Coverage for **exp_pro_gateway.py** : 73%



197 statements

| 148 run | | 4

49 missing

0 excluded

11 partial

```
1 #!/usr/bin/env python3
2
   0.000
3
 4 exp_pro_gateway.py
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6
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8
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    Foundation, Inc., 51 Franklin St, Fifth Floor, Boston, MA 02110-1301 USA
19
20
21
   import argparse
23
  import signal
   import sys
25 import threading
   import time
27
   import explorerhat as eh
29
  from python_banyan.gateway_base import GatewayBase
30
31
32 # noinspection PyMethodMayBeStatic, PyMethodMayBeStatic, SpellCheckingInspection, DuplicatedCode
33 class ExpProGateway(GatewayBase, threading.Thread):
```

```
0.000
34
35
       A OneGPIO type gateway for the Pimoroni Explorer Hat Pro
36
37
38
       # noinspection PyDefaultArgument, PyRedundantParentheses
39
       def __init__(self, *subscriber_list, **kwargs):
40
            :param subscriber_list: a tuple or list of topics to be subscribed to
41
            :param kwargs: contains the following parameters:
42
43
44
           see the argparse section at the bottom of this file.
45
46
           # initialize the parent
47
48
           super(ExpProGateway, self).__init__(
                subscriber_list=subscriber_list,
49
50
               back_plane_ip_address=kwargs[
                    'back_plane_ip_address'],
51
52
                subscriber_port=kwargs[
                    'subscriber_port'],
53
54
                publisher_port=kwargs[
55
                    'publisher_port'],
56
                process_name=kwargs[
                    'process_name'],
57
                board_type=kwargs['board_type'],
58
59
60
           # get sensitivity levels for the analog inputs
61
           sensitivity = kwargs['threshold']
62
           # format is different if provided as default values vs.
63
           # user entered values. format appropriately.
64
           if isinstance(sensitivity, list):
                                                                                                                        65 + 67
65
66
               # convert string values to floats
                sensitivity = [float(i) for i in sensitivity]
67
68
           else:
                sensitivity = [float(i) for i in sensitivity.split(',')]
69
70
71
           if len(sensitivity) != 4:
                                                                                                                         71 \rightarrow 72
72
                raise RuntimeError('You must specify 4 thresholds')
73
```

```
74
            # the explorer analog input code sends data
 75
            # too fast to process properly, so using
            # the lock solves this issue.
 76
 77
 78
            self.the_lock = threading.RLock()
 79
 80
            # get the report topic passed in
            self.report_topic = (kwargs['report_topic'])
 81
 82
            # A map of gpio pins to input channel numbers
 83
 84
            self.gpio_input_pins = {23: 1, 22: 2, 24: 3, 25: 4}
 85
 86
            # A map of digital output and led object to gpio pins
 87
            self.digital_output_pins = {4: eh.light.blue,
                                         17: eh.light.yellow,
 88
                                         27: eh.light.red,
 89
 90
                                         5: eh.light.green,
                                         6: eh.output.one,
 91
 92
                                         12: eh.output.two,
                                         13: eh.output.three,
 93
                                         16: eh.output.four
 94
 95
                                         }
 96
            # enable all of the digital inputs and assign
 97
 98
            # a callback for when the pin goes high
            eh.input.one.on_high(self.input_callback_high)
 99
            eh.input.two.on_high(self.input_callback_high)
100
101
            eh.input.three.on_high(self.input_callback_high)
            eh.input.four.on_high(self.input_callback_high)
102
103
104
            # assign a callback for when a pin goes low
105
            eh.input.one.on_low(self.input_callback_low)
106
            eh.input.two.on_low(self.input_callback_low)
107
            eh.input.three.on_low(self.input_callback_low)
            eh.input.four.on_low(self.input_callback_low)
108
109
            # enable touch pins with callback
110
111
            eh.touch.pressed(self.touch pressed)
112
            eh.touch.released(self.touch_released)
113
```

```
114
            # enable analog inputs if user selected to do so
            # when instantiating ExpProGateway
115
            if kwargs['enable_analog_input']:
116
                                                                                                                      116 + 123
                 eh.analog.one.changed(self.analog_in1, sensitivity[0])
117
                eh.analog.two.changed(self.analog_in2, sensitivity[1])
118
119
                eh.analog.three.changed(self.analog_in3, sensitivity[2])
                eh.analog.four.changed(self.analog_in4, sensitivity[3])
120
121
122
            # start the banyan receive loop
123
            try:
                 self.receive_loop()
124
            except KeyboardInterrupt:
125
                self.clean_up()
126
127
                sys.exit(0)
128
        def init_pins_dictionary(self):
129
130
131
            We will not be using this for this gateway, so just pass.
132
133
            pass
134
135
        def touch_pressed(self, pin, state):
            with self.the_lock:
136
137
                 timestamp = self.get_time_stamp()
138
139
                payload = {'report': 'touch', 'pin': pin,
                            'value': 1, 'timestamp': timestamp}
140
141
                self.publish_payload(payload, self.report_topic)
142
143
        def touch_released(self, pin, state):
            with self.the_lock:
144
                 timestamp = self.get_time_stamp()
145
146
147
                payload = {'report': 'touch', 'pin': pin,
                            'value': 0, 'timestamp': timestamp}
148
149
                self.publish_payload(payload, self.report_topic)
150
151
        def input_callback_high(self, data):
152
153
            This method is called by pigpio when it detects a change for
```

```
154
            a digital input pin. A report is published reflecting
            the change of pin state for the pin.
155
             :param data: callback data
156
             0.00
157
158
            with self.the_lock:
159
                 timestamp = self.get_time_stamp()
                # translate pin number
160
                if data.pin in self.gpio_input_pins:
161
162
                     pin = self.gpio_input_pins[data.pin]
                    payload = {'report': 'digital_input', 'pin': pin,
163
164
                                'value': 1, 'timestamp': timestamp}
                     self.publish_payload(payload, self.report_topic)
165
166
                else:
                     raise RuntimeError('unknown input pin: ', data.pin)
167
168
        def input_callback_low(self, data):
169
             0.00
170
171
            This method is called by pigpio when it detects a change for
172
            a digital input pin. A report is published reflecting
173
            the change of pin state for the pin.
             :param data: callback data
174
175
            with self.the_lock:
176
177
                 timestamp = self.get_time_stamp()
178
                # translate pin number
179
                if data.pin in self.gpio_input_pins:
180
                     pin = self.gpio_input_pins[data.pin]
181
                     payload = {'report': 'digital_input', 'pin': pin,
                                'value': 0, 'timestamp': timestamp}
182
                     self.publish_payload(payload, self.report_topic)
183
184
                else:
                     raise RuntimeError('unknown input pin: ', data.pin)
185
186
187
        def analog_in1(self, data, value):
            with self.the_lock:
188
                # explorer sometimes sends bogus data - just ignore it
189
                if value > 5.1:
190
191
                     return
192
                else:
193
                     self.publish_analog_data(1, value)
```

```
194
195
        def analog_in2(self, data, value):
196
            with self.the_lock:
                # explorer sometimes sends bogus data - just ignore it
197
198
                if value > 5.1:
199
                     return
200
                else:
                     self.publish_analog_data(2, value)
201
202
203
        def analog_in3(self, data, value):
204
            with self.the_lock:
                # explorer sometimes sends bogus data - just ignore it
205
206
                if value > 5.1:
207
                     return
208
                else:
                     self.publish_analog_data(3, value)
209
210
211
        def analog_in4(self, data, value):
212
            with self.the_lock:
                # explorer sometimes sends bogus data - just ignore it
213
                if value > 5.1:
214
215
                     return
216
                else:
217
                     self.publish_analog_data(4, value)
218
219
        def publish_analog_data(self, pin, value):
            # timestamp = self.get_time_stamp()
220
221
            timestamp = self.get_time_stamp()
            payload = {'report': 'analog_input', 'pin': pin,
222
                        'value': value, 'timestamp': timestamp}
223
            self.publish_payload(payload, self.report_topic)
224
225
226
        def additional_banyan_messages(self, topic, payload):
227
            This method will pass any messages not handled by this class to the
228
229
            specific gateway class. Must be overwritten by the hardware gateway
            class.
230
231
             :param topic: message topic
232
             :param payload: message payload
             0.00
233
```

```
234
            # dc motor commands
235
236
            print(payload)
            if payload['command'] == 'dc_motor_forward':
237
                 speed = payload['speed'] * 100
238
239
                if payload['motor'] == 1:
                     eh.motor.one.speed(speed)
240
                elif payload['motor'] == 2:
                                                                                                                       241 → 244
241
242
                     eh.motor.two.speed(speed)
                 else:
243
                     raise RuntimeError('unknown motor number')
244
245
246
            elif payload['command'] == 'dc_motor_reverse':
                                                                                                                       246 → 25€
                 speed = payload['speed'] * 100
247
                if payload['motor'] == 1:
248
                     eh.motor.one.speed(speed)
249
250
                 elif payload['motor'] == 2:
                                                                                                                       250 + 253
                     eh.motor.two.speed(speed)
251
252
                else:
                     raise RuntimeError('unknown motor')
253
254
255
            else:
                 raise RuntimeError('Unknown motor command')
256
257
258
        def analog_write(self, topic, payload):
259
260
261
             :param topic: message topic
             :param payload: message payload
262
263
264
            raise NotImplementedError
265
266
        def digital_read(self, pin):
267
268
269
             :param pin:
270
271
            raise NotImplementedError
272
273
        def digital_write(self, topic, payload):
```

```
\Pi \Pi \Pi
274
275
            Set a signal, specified by its pin number in the payload,
             to the value specified in the payload.
276
277
            Typical message: to_hardware {'command': 'digital_write', 'value': 0, 'pin': 0}
278
279
280
             :param topic: message topic
             :param payload: message payload
281
282
283
            # we will use the fade function
284
            pin = payload['pin']
            value = payload['value']
285
286
            if pin in self.digital_output_pins:
                                                                                                                       286 + 290
                output_object = self.digital_output_pins[pin]
287
                 output_object.fade(0, value, .0001)
288
             else:
289
290
                 raise RuntimeError('illegal digital output pin: ', pin)
291
292
        def disable_analog_reporting(self, topic, payload):
293
294
295
296
             :param topic: message topic
             :param payload: message payload
297
298
299
            raise NotImplementedError
300
301
        def disable_digital_reporting(self, topic, payload):
302
303
             :param topic: message topic
             :param payload: message payload
304
             0.00
305
306
            raise NotImplementedError
307
        def enable_analog_reporting(self, topic, payload):
308
309
310
             :param topic: message topic
311
             :param payload: message payload
312
313
            raise NotImplementedError
```

```
314
315
        def enable_digital_reporting(self, topic, payload):
316
317
             :param topic: message topic
             :param payload: message payload
318
319
320
            raise NotImplementedError
321
322
        def i2c_read(self, topic, payload):
323
324
             :param topic: message topic
325
             :param payload: message payload
326
327
            raise NotImplementedError
328
329
        def i2c_write(self, topic, payload):
330
             :param topic: message topic
331
             :param payload: message payload
332
333
            raise NotImplementedError
334
335
336
        def play_tone(self, topic, payload):
337
338
             :param topic: message topic
339
             :param payload: message payload
340
341
            raise NotImplementedError
342
343
        def pwm_write(self, topic, payload):
344
            Set the specified drive pin to the specified pwm level
345
346
347
            Typical message:
            to_hardware {'pin': 0, 'command': 'pwm_write', 'value': 0.41}
348
349
350
             :param topic: message topic
351
             :param payload: message payload
352
353
            raise NotImplementedError
```

```
354
355
        def servo_position(self, topic, payload):
356
            Set servo angle for the specified servo
357
358
359
            Typical message:
            to_hardware {'command': 'servo_position', 'position': 114, 'pin': 1}
360
361
362
             :param topic: message topic
             :param payload: message payload
363
364
365
            raise NotImplementedError
366
        def set_mode_analog_input(self, topic, payload):
367
368
369
            Set a signal to analog input
370
            Typical message:
371
            to_hardware {'command': 'set_mode_analog_input', 'pin': 5}
372
373
374
             :param topic: message topic
375
             :param payload: message payload
376
377
            pass
378
379
        def set_mode_digital_input(self, topic, payload):
380
381
            This method sets a pin as digital input.
             :param topic: message topic
382
            :param payload: {"command": "set_mode_digital_input", "pin": "PIN", "tag":"TAG" }
383
384
385
            pass
386
387
        def set_mode_digital_input_pullup(self, topic, payload):
388
            pass
389
        def set_mode_digital_output(self, topic, payload):
390
391
392
            This method sets a pin as a digital output pin.
393
             :param topic: message topic
```

```
394
             :param payload: {"command": "set_mode_digital_output",
                              "pin": PIN, "tag":"TAG" }
395
396
            # self.pi.set_mode(payload['pin'], pigpio.OUTPUT)
397
398
399
400
        def set_mode_pwm(self, topic, payload):
401
             This method sets a GPIO pin capable of PWM for PWM operation.
402
              :param topic: message topic
403
404
              :param payload: {"command": "set_mode_pwm", "pin": "PIN", "tag":"TAG" }
405
406
            raise NotImplementedError
407
408
        def set_mode_i2c(self, topic, payload):
409
410
             :param topic: message topic
             :param payload: message payload
411
412
413
            raise NotImplementedError
414
415
        def set_mode_servo(self, topic, payload):
416
417
            {'command': 'set_mode_servo', 'pin': 1}
418
419
             :param topic: message topic
420
             :param payload: message payload
            0.000
421
422
            pass
423
424
        def set_mode_sonar(self, topic, payload):
            0.00
425
426
             :param topic: message topic
427
             :param payload: message payload
428
            raise NotImplementedError
429
430
431
        def set_mode_stepper(self, topic, payload):
432
             - mode does not need to set - the stepper objects
433
```

```
434
            are used directly.
             :param topic: message topic
435
436
             :param payload: message payload
437
438
            raise NotImplementedError
439
440
        def set_mode_tone(self, topic, payload):
441
442
443
             :param topic: message topic
444
             :param payload: message payload
445
446
            raise NotImplementedError
447
448
        def stepper_write(self, topic, payload):
449
450
             - stepper objects are handled directly
             :param topic: message topic
451
452
             :param payload: message payload
453
454
            raise NotImplementedError
455
        def get_time_stamp(self):
456
457
            Get the time of the pin change occurence
458
             :return: Time stamp
459
460
461
            t = time.time()
462
            return time.strftime('%Y-%m-%d %H:%M:%S', time.localtime(t))
463
464
    def exp_pro_gateway():
465
466
        parser = argparse.ArgumentParser()
        parser.add_argument("-a", dest="enable_analog_input", default="false",
467
                             help="Set to True to enable analog input")
468
        parser.add_argument("-b", dest="back_plane_ip_address", default="None",
469
                             help="None or IP address used by Back Plane")
470
471
        parser.add_argument("-d", dest="board_type", default="None",
472
                             help="This parameter identifies the target GPIO "
                                  "device")
473
```

```
474
        parser.add_argument("-1", dest="subscriber_list",
475
                             default="to_hardware", nargs='+',
                             help="Banyan topics space delimited: topic1 topic2 "
476
                                  "topic3")
477
478
        parser.add_argument("-n", dest="process_name", default="CrickitGateway",
479
                             help="Set process name in banner")
        parser.add_argument("-p", dest="publisher_port", default='43124',
480
                             help="Publisher IP port")
481
482
        parser.add_argument("-r", dest="report_topic", default='report_from_hardware',
                             help="Topic to publish reports from hardware.")
483
        parser.add_argument("-s", dest="subscriber_port", default='43125',
484
485
                             help="Subscriber IP port")
486
        parser.add_argument("-t", dest="threshold", default="4.99, 4.99, 4.99",
                             nargs="+", help="A space delimited list of analog input sensitivities. Must contain 4 values
487
                                             "between 0.0 and 5.0")
488
489
490
        args = parser.parse_args()
        if args.back_plane_ip_address == 'None':
                                                                                                                     491 + 493
491
492
            args.back_plane_ip_address = None
        if args.board_type == 'None':
                                                                                                                     493 + 495
493
            args.back_plane_ip_address = None
494
495
        args.enable_analog_input = args.enable_analog_input.lower()
        if args.enable_analog_input == 'true':
                                                                                                                     496 + 499
496
            args.enable analog input = True
497
498
        else:
499
            args.enable_analog_input = False
        kw_options = {
500
501
             'enable_analog_input': args.enable_analog_input,
             'back_plane_ip_address': args.back_plane_ip_address,
502
             'publisher_port': args.publisher_port,
503
             'subscriber_port': args.subscriber_port,
504
             'process_name': args.process_name,
505
506
            # 'loop_time': float(args.loop_time),
             'report topic': args.report topic,
507
             'board_type': args.board_type,
508
             'threshold': args.threshold}
509
510
511
        try:
512
            app = ExpProGateway(args.subscriber_list, **kw_options)
        except KeyboardInterrupt:
513
```

```
514
            sys.exit()
515
        # noinspection PyUnusedLocal
516
        def signal_handler(sig, frame):
517
            print("Control-C detected. See you soon.")
518
            app.clean_up()
519
            sys.exit(0)
520
521
        # listen for SIGINT
522
523
        signal.signal(signal.SIGINT, signal_handler)
        signal.signal(signal.SIGTERM, signal_handler)
524
525
526
527 if __name__ == '__main__':
        # replace with name of function you defined above
528
        exp_pro_gateway()
529
```

527 **→** exi

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