyperparameter tuning, Regularization and Optimization
3. Structuring your Machine Learning project
4. Convolutional Neural Networks
5. Natural Language Processing: Building sequence models

Outline of this Course

Week 1: Introduction

Week 2: Basics of Neural Network programming

Week 3: One hidden layer Neural Networks

Week 4: Deep Neural Networks



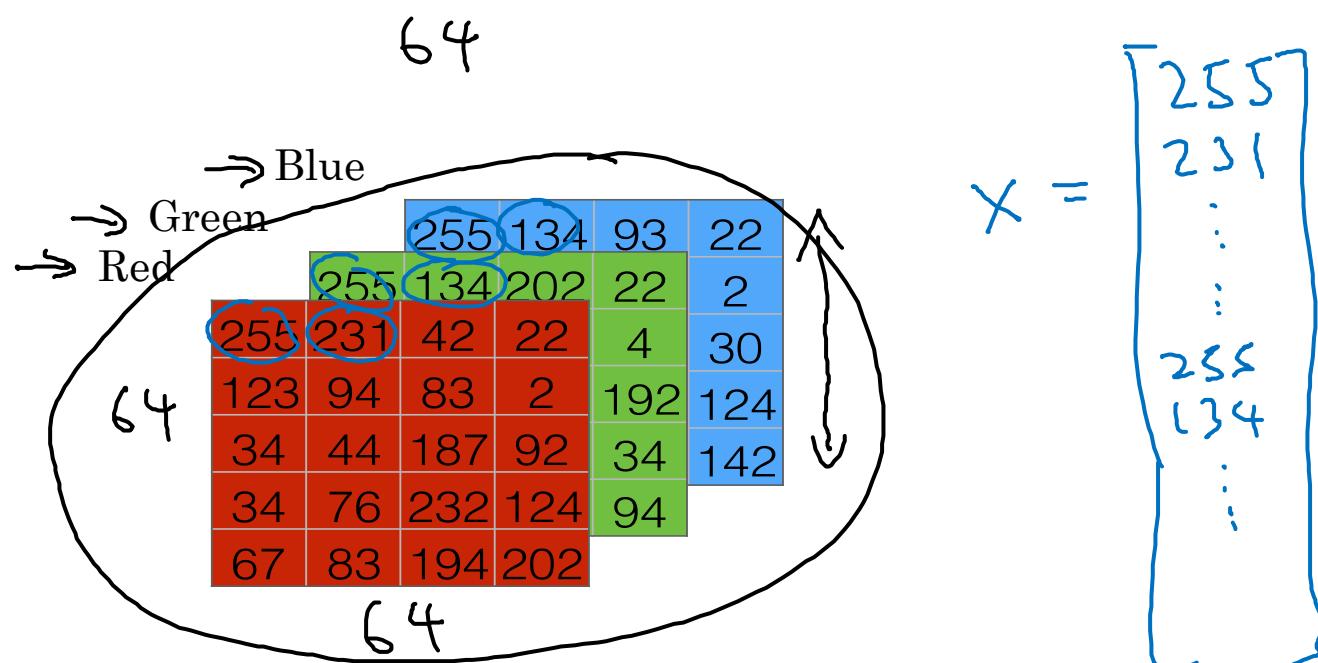
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Basics of Neural Network Programming

Binary Classification

Binary Classification

64 →  → 1 (cat) vs 0 (non cat)



$$64 \times 64 \times 3 = 12288$$

$$n = n_x = 12288$$

$$X \rightarrow y$$

Notation

(x, y) $x \in \mathbb{R}^{n_x}$, $y \in \{0, 1\}$

m training examples : $\{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(m)}, y^{(m)})\}$

$M = M_{\text{train}}$

$M_{\text{test}} = \# \text{test examples.}$

$$X = \begin{bmatrix} | & | & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & | & | \end{bmatrix}^{n_x}$$

$X \in \mathbb{R}^{n_x \times m}$

$X.\text{shape} = (n_x, m)$

$Y = [y^{(1)} \ y^{(2)} \ \dots \ y^{(m)}]$

$Y \in \mathbb{R}^{1 \times m}$

$Y.\text{shape} = (1, m)$



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Basics of Neural Network Programming

Logistic Regression

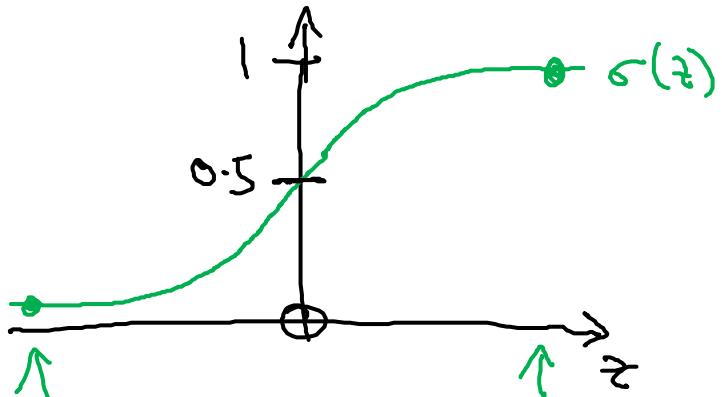
Logistic Regression

Given x , want

$$x \in \mathbb{R}^{n_x}$$

Parameters: $\underline{\omega} \in \mathbb{R}^{n_x}$, $b \in \mathbb{R}$.

Output $\hat{y} = \sigma(\underbrace{\omega^T x + b}_z)$



$$\hat{y} = \frac{P(y=1|x)}{0 \leq \hat{y} \leq 1}$$

$$x_0 = 1, \quad x \in \mathbb{R}^{n_x+1}$$

$$\hat{y} = \sigma(\underline{\omega}^T x)$$

$$\underline{\omega} = \begin{bmatrix} \omega_0 \\ \omega_1 \\ \omega_2 \\ \vdots \\ \omega_{n_x} \end{bmatrix} \left\{ \begin{array}{l} b \leftarrow \omega_0 \\ \omega \leftarrow \begin{bmatrix} \omega_1 & \omega_2 & \dots & \omega_{n_x} \end{bmatrix} \end{array} \right.$$

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

If z large $\sigma(z) \approx \frac{1}{1+0} = 1$

If z large negative number

$$\sigma(z) = \frac{1}{1 + e^{-z}} \approx \frac{1}{1 + \text{Bignum}} \approx 0$$



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Basics of Neural Network Programming

Logistic Regression cost function

$$\rightarrow \hat{y}^{(i)} = \sigma(\underline{w^T x^{(i)}} + b), \text{ where } \sigma(z^{(i)}) = \frac{\underline{z^{(i)}}}{1+e^{-z^{(i)}}}$$

Given $\{(x^{(1)}, y^{(1)}), \dots, (x^{(m)}, y^{(m)})\}$, want $\hat{y}^{(i)} \approx y^{(i)}$.

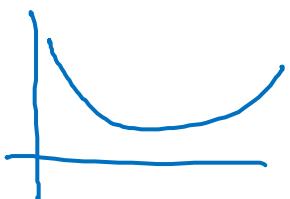
Loss (error) function:

$$L(\hat{y}, y) = \frac{1}{2} (\hat{y} - y)^2$$

$$L(\hat{y}, y) = - (y \log \hat{y} + (1-y) \log(1-\hat{y})) \leftarrow$$

$x^{(i)}$
 $y^{(i)}$
 $z^{(i)}$

i-th example.



If $y=1$: $L(\hat{y}, y) = -\log \hat{y} \leftarrow$ Want $\log \hat{y}$ large, Want \hat{y} large.

If $y=0$: $L(\hat{y}, y) = -\log(1-\hat{y}) \leftarrow$ Want $\log(1-\hat{y})$ large ... Want \hat{y} small

Cost function: $J(w, b) = \frac{1}{m} \sum_{i=1}^m L(\hat{y}^{(i)}, y^{(i)}) = \frac{1}{m} \sum_{i=1}^m [y^{(i)} \log \hat{y}^{(i)} + (1-y^{(i)}) \log(1-\hat{y}^{(i)})]$



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Basics of Neural Network Programming

Logistic Regression cost function

Logistic Regression cost function

$$\rightarrow \hat{y}^{(i)} = \sigma(w^T \underline{x}^{(i)} + b), \text{ where } \sigma(z^{(i)}) = \frac{1}{1+e^{-z^{(i)}}} \quad z^{(i)} = w^T \underline{x}^{(i)} + b$$

Given $\{(x^{(1)}, y^{(1)}), \dots, (x^{(m)}, y^{(m)})\}$, want $\hat{y}^{(i)} \approx y^{(i)}$.

$x^{(i)}$
 $y^{(i)}$
 $z^{(i)}$

i-th example.

Loss (error) function:

$$L(\hat{y}, y) = \frac{1}{2} (\hat{y} - y)^2$$



$$L(\hat{y}, y) = - (y \log \hat{y} + (1-y) \log(1-\hat{y})) \leftarrow$$



If $y=1$: $L(\hat{y}, y) = -\log \hat{y} \leftarrow$ Want $\log \hat{y}$ large, Want \hat{y} large.

If $y=0$: $L(\hat{y}, y) = -\log(1-\hat{y}) \leftarrow$ Want $\log(1-\hat{y})$ large ... Want \hat{y} small

Cost function: $J(w, b) = \frac{1}{m} \sum_{i=1}^m L(\hat{y}^{(i)}, y^{(i)}) = \frac{1}{m} \sum_{i=1}^m [y^{(i)} \log \hat{y}^{(i)} + (1-y^{(i)}) \log(1-\hat{y}^{(i)})]$



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Basics of Neural Network Programming

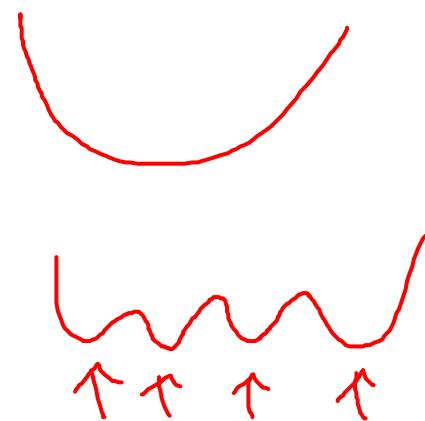
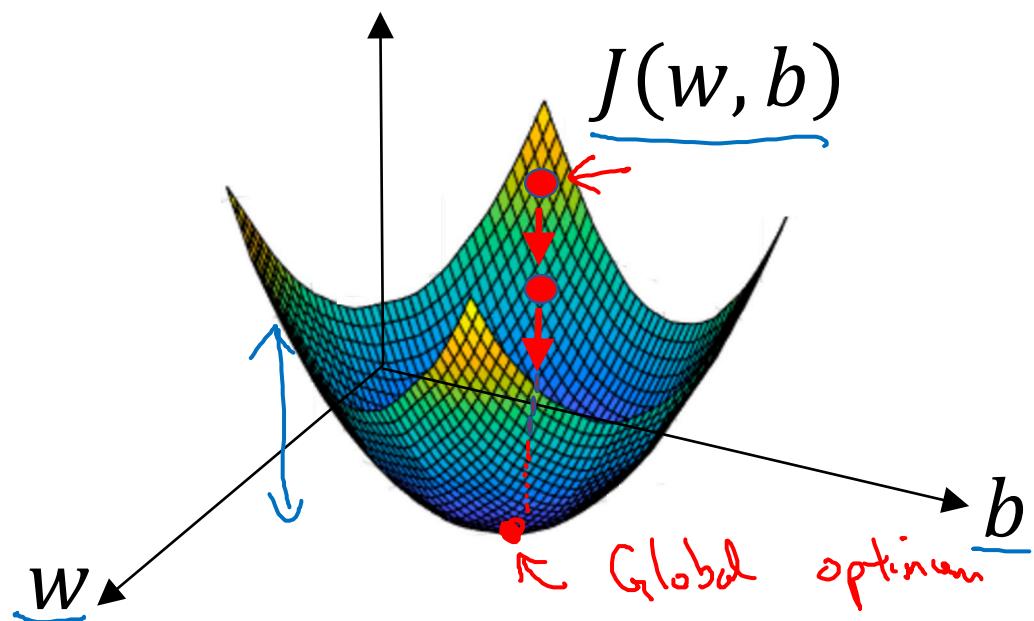
Gradient Descent

Gradient Descent

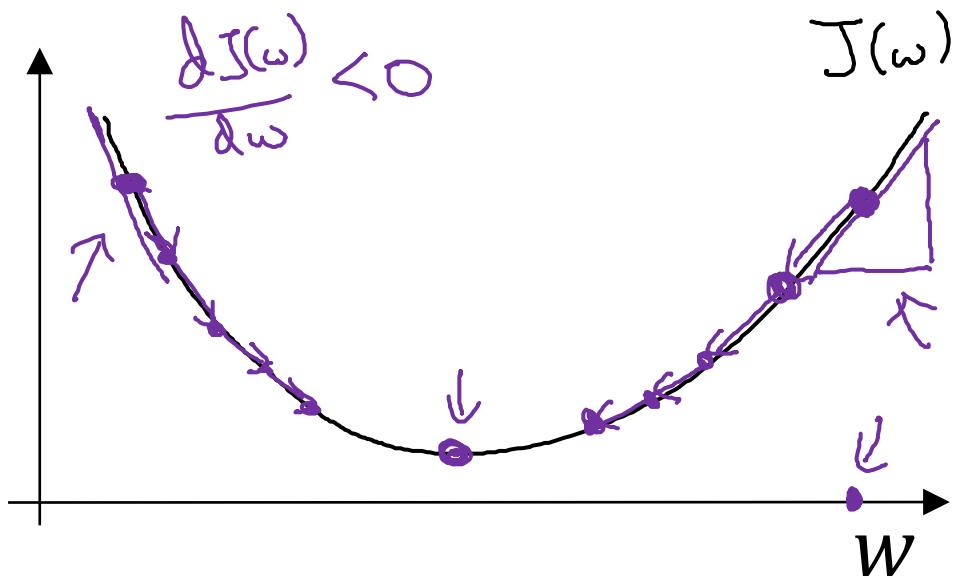
Recap: $\hat{y} = \sigma(w^T x + b)$, $\sigma(z) = \frac{1}{1+e^{-z}}$ 

$$J(w, b) = \frac{1}{m} \sum_{i=1}^m \mathcal{L}(\hat{y}^{(i)}, y^{(i)}) = -\frac{1}{m} \sum_{i=1}^m y^{(i)} \log \hat{y}^{(i)} + (1 - y^{(i)}) \log(1 - \hat{y}^{(i)})$$

Want to find w, b that minimize $J(w, b)$



Gradient Descent



Repeat {

$$\omega := \omega - \alpha \frac{dJ(\omega)}{d\omega}$$

}

$\omega := \omega - \alpha \frac{dJ(\omega)}{d\omega}$

learning rate

$$\underbrace{\frac{dJ(\omega)}{d\omega}}_{= ?}$$

$$J(\omega, b)$$

$$\omega := \omega - \alpha \frac{dJ(\omega, b)}{d\omega}$$

$$b := b - \alpha \frac{dJ(\omega, b)}{db}$$

$$\frac{dJ(\omega, b)}{d\omega}$$

$$\frac{\partial J(\omega, b)}{\partial \omega}$$

$$\frac{\partial J(\omega, b)}{\partial b}$$

"partial derivative" J

$d\omega$

db

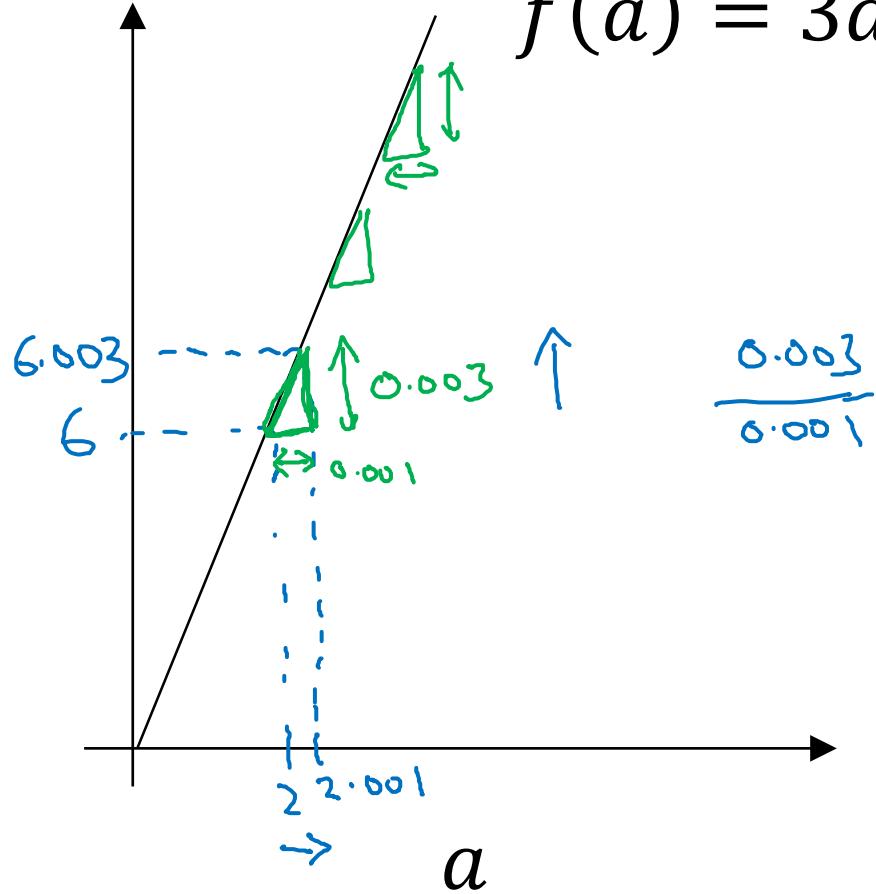


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Basics of Neural Network Programming

Derivatives

Intuition about derivatives



$$\frac{0.003}{0.001} = \frac{\text{height}}{\text{width}}$$

$\rightarrow a = 2 \quad f(a) = 6$
 $a = 2.001 \quad f(a) = 6.003$

slope (derivative) of $f(a)$ at $a=2$ is 3

$\rightarrow a = 5 \quad f(a) = 15$
 $a = 5.001 \quad f(a) = 15.003$

slope at $a=5$ is also 3

$$\frac{d f(a)}{da} = 3 = \frac{d}{da} f(a)$$

0.001
0.00000001
0.0000000001

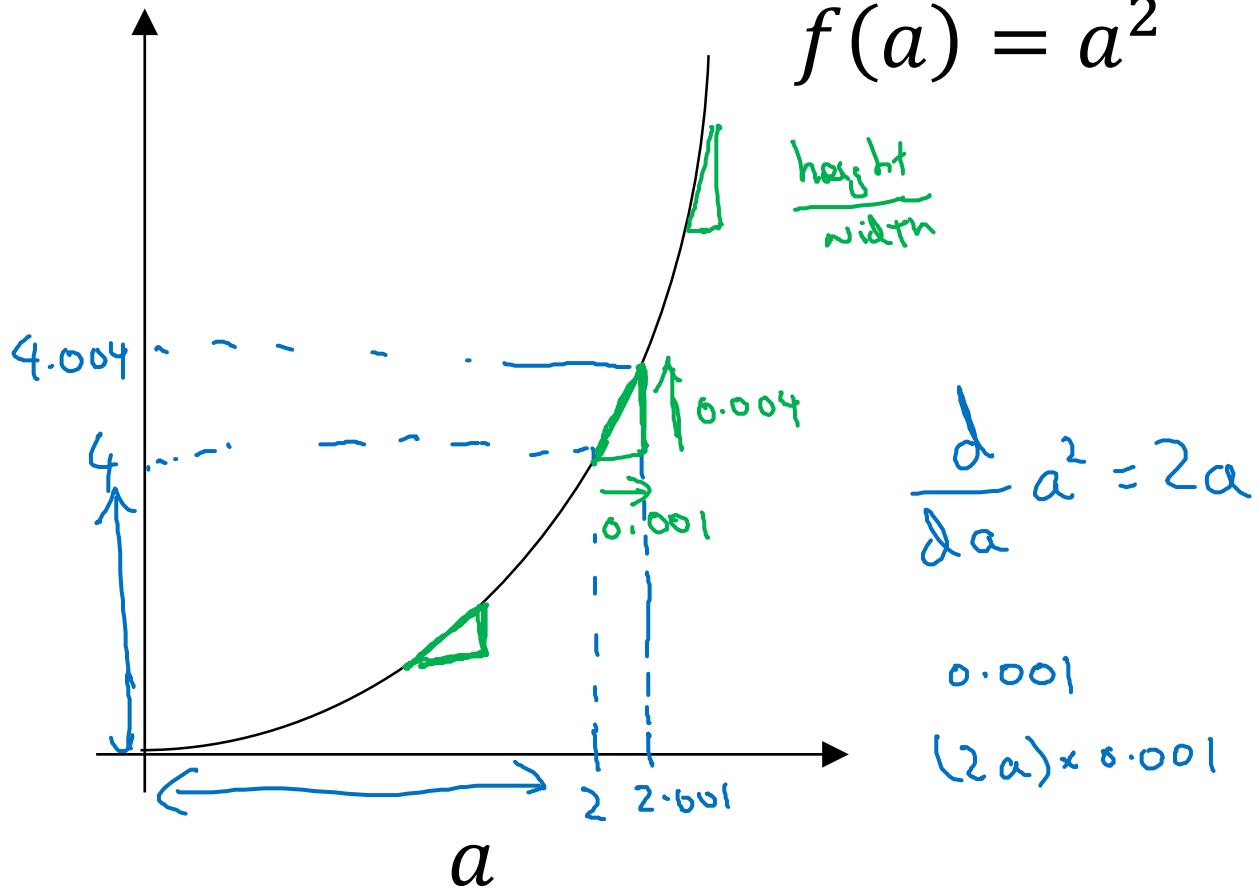


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Basics of Neural Network Programming

More derivatives
examples

Intuition about derivatives



$\alpha = 2$ $f(\alpha) = 4$

$\alpha = 2.001$ $f(\alpha) \approx 4.004$

$\frac{(4.004 - 4)}{0.001}$

slope (derivative) of $f(a)$ at $a=2$ is 4.

$\frac{d}{da} f(a) = 4$ when $a=2$.

$\alpha = 5$ $f(\alpha) = 25$

$\alpha = 5.001$ $f(\alpha) \approx 25.010$

$\frac{d}{da} f(a) = 10$ when $a=5$

$\frac{d}{da} f(a) = \frac{d}{da} a^2 = 2a$

$0.001 \leftarrow$
 $0.00000\dots 01 \leftarrow$

More derivative examples

$$f(a) = a^2$$

$$\frac{d}{da} f(a) = \frac{2a}{4}$$

$$f(a) = a^3$$

$$\frac{d}{da} f(a) = \frac{3a^2}{3 \times 2^2} = 12$$

$$f(a) = \frac{\log_e(a)}{\ln(a)}$$

$$\frac{d}{da} f(a) = \frac{1}{a}$$
$$\frac{d}{da} f(a) = \boxed{\frac{1}{2}}$$

$$a = 2$$

$$a = 2.001$$

$$f(a) = 4$$

$$f(a) \approx 4.004$$

$$a = 2$$

$$a = \underline{2.001}$$

$$f(a) = 8$$

$$f(a) \approx \underline{8.012}$$

$$a = 2$$

$$a = \underline{2.001}$$

$$f(a) \approx 0.69315$$

$$f(a) \approx \underline{0.69365}$$

$$\frac{0.0005}{0.0005}$$

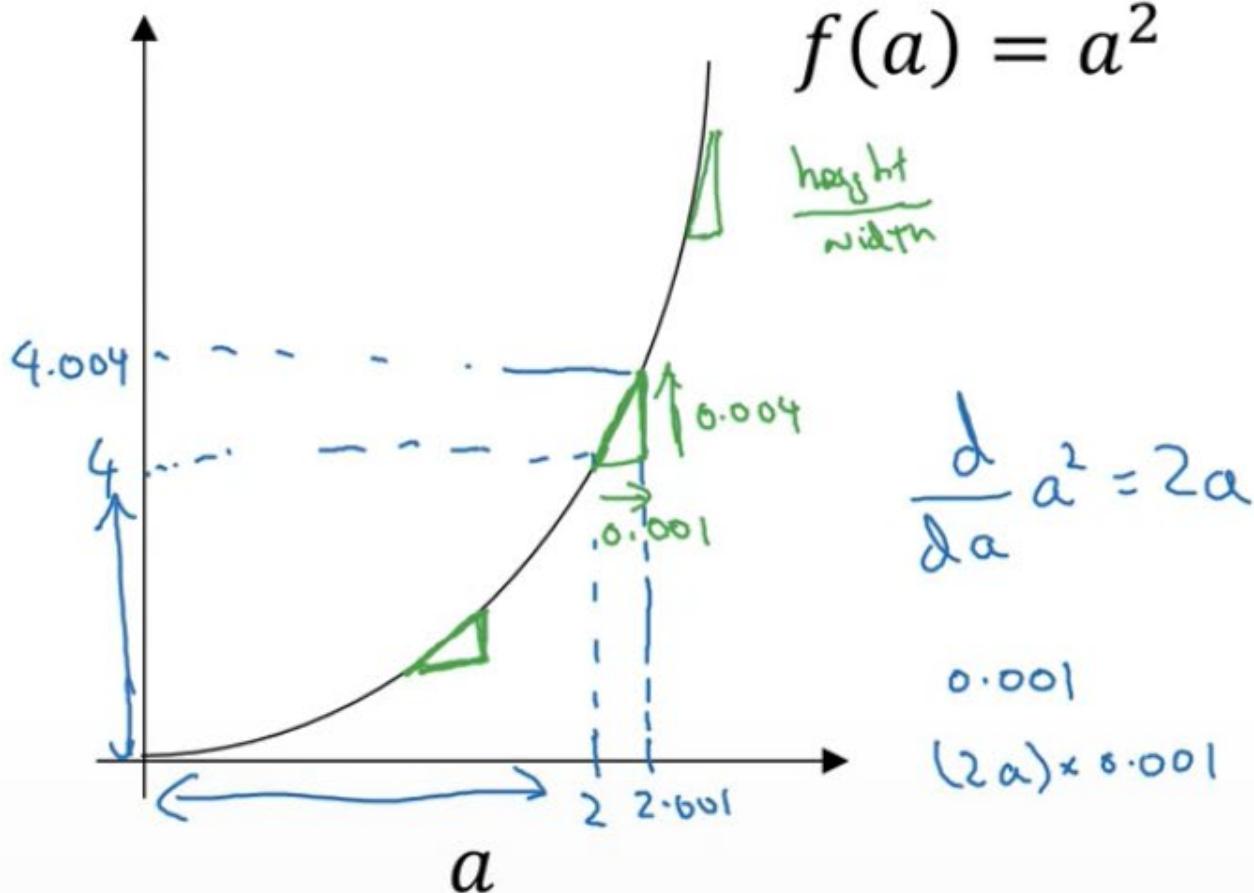


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Basics of Neural Network Programming

More derivatives
examples

Intuition about derivatives



$a = 2$ $f(a) = 4$

$a = 2.001$ $f(a) \approx 4.004$

$\frac{d}{da} f(a) = 4$ when $a = 2$.

$a = 5$ $f(a) = 25$

$a = 5.001$ $f(a) \approx 25.010$

$\frac{d}{da} f(a) = 10$ when $a = 5$

$\frac{d}{da} f(a) = \frac{d}{da} a^2 = 2a$

0.001 ←
0.00000...01 ←

More derivative examples

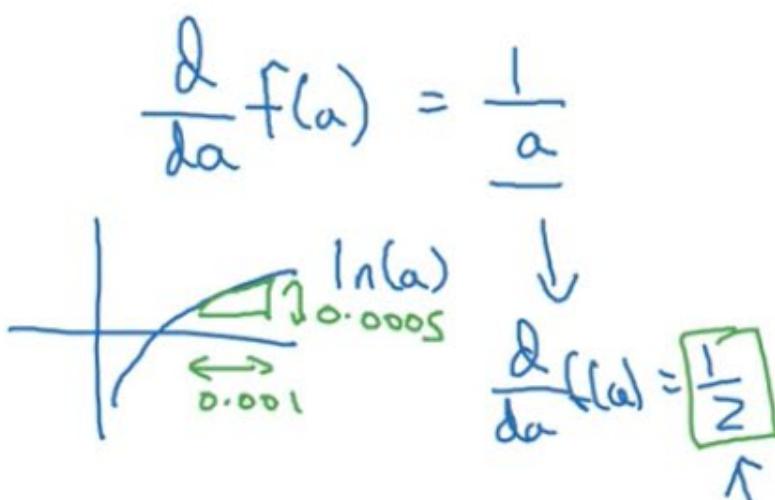
$$f(a) = a^2$$

$$\frac{\partial}{\partial a} f(a) = \underbrace{2a}_{4}$$

$$f(a) = a^3$$

$$\frac{\partial}{\partial a} f(a) = \underbrace{3a^2}_{3 \times 2^2} = 12$$

$$f(a) = \frac{\log_e(a)}{\ln(a)}$$



$$a = 2$$

$$a = 2.001$$

$$f(a) = 4$$

$$f(a) \approx 4.004$$

$$a = 2$$

$$a = \underline{2.001}$$

$$f(a) = 8$$

$$f(a) \approx \underline{8.012}$$

$$a = 2$$

$$a = \underline{2.001}$$

$$f(a) \approx 0.69315$$

$$f(a) \approx \underline{0.69365}$$

$$\frac{0.0005}{0.0005}$$



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Basics of Neural Network Programming

Computation Graph

Computation Graph

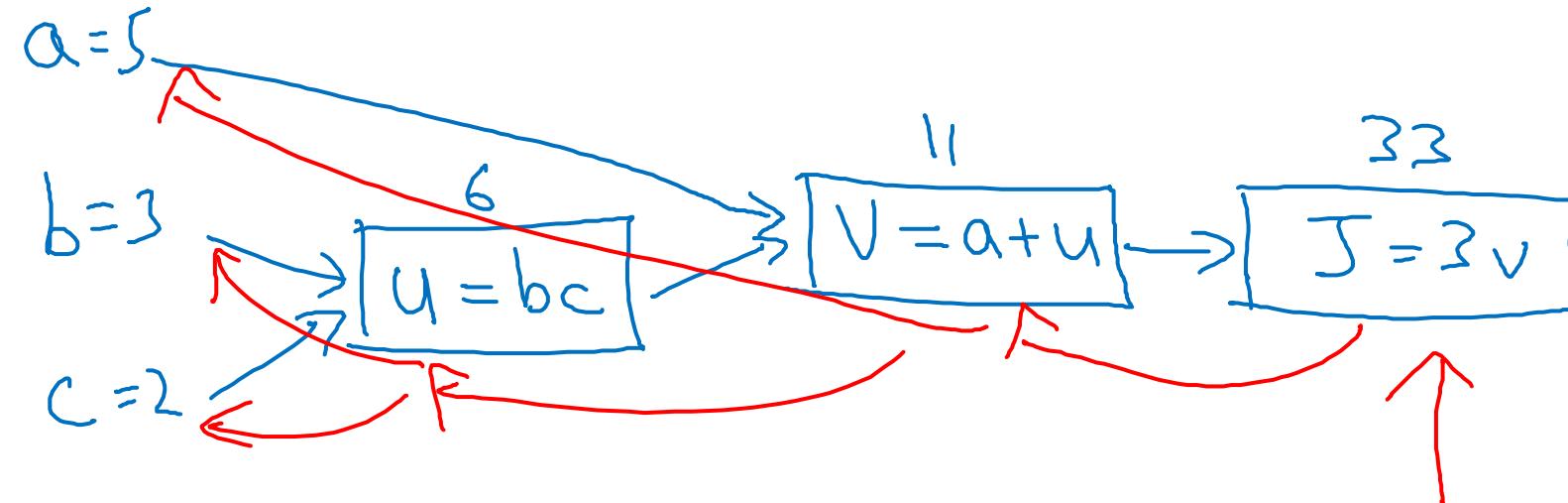
$$J(a, b, c) = 3(u + bc) = 3(5 + 3 \times 2) = 33$$

$\underbrace{u}_{\downarrow}$
 $\underbrace{v}_{\downarrow}$
 $\underbrace{J}_{\downarrow}$

$$u = bc$$

$$v = a + u$$

$$J = 3v$$





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Basics of Neural Network Programming

Derivatives with a Computation Graph

Computing derivatives

$$a = 5 \quad \frac{dJ}{da} \text{ "da"=3}$$

$$b = 3 \quad u = bc \quad 6$$

$$c = 2$$

(11) $v = a + u$ → $J = 3v$

$$\frac{dJ}{dv} \text{ "dv"=3}$$

$$\boxed{\frac{dJ}{dv} = ? = 3}$$

$a \rightarrow v \rightarrow J$

$$\frac{dJ}{da} = 3 = \frac{dJ}{dv} \frac{dv}{du} \frac{du}{da}$$

$$\boxed{\frac{dv}{da} = 1}$$

$$\boxed{\frac{\partial \text{FinalOutputVar}}{\partial \text{var}}}$$

$$a = 5 \rightarrow 5.001 \\ \rightarrow v = 11 \rightarrow 11.001$$

$$J = 33 \rightarrow 33.003$$

$$\frac{\partial J}{\partial \text{var}} \\ \underline{\text{"dvar"}}$$

$$f(a) = 3a$$

$$\frac{df(b)}{da} = \frac{df}{da} = 3$$

$$J = 3v$$

$$\frac{dJ}{dv} = 3$$

Computing derivatives

$\frac{\partial J}{\partial a} \rightarrow \underline{a = 5}$
 $\frac{\partial J}{\partial b} \rightarrow \underline{b = 3}$
 $\frac{\partial J}{\partial c} \rightarrow \underline{c = 2}$
 $\frac{\partial J}{\partial u} = 3$
 $\frac{\partial J}{\partial v} = 3$

$a = 5$ → $v = a + u$
 $b = 3$ → $v = a + u$
 $c = 2$ → $u = bc$
 $u = bc$ → $v = a + u$
 $u = 6$ → $v = a + u$
 $\underline{du = 3}$

$v = a + u$ → $J = 3v$
 $\underline{dv = 3}$ → $\underline{\frac{\partial J}{\partial v} = 3}$

$\frac{\partial J}{\partial u} = 3 = \frac{\partial J}{\partial v} \cdot \frac{\partial v}{\partial u}$
 $\frac{\partial J}{\partial u} = 3 = 3 \cdot -1$

$\frac{\partial J}{\partial b} = \boxed{\frac{\partial J}{\partial u}} \cdot \underbrace{\frac{\partial u}{\partial b}}_{=2} = 6$
 $\frac{\partial J}{\partial a} = \boxed{\frac{\partial J}{\partial u}} \cdot \underbrace{\frac{\partial u}{\partial a}}_{=3} = 9$

$u = 6 \rightarrow 6.001$
 $v = 11 \rightarrow 11.001$
 $J = 33 \rightarrow 33.003$

$b = 3 \rightarrow 3.001$
 $u = b \cdot c = 6 \rightarrow 6.002$
 $J = 33.006$

$c = 2$
 $.006$

$v = 11.002$
 $J = 3v$

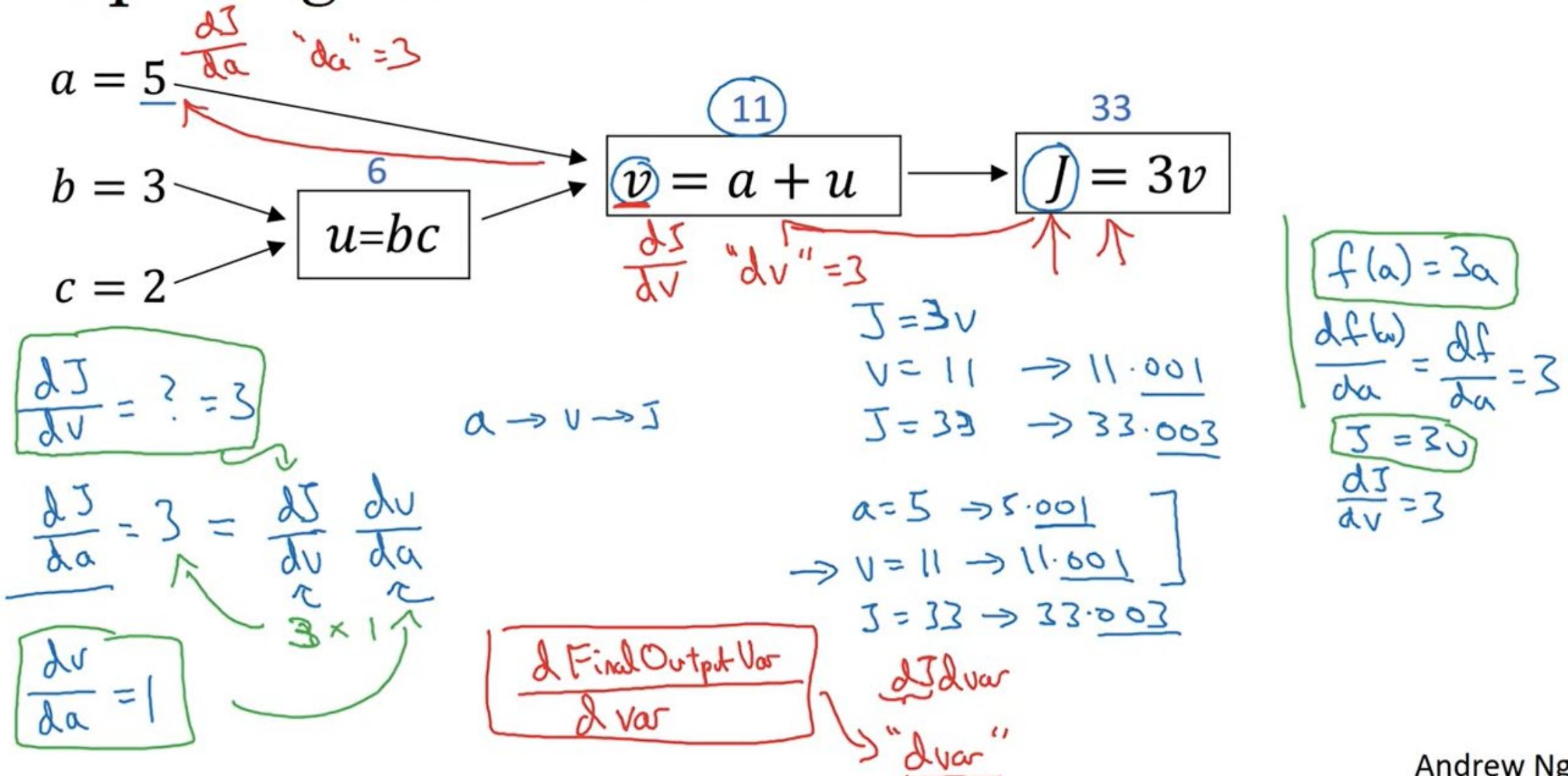


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Basics of Neural Network Programming

Derivatives with a Computation Graph

Computing derivatives



Computing derivatives

$\frac{\partial J}{\partial a} \rightarrow a = 5 \quad \frac{\partial a}{\partial a} = 1$
 $\frac{\partial J}{\partial b} \rightarrow b = 3 \quad \frac{\partial b}{\partial b} = 1$
 $\frac{\partial J}{\partial c} \rightarrow c = 2 \quad \frac{\partial c}{\partial c} = 1$
 $\frac{\partial J}{\partial u} = 3 = \frac{\partial J}{\partial v} \cdot \frac{\partial v}{\partial u}$
 $\frac{\partial J}{\partial b} = \boxed{3} \quad \frac{\partial J}{\partial c} = \boxed{9}$
 $\frac{\partial J}{\partial u} = \boxed{3}$
 $\frac{\partial J}{\partial c} = \boxed{9}$

$v = a + u \quad 11 \quad \frac{\partial v}{\partial a} = 1 \quad \frac{\partial v}{\partial u} = 1$
 $J = 3v \quad 33 \quad \frac{\partial J}{\partial v} = 3$

$u = bc \quad 6 \quad \frac{\partial u}{\partial b} = c \quad \frac{\partial u}{\partial c} = b$

$u = 6 \rightarrow 6.001$
 $v = 11 \rightarrow 11.001$
 $J = 33 \rightarrow 33.003$

$b = 3 \rightarrow 3.001$
 $u = b \cdot c = 6 \rightarrow 6.002$
 $J = 33.006$

$c = 2.006$
 $v = 11.002$
 $J = 33.006$



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Basics of Neural Network Programming

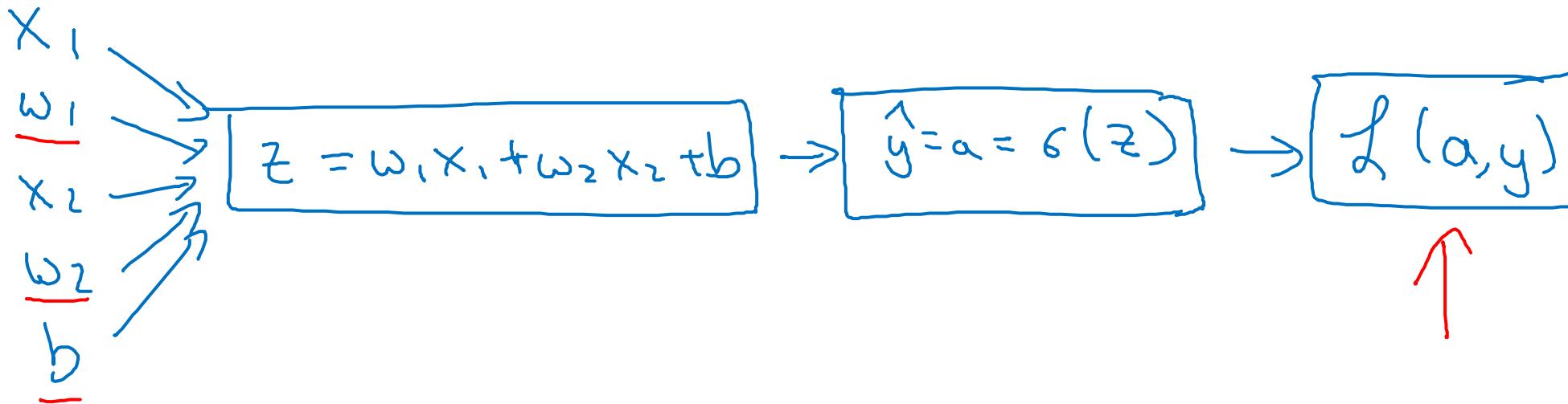
Logistic Regression Gradient descent

Logistic regression recap

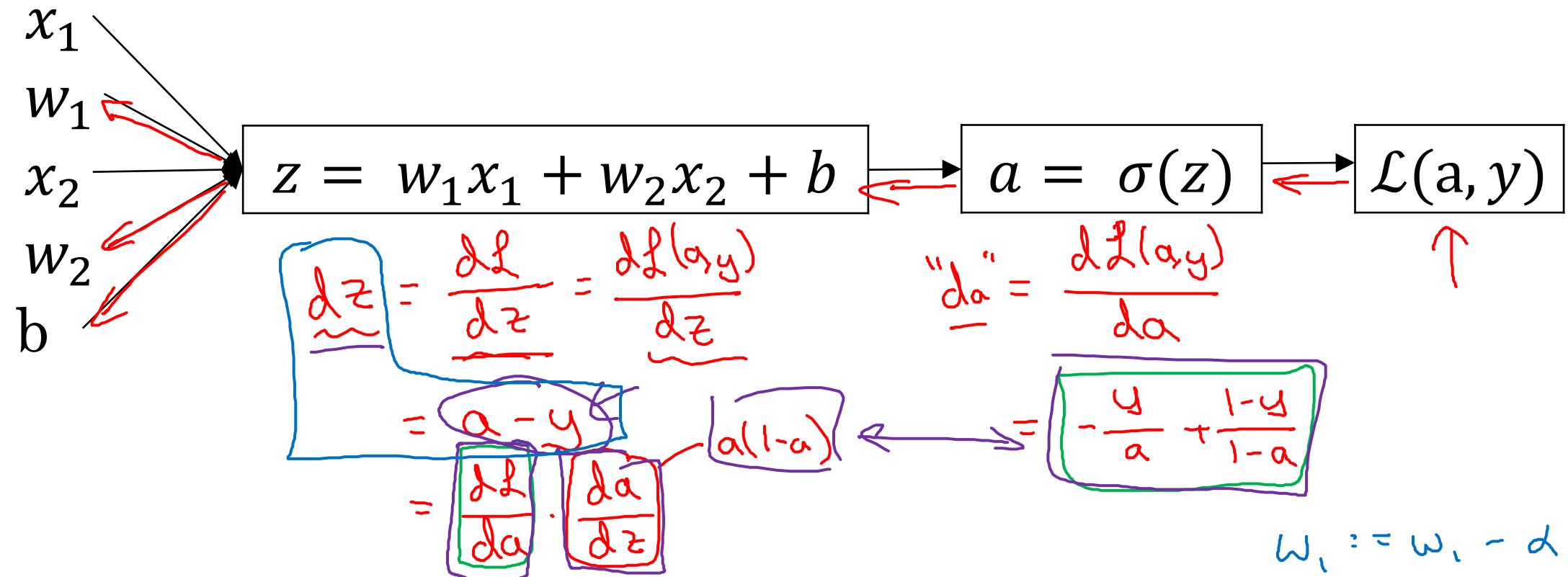
$$\rightarrow z = w^T x + b$$

$$\rightarrow \hat{y} = a = \sigma(z)$$

$$\rightarrow \mathcal{L}(a, y) = -(y \log(a) + (1 - y) \log(1 - a))$$



Logistic regression derivatives



$$\frac{\partial \mathcal{L}}{\partial w_1} = "dw_1" = x_1 \cdot dz.$$

$$dw_2 = x_2 \cdot dz. \quad db = dz.$$

$$w_1 := w_1 - d dw_1$$

$$w_2 := w_2 - d dw_2$$

$$b := b - d db.$$



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Basics of Neural Network Programming

Gradient descent
on m examples

Logistic regression on m examples

$$\underline{J(\omega, b)} = \frac{1}{m} \sum_{i=1}^m l(a^{(i)}, y^{(i)}) \quad (x^{(i)}, y^{(i)})$$
$$\Rightarrow a^{(i)} = \hat{y}^{(i)} = g(z^{(i)}) = g(\omega^\top x^{(i)} + b) \quad \underline{dw_1^{(i)}}, \underline{dw_2^{(i)}}, \underline{db^{(i)}}$$

$$\underline{\frac{\partial}{\partial \omega_1} J(\omega, b)} = \frac{1}{m} \sum_{i=1}^m \underbrace{\frac{\partial}{\partial \omega_1} l(a^{(i)}, y^{(i)})}_{\underline{dw_1^{(i)}} - (x^{(i)}, y^{(i)})}$$

Logistic regression on m examples

$$J=0; \underline{\Delta w_1}=0; \underline{\Delta w_2}=0; \underline{\Delta b}=0$$

→ For $i = 1$ to m

$$z^{(i)} = \omega^\top x^{(i)} + b$$

$$a^{(i)} = \sigma(z^{(i)})$$

$$J_t = -[y^{(i)} \log a^{(i)} + (1-y^{(i)}) \log(1-a^{(i)})]$$

$$\underline{\Delta z^{(i)}} = a^{(i)} - y^{(i)}$$

$$\begin{cases} \Delta w_1 += x_1^{(i)} \Delta z^{(i)} \\ \Delta w_2 += x_2^{(i)} \Delta z^{(i)} \end{cases}$$

$$\begin{matrix} \Delta w_3 \\ \vdots \\ \Delta w_n \end{matrix} \quad \Delta b += \Delta z^{(i)}$$

$$J / m \leftarrow$$

$$\Delta w_1 / m; \Delta w_2 / m; \Delta b / m. \leftarrow$$

$$\Delta w_1 = \frac{\partial J}{\partial w_1}$$

$$w_1 := w_1 - \alpha \frac{\partial J}{\partial w_1}$$

$$w_2 := w_2 - \alpha \frac{\partial J}{\partial w_2}$$

$$b := b - \alpha \frac{\partial J}{\partial b}.$$

Vectorization



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Basics of Neural Network Programming

Gradient descent on m examples

Logistic regression on m examples

$$\underline{J(w,b)} = \frac{1}{m} \sum_{i=1}^m l(a^{(i)}, y^{(i)}) \quad (x^{(i)}, y^{(i)})$$
$$\rightarrow a^{(i)} = \hat{y}^{(i)} = g(z^{(i)}) = g(w^\top x^{(i)} + b) \quad \underline{dw_1^{(i)}}, \underline{dw_2^{(i)}}, \underline{db^{(i)}}$$

$$\underline{\frac{\partial}{\partial w_1} J(w,b)} = \frac{1}{m} \sum_{i=1}^m \underbrace{\frac{\partial}{\partial w_1} l(a^{(i)}, y^{(i)})}_{\underline{dw_1^{(i)}} - (x^{(i)}, y^{(i)})}$$

Logistic regression on m examples

$$J=0; \frac{\partial w_1}{\partial w_1}=0; \frac{\partial w_2}{\partial w_2}=0; \frac{\partial b}{\partial b}=0$$

→ For $i = 1$ to m

$$z^{(i)} = \omega^\top x^{(i)} + b$$

$$a^{(i)} = \sigma(z^{(i)})$$

$$J_t = -[y^{(i)} \log a^{(i)} + (1-y^{(i)}) \log(1-a^{(i)})]$$

$$\frac{\partial z^{(i)}}{\partial} = a^{(i)} - y^{(i)}$$

$$\left[\begin{array}{l} \frac{\partial w_1}{\partial w_1} += x_1^{(i)} \frac{\partial z^{(i)}}{\partial} \\ \frac{\partial w_2}{\partial w_2} += x_2^{(i)} \frac{\partial z^{(i)}}{\partial} \\ \frac{\partial b}{\partial b} += \frac{\partial z^{(i)}}{\partial} \end{array} \right] \quad \sum_{i=1}^m$$

$$\frac{\partial w_1}{\partial w_1} = m \left(\frac{\partial z^{(i)}}{\partial} \right)$$

$$J / = m \leftarrow$$

$$\frac{\partial w_1}{\partial w_1} / = m; \quad \frac{\partial w_2}{\partial w_2} / = m; \quad \frac{\partial b}{\partial b} / = m. \quad \leftarrow$$

$$\frac{\partial w_1}{\partial w_1} = \frac{\partial J}{\partial w_1}$$

$$w_1 := w_1 - \alpha \frac{\partial w_1}{\partial J}$$

$$w_2 := w_2 - \alpha \frac{\partial w_2}{\partial J}$$

$$b := b - \alpha \frac{\partial b}{\partial J}$$

Vectorization



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Basics of Neural Network Programming

Vectorization

What is vectorization?

$$z = \underbrace{\omega^T x}_{\text{Non-vectorized}} + b$$

Non-vectorized:

$$z = 0$$

```
for i in range(n - x):  
    z += w[i] * x[i]
```

$$z += b$$

$$\omega = \begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix} \quad x = \begin{bmatrix} \vdots \\ \vdots \\ \vdots \end{bmatrix}$$

$\omega \in \mathbb{R}^{n_x}$
 $x \in \mathbb{R}^{n_x}$

Vectorized

$$z = \underbrace{\text{np.dot}(\omega, x)}_{w^T x} + b$$

\rightarrow GPU } SIMD - single instruction
 \rightarrow CPU } multiple data.



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Basics of Neural Network Programming

More vectorization examples

Neural network programming guideline

Whenever possible, avoid explicit for-loops.

Neural network programming guideline

Whenever possible, avoid explicit for-loops.

$$u = Av$$

$$u_i = \sum_j A_{ij} v_j$$

$u = np.zeros((n,))$

for i ...

 for j ...

$u[i] += A[:, i] * v[j]$

$$u = np.dot(A, v)$$

Vectors and matrix valued functions

Say you need to apply the exponential operation on every element of a matrix/vector.

$$v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \rightarrow u = \begin{bmatrix} e^{v_1} \\ e^{v_2} \\ \vdots \\ e^{v_n} \end{bmatrix}$$

```
→ u = np.zeros((n, 1))  
for i in range(n): ←  
    → u[i] = math.exp(v[i])
```

```
import numpy as np  
u = np.exp(v) ←  
↑  
np.log(v)  
np.abs(v)  
np.maximum(v, 0)  
v**2  
v/v
```

Logistic regression derivatives

$$J = 0, \quad \boxed{dw_1 = 0, \quad dw_2 = 0}, \quad db = 0$$

$$d\omega = np.zeros((n_x, 1))$$

for i = 1 to n:

$$z^{(i)} = w^T x^{(i)} + b$$

$$a^{(i)} = \sigma(z^{(i)})$$

$$J += -[y^{(i)} \log \hat{y}^{(i)} + (1 - y^{(i)}) \log(1 - \hat{y}^{(i)})]$$

$$dz^{(i)} = a^{(i)}(1 - a^{(i)})$$

for j=1..n_x
 $d\omega_j := \dots$

$$\boxed{\begin{aligned} dw_1 &+= x_1^{(i)} dz^{(i)} \\ dw_2 &+= x_2^{(i)} dz^{(i)} \\ db &+= dz^{(i)} \end{aligned}}$$

$n_x = 2$

$$d\omega += x^{(i)} dz^{(i)}$$

$$J = J/m, \quad \boxed{dw_1 = dw_1/m, \quad dw_2 = dw_2/m}, \quad db = db/m$$

$$d\omega /= m.$$



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Basics of Neural Network Programming

More vectorization
examples

Neural network programming guideline

Whenever possible, avoid explicit for-loops.

$$u = Av$$

$$u_i = \sum_j A_{ij} v_j$$

$$u = np.zeros(n, 1)$$

for i ... \leftarrow

 for j ... \leftarrow

$$u[i] += A[:, i] * v[i]$$

$$u = np.dot(A, v)$$

Vectors and matrix valued functions

Say you need to apply the exponential operation on every element of a matrix/vector.

$$v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \rightarrow u = \begin{bmatrix} e^{v_1} \\ e^{v_2} \\ \vdots \\ e^{v_n} \end{bmatrix}$$

```
→ u = np.zeros((n, 1))
for i in range(n):
    → u[i] = math.exp(v[i])
```

```
import numpy as np
u = np.exp(v) ←
→
np.log(u)
np.abs(u)
np.maximum(u, 0)
v**2           √v
```

Logistic regression derivatives

$$J = 0, \quad \boxed{dw_1 = 0, dw_2 = 0}, \quad db = 0$$

$$\delta w = np.zeros((n_x, 1))$$

for i = 1 to m:

$$z^{(i)} = w^T x^{(i)} + b$$

$$a^{(i)} = \sigma(z^{(i)})$$

$$J += -[y^{(i)} \log \hat{y}^{(i)} + (1 - y^{(i)}) \log(1 - \hat{y}^{(i)})]$$

$$\frac{\partial J}{\partial w_j} = x_j^{(i)} \delta z^{(i)}$$

$$\left. \begin{aligned} dw_1 &+= x_1^{(i)} \delta z^{(i)} \\ dw_2 &+= x_2^{(i)} \delta z^{(i)} \\ db &+= \delta z^{(i)} \end{aligned} \right| n_x=2$$

$$\delta w += x^{(i)} \delta z^{(i)}$$

$$J = J/m, \quad \boxed{dw_1 = \delta w_1/m, \quad dw_2 = \delta w_2/m, \quad db = \delta b/m}$$

$$\delta w /= m.$$



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Basics of Neural Network Programming

Vectorizing Logistic Regression

Vectorizing Logistic Regression

$$\begin{array}{l} \rightarrow z^{(1)} = w^T x^{(1)} + b \\ \xrightarrow{\text{---}} a^{(1)} = \sigma(z^{(1)}) \end{array}$$

$$\begin{array}{l} \xrightarrow{\text{---}} z^{(2)} = w^T x^{(2)} + b \\ \xrightarrow{\text{---}} a^{(2)} = \sigma(z^{(2)}) \end{array}$$

$$\begin{array}{l} \xrightarrow{\text{---}} z^{(3)} = w^T x^{(3)} + b \\ \xrightarrow{\text{---}} a^{(3)} = \sigma(z^{(3)}) \end{array}$$

$$\underline{\underline{X}} = \left[\begin{array}{c|c|c|c} x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ \hline | & | & & | \\ \hline & & & \end{array} \right]$$

$$\frac{(n_{x,m})}{\mathbb{R}^{n_x \times m}}$$

$$\overbrace{\omega^T}^1 \left[\begin{array}{c|c|c|c} 1 & x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ \hline | & | & & & | \\ \hline & & & & \end{array} \right]$$

$$\underline{\underline{Z}} = \left[\begin{array}{c|c|c|c} z^{(1)} & z^{(2)} & \dots & z^{(m)} \\ \hline | & | & & | \\ \hline & & & \end{array} \right] = \omega^T \underline{\underline{X}} + \underbrace{\left[\begin{array}{c|c|c|c} b & b & \dots & b \\ \hline | & | & & | \\ \hline & & & \end{array} \right]}_{1 \times m} = \left[\begin{array}{c|c|c|c} \underline{\omega^T x^{(1)} + b} & & & \\ \hline & \underline{\omega^T x^{(2)} + b} & & \\ \hline & & \ddots & \\ \hline & & & \underline{\omega^T x^{(m)} + b} \end{array} \right]_{1 \times m}$$

$$\rightarrow \underline{\underline{Z}} = \text{np.dot}(\omega.T, X) + \underbrace{\underline{\underline{b}}}_{(1,1)}$$

R

"Broadcasting"

$$\underline{\underline{A}} = \left[\begin{array}{c|c|c|c} a^{(1)} & a^{(2)} & \dots & a^{(m)} \\ \hline | & | & & | \\ \hline & & & \end{array} \right] = \sigma(\underline{\underline{Z}})$$



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Basics of Neural Network Programming

Vectorizing Logistic Regression's Gradient Computation

Vectorizing Logistic Regression

$$dz^{(1)} = a^{(1)} - y^{(1)} \quad dz^{(2)} = a^{(2)} - y^{(2)}$$

$$dz = [dz^{(1)} \ dz^{(2)} \ \dots \ dz^{(m)}] \quad | \times m$$

$$A = [a^{(1)} \ \dots \ a^{(m)}]. \quad Y = [y^{(1)} \ \dots \ y^{(m)}]$$

$$\rightarrow dz = A - Y = [a^{(1)} - y^{(1)} \ a^{(2)} - y^{(2)} \ \dots]$$

$$\begin{aligned} \rightarrow dw &= 0 \\ dw + &= \frac{x^{(1)} dz^{(1)}}{} \\ dw + &= \frac{x^{(2)} dz^{(2)}}{} \\ &\vdots \\ dw &= m \end{aligned}$$

$$\begin{aligned} db &= 0 \\ db + &= dz^{(1)} \\ db + &= dz^{(2)} \\ &\vdots \\ db &= dz^{(m)} \end{aligned}$$

db/m

$$\begin{aligned} db &= \frac{1}{m} \sum_{i=1}^m dz^{(i)} \\ &= \frac{1}{m} \underbrace{\text{np. sum}(dz)} \end{aligned}$$

$$\begin{aligned} dw &= \frac{1}{m} \times dz^T \\ &= \frac{1}{m} \left[\begin{array}{c|c} x^{(1)} & x^{(m)} \\ \hline 1 & 1 \end{array} \right] \left[\begin{array}{c} dz^{(1)} \\ \vdots \\ dz^{(m)} \end{array} \right] \\ &= \frac{1}{m} \left[\underbrace{x^{(1)} dz^{(1)}}{} + \dots + \underbrace{x^{(m)} dz^{(m)}}{} \right] \\ &\qquad\qquad\qquad n \times 1 \end{aligned}$$

Implementing Logistic Regression

$$J = 0, dw_1 = 0, dw_2 = 0, db = 0$$

for i = 1 to m:

$$z^{(i)} = w^T x^{(i)} + b$$

$$a^{(i)} = \sigma(z^{(i)})$$

$$J += -[y^{(i)} \log a^{(i)} + (1 - y^{(i)}) \log(1 - a^{(i)})]$$

$$dz^{(i)} = a^{(i)} - y^{(i)}$$

$$\left. \begin{array}{l} dw_1 += x_1^{(i)} dz^{(i)} \\ dw_2 += x_2^{(i)} dz^{(i)} \end{array} \right\} dw += X^{(i)} * dz^{(i)}$$

$$db += dz^{(i)}$$

$$J = J/m, dw_1 = dw_1/m, dw_2 = dw_2/m$$

$$db = db/m$$

for iter in range(1000):

$$z = w^T X + b$$

$$= np.dot(w.T, X) + b$$

$$A = \sigma(z)$$

$$dZ = A - Y$$

$$dw = \frac{1}{m} X dZ^T$$

$$db = \frac{1}{m} np.sum(dZ)$$

$$w := w - \alpha dw$$

$$b := b - \alpha db$$



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Basics of Neural Network Programming

Vectorizing Logistic Regression's Gradient Computation

Vectorizing Logistic Regression

$$dz^{(1)} = a^{(1)} - y^{(1)}$$

$$dz^{(2)} = a^{(2)} - y^{(2)}$$

...

$$dz = \begin{bmatrix} dz^{(1)} & dz^{(2)} & \dots & dz^{(m)} \end{bmatrix}_{1 \times m}$$

$$A = [a^{(1)} \dots a^{(m)}], \quad Y = [y^{(1)} \dots y^{(m)}]$$

$$\rightarrow dz = A - Y = [a^{(1)} - y^{(1)} \quad a^{(2)} - y^{(2)} \quad \dots]$$

$$\rightarrow dw = 0$$

$$\frac{dw}{dw} + = \frac{x^{(1)} dz^{(1)}}{x^{(1)} dz^{(1)}}$$

$$\frac{dw}{dw} + = \frac{x^{(2)} dz^{(2)}}{x^{(2)} dz^{(2)}}$$

$$| dw | = m$$

$$db = 0$$

$$db + = dz^{(1)}$$

$$db + = dz^{(2)}$$

$$db + = dz^{(m)}$$

$$db / = m.$$

$$db = \frac{1}{m} \sum_{i=1}^m dz^{(i)}$$

$$= \frac{1}{m} \underline{\text{np.sum}(dz)}$$

$$dw = \frac{1}{m} \times dz^T$$

$$= \frac{1}{m} \begin{bmatrix} 1 & \dots & 1 \end{bmatrix} \begin{bmatrix} dz^{(1)} \\ \vdots \\ dz^{(m)} \end{bmatrix}$$

$$= \frac{1}{m} \left[\underline{x^{(1)} dz^{(1)}} + \dots + \underline{x^{(m)} dz^{(m)}} \right]$$

$$n \times 1$$

Implementing Logistic Regression

$$J = 0, dw_1 = 0, dw_2 = 0, db = 0$$

for $i = 1$ to m :

$$z^{(i)} = w^T x^{(i)} + b$$

$$a^{(i)} = \sigma(z^{(i)})$$

$$J += -[y^{(i)} \log a^{(i)} + (1 - y^{(i)}) \log(1 - a^{(i)})]$$

$$dz^{(i)} = a^{(i)} - y^{(i)}$$

$$\left. \begin{aligned} dw_1 &+= x_1^{(i)} dz^{(i)} \\ dw_2 &+= x_2^{(i)} dz^{(i)} \end{aligned} \right\} \quad \partial \omega := X^{(i)} * dz^{(i)}$$

$$db += dz^{(i)}$$

$$J = J/m, dw_1 = dw_1/m, dw_2 = dw_2/m$$

$$db = db/m$$

```
for iter in range(1000):  
    z = w^T X + b  
    = np.dot(w.T, X) + b  
    A = sigma(z)  
    dZ = A - Y  
    dw = 1/m * dZ^T  
    db = 1/m * np.sum(dZ)  
  
    w := w - alpha * dw  
    b := b - alpha * db
```



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Basics of Neural Network Programming

Broadcasting in Python

Broadcasting example

Calories from Carbs, Proteins, Fats in 100g of different foods:

	Apples	Beef	Eggs	Potatoes	
Carb	56.0	0.0	4.4	68.0	
Protein	1.2	104.0	52.0	8.0	
Fat	1.8	135.0	99.0	0.9	
	59 cal				\downarrow^0
		$\frac{56}{59} \approx 94.9\%$			$\xrightarrow{1}$

Calculate % of calories from Carb, Protein, Fat. Can you do this without explicit for-loop?

`cal = A.sum(axis = 0)`

`percentage = 100*A/(cal.reshape(1,4))`

$\uparrow^{(3,4)} / (1,4)$

Broadcasting example

$$\begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} + \begin{bmatrix} 100 \\ 100 \\ 100 \\ 100 \end{bmatrix} \xrightarrow{100}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 100 & 200 & 300 \\ 100 & 200 & 300 \end{bmatrix} \xleftarrow{(m,n) \quad (2,3)} \xrightarrow{(1,n) \rightsquigarrow (m,n) \quad (2,3)}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} + \begin{bmatrix} 100 & 100 & 100 \\ 200 & 200 & 200 \end{bmatrix} = \xleftarrow{(m,n)}$$

General Principle

$$\begin{array}{ccc} (m, n) & \xrightarrow{\quad \pm \quad} & (1, n) \rightsquigarrow (m, n) \\ \underline{\text{matrix}} & \xrightarrow{\quad \times \quad} & (m, 1) \rightsquigarrow (m, n) \end{array}$$

$$\begin{array}{ccccc} (m, 1) & + & \mathbb{R} & & \\ \left[\begin{smallmatrix} 1 \\ 2 \\ 3 \end{smallmatrix} \right] & + & 100 & = & \left[\begin{smallmatrix} 101 \\ 102 \\ 103 \end{smallmatrix} \right] \\ [1 \ 2 \ 3] & + & 100 & = & [101 \ 102 \ 103] \end{array}$$

Matlab/Octave: bsxfun



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Basics of Neural Network Programming

A note on python/
numpy vectors

Python Demo

Python / numpy vectors

```
import numpy as np  
  
a = np.random.randn(5)  
  
a = np.random.randn( (5, 1) )  
  
a = np.random.randn( (1, 5) )  
  
assert(a.shape = (5, 1))
```



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Basics of Neural Network Programming

Explanation of logistic
regression cost function
(Optional)

Logistic regression cost function

$$\hat{y} = g(w^T x + b) \quad \text{where} \quad g(z) = \frac{1}{1+e^{-z}}$$

Interpret $\hat{y} = p(y=1|x)$

If $y=1$: $p(y|x) = \hat{y}$

If $y=0$: $p(y|x) = 1 - \hat{y}$

Logistic regression cost function

$$\begin{aligned} &\rightarrow \boxed{\text{If } y = 1: \quad p(y|x) = \hat{y}} \\ &\rightarrow \boxed{\text{If } y = 0: \quad p(y|x) = 1 - \hat{y}} \end{aligned} \quad \left. \right\} p(y|x)$$
$$p(y|x) = \hat{y}^y (1-\hat{y})^{(1-y)} \quad \leftarrow$$
$$\text{If } y=1: \quad p(y|x) = \hat{y} \underbrace{(1-\hat{y})^0}_{=1}$$
$$\text{If } y=0: \quad p(y|x) = \hat{y}^0 (1-\hat{y})^{(1-y)} = 1, \quad (1-\hat{y}) = \underline{1-\hat{y}}$$
$$\uparrow \log p(y|x) = \log \hat{y}^y (1-\hat{y})^{(1-y)} = y \log \hat{y} + (1-y) \log (1-\hat{y})$$
$$= -\frac{1}{n} \cancel{\sum} (\hat{y}, y) \downarrow$$

Cost on m examples

$$\frac{\log p(\text{labels in training set})}{\log p(\dots)} = \log \prod_{i=1}^m p(y^{(i)} | x^{(i)}) \leftarrow$$

$$\begin{aligned}\frac{\log p(\dots)}{\log p(\dots)} &= \sum_{i=1}^m \underbrace{\log p(y^{(i)} | x^{(i)})}_{-L(\hat{y}^{(i)}, y^{(i)})} \\ &= -\sum_{i=1}^m L(\hat{y}^{(i)}, y^{(i)})\end{aligned}$$

Maximum likelihood
estimation \nwarrow

Cost:
(minimize) $J(w, b) = \frac{1}{m} \sum_{i=1}^m L(\hat{y}^{(i)}, y^{(i)})$

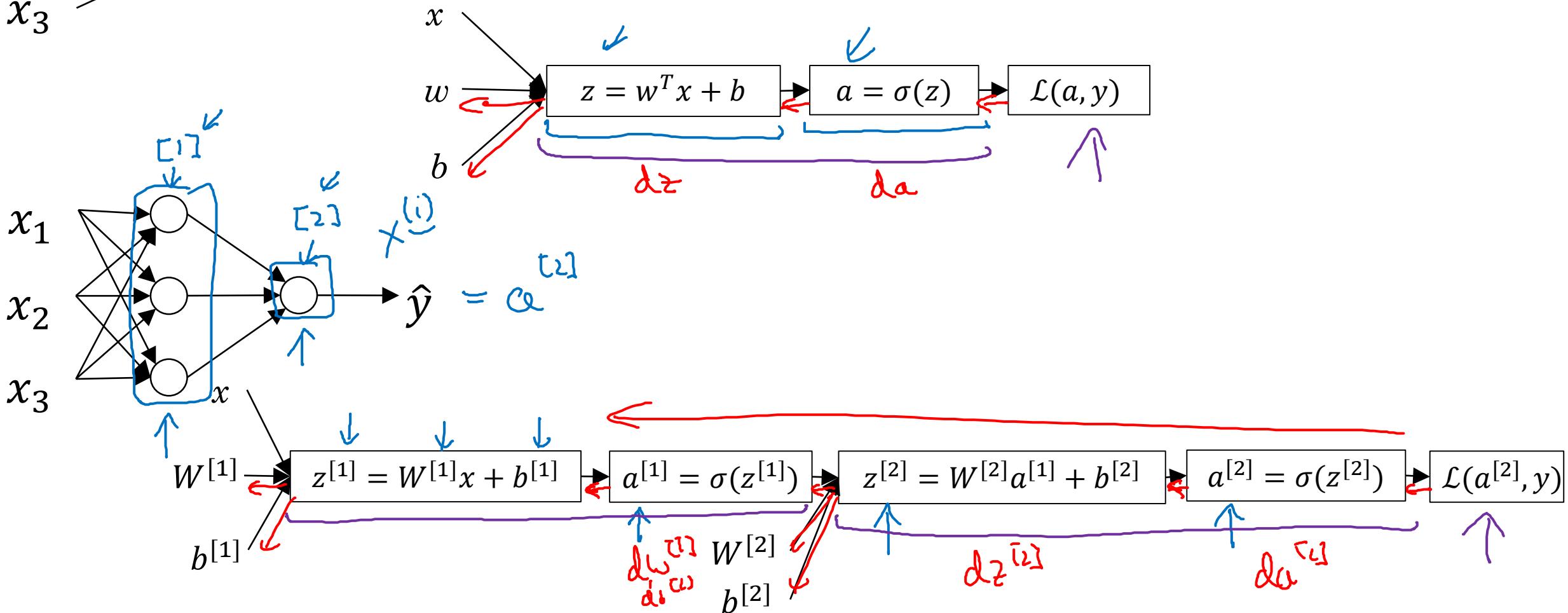
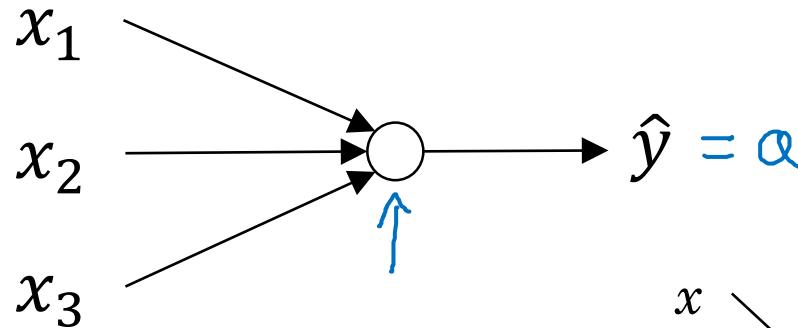


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One hidden layer
Neural Network

Neural Networks
Overview

What is a Neural Network?



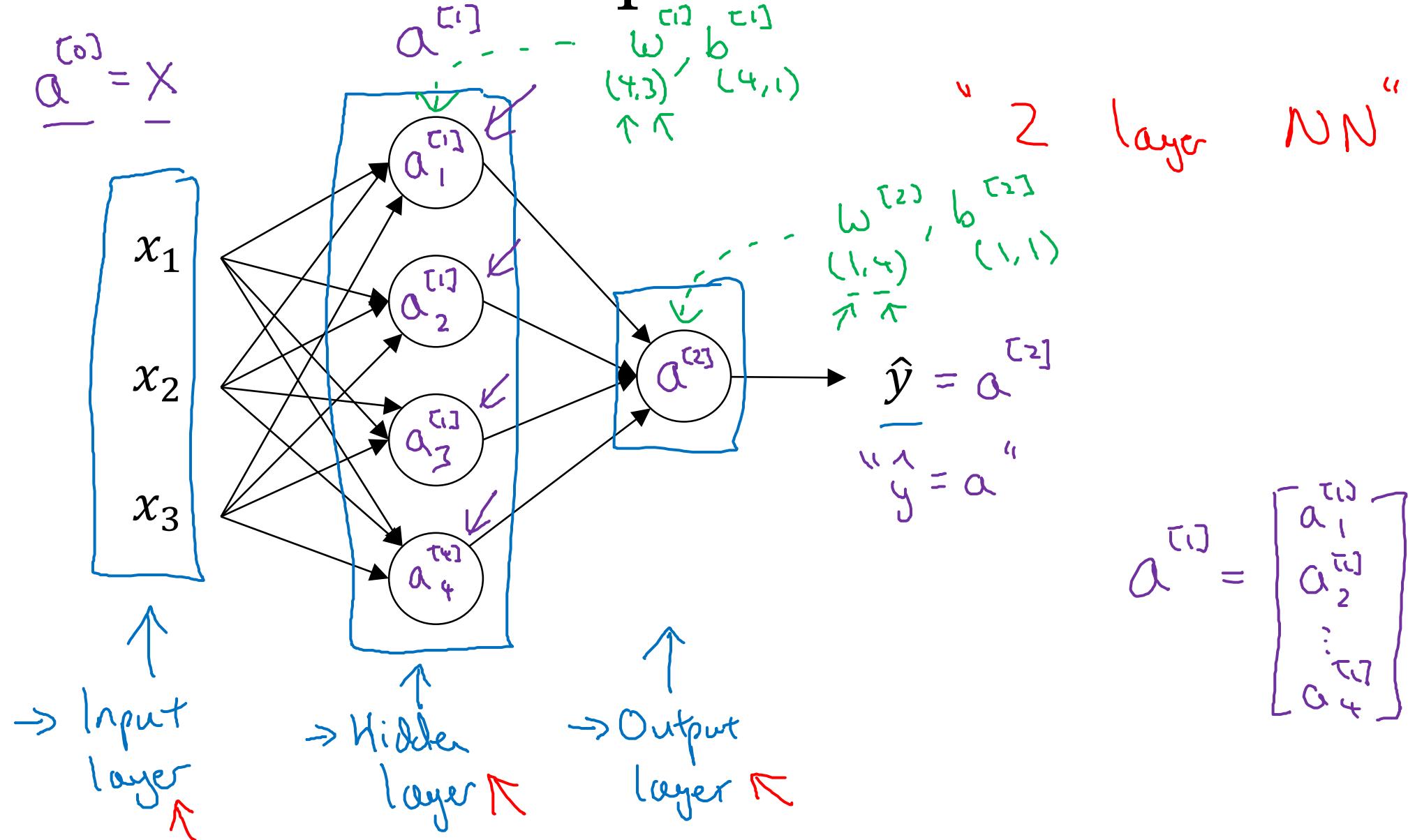


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One hidden layer
Neural Network

Neural Network
Representation

Neural Network Representation



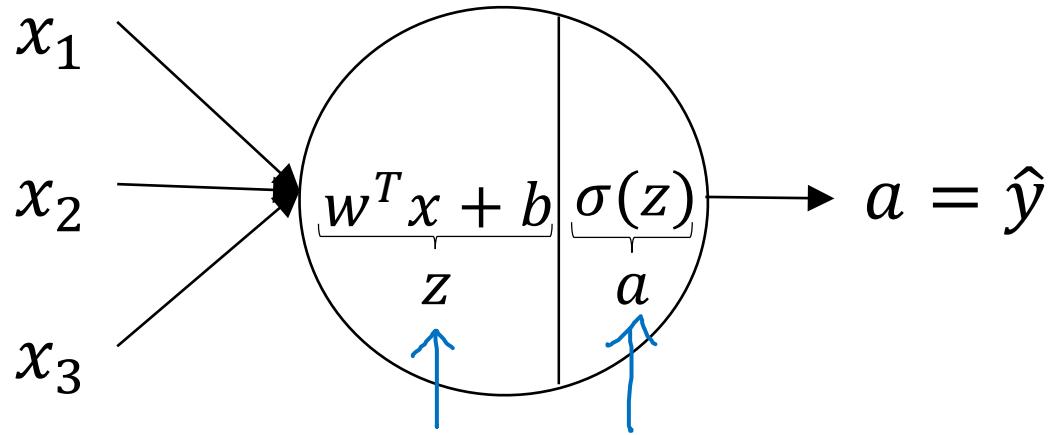


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One hidden layer Neural Network

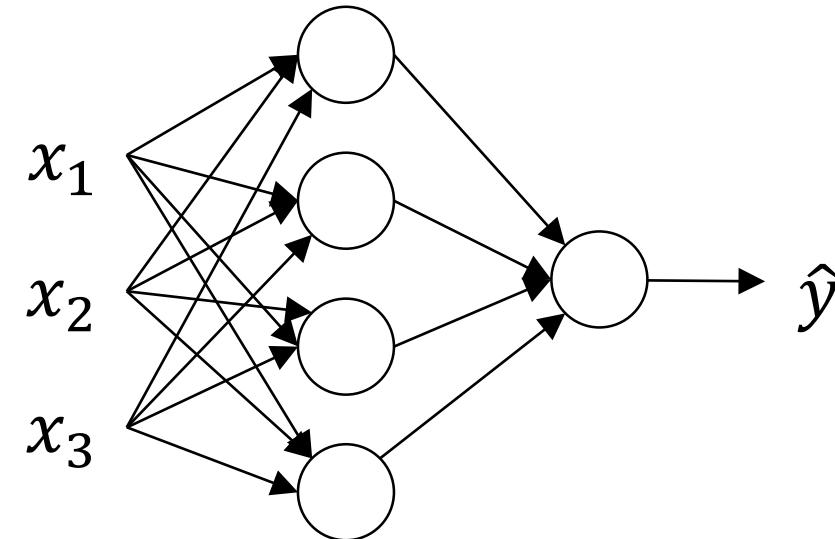
Computing a Neural Network's Output

Neural Network Representation

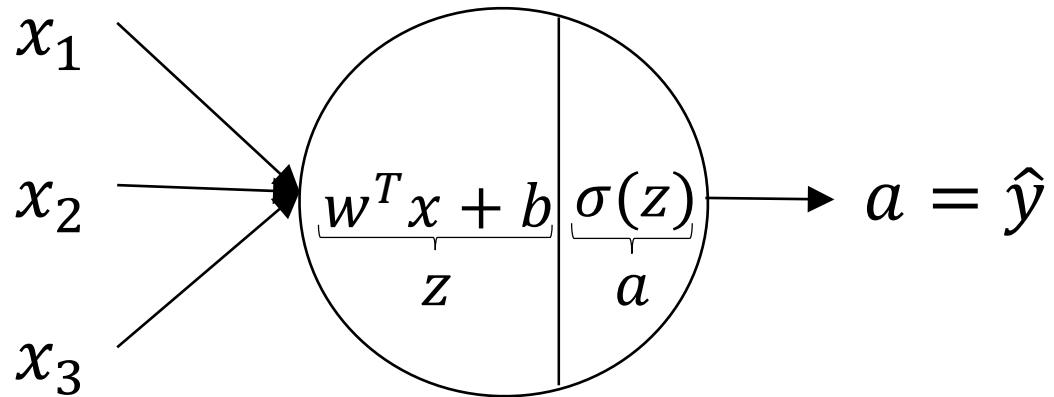


$$z = w^T x + b$$

$$a = \sigma(z)$$

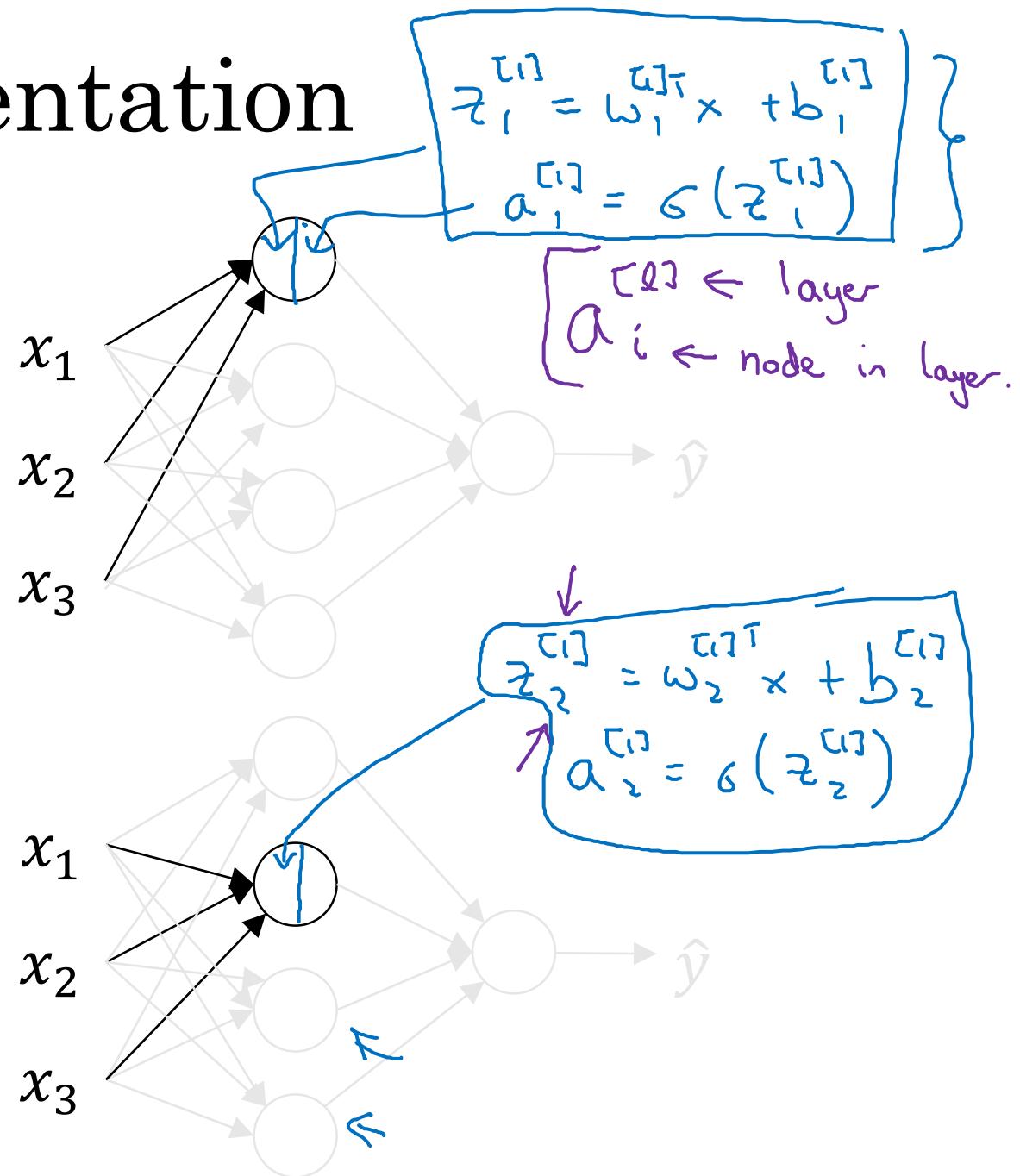


Neural Network Representation

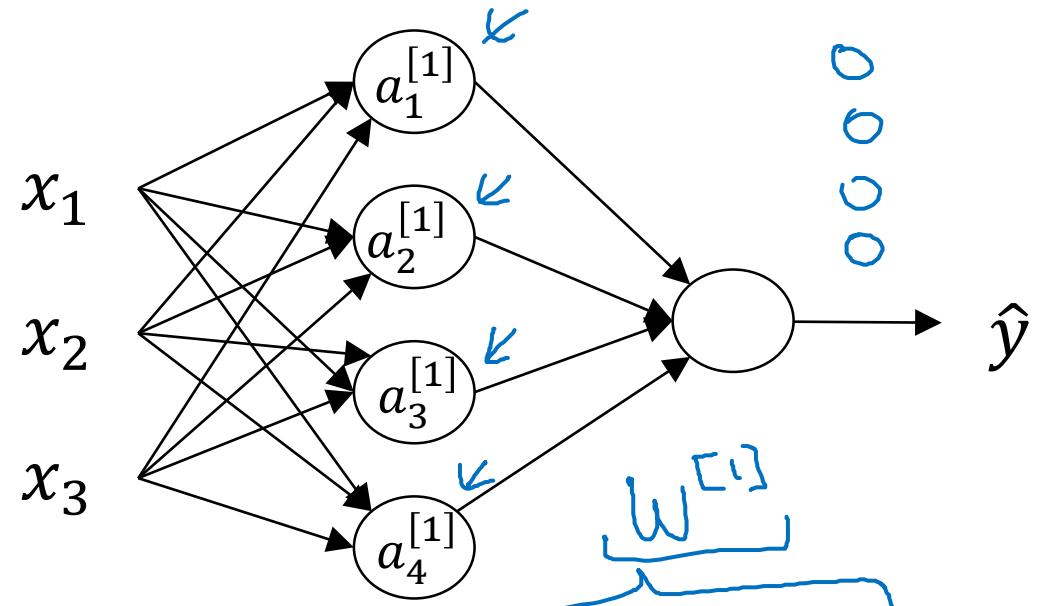


$$z = w^T x + b$$

$$a = \sigma(z)$$



Neural Network Representation



$$\rightarrow z^{[1]} = \begin{bmatrix} w_1^{[1]T} \\ w_2^{[1]T} \\ w_3^{[1]T} \\ w_4^{[1]T} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ b_3^{[1]} \\ b_4^{[1]} \end{bmatrix}$$

$$\rightarrow a^{[1]} = \begin{bmatrix} a_1^{[1]} \\ \vdots \\ a_4^{[1]} \end{bmatrix} = g(z^{[1]})$$

Diagram illustrating the mathematical representation of the neural network:

Inputs: x

Hidden Layer 1:

- $z_1^{[1]} = w_1^{[1]T} x + b_1^{[1]}$
- $z_2^{[1]} = w_2^{[1]T} x + b_2^{[1]}$
- $z_3^{[1]} = w_3^{[1]T} x + b_3^{[1]}$
- $z_4^{[1]} = w_4^{[1]T} x + b_4^{[1]}$

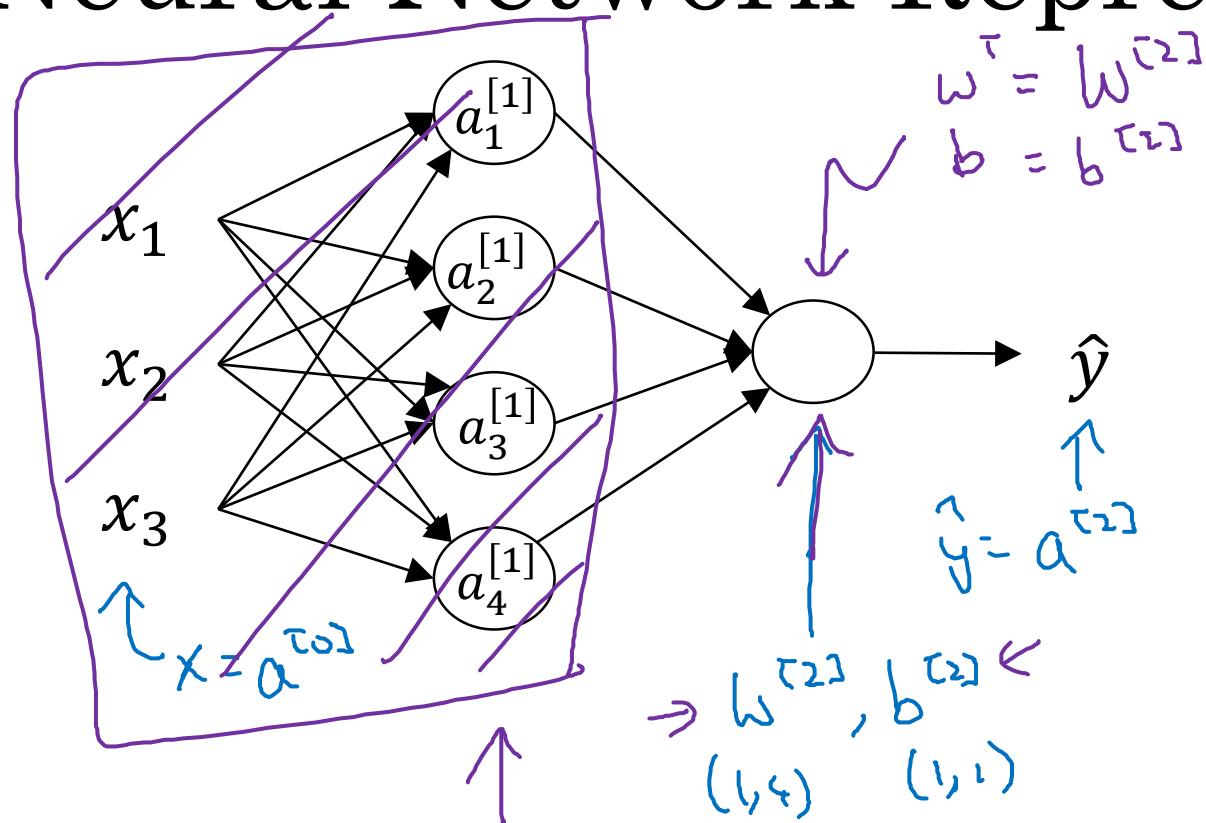
Activation Function:

- $a_1^{[1]} = \sigma(z_1^{[1]})$
- $a_2^{[1]} = \sigma(z_2^{[1]})$
- $a_3^{[1]} = \sigma(z_3^{[1]})$
- $a_4^{[1]} = \sigma(z_4^{[1]})$

Final Output:

$$z^{[1]} = \begin{bmatrix} z_1^{[1]} \\ z_2^{[1]} \\ z_3^{[1]} \\ z_4^{[1]} \end{bmatrix}$$

Neural Network Representation learning



Given input x :

$$\rightarrow z^{[1]} = W^{[1]} a^{[0]} + b^{[1]} \quad \begin{matrix} (4,1) & (4,3) & (3,1) & (4,1) \end{matrix}$$

$$\rightarrow a^{[1]} = \sigma(z^{[1]}) \quad \begin{matrix} (4,1) \\ (4,1) \end{matrix}$$

$$\rightarrow z^{[2]} = W^{[2]} a^{[1]} + b^{[2]} \quad \begin{matrix} (1,1) & (1,4) & (4,1) & (1,1) \end{matrix}$$

$$\rightarrow a^{[2]} = \sigma(z^{[2]}) \quad \begin{matrix} (1,1) \\ (1,1) \end{matrix}$$

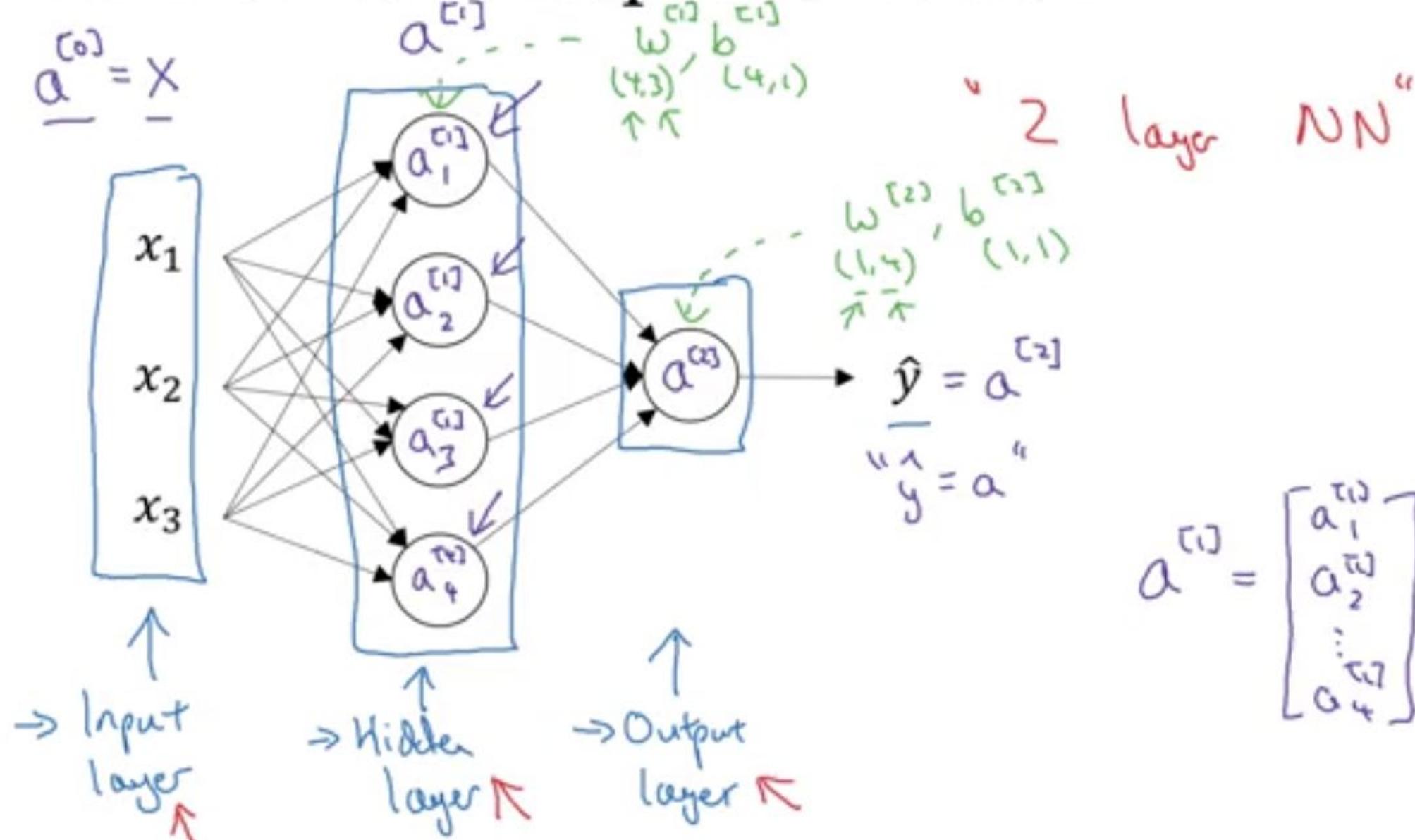


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One hidden layer
Neural Network

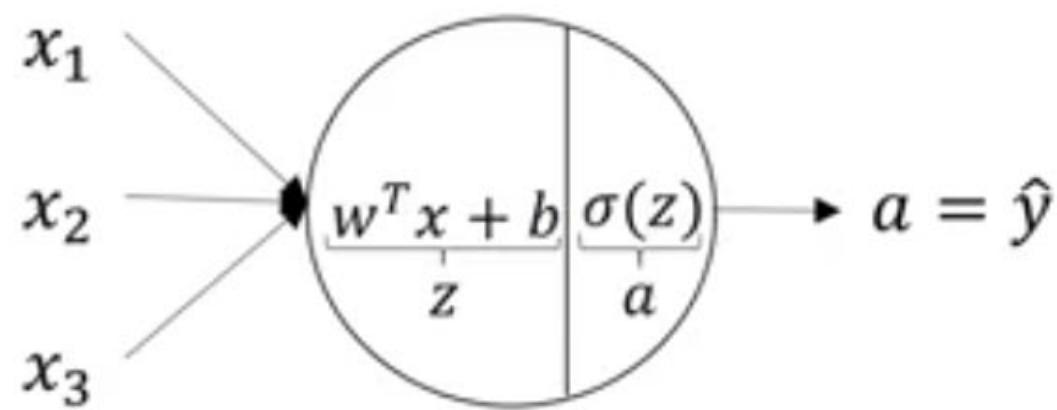
Computing a
Neural Network's
Output

Neural Network Representation



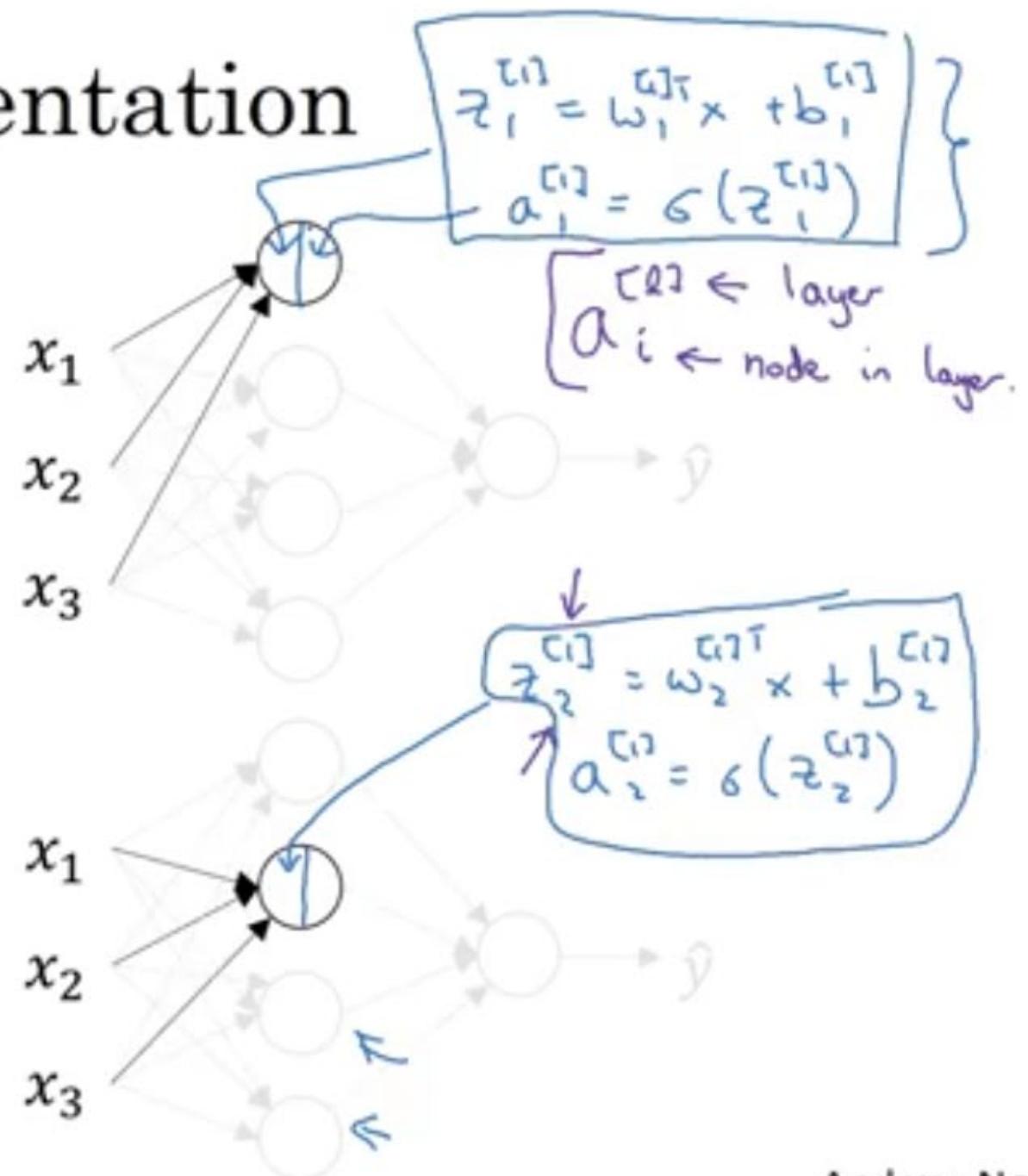
$$\underline{a}^{(1)} = \begin{bmatrix} a_1^{(1)} \\ a_2^{(1)} \\ \vdots \\ a_4^{(1)} \end{bmatrix}$$

Neural Network Representation

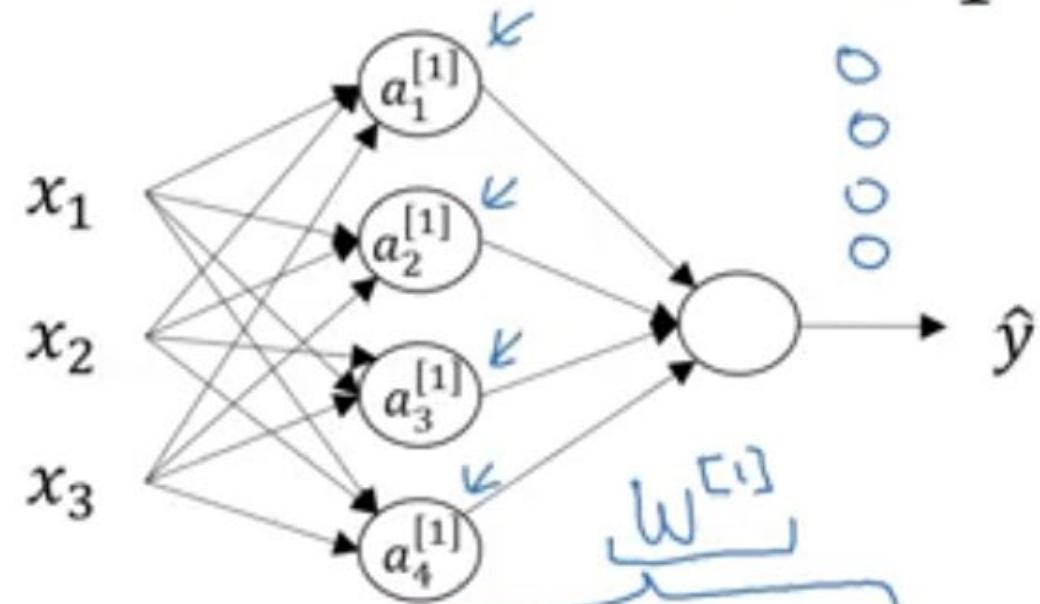


$$z = w^T x + b$$

$$a = \sigma(z)$$



Neural Network Representation



$$\rightarrow z^{[1]} = \begin{bmatrix} w_1^{(1)T} \\ w_2^{(1)T} \\ w_3^{(1)T} \\ w_4^{(1)T} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1^{(1)} \\ b_2^{(1)} \\ b_3^{(1)} \\ b_4^{(1)} \end{bmatrix}$$

$$\rightarrow a^{[1]} = \begin{bmatrix} a_1^{[1]} \\ \vdots \\ a_4^{[1]} \end{bmatrix} = \sigma(z^{[1]})$$

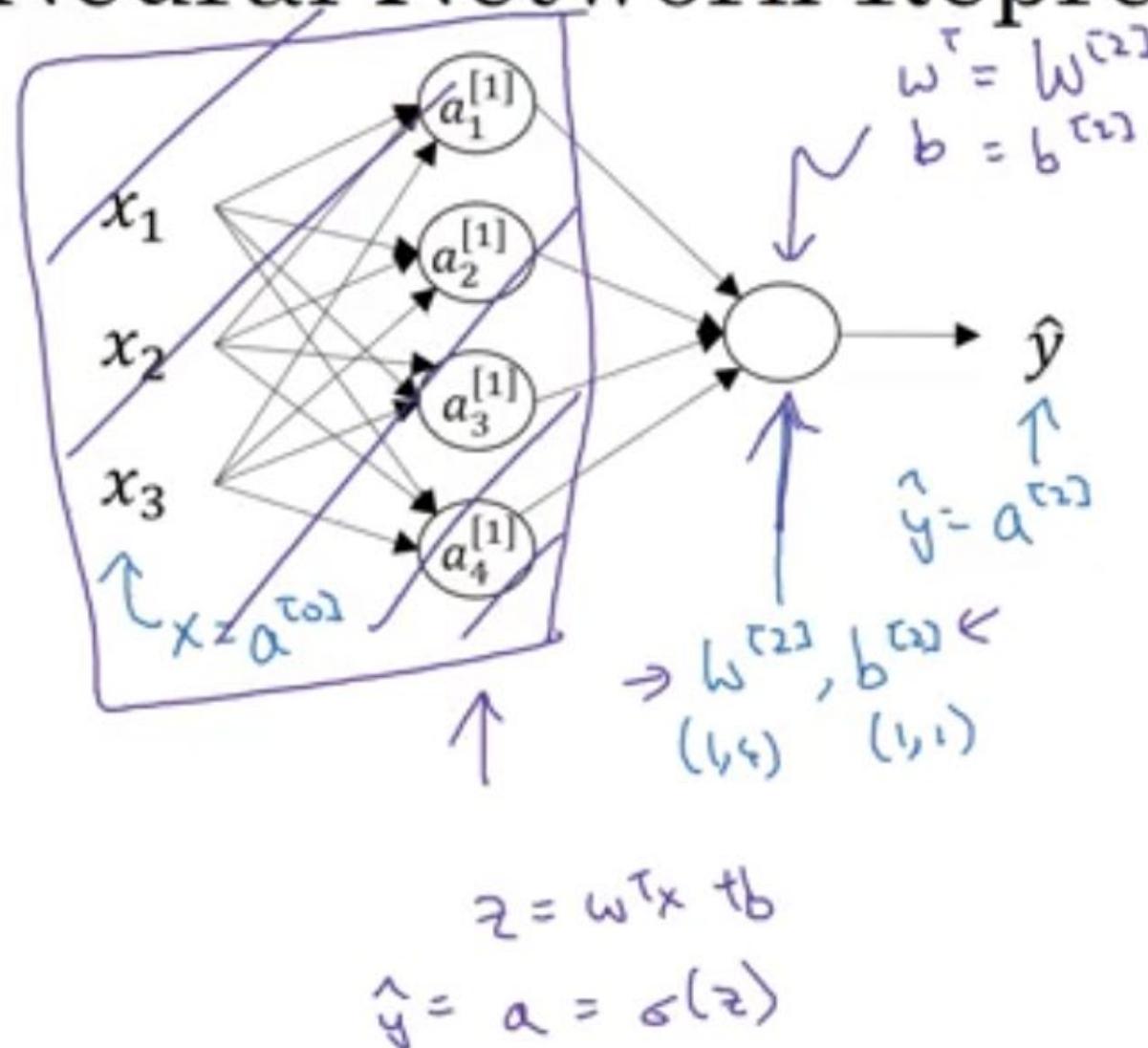
Handwritten notes for the first layer calculations:

$$\begin{aligned} z_1^{[1]} &= w_1^{[1]T} x + b_1^{[1]} \\ z_2^{[1]} &= w_2^{[1]T} x + b_2^{[1]} \\ z_3^{[1]} &= w_3^{[1]T} x + b_3^{[1]} \\ z_4^{[1]} &= w_4^{[1]T} x + b_4^{[1]} \end{aligned}$$

$$\begin{aligned} a_1^{[1]} &= \sigma(z_1^{[1]}) \\ a_2^{[1]} &= \sigma(z_2^{[1]}) \\ a_3^{[1]} &= \sigma(z_3^{[1]}) \\ a_4^{[1]} &= \sigma(z_4^{[1]}) \end{aligned}$$

$$\begin{aligned} \rightarrow z^{[1]} &= \begin{bmatrix} w_1^{(1)T} x + b_1^{(1)} \\ w_2^{(1)T} x + b_2^{(1)} \\ w_3^{(1)T} x + b_3^{(1)} \\ w_4^{(1)T} x + b_4^{(1)} \end{bmatrix} \\ &= \begin{bmatrix} z_1^{(1)} \\ z_2^{(1)} \\ z_3^{(1)} \\ z_4^{(1)} \end{bmatrix} \end{aligned}$$

Neural Network Representation learning



Given input x :

$$\begin{aligned} \rightarrow z^{[1]} &= W^{[1]} x^{[0]} + b^{[1]} \\ &\quad (4,1) \quad (4,3) \quad (3,1) \quad (4,1) \\ \rightarrow a^{[1]} &= \sigma(z^{[1]}) \\ &\quad (4,1) \\ \rightarrow z^{[2]} &= W^{[2]} a^{[1]} + b^{[2]} \\ &\quad (1,1) \quad (4,4) \quad (4,1) \quad (1,1) \\ \rightarrow a^{[2]} &= \sigma(z^{[2]}) \\ &\quad (1,1) \end{aligned}$$

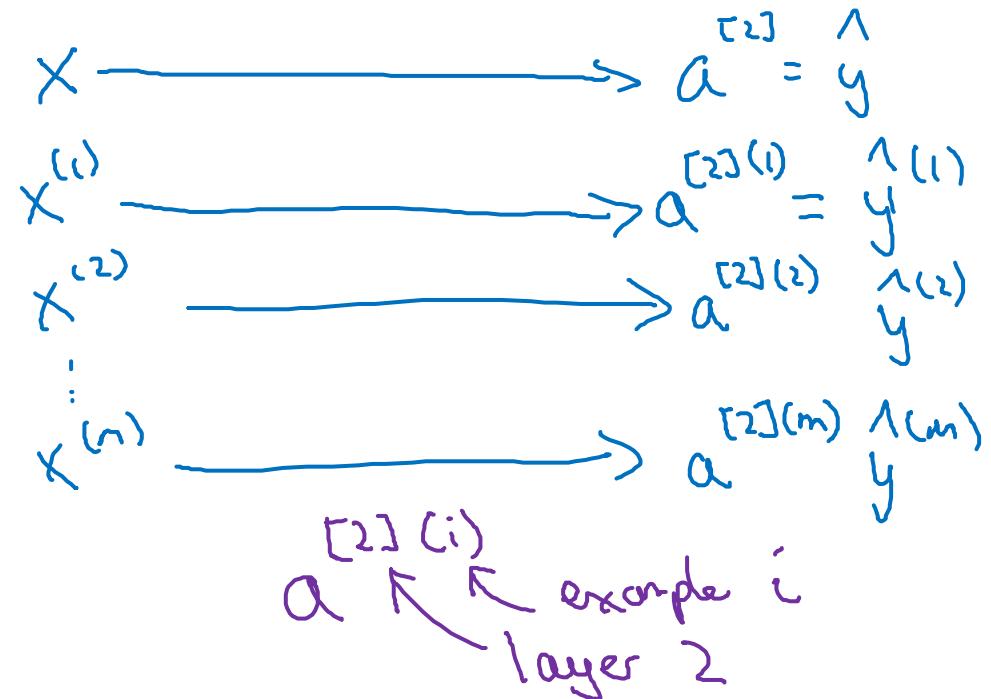
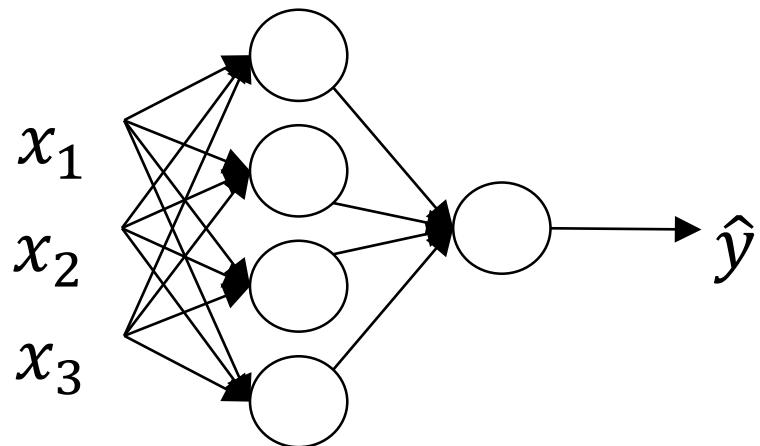


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One hidden layer Neural Network

Vectorizing across
multiple examples

Vectorizing across multiple examples



$\left. \begin{array}{l} z^{[1]} = W^{[1]}x + b^{[1]} \\ a^{[1]} = \sigma(z^{[1]}) \\ z^{[2]} = W^{[2]}a^{[1]} + b^{[2]} \\ a^{[2]} = \sigma(z^{[2]}) \end{array} \right\}$

for $i = 1$ to m ,

$z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}$

$a^{[1](i)} = \sigma(z^{[1](i)})$

$z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2]}$

$a^{[2](i)} = \sigma(z^{[2](i)})$

Vectorizing across multiple examples

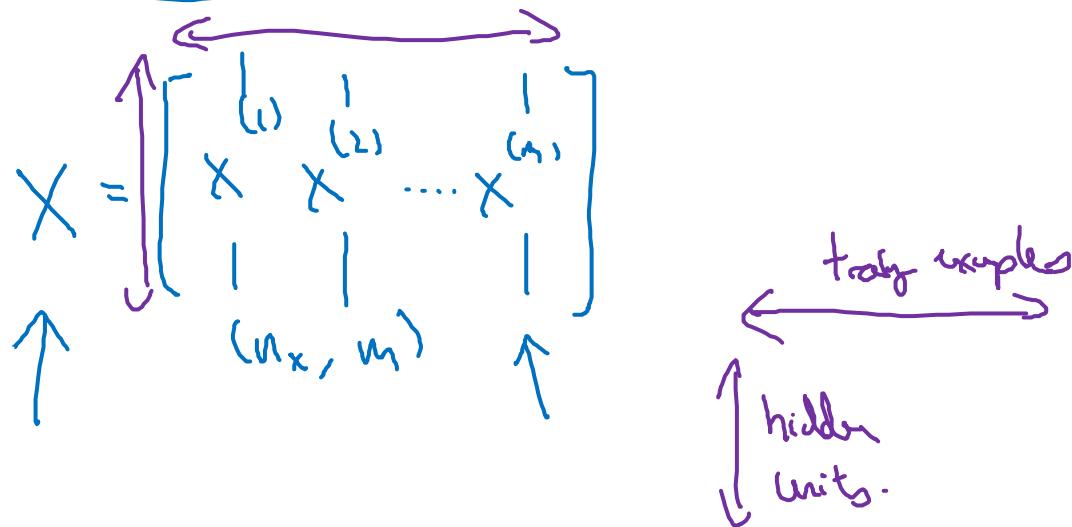
for $i = 1$ to m :

$$z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}$$

$$a^{[1](i)} = \sigma(z^{[1](i)})$$

$$z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2]}$$

$$a^{[2](i)} = \sigma(z^{[2](i)})$$



$$\begin{aligned} z^{[1]} &= W^{[1]}X + b^{[1]} \\ \rightarrow A^{[1]} &= \sigma(z^{[1]}) \\ \rightarrow z^{[2]} &= W^{[2]}A^{[1]} + b^{[2]} \\ \rightarrow A^{[2]} &= \sigma(z^{[2]}) \end{aligned}$$

The diagram shows the vectorized hidden states $z^{[1]}$ as a column vector with elements $z^{1}, z^{[1](2)}, \dots, z^{[1](m)}$. Below it, the activations $A^{[1]}$ are shown as a column vector with elements $a^{1}, a^{[1](2)}, \dots, a^{[1](m)}$. Purple arrows indicate the flow from $z^{[1]}$ to $A^{[1]}$. A purple bracket on the right indicates the dimension is (n_a, m) , where n_a is labeled "hidden units".



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One hidden layer Neural Network

Explanation for vectorized implementation

Justification for vectorized implementation

$$z^{1} = w^{[1]} x^{(1)} + b^{[1]}, \quad z^{[1](2)} = w^{[1]} x^{(2)} + b^{[1]}, \quad z^{[1](3)} = w^{[1]} x^{(3)} + b^{[1]}$$

$$w^{[1]} = \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix}$$

$$w^{[1]} x^{(1)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$w^{[1]} x^{(2)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

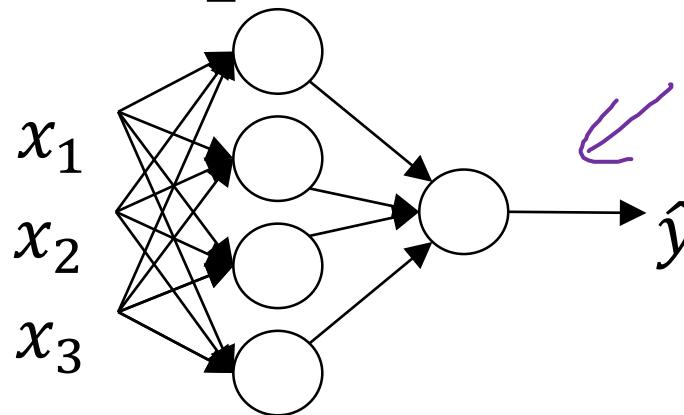
$$w^{[1]} x^{(3)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$z^{[1]} = w^{[1]} X + b^{[1]}$$

\times

$$w^{[1]} x^{(1)} = z^{1}$$
$$w^{[1]} x^{(2)} = z^{[1](2)}$$
$$w^{[1]} x^{(3)} = z^{[1](3)}$$
$$z^{1} + b^{[1]} = z^{[1]}$$
$$z^{[1](2)} + b^{[1]} = z^{[1]}$$
$$z^{[1](3)} + b^{[1]} = z^{[1]}$$

Recap of vectorizing across multiple examples



$$X = \begin{bmatrix} | & | & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & | \end{bmatrix}$$

A matrix X where each column $x^{(i)}$ represents the input features for example i . A purple arrow points from the text "vectorizing across multiple examples" to the vertical bars separating the columns of X .

$$\underline{A^{[1]}} = \begin{bmatrix} | & | & | \\ a^{1} & a^{[1](2)} & \dots & a^{[1](m)} \\ | & | & | \end{bmatrix}$$

A matrix $A^{[1]}$ where each column $a^{[1](i)}$ represents the activations of all neurons in the first layer for example i . A purple arrow points from the text "vectorizing across multiple examples" to the vertical bars separating the columns of $A^{[1]}$.

for $i = 1$ to m

$\rightarrow z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}$

$\rightarrow a^{[1](i)} = \sigma(z^{[1](i)})$

$\rightarrow z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2]}$

$\rightarrow a^{[2](i)} = \sigma(z^{[2](i)})$

$A^{[0]} \leftarrow x = a^{[0]}$

$x^{(i)} = a^{[0](i)}$

$Z^{[1]} = W^{[1]}X + b^{[1]} \leftarrow w^{[1]}A^{[0]} + b^{[1]}$

$A^{[1]} = \sigma(Z^{[1]})$

$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$

$A^{[2]} = \sigma(Z^{[2]})$



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One hidden layer Neural Network

Explanation
for vectorized
implementation

Justification for vectorized implementation

$$z^{(1)(1)} = \omega^{(1)} x^{(1)} + b^{(1)}, \quad z^{(1)(2)} = \omega^{(2)} x^{(2)} + b^{(2)}, \quad z^{(1)(3)} = \omega^{(3)} x^{(3)} + b^{(3)}$$

$$\omega^{(1)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$\omega^{(1)} x^{(1)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$\omega^{(2)} x^{(2)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

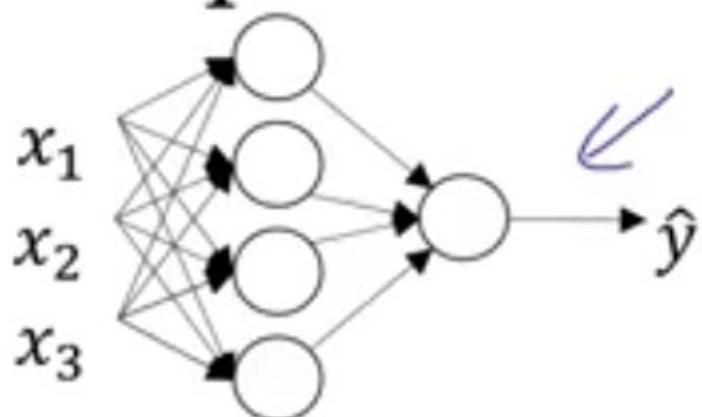
$$\omega^{(3)} x^{(3)} = \begin{bmatrix} \cdot \\ \cdot \\ \cdot \end{bmatrix}$$

$$\begin{aligned} \omega^{(1)} \begin{bmatrix} 1 & 1 & 1 \\ x^{(1)} & x^{(2)} & x^{(3)} \dots \end{bmatrix} &= \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ z^{(1)(1)} & z^{(1)(2)} & z^{(1)(3)} \dots \end{bmatrix} = z^{(1)} \\ z^{(1)} &= \omega^{(1)} x + b^{(1)} \end{aligned}$$

\times

$$\omega^{(1)} x^{(1)} = z^{(1)(1)}$$

Recap of vectorizing across multiple examples



$$X = \begin{bmatrix} | & | & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & | \end{bmatrix}$$

$$\underline{A^{[1]}} = \begin{bmatrix} | & | & | \\ a^{1} & a^{[1](2)} & \dots & a^{[1](m)} \\ | & | & | \end{bmatrix}$$

for i = 1 to m

$\rightarrow z^{[1](i)} = W^{[1]}x^{(i)} + b^{[1]}$

$\rightarrow a^{[1](i)} = \sigma(z^{[1](i)})$

$\rightarrow z^{[2](i)} = W^{[2]}a^{[1](i)} + b^{[2]}$

$\rightarrow a^{[2](i)} = \sigma(z^{[2](i)})$

$Z^{[1]} = W^{[1]}X + b^{[1]} \leftarrow w^{[1]}A^{[1]} + b^{[1]}$

$A^{[1]} = \sigma(Z^{[1]})$

$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$

$A^{[2]} = \sigma(Z^{[2]})$

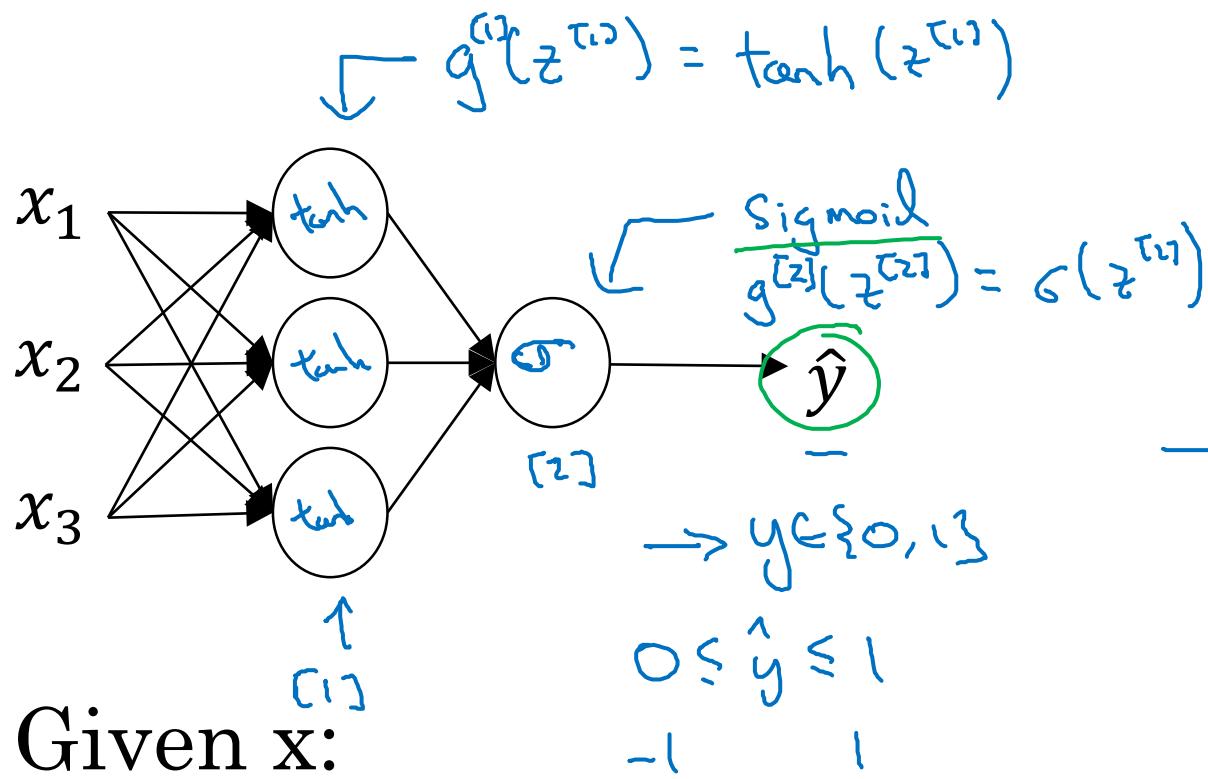


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One hidden layer
Neural Network

Activation functions

Activation functions

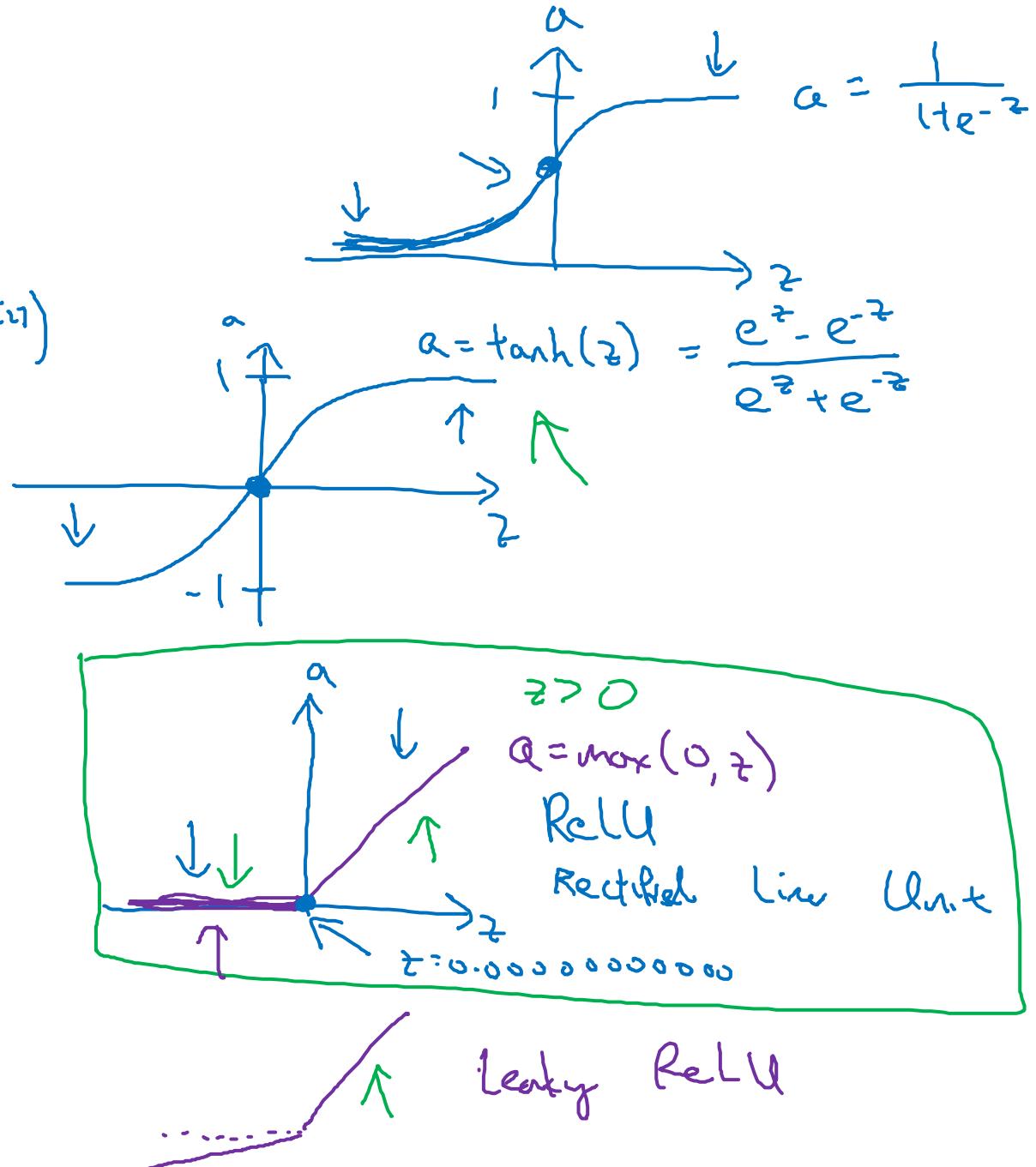


$$z^{[1]} = W^{[1]}x + b^{[1]}$$

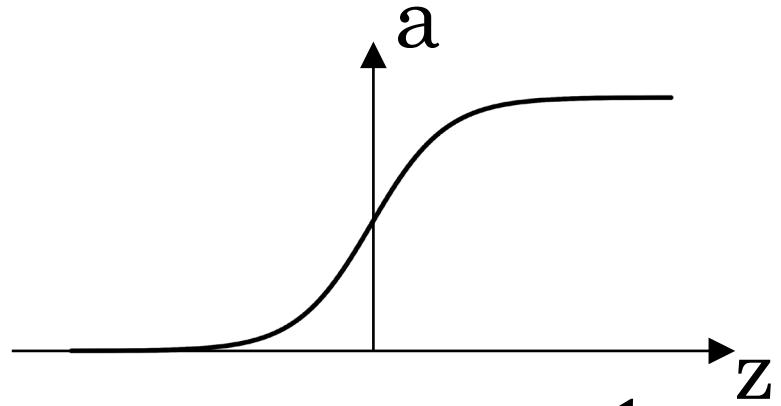
$$\rightarrow a^{[1]} = \sigma(z^{[1]})$$

$$z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

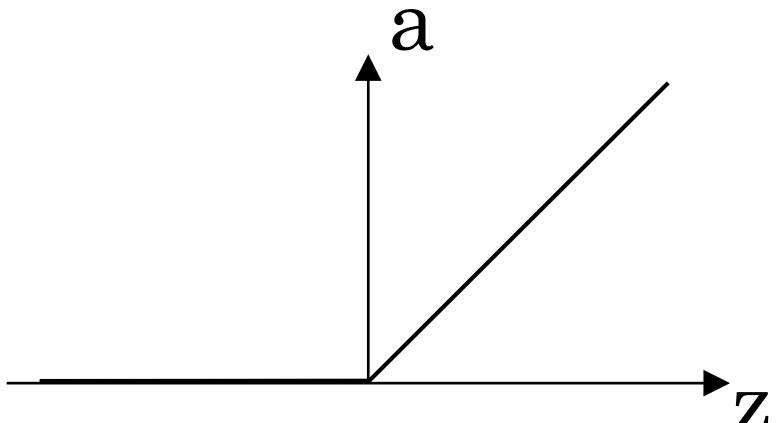
$$\rightarrow a^{[2]} = \sigma(z^{[2]})$$



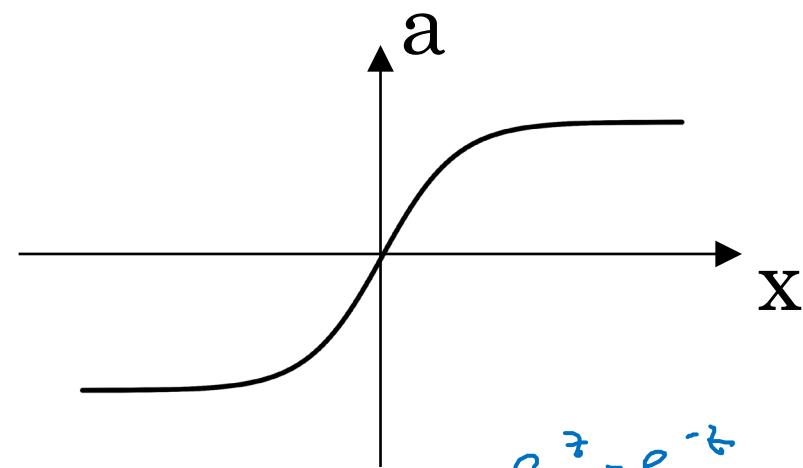
Pros and cons of activation functions



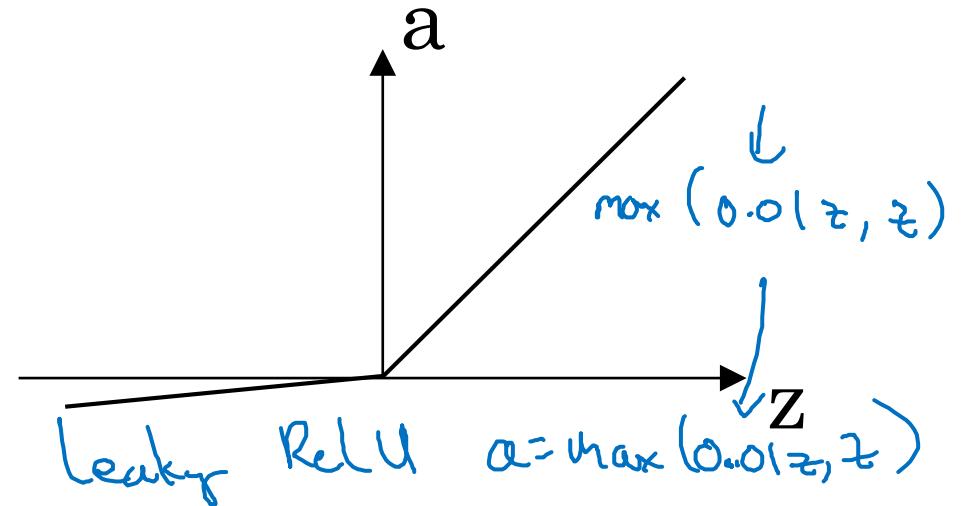
$$\text{sigmoid: } a = \frac{1}{1 + e^{-z}}$$



$$\text{ReLU} \quad a = \max(0, z)$$



$$\tanh: a = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$



$$\text{Leaky ReLU} \quad a = \max(0.01z, z)$$

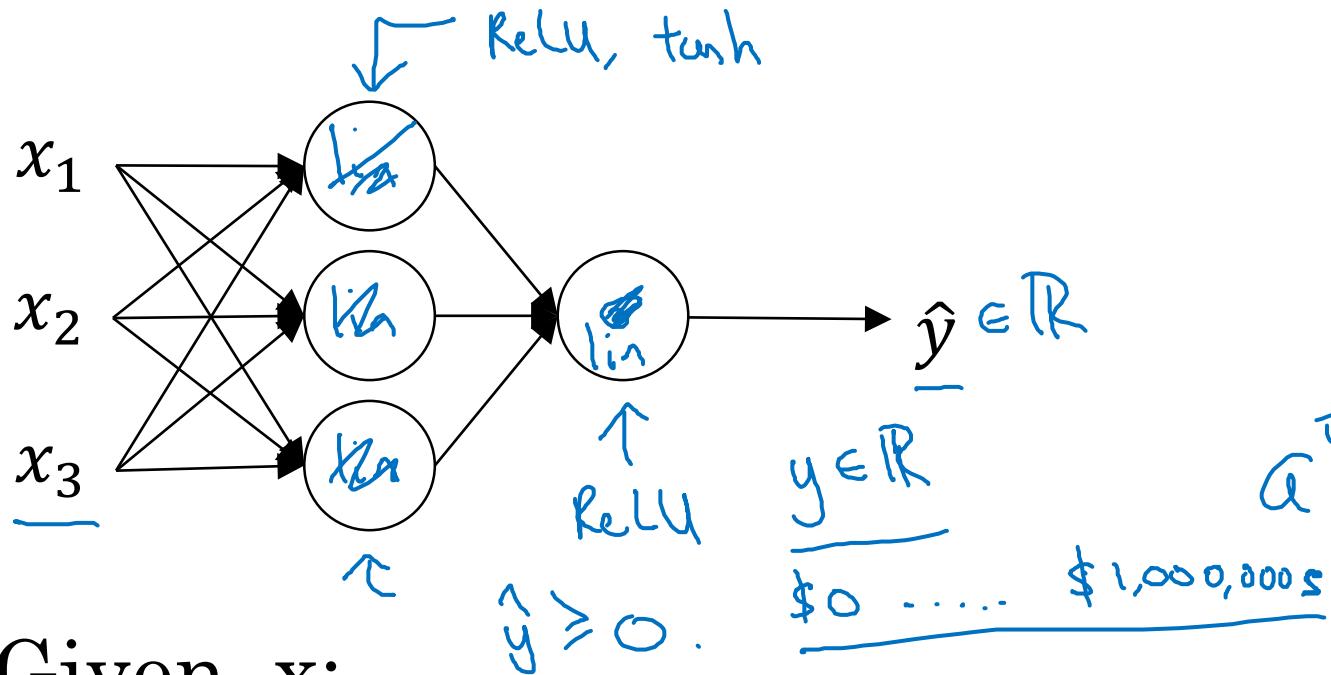


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One hidden layer Neural Network

Why do you
need non-linear
activation functions?

Activation function



Given x :

$$\rightarrow z^{[1]} = W^{[1]}x + b^{[1]}$$

$$\rightarrow a^{[1]} = \cancel{g^{[1]}(z^{[1]})} \geq^{z^{[1]}}$$

$$\rightarrow z^{[2]} = W^{[2]}a^{[1]} + b^{[2]}$$

$$\rightarrow a^{[2]} = \cancel{g^{[2]}(z^{[2]})} \geq^{z^{[2]}}$$

$g(z) = z$
"linear activation
function"

$$a^{[1]} = z^{[1]} = \underbrace{W^{[1]}x + b^{[1]}}_{a^{[1]}}$$

$$a^{[2]} = z^{[2]} = \underbrace{W^{[2]}a^{[1]} + b^{[2]}}_{a^{[2]}}$$

$$a^{[2]} = W^{[2]} \left(\underbrace{W^{[1]}x + b^{[1]}}_{a^{[1]}} \right) + b^{[2]}$$

$$= (\underbrace{W^{[2]} W^{[1]}}_{w'})x + (\underbrace{W^{[2]} b^{[1]} + b^{[2]}}_{b'})$$

$$= \underbrace{w'x + b'}_{g(z)}$$

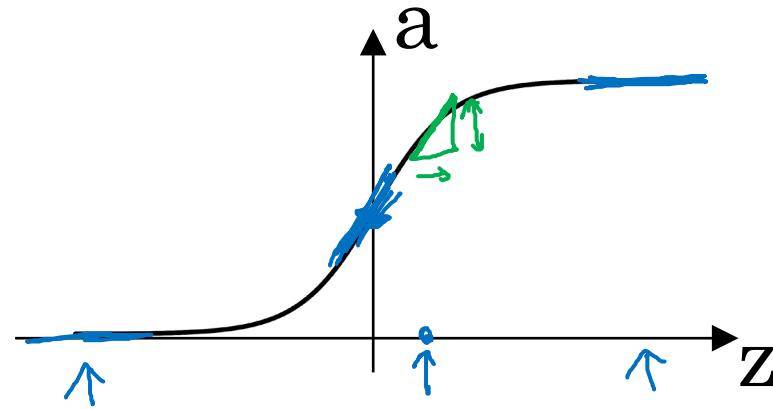


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One hidden layer
Neural Network

Derivatives of
activation functions

Sigmoid activation function



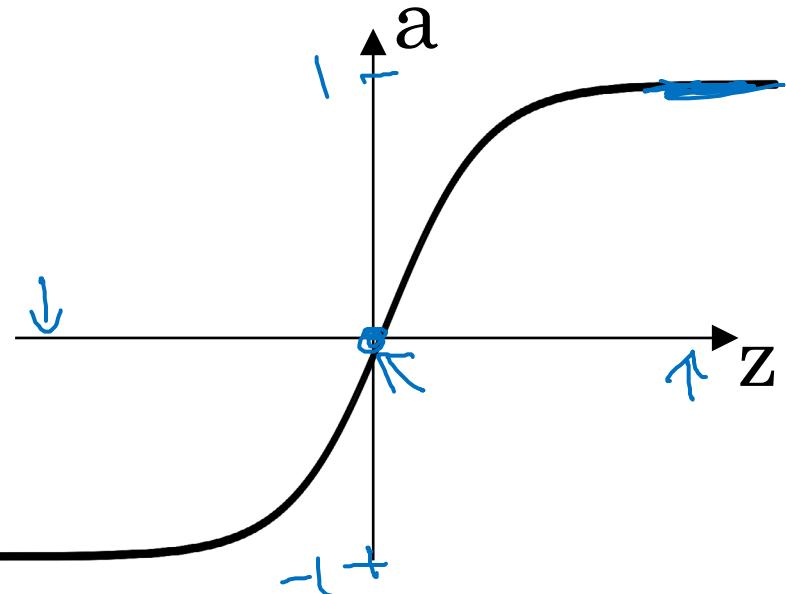
$$g(z) = \frac{1}{1 + e^{-z}}$$

$$a = g(z) = \frac{1}{1 + e^{-z}}$$

$$\begin{aligned}
 g'(z) &= \boxed{\frac{d}{dz} g(z)} \\
 &= \frac{1}{1 + e^{-z}} \left(1 - \frac{1}{1 + e^{-z}} \right) \\
 &= g(z) \left(1 - g(z) \right) \quad \leftarrow \boxed{g'(z) = a(1-a)} \\
 &= \boxed{a(1-a)}
 \end{aligned}$$

$$\begin{aligned}
 z = 10, \quad g(z) &\approx 1 \\
 \frac{d}{dz} g(z) &\approx 1(1-1) \approx 0 \\
 z = -10, \quad g(z) &\approx 0 \\
 \frac{d}{dz} g(z) &\approx 0 \cdot (1-0) \approx 0 \\
 z = 0, \quad g(z) &= \frac{1}{2} \\
 \frac{d}{dz} g(z) &= \frac{1}{2}(1-\frac{1}{2}) = \frac{1}{4}
 \end{aligned}$$

Tanh activation function



$$g(z) = \tanh(z)$$

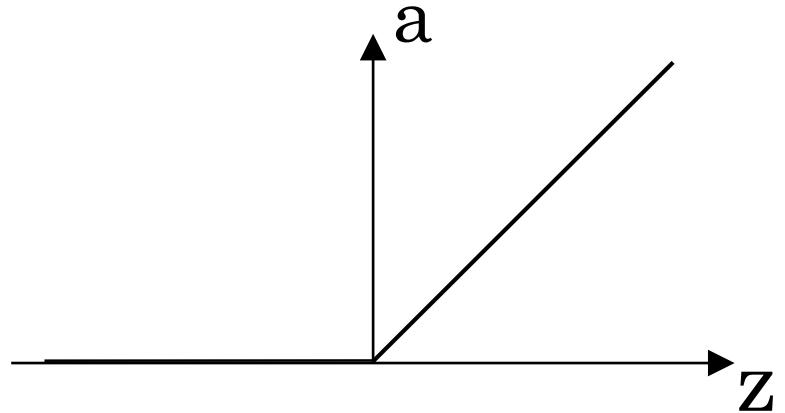
$$= \frac{e^z - e^{-z}}{e^z + e^{-z}}$$

$$\begin{aligned} g'(z) &= \frac{d}{dz} g(z) = \text{slope of } g(z) \text{ at } z \\ &= 1 - \underline{\underline{(\tanh(z))^2}} \end{aligned}$$

$$a = g(z), \quad g'(z) = 1 - a^2$$

$$\left| \begin{array}{ll} z = 10 & \tanh(z) \approx 1 \\ & g'(z) \approx 0 \\ z = -10 & \tanh(z) \approx -1 \\ & g'(z) \approx 0 \\ z = 0 & \tanh(z) = 0 \\ & g'(z) = 1 \end{array} \right.$$

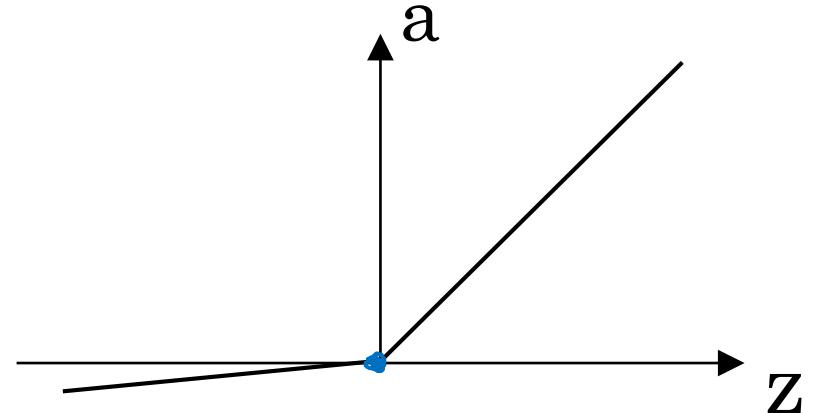
ReLU and Leaky ReLU



ReLU

$$g(z) = \max(0, z)$$

$$\Rightarrow g''(z) = \begin{cases} 0 & \text{if } z < 0 \\ -1 & \text{if } z \geq 0 \\ \text{undefined} & \text{if } z = 0 \end{cases}$$



Leaky ReLU

$$g(z) = \max(0.01z, z)$$

$$g'(z) = \begin{cases} 0.01 & \text{if } z < 0 \\ 1 & \text{if } z \geq 0 \end{cases}$$



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One hidden layer
Neural Network

Gradient descent for
neural networks

Gradient descent for neural networks

Parameters: $(\omega^{(1)}, b^{(1)})$, $(\omega^{(2)}, b^{(2)})$, \dots , $(\omega^{(L)}, b^{(L)})$, $n_x = n^{(0)}, n^{(1)}, \dots, n^{(L)} = 1$

Cost function: $J(\underline{\omega}^{(1)}, \underline{b}^{(1)}, \underline{\omega}^{(2)}, \underline{b}^{(2)}) = \frac{1}{m} \sum_{i=1}^m l(\hat{y}, y)$

Gradient descent:

→ Repeat {

→ Compute predicts $(\hat{y}^{(i)}, i=1 \dots m)$

$$\frac{\partial J}{\partial \omega^{(1)}} = \frac{\partial J}{\partial \omega^{(1)}}, \quad \frac{\partial J}{\partial b^{(1)}} = \frac{\partial J}{\partial b^{(1)}}, \dots$$

$$\omega^{(1)} := \omega^{(1)} - \alpha \frac{\partial J}{\partial \omega^{(1)}}$$

$$b^{(1)} := b^{(1)} - \alpha \frac{\partial J}{\partial b^{(1)}}$$

↓

$\omega^{(2)} := \dots$

$b^{(2)} := \dots$

Formulas for computing derivatives

Forward propagation:

$$z^{[1]} = w^{[1]}X + b^{[1]}$$

$$A^{[1]} = g^{[1]}(z^{[1]}) \leftarrow$$

$$z^{[2]} = w^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = g^{[2]}(z^{[2]}) = \underline{\underline{\sigma}}(z^{[2]})$$

Back propagation:

$$dz^{[2]} = A^{[2]} - Y \leftarrow$$

$$dW^{[2]} = \frac{1}{m} dz^{[2]} A^{[1]T}$$

$$db^{[2]} = \frac{1}{m} \underline{\underline{\text{np.sum}}}(dz^{[2]}, \underline{\underline{\text{axis=1}}}, \underline{\underline{\text{keepdims=True}}})$$

$$dz^{[1]} = \underbrace{w^{[2]T} dz^{[2]}}_{(n^{[2]}, m)} \times \underbrace{g^{[2]'}(z^{[2]})}_{\text{element-wise product}} (n^{[1]}, m)$$

$$dW^{[1]} = \frac{1}{m} dz^{[1]} X^T$$

$$\cancel{db^{[1]} = \frac{1}{m} \underline{\underline{\text{np.sum}}}(dz^{[1]}, \underline{\underline{\text{axis=1}}}, \underline{\underline{\text{keepdims=True}}})}$$

$$Y = [y^{(1)}, y^{(2)}, \dots, y^{(m)}]$$

$$(n^{[1]}) \leftarrow$$

$$\cancel{(n^{[2]}, 1) \leftarrow}$$

$$\cancel{(n^{[1]}, m)}$$

$$(n^{[1]}, m)$$

reshape ↑



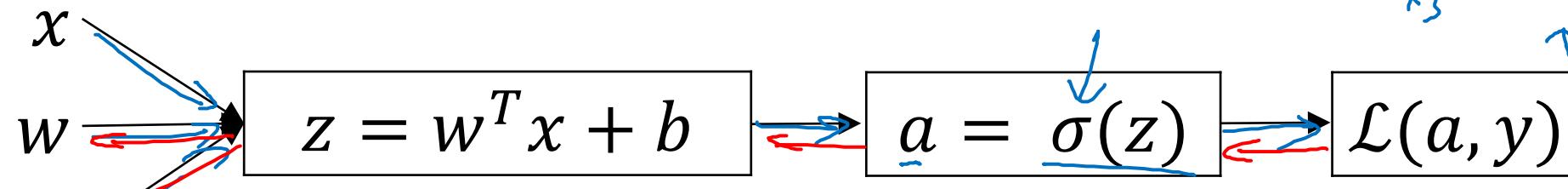
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One hidden layer
Neural Network

Backpropagation
intuition (Optional)

Computing gradients

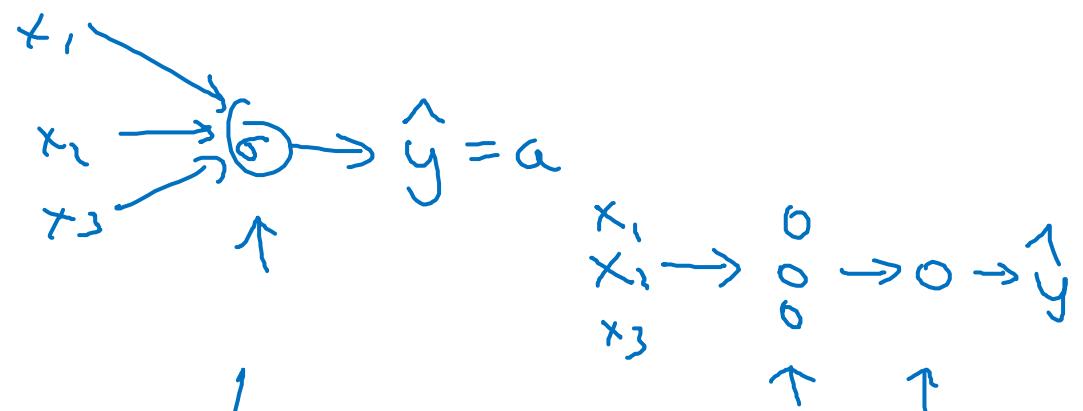
Logistic regression



$$\begin{aligned} & \frac{\partial z}{\partial w} = x \\ & \frac{\partial z}{\partial b} = 1 \\ & \frac{\partial \mathcal{L}}{\partial z} = \frac{\partial \mathcal{L}}{\partial a} \cdot g'(z) \\ & g(z) = \sigma(z) \\ & \frac{\partial \mathcal{L}}{\partial z} = \frac{\partial \mathcal{L}}{\partial a} \cdot \frac{\partial a}{\partial z} \end{aligned}$$

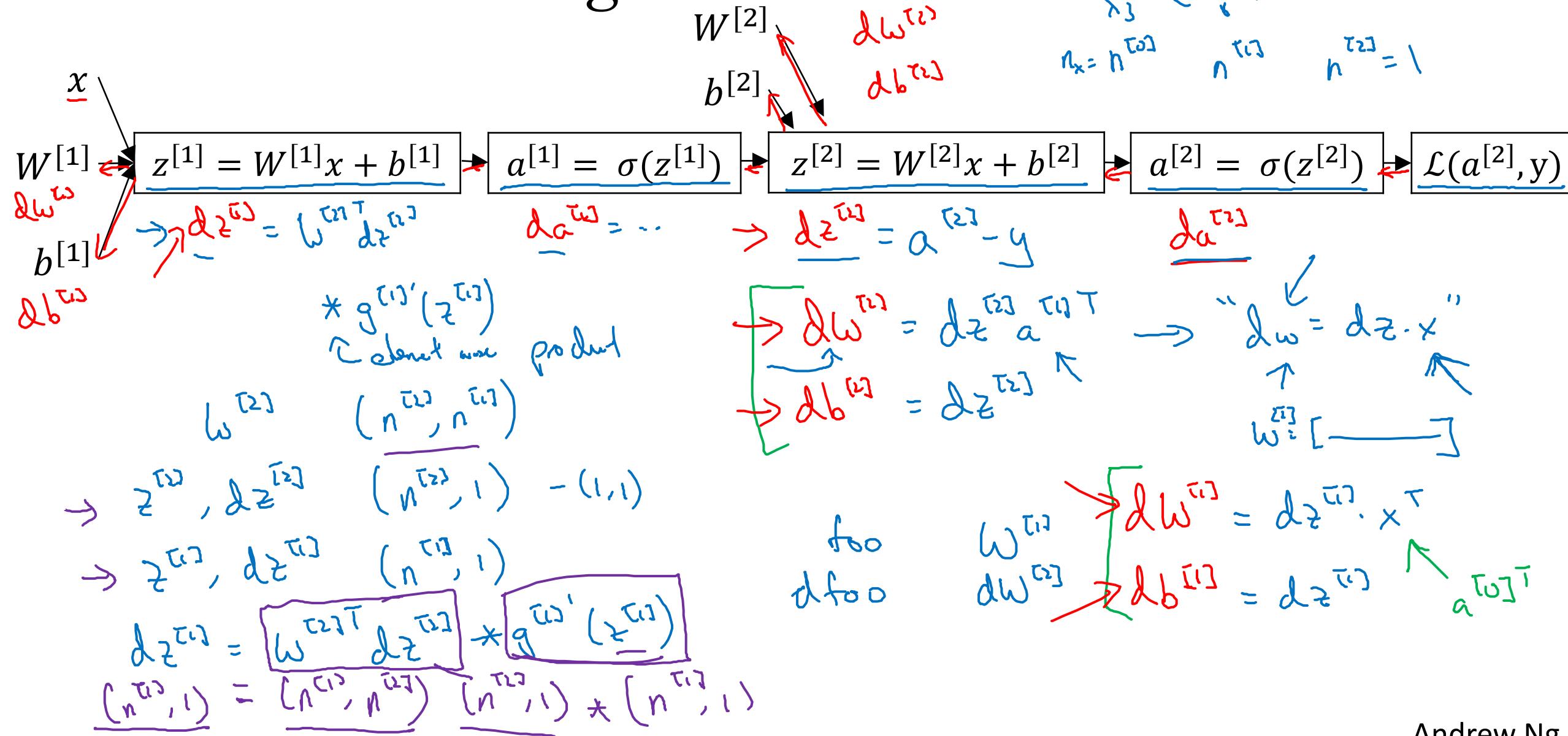
" $\frac{\partial z}{\partial w}$ " = " $\frac{\partial a}{\partial z}$ "

$$\frac{\partial}{\partial z} g(z) = g'(z)$$



$$\begin{aligned} \frac{\partial \mathcal{L}}{\partial a} &= \frac{d}{da} \mathcal{L}(a, y) = -y \log a - (1-y) \log(1-a) \\ &= -\frac{y}{a} + \frac{1-y}{1-a} \end{aligned}$$

Neural network gradients



Summary of gradient descent

$$dz^{[2]} = a^{[2]} - y$$

$$dW^{[2]} = dz^{[2]} a^{[1]T}$$

$$db^{[2]} = dz^{[2]}$$

$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

$$dW^{[1]} = dz^{[1]} x^T$$

$$db^{[1]} = dz^{[1]}$$

Vectorized implementation:

$$\begin{aligned} z^{[1]} &= \underbrace{w^{[1]} x + b^{[1]}}_{\text{Implementation}} \\ a^{[1]} &= g^{[1]}(z^{[1]}) \end{aligned}$$

$$Z^{[1]} = \begin{bmatrix} | & | & | & | \\ z^{1} & z^{[1](2)} & \dots & z^{[1](n)} \\ | & | & | & | \end{bmatrix}$$

$$\begin{aligned} z^{[1]} &= w^{[1]} X + b^{[1]} \\ A^{[1]} &= g^{[1]}(Z^{[1]}) \end{aligned}$$

Summary of gradient descent

$$\underline{dz}^{[2]} = \underline{a}^{[2]} - \underline{y}$$

$$dW^{[2]} = dz^{[2]} a^{[1]T}$$

$$db^{[2]} = dz^{[2]}$$

$$dz^{[1]} = W^{[2]T} dz^{[2]} * g^{[1]'}(z^{[1]})$$

(n^{T₁}, 1)

$$dW^{[1]} = dz^{[1]} X^T$$

$$db^{[1]} = dz^{[1]}$$

$$\underline{dZ}^{[2]} = \underline{A}^{[2]} - \underline{Y}$$

$$dW^{[2]} = \frac{1}{m} dZ^{[2]} A^{[1]T}$$

$$db^{[2]} = \frac{1}{m} np.sum(dZ^{[2]}, axis = 1, keepdims = True)$$

$$dZ^{[1]} = \underbrace{W^{[2]T} dZ^{[2]}}_{(n^{T₂}, m)} * \underbrace{g^{[1]'}(Z^{[1]})}_{(n^{T₁}, m)}$$

elementwise product

$$dW^{[1]} = \frac{1}{m} dZ^{[1]} X^T$$

$$db^{[1]} = \frac{1}{m} np.sum(dZ^{[1]}, axis = 1, keepdims = True)$$

$$J(\cdot) = \frac{1}{m} \sum_{i=1}^m \mathcal{L}(\hat{y}_i, y_i)$$

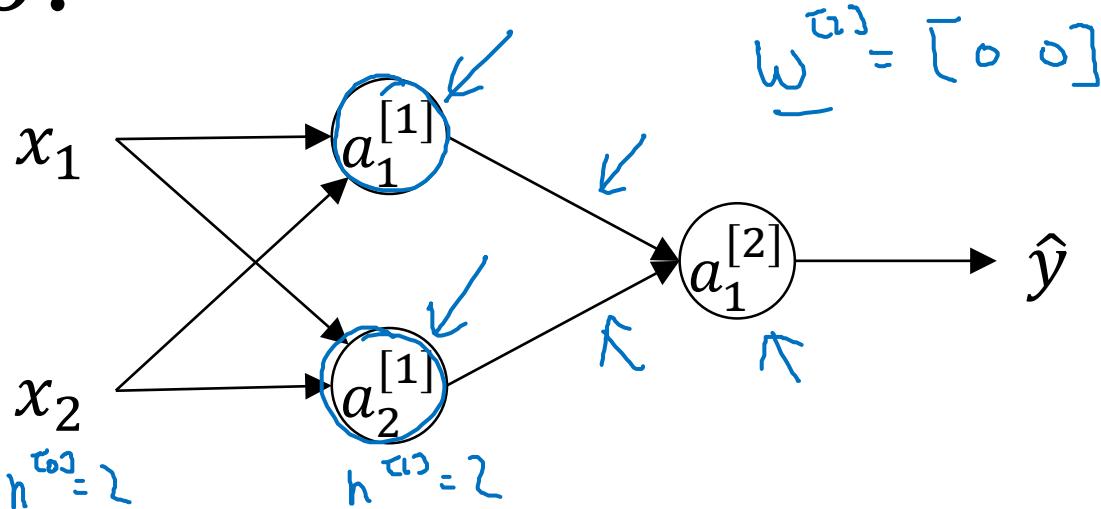


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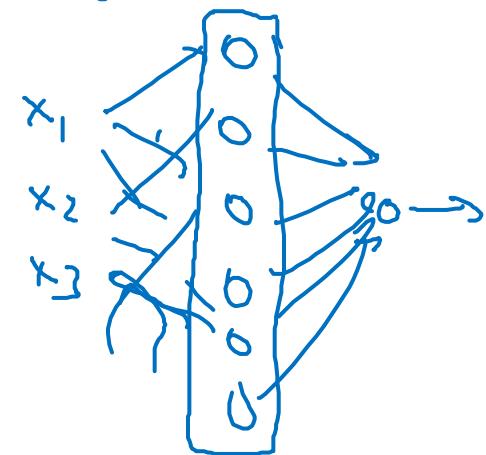
One hidden layer
Neural Network

Random Initialization

What happens if you initialize weights to zero?



Symmetric

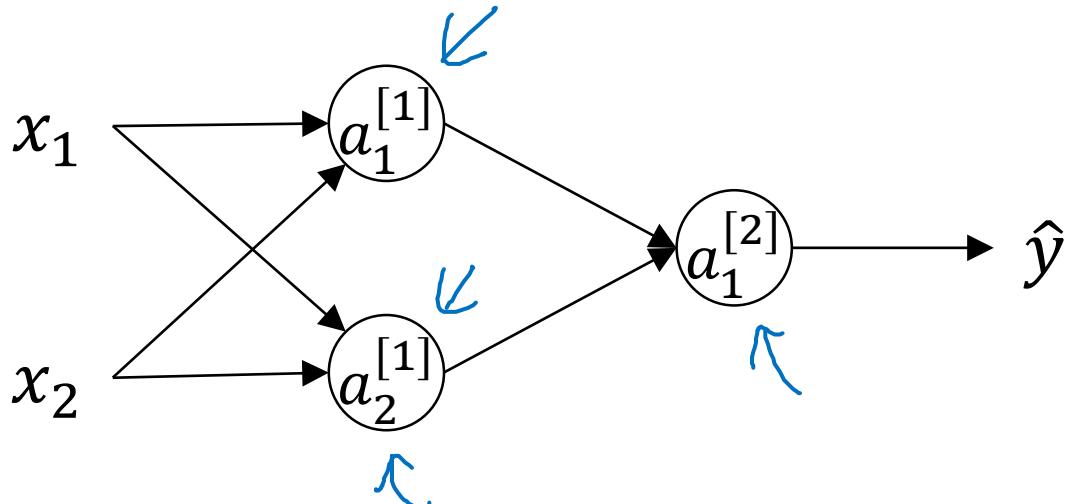


$$W^L = \begin{bmatrix} \dots & \dots & \dots \end{bmatrix}$$

$$\Delta W = \begin{bmatrix} u & v \\ u & v \end{bmatrix}$$

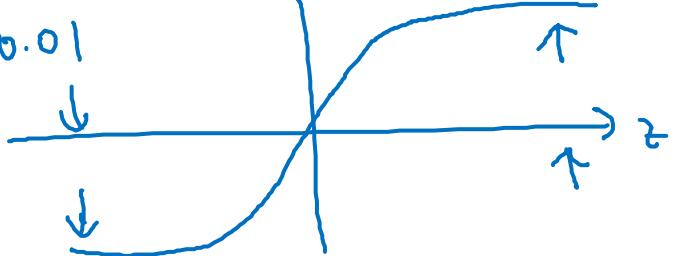
$$W^L = W^L - \lambda \Delta W$$

Random initialization



$$\begin{aligned} \rightarrow w^{[1]} &= \text{np.random.randn}(2, 2) \times \frac{0.01}{100?} \\ b^{[1]} &= \text{np.zeros}(2, 1) \\ w^{[2]} &= \text{np.random.randn}(1, 2) \times 0.01 \\ b^{[2]} &= 0 \end{aligned}$$

$$\begin{aligned} z^{[1]} &= w^{[1]} \times + b^{[1]} \\ a^{[1]} &= g^{[1]}(z^{[1]}) \end{aligned}$$



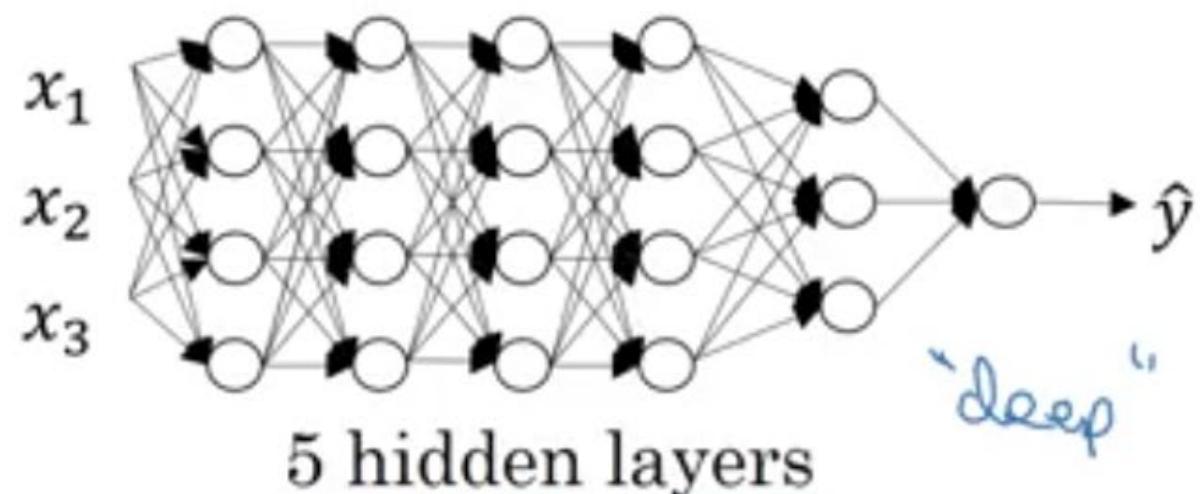
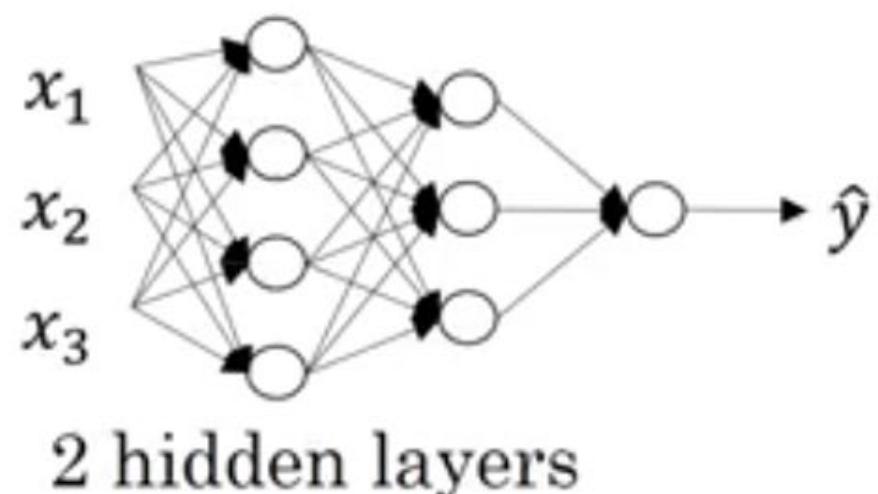
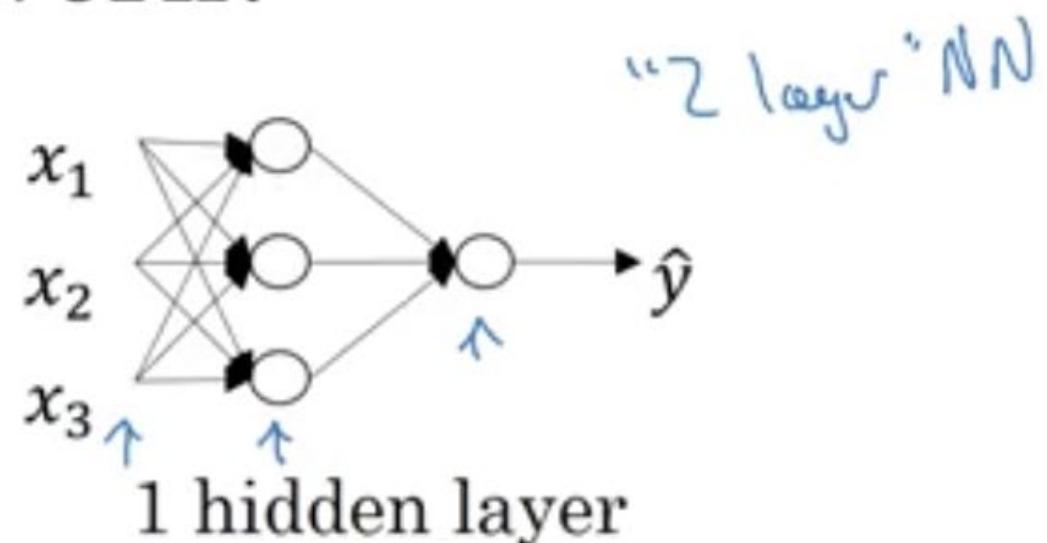
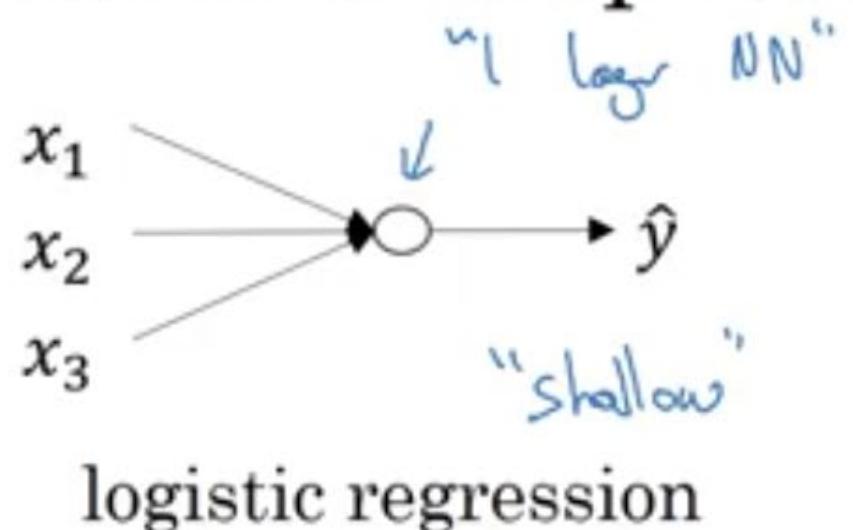


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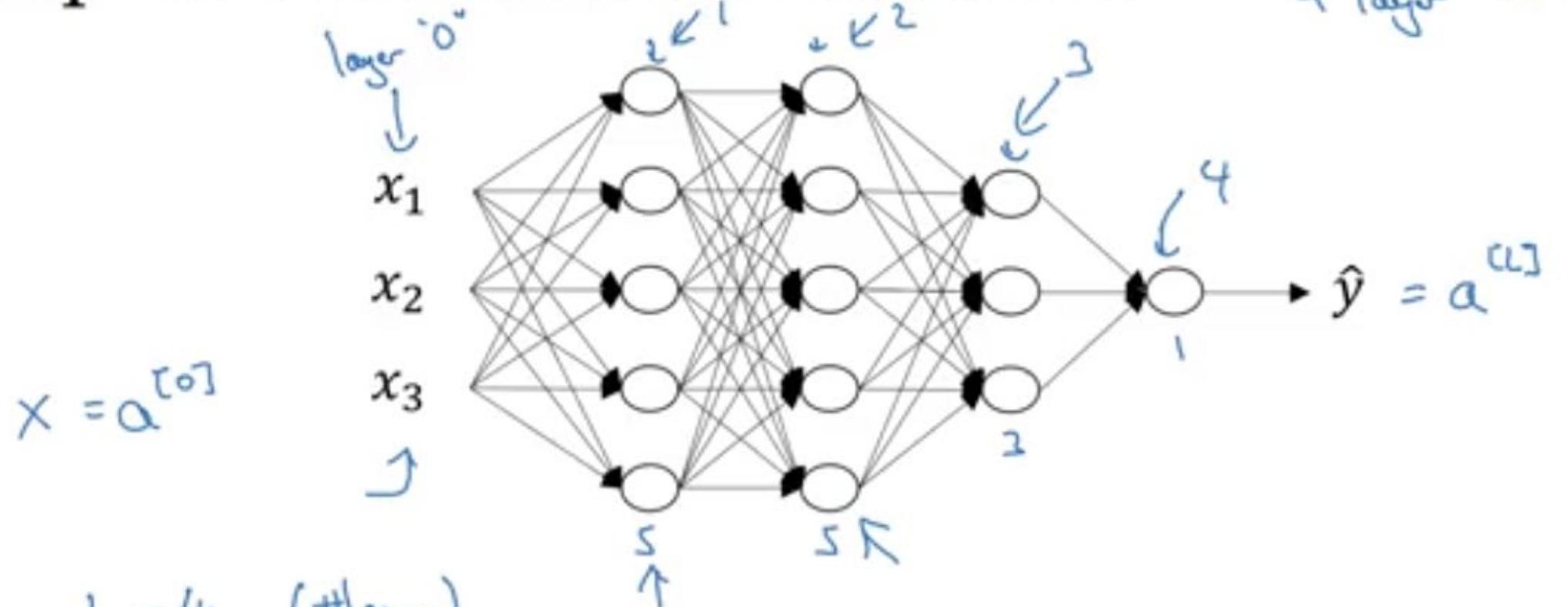
Deep Neural Networks

Deep L-layer Neural network

What is a deep neural network?



Deep neural network notation



$L = 4$ (#layers)

$n^{[l]}$ = #units in layer l

$a^{[l]}$ = activations in layer l

$a^{[l]} = g^{[l]}(z^{[l]})$, $w_{j,n}^{[l]}$ = weights for $z_j^{[l]}$

$n^{[1]} = 5$, $n^{[2]} = 5$, $n^{[3]} = 3$, $n^{[4]} = n^{[L]} = 1$
 $n^{[0]} = n_x = 3$

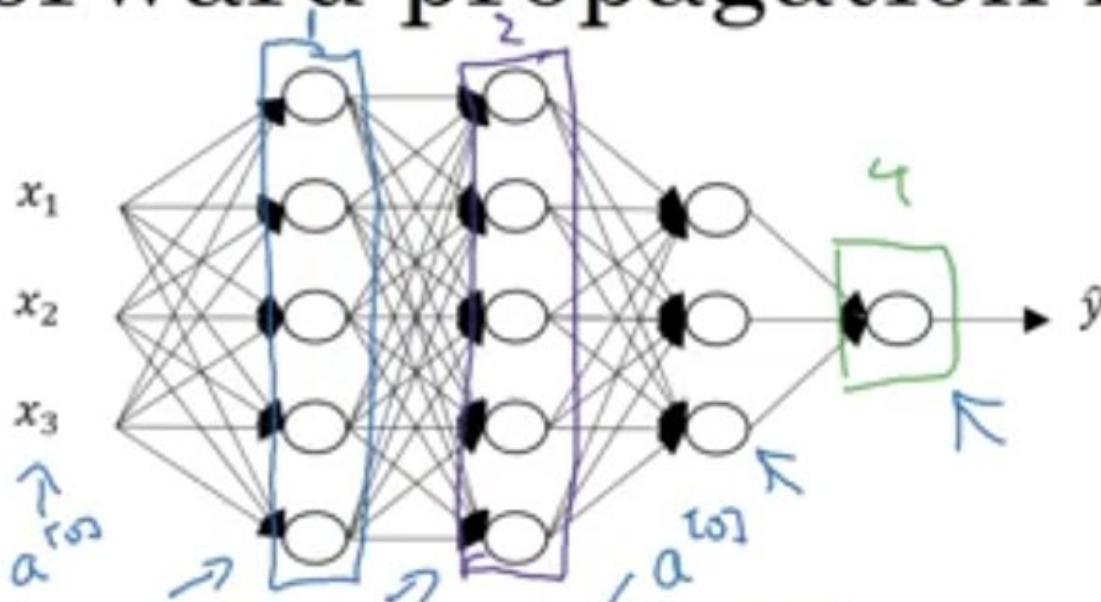


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Deep Neural Networks

Forward Propagation in a Deep Network

Forward propagation in a deep network



$$x : z^{[1]} = \underline{w^{[1]}} \underline{a^{[0]}} + \underline{b^{[1]}}$$

$$\underline{a^{[1]}} = g^{[1]}(z^{[1]})$$

$$\begin{aligned} z^{[2]} &= \underline{w^{[2]}} \underline{a^{[1]}} + \underline{b^{[2]}} \\ a^{[2]} &= g^{[2]}(z^{[2]}) \end{aligned}$$

$$z^{[4]} = \underline{w^{[4]}} \underline{a^{[3]}} + \underline{b^{[4]}}, \quad a^{[4]} = g^{[4]}(z^{[4]})$$

$A^{[0]} = X$

$$\rightarrow z^{[l]} = \underline{w^{[l]}} \underline{A^{[l-1]}} + \underline{b^{[l]}}$$

$$A^{[l]} = g^{[l]}(z^{[l]})$$

Verteind:

$$\rightarrow z^{[1]} = \underline{w^{[1]}} \cancel{\underline{A^{[0]}}} + \underline{b^{[1]}}$$

$$A^{[1]} = g^{[1]}(z^{[1]})$$

$$\rightarrow z^{[2]} = \underline{w^{[2]}} A^{[1]} + \underline{b^{[2]}}$$

$$\rightarrow A^{[2]} = g^{[2]}(z^{[2]})$$

$$\hat{Y} = g(z^{[4]}) = A^{[4]}$$

for $l=1..4$



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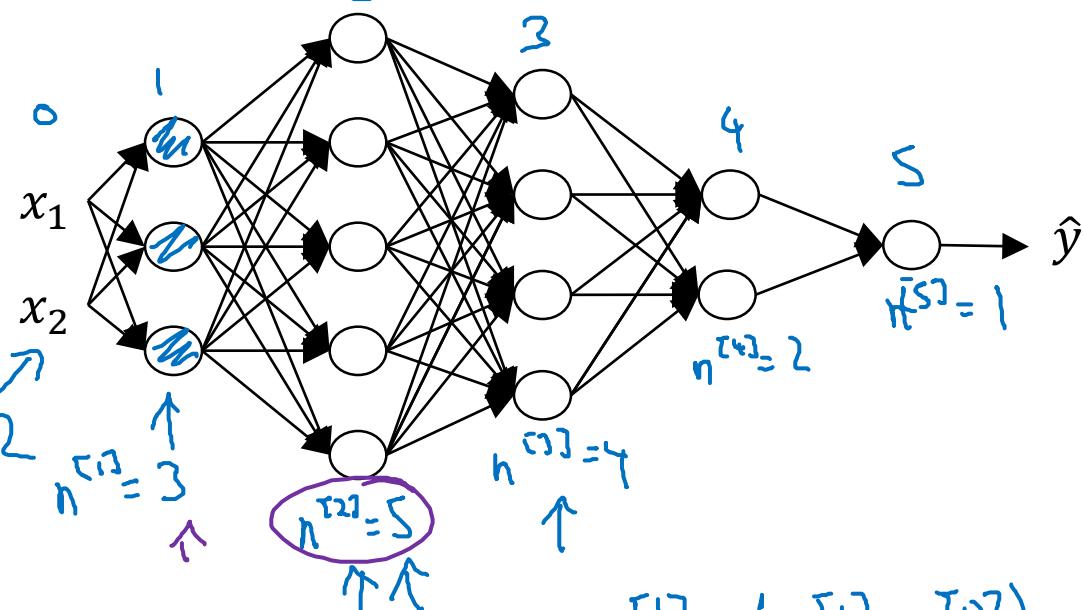
Deep Neural Networks

Getting your matrix dimensions right

Parameters $W^{[l]}$ and $b^{[l]}$

$$\downarrow z^{[0]} = g^{[0]}(a^{[0]}) \uparrow$$

$$\downarrow a^{[0]} \uparrow$$



$$\downarrow z^{[1]} = \boxed{W^{[1]} \cdot x} + \boxed{b^{[1]}} \uparrow$$

$$(3,1) \leftarrow (3,2) \quad (2,1)$$

$$(\underline{n^{[1]}}, 1) \quad (\underline{n^{[1]}}, \underline{n^{[2]}}) \quad (\underline{n^{[2]}}, 1)$$

$$[\cdot] = [\vdots \vdots] \quad [\vdots]$$

$L=5$

$$W^{[1]}: (n^{[1]}, n^{[0]})$$

$$W^{[2]}: (5, 3) \quad (n^{[2]}, n^{[1]})$$

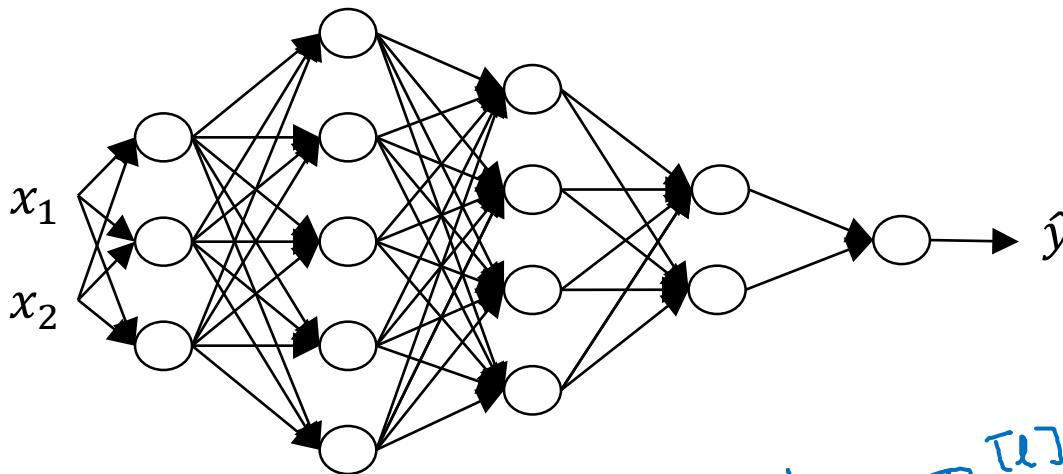
$$\begin{aligned} z^{[2]} &= \boxed{W^{[2]} \cdot a^{[1]}} + \boxed{b^{[2]}} \\ \rightarrow (5,1) &\quad (5,3) \quad (2,1) \quad (5,1) \\ &\quad (\underline{n^{[2]}}, 1) \end{aligned}$$

$$W^{[3]}: (4, 5)$$

$$W^{[4]}: (2, 4), \quad W^{[5]}: (1, 2)$$

$$\begin{cases} W^{[l]}: (n^{[l]}, n^{[l-1]}) \\ b^{[l]}: (n^{[l]}, 1) \\ \delta W^{[l]}: (n^{[l]}, n^{[l-1]}) \\ \delta b^{[l]}: (n^{[l]}, 1) \end{cases}$$

Vectorized implementation



$$z^{[l]} = w^{[l]} \cdot x + b^{[l]}$$

$$(n^{[l]}, 1) \quad (n^{[l]}, n^{[l+1]}) \quad (n^{[l]}, 1)$$

$$\left[z^{1} \ z^{[1](2)} \dots z^{[1](m)} \right]$$

$$\sum^{[l]} = w^{[l]} \cdot X + b^{[l]}$$

$$\overbrace{(n^{[l]}, m)}^{\uparrow} \quad \underbrace{(n^{[l]}, n^{[l+1]})}_{\uparrow} \quad \overbrace{(n^{[l]}, m)}^{\uparrow} \quad \overbrace{(n^{[l]}, m)}^{\uparrow}$$

$$z^{[l]}, a^{[l]} : (n^{[l]}, 1)$$

$$z^{[l]}, A^{[l]} : (n^{[l]}, m)$$

$$l=0 \quad A^{[0]} = X = (n^{[0]}, m)$$

$$dz^{[l]}, dA^{[l]} : (n^{[l]}, m)$$

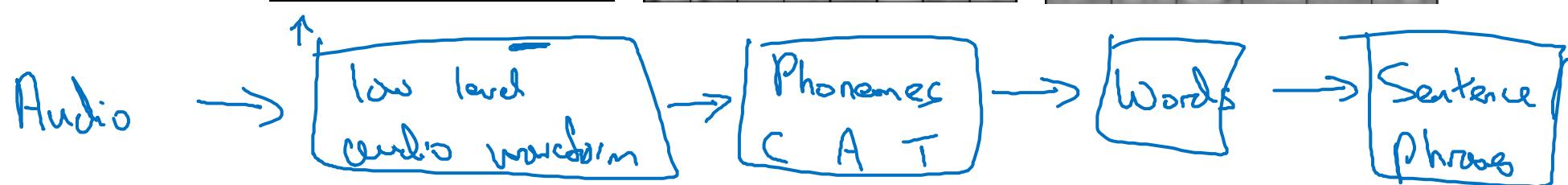
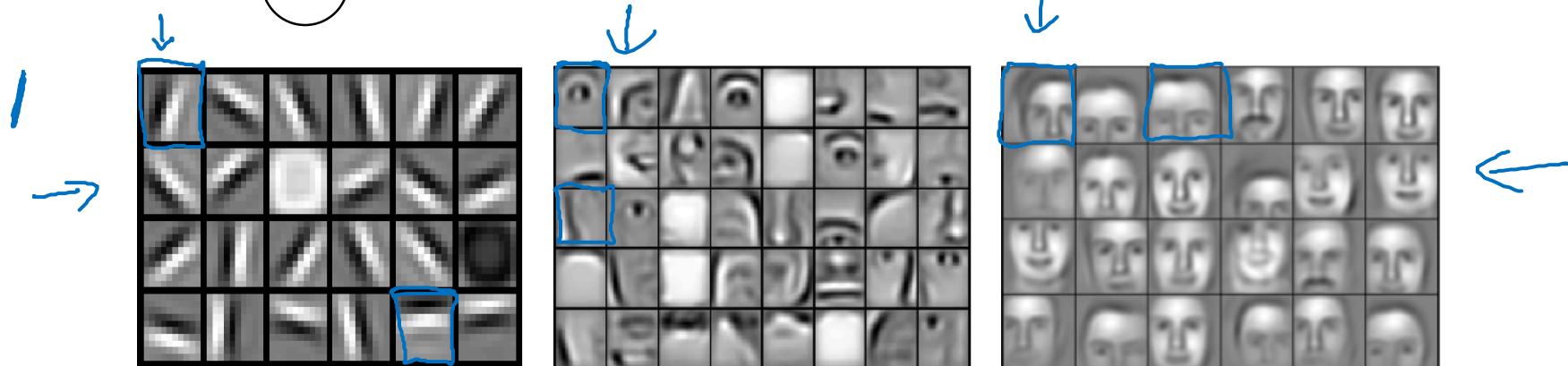
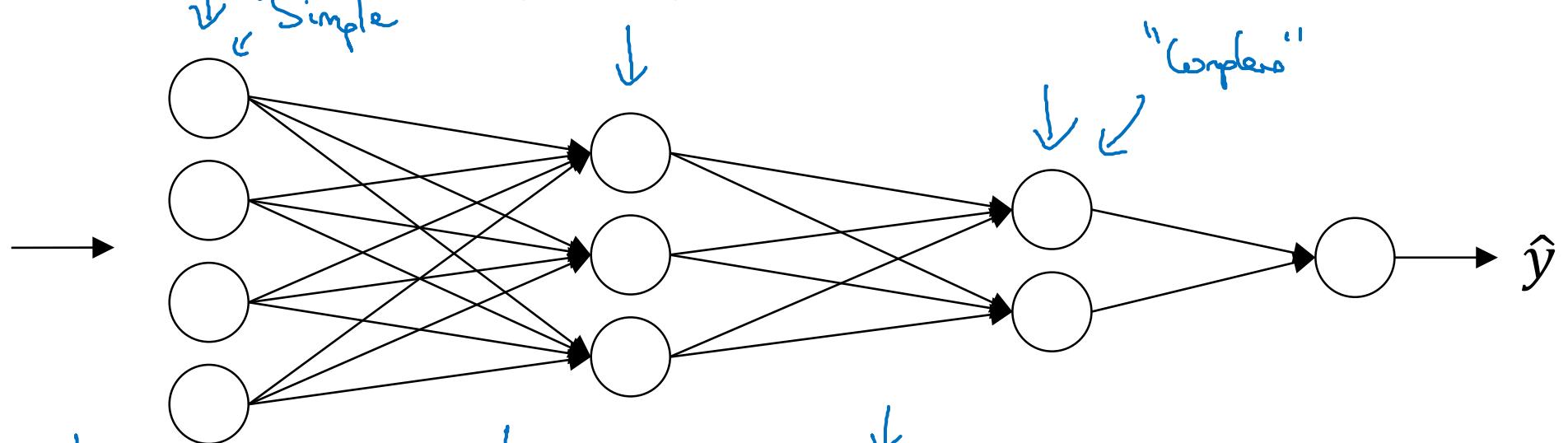
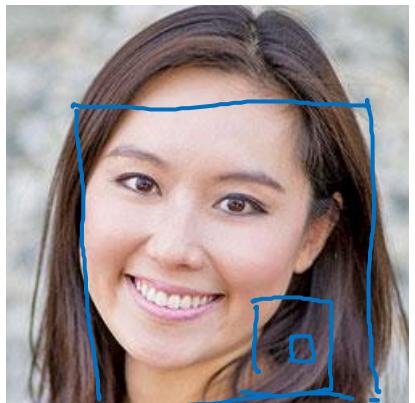


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Deep Neural Networks

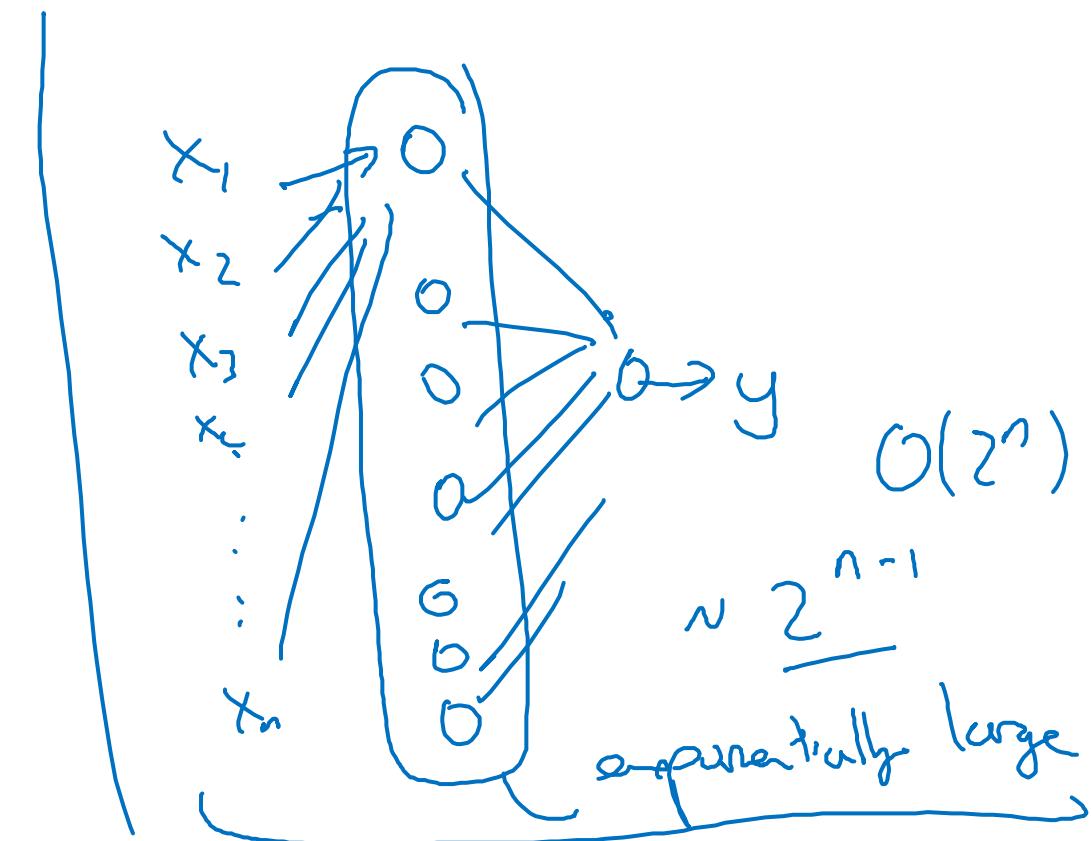
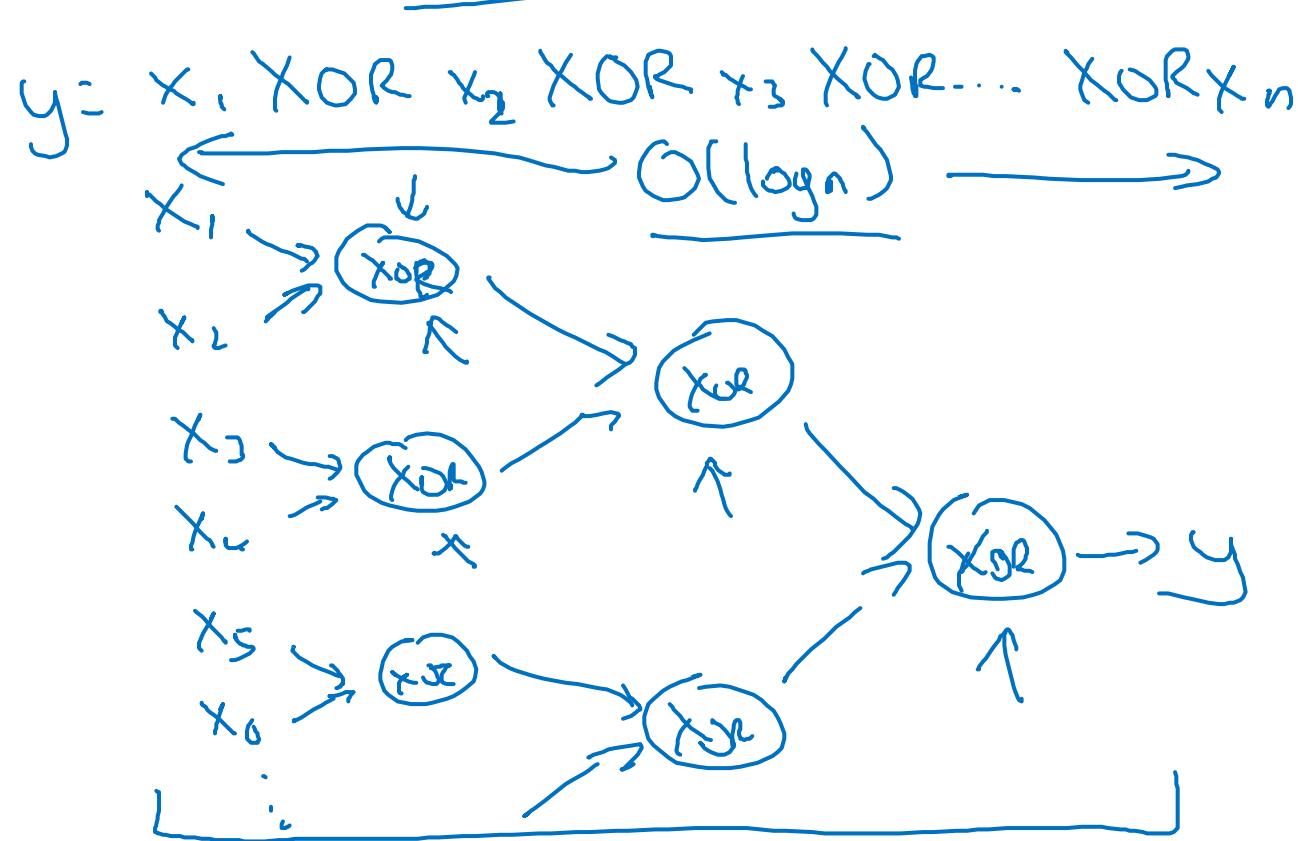
Why deep representations?

Intuition about deep representation



Circuit theory and deep learning

Informally: There are functions you can compute with a “small” L-layer deep neural network that shallow networks require exponentially more hidden units to compute.



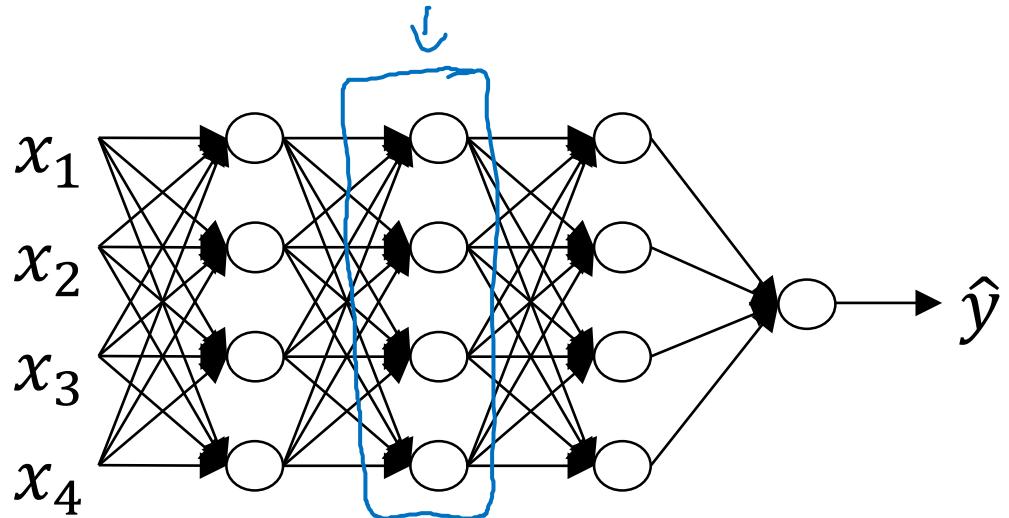


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Deep Neural Networks

Building blocks of
deep neural networks

Forward and backward functions

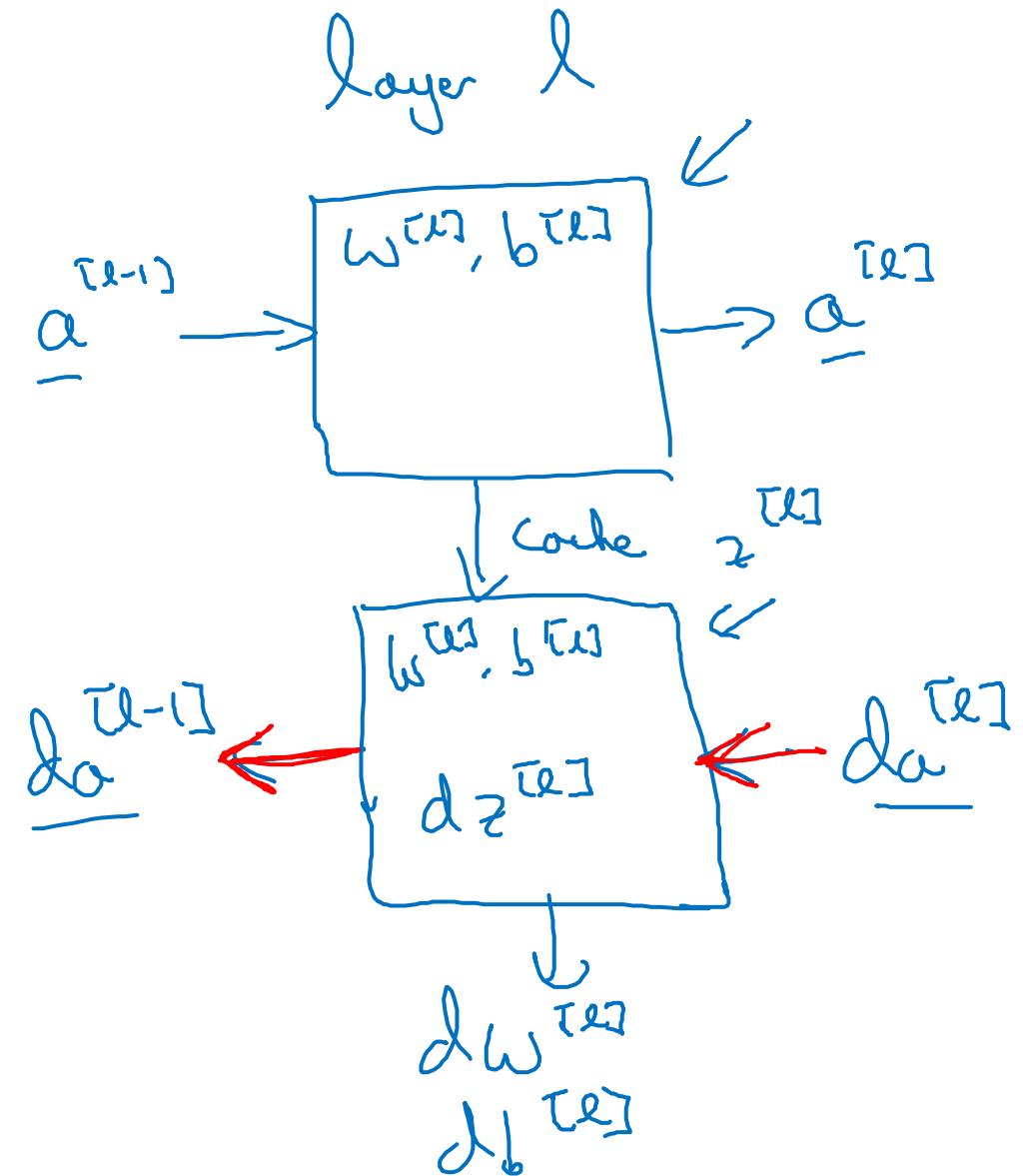


layer l: $w^{[l]}, b^{[l]}$

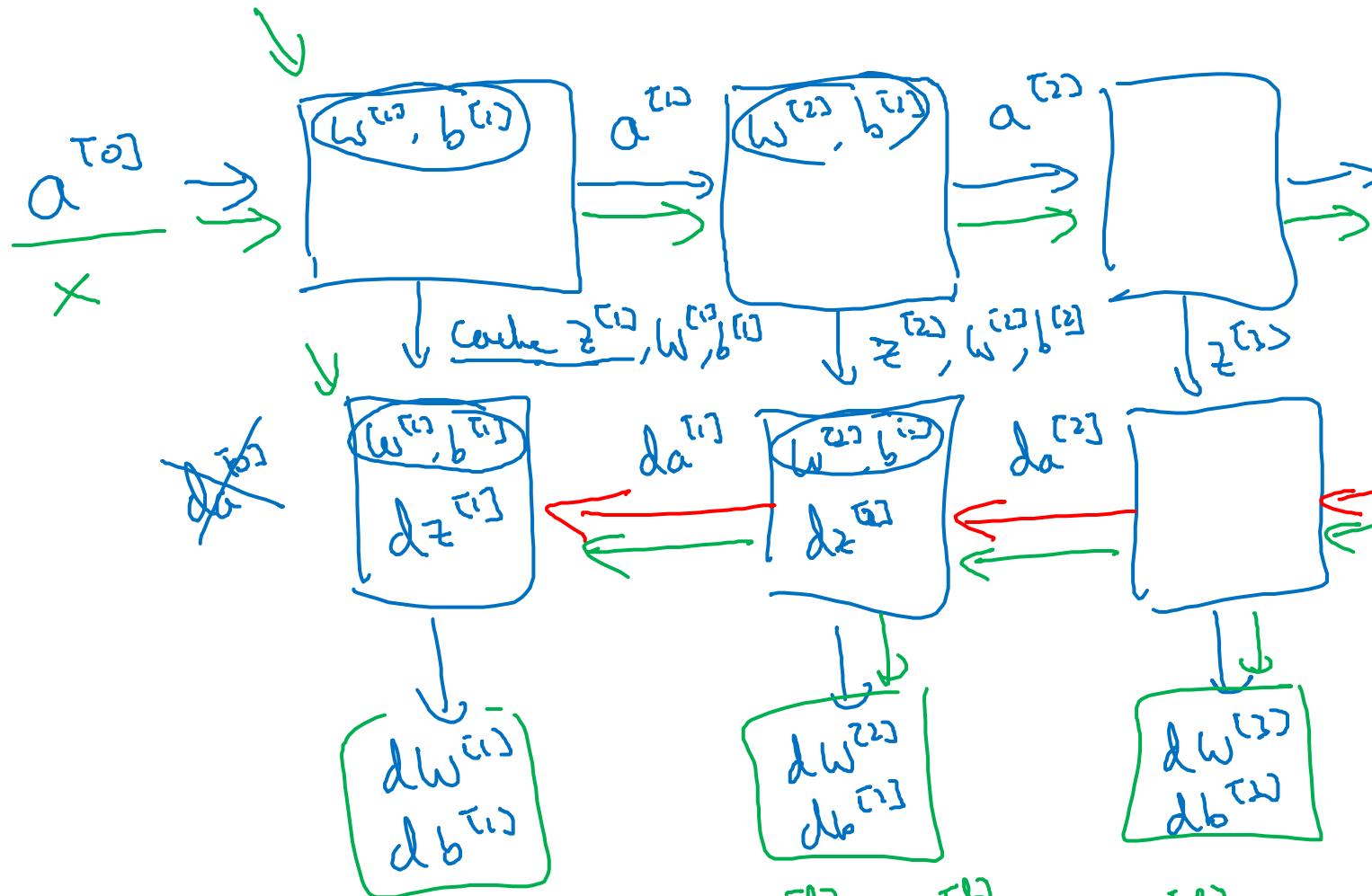
→ Forward: Input $a^{[l-1]}$, output $a^{[l]}$

$$\underline{z}^{[l]} = w^{[l]} \underline{a}^{[l-1]} + b^{[l]}$$
$$\underline{a}^{[l]} = g^{[l]}(\underline{z}^{[l]})$$

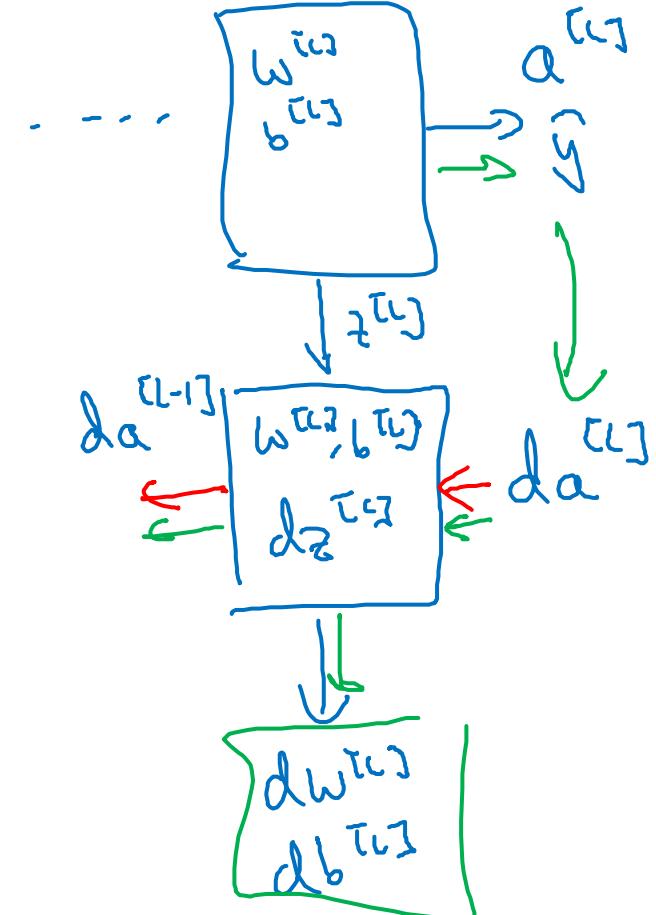
→ Backward: Input $da^{[l]}$, output $\frac{da}{dw^{[l]}}$, $\frac{da}{db^{[l]}}$



Forward and backward functions



$$w^{[l]} := w^{[l]} - \alpha dw^{[l]}$$
$$b^{[l]} := b^{[l]} - \alpha db^{[l]}$$





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Deep Neural Networks

Forward and backward propagation

Forward propagation for layer l

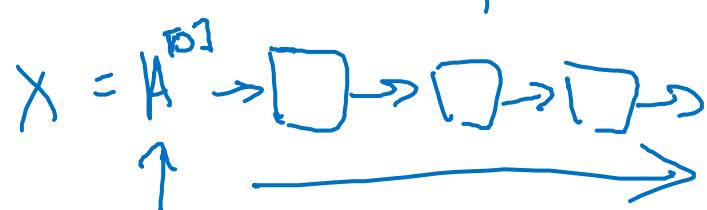
→ Input $a^{[l-1]} \leftarrow$

→ Output $a^{[l]}$, cache ($\underline{z^{[l]}}$)

$$z^{[l]} = w^{[l]} \cdot a^{[l-1]} + b^{[l]}$$

$$a^{[l]} = g^{[l]}(z^{[l]})$$

$$\begin{matrix} a^{[0]} \\ A^{[0]} \end{matrix}$$



Vertwijf:

$$z^{[l]} = w^{[l]} \cdot A^{[l-1]} + b^{[l]}$$

$$A^{[l]} = g^{[l]}(z^{[l]})$$

Backward propagation for layer l

→ Input $\underline{da}^{[l]}$

→ Output $\boxed{\underline{da}^{[l-1]}}$, $dW^{[l]}$, $db^{[l]}$

$$dz^{[l]} = \text{do}^{(l)} * g^{(l)}'(z^{[l]})$$

$$\underline{dW^{[l]}} = dz^{[l]} \cdot \underline{a^{[l-1]}}$$

$$\underline{db^{[l]}} = dz^{[l]}$$

$$\boxed{da^{[l-1]}} = W^{[l]T} \cdot dz^{[l]}$$

$$\underline{dz^{[l]}} = W^{[l+1]T} \cdot dz^{[l+1]} * g^{(l+1)}'(z^{[l]})$$

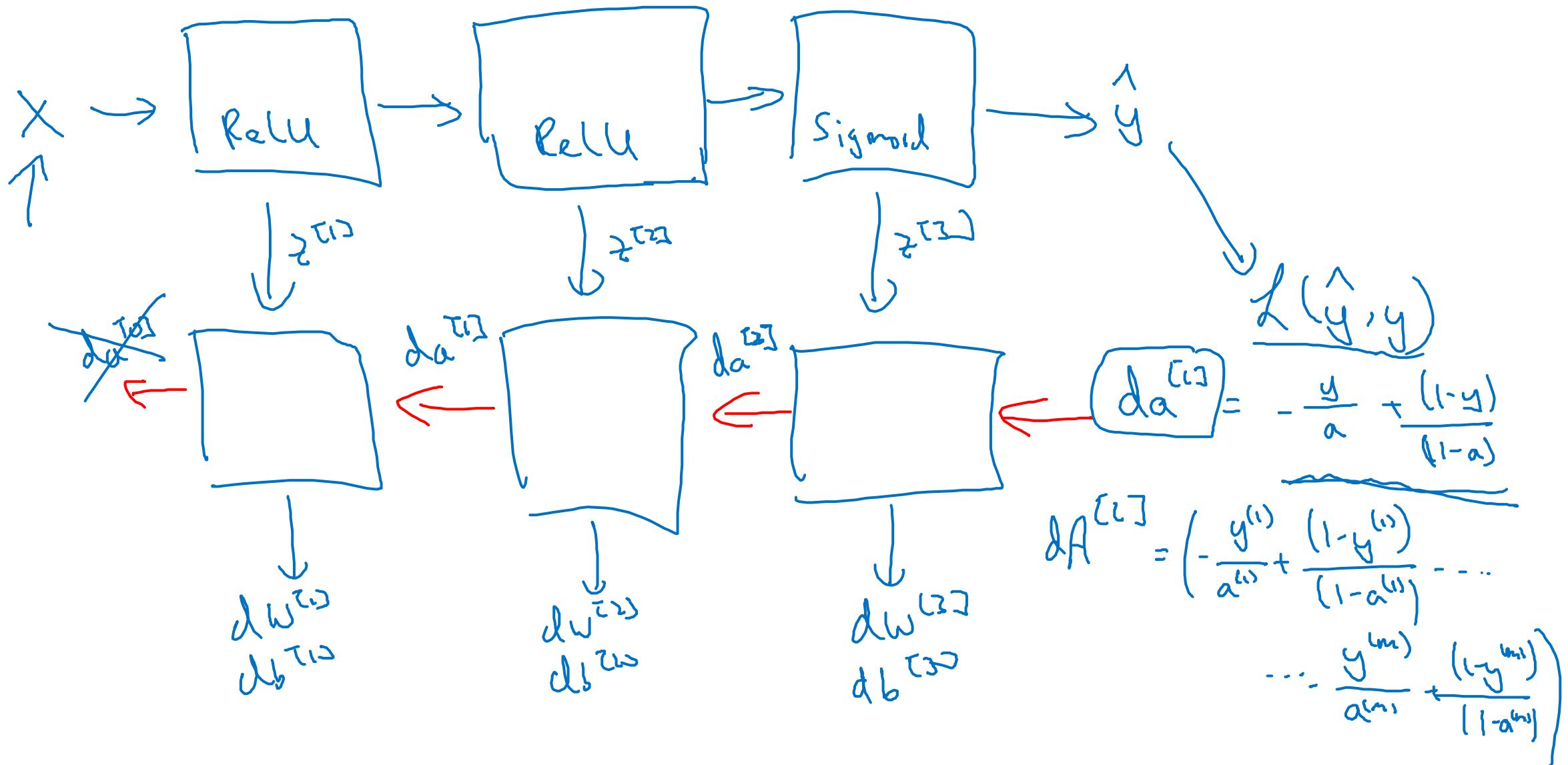
$$dz^{[l]} = \boxed{dA^{[l]}} * g^{(l)}'(z^{[l]})$$

$$\underline{dW^{[l]}} = \frac{1}{m} dz^{[l]} \cdot A^{[l-1]T}$$

$$\underline{db^{[l]}} = \frac{1}{m} \text{np.sum}(dz^{[l]}, \text{axis}=1, \text{keepdims=True})$$

$$\boxed{dA^{[l-1]}} = W^{[l]T} \cdot dz^{[l]}$$

Summary





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Deep Neural Networks

Forward and backward propagation

Forward propagation for layer l

- Input $a^{[l-1]} \leftarrow$
- Output $a^{[l]}$, cache ($\underline{z^{[l]}}$)

$$z^{[l]} = w^{[l]} \cdot a^{[l-1]} + b^{[l]}$$

$$a^{[l]} = g^{[l]}(z^{[l]})$$

$$\begin{matrix} a^{[0]} \\ A^{[0]} \end{matrix}$$

$$x = \underset{\uparrow}{A^{[0]}} \rightarrow \square \rightarrow \square \rightarrow \square \rightarrow \dots$$

Vertwijf:

$$z^{[l]} = w^{[l]} \cdot A^{[l-1]} + b^{[l]}$$

$$A^{[l]} = g^{[l]}(z^{[l]})$$

Backward propagation for layer l

→ Input $\underline{da}^{[l]}$

→ Output $\boxed{\underline{da}^{[l-1]}}$, $\underline{dW}^{[l]}$, $\underline{db}^{[l]}$

$$dz^{[l]} = \text{do}^{(l)} * g^{(l)}(z^{(l)})$$

$$\underline{dW}^{(l)} = dz^{(l)} \cdot \underline{a}^{(l-1)}$$

$$\underline{db}^{(l)} = dz^{(l)}$$

$$\boxed{da^{(l-1)}} = W^{(l)T} \cdot dz^{(l)}$$

$$\underline{dz}^{(l)} = W^{(l+1)T} \cdot dz^{(l+1)} * g^{(l+1)}(z^{(l)})$$

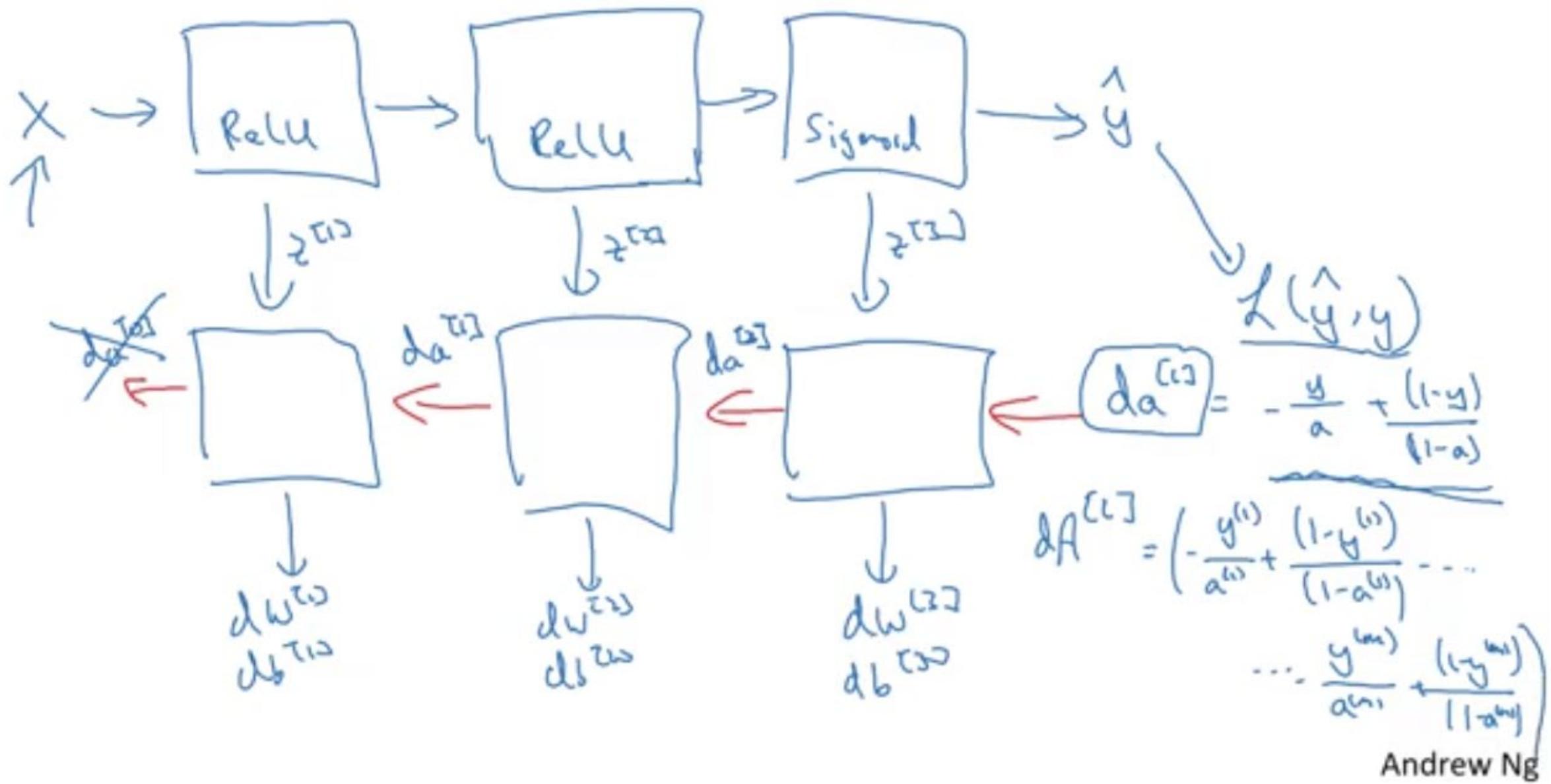
$$dz^{(l)} = \boxed{dA^{(l)}} * g^{(l)}(z^{(l)})$$

$$\underline{dW}^{(l)} = \frac{1}{m} dz^{(l)} \cdot A^{(l-1)T}$$

$$\underline{db}^{(l)} = \frac{1}{m} \text{np.sum}(dz^{(l)}, \text{axis}=1, \text{keepdims=True})$$

$$\boxed{dA^{(l-1)}} = W^{(l)T} \cdot dz^{(l)}$$

Summary





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Deep Neural Networks

Parameters vs Hyperparameters

What are hyperparameters?

Parameters: $W^{[1]}, b^{[1]}, W^{[2]}, b^{[2]}, W^{[3]}, b^{[3]} \dots$

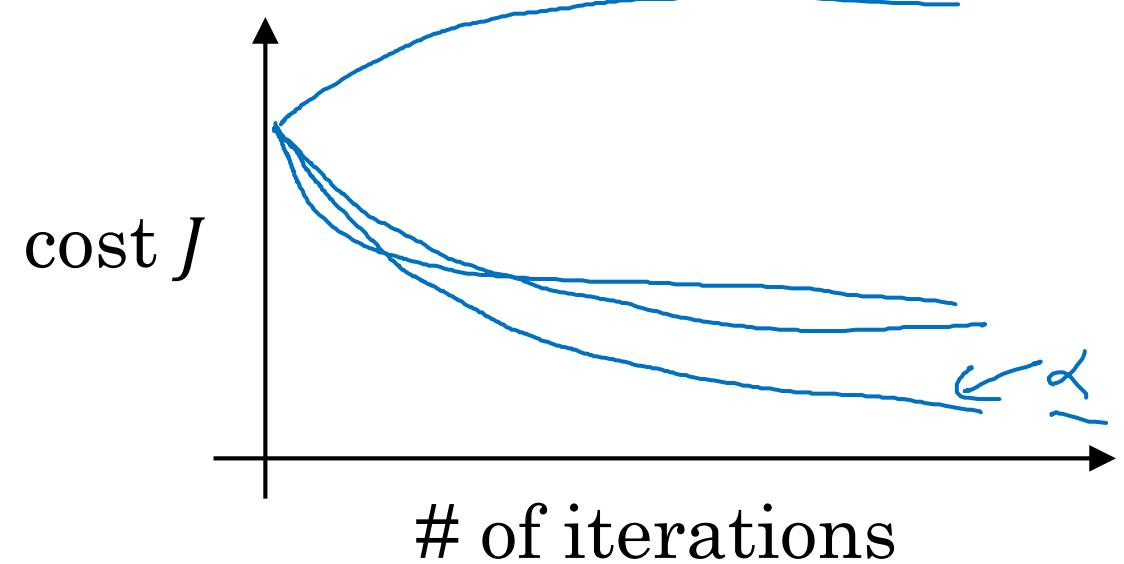
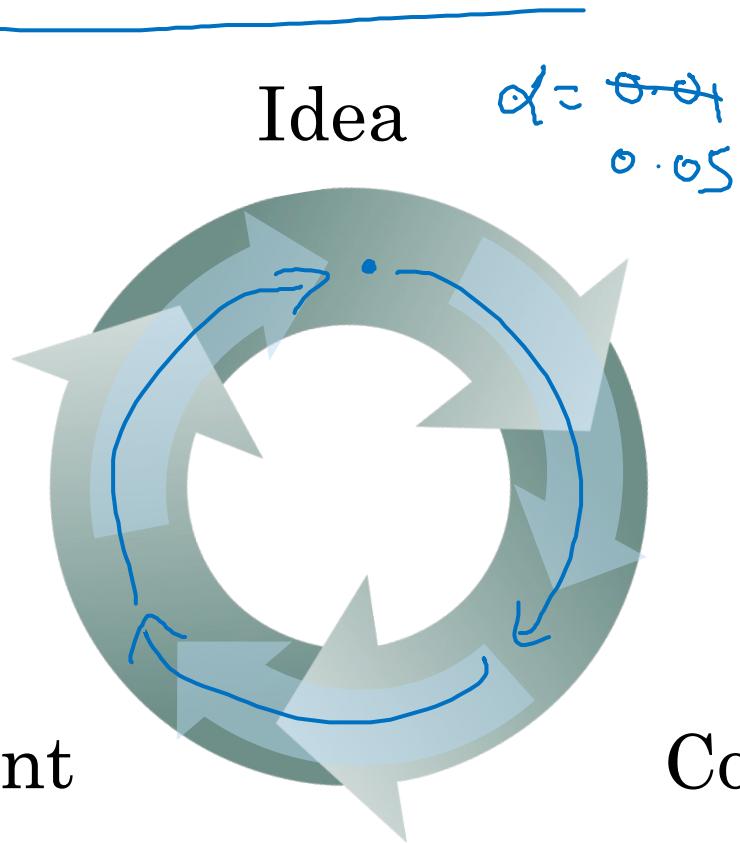
Hyperparameters:

- learning rate $\frac{\alpha}{\text{#iterations}}$
- #hidden layers L
- #hidden units $n^{[1]}, n^{[2]}, \dots$
- choice of activation function

Curly brace groups the last three items.

Later: Momentum, minibatch size, regularizations, ...

Applied deep learning is a very empirical process



Vision, Speech, NLP, Ad, Search, Reinforcement.



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Deep Neural Networks

What does this
have to do with
the brain?

Forward and backward propagation

$$Z^{[1]} = W^{[1]}X + b^{[1]}$$

$$A^{[1]} = g^{[1]}(Z^{[1]})$$

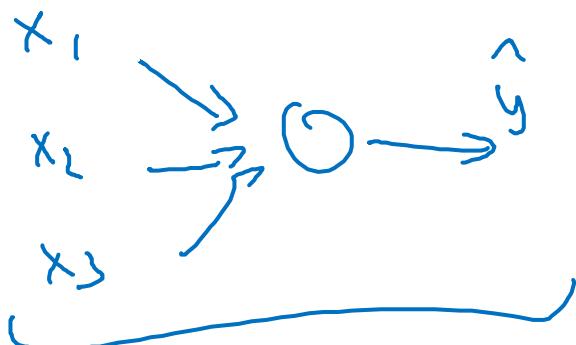
$$Z^{[2]} = W^{[2]}A^{[1]} + b^{[2]}$$

$$A^{[2]} = g^{[2]}(Z^{[2]})$$

:

$$A^{[L]} = g^{[L]}(Z^{[L]}) = \hat{Y}$$

"It's like the brain"



$$dZ^{[L]} = A^{[L]} - Y$$

$$dW^{[L]} = \frac{1}{m} dZ^{[L]} A^{[L]T}$$

$$db^{[L]} = \frac{1}{m} np.\text{sum}(dZ^{[L]}, axis = 1, keepdims = True)$$

$$dZ^{[L-1]} = dW^{[L]T} dZ^{[L]} g'^{[L]}(Z^{[L-1]})$$

:

$$dZ^{[1]} = dW^{[L]T} dZ^{[2]} g'^{[1]}(Z^{[1]})$$

$$dW^{[1]} = \frac{1}{m} dZ^{[1]} A^{[1]T}$$

$$db^{[1]} = \frac{1}{m} np.\text{sum}(dZ^{[1]}, axis = 1, keepdims = True)$$

