

# Instrumental Variables

HETEROGENEOUS EFFECTS

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MIXTAPE  
SESSIONS



# Roadmap

The LATE Theorem

Potential Outcome Setup

Theorem and Extensions

Characterizing Compliers

Outcomes

Covariates

Marginal Treatment Effects

Continuous Instruments

Discrete Instruments

# From Constant to Heterogeneous Effects

So far we have implicitly been considering models w/ constant effects

- $Y_i = \alpha + \beta D_i + \varepsilon_i$  implies  $\partial Y / \partial D = \beta$  for all observations  $i$
- What if this model is *misspecified*? I.e. what if  $Y_i = \alpha + \beta_i D_i + \varepsilon_i$ ?

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- Recall charter lottery vs. takeover IVs: very different setups!

Formalized in the (Nobel-winning!) Imbens and Angrist '94 LATE thm.

- Using a general potential outcomes framework...

## Potential Outcome Setup

Let  $Y_i(0)$  and  $Y_i(1)$  denote individual  $i$ 's potential outcomes given a binary treatment  $D_i \in \{0, 1\}$

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Imbens-Angrist' insight: we can also do this for an IV first stage:

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Under what assumptions can we causally interpret `ivreg2 Y (D=Z)`?

## Imbens and Angrist (1994) Assumptions

1. As-good-as-random assignment:  $Z_i \perp (Y_i(0), Y_i(1), D_i(0), D_i(1))$ 
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4. Monotonicity:  $D_i(1) \geq D_i(0)$  for all  $i$  (i.e., almost-surely)
  - The instrument can only shift the treatment in one direction

## Local Average Treatment Effect (LATE) Identification

Imbens and Angrist showed that under these assumptions:

$$\beta^{IV} = E[Y_i(1) - Y_i(0) \mid D_i(1) > D_i(0)]$$

The IV estimand  $\beta^{IV}$  identifies a LATE: the average treatment effect  $Y_i(1) - Y_i(0)$  among *compliers*: those with  $1 = D_i(1) > D_i(0) = 0$

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- Monotonicity rules out the presence of *defiers*, with  $D_i(1) < D_i(0)$

⇒ Different (valid) IVs can identify different LATEs!

## What Does This Mean Practically?

Two conceptually distinct considerations: *internal* vs. *external* validity

- Context of an IV, and who the compliers likely are, may matter
- Usual “overidentification” test logic fails: two valid IVs may have different estimands! (see Kitagawa (2015) for alternative tests)

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In addition to as-good-as-random assignment / exclusion, we may need to worry about monotonicity when we do IV

- Sensible in earlier lottery / natural experiment / panel examples
- Maybe questionable in judge IVs (coming soon!)

## Extensions

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- Angrist/Imbens '95: multivalued (ordered)  $D_i$ , saturated covariates
- Angrist/Graddy/Imbens '00: continuous  $D_i$  (supply/demand setup)
- Heckman/Vytlicil '05: continuous  $Z_i$  (more on this soon)
- Multiple unordered treatments is harder (e.g. Behaghel et al. 2013)

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Recent discussions highlight importance of including flexible controls

- E.g. Sloczyński '20, Borusyak and Hull '21, Mogstad et al. '22
- If monotonicity only holds conditional on  $X_i$ , may need  $Z_i$ -by- $X_i$  interactions (which may lead to many-weak problems...)

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# Who Are the Compliers?

Characterizing the  $i$  that make up the IV estimand ( $w/D_i(1) > D_i(0)$ ) is key for understanding internal vs. external validity

- Unfortunately we can't identify compliers directly: we only observe  $D_i(1)$  (when  $Z_i = 1$ ) or  $D_i(0)$  (when  $Z_i = 0$ ), not both together!

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It turns out we can still characterize compliers by their outcomes ( $Y_i(0)$  and  $Y_i(1)$ ) and other observables  $X_i$

- Comparing  $E[X_i | D_i(1) > D_i(0)]$  to  $E[X_i]$  can maybe shed light on how  $E[Y_i(1) - Y_i(0) | D_i(1) > D_i(0)]$  compares to  $E[Y_i(1) - Y_i(0)]$

## Outcomes

Computing  $E[Y_i(1) \mid D_i(1) > D_i(0)]$  is surprisingly easy in the IA setup

- Define  $W_i = Y_i D_i$ , and note that this new outcome has potentials with respect to  $D_i$  of  $W_i(1) = Y_i(1)$  and  $W_i(0) = 0$

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$$E[W_i(1) - W_i(0) | D_i(1) > D_i(0)] = E[Y_i(1) | D_i(1) > D_i(0)]$$

Similar logic shows that IV with  $Y_i(1 - D_i)$  as the outcome and  $1 - D_i$  as the treatment identifies  $E[Y_i(1) | D_i(1) > D_i(0)]$

- So easy to do! And extends to covariates / multiple IVs...

# Characterizing Charter Lottery Complier $Y_i(0)$ 's

TABLE 6—POTENTIAL-OUTCOME GAPS IN URBAN AND NONURBAN AREAS

Subject	Urban				Nonurban			
	Treatment effect (1)	$E_u[Y_0 D=0]$ (2)	$\lambda_0^u$ (3)	$\lambda_1^u$ (4)	Treatment effect (5)	$E_n[Y_0 D=0]$ (6)	$\lambda_0^n$ (7)	$\lambda_1^n$ (8)
<i>Panel A. Middle school</i>								
Math	0.483*** (0.074)	-0.399*** (0.011)	0.077 (0.049)	0.560*** (0.054)	-0.177** (0.074)	0.236*** (0.007)	0.010 (0.061)	-0.143*** (0.042)
N	4,858				2,239			
ELA	0.188*** (0.064)	-0.422*** (0.012)	0.118** (0.054)	0.306*** (0.049)	-0.148*** (0.048)	0.260*** (0.007)	0.102** (0.050)	-0.086*** (0.030)
N	4,551				2,323			
<i>Panel B. High school</i>								
Math	0.557*** (0.164)	-0.371*** (0.021)	0.074 (0.099)	0.602*** (0.151)	0.065 (0.146)	0.241*** (0.008)	0.207 (0.145)	0.271*** (0.041)
N	3,743				432			
ELA	0.417*** (0.140)	-0.369*** (0.018)	-0.004 (0.096)	0.410*** (0.119)	0.064 (0.151)	0.250*** (0.008)	0.237 (0.152)	0.301*** (0.051)
N	4,858				435			

Source: Angrist, Pathak, and Walters (2013)

## Covariates

For covariates  $X_i$  (not affected by  $D_i$ ) we can follow a similar trick:

- Either IV'ing  $X_i D_i$  on  $D_i$  or IV'ing  $X_i(1 - D_i)$  on  $1 - D_i$  identifies complier characteristics  $E[X_i | D_i(1) > D_i(0)]$
- Shouldn't be very different (implicit balance test); can be averaged

# Covariates

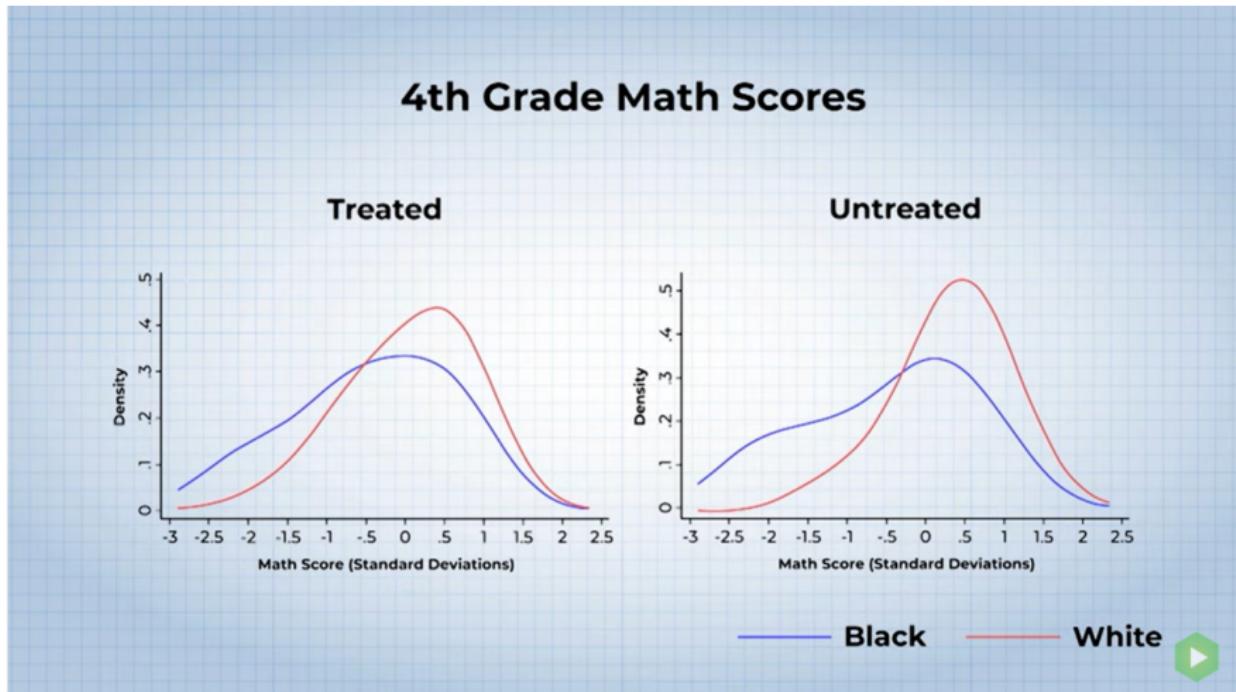
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Abadie (2003) gives a slicker (but a bit more involved) approach to estimating any function of  $(Y_i(0), Y_i(1), X_i)$  for compliers

- Involves weighting by  $\kappa = 1 - \frac{D_i(1-Z_i)}{1-E[Z_i|W_i]} - \frac{(1-D_i)Z_i}{E[Z_i|W_i]}$  where  $W_i$  are any necessary “design controls” (e.g. lottery risk sets)
- You can do some really cool stuff with this!

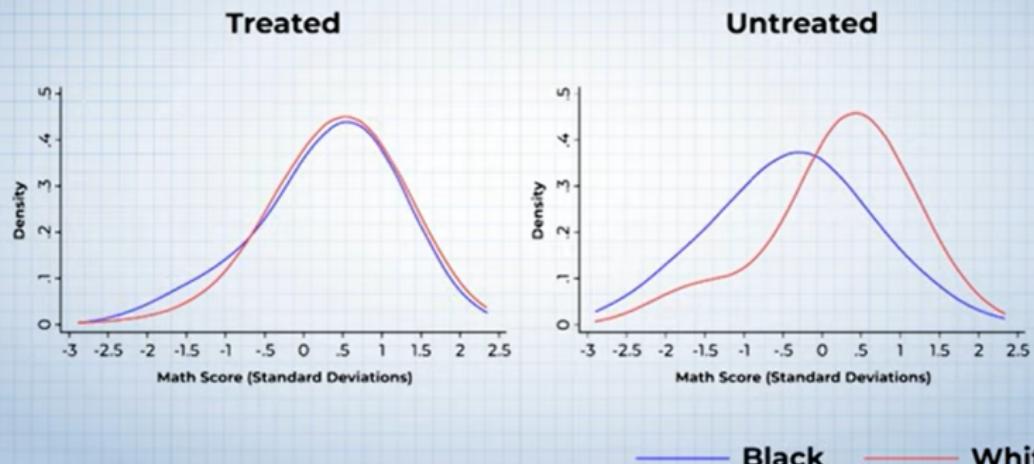
# Black/White Potential Outcomes, Pre-Charter



Source: Josh Angrist Nobel Lecture (2021)

# Black/White Potential Outcomes, Post-Charter

## 8th Grade Math Scores



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## Heckman and Vytlacil (2005, 2007, 2010, 2013...)

If we have a  $Z_i$  that varies continuously, we might learn more about how treatment effects vary with compliance

- Different types of  $i$  may “respond” at different margins of  $Z_i$

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Heckman-Vytlacil write  $D_i = \mathbf{1}[p(Z_i) \geq U_i]$ , with  $U_i \mid Z_i \sim U(0, 1)$

- $p(z) = Pr(D_i = 1 \mid Z_i = z)$  is the treatment propensity score
- $U_i$  indexes treatment “resistance” (i.e. types of compliers); Vytlacil (2002) shows model is equivalent to IA’s monotonicity w/ binary  $Z_i$

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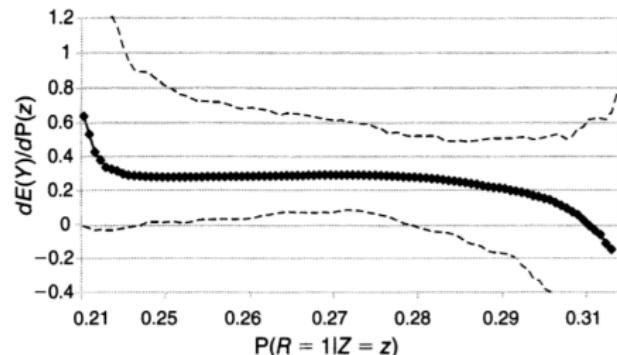
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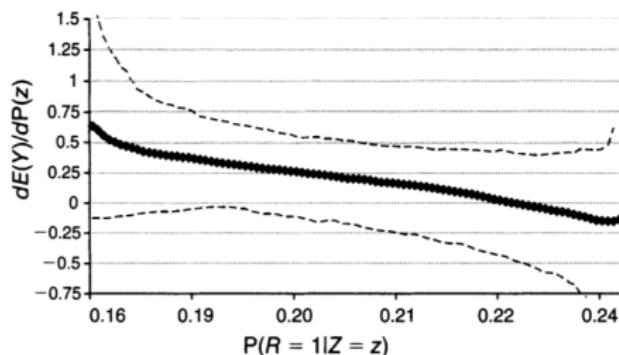
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Now we can consider how  $Y_i(1) - Y_i(0)$  varies continuously with  $U_i$  ...

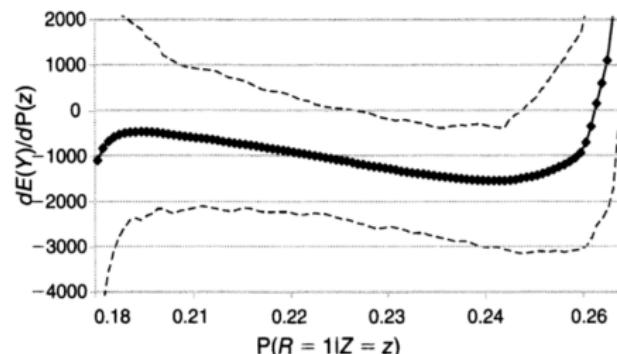
# Doyle (2007): MTEs of Foster Care Removal



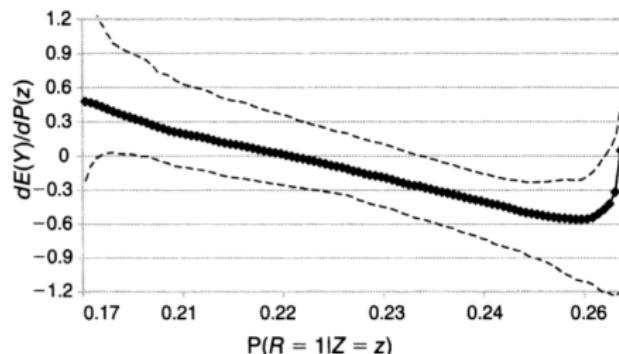
A. DELINQUENCY MTE



B. TEEN MOTHERHOOD MTE



C. EARNINGS MTE



D. EMPLOYMENT MTE

# Local Instrumental Variables

Heckman (2000) shows that MTEs are identified by “local IV”:

$$E[Y_i(1) - Y_i(0) \mid U_i = p] = \frac{\partial E[Y_i \mid p(Z_i) = p]}{\partial p}$$

under natural extensions of Imbens and Angrist (1994)

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- Suggests we flexibly estimate  $p(z) = Pr(D_i = 1 \mid Z_i = z)$ ,  
 $E[Y_i \mid p(Z_i)]$ , and then take the derivative of the latter
- In practice this is often done parametrically, and with controls

## What if We Don't Have Continuous Instruments?

A fascinating recent literature considers intermediate cases of Imbens-Angrist and Heckman-Vytlačil:

- Discrete (binary/multivalued)  $Z_i$ , with parametric/shape restrictions to trace out (or maybe bound) the MTE curve
- Effectively using a model to “extrapolate” from local variation, maybe to identify more policy-relevant parameters

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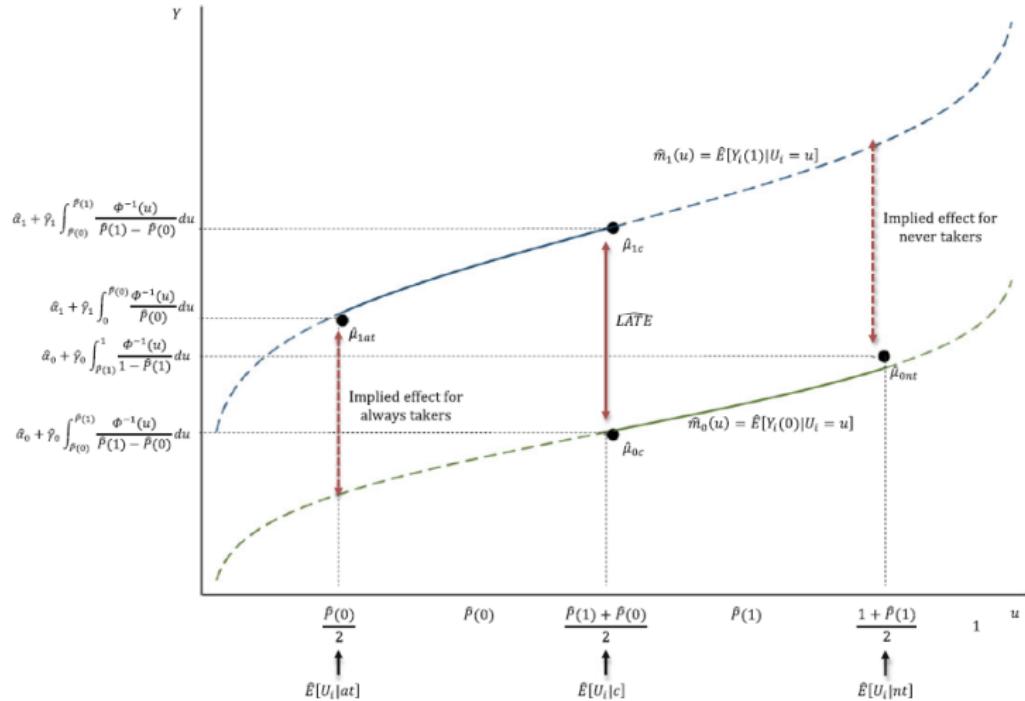
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Some examples: Brinch et al. (2017), Mogstad et al. (2018), Kline and Walters (2019), Hull (2020), Arnold et al. (2021), Kowalski (2022)...

- Lots more to do here (especially on the practical side)

# How Parametric “Heckit” Models Extrapolate LATEs



“Heckit” model:  $E[Y_i(d)|U_i] = a_d + \gamma_d \phi^{-1}(U_i)$