

There are four tasks each carrying the same weight.

1. Fully Controllable Camera (1.exe)
2. Sphere to/from Cube (1.exe)
3. Wheel (2.exe)

1. Fully Controllable Camera (1.exe)

up arrow - move forward

down arrow - move backward

right arrow - move right

left arrow - move left

PgUp - move up

PgDn - move down

1 - rotate/look left

2 - rotate/look right

3 - look up

4 - look down

5 - tilt clockwise

6 - tilt counterclockwise

Hint:

Maintain 4 global variables: 1 3d point `pos` to indicate the position of the camera and 3 3d **unit** vectors `u`, `r`, and `l` to indicate the up, right, and look directions respectively. `u`, `r`, and `l` must be perpendicular to each other, i.e., $u \cdot r = r \cdot l = l \cdot u = 0$, $u = r \times l$, $l = u \times r$, and $r = l \times u$. You should initialize and maintain the values of `u`, `r`, and `l` such that the above property holds throughout the execution of the program. For example, you can initialize them as follows: $u = (0, 0, 1)$, $r = (-1/\sqrt{2}, 1/\sqrt{2}, 0)$, $l = (-1/\sqrt{2}, -1/\sqrt{2}, 0)$, and `pos = (100, 100, 0)`. And while changing `u`, `r`, and `l`, make sure that they remain unit vectors perpendicular to each other.

The first 6 operations listed above are move operations, where the position of the camera changes but the up, right, and look directions do not. The last 6 operations are rotate operations, where the camera position does not change, but the direction vectors do.

In case of a move operation, move `pos` a certain amount along the appropriate direction, but leave the direction vectors unchanged. For example, in the move right operation, move `pos` along `r` by 2 (or by any amount you find appropriate) units.

In case of a rotate operation, rotate two appropriate direction vectors a certain amount around the other direction vector, but leave the position of the camera unchanged. For example, in the look up operation, rotate \mathbf{l} and \mathbf{u} counterclockwise with respect to \mathbf{r} by 3 (or by any amount you find appropriate) degrees [vector.ppt slide#12].

If you maintain \mathbf{pos} , \mathbf{u} , \mathbf{r} , and \mathbf{l} in this way, your `gluLookAt` statement will look as follows:

```
gluLookAt(pos.x, pos.y, pos.z,  
          pos.x + l.x, pos.y + l.y, pos.z + l.z,  
          u.x, u.y, u.z);
```

2. Sphere to/from Cube (1.exe)

Home - cube to sphere

End - sphere to cube

Draw one eighth of a sphere, one fourth of a cylinder and a square once.

Use transformations (translation, rotation etc.) to put them in the right places.

3. Wheel (2.exe)

w - move forward

s - move backward

a - rotate left

d - rotate right

Use arrow keys to move the camera.

Keep in mind that a full (360 degree) rotation of the wheel moves the wheel linearly by a length equal to the perimeter of the wheel.

It is not required to strictly imitate the color patterns, but the shape of the wheel must be discernible.

For Camera, use the 2nd out of the three `gluLookAt` statements (Line 291) in the demo code.