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Abstract. TODO

1 Introduction

2 A Ternary Semantics for SAND Attack Trees

References

1. Ravi Jhawar, Barbara Kordy, Sjouke Mauw, Saša Radomirović, and Rolando Trujillo-Rasua. Attack trees with sequential conjunction. In Hannes Federrath and Dieter Gollmann, editors, *ICT Systems Security and Privacy Protection*, volume 455 of *IFIP Advances in Information and Communication Technology*, pages 339–353. Springer International Publishing, 2015.

Appendix

.1 SSG Semantics

In this appendix I show that the category of source-sink graphs defined by Jhawar et al. [1] is symmetric monoidal. First, recall the definition of source-sink graphs and their homomorphisms.

Definition 1. A *source-sink graph* over B is a tuple $G = (V, E, s, z)$, where V is the set of vertices, E is a multiset of labeled edges with support $E^* \subseteq V \times B \times V$, $s \in V$ is the unique start, $z \in V$ is the unique sink, and $s \neq z$.

Suppose $G = (V, E, s, z)$ and $G' = (V', E', s', z')$. Then a **morphism between source-sink graphs**, $f : G \rightarrow G'$, is a graph homomorphism such that $f(s) = s'$ and $f(z) = z'$.

Suppose $G = (V, E, s, z)$ and $G' = (V', E', s', z')$ are two source-sink graphs. Then given the above definition it is possible to define sequential and non-communicating parallel composition of source-sink graphs where I denote disjoint union of sets by $+$ (p 7. [1]):

Sequential Composition :

$$G \triangleright G' = ((V \setminus \{z\}) + V', E^{[s'/z]} + E', s, z')$$

Parallel Composition :

$$G \odot G' = ((V \setminus \{s, z\}) + V', E^{[s'/s, z'/z]} + E', s', z')$$

It is easy to see that we can define a category of source-sink graphs and their homomorphisms. Furthermore, it is a symmetric monoidal category where parallel composition is the symmetric tensor product. It is well-known that any category with co-products is symmetric monoidal where the co-product is the tensor product.

I show here that parallel composition defines a co-product. This requires the definition of the following morphisms:

$$\begin{aligned} \text{inj}_1 &: G_1 \rightarrow G_1 \odot G_2 \\ \text{inj}_2 &: G_2 \rightarrow G_1 \odot G_2 \\ \langle f, g \rangle &: G_1 \odot G_2 \rightarrow G \end{aligned}$$

In the above $f : G_1 \rightarrow G$ and $g : G_2 \rightarrow G$ are two source-sink graph homomorphisms. Furthermore, the following diagram must commute:

$$\begin{array}{ccccc} & & G & & \\ & f \swarrow & \uparrow \langle f, g \rangle & \searrow g & \\ G_1 & \xrightarrow{\text{inj}_1} & G_1 \odot G_2 & \xleftarrow{\text{inj}_2} & G_2 \end{array}$$

Suppose $G_1 = (V_1, E_1, s_1, z_1)$, $G_2 = (V_2, E_2, s_2, z_2)$, and $G = (V, E, s, z)$ are source-sink graphs, and $f : G_1 \rightarrow G$ and $g : G_2 \rightarrow G$ are source-sink graph morphisms – note that $f(s_1) = g(s_2) = s$ and $f(z_1) = g(z_2) = z$ by definition. Then we define the required co-product morphisms as follows:

$$\begin{aligned} \text{inj}_1 &: V_1 \rightarrow (V_1 \setminus \{s_1, z_1\}) + V_2 \\ \text{inj}_1(s_1) &= s_2 \\ \text{inj}_1(z_1) &= z_2 \\ \text{inj}_1(v) &= v, \text{ otherwise} \end{aligned}$$

$$\begin{aligned} \text{inj}_2 &: V_2 \rightarrow (V_1 \setminus \{s_1, z_1\}) + V_2 \\ \text{inj}_2(v) &= v \end{aligned}$$

$$\begin{aligned} \langle f, g \rangle &: (V_1 \setminus \{s_1, z_1\}) + V_2 \rightarrow V \\ \langle f, g \rangle(v) &= f(v), \text{ where } v \in V_1 \\ \langle f, g \rangle(v) &= g(v), \text{ where } v \in V_2 \end{aligned}$$

It is easy to see that these define graph homomorphisms. All that is left to show is that the diagram from above commutes:

$$\begin{aligned}
(\text{inj}_1; \langle f, g \rangle)(s_1) &= \langle f, g \rangle(\text{inj}_1(s_1)) \\
&= g(s_2) \\
&= s \\
&= f(s_1)
\end{aligned}$$

$$\begin{aligned}
(\text{inj}_1; \langle f, g \rangle)(z_1) &= \langle f, g \rangle(\text{inj}_1(z_1)) \\
&= g(z_2) \\
&= z \\
&= f(z_1)
\end{aligned}$$

Now for any $v \in V_1$ we have the following:

$$\begin{aligned}
(\text{inj}_1; \langle f, g \rangle)(v) &= \langle f, g \rangle(\text{inj}_1(v)) \\
&= f(v)
\end{aligned}$$

The equation for inj_2 is trivial, because inj_2 is the identity.